Research Article

A New Approach to Asymptotic Behavior for a Finite Element Approximation in Parabolic Variational Inequalities

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The paper deals with the theta time scheme combined with a finite element spatial approximation of parabolic variational inequalities. The parabolic variational inequalities are transformed into noncoercive elliptic variational inequalities. A simple result to time energy behavior is proved, and a new iterative discrete algorithm is proposed to show the existence and uniqueness. Moreover, its convergence is established. Furthermore, a simple proof to asymptotic behavior in uniform norm is given.

1. Introduction

A great work has been done on questions of existence and uniqueness for parabolic variational and quasivariational inequalities over the last three decades. However, very much remains to be done on the numerical analysis side, especially error estimates and asymptotic behavior for the free boundary problems (cf., e.g., [1–8]).

In this paper, we propose a new iterative discrete algorithm to prove the existence and uniqueness, and we devote the asymptotic behavior using the θ time scheme combined with a finite element spatial approximation for parabolic inequalities.

Let us assume that K is an implicit convex set defined as follows:

$$K = \left\{ v(t, x) \in L^2(0, T, H_0^1(\Omega)), v(t, x) \leq \psi(t, x), v(0, x) = v_0 \text{ in } \Omega \right\}, \quad (1.1)$$

with

$$\psi \in L^2(0, T, W^{2,\infty}(\Omega)). \quad (1.2)$$

We consider the following problem, find $u \in K$ solution of

$$\begin{aligned} \frac{\partial u}{\partial t} + Au &\leq f \quad \text{in } \Sigma, \\ u(t, x) &= 0 \quad \text{in } \Gamma, \end{aligned} \quad (1.3)$$

where Σ is a set in $\mathbb{R} \times \mathbb{R}^N$ defined as $\Sigma = \Omega \times [0, T]$ with $T < +\infty$, and Ω is convex domain in $\mathbb{R}^N$, with sufficiently smooth boundary Γ .

The symbol $(\cdot, \cdot)$ stands for the inner product in $L^2(\Omega)$, and A is an operator defined over $H^1(\Omega)$ by

$$Au = -\sum_{ij=1}^N \frac{\partial}{\partial x_i} a_{ij}(x) \frac{\partial u}{\partial x_j} + \sum_{j=1}^N b_j(x) \frac{\partial u}{\partial x_j} + a_0(x)u, \quad (1.4)$$

and whose coefficients: $a_{ij}(x), b_j(x), a_0(x) \in L^\infty(\Omega) \cap C_2(\overline{\Omega})$, $x \in \overline{\Omega}$, $1 \leq i, j \leq N$ are sufficiently smooth functions and satisfy the following conditions:

$$a_{ij}(x) = a_{ji}(x); \quad a_0(x) \geq \beta > 0, \quad \beta \text{ is a constant.} \quad (1.5)$$

$$\sum_{ij=1}^N a_{ij}(x) \xi_i \xi_j \geq \gamma |\xi|^2; \quad \xi \in \mathbb{R}^N, \quad \gamma > 0, \quad x \in \overline{\Omega}. \quad (1.6)$$

f is a regular functions satisfying

$$f \in L^2(0, T, L^\infty(\Omega)) \cap C^1(0, T, H^{-1}(\Omega)), \quad f \geq 0. \quad (1.7)$$

We specify the following notations:

$$\|\cdot\|_{L^2(\Omega)} = \|\cdot\|_2, \quad \|\cdot\|_1 = \|\cdot\|_{H_0^1(\Omega)}, \quad \|\cdot\|_{L^\infty(\Omega)} = \|\cdot\|_\infty. \quad (1.8)$$

As we have said before, the aim of the present paper is to show that the asymptotic behavior can be properly approximated by a θ time scheme combined with a finite element spatial using a new iterative algorithm. We precede our analysis in two steps: in the first step, we discretize in space; that is, we approach the space H_0^1 by a space discretization of finite dimensional $V^h \subset H_0^1$. In the second step, we discretize the problem with respect to time using the θ -scheme. Therefore, we search a sequence of elements $u_h^n \in V^h$ which approaches $u^n(t_n)$, $t_n = n\Delta t$, with initial data $u_h^0 = u_{0h}$. Our approach stands on a discrete stability result and error estimate for parabolic variational inequalities.

The paper is organized as follows. In Section 2, we prove the simple result to time energy behavior of the semidiscrete parabolic variational inequalities. In Section 3, we prove the L^∞ -stability analysis of the θ -scheme for P.V.I, and finally, in Section 4, we first associate with the discrete P.V.I problem a fixed point mapping, and we use that in proving the existence of a unique discrete solution, and later, we establish the asymptotic behavior estimate of θ -scheme by the uniform norm for the problem studied.

