Research Article
Design and Performance Analysis of MISO-ORM-DCSK System over Rayleigh Fading Channels

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A novel chaotic communicationsystem, named Orthogonality-based Reference Modulated-Differential Chaos Shift Keying (ORM-DCSK), is proposed to enhance the performance of RM-DCSK. By designing an orthogonal chaotic generator (OCG), the intrasignal interference components in RM-DCSK are eliminated. Also, the signal frame format is expanded so the average bit energy is reduced. As a result, the proposed system has less interference in decision variables. Furthermore, to investigate the bit error rate (BER) performance over Rayleigh fading channels, the MISO-ORM-DCSK is studied. The BER expressions of the new system are derived and analyzed over AWGN channel and multipath Rayleigh fading channel. All simulation results not only show that the proposed system can obtain significant improvement but also verify the analysis in theory.

1. Introduction

Chaos based digital communication systems have been proposed and studied in recent years [1–7]. The differential chaos shift keying (DCSK) and its constant power version called frequency-modulated DCSK (FM-DCSK) are widely studied. However, the drawbacks of DCSK or FM-DCSK are low data rate and poor security [1, 2]. In order to address those problems, NR-DCSK, OFDM-DCSK, and short reference DCSK are proposed in [8–10]. Based on the robustness of DCSK against linear and nonlinear channel distortions, Kaddoum et al. studied DCSK for PLC applications. On the other hand, smart antenna technology can eliminate the multipath wave propagation [11]. Therefore, MIMO-DCSK and STBC-DCSK are proposed to improve the performance of DCSK system [12–14]. Furthermore, the reference modulated DCSK (RM-DCSK) is proposed in [15]. In RM-DCSK system, the chaotic signal sent in each time slot not only carries one bit of information but also serves as the reference signal of the information bit transmitted in its following slot. For this reason, the attainable data rate of RM-DCSK is doubled in comparison to DCSK. However, the intrasignal interference is produced in decision variables at the receiver. Therefore, compared to DCSK, BER performance of RM-DCSK is not improved.

In this paper, the ORM-DCSK system is proposed as an improved version for RM-DCSK. A novel orthogonal chaotic generator (OCG) is designed to generate orthogonal chaos signal. Also, the signal frame format is extended. Furthermore, two transmit antennas are used in the transmitter of the ORM-DCSK and BER formula is derived.

The remainder of this paper is organized as follows: in Section 2, the principle of MISO-ORM-DCSK is presented. In Section 3, the BER expressions are analyzed. In Section 4, simulation results are shown to evaluate the performance of the new system. Finally, summaries are given in Section 5.

2. MISO-ORM-DCSK

In this section, the baseband implementation of MISO-ORM-DCSK is introduced and some details are explained.
2.1. Signal Format. Figure 1 shows the frame format of ORM-DCSK system. Different from RM-DCSK, there are $N$ adjacent time slots in each frame, in which average bit energy (labeled as $E_b$) decreases from $1.5\beta E(x_i^2)$ to $(1 + 1/N)\beta E(x_i^2)$. The time slot is divided into $\beta$ chips to carry the chaotic sequences and $b_l$ is the $l$th information bit in $k$th frame. Concretely, $X_k$ is modulated by the information bit $b_l \in \{+1, -1\}$ in the first time slot of $k$th frame. In the second time slot, $b_2b_1X_k$ is sent. In the $N$th time slot, $b_{N-1}\cdots b_1X_k+X_{k+1}$ is sent. Here, $X_{k+1}$ can be converted into the reference sequence of $(k+1)$th frame. In Figure 1, $X_k = (1/\sqrt{M_T}) \cdot [x_k(1), x_k(2), \ldots, x_k(\beta)]$ and $M_T$ is the number of transmit antennas.

2.2. Transmitter Structure. Figure 2 shows the block diagram of orthogonal chaotic generator (OCG). It is necessary to make the chaotic carriers transmitted in neighboring two frames orthogonal to erase the intrasignal interference components included in decision variables clearly. We assume that the spreading factor is six ($\beta = 6$). In the first-time slot period, as shown in Figure 2, the switch is connected to bottom. The chaotic sequence $U = [a, b, c]$ is multiplied by $w_2^{2} = [+1, -1]$. In other words, $X_k = U \cdot w_2^{2} = [a, -a, b, -b, c, -c]$. During second- to $(N-1)$th-slots period, the switch is suspended. In the $N$th-time slot period, the switch is connected to bottom. The chaotic sequence $V = [x, y, z]$ is multiplied by $w_2^{2} = [+1, +1]$. $X_{k+1} = V \cdot w_2^{2} = [x, x, y, y, z, z]$. In the first-time slot period of $(k+1)$th frame, the switch is connected to bottom again. $X_{k+1} = V \cdot w_2^{2} = [x, -x, y, -y, z, -z]$.

