Research Article

Existence and Uniqueness of the Positive Definite Solution for the Matrix Equation $X = Q + A^*(\bar{X} - C)^{-1}A$

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We consider the nonlinear matrix equation $X = Q + A^*(\bar{X} - C)^{-1}A$, where $Q$ is positive definite, $C$ is positive semidefinite, and $\bar{X}$ is the block diagonal matrix defined by $\bar{X} = \text{diag}(X, X, \ldots, X)$. We prove that the equation has a unique positive definite solution via variable replacement and fixed point theorem. The basic fixed point iteration for the equation is given.

1. Introduction

We consider the matrix equation

$$X = Q + A^*(\bar{X} - C)^{-1}A,$$  

(1)

where $Q$ is an $n \times n$ positive definite matrix, $C$ is an $mn \times mn$ positive semidefinite matrix, $A$ is arbitrary $mn \times n$ matrix, and $\bar{X}$ is the block diagonal matrix defined by $\bar{X} = \text{diag}(X, X, \ldots, X)$ in which $X$ is an $n \times n$ matrix. This matrix equation is connected with certain interpolation problem (see [1]).

When $C = 0$, we write $A$ as the $m \times 1$ block matrix

$$A = \begin{pmatrix} A_1 \\ A_2 \\ \vdots \\ A_m \end{pmatrix},$$  

(2)

where $A_1, \ldots, A_m$ are $n \times n$ matrices. Then (1) is equal to $X = Q + \sum_{i=1}^m A_i^*X^{-1}A_i$, which has been investigated by many authors (see [2–9]). However, are few little theoretical results when $C \neq 0$. Ran and Reurings [1] have proved that (1) has a unique positive definite solution. Based on this, Sun [10] presented some perturbation results for the unique solution. Fixed point theorem is often used to discuss the existence and uniqueness of the solution. However, for (1), it is difficult to prove the uniqueness of the solution directly by using fixed point theorems. In this paper, we turn (1) into its equivalent equation via variable replacement. Then we consider its equivalent equation by using fixed point theorem. This provides a new proof for the existence and uniqueness of the positive definite solution. And this method is shown to be much easier than the way of [1]. In addition, the basic fixed point iteration for the equation is given.

In this paper we use $\mathfrak{C}(n)$ to denote $n \times n$ complex matrices, $\mathcal{P}(n)$ to denote $n \times n$ positive definite matrices, and $\mathcal{K}(n)$ to denote $n \times n$ positive semidefinite matrices. For $X, Y \in \mathcal{K}(n)$, we write $X \succeq Y$ ($X \succ Y$) if $X - Y$ is positive semidefinite (definite). $A^*$ denotes the conjugate transpose of a matrix $A$. Let $\lambda_{\max}(A^*A)$, $\lambda_{\min}(A^*A)$, $\lambda_{\max}(C)$, and $\lambda_{\min}(C)$.

2. The Case of $\bar{Q} > C$

In this section, we discuss (1) with $\bar{Q} > C$. Let $S_1(n) \subset P(n)$ be the set defined by

$$S_1(n) = \left\{ X \in P(n) \mid \bar{X} > C \right\}.$$  

(3)

We are interested in positive definite solutions of (1) in this set. A matrix $X$ is a solution of (1) if and only if it is a fixed point of the map $G_1$ defined by

$$G_1(X) = Q + A^*(\bar{X} - C)^{-1}A.$$  

(4)
Let $C_1 = \tilde{Q} - C$. For $\tilde{Q} > C$, we know that $C_1$ is a positive definite matrix. Then (1) turns into

$$X - Q = A^*(\tilde{X} - \tilde{Q} + C_1)^{-1}A.$$  (5)

Let $Y = X - Q$. Then (1) eventually becomes

$$Y = A^*(\tilde{Y} + C_1)^{-1}A.$$  (6)

In the following, we consider the existence and uniqueness of the positive definite solution of (6). And then we can easily get corresponding conclusions about (1).

