

Research Article

Maximize Expected Profits by Dynamic After-Sales Service Investment Strategy Based on Word-of-Mouth Marketing in Social Network Shopping

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This paper discusses how word-of-mouth marketing affects the profits of product sales in social network-based shopping under good after-sales service. First, a new word-of-mouth communication model based on silent evaluation, positive evaluation, and negative evaluation is proposed. Second, we use the way of increasing after-sales service to achieve high praise and thereby maximize the expected profits. Thus, the proportion control problem of after-sales service investment is modeled as an optimal control problem. Third, the existence of optimal control is proved, and an optimal control strategy for dynamic proportion of after-sales service investment is proposed. Fourth, through data simulation of different real-world networks, it is verified that the expected profits under the dynamic after-sales service strategy is higher than that under any uniform control strategy. Finally, sensitivity analysis is performed to explore how different parameters affect the expected profits.

1. Introduction

With the boom of social networking, more and more consumers are making purchase decisions based on word of mouth (WOM). Nearly three-quarters (73%) of consumers regularly recommend products to their friends, according to an Accenture survey [1]. The rapid advancement of e-commerce and logistics networks has changed the way of shopping in China. Online shopping is characterized by easy access to actual WOM. Compared with traditional advertising strategies, WOM influence strategies cost less and deliver more revenue [2–9].

In recent years, researchers have examined ways to maximize product profits from different perspectives based on WOM marketing. For example, the relationship between users was used to explore the impact of WOM marketing on consumers [10–12]. Users' WOM feedback

data was used to mine information that is conducive to enterprises' innovation or growth [13–15]. A dynamic discount pricing strategy aiming at maximizing product profits based on WOM marketing was proposed [16–18]. Using WOM as an epidemic, a framework was constructed to discuss the impact of WOM on sales based on epidemic models [19–21].

In recent years, social network-based shopping, typified by shopping on WeChat, has emerged in China. The biggest characteristic of this shopping lies in its reliance on social networks for product sales. In particular, since the early 2020, when the COVID-19 outbreak caused a sharp drop in customer visits and product sales in physical stores, more and more sellers have begun to set up shopping groups to sell products on social networks such as WeChat. These shopping groups, which we call community buying groups, tend to have the following characteristics:

Members in such a group are often closely related, i.e., they may be members of the same company, neighbor users, etc. This makes it easy to spread WOM among different nodes within a social network, which directly affects product sales. Since most customers are familiar with each other, reviews are usually truthful and valid. Therefore, positive WOM has a significant impact on product sales.

Community group buying often involves repeat purchases, and positive WOM, in particular, prompts consumers to make repeat purchases. Therefore, WOM affects the initial purchase intention of customers.

After customers buy a product, their evaluation is usually three-fold: silent, positive, and negative. Evidently, positive WOM helps to increase the purchase intention of the remaining customers, and negative WOM reduces their purchase intention.

After-sales service works in two ways for enhancing WOM. On the one hand, it encourages customers who have been remaining silent to post more positive reviews; on the other hand, it helps to reverse customers' negative reviews and finally drive positive WOM publicity.

We note that several studies have been conducted on the positive and negative effects of WOM [22–26]. Based on the cognitive dissonance theory and social support theory, Balaji et al. [27] studied the roles of situational factors, personal factors, and social network factors in determining customers' willingness to use social networking sites for negative WOM communication. Verhagen et al. [28] proposed a sender-oriented model to explore the effects of emotions and negative online WOM on re-sponsorship and switching intention. Dalman et al. [29] investigated how high-equity and low-equity brands attract negative WOM from consumers in the event of market failure. Weitzl et al. [30] suggested that online care (i.e., messages in response to online complaints) can mitigate complainants' adverse attributions of failure (i.e., track, controllability, and stability).

Inspired by the epidemic model, this paper takes WOM as a kind of epidemic and establishes a nodal dynamic WOM propagation model. From the characteristics of community group buying, it can be concluded that WOM has important implications for product sales. However, community group buying is small in scale and the profit it generates is limited. Investing heavy resources to maintain WOM would be costly. In this paper, we focus on how to dynamically invest in after-sales service to maximize profits. The main contributions are as follows:

First, a node-level model based on WOM marketing is established to reveal the influence of WOM on consumers' purchase intention.

Second, on this basis, the dynamic control problem of WOM through after-sales service is modeled as an optimal control problem.

Third, we prove that the model has optimal control and obtain the optimal system for solving the model.

Fourth, by solving the corresponding optimal system, some optimal control strategies are given, which are then compared with uniform control. The comparison demonstrates the superiority of optimal control strategies over uniform control ones.

Finally, the influence of after-sales service on product sales is further discussed through sensitivity analysis of relevant after-sales service parameters.

The remainder of the paper is organized as follows. In Section 2, we establish a node-level Target-Buying-Refusing (TBR) model based on WOM marketing and model the dynamic after-sales service (DAS) problem as an optimal control problem. In Section 3, we perform theoretical analysis on the optimal control problem and give a dynamic strategy for after-sales service investment. Some optimal DAS strategies are given in Section 4. In Section 5, the influence of some after-sales service parameters on expected profits is further revealed. The concluding remarks are drawn in Section 6.

2. The Modeling of the DAS Investment Problem

In this section, we consider the WOM marketing problem with DAS investment. In view of the sales activities involved in community group buying, a DAS investment strategy is developed in order to maximize profits for sellers. The highlights of this section are as follows: (1) introducing basic symbols and terms; (2) establishing a TBR model based on WOM marketing; (3) modeling the DAS problem as an optimal control problem.

2.1. Terms and Notations. Assuming the number of users for a community group purchase is N , we let $G = (V, E)$ denote the topology of this network. Specifically, $V = (V_1, V_2, \dots, V_N)$ represents the nodes of the network and N is the number of nodes in the network; furthermore, $E_{ij} = \{V_i, V_j\} \in E$, which represents nodes V_i and V_j are friends, so G is an undirected network; $A = (a_{ij})_{N \times N}$ represents the adjacency matrix of network G . When $a_{ij} = 1$, V_i and V_j can share their reviews on products with each other.

Let the vector $O(t) = (O_1(t), O_2(t), \dots, O_N(t))$ represent the state of N nodes in the network at time t . Assuming that a product is sold in a finite time horizon $[0, T]$, individual users may have the following three states in community group buying: $O_i(t) = 0$, $O_i(t) = 1$, and $O_i(t) = 2$, corresponding to target customers (who have not yet decided whether to buy the product), buying customers (who buy the product), and refusing customers (who refuse to buy the product) at time t , respectively. Let $T_i(t)$, $B_i(t)$, and $R_i(t)$ denote the expected probabilities of node V_i being target customers, buying customers, and refusing customers at time t , respectively:

$$\begin{aligned}
T_i(t) &= \Pr\{O_i(t) = 0\}, \\
B_i(t) &= \Pr\{O_i(t) = 1\}, \\
R_i(t) &= \Pr\{O_i(t) = 2\}.
\end{aligned} \tag{1}$$

Note that $T_i(t) + B_i(t) + R_i(t) = 1$. Specifically, buying customers are categorized into three groups in terms of their evaluation: silent, positive, and negative. Let $S_i(t)$, $P_i(t)$, and $N_i(t)$ represent the expected probabilities of buying customers who remain silent and give positive and negative evaluations at time t , respectively.

To solve the WOM propagation problem with DAS investment, we introduce the following assumptions:

Due to the shopping share of neighbor nodes who buy the products, target customers become buying customers with a probability of ρ on average

Due to the shopping share of neighbor nodes who refuse to buy the products, target customers become refusing customers with a probability of γ on average

For buying customers, α_1 , α_2 , and α_3 represent the probabilities of them remaining silent, giving positive evaluation and giving negative evaluation; hence, $\alpha_1 + \alpha_2 + \alpha_3 = 1$

Due to the positive WOM effect of buyers, target customers become buying customers with a probability of β_1 on average

Due to the negative WOM effect of buyers, target customers become refusing customers with a probability of β_2 on average

The above assumptions are independent of each other, and the state transition diagram of the node is shown in Figure 1. In practice, parameters ρ , γ , α_1 , α_2 , α_3 , β_1 , β_2 can be estimated from the information of the network.

