Research Article

The Maxwell-Boltzmann-Euler System with a Massive Scalar Field in All Bianchi Spacetimes

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We prove the existence and uniqueness of regular solution to the coupled Maxwell-Boltzmann-Euler system, which governs the collisional evolution of a kind of fast moving, massive, and charged particles, globally in time, in a Bianchi of types I to VIII spacetimes. We clearly define function spaces, and we establish all the essential energy inequalities leading to the global existence theorem.

1. Introduction

In this paper, we study the coupled Maxwell-Boltzmann-Euler system which governs the collisional evolution of a kind of fast moving, massive, and charged particles and which is one of the basic systems of the kinetic theory.

The spacetimes considered here are the Bianchi of types I to VIII spacetimes where homogeneous phenomena such as the one we consider here are relevant. Note that the whole universe is modeled and particles in the kinetic theory may be particles of ionized gas as nebular galaxies or even cluster of galaxies, burning reactors, and solar wind, for which only the evolution in time is really significant, showing thereafter the importance of homogeneous phenomena.

The relativistic Boltzmann equation rules the dynamics of a kind of particles subject to mutual collisions, by determining their distribution function, which is a nonnegative real-valued function of both the position and the momentum of the particles. Physically, this function is interpreted as the probability of the presence density of the particles in a given volume, during their collisional evolution. We consider the case of instantaneous, localized, binary, and elastic collisions. Here the distribution function is determined by the Boltzmann equation through a nonlinear operator called the collision operator. The operator acts only on the momentum of the particles and describes, at any time, at each point where two particles collide with each other, the effects of the behaviour imposed by the collision on the distribution function, also taking in account the fact that the momentum of each particle is not the same, before and after the collision, with only the sum of their two momenta being preserved.

The Maxwell equations are the basic equations of electromagnetism and determine the electromagnetic field $F$ created by the fast moving charged particles. We consider the case where the electromagnetic field $F$ is generated, through the Maxwell equations by the Maxwell current defined by the distribution function $f$ of the colliding particles, a charge density $e$, and a future pointing unit vector $u$, tangent at any point to the temporal axis.

The matter and energy content of the spacetime is represented by the energy-momentum tensor which is a function of the distribution function $f$, the electromagnetic field $F$, and a massive scalar field $\Phi$, which depends only on the time $t$.

The Euler equations simply express the conservation of the energy-momentum tensor.

The system is coupled in the sense that $f$, which is subject to the Boltzmann equation, generates the Maxwell current in the Maxwell equations and is also present in the Euler equations, whereas the electromagnetic field $F$, which is subject to the Maxwell equations, is in the Lie derivative of $f$ with respect to the vectors field tangent to the trajectories of the particles. $F$ also figures in the Euler equations.
We consider for the study all the Bianchi of types I to VIII spacetimes, excluding thereby the Bianchi type IX spacetime also called the Kantowski-Sachs spacetime which has the flaw to develop singularities in peculiar finite time and is not convenient for the investigation of global existence of solutions.

The main objective of the present work is to extend the result obtained in [1–3] where the particular case of the Bianchi type I spacetime is investigated. The choice of function spaces and the process of establishing the energy inequalities are highly improved.

The paper is organized as follows.

In Section 2, we introduce the spacetime and we give the unknowns.

In Section 3, we describe the Maxwell-Boltzmann-Euler system.

In Section 4, we define the function spaces and we establish the energy inequalities.

In Section 5, we study the local existence of the solution.

In Section 6, we prove the global existence of the solution.

2. The Spacetime and the Unknowns

Greek indexes $\alpha, \beta, \gamma, \ldots$ range from 0 to 3, and Latin indexes $i, j, k, \ldots$ from 1 to 3. We adopt the Einstein summation convention:

$$A^\alpha B_\alpha = \sum_\alpha A^\alpha B_\alpha.$$  \hspace{1cm} (1)

We consider the collisional evolution of a kind of fast moving, massive, and charged particles in the time-oriented Bianchi types 1 to 8 spacetimes ($\mathbb{R}^4$, $\bar{g}$) and denote by $x^\alpha = (x^0, x^i) = (t, x^i)$ the usual coordinates in $\mathbb{R}^4$, where $x^0 = t$ represents the time and $(x^i)$ the space; $\bar{g}$ stands for the given metric tensor of Lorentzian signature $(-, +, +, +)$ which writes

$$\bar{g} = -(dt)^2 + g_{ij}dx^i dx^j,$$  \hspace{1cm} (2)

where $g_{ij}$ are continuously differentiable functions on $\mathbb{R}$, components of a 3-symmetric metric tensor $g = (g_{ij})$, whose variable is denoted by $t$.

The expression of the Levi-Civita connection $\gamma$ associated with $\bar{g}$, which is

$$\gamma^\lambda_{\alpha\beta} = \frac{1}{2} \bar{g}^{\mu\nu} \left[ \partial_\alpha \bar{g}_{\mu\beta} + \partial_\mu \bar{g}_{\alpha\beta} - \partial_\beta \bar{g}_{\alpha\mu} \right],$$  \hspace{1cm} (3)

gives directly

$$\gamma^0_{ij} = \frac{1}{2} \partial_0 g_{ij}, \quad \gamma^i_{0j} = \frac{1}{2} \bar{g}^{ij} \partial_0 g_{ij}, \quad i, j \in \{1, 2, 3\}$$  \hspace{1cm} (4)

$$\gamma^\lambda_{\alpha\beta} = 0 \quad \text{otherwise.}$$

Recall that $\gamma^\alpha_{\lambda\beta} = \gamma^\alpha_{\beta\lambda}$.

We require the assumption that $\partial_0 g_{ij}/g_{ij}$ are bounded. This implies that there exists a constant $C > 0$ such that

$$\left| \frac{\partial_0 g_{ij}}{g_{ij}} \right| \leq C.$$  \hspace{1cm} (5)

As a direct consequence, we have, for $t \in \mathbb{R}^+$,

$$\left| g_{ij}(t) \right| \leq g^0_{ij} e^{Ct}, \quad \left| \frac{1}{g_{ij}(t)} \right| \leq \frac{1}{g^0_{ij}} e^{Ct},$$  \hspace{1cm} (6)

where $g^0_{ij} = g_{ij}(0)$.

The massless particles have a rest mass $m > 0$, normalized to the unity, that is, $m = 1$. We denote by $T(\mathbb{R}^4)$ the tangent bundle of $\mathbb{R}^4$ with coordinates $(x^\alpha, p^\beta)$, where $p = (p^0, \bar{p})$ stands for the momentum of each particle and $\bar{p} = (p^i)$, $i = 1, 2, 3$. Really the charged particles move on the future sheet of the mass shell or the mass hyperboloid $P(\mathbb{R}^4) \subset T(\mathbb{R}^4)$, whose equation is $P_x(\rho) : \bar{g}_x(\rho, p) = 1$ or, equivalently, using expression (2) of $g$:

$$p^0 = \sqrt{1 + g_{ij} p^i p^j},$$  \hspace{1cm} (7)

where the choice $p^0 > 0$ symbolizes the fact that, naturally, the particles eject towards the future.

Setting

$$\varrho = \sqrt{\sum_{i=1}^3 (p^i)^2} = \varrho(\bar{p}),$$  \hspace{1cm} (8)

if $\varrho > 1$, the relations (6) and (7) also show that in any interval $[0, T], T > 0$:

$$A p^0 \leq \varrho \leq B p^0,$$  \hspace{1cm} (9)

where $A = A(T) > 0, B = B(T) > 0$ are constants.

The invariant volume element in $P_x(\rho)$ reads

$$\omega_\rho = |\bar{g}|^{1/2} dp^1 dp^2 dp^3,$$  \hspace{1cm} (10)

where

$$|\bar{g}| = |\det g_{ij}|.$$  \hspace{1cm} (11)

We denote by $f$ the distribution function which measures the probability of the presence of particles in the plasma. $f$ is a nonnegative unknown real-valued function of both the position $(x^\alpha)$ and the 4-momentum of the particles $p = (p^\alpha)$, so:

$$f : T(\mathbb{R}^4) \approx \mathbb{R}^4 \times \mathbb{R}^4 \longrightarrow \mathbb{R}^+,$$  \hspace{1cm} (12)

$$\{x^\alpha, p^\alpha\} \longmapsto f(\{x^\alpha, p^\alpha\}) \in \mathbb{R}^+.$$  \hspace{1cm}

We define a scalar product on $\mathbb{R}^4$ by setting for $p = (p^0, \bar{p}) = (p^0, p^i)$ and $q = (q^0, \bar{q}) = (q^0, q^i)$:

$$\bar{p} \cdot \bar{q} = g_{ij} p^i q^j.$$  \hspace{1cm} (13)

In this paper we consider the homogeneous case for which $f$ depends only on the time $x^0 = t$ and $\bar{p}$. According to the Laplace law, the fast moving and charged particles
create an unknown electromagnetic field $F$ which is a 2-
closed antisymmetric form and locally writes

$$F = F_{\alpha\beta} \, dx^\alpha \wedge dx^\beta. \quad (14)$$

So in the homogeneous case we consider

$$F_{\alpha\beta} : \mathbb{R} \rightarrow \mathbb{R}, \quad t \mapsto F_{\alpha\beta}(t) \in \mathbb{R}. \quad (15)$$

In the presence of the electromagnetic field $F$, the

trajectories $s \mapsto (x^a(s), p^a(s))$ of the charged particles are no

longer the geodesics of spacetime $(\mathbb{R}^4, g)$ but the solutions of the differential system:

$$\frac{dx^a}{ds} = p^a; \quad \frac{dp^a}{ds} = F^a, \quad (16)$$

where

$$p^a = \mathcal{P}(F, f) = -\Gamma_{\alpha\beta}^\gamma p^\gamma \rho^\mu + e p^\beta F^a_{\beta}, \quad (17)$$

where $e = e(t)$ denotes the charge density of particles.

Notice that the differential system (16) shows that the vectors field $X(F)$ defined locally by

$$X(F) = (p^a, F^a(F)), \quad (18)$$

where $p^a$ is given by (17), is tangent to the trajectories.

The charged particles also create a current $J = (J^\beta)$, $\beta = 0, 1, 2, 3$, called the Maxwell current which we take in the form

$$J^\beta = \int_{\mathbb{R}^3} p^\beta f \omega_p - eu^\beta \quad (19)$$

in which $u = (u^\beta)$ is a unit future pointing timelike vector, tangent to the time axis at any point, which means that $u^0 = 1$, $u^i = u_i = 0$, and $i = 1, 2, 3$. The particles are then supposed to be spatially at rest.

The electromagnetic field $F = (F^{0i}, F_{ij})$, where $F^{0i}$ and $F_{ij}$ stand for the electric and magnetic parts, respectively, is subject to the Maxwell equations.

3. The Maxwell-Boltzmann-Euler System in $F$, $f$, and $\Phi$

3.1. The Maxwell Equations in $F$. The Maxwell system in $F$ can be written, using the covariant notation:

$$\nabla_\alpha F^\alpha_{\beta} = J^\beta \quad (20)$$

$$\nabla_\alpha F^\alpha_{\beta} + \nabla_\beta F^\alpha_{\gamma} + \nabla_\gamma F^\gamma_{\alpha\beta} = 0. \quad (21)$$

Equations (20) and (21) are, respectively, the first and second groups of the Maxwell equations, and $\nabla_\alpha$ stands for the covariant derivative in $g$. In (20), $J^\beta$ represents the Maxwell current we take in the form (19). Now the well-known identity $\nabla_\alpha \nabla_\beta F^\gamma_{\alpha\beta} = 0$ imposes, given (20), that the current $J^\beta$ is always subject to the conservation law:

$$\nabla_\beta J^\beta = 0. \quad (22)$$

However using $\beta = 0$ in (20), we obtain since $F = F(t)$, $F^{0\lambda} = -F^{\lambda 0}$ and by (4) that

$$J^0 = 0. \quad (23)$$

By (23), the expression (19) of $J^\beta$ in which we set $\beta = 0$ then allows to compute $e$ and gives, since $u^0 = 1$,

$$e(t) = \int_{\mathbb{R}^3} f(t, \nu) (\det g)^{1/2} d\nu, \quad (24)$$

which shows that $f$ determines $e$.