2. Priory Estimate of the Discrete Parabolic Variational Inequalities

We can reformulate (1.3) to the following variational inequality:

$$\left(\frac{\partial u}{\partial t}, v - u \right) + a(u, v - u) \geq (f, v - u), \quad v \in K, \quad (2.1)$$

where $a(\cdot, \cdot)$ is the bilinear form associated with operator A defined in (1.4). Namely,

$$a(u, v) = \int_{\Omega} \left(\sum_{i,j=1}^N a_{ij}(x) \frac{\partial u}{\partial x_i} \frac{\partial v}{\partial x_j} + \sum_{j=1}^N b_j(x) \frac{\partial u}{\partial x_j} v + a_0(x) uv \right) dx, \quad (2.2)$$

Theorem 2.1 (see [9]). *The problem (1.3) has an unique solution $u \in K(u)$. Moreover, one has*

$$u \in L^2(0, T; H_0^1(\Omega)), \quad \frac{\partial u}{\partial t} \in L^2(0, T; H^{-1}(\Omega)). \quad (2.3)$$

Lemma 2.2 (Sobolev-Poincare inequality). *Let Ω be a bounded overt in $\mathbb{R}^N$, with sufficiently smooth boundary Γ , then there exists a C_* such that*

$$\|u\|_2 \leq C_* \|\nabla u\|_2, \quad v \in H_0^1(\Omega) \cap C^2(\overline{\Omega}), \quad \nabla = \sum_{i=1}^N \frac{\partial}{\partial x_i}. \quad (2.4)$$

2.1. The Discrete Problem

Let us assume that Ω can be decomposed into triangles and τ_h denotes the set of all the elements $h > 0$, where h is the mesh size. We assume that the family τ_h is regular and quasi-uniform, and we consider the usual basis of affine functions $\varphi_i, i = \{1, \dots, m(h)\}$ defined by $\varphi_i(M_j) = \delta_{ij}$, where M_j is a vertex of the considered triangulation. We introduce the following discrete spaces V^h of finite element:

$$V_h = \left\{ v_h \in L^2(0, T, H_0^1(\Omega)) \cap C(0, T, H_0^1(\overline{\Omega})), \text{ such that } v_h|_k \in P_1, k \in \tau_h, \right. \\ \left. v_h \leq r_h \psi, v_h(\cdot, 0) = v_{h0} \text{ in } \Omega. \right\}. \quad (2.5)$$

We consider r_h to be the usual interpolation operator defined by

$$v \in L^2(0, T, H_0^1(\Omega)) \cap C(0, T, H_0^1(\overline{\Omega})), \quad r_h v = \sum_{i=1}^{m(h)} v(M_i) \varphi_i(x). \quad (2.6)$$

The Discrete Maximum Principle Assumption (see [10])

The matrix whose coefficients $a(\varphi_i, \varphi_j)$ are supposed to be M -matrix. For convenience, in all the sequels, C will be a generic constant independent on h .

2.1.1. Priory Estimate

Theorem 2.3. *Let us assume that the discrete bilinear form $a(\cdot, \cdot)$ defined as (2.2) is weakly coercive in $V^h \subset H_0^1(\Omega)$. Then, there exists two constants $\alpha > 0$ and $\lambda > 0$ such that*

$$a(u_h, u_h) + \lambda \|u_h\|_2 \geq \alpha \|u_h\|_1, \quad (2.7)$$

where

$$\lambda = \left(\frac{\|b_j\|_\infty^2}{2\gamma} + \frac{\gamma}{2} + \|a_0\|_\infty \right), \quad \alpha = \frac{\gamma}{2}. \quad (2.8)$$

Proof. The bilinear form $a(\cdot, \cdot)$ is defined by

$$a(u_h, u_h) = \int_{\Omega} \left(\sum_{ij=1}^N a_{ij}(x) \frac{\partial u_h}{\partial x_i} \frac{\partial u_h}{\partial x_j} + \sum_{j=1}^N b_j(x) \frac{\partial u_h}{\partial x_j} u_h + a_0(x) u_h^2 \right) dx, \quad (2.9)$$

under assumption (1.6), we have

$$\sum_{ij=1}^N \int_{\Omega} a_{ij}(x) \frac{\partial u_h}{\partial x_i} \frac{\partial u_h}{\partial x_j} > \gamma \sum_{i=1}^N \left(\int_{\Omega} \frac{\partial u_h}{\partial x_i} \right)^2 = \gamma \|\nabla u_h\|_2^2, \quad (2.10)$$

and since

$$\begin{aligned} \left| \sum_{j=1}^N \int_{\Omega} b_j(x) \frac{\partial u_h}{\partial x_j} u_h \right| &\leq \sup_j |b_j| \sum_{j=1}^N \int_{\Omega} \left| \frac{\partial u_h}{\partial x_j} u_h \right| \\ &\leq \|b_j\|_\infty \|\nabla u_h\|_2 \|u_h\|_2, \end{aligned} \quad (2.11)$$

