Research Article

Existence of Solutions of Fractional Differential Equation with p -Laplacian Operator at Resonance

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By using the extension of Mawhin's continuation theorem due to Ge, we consider boundary value problems for fractional p -Laplacian equation. A new result on the existence of solutions for the fractional boundary value problem is obtained, which generalizes and enriches some known results to some extent from the literature.

1. Introduction and Preliminaries

Recently, fractional differential equations have played an important role in many fields such as physics, electrical circuits, and control theory (see [1–9]). Many scholars have paid more attention to boundary value problems for fractional differential equations (see [10–25]).

By using a fixed point theorem on a cone, Agarwal et al. (see [10]) considered a two-point boundary value problem at nonresonance given by

$$\begin{aligned} D_{0+}^{\alpha} x(t) + f(t, x(t), D_{0+}^{\mu} x(t)) &= 0, \\ x(0) = x(1) &= 0, \end{aligned} \quad (1)$$

where $1 < \alpha < 2$, $\mu > 0$ are real numbers, $\alpha - \mu \geq 1$, and D_{0+}^{α} is the Riemann-Liouville fractional derivative.

By using the coincidence degree theory, Bai (see [20]) considered the following m -point fractional boundary value problems:

$$\begin{aligned} D_{0+}^{\alpha} u(t) &= f(t, u(t), D_{0+}^{\alpha-1} u(t)) + e(t), \quad 0 < t < 1, \\ I_{0+}^{2-\alpha} u(t)|_{t=0} &= 0, \quad u(1) = \sum_{i=1}^{m-2} \beta_i u(\eta_i), \end{aligned} \quad (2)$$

where $1 < \alpha \leq 2$ is a real number, $\beta_i \in \mathbb{R}$, $\eta_i \in (0, 1)$ are given constants such that $\sum_{i=1}^{m-2} \beta_i \eta_i^{m-1} = 1$, and D_{0+}^{α} , I_{0+}^{α} are the Riemann-Liouville differentiation and integration.

The turbulent flow in a porous medium is a fundamental mechanics problem. For studying this type of problems, Leibenson (see [26]) introduced the p -Laplacian equation as follows:

$$(\phi_p(x'(t)))' = f(t, x(t), x'(t)), \quad (3)$$

where $\phi_p(s) = |s|^{p-2}s$, $p > 1$. Obviously, ϕ_p is invertible and its inverse operator is ϕ_q , where $q > 1$ is a constant such that $1/p + 1/q = 1$.

In the past few decades, many important results relative to (3) with certain boundary value conditions have been obtained. We refer the reader to [27–31] and the references cited therein. However, to the best of our knowledge, there are relatively few results on boundary value problems for fractional p -Laplacian equations.

Motivated by the work above, in this paper, we investigate the existence of solutions for boundary value problem (BVP for short) of fractional p -Laplacian equation with the following form:

$$\begin{aligned} D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha} x(t)) &= f(t, x(t), D_{0+}^{\alpha} x(t)), \quad t \in [0, 1], \\ D_{0+}^{\alpha} x(0) &= D_{0+}^{\alpha} x(1) = x'(0) = 0, \end{aligned} \quad (4)$$

where $0 < \beta \leq 1$, $1 < \alpha \leq 2$, D_{0+}^{α} is Caputo fractional derivative, and $f: [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ is continuous.

BVP (4) happens to be at resonance in the sense that its associated linear homogeneous boundary value problem

$$\begin{aligned} D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha} x(t)) &= 0, \quad t \in [0, 1], \\ D_{0+}^{\alpha} x(0) &= D_{0+}^{\alpha} x(1) = x'(0) = 0 \end{aligned} \quad (5)$$

has a nontrivial solution $x(t) = c$, where $c \in \mathbb{R}$.

For the convenience of the reader, we present here some necessary basic knowledge and definitions about fractional calculus theory, which can be found, for instance, in [32–35].