The second set (21) of the Maxwell equations is identically satisfied since $F = F(t)$, and the first set reduces to $\partial F_{ij} = 0$. Then $F_{ij}$ is constant and

$$F_{ij} = F_{ij}(0) = \varphi_{ij}. \quad (25)$$

This physically shows that the magnetic part of $F$ does not evolve and stays in its primitive state. It remains to determine the electric part $F^{0i}$.

Writing (19) for $\beta = i$, using (4), $\omega_p = |g|^{1/2} (dp^1 dp^2 dp^3 / \rho^0)$, and $u^0 = 0$, implies that

$$J^i = \int_{\mathbb{R}^3} (J^i f(t, \nu)) (\det g)^{1/2} d\nu. \quad (26)$$

By (20), we obtain the linear o.d.e in $F^{0i}$ which writes

$$\partial_t F^{0i} - H F^{0i} = \int_{\mathbb{R}^3} p^i f(t, \nu) (\det g)^{1/2} d\nu. \quad (27)$$

Remark 1. In (27), the expression

$$H = -\frac{1}{2} \Gamma_{\beta\gamma}^{kl} \partial_\beta g_{\gamma\mu} \quad (28)$$

represents the second fundamental form in $(\mathbb{R}^3, g)$. Really $H$ is the trace of the 2-symmetric tensor $K = (K_{ij})$ where $K_{ij} = -(1/2) \partial_\beta g_{\gamma\mu}$. $H$ is called the middle curvature of $(\mathbb{R}^3, g)$. Since $g = (g_{ij})$ is given, so is $H$.

3.2. The Relativistic Boltzmann Equation in $f$. The relativistic Boltzmann equation in $f$, for charged particles in the Bianchi types 1 to 8 spacetimes, can be written:

$$L_x f = Q(f, f), \quad (29)$$

where $L_x$ is the Lie derivative of $f$ with respect to the vectors field $X(F)$ defined by (18) and $Q(f, f)$, the collision operator we now introduce.

According to Lichnerowicz and Chernikov, we consider a scheme, in which, at a given position $(t, x^i)$, only two particles collide with each other, without destroying each other, with the collision affecting only the momentum of each particle, which changes after shock, only the sum of the two momenta being preserved. If $p, q$ stand for the two momenta before the shock and $p', q'$ for the two momenta after the shock, then we have

$$p + q = p' + q'. \quad (30)$$
The collision operator $Q$ is then defined, using functions $f$ and $g$ on $\mathbb{R}^3$, and the previous notations by

$$Q (f, g) = Q^+ (f, g) - Q^- (f, g),$$

(31)

where

$$Q^+ (f, g) = \int_{\mathbb{R}^3} \omega_3 (t, \bar{p}, \bar{q}, \Omega) d\Omega$$

and

$$Q^- (f, g) = \int_{\mathbb{R}^3} \omega_3 (t, \bar{p}, \bar{q}, \Omega) d\Omega$$

(32)

whose elements we now introduce step by step, specifying properties and hypotheses we adopt:

(i) $S^2$ is the unit sphere of $\mathbb{R}^3$, whose area element is denoted by $d\Omega$;

(ii) $\sigma$ is a nonnegative continuous real-valued function of all its arguments, called the collision kernel or the cross-section of the collisions, on which we require the boundedness and Lipschitz continuity assumptions, in which $C_1 > 0$ is a constant:

$$0 \leq \sigma(t, \bar{p} + \bar{q}, \Omega) \leq C_1$$

$$|\sigma(t, \bar{p}, \bar{q}, \Omega) - \sigma(t, \bar{p}, \bar{q}, \Omega)| \leq C_1 ||\bar{p} - \bar{q}||$$

(33)

where $||\bar{p}|| = (\sum_{i=1}^3 (p_i^0)^2)^{1/2} = \rho$ is the norm in $\mathbb{R}^3$.

(iii) The conservation law $p + q = p' + q'$ splits into

$$p^0 + q^0 = p'^0 + q'^0,$$

(34)

$$\bar{p} + \bar{q} = \bar{p}' + \bar{q}'.$$

(35)

Equation (34) expresses, using (7), the conservation of the quantity:

$$\tilde{e} = \sqrt{1 + g_{ij} p_i^0 q_j^0} = \sqrt{1 + g_{ij} p_i^0 q_j^0}$$

(36)

called the elementary energy of the unit rest mass particles; we can interpret (35) by setting, following Glassey and Strauss in [4, equation (42)],

$$\bar{p} = \bar{p} + a(\bar{p}, \bar{q}, \Omega) \Omega$$

$$\bar{q} = \bar{q} - a(\bar{p}, \bar{q}, \Omega) \Omega$$

(37)

in which $a(\bar{p}, \bar{q}, \Omega)$ is a real-valued function. Using (7) to express $p'^0, q'^0$ in terms of $\bar{p}', \bar{q}'$, and next (37) to express $\bar{p}', \bar{q}'$ in terms of $\bar{p}, \bar{q}$, we prove that (34) leads to a quadratic equation in $a$, which solves to give the only nontrivial solution:

$$a(\bar{p}, \bar{q}, \Omega) = \frac{2 p^0 q^0 e^\omega \cdot (\bar{q} - \bar{p})}{(\tilde{e})^2 - [\Omega \cdot (\bar{p} + \bar{q})]}$$

(38)

in which $\tilde{p} = \bar{p}/p^0$, $\tilde{e}$ is given by (36), and the dot (·) is the scalar product defined by (13).

Consequently, using (37), that the functions in the integrals (32) depend only on $\bar{p}, \bar{q}, \Omega$ and that these integrals with respect to $\bar{q}$ and $\Omega$ give functions $Q^+ (f, g)$ and $Q^- (f, g)$ of the single variable $\bar{p}$.

Using now the usual properties of the determinants, we compute the Jacobian of the change of variables $(\bar{p}, \bar{q}) \mapsto (\bar{p}', \bar{q}')$ defined by (37) and find

$$\frac{\partial (p', q')}{\partial (p, q)} = \frac{p^0 q'^0}{p^0 q'^0}.$$

(39)

But $f = f(t, \tilde{p})$, so using (7), the Boltzmann equation (29) leads to the following form:

$$\frac{\partial f}{\partial t} + \frac{p^0}{p^0} \frac{\partial f}{\partial p^0} = \frac{1}{p^0} Q(f, f).$$

(40)

3.3. The Euler Equations. The Euler equations only express the conservation of the energy-momentum tensor $T_{\alpha\beta}$ and write

$$\nabla_\alpha T_{\alpha\beta} = 0.$$

(41)

In (41),

$$T_{\alpha\beta} = T^1_{\alpha\beta} + \tau_{\alpha\beta} + T^2_{\alpha\beta},$$

(42)

where

$$T^1_{\alpha\beta} = \int_{\mathbb{R}^3} P_\alpha P_\beta f(t, \bar{p}) (\det g)^{1/2} d\bar{p},$$

(43)

$$\tau_{\alpha\beta} = -\frac{\partial_\alpha}{4} \frac{\rho^0}{\rho^0} F_{\lambda\mu} + F_{\lambda\mu} F_{\alpha\beta},$$

(44)

$$T^2_{\alpha\beta} = \nabla_\alpha \Phi \nabla_\beta \Phi - \frac{\partial_\alpha}{2} \left[\nabla^\lambda \Phi \nabla_\lambda \Phi + m_0^2 \Phi^2\right].$$

(45)

(i) $T^1_{\alpha\beta}$ is the energy-momentum tensor associated with $f$;

(ii) $\tau_{\alpha\beta}$ is the Maxwell tensor associated with $F$;

(iii) $T^2_{\alpha\beta}$ is the energy-momentum tensor associated with the scalar field $\Phi$ whose mass is denoted by $m_0$, with $m_0 > 0$.

Equation (42) shows that (41) writes

$$\nabla_\alpha T^{1,\alpha\beta} + \nabla_\alpha T^{2,\alpha\beta} + \nabla_\alpha T^{2,\alpha\beta} = 0.$$
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Now, using (21), we have
\[
\nabla_\alpha \tau^{\alpha \beta} = \frac{d}{dx} \left( \frac{1}{2} \Phi \left( \sigma^2 \Phi - m_0^2 \right) \right),
\]
and using (45),
\[
\nabla_\alpha T^{2,\alpha \beta} = \nabla_\beta \Phi \left( \sigma^2 \Phi - m_0^2 \right),
\]
where \( \sigma^2 = \nabla_\alpha \nabla^\alpha \) is the D'Alembertian.

We deduce from (20), (48), and (49) that the Euler equations (41) are satisfied if \( \Phi \) verifies the second-order differential equation:
\[
\nabla_\beta \Phi \left( \sigma^2 \Phi - m_0^2 \right) + F^\alpha_\beta \nabla_\alpha F_{\alpha \lambda} = 0.
\]

For \( \beta = i \), (50) leads to the constraints system:
\[
F_i^j \int_{\mathbb{R}^3} \frac{p^j_i}{p_0^j} f(t, \tilde{p}) (\det g)^{1/2} d\tilde{p} = 0, \quad i = 1, 2, 3,
\]
where \( H \) is defined in (27).

Setting in (52)
\[
U = \frac{1}{2} \left( \Phi \right)^2,
\]
it comes that
\[
U \geq 0 \quad \Phi = \pm \sqrt{2U}.
\]

One supposes in what follows that \( \Phi \) is continuously differentiable, is not a constant, and is decreasing. This implies that
\[
\Phi = -\sqrt{2U},
\]
\[
\Phi(t) \leq \Phi(0), \quad t \in \mathbb{R}^+.
\]

Equation (52) is then equivalent to the nonlinear first-order differential system given as follows:
\[
\dot{\Phi} = -\sqrt{2U},
\]
\[
\dot{U} = 2HU + m_0^2 \Phi \sqrt{2U} + g_{ij} E^j \int_{\mathbb{R}^3} \frac{p^j_i}{p_0^j} f(t, \tilde{p}) (\det g)^{1/2} d\tilde{p},
\]
where \( E^i = F_q^i \).

3.4. The Coupled System. From (17), using (4), we obtain
\[
\frac{p^j_i}{p_0^j} = -2T_0^j p^i + e \left[ -E^i + g^i \frac{p^k F_{ki}}{p_0^i} \right], \quad i = 1, 2, 3.
\]

Using (24), (27), (40), (56), and (57), the Maxwell-Boltzmann-Euler system in \( (F, f, \Phi, U) \) reduces to the following form:
\[
E^i = HE^i + \int_{\mathbb{R}^3} \frac{p^j_i}{p_0^j} f(t, \tilde{p}) (\det g)^{1/2} d\tilde{p},
\]
\[
\frac{\partial f}{\partial t} + \left[ -2T_0^j p^i + \left( -E^i + g^i \frac{p^k F_{ki}}{p_0^i} \right) \right] \times \int_{\mathbb{R}^3} f(t, \tilde{p}) (\det g)^{1/2} d\tilde{p} \frac{\partial f}{\partial p^k} = \frac{1}{p_0^k} Q(f, f),
\]
\[
\Phi = -\sqrt{2U},
\]
\[
\dot{U} = 2HU + m_0^2 \Phi \sqrt{2U} + g_{ij} E^j \int_{\mathbb{R}^3} \frac{p^j_i}{p_0^j} f(t, \tilde{p}) (\det g)^{1/2} d\tilde{p},
\]
which is an integrodifferential system to solve in what is to follow.