The vector,

$$E(t) = (T(t), B(t), R(t)), \tag{2}$$

represents the expected state of nodes in the network at time t , where

$$\begin{cases}
T(t) = (T_1(t), T_2(t), \dots, T_N(t)), \\
B(t) = (B_1(t), B_2(t), \dots, B_N(t)), \\
R(t) = (R_1(t), R_2(t), \dots, R_N(t)).
\end{cases} \tag{3}$$

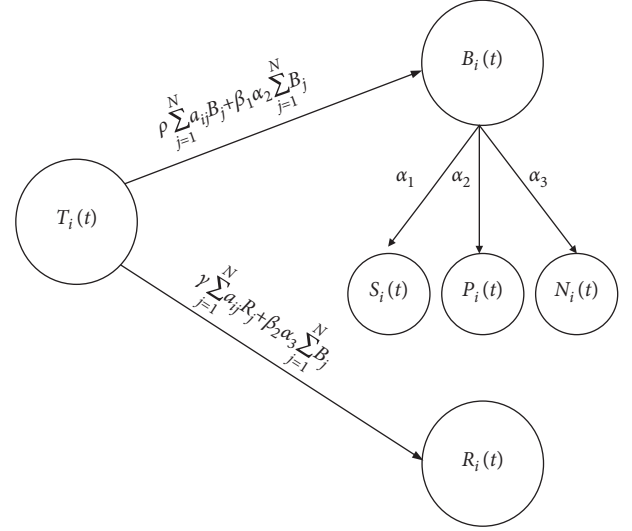


FIGURE 1: State transition diagram of individual V_i at time t .

For ease of understanding, a simple example is given. Assume that there is a topological relationship between network nodes, as shown in Figure 2, and the probability that node 1 is a target customer is 1 at time t , i.e., $T_1(t) = \Pr\{O_1(t) = 0\} = 1$. Suppose the adjacency matrix of nodes in the network is

$$A = \begin{pmatrix} 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \end{pmatrix}. \tag{4}$$

The probabilities of network nodes being in each state are shown in Table 1.

Parameter values are shown in Table 2.

Then, the probability that node 1 is a buying node at $t + \Delta t$ is

$$\begin{aligned}
B_1(t + \Delta t) &= \Pr\{O_1(t + \Delta t) = 1\} = \rho \sum_{j=1}^N a_{1j} B_j + \beta_1 \alpha_2 \sum_{j=1}^N B_j \\
&= \rho (a_{12} \cdot B_2 + a_{13} \cdot B_3 + a_{14} \cdot B_4) + \beta_1 \alpha_2 (B_1 + B_2 + B_3 + B_4 + B_5 + B_6) \\
&= 0.1 \cdot (0.7 + 0.7 + 0.2) + 0.02 \cdot (0.7 + 0.7 + 0.2 + 0.6 + 0.2) = 0.208.
\end{aligned} \tag{5}$$

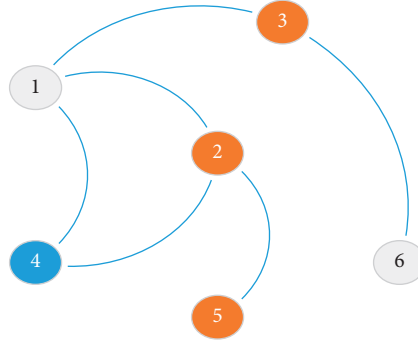


FIGURE 2: A simple network topology.

TABLE 1: Probabilities of nodes being in each state.

Node number	Probability of T_i	Probability of B_i	Probability of R_i
2	0.2	0.7	0.1
3	0.1	0.7	0.2
4	0.2	0.2	0.6
5	0.3	0.6	0.1
6	0.7	0.2	0.1

Then, the probability that node 1 is a refusing node at $t + \Delta t$ is

$$\begin{aligned}
 R_1(t + \Delta t) &= \Pr(O_1(t + \Delta t) = 2) = \gamma \sum_{j=1}^N a_{ij} R_j + \beta_2 \alpha_3 \sum_{j=1}^N B_j \\
 &= \gamma (a_{12} \cdot R_2 + a_{13} \cdot R_3 + a_{14} \cdot R_4) + \beta_2 \alpha_3 (B_1 + B_2 + B_3 + B_4 + B_5 + B_6) \\
 &= 0.1 \cdot (0.1 + 0.2 + 0.6) + 0.04 \cdot (0.7 + 0.7 + 0.2 + 0.6 + 0.2) = 0.186.
 \end{aligned} \tag{6}$$

Then, the probability that node 1 is a target node at $t + \Delta t$ is

$$T_1(t + \Delta t) = 1 - 0.208 - 0.186 = 0.606. \tag{7}$$

2.2. *Dynamic TBR Model Based on WOM Marketing.* The TBR model based on WOM marketing to be derived later conforms to the above assumption. The following system gives an equivalent form of the exact TBR model:

$$\begin{cases}
 \frac{dT_i(t)}{dt} = - \left[\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 \alpha_2 \sum_{j=1}^N B_j(t) + \gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 \alpha_3 \sum_{j=1}^N B_j(t) \right] T_i(t), \\
 \frac{dB_i(t)}{dt} = \left[\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 \alpha_2 \sum_{j=1}^N B_j(t) \right] T_i(t), \\
 \frac{dR_i(t)}{dt} = \left[\gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 \alpha_3 \sum_{j=1}^N B_j(t) \right] T_i(t),
 \end{cases} \tag{8}$$

TABLE 2: Values of parameters based on network.

Parameter	ρ	γ	α_1	α_2	α_3	β_1	β_2
Value	0.1	0.2	0.4	0.2	0.4	0.1	0.1

under the initial condition $\mathbf{E}(0) = \mathbf{E}_0$.

System (8) may be written in system as

$$\begin{cases} \frac{d\mathbf{E}(t)}{dt} = \mathbf{f}_1(\mathbf{E}(t)), & 0 \leq t \leq T, \\ \mathbf{E}(0) = \mathbf{E}_0. \end{cases} \quad (9)$$

2.3. Optimal Control Modeling of the DAS Problem. We refer to the function $\theta = \{\theta_1(t), \theta_2(t)\}$, $0 \leq t \leq T$, as a DAS strategy. $\theta_1(t)$ is the proportion of investment in the first type of after-sales service, including the proportion of silent users converted into positive reviews through cash back. $\theta_2(t)$ is the proportion of investment in the second type of after-sales service, including the proportion of negative reviews converted into positive ones by compensating users for their losses. Therefore, we assume that the DAS strategy is

$$\theta = \{(\theta_1(t), \theta_2(t)) \in L[0, T]^2 \mid 0 \leq \theta_1(t) \leq \bar{\theta}_1, \quad 0 \leq \theta_2(t) \leq \bar{\theta}_2, 0 \leq t \leq T\}, \quad (10)$$

where $L[0, T]^2$ represents the set of all Lebesgue integrable functions defined on $[0, T]$ [31].

It is widely known that profits are closely associated with the sales of products. Theoretically, the higher the sales of products is, the more negative reviews there will be. In WOM-oriented community group buying, in particular, negative reviews will directly affect the sales of products, resulting in a decline in profits. The proportion of positive WOM can be increased by investing in after-sales service. However, such investment tends to increase the cost and reduce the profit. In view of this, this paper intends to establish a dynamic proportion of investment in after-sales service to maximize the final profit.

