Research Article
The Stability of the Solutions for a Porous Medium Equation with a Convection Term

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1. Introduction
Consider the motion of the ideal barotropic gas through a porous medium. Let \( \rho \) be the gas density, \( V \) the velocity, and \( p \) the pressure. The motion is governed by the mass conservation law
\[
\rho_t + \text{div} (\rho V) = 0,
\]
the Darcy law
\[
V = -k(x) \nabla \rho,
\]
and the equation of stage \( p = P(\rho) \). Here, \( k(x) \) is a given matrix. We usually assume that \( P(\rho) = \mu \rho^\alpha \) with \( \mu, \alpha = \text{const} \). The above laws then lead to a semilinear parabolic equation for the density \( \rho \):
\[
\rho_t = \frac{\mu \alpha}{1 + \alpha} \text{div} \left( k(x) \nabla \rho^{1+\alpha} \right).
\]
If \( k(x) = a(x) I \), where \( a(x) \) is a function and \( I \) is the unit matrix, then (3) becomes
\[
\rho_t = \frac{\mu \alpha}{1 + \alpha} \text{div} \left( a(x) \nabla \rho^{1+\alpha} \right) = \mu \alpha \text{div} \left( a(x) \rho^\alpha \nabla \rho \right).
\]
Also, (4) can be regarded as the generalization of the nonlinear heat equation
\[
u_t = \text{div} \left( h(u, x) \nabla u \right),
\]
where the function \( h(u, x) \) has the meaning of nonlinear thermal conductivity dependent on the temperature \( u = u(x, t) \). If \( a(x) \equiv 1 \) in (4) or \( h(u, x) \equiv h(u) \) in (5), that is,
\[
u_t = \Delta u^m,
\]
which is called the porous medium equation, there are well-known monographs or textbooks devoting to the well-posedness problem of (6); one can refer to [1–6] and the references therein. If \( a(x) \geq 0 \) in (4) or \( h(u, x) \) depending on \( x \) in (5), the situation may be different from that of (6). For example, if \( a(x)|_{x\in\partial\Omega} = 0 \), we consider the equation
\[
u_t = \nabla (a(x) \nabla u),
\]
and suppose that there are two classical solutions \( u \) and \( v \) of (7) with the initial values \( u_0 \) and \( v_0 \), respectively. Then it is easy to show that
\[
\int_{\Omega} |u(x, t) - v(x, t)|^2 \, dx \leq \int_{\Omega} |u_0(x) - v_0(x)|^2 \, dx,
\]
which implies that the classical solutions (if there are) of (7) are controlled by the initial value completely. In other words, the stability of the classical solutions of (7) is true without any boundary value condition. Yin and Wang [7] also showed that the non-Newtonian fluid equation with the type
\[
u_t = \text{div} \left( d^\alpha (x) |\nabla u|^{p-2} \nabla u \right), \quad (x, t) \in \Omega \times (0, T)
\]
has similar properties, where $\Omega$ is a bounded domain in $\mathbb{R}^N$ with appropriately smooth boundary, $d(x) = \text{dist}(x, \partial \Omega)$, and $\alpha > 0$ is a constant. Since the diffusion coefficient $d^\alpha(x)$ vanishes on the boundary, it seems that there is no heat flux across the boundary. However, Yin and Wang [7] showed that the fact might not coincide with what we image. In fact, the exponent $\alpha$, which characterizes the vanishing ratio of the diffusion coefficient near the boundary, does determine the behavior of the heat transfer near the boundary. They proved that, if $0 < \alpha < p - 1$, the solution of (9), $u \in H^p_0$ for some constant $p > 1$, and the trace of $u$ on the boundary can be defined in the traditional way; then, in physics sense, there is no heat flux across the boundary actually, while, if $\alpha \geq p - 1$, the existence and uniqueness of solutions were proved without any boundary conditions, which means that whether there is heat flux across the boundary is uncertain. Later, Yin and Wang [8] had shown that only a partial boundary value condition matches up with the equation

\[
\frac{\partial u}{\partial t} - \text{div}\left(a(x)|\nabla u|^{p-2} \nabla u\right) - f_j(x) D_j u = f_j(x) D_j u + c(x, t) u = g(x, t), \quad (x, t) \in \Omega \times (0, T).
\]

(10)

Inspired by Yin and Wang [7, 8], we will study the porous medium equation with a convection term,

\[
u_i = \text{div}(d^\alpha \nabla u^m) + \sum_{i=1}^N \frac{\partial b_i(u^m)}{\partial x_i},
\]

(11)

with the initial value

\[u(x, 0) = u_0(x), \quad x \in \Omega,\]

(12)

and with the partial boundary condition

\[u(x, t) = 0, \quad (x, t) \in \Sigma_m \times (0, T),\]

(13)

where $\Sigma_m$ is defined as follows. When $0 < \alpha < 1, \Sigma_m = \partial \Omega$; when $\alpha \geq 1, \Sigma_m = \{x \in \partial \Omega : b_i'(0) n_i(x) < 0\}$ and $\{n_i\}$ is the inner normal vector of $\Omega$. The expression of $\Sigma_m$ is derived in [9], we do not repeat the details here.

We suppose that $b_i(s)$ is a $C^1$ function, and

\[d^{\alpha/2} \nabla u_0^m \in L^2(\Omega), \quad 0 \leq u_0 \in L^\infty(\Omega).\]

(14)

Definition 1. A nonnegative function $u(x, t)$ is said to be the weak solution of (11) with the initial value (12), if

\[
\int_{\Omega} \left(\frac{\partial \varphi}{\partial t} u + d^\alpha \nabla u^m \nabla \varphi\right) dx dt + \int_{\Omega} b_i(u^m) \varphi_{x_i}(x, t) dx dt = \int_{\Omega} u_0 \varphi(x, 0) dx,
\]

and the initial condition is satisfied in the sense that

\[
\lim_{t \to 0} \int_{\Omega} |u(x, t) - u_0(x)| dx = 0.
\]

(17)

If $u(x, t)$ satisfies (13) in the sense of the trace in addition, then we say it is a weak solution of the initial-boundary value problem of (11).