**Theorem 1.** Equation (6) has a positive semidefinite solution for any $A \in \mathcal{C}(n)$.

*Proof.* A matrix $Y$ is a solution of (6) if and only if it is a fixed point of the map $F$ defined by $F(Y) = A^*(\tilde{Y} + C_1)^{-1}A$. Note that $F$ maps $[0, F(0)]$ into itself, because $F$ is order reversing. Hence it has a fixed point in the $[0, F(0)]$. That is to say (6) has a positive semidefinite solution. □

**Theorem 2.** If $Y$ is positive semidefinite solution of (6), then $Y \in [0, F(0)]$.

*Proof.* By $Y \geq 0$, and $C_1 > 0$, we know that $(\tilde{Y} + C_1)^{-1} > 0$ and $A^*(\tilde{Y} + C_1)^{-1}A \geq 0$; then $Y = A^*(\tilde{Y} + C_1)^{-1}A \geq 0$. By $Y \geq 0$, we know that $Y = A^*(\tilde{Y} + C_1)^{-1}A \leq A^*C_1^{-1}A = F(0)$. That is, $Y \in [0, F(0)]$. □

For proving the uniqueness, we first verify the following lemma.

**Lemma 3.** Let $\eta(t) = \frac{((1-t)C_1)/(C_1 + C_1^{-1}A))}{\eta > 0}$. For any $Y \in [0, F(0)]$ and $0 < t < 1$, one has

$$F^2(tY) \geq t(1 + \eta(t))F^2(Y).$$  (7)

*Proof.* By Theorem 2, we know $F(Y) \in [0, F(0)]$ for any $Y \in [0, F(0)]$. Then $F^2(Y) \in [0, F(0)]$ for any $Y \in [0, F(0)]$. Let $F(tY) = A^*(\tilde{tY} + C_1)^{-1}A$, and $F_1(tY) = A^*(\tilde{tY} + tC_1)^{-1}A$. For any $Y \in [0, F(0)]$ and $0 < t < 1$, we have

$$F^2(tY) - t(1 + \eta(t))F^2(Y)
= A^*(\tilde{F(tY)} + C_1)^{-1}A - tA^*(\tilde{F(tY)} + C_1)^{-1}A
- t\eta(t)F^2(Y)
= tA^*\left[\left(\frac{\tilde{F(tY)}}{C_1 + C_1^{-1}A}\right) - t\right]A
- t\eta(t)F^2(Y)
\geq tA^*\left(\frac{\tilde{F(tY)}}{C_1 + C_1^{-1}A}\right)A - tA^*\left(\tilde{F(tY)} + C_1\right)^{-1}A
- t\eta(t)F^2(Y)$$

Analogously one can prove that

$$0 \leq F^{2k}(0) \leq F^{2k+2}(0) \leq F^{2k+1}(0) \leq F^{2k-1}(0) \leq F(0).$$  (11)

Hence, the sequence $\{F^{2k}(0), k \geq 0\}$ is monotone increasing and is bounded from above by $F(0)$. Thus, the sequence $\{F^{2k}(0), k \geq 0\}$ has a finite positive definite limit. Moreover, the sequence $\{F^{2k+1}(0), k \geq 0\}$ is monotone decreasing and is bounded from below by 0. Thus, the sequence $\{F^{2k+1}(0), k \geq 0\}$ has a finite positive definite limit. Let

$$\lim_{k \to \infty} F^{2k}(0) = Y^{(1)}, \quad \lim_{k \to \infty} F^{2k+1}(0) = Y^{(2)};$$  (12)
then $0 \leq Y^{(i)} \leq F(0)$ for $i = 1, 2$. Clearly, both $Y^{(1)}$ and $Y^{(2)}$ are the positive fixed points of $F(Y)$. Then

$$Y^{(1)} = F^2(Y^{(1)}) = A^* \left[ F(Y^{(1)}) + C_1 \right]^{-1} A$$

$$\geq A^* \left( \lambda C_1^{-2} C_1 + C_1 \right)^{-1} A$$

$$\geq A^* \left( \lambda C_1^{-2} + 1 \right)^{-1} C_1^{-1} A$$

$$= \frac{1}{\lambda C_1^{-2} + 1} A^* C_1^{-1} A$$

$$\geq \frac{1}{\lambda C_1^{-2} + 1} F^2(Y^{(2)})$$

$$= \frac{1}{\lambda C_1^{-2} + 1} Y^{(2)}.$$ (13)