Definition 1. The Riemann-Liouville fractional integral operator of order $\alpha > 0$ of a function $x : (0, +\infty) \rightarrow \mathbb{R}$ is given by

$$I_{0+}^{\alpha} x(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} x(s) ds, \quad (6)$$

provided that the right side integral is pointwise defined on $(0, +\infty)$.

Definition 2. The Caputo fractional derivative of order $\alpha > 0$ of a continuous function $x : (0, +\infty) \rightarrow \mathbb{R}$ is given by

$$D_{0+}^{\alpha} x(t) = I_{0+}^{n-\alpha} \frac{d^n x(t)}{dt^n} = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{n-\alpha-1} x^{(n)}(s) ds, \quad (7)$$

where n is the smallest integer greater than or equal to α , provided that the right side integral is pointwise defined on $(0, +\infty)$.

Lemma 3. Assume that $D_{0+}^{\alpha} x \in C[0, 1]$, $\alpha > 0$. Then

$$I_{0+}^{\alpha} D_{0+}^{\alpha} x(t) = x(t) + c_0 + c_1 t + c_2 t^2 + \cdots + c_{n-1} t^{n-1}, \quad (8)$$

where $c_i = -x^{(i)}(0)/i!$, $i = 0, 1, 2, \dots, n-1$, and here n is the smallest integer greater than or equal to α .

Now, one briefly recalls some notations and an abstract existence result, which can be found in [36].

Definition 4. Let X and Y be two Banach spaces with norms $\|\cdot\|_X$ and $\|\cdot\|_Y$, respectively. A continuous operator

$$M : X \cap \text{dom } M \rightarrow Y \quad (9)$$

is said to be quasilinear if

- (i) $\text{Im } M := M(X \cap \text{dom } M)$ is a closed subset of Y ,
- (ii) $\text{Ker } M := \{X \cap \text{dom } M : Mu = 0\}$ is linearly homeomorphic to $\mathbb{R}^n$, $n < \infty$.

Definition 5. Let X be a real Banach space and let $\widehat{X} \subset X$. The operator $P : X \rightarrow \widehat{X}$ is said to be a projector provided that $P^2 = P$, $P(\lambda_1 x_1 + \lambda_2 x_2) = \lambda_1 P(x_1) + \lambda_2 P(x_2)$ for $x_1, x_2 \in X$ and $\lambda_1, \lambda_2 \in \mathbb{R}$. The operator $Q : X \rightarrow \widehat{X}$ is said to be a semiprojector provided $Q^2 = Q$.

Definition 6 (see [36]). Let $\widehat{X} = \text{Ker } M$ and let $\widetilde{X}$ be the complement space of $\widehat{X}$ in X , and then $X = \widehat{X} \oplus \widetilde{X}$. On the other hand, suppose that $\widehat{Y}$ is a subspace of Y and $\widetilde{Y}$ is the complement space of $\widehat{Y}$ in Y so that $Y = \widehat{Y} \oplus \widetilde{Y}$. Let $P : X \rightarrow \widehat{X}$ be a projector, let $Q : Y \rightarrow \widehat{Y}$ be a semiprojector, and let $\Omega \subset X$ be an open and bounded set with origin $\theta \in \Omega$, where θ is the origin of a linear space.

Suppose that $N_{\lambda} : \overline{\Omega} \rightarrow Y$, $\lambda \in [0, 1]$, is a continuous operator. Denote N_1 by N . Let $\Sigma_{\lambda} = \{x \in \overline{\Omega} : Mx = N_{\lambda}x\}$. N_{λ} is said to be M -compact in $\overline{\Omega}$ if there is $\widehat{Y} \subset Y$ with $\dim \widehat{Y} = \dim \widehat{X}$ and an operator $R : \overline{\Omega} \times [0, 1] \rightarrow X$ continuous and compact such that, for $\lambda \in [0, 1]$,

$$(I - Q) N_{\lambda}(\overline{\Omega}) \subset \text{Im } M \subset (I - Q) Y, \quad (10)$$

$$QN_{\lambda}x = \theta, \quad \lambda \in (0, 1) \iff QNx = \theta, \quad (11)$$