First of all, we will study the well-posedness problem of (11).

**Theorem 2.** If $m > 0, 2 > \alpha > 0, u_0(x) \geq 0$ satisfy (15), then (11) with initial value (12) has a nonnegative solution. Moreover, if $0 < \alpha < 1$, then $\Sigma_m = \partial \Omega$; the solution is unique.

Then, we will study the stability of the solutions.

**Theorem 3.** If $b_i(u) \equiv 0$, i.e. equation (11) is not with the convection term, $u$ and $v$ are two solutions of equation (11) with the initial value $u_0(x)$, $v_0(x)$ respectively, $\alpha > 1$, then

\[
\int_{\Omega} |u(x, t) - v(x, t)| \leq c \int_{\Omega} |u_0(x) - v_0(x)| dx.
\]

(18)

Since $b_i(u) \equiv 0$ in Theorem 3, there are some regrets more or less. For (11) itself, we can not prove the same conclusion for the time being. However, as compensation, we can consider a more complicate equation than (11),

\[
u_i = \text{div}(d^\alpha \nabla u^m) + \sum_{i=1}^N \frac{\partial b_i(u^m, x, t)}{\partial x_i},
\]

(19)

**Theorem 4.** Let $u$ and $v$ be two solutions of (19) with the initial values $u_0(x)$, $v_0(x)$, respectively, if $1 < \alpha < 2$, and

\[|b_i(\xi, x, t)| \leq a(\xi), \quad a(\xi)|_{x \equiv \partial \Omega} = 0;\]

(20)

\[a(\xi) \text{satisfies}
\]

\[
\int_{\Omega} a(\xi) d^\alpha dx \leq c;
\]

(21)

then the stability of the weak solutions is true in the sense of (18).

It is more or less strange that the case $\alpha = 1$ is not included in Theorems 3 and 4.

At last, we will probe the stability of the weak solutions based on the partial boundary value condition.

**Theorem 5.** Let $u, v$ be two solutions of (11) with the initial values $u_0(x)$, $v_0(x)$, respectively. If $2 > \alpha \geq 1, m > 0$,

\[
\int_{\Omega} d^{\alpha-1} |\nabla u^m| < \infty,
\]

\[
\int_{\Omega} d^{\alpha-1} |\nabla v^m| < \infty.
\]

(22)
and the partial boundary condition (12) is satisfied in the sense of trace, then
\[ \int_{\Omega} |u(x, t) - v(x, t)| \, dx \leq c \int_{\Omega} |u_0(x) - v_0(x)| \, dx + \int_{\Sigma} |u^m - v^m| \, d\Sigma, \]  
(23)
where \( \Sigma^m = \partial \Omega \setminus \Sigma_m \).

**Theorem 6.** If \( \Omega \) is a \( C^2 \) domain, \( \alpha \geq 2 \), and \( m \geq 1 \), then (11) with the initial value \( u_0 \) and the partial boundary condition (13) has a BV solution. Moreover, let \( u, v \) be two solutions of (11) with the different initial values \( u_0(x), v_0(x) \), respectively. Then
\[ \int_{\Omega} |u(x, t) - v(x, t)| \leq \int_{\Omega} |u_0(x) - v_0(x)| \, dx + \int_{\Sigma} |u - v| \, d\Sigma, \]  
(24)
where \( \Sigma^m = \partial \Omega \setminus \Sigma_m \), \( \Sigma_m = \{ x \in \Omega : b^i(0) \eta_i(x) < 0 \} \), and \( \{ \eta_i \} \) is the inner normal vector of \( \Omega \).

If \( h_b \equiv 0 \), Theorem 6 has been included in Theorem 3, while, if \( h_b \equiv 0 \) is not true, then Theorem 6 has its independent sense. Such phenomena that the solution of a degenerate parabolic equation may be free from the limitation of the boundary condition also can be found in [7–14]. We will use some ideas in [9, 14]. The uniqueness of the weak solutions when \( \Sigma_m = \partial \Omega \) had been proved in [14]. Since [14] was written in Chinese, for the completeness of the paper, we still give its proof in what follows. In addition, how to obtain the stability (23) without condition (22) is a very interesting problem. Last but not least, roughly speaking, in this paper, we can show that if \( 0 < \alpha < 1 \) or \( \alpha \geq 2 \), then the weak solution \( u \) can be defined the trace on the boundary in the traditional sense; it is surprising that if \( 1 \leq \alpha < 2 \), whether \( u \) can be defined the trace on the boundary is unknown for the time being.

### 2. The Well-Posedness Problem

We consider the following regularized problem:
\[ u_{nt} = \text{div} \left( \left( d + \frac{1}{n} \right)^\alpha \nabla u_n^m \right) + \sum_{i=1}^{N} \frac{\partial b_i(u_n^m)}{\partial x_i}, \]  
(25)
\( (x, t) \in Q_T, \)

\[ u_n(x, t) = \frac{1}{n}, \quad (x, t) \in S_T = \partial \Omega \times (0, T), \]

\[ u_n(x, 0) = u_{0n}(x) = u_0(x) + \frac{1}{n}, \quad x \in \Omega. \]

According to the standard parabolic equation theory, there is a weak solution
\[ u_n \in L^\infty (Q_T), \]
\[ \nabla u_n^m \in L^2 (Q_T), \]  
(26)
which satisfies
\[ \frac{1}{n} \leq u_n(x, t) \leq \| u_0 \|_{L^\infty(\Omega)} + \frac{1}{n}, \quad (x, t) \in Q_T, \]  
(27)
by the maximum principle.

