Research Article

Two New Types of Multiple Granulation Rough Set

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In the paper proposed two new types of the multiple granulation rough set models, where a target concept is approximated from two different kinds of views by using the equivalence classes induced by multiple granulations. A number of important properties of the two types of MGRS are investigated. From the properties, it can be found that Pawlak’s and Qian’s rough set models are special instances of those of our MGRS. Moreover, several important measures are presented in two types of MGRS, such as rough measure and quality of approximation. Furthermore, the relationship and difference are discussed carefully among Pawlak’s rough set, Qian’s MGRS, and two new types of MGRS. In order to illustrate our multiple granulations rough set model, some examples are considered, which are helpful for applying this theory in practical issues. One can get that the paper is meaningful both in the theory and in application for the issue of knowledge reduction in complex information systems.

1. Introduction

Rough set theory proposed by Pawlak [1–3] is an extension of the classical set theory and can be regarded as a soft computing tool to handle imprecision, vagueness, and uncertainty in data analysis. The theory has found its successive applications in the fields of pattern recognition [4], medical diagnosis [5], data mining [6–8], conflict analysis [9], algebra [10–12], and so on. Recently, the theory has generated a great deal of interest among more and more researchers.

The rough set theory is based upon the classification mechanism, from which the classification can be viewed as an equivalence relation, and knowledge granule induced by the equivalence relation can be viewed as a partition of the universe of discourse. In rough set theory, two classical sets, so-called lower and upper approximations or Pawlak’s rough approximations, a constructed and any subset of a universe of discourse can be expressed by them. In framework based on rough set theory, an attribute set is viewed as a granular space, which partitions the universe into some knowledge granules or elemental concepts. Partition, granulation, and approximation are the methods widely used in human reasoning [13, 14]. Rough set methodology presents a novel paradigm to deal with uncertainty and has been applied to feature selection [15], knowledge reduction [16–19], rule extraction [20–23], uncertainty reasoning [24, 25], and granular computing [26–31].

In practice, due to the existence of uncertainty and complexity of particular problem, the problem would not be settled perfectly by means of classical rough set. Therefore, it is vital to generalize the classical rough set model. To overcome this limitation, classical rough sets have been accomplished to several interesting and meaningful general models in recent years, which include rough set model based on tolerance relations [32], rough set model based on neighborhood operators [33], Bayesian rough set model [34], fuzzy rough set model [35], rough fuzzy set model [35], and fuzzy probabilistic rough set model [3, 9, 19, 36–45].

On the other hand, information granules have played a significant role in human cognitive processes. Information granules refer to pieces, classes, and groups divided in
accordance with characteristics and performances of complex information in the process of human understanding, reasoning, and decision making. Such information processing is called the information granulation. Zadeh firstly proposed and discussed the issue of fuzzy information granulation [46] in 1979. Then, the basic idea of information granulation has been applied to many fields, such as theory of rough sets [1, 2, 47], fuzzy sets [14, 48], and evidence theories [49], and a growing number of scholars are concerned about the discipline. In 1985, Hobbs proposed the concept of granularity [50]. Zadeh firstly presented the concept of granular computing [46] in the period from 1996 to 1997. At this time, granular computing has played a more and more important role in soft computing, knowledge discovery, and data mining, and ones have achieved a large amount of excellent results [19, 27, 30, 51–58].

However, in essence, the approximations in the past approaches are still based on a singleton granulation induced from an indiscernibility relation, which can be applied to knowledge representation in distributive systems and groups of intelligent agents. In view of granular computing, an equivalence relation on the universe can be regarded as a granulation, and a partition on the universe can be regarded as a granulation space [56, 59]. Hence, the classical rough set theory is based on a single granulation (only one equivalence relation). Note that any attribute set can induce a certain equivalence relation in an information system. In the literature, to more widely apply the rough set theory in practical applications, Qian et al. [60] extended Pawlak’s single-granulation rough set model to a multi-granulation rough set model (MGRS), where the set approximations are defined by multiple equivalence relations on the universe.

The main objective of this paper is to extend Pawlak’s single-granulation rough set model and Qian’s multigranulation rough set model (MGRS) to two new types of multiple granulation rough set model, where the set approximations are defined by using multiple equivalence relations on the universe. The rest of the paper is organized as follows. Some preliminary concepts in Pawlak’s rough set theory and main concepts in Qian’s MGRS are briefly reviewed in Section 2. In Sections 3 and 4, for an information system, based on multiple equivalence relations, two new types of multiple granulation rough set model are obtained, respectively, where a target concept is approximated from two different kinds of views by using the equivalence classes induced by multiple granulations. And a number of important properties of the two types of MGRS are investigated. It is shown that some of the properties of Pawlak’s and Qian’s rough set theory are special instances of those of our MGRS. Several important measures are presented in two types of MGRS, such as rough measure, quality of approximation. In Section 5, the relationship and difference are discussed among Pawlak’s rough set, Qian’s MGRS, and two new types of MGRS. Furthermore, to illustrate our multiple granulations rough set model, some examples are presented, which are helpful for applying this theory in practical issues. And finally, the paper is concluded by a summary and outlook for further research in Section 6.

## 2. Preliminaries

The following recalls necessary concepts and preliminaries required in the sequel of our work. Detailed description of the theory can be found in the literatures [1–3, 19, 60].

### 2.1. Pawlak’s Rough Set

The notion of information system (sometimes called data tables, attribute-value systems, knowledge representation systems, etc.) provides a convenient tool for the representation of objects in terms of their attribute values.

An information system is an ordered quadruple $\mathcal{I} = (U, AT, V, f)$, where

(i) $U = \{u_1, u_2, \ldots, u_n\}$ is a nonempty finite set of objects,

(ii) $AT = \{a_1, a_2, \ldots, a_p\}$ is a nonempty finite set of attributes,

(iii) $V = \bigcup_{a \in AT} V_a$ and $V_a$ is a domain of attribute $a$,

(iv) $f : U \times AT \rightarrow V$ is a function such that $f(u,a) \in V_a$, for every $a \in AT$, $x \in U$, called an information function.

An information system with the decision is a special case of information systems in which, among the attributes, we distinguish the ones called decision attribute. The other attributes are called condition attributes. Therefore, $\mathcal{F} = (U, C \cup \{d\}, V, f)$ and $C \cap \{d\} = \emptyset$, where sets $C$ and $\{d\}$ are the condition attributes and the decision attribute, respectively. Let $\mathcal{F} = (U, AT, V, f)$ be an information system, for $A \subseteq AT$, and denote

$$R_A = \{(u, v) \in U \times U \mid f(u,a) = f(v,a), \forall a \in A\}, \tag{1}$$

then $R_A$ is reflexive, symmetric, and transitive. So it is an equivalence relation on $U$.

Moreover, denote

$$[u]_A = \{v \in U \mid (u, v) \in R_A\},$$

$$U_A = \{[u]_A, \forall u \in U\}, \tag{2}$$

then $[u]_A$ is called the equivalence class of $u$, and $U_A$ is called the equivalence class set of $U$. For equivalence classes and equivalence relations, the following properties hold.

(i) If $B \subseteq A$, then $R_A \subseteq R_B$.

(ii) If $B \subseteq A$, then $[u]_B \subseteq [u]_A$.

(iii) If $v \in [u]_A$, then $[v]_A = [u]_A$.

For any subset $X \subseteq U$ and $A \subseteq AT$ in information system $\mathcal{F} = (U, AT, V, f)$, the Pawlak’s lower and upper approximations of $X$ with respect to equivalence relation $R_A$ could be defined as follows (see [1–3, 19]):

$$R_A(X) = \{u \in U \mid [u]_A \subseteq X\}, \tag{3}$$

$$\overline{R}_A(X) = \{u \in U \mid [u]_A \cap X \neq \emptyset\}.$$

The area of uncertainty or boundary is defined as

$$\text{Bnd}_A(X) = \overline{R}_A(X) - R_A(X). \tag{4}$$
To measure the imprecision and roughness of a rough set, Pawlak recommended that \( X \neq \emptyset \) has the ratio

\[
\rho_A (X) = 1 - \frac{|R_A (X)|}{|U|},
\]

which is called the rough measure of \( X \) by equivalence \( R_A \).

Furthermore, for an information system with the decision \( \mathcal{I} = (U, C \cup \{d\}, V, f) \) and \( A \subseteq C \), a frequently applied measure for the situation is the quality of approximation of \( R_d \) by \( R_A \), also called the degree of dependency. It is defined as

\[
y (A, d) = \frac{1}{|U|} \sum_{j=1}^{k} R_A (D_j),
\]

where \( R_d = \{(u, v) \in U \times U \mid g(u, d) = g(v, d)\} \), and \( U/d = \{[u]_d\} \), for all \( u \in U \) = \{\( D_1, D_2, \ldots, D_k \)\}.

2.2. Qian’s Multiple Granulation Rough Set. In the rough set model MGRS, unlike Pawlak’s rough set theory, a target concept is approximated through multiple partitions induced by multiple equivalence relations [60]. In the following, we recall the relevant concepts about MGRS, and the description in detail can be found in [60].