Let $t_0 = \sup \{ t \mid Y^{(1)} \geq t Y^{(2)} \}$; then $0 < t_0 < +\infty$. Now we prove that $t_0 \geq 1$. Assume, on the contrary, that $0 < t_0 < 1$; then $Y^{(1)} \geq t_0 Y^{(2)}$. By Lemma 3 and monotonicity of $F^2(Y)$, we have

$$Y^{(1)} = F^2(Y^{(1)}) \geq F^2(t_0 Y^{(2)}) \geq (1 + \eta(t_0)) t_0 F^2(Y^{(2)})$$

$$= (1 + \eta(t_0)) t_0 Y_2.$$ (14)

Since $(1 + \eta(t_0)) t_0 > t_0$, then it is a contradiction to the definition of $t_0$. Hence we have $t_0 \geq 1$; therefore $Y^{(1)} \geq Y^{(2)}$. Similarly, we can get $Y^{(1)} \leq Y^{(2)}$. Therefore, $Y^{(1)} = Y^{(2)}$. Let $\Omega = [0, F(0)]$. By Theorem 1, we know $F(\Omega) \subseteq \Omega$. Hence $F^2(\Omega) \subseteq \Omega$. That is, $F^2$ has only one positive fixed point in $\Omega$. In other words, the equation $Y = F(Y)$ has only one positive definite solution. Hence $Y^{(1)} = Y^{(2)}$. It follows that $\lim_{n \to \infty} F^n(0)$ is a fixed point of $F^2$. Since the positive definite solution of $F(Y) = Y$ solves $Y = F^2(Y)$, then $F^2(Y) = Y$ has only one positive definite solution. Hence $\lim_{n \to \infty} F^n(0)$ is the unique fixed point of $F$.

For any $Y_0 > 0$, we get

$$Y_1 \geq 0,$$

$$0 \leq Y_2 = A^* \left( \bar{Y}_1 + C_1 \right)^{-1} A \leq A^* C_1^{-1} A = F(0).$$ (15)

By induction, we have for any $k = 1, 2, \ldots$

$$F^{2k}(0) \leq Y_{2k+1} \leq F^{2k}(0),$$

$$F^{2k-2}(0) \leq Y_{2k} \leq F^{2k-1}(0).$$ (16)

Now letting $k \to \infty$ on both sides of the above inequalities, we can get

$$\lim_{k \to \infty} Y_k = \lim_{n \to \infty} F^n(0) = Y.$$ (17)

Since (1) is equal to (6) when $X = Y + Q$, then we know that $X$ is a positive definite solution of (1) if and only if $Y$ is a positive semidefinite solution of (6). And furthermore, $Y \in [Q, F(0)]$ if and only if $X \in [Q, G_1(Q)]$. Thus, we can get the following conclusions about (1).

**Theorem 5.** Equation (1) with $\bar{Q} > C$ has a positive definite solution for any $A \in \mathcal{Q}(n)$.

**Theorem 6.** If $X$ is a positive definite solution of (1) with $\bar{Q} > C$, then $X \in [Q, G_1(Q)] \subset S_2(n)$.

**Theorem 7.** Let $Q \in \mathcal{P}(n)$ and $C \in \mathcal{P}(mn)$ such that $\bar{Q} > C$. Then (1) has a unique solution $X$ in $S_1(n)$ and for any $X_0 \in [Q, G_1(Q)]$, the iteration

$$X_{n+1} = Q + A^* (\bar{X}_n - C)^{-1} A, \quad n = 0, 1, 2, \ldots,$$ (18)

converges to $X$; that is, $\lim_{n \to \infty} X_n = X$.