then we make use of the algebraic inequality

$$ab \leq \frac{1}{2} (a^2 + b^2), \quad \forall a, b \in \mathbb{R}, \quad \forall \gamma > 0, \quad (2.12)$$

and choosing

$$\begin{aligned} a &= \|\nabla u_h\|_2 \cdot \sqrt{\gamma}, \\ b &= \frac{\|b_j\|_\infty}{\sqrt{\gamma}} \|u_h\|_2, \end{aligned} \quad (2.13)$$

then we end up with

$$\left| \sum_{j=1}^N \int_{\Omega} b_j(x) \frac{\partial u_h}{\partial x_j} u_h \right| \geq - \left(\frac{\gamma}{2} \|\nabla u_h\|_2^2 + \frac{\|b_j\|_{\infty} \cdot \|u_h\|_2}{2\gamma} \right), \quad (2.14)$$

so we get

$$a(u_h, u_h) \geq \gamma \|\nabla u_h\|_2^2 - \frac{\gamma}{2} \|\nabla u_h\|_2^2 + \frac{\|b_j\|_{\infty}}{2\gamma} \|u_h\|_2 - \|a_0\|_{\infty} \|u_h\|_2^2. \quad (2.15)$$

It can easily verified that

$$a(u_h, u_h) \geq \frac{\gamma}{2} (\|\nabla u_h\|_2 + \|u_h\|_2^2) - \left(\frac{\|a_j\|_{\infty}^2}{2\gamma} + \frac{\gamma}{2} + \|a_0\|_{\infty} \right) \|u_h\|_2^2. \quad (2.16)$$

Consequently, we deduce from above that

$$a(u_h, u_h) + \lambda \|u_h\|_2^2 \geq \alpha \|u_h\|_1^2 \quad \text{such that } \alpha = \frac{\gamma}{2}, \quad \lambda = \left(\frac{\|a_j\|_{\infty}^2}{2\gamma} + \frac{\gamma}{2} + \|a_0\|_{\infty} \right). \quad (2.17)$$

□

We can identify the following result on the time energy behavior:

$$E_h(t) = \int_{\Omega} u_h^2 dx. \quad (2.18)$$

Setting $v = 0$ on (2.1) and after discretization by the finite element in the V^h , we have the semidiscretization problem

$$\left(\frac{\partial u_h}{\partial t}, u_h \right) + a(u_h, u_h) = \frac{1}{2} \int_{\Omega} \frac{\partial u_h^2}{\partial t} dx + a(u_h, u_h) \leq (f, u_h). \quad (2.19)$$

Using Theorem 2.3, we deduce that

$$\begin{aligned} \frac{1}{2} \int_{\Omega} \frac{du_h^2}{dt} dx + a(u_h, u_h) &\geq \frac{1}{2} \frac{d}{dt} \int_{\Omega} u_h^2 dx + \alpha \|u_h\|_1^2 - \lambda \|u_h\|_2^2 \\ &= \frac{1}{2} \frac{d}{dt} \int_{\Omega} u_h^2 dx + \alpha \|u_h\|_2^2 + \alpha \|\nabla u_h\|_2^2 - \lambda \|u_h\|_2^2 \\ &= \frac{1}{2} \left(\frac{d}{dt} E_h(t) + 2(\alpha - \lambda) E_h(t) + 2\alpha \|\nabla u_h\|_2^2 \right) \\ &\geq \frac{1}{2} \left(\frac{d}{dt} E_h(t) + 2(\alpha - \lambda) E_h(t) + \frac{2\alpha}{C_*^2} \int_{\Omega} u_h^2 dx \right). \end{aligned} \quad (2.20)$$

Thus, we have

$$\frac{d}{dt} \int_{\Omega} u_h^2 dx + \alpha \|u_h\|_1^2 - \lambda \|u_h\|_2^2 \geq \frac{d}{dt} (E_h(t)) + 2 \left(\alpha - \lambda + \frac{\alpha}{C_*^2} \right) E_h(t). \quad (2.21)$$

Applying the Cauchy-Schwartz inequality on the right-hand side of (2.1), we find

$$(f, u_h) = \int_{\Omega} f(x, t) u_h(x, t) dx \leq \|f\|_2 \|u_h\|_2. \quad (2.22)$$

So that

$$\frac{d}{dt} E_h(t) + 2 \left(\alpha - \lambda + \frac{\alpha}{C_*^2} \right) E_h(t) \leq 2 \|f\|_2 \|u_h\|_2. \quad (2.23)$$

Using Young's inequality

$$ab \leq \varepsilon a^2 + \frac{1}{4\varepsilon} b^2, \forall a, b \in \mathbb{R}, \forall \varepsilon > 0. \quad (2.24)$$