We are searching a solution \( (F, f, \Phi, U) \) of the Cauchy problem (59)-(60)-(61)-(62) globally in time on \([0, +\infty]\) for the initial data:
\[
E^i(0) = E_0^i, \quad E_{ij}(0) = \Phi_{ij}, \quad f(0, \tilde{p}) = f_0(\tilde{p}), \quad \tilde{p} \in \mathbb{R}^3; \quad \Phi(0) = \Phi_0; \quad U(0) = U_0.
\]

3.5. The Problem of Constraints. We must find a nontrivial solution \( (F, f, \Phi, U) \) of the Cauchy problem (59)-(60)-(61)-(62) satisfying the system (51) of constraints which writes after computation
\[
\left( g^{12} f^1 - g^{11} f^2 \right) \Phi_{21} + \left( g^{13} f^1 - g^{11} f^3 \right) \Phi_{31} = 0
\]
\[
\left( g^{12} f^1 - g^{11} f^2 \right) \Phi_{21} + \left( g^{13} f^1 - g^{11} f^3 \right) \Phi_{31} = 0
\]
\[
\left( g^{22} f^2 - g^{21} f^2 \right) \Phi_{21} + \left( g^{23} f^2 - g^{21} f^3 \right) \Phi_{31} = 0
\]
\[
\left( g^{22} f^2 - g^{21} f^2 \right) \Phi_{21} + \left( g^{23} f^2 - g^{21} f^3 \right) \Phi_{31} = 0
\]
\[
\left( g^{32} f^2 - g^{31} f^2 \right) \Phi_{21} + \left( g^{33} f^2 - g^{31} f^3 \right) \Phi_{31} = 0
\]
\[
\left( g^{32} f^2 - g^{31} f^2 \right) \Phi_{21} + \left( g^{33} f^2 - g^{31} f^3 \right) \Phi_{31} = 0.
\]

4. Function Spaces and Energy Inequalities

We define now the function spaces in which we are searching the solution to the Maxwell-Boltzmann-Euler system. We also establish some useful energy estimations.
Definition 2 \((E^m_s(0, T, R^3))\). Let \(T > 0, m \in \mathbb{N}, s \in \mathbb{R}\) be given.

We define \(E^m_s(R^3)\) as
\[
E^m_s(R^3) = \left\{ y \in \mathcal{C}([0, T]; \mathcal{S}(R^3)) : (1 + q)^s y(t, \cdot) \in L^2_y(R^3), |\beta| \leq m \right\}.
\]

\(E^m_s(R^3)\) will be endowed with the norm
\[
\left\| y \right\|_{E^m_s(R^3)} = \max_{0 \leq |\beta| \leq m} \left\| (1 + q)^s \partial^\beta_y y(t, \cdot) \right\|_{L^2_y(R^3)}.
\]

\(E^m_s(0, T, \mathbb{R}^3)\) is a Banach space.

\(H^m_s(0, T, \mathbb{R}^3)\) will be the completion of \(E^m_s(0, T, \mathbb{R}^3)\) for the norm \(\left\| \cdot \right\|_{E^m_s(0, T, \mathbb{R}^3)}\).

For \(r > 0\) to be given, we define
\[
E^m_{sr} = \left\{ y \in E^m_s(0, T, \mathbb{R}^3) : y \geq 0 \text{ a.e.} \right\}
\]

Endowed with the induced distance by the norm \(\left\| \cdot \right\|_{E^m_s(0, T, \mathbb{R}^3)}\), \(E^m_{sr}\) is a complete metric subspace of \(E^m_s(0, T, \mathbb{R}^3)\).

Remark 3. If \(m = 0\), then \(y \in E^m_s(\mathbb{R}^3) \iff (1 + q)^s y \in L^2_y(\mathbb{R}^3)\), so \(E^0_s(\mathbb{R}^3)\) will be denoted by \(L^2_y(\mathbb{R}^3)\).

Remark 4. The reasons for the choice of the function space \(H^m_s(0, T, \mathbb{R}^3)\) for \(m = 3\) and \(d > 5/2\).

With the objective of the present work being the existence of solution to the Maxwell-Boltzmann-Euler system, and particularly the Boltzmann equation (40), we are searching a function \(f = f(t, p)\) which is continuously differentiable; in particular we can search \(f = f(t, \cdot)\) belonging to the space \(\mathcal{C}_b^1(R^3_p)\).

We want to use the Faedo-Galerkin method which is applied for separable Hilbert spaces. That is the case for the Sobolev spaces \(H^m_s(0, T, \mathbb{R}^3), m \in \mathbb{N}\).

We need then to find an integer \(m\) such that
\[
H^m(\mathbb{R}^3_p) \hookrightarrow \mathcal{C}_b^1(\mathbb{R}^3_p).
\]

But we know by the Sobolev theorems that
\[
W^m_p(\mathbb{R}^n) \hookrightarrow \mathcal{C}^k(\mathbb{R}^n), \quad m > k + \frac{n}{p}.
\]

Since in our case we have \(n = 3, p = 2\), and \(k = 1 (W^m_p = H^m)\), we must choose \(m\) such that
\[
m > 1 + \frac{3}{2} = \frac{5}{2}.
\]

The smallest integer \(m\) satisfying \(m > 5/2\) is naturally \(m = 3\).

Consequently we have
\[
H^3(\mathbb{R}^3_p) \hookrightarrow H^3(\mathbb{R}^3) \hookrightarrow \mathcal{C}_b^1(\mathbb{R}^3_p).
\]

Furthermore if
\[
d > \frac{5}{2},
\]

then
\[
H^m(\mathbb{R}^3_p) \hookrightarrow L^2(\mathbb{R}^3_p) \hookrightarrow L^1(\mathbb{R}^3_p),
\]

where \(L^1(\mathbb{R}^3_p)\) is defined in [1].

It then results that
\[
H^m(\mathbb{R}^3_p) \cap L^1(\mathbb{R}^3_p) = H^m(\mathbb{R}^3_p).
\]

We can now state the following results which will be fundamental.

Lemma 5. There exists a real number \(T > 0\) such that
\[
(\alpha)^2 - |\Omega \cdot (p + \tilde{\eta})|^2 > 2.
\]

Furthermore, one has
\[
(\alpha)^2 - |\Omega \cdot (p + \tilde{\eta})|^2 \geq \left(1 - \sum_{i,j} g_{ij}\right)(p^0)^2,
\]
\[
(\alpha)^2 - |\Omega \cdot (p + \tilde{\eta})|^2 \geq \left(1 - \sum_{i,j} g_{ij}\right)(q^0)^2,
\]
\[
(\alpha)^2 - |\Omega \cdot (p + \tilde{\eta})|^2 \geq \left(1 - \sum_{i,j} g_{ij}\right)p^0 q^0,
\]

and the function \((\tilde{\Omega}, \tilde{\eta}, \Omega) \mapsto D^\beta_{\tilde{\Omega}, \tilde{\eta}, \Omega}, 0 \leq |\beta| \leq 3\) is bounded.

Proof. See [2].
Proposition 6. Let \( d > 5/2, \|\sigma\|_{L^1(\mathbb{R}^3)} \in L^\infty(\mathbb{R}) \) and 
\((\partial^\beta \sigma)(1+|p|)^{|\beta|-1} \in L^\infty(\mathbb{R}^3 \times \mathbb{R}^3 \times S^2), |\beta| \leq 3 \) be given.
If \( f, g \in H^d_\alpha(\mathbb{R}^3) \), then 
\((1/p^0)^0 Q (f) (g) \in H^d_\alpha(\mathbb{R}^3) \), and one has
\[
\left\| \frac{1}{p^j} Q (f, g) \right\|_{H^d_\alpha(\mathbb{R}^3)} \leq C \|f\|_{H^d_\alpha(\mathbb{R}^3)} \|g\|_{H^d_\alpha(\mathbb{R}^3)},
\]
(79)
where \( C = C(T) > 0 \).
Moreover
\[
\left\| \frac{1}{p^j} Q (f, f) - \frac{1}{p^j} Q (g, g) \right\|_{H^d_\alpha(\mathbb{R}^3)} \leq C \left( \|f\|_{H^d_\alpha(\mathbb{R}^3)} + \|g\|_{H^d_\alpha(\mathbb{R}^3)} \right) \|f - g\|_{H^d_\alpha(\mathbb{R}^3)}.
\]
(80)
Proof. We simply use Lemma 5. For the details, see [2]. □

Proposition 7. Let \( d > 5/2, f \in H^d(\mathbb{R}^3) \) be given. Then \( |f| \leq C (\det g)^{1/2} \|f\|_{L^2(\mathbb{R}^3)}, \) \( i = 1, 2, 3 \).
Proof. See [2]. □

Remark 8. The hypothesis of Proposition 6 concerning the collision kernel \( \sigma \) is a supplementary hypothesis for the investigation of the solution to the Boltzmann equation.

In what is to follow, we are searching the local existence and the uniqueness of the solution to the Cauchy problem (59)-(60)-(61)-(62) in a function space which we will precise, applying the standard theory of first-order differential systems.

The framework we will refer to for \( f \) is \( H^d(0, T, \mathbb{R}^3) \).

The framework we will refer to for \( \bar{E} \) is \( \mathbb{R}^3 \), whose norm is denoted by \( \| \cdot \| \) or \( \| \cdot \|_{\mathbb{R}^3} \):
\[
\mathcal{C}(\mathbb{R}^3)
\]
(81)
\[
= \{ h : [0, T] \rightarrow \mathbb{R}^3 \text{ continuous and bounded} \}.
\]

\( \mathcal{C}(\mathbb{R}^3) \) is a Banach space for the norm:
\[
\|h\| = \sup \|h(t)\|, \ t \in [0, T].
\]
(82)

The framework we will refer to for \( \Phi \) and \( U \) is \( \mathbb{R} \), whose norm is denoted by \( | \cdot | \) (or \( \| \cdot \|_{\mathbb{R}} \)):
\[
\mathcal{C}(\mathbb{R})
\]
(83)
\[
= \{ h : [0, T] \rightarrow \mathbb{R} \text{ continuous and bounded} \}.
\]

\( \mathcal{C}(\mathbb{R}) \) is a Banach space for the norm:
\[
\|h\| = \sup |h(t)|, \ t \in [0, T].
\]
(84)

(i) We consider on \( \mathbb{R}^3 \times H^d_\alpha(0, T, \mathbb{R}^3) \times \mathbb{R} \) the norm:
\[
\left\| (E, f, \Phi, U) \right\| = \left\| E \right\| + \|f\| + |\Phi| + |U|.
\]
(85)

(ii) We consider on \( \mathcal{C}([0, T]; \mathbb{R}^3) \times H^d_\alpha(0, T, \mathbb{R}^3) \times \mathcal{C}([0, T]; \mathbb{R}) \times \mathcal{C}([0, T]; \mathbb{R}) \) the norm:
\[
\left\| (E, f, \Phi, U) \right\| = \left\| E \right\| + \|f\| + \|\Phi\| + \|U\|.
\]
(86)

(iii) We will consider the Cauchy problem (59)-(60)-(61)-(62) for the initial data:
\[
E^i(0) = E^i_0, \quad F_{ij}(0) = \delta_{ij}, \quad f(0, \bar{p}) = f_0(\bar{p}),
\]
(87)
\[
\bar{p} \in \mathbb{R}^3; \quad \Phi(0) = \Phi_0; \quad U(0) = U_0,
\]
where \( f_0 \) is given in \( H^d_\alpha(0, T, \mathbb{R}^3), E^i_0, \delta_{ij}, \Phi_0 \in \mathbb{R}, \)
\( i, j = 1, 2, 3 \), and \( U_0 \in \mathbb{R}^3 \).

5. The Local Existence of Solution

Theorem 9. Let \( \bar{f} \in H^d_\alpha(0, T, \mathbb{R}^3) \) be given, and let \( \bar{E} = (\bar{E}^i) \in \mathbb{R}^3 \) be fixed. Then the linearized partial differential equation
\[
\frac{\partial f}{\partial t} + \sum_{i=1}^{3} \frac{\partial}{\partial p^i} \left( -2 \Gamma_{ij} p^j + \left( \bar{E}^i + \frac{p^k}{p^j} g^{ij} \phi_{kj} \right) \bar{f} \right)
\]
\[
\times \int_{\mathbb{R}^3} f(t, \bar{p}) (\det g)^{1/2} d\bar{p} \frac{\partial f}{\partial p^i} = \frac{1}{p^0} Q(f, f),
\]
(88)
whose unknown is \( f \), with \( f(0, \bar{p}) = f_0 \), has in \( H^d_\alpha(0, T, \mathbb{R}^3) \) a local unique and bounded \(-\star\)-weak solution.

