Set of Oscillation Criteria for Second Order Nonlinear Forced Differential Equations with Damping

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By employing a generalized Riccati technique and an integral averaging technique, some new oscillation criteria are established for the second order nonlinear forced differential equation with damping. These results extend, improve, and unify some known oscillation criteria in the existing literature.

1. Introduction

The oscillatory problem for second order nonlinear forced differential equation with damping

\[
\left( r(t) \psi(x(t)) f \left( x'(t) \right) \right)' + h(t) f \left( x'(t) \right) + q(t) \Phi \left( x'(t) \right) = H(t, x(t), x'(t)), \quad t \geq t_0, \tag{1}
\]

is concerned, where \( r, h, q \in C([t_0, \infty), \mathbb{R}) \) and \( f, \psi, g, \Phi \in C(\mathbb{R}, \mathbb{R}) \) and \( H \) is a continuous function on \([t_0, \infty) \times \mathbb{R}^2\).

Throughout this paper we will also suppose that there are positive constants \( k_1, k_2, k_3, k_4, k_5, l \), and \( k \) satisfying the following:

\begin{align*}
(A_1) & \; r(t) > 0, t \geq 0, \\
(A_2) & \; 0 < k_1 \leq \psi(x(t)) \leq k_2 \text{ for all } x, \\
(A_3) & \; l > 0 \text{ and } f^2(y) \leq lyf(y) \text{ for all } y \in \mathbb{R}, \\
(A_4) & \; q(t) \geq 0 \text{ and } 0 < k_3 \leq \Phi(x'(t)), \\
(A_5) & \; x \cdot g(x) > 0 \text{ and } 0 < k \leq g'(x) \text{ for all } x \neq 0, \\
(A_6) & \; p : [t_0, \infty) \rightarrow \mathbb{R} \text{ is continuous function such that } H(t, x, y)/g(x) \leq p(t) \forall t \in [t_0, \infty); \; x, y \in \mathbb{R} \text{ and } x \neq 0, \\
(A_7) & \; 0 < k_4 \leq (f(y)/y) \leq k_5 \text{ for all } y \neq 0.
\end{align*}

We will consider only nontrivial solutions of (1) which are defined for all large \( t \). A solution of (1) is said to be oscillatory if it has a sequence of zeros clustering at \( \infty \) and nonoscillatory otherwise. Equation (1) is said to be oscillatory if all its solutions are oscillatory.

In the late 19th century, some scholars focus on sufficient conditions for the oscillation theorems of different classes of differential equations with damping. We refer to the new published papers [1–11]. The oscillatory theory of second order nonlinear differential equations has been widely applied in research of lossless high-speed computer network and physical sciences.

Recently, the oscillatory behavior for various particular cases of (1), such as the nonlinear differential equations

\[
\left( r(t) x'(t) \right)' + h(t) x'(t) + q(t) g(x(t)) \Phi \left( x'(t) \right) = 0, \\
\left( r(t) \psi(x(t)) f \left( x'(t) \right) \right)' + h(t) f \left( x'(t) \right) + q(t) g(x(t)) \Phi \left( x'(t) \right) = 0, \\
\left( r(t) \psi(x(t)) f \left( x'(t) \right) \right)' + h(t) f \left( x'(t) \right) + \varphi(t, x(t)) = H(t, x(t), x'(t)), \tag{2}
\]

has been studied extensively by numerous authors with different methods; see, for example, [9–11] and the references quoted therein.

In this paper, by using a generalized Riccati and integral averaging technique, several new oscillation criteria for (1) are established.

A significant drawback of many oscillation results for differential equations with damping reported in the literature is a necessity to impose a variety of additional restrictions on the sign of the damping term h(t). We emphasize that our theorems are free of particular restrictions on h(t).

2. Main Results

For convenience, we introduce the class of the function Ω. Let D = \{t, s : t_0 \leq s \leq t\}. A function H^* \in (D, \mathbb{R}) is said to belong to the class Ω, if

(1) H^*(t, t) = 0 for t \geq t_0 and H^*(t, s) > 0 for t > s \geq t_0,
(2) H^*(t, s) has continuous and nonpositive partial derivatives on D with respect to the second variable,
(3) there exists a function h_1(t, s) \in C(D, \mathbb{R}) such that

\[ -\partial H^*(t, s)/\partial s = h_1(t, s) \sqrt{H^*(t, s)}. \]

In this section, several oscillation conditions for (1) are established under the assumptions (A_1)–(A_3).

**Theorem 1.** Let assumptions (A_1)–(A_3) be fulfilled and H^* ∈ Ω. If there exist functions R \in C([t_0, \infty), \mathbb{R}^+) and \varphi \in C^1([t_0, \infty), \mathbb{R}) such that (rR) \in C^1([t_0, \infty), \mathbb{R}) and

\[
\lim_{t \to \infty} \sup_{t_0} 1 \int_{t_0}^{t} H^*(t, s) Q(s) - \frac{lk_2}{4k} \varphi(s) R(s) h_2^2(t, s) \, ds = \infty,
\]

where

\[
Q(t) = \varphi(t) \left\{ k_3 q(t) - p(t) + \frac{k}{lk_2} r(t) R(t) \right\} - \frac{1}{k_2} h(t) R(t) - \frac{1}{4k} \left( \frac{1}{k_2} - \frac{1}{k_3} \right) h^2(t) \frac{r(t)}{g(t)},
\]

\[
h_2(t, s) = h_1(t, s) - \sqrt{H^*(t, s)} \left( \frac{\varphi'(s)}{\varphi(s)} + 2 \frac{k}{lk_3} R(s) - \frac{h(s)}{k_2 r(s)} \right),
\]

then (1) is oscillatory.

**Proof.** Let x(t) be a nonoscillatory solution of (1). Then there exists a T_0 \geq t_0 such that x(t) \not\equiv 0 for all t \geq T_0. Without loss of generality, we may assume that x(t) \not\equiv 0 on interval [T_0, \infty). A similar argument holds also for the case when x(t) is eventually negative. Defining a generalized Riccati transformation by

\[
w'(t) = \varphi(t) r(t) \left[ \frac{\psi(x(t)) f(x'(t))}{g(x(t))} + R(t) \right],
\]

for all t \geq T_0, then differentiating Equation (5), and using (1) and (A_1)–(A_3), it follows

\[
w'(t) = \varphi(t) H(t, x(t), x'(t)) - \frac{\varphi(t) h(t) f(x'(t))}{g(x(t))}
- \varphi(t) q(t) \Phi(x'(t))
- \varphi(t) \frac{r(t) \psi(x(t)) f(x'(t)) g'(x(t)) x'(t)}{g^2(x(t))}
+ \varphi(t) (r(t) R(t))' + w(t) \frac{q'(t)}{\varphi(t)},
\]

