Research Article

Exact Solutions of the Dirac Hamiltonian on the Sphere under Hyperbolic Magnetic Fields

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Two-dimensional massless Dirac Hamiltonian under the influence of hyperbolic magnetic fields is mentioned in curved space. Using a spherical surface parameterization, the Dirac operator on the sphere is presented and the system is given as two supersymmetric partner Hamiltonians which coincides with the position dependent mass Hamiltonians. We introduce two ansatzes for the component of the vector potential to acquire effective solvable models, which are Rosen-Morse II potential and the model given Midya and Roy, whose bound states are Jacobi X_1 type polynomials, and we adapt our work to these special models under some parameter restrictions. The energy spectrum and the eigenvectors are found for Rosen-Morse II potential. On the other hand, complete solutions are given for the second system. The vector and the effective potentials with their eigenvalues are sketched for each system.

1. Introduction

Since the isolation of graphene investigated in 2004 by Novoselov et al. [1], this new material has spurred an intense interest in its applications in the fields of the condensed matter physics and the quantum field theory. The charge carriers in flat graphene are modeled in continuum by the Dirac-Weyl operator for massless fermions [2, 3]. Apart from some spectacular properties of graphene such as the half-integer quantum Hall effect [1, 2, 4–6], observation of Klein tunneling for the two-dimensional massless Dirac electrons [7–9], algebraic approaches to impurities [10], and graphene wormholes [11], interesting flexural modes of the graphene have also attracted much attention [12–17]. According to the Landau-Peierls theorem, the flat graphene does not exist at all [18, 19]. The curvature effects on the quality factor of the graphene nanoresonators can be found in [20]. Moreover, it is seen that graphene nanoribbons can be the solution of improving energy storage in ultra-high capacitors and bending nanodevices [21–23]. In this manner, instead of a flat graphene, curved graphene has such mechanical and electrical properties that lead to the possibility of a bending

component of some nanodevices. In the relativistic territory, the Dirac equation in curved spacetime has been studied as its generalization to the Robertson-Walker spacetime in a Cartesian tetrad gauge [24], the gravitational effects in Hydrogen atom [25], bound states of the Dirac equation in gravitational fields [26], exact solutions in $(1+1)$ and $(2+1)$ dimensions [27, 28], some conditions on the modified Dirac equation which admits a symmetry operator [29], and the Hawking-Unruh phenomenon on graphene [30]. On the other hand, the system on the two-sphere or on the pseudo-sphere is related to some interesting generalizations of the planar Landau level problems [31, 32]. The supersymmetry is known to be responsible for the mathematical structure of the Landau levels. The Pauli Hamiltonian for a nonrelativistic spin-1/2 particle possesses $N = 2$ supersymmetry [33, 34]. The Dirac equation and its analysis and discussion within supersymmetric quantum mechanics can be found in [35–39]. Moreover, extending a study of Bochner [40], exceptional orthogonal polynomials were introduced first in [41]. Later, it is shown that there is a relation between exceptional orthogonal polynomials and the Darboux transformation [42, 43].

In this study, the Dirac equation in curved space is written for the curved graphene models to show that an exactly solvable bound state model for the Dirac equation in a two-dimensional curved space can be reduced into a Schrödinger-like operator and the bound states can be discussed using the concepts of quantum mechanics. Rosen-Morse II potential (hyperbolic Rosen-Morse) model is studied as a first example and the next one is related with the soliton models [44]. This potential family is empirically useful to investigate the polyatomic vibrational states of NH_3 molecule [45]. Also, trigonometric Rosen-Morse potential is studied in the confinement phenomena of quarks in hadrons and this potential is responsible for the quark-gluon dynamics through the QCD calculations [46, 47]. Hyperbolic potentials are popular in nonrelativistic quantum mechanics with their soliton models [48]. Considering these instanton structures, hyperbolic interactions and their connection with the QCD and Morse-Rosen potentials can be found in an interesting work [49]. Also, actual relativistic vibrational states for the molecules are studied in [50]. Thus, our study may be a motivation in the relativistic domain for the relevant QCD models.