Thus, we obtain

$$\frac{d}{dt} E_h(t) + 2 \left(\alpha - \lambda + \frac{\alpha}{C_*^2} \right) E_h(t) \leq 2\varepsilon E_h(t) + \frac{1}{2\varepsilon} \|f\|_2^2, \quad (2.25)$$

taking $\eta = \alpha - \lambda + \alpha/C_*^2$, thus we have

$$\frac{d}{dt} E_h(t) + 2(\eta - \varepsilon) E_h(t) \leq \frac{1}{2\varepsilon} \|f\|_2^2. \quad (2.26)$$

Or, equivalently

$$\left(e^{2(\eta - \varepsilon)t} E_h(t) \right)' \leq \frac{1}{2\varepsilon} e^{2(\eta - \varepsilon)t} \int_{\Omega} (f(x, t))^2 dx. \quad (2.27)$$

Integrating the last inequality from 0 to t , we get

$$E_h(t) \leq e^{-2(\eta - \varepsilon)t} E_h(0) + \frac{1}{2\varepsilon} \int_0^t \left[e^{2(\eta - \varepsilon)(s-t)} \left(\int_{\Omega} (f(x, s))^2 dx \right) \right] ds. \quad (2.28)$$

Remark 2.4. In particular, when $f = 0$ and choosing $\varepsilon < \eta$, then (2.28) shows that the energy $E(t)$ decreasing exponentially fast in time.

3. The θ -Scheme Method for the Parabolic Variational Inequalities

3.1. Stability Analysis for the P.V.I

We apply the finite element method to approximate inequality (2.1), and the discrete P.V.I takes the form of

$$\left(\frac{\partial u_h}{\partial t}, v_h - u_h \right) + a(u_h, v_h - u_h) \geq (f, v_h - u_h), \quad v_h \in V^h. \quad (3.1)$$

Now, we apply the θ -scheme on the semidiscrete problem (3.1); for any $\theta \in [0, 1]$ and $k = 1, \dots, n$, we have

$$\left(u_h^k - u_h^{k-1}, v_h - u_h^{\theta,k} \right) + \Delta t \cdot a(u_h^{\theta,k}, v_h - u_h^{\theta,k}) \geq \Delta t \cdot (f^{\theta,k}, v_h - u_h^{\theta,k}), \quad v_h \in V^h, \quad (3.2)$$

where

$$\begin{aligned} u_h^{\theta,k} &= \theta u_h^k + (1 - \theta) u_h^{k-1}, \\ f^{\theta,k} &= \theta f(t_k) + (1 - \theta) f(t_{k-1}). \end{aligned} \quad (3.3)$$

It is possible to analyze the stability by taking the advantage of the structure of eigenvalues of the bilinear form $a(\cdot, \cdot)$. We recall that W is compactly embedded in $L^2(\Omega)$, since Ω is bounded. Thus, there exists a nondecreasing sequence of eigenvalues $\delta \leq \lambda_1 \leq \lambda_2 \leq \dots$ for the bilinear form $a(\cdot, \cdot)$ satisfying

$$\omega_j \in L^2, \quad \omega_j \neq 0: a(\omega_j, v_h) = \lambda_j(\omega_j, v_h), \quad \forall v_h \in V^h. \quad (3.4)$$

The corresponding eigenfunctions $\{\omega_j\}$ form a complete orthonormal basis in $L^2(\Omega)$. In analogous way, when considering the finite dimensional problem in W^h , we find a sequence of eigenvalues $\delta \leq \lambda_{1h} \leq \lambda_{2h} \leq \dots \leq \lambda_{m(h)}$ and L^2 -orthonormal basis of eigenvectors $\omega_{ih} \in W^h$, $i = 1, 2, \dots, m(h)$. Any function v_h in V^h can thus be expanded with respect to the system ω_{ih} as

$$v_h = \sum_{i=1}^{m(h)} (v_h, \omega_{ih}) \omega_{ih}, \quad (3.5)$$

in particular, we have

$$u_h^k = \sum_{i=1}^{m(h)} u_i^k \omega_{ih}, \quad u_i^k = (u_h^k, \omega_{ih}). \quad (3.6)$$

Moreover, let f_h^k be the L^2 -orthogonal projection of $f^{\theta,k}$ into W^h , that is, $f_h^k \in W^h$ and

$$(f_h^k, v_h) = (f^{\theta,k}, v_h), \quad (3.7)$$

and set

$$f_h^k = \sum_{i=1}^{m(h)} f_i^k \omega_{ih}, \quad f_i^k = (f_h^k, \omega_{ih}). \quad (3.8)$$

We are now in a position to prove the stability for $\theta \in [0, 1/2[$

Choosing in (3.1) $v_h = 0$, thus we have

$$\frac{1}{\Delta t} (u_h^k - u_h^{k-1}, u_h^{\theta,k}) + a(u_h^{\theta,k}, u_h^{\theta,k}) \leq (f_h^{\theta,k}, u_h^{\theta,k}), \quad u_h^{\theta,k} \in V^h. \quad (3.9)$$