\[
w'(t) \leq \frac{q'(t)}{\varphi(t)} w(t) - \frac{\varphi(t) h(t) f(x'(t))}{g(x(t))}
- \varphi(t) (k_3 q(t) - p(t))
- \frac{k}{4kr(t)} \frac{r(t) \psi(x(t)) f(x'(t)) g'(x(t)) x'(t)}{g^2(x(t))}
+ \varphi(t) (r(t) R(t))' + w(t) \frac{q'(t)}{\varphi(t)},
\]

\[
w'(t) \leq \varphi(t) (r(t) R(t))' - \varphi(t) (k_3 q(t) - p(t))
+ \varphi(t) (r(t) R(t))' = \varphi(t) (r(t) R(t))' - \varphi(t) (k_3 q(t) - p(t))
+ \frac{q'(t)}{\varphi(t)} w(t) + \frac{lq(t) h^2(t)}{4k r(t) \psi(x(t))} - \frac{\varphi(t)}{k_2}
\times \left[ \frac{kr(t) \psi(x(t)) f(x'(t))}{g(x(t))} + \frac{h(t)}{2} \sqrt{\frac{l}{kr(t)}} \right]^2
\]

\[
\leq \varphi(t) (r(t) R(t))' - \varphi(t) (k_3 q(t) - p(t))
+ \frac{q'(t)}{\varphi(t)} w(t) + \frac{lq(t) h^2(t)}{4k r(t) \psi(x(t))} - \frac{\varphi(t)}{k_2}
\times \left[ \frac{kr(t) \psi(x(t)) f(x'(t))}{g(x(t))} + \frac{h(t)}{2} \sqrt{\frac{l}{kr(t)}} \right]^2
\]

\[
= \varphi(t) (r(t) R(t))' - \varphi(t) (k_3 q(t) - p(t))
+ \frac{q'(t)}{\varphi(t)} w(t) + \frac{lq(t) h^2(t)}{4k r(t) \psi(x(t))} - \frac{\varphi(t)}{k_2}
\times \left[ \frac{kr(t) \psi(x(t)) f(x'(t))}{g(x(t))} + \frac{h(t)}{2} \sqrt{\frac{l}{kr(t)}} \right]^2
\]

\[
\leq \varphi(t) (r(t) R(t))' - \varphi(t) (k_3 q(t) - p(t))
+ \frac{q'(t)}{\varphi(t)} w(t) + \frac{lq(t) h^2(t)}{4k r(t) \psi(x(t))} - \frac{\varphi(t)}{k_2}
\times \left[ \frac{kr(t) \psi(x(t)) f(x'(t))}{g(x(t))} + \frac{h(t)}{2} \sqrt{\frac{l}{kr(t)}} \right]^2
\]

\[
= -Q(t) + \left( \frac{q'(t)}{\varphi(t)} + \frac{2k R(t)}{lk_2} - \frac{h(t)}{k_2 r(t)} \right) w(t)
- \frac{k}{lk_2 \varphi(t) r(t) w^2(t)},
\]

(6)
for all \( t \geq T_0 \) with \( Q(t) \) defined as above. Then we obtain

\[
Q(t) \leq -w'(t) + \left( \frac{q'(t)}{q(t)} + \frac{2kR(t)}{lk_2} - \frac{h(t)}{k_2r(t)} \right) w(t) + \frac{k}{lk_2\phi(t)r(t)} w^2(t) .
\] (7)

Multiplying both sides of (7) by \( H^*(t, s) \), integrating it with respect to \( s \) from \( T \) to \( t \), and using the properties of the function \( H^*(t, s) \), we get, for all \( t \geq T \geq T_0 \),

\[
\int_T^t H^*(t, s) Q(s) ds \\
\leq - \int_T^t H^*(t, s) w'(s) ds \\
+ \int_T^t H^*(t, s) \left( \frac{q'(s)}{q(s)} + \frac{2kR(s)}{lk_2} - \frac{h(s)}{k_2r(s)} \right) w(s) ds \\
- \int_T^t H^*(t, s) \frac{k}{lk_2\phi(s)r(s)} w^2(s) ds \\
= H^*(t, T) w(T) - \int_T^t w(s) h_1(t, s) \sqrt{H^*(t, s)} ds \\
+ \int_T^t H^*(t, s) \left( \frac{q'(s)}{q(s)} + \frac{2kR(s)}{lk_2} - \frac{h(s)}{k_2r(s)} \right) w(s) ds \\
- \int_T^t H^*(t, s) \frac{k}{lk_2\phi(s)r(s)} w^2(s) ds \\
= H^*(t, T) w(T) \\
- \int_T^t \left[ h_2(t, s) \sqrt{H^*(t, s)} w(s) + \frac{kH^*(t, s)}{lk_2\phi(s)r(s)} w^2(s) \right] ds.
\] (8)

Therefore, for all \( t \geq T \geq T_0 \),

\[
\int_T^t \left[ Q(s) H^*(t, s) - \frac{lk_2}{4k} \phi(s) r(s) h_2^2(t, s) \right] ds \\
\leq H^*(t, T) w(T) - \int_T^t \left[ \frac{kH^*(t, s)}{lk_2\phi(s)r(s)} w(s) \right] ds.
\]

Applying inequality (9), for \( T = T_0 \), yields

\[
\lim_{t \to \infty} \sup_{t \geq t_0} \frac{1}{H^*(t, t_0)} \\
\times \int_{t_0}^t \left[ Q(s) H^*(t, s) - \frac{lk_2}{4k} \phi(s) r(s) h_2^2(t, s) \right] ds \\
\leq \int_{t_0}^{T_0} |Q(s)| ds + H^*(t, t_0) |w(T_0)| < \infty.
\] (11)

It follows that

\[
\lim_{t \to \infty} \sup_{t \geq t_0} \frac{1}{H^*(t, t_0)} \times \int_{t_0}^t H^*(t, s) Q(s) ds = \infty, \quad t_0 > t_0 > 0
\]

which contradicts assumption (3), so (1) is oscillatory.

**Corollary 2.** If condition (3) is replaced by conditions

\[
\lim_{t \to \infty} \sup_{t \geq t_0} \frac{1}{H^*(t, t_0)} \int_{t_0}^t Q(s) ds = \infty,
\]

\[
\lim_{t \to \infty} \sup_{t \geq t_0} \frac{1}{H^*(t, t_0)} \int_{t_0}^t \phi(s) r(s) h_2^2(t, s) ds < \infty,
\]

then (1) is oscillatory, where \( Q(s) \) and \( h_2(t, s) \) are the same as defined in Theorem 1.
Example 3. Consider the nonlinear damped differential equation
\[
\left[ t^{-1} (2 - \sin x(t)) \left( \frac{x'(t)}{1 + (x'(t))^2} \right) \right]' + \cos t \frac{x'(t)}{1 + (x'(t))^2} + t^2 (1 - \cos t) x(t) \left( 1 + x^4(t) \right) \left( 1 + x'^2(t) \right) = x^5(t) \sin t \cos x'(t), \quad t \geq t_0 = 1,
\]
where \( x \in (-\infty, \infty) \) and \( t \geq t_0 = 1 \). Since \( k_1 = 1/2, k_2 = k_3 = 1 \), and \( l = 1 \) the assumptions (A1)–(A6) hold. If we take \( R(t) = 0 \) and \((H(t, x, x'))/(g(x(t))) \leq 1 = p(t)\), then \( \varphi(t) = t \) and \( H^*(t, s) = (t - s)^2 \). A direct computation yields that the conditions of Theorem 1 are satisfied; Example 3 is oscillatory.