**Theorem 7.** If \( m > 0, 2 > \alpha > 0 \), and \( u_0(x) \geq 0 \) satisfy (14), then (11) with initial value (12) has a nonnegative solution.

**Proof.** First we suppose that \( u_0 \in C^0_0(\Omega) \) and \( 0 \leq u_0 \leq M \), and consider the following normalized problem
\[ u_{nt} = \text{div} \left( a_n(u_n) \nabla u_n \right) + \sum_{i=1}^{N} \frac{\partial b_i(u_n^m)}{\partial x_i}, \]  
(28)
\( (x, t) \in Q_{T_n} \)

\[ u_n(x, t) = \frac{1}{n}, \quad (x, t) \in \partial \Omega \times (0, T), \]

\[ u_n(x, 0) = u_{0n}(x), \quad x \in \Omega. \]

Here, \( a_n(u) \geq c(n) > 0 \), and
\[ a_n(u) = m \left( d + \frac{1}{n} \right)^\alpha u_n^{m-1}, \quad \text{if} \ u \in \left[ \frac{1}{n}, M + \frac{1}{n} \right]. \]  
(29)

Thus, the solution of the problem \( u_n \) is also a solution of problem (25). Moreover, by comparison theorem, we clearly have
\[ u_{n+1}(x, t) \leq u_n(x, t), \]  
(30)
which yields
\[ u(x, t) = \lim_{n \to \infty} u_n(x, t). \]  
(31)

Now, we can prove that the limit function \( u \) is a weak solution of (6) with the initial value (8).

Multiplying both sides of the first equation in (25) by \( \phi = u_n^m - (1/n)^m \) and integrating it over \( Q_T \), we have
\[ \int_{Q_T} u_{nt} \left( u_n^m - \frac{1}{n} \right)^m \, dx \, dt \]
\[ = \int_{\Omega} u_n \left( u_n^m - \frac{1}{n} \right)^m \bigg|_{t=0}^{t=T} \, dx \]
\[ - \int_{Q_T} u_n^m \frac{\partial}{\partial t} \left( u_n^m - \frac{1}{n} \right)^m \, dx \, dt \]
\[ = \int_{\Omega} u_n(x, T) \left( u_n^m(x, T) - \frac{1}{n} \right)^m \, dx \]
\[ - \int_{\Omega} u_n(x, 0) \left( u_0^m(x) - \frac{1}{n} \right)^m \, dx \]
\[ - \int_{Q_T} nu_n^m u_{nt} \, dx \, dt \]
\[ = \int_{Q_T} \text{div} \left( \left( d + \frac{1}{n} \right)^\alpha \nabla u_n^m \right) \left( u_n^m - \frac{1}{n} \right)^m \, dx \, dt \]
\[ + \sum_{i=1}^{N} \int_{Q_T} \frac{\partial b_i(u_n^m)}{\partial x_i} \left( u_n^m - \frac{1}{n} \right)^m \, dx \, dt.]  
(32)
By the fact
\[ \int_{Q_{r'}} \frac{\partial b_i(u_n^m)}{\partial x_i} \left( u_n^m - \left( \frac{1}{n} \right)^m \right) dx dt = - \int_{Q_{r'}} b_i(u_n^m) \frac{\partial}{\partial x_i} \left( u_n^m - \left( \frac{1}{n} \right)^m \right) dx dt \]
\[ = - \int_{Q_{r'}} b_i(u_n^m) \frac{\partial}{\partial x_i} \left( u_n^m \right) dx dt = 0, \]
then we have
\[ (m+1) \int_{Q_{r'}} \left( d + \frac{1}{n} \right)^{\alpha/2} |\nabla u_n^m|^2 dx dt \]
\[ = \int_{Q_{r'}} \left( u_n^m(x) - \frac{1}{n} \right) u_{in}(x) dx \]
\[ - \int_{Q_{r'}} u_n(x,T) \left( u_n^m(x,T) - \frac{1}{n} \right) dx \]
\[ + \int_{Q_{r'}} \frac{\partial b_i(u_n^m)}{\partial x_i} \left( u_n^m - \left( \frac{1}{n} \right)^m \right) dx dt \]
\[ \leq \int_{\Omega} \left( u_n^m(x) + \frac{1}{n} \right)^{m+1} dx + \frac{1}{n} \left( M + \frac{1}{n} \right) \int_{Q_{r'}} dx. \]
Thus, we obtain
\[ \left| \left( d + \frac{1}{n} \right)^{\alpha/2} \| \nabla u_n^m \|_{L^2(Q_{r'})} \right| \leq c. \] (35)

By choosing a subsequence, we can assume that
\[ \left( d + \frac{1}{n} \right)^{\alpha/2} \| \nabla u_n^m \| \to \zeta, \] (36)
weakly in $L^2$. We need to prove that
\[ \zeta = d^{\alpha/2} \nabla u^m. \] (37)

For any $\forall \psi \in C^0_\infty(\Omega)$, denoting that $d_n \equiv d+1/n$, we have
\[ \int_{Q_{r'}} d_n^{\alpha/2} \nabla u_n^m \cdot \psi dx dt \]
\[ = \int_{Q_{r'}} \nabla (d_n^{\alpha/2} u_n^m) \cdot \psi dx dt \]
\[ = \frac{\alpha}{2} \int_{Q_{r'}} d_n^{\alpha/2-1} \nabla d \cdot u_n^m \psi dx dt \] (38)
\[ \leq \frac{\alpha}{2} \int_{Q_{r'}} d_n^{\alpha/2-1} \nabla d \cdot u_n^m \psi dx dt. \]