$$R(\cdot, 0) \text{ is the zero operator and } R(\cdot, \lambda)|_{\Sigma_{\lambda}} = (I - P)|_{\Sigma_{\lambda}}, \quad (12)$$

$$M[P + R(\cdot, \lambda)] = (I - Q) N_{\lambda}. \quad (13)$$

Lemma 7 (see [36] Ge-Mawhin's continuation theorem). Let X and Y be two Banach spaces with norms $\|\cdot\|_X$ and $\|\cdot\|_Y$, respectively. $\Omega \subset X$ is an open and bounded nonempty set. Suppose that

$$M : X \cap \text{dom } M \rightarrow Y \quad (14)$$

is a quasilinear operator and

$$N_{\lambda} : \overline{\Omega} \rightarrow Y, \quad \lambda \in [0, 1] \quad (15)$$

is M -compact in $\overline{\Omega}$. In addition, if

$$(C_1) \quad Mx \neq N_{\lambda}x, \quad \forall (x, \lambda) \in (\text{dom } M \cap \partial\Omega) \times (0, 1),$$

$$(C_2) \quad QNx \neq 0, \text{ for } x \in \text{dom } M \cap \partial\Omega,$$

$$(C_3) \quad \deg(JQN, \text{Ker } M \cap \Omega, 0) \neq 0,$$

where $N = N_1$, then the equation $Mx = Nx$ has at least one solution in $\overline{\Omega}$.

In this paper, we take $Y = C[0, 1]$ with the norm $\|x\|_{\infty} = \max_{t \in [0, 1]} |x(t)|$ and $X = \{x \mid x, D_{0+}^{\alpha} x \in Y\}$ with the norm $\|x\|_X = \max\{\|x\|_{\infty}, \|D_{0+}^{\alpha} x\|_{\infty}\}$. By means of the linear functional analysis theory, we can prove that X is a Banach space.

Define the operator $M : \text{dom } M \subset X \rightarrow Y$ by

$$Mx = D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha} x), \quad (16)$$

where

$$\begin{aligned} \text{dom } M &= \{x \in X \mid D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha} x) \in Y, \\ D_{0+}^{\alpha} x(0) &= D_{0+}^{\alpha} x(1) = x'(0) = 0\}. \end{aligned} \quad (17)$$

Define the operator $N : X \rightarrow Y$ by

$$Nx(t) = f(t, x(t), D_{0+}^{\alpha} x(t)), \quad \forall t \in [0, 1]. \quad (18)$$

Then BVP (4) is equivalent to the operator equation. Consider

$$Mx = Nx, \quad x \in \text{dom } M. \quad (19)$$

2. Main Result

We will always assume that the nonlinearity $f(t, u, v)$ will be retained:

(H₁) there exist nonnegative functions $a, b, c \in Y$ such that

$$|f(t, u, v)| \leq a(t) + b(t)|u|^{p-1} + c(t)|v|^{p-1}, \quad \forall t \in [0, 1],$$

$$(u, v) \in \mathbb{R}^2; \quad (20)$$

(H₂) there exists a constant $B > 0$ such that

either

$$uf(t, u, v) > 0, \quad \forall t \in [0, 1], v \in \mathbb{R}, |u| > B, \quad (21)$$

or

$$uf(t, u, v) < 0, \quad \forall t \in [0, 1], v \in \mathbb{R}, |u| > B. \quad (22)$$

Moreover, we will always assume that $f: [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ is continuous and

$$\frac{1}{\Gamma(\beta + 1)} \left(\frac{2\|b\|_\infty}{(\Gamma(\alpha + 1))^{p-1}} + \|c\|_\infty \right) < 1. \quad (23)$$

Now, we begin with some lemmas below.

