A New Capacitor-Less Buck DC-DC Converter for LED Applications

Munir Al-Absi, Zainulabideen Khalifa, and Alaa Hussein

Electrical Engineering Department, Faculty of Engineering, King Fahd University of Petroleum and Minerals, Dhahran, Saudi Arabia

Correspondence should be addressed to Munir Al-Absi; mkulaib@kfupm.edu.sa

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1. Introduction

Light emitting diodes (LEDs) are starting to experience widespread usage in many lighting applications. LEDs are replacing florescent lighting because of the LEDs' advantages compared to the florescent lamps. These advantages are mainly lower power consumption and longer life expectancy. However, commercial LED drivers limit the life expectancy of the LED lighting system to around one-fifth of the lifetime of the LED itself. The main reason of the driver short lifetime is the smoothing capacitor at the output. This is due to leakage in this capacitor, and hence this causes degradation in the driver performance with time. Several works on electrolytic capacitor-less LED drives have been presented to maximize the overall lifetime of the LED system and the recent states of the art are given in [1–7]. In [1], a current injection approach is used. In [2–7] several single-stage topologies using multiple switches or using shared switch techniques are presented. Most of the works presented require relatively complicated power circuits or current controlled technique to reduce the size of the energy storage capacitor. These topologies lead to larger area and higher cost. A new design of capacitor-less driver is presented in [8]. The design used a storage capacitor \( C_d \) and a two-winding dual inductor.

The major intention of this paper is to build upon the results obtained in [9] and present the mathematical model and experimental results to confirm the functionality of the design. The rest of the paper is organized as follows: Section 2 describes the proposed design. Mathematical analysis and experimental results are given in Section 3. Section 4 concludes the paper.

2. The Proposed Design

The proposed design is based on the well-known buck converter shown in Figure 1, where the output voltage is the voltage across the load resistance \( R_L \) and \( C_0 \). \( V_{puls} \) represents the controlling pulses generated from the control circuit. The DC output voltage is given by

\[
V_{O(\text{DC})} = \frac{D(V_{\text{in}} - V_{ds}) - D'V_d}{1 + r_L/R_L}, \tag{1}
\]

where \( V_{ds} \) is the drain-to-source voltage of the MOS transistor used for switching, \( r_L \) is the inductor resistance, \( V_d \) is the diode voltage drop, \( D \) is the ON duty cycle of the control pulse, and \( D' \) is the OFF duty cycle of the pulse.

The inductor \( L \) and the smoothing capacitor \( C_0 \) will average the pulses passing through Q1 causing ripples on the load. The ripple voltage will be affected by the duty cycle, the switching frequency, the inductance, the internal resistance of
the smoothing capacitor ESR, and the value of the smoothing capacitor.

The approximate voltage ripples assuming linear models and a small ripple voltage are given by [10]

\[ \Delta V_r = \frac{V_{in} - (V_o + V_{ds} + V_rL)}{L f_s} \times D \left( \frac{1}{8C_o f_s} + ESR \right), \] (2)

where \( f_s \) is the switch frequency of \( V_{pulse} \), \( L \) is the inductor, \( V_{rL} \) is the voltage across the inductor resistance, and ESR is the capacitor series resistor.

The proposed design is a modified version of the design in Figure 1 and is shown in Figure 2, where the load is an array of LEDs, as it is the case in all commercially available LED lamps. The internal capacitance of the LED array will act as a smoothing capacitor if a proper switching frequency and duty cycle are chosen, and hence no external smoothing capacitor is needed.

3. Mathematical Analysis and Experimental Results

3.1. Mathematical Analysis. It is well known that the LED in conduction mode can be modeled using a resistor and an ideal diode for DC mode and a capacitor and a resistor in parallel for AC mode as shown in Figures 3(a) and 3(b), respectively. The resistance \( r_s \) represents the constant series contact resistance and quasineutral region resistance of the LED, \( r_d \) represents the small signal resistance of the LED at certain DC current, and \( C_d \) represents the diffusion capacitance at a certain DC current. In conduction mode, \( r_d \) is the reciprocal of the conductance which is equal to the DC current divided by the thermal voltage. This indicates that as the DC current increases, the value of the resistance \( r_d \) will decrease. Moreover, the value of \( C_d \) also is a function of the conductance and its value will increase as the current increases [11].

With reference to Figure 2, the DC output voltage across the LEDs is the same as in (1) with \( R_L \) replaced by \( R_{LED} \). The LED equivalent circuits shown in Figure 3 are used in this analysis. The DC output voltage is given by

\[ V_{O(DC)} = D (V_{in} - V_{ds}) - D'V_d \left( \frac{1}{r_s} + \frac{1}{r_d} \right), \] (3)

where \( r_L \) is inductor resistance. The value of \( R_{LED} \) depends on the current passing through the LED, and it can be deduced from the \( I-V \) characteristics curve of the LED shown in Figure 4. It is clear from Figure 4 that as the current increases, the value of \( R_{LED} \) will decrease.