Proof. We use the Faedo-Galerkin method in the function space \( H^d_\alpha(0, T, \mathbb{R}^3) \). For the other details, see [1]. □

Theorem 10. Let \( \bar{E} = (\bar{E}^i) \in \mathbb{R}^3, i = 1, 2, 3, \) be fixed. Then the Boltzmann equation,
\[
\frac{\partial f}{\partial t} + \sum_{i=1}^{3} \frac{\partial}{\partial p^i} \left( -2 \Gamma_{ij} p^j + \left( \bar{E}^i + \frac{p^k}{p^j} g^{ij} \phi_{kj} \right) \bar{f} \right)
\]
\[
\times \int_{\mathbb{R}^3} f(t, \bar{p}) (\det g)^{1/2} d\bar{p} \frac{\partial f}{\partial p^i} = \frac{1}{p^0} Q(f, f),
\]
(89)
has in \( H^d_\alpha(0, T, \mathbb{R}^3) \) a local unique \(-\star\)-weak solution \( f \) such that \( f(0) = f_0 \).
Proof. We use the Banach fixed point theorem in $H^3_d(0, T, \mathbb{R}^3_p)$ for the map:

$$\tilde{f} \in H^3_d(0, T, \mathbb{R}^3_p) \mapsto \Xi(\tilde{f}) = f,$$  

(90)

where $f$ satisfies (88).

(i) We firstly prove, using a sequence of approximations $(f^N)$ of $f$, the Banach-Alaoglu theorem and the fact that $H^3_d(0, T, \mathbb{R}^3_p)$ is a reflexive space (see [1]) that we can choose $\|f_0\|_{H^3_0(0, T, \mathbb{R}^3_p)}$ and $T > 0$ such that

$$\tilde{f} \in H^3_d(0, T, \mathbb{R}^3_p) \implies \Xi(\tilde{f}) = f \in H^3_d(0, T, \mathbb{R}^3_p).$$  

(91)

(ii) Let now $\tilde{f}_1, \tilde{f}_2 \in H^3_d(0, T, \mathbb{R}^3_p)$ be given, and let $f_1, f_2$ be two solutions of (88). Then

\[
\frac{\partial f_1}{\partial t} + \left[ -2\bar{t}_{ij} \tilde{p}^i + \left( \bar{E} - \frac{P}{\rho_p} \bar{g}^{ji} \bar{q}_{ki} \right) \right] \times \int_{\mathbb{R}^3} \tilde{f}_1 (t, \tilde{p}) (\text{det } g)^{1/2} d\tilde{p} \frac{\partial f_1}{\partial \tilde{p}^i} = \frac{1}{p^0} Q (\tilde{f}_1, \tilde{f}_1),
\]  

and

\[
\frac{\partial f_2}{\partial t} + \left[ -2\bar{t}_{ij} \tilde{p}^i + \left( \bar{E} - \frac{P}{\rho_p} \bar{g}^{ji} \bar{q}_{ki} \right) \right] \times \int_{\mathbb{R}^3} \tilde{f}_2 (t, \tilde{p}) (\text{det } g)^{1/2} d\tilde{p} \frac{\partial f_2}{\partial \tilde{p}^i} = \frac{1}{p^0} Q (\tilde{f}_2, \tilde{f}_2).
\]  

(92)

Let $G = f_1 - f_2$ and $\tilde{G} = \tilde{f}_1 - \tilde{f}_2$. Then we get

\[
\frac{\partial G}{\partial t} + \frac{P^i (\tilde{G}, \tilde{E})}{p^0} \frac{\partial G}{\partial \tilde{p}^i} = \frac{1}{p^0} Q (\tilde{f}_1, \tilde{G}) - \frac{1}{p^0} Q (\tilde{G}, \tilde{f}_2).
\]  

(93)

Conveniently using energy inequalities established in [1], the system (92), and remembering that $G(0, \tilde{p}) = 0$, we obtain

\[
\left\| (1 + |\tilde{p}|)^{4d |\beta| / 3} G(t) \right\|_{L^2} \leq C_2 \int_0^t \left\| (1 + |\tilde{p}|)^{4d |\beta| / 3} \frac{\partial G}{\partial \tilde{p}^i} \right\|_{L^2} (r) d\tau,
\]  

(94)

where $C_2 = C (g^0, r, T, |E_0|, |\bar{q}_{ij}|)$ is a positive constant.

Then taking the sup in (94), for $t \in [0, T]$ and $|\beta| \leq 3$, we get

\[
\| G \|_{H^3_d(0,T,\mathbb{R}^3_p)} \leq C \int_0^T \sup_{r \in [0,T]} \left( (1 + |\tilde{p}|)^{4d |\beta| / 3} \frac{\partial G}{\partial \tilde{p}^i} \right) (r) d\tau,
\]  

(95)

which implies

\[
\| G \|_{H^3_d(0,T,\mathbb{R}^3_p)} \leq CT \| G \|_{H^3_d(0,T,\mathbb{R}^3_p)}.
\]  

(96)

The relations (91), (96) show clearly that $H^3_d(0, T, \mathbb{R}^3_p) \rightarrow H^3_d(0, T, \mathbb{R}^3_p)$, $\tilde{f} \mapsto \Xi(\tilde{f}) = f$ is a contracting map, so by the Banach theorem $\Xi$ has a unique fixed point $f = \tilde{f}$ and the proof of Theorem 10 is complete.

Next, let us introduce the subgroup $G$ of $\mathcal{E}_3$ defined by

$$G = \left\{ N_{\epsilon, \theta} \in \mathcal{E}_3, \quad \begin{cases} \epsilon = 0 \\ \cos \theta - \sin \theta \\ \sin \theta \cos \theta \end{cases}, \quad \epsilon, \theta \in \mathbb{R}, \quad \epsilon^2 = 1 \right\}.$$  

(97)

A function $g$ on $\mathbb{R}^3$ is said to be invariant under $G$ if

$$g(N\tilde{p}) = g(\tilde{p}); \quad \forall N \in G, \quad \forall \tilde{p} \in \mathbb{R}^3.$$  

(98)

Using the observation that $p^0$ is invariant under $G$, it is proved in [6] that if $f_0$ is invariant under $G$, then so will be the solution $f$ of the Boltzmann equation satisfying $f_0(\tilde{p}) = f(0, \tilde{p})$. It is also proved in [7] that $f_i = \int_{\mathbb{R}^3} (p^i f(t, \tilde{p})(\text{det } g)^{1/2} / p^0) d\tilde{p} = 0$, $i = 1, 2, 3$ if and only if $f_0$ is invariant under $G$.

One requires in all what follows that the initial datum $f_0 = f(0, \cdot)$ of the distribution function $f$ is not invariant under $G$. The immediate consequence is that

$$f_i = \int_{\mathbb{R}^3} (p^i f(t, \tilde{p})(\text{det } g)^{1/2} / p^0) d\tilde{p} \neq 0, \quad i = 1, 2, 3.$$  

(99)

Now, computing the determinant of the system (64), we conclude that, under our requirement, the problem of constraints (64) admits on $[0, T]$ a nontrivial solution:

$$f \neq 0; \quad \varphi_{12} = \varphi_{13} = \varphi_{23} = 0,$$  

(100)

where $f$ is the unique solution to the Boltzmann equation (60) on $[0, T]$ in which $\tilde{E}$ is given.
Let us now state the following result which shows helpful in what is to follow.

**Proposition 11.** The Cauchy problem (59)-(60)-(61)-(62) is equivalent to the following problem, for \( i = 1, 2, 3 \):

\[
\begin{align*}
\frac{dE_i}{dt} &= HE_i + \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq \quad (E_1) \\
\frac{dp_i}{dt} &= -2\Gamma_{ij} p^j + \int_{\mathbb{R}^3} f(dg) dq \quad (E_2) \\
\frac{d\Phi}{dt} &= -\sqrt{2U} \quad (E_3) \\
\frac{dU}{dt} &= 2HU + m_0^2 \Phi \sqrt{2U} + g_3 E_i \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq \quad (E_4) \\
E_i(0) &= E_{i0} \quad \Phi(0) = \Phi_0 \quad \quad (E_5) \\
f(0, \bar{p}) &= f_0(\bar{p}) \quad \bar{p} \in \mathbb{R}^3 \quad \quad (E_6) \\
U(0) &= U_0. \\
\end{align*}
\]  

(101)

*Proof.* See [1]. \(\square\)

The framework we will refer to for \( \bar{p} \in \mathbb{R}^3 \), whose norm is denoted by \( \| . \| \) or \( \| . \|_{\mathbb{R}^3} \).

Let \( I = (I_1, I_2, I_3, I_4, I_5) \) denote the r.h.s. of (59)-(60)-(61)-(62), that is,

\[
\begin{align*}
I_1(t, \mathbb{R}^3, p, f, U) &= HE_i + \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq \\
I_2(t, \mathbb{R}^3, p, f, U) &= -2\Gamma_{ij} p^j + \int_{\mathbb{R}^3} f(dg) dq \quad \quad (E_2) \\
I_3(t, \mathbb{R}^3, p, f, U) &= -\sqrt{2U} \quad (E_3) \\
I_4(t, \mathbb{R}^3, p, f, U) &= 2HU + m_0^2 \sqrt{2U} + g_3 E_i \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq. \\
I_5(t, \mathbb{R}^3, p, f, U) &= 0. \\
\end{align*}
\]  

(102)

It then appears that, on the contrary to the uncharged case studied in [6, 8], the momentum \( p^0 = (p^0, \bar{p}) \) also becomes an unknown in the charged case. Note that \( f \) and \( \bar{p} \) are now independent variables for the system \( (E_1)-(E_2)-(E_3)-(E_4)-(E_5) \). In this context, the collision operator \( Q \) defined by (31) will depend on \( \bar{p} \) only through the collision kernel \( \sigma \), and we show it by writing now \( Q(f, f, \bar{p}) \) instead of \( Q(f, f, \bar{p}) \). One must from now be careful in order to avoid any confusion between the unknown \( \bar{p} \) of the system \( (E_1)-(E_2)-(E_3)-(E_4)-(E_5) \) and the variable \( \bar{p} \) in (26), (27), (57), and (62), for example. For this reason, we denoted the variable in the integrals in \( (E_1), (E_2), \) and \( (E_3) \) by \( \bar{p} \) instead of \( \bar{p} \).

**Proposition 12.** Let \( \bar{p} = (p^i), \bar{p}^j = (p_j^i) \in \mathbb{R}^3, j = 1, 2, \) \( f \in H_4^3(\mathbb{R}^3) \) be given. Then

\[
\begin{align*}
\frac{dE^i}{dt} &= HE^i + \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq \\
\frac{dp^i}{dt} &= -2\Gamma_{ij} p^j + \int_{\mathbb{R}^3} f(dg) dq \\
\frac{d\Phi}{dt} &= -\sqrt{2U} \\
\frac{dU}{dt} &= 2HU + m_0^2 \sqrt{2U} + g_3 E^i \int_{\mathbb{R}^3} \frac{q f(dg)}{q^0} dq \\
E^i(0) &= E_{i0} \quad \Phi(0) = \Phi_0 \quad \quad (E_5) \\
f(0, \bar{p}) &= f_0(\bar{p}) \quad \bar{p} \in \mathbb{R}^3 \quad \quad (E_6) \\
U(0) &= U_0. \\
\end{align*}
\]  

(103)

where

\[
\begin{align*}
B_1 &= 2 \sum_i \sqrt{g_{ii}} \sum_j \frac{1}{g_{jj}} \sum_{i, j} \frac{1}{g_{kk}} + 2 \sum g_{ij} \left( \sum_k \frac{1}{g_{kk}} \right)^2 + 1, \\
B_2 &= 2 \sum_i \sqrt{g_{ii}} + 2 \sum g_{ij} \sum_k \frac{1}{g_{kk}}, \\
B_3 &= B_3 (T; g_{ij}).
\end{align*}
\]  

(104)

*Proof.* See [7]. \(\square\)

We prove the following.