Lemma 8. Let M be defined by (16), and then

$$\text{Ker } M = \{x \in X \mid x(t) = c \in \mathbb{R}, \forall t \in [0, 1]\}, \quad (24)$$

$$\text{Im } M = \left\{ y \in Y \mid \int_0^1 (1-s)^{\beta-1} y(s) ds = 0 \right\}, \quad (25)$$

and M is a quasilinear operator

Proof. By Lemma 3, $D_{0+}^\beta \phi_p(D_{0+}^\alpha x(t)) = 0$ has solution:

$$x(t) = c_0 + c_1 t + I_{0+}^\alpha \phi_q(c_2)$$

$$= c_0 + c_1 t + \frac{\phi_q(c_2)}{\Gamma(\alpha + 1)} t^\alpha, \quad c_0, c_1, c_2 \in \mathbb{R}, \quad (26)$$

which satisfies

$$D_{0+}^\alpha x(t) = \phi_q(c_2). \quad (27)$$

Combining with the boundary value condition $D_{0+}^\alpha x(0) = 0$ and $x'(0) = 0$, we can get that (24) holds.

If $y \in \text{Im } M$, then there exists a function $x \in \text{dom } M$ such that $y(t) = D_{0+}^\beta \phi_p(D_{0+}^\alpha x(t))$. Based on Lemma 3, we have

$$D_{0+}^\alpha x(t) = \phi_q(I_{0+}^\beta y(t) + c)$$

$$= \phi_q\left(\frac{1}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} y(s) ds + c\right), \quad c \in \mathbb{R}. \quad (28)$$

From condition $D_{0+}^\alpha x(0) = 0$, one has $c = 0$. By the condition $D_{0+}^\alpha x(1) = 0$, we obtain that

$$\int_0^1 (1-s)^{\beta-1} y(s) ds = 0. \quad (29)$$

Thus, we get (25).

Then we have $\dim \text{Ker } M = 1$ and $M(\text{dom } M \cap X) \subset Y$ closed. Therefore, M is a quasilinear operator. $\square$

Lemma 9. Let $\Omega \subset X$ be an open and bounded set; then N_λ is M -compact in $\overline{\Omega}$.

Proof. Define the continuous projector $P: X \rightarrow \widehat{X}$ and the semiprojector $Q: Y \rightarrow \widehat{Y}$:

$$Px(t) = x(0), \quad \forall t \in [0, 1],$$

$$Qy(t) = \beta \int_0^1 (1-s)^{\beta-1} y(s) ds, \quad \forall t \in [0, 1]. \quad (30)$$

where $\widehat{X} = \text{Ker } M$ and $\widehat{Y} = \text{Im } Q$.

Obviously, $\text{Im } P = \text{Ker } M$ and $P^2 x(t) = Px(t)$. It follows from $x = (x - Px) + Px$ that $X = \text{Ker } P + \text{Ker } M$. By a simple calculation, we can get $\text{Ker } M \cap \text{Ker } P = \{0\}$. Then we get

$$X = \text{Ker } M \oplus \text{Ker } P = \widehat{X} \oplus \overline{X}. \quad (31)$$

By the definition of Q , we can get

$$Q^2 y = Qy \cdot \beta \int_0^1 (1-s)^{\beta-1} ds = Qy. \quad (32)$$

Let $y = (y - Qy) + Qy$, where $y - Qy \in \text{Ker } Q = \text{Im } M$, $Qy \in \text{Im } Q$. It follows from $\text{Ker } Q = \text{Im } M$ and $Q^2 y = Qy$ that $\text{Im } Q \cap \text{Im } M = \{0\}$. Then, we have

$$Y = \text{Im } Q \oplus \text{Im } M = \widehat{Y} \oplus \widetilde{Y}. \quad (33)$$

Thus

$$\dim \widehat{X} = \dim \text{Ker } M = \dim \text{Im } Q = \dim \widehat{Y}. \quad (34)$$

Let $\Omega \subset X$ be an open and bounded set with $\theta \in \Omega$. For each $x \in \Omega$, we can get $Q[(I-Q)N_\lambda x] = 0$. Thus, $(I-Q)N_\lambda x \in \text{Im } M = \text{Ker } Q$. Take any $y \in \text{Im } M$ in the type $y = (y - Qy) + Qy$. Since $Qy = 0$, we can get $(I-Q)y \in Y$. So (10) holds. It is easy to verify (11).