Let $n \to \infty$. The left hand side is
\[ \lim_{n \to \infty} \int_{Q_{r'}} d_n^{\alpha/2} \nabla u_n^m \cdot \psi dx dt = \int_{Q_{r'}} \zeta \psi dx dt. \] (39)

while on the right hand side, by
\[ |\nabla d \cdot u_n^m| \leq c |\nabla d| \cdot |u_n^m| \leq c \left( M + \frac{1}{n} \right)^m \leq c, \] (40)
and by the condition $0 < \alpha < 2$,
\[ \int_{\Omega} d_n^{\alpha/2-1} dx \leq c, \] (41)
using the control convergent theorem,
\[ \frac{\alpha}{2} \lim_{n \to \infty} \int_{Q_{r'}} d_n^{\alpha/2-1} \nabla d \cdot u_n^m \psi dx dt \]
\[ = \frac{\alpha}{2} \int_{Q_{r'}} d^{\alpha/2-1} \nabla d \cdot u^m \psi dx dt, \] (42)
we have
\[ \lim_{n \to \infty} \left[ - \int_{Q_{r'}} d_n^{\alpha/2-1} \nabla d \cdot \psi dx dt \right] \]
\[ = \frac{\alpha}{2} \int_{Q_{r'}} d^{\alpha/2-1} \nabla d \cdot u^m \psi dx dt - \frac{\alpha}{2} \int_{Q_{r'}} d_n^{\alpha/2-1} \nabla d \cdot \psi dx dt \]
\[ = \int_{Q_{r'}} d^{\alpha/2} \nabla u^m \cdot \psi dx dt. \]
Thus we obtain (37).
At the same time, since $b_i \in C^1$, by (31), we have
\[ \lim_{n \to \infty} b_i(u_n^m) = b_i(u^m). \] (44)
Thus, $u$ is a solution of (11) with the initial value (12).

If $u_0$ only satisfies (14), by considering the problem of (25) with the initial value $u_0 \varepsilon$ which is the mollified function of $u_0$, then we can get the conclusion by a process of limitation. Certainly, the solution $u(x, t)$ generally is not continuous at $t = 0$, but satisfies (15) and (17). Theorem 7 is proved.

Lemma 8. Let $u_0$ satisfy (14). If $0 < \alpha < 1$ and $u$ is a solution of (11) with the initial value (12), then there exists a constant $\gamma > 1$ such that
\[ \int_{Q_{r'}} |\nabla u^m|^\gamma dx dt \leq c. \] (45)

Proof. Since $\alpha < 1$, there exists constant $\beta \in (\alpha, 1)$, $\beta < (\alpha + 1)/2$ such that $2 - \alpha/\beta > 1$. Therefore, there exists $\gamma \in (1, 2 - \alpha/\beta)$ such that $\beta \gamma < 1$. Therefore,
\[ \int_{Q_{r'}} |\nabla u^m|^\gamma dx dt \]
\[ = \int_{\{ x \in Q_{r'} : |\nabla u^m| \leq c \}} |\nabla u^m|^\gamma dx dt \]
\[ + \int_{\{ x \in Q_{r'} : |\nabla u^m| > c \}} |\nabla u^m|^\gamma dx dt \]
\[ \leq \int_{Q_{r'}} d^{-\beta \gamma} dx dt + \int_{Q_{r'}} d^\alpha |\nabla u^m|^\beta \gamma dx dt \]

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Thus \( u^m \) can be defined the trace on the boundary in the traditional way. By the definition of the trace, we also know that \( u \) can be defined as the trace on the boundary in the traditional way. The lemma is proved. 

**Theorem 9.** If \( m > 0 \), \( 1 > \alpha > 0 \) and \( u_0(x) \geq 0 \) satisfies (14), then \( \Sigma_m = \partial \Omega \), and the solution of the initial-boundary value problem (11)–(13) is unique.

**Proof.** First of all, by Theorem 7 and Lemma 8, there is a nonnegative solution of the initial-boundary value problem (11)–(13). Then, we prove its uniqueness. Let \( u, v \) be two solutions of equation (11) with 

\[
\begin{align*}
  u(x,0) &= v(x,0), \\
  u(x,t) &= v(x,t) = 0, \quad (x,t) \in \partial \Omega \times (0,T).
\end{align*}
\]

For all \( 0 \leq \varphi \in C_0^1(\Omega_T) \),

\[
\begin{align*}
  \iint_{Q_T} \varphi \frac{\partial (u - v)}{\partial t} \, dx \, dt \\
  &= - \iint_{Q_T} d^m (\nabla u - \nabla v^m) \cdot \nabla \varphi \, dx \, dt \\
  & \quad - \sum_{i=1}^N \iint_{Q_T} [b_i (u^m) - b_i (v^m)] \varphi_{x_i} \, dx \, dt.
\end{align*}
\]

For any given positive integer \( n \), let \( g_n(s) = \int_0^s h_n(\tau) \, d\tau \), \( h_n(s) = 2n(1 - n|s|)_+ \). Then \( h_n(s) \in C(\mathbb{R}) \), and we have

\[
\begin{align*}
  h_n(s) &\geq 0, \\
  |sh_n(s)| &\leq 1, \\
  |g_n(s)| &\leq 1, \\
  \lim_{n \to \infty} g_n(s) &\to \text{sgn} \, s, \\
  \lim_{n \to \infty} sg_n'(s) &\to 0.
\end{align*}
\]

Since \( 0 < \alpha < 1 \), by Lemma 8, we can define the traces of \( u, v \) on the boundary. By a process of limit, we can choose \( g_n(u^m - v^m) \) as the test function; then

\[
\begin{align*}
  \int_{\Omega} g_n(u^m - v^m) \frac{\partial (u - v)}{\partial t} \, dx + \int_{\Omega} d^m (\nabla u - \nabla v^m) \\
  \cdot \nabla (u^m - v^m) \cdot g'_n(u^m - v^m) \, dx \\
  + \sum_{i=1}^N \iint_{Q_T} [b_i (u^m) - b_i (v^m)] (u^m - v^m)_{x_i} \\
  \cdot g'_n(u^m - v^m) \, dx \, dt = 0.
\end{align*}
\]

