

DETERMINATION OF COMPLETE O.D.F.s UNDER ASSUMPTION OF A MINIMAL VALUE

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1. Introduction

In the harmonic method the calculation of a complete O.D.F. from pole figure data is worked out in two distinct stages:

- the first one aims to calculate the reduced O.D.F., $\tilde{f}(g)$, (also called the even part of the O.D.F.) which makes it possible to recalculate any pole-figure. Because of experimental errors of the pole figure data, the reduced O.D.F. may correspond to recalculated pole-figures which exhibit some negative values. Dahms and Bunge have proposed to use an iterative technique which intends to ensure a physical meaning to the reduced O.D.F. i.e. recalculated pole-figures which are positive everywhere /1/. The interest of this technique in the harmonic method will be illustrated at the end of the present paper.

-the second stage of the texture analysis consists in calculating a complete O.D.F., $f(g)$, starting from the reduced one, $\tilde{f}(g)$ (this means that an odd part, $\hat{f}(g)$, which has no influence on pole-figures, is added to the even one). Several possibilities have been suggested for this purpose : the zero range method /2/, the gaussian peaks /3/, the quadratic method /4/. More recently Dahms and Bunge have proposed to use an iterative technique once more to calculate a complete O.D.F. by using the positivity condition $f(g) \geq 0$ /5/. They have also emphasized that a condition $f(g) \geq r_{\min}$ can be used, instead of the positivity condition, which means that a solution is searched with a given isotropic component or "phon", r_{\min} (obviously $0 \leq r_{\min} \leq 1$). The present paper tries to answer the question : how to choose such a r_{\min} value and what the effect of this choice is on the determination of the complete O.D.F.

2. Determination of a complete O.D.F. by the iterative technique

Assuming that a reduced O.D.F., $\tilde{f}(g)$, has been calculated from the experimental pole figures the complete O.D.F. can thus be determined in an iterative way and reads at the n^{th} step

$$f_n(g) = f_{n-1}(g) + \lambda_n \overset{\approx}{\approx} f_n(g) \quad (1)$$

$$\text{with } \hat{f}_n(g) \begin{cases} = 0 & \text{if } f_{n-1}(g) \geq r_{\min} \\ = r_{\min} - f_{n-1}(g) & \text{if } f_{n-1}(g) < r_{\min} \end{cases} \quad (2)$$

$$\text{and } f_0(g) = \tilde{f}(g) \quad (3)$$

and where λ_n is an optimization parameter which minimizes the distance of the current solution, $f_n(g)$, to the set of admissible solutions satisfying $f(g) \geq r_{\min}/6,7/$.

The symbol \approx appearing over $\hat{f}(g)$ in relation (1) means that only the odd part of this function is added so that in the final solution the even part, $\tilde{f}(g)$ is never modified along the iterations.

3. Results for a theoretical example.

To test the effect of the choice of r_{\min} on the calculated O.D.F. we have first used the so-called "Santa-Fe example" proposed by Matthies /8/. In this example the O.D.F. runs from

$f_{\min}^{\text{true}} = 0.72$ up to $f_{\max}^{\text{true}} = 5.04$ whereas the reduced O.D.F. is

between $\tilde{f}_{\min}^{\text{true}} = 0.07$ and $\tilde{f}_{\max}^{\text{true}} = 3.96$.

Starting from the corresponding pole-figures we have first determined $\tilde{f}(g)$ and then calculated $f(g)$ for 13 different

situations i.e. for 13 different r_{min} values. The results are not discussed in terms of O.D.F. sections because most of them are very similar but only in terms of maximum and minimum. At this point it is important to distinguish between r_{min} which is the requested minimum introduced in the iterative technique and f_{min} which is the minimal value of the calculated O.D.F.

When starting from $\tilde{f}(g)$, if it exists a solution $f(g)$ with $f_{min} = r_{min}$ the algorithm will of course find it ; if such a solution does not exist the calculated O.D.F. will have a minimal value $f_{min} \neq r_{min}$.