**Proposition 13.** Let \( E_1, E_2, \bar{p}_1, \bar{p}_2 \in \mathbb{R}^3, f_1, f_2, U_1, U_2 \in \mathbb{R}, \) \( f_1, f_2 \in H_4^3(0, T; \mathbb{R}^3) \) be given. Then

\[
\begin{align*}
\| I_1(t, E_1, \bar{p}_1, f_1, U_1) - I_1(t, E_2, \bar{p}_2, f_2, U_2) \|_{\mathbb{R}^3} &\leq C_3 \left( \| E_1 - E_2 \|_{\mathbb{R}^3} + \| f_1 - f_2 \|_{H_4^3(0, T; \mathbb{R}^3)} \right) \\
\| I_2(t, E_1, \bar{p}_1, f_1, U_1) - I_2(t, E_2, \bar{p}_2, f_2, U_2) \|_{\mathbb{R}^3} &\leq C_4 \left( \| E_1 - E_2 \|_{\mathbb{R}^3} + \| \bar{p}_1 - \bar{p}_2 \|_{\mathbb{R}^3} \\
&\quad + \| f_1 - f_2 \|_{H_4^3(0, T; \mathbb{R}^3)} \right)
\end{align*}
\]  

(105)

(106)
\[ \left\| I_3 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_3 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) \right\|_{L^2(0,T; \mathbb{R}^2)} \leq C_5 \left( \| \mathcal{F}_1 - \mathcal{F}_2 \|_{\mathbb{R}^2} + \| f_1 - f_2 \|_{L^2(0,T; \mathbb{R}^2)} \right) \]

(107)

\[ \left\| I_4 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_4 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) \right\|_{\mathbb{R}} \leq C_6 \| U_1 - U_2 \|_{\mathbb{R}} \]

(108)

\[ \left\| I_5 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_5 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) \right\|_{\mathbb{R}} \leq C_7 \left( \| E_1 - E_2 \|_{\mathbb{R}^2} + \| f_1 - f_2 \|_{L^2(0,T; \mathbb{R}^2)} \right) + \| \Phi_1 - \Phi_2 \|_{\mathbb{R}} + \| U_1 - U_2 \|_{\mathbb{R}} \]

(109)

where

\[ C_3 = C \left( |H| + (\det g)^{1/2} \right) \]

\[ C_4 = C \left( \sum_{i,j} g^{ij} \right)^2 + C (\det g)^{1/2} \left( \| f_1 \| + \| E_2 \| \right) \]

(110)

\[ C_5 = B_3 + C \left( T, g^0 \right) (\det g)^{1/2} \left( \| f_1 \| + \| f_2 \| \right) + CB_2, \]

\[ C_6 = \frac{\sqrt{2}}{\sqrt{U_1} + \sqrt{U_2}}, \]

\[ C_7 = C \left( |H| + \frac{m_0^2 |\Phi_1| \sqrt{2}}{\sqrt{U_1} + \sqrt{U_2}} + m_0^2 \sqrt{2U_1} \right) \]

\[ + C (\det g)^{1/2} \sum_{i,j} g_{ij} \left( \| E_2 \| + \| f_1 \| \right). \]

Proof. (a) We have, using (102),

\[ I_1 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_1 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) = \left( H \left( E_1 - E_2 \right) \right) \]

(111)

\[ \left. + \int_{\mathbb{R}^3} q^0 (f_1 (t, \bar{p}) - f_2 (t, \bar{p})) (\det g)^{1/2} \right. \frac{d\bar{q}}{q^0}. \]

So by (5) and Proposition 7,

\[ \left| H \left( E_1 - E_2 \right) + \int_{\mathbb{R}^3} q^0 (f_1 (t, \bar{p}) - f_2 (t, \bar{p})) (\det g)^{1/2} \right. \frac{d\bar{q}}{q^0} \]

\[ \leq |H| \left| E_1 - E_2 \right| + C (\det g)^{1/2} \| f_1 - f_2 \|_{L^2(\mathbb{R}^3)}. \]

(112)

It follows by (6) that

\[ \left| I_1 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_1 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) \right|_{\mathbb{R}} \]

\[ \leq C \left( |H| + (\det g)^{1/2} \right) \]

(113)

\[ \times \left( \| E_1 - E_2 \|_{\mathbb{R}^3} + \| f_1 - f_2 \|_{L^2(\mathbb{R}^3)} \right). \]

(b) We still have, by (102),

\[ I_2 \left( t, E_1, p_1, f_1, \Phi_1, U_1 \right) - I_2 \left( t, E_2, p_2, f_2, \Phi_2, U_2 \right) \]

\[ = (2 \Gamma_{ij} (p^i_1 - p^i_2)) \]

\[ \left. + (\det g)^{1/2} g^{ij} \varphi_{kj} \left[ \frac{p^k_2}{p^k_1} \left( \int_{\mathbb{R}^3} f_2 d\bar{q} - \frac{p^k_1}{p^k_2} \left( \int_{\mathbb{R}^3} f_1 d\bar{q} \right) \right) \right. \]

\[ \left. + (\det g)^{1/2} \varphi_{kj} \left( E_2 \left( \int_{\mathbb{R}^3} f_2 d\bar{q} - E_1 \left( \int_{\mathbb{R}^3} f_1 d\bar{q} \right) \right) \right) \right), \]

(114)

But (5) gives

\[ \left| 2 \Gamma_{ij} (p^i_1 - p^i_2) \right| \leq C \left( \sum_{i,j} g^{ij} \right) \| \mathcal{F}_1 - \mathcal{F}_2 \|_{\mathbb{R}^3}. \]

(115)

Invoking Proposition 12, we have

\[ \left| (\det g)^{1/2} g^{ij} \varphi_{kj} \left[ \frac{p^k_2}{p^k_1} \left( \int_{\mathbb{R}^3} f_2 d\bar{q} - \frac{p^k_1}{p^k_2} \left( \int_{\mathbb{R}^3} f_1 d\bar{q} \right) \right) \right. \]

\[ \left. + (\det g)^{1/2} \varphi_{kj} \left( E_2 \left( \int_{\mathbb{R}^3} f_2 d\bar{q} - E_1 \left( \int_{\mathbb{R}^3} f_1 d\bar{q} \right) \right) \right) \right| \]

\[ \leq (\det g)^{1/2} \left| \frac{p^k_2}{p^k_1} \left( \int_{\mathbb{R}^3} f_2 d\bar{q} - \frac{p^k_1}{p^k_2} \left( \int_{\mathbb{R}^3} f_1 d\bar{q} \right) \right) \right| \]

\[ \left. + \left( \int_{\mathbb{R}^3} (f_2 - f_1) d\bar{q} \right) \right| \]

\[ \leq (\det g)^{1/2} \left( \int_{\mathbb{R}^3} (f_2 - f_1) d\bar{q} \right) \]

\[ \leq (\det g)^{1/2} \left( \int_{\mathbb{R}^3} (f_2 - f_1) d\bar{q} \right) \]

\[ \times \left( \sum_{i,j} \varphi_{ij} \right) \]

\[ \times \left( C B_1 \left( \| f_1 \| + \| f_2 \| \right) \right). \]

(116)

So by addition, we conclude that (106) holds.
We also have, using (102),
\[ I_3(t, E_1, p_1, f_1, \Phi_1, U_1) - I_3(t, E_2, p_2, f_2, \Phi_2, U_2) = \frac{1}{p_1^0} Q(f_1, f_1, \overline{P}_1) - \frac{1}{p_2^0} Q(f_2, f_2, \overline{P}_2) \]
\[ = \frac{1}{p_1^0} (Q(f_1, f_1, \overline{P}_1) - Q(f_2, f_2, \overline{P}_1)) \]
\[ + \frac{1}{p_1^0} (Q(f_2, f_2, \overline{P}_1) - Q(f_2, f_2, \overline{P}_2)) \]
\[ + \left( \frac{1}{p_1^0} - \frac{1}{p_2^0} \right) Q(f_2, f_2, \overline{P}_2). \]

By Proposition 6, we have
\[ \left\| \frac{1}{p_1^0} (Q(f_1, f_1, \overline{P}_1) - Q(f_2, f_2, \overline{P}_1)) \right\|_{H^2[0,T,R^4]} \]
\[ \leq C \left( T, g_{ij}^0 \right) \left( \| f_1 \|_2 + \| f_2 \|_2 \right) \| f_1 - f_2 \|. \]

Using also Proposition 6, we find
\[ \left\| \frac{1}{p_1^0} (Q(f_2, f_2, \overline{P}_1) - Q(f_2, f_2, \overline{P}_2)) \right\|_{H^2[0,T,R^4]} \]
\[ \leq B_1 \| f_2 \|^2 \left\| \overline{P}_1 - \overline{P}_2 \right\|_{R^3}. \]

Still using Proposition 6 and invoking Proposition 12, we find
\[ \left\| \left( \frac{1}{p_1^0} - \frac{1}{p_2^0} \right) Q(f_2, f_2, \overline{P}_2) \right\|_{H^2[0,T,R^4]} \]
\[ \leq C B_2 \| f_2 \|^2 \left\| \overline{P}_1 - \overline{P}_2 \right\|_{R^3}. \]

Adding the last three inequalities, we obtain (107).

(d) Similarly, by (102),
\[ I_4(t, E_1, \overline{P}_1, f_1, \Phi_1, U_1) - I_4(t, E_2, \overline{P}_2, f_2, \Phi_2, U_2) \]
\[ = \sqrt{2U_1} - \sqrt{2U_2} = \frac{\sqrt{2}}{\sqrt{U_1} + \sqrt{U_2}} (U_1 - U_2). \]

So
\[ \left| I_4(t, E_1, \overline{P}_1, f_1, \Phi_1, U_1) - I_4(t, E_2, \overline{P}_2, f_2, \Phi_2, U_2) \right| \]
\[ \leq \frac{\sqrt{2}}{\sqrt{U_1} + \sqrt{U_2}} |U_1 - U_2| \quad \text{(122)} \]

(e) Finally by (102) we have
\[ I_5(t, E_1, \overline{P}_1, f_1, \Phi_1, U_1) - I_5(t, E_2, \overline{P}_2, f_2, \Phi_2, U_2) \]
\[ = 2H(U_1 - U_2) + m_0^2 \left( \Phi_1 \sqrt{2U_1} - \Phi_2 \sqrt{2U_2} \right) \]
\[ + \left( g_{ij}(\det g)^{1/2} \int_{R^3} \frac{q^i f_i(t,\overline{P})}{q^j} \, dq \right) \]
\[ - \left( g_{ij}(\det g)^{1/2} \int_{R^3} \frac{q^i f_i(t,\overline{P})}{q^j} \, dq \right) \]
\[ = 2H(U_1 - U_2) + m_0^2 \Phi_1 \left( \sqrt{2U_1} - \sqrt{2U_2} \right) \]
\[ + m_0^2 \sqrt{2U_2} (\Phi_1 - \Phi_2) \]
\[ + g_{ij}(\det g)^{1/2} \int_{R^3} \frac{q^i f_i(t,\overline{P})}{q^j} \, dq \left( E_i - E_j \right) \]
\[ + g_{ij}(E_i - E_j) \int_{R^3} \frac{q^i f_i(t,\overline{P})}{q^j} \, dq. \]

So by Propositions 6 and 7, using (2) and the inequalities obtained for $I_1, I_2, I_4$,
\[ \left| I_5(t, E_1, \overline{P}_1, f_1, \Phi_1, U_1) - I_5(t, E_2, \overline{P}_2, f_2, \Phi_2, U_2) \right| \]
\[ \leq C_7 \left( \left\| E_1 - E_2 \right\|_{R^3} + \left\| f_1 - f_2 \right\|_{R^3} + \left\| \Phi_1 - \Phi_2 \right\|_{R^3} + \left\| U_1 - U_2 \right\|_{R^3} \right), \]

where
\[ C_7 = C |H| + m_0^2 \left| \Phi_2 \right| \sqrt{\frac{\sqrt{2}}{U_1}} + m_0^2 \sqrt{\frac{\sqrt{2}}{U_2}} \]
\[ + C \left( \det g \right)^{1/2} \sum_{i,j} g_{ij} \left( \left\| E_i \right\| + \left\| f_i \right\| \right). \]

This completes the proof of Proposition 13. \qed

One requires in what follows that, for any real number $T > 0$,
\[ U(t) > \frac{U_0}{2}, \quad \forall t \in [0, T]. \]

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Theorem 14. Let $t_0 \geq 0$, $(E_0, f_0, \overline{P}_0, \Phi_0, U_0) \in R^3 \times R^3 \times H^1(0, T, R^3) \times R \times R$ be given. Then the following holds.
There exists a real number $\delta > 0$ such that the Cauchy problem \( (S) \) has a unique solution:
\[ (E, \overline{P}, f, \Phi, U) \in (C([t_0, t_0 + \delta]; R^3))^2 \]
\[ \times H^1(0, t_0 + \delta, R^3) \]
\[ \times (C([t_0, t_0 + \delta]; R))^2 \]
satisfying \((E, \rho, f, \Phi, U)(t_0) = (E_0, \rho_0, f_0, \Phi_0, U_0)\). Moreover, \(f\) satisfies the relation:

\[
\|f\| = \sup \{\|f(t)\|, t \in [t_0, t_0 + \delta]\} \leq \|f_{t_0}\|. \tag{128}
\]

**Proof.** We apply the standard theory on the first-order differential systems to \((E_1) - (E_2) - (E_3) - (E_4) - (E_5)\).