Moreover, we can prove that

\[
\lim_{n \to \infty} \int_{\Omega} (b_i (u^m) - b_i (v^m)) g'_n(u^m - v^m) \\
\cdot (\nabla (u^m - v^m))_{x_i} \, dx = 0.
\]

In detail, the limitation (51) is established by the following calculations.

\[
\int_{\Omega} (b_i (u^m) - b_i (v^m)) g'_n(u^m - v^m) \\
\cdot (\nabla (u^m - v^m))_{x_i} \, dx \\
\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} \left| b_i (u^m) - b_i (v^m) \right| |(u^m - v^m)|_{x_i} \, dx
\]

\[
\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} d^{n/2} (u^m - v^m) |(u^m - v^m)|_{x_i} \, dx \\
\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} d^{n/2} (u^m - v^m) \, dx \\
\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} \left| d^{n/2} b_i (u^m) - b_i (v^m) \right|^2 \, dx^{1/2}.
\]

Since \( 0 < \alpha < 1 \),

\[
\int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} \left| d^{n/2} b_i (u^m) - b_i (v^m) \right|^2 \, dx^{1/2}
\]

\[
\leq c \int_{\Omega} d^m (x) \, dx \leq c \int_{\Omega} d^m (x) \, dx \\
= c \int_{\{x \in \Omega : |u^m - v^m| = 0\}} d^m (x) \, dx = 0.
\]

If the set \( \{x \in \Omega : |u^m - v^m| = 0\} \) has a positive measure, then

\[
\lim_{n \to \infty} \int_{\{x \in \Omega : |u^m - v^m| < 1/n\}} d^m |(u^m - v^m)|^2 \, dx
\]

\[
= \int_{\{x \in \Omega : |u^m - v^m| = 0\}} d^m |(u^m - v^m)|^2 \, dx = 0.
\]

Therefore, in both cases, the right hand side of inequality (52) goes to 0 as \( n \to \infty \).
Clearly, we have
\[
\lim_{n \to \infty} \int_{\Omega} d^a (\nabla u^m - \nabla v^m) \cdot \nabla \phi_n (u^m - v^m) \, dx \\
\geq 0,
\]
\[
\lim_{n \to \infty, \lambda \to 0} \int_{\Omega} \phi (x) g_n (u^m - v^m) d^a (u - v) \, dx \\
= \lim_{n \to \infty} \int_{\Omega} g_n (u^m - v^m) \frac{d}{dt} (u - v) \, dx \\
= \int_{\Omega} \text{sgn}(u - v) \frac{d}{dt} (u - v) \, dx
\]

Now, let \( n \to \infty \) in (50). Then
\[
\int_{\Omega} |u(x, t) - v(x, t)| \, dx \leq \int_{\Omega} |u_0(x) - v_0(x)| \, dx
\]
\[
= 0.
\]
We have the conclusion.

By Theorems 7 and 9, we clearly have the following.

**Corollary 10.** Theorem 2 is true.

### 3. The Stability without the Boundary Value Condition

Consider a simpler equation than (11).

\[
\begin{align*}
  u_t &= \text{div} (d^a \nabla u^m), \quad (x, t) \in Q_T = \Omega \times (0, T), \\
  \text{with the initial value (12), but without any boundary value condition. For a small positive constant } \lambda > 0, \text{ let } \\
  \Omega_1 &= \{ x \in \Omega : d(x) = \text{dist}(x, \partial \Omega) > \lambda \}, \\
  \phi (x) &= \begin{cases} 
    1, & \text{if } x \in \Omega_2, \\
    1 / \lambda (d(x) - \lambda), & \text{if } x \in \Omega_1 \setminus \Omega_2, \\
    0, & \text{if } x \in \Omega \setminus \Omega_1.
  \end{cases}
\end{align*}
\]

and let

\[
\begin{align*}
  \phi_n &= \begin{cases} 
    1, & \text{if } x \in \Omega_2, \\
    1 / \lambda (d(x) - \lambda), & \text{if } x \in \Omega_1 \setminus \Omega_2, \\
    0, & \text{if } x \in \Omega \setminus \Omega_1.
  \end{cases}
\end{align*}
\]

**Proof of Theorem 3.** Suppose \( u_0, v_0 \) only satisfy (7), \( \alpha > 1 \). Let \( u, v \) be two solutions of (58) with the initial-boundary values \( u_0, v_0 \), respectively. For all \( 0 \leq \phi \in C_0^\infty(Q_T), \)

\[
\int_{Q_T} \phi \frac{\partial (u - v)}{\partial t} \, dx \, dt = - \int_{Q_T} d^a (\nabla u^m - \nabla v^m) \cdot \nabla \phi \, dx \, dt
\]

By a process of limit, we can choose \( \phi_n (u^m - v^m) \) as the test function; then

\[
\int_{\Omega} \phi (x) g_n (u^m - v^m) \frac{d}{dt} (u - v) \, dx \\
+ \int_{\Omega} d^a (\nabla u^m - \nabla v^m) \cdot \nabla \phi_n (u^m - v^m) \, dx \\
+ \int_{\Omega} d^a (\nabla u^m - \nabla v^m) \cdot \nabla \phi g_n (u^m - v^m) \, dx = 0.
\]

The last equality of (65) is due to that since \( \alpha > 1 \), we have

\[
\lim_{\lambda \to 0} \left( \int_{Q_T} d^a (\nabla u^m)^2 + |\nabla v^m|^2 \, dx \right)^{1/2} = 0.
\]

Consider a more complicated equation than (11).