Figure 1 shows both the maximum, f_{max} , and minimum, f_{min} , of each calculated O.D.F.. It appears clearly that as long as r_{min} is less than f_{min} the calculated O.D.F. is somewhat different from the true O.D.F.. On the contrary if r_{min} is

greater than f_{min}^{true} the calculated O.D.F. is very close to the true one. This is important because in a texture analysis the available information is the minimal value in the pole-figures $P_{min} = \{ \text{Min } P_{hi}(y), \forall hi, \forall y \}$ which is known to obey the inequality :

$$f_{min} \leq P_{min} \quad (4)$$

Then by setting $r_{min} = P_{min}$ in the O.D.F. calculation a solution will be found with the maximal phon and the fact that r_{min} could be an overestimation of the isotropic component, f_{min}^{true} , has a small influence on the quality of the result.

In this Santa Fe example $P_{min} = 0.72$; by using $r_{min} = P_{min} = 0.72$ in the texture analysis it can be seen from Figure 1 that the calculated O.D.F. is very close to the true O.D.F..

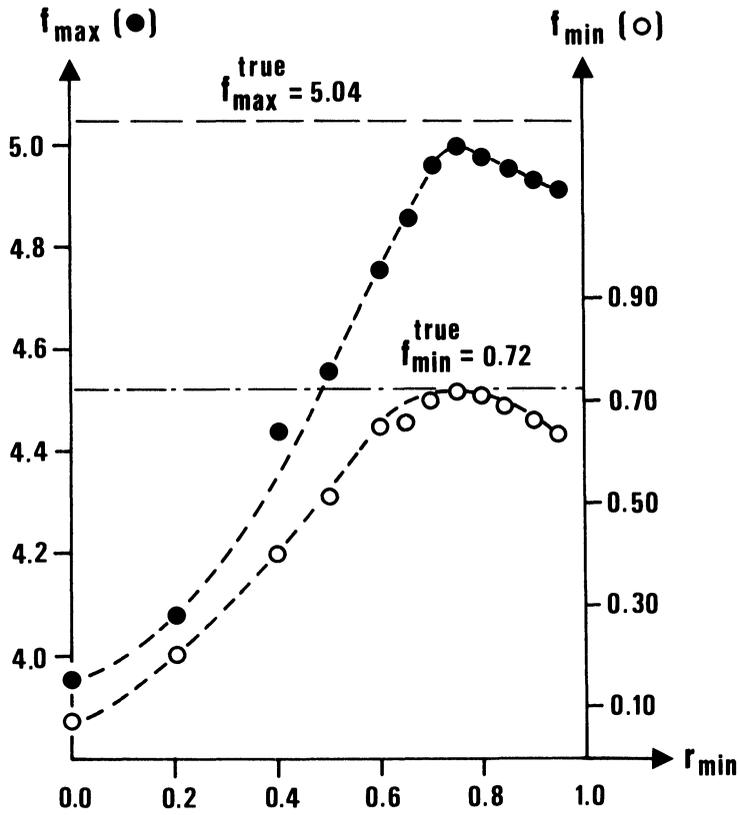


Figure 1 : Maximal and minimal value of the O.D.F., f_{\max} (●) and f_{\min} (○), as a function of r_{\min} for the Santa-Fe example

4. Results for a real specimen

Three incomplete pole-figures have been measured in a "standard" way (up to $\phi_{\max} = 75^\circ$, steps of 5° in azimuth and declination) and 5 texture analyses have been performed

from these data. In the first texture analysis (TA number 1) no positivity is activated during the first stage of analysis and the complete O.D.F. is calculated with $r_{min} = 0$.

On the contrary, for the four other analyses, the reduced O.D.F. is determined with positivity technique before to perform the second stage of calculation for the complete O.D.F. with $r_{min} = 0., 0.2, 0.4$ and 0.6 respectively.

In table I are reported the minimal and maximal values, f_{min} and f_{max} , of the calculated O.D.F., $f(g)$, and figure 2 shows some sections of the O.D.F. corresponding to the texture analyses numbered TA1, TA2 and TA5.

Texture Analysis number	requested minimum r_{min}	minimal value of $f(g) : f_{min}$	maximal value of $f(g) : f_{max}$
TA 1	0.	-2.30	10.41
TA 2	0.	-0.13	9.51
TA 3	0.2	-0.23	9.51
TA 4	0.4	-0.26	9.57
TA 5	0.6	-0.30	9.54

Table I : Calculated minimal and maximal values of $f(g)$, f_{min} and f_{max} , for 5 different texture analyses from the same set of 3 incomplete pole-figures of a low carbon steel.

It appears clearly that without positivity at the first stage (TA number 1) no satisfactory solution is found (the minimal value, f_{min} , is greatly negative) . For the other four analyses realistic results are obtained with f_{min} near zero (f_{min} decreases very slowly with increasing r_{min}) .