Since \(g_{ij}, \partial_0 g_{ij}, 1/g_{ij}, \alpha\) are continuous functions of \(t\), so is the function

\[
I(t, E, \rho, f, \Phi, U) = (I_1, I_2, I_3, I_4, I_5). \tag{129}
\]

By continuity of the functions \(z = g_{ij}, 1/g_{ij}\) at \(t = t_0\), there exists a real number \(\delta_0 > 0\) such that

\[
t \in \mathbb{R}^2, \|E - E_{t_0}\| < \delta, \tag{130}
\]

The previous relation implies, using (5) and (6) to bound \(z = g_{ij}, 1/g_{ij}\) at \(t = t_0\), that

\[
t \in |t_0 - \delta, t_0 + \delta| \implies \|z(t)\| \leq \|z(t_0)\| + 1. \tag{131}
\]

Next, set

\[
B(E_{t_0}, 1) = \{E \in \mathbb{R}^2, \|E - E_{t_0}\| < 1\}, \tag{132}
\]

\[
B(f_{t_0}, 1) = \{f \in H_2^1(0, T), \|f - f_{t_0}\| < 1\}. \tag{133}
\]

Then

\[
f \in B(f_{t_0}, 1) \implies \|f\| \leq \|f_{t_0}\| + 1,
\]

\[
E \in B(E_{t_0}, 1) \implies \|E\| < \|E_{t_0}\| + 1. \tag{134}
\]

Now consider the neighborhood \(V_{t_0} = \{t \in \mathbb{R}^2, \|E - E_{t_0}\| < \delta_0, \|f - f_{t_0}\| < 1, \|\Phi - \Phi_{t_0}\| < 1, \|U - U_{t_0}\| < 1\}\) in the Banach space \(\mathbb{R} \times \mathbb{R}^2 \times H_2^1(0, T), \|E, f, \Phi, U\| \times \mathbb{R} \times \mathbb{R}\) and take

\[
(t, E_{t_1}, f_{t_1}, \Phi_{t_1}, U_{t_1}), (t, E_{t_2}, f_{t_2}, \Phi_{t_2}, U_{t_2}) \in V_{t_0}. \tag{135}
\]

We deduce from the inequalities (105), (106), (107), (108), and (109) the definitions of \(C_3, C_4, C_5, C_6, C_7\), the implications

\[
t \in |t_0 - \delta_0, t_0 + \delta_0| \implies |z(t)| \leq \left(\sum_{i,j} g_{ij}^0 + \frac{1}{g_{ij}^0}\right) e^{C_0} + 1,
\]

\[
E \in B(E_{t_0}, 1) \implies \|E\| < \|E_{t_0}\| + 1, \tag{136}
\]

\[
f \in B(f_{t_0}, 1) \implies \|f\| \leq \|f_{t_0}\| + 1,
\]

\[
\Phi \in [-\Phi_{t_0} + 1, \Phi_{t_0} + 1] \implies \|\Phi\| < \|\Phi_{t_0}\| + 1,
\]

\[
U \in [-U_{t_0} + 1, U_{t_0} + 1] \implies \|U\| < \|U_{t_0}\| + 1,
\]

and the relation (126) that there exists a constant

\[
C_8 = C_8 \left(\rho_0, g_{ij}^0, f_{t_0}, E_{t_0}^i, \Phi_{t_0}^j, U_{t_0}\right) \tag{137}
\]

such that

\[
\|f(t, E, \rho, f, \Phi, U)\| \leq C_8 \left(\|E - E_{t_0}\|, \|\rho - \rho_{t_0}\|, \|f_0 - f_{t_0}\|, \|\Phi_0 - \Phi_{t_0}\|, \|U_0 - U_{t_0}\|\right). \tag{138}
\]

which shows that \(I = (I_1, I_2, I_3, I_4, I_5)\) is locally Lipschitzian in \((E, \rho, f, \Phi, U)\) with respect to the norm of the Banach space \(\mathbb{R} \times \mathbb{R} \times H_2^1(0, T), \|E, f, \Phi, U\| \times \mathbb{R} \times \mathbb{R}\). The existence of a unique solution \((E, \rho, f, \Phi, U)(t_0) = (E_{t_0}, \rho_{t_0}, f_{t_0}, \Phi_{t_0}, U_{t_0})\) is guaranteed by the standard theory on the first-order differential systems.

The relation \(\|f(t)\| = \sup \{\|f(t)\|, t \in [0, \delta]\} \leq \|f_{t_0}\|\) is established in [8].

As a direct consequence, we can deduce that there exists a real number \(\delta > 0\) such that the Maxwell-Boltzmann-Euler system (20)-(21)-(40)-(52) in all Bianchi types 1 to 8 spacetimes has a unique solution \((F, f, \Phi)\) on \([0, \delta]\) satisfying

\[
F^0(0) = F^0, \quad F_i(0) = \Phi_i, \quad f(0) = f_0, \quad \Phi(0) = \Phi_0. \tag{139}
\]

### 6. The Global Existence

#### 6.1. The Method.

Let \([0, T]\) be the maximal existence domain of solution, denoted here by \((E, \rho, f, \Phi, U)\) and given by Theorem 14. of the system \((E_1) - (E_2) - (E_3) - (E_4) - (E_5)\), with the initial data \((E_0, \rho_0, f_0, \Phi_0, U_0) = (E_{t_0}, \rho_{t_0}, f_{t_0}, \Phi_{t_0}, U_{t_0})\) in the Banach space \(\mathbb{R} \times \mathbb{R} \times \mathbb{R} \times H_2^1(0, T), \|E, f, \Phi, U\| \times \mathbb{R} \times \mathbb{R}\).

We intend to prove that \(T = +\infty\).

(a) If we already have \(T = +\infty\), then the problem of global existence is solved.

(b) We are going to show that if we suppose \(T < +\infty\), then the solution \((E, \rho, f, \Phi, U)\) can be extended beyond \(T\), which contradicts the maximality of \(T\).

(c) The method is as follows: suppose \(0 < T < +\infty\) and let \(t_0 \in [0, T]\). We want to show that there exists a strictly positive number \(\delta > 0\) independent of \(t_0\) such that the system \((E_1) - (E_2) - (E_3) - (E_4) - (E_5)\) on \([t_0, t_0 + \delta]\), with the initial data \((E(t_0), \rho(t_0), f(t_0), \Phi(t_0), U(t_0))\) at \(t = t_0\), admits a unique solution \((E, \rho, f, \Phi, U)\) on \([t_0, t_0 + \delta]\). Then, by taking \(t_0\) sufficiently close to \(T\), for example, \(t_0\) such that \(0 < T - t_0 < (\delta/2)\), and hence \(T < t_0 + (\delta/2)\), we can extend the solution
\[
\frac{dE^i}{dt} = T_1(t, E, \overline{p}, f, \Phi, U), \quad \frac{dp^i}{dt} = T_2(t, E, \overline{p}, f, \Phi, U), \quad \frac{df}{dt} = T_3(t, E, \overline{p}, f, \Phi, U), \quad \frac{d\Phi}{dt} = T_4(t, E, \overline{p}, f, \Phi, U), \quad \frac{dU}{dt} = T_5(t, E, \overline{p}, f, \Phi, U),
\]
where
\[
T_1(t, E, \overline{p}, f, \Phi, U) = \left( HE^i + \int_{R^3} \frac{q^i \overline{f} (\det g)^{1/2}}{q^0} dq \right),
\]
\[
T_2(t, E, \overline{p}, f, \Phi, U) = \left( \frac{1}{\rho^0(\overline{p})} Q(f, f, \overline{p}) \right),
\]
\[
T_3(t, E, \overline{p}, f, \Phi, U) = -\sqrt{2U},
\]
\[
T_4(t, E, \overline{p}, f, \Phi, U) = 2HU + m_0^2 \Phi \sqrt{2U} + g_0E^i \int_{R^3} \frac{q^i \overline{f} (\det g)^{1/2}}{q^0} dq, \quad i = 1, 2, 3.
\]

We prove the following.

**Proposition 16.** Let \( t_0 \in [0, T\], \delta \in ]0, 1[, \) and \( (\overline{E}, \overline{p}, f, \Phi, U) \in \left( \mathbb{C}([t_0, t_0 + \delta] ; \mathbb{R}^3) \right)^2 \times H_{d,r}^3(t_0, t_0 + \delta, \mathbb{R}^3) \times (\mathbb{C}([t_0, t_0 + \delta] ; \mathbb{R}^3))^2 \times H_{d,r}^3 \times \mathbb{R} \times \mathbb{R}^3 \) be given. Then, the differential system (144)-(145)-(146)-(147)-(148) has a unique solution \( (\overline{E}, \overline{p}, f, \Phi, U) \in \left( \mathbb{C}([t_0, t_0 + \delta] ; \mathbb{R}^3) \right)^2 \times H_{d,r}^3 \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}^3 \) such that \( (\overline{E}, \overline{p}, f, \Phi, U)(t_0) = (\overline{E}_{t_0}, \overline{p}_{t_0}, f_{t_0}, \Phi_{t_0}, U_{t_0}) \).

**Proof.** (a) We consider (144) in \( \overline{E} \), with \( T_i \) defined by (149) in which \( \overline{f} \) is fixed. Since \( g_{ij}, 1/g_{ij}, \partial_0 g_{ij} \) are continuous functions of \( t \), so is \( T_i \). Next, we deduce from (105) in which we set \( f_1 = f_2 = \overline{f} \) that
\[
\left\| I_1(t, E, \overline{E}, \overline{f}, \Phi, U_1) - I_1(t, E, \overline{E}, \overline{f}, \Phi, U_2) \right\|_{R^3} \leq C_3 \left\| \overline{E}_1 - \overline{E}_2 \right\|,
\]
where \( C_3 = C |H| + (\det g)^{1/2} \).
Now we can use (5) and (6) to bound $z = g_{ij}$, $1/g_{ij}$, $\partial_0 g_{ij}$ and we obtain, for $t \in [t_0, t_0 + \delta]$, then $t \leq t_0 + \delta \leq T + 1$,

$$|z(t)| \leq \left( C + \sum_{i,j} g_{ij}^0 \right) e^{C(T+1)} + 1, \quad t \in [t_0, t_0 + \delta], \quad z = g_{ij} \partial_0 g_{ij}. \tag{151}$$

We then deduce from (151) that

$$C_3 \leq C_3', \quad \text{where } C_3' = C_3' \left( g_{ij}^0, T \right). \tag{152}$$

By (150) and (152), $\overline{T}$ is (globally) Lipschitzian with respect to the $\mathbb{R}^3$-norm and the local existence of a solution $\overline{E}$ of (144) such that $\overline{E}(t_0) = \overline{E}(t_0)$ is guaranteed by the standard theory of first-order differential systems.