Theorem 4. Let assumptions (A1)–(A6) be fulfilled and \( H^* \in \Omega \). Suppose that
\[
0 < \inf_{s \in \mathbb{R}_+} \left\{ \lim_{t \to \infty} \inf_{t_0} \frac{H^*(t, s)}{H^*(t, t_0)} \right\} \leq \infty. \tag{15}
\]
If there exist functions \( R, \chi \in C([t_0, \infty), \mathbb{R}) \) and \( \varphi \in C^1([t_0, \infty), \mathbb{R}^+ \) such that \((rR) \in C^1([t_0, \infty), \mathbb{R}) \) and
\[
\lim_{t \to \infty} \sup_{t_0} \frac{1}{H^*(t, t_0)} \int_{t_0}^t \varphi(s) r(s) h_2^2(t, s) ds < \infty, \tag{16}
\]
\[
\lim_{t \to \infty} \sup_{t_0} \frac{1}{H^*(t, t_0)} \int_{t_0}^t \frac{\chi^2(s)}{\varphi(s) r(s)} ds = \infty, \tag{17}
\]
and for any \( T \geq t_0 \)
\[
\lim_{t \to \infty} \sup_{t_0} \frac{1}{H^*(t, T)} \left\{ \int_{t_0}^t H^*(t, s) Q(s) - \frac{l k_2}{4 k} \varphi(s) r(s) h_2^2(t, s) ds \right\} \geq \chi(T), \tag{18}
\]
where \( Q(s) \) and \( h_2(t, s) \) are the same as defined in Theorem 1, and
\[
\chi_0(s) = \max\{\chi(s), 0\}, \tag{19}
\]
then (1) is oscillatory.

Proof. Let \( x(t) \) be a nonoscillatory solution of (1). Then there exists a \( T_0 \geq t_0 \) such that \( x(t) \neq 0 \) for all \( t \geq T_0 \). Without loss of generality, we may assume that \( x(t) > 0 \) on interval \([T_0, \infty)\). A similar argument holds also for the case when \( x(t) \) is eventually negative.

Define the function \( w(t) \) as in (5). Similar to the proof of Theorem 1, we obtain inequality (9). Further, it follows
\[
\frac{1}{H^*(t, T)} \int_{T}^{t} \left[ Q(s) H^*(t, s) - \frac{l k_2}{4 k} \varphi(s) r(s) h_2^2(t, s) \right] ds \leq w(T) - \frac{1}{H^*(t, T)} \times \int_{T}^{t} \left[ \frac{k H^*(t, s)}{4 k} \varphi(s) r(s) + \frac{1}{2} \frac{l k_2 \varphi(s) r(s)}{k} h_2^2(t, s) \right] ds, \tag{20}
\]
for \( t > T \geq T_0 \) and therefore
\[
\lim_{t \to \infty} \sup_{t_0} \frac{1}{H^*(t, T)} \times \int_{T}^{t} \left[ Q(s) H^*(t, s) - \frac{l k_2}{4 k} \varphi(s) r(s) h_2^2(t, s) \right] ds \leq w(T) - \frac{1}{H^*(t, T)} \times \int_{T}^{t} \left[ \frac{k H^*(t, s)}{4 k} \varphi(s) r(s) + \frac{1}{2} \frac{l k_2 \varphi(s) r(s)}{k} h_2^2(t, s) \right] ds. \tag{21}
\]
Thus, by (18), we get
\[
w(T) \geq \chi(T) + \lim_{t \to \infty} \inf_{t_0} \frac{1}{H^*(t, T)} \times \int_{T}^{t} \left[ \frac{k H^*(t, s)}{4 k} \varphi(s) r(s) + \frac{1}{2} \frac{l k_2 \varphi(s) r(s)}{k} h_2^2(t, s) \right] ds, \tag{22}
\]
for all \( t > T \geq T_0 \). This implies that
\[
w(T) \geq \chi(T), \quad \forall T \geq T_0,
\]
\[
\lim_{t \to \infty} \inf_{t_0} \frac{1}{H^*(t, T_0)} \times \int_{T_0}^{t} \left[ \frac{k H^*(t, s)}{4 k} \varphi(s) r(s) + \frac{1}{2} \frac{l k_2 \varphi(s) r(s)}{k} h_2^2(t, s) \right] ds \leq w(T_0) - \chi(T_0) < \infty. \tag{23}
\]
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Define

\[
\alpha(t) = \frac{1}{H^*(t, T_0)} \int_{T_0}^{t} kH^* (t, s) \frac{\omega^2 (s)}{l k_2 \varphi (s) r (s)} ds,
\]

\[
\beta(t) = \frac{1}{H^*(t, T_0)} \int_{T_0}^{t} h_2 (t, s) \sqrt{H^*(t, s)} w (s) ds,
\]

for all \( t > T_0 \). Then

\[
\lim_{t \to \infty} \inf \left[ \alpha(t) + \beta(t) \right] \leq \lim_{t \to \infty} \inf \frac{1}{H^*(t, T_0)} \int_{T_0}^{t} \frac{kH^* (t, s)}{l k_2 \varphi (s) r (s)} \frac{\omega^2 (s)}{H^*(s, s)} ds \times \left[ \sqrt{\frac{kH^* (t, s)}{l k_2 \varphi (s) r (s)}} w (s) \right] ds < \infty.
\]

(24)

In order to show that

\[
\int_{T_0}^{\infty} \frac{\omega^2 (s)}{\varphi (s) r (s)} ds < \infty,
\]

(25)

suppose that

\[
\int_{T_0}^{\infty} \frac{\omega^2 (s)}{\varphi (s) r (s)} ds = \infty.
\]

(26)

By (15), there exists a positive constant \( \lambda \) such that

\[
\inf_{t \geq t_0} \left\{ \lim_{t \to \infty} \frac{H^* (t, s)}{H^* (t, t_0)} \right\} > \lambda > 0.
\]

(27)

On the other hand, according to (27) for any positive constant \( \gamma \) there exists a \( T_1 > T_0 \) such that

\[
\int_{T_0}^{t} \frac{\omega^2 (s)}{\varphi (s) r (s)} ds \geq \frac{\gamma}{\lambda} \forall t \geq T_1.
\]

(28)