The inequalities (3.2) is equivalent to

$$\frac{1}{\Delta t} (u_i^k - u_i^{k-1}) + \lambda_{ih} (\theta u_i^k + (1-\theta) u_i^{k-1}) \leq f_i^k. \quad (3.10)$$

Since ω_{ih} are the eigenfunctions means

$$a(\omega_{ih}, \omega_{ih}) = \lambda_{ih}(\omega_{ih}, \omega_{ih}) = \lambda_{ih} \cdot \delta_{ii} = \lambda_{ih}, \quad (3.11)$$

for each $k = 0, \dots, m(h) - 1$, we can rewrite (3.9) as

$$u_i^k \leq \frac{1 - (1-\theta) \cdot \Delta t \cdot \lambda_{ih}}{1 + \theta \Delta t \cdot \lambda_{ih}} u_i^{k-1} + \frac{\Delta t}{1 + \theta \Delta t \cdot \lambda_{ih}} f_i^k, \quad (3.12)$$

this inequality system stable if and only if

$$\left| \frac{1 - (1-\theta) \cdot \Delta t \cdot \lambda_{ih}}{1 + \theta \Delta t \cdot \lambda_{ih}} \right| < 1, \quad (3.13)$$

that is to say

$$2\theta - 1 > -\frac{2}{\lambda_{ih} \cdot \Delta t} \quad (3.14)$$

means

$$\Delta t < \frac{2}{(1-2\theta)\lambda_{ih}}. \quad (3.15)$$

So that this relation satisfied for all the eigenvalues λ_{ih} of bilinear form $a(\cdot, \cdot)$, we have to choose their highest value, and we take it for $\lambda_{mh} = \rho(A)$ (rayon spectral)

We deduce that if $\theta \geq 1/2$ the θ -scheme way is stable unconditionally (i.e., stable for all Δt). However, if $0 \leq \theta < 1/2$ the θ -scheme is stable unless

$$\Delta t < \frac{2}{(1-2\theta)\rho(A)}. \quad (3.16)$$

We can prove that there exist two positive constants c_1, c_2 such that

$$\frac{c_1}{h^2} \leq \lambda_{mh} = c_2 h^{-2}, \quad (3.17)$$

thus the method of θ -scheme is stable if and only if

$$\Delta t < \frac{2C}{(1-2\theta)} h^2. \quad (3.18)$$

Notice that this condition is always satisfied if $0 \leq \theta < 1/2$. Hence, taking the absolute value of (3.12), we have

$$|u_i^m| < |u_i^0| + \frac{\Delta t}{1 + \theta \Delta t \cdot \lambda_{ih}} \sum_{i=1}^{m-1} f_i^k, \quad (3.19)$$

also we deduce that

$$\|u_i^m\|_\infty < \|u_i^0\|_\infty + \left\| \frac{\Delta t}{1 + \theta \Delta t \cdot \lambda_{ih}} \right\|_\infty \sum_{i=1}^{m-1} \|f_i^k\|_\infty. \quad (3.20)$$

Remark 3.1 (cf. [4]). We assume that the coerciveness assumption (Theorem 2.3) is satisfied with $\lambda = 0$, and for each $k = 1, \dots, n$, we find

$$\|u_h^k\|_2^2 + 2\Delta t \sum_{k=1}^n a(u_h^{\theta,k}, u_h^{\theta,k}) \leq C(n) \left(\sum_{k=1}^n \Delta t \|f^{\theta,k}\|_2^2 \right). \quad (3.21)$$

4. Asymptotic Behavior of θ -Scheme for the P.V.I

This section is devoted to the proof of the main result of the present paper; we need first to study some properties such as proving the existence and uniqueness for parabolic variational inequalities.

4.1. Existence and Uniqueness for P.V.I

Theorem 4.1 (cf. [2, 3]). *Under the previous assumptions, and the maximum principle, there exists a constant C independent of h such that*

$$\|u^\infty - u_h^\infty\|_\infty \leq Ch^2 |\log h|^2, \quad (4.1)$$

where u^∞ and u_h^∞ are, respectively, stationery solutions to the following continue and discrete inequalities:

$$b(u^\infty, v - u^\infty) \geq (f + \lambda u^\infty, v - u^\infty), \quad v \in H_0^1(\Omega), \quad (4.2)$$

$$b(u_h^\infty, v_h - u_h^\infty) \geq (f + \lambda u_h^\infty, v_h - u_h^\infty), \quad v_h \in V^h, \quad (4.3)$$

such that

$$b(\cdot, \cdot) = a(\cdot, \cdot) + \lambda(\cdot, \cdot), \quad (4.4)$$

where λ is a positive constant arbitrary. We have $u_h^{\theta,k} = \theta u_h^k + (1 - \theta)u_h^{k-1} \leq \theta r_h \psi + (1 - \theta)r_h \psi = r_h \psi$. Thus, we can rewrite (3.1) as, for $u_h^{\theta,k} \in V^h$

$$\left(\frac{u_h^{\theta,k}}{\theta \Delta t}, v_h - \tilde{u}_h^k \right) + a(u_h^{\theta,k}, v_h - u_h^{\theta,k}) \geq \left(f^{\theta,k} + \frac{u_h^{k-1}}{\theta \Delta t}, v_h - u_h^{\theta,k} \right), \quad v_h \in V^h. \quad (4.5)$$

