Research Article

A Proposal to the Solution of Multiobjective Linear Fractional Programming Problem

Nuran Güzel

Department of Mathematics, Faculty of Art and Sciences, Yildiz Technical University, Davutpaşa, 34210 Istanbul, Turkey

Correspondence should be addressed to Nuran Güzel; nguzel@yildiz.edu.tr

Received 18 March 2013; Accepted 10 September 2013

Copyright © 2013 Nuran Güzel. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We have proposed a new solution to the Multiobjective Linear Fractional Programming Problem (MOLFPP). The proposed solution is based on a theorem that deals with nonlinear fractional programming with single objective function and studied in the work by Dinkelbach, 1967. As a new contribution, we have proposed that $x$ is an efficient solution of MOLFPP if $x$ is an optimal solution of problem $\max_{x \in X} \sum_{i=1}^{k} (N_i(x) - Z^*_i D_i(x))$, where $Z^*_i = N_i(x^*_i)/D_i(x^*_i)$ for all $i$. Hence, MOLFPP is simply reduced to linear programming problem (LPP). Some numerical examples are provided in order to illustrate the applications of the proposed method. The optimization software package, namely, WinQSB (Chang, 2001), has been employed in the computations.

1. Introduction

Fractional programming concerns with the optimization problem of one or several ratios of functions subject to some constraints. These ratios are quantities that measure the efficiency of system, such as cost/profit, cost/time, cost/volume, and output/worker, while several ratios of functions are measured in different scales at the existence of some conflicts. The optimal solution for an objective function may not be an optimal solution for some other objective functions. Therefore, one needs to find the notion of the best compromise solution, also known as nondominant solution [1, 2].

In the literature, for various types of fractional programming, there are many different sorts of studies; some of them deal with theory [3–6], and some of them concern with solution methods [2, 7–18] and applications [19]. Dinkelbach [7] presented the algorithm based on a theorem by Jagannathan [20] concerning the relationship between fractional and parametric programming and restated and proved this theorem in somewhat simpler way. Leber et al. proposed [19] to use a fractional programming algorithm (the Dinkelbach algorithm) to calculate the melting temperature of pairings of two single DNA strands in biology.

If both the numerator and denominator of these ratios of functions in fractional programming are linear functions under some technological linear restrictions, then we have the multiple objective linear fractional programming (MOLFP) problems. There are so many studies including different approaches to solve different models of MOLFP problems in literature. Kornbluth and Steuer [21] proposed some possible linear fractional criteria [1] and have presented a generalized approach for solving a goal programming with linear fractional criteria [22]. Luhandjula [23] proposed a linguistic variable approach to solve a MOLFP problem. This approach simply and adequately describes imprecise aspirations of the decision maker to obtain a solution that is in some sense good in his/her opinion. These linguistic descriptions are considered as fuzzy objectives and are aggregated as in fuzzy linear programming [1].

Dutta et al. [24] modified the linguistic approach of Luhandjula such as to develop a method which yields always an efficient solution for optimising MOLFP problem. Stancu-Minasian and Pop [2] pointed out certain shortcomings in the work of Dutta et al. and have given the correct proof of theorem, which validates the obtaining of the efficient solutions. Lee and Tcha [25] developed iterative solution method to generate a sequence of linear inequality problems by parameterizing objective values to obtain a compromise solution of MOLFP problem. Chakraborty and Gupta [22] have presented a different methodology that always yields an efficient solution for solving MOLFP problem. In this
methodology, MOLFPP may be solved easily with the transformation $y = tx, t > 0$ resulting in a multiple objective linear programming (MOLP) problem. It has been considered as the least value of both $1/D_i(x)$ if objective function $Z_i(x) \geq 0$ for some $x$ in the feasible region and $1/(-N_i(x))$ if objective function $Z_i(x) < 0$, for each $x$ in the feasible region. After original MOLF problem reduces to an equivalent MOLP problem, the resulting MOLP problem is solved using fuzzy set theoretical approach by suitably defined membership functions and using min operator introduced by Zimmermann.