Remark 1. Assuming that the profit per unit of a product is c_1 , the total profit from selling the product at time $[0, T]$ is

$$L_1(\theta) = \int_0^T \sum_{i=1}^N c_1 B_i(t) dt. \quad (11)$$

Remark 2. Assuming that the investment proportion of the first type of after-sales service is $\theta_1(t)$ and its average unit cost is c_2 , the cost of after-sales service at time $[0, T]$ is

$$L_2(\theta) = \int_0^T \sum_{i=1}^N c_2 \alpha_1 \theta_1(t) B_i(t) dt. \quad (12)$$

Remark 3. Assuming that the investment proportion of the second type of after-sales service is $\theta_2(t)$ and its average unit cost is c_3 , the cost of after-sales service at time $[0, T]$ is

$$L_3(\theta) = \int_0^T \sum_{i=1}^N c_3 \alpha_3 \theta_2(t) B_i(t) dt. \quad (13)$$

In summary, the expected profit is

$$\begin{aligned} J(\theta) &= L_1(\theta) - L_2(\theta) - L_3(\theta) \\ &= \int_0^T \sum_{i=1}^N (c_1 - c_2 \alpha_1 \theta_1(t) - c_3 \alpha_3 \theta_2(t)) B_i(t) dt \\ &\equiv \int_0^T \mathbf{F}(\mathbf{E}(t), \theta(t)) dt, \end{aligned} \quad (14)$$

where

$$\mathbf{F}(\mathbf{E}(t), \theta(t)) = \sum_{i=1}^N (c_1 - c_2 \alpha_1 \theta_1(t) - c_3 \alpha_3 \theta_2(t)) B_i(t). \quad (15)$$

Based on the above discussions and assumptions, this DAS problem can be modeled as an optimal control problem as follows:

$$\max_{\theta \in \Theta} = \int_0^T \mathbf{F}(\mathbf{E}(t), \theta(t)) dt$$

subject to

$$\left\{ \begin{array}{l} \frac{dT_i(t)}{dt} = \left[\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2) \sum_{j=1}^N B_j(t) \right. \\ \left. + \gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 (\alpha_3 (1 - \theta_2)) \sum_{j=1}^N B_j(t) \right] T_i(t), \\ \frac{dB_i(t)}{dt} = \left[\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2) \sum_{j=1}^N B_j(t) \right] T_i(t), \\ \frac{dR_i(t)}{dt} = \left[\gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 (\alpha_3 (1 - \theta_2)) \sum_{j=1}^N B_j(t) \right] T_i(t), \\ \mathbf{E}(0) = \mathbf{E}_0. \end{array} \right. \quad (16)$$

The associated TBR model based on WOM can be rewritten as

$$\left\{ \begin{array}{l} \frac{d\mathbf{E}(t)}{dt} = \mathbf{f}_2(\mathbf{E}(t), \theta(t)), \quad 0 \leq t \leq T, \\ \mathbf{E}(0) = \mathbf{E}_0. \end{array} \right. \quad (17)$$

We refer to this optimal control problem as the DAS problem. This model can be described as a 15-tuple problem as follows:

$$\Phi = (G, \rho, \gamma, \alpha_1, \alpha_2, \alpha_3, \beta_1, \beta_2, \bar{\theta}_1, \bar{\theta}_2, c_1, c_2, c_3, \mathbf{E}_0, T). \quad (18)$$

3. Theoretical Study of the DAS Control Problem

3.1. Solvability of the DAS Problem. First, we prove that the DAS problem is an optimal control problem and is solvable. Hence, we derive Lemma 1 [32].

Lemma 1. *The DAS problem is an optimal control problem if all the following five conditions hold.*

- (1) Θ is convex and closed
- (2) There exists $\theta \in \Theta$ such that system (17) is solvable

(3) $\mathbf{f}_2(\mathbf{E}, \theta)$ is bounded by a linear function in \mathbf{E}

(4) $\mathbf{F}(\mathbf{E}, \theta)$ is convex on Θ

(5) There exists $\delta > 1, d_1 > 0$, and d_2 such that $\mathbf{F}(\mathbf{E}, \theta) \geq \|\theta\|_2^\delta + d_2$

Then, we can deduce the following theorem.

Theorem 1. *The DAS problem is an optimal control problem.*

Proof. First, let $\theta = (\theta_1(t), \theta_2(t))$ be a limit point of Θ . Then, there exists a sequence $\theta^n(t) = (\theta_1^n(t), \theta_2^n(t))$, $n = 1, 2, \dots$, of points of Θ , which approaches $\theta(t)$. Since

$$\begin{aligned} 0 \leq \theta_1(t) &= \lim_{n \rightarrow \infty} \theta_1^n(t) \leq \bar{\theta}_1 \leq 1, \\ 0 \leq \theta_2(t) &= \lim_{n \rightarrow \infty} \theta_2^n(t) \leq \bar{\theta}_2 \leq 1, \quad 0 \leq t \leq T. \end{aligned} \quad (19)$$

Θ is closed. Let $\theta^{(1)}, \theta^{(2)} \in \Theta$, $0 < \eta < 1$, $\hat{\theta} = (1 - \eta)\theta^{(1)} + \eta\theta^{(2)}$. As $L[0, T]^2$ is a real vector space, we have $\hat{\theta} \in L[0, T]^2$ and $0 \leq (1 - \eta)\theta^{(1)}(t) + \eta\theta^{(2)}(t) \leq (1 - \eta)\bar{\theta}_1 + \eta\bar{\theta}_1 = \bar{\theta}_1$. Hence, Θ is convex. Second, let $\theta^*(t) \in \Theta$. As $\mathbf{f}_2(\mathbf{E}, \theta^*)$ is continuously differentiable, it follows by the continuation theorem for differentiable systems [33] that the corresponding state evolution state is solvable.

Third, it follows from (17) that for $1 \leq i \leq N$. As $T_i(t) = 1 - B_i(t) - R_i(t)$ and $0 \leq \theta(t) \leq 1$, then we have

$$\begin{aligned}
-\left(\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 \sum_{j=1}^N B_j(t) + \gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 \alpha_3 \sum_{j=1}^N B_j(t)\right) &\leq \frac{dT_i}{dt} \leq \beta_2 \alpha_3 \sum_{j=1}^N B_j, \\
\left(\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 \alpha_2 \sum_{j=1}^N B_j(t)\right) T_i &\leq \frac{dB_i}{dt} \leq \left(\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 \sum_{j=1}^N B_j(t)\right) T_i, \\
\left(\gamma \sum_{j=1}^N a_{ij} R_j(t)\right) T_i &\leq \frac{dR_i}{dt} \leq \left(\gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 \alpha_3 \sum_{j=1}^N B_j(t)\right) T_i.
\end{aligned} \tag{20}$$

Hence, $f_2(\mathbf{E}, \theta)$ is bounded by a linear function in \mathbf{E} . The fourth condition follows that $\mathbf{F}(\mathbf{E}, \theta)$ is linear in Θ and is therefore convex.

Finally, $\mathbf{F}(\mathbf{E}, \theta) \geq 0 \geq (\theta_1^2 + \theta_2^2) - (\bar{\theta}_1^2 + \bar{\theta}_2^2) = \|\theta\|_2^2 - (\bar{\theta}_1^2 + \bar{\theta}_2^2)$. Then, there exists $d_1 = 1, \delta = 2, d_2 = -(\bar{\theta}_1^2 + \bar{\theta}_2^2)$ such

that $\mathbf{F}(\mathbf{E}, \theta) \geq d_1 \|\theta\|_2^\delta + d_2$. By Lemma 1, Theorem 1 is proved. \square

3.2. The Optimality System. According to the optimal control theory, the Hamiltonian function of the DAS problem is

$$\begin{aligned}
H(\mathbf{E}(t), \theta(t), X(t)) &= \sum_{i=1}^N (c_1 - c_2 \alpha_1 \theta_1 - c_3 \alpha_3 \theta_2) B_i(t) \\
&+ \sum_{i=1}^N \lambda_i(t) \left[-\left(\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2) \sum_{j=1}^N B_j(t) \right. \right. \\
&+ \left. \left. \gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 (\alpha_3 (1 - \theta_2)) \sum_{j=1}^N B_j(t)\right) T_i(t) \right] \\
&+ \sum_{i=1}^N \mu_i(t) \left[\left(\rho \sum_{j=1}^N a_{ij} B_j(t) + \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2) \sum_{j=1}^N B_j(t)\right) T_i(t) \right] \\
&+ \sum_{i=1}^N \nu_i(t) \left[\left(\gamma \sum_{j=1}^N a_{ij} R_j(t) + \beta_2 (\alpha_3 (1 - \theta_2)) \sum_{j=1}^N B_j(t)\right) T_i(t) \right],
\end{aligned} \tag{21}$$

where $X(t) = (\lambda(t), \mu(t), \nu(t)) = (\lambda_1, \lambda_2, \dots, \lambda_N, \mu_1, \mu_2, \dots, \mu_N, \nu_1, \nu_2, \dots, \nu_N)$ is the adjoint of H . We give the necessary condition for the optimal control of the DAS problem as follows.