Furthermore, define $R: \overline{\Omega} \times [0, 1] \rightarrow \widetilde{X}$ by

$$R(x, \lambda)(t)$$

$$= \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \phi_q$$

$$\times \left(\frac{1}{\Gamma(\beta)} \int_0^s (s-\tau)^{\beta-1} \right.$$

$$\left. \times ((I-Q)N_\lambda x(\tau)) d\tau \right) ds. \quad (35)$$

By the continuity of f , it is easy to get that $R(x, \lambda)$ is continuous on $\bar{\Omega} \times [0, 1]$. Moreover, for all $x \in \bar{\Omega}$, there exists a constant $T > 0$ such that $|I_{0+}^{\beta}(I - Q)N_{\lambda}x(\tau)| \leq T$, so we can easily obtain that $R(\bar{\Omega}, \lambda)$ is uniformly bounded. By the Arzelà-Ascoli theorem, we just need to prove that $R : \bar{\Omega} \times [0, 1] \rightarrow \bar{X}$ is equicontinuous. Furthermore, for $0 \leq t_1 < t_2 \leq 1$, $(x, \lambda) \in \bar{\Omega} \times [0, 1]$, we have

$$\begin{aligned} & |R(x, \lambda)(t_2) - R(x, \lambda)(t_1)| \\ &= \left| I_{0+}^{\alpha} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(t_2) \right) \right. \\ & \quad \left. - I_{0+}^{\alpha} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(t_1) \right) \right|. \end{aligned} \quad (36)$$

By $|I_{0+}^{\beta}(I - Q)N_{\lambda}x| \leq T$, we have

$$\begin{aligned} & \left| I_{0+}^{\alpha} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(t_2) \right) - I_{0+}^{\alpha} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(t_1) \right) \right| \\ & \leq \frac{1}{\Gamma(\alpha)} \left| \int_0^{t_2} (t_2 - s)^{\alpha-1} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(s) \right) ds \right. \\ & \quad \left. - \int_0^{t_1} (t_1 - s)^{\alpha-1} \phi_q \left(I_{0+}^{\beta} (I - Q) N_{\lambda} x(s) \right) ds \right| \\ & \leq \frac{\phi_q(T)}{\Gamma(\alpha)} \left[\int_0^{t_1} (t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1} ds \right. \\ & \quad \left. + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} ds \right] \\ & = \frac{\phi_q(T)}{\Gamma(\alpha + 1)} (t_2^{\alpha} - t_1^{\alpha}). \end{aligned} \quad (37)$$

Since t^{α} is uniformly continuous on $[0, 1]$, so $R(\bar{\Omega}, \lambda)$ is equicontinuous. Similarly, we can get that $I_{0+}^{\beta}((I - Q)N_{\lambda}x(\tau)) \subset C[0, 1]$ is equicontinuous, and considering that $\phi_q(s)$ is uniformly continuous on $[-T, T]$, we get that $D_{0+}^{\alpha}R(\bar{\Omega}, \lambda) = I_{0+}^{\beta}((I - Q)N_{\lambda}(\bar{\Omega}))$ is also equicontinuous. So we can obtain that $R(\bar{\Omega}, \lambda) \rightarrow \bar{X}$ is compact.

For each $x \in \Sigma_{\lambda} = \{x \in \bar{\Omega} : Mx = N_{\lambda}x\}$, we have $D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha}x(t)) = N_{\lambda}x(t) \in \text{Im } M$. Thus,

$$\begin{aligned} & R(x, \lambda)(t) \\ &= \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} \phi_q \\ & \quad \times \left(\frac{1}{\Gamma(\beta)} \int_0^s (s - \tau)^{\beta-1} \right. \\ & \quad \left. \times ((I - Q)N_{\lambda}x(\tau)) d\tau \right) ds. \end{aligned}$$

$$\begin{aligned} &= \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} \phi_q \\ & \quad \times \left(\frac{1}{\Gamma(\beta)} \int_0^s (s - \tau)^{\beta-1} \right. \\ & \quad \left. \times D_{0+}^{\beta} \phi_p(D_{0+}^{\alpha}x(\tau)) d\tau \right) ds, \end{aligned} \quad (38)$$

which together with $D_{0+}^{\alpha}x(0) = x'(0) = 0$ yields that

$$R(x, \lambda)(t) = x(t) - x(0) = [(I - P)x](t). \quad (39)$$

It is easy to verify that $R(x, 0)(t)$ is the zero operator. So (12) holds.