In this paper, we have investigated a solution to the MOLF problem based on a theorem previously studied by Dinkelbach [7]. We have proposed that a feasible solution $\overline{x}$ of MOLFPP is an efficient solution of MOLFPP if $\overline{x} \in R^n$ is an optimal solution of problem $\max_{x \in X} \sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x))$, where $Z_i^* = N_i(x^*)/D_i(x^*)$ for all $i$. Thus, MOLFPP is reduced to linear programming problem (LPP), and its solution procedure can be easily applied.

1.1. Linear Fractional Programming Problem (LFPP). The general LFPP is defined as follows:

$$\max_{x \in X} \frac{N(x)}{D(x)} \quad (1)$$

$N(x) = c^T x + \alpha, D(x) = d^T x + \beta$ are valued and continuous functions on $X$ and $d^T x + \beta \neq 0$ for all $x$ and $X = \{ x \mid Ax = b, x \geq 0 \}, x \in R^n, b \in R^m, A \in R^{m \times n}$. 

$c^T, d^T \in R^n, \alpha, \beta \in R$ are assumed to be nonempty convex and compact set in $R^n$.

Theorem 1. Consider

$$\begin{align*}
\max & \quad \frac{N(x)}{D(x)} \\
\text{s.t.} & \quad Ax \leq b, \\
& \quad x \geq 0, x \in X = \{ x \mid Ax = b, x \geq 0 \} \\
& \quad \Rightarrow D(x) > 0.
\end{align*} \quad (2a)$$

$$\begin{align*}
\max & \quad tN\left(\frac{y}{t}\right) \\
\text{s.t.} & \quad A\left(\frac{y}{t}\right) - b \leq 0, \\
& \quad tD\left(\frac{y}{t}\right) \leq 1, \\
& \quad t > 0, y \geq 0.
\end{align*} \quad (2b)$$

For some $\xi \in X$, $N(\xi) \geq 0$, if (2a) reaches a (global) maximum at $x = x^*$, then (2b) reaches a (global) maximum at point $(t, y) = (t^*, y^*)$, where $y^*/t^* = x^*$ and the objective functions at these points are equal [22, 26].

Theorem 2 (see [22, 26]). If (2a) is a standard concave-convex fractional programming problem which reaches a (global) maximum at point $x^*$, then the corresponding transformed problem (2b) attains the same maximum value at a point $(t^*, y^*)$, where $y^*/t^* = x^*$.

Moreover (2b) has a concave objective function and a convex feasible set.

Theorem 3 (see [7]). $z^* = N(x^*)/D(x^*) = \max \{ N(x)/D(x) \mid x \in X \}$ if and only if $F(z^*, x^*) = \max \{ N(x) - z^*D(x) \mid x \in X \} = 0$.

2. Proposed Approach for Objective Functions of MOLF Problem

The vector-maximum Multiple Objective Linear Fractional programming (MOLFP) problem is defined as follows:

$$\begin{align*}
\max & \quad \{ Z(x) = \left( \frac{N_1(x)}{D_1(x)}, \frac{N_2(x)}{D_2(x)}, \ldots, \frac{N_k(x)}{D_k(x)} \right) \mid x \in X \},
\end{align*} \quad (3)$$

where $X = \{ x \in R^n/ Ax \leq b, x \geq 0 \}$ is convex and nonempty bounded set, $A$ is an $m \times n$ constraint matrix, $x$ is an $n$-dimensional vector of decision variable, and $b \in R^m$, $k \geq 2$, $N_i(x) = c_i^T x + \alpha_i, D_i(x) = d_i^T x + \beta_i$, for all $i = 1, \ldots, k$, $c_i^T, d_i^T \in R^n, \alpha_i, \beta_i \in R$, for all $i = 1, \ldots, k, D_i(x) = d_i x + \beta_i > 0$, for all $i = 1, \ldots, k, x \in X$.