2. Dirac Operator in Two-Dimensional Curved Space

On a two-dimensional surface, the Dirac operator is given by [51]

$$\mathcal{H}_D = -i\gamma^a \left(E_a^\mu \partial_\mu + \frac{1}{2} E_a^\mu \partial_\mu \ln \sqrt{g} + \frac{1}{2} \partial_\mu E_a^\mu \right). \quad (1)$$

The symbol γ^μ corresponds to the generalized Dirac matrices satisfying the relation

$$\gamma^a E_a^\mu = \gamma^\mu \quad (2)$$

and the anticommutation relation is

$$\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu}. \quad (3)$$

Here, E_a^μ are the tetrad fields, g is the determinant of the metric tensor, and $g_{\mu\nu}$ is the metric tensor for the curved spacetime; the Latin indices refer to local inertial frame and the Greek indices refer to curved spacetime. Generally, $g_{\mu\nu}$ is given by

$$g_{\mu\nu}(\mathbf{x}) = \eta_{ab} e_\mu^a(\mathbf{x}) e_\nu^b(\mathbf{x}), \quad (4)$$

where $\mathbf{x} = (t, x)$, $\eta_{ab} = \text{diag}(+1, -1)$, and e_μ^a and E_a^μ are zweibeins and their inverse satisfies

$$\delta^{ab} E_a^\mu E_b^\nu = g^{\mu\nu}, \quad g_{\mu\nu} E_a^\mu E_b^\nu = \delta_{ab}. \quad (5)$$

The conformal metric tensor is given by [51]

$$g_{\mu\nu} = e^{2\sigma} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad (6)$$

where $\sigma(\vec{x})$ is a spatial function. Using (5) and (6), we obtain $E_a^\nu = e^{-\sigma} \delta_a^\nu$. As it is explained in [51], $P_\mu = -i\partial_\mu$ is the flat

momentum operator replaced by $P_\mu \rightarrow P_\mu - A_\mu$, where A_μ is the vector potential which is spatial dependent. In two dimensions, Dirac matrices reduce to Pauli matrices; then, the Dirac operator becomes

$$\mathcal{H}_D = -2ie^\sigma \begin{pmatrix} 0 & \partial_z - iA_z + \frac{1}{2}\partial_z \sigma \\ \partial_{z^*} - iA_{z^*} + \frac{1}{2}\partial_{z^*} \sigma & 0 \end{pmatrix}, \quad (7)$$

where $*$ denotes the complex conjugate and the transformation $z = x^1 + ix^2$ is used in the Hamiltonian above for the sake of simplicity. In this manner, we use $\partial_z = (1/2)(\partial_1 - i\partial_2)$, $A_z = (1/2)(A_1 - iA_2)$. The operator (7) is also studied in [52]. Now we take $\mathcal{H}_D$ which can be mapped to the operator $\overline{\mathcal{H}}_D$ using a transformation operator U as

$$\overline{\mathcal{H}}_D = U \mathcal{H}_D U^{-1}, \quad U = \begin{pmatrix} e^{\sigma/2} & 0 \\ 0 & e^{\sigma/2} \end{pmatrix}. \quad (8)$$

Therefore, we have

$$\overline{\mathcal{H}}_D = \alpha \begin{pmatrix} 0 & \partial_1 - i\partial_2 - iA_1 - A_2 \\ \partial_1 + i\partial_2 - iA_1 + A_2 & 0 \end{pmatrix}, \quad (9)$$

where $\alpha = -ie^\sigma$. Let us bring the attention to the isothermal coordinates and parameterization [53]. Because the topological equivalent of a layer is known as a sphere, then we may deal with a sphere with radii R and the surface parameterization of the sphere is given by

$$\mathbf{x}(u, v) = R(\cos u \cos v, \sin u \cos v, \sin v), \quad (10)$$

and the metric can be written as

$$\begin{aligned} (ds)^2 &= R^2 (\cos^2 v du^2 + dv^2) \\ &= R^2 \cos^2 v \left(du + i \frac{dv}{\cos v} \right) \left(du - i \frac{dv}{\cos v} \right). \end{aligned} \quad (11)$$