Thus, our problem (4.5) is equivalent to the following noncoercive elliptic variational inequalities:

$$b(u_h^{\theta,k}, v_h - \tilde{u}_h^k) \geq (f^{\theta,k} + \mu u_h^{k-1}, v_h - u_h^{\theta,k}), \quad v_h \in V^h, \quad (4.6)$$

such that

$$b(u_h^{\theta,k}, v_h - u_h^{\theta,k}) = \mu(u_h^{\theta,k}, v_h - u_h^{\theta,k}) + a(u_h^{\theta,k}, v_h - u_h^{\theta,k}), \quad v_h, u_h^{\theta,k} \in V^h, \quad (4.7)$$

$$\mu = \frac{1}{\theta \Delta t} = \frac{T}{\theta k},$$

where $u_h^{\theta,1}$ is the solution to the following discrete inequality:

$$a(u_h^{\theta,1}, v_h - u_h^{\theta,1}) = (g(t_k), v_h - u_h^{\theta,1}), \quad v_h \in V^h, \quad (4.8)$$

where $g(t_k)$ is a regular function given.

4.1.1. A Fixed Point Mapping Associated with Discrete Problem (4.7)

We consider the mapping

$$T_h : L_+^\infty(\Omega) \longrightarrow V^h$$

$$w \longrightarrow T_h(w) = \xi_h, \quad (4.9)$$

where ξ_h is the unique solution of the following P.V.I: find $\xi_h \in V^h$

$$b(\xi_h, v_h - \xi_h) \geq (f^{\theta,k} + \mu w, v_h - \xi_h), \quad v_h \in V^h. \quad (4.10)$$

Proposition 4.2. *Under the previous hypotheses and notations, if one sets $\theta \geq 1/2$, the mapping T_h is a contraction in $L^\infty(\Omega)$ with rate of contraction $1/(1 + \beta \cdot \theta \cdot \Delta t)$. Therefore, T_h admits a unique fixed point which coincides with the solution of P.V.I (4.7).*

Proof. For $w, \tilde{w}$ in $L^\infty(\Omega)$, we consider $\xi_h = T_h(w) = \partial(f^{\theta,k} + \mu w, r_h \psi)$ and $\tilde{\xi}_h = T_h(\tilde{w}) = \partial(f^{\theta,k} + \mu \tilde{w}, r_h \tilde{\psi})$ solution to quasivariational inequalities (4.7) with right-hand side $F^{\theta,k} = f^{\theta,k} + \mu w_h$, $\tilde{F}^{\theta,k} = f^{\theta,k} + \mu \tilde{w}_h$.

Now, setting

$$\phi = \frac{1}{\beta + \mu} \|F^{\theta,k} - \tilde{F}^{\theta,k}\|_\infty, \quad (4.11)$$

then for $\xi_h + \phi$ is solution of

$$\begin{aligned} b(\xi_h + \phi, (v_h + \phi) - (\xi_h + \phi)) &\geq (F^{\theta,k} + a_0 \phi, (v_h + \phi) - (\xi_h + \phi)), \\ \xi_h + \phi &\leq r_h \psi + \phi, \quad v_h + \phi \leq r_h \psi + \phi, \quad \forall v_h \in V^h. \end{aligned} \quad (4.12)$$

Also, we have

$$\begin{aligned} F^{\theta,k} &\leq \tilde{F}^{\theta,k} + \|F^{\theta,k} - \tilde{F}^{\theta,k}\|_\infty \\ &\leq \tilde{F}^{\theta,k} + \frac{a_0}{\beta + \mu} \|F^{\theta,k} - \tilde{F}^{\theta,k}\|_\infty \\ &\leq \tilde{F}^{\theta,k} + a_0 \phi, \end{aligned} \quad (4.13)$$

thus

$$\partial_h(F^{\theta,k}, r_h \psi + \phi) \leq \partial_h(\tilde{F}^{\theta,k} + a_0(x)\phi, r_h \tilde{\psi} + \phi) \leq \partial_h(\tilde{F}^{\theta,k}, r_h \tilde{\psi}) + \phi, \quad (4.14)$$