On the other hand, consider

$$\begin{aligned} & M[Px + R(x, \lambda)](t) \\ &= M \left[\frac{1}{\Gamma(\alpha)} \right. \\ & \quad \times \int_0^t (t - s)^{\alpha-1} \phi_q \left(\frac{1}{\Gamma(\beta)} \int_0^s (s - \tau)^{\beta-1} \right. \\ & \quad \left. \times ((I - Q)N_{\lambda}x(\tau)) d\tau \right) ds \\ & \quad \left. + x(0) \right] \\ &= [((I - Q)N_{\lambda})x](t). \end{aligned} \quad (40)$$

So (13) holds. Then we get that N_{λ} is M -compact in $\bar{\Omega}$. The proof is complete. $\square$

Lemma 10. Suppose that (H_1) , (H_2) hold; then the set

$$\Omega_1 = \{x \in \text{dom } M \setminus \text{Ker } M \mid Mx = \lambda Nx, \lambda \in (0, 1)\} \quad (41)$$

is bounded.

Proof. Take $x \in \Omega_1$; then $Mx = \lambda Nx$, $D_{0+}^{\alpha}x(0) = x'(0) = 0$, and $Nx \in \text{Im } M$. By (25), we have

$$\int_0^1 (1 - s)^{\beta-1} f(s, x(s), D_{0+}^{\alpha}x(s)) ds = 0. \quad (42)$$

Then, by the integral mean value theorem, there exists a constant $\xi \in (0, 1)$ such that $f(\xi, x(\xi), D_{0+}^{\alpha}x(\xi)) = 0$. So, from (H_2) , we get $|x(\xi)| \leq B$. By $x'(0) = 0$, we get

$$\begin{aligned} & x(t) = x(0) + x'(0)t + I_{0+}^{\alpha}D_{0+}^{\alpha}x(t) \\ &= x(0) + \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} D_{0+}^{\alpha}x(s) ds. \end{aligned} \quad (43)$$

Take $t = \xi$; we have

$$x(\xi) = x(0) + \frac{1}{\Gamma(\alpha)} \int_0^{\xi} (\xi - s)^{\alpha-1} D_{0+}^{\alpha}x(s) ds. \quad (44)$$

Then we have

$$\begin{aligned} |x(0)| &\leq |x(\xi)| + \frac{1}{\Gamma(\alpha)} \int_0^\xi (\xi-s)^{\alpha-1} |D_{0+}^\alpha x(s)| ds \\ &\leq |x(\xi)| + \frac{1}{\Gamma(\alpha)} \|D_{0+}^\alpha x\|_\infty \cdot \frac{1}{\alpha} \xi^\alpha \\ &\leq B + \frac{1}{\Gamma(\alpha+1)} \|D_{0+}^\alpha x\|_\infty. \end{aligned} \quad (45)$$

So we get

$$\begin{aligned} |x(t)| &\leq |x(0)| + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |D_{0+}^\alpha x(s)| ds \\ &\leq |x(0)| + \frac{1}{\Gamma(\alpha)} \|D_{0+}^\alpha x\|_\infty \cdot \frac{1}{\alpha} t^\alpha \\ &\leq B + \frac{2}{\Gamma(\alpha+1)} \|D_{0+}^\alpha x\|_\infty, \quad \forall t \in [0, 1]. \end{aligned} \quad (46)$$

That is,

$$\|x\|_\infty \leq B + \frac{2}{\Gamma(\alpha+1)} \|D_{0+}^\alpha x\|_\infty. \quad (47)$$