Suppose that \( \mathcal{I} = (U, A^T, V, f) \) is an information system, and \( P_1, P_2, \ldots, P_m \) are \( m \)-attribute subsets. A lower approximation and an upper approximation of \( X \) are related to \( P_1, P_2, \ldots, P_m \) by the following:

\[
\sum_{i=1}^{m} P_i X = \bigcup \{u \mid [u]_{P_i} \subseteq X, \text{ for some } i \leq m\},
\]

\[
\sum_{i=1}^{m} P_i X = \sim \bigcup \sum_{i=1}^{m} P_i (\sim X).
\]

Similarly, the boundary region in MGRS can be expressed as

\[
\text{Bnd}^{\sum_{i=1}^{m} P_i} (X) = \bigcup \sum_{i=1}^{m} P_i X \setminus \bigcup \sum_{i=1}^{m} P_i X.
\]

Figure 1 shows the difference between Pawlak’s rough set model and the MGRS model.

From the figure, we can find that the bias region is the lower approximation of a set \( X \) obtained by a single granulation \( P \cup Q \), which are expressed by the equivalence classed in the quotient set \( U/(P \cup Q) \), and the shadow region is the lower approximation of \( X \) induced by two granulations \( P + Q \), which are characterized by the equivalence classes in quotient set \( U/P \) and the quotient set \( U/Q \).

3. The First Type of Multiple Granulation Rough Set

In this section, we will propose the first type of multiple granulation rough set.
equivalence classes induced by multiequivalence relations in an information system, whereas Pawlak's lower and upper approximations are represented via those derived by only on equivalence relation.

One can understand the first two granulation rough set and show the difference between the Qian's MGRS and Pawlak's rough set through Figure 2.

Just from Definition 1, we can obtain the following properties in the 1st TGRS in an information system.

**Proposition 2.** Let \( J = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \) and \( X \subseteq U \). Then the following properties hold.

\[
\begin{align*}
(FL_1) \quad & FR_{A \cup B}(X) \subseteq X \quad \text{(Contraction)} \\
(FL_2) \quad & FR_{A \cup B}(X) \supseteq X \quad \text{(Extension)} \\
(FL_3) \quad & FR_{A \cup B}(\sim X) = \sim FR_{A \cup B}(X) \quad \text{(Duality)} \\
(FL_4) \quad & FR_{A \cup B}(U) = U \quad \text{(Conormality)} \\
(FL_5) \quad & FR_{A \cup B}(X) = FR_{B \cup A}(X) \quad \text{(Commutativity)} \\
(FL_6) \quad & FR_{A \cup B}(X) = FR_{B \cup A}(X) \quad \text{(Commutativity)}
\end{align*}
\]

Proof. It is obvious that all terms hold when \( A = B \). When \( A \neq B \), the proposition can be proved as follows.

(FL_1) For any \( u \in FR_{A \cup B}(X) \), it can be known that \([u]_A \subseteq X \) or \([u]_B \subseteq X \) by Definition 1. However, \( u \in [u]_A \) and \( u \in [u]_B \). So we can have \( u \in X \). Hence, \( FR_{A \cup B}(X) \subseteq X \).

(FU_1) For any \( u \in FR_{A \cup B}(X) \), we have \( u \in [u]_A \) and \( u \in [u]_B \). So \([u]_A \cap X \neq \emptyset \) and \([u]_B \cap X \neq \emptyset \), that is to say, \( u \in FR_{A \cup B}(X) \). Hence, \( X \subseteq FR_{A \cup B}(X) \).

(FU_2) For any \( u \in FR_{A \cup B}(\sim X) \), then

\[
\begin{align*}
& u \in FR_{A \cup B}(\sim X) \iff [u]_A \subseteq \sim X, \text{ or } [u]_B \subseteq \sim X, \\
& \iff [u]_A \cap X = \emptyset, \text{ or } [u]_B \cap X = \emptyset, \\
& \iff u \notin FR_{A \cup B}(X), \\
& \iff u \in \sim FR_{A \cup B}(X).
\end{align*}
\]

Hence, \( FR_{A \cup B}(\sim X) = \sim FR_{A \cup B}(X) \).

(FU_3) By (FL_2), we have \( FR_{A \cup B}(X) = \sim FR_{A \cup B}(\sim X) \). So it can be obtained that \( \sim FR_{A \cup B}(X) = \sim FR_{A \cup B}(\sim X) \). Thus, \( FR_{A \cup B}(0) = 0 \).

(FU_4) By (FL_2), we have \( FR_{A \cup B}(U) = FR_{A \cup B}(\sim 0) = \sim FR_{A \cup B}(0) = 0 \).

(FU_5) By (FL_2), we have \( FR_{A \cup B}(U) = FR_{A \cup B}(\sim 0) = \sim FR_{A \cup B}(0) = 0 \).

(FU_6) By (FL_2), we have \( FR_{A \cup B}(U) = FR_{A \cup B}(\sim 0) = \sim FR_{A \cup B}(0) = 0 \).

In order to discover the relationship between the 1st TGRS approximations of a single set and the 1st TGRS approximations of two sets described on the universe, the following properties are given.

**Proposition 3.** Let \( J = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \) and \( X, Y \subseteq U \). Then the following properties hold.

\[
\begin{align*}
(FL_7) \quad & FR_{A \cup B}(X \cap Y) \subseteq FR_{A \cup B}(X) \cap FR_{A \cup B}(Y) \quad \text{(L-Multiplication)} \\
(FL_8) \quad & FR_{A \cup B}(X \cup Y) \supseteq FR_{A \cup B}(X) \cup FR_{A \cup B}(Y) \quad \text{(L-Addition)} \\
(FL_9) \quad & FR_{A \cup B}(X \cup Y) \subseteq FR_{A \cup B}(X) \cup FR_{A \cup B}(Y) \quad \text{(Granularity)} \\
(FL_{10}) \quad & FR_{A \cup B}(X \cup Y) \supseteq FR_{A \cup B}(X) \cup FR_{A \cup B}(Y) \quad \text{(Granularity)} \\
(FL_{11}) \quad & FR_{A \cup B}(X \cap Y) \subseteq FR_{A \cup B}(X) \cap FR_{A \cup B}(Y) \quad \text{(U-Multiplication)}
\end{align*}
\]

Proof. It is obvious that all terms hold when \( A = B \) or \( X = Y \). When \( A \neq B \) and \( X \neq Y \), the proposition can be proved as follows.

(FL_7) For any \( u \in FR_{A \cup B}(X \cap Y) \), we have that \([u]_A \subseteq (X \cap Y) \) or \([u]_B \subseteq (X \cap Y) \) by Definition 1. Then, it can be obtained that \([u]_A \subseteq X \) and \([u]_B \subseteq Y \) hold at the same time or \([u]_B \subseteq X \) and \([u]_B \subseteq Y \) hold at the same time. So, not only \([u]_A \subseteq X \) or \([u]_B \subseteq Y \) hold, but \([u]_A \subseteq Y \) or \([u]_B \subseteq X \) hold.
hold at the same time. That is to say that \( u \in FR_{A+B}(X) \) and \( u \in FR_{A+B}(Y) \), that is, \( u \in FR_{A+B}(X) \cap FR_{A+B}(Y) \).

Hence, \( FR_{A+B}(X \cap Y) \subseteq FR_{A+B}(X) \cap FR_{A+B}(Y) \).

\[ (FU_g) \text{ For any } u \in FR_{A+B}(X) \cup FR_{A+B}(Y), \text{ we have } u \in FR_{A+B}(X) \text{ or } u \in FR_{A+B}(Y). \]

Then \( [u_A \cap X \neq \emptyset \text{ and } [u_B \cap Y \neq \emptyset \text{ hold at the same time or } [u_A \cap Y \neq \emptyset \text{ and } [u_B \cap Y \neq \emptyset \text{ hold at the same time. So, not only } [u_A \cap (X \cup Y) \neq \emptyset \text{ hold, but } [u_B \cap (X \cup Y) \neq \emptyset \text{ hold. That is to say } u \in FR_{A+B}(X \cup Y). \]

Hence, \( FR_{A+B}(X \cup Y) \supseteq FR_{A+B}(X) \cup FR_{A+B}(Y). \)

\[ (FL_g) \text{ Since } X \subseteq Y, \text{ one can have } X \cap Y = X. \text{ Then, } \]
\[ FR_{A+B}(X \cap Y) = FR_{A+B}(X). \]

Besides, it can be found that \( FR_{A+B}(X \cap Y) \subseteq FR_{A+B}(X) \cap FR_{A+B}(Y) \) by \( (FL_g). \) So, we can obtain that \( FR_{A+B}(X) \subseteq FR_{A+B}(X) \cap FR_{A+B}(Y) \), that is to say that \( FR_{A+B}(X) = FR_{A+B}(X) \cap FR_{A+B}(Y). \)

Thus, \( FR_{A+B}(X) \subseteq FR_{A+B}(Y). \)

\[ (FU_g) \text{ Since } X \subseteq X \cup Y \text{ and } Y \subseteq X \cup Y, \text{ by } (FL_g) \text{ it can be obtained that } \]
\[ FR_{A+B}(X) \subseteq FR_{A+B}(X \cup Y), \]
\[ FR_{A+B}(Y) \subseteq FR_{A+B}(X \cup Y). \]

So, we have \( FR_{A+B}(X) \cup FR_{A+B}(Y) \subseteq FR_{A+B}(X \cup Y). \)

\[ (FU_g) \text{ Since } X \cap Y \subseteq X \text{ and } X \cap Y \subseteq Y, \text{ by } (FU_g) \text{ it can be obtained that } \]
\[ FR_{A+B}(X \cap Y) \subseteq FR_{A+B}(X), \]
\[ FR_{A+B}(Y \cap Y) \subseteq FR_{A+B}(Y). \]

So, we have \( FR_{A+B}(X \cap Y) \subseteq FR_{A+B}(X) \cap FR_{A+B}(Y). \)

The proposition was proved. \( \square \)

Here, we employ an example to illustrate the previous concepts and properties with respect to the 1st TGRS.