Theorem 2. Suppose $\theta = (\theta_1(t), \theta_2(t))$ is an optimal control of the DAS problem (16) and \mathbf{E} is the solution to the associated TBR model (17). Then, there exists an adjoint function $X(t) = (\lambda(t), \mu(t), \nu(t))$ such that the following equations hold:

$$\left\{ \begin{array}{l}
\frac{d\lambda_i(t)}{dt} = (\lambda_i - \mu_i) \sum_{j=1}^N (\rho a_{ij} + \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2)) B_j(t) \\
+ (\lambda_i - \nu_i) \sum_{j=1}^N \gamma a_{ij} R_j + (\lambda_i - \nu_i) \sum_{j=1}^N \beta_2 \alpha_3 (1 - \theta_2) B_j, \\
\frac{d\mu_i(t)}{dt} = -c_1 + c_2 \alpha_1 \theta_1 + c_3 \alpha_3 \theta_2 + \sum_{j=1}^N \rho a_{ji} T_j(t) (\lambda_j - \mu_j) \\
+ \beta_1 (\alpha_2 + \alpha_1 \theta_1 + \alpha_3 \theta_2) \sum_{j=1}^N (\lambda_j - \mu_j) T_j(t) + \beta_2 \alpha_3 (1 - \theta_2) \sum_{j=1}^N (\lambda_j - \nu_j) T_j(t) \\
\frac{d\nu_i(t)}{dt} = \gamma \sum_{j=1}^N a_{ji} (\lambda_j - \nu_j) T_j(t), \\
0 \leq t \leq T, i = 1, 2, \dots, N, \\
\lambda(T) = \mu(T) = \nu(T) = 0.
\end{array} \right. \quad (22)$$

Moreover, let

$$\begin{aligned}
g_1(t) &= \beta_1 \alpha_1 \sum_{i=1}^N T_i(t) (\mu_i - \lambda_i) - c_2 \alpha_1, \\
g_2(t) &= \sum_{i=1}^N T_i(t) (\beta_1 \alpha_3 (\mu_i - \lambda_i) + \beta_2 \alpha_3 (\lambda_i - \nu_i)) - c_3 \alpha_3.
\end{aligned} \quad (23)$$

Then, for $0 \leq t \leq T$, we have

$$\theta_i(t) = \begin{cases} \bar{\theta}_i, & g_i(t) > 0, \\ 0, & g_i(t) < 0. \end{cases} \quad (24)$$

Proof. According to Pontryagin Minimum Principle [32], there exists (λ, μ, ν) such that

$$\left\{ \begin{array}{l}
\frac{d\lambda_i}{dt} = -\frac{\partial H(E(t), \theta(t), X(t))}{\partial T_i}, \quad 0 \leq t \leq T, i = 1, 2, \dots, N, \\
\frac{d\mu_i}{dt} = -\frac{\partial H(E(t), \theta(t), X(t))}{\partial B_i}, \quad 0 \leq t \leq T, i = 1, 2, \dots, N, \\
\frac{d\nu_i}{dt} = -\frac{\partial H(E(t), \theta(t), X(t))}{\partial R_i}, \quad 0 \leq t \leq T, i = 1, 2, \dots, N.
\end{array} \right. \quad (25)$$

The first $3N$ equations in system (22) follow by direct calculations. Since the terminal cost is unspecified and the final state is free, we have $\lambda(T) = \mu(T) = \nu(T) = 0$. According to Pontryagin Maximum Principle, we have

$$H(E(t), \theta(t), X(t)) = \arg \max_{\bar{\theta} \in \Theta} H(E(t), \bar{\theta}, X(t)), \quad 0 \leq t \leq T. \quad (26)$$

Equations (23) and (24) follow by the following direct calculations:

$$\begin{aligned}
\frac{\partial H}{\partial \theta_1} &= \sum_{j=1}^N B_j \left(\beta_1 \alpha_1 \sum_{i=1}^N T_i(t) (\mu_i - \lambda_i) - c_2 \alpha_1 \right), \\
\frac{\partial H}{\partial \theta_2} &= \sum_{j=1}^N B_j \left(\sum_{i=1}^N T_i(t) (\beta_1 \alpha_3 (\mu_i - \lambda_i) + \beta_2 \alpha_3 (\lambda_i - \nu_i)) - c_3 \alpha_3 \right).
\end{aligned} \quad (27)$$

□

By the optimal control theory, equations (16) and (22) constitute the optimality system for the TBR model. We refer to the control in each solution to the optimality system as a potential optimal control (POC) of the DAS problem. It is seen from equation (24) that the optimality system may have more than one POC.

4. Examples of the POC

For the notion of POC we introduced earlier for the DAS problem, now we provide some examples of the POC. First, the optimality system (17) and (22) is solved using the Runge–Kutta and backward Runge–Kutta fourth-order iterative procedure [34, 35].

To generate a large number of DAS examples, three real-world networks are selected: Facebook network G_{FA} , e-mail network G_{EM} , and Twitter network G_{TW} . We select the subnet of the network as the total number of nodes of the

three networks with $N = 100$. Let A_{FA}, A_{EM} , and A_{TW} denote the adjacency matrix of G_{FA}, G_{EM} , and G_{TW} , and the network topology is shown in Figure 3. Let the initial value $E_0 = (T_0, B_0, R_0) = (0.7, \dots, 0.7, 0.2, \dots, 0.2, 0.1, \dots, 0.1)$.

Experiment 1. Stabilities of the three states.

The parameters and their values are shown in Table 3.

As can be seen from Figure 4, in all of three networks, the expected probabilities of the three states are stable at a fixed value. Moreover, when the probability of negative evaluation in the network is larger than that of positive evaluation, nodes tend to refuse to buy the product.

Experiment 2. Optimal control strategies in networks.

Consider the TBR model (17) with $G = G_{FA}, G = G_{EM}, G = G_{TW}, \bar{\theta}_1 = 1, \bar{\theta}_2 = 1, c_1 = 50, c_2 = 5$, and $c_3 = 10$, and the remaining parameters are shown in Table 3. The optimal control θ_{poc} is obtained by solving the optimal system, as shown in Figure 5. Figure 6 exhibits $\theta_{poc} \cup \theta_{p,q}$, $p = (0, 0.1, 0.2, \dots, 1)$ and $q = (0, 0.1, 0.2, \dots, 1)$. It is seen that $J(\theta_{poc}) > J(\theta_{p,q})$, for all $p, q \in [0, 1]$. θ_{poc} is superior to all the uniform controls in the three networks in terms of expected profits. In the above experiment and 100 similar experiments, it is worth emphasizing that θ_{poc} outperforms all static controls in terms of expected profits across all the networks, which demonstrates the optimality of θ_{poc} .

As can be seen from Figure 6, when there is no after-sales service ($\theta_{0,0}$) in the community group buying network, the expected profit of sales in the whole network is the lowest due to the influence of negative WOM. When $q = 1$, although p is different, the expected profit generated by community group buying is almost the same for the three networks. This phenomenon indicates that reversing negative WOM through after-sales service is more helpful in improving expected profits than operations such as cash back. Moreover, it can be seen from Figures 5 and 6 that the DAS optimal control strategies are concentrated at the initial time, which suggests the importance of timely after-sales service. Delayed or continuous after-sales service has no obvious effect on improving consumers' purchase intention and increasing expected profits.

Experiment 3. Effects of optimal control strategies.

As shown in Figure 7, we compare the expected probabilities of buying and refusing states without control and with the optimal control strategy. It can be inferred that, through DAS optimal control strategies, the probability of buying is greatly increased, while that of refusing buying is greatly decreased. This further proves the importance of after-sales service.

5. The Influence of Parameters on Expected Profits

In this section, we discuss how different parameters affect the expected profits. On the one hand, taking node 30 as an example, we discuss the effects of different parameters on

purchase intention. On the other hand, given the similar simulation results of the three networks, the e-mail network is taken as an example for illustration, as shown in Figure 8.

Experiment 4. Effects of parameters $\rho, \gamma, \beta_1, \beta_2$ on purchase intention.

Let $\rho, \gamma, \beta_1, \beta_2 = [0.1, 0.3, 0.5, 0.7, 0.9]$ respectively, and the other parameters are shown in Table 3. The probability of the node's purchase intention increases as ρ and β_1 increase, as shown in Figures 8(a) and 8(c), and decreases as γ and β_2 increase, as shown in Figures 8(b) and 8(d). This finding is consistent with the actual representations of the parameters.