hence

$$\xi_h \leq \tilde{\xi}_h + \phi. \quad (4.15)$$

Similarly, interchanging the roles of w and $\tilde{w}$, we also get

$$\tilde{\xi}_h \leq \xi_h + \phi. \quad (4.16)$$

Finally, this yields

$$\begin{aligned}
\left\| \partial_h \left(F^{\theta,k}, r_h \psi \right) - \partial_h \left(\tilde{F}^{\theta,k}, r_h \tilde{\psi} \right) \right\|_{\infty} &\leq \frac{1}{\beta + \mu} \left\| F^{\theta,k} - \tilde{F}^{\theta,k} \right\|_{\infty} \\
&\leq \frac{1}{\beta + \mu} \left\| f^{\theta,k} + \mu w - f^{\theta,k} - \mu \tilde{w} \right\|_{\infty} \|w - \tilde{w}\|_{\infty} \quad (4.17) \\
&\leq \frac{1}{1 + \beta \theta \Delta t} \|w - \tilde{w}\|_{\infty},
\end{aligned}$$

which completes the proof. $\square$

Remark 4.3. If we set $0 \leq \theta < 1/2$, the mapping T_h is a contraction in $L^{\infty}(\Omega)$ with rate of contraction $2/(2 + \beta\theta(1 - 2\theta)\rho(A))$, where $\rho(A)$ is a spectral radius of operator A .

Proof. Under condition of stability, we have shown the θ -scheme is stable if and only if $\Delta t < (2C/(1 - 2\theta))h^2$.

Thus it can be easily show that

$$\begin{aligned}
\left\| \partial_h \left(F^{\theta,k}, r_h \psi \right) - \partial_h \left(\tilde{F}^{\theta,k}, r_h \tilde{\psi} \right) \right\|_{\infty} &\leq \frac{1}{1 + \beta \theta \Delta t} \|w - \tilde{w}\|_{\infty} \\
&\leq \frac{2}{2 + \beta \theta (1 - 2\theta) \rho(A)} \|w - \tilde{w}\|_{\infty} \quad (4.18) \\
&\leq \frac{1}{1 + \beta \theta ((1 - 2\theta)/2Ch^2)} \|w - \tilde{w}\|_{\infty} \\
&= \frac{2Ch^2}{2Ch^2 + \beta \theta (1 - 2\theta)} \|w - \tilde{w}\|_{\infty},
\end{aligned}$$

also it can be found that

$$\begin{aligned}
\left\| \partial_h \left(F^{\theta,k}, r_h \psi \right) - \partial_h \left(\tilde{F}^{\theta,k}, r_h \tilde{\psi} \right) \right\|_{\infty} &\leq \frac{1}{1 + \beta \theta ((1 - 2\theta)/2Ch^2)} \|w - \tilde{w}\|_{\infty} \quad (4.19) \\
&= \frac{2Ch^2}{2Ch^2 + \beta \theta (1 - 2\theta)} \|w - \tilde{w}\|_{\infty},
\end{aligned}$$

thus the mapping T_h is a contraction in $L^{\infty}(\Omega)$ with rate of contraction $(2Ch^2)/(2Ch^2 + \beta\theta(1 - 2\theta))$. Therefore, T_h admits a unique fixed point which coincides with the solution of P.V.I (4.7)

$$\begin{aligned}
\|T_h(w) - T_h(\tilde{w})\|_{\infty} &\leq \frac{1}{\beta + \mu} \left\| F^{\theta,k} - \tilde{F}^{\theta,k} \right\|_{\infty} \\
&= \frac{1}{\beta + \mu} \left\| f^{\theta,k} + \mu w - f^{\theta,k} - \mu \tilde{w} \right\|_{\infty} \quad (4.20) \\
&\leq \frac{\mu}{\beta + \mu} \|w - \tilde{w}\|_{\infty} \\
&\leq \frac{1}{1 + \beta \theta \Delta t} \|w - \tilde{w}\|_{\infty}.
\end{aligned}$$

This completes the proof. $\square$

4.2. Discrete Algorithm

Starting from $u_h^0 = u_{0h}$ (initial data) and the $u_h^{\theta,1}$ solution of problem (4.7), we introduce the following discrete algorithm:

$$u_h^{\theta,k} = T_h u_h^{k-1}, \quad k = 1, \dots, n, \quad (4.21)$$

where $u_h^{\theta,k}$ is the solution of the problem (4.7).

Remark 4.4. If we choose $\theta = 1$ in (4.21), we get Bensoussan's algorithm. The idea of this choice has been studied by Boulbrachen (cf. [3]).

Proposition 4.5. *Under the previous hypotheses, one has the following estimate of convergence: if $\theta \geq 1/2$*

$$\|u_h^{\theta,k} - u_h^\infty\|_\infty \leq \left(\frac{1}{1 + \beta\theta\Delta t} \right)^k \|u_h^\infty - u_{h_0}\|_\infty, \quad (4.22)$$

and one has for

$$\|u_h^{\theta,k} - u_h^\infty\|_\infty \leq \left(\frac{2Ch^2}{2Ch^2 + \beta\theta(1 - 2\theta)} \right)^k \|u_h^\infty - u_{h_0}\|_\infty \quad \text{for } 0 \leq \theta < \frac{1}{2}. \quad (4.23)$$

Proof. we set a first case $\theta \geq 1/2$, and we have

$$\begin{aligned} u_h^\infty &= T_h u_h^\infty, \\ \|u_h^{\theta,1} - u_h^\infty\|_\infty &= \|T_h u_h^0 - T_h u_h^\infty\|_\infty \leq \left(\frac{1}{1 + \beta\theta\Delta t} \right) \|u_h^0 - u_h^\infty\|_\infty. \end{aligned} \quad (4.24)$$

for $k \geq 2$, we use the Bensoussan-Lions' algorithm ($u_h^k = T_h u_h^{k-1}$, $k = 1, \dots, n$) for a noncoercive elliptic quasivariational inequalities (cf., e.g., [2, 3]) for details.