Example 4. Table 1 depicts an information system containing some information about an emporium investment project.

Locus, investment, and population density are the conditional attributes of the systems, whereas Decision is the decision attribute. In the sequel, \( L, I, P, \) and \( D \) will stand for locus, investment, population density and \{Decision\}, respectively. The domains are as follows: \( V_L = \{ B—Bad, C—Common, G—Good, G’—Better \}, \)
\( V_I = \{ H—High, L—Low \}, \)
\( V_P = \{ B—Big, S—Small, M—Medium \}, \)
and \( V_D = \{ Y—Yes, N—No \}. \)

From the table, we can find that
\[ R_L = \{ [u_1, u_5], [u_2, u_6], [u_3, u_4], [u_5, u_8], \}
\[ R_P = \{ [u_1, u_2], [u_3, u_4, u_5], [u_6, u_7, u_8], \}
\[ R_{LP} = \{ [u_1], [u_2], [u_3, u_4], [u_5], [u_6], [u_7], [u_8]. \]

And, if we take \( X = \{ u_1, u_2, u_6, u_8 \}, \) then by computing we have
\[ FR_{LP}(X) = \{ u_1, u_2, u_6, u_8 \}, \]
\[ FR_{LP}(X) = \{ u_1, u_2, u_6, u_7, u_8 \}. \]

However, the lower approximation and upper approximation of \( X \) based on Pawlak’s rough set are
\[ R_L(X) = \{ u_1, u_8 \}, \]
\[ R_P(X) = \{ u_1, u_2, u_5, u_6, u_7, u_8 \}, \]
\[ R_{LP}(X) = \{ u_1, u_2, u_6, u_7, u_8 \}, \]
\[ R_{LP}(X) = \{ u_1, u_2, u_6, u_8 \}. \]

Obviously, one can check the following properties.
\[ R_L(X) \cup R_P(X) = FR_{LP}(X), \]
\[ R_L(X) \cap R_P(X) = FR_{LP}(X), \]
\[ FR_{LP}(X) \subseteq R_{LP}(X) \subseteq X \subseteq R_{LP}(X) \subseteq FR_{LP}(X). \]

3.2. The First Type of Multiple Granulation Rough Set. In this subsection, we will consider the first type of multiple granulation approximations of a target set by using multiple equivalence relations in an information system.

Definition 5. Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_1, A_2, \ldots, A_s \subseteq AT \) be attribute subsets \( s \leq 2^{AT} \), and \( R_{A_1}, R_{A_2}, \ldots, R_{A_s} \) be equivalence relations, respectively. The operators \( FR_{\sum_{i=1}^{s} A_i} \) and \( FR_{\sum_{i=1}^{s} A_i} : \mathcal{P}(U) \to \mathcal{P}(U) \) are defined as follows. For all \( X \in \mathcal{P}(U), \)
\[ FR_{\sum_{i=1}^{s} A_i}(X) = \left\{ u \mid \bigvee_{i=1}^{m} \left( [u]_{A_i} \subseteq X \right) \right\}, \]
\[ FR_{\sum_{i=1}^{s} A_i}(X) = \left\{ u \mid \bigcup_{i=1}^{m} \left( [u]_{A_i} \cap X \neq \emptyset \right) \right\}, \]
where “\( \vee \)” means "some", and “\( \wedge \)” means "all". We call them the first type of multiple granulation lower and upper approximation operators, and we call \( FR_{\sum_{i=1}^{s} A_i}(X) \) and \( FR_{\sum_{i=1}^{s} A_i}(X) \) the first type of multiple granulation lower approximation set and upper approximation of \( X \), respectively.

Moreover, if \( FR_{\sum_{i=1}^{s} A_i}(X) \neq FR_{\sum_{i=1}^{s} A_i}(X) \), we say that \( X \) is the first type of definable set with respect to these multiple granulation spaces.
Similarly, the area of uncertainty or boundary region of this rough set is defined as
\[
\text{Bnd}^F_{\Sigma_{i=1}^s, A_i} (X) = FR^{\Sigma_{i=1}^s, A_i}_{s}(X) - FR^{\Sigma_{i=1}^r, A_i}_{r}(X).
\]

To describe conveniently the ideas in our context, we express the first type of multiple granular rough set by using the 1st MGRS. Moreover, one can obtain the following properties of the 1st MGRS approximations.

**Proposition 6.** Let \( \mathcal{I} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then the following properties hold.
\[
\begin{align*}
(F_{L_{1}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \subseteq X \quad \text{(Contraction)}, \\
(F_{U_{1}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(X) \supseteq X \quad \text{(Extension)}, \\
(F_{L_{2}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(\sim X) = \sim FR^{\Sigma_{i=1}^r, A_i}_{r}(X) \quad \text{(Duality)}, \\
(F_{U_{2}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(\sim X) = \sim FR^{\Sigma_{i=1}^r, A_i}_{r}(X) \quad \text{(Duality)}, \\
(F_{L_{3}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(\emptyset) = 0 \quad \text{(Normality)}, \\
(F_{U_{3}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(\emptyset) = 0 \quad \text{(Normality)}, \\
(F_{L_{4}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(U) = U \quad \text{(Conormality)}, \\
(F_{U_{4}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(U) = U \quad \text{(Conormality)}, \\
(F_{L_{5}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(X) = FR_{R^1 A}(X) \quad \text{(Commutativity)}, \\
(F_{U_{5}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(X) = FR_{R^1 A}(X) \quad \text{(Commutativity)}.
\end{align*}
\]

**Proof.** The proof of these items is similar to Proposition 2. \qed

**Proposition 7.** Let \( \mathcal{I} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \) and \( X, Y \subseteq U \). Then the following properties hold.
\[
\begin{align*}
(F_{L_{6}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{s}(X \cap Y) \subseteq FR^{\Sigma_{i=1}^r, A_i}_{r}(X) \cap FR^{\Sigma_{i=1}^r, A_i}_{r}(Y) \quad \text{(L-Multiplication)}, \\
(F_{U_{6}}) & \quad FR^{\Sigma_{i=1}^s, A_i}_{r}(X \cup Y) \supseteq FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \cup FR^{\Sigma_{i=1}^s, A_i}_{s}(Y) \quad \text{(L-Addition)}, \\
(F_{L_{7}}) & \quad X \subseteq Y \Rightarrow FR^{\Sigma_{i=1}^s, A_i}_{s}(Y) \subseteq FR^{\Sigma_{i=1}^r, A_i}_{r}(X) \quad \text{(Granularity)}, \\
(F_{U_{7}}) & \quad X \subseteq Y \Rightarrow FR^{\Sigma_{i=1}^r, A_i}_{r}(Y) \subseteq FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \quad \text{(Granularity)},
\end{align*}
\]

\text{(FU) } X \subseteq Y \Rightarrow FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \subseteq FR^{\Sigma_{i=1}^r, A_i}_{r}(Y) \quad \text{(Granularity)},

\text{(FU) } FR^{\Sigma_{i=1}^s, A_i}_{r}(X \cup Y) \supseteq FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \cup FR^{\Sigma_{i=1}^s, A_i}_{s}(Y) \quad \text{(U-Addition)},

\text{(FU) } FR^{\Sigma_{i=1}^s, A_i}_{r}(X \cap Y) \subseteq FR^{\Sigma_{i=1}^s, A_i}_{s}(X) \cap FR^{\Sigma_{i=1}^s, A_i}_{s}(Y) \quad \text{(U-Multiplication)}.

**Proof.** The proof of these items is similar to Proposition 3. \qed

Next, we will investigate several elementary measures in the 1st MGRS and their properties.

Uncertainty of a set (category) is due to the existence of a borderline region. The bigger the borderline region of a set is, the lower the accuracy of the set is (and vice versa). To more precisely express this idea, we introduce the accuracy measure to the 1st MGRS as follows.