Definition 4. $\overline{x} \in R^n$ is an efficient solution of MOLFPP if there is no $\overline{x} \in R^n$ such that $N_i(\overline{x})/D_i(\overline{x}) \geq N_i(\overline{x})/D_i(\overline{x}), i = 1, 2, \ldots, k, N_i(\overline{x})/D_i(\overline{x}) > N_i(\overline{x})/D_i(\overline{x}),$ for at least one $i$.

In this study, in order to solve MOLF problem in (3), we can maximize each objective function $Z_i(x)$ subject to the given set of constraints using one of the methods proposed for single fractional objective function in [27] or others. Let $x_i^*$ and $Z_i^*$ be the global maximum points and values of each objective function $Max[Z_i(x) = (c_i x + \alpha_i)/(d_i x + \beta_i)| x \in X]$ for all $i = 1, 2, \ldots, k$. Now, we can prove that the solution $\overline{x}$ is an efficient solution of $Max[Z_i(x) = (c_i x + \alpha_i)/(d_i x + \beta_i), i = 1, 2, \ldots, k | x \in X]$.

If $\overline{x}$ is an optimal solution of problem: $\max \{ \sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \mid x \in X \}$, where is $Z_i^* = N_i(x_i^*)/D_i(x_i^*)$ for all $i = 1, 2, \ldots, k$.

Let $\overline{x}$ maximise problem $\max \{ \sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \mid x \in X \}$; then we can write inequality $\sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \leq \sum_{i=1}^{k} (N_i(\overline{x}) - Z_i^*D_i(\overline{x}))$ for any feasible solution $x \in X$. Hence,

$$\sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \leq \sum_{i=1}^{k} (N_i(\overline{x}) - Z_i^*D_i(\overline{x})) \quad (4)$$

for $x \in X$. 

Abstract and Applied Analysis
From these inequalities, one obtains $N_i(x) - Z_i^*D_i(x) \leq N_i(x) - Z_i^*D_i(x) \leq 0$, for all $i, x \in X$.

We have $D_i(x)[N_i(x)/D_i(x) - Z_i^*] \leq D_i(x)[N_i(x)/D_i(x) - Z_i^*]$ for all $i$:

$$
\left[ \frac{N_i(x)}{D_i(x)} - Z_i^* \right] \leq \frac{D_i(x)}{D_i(x)} \left[ \frac{N_i(x)}{D_i(x)} - Z_i^* \right].
$$

(3)

Both via Theorem 3 and the inequality $D_i(x)/D_i(x) \geq 1$, one can write that $[N_i(x)/D_i(x) - Z_i^*] \leq [N_i(x)/D_i(x) - Z_i^*]$ and $[N_i(x)/D_i(x)] \leq [N_i(x)/D_i(x)]$ for all $i$. If $\bar{x}$ maximise the problem $\max \sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \mid x \in X$, then it is an efficient solution of $\max \{Z_i(x) = (c_i + a_i)/(d_i + b_i), i = 1, 2, \ldots, k \mid x \in X\}$. Now, assume that $\bar{x}$ is not an efficient of MOLFPP, then there exists a feasible solution $x$ of MOLFPP and $N_i(\bar{x})/D_i(\bar{x}) \leq N_i(x)/D_i(x)$ for all $i$ and $N_i(\bar{x})/D_i(\bar{x}) < N_i(x)/D_i(x)$ at least one $j$, where $x, \bar{x} \in X$.

It follows that $N_i(\bar{x})/D_i(\bar{x}) \leq N_i(x)/D_i(x) \leq Z_i^*$, $N_i(\bar{x}) - Z_i^*D_i(\bar{x}) \leq N_i(x) - Z_i^*D_i(x)$ for all $i$ and $N_i(\bar{x}) - Z_i^*D_i(x) < N_i(x) - Z_i^*D_i(x)$ at least one $j$. Summing the $k$-inequalities, we have $\sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x)) \leq \sum_{i=1}^{k} (N_i(x) - Z_i^*D_i(x))$. This inequality leads to a contradiction.