For \( t \geq T_1 \),

\[
\alpha(t) = \frac{1}{H^*(t, T_0)} \int_{T_0}^{t} kH^* (t, s) \frac{\omega^2 (s)}{l k_2 \varphi (s) r (s)} ds
\]

\[
= \frac{k}{l k_2 H^* (t, T_0)} \int_{T_0}^{t} H^* (t, s) d \left[ \int_{T_0}^{s} \frac{\omega^2 (u)}{\varphi (u) r (u)} du \right]_{T_0}^{t}
\]

\[
- \left[ \int_{T_0}^{t} \left( \int_{T_0}^{s} \frac{\omega^2 (u)}{\varphi (u) r (u)} du \right) \frac{\partial H^* (t, s)}{\partial s} ds \right]
\]

\[
= \int_{T_0}^{t} \left( \int_{T_0}^{s} \frac{\omega^2 (u)}{\varphi (u) r (u)} du \right) \frac{\partial H^* (t, s)}{\partial s} ds
\]

\[
\geq \frac{k}{\lambda l k_2 H^* (t, T_0)} \int_{T_0}^{t} \left( \int_{T_0}^{s} \frac{\omega^2 (u)}{\varphi (u) r (u)} du \right) \frac{\partial H^* (t, s)}{\partial s} ds
\]

(29)

By (28) we can easily see that

\[
\lim_{t \to \infty} \inf \frac{H^* (t, T_1)}{H^* (t, t_0)} > \lambda > 0.
\]

(30)

Then there exists \( T_2 \geq T_1 \) such that \( (H^* (t, T_1)/H^* (t, t_0)) \geq \lambda \) for all \( t \geq T_2 \). Therefore, by (30), \( \alpha(t) \geq \frac{\gamma k}{l k_2} \) for all \( t \geq T_2 \), and since \( \gamma \) is an arbitrary constant, we can make a conclusion that

\[
\lim_{t \to \infty} \alpha(t) = \infty.
\]

(31)

Next, let us consider a sequence \{\( t_n = n \)\} in \( (T_0, \infty) \) with \( \lim_{n \to \infty} t_n = \infty \) and such that

\[
\lim_{n \to \infty} \left( \alpha(t_n) + \beta(t_n) \right) = \lim_{t \to \infty} \inf \left\{ \alpha(t) + \beta(t) \right\}.
\]

(32)

Now, by (25), there exists a constant \( N \) such that

\[
\alpha(T_n) + \beta(T_n) \leq N \quad (n = 1, 2, \ldots),
\]

(33)

hence (32) leads to

\[
\lim_{n \to \infty} \beta(t_n) = -\infty.
\]

(34)

By taking into account (32), from (34), we derive

\[
1 + \frac{\beta(t_n)}{\alpha(t_n)} \leq \frac{N}{\alpha(t_n)} < \epsilon \quad \text{for } n \text{ large enough},
\]

(35)

where \( \epsilon \in (0, 1) \). Thus

\[
\frac{\beta(t_n)}{\alpha(t_n)} < \epsilon - 1 < 0.
\]

(36)
The above inequality and (35) imply that
\[
\beta^2(t_n) \frac{\alpha(t_n)}{\alpha(t_n)} > (\varepsilon - 1) \beta(t_n),
\]
and for every \( T \geq t_0 \)
\[
\lim_{t \to \infty} \inf \frac{1}{H^* (t, T)} \int_t^t H^* (t, s) Q(s) ds \geq \chi (T),
\]
where \( Q(t) \) and \( h_2(t, s) \) are defined as in Theorem 1, \( \chi (s) = \max \{ \chi (s), 0 \} \), then (1) is oscillatory.

Proof. Without loss of generality, we assume that there exists a solution \( x(t) \) of (1) such that \( x(t) > 0 \) on \([T_0, \infty)\) for some \( T_0 \geq t_0 \). The function \( w(t) \) is defined as in (5). Then, following the proof of Theorem 4, we have (20). Now it follows that
\[
\lim_{t \to \infty} \inf \frac{1}{H^* (t, T)} \times \int_T^T \left( H^* (t, s) Q(s) - \frac{I_k}{4k} \varphi(s) r(s) h_2^2 (t, s) \right) ds \geq \chi (T),
\]
for every \( T \geq T_0 \). By (45), we know that (23) holds and
\[
\lim_{t \to \infty} \sup \frac{1}{H^* (t, T)} \times \int_T^T \left( \frac{kH^* (t, s)}{l_k \varphi(s) r(s)} w(s) + \frac{1}{2} \frac{l_k \varphi(s) r(s)}{k} h_2 (t, s) \right)^2 ds,
\]
\[
\leq w (T) - \chi (T_0) < \infty.
\]
Then,
\[
\lim_{t \to \infty} \sup \left[ \alpha (t) + \beta (t) \right]
\]
\[
\leq \lim_{t \to \infty} \sup \frac{1}{H^* (t, T_0)}
\]
\[
\times \int_T^T \left( \frac{kH^* (t, s)}{l_k \varphi(s) r(s)} w(s) + \frac{1}{2} \frac{l_k \varphi(s) r(s)}{k} h_2 (t, s) \right)^2 ds < \infty,
\]
where \( \alpha (t) \) and \( \beta (t) \) are defined as in the proof of Theorem 4.

It follows from (44) and (45) that
\[
\lim_{t \to \infty} \inf \frac{1}{H^* (t, t_0)} \int_t^t H^* (t, s) Q(s) ds < \infty,
\]
and
\[
\lim_{t \to \infty} \sup \frac{1}{H^* (t, t_0)} \int_t^t r(s) \varphi(s) h_2^2 (t, s) ds = \infty.
\]
Then there exists a sequence \( \{ t_n \}_{n=1}^\infty \) in \((T_0, \infty)\) such that
\[
\lim_{t \to \infty} H^\ast (t_n, t_0) \int_{t_0}^{t_n} \varphi(s) r(s) h^2_s(t_n, s) \, ds
= \lim_{t \to \infty} \inf_{t \to \infty} \frac{1}{H^\ast (t, t_0)} \int_{t_0}^{t} \varphi(s) r(s) h^2_s(t, s) \, ds < \infty.
\] (50)

Now, suppose that (27) holds. With the same argument as in Theorem 4, we conclude that (32) is satisfied. By (48), there exists a constant \( N_1 \) such that
\[
\alpha(t_n) + \beta(t_n) \leq N_1 \quad \forall n > N_1.
\] (51)

Then, similar to the proof of Theorem 4, we obtain (41) which contradicts (50), and hence (27) fails. From (23) and (26) we have
\[
\int_{T_0}^\infty \mu^2(s) r(s) \varphi(s) ds \leq \int_{T_0}^\infty \nu^2(s) r(s) \varphi(s) ds < \infty,
\] (52)
which contradicts assumption (17).