**Definition 8.** Let \( \mathcal{I} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). The 1st rough measure of \( X \) by \( \Sigma_{i=1}^s A_i \) is defined as
\[
\rho^{F}_{\Sigma_{i=1}^s, A_i}(X) = 1 - \frac{FR^{\Sigma_{i=1}^r, A_i}_{r}(X)}{FR^{\Sigma_{i=1}^s, A_i}_{s}(X)},
\]
where \( X \neq \emptyset \).

From the definitions, one can derive the following properties.

**Proposition 9.** Let \( \mathcal{I} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then
\[
\rho_{A_i}(X) \geq \rho^{F}_{\Sigma_{i=1}^s, A_i}(X) \geq \rho^{R}_{\Sigma_{i=1}^r, A_i}(X).
\]

**Proof.** By Corollary 32, we have
\[
\begin{align*}
R^{F}_{A_i}(X) & \subseteq FR^{\Sigma_{i=1}^s, A_i}_{s}(X), \\
R^{F}_{A_i}(X) & \supseteq FR^{\Sigma_{i=1}^r, A_i}_{r}(X).
\end{align*}
\]
And by Corollary 40, we have
\[
\begin{align*}
FR^{\Sigma_{i=1}^s, A_i}_{s}(X) & \subseteq R^{F}_{\Sigma_{i=1}^r, A_i}_{r}(X), \\
FR^{\Sigma_{i=1}^s, A_i}_{s}(X) & \supseteq R^{F}_{\Sigma_{i=1}^r, A_i}_{r}(X).
\end{align*}
\]

---

**Table 1:*** An information system about emporium investment project.

<table>
<thead>
<tr>
<th>Project</th>
<th>Locus</th>
<th>Investment</th>
<th>Population density</th>
<th>Decision</th>
</tr>
</thead>
<tbody>
<tr>
<td>( u_1 )</td>
<td>C</td>
<td>L</td>
<td>B</td>
<td>N</td>
</tr>
<tr>
<td>( u_2 )</td>
<td>G(^c)</td>
<td>H</td>
<td>B</td>
<td>Y</td>
</tr>
<tr>
<td>( u_3 )</td>
<td>B</td>
<td>L</td>
<td>S</td>
<td>N</td>
</tr>
<tr>
<td>( u_4 )</td>
<td>B</td>
<td>H</td>
<td>S</td>
<td>N</td>
</tr>
<tr>
<td>( u_5 )</td>
<td>G</td>
<td>L</td>
<td>S</td>
<td>N</td>
</tr>
<tr>
<td>( u_6 )</td>
<td>G</td>
<td>H</td>
<td>M</td>
<td>Y</td>
</tr>
<tr>
<td>( u_7 )</td>
<td>C</td>
<td>H</td>
<td>M</td>
<td>Y</td>
</tr>
<tr>
<td>( u_8 )</td>
<td>G(^c)</td>
<td>H</td>
<td>M</td>
<td>Y</td>
</tr>
</tbody>
</table>
So, the following hold:

\[
\frac{|R_{A_i}(X)|}{|A_i(X)|} \leq \frac{|FR_{\Sigma_{i=1}^s A_i}(X)|}{|FR_{\Sigma_{i=1}^s A_i}(X)|} \leq \frac{|R'_{\Sigma_{i=1}^s A_i}(X)|}{|R'_{\Sigma_{i=1}^s A_i}(X)|}.
\] (24)

Hence, by the Definition 8, we have

\[
\rho_{A_i}(X) \geq \rho_{FR_{\Sigma_{i=1}^s A_i}}(X) \geq \rho_{R'_{\Sigma_{i=1}^s A_i}}(X).
\] (25)

The proof was completed. \(\Box\)

Example 10 (continued from Example 4). Computing the 1st rough measures of \(X = \{u_1, u_2, u_6, u_8\}\) by using the results in Example 4, it follows that

\[
\rho_L(X) = 1 - \frac{|R_L(X)|}{|L|} = \frac{2}{3},
\]

\[
\rho_P(X) = 1 - \frac{|R_P(X)|}{|P|} = \frac{3}{5},
\] (26)

\[
\rho_{L\cup P}(X) = 1 - \frac{|R_{L\cup P}(X)|}{|L\cup P|} = 0,
\]

\[
\rho_{FR_{L\cup P}}(X) = 1 - \frac{|FR_{L\cup P}(X)|}{|FR_{L\cup P}(X)|} = \frac{2}{5}.
\]

Clearly, it follows from the earlier computation that

\[
\rho_L(X) \geq \rho_{FR_{L\cup P}}(X) \geq \rho_{L\cup P}(X),
\] (27)

\[
\rho_P(X) \geq \rho_{FR_{L\cup P}}(X) \geq \rho_{L\cup P}(X).
\]

Note that the rough measure of a target concept defined by using multiple granulations is always much better than that defined by using a single granulation, which is suitable for more precisely characterizing a target concept and problem solving according to user requirements.

Definition II. Let \(\mathcal{I} = (U, C \cup \{d\}, V, f)\) be a decision table, \(A_j \subseteq C, i = 1, 2, \ldots, s\), and \(\{D_1, D_2, \ldots, D_k\}\) be all decision classes induced by decision attribute \(d\). Approximation quality of \(d\) by \(\sum_{i=1}^s A_i\), called the 1st degree of dependence, is defined as

\[
\gamma_F \left( \sum_{i=1}^s A_i, d \right) = \frac{1}{|U|} \sum_{j=1}^k \left| FR_{\sum_{i=1}^s A_i}(D_j) \right|.
\] (28)

This measure can be used to evaluate the deterministic part of the rough set description of \(U/d\) by counting those objects which can be reclassified as blocks of \(U/d\) with the knowledge given by \(\sum_{i=1}^s A_i\). Moreover, we have the following properties with respect to the above definition.

**Proposition 12.** Let \(\mathcal{I} = (U, C \cup \{d\}, V, f)\) be a decision table, \(A_i \subseteq C, i = 1, 2, \ldots, s\), and let \(\{D_1, D_2, \ldots, D_k\}\) be all decision classes induced by decision attribute \(d\). Then

\[
\gamma(A_i, d) \leq \gamma_F \left( \sum_{i=1}^s A_i, d \right) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\] (29)

**Proof.** For every \(D_j, j = 1, 2, \ldots, k\), by Corollaries 32 and 40, we have

\[
R_{A_j}(D_j) \subseteq FR_{\sum_{i=1}^s A_i}(D_j) \subseteq R_{R'_{\sum_{i=1}^s A_i}}(D_j).
\] (30)

So,

\[
\left| R_{A_j}(D_j) \right| \leq \left| FR_{\sum_{i=1}^s A_i}(D_j) \right| \leq \left| R_{R'_{\sum_{i=1}^s A_i}}(D_j) \right|.
\] (31)

Hence, by Definition II, we have

\[
\gamma(A_i, d) \leq \gamma_F \left( \sum_{i=1}^s A_i, d \right) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\] (32)

The proof was completed. \(\Box\)

Example 13 (continued from Example 4). Computing the degree of dependence of \(X = \{u_1, u_2, u_6, u_8\}\).

From Table 1, we can have \(U/D = \{D_Y, D_N\}\) and

\[
D_Y = \{u_2, u_6, u_7, u_8\},
\]

\[
D_N = \{u_1, u_3, u_4, u_5\}.
\] (33)

Moreover, the following can be computed by Table 1 and the results of Example 4,

\[
R_L(D_Y) = \{u_2, u_8\},
\]

\[
R_P(D_Y) = \{u_6, u_7, u_8\},
\]

\[
R_{L\cup P}(D_Y) = \{u_2, u_6, u_7, u_8\},
\]

\[
FR_{L\cup P}(D_Y) = \{u_2, u_6, u_7, u_8\},
\]

\[
R_L(D_N) = \{u_3, u_4\},
\]

\[
R_P(D_N) = \{u_3, u_4, u_5\},
\]

\[
R_{L\cup P}(D_N) = \{u_1, u_3, u_4, u_5\},
\]

\[
FR_{L\cup P}(D_N) = \{u_3, u_4, u_5\}.
\]

So, we have

\[
\gamma(L, D) = \frac{1}{|U|} \left( |R_L(D_Y)| + |R_L(D_N)| \right) = \frac{1}{2},
\]

\[
\gamma(P, D) = \frac{1}{|U|} \left( |R_P(D_Y)| + |R_P(D_N)| \right) = \frac{3}{4},
\]

\[
\gamma(L \cup P, D) = \frac{1}{|U|} \left( |R_{L\cup P}(D_Y)| + |R_{L\cup P}(D_N)| \right) = 1,
\]

\[
\gamma_F(L + P, D) = \frac{1}{|U|} \left( |FR_{L\cup P}(D_Y)| + |FR_{L\cup P}(D_N)| \right) = \frac{7}{8}.
\] (35)

Hence, it can be found that

\[
\gamma(L, D) \leq \gamma_F(L + P, D) \leq \gamma(L \cup P, D),
\]

\[
\gamma(P, D) \leq \gamma_F(L + P, D) \leq \gamma(L \cup P, D).
\] (36)
4. The Second Type of Multiple Granulation Rough Set

In this section, we will consider another multiple granulation rough set.