\[
\begin{align*}
  u_t &= \text{div} (d^a \nabla u^m) + \sum_{i=1}^N \frac{\partial b_i (u^m, x, t)}{\partial x_i}, \\
  (x, t) &\in Q_T = \Omega \times (0, T),
\end{align*}
\]

with the initial value (12), but without any boundary value condition.
Proof of Theorem 4. Suppose $u_0, v_0$ only satisfy (7), $1 < \alpha < 2$. Let $u, v$ be two solutions of equation (11) with the initial-boundary values $u_0, v_0,$ respectively. For all $0 \leq \varphi \in C^0(\Omega_T)$, and for the second term, we have
\[
\int_{Q_T} \varphi \frac{\partial (u-v)}{\partial t} \, dx \, dt
= - \int_{Q_T} d^\alpha \left( \nabla u^m - \nabla v^m \right) \cdot \nabla \varphi \, dx \, dt
- \sum_{i=1}^N \int_{Q_T} \left[ b_i (u^m, x, t) - b_i (v^m, x, t) \right] \varphi \, dx \, dt.
\]
By a process of limit, we can choose $g_n(\phi(u^m - v^m))$ as the test function; then
\[
\int_\Omega g_n(\phi(u^m - v^m)) \frac{\partial (u-v)}{\partial t} \, dx + \int_\Omega d^\alpha \left( \nabla u^m - \nabla v^m \right) \cdot \phi (u^m - v^m) \, dx
+ \int_\Omega d^\alpha \left( \nabla u^m - \nabla v^m \right) \cdot \phi (u^m - v^m) \, dx
- \sum_{i=1}^N \int_{Q_T} \left[ b_i (u^m, x, t) - b_i (v^m, x, t) \right] \cdot g_n'(\phi(u^m - v^m)) \, dx \, dt = 0.
\]
For the third term, since
\[
\lim_{\lambda \to 0} \int_{\Omega_1 \setminus \Omega_{23}} \left[ d^{\alpha/2-1} (u^m - v^m) g_n' (\phi(u^m - v^m)) \right]^2 \, dx
\leq \lim_{\lambda \to 0} \int_\Omega d^{\alpha-2} \left| (u^m - v^m) g_n' (\phi(u^m - v^m)) \right|^2 \, dx
\leq \int_\Omega d^{\alpha-2} \, dx \leq c,
\]
by $0 > \alpha - 2 > -1$, we have
\[
\lim_{\lambda \to 0} \int_\Omega d^\alpha \left( \nabla u^m - \nabla v^m \right) \cdot \phi (u^m - v^m) \, dx
\cdot g_n' (\phi(u^m - v^m)) \, dx
= \lim_{\lambda \to 0} \int_{\Omega_1 \setminus \Omega_{23}} \frac{c}{\lambda} \, d^\alpha \left| \nabla u^m - \nabla v^m \right| \left( (u^m - v^m) g_n' (\phi(u^m - v^m)) \right) \, dx \leq c
\cdot g_n' (\phi(u^m - v^m)) \, dx \leq c.
\]
Let us analyze every term in the left hand side of (70). For the first term, we clearly have
\[
\lim_{n \to \infty} \lim_{\lambda \to 0} \int_\Omega g_n(\phi(u^m - v^m)) \frac{\partial (u-v)}{\partial t} \, dx
= \lim_{n \to \infty} \int_\Omega g_n (u^m - v^m) \frac{\partial (u-v)}{\partial t} \, dx
= \int_\Omega \operatorname{sgn} (u^m - v^m) \frac{\partial (u-v)}{\partial t} \, dx
= \int_\Omega \operatorname{sgn} (u-v) \frac{\partial (u-v)}{\partial t} \, dx = \frac{d}{dt} \| u - v \|_1.
\]
For the second term, we have
\[
\int_\Omega d^\alpha \left( \nabla u^m - \nabla v^m \right) \cdot \phi (u^m - v^m) \, dx \geq 0.
\]
\[\lim_{\lambda \to 0} \left| \int_{\Omega} \left( b_1 \left( u^m, x, t \right) - b_1 \left( v^m, x, t \right) \right) g_n' \left( \phi \left( u^m - v^m \right) \right) \left( u^m - v^m \right)_x, \phi \left( x \right) dx \right| \]
\[= \left| \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} (b_1 (u^m, x, t) - b_1 (v^m, x, t)) g_n' (u^m - v^m) (u^m - v^m)_x, dx \right| \]
\[\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} \left| \frac{b_1 (u^m, x, t) - b_1 (v^m, x, t)}{u^m - v^m} \right| \left| (u^m - v^m)_x \right| dx \]
\[= c \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} \left| d^{\alpha/2} \frac{b_1 (u^m, x, t) - b_1 (v^m, x, t)}{u^m - v^m} \right| d^{\alpha/2} \left( u^m - v^m \right)_x dx \]
\[\leq c \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} \left( d^{\alpha/2} \frac{b_1 (u^m, x, t) - b_1 (v^m, x, t)}{u^m - v^m} \right)^2 dx \]
\[\cdot \left[ \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} \left| d^{\alpha/2} \left( u^m - v^m \right)^2 dx \right|^{1/2} \right]. \]  

By (21),
\[
\int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} \left( d^{\alpha/2} \frac{b_1 (u^m, x, t) - b_1 (v^m, x, t)}{u^m - v^m} \right)^2 dx \leq \left\{ \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} a (x) d^{\alpha} dx \right\}^{1/2} \leq c. \]

Let \( n \to \infty \) in (78). If \( \{x \in \Omega : |u^m - v^m| = 0\} \) is a set with \( 0 \) measure, then
\[
\lim_{n \to \infty} \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} a (x) d^{\alpha} dx = 0. \tag{80} \]

If the set \( \{x \in \Omega : |u^m - v^m| = 0\} \) has a positive measure, then,
\[
\lim_{n \to \infty} \int_{\{x \in \Omega : |u^m - v^m| < 1/n \}} d^{\alpha} \left| \nabla \left( u^m - v^m \right) \right|^2 dx \leq 0. \tag{81} \]

Therefore, in both cases, the right hand side of inequality (74) goes to 0 as \( n \to \infty \).