Thus, we have made a proposal for the solution of MOLFPP based on the above proof. These examples considered by Chakraborty and Gupta in [22] use Zimmermann’s min operator for the fuzzy model.

### 3. Numerical Examples

**Example 1.** Let us consider a MOLFPP with two objectives as follows:

$$
\begin{align*}
\text{Max} & \quad Z_1(x) = \frac{-3x_1 + 2x_2}{x_1 + 2x_2 + 3}, \\
& \quad Z_2(x) = \frac{7x_1 + x_2}{5x_1 + 2x_2 + 1}
\end{align*}
$$

s.t. $x_1 - x_2 \geq 1$

$2x_1 + 3x_2 \leq 15$

$x_1 \geq 3$

$x_1, x_2 \geq 0.
$

(6)

It is observed that $Z_1 < 0, Z_2 \geq 0$, for each $x$ in the feasible region:

$$
\frac{-15}{7} \leq Z_1 \leq \frac{-14}{23}, \quad \frac{139}{121} \leq Z_2 \leq \frac{105}{77}.
$$

(7)

This MOLFPP is equivalent to the following LPP. The given MOLF problem can be written as

$$
\begin{align*}
\text{Max} & \quad \left\{ -3x_1 + 2x_2 + \frac{14}{23} (x_1 + x_2 + 3) \\
& \quad + \frac{7}{23} x_1 + x_2 \right. \\
& \quad \left. + 4x_2 - \frac{14}{17} (2x_1 + 3x_2 + 2) \right\},
\end{align*}
$$

s.t. $x_1 - x_2 \geq 1$

$2x_1 + 3x_2 \leq 15$

$x_1 + 9x_2 \geq 9$

$x_1 \geq 3.
$

(11)

**Example 2.** Let us consider a MOLFPP with three objectives as follows:

$$
\begin{align*}
\text{Max} & \quad Z_1(x) = -3x_1 + 2x_2 \\
& \quad Z_2(x) = \frac{7x_1 + x_2}{5x_1 + 2x_2 + 1} \\
& \quad Z_3(x) = \frac{x_1 + 4x_2}{2x_1 + 3x_2 + 2}
\end{align*}
$$

s.t. $x_1 - x_2 \geq 1$

$2x_1 + 3x_2 \leq 15$

$x_1 + 9x_2 \geq 9$

$x_1 \geq 3$

$x_1, x_2 \geq 0.
$

(10)

The solution of the earlier linear programming problem is obtained as $x_1 = 3, x_2 = 2$.

The solution for original problem is given by

$$
\begin{align*}
x_1 = 3, \quad x_2 = 2, \quad Z_1 &= \frac{-5}{8}, \quad Z_2 = \frac{23}{20}.
\end{align*}
$$

(9)
The solution of the above linear programming problem is obtained as \( x_1 = 3, \ x_2 = 2 \). The solution for the given MOLFP problem is given by

\[
\begin{align*}
1 \quad x_1 &= 3, \qquad x_2 = 2, \quad Z_1 = \frac{-5}{8}, \quad Z_2 = \frac{23}{20}, \quad Z_3 = \frac{11}{14}.
\end{align*}
\] (12)

4. Conclusion

In this paper, we have presented a new solution to the Multiobjective Linear Fractional Programming Problem (MOLFP). The solution is based on a theorem proposed in [7] dealing with nonlinear fractional programming with single objective function. With the help of this suggested approach, all of linear fractional objective functions of MOLFP problem become a single objective function. Furthermore the MOLFP problem is transformed into LPP. Thus, the complexity and the computations in solving MOLFP problem reduce in a certain amount. We used two numerical examples solved with different methods in [18, 22, 28].

Conflict of Interests

The author declares that there is no conflict of interests regarding the publication of this paper.

References