4.1. The Second Type of Two Granulation Rough Set. We first discuss the second type of two granulation approximations of a target set by using two equivalence relations in an information system.

Definition 14. Let \( \mathcal{F} = (U, AT, V, f) \) be an information system and \( A, B \subseteq AT \). The operators \( SR_{A+B} \) and \( SR_{A+B} : \mathcal{P}(U) \rightarrow \mathcal{P}(U) \) are defined as follows. For all \( X \in \mathcal{P}(U) \),

\[
FR_{A+B}(X) = \{ u | [u]_A \subseteq X, [u]_B \subseteq X \},
\]

\[
FR_{A+B}(X) = \{ u | [u]_A \cap X \neq \emptyset, \text{ or } [u]_B \cap X \neq \emptyset \}.
\]

We call them the second type of two granulation lower and upper approximation operators, and we call \( SR_{A+B}(X) \) and \( FR_{A+B}(X) \) the second type of two granulation lower approximation set and upper approximation of \( X \), respectively.

Moreover, if \( SR_{A+B}(X) \neq SR_{A+B}(X) \), we say that \( X \) is the second type of granulation with respect to two granulation spaces \( A \) and \( B \). Otherwise, we say that \( X \) is the second type of definable set with respect to two granulation spaces \( A \) and \( B \).

The area of uncertainty or boundary region of this rough set is defined as

\[
Bnd^S_{R_{A+B}}(X) = SR_{A+B}(X) - SR_{A+B}(X).
\]

It can be found that the second two granulation rough set will be Pawlak's rough set when two granulation spaces \( A \) and \( B \) satisfy \( A = B \). To describe conveniently in our context, we express the second type of two granulation rough set by using the 2nd TGRS.

By the previous definition, it can be seen that the second TGRS lower and upper approximations are consistent with Pawlak's rough set. Furthermore, one can find that the second TGRS lower and upper approximations are defined through using the equivalence classes induced by multi equivalence relations in an information system, whereas Pawlak's lower and upper approximations are represented by those derived by only one equivalence relation. And the 2nd TGRS lower and upper approximations are dual with the 2nd TGRS lower and upper approximations.

One can understand the second two granulation rough set and show the difference between the 1st TGRS and Pawlak's rough set through Figure 3.

Just from Definition 14, we can obtain the following properties in the 2nd TGRS in an information system.

Proposition 15. Let \( \mathcal{F} = (U, AT, V, f) \) be an information system, \( A, B \subseteq AT \) and \( X \subseteq U \). Then the following properties hold.

\[
(SL_1) \ SR_{A+B}(X) \subseteq X \quad (\text{Contraction}),
\]

\[
(SL_2) \ SR_{A+B}(~X) = ~SR_{A+B}(X) \quad (\text{Commutativity}),
\]

\[
(SU_1) \ SR_{A+B}(X) \supseteq X \quad (\text{Extension}),
\]

\[
(SU_2) \ SR_{A+B}(~X) = ~SR_{A+B}(X) \quad (\text{Duality}),
\]

\[
(SU_3) \ SR_{A+B}(\emptyset) = \emptyset \quad (\text{Normality}),
\]

\[
(SU_4) \ SR_{A+B}(U) = U \quad (\text{Conormality}),
\]

\[
(SU_5) \ SR_{A+B}(X) = SR_{B+A}(X) \quad (\text{Commutativity}),
\]

\[
(SUR_1) \ UA \subseteq X \longrightarrow [u]_A \subseteq X \quad (\text{Extension}),
\]

\[
(SUR_2) \ UB \subseteq X \longrightarrow [u]_B \subseteq X \quad (\text{Extension}),
\]

\[
(SUR_3) \ SA \subseteq UB \longrightarrow [u]_B \subseteq X \quad (\text{Extension}),
\]

\[
(SUR_4) \ SB \subseteq UA \longrightarrow [u]_A \subseteq X \quad (\text{Extension}),
\]

\[
(SUR_5) \ SU \subseteq AB \longrightarrow [u]_B \subseteq X \quad (\text{Extension}).
\]

Hence, \( SR_{A+B}(~X) = ~SR_{A+B}(X) \).
By \((SL_2)\), we have \(SR_{A+B}(X) = \overline{SR_{A+B}(\sim X)}\). So it can be obtained that \(\sim SR_{A+B}(X) = \overline{SR_{A+B}(\sim X)}\).

\((SL_3)\) From \((SL_2)\), we have \(SR_{A+B}(\emptyset) \subseteq \emptyset\). Besides, it is well known that \(\emptyset \subseteq SR_{A+B}(\emptyset)\). So, \(\overline{SR_{A+B}(\emptyset)} = \emptyset\).

\((SU_3)\) If \(\overline{SR_{A+B}(\emptyset)} \neq \emptyset\), then there must exist a \(u \in SR_{A+B}(\emptyset)\). So, we can find that \([u]_A \cap \emptyset \neq \emptyset\) or \([u]_B \cap \emptyset \neq \emptyset\). Obviously, this is a contradiction. Thus, \(\overline{SR_{A+B}(\emptyset)} = \emptyset\).

\((SU_4)\) \(\overline{SR_{A+B}(U)} = \overline{SR_{A+B}(\sim U)} = \overline{SR_{A+B}(\emptyset)} = \emptyset = U\). 

\((SU_5)\) \(\overline{SR_{A+B}(X)} = \overline{SR_{A+B}(\sim X)} = \overline{SR_{A+B}(\emptyset)} = \emptyset = U\). 

\((SL_5)\) and \((SU_3)\) can be proved directly by Definition 14.

In order to discover the relationship between the second TGRS approximations of a single set and the second TGRS approximations of two sets described on the universe, the following properties are given.

**Proposition 16.** Let \(\mathcal{F} = (U, AT, V, f)\) be an information system, \(A, B \subseteq AT\) and \(X, Y \subseteq U\). Then the following properties hold.

\((SL_6)\) \(SR_{A+B}(X \cap Y) = SR_{A+B}(X) \cap SR_{A+B}(Y)\) (L-Multiplication),

\((SU_6)\) \(\overline{SR_{A+B}(X \cup Y)} = \overline{SR_{A+B}(X)} \cup \overline{SR_{A+B}(Y)}\) (L-Addition),

\((SL_7)\) \(X \subseteq Y \Rightarrow SR_{A+B}(X) \subseteq SR_{A+B}(Y)\) (Granularity),

\((SU_7)\) \(X \subseteq Y \Rightarrow \overline{SR_{A+B}(X)} \subseteq \overline{SR_{A+B}(Y)}\) (Granularity),

\((SL_8)\) \(SR_{A+B}(X \cup Y) \supseteq \overline{SR_{A+B}(X)} \cup \overline{SR_{A+B}(Y)}\) (U-Addition),

\((SU_8)\) \(\overline{SR_{A+B}(X \cap Y)} \subseteq \overline{SR_{A+B}(X)} \cap \overline{SR_{A+B}(Y)}\) (U-Multiplication).

**Proof.** It is obvious that all terms hold when \(A = B\) or \(X = Y\). When \(A \neq B\) and \(X \neq Y\), the proposition can be proved as follows.

\((SL_6)\) For any \(u \in SR_{A+B}(X \cap Y)\), by Definition 18 we have

\[ u \in \overline{SR_{A+B}(X \cap Y)} \iff [u]_A \subseteq (X \cap Y), \quad [u]_B \subseteq (X \cap Y), \]

\[ \iff [u]_A \subseteq X, \quad [u]_B \subseteq Y, \]

\[ [u]_B \subseteq X, \quad [u]_B \subseteq Y, \]

\[ [u]_A \subseteq Y, \quad [u]_B \subseteq Y, \]

\[ \iff u \in SR_{A+B}(X), \quad u \in SR_{A+B}(Y), \]

\[ \iff u \in SR_{A+B}(X) \cap SR_{A+B}(Y). \] \hfill (40)

Hence, \(\overline{SR_{A+B}(X \cap Y)} = SR_{A+B}(X) \cap SR_{A+B}(Y)\).

\((SU_6)\) For any \(u \in SR_{A+B}(X \cup Y)\), by Definition 18 we have

\[ u \in \overline{SR_{A+B}(X \cup Y)} \iff [u]_A \cap (X \cup Y) \neq \emptyset, \quad [u]_B \cap (X \cup Y) \neq \emptyset, \]

\[ \iff [u]_A \cap X \neq \emptyset, \quad [u]_B \cap Y \neq \emptyset, \]

\[ or \quad [u]_B \cap X \neq \emptyset, \quad [u]_B \cap Y \neq \emptyset, \]

\[ \iff u \in SR_{A+B}(X), \quad or \quad u \in SR_{A+B}(Y), \]

\[ \iff u \in SR_{A+B}(X) \cup SR_{A+B}(Y). \] \hfill (41)

Hence, \(\overline{SR_{A+B}(X \cup Y)} = SR_{A+B}(X) \cup SR_{A+B}(Y)\).