We may rewrite the metric using the transformation $w = \log(\tan v + \sec v)$. Then, the metric of the patch is written as

$$ds^2 = \lambda^2 (du^2 + dw^2), \quad (12)$$

where $\lambda = R \cos v$. If we use the transformation $\cosh w = \sec v$, we get $e^\sigma = R \text{sech } w$. It can be pointed out that the eigenvectors of the operator $\overline{\mathcal{H}}_D$ are $\Psi = e^{iku} \begin{pmatrix} \psi_1 \\ i\psi_2 \end{pmatrix}$, where we take $x^1 = w$ and $x^2 = u$, and k is the wave number. We also note that the vector potential and its components are selected as $A_\mu = [0, A_u(w), 0]$. Let us now look at the eigenvalue equation $\overline{\mathcal{H}}_D \Psi(\vec{x}) = E \Psi(\vec{x})$.

3. Dirac Hamiltonians

The Dirac Hamiltonian in (9) can be rewritten as

$$\begin{aligned} \alpha (\partial_w - i\partial_u - A_u(w)) (e^{iku} \psi_2(w)) &= E (e^{iku} \psi_1(w)), \\ \alpha (\partial_w + i\partial_u - A_u(w)) (e^{iku} \psi_1(w)) &= E (e^{iku} \psi_2(w)). \end{aligned} \quad (13)$$

The equations given above lead to

$$\mathcal{H}_D^j \psi_j(w) = \bar{E}^2 \psi_j(w), \quad \bar{E} = ER, \quad (14)$$

where $j = 1, 2$. Then, Hamiltonians, $\mathcal{H}_D^j$, shown in a joint expression can be given as

$$\begin{aligned} \mathcal{H}_D^j = & -\cosh^2 w \frac{d^2}{dw^2} - \sinh w \cos hw \frac{d}{dw} \\ & + \left[\left((k - A_u(w))^2 + (-1)^j A'(w) \right) \cosh^2 w \right. \\ & \left. + (-1)^j (A_u(w) - k) \cosh w \sinh w \right]. \end{aligned} \quad (15)$$

We may transform (14) into a Sturm-Liouville type equation using a similarity transformation. We obtain

$$\begin{aligned} \mathfrak{h}_j &= \rho^{-1} \bar{\mathcal{H}}_D^j \rho, \\ \rho &= \sqrt{\cosh w} \implies \mathfrak{h}_j \\ &= -\cosh^2 w \frac{d^2}{dw^2} - 2 \sinh w \cos hw \frac{d}{dw} + V_{\text{eff}}^j(w), \end{aligned} \quad (16)$$

where

$$\begin{aligned} V_{\text{eff}}^j(w) &= \left((k - A_u(w))^2 + (-1)^j A'(w) \right) \cosh^2 w \\ &+ (-1)^j (A_u(w) - k) \cosh w \sinh w \\ &- \frac{3}{4} \cosh^2 w + \frac{1}{4}. \end{aligned} \quad (17)$$

Thus, the transformed Dirac system can be given as

$$\mathfrak{h}_j \phi_j = \bar{E}^2 \phi_j, \quad \phi_j = \rho \psi_j. \quad (18)$$

We emphasize that the solutions $\phi_{j,n}$ have to satisfy $\int_{\Omega} \{ |\phi_{1,n}(w)|^2 + |\phi_{2,n}(w)|^2 \} dw < \infty$ for the physical reasons, and here n is a quantum number. We will examine (18) in the following section using the choices of $A_u(w)$.

3.1. Hyperbolic Model I. Let us choose $A_u(w)$ as

$$A_u(w) = C_1 \text{sech}^2 w + C_2 \tanh w + C_3, \quad (19)$$

where C_1, C_2, C_3 are constants; we may obtain

$$\begin{aligned} \bar{V}_{\text{eff}}^1(w) &= -C_2 + 2C_1 C_3 - 2C_1 k \\ &+ \left((C_3 - k)^2 - \frac{1}{2} \right) \cosh^2 w + C_1^2 \text{sech}^2 w \\ &+ (-C_3 + 2C_2 C_3 + k - 2C_2 k) \cosh w \sinh w \\ &+ \left(C_2^2 - C_2 - \frac{1}{4} \right) \sinh^2 w + C_1 (1 + 2C_2) \tanh w. \end{aligned} \quad (20)$$