Now, since $\overline{E}$ satisfies (144) in which $\overline{T}$ is given by (149), following the same way as in the proof of Lemma 15, substituting $\overline{E}$ to $\overline{E}$, $\overline{T}$ to $\overline{T}$, and integrating this time over $[t_0, t_0 + t]$, $t \in [0, \delta]$, lead to

$$\left| E_i^i (t_0 + t) \right| \leq \left| E_i^i (t_0) \right| + C \int_{t_0}^{t} \left| E_i^i (s) \right| ds, \quad t \in [0, \delta], \quad i = 1, 2, 3, \tag{153}$$

where $C_0' = C_0' \left( g_{ij}^0, T, r, \|E_i^i\| \right)$. However, by Lemma 15, we have, since $t_0[0, T]: |E_i^i(t_0)| \leq (|E_i^i| + C_2 T)e^{C T}$. Then, by Gronwall inequality,

$$\left| E_i^i (t_0 + t) \right| \leq \left( \left| E_i^i (t_0) \right| + C_2 T \right) e^{C T} + C_1 T \right) e^{C T}, \quad t \in [0, \delta], \quad i = 1, 2, 3, \tag{154}$$

where (see [1]) $C_{10}, C_{11}$ are two constants appearing in Lemma 15 when we bound $t \to \overline{p}(t)$, which shows that every solution $\overline{E}$ of (144) is uniformly bounded. By the standard theory of first-order differential systems, the solution $\overline{E}$ is defined all over $[t_0, t_0 + \delta]$ and $\overline{E} \in C([t_0, t_0 + \delta]; \mathbb{R}^3)$.

(b) We also consider (145) in $\overline{p}$, with $\overline{T}$ defined by (149) in which $\overline{E}, \overline{T}$ are fixed. Since $g_{ij}, 1/g_{ij}, \partial_0 g_{ij}, \overline{E}, \overline{T}$ are continuous functions of $t$, so is $\overline{T}$. Next, we deduce from (106) in which we set $\overline{E}_i = \overline{E}_j = \overline{E}_k = \overline{E}$ that

$$\left\| I_2 \left( t, \overline{E}, \overline{F}, \Phi, U_1 \right) - I_2 \left( t, \overline{E}, \overline{F}, \Phi, U_2 \right) \right\|_2 \leq C_4 \| \overline{P}_1 - \overline{P}_2 \|, \tag{155}$$

where

$$C_4 = C \left( \sum_{i,j} g_{ij}^0 \right)^2 + C \left( \det g \right)^{1/2} \left( \left\| f_1 \right\| + \left\| \overline{E}_2 \right\| \right) + C \left( \det g \right)^{1/2} \sum_{i,j} g_{ij} \sum_{k} \left| \phi_{ij} \right| \left( B_1 + \sum_{k} \frac{1}{\sqrt{g_{kk}}} \right). \tag{156}$$

Now we can use (5) and (6) to bound $z = g_{ij}$, $1/g_{ij}$ and we obtain, for $t \in [t_0, t_0 + \delta]$, then $t \leq t_0 + \delta \leq T + 1$,

$$|z(t)| \leq \left( \sum_{i,j} g_{ij}^0 + \sum_{i,j} \frac{1}{g_{ij}} \right) e^{C(T+1)} + 1, \quad t \in [t_0, t_0 + \delta], \quad z = g_{ij} \frac{1}{g_{ij}}. \tag{157}$$

We then deduce from (157), using

$$\left| E_i^i (t_0 + t) \right| \leq \left( \left| E_i^i (t_0) \right| + C_3 T \right) e^{C T} + C_4 T e^{C T}, \quad t \in [0, \delta], \quad i = 1, 2, 3, \tag{158}$$

since $\overline{E} = \overline{E}_1 = \overline{E}_2$ is uniformly bounded, and $\| \overline{E} \| \leq \| \overline{F} \| \leq r$, since $\overline{F} \in L^3_{2r}(t_0, t_0 + \delta, \mathbb{R}^3)$ that

$$C_4 \leq C_4', \quad \text{where } C_4' = C_4' \left( g_{ij}^0, E_0, |\phi_{ij}|, T, r \right). \tag{159}$$

By (155) and (159), $\overline{T}_2$ is (globally) Lipschitzian with respect to the $\mathbb{R}^3$-norm and the local existence of a solution $\overline{p}$ of (145) such that $\overline{p}(t_0) = \overline{p}(t_0)$ is guaranteed by the standard theory of first-order differential systems.

Now, since $\overline{p}$ satisfies (152) in which $\overline{T}$ is given by (149), following the same way as in the proof of Lemma 15, substituting $\overline{E}$ to $\overline{E}$, $\overline{p}$ to $\overline{p}$, and $\overline{T}$ to $\overline{T}$, and integrating this time over $[t_0, t_0 + t], t \in [0, \delta]$ lead to

$$\left| p_i (t_0 + t) \right| \leq \left( \left| p_i (t_0) \right| + C_{12} T \right) e^{C T} + C_4 T e^{C T}, \quad t \in [0, \delta], \quad i = 1, 2, 3, \tag{160}$$

where $C_{12} = C_{12} \left( g_{ij}^0, |E_1^i|, |\phi_{ij}|, T, r \right)$. However, by Lemma 15, we have, since $t_0[0, T]: \left| p_i (t_0) \right| \leq (|p_0| + C_4 T)e^{C T}$. Then, by Gronwall inequality,

$$\left| p_i (t_0 + t) \right| \leq \left( \left| p_i (t_0) \right| + C_{14} T \right) e^{C T} + C_{14} T e^{C T}, \quad t \in [0, \delta], \quad i = 1, 2, 3, \tag{161}$$

which shows that every solution $\overline{p}$ of (152) is uniformly bounded. By the standard theory of first-order differential systems, the solution $\overline{p}$ is defined all over $[t_0, t_0 + \delta]$ and $\overline{p} \in C([t_0, t_0 + \delta]; \mathbb{R}^3)$.

(c) Next, we have proved in Theorem 10 that the single equation (146) in $f$ has a unique solution $f \in L^3_{2r}(t_0, t_0 + \delta, \mathbb{R}^3)$, substituting $t_0$ to $0, t_0 + \delta$ to $T$, such that $f(t_0) = \overline{f}(t_0)$.

(d) For (147) in $\Phi$, we have by (108)

$$\left\| I_4 \left( t, \overline{F}, \overline{P}_1, f_1, \Phi, U_1 \right) - I_4 \left( t, \overline{F}, \overline{P}_2, f_2, \Phi, U_2 \right) \right\|_2 \leq C_6 \left\| U_1 - U_2 \right\|_w, \tag{162}$$

where

$$C_6 = \frac{\sqrt{2}}{\sqrt{C_0}}. \tag{163}$$

Equations (162) and (163) show that $\overline{T}_4$ is (globally) Lipschitzian with respect to the $\mathbb{R}$-norm and the local existence of
a solution $\Phi$ of (147) such that $\Phi(t_0) = \bar{\Phi}(t_0)$ is guaranteed by the standard theory on first-order differential systems.

Since $\Phi$ satisfies (147) in which $\bar{T}_\delta$ is given by (149), substituting $U$ to $\bar{U}$ in Lemma 15, we find

$$|\Phi(t)| \leq \left| \Phi_0 \right| + (1 + T) \sqrt{2 \left( \left( U_0 + C \left( \left| \bar{E}_0 \right| + \sum_{i=1}^{3} C^i T \right) e^{CT} rT \right) + m_0^3 T \max \left\{ \Phi_0^2, \Phi^2(T) \right\} \right) e^{CT}}, \quad t \in [0, \delta].$$

and conclude that every solution $\Phi$ of (147) is uniformly bounded. By the standard theory of first-order differential systems, the solution $\Phi$ is defined all over $[t_0, t_0 + \delta]$ and $\Phi \in \mathcal{C}([t_0, t_0 + \delta]; \mathbb{R})$.

(e) In the end, for (148) in $U$, with $\bar{T}_\delta$ still defined by (149) in which $\bar{E}, \bar{f}$ are fixed. Since $g_{ij}, l/g_{ij}, \delta g_{ij}, \bar{E}, \bar{f}$ are continuous functions of $t$, so is $\bar{T}_\delta$. We deduce from (109) in which we set $E_1 = \bar{E}_2 = \bar{E}, f_1 = f_2 = \bar{f}$ that

$$\left\| I_5 \left( t, \bar{E}, \bar{p}_1, \bar{f}, \bar{\Phi}_1, U_1 \right) - I_5 \left( t, \bar{E}, \bar{p}_2, \bar{f}, \bar{\Phi}_2, U_2 \right) \right\| \leq C_7 \left( \left\| \Phi_1 - \Phi_2 \right\|_R + \left\| U_1 - U_2 \right\|_R \right).$$

Applying the Gronwall inequality this time over $[t_0, t_0 + t]$, $t \in [0, \delta[$, we find

$$|\Phi(t)| \leq \left| \Phi_0 \right| + (1 + T) \sqrt{2 \left( \left( U_0 + C \left( \left| \bar{E}_0 \right| + \sum_{i=1}^{3} C^i T \right) e^{CT} rT \right) + m_0^3 T \max \left\{ \Phi_0^2, \Phi^2(T) \right\} \right) e^{CT}}, \quad t \in [0, \delta].$$

and Lemma 15, we find

$$C_7 \leq C'_7,$$

where $C'_7 = C'_7 \left( g_{ij}, \delta, m_0, \left| \bar{E}_0 \right|, \left| \Phi_0 \right|, U_0, r \right)$.

We conclude by (166), (169) that $\bar{T}_\delta$ is (globally) Lipschitzian with respect to the $R$-norm and the local existence of a solution $U$ of (148) such that $U(t_0) = \bar{U}(t_0)$ is then guaranteed by the standard theory on first-order differential systems.

We similarly show that every solution $U$ of (148) is uniformly bounded and by the standard theory of first-order differential systems, $U$ is defined all over $[t_0, t_0 + \delta]$ and $U \in \mathcal{C}([t_0, t_0 + \delta]; \mathbb{R})$.

This ends the proof of Proposition 16.

We now set

$$X^\delta = \left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2 \times H^3_{d_\delta} \left( t_0, t_0 + \delta, \mathbb{R}^3 \right)$$

$$Y^\delta = \left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2 \times H^3_{d_\delta} \left( t_0, t_0 + \delta, \mathbb{R}^3 \right) \times \left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2.$$

$X^\delta$ is a complete metric subspace of the Banach space $\left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2 \times H^3_{d_\delta} \left( t_0, t_0 + \delta, \mathbb{R}^3 \right)$ and $Y^\delta$ is a complete metric subspace of the Banach space $\left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2 \times H^3_{d_\delta} \left( t_0, t_0 + \delta, \mathbb{R}^3 \right) \times \left( \mathcal{C} \left( [t_0, t_0 + \delta]; \mathbb{R}^3 \right) \right)^2.$

With Proposition 16 we define the map:

$$g : X^\delta \longrightarrow Y^\delta,$$

where $g : \text{dom}(g) \longrightarrow \text{im}(g)$.

We claim the following.
Proposition 17. Let \( t_0 \in [0, T] \). There exists a number \( \delta \in (0, 1] \), independent of \( t_0 \), such that the system \((E_2, p, f, \Phi, U)\) has a unique solution \((E, p, f, \Phi, U)(t)\) such that \((E, p, f, \Phi, U)(t_0) = (\overline{E}(t_0), \overline{p}(t_0), \overline{f}(t_0), \overline{\Phi}(t_0), \overline{U}(t_0))\).

Proof. We will prove that there exists a number \( \delta \in (0, 1] \), independent of \( t_0 \), such that the map \( g \), defined by (172), induces a contraction of the complete metric space \( \mathcal{X}_0^\delta \) defined by (170), which will then have a fixed point \((E, p, f, \Phi, U)\) of the system \((E_1, p, f, \Phi, U)\).

With the initial data \((E(t_0), p(t_0), f(t_0), \Phi(t_0), U(t_0))\) at \( t = t_0 \), the differential system (144)-(145)-(146)-(147)-(148) is equivalent for \( i = 1, 2, 3 \), and using notations (149) to the integral system

\[
(\int_{t_0}^{t_0+\tau} I_1(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad (E_1(t_0+t) = \overline{E}(t_0) + \int_{t_0}^{t_0+\tau} I_1(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad (p_1(t_0+t) = \overline{p}_1(t_0) + \int_{t_0}^{t_0+\tau} I_2(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad (f(t_0+t) = \overline{f}(t_0) + \int_{t_0}^{t_0+\tau} I_3(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad (\Phi(t_0+t) = \overline{\Phi}(t_0) + \int_{t_0}^{t_0+\tau} I_4(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad (U(t_0+t) = \overline{U}(t_0) + \int_{t_0}^{t_0+\tau} I_5(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau,
\]

where

\[
\int_{t_0}^{t_0+\tau} I_1(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad \int_{t_0}^{t_0+\tau} I_2(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad \int_{t_0}^{t_0+\tau} I_3(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad \int_{t_0}^{t_0+\tau} I_4(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau, \quad \int_{t_0}^{t_0+\tau} I_5(t, E, \overline{p}, \overline{f}, \Phi, U)(\tau) \, d\tau.
\]

(a) Now we can deduce, from (106) in which we set \( f_1 = \overline{f}_1, f_2 = \overline{f}_2 \),

\[
\left\| I_1 \left( t, E_1, \overline{p}_1, \overline{f}_1, \Phi, U_1 \right) - I_1 \left( t, E_2, \overline{p}_2, \overline{f}_2, \Phi, U_2 \right) \right\|_{\mathcal{H}^3_1(R^3)} 
\leq C_3 \left( \| E_1 - E_2 \|_{\mathcal{H}^3_1(R^3)} + \| \overline{f}_1 - \overline{f}_2 \|_{\mathcal{H}^3_1(R^3)} \right) (\tau),
\]

where \( C_3 = C_3'(g_0^\delta, T) \) is still given by (152).