\((SL_7)\) Since \(X \subseteq Y\), one can have \(X \cap Y = X\). Then, \(SR_{A+B}(X \cap Y) = SR_{A+B}(X)\). Besides, it can be found that \(\overline{SR_{A+B}(X \cap Y)} = \overline{SR_{A+B}(X)}\). So, we can obtain that \(SR_{A+B}(X) = SR_{A+B}(X) \cup SR_{A+B}(Y)\), that is to say that \(SR_{A+B}(X) \subseteq \overline{SR_{A+B}(Y)}\).

\((SU_7)\) Since \(X \subseteq Y\) and \(Y \subseteq X\), by \((SL_7)\) it can be obtained that

\[ SR_{A+B}(X) \subseteq SR_{A+B}(X \cup Y), \]

\[ \overline{SR_{A+B}(Y)} \subseteq SR_{A+B}(X \cup Y). \] \hfill (42)

So, we have \(\overline{SR_{A+B}(X \cup Y)} \subseteq \overline{SR_{A+B}(X)} \cap SR_{A+B}(X \cup Y)\).

\((SU_8)\) Since \(X \cap Y \subseteq X\) and \(X \cap Y \subseteq Y\), by \((SU_7)\) it can be obtained that

\[ \overline{SR_{A+B}(X \cap Y)} \subseteq \overline{SR_{A+B}(X)}, \]

\[ SR_{A+B}(Y) \subseteq \overline{SR_{A+B}(X \cap Y)}. \] \hfill (43)

So, we have \(\overline{SR_{A+B}(X \cap Y)} \subseteq \overline{SR_{A+B}(X)} \cap \overline{SR_{A+B}(X)}\).

The proposition was proved.

**Example 17** (continued from Example 4). In Example 4, we have known that

\[ R_k = \{ [u_1, u_7], [u_2, u_8], [u_3, u_4], [u_5, u_6] \}, \]

\[ R_p = \{ [u_1, u_2], [u_3, u_4, u_5], [u_6, u_7, u_8] \}, \]

\[ R_{LDP} = \{ [u_1], [u_2], [u_3, u_4], [u_5], [u_6], [u_7], [u_8] \}. \] \hfill (44)

And, if we take \(X = \{ u_1, u_2, u_6, u_8 \}\) again, then by computing we have

\[ \overline{SR_{LDP}(X)} = \{ u_6 \}, \]

\[ \overline{SR_{LDP}(X)} = \{ u_1, u_2, u_5, u_7, u_9 \}. \] \hfill (45)
However, the lower approximation and upper approximation of $X$ based on Pawlak’s rough set were obtained in Example 4 as follows:

$$R_L(X) = \{u_2,u_8\},$$
$$\overline{R}_L(X) = \{u_1,u_2,u_3,u_4,u_6,u_7,u_8\},$$
$$R_P(X) = \{u_1,u_2\},$$
$$\overline{R}_P(X) = \{u_1,u_2,u_6,u_7,u_8\},$$

(46)

So, one can check the following properties.

$$R_L(X) \cap R_P(X) = FR_{L+P}(X),$$
$$R_L(X) \cup R_P(X) = SR_{L+P}(X),$$

(47)

### 4.2. The Second Type of Multiple Granulation Rough Set

In this subsection, we will consider the second type of multiple granulation approximations of a target set by using multiple equivalence relations in an information system.

**Definition 18.** Let $\mathcal{I} = (U, AT, V, f)$ be an information system, $A_1, A_2, \ldots, A_s \subseteq AT$ attribute subsets ($s \leq 2^{\#AT}$), and $R_{A_1}, R_{A_2}, \ldots, R_{A_s}$ equivalence relations, respectively. The operators $SR_{\sum_{i=1}^{s} A_i}$ and $\overline{SR}_{\sum_{i=1}^{s} A_i}$, $\mathcal{P}(U) \rightarrow \mathcal{P}(U)$ are defined as follows. For all $X \in \mathcal{P}(U)$,

$$SR_{\sum_{i=1}^{s} A_i}(X) = \left\{ u \mid \sum_{i=1}^{m} \{[u]_{A_i} \subseteq X \} \right\},$$

(48)

$$\overline{SR}_{\sum_{i=1}^{s} A_i}(X) = \left\{ u \mid \sum_{i=1}^{m} \{[u]_{A_i} \cap X \neq \emptyset \} \right\},$$

where “$\vee$” means “some” and “$\wedge$” means “all.” We call them the second type of multiple granulation lower and upper approximation operators, and we call $SR_{\sum_{i=1}^{s} A_i}(X)$ and $\overline{SR}_{\sum_{i=1}^{s} A_i}(X)$ the second type of multiple granulation lower approximation set and upper approximation of $X$, respectively.

Moreover, if $SR_{\sum_{i=1}^{s} A_i}(X) \neq \overline{SR}_{\sum_{i=1}^{s} A_i}(X)$, we say that $X$ is the second type of rough set with respect to multiple granulation spaces $A_1, A_2, \ldots, A_s$. Otherwise, we say that $X$ is the second type of definable set with respect to these multiple granulation spaces.

Similarly, the area of uncertainty or boundary region of this rough set is defined as

$$Bnd_{\sum_{i=1}^{s} A_i}(X) = SR_{\sum_{i=1}^{s} A_i}(X) - \overline{SR}_{\sum_{i=1}^{s} A_i}(X).$$

To describe conveniently in our context, we express the second type of multiple granulation rough set by using the 2nd MGRS. Moreover, one can obtain the following properties of the 2nd MGRS approximations.

**Proposition 19.** Let $\mathcal{I} = (U, AT, V, f)$ be an information system, $A_i \subseteq AT$, $i = 1, 2, \ldots, s$, and $X \subseteq U$. Then the following properties hold.

1. $SR_{\sum_{i=1}^{s} A_i}(X) \subseteq X$ (Contraction),
2. $SR_{\sum_{i=1}^{s} A_i}(X) \supseteq X$ (Extension),
3. $SR_{\sum_{i=1}^{s} A_i}(\sim X) = \sim SR_{\sum_{i=1}^{s} A_i}(X)$ (Duality),
4. $SR_{\sum_{i=1}^{s} A_i}(\sim X) = \sim SR_{\sum_{i=1}^{s} A_i}(X)$ (Duality),
5. $SR_{\sum_{i=1}^{s} A_i}(\emptyset) = \emptyset$ (Normality),
6. $SR_{\sum_{i=1}^{s} A_i}(\emptyset) = \emptyset$ (Normality),
7. $SR_{\sum_{i=1}^{s} A_i}(U) = U$ (Conormality),
8. $SR_{\sum_{i=1}^{s} A_i}(U) = U$ (Conormality),
9. $SR_{\sum_{i=1}^{s} A_i}(X) = SR_{RS-A}(X)$ (Commutativity),
10. $SR_{\sum_{i=1}^{s} A_i}(X) = SR_{RS-A}(X)$ (Commutativity).

**Proof.** The proof of these items is similar to Proposition 15.

**Proposition 20.** Let $\mathcal{I} = (U, AT, V, f)$ be an information system, $A_i \subseteq AT$, $i = 1, 2, \ldots, s$, and $X, Y \subseteq U$. Then the following properties hold.

1. $SR_{\sum_{i=1}^{s} A_i}(X \cap Y) \subseteq SR_{\sum_{i=1}^{s} A_i}(X) \cap SR_{\sum_{i=1}^{s} A_i}(Y)$ (L-Multiplication),
2. $SR_{\sum_{i=1}^{s} A_i}(X \cup Y) \supseteq SR_{\sum_{i=1}^{s} A_i}(X) \cup SR_{\sum_{i=1}^{s} A_i}(Y)$ (L-Addition),
3. $X \subseteq Y \Rightarrow SR_{\sum_{i=1}^{s} A_i}(X) \subseteq SR_{\sum_{i=1}^{s} A_i}(Y)$ (Granularity),
4. $X \subseteq Y \Rightarrow SR_{\sum_{i=1}^{s} A_i}(X) \subseteq SR_{\sum_{i=1}^{s} A_i}(Y)$ (Granularity),
5. $SR_{\sum_{i=1}^{s} A_i}(X) \cup Y) \supseteq SR_{\sum_{i=1}^{s} A_i}(X) \cup SR_{\sum_{i=1}^{s} A_i}(Y)$ (U-Multiplication),
6. $SR_{\sum_{i=1}^{s} A_i}(X \cap Y) \supseteq SR_{\sum_{i=1}^{s} A_i}(X) \cap SR_{\sum_{i=1}^{s} A_i}(Y)$ (U-Addition).

**Proof.** The proof of these items is similar to Proposition 16.

Next, we will investigate several elementary measures in the 2nd MGRS and their properties.

Similarly, we introduce the accuracy measure to the 2nd MGRS as follows.