Experiment 5. Effects of parameters $\alpha_1, \alpha_2, \alpha_3$ on purchase intention.

Since $\alpha_1 + \alpha_2 + \alpha_3 = 1$, let

- (1) $\alpha_1, \alpha_2 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_3 = 1 - \alpha_1 - \alpha_2$
- (2) $\alpha_1, \alpha_3 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_2 = 1 - \alpha_1 - \alpha_3$
- (3) $\alpha_2, \alpha_3 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_1 = 1 - \alpha_2 - \alpha_3$

When $T = 25$, take the probability of buying for node 30 as an example. As shown in Figure 9(a), when α_2 is very small, the probability changes little with the increase of α_1 . Specifically, despite the increased probability of silent purchase, the probability of final node purchase does not increase significantly. This is because the probability of positive WOM is fixed at a small value. When α_2 is large, the probability increases significantly as α_1 increases. When the probability of positive WOM is fixed at a large value, the probability of negative WOM decreases as the probability of silent purchase increases, so the probability of final node purchase increases significantly. The situation in Figure 9(b) is similar to that in Figure 9(a). It can be clearly seen from Figure 9(c) that the purchase probability increases with the increase of α_2 and decreases with the increase of α_3 .

Under optimal dynamic after-sales service control, the expected profit exhibits different levels of sensitivity to different parameters. Therefore, we will further discuss how the parameters affect the expected profit of the entire community group buying network later in this section.

Experiment 6. Effects of parameters $\rho, \gamma, \beta_1, \beta_2$ on the expected profit.

Let $\rho, \gamma, \beta_1, \beta_2 = [0.1, 0.3, 0.5, 0.7, 0.9]$, respectively, and the other parameters are shown in Table 3. As can be seen from Figure 10, the expected profit of the whole network increases with the increase of ρ, β_1 and decreases with the increase of γ, β_2 after-sales service is available. Based on Figure 8, it can be concluded that when consumers' purchase intention increases, the expected profit also increases in the network.

Experiment 7. Effects of parameters $\alpha_1, \alpha_2, \alpha_3$ on expected profits.

Since $\alpha_1 + \alpha_2 + \alpha_3 = 1$, let

- (1) $\alpha_1, \alpha_2 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_3 = 1 - \alpha_1 - \alpha_2$
- (2) $\alpha_1, \alpha_3 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_2 = 1 - \alpha_1 - \alpha_3$
- (3) $\alpha_2, \alpha_3 = [0.1, 0.2, 0.3, 0.4, 0.5]$ and $\alpha_1 = 1 - \alpha_2 - \alpha_3$

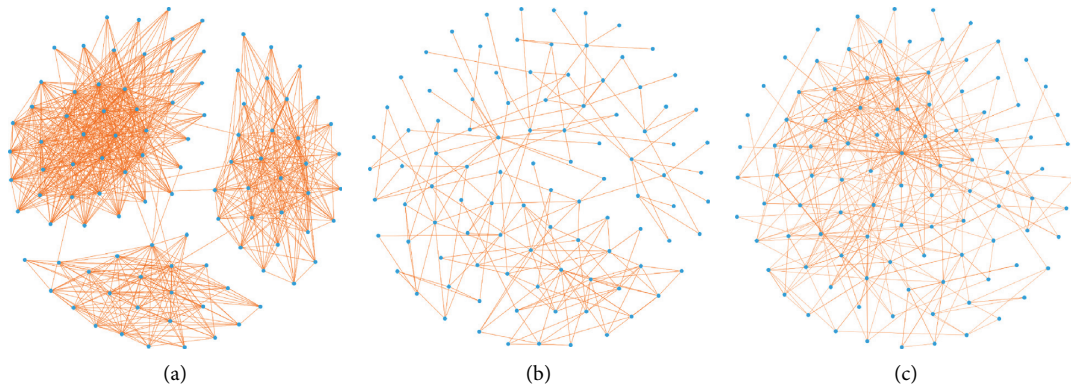


FIGURE 3: (a) Facebook network, (b) e-mail network, and (c) Twitter network.

TABLE 3: Parameters based on the network.

Parameters	ρ	γ	α_1	α_2	α_3	β_1	β_2	T
Value	0.1	0.2	0.4	0.2	0.4	0.1	0.1	25

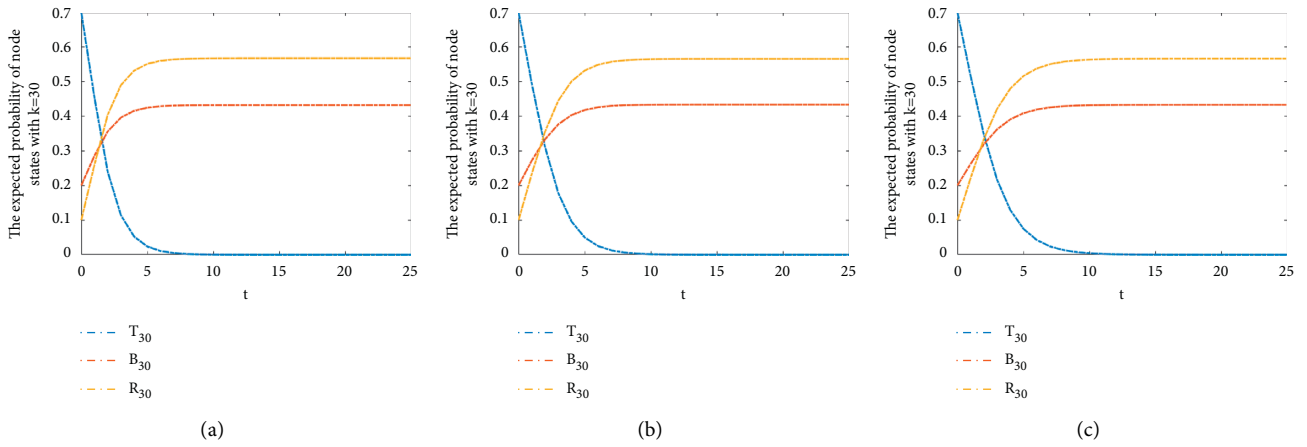


FIGURE 4: (a) Facebook network, (b) e-mail network, and (c) Twitter network.

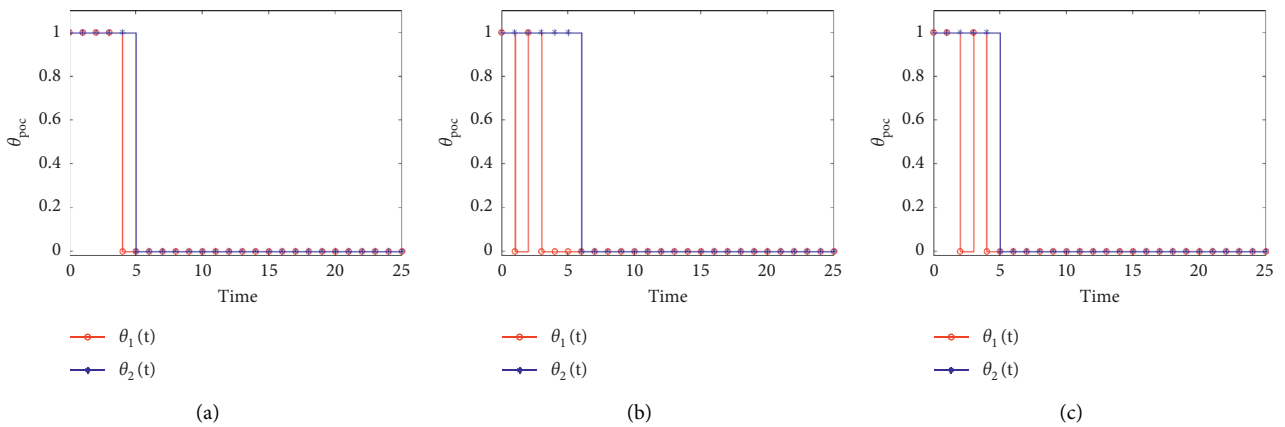


FIGURE 5: Optimal control strategies θ_{poc} in networks: (a) Facebook network, (b) e-mail network, and (c) Twitter network.