(b) Next, since \((E_j, p_j, f_j, \Phi_j, U_j) \in \mathcal{X}^\delta_0, j = 1, 2, \) we deduce from (107) in which we set \( E_1 = E_1, E_2 = E_2, f_1 = \overline{f}_1, f_2 = \overline{f}_2 \)

\[
\left\| I_2 \left( t, E_1, \overline{p}_1, \overline{f}_1, \Phi_1, U_1 \right) - I_2 \left( t, E_2, \overline{p}_2, \overline{f}_2, \Phi_2, U_2 \right) \right\|_{\mathcal{H}^3_1(R^3)} 
\leq C_4 \left( \| E_1 - E_2 \|_{\mathcal{H}^3_1(R^3)} + \| \overline{p}_1 - \overline{p}_2 \|_{\mathcal{H}^3_1(R^3)} \right) (\tau),
\]

where \( C_4 = C_4'(g_0^\delta, |\Phi_j|_1, T, r) \) is given by (159).

(c) We have by (108) in which we set \( \overline{p}_1 = \overline{p}_1, \overline{p}_2 = \overline{p}_2, \) since \((E_j, p_j, f_j) \in \mathcal{X}^\delta_0, \) and using \( C_5 = B_3 + C(T, g_0^\delta) \( (\det g))^{1/2} \| f_j \|_1 + \| f_j \|_3 \) + C \) is still given by (108):

\[
\left\| I_3 \left( t, E_1, \overline{p}_1, \overline{f}_1, \Phi_1, U_1 \right) - I_3 \left( t, E_2, \overline{p}_2, \overline{f}_2, \Phi_2, U_2 \right) \right\|_{\mathcal{H}^3_1(R^3)} 
\leq C_5 \left( \| \overline{p}_1 - \overline{p}_2 \|_{\mathcal{H}^3_1(R^3)} + \| f_1 - f_2 \|_{\mathcal{H}^3_1(R^3)} \right) (\tau),
\]

where \( C_5 = C_5'(g_0^\delta, T, r) \).
(d) We also have, using (109),
\[
\| I_4(t, E_1, p_1, f_1, \Phi_1, U_1) - I_4(t, E_2, p_2, f_2, \Phi_2, U_2) \|_R \\
\leq C_6' \left( \| U_1 - U_2 \|_R \right) (r),
\]
where \( C_6' \) is given by (163).

(e) Finally, from (126) in which we set \( E_1 = \overline{E}_1, E_2 = \overline{E}_2, \)
\( f_1 = \overline{f}_1, f_2 = \overline{f}_2, \) using the fact that \( E_j, \Phi_j, U_j, j = 1, 2 \) are uniformly bounded and \( \| \overline{f}_j(t) \| \leq \| f_j \| \leq r, \)
\( j = 1, 2, \) we deduce that
\[
\| I_5(t, \overline{E}_1, \overline{p}_1, \overline{f}_1, \Phi_1, U_1) - I_5(t, \overline{E}_2, \overline{p}_2, \overline{f}_2, \Phi_2, U_2) \|_R \\
\leq C_7' \left( \| \overline{E}_1 - \overline{E}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| \right)_{H^1[R^3]} \\
+ \| \Phi_1 - \Phi_2 \|_R + \| U_1 - U_2 \|_R (r),
\]
where \( C_7' = C_7' (g_{ij}, T, m_0, [E_0], [\Phi_0], U_0, r) \) is given by (169).

Already notice that the constants \( C_5', C_4', C_5', C_6', \) and \( C_7' \)
are absolute constants independent of \( t_0. \)

Now using the inequalities (179), (180), (181), (182), and (183), we deduce from (178), using the norm \( \| \cdot \| \) and since \( t \in [0, \delta] \)
\[
\| E_1 - E_2 \| \leq C_4' \delta (\| E_1 - E_2 \| + \| \overline{f}_1 - \overline{f}_2 \|) \\
\| \overline{p}_1 - \overline{p}_2 \| \\
\leq C_4' \delta (\| \overline{E}_1 - \overline{E}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| + \| \overline{f}_1 - \overline{f}_2 \|) \\
\| f_1 - f_2 \| \leq C_5' \delta (\| \overline{p}_1 - \overline{p}_2 \| + \| f_1 - f_2 \|) \\
\| \Phi_1 - \Phi_2 \| \leq C_6' \delta (\| U_1 - U_2 \|) \\
\| U_1 - U_2 \| \leq C_6' \delta (\| E_1 - E_2 \| + \| \overline{f}_1 - \overline{f}_2 \| \\
+ \| \Phi_1 - \Phi_2 \| + \| U_1 - U_2 \|).
\]

Now add (184) to obtain
\[
\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| f_1 - f_2 \| \\
+ \| \Phi_1 - \Phi_2 \| + \| U_1 - U_2 \| \\
\leq (C_4' + C_4' + C_5' + C_6' + C_7') \delta \\
\times (\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \|) \\
+ (C_4' + C_4' + C_5' + C_6' + C_7') \delta \\
\times (\| f_1 - f_2 \| + \| \Phi_1 - \Phi_2 \| + \| U_1 - U_2 \|) \\
+ (C_4' + C_5' + C_7') \delta \\
\times (\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| \overline{f}_1 - \overline{f}_2 \|).
\]

First of all we take \( \delta \) such that
\[
(C_4' + C_4' + C_5' + C_6' + C_7') \delta < \frac{1}{2}.
\]

Then, reporting (186) in (185) and simplifying, we obtain
\[
\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| f_1 - f_2 \| \\
+ \| \Phi_1 - \Phi_2 \| + \| U_1 - U_2 \| \\
\leq 2 \left( C_4' + C_5' + C_7' \right) \delta \\
\times (\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| \overline{f}_1 - \overline{f}_2 \|).
\]

Secondly choosing \( \delta \) such that
\[
2 \left( C_4' + C_5' + C_7' \right) \delta < \frac{1}{2},
\]
(187) becomes
\[
\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| f_1 - f_2 \| \\
+ \| \Phi_1 - \Phi_2 \| + \| U_1 - U_2 \| \\
\leq \frac{1}{2} \left( \| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| ight)
\]
from which we deduce that
\[
\| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| f_1 - f_2 \| \\
\leq \frac{1}{2} \left( \| E_1 - E_2 \| + \| \overline{p}_1 - \overline{p}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| + \| \overline{f}_1 - \overline{f}_2 \| ight).
\]

Consequently, if we take
\[
0 < \delta < \inf \left\{ 1, \frac{1}{4} \left( C_4' + C_4' + C_5' + C_6' + C_7' \right) \right\},
\]
(191) shows that \( g : X^0_\delta \rightarrow Y^0_\delta, (\overline{E}, \overline{p}, \overline{f}) \mapsto (\overline{E}, \overline{p}, \overline{f}) \)
defined by (172) induces a contraction \( (\overline{E}, \overline{p}, \overline{f}) \mapsto (\overline{E}, \overline{p}, \overline{f}) \)
in the complete metric space \( X^0_\delta \) which then has a unique fixed point \( (\overline{E}, \overline{p}, \overline{f}) \) and solution of the integral system (173)-(174)-(175) and, hence, of the differential system \( (E_1)-(E_2)-(E_3) \) such that \( (\overline{E}, \overline{p}, f(t_0)) = (\overline{E}(t_0), \overline{p}(t_0), f(t_0)) \). But using
the fact that \((E, p, f) \in C([t_0, t_0 + \delta]; \mathbb{R}^3) \times H^3_{d,r}(t_0, t_0 + \delta, \mathbb{R}^3)\) and that \(t \to E(t), t \to p(t)\) are uniformly bounded, we conclude by Proposition 16 that the subsystem \((E_k)(E_j)\) in \((\Phi, U)\) is globally Lipschitzian in \((\Phi, U)\). So the unique solution \((\Phi, U)\), such that \((\Phi, U)(t_0) = (\bar{\Phi}(t_0), \bar{U}(t_0))\), is global on \([t_0, t_0 + \delta]\) since \(\Phi\) and \(U\) remain uniformly bounded.

Consequently, for \(t_0 \in [0, T]\), there exists a number \(\delta \in [0, 1]\), independent of \(t_0\), such that the system \((E_1)(E_2)(E_3)(E_4)(E_5)(E_6)\) has a unique solution \((\bar{E}, \bar{p}, f, \Phi, U) \in \mathbb{Y}_0^\delta\) such that

\[
(E, p, f, \Phi, U)(t_0) = (\bar{E}(t_0), \bar{p}(t_0), \bar{f}(t_0), \bar{\Phi}(t_0), \bar{U}(t_0)).
\]

(192)

This completes the proof of Proposition 17.

Based on the method detailed in Section 6.1, we have proved the following result.

**Theorem 18.** Let \(E_0 = (E_0) \in \mathbb{R}^3, \psi_{ij} \in \mathbb{R}, f_0 \in H^3(0, T, \mathbb{R}^3), \Phi_0 \in \mathbb{R}, U_0 \in \mathbb{R}^+, \) be given, such that \(|f_0| \leq r, \) where \(r > 0\) is a given real number. Then,

1. the differential system (59)-(60)-(61)-(62) has a unique global solution \((E, f, \Phi, U)\) defined all over the interval \([0, +\infty]\) and such that

\[
(E, f, \Phi, U)(0) = (E_0, f_0, \Phi_0, U_0),
\]

(193)

2. the Maxwell-Boltzmann-Euler system (20)-(21))-(40)-(41) in all Bianchi types I to VIII spacetimes has a unique global solution \((F, f, \Phi)\) defined all over the interval \([0, +\infty]\) and satisfying \(E(0) = E_0, F_{ij}(0) = \psi_{ij}, f(0) = f_0, \Phi(0) = \Phi_0\).

7. Conclusion

The physical significance of the work we did in the present paper is the study of the global dynamics of a kind of fast moving, massive, and charged particles, in the case where the gravitational forces are neglected in front of the electromagnetic forces. We have coupled the Maxwell-Boltzmann system with the Euler equations which simply express the conservation of the Stress-matter tensor for the unknown \(\Phi\) representing a massive scalar field. Notice that this present work follows our paper titled “Global regular solutions to the Maxwell-Boltzmann-Euler system in a Bianchi type 1 spacetime in presence of a massive scalar field,” where the unknowns were like now, the electromagnetic field \(F\), subject to the Maxwell equations, the distribution function \(f\), subject to the Boltzmann equation, and the massive scalar field \(\Phi\), subject to the Euler equations. We have generalized in this present work the result obtained for the Bianchi types 1 spacetime to all Bianchi types 1 to 8 spacetimes. We have only excluded the case of Bianchi type 9 spacetime for the main reason we gave in Section 1. We have also improved the process to establish energy inequalities and the definition of function spaces. In our future investigations we intend to study the same system coupled this time with the Einstein equations with the cosmological constant. The investigation of the global existence of solutions to this Einstein-Maxwell-Boltzmann-Euler system with cosmological constant \(\Lambda\) is with a great interest, in the sense that some recent observations show that the whole universe is in an accelerated expansion, and it is the presence of the cosmological constant in the Einstein equations which mathematically shapes this phenomenon, which is also very important for the evolution of our universe and consequently for the humanity.

**References**


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