We assume that

$$\|u_h^{\theta,k} - u_h^\infty\|_\infty \leq \left(\frac{1}{1 + \beta\theta\Delta t} \right)^k \|u_h^0 - u_h^\infty\|_\infty, \quad (4.25)$$

so

$$\|u_h^{\theta,k+1} - u_h^\infty\|_\infty = \|T_h u_h^k - T_h u_h^\infty\|_\infty \leq \left(\frac{1}{1 + \beta\theta\Delta t} \right) \|u_h^k - u_h^\infty\|_\infty, \quad (4.26)$$

thus

$$\|u_h^{\theta,k+1} - u_h^\infty\|_\infty \leq \left(\frac{1}{1 + \beta\theta\Delta t} \right)^{k+1} \|u_h^0 - u_h^\infty\|_\infty, \quad (4.27)$$

for a second case $0 \leq \theta < 1/2$, it can be easily shown that

$$\left\| u_h^{\theta,k} - u_h^\infty \right\|_\infty \leq \left(\frac{2Ch^2}{2Ch^2 + \beta\theta(1-2\theta)} \right)^k \left\| u_h^0 - u_h^\infty \right\|_\infty. \quad (4.28)$$

□

4.2.1. Asymptotic Behavior

This section is devoted to the proof of main result of the present paper, where we prove the theorem of the asymptotic behavior in L^∞ -norm for parabolic variational inequalities

Now, we evaluate the variation in L^∞ between $u_h^\theta(T, x)$, the discrete solution calculated at the moment $T = n\Delta t$ and u^∞ , the asymptotic continuous solution of (4.2)

Theorem 4.6 (The main result). *Under condition of Theorem 4.1 and Proposition 4.5, one has for the first case $\theta \geq 1/2$,*

$$\left\| u_h^{\theta,n} - u^\infty \right\|_\infty \leq C \left[h^2 |\log h|^2 + \left(\frac{1}{1 + \beta\theta\Delta t} \right)^n \right], \quad (4.29)$$

and for the second case $0 \leq \theta < 1/2$,

$$\left\| u_h^{\theta,n} - u^\infty \right\|_\infty \leq C \left[h^2 |\log h|^2 + \left(\frac{2Ch^2}{2Ch^2 + \beta\theta(1-2\theta)} \right)^n \right], \quad (4.30)$$

where C is a constant independent of h and k .

Proof. We have

$$u_h^{\theta,k}(x) = u_h(t, x) \quad \text{for } t \in](k-1)\Delta t; k\Delta t[, \quad (4.31)$$

thus

$$u_h^{\theta,n}(x) = u_h(T, x), \quad (4.32)$$

then

$$\begin{aligned} \left\| u_h^\theta(T, x) - u^\infty \right\|_{L^\infty(\Omega)} &= \left\| u_h^{\theta,n} - u^\infty \right\|_{L^\infty(\Omega)} \\ &\leq \left\| u_h^{\theta,n} - u_h^\infty \right\|_{L^\infty(\Omega)} + \left\| u_h^\infty - u^\infty \right\|_{L^\infty(\Omega)}. \end{aligned} \quad (4.33)$$

Using, Theorem 4.1 and Proposition 4.5, we have for $\theta \geq 1/2$,

$$\left\| u_h^{\theta,n} - u^\infty \right\|_\infty \leq C \left[h^2 |\log h|^2 + \left(\frac{1}{1 + \beta\theta\Delta t} \right)^n \right], \quad (4.34)$$

and for $0 \leq \theta < 1/2$, we have

$$\|u_h^{\theta,n} - u^\infty\|_\infty \leq C \left[h^2 |\log h|^2 + \left(\frac{2Ch^2}{2Ch^2 + \beta\theta(1-2\theta)} \right)^n \right]. \quad (4.35)$$

□

5. Conclusion

In this paper, we have introduced a new approach for the theta time scheme combined with a finite element spatial approximation of parabolic variational inequalities (P.V.I). We have given a simple result to time energy behavior and established a convergence and asymptotic behavior in uniform norm. The type of estimation, which we have obtained here, is important for the calculus of quasistationary state for the simulation of petroleum or gaseous deposit. A future paper will be devoted to the computation of this method, where efficient numerical monotone algorithms will be treated.

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