Equating the coefficients of $\cosh w \sinh w$, $\cosh^2 w$, and $\sinh^2 w$ to zero, one can obtain C_2 and C_3 as

$$\{(C_2); (C_3)\} = \left\{ \left(-\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{3}{2} \right); (k, -1+k, 1+k, k) \right\}. \quad (21)$$

Thus, (20) becomes

$$\begin{aligned} \bar{V}_{\text{eff}}^1(w) &= C_1^2 \text{sech}^2 w + C_1 (1 + 2C_2) \tanh w \\ &+ \left(C_2 - \frac{1}{2} \right)^2 + 2C_1 (C_3 - k) - \frac{1}{2}, \end{aligned} \quad (22)$$

and also $V_{\text{eff}}^2(w)$ turns into

$$\begin{aligned} \bar{V}_{\text{eff}}^2(w) &= C_1^2 \text{sech}^2 w + C_1 (-1 + 2C_2) \tanh w \\ &+ 2C_2 \cosh^2 w + 2(C_3 - k) \cosh w \sinh w \\ &+ \left(C_2 + \frac{1}{2} \right)^2 - 2C_1 (C_3 - k) - \frac{1}{2}. \end{aligned} \quad (23)$$

As it is seen from (23), $V_{\text{eff}}^2(w)$ is not a solvable potential model while (22) is known as Rosen-Morse II potential [54]. As a result, they are not shape invariant potentials but they share the same energy spectrum except the ground state. If we take $C_2 \neq -1/2$, this implies $C_3 = k - 1$, $C_3 = k + 1$, or $C_3 = k$. Next, we will come up with the whole solutions of the system (22). Hence, we use the transformations given in (18)

$$\phi_1 = \text{sech}^2 w G(t), \quad t = \tanh w \quad (24)$$

and we get

$$\begin{aligned} \frac{d^2 G}{dt^2} - \frac{4t}{1-t^2} \frac{dG}{dt} + \frac{1}{(1-t^2)^2} \\ \times \left(\bar{E}^2 - (C_1^2 + 2)(1-t^2) - C_1(1+2C_2 t) \right. \\ \left. - \left(C_2 - \frac{1}{2} \right)^2 - 2C_1(C_3 - k) + \frac{1}{2} \right) G(t) = 0. \end{aligned} \quad (25)$$

We propose a solution which is $G(t) = (1-t)^{(a-1)/2} (1+t)^{(b-1)/2} F(t)$, where $F(t)$ is a polynomial that we look for and we obtain

$$\begin{aligned} (1-t^2) \frac{d^2 F}{dt^2} + (b-a-(a+b+2)t) \frac{dF}{dt} \\ + \frac{1}{1-t^2} (At^2 + Bt + C) F(t) = 0, \end{aligned} \quad (26)$$

where A, B, C are constants. Hence, the solutions of the system are given as

$$E_{1,n} = \pm \frac{1}{R} \left(\frac{1}{2} + 2C_1(k - C_3) - \left(C_2 - \frac{1}{2}\right)^2 - \left(\frac{-1 + \sqrt{1 - 4C_1^2}}{2} - n \right)^2 - \frac{(C_1(1 + 2C_2)/2)^2}{\left(\left(-1 + \sqrt{1 - 4C_1^2} \right) / 2 - n \right)^2} \right)^{1/2}, \quad (27)$$

$$\phi_{1,n} = N_1(1 - \tanh w)^{(-1 + \sqrt{1 - 4C_1^2})/2} (1 + \tanh w)^{C_1(1 + 2C_2)/2} \times P_n^{(-1 + \sqrt{1 - 4C_1^2}, C_1(1 + 2C_2))}(\tanh w), \quad (28)$$

where the symbol $P_n^{(\cdot, \cdot)}(\tanh w)$ corresponds to the Jacobi polynomials. We also note that $C_1 < 1/2$ for the physical solutions. It is noted that $\bar{V}_{\text{eff}}^2(w)$ which is not a solvable model shares the same spectrum with $\bar{V}_{\text{eff}}^1(w)$ except for the ground state [54] (Figure 1).