**Theorem 6.** Let assumptions \((A_1)-(A_6)\) be fulfilled and \( H^\ast \in \Omega \). Suppose there exist functions \( R, \chi \in C([t_0, \infty), \mathbb{R}) \) and \( \varphi \in C^1([t_0, \infty), \mathbb{R}^+) \), such that \( (rR) \in C^1([t_0, \infty), \mathbb{R}) \), and (17) and (45) hold, and
\[
\lim_{t \to \infty} \inf_{t \to \infty} \frac{1}{H^\ast (t, t_0)} \int_{t_0}^{t} \varphi(s) r(s) h^2_s(t, s) \, ds < \infty,
\] (53)
where \( Q(t) \) and \( h^2_s(t, s) \) are defined as in Theorem 1 and \( \chi_s(s) = \max \{ \chi(s), 0 \} \), then (1) is oscillatory.

The proof of Theorem 6 is similar to the proof of Theorem 5.

**Example 7.** Consider the nonlinear damped differential equation
\[
\left[ \frac{2 + \cos t}{1 + \cos^2 t} \right] \left( \frac{1 + x^2(t)}{2 + x^2(t)} \right) \left( \frac{x'(t)}{1 + \alpha(x'(t))^2} \right) \left( \frac{x'(t)}{1 + \alpha(x'(t))^2} \right)
+ 2 \sin t |\cos t| \frac{x'(t)}{1 + \alpha x^2(t)}
+ \frac{9(1 + \cos^2 t)}{10 + \cos^2 t} x^3(t) \left( 1 + x^2(t) \right) \left( 1 + x^2(t) \right)
= 2x^7(t) \sin t \cos x'(t) \frac{t}{t^2}
\] (54)

Obviously, for all \( x \in (-\infty, \infty) \) and \( t \geq t_0 = 1, \alpha \geq 0 \) is a constant. Since \( k_1 = 1/2, k_2 = k_3 = 1, \) and \( l = 1, \) the assumptions \((A_1)-(A_6)\) hold. If \( R(t) = 0 \) and \( H(t, x, x')/(g(x(t))) \leq 2/t^2 = \rho(t) \), then \( \rho(t) = t^{-2} \) and \( H(t,s) = (t-s)^2 \), for all \( t \geq 1. \)

A direct computation yields
\[
\lim_{t \to \infty} \inf_{t \to \infty} \frac{1}{H(t, t_0)} \int_{t_0}^{t} \left( H(t, s) Q(s) - \frac{h^2_s}{4k^2} \varphi(s) r(s) h^2_s(t, s) \right) \, ds
= \lim_{t \to \infty} \frac{1}{t^2} \int_{t}^{t} \left( (t-s)^2 s^{-2} \right.
\times \left. \left( \frac{1 + \cos^2 s}{10 + \cos^2 s} \right) \sin^2 s \frac{\cos \left( 1 + \cos^2 s \right)}{2 + \cos^2 s} \right)
\times \left. \left( \frac{2 \sin s |\cos s| \left( 1 + \cos^2 s \right)}{2 + \cos^2 s} \right) + \frac{2}{s} \right)
\times \left. \left( \frac{t-s}{5s} \right) - \frac{2}{s^2} \left( \frac{t-s}{5s} \right) \right)^2 \right) \, ds
\]
\[
= \frac{2}{3T^3} + \frac{\sqrt{6}}{2T^2} + \frac{71}{100T}
\]

\[
\lim_{t \to \infty} \inf_{t \to \infty} \frac{1}{H(t, t_0)} \int_{t_0}^{t} \varphi(s) r(s) h^2_s(t, s) \, ds
= \lim_{t \to \infty} \frac{1}{t^2} \int_{1}^{t} \left( \frac{s^2 + 2 + \cos^2 s}{1 + \cos^2 s} \right)
\times \left. \left( \frac{2 \sin s |\cos s| \left( 1 + \cos^2 s \right)}{2 + \cos^2 s} \right) + \frac{2}{s} \right)
\times \left. \left( \frac{t-s}{5s} \right) - \frac{2}{s^2} \left( \frac{t-s}{5s} \right) \right)^2 \right) \, ds
\]
\[
\leq \lim_{t \to \infty} \inf_{t \to \infty} \frac{1}{t^2} \int_{1}^{t} \left( \frac{s^2 + 2}{2} \left[ 1 + \left( \frac{2}{3} + \frac{1}{s} \right) \right] \right) \, ds
\]
\[
= \infty.
\] (55)

We conclude by Theorem 6 that all solutions of this equation are oscillatory.
Remark 8. If (5) is replaced by
\[ w(t) = \varphi(t) \left[ \frac{r(t) \psi(x(t)) f(x'(t))}{x(t)} + r(t) R(t) \right], \]
and (A_2) by \((g(x)/x) \geq k > 0\) for \(x \neq 0\), we can obtain similar oscillation results that are derived in the present paper.

Remark 9. If we take \(\Phi(x'(t)) = 1\), \(H(t, x, x') = 0\), it is easy to see that Theorems 1–6 reduce to Theorems 1–4 of Wang [8]. If we take \(\Phi(x'(t)) = 1\), \(\psi(x(t)) = 1\), and \(H(t, x'(t), x(t)) = 0\) for \(x, y \in \mathbb{R}\), then (1) reduces to (r(t)x'(t))' + h(t)x'(t) + q(t)g(x(t)) = 0, and by taking \(\varphi(t) = \exp(-2k \int_{t_0}^t R(s)ds)\), Theorems 1–5 reduce to Theorems 1–3 of Rogovchenko and Tuncay [6].

Remark 10. Theorems 1–6 and Corollary 2 are obtained by analogy with Theorems 1–4 from [9], and we do not require any restriction on the sign and differentiability of \(h(t)\).

The following lemma will significantly simplify the proofs of next theorems. First recall class functions defined on \(D = \{t, s\} : t_0 \leq s \leq t\). A function \(H \in \mathbb{D}(D, \mathbb{R})\) is said to belong to the class \(\mathcal{C}\) if

\( H(t, t) = 0 \) for \( t \geq t_0 \) and \( H(t, s) > 0 \) when \( t \neq s \),
\( H(t, s) \) has partial derivatives on \( D \) such that
\[ \frac{\partial H(t, s)}{\partial s} = -h_1(t, s) \sqrt{H(t, s)}, \]
\[ \frac{\partial H(t, s)}{\partial t} = h_2(t, s) \sqrt{H(t, s)}, \]
for some \(h_1, h_2 \in L_{\text{loc}}^1(D, \mathbb{R})\).

**Lemma 11.** Let \(B_1, B_2, B_3 \in C([t_0, \infty), \mathbb{R})\) with \(B_3 > 0\), \(Z \in C^1([t_0, \infty), \mathbb{R})\). If there exist \((a, b) \subset [t_0, \infty)\) and \(c \in (a, b)\) such that
\[ Z' \leq -B_1(s) + B_2(s)Z - B_3(s)Z^2, \quad s \in (a, b), \] \[ \text{then} \]
\[ \frac{1}{H(c, a)} \int_a^c \left[ B_1(s) - \frac{1}{4B_3(s)} \theta_1^2(s, a) \right] ds \]
\[ + \frac{1}{H(b, c)} \int_c^b \left[ B_2(s) - \frac{1}{4B_3(s)} \theta_2^2(b, s) \right] ds \leq 0, \] \[ \text{for all} \ H \in \mathcal{C}, \]
\[ \theta_1(s, a) = \left[ h_1(s, a) + B_2(s) \sqrt{H(s, a)} \right], \]
\[ \theta_2(b, s) = \left[ h_2(b, s) - B_3(s) \sqrt{H(b, s)} \right]. \]

The proof of this lemma is similar to that of [4] and hence will be omitted.