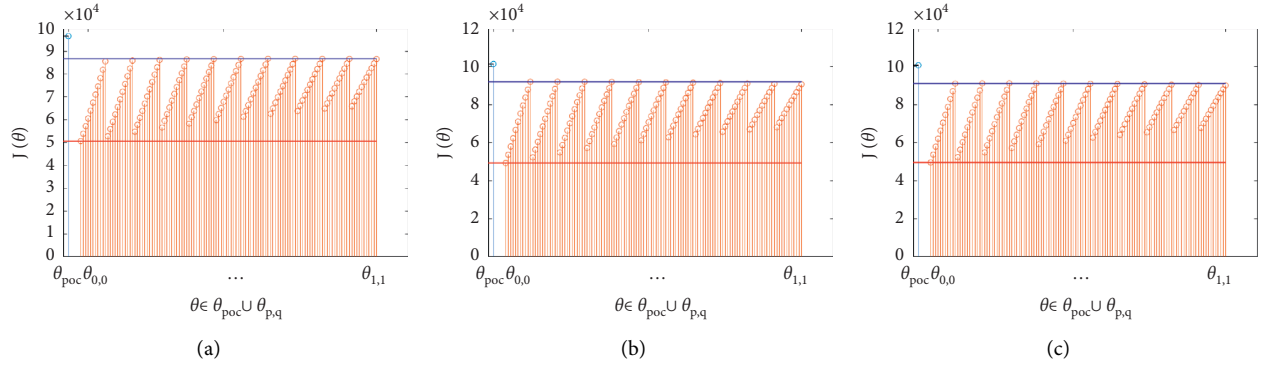


FIGURE 6: Comparison between optimal control strategy θ_{poc} and uniform control strategy $\theta_{p,q}$ in terms of expected profit $J(\theta)$: (a) Facebook network, (b) e-mail network, and (c) Twitter network.

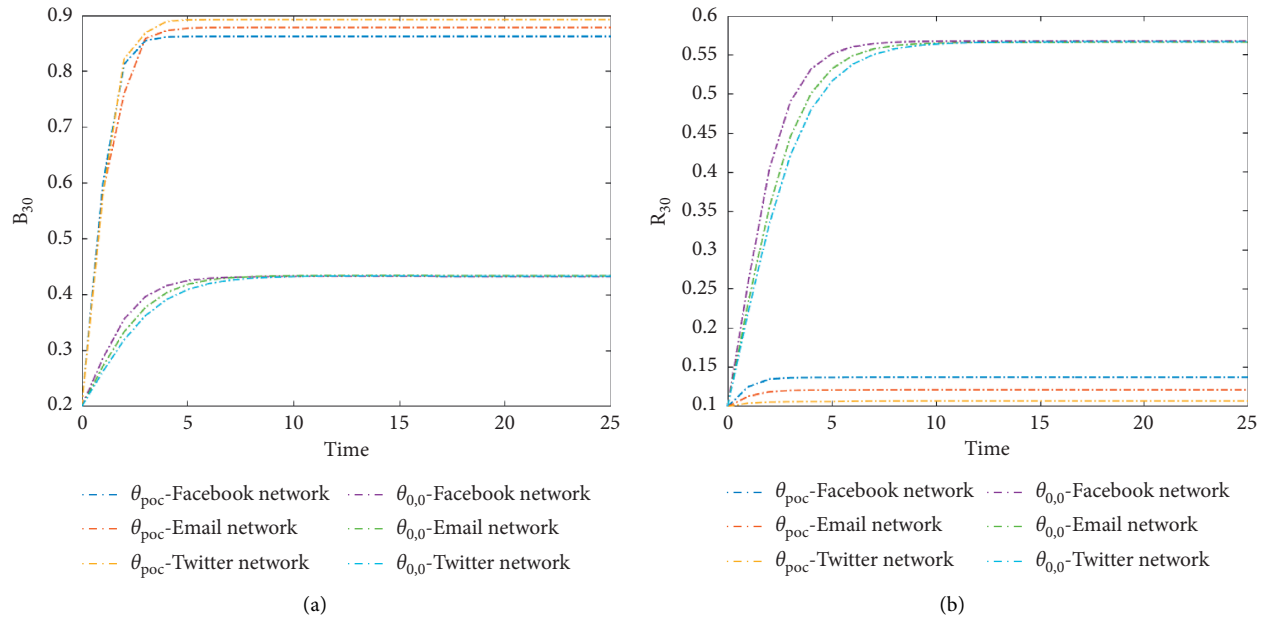


FIGURE 7: (a) Expected probability of buying for node 30 under θ_{poc} and without control $\theta_{0,0}$ and (b) expected probability of refusing for node 30 under θ_{poc} and without control $\theta_{0,0}$.

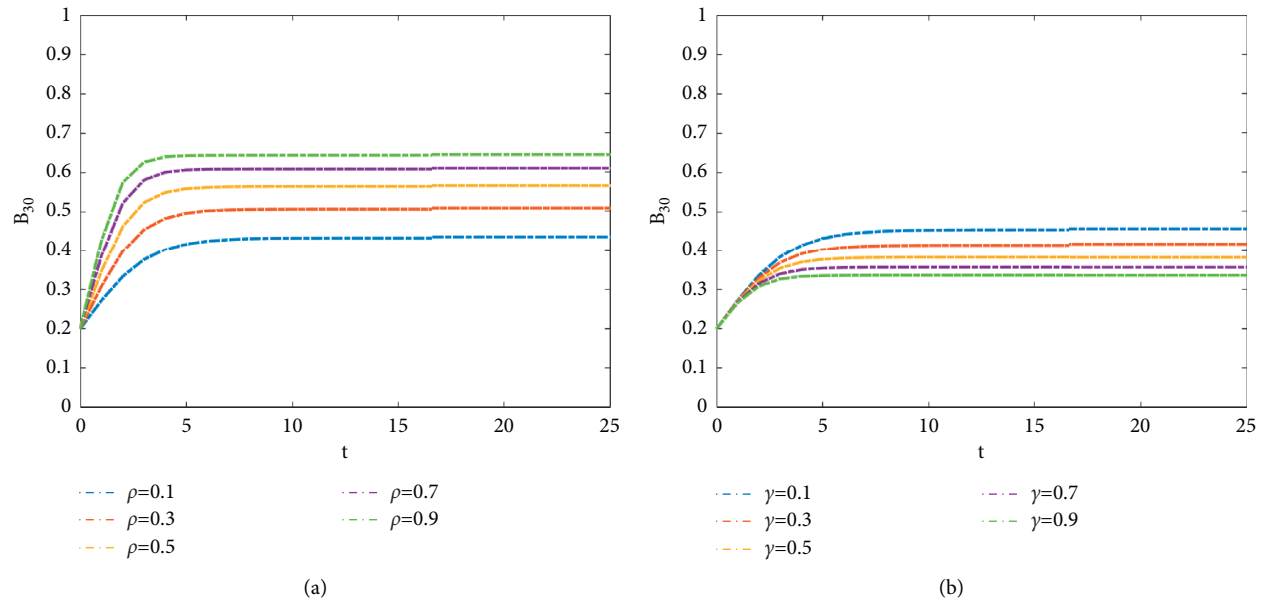


FIGURE 8: Continued.