To find the effective capacitance of the LED, the ripple current is given by

\[ \Delta I_{pp} = \frac{V_{in} - (V_o + V_{ds} + V_{rL})}{L f_s} \times D, \] (4)

where \( \Delta I_{pp} \) is the ripple current through the inductor \( L \). From Figure 2 and the model of Figure 3, the output voltage ripple
explained in the next section. This fact is supported by the observation that as the DC current increases, the ripple voltage decreases, which is another parameter that can be used to indicate that the LED is in the conduction region. Figures 8 and 9 show the ripple voltage at 100 kHz for different DC current values.

3.2. Experimental Results. The circuit shown in Figure 2 was connected in the laboratory using off-the-shelf components to test the proposed design experimentally. The LED used is the sum of 3 series packages of 11 parallel LEDs per package giving a total of 33 LEDs. The output voltage is measured across the LED packages. The components used are as follows: $L$ is an inductor of 470 nH, $Q1$ is an N-MOS power transistor BUZ71, $V_p$ is the switching control pulse with an amplitude of 10 V, and $D1$ is a silicon fast switching diode 1N914. The inductor's series resistance was measured and its value was approximately 4 Ω. It was assumed that the AC source was rectified and provided a DC output called $V_{IN}$ with nominal voltage of 35 V. The LED’s I-V characteristics shown in Figure 4 have been used to extract the value of $R_{LED}$ for different DC current values.

The behavior of the circuit was studied by varying the duty cycle of $V_p$ from 18% to 44% at three different frequencies (100 kHz, 150 kHz, and 200 kHz). The maximum duty cycle was set to 44% because this duty cycle will produce the maximum LED current. The DC output and ripple voltage are plotted in Figure 6. As is clear from the figure, as the duty cycle increases, the DC output voltage increases. The ripple voltage decreased with the increase in frequency.

From Figure 6, the DC voltage is changing linearly with the duty cycle for $D > 30%$. Also, it is clear that, for duty cycle greater than 30%, the error is less than 3%. The deviation between theoretical and experimental results is shown in Figure 7. It is evident from the plot that a designer should select the switching pulse duty cycle to be greater than 30% to minimize the error and a higher frequency to minimize the ripple voltage.

If the voltage across the LED reached below a certain value, there will be no diffusion capacitor, and the LED's voltage will drop logarithmically, causing the large error shown in Figure 7. This value can be estimated from the knees of each curve and depends on the forward current as well, since it depends on how deep the LED is in the conduction region. Figures 8 and 9 show the ripple voltage at 100 kHz with duty cycle of 18% and 40%, respectively. The nonlinearity is clearly shown in Figure 8, where the OFF period was long enough to drive the LED to the weak conduction region while the ripple of Figure 9 is almost linear. It is clear that the ripple is linear for higher duty cycle.
To investigate the changes on the DC output voltages and ripple, the frequency was swept from 50 kHz to 300 kHz at a fixed duty cycle of 40%, and the output was probed. The result is shown in Figure 10. It is clear that the ripple voltage is decreasing as the frequency increases and the DC voltage is almost constant. The minimum ratio of ripple voltage to DC voltage is around 1.4% and it can be decreased further by increasing the frequency.

Efficiency is an important factor in a LED driver. The efficiency was found by measuring the DC output voltage, the output current, the DC input voltage, and the input current for each duty cycle for different frequencies. Experimental results displayed in Figure 11 show that the average efficiency is 85%. The efficiency can be further improved using an inductor with smaller internal resistance and a transistor with smaller ON resistance.

Because of the slight changes in the DC output voltage, the efficiency is barely changing with the change of the frequency, as shown in Figure 12. The average of the efficiency over the frequency range was about 88%. Increasing the frequency further will lead to smaller ripple voltages and smaller components for better integration. However, increasing the switching frequency will reduce the efficiency of the drive because of the switching power loss for light loads [12]. As for LED lighting applications, the LED load needs to draw high current specially when using a capacitor-less drive. This is because it is better to use many parallel LEDs for higher...
summation of LED capacitance, which gives this method one more advantage.

4. Conclusion

A new approach to designing capacitor-less buck DC-DC converter was developed and tested. The proposed single switch circuit is able to reduce the ripple in a compact form and can be extended to any other LED configuration. The design's mathematical model was developed based on experimental verification. The efficiency of the driver is 85% and we expect the lifetime to be much higher than existing drives, as there is no capacitor in the switching path of the driver.

Competing Interests

The authors declare that they have no competing interests.

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