### 3. The Case of $\bar{Q} < C$

In this section, we discuss (1) with $\bar{Q} < C$ and $A^* (\bar{Q} - C)^{-1} A < Q$. In fact, $C \in \mathcal{P}(n)$ must be a positive definite matrix in this case, because $\bar{Q} < C$ and because $Q$ is a positive definite matrix. We consider the matrix equation

$$X = Q - A^* (C - \bar{X})^{-1} A,$$ (19)

which is equal to (1). Let $S_2(n) \subset P(n)$ be the set defined by

$$S_2(n) = \{ X \in P(n) \mid \bar{X} < C \}.$$ (20)

We are interested in positive definite solutions of (1) in this set. A matrix $X$ is a solution of (1) if and only if it is a fixed point of the map $G_2$ defined by

$$G_2(X) = Q - A^* (C - \bar{X})^{-1} A.$$ (21)

Let $C_2 = C - \bar{Q}$; for $\bar{Q} < C$, we have $C_2$ being a positive definite matrix. Then (1) turns into

$$Q - X = A^* (\bar{Q} - \bar{X} + C_2)^{-1} A.$$ (22)

Let $Y = Q - X$. Then (1) eventually becomes

$$Y = A^* (\bar{Y} + C_2)^{-1} A.$$ (23)

We note that (23) should have the same results as (6). Then we directly give the following conclusions without proof.

**Theorem 8.** Equation (1) with $\bar{Q} < C$ and $A^* (C - \bar{Q})^{-1} A < Q$ has a positive definite solution for any $A \in \mathcal{Q}(n)$.

**Theorem 9.** If $X$ is a positive definite solution of (1) with $\bar{Q} < C$ and $A^* (C - \bar{Q})^{-1} A < Q$, then $X \in [G_2(Q), Q] \subset S_2(n)$. 
Theorem 10. Let $Q \in \mathcal{P}(n)$ and $C \in \mathcal{P}(mn)$ such that $\hat{Q} < C$. Then (1) has a unique solution $X$ in $S_2(n)$, and for any $X_0 \in [G_2(Q), Q]$, the iteration

$$X_{n+1} = Q - A^* (C - X_n)^{-1} A, \quad n = 0, 1, 2, \ldots,$$

converges to $X$; that is, $\lim_{n \to \infty} X_n = X$.

4. Numerical Examples

We now use numerical examples to illustrate our results. All computations were performed using MATLAB, version 7.01. We denote $\varepsilon(X) = \|X - A^*(\hat{X} - C)^{-1} A\|_\infty$ and use the stopping criterion $\varepsilon(X) < 1.0 \times 10^{-10}$.

**Example 1.** Consider (1) with $n = 2, m = 3$, and

$$A = \begin{pmatrix} 2 & -2 \\ 1 & 0 \\ -5 & 3 \\ 6 & 2 \\ -3 & 1 \\ 6 & 5 \end{pmatrix}, \quad Q = \begin{pmatrix} 20 & -1 \\ -1 & 13 \end{pmatrix},$$

(25)

where the matrices $Q$ and $C$ satisfy $\hat{Q} > C$. Considering the iterative method (18) with $X_0 = Q$, after 23 iterations we get the following result:

$$X = X_{23} = \begin{pmatrix} 27.28666873488235 & 1.12493304573834 \\ 1.12493304573834 & 16.21667821374470 \end{pmatrix},$$

(26)

and $\varepsilon(X_{23}) = \|X_{23} - A^*(\hat{X}_{23} - C)^{-1} A\|_\infty = 8.62208027080936 \times 10^{-11}$. It is not difficult to verify that $X \in [Q, G_1(Q)] \subset S_2(n)$.

**Example 2.** Consider (1) with $n = 2, m = 3$, and

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \\ -1 & 0 \\ 1 & 2 \\ 2 & 1 \\ -1 & 1 \end{pmatrix}, \quad Q = \begin{pmatrix} 4 & -1 \\ -1 & 5 \end{pmatrix},$$

(27)

where the matrices $Q$ and $C$ satisfy $\hat{Q} < C$ and $A^*(C - \hat{Q})^{-1} A < Q$. Considering the iterative method (24) with $X_0 = Q$, after 7 iterations one gets an approximation to the positive definite solution $X$. It is

$$X = X_7 = \begin{pmatrix} 3.48707713254602 & -1.33049056598352 \\ -1.33049056598352 & 4.39117111733130 \end{pmatrix}$$

(28)

and $\varepsilon(X_7) = \|X_7 - A^*(\hat{X}_7 - C)^{-1} A\|_\infty = 6.44789771266753 \times 10^{-11}$. It is not difficult to verify that $X \in [G_2(Q), Q] \subset S_2(n)$.

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