In the next theorems we define the following functions that will be used in the proofs. Let
\[ \beta(t) = k_1k_2\varphi(t)r(t) - k_1\varphi(t)h(t), \]
\[ \delta(t) = \frac{1}{\varphi(t)r(t)\psi(x(t))}, \]
\[ \gamma(t, T) = \delta(t) \left( \int_T^t \delta(s) ds \right)^{-1}. \]

**Theorem 12.** Suppose that \((A_1)-(A_7)\) hold. Assume that
\[ \int_{t_0}^\infty g(u) du < \infty, \quad \int_{t_0}^\infty \sqrt{g(u)} du < \infty, \]
\[ \min \left\{ \inf_{u \neq 0} \int_u^\infty \sqrt{g'(u)} du, \right\} > 0, \]
\[ \beta(t) \geq 0, \quad \beta'(t) \leq 0, \quad t \geq t_0, \]
\[ \int_{t_0}^\infty \delta(s) ds = 0. \]

If there exists a continuously differentiable function \(\phi : [t_0, \infty) \to (0, \infty)\) such that \(\phi't\) is nonnegative and decreasing function, we have
\[ \lim_{t \to \infty} \int_{t_0}^t \phi(s) \left( k_2q(s) - p(s) \right) ds > -\infty. \]

There exists an interval \((a, b) \subset [T, \infty), \) and that there exists \(c \in (a, b), \) \(H \in \mathcal{C}, \) and for any constant \(F > 0, \) such that
\[ \frac{1}{H(c, a)} \int_a^c \left[ H(s, a) \phi(s) (k_2q(s) - p(s)) - \frac{1}{4F} \gamma(s, t_0) \theta_1^2(s, a) \right] ds \]
\[ + \frac{1}{H(b, c)} \int_c^b \left[ H(b, s) \phi(s) (k_2q(s) - p(s)) - \frac{1}{4F} \gamma(s, t_0) \theta_2^2(b, s) \right] ds > 0, \] \[ \text{where} \]
\[ \theta_1(s, a) = \left[ h_1(s, a) + \frac{1}{k_4} \delta(s) \beta(s) \sqrt{H(s, a)} \right], \]
\[ \theta_2(b, s) = \left[ h_2(b, s) - \frac{1}{k_4} \delta(s) \beta(s) \sqrt{H(b, s)} \right]. \]

Then (1) is oscillatory.
Proof. Without loss of generality, we may assume that there exists a nonoscillatory solution $x(t) > 0$ on $[T, \infty)$ for some $0 \leq t_0 \leq T$. The similar argument holds also for $x(t) < 0$. Define the function $w(t)$ as

$$w(t) = \frac{\phi(t) \cdot r(t) \cdot \psi(x(t)) \cdot f(x'(t))}{g(x(t))}. \quad (70)$$

Differentiating (70), using (1) and (A1)–(A7), we get

$$w'(t) \leq -\phi(t) (k_3 q(t) - p(t)) - \frac{k_4 \phi(t) \cdot h(t) \cdot x'(t)}{g(x(t))} \cdot x'(t) \cdot g'(x(t))$$

$$- \frac{l}{\phi(t) \cdot r(t) \cdot \psi(x(t))} \cdot w^2(t) \cdot g'(x(t)) \cdot x'(t)$$

$$- \phi(t) (k_3 q(t) - p(t)) + \beta(t) \cdot \frac{x'(t)}{g(x(t))} \cdot g'(x(t))$$

$$- \delta(t) \cdot w^2(t) \cdot g'(x(t)). \quad (71)$$

Integrating (71) from $t_0$ to $t$ we get that

$$w(t) \leq w(t_0) - \int_{t_0}^{t} \phi(s) \cdot (k_3 q(s) - p(s)) \cdot ds$$

$$+ \int_{t_0}^{t} \beta(s) \cdot \frac{x'(s)}{g(x(s))} \cdot ds - \int_{t_0}^{t} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds. \quad (72)$$

Since $\beta(s) \leq 0$, then by Bonnet’s Theorem, there exist $b_h \in [t_0, \infty)$ for every $t \geq t_0$ such that

$$\int_{t_0}^{t} \beta(s) \cdot \frac{x'(s)}{g(x(s))} \cdot ds = \beta(t_0) \int_{t_0}^{b_h} \frac{x'(s)}{g(x(s))} \cdot ds \leq \beta(t_0) \int_{x(t_0)}^{\infty} \frac{du}{g(u)} = k_6,$$ \quad (73)

where $k_6 > 0$ is a constant. Then, we have, for $t \geq t_0$,

$$w(t) \leq F - \int_{t_0}^{t} \phi(s) \cdot (k_3 q(s) - p(s)) \cdot ds$$

$$- \int_{t_0}^{t} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds, \quad (74)$$

where $F = w(t_0) + k_6$.

Three cases of the oscillatory solutions are discussed below.

**Case 1.** Assume that $x'(t)$ is oscillatory; then there exists a sequence $\{t_n\}_{n=1,2,\ldots}$ such that

$$\lim_{n \to \infty} t_n = \infty$$

and $x(t_n) = 0$, $n = 1, 2, \ldots$ on $[t_0, \infty)$. From (74) we get

$$\int_{t_n}^{t_0} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds \leq F - \int_{t_n}^{t_0} \phi(s) \cdot (k_3 q(s) - p(s)) \cdot ds, \quad n = 1, 2, \ldots. \quad (75)$$

Using (67) we obtain

$$\int_{t_0}^{t_n} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds < \infty. \quad (76)$$

Then there exists a constant $A > 0$, such that

$$\int_{t_0}^{t_n} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds \leq A, \quad t \geq t_0. \quad (77)$$

Using Schwarz inequality, (A7), and (77) we have

$$\left| \int_{x(t_0)}^{\infty} \frac{x'(s)}{g(x(s))} \cdot \sqrt{g'(x(s))} \cdot ds \right|^2 \leq \frac{1}{k_4} \int_{x(t_0)}^{\infty} \delta(s) \cdot \left( \int_{t_0}^{\infty} \frac{\sqrt{g'(x(s))}}{g(x(s))} \cdot ds \right)^2 \leq \frac{1}{k_4} \left( \int_{t_0}^{\infty} \delta(s) \cdot ds \right) \left( \int_{t_0}^{\infty} \delta(s) \cdot w^2(s) \cdot g'(x(s)) \cdot ds \right) \leq \frac{A}{k_4} \int_{t_0}^{\infty} \delta(s) \cdot ds, \quad t \geq t_0. \quad (78)$$