At last, Now, after letting \( \lambda \to 0 \), let \( n \to \infty \) in (71). By (72), (73), (74), (76), (77), (78), (79), (80), and (81), then
\[
\int_{\Omega} |u (x, t) - v (x, t)| dx \leq \int_{\Omega} |u_0 (x) - v_0 (x)| dx. \tag{82} \]

Theorem 4 is proved. \( \square \)

4. The Stability Based on the Partial Boundary Value Condition

In this section, we will prove Theorem 5; the proof is similar as that of Theorem 4 for \( \alpha < 2 \). Let \( u, v \) be two solutions of (II) with the initial-boundary values \( u_0, v_0 \), respectively, and with the same homogeneous partial boundary value condition
\[
u (x, t) = v (x, t) = 0, \quad (x, t) \in \Sigma_m \times (0, T), \tag{83} \]

For all \( \varphi \in C_0^1 (Q_T) \),
\[
\int_{Q_T} \varphi \frac{\partial (u - v)}{\partial t} dx dt = - \int_{Q_T} \left[ \nabla u^m - \nabla v^m \right] \cdot \nabla \varphi dx dt \tag{84} \]
\[\quad - \sum_{i=1}^N \int_{Q_T} [b_i (u^m) - b_i (v^m)] \varphi_i dx dt. \]

By a process of limit, we can choose \( g_n (\phi (u^m - v^m)) \) as the test function as in Theorem 4; then
\[
\int_{Q_T} g_n (\phi (u^m - v^m)) \frac{\partial (u - v)}{\partial t} dx + \int_{\Omega} d^{\alpha} \left( \nabla u^m - \nabla v^m \right) \cdot \nabla \varphi (u^m - v^m) dx \]
\[+ \int_{\Omega} d^{\alpha} \left( \nabla u^m - \nabla v^m \right) \cdot \nabla \phi (u^m - v^m) g_n' (u^m - v^m) dx \]
\[\quad - \int_{\Omega} d^{\alpha} \left( \nabla v^m \right) dx + \sum_{i=1}^N \int_{Q_T} [b_i (u^m) - b_i (v^m)] \left[ \phi \left( u^m - v^m \right) \right] \]
\[\cdot \left[ \phi (u^m - v^m) + \phi (u^m - v^m)_x \right] dx dt = 0. \tag{85} \]
Let us analyze every term in (85). By $|b_t(u^m) - b_t(v^m)| \leq c|u^m - v^m|$ and then according to the definition of the trace, by (83), we have

$$
\lim_{\lambda \to 0} \left[ \int_{\Omega} [b_t(u^m) - b_t(v^m)] g'_n(\phi(u^m - v^m)) (u^m - v^m) \right]_{x_i} \cdot \phi(x) \, dx 
\leq c \lim_{\lambda \to 0} \int_{\Omega \setminus \Omega_{\Delta_1}} |b_t(u^m) - b_t(v^m)| \, d\Sigma.
$$

Moreover, we can prove that

$$
\lim_{n \to \infty} \lim_{\lambda \to 0} \int_{\Omega} (b_t(u^m) - b_t(v^m)) g'_n(\phi(u^m - v^m)) \cdot (u^m - v^m)_{x_i} \cdot \phi(x) \, dx = 0.
$$

In detail, the limitation (87) is established by the following calculations.

$$
\lim_{\lambda \to 0} \left[ \int_{\Omega} (b_t(u^m) - b_t(v^m)) g'_n(\phi(u^m - v^m)) (u^m - v^m)_{x_i} \cdot \phi(x) \, dx \right] 
\leq c \lim_{\lambda \to 0} \int_{\Omega \setminus \Omega_{\Delta_1}} |b_t(u^m) - b_t(v^m)| \, d\Sigma.
$$

If the set $\{x \in \Omega : |u^m - v^m| = 0\}$ has a positive measure, then, by (22),

$$
\lim_{n \to \infty} \int_{\Omega} [u^m - v^m] |\nabla (u^m - v^m)|^2 \, dx 
\leq \int_{\Omega} [u^m - v^m] (\|\nabla u^m\|^2 + \|\nabla v^m\|^2) \, dx = 0.
$$

Therefore, in both cases, the right hand side of inequality (88) goes to 0 as $n \to \infty$.

At the same time, then,

$$
\lim_{\lambda \to 0} \int_{\Omega} d^{(\alpha-1)/2} (u^m - v^m) \cdot \nabla \phi(u^m - v^m) g'_n(\phi(u^m - v^m)) \, dx 
\leq c \lim_{\lambda \to 0} \int_{\Omega \setminus \Omega_{\Delta_1}} d^{(\alpha-1)/2} (u^m - v^m) \cdot g'_n(\phi(u^m - v^m)) \, dx.
$$

Since

$$
\lim_{\lambda \to 0} \int_{\Omega \setminus \Omega_{\Delta_1}} d^{(\alpha-1)/2} (u^m - v^m) \cdot g'_n(\phi(u^m - v^m)) \, dx \leq \int_{\Omega} d^{\alpha-1} \, dx 
\leq c \int_{\Omega} d^{\alpha-1} \, dx
$$

and by (22)

$$
\lim_{n \to \infty} \int_{\Omega \setminus \Omega_{\Delta_1}} d^{(\alpha-1)/2} (u^m - v^m) \cdot g'_n(\phi(u^m - v^m)) \, dx = 0.
$$

then we have

$$
\lim_{\lambda \to 0} \int_{\Omega} d^{(\alpha-1)/2} (u^m - v^m) \cdot \nabla \phi(u^m - v^m) g'_n(\phi(u^m - v^m)) \, dx = 0.
$$

Clearly,.

$$
\lim_{n \to \infty} \lim_{\lambda \to 0} \int_{\Omega \setminus \Omega_{\Delta_1}} g'_n(\phi(u^m - v^m)) \frac{d}{dt} (u - v) \, dx 
= \frac{d}{dt} \|u - v\|_1.
$$
Now, after letting $\lambda \to 0$, let $n \to \infty$ in (85). Then
\[
\int_{\Omega} |u(x, t) - v(x, t)| \, dx 
\leq \int_{\Omega} |u_0(x) - v_0(x)| \, dx + c \int_{\sigma^*} |u - v| \, d\Sigma
\]
(97)
and
\[
+ c \int_0^t \int_{\Omega} |u(x, t) - v(x, t)| \, dx \, dt.
\]
By Gronwall Lemma, the stability (23) is true. Theorem 5 is proved.