3.2. Hyperbolic Model II. If we set A_u as given below

$$A_u(w) = C_1 \text{sech}^2 w + C_2 \frac{\text{sech}^2 w \tanh w}{a_1 \tanh w - a_2} + C_3 \tanh w + C_4, \quad (29)$$

where we use constants C_1, C_2, C_3, C_4 , we may get

$$\begin{aligned} \bar{V}_{\text{eff}}^1(w) &= \frac{1}{4} - C_3 + 2C_1C_4 - 2C_1k \\ &+ \left(-\frac{3}{4} + (k - C_4)^2 \right) \cosh^2 w + C_1^2 \text{sech}^2 w \\ &+ C_3(C_3 - 1) \sinh^2 w \\ &+ (k - C_4 + 2C_3C_4 - 2C_3k) \cosh w \sinh w \\ &+ C_1(1 + 2C_3) \tanh w - \frac{C_2 \text{sech}^2 w}{a_1 \tanh w - a_2} \\ &+ \frac{a_1 C_2 \text{sech}^2 w \tanh w}{(a_1 \tanh w - a_2)^2} + \frac{C_2^2 \text{sech}^2 w \tanh^2 w}{(a_1 \tanh w - a_2)^2} \\ &+ \frac{2C_2(C_4 - k) \tanh w}{a_1 \tanh w - a_2} + \frac{2C_1C_2 \text{sech}^2 w \tanh w}{(a_1 \tanh w - a_2)} \\ &+ \frac{C_2(1 + 2C_3) \tanh^2 w}{a_1 \tanh w - a_2}. \end{aligned} \quad (30)$$

In [44], it is shown that a class of exactly solvable potentials, whose solutions correspond to the Jacobi-type X_1 exceptional orthogonal polynomials, can be generated. In their work, the eigenvalue equation is given by [44]

$$H_{\text{eff}} \psi(x) = \varepsilon \psi(x), \quad H_{\text{eff}} = -\Delta + v_{\text{eff}}(x), \quad (31)$$

where $\psi(x) = f(x)F(g(x))$ and $F(g(x))$ satisfies the differential equation which is

$$\frac{d^2 F}{dg^2} + Q(g) \frac{dF}{dg} + R(g) F = 0. \quad (32)$$

The authors choose $F_n \sim P_n^{(\alpha, \beta)}(x)$, $n = 1, 2, 3, \dots$, $\alpha, \beta > -1$, $\alpha \neq \beta$, where $P_n^{(\alpha, \beta)}(x)$ is the Jacobi-type X_1 polynomial in Example 2 in their work and obtain

$$\begin{aligned} \varepsilon - v_{\text{eff}}(x) &= \frac{g'}{\lambda} \left(\frac{A_1 g + A_2}{1 - g^2} + \frac{A_3 g + A_4}{(1 - g^2)^2} \right. \\ &\quad \left. + \frac{A_5}{(\beta - \alpha)g - (\beta + \alpha)} + \frac{A_6}{((\beta - \alpha)g - (\beta + \alpha))^2} \right), \end{aligned} \quad (33)$$

where A_i , $i = 1, 2, \dots, 6$ are constants in terms of α, β [44] and $g(x) = \tanh x$ and λ is a constant. If $g(x)$ is used in (33), then we get

$$\begin{aligned} \varepsilon - v_{\text{eff}}(x) &= \frac{A_6 \text{sech}^2 x}{(a_1 \tanh x - a_2)^2} + \frac{A_5 \text{sech} x}{(a_1 \tanh x - a_2)} \\ &+ A_4 \cosh^2 x + A_3 \sinh x \cosh x + A_2 + A_1 \tanh x. \end{aligned} \quad (34)$$