Applying (64),

$$\int_{x(t_0)}^{\infty} \sqrt{g'(x(t))} \cdot \frac{\sqrt{g'(u)}}{g(u)} \cdot du \geq M, \quad t \geq t_0, \quad (79)$$

where $M$ is a positive constant.
Let \( M_1 = \int_{x(t_0)}^{\infty} \left( \sqrt{\frac{g'(u)}{g(u)}} \right) du > 0 \); applying (78) we have

\[
g'(x(t)) \geq M^2 \left[ M_1 - \int_{x(t)}^{\infty} \frac{g'(u)}{g(u)} du \right]^{-2} = M^2 \left[ \frac{x'(t)}{g(x(t))} \right]^{-2} \]

Using (78) in the above inequality leads to

\[
g'(x(t)) \geq M^2 \left[ M_1 + \left( \frac{A}{k_4} \int_{x(t_0)}^{t} \delta(s) ds \right)^{1/2} \right]^{-2}. \tag{80}\]

Then, there exist constants \( J > 0 \) and \( T > t_0 \), such that

\[
g'(x(t)) \geq J \left( \frac{A}{k_4} \int_{x(t_0)}^{t} \delta(s) ds \right)^{-1}, \quad t \geq T. \tag{82}\]

Substituting (82) in (71) we get

\[
w'(t) \leq -\phi(t) (k_3 q(t) - p(t)) + \frac{1}{k_4} \delta(t) \beta(t) w(t) - \int_{t_0}^{t} \phi(t) ds, \quad t \geq T. \tag{83}\]

From (83) and by Lemma 11, we conclude that for any \( c \in (a, b) \) and \( H \in \xi \)

\[
\frac{1}{H(c, a)} \int_{a}^{c} \left[ H(s, a) \phi(t) (k_3 q(t) - p(t)) - \frac{1}{4J} \theta(s, a) \right] ds + \frac{1}{H(b, c)} \int_{b}^{c} \left[ H(b, s) \phi(t) (k_3 q(t) - p(t)) - \frac{1}{J} \theta(b, s) \right] ds \leq 0,
\]

which contradicts condition (68).

Case 2. Assuming that \( x'(t) > 0 \) for \( t_0 \leq t_1 \leq t \), then \( w(t) > 0 \) for \( t \geq t_1 \), and by (74) we have

\[
\int_{t_1}^{t} \delta(s) w^2(s) g'(x(s)) ds \leq F - \int_{t_1}^{t} \phi(s) (k_3 q(s) - p(s)) ds, \quad t \geq t_1. \tag{85}\]

From (67) we see that

\[
\int_{t_1}^{\infty} \delta(s) w^2(s) g'(x(s)) ds < \infty. \tag{86}\]

The following steps are similar to the proof of Case 1.

Case 3. Assume that \( x'(t) < 0 \) for \( t_0 \leq t_1 \leq t \); if (86) holds, then we have similar discussion in Case 2. If the integration in (86) is divergent, we can get the following inequality from (74) and (67):

\[
F_1 + \int_{t_1}^{t} \delta(s) w^2(s) g'(x(s)) ds < 0, \quad t \geq t_1. \tag{87}\]

From (87) and (88) we have

\[
w(t) < 0, \tag{89}\]

and from (86) we find

\[
\frac{\delta(t) w^2(t) g'(x(t))}{F_1 + \int_{t_1}^{t} \delta(s) w^2(s) g'(x(s)) ds} \geq \frac{-x'(t) g(x(t))}{g(x(t))}, \quad t \geq t_2. \tag{90}\]

Integrating the above inequality, we obtain

\[
\ln \left[ F_1 + \int_{t_1}^{t} \delta(s) w^2(s) g'(x(s)) ds \right] \geq \ln \frac{g(x(t_2))}{g(x(t))}, \quad t \geq t_2. \tag{91}\]

Therefore

\[
F_1 + \int_{t_1}^{t} \delta(s) w^2(s) g'(x(s)) ds \geq g(x(t_2)) g(x(t)), \quad t \geq t_2. \tag{92}\]

Applying (87) and (92), we get

\[
x'(t) \leq -\frac{1}{k_4} \delta(t) g(x(t_2)) < 0. \tag{93}\]

Hence

\[
x(t) \leq x(t_2) - \frac{1}{k_4} g(x(t_2)) \int_{t_2}^{t} \delta(s) ds \rightarrow -\infty, \quad t \rightarrow \infty. \tag{94}\]

The above inequality contradicts \( x(t) > 0 \). This completes the proof.
**Theorem 13.** Suppose that $(A_1)$–$(A_7)$ and $(62)$–$(64)$ hold. Assume that there exists a function $\phi: [t_0, \infty) \to (0, \infty)$ such that $(65)$–$(68)$ and there exists $H \in \zeta$ such that

$$
\lim_{t \to \infty} \sup_{t_0 \leq t} \int_{t_0}^{t} \left[ H(s, a_0)(k_3 q(s) - p(s)) \right] ds > 0,
$$

and

$$
\lim_{t \to \infty} \sup_{t_0 \leq t} \int_{t_0}^{t} \left[ H(t, s)(k_3 q(s) - p(s)) \right] ds > 0
$$

hold for all $a_0 \in [t_2, \infty)$, where $\theta_1, \theta_2,$ and $J$ are the same as in Theorem 12. Then (1) is oscillatory.

**Proof.** Suppose that $x(t) \neq 0$ for all $t \in [t_2, \infty)$ for some $t_2 \geq t_1$. Set $a = t_2$ in (23). We can get $c > a$ such that

$$
\int_{a}^{c} \left[ H(s, a)(k_3 q(s) - p(s)) \right] ds > 0
$$

Similarly, with (96) by setting $a = c > t_2$, it follows that there exists $b > c$ such that

$$
\int_{c}^{b} \left[ H(b, s)(k_3 q(s) - p(s)) \right] ds > 0.
$$

Clearly, we can observe that (68) is satisfied. Then (1) is oscillatory.