By $Mx = \lambda Nx$ and $D_{0+}^\alpha x(0) = 0$, we get

$$\begin{aligned} \phi_p(D_{0+}^\alpha x(t)) &= \lambda I_{0+}^\beta Nx(t) \\ &= \frac{\lambda}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} f(s, x(s), D_{0+}^\alpha x(s)) ds. \end{aligned} \quad (48)$$

So, from (H_1) , we have

$$\begin{aligned} |\phi_p(D_{0+}^\alpha x(t))| &\leq \frac{1}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} |f(s, x(s), D_{0+}^\alpha x(s))| ds \\ &\leq \frac{1}{\Gamma(\beta)} \int_0^t (t-s)^{\beta-1} (a(s) + b(s) |x(s)|^{p-1} \\ &\quad + c(s) |D_{0+}^\alpha x(s)|^{p-1}) ds \\ &\leq \frac{1}{\Gamma(\beta)} (\|a\|_\infty + \|b\|_\infty \|x\|_\infty^{p-1} \\ &\quad + \|c\|_\infty \|D_{0+}^\alpha x\|_\infty^{p-1}) \cdot \frac{1}{\beta} t^\beta \\ &\leq \frac{1}{\Gamma(\beta+1)} (\|a\|_\infty + \|b\|_\infty \|x\|_\infty^{p-1} \\ &\quad + \|c\|_\infty \|D_{0+}^\alpha x\|_\infty^{p-1}), \quad \forall t \in [0, 1], \end{aligned} \quad (49)$$

which together with $|\phi_p(D_{0+}^\alpha x(t))| = |D_{0+}^\alpha x(t)|^{p-1}$ and (47) yields that

$$\begin{aligned} \|D_{0+}^\alpha x\|_\infty^{p-1} &\leq \frac{1}{\Gamma(\beta+1)} [\|a\|_\infty + \|b\|_\infty \\ &\quad \times \left(B + \frac{2}{\Gamma(\alpha+1)} \|D_{0+}^\alpha x\|_\infty\right)^{p-1} \\ &\quad + \|c\|_\infty \|D_{0+}^\alpha x\|_\infty^{p-1}]. \end{aligned} \quad (50)$$

In view of (23), we can see that there exists a constant $M_1 > 0$ such that

$$\|D_{0+}^\alpha x\|_\infty \leq M_1. \quad (51)$$

Thus, from (47), we get

$$\|x\|_\infty \leq B + \frac{2M_1}{\Gamma(\alpha+1)} := M_2. \quad (52)$$

Combining (51) with (52), we have

$$\|x\|_X = \max\{\|x\|_\infty, \|D_{0+}^\alpha x\|_\infty\} \leq \max\{M_1, M_2\} := M. \quad (53)$$

Therefore, Ω_1 is bounded. The proof is complete. $\square$

Lemma 11. Suppose that (H_2) holds; then the set

$$\Omega_2 = \{x \in \text{Ker } M \mid Nx \in \text{Im } M\} \quad (54)$$

is bounded.

Proof. For $x \in \Omega_2$, we have $x(t) = c$, $c \in \mathbb{R}$ and $Nx \in \text{Im } M$. Then we get

$$\int_0^1 (1-s)^{\beta-1} f(s, c, 0) ds = 0, \quad (55)$$

which together with (H_2) implies $|c| \leq B$. Thus, we have

$$\|x\|_X \leq \max\{B, 0\} = B. \quad (56)$$

Hence, Ω_2 is bounded. The proof is complete. $\square$

Lemma 12. Suppose that the first part of (H_2) holds; then the set

$$\Omega_3 = \{x \in \text{Ker } M \mid \lambda x + (1-\lambda)QNx = 0, \lambda \in [0, 1]\} \quad (57)$$

is bounded.