If we compare (30) and (33) we see that $\lambda = 1$, $a_1 = \beta - \alpha$, and $a_2 = \beta + \alpha$ in our problem. The energy spectrum and the solutions of (31) are given in [44]. Hence, we continue to compare $\varepsilon - v_{\text{eff}}(x)$ and $\bar{E}^2 - \bar{V}_{\text{eff}}^1(w)$ which may provide complete solutions of our system without solving a differential equation. Let us add and subtract the terms $C_5 \text{sech}^2 w / (-a_2 + a_1 \tanh w) + C_6$ to the right-hand side of (30). Then, we shall obtain

FIGURE 1: The graphs of (a) component of the vector potential $A_u(w)$ in (19), effective models (b) $\bar{V}_{\text{eff},1}$ (22) and (c) $\bar{V}_{\text{eff},2}$ (23) for the values of $C_1 = 0.4$, $C_2 = 0.5$, $R = 1$, $C_3 = k + 1$, and $k = 2$, and (d) the energies $\pm E_{1,n}$ in (27) for $k = 200$. There are bound states only for $n = 0, 1, 2$ and $\bar{V}_{\text{eff},2}$ is an increasing function in the positive domain while $\bar{V}_{\text{eff},1}$ remains nearly constant. The scalar component of the vector potential A_u is similar to $\bar{V}_{\text{eff},1}$.

$$\begin{aligned}
 \bar{V}_{\text{eff}}^1(w) = & \frac{1}{4} - C_6 + 2C_1C_4 - 2C_1k - C_3^2 \\
 & + \left((k - C_4)^2 + \left(C_3 - \frac{1}{2} \right)^2 - 1 \right) \cosh^2 w \\
 & + (k - C_4 + 2C_3C_4 - 2C_3k) \cosh w \sinh w \\
 & + C_1(1 + 2C_3) \tanh w \\
 & - \frac{(C_2 + C_5) \text{sech}^2 w}{a_1 \tanh w - a_2} + \frac{(a_2^2 C_1^2 - a_1 a_2 C_1) \text{sech}^2 w}{(a_1 \tanh w - a_2)^2}, \\
 & + \frac{a_1^2 C_1 (1 + C_1 \tanh w) \text{sech}^2 w \tanh w}{(a_1 \tanh w - a_2)^2} \\
 & + \frac{2a_1 C_1 (k - C_4) \tanh w}{a_1 \tanh w - a_2} \\
 & - \frac{2a_1 C_1^2 \text{sech}^2 w \tanh w}{a_1 \tanh w - a_2} \\
 & + \frac{a_1 C_1 (1 - 2C_3) \tanh^2 w}{a_1 \tanh w - a_2}.
 \end{aligned} \tag{35}$$

$$\begin{aligned}
 \bar{V}_{\text{eff}}^2(w) = & \frac{1}{4} - C_3 + 2C_1C_4 - 2C_1k \\
 & + \left((k - C_4)^2 - \frac{3}{4} \right) \cosh^2 w + C_3(1 + C_3) \sinh^2 w \\
 & + (C_4 - k + 2C_3C_4 - 2C_3k) \cosh w \sinh w \\
 & + C_1(-1 + 2C_3) \tanh w - \frac{a_1 C_1 \text{sech}^2 w}{a_1 \tanh w - a_2}
 \end{aligned}$$

Here we may use some constraints on the parameters which may be expressed in terms of C_1 ,

$$\begin{aligned}
 C_2 = -a_1 C_1, \quad C_3 = -\frac{a_1^2 - a_2^2 - 2a_1 a_2 k}{2(a_1^2 - a_2^2)}, \\
 C_4 = -\frac{a_2^2 k}{a_1^2 - a_2^2}, \quad C_5 = -2a_1 C_1 C_3, \\
 C_6 = \frac{2a_1^2 k C_1}{a_1^2 - a_2^2}.
 \end{aligned} \tag{36}$$

(37)

FIGURE 2: The graphs of (a) component of the vector potential $A_u(w)$ in (29), effective models (b) $\bar{V}_{\text{eff},1}$ (35) and (c) $\bar{V}_{\text{eff},2}$ (36), and (d) the energy $E_{1,m}$ in (40). The effective potential well $\bar{V}_{\text{eff},2}$ and $\bar{V}_{\text{eff},1}$, and $A_u(w)$ have the same singularity point. Energy eigenvalues are increasing.