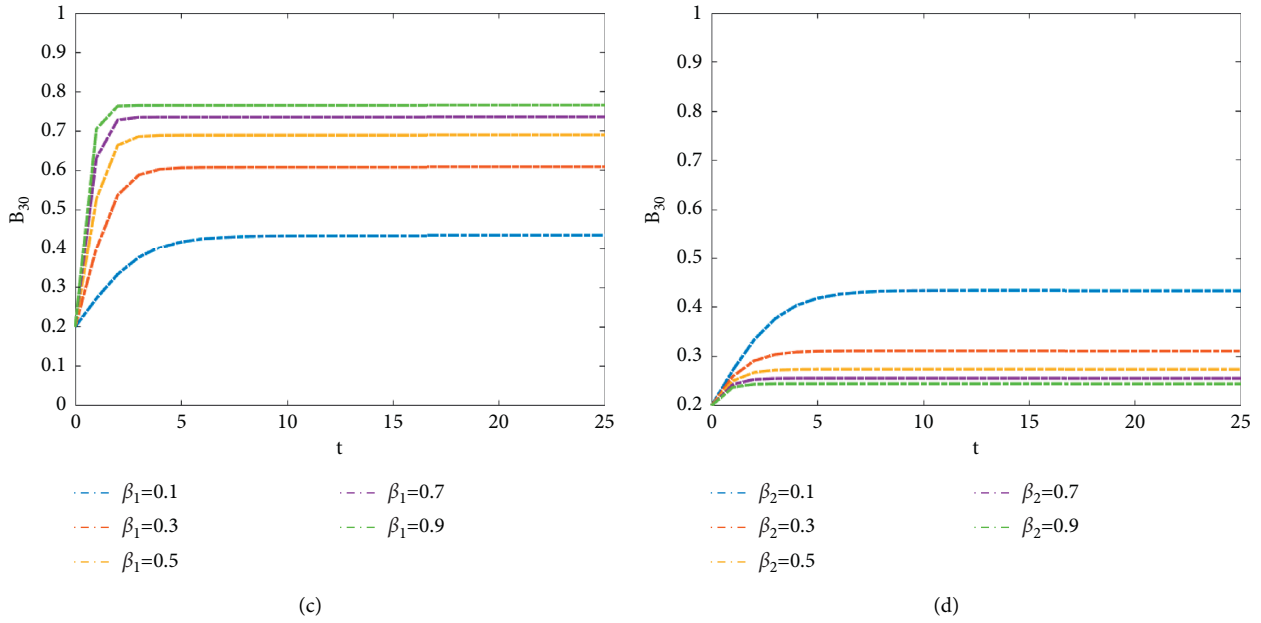


FIGURE 8: Parameters on the expected probability of buying for node 30: (a) ρ , (b) γ , (c) β_1 , and (d) β_2 .

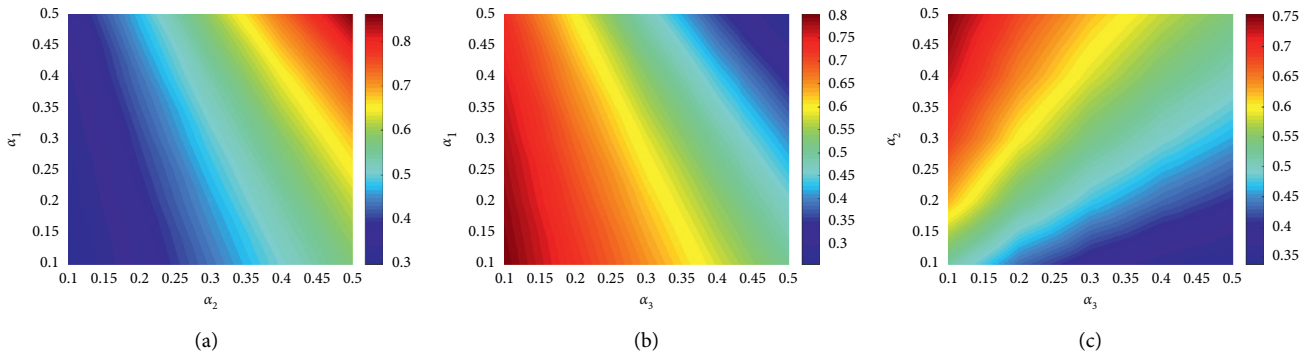


FIGURE 9: Parameters on the expected probability of buying for node 30: (a) α_1, α_2 , (b) α_1, α_3 , and (c) α_2, α_3 .

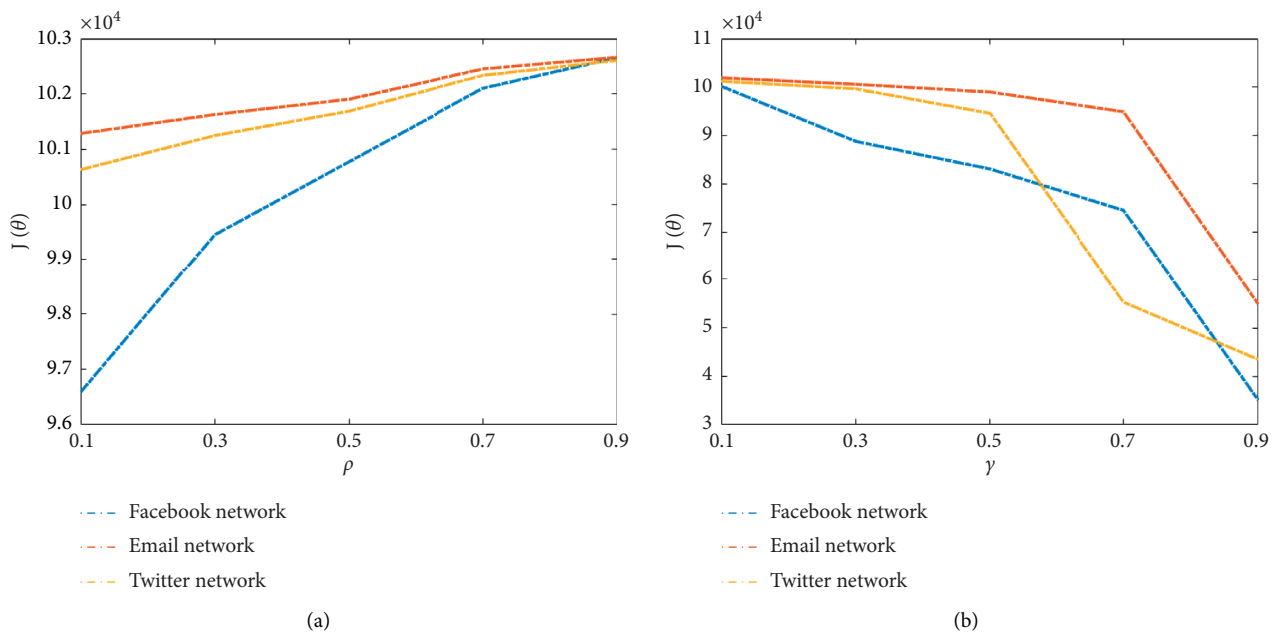


FIGURE 10: Continued.

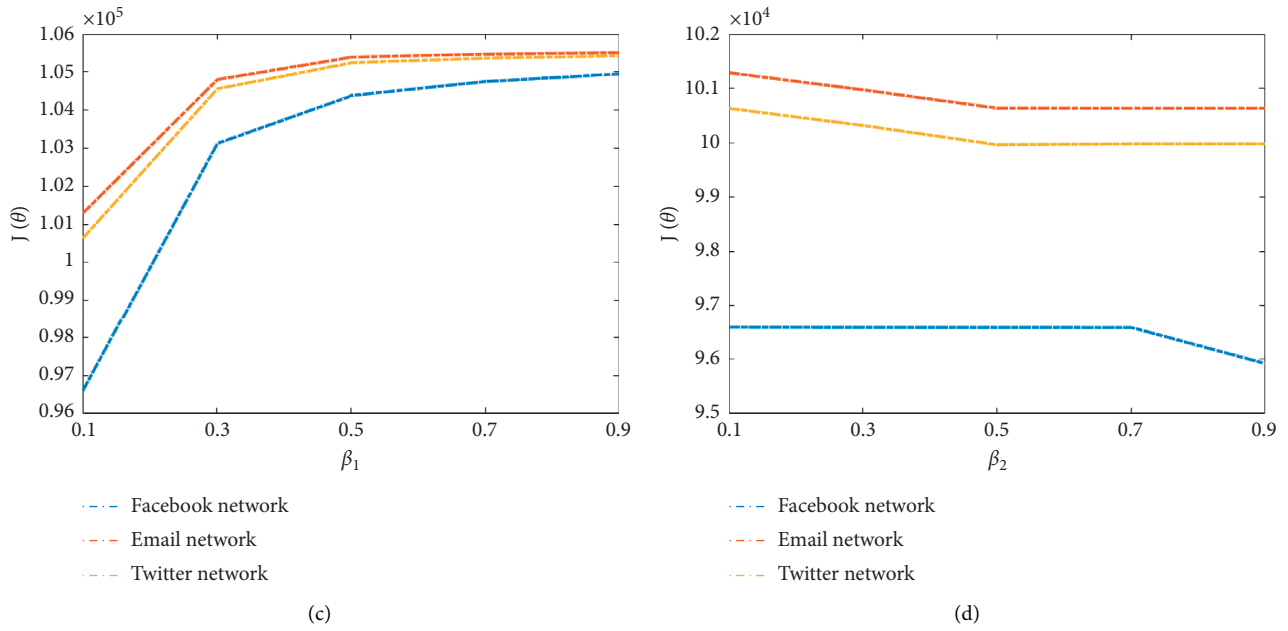


FIGURE 10: Parameters on the expected probability of buying for node 30: (a) ρ , (b) γ , (c) β_1 , and (d) β_2 .