Proof. For $x \in \Omega_3$, we have $x(t) = c$, $c \in \mathbb{R}$, and

$$\lambda c + (1-\lambda)\beta \int_0^1 (1-s)^{\beta-1} f(s, c, 0) ds = 0. \quad (58)$$

If $\lambda = 0$, then $|c| \leq B$ because of the first part of (H_2) . If $\lambda \in (0, 1]$, we can also obtain $|c| \leq B$. Otherwise, if $|c| > B$, in view of the first part of (H_2) , one has

$$\lambda c^2 + (1-\lambda)\beta \int_0^1 (1-s)^{\beta-1} cf(s, c, 0) ds > 0, \quad (59)$$

which contradicts (58). Therefore, Ω_3 is bounded. The proof is complete. $\square$

Remark 13. If the second part of (H_2) holds, then the set

$$\Omega'_3 = \{x \in \text{Ker } M - \lambda x + (1 - \lambda) QNx = 0, \lambda \in [0, 1]\} \quad (60)$$

is bounded.

Theorem 14. Let $f : [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ be continuous. Suppose that (H_1) , (H_2) hold. Then BVP (4) has at least one solution.

Proof. Set $\Omega = \{x \in X \mid \|x\|_X < \max\{M, B\} + 1\}$. It follows from Lemmas 8 and 9 that M is a quasilinear operator and N_λ is M -compact on $\bar{\Omega}$. By Lemmas 10 and 11, we get that the following two conditions are satisfied:

$$\begin{aligned} (C_1) \quad & Mx \neq N_\lambda x, \forall (x, \lambda) \in (\text{dom } M \cap \partial\Omega) \times (0, 1), \\ (C_2) \quad & QNx \neq 0, \text{ for } x \in \text{dom } M \cap \partial\Omega. \end{aligned}$$

Take

$$H(x, \lambda) = \pm \lambda x + (1 - \lambda) QNx. \quad (61)$$

According to Lemma 12 (or Remark 13), we know that $H(x, \lambda) \neq 0$ for $x \in \text{Ker } M \cap \partial\Omega$. Therefore

$$\begin{aligned} \deg(QN|_{\text{Ker } M}, \Omega \cap \text{Ker } M, 0) \\ &= \deg(H(\cdot, 0), \Omega \cap \text{Ker } M, 0) \\ &= \deg(H(\cdot, 1), \Omega \cap \text{Ker } M, 0) \\ &= \deg(\pm I, \Omega \cap \text{Ker } M, 0) \neq 0. \end{aligned} \quad (62)$$

So the condition (C_3) of Lemma 7 is satisfied. By Lemma 7, we can get that $Mx = Nx$ has at least one solution in $\text{dom } M \cap \bar{\Omega}$. Therefore BVP (4) has at least one solution. The proof is complete. $\square$

3. Example

In this section, we will give an example to illustrate our main result.

Example 1. Consider the following BVP:

$$\begin{aligned} D_{0+}^{3/4} \phi_3(D_{0+}^{3/2} x(t)) &= -\frac{25}{3} + \frac{1}{3} x^2(t) \\ &\quad + te^{-|D_{0+}^{3/2} x(t)|}, \quad t \in [0, 1], \end{aligned} \quad (63)$$

$$D_{0+}^{3/2} x(0) = D_{0+}^{3/2} x(1) = x'(0) = 0.$$

Corresponding to BVP (4), we get that $p = 3$, $\alpha = 3/2$, $\beta = 3/4$, and

$$f(t, u, v) = -\frac{25}{3} + \frac{1}{3} u^2 + te^{-|v|}. \quad (64)$$

Choose $a(t) = 10$, $b(t) = 1/3$, $c(t) = 0$, $B = 5$. By a simple calculation, we can get that $\|b\|_\infty = 1/3$, $\|c\|_\infty = 0$ and

$$\frac{1}{\Gamma(3/4 + 1)} \left(\frac{2/3}{(\Gamma(3/2 + 1))^2} + 0 \right) < 1. \quad (65)$$

Obviously, BVP (63) satisfies all conditions of Theorem 14. Hence, it has at least one solution.

4. Conclusions

In this paper, the boundary value problem for p -Laplacian equation at resonance is investigated. In view of the boundary value problem (4) is equivalent to the operator equation (19); we only need to find a fixed point of the operator equation (19). Firstly, we established the sufficient conditions of existence of boundary value problem for p -Laplacian equation. Then, by using the extension of Mawhin's continuation theorem due to Ge, we got the fixed point of operator equation (19).

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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