Under these constraints, $\bar{V}_{\text{eff}}^1$ can be obtained as given in (35). Now we can compare (34) and (35) using A_i , $i = 1, 2, \dots, 6$ given in [44]. These constants are given as [44]

$$\begin{aligned}
 A_1 &= \frac{\beta^2 - \alpha^2}{2\alpha\beta}, \\
 A_2 &= n^2 + (\beta + \alpha - 1)n \\
 &\quad + \frac{1}{4}((\beta + \alpha)^2 - 2(\beta + \alpha) - 4) + \frac{\beta^2 + \alpha^2}{2\alpha\beta}, \\
 A_3 &= \frac{\beta^2 - \alpha^2}{2}, \quad A_4 = -\frac{\beta^2 + \alpha^2 - 2}{2}, \\
 A_5 &= \frac{(\beta + \alpha)(\beta - \alpha)^2}{2\alpha\beta}, \quad A_6 = -2(\beta - \alpha)^2.
 \end{aligned} \tag{38}$$

Using (34), (35), (37), and (38), we obtain

$$\beta = \pm \frac{1}{1+k}, \quad \alpha = \pm \frac{1}{1-k}. \tag{39}$$

The energy eigenvalues and corresponding wave functions of the system are given in [44]. Using the results of [44] we may give the spectrum of our system as

$$\begin{aligned}
 E_{1,m} &= \pm \frac{1}{R} \left(\left(m + \frac{\alpha + \beta}{2} \right) \left(m + \frac{\alpha + \beta + 2}{2} \right) \right. \\
 &\quad \left. + \frac{\beta}{\alpha} - \frac{\alpha^2 + \beta^2 - 2}{4} - \frac{k^2}{(1+k^2)^2} \right)^{1/2},
 \end{aligned} \tag{40}$$

where $m = n - 1$, $m = 0, 1, 2, \dots$ and one can see that the inside of the square root is positive. And the solutions are given by [44]

$$\begin{aligned}
 \phi_{1,m}(w) &= N_m \frac{(1 - \tanh w)^{(\alpha+1)/2} (1 + \tanh w)^{(\beta+1)/2}}{\alpha + \beta + (\alpha - \beta) \tanh w} \\
 &\quad \times P_{m+1}^{(\alpha, \beta)}(\tanh w),
 \end{aligned} \tag{41}$$

where N_m is the normalization constant. Hence, $\bar{V}_{\text{eff}}^2(w)$ also shares the same energy except for the ground state [54] (Figure 2),

$$E_{1,m} = E_{2,m-1}, \quad m = 1, 2, \dots \tag{42}$$

4. Conclusion

In this paper, we have studied the quantum behavior of a massless two-dimensional Dirac particle subjected to a hyperbolic magnetic field in the curved space which is a two-dimensional surface on the sphere. Using appropriate transformations, we have given the Dirac Hamiltonian system a pair of first order differential equations and, then, effective Dirac Hamiltonians are expressed. Two specific models are studied according to the special choices of $A_u(w)$. In fact, $\mathfrak{h}_j$ is the physical Hamiltonian of the system with a coefficient of the second order derivative, and $\cosh^2 w$ corresponds to the inverse of the mass function in the position dependent mass Hamiltonian theories. We have seen that this specific choice leads to two specific exactly solvable effective potential models. In the first example, the Rosen-Morse II effective potential is obtained under some parameter restrictions. Energy eigenvalues and corresponding eigenfunctions are obtained using polynomial solutions. In the latter case we have adapted our model Hamiltonian $\mathfrak{h}_j$ to a general one given in Example 2 in [44] and the bound state solutions are written. The partner potential $\bar{V}_{\text{eff}}^2$ is different and more general than those obtained in [44]. On the contrary to the results in [44], the partner potentials are not shape invariant in our case. We also note that we have obtained only a limited number of bound states for the Rosen-Morse II effective potential and when the radius of the sphere approaches infinity, the energy of the system becomes zero in each case.

Conflict of Interests

The author declares that there is no conflict of interests regarding the publication of this paper.

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