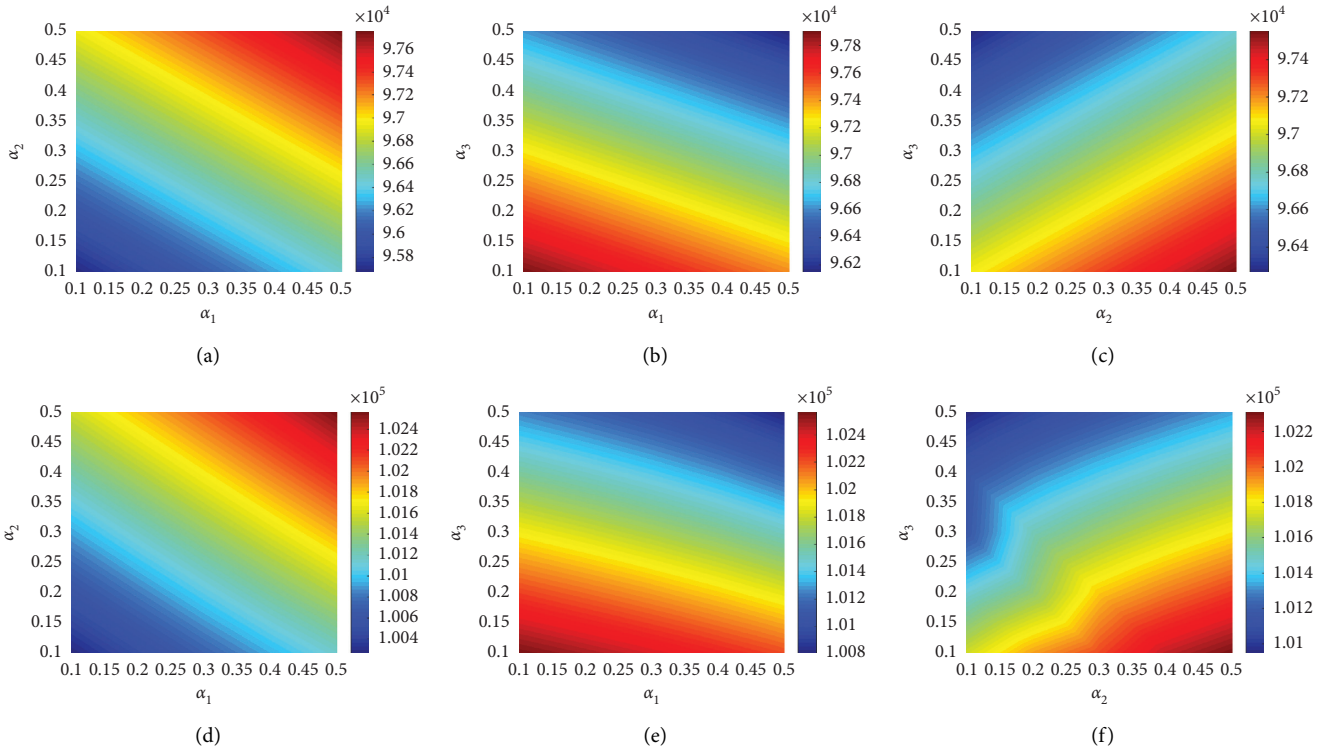


FIGURE 11: Continued.

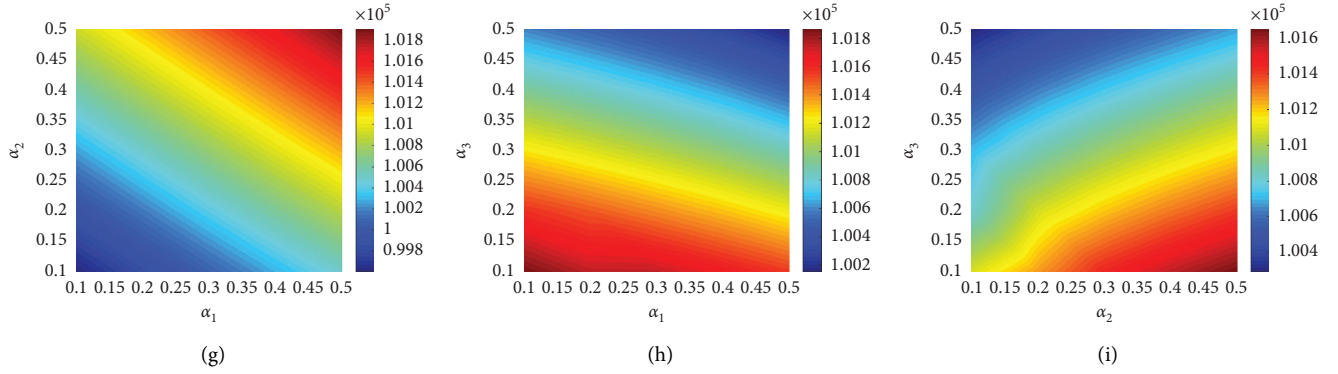


FIGURE 11: Parameters $\alpha_1, \alpha_2, \alpha_3$ on the expected profit. (a–c) $\alpha_1, \alpha_2, \alpha_3$ on Facebook network; (d–f) $\alpha_1, \alpha_2, \alpha_3$ on e-mail network; (g–i) $\alpha_1, \alpha_2, \alpha_3$ on Twitter network.

TABLE 4: Summary of experimental conclusion.

Number	Conclusion	Supporting experiments
C_1	The three states in the network will stabilize to a fixed constant over time	Experiment 1
C_2	The DAS optimal control strategy outperforms any uniform control strategy and can greatly improve the expected profit	Experiments 2 and 3
C_3	Reversing negative reviews is more helpful in improving expected profits than improve silent evaluation	Experiment 2
C_4	The probability ρ of T_i being converted to B_i is positively correlated with expected profits	Experiments 4 and 6
C_5	The probability γ of T_i being converted to R_i is negatively correlated with expected profits	Experiments 4 and 6
C_6	The probability of positive evaluation α_2 is positively correlated with expected profits	Experiments 5 and 7
C_7	The probability of negative evaluation α_3 is positively correlated with expected profits	Experiments 5 and 7
C_8	Probability β_1 influenced by positive WOM is positively correlated with expected profits	Experiments 4 and 6
C_9	Probability β_2 influenced by negative WOM is negatively correlated with expected profits	Experiments 4 and 6
C_{10}	When the probability α_2 (α_3) of positive (negative) WOM is fixed and small, the probability of silent evaluation α_1 has a weak positive (negative) correlation with purchase intention	Experiment 5
C_{11}	When the probability α_2 (α_3) of positive (negative) WOM is fixed and large, the probability of silent evaluation α_1 has a strong positive (negative) correlation with purchase intention	Experiment 5

As can be seen from Figure 11, the expected profit is not closely related to the proportion of silent customers, but is directly proportional to positive WOM and inversely proportional to negative WOM. This conclusion is consistent with the analysis in Figure 9.

The experimental conclusions are summarized in Table 4.

6. Conclusion

This paper aims at maximizing the expected profits of product sales in social network shopping by dynamically controlling the proportion of after-sales service investment based on word-of-mouth marketing. First, the problem is modeled as an optimal control problem. Second, a potential optimal control strategy is proposed and the optimal control problem is identified by solving the optimal system. Finally, some comparative experiments demonstrate that the proposed dynamic control strategy is superior to any uniform control strategy, and the expected profits show different levels of sensitivity to different after-sales service parameters. Therefore, the proposed dynamic after-sales investment strategy can serve as an effective approach to

maximizing the expected profits of product sales in social network shopping. In this regard, there are a number of research topics worthy of further study. The problem of balancing profits and after-sales investment can be modeled as a game theory problem to ensure maximum interests for individuals.

Data Availability

The data used to support the findings of this study are included within the article.

Conflicts of Interest

The authors declare no potential conflicts of interest.

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