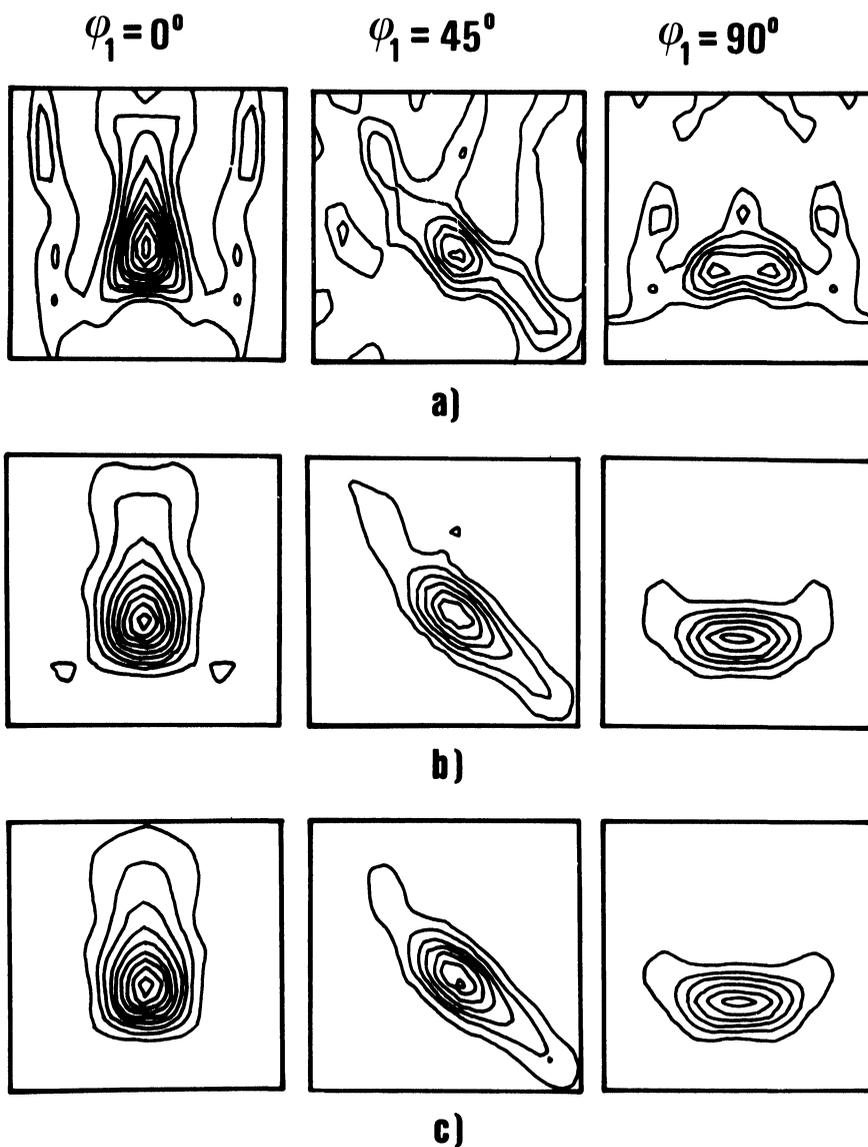


Figure 2 : Three O.D.F. sections ($\varphi_1=0^\circ, \varphi_1=45^\circ, \varphi_1=90^\circ$) of an annealed low carbon steel for several analysis conditions :

a) TA 1 ; b) TA 2 ; c) TA 5
 levels : 1. ,2. ,3. ,4. ,5. ,6. ,7. ,8. ,9.

5. Conclusion

The previous results allow to emphasize the two following points :

- a "bad" solution $\tilde{f}(g)$ at the first stage of the analysis prevents a further satisfactory result for the complete O.D.F., $f(g)$, as it was illustrated in the case of a steel. This obvious statement means that the iterative technique of positivity is necessary at both stages of the texture analysis with the harmonic method.

- by choosing $r_{min} = P_{min}$ for the calculation of the complete O.D.F., a solution is reached which is very closed to the one obeying the requirement of maximal phon without the necessity of iterations on this phon as in the WIMV method /8/. This last point has likely to be restricted to the case of texture functions with plateau (i.e. functions which present a minimal value in a large part of the Euler space as in the two studied examples). This is fortunately the most usual case in texture analysis.

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