**Definition 21.** Let $\mathcal{I} = (U, AT, V, f)$ be an information system, $A_i \subseteq AT$, $i = 1, 2, \ldots, s$ and $X \subseteq U$. The 2nd rough measure of $X$ by $\sum_{i=1}^{s} A_i$ is defined as

$$\rho_{\sum_{i=1}^{s} A_i}(X) = 1 - \frac{|SR_{\sum_{i=1}^{s} A_i}(X)|}{|\overline{SR}_{\sum_{i=1}^{s} A_i}(X)|},$$

(50)

where $X \neq \emptyset$.

From the definitions, one can derive the following properties.
**Proposition 22.** Let \( \mathcal{F} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT \), \( i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then

\[
\rho_{\sum_{i=1}^s A_i}(X) \geq \rho_{A_i}(X) \geq \rho_{\sum_{i=1}^s A_i}(X).
\]  

(51)

**Proof.** By Corollary 34, we have

\[
\frac{SR_{\sum_{i=1}^s A_i}(X)}{SR_{\sum_{i=1}^s A_i}(X)} \leq \frac{R_{A_i}(X)}{R_{A_i}(X)} \leq \frac{R_{\sum_{i=1}^s A_i}(X)}{R_{\sum_{i=1}^s A_i}(X)}.
\]  

(52)

And, we have known that

\[
R_{A_i}(X) \subseteq R_{\sum_{i=1}^s A_i}(X),
\]

(53)

\[
R_{\sum_{i=1}^s A_i}(X) \supseteq R_{\sum_{i=1}^s A_i}(X).
\]

(54)

Hence, by the Definition 21, we have

\[
\rho_{\sum_{i=1}^s A_i}(X) \geq \rho_{A_i}(X) \geq \rho_{\sum_{i=1}^s A_i}(X).
\]  

(55)

The proof was completed. \( \Box \)

**Example 23** (continued from Examples 4 and 17). Computing the 2nd rough measures of \( X = \{u_1, u_2, u_6, u_8\} \) in the system given in Example 4. By Example 17, it follows that

\[
\rho_L(X) = 1 - \frac{|L_L(X)|}{|L(X)|} = \frac{2}{3},
\]

\[
\rho_P(X) = 1 - \frac{|P_P(X)|}{|P(X)|} = \frac{3}{5},
\]

\[
\rho_{L\cup P}(X) = 1 - \frac{|L\cup P(X)|}{|L\cup P(X)|} = 0,
\]

\[
\rho_{L+P}(X) = 1 - \frac{|SR_{L+P}(X)|}{|SR_{L+P}(X)|} = \frac{5}{6}.
\]

Clearly, it follows from the earlier computation that

\[
\rho_{L+P}(X) \geq \rho_{L}(X) \geq \rho_{L\cup P}(X),
\]

\[
\rho_{L+P}(X) \geq \rho_{P}(X) \geq \rho_{L\cup P}(X).
\]

(56)

Similar to the 1st MGRS, in the following we will discuss the 2nd degree of dependence.

**Definition 24.** Let \( \mathcal{F} = (U, C \cup \{d\}, V, f) \) be a decision table, \( A_i \subseteq C \), \( i = 1, 2, \ldots, s \), and \( \{D_1, D_2, \ldots, D_k\} \) all decision classes induced by decision attribute \( d \). Approximation quality of \( d \) by \( \sum_{i=1}^s A_i \), called the 2nd degree of dependence, is defined as

\[
\gamma_S \left( \sum_{i=1}^s A_i, d \right) = \frac{1}{|U|} \sum_{j=1}^k \left( \left| SR_{\sum_{i=1}^s A_i}(D_j) \right| \right).
\]

(58)

Moreover, we have the following properties with respect to the above definition.

**Proposition 25.** Let \( \mathcal{F} = (U, C \cup \{d\}, V, f) \) be a decision table, \( A_i \subseteq C \), \( i = 1, 2, \ldots, s \), and \( \{D_1, D_2, \ldots, D_k\} \) all decision classes induced by decision attribute \( d \). Then

\[
\gamma_S \left( \sum_{i=1}^s A_i, d \right) \leq \gamma(A_i, d) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\]

(59)

**Proof.** For every \( D_j \), \( j = 1, 2, \ldots, k \), by Corollaries 32 and 40, we have

\[
|SR_{\sum_{i=1}^s A_i}(D_j)| \subseteq |R_{A_i}(D_j)| \subseteq |R_{\sum_{i=1}^s A_i}(D_j)|.
\]

(60)

So,

\[
|SR_{\sum_{i=1}^s A_i}(D_j)| \leq |R_{A_i}(D_j)| \leq |R_{\sum_{i=1}^s A_i}(D_j)|.
\]

(61)

Hence, by the Definition 24, we have

\[
\gamma_S \left( \sum_{i=1}^s A_i, d \right) \leq \gamma(A_i, d) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\]

(62)

The proof was completed. \( \Box \)

**Example 26** (continued from Examples 4 and 17). Computing the 2nd degree of dependence of \( X = \{u_1, u_2, u_6, u_8\} \).

In Example 10, we have known that \( U/D = \{D_Y, D_N\} \) and

\[
\gamma(L, D) = \frac{1}{2},
\]

\[
\gamma(P, D) = \frac{3}{4},
\]

\[
\gamma(L \cup P, D) = 1.
\]

(63)

Moreover, the following can be computed by Table 1 and the results of Example 17,

\[
SR_{L+P}(D_Y) = \{u_8\},
\]

\[
SR_{L+P}(D_N) = \{u_3, u_4\}.
\]

(64)

So, we have

\[
\gamma_S(L + P, D) = \frac{1}{|U|} \left( |SR_{L+P}(D_Y)| + |SR_{L+P}(D_N)| \right) = \frac{3}{8}.
\]

(65)
Hence, it can be found that
\[
\gamma_S(L + P, D) \leq \gamma(L, D) \leq \gamma(L \cup P, D) \\
\gamma_S(L + P, D) \leq \gamma(P, D) \leq \gamma(L \cup P, D).
\] (66)

5. Difference and Relationship among Pawlak's Rough Set, and the 1st MGRS, the 2nd MGRS

From the previous sections, we have known the concepts and properties of the 1st MGRS and the 2nd MGRS. We will investigate the difference and relationship among Pawlak's rough set, the 1st MGRS, and the 2nd MGRS in this section.

Proposition 27. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( FR_{A \cup B}(X) \subseteq R_{A \cup B}(X), \)
2. \( FR_{A \cup B}(X) \supseteq R_{A \cup B}(X). \)

Proof. (1) For any \( u \in FR_{A \cup B}(X), \) it can be known that \([u]_A \subseteq X \) or \([u]_B \subseteq X \) by Definition 14. On the other hand, since \( A \subseteq A \cup B \) and \( B \subseteq A \cup B, \) we have \([u]_{A \cup B} \subseteq [u]_A \) and \([u]_{A \cup B} \subseteq [u]_B. \) So we can obtain that \([u]_{A \cup B} \subseteq X. \) That is to say that \( u \in R_{A \cup B}(X). \) Hence, \( FR_{A \cup B}(X) \subseteq R_{A \cup B}(X). \)

(2) For \( B, A \subseteq AT \) and \( X \subseteq U, \) we can obtain that \( R_{A \cup B}(X) \supseteq R_{A \cup B}(X). \) Then, it can be known that \( FR_{A \cup B}(X) \supseteq R_{A \cup B}(X) \) by the conclusion of (1). So, one can obtain that \( FR_{A \cup B}(X) \supseteq R_{A \cup B}(X). \)

The proof was completed. \( \square \)

Corollary 28. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( SR^{\Sigma \cdot A}(X) \subseteq R^{\Sigma \cdot A}(X), \)
2. \( SR^{\Sigma \cdot A}(X) \supseteq R^{\Sigma \cdot A}(X). \)

Proof. (1) For any \( u \in SR^{\Sigma \cdot A}(X) \), it can be known that \([u]_A \subseteq X \) and \([u]_B \subseteq X \) by Definition 14. On the other hand, since \( A \subseteq A \cup B \) and \( B \subseteq A \cup B, \) we have \([u]_{A \cup B} \subseteq [u]_A \) and \([u]_{A \cup B} \subseteq [u]_B. \) So we can obtain that \([u]_{A \cup B} \subseteq X. \) That is to say that \( u \in R_{A \cup B}(X). \) Hence, \( SR^{\Sigma \cdot A}(X) \subseteq R_{A \cup B}(X). \)

(2) For \( B, A \subseteq AT, \) and \( X \subseteq U, \) we can obtain that \( R_{A \cup B}(X) \supseteq R_{A \cup B}(X). \) Then, it can be known that \( SR^{\Sigma \cdot A}(X) \supseteq R_{A \cup B}(X) \) by the conclusion of (1). So, one can obtain that \( SR^{\Sigma \cdot A}(X) \supseteq R_{A \cup B}(X). \)

The proof was completed. \( \square \)