5. The BV Solution of Equation

Recently, Zhan considered the initial-boundary value problem of the following equation in [9]
\[
\frac{\partial u}{\partial t} = \frac{\partial}{\partial x_i} \left(a(u, x, t) \frac{\partial u}{\partial x_i} \right) + \text{div}_3 (b(u)),
\]
(98)
where
\[
u(x, t) = 0, \quad (x, t) \in \partial \Omega \times (0, T),
\]
(100)
and (107). If $a_x \equiv \partial a(u, x, t)/\partial x_i$ and $a_i$ are all bounded, assumption (108) is true; then
\[
\lim_{t \to 0} \int_{\Omega} |u(x, t) - u_0(x)| \, dx = 0.
\]
(104)
The existence of the BV solution of equation (98) is by considering the following regularized problem:
\[
\frac{\partial u}{\partial t} = \frac{\partial}{\partial x_i} \left(a(u, x, t) \frac{\partial u}{\partial x_i} \right) + \epsilon \Delta u + \sum_{i=1}^{N} \frac{\partial b_i (u)}{\partial x_i},
\]
(105)
in $Q_T$, with the initial-boundary conditions
\[
u(x, 0) = u_0(x), \quad x \in \Omega,
\]
(106)
and
\[
u(x, t) = 0, \quad (x, t) \in \partial \Omega \times (0, T).
\]
(107)
If there is a constant $\delta > 0$ such that
\[
a_x \Delta u + \sum_{i=1}^{N} (a_i) \geq 0,
\]
(108)
then we have the following important estimate.

**Theorem 12** (see [9]). Let $u_\epsilon$ be the solution of (105) with (106) and (107). If $a_x \Delta u + \sum_{i=1}^{N} (a_i) \geq 0$, then
\[
\|\nabla u_\epsilon\|_{L^2(\Omega)} \leq c,
\]
(109)
where $|\nabla u|^2 = \sum_{i=1}^{N} |\partial u/\partial x_i|^2 + |\partial u/\partial t|^2$ and $c$ is independent of $\epsilon$.

By the theorem, we can prove the existence of the entropy solution $u \in \text{BV}(Q_T)$ of equation (98) in the sense of Definition II.

**Theorem 13** (see [9]). Suppose that $A(s, x, t) \in C^3$, $b(s) \in C^2$, $u_0(x) \in L^\infty(\Omega) \cap C^2(\Omega)$, and there is a constant $\delta > 0$ such that (108) is true. Then (98) with the initial condition (99) has an entropy solution in the sense of Definition II. Moreover, let $u, v$ be two solutions of (6) with the initial value $u_0(x)$, $v_0(x)$ satisfying (7). Then
\[
\int_{\Omega} |u(x, t) - v(x, t)| \, dx \leq \int_{\Omega} |u_0(x) - v_0(x)| \, dx
\]
(110)
and
\[
+ \int_{\Sigma^*_m} |u - v| \, d\Sigma,
\]
(111)
where $\Sigma^*_m = \partial \Omega \setminus \Sigma_m$, $\Sigma_m = \{x \in \partial \Omega : b'_i(0)n_i(x) < 0\}$, and $|n_i|$ is the inner normal vector of $\Omega$. In particular, if $b(s) \equiv 0$, then $\Sigma^*_m = \partial \Omega$; we have
\[
\int_{\Omega} |u(x, t) - v(x, t)| \, dx \leq \int_{\Omega} |u_0(x) - v_0(x)| \, dx.
\]
If $b_i(s) \equiv 0$, Theorem 13 implies that the solution of (98) is controlled by the initial condition. In other words, no boundary value condition is needed.

Now, let
\[
a(u, x, t) = m d^\alpha u^{m-1}. \tag{112}
\]
Then, for any $0 \leq u \leq M$,
\[
a_t = 0, \quad a_{x_i} = m d^{\alpha - 1} d_{x_i} u^{m-1}, \tag{113}
\]
by the fact that $|\nabla d|^2 = 1$ a.e. in $\Omega$,
\[
a(u, x, t) - \delta \sum_{s=1}^{N+1} (a_{x_i})^2 = m d^\alpha u^{m-1} - \delta m^2 d^\alpha u^{2m-2} \sum_{s=1}^{N+1} = m d^\alpha u^{m-1} (1 - \delta m^\alpha d^{\alpha - 2} u^{m-1}). \tag{114}
\]
If $\alpha \geq 2, m \geq 1$, there exists $\delta$ such that inequality (108) is true. But, in general, the distance function $d$ only is a continuous function and is differential for almost everywhere in $\Omega$; then
\[
a(s, x, t) = m d^\alpha s^{m-1} \tag{115}
\]
does not belong to $C^2$, so we can not have Theorems 12 and 13 directly. However, if we check the proof of Theorems 12 and 13, only if we assume that $\Omega$ is a appropriately smooth such that $d_{x_i}(x)$ is integral on $\partial \Omega$, then similar to the proof of Theorems 12 and 13, we can prove Theorem 4; we omit the details here.

Remark 14. If $\Omega$ is a $C^2$ domain, then $d(x)$ is differential near the boundary $\partial \Omega$, so $d_{x_i}(x)$ is a continuous function on $\partial \Omega$ and is integral on $\partial \Omega$.

Remark 15. If $\alpha \geq 2, m \geq 1$, by Theorem 12, $u \in BV(Q_T)$, we can define the trace of $u$ on the boundary $\partial \Omega$.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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