**Example 14.** Consider the following second order nonlinear differential equation with damping:

$$
\left[ \frac{1}{1 + t^2} \right] \left[ x'(t) \frac{x'(t)}{1 + \left( x'(t) \right)^2} \right]^2
$$

$$
- \frac{1}{t} \left[ 3x'(t) \frac{\left( x'(t) \right)^2}{1 + \left( x'(t) \right)^2} \right]
$$

$$
+ \frac{3 + t^2}{4} \left[ \frac{2}{t - (6n - 4) \pi} + \frac{1 + t^2}{t} \right] x(t) \left( 1 + x^2(t) \right) \left( 1 + \left( x'(t) \right)^2 \right)
$$

$$
= \frac{x^3(t) \cos t \sin x'(t)}{t^2},
$$

for $6n - 4 \leq t \leq (6n - \frac{7}{2}) \pi$ for $n = 1, 2, \ldots$
From (A1)–(A6) and (101) we have

$$w^\prime(t) \leq p(t) - k_3q(t) - \frac{h(t)}{k_2r(t)}w(t) - \frac{M}{r(t)}w^3(t).$$  \hspace{1cm} (105)$$

Then, for all \( t \geq t_0 \),

$$\int_{t_0}^{t} (t-s)^3 \rho(s) (k_3q(s) - p(s)) \, ds$$

\( \leq \int_{t_0}^{t} (t-s)^3 \rho(s) w'(s) \, ds \)

\( - \int_{t_0}^{t} (t-s)^3 \rho(s) \frac{h(s)}{k_2r(s)}w(s) \, ds \)

\( - M \int_{t_0}^{t} (t-s)^3 \rho(s) \frac{r(s)}{r(s)}w^2(s) \, ds. \) \hspace{1cm} (106)

Note that

$$\int_{t_0}^{t} (t-s)^3 \rho(s) w'(s) \, ds$$

\( = (t - t_0) \rho(t_0) w(t_0) \)

\( - \int_{t_0}^{t} [\lambda \rho(s) - (t-s) \rho'(s)] (t-s)^3 w(s) \, ds. \) \hspace{1cm} (107)

Substituting (107) in (102) we obtain

$$\int_{t_0}^{t} (t-s)^3 \rho(s) (k_3q(s) - p(s)) \, ds$$

\( \leq (t - t_0) \rho(t_0) w(t_0) \)

\( - \int_{t_0}^{t} [\lambda \rho(s) - (t-s) \rho'(s)] (t-s)^3 w(s) \, ds \)

\( - \int_{t_0}^{t} (t-s)^3 \rho(s) \frac{h(s)}{k_2r(s)}w(s) \, ds \)

\( - M \int_{t_0}^{t} (t-s)^3 \rho(s) \frac{r(s)}{r(s)}w^2(s) \, ds. \) \hspace{1cm} (108)

Then,

$$\int_{t_0}^{t} \left\{ (t-s)^3 \rho(s) (k_3q(s) - p(s)) - \frac{r(s)}{4M \rho(s)} \right\} ds$$

\( \times \left[ (t-s) \rho(s) \frac{h(s)}{k_2r(s)} + \lambda \rho(s) - (t-s) \rho'(s) \right]^2 \)

\( \times (t-s)^{\lambda-2} \} ds \)

\( \leq (t - t_0) \rho(t_0) w(t_0) \)

\( - \int_{t_0}^{t} \left\{ \frac{M \rho(s)}{r(s)} (t-s)^{\lambda/2} w(s) + \frac{r(s)}{2M \rho(s)} \right\} ds \)

\( \times \left[ (t-s) \rho(s) \frac{h(s)}{k_2r(s)} + \lambda \rho(s) - (t-s) \rho'(s) \right]^2 \}

\( \times (t-s)^{\lambda-2}/2 \} ds \)

\( \leq (t - t_0) \rho(t_0) w(t_0). \) \hspace{1cm} (109)

Dividing (109) by \( t^\lambda \) and taking the upper limit as \( t \to \infty \), it contradicts with (102). This completes the proof. \( \square \)

Example 17. Consider the following second order nonlinear differential equation with damping:

$$\left[ \left( \frac{t+1}{t(t+2)} \right) x''(t) \right]' + \frac{1}{t(t+1)} x'(t)$$

\( + \frac{t(3+t)}{(t+1)^2} x(t) \left( 3 + x'^2(t) \right) = -2tx(t) \cos(t) \sin(x'(t)) \),

\( t \geq t_0 = 1. \)

(110)

We note that \( g'(x)/\psi(x) = 1 > 0 \), \( l = k_2 = k_3 = 1 \).

Considering \( \rho(t) = t \) and \( \lambda = 2 \), then

$$\lim_{t \to \infty} \sup \frac{1}{t^2} \int_{1}^{t} \left\{ (t-2)^2 s^2 (s+2) - \frac{s+1}{4s^2 (s+2)} \right\} ds$$

\( = \lim_{t \to \infty} \sup \frac{1}{t^2} \left[ \frac{1}{3} t^3 + \frac{t^2}{8} - t^2 \ln(1+t) - \frac{5t}{3} \right] \)

\( - \frac{t}{16} \ln(2+t) + \frac{t}{16} \ln t - \frac{5}{16} \ln t \)

\( - \frac{7}{16} \ln(2+t) + \frac{29}{24} + 2 \ln(1+t) \)

\( + t^2 \ln 2 + \frac{7}{16} \ln 3 - 2 \ln 2 + \frac{t}{16} \ln 3 \),

\( = \infty, \)

$$\lim_{t \to \infty} \sup \frac{1}{t^2} \left\{ (t-s)^{3/2} \rho(s) (k_3q(s) - p(s)) - \frac{r(s)}{4M \rho(s)} \right\} ds \)

\( \times \left[ (t-s) \rho(s) \frac{h(s)}{k_2r(s)} + \lambda \rho(s) - (t-s) \rho'(s) \right]^2 \}

\( \times (t-s)^{\lambda-2}/2 \} ds \)
\[
\lim_{t \to \infty} \sup_{s \leq t} \frac{1}{t^2} \times \int_{1}^{t} \{ (t-s)^2 s \left( \frac{s^2}{(s+1)^3} + \frac{2s}{(s+1)^3} \right) \\
- \frac{s+1}{4Ms^2 (s+2)} \\
\times \left( \frac{s}{s(s+1)} + 2s - (t-s)(1) \right)^2 \} ds.
\]

(111)

Example 17 is oscillatory.

Remark 18. If \( r(t) = 1 \), \( \psi(x) = 1 \), \( f(x') = x' \), \( g(x) = x \), \( \Phi(x') = 1 \), and \( H(t, x, x') = 0 \), Theorem 16 reduces to Theorem 1 of Philos [5]. Furthermore, when \( \psi(x) = 1 \), \( \Phi(x') = 1 \), and \( H(t, x, x') = 0 \), then Theorem 16 reduces to Theorem 1 of Elabbasy and Elsharabasy [2].

Corollary 19. If condition (101) in Theorem 16 is replaced by

\[
\lim_{t \to \infty} \sup_{s \leq t} \frac{1}{t^4} \times \int_{t_0}^{t} \frac{r(s)}{\rho(s)} \left\{ (t-s) \rho(s) \frac{h(s)}{k_2 r(s)} + \lambda \rho(s) - (t-s) \rho'(s) \right\}^2 \\
\times (t-s)^{\lambda-2} ds < \infty,
\]

\[
\lim_{t \to \infty} \sup_{s \leq t} \frac{1}{t^4} \int_{t_0}^{t} (t-s)^{\lambda} \rho(s) (k_3 q(s) - p(s)) ds = \infty,
\]

(112)

then Theorem 16 is still valid.

Conflict of Interests

The authors declare that they have no conflict of interests.

Authors’ Contribution

All authors completed the paper together. All authors read and approved the final paper.

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