Corollary 30. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( SR^{\Sigma \cdot A_i}(X) \subseteq R^{\Sigma \cdot A_i}(X), \)
2. \( SR^{\Sigma \cdot A_i}(X) \supseteq R^{\Sigma \cdot A_i}(X). \)

Proposition 31. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( FR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cup R_B(X), \)
2. \( FR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cap R_B(X). \)

Proof. (1) For any \( u \in FR^{\Sigma \cdot A \cup B}(X), \) we have
\[
\text{we have } u \in FR^{\Sigma \cdot A \cup B}(X) \iff [u]_A \subseteq X, [u]_B \subseteq X,
\]
\[
\iff u \in R_A(X), u \in R_B(X), \quad (67)
\]
\[
\iff u \in R_A(X) \cup R_B(X).
\]

Hence, \( FR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cup R_B(X). \)

(2) For any \( u \in FR^{\Sigma \cdot A \cup B}(X), \) we have
\[
\text{we have } u \in FR^{\Sigma \cdot A \cup B}(X) \iff [u]_A \cap X \neq \emptyset, [u]_B \cap X \neq \emptyset
\]
\[
\iff u \in R_A(X), u \in R_B(X), \quad (68)
\]
\[
\iff u \in R_A(X) \cap R_B(X).
\]

Hence, \( FR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cap R_B(X). \)

The proof was completed. \( \square \)

Corollary 32. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( FR^{\Sigma \cdot A_i}(X) = R_A(X), \)
2. \( FR^{\Sigma \cdot A_i}(X) = R_A(X). \)

Proposition 33. Let \( \mathcal{S} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT, \) and \( X \subseteq U. \) Then, the following properties hold.

1. \( SR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cup R_B(X), \)
2. \( SR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cap R_B(X). \)

Proof. (1) For any \( u \in SR^{\Sigma \cdot A \cup B}(X), \) we have
\[
u \in SR^{\Sigma \cdot A \cup B}(X) \iff [u]_A \subseteq X, [u]_B \subseteq X,
\]
\[
\iff u \in R_A(X), u \in R_B(X), \quad (69)
\]
\[
\iff u \in R_A(X) \cap R_B(X).
\]

Hence, \( SR^{\Sigma \cdot A \cup B}(X) = R_A(X) \cap R_B(X). \)
For any \( u \in SR_{A+B}(X) \), we have
\[
\begin{align*}
&u \in SR_{A+B}(X) \iff [u]_A \cap X \neq \emptyset, \text{ or } [u]_B \cap X \neq \emptyset, \\
&\iff u \in R_A(X), \text{ or } u \in R_B(X), \\
&\iff u \in R_A(X) \cup R_B(X). 
\end{align*}
\]
Hence, \( SR_{A+B}(X) = R_A(X) \cup R_B(X) \).

The proof was completed. \( \square \)

**Corollary 34.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{\Sigma_i A_i}(X) = \bigcap_{i=1}^s R_{A_i}(X), \\
(2) & \quad SR_{\Sigma_i A_i}(X) = \bigcup_{i=1}^s R_{A_i}(X).
\end{align*}
\]

**Proposition 35.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \), and \( X, Y \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad FR_{A+B}(X \cap Y) = (R_A(X) \cap R_A(Y)) \cup (R_B(X) \cap R_B(Y)), \\
(2) & \quad FR_{A+B}(X \cup Y) = (R_A(X) \cup R_A(Y)) \cap (R_B(X) \cup R_B(Y)).
\end{align*}
\]

**Proof.** It can be obtained easily by Proposition 31. \( \square \)

**Corollary 36.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X, Y \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad FR_{\Sigma_i A_i}(X \cap Y) = \bigcup_{i=1}^s (R_{A_i}(X) \cap R_{A_i}(Y)), \\
(2) & \quad FR_{\Sigma_i A_i}(X \cup Y) = \bigcap_{i=1}^s (R_{A_i}(X) \cup R_{A_i}(Y)).
\end{align*}
\]

**Proposition 37.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \), and \( X, Y \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{A+B}(X \cap Y) = (R_A(X) \cap R_A(Y)) \cup (R_B(X) \cap R_B(Y)), \\
(2) & \quad SR_{A+B}(X \cup Y) = (R_A(X) \cup R_A(Y)) \cap (R_B(X) \cup R_B(Y)).
\end{align*}
\]

**Proof.** It can be obtained directly by Proposition 33. \( \square \)

**Corollary 38.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{\Sigma_i A_i}(X \cap Y) = \bigcap_{i=1}^s (R_{A_i}(X) \cap R_{A_i}(Y)), \\
(2) & \quad SR_{\Sigma_i A_i}(X \cup Y) = \bigcup_{i=1}^s (R_{A_i}(X) \cup R_{A_i}(Y)).
\end{align*}
\]

**Proposition 39.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{A+B}(X) \subseteq FR_{A+B}(X) \subseteq R_{A \cup B}(X), \\
(2) & \quad SR_{A+B}(X) \supseteq FR_{A+B}(X) \supseteq R_{A \cup B}(X).
\end{align*}
\]

**Proof.** It can be obtained easily by Definitions 1 and 14 and Propositions 27 and 29. \( \square \)

**Corollary 40.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{\Sigma_i A_i}(X) \subseteq FR_{\Sigma_i A_i}(X) \subseteq R_{\Sigma_i A_i}(X), \\
(2) & \quad SR_{\Sigma_i A_i}(X) \supseteq FR_{\Sigma_i A_i}(X) \supseteq R_{\Sigma_i A_i}(X).
\end{align*}
\]

**Proposition 41.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( B, A \subseteq AT \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{A+B}(X) \subseteq R_A(X) \lor R_B(X) \subseteq FR_{A+B}(X), \\
(2) & \quad SR_{A+B}(X) \supseteq R_A(X) \lor R_B(X) \supseteq FR_{A+B}(X).
\end{align*}
\]

**Proof.** It can be obtained easily by Propositions 31 and 33 \( \square \)

**Corollary 42.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then, the following properties hold.
\[
\begin{align*}
(1) & \quad SR_{\Sigma_i A_i}(X) \subseteq R_{A_i}(X) \lor R_{A_i}(X) \subseteq FR_{\Sigma_i A_i}(X), \\
(2) & \quad SR_{\Sigma_i A_i}(X) \supseteq R_{A_i}(X) \lor R_{A_i}(X) \supseteq FR_{\Sigma_i A_i}(X).
\end{align*}
\]

**Proposition 43.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then
\[
\begin{align*}
&\frac{s}{\sum_{i=1}^s A_i} \leq \gamma(A_i, d) \\
\leq &\frac{s}{\gamma_F} \left( \sum_{i=1}^s A_i \right) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\end{align*}
\]

**Proof.** It can be obtained directly by Definitions 8 and 21 and Corollary 42. \( \square \)

**Proposition 44.** Let \( \mathcal{J} = (U, AT, V, f) \) be an information system, \( A_i \subseteq AT, i = 1, 2, \ldots, s \), and \( X \subseteq U \). Then
\[
\begin{align*}
&\frac{s}{\sum_{i=1}^s A_i} \leq \gamma(A_i, d) \\
\leq &\frac{s}{\gamma_F} \left( \sum_{i=1}^s A_i \right) \leq \gamma \left( \bigcup_{i=1}^s A_i, d \right).
\end{align*}
\]

**Proof.** It can be obtained directly by Definitions 11 and 24 and Corollary 42. \( \square \)

One can understand the relationship and difference presented by the previous propositions through the following Figures 4 and 5.
14 ISRNApplied Mathematics

RA
RB
X
U
SRA+B(X)
FRA+B(X)
RA∪B(X)

Figure 4: Difference and relationship of lower approximations among the 1st, the 2nd TGRS, and classical RS.

SR_{L,P}(X) ⊆ FR_{L,P}(X) ⊆ R_{L,P}(X)

6. Conclusion

The original rough set model cannot be used to deal with the information systems with complicated context. Nevertheless, by relaxing the indiscernibility relation to more general binary relations, many improved rough set models have been successfully applied into the information systems with complicated context for knowledge acquisition. The contribution of this corresponding paper is to extend Pawlak’s single granulation rough set model and Qian’s multigranulation rough set model (MGRS) to two new types of the multiple granulation rough set model. In this paper, two new types of the multiple granulation rough set model have been constructed, respectively, based on multiple equivalence relations for an information system. In the two new types of multiple granulations rough set model, a target concept was approximated from two different kinds of views by using the equivalence classes induced from multiple granulations. In particular, some important properties of the two types of MGRS were investigated and have shown the relationship and difference among Pawlak’s rough set, Qian’s MGRS, and two new types of MGRS. Moreover, several important measures have been developed in two types of MGRS, such as rough measure and quality of approximation. From the contribution, it can be found that when two attribute sets in information systems possess a contradiction or an inconsistent relationship, or when efficient computation is required, the two new types of MGRS will display their advantage for rule extraction and knowledge discovery.

In our further research, we will extend other rough set methods in the context of multiple granulations such as viable precision rough set model and rough set induced by covering.

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