The chaotic sequences generated by the OCG satisfy

\[
\begin{align*}
X_k &\perp \bar{X}_{k+1}, \\
\bar{X}_{k+1} &\perp X_{k+1}, \\
X_{k+1} &= \left(\bar{X}_{k+1} W\right), \\
X_{k+1} &\perp (X_k W).
\end{align*}
\]

2.3. Receiver Structure. The receiver structure of ORM-DCSK is depicted in Figure 4, which has similar appearance to RM-DCSK detector. In our receiver, to demodulate $b_l$, we make the switch up. The modification function $W$ is used to adjust the relationship between signal in first bit period of $k$th frame and signal in its former time slot. When decoding $b_l$ ($l = 2, 3, \ldots, N$) of $k$th frame, we make the switch down. Furthermore, the information extraction could work quite well if the receiver knows the starting time of each time slot. As a result, there is a timing synchronization circuit in our receiver, as done in RM-DCSK. To acquire perfect bit synchronization, many traditional timing techniques could be adopted, like data-aided timing synchronization algorithm designed for DCSK [17].
2.4. Channel Model. The channel between each transmit antenna and the receive antenna is two-ray Rayleigh quasi-static block faded channel. \( \xi \) denotes a noise sample following a Gaussian distribution with zero mean and variance \( N_0/2 \). Further, \( \alpha_{m,1} \) and \( \alpha_{m,2} \) denote the gains of the two paths between \( m \)-th \((m = 1, 2) \) transmit antenna and the receive antenna, which are independent, Rayleigh distributed random variables. It is assumed that the channel state remains constant during each bit period.

According to different channel gains, we consider the following two cases:

\[
\begin{align*}
\text{Case 1: } E\left\{ (\alpha_1)^2 \right\} &= E\left\{ (\alpha_2)^2 \right\} = \frac{1}{2}, \\
\text{Case 2: } E\left\{ (\alpha_1)^2 \right\} &= \frac{2}{3}, \\
E\left\{ (\alpha_2)^2 \right\} &= \frac{1}{3}.
\end{align*}
\]

(3)

At the receiver, we denote the received signal vector during the bit duration by \( r_l \) \((l = 1, \ldots, N) \). Then, \( r_l \) can be given by

\[
r_l = \sum_{m=1}^{M_T} \alpha_{m,1} s_{m,l} + \sum_{m=1}^{M_T} \alpha_{m,2} s_{m,l}^* + \xi_l.
\]

(4)

Here, \( s_{m,l} \) \((i = 1, 2) \) is delayed signal transmitted during \( i \)th bit duration and \( \xi_l \) is the additive white Gaussian noise vector.

As described in Figure 1, the chaotic wavelet sent in each time slot not only carries one bit of data but also serves as the reference signal of the data bit transmitted in its next time slot. Then, \( r_{l-1} \) can be denoted as the reference segment for \( r_l \). In this case, the outputs of the demodulators should be given by

\[
\begin{align*}
\bar{c}_1 &= r_1 \cdot r_0 \cdot w, \\
\bar{c}_l &= r_l \cdot r_{l-1} \quad (l = 2, \ldots, N).
\end{align*}
\]

(5)

In (5), \( r_0 \) is signal of last slot time of previews frame. Finally, based on the following rule, the estimated information bit is decided as “+1” or “−1”:

\[
\bar{b}_l = \begin{cases} 
+1, & \bar{c}_l > 0, \\
-1, & \bar{c}_l < 0.
\end{cases}
\]

(6)

3. Performance Analysis

In this section, BER expression is derived over Rayleigh fading channels. Based on Figure 1 and (5), it can be easily found that the statistical properties of \( \bar{c}_l \) \((l = 1, 2, \ldots, N) \) are different. Then, we must calculate the BER performance of each bit, which differs from RM-DCSK.

The logistic map \( x_{n+1} = 1 - 2x_n^2, -1 < x_i < 1, x_j \neq \{0, \pm 0.5\} \), is used with \( E(x_i) = 0 \) and \( E(x_i^2) = 0.5 \). Var \((x_i^2) \) = 0.125, where \( E() \) and \( \text{Var}() \) denote the expectation operator and variance operator, respectively. We can get the average bit energy \( E_b = (1 + 1/N)\beta E(x_i^2) \).

To further simplify the analysis, we can assume that \( \tau_{m,1} = 0, \tau_{m,2} = \tau \), and multipath time delay is much smaller than the spreading factor; that is, \( 0 < \tau \ll \beta \). Thus, (4) can be rewritten as

\[
r_l = \sum_{m=1}^{M_T} \alpha_{m,1} s_{m,l} + \sum_{m=1}^{M_T} \alpha_{m,2} s_{m,l}^* + \xi_l.
\]

(7)

Therefore, without loss of generality, we consider the error rate of the bit \( b_2 \). Substituting (7) into (5) for \( l = 2 \), we can get

\[
\begin{align*}
c_2 &= r_2 \cdot r_1 \\
&= \left[ \frac{1}{\sqrt{M_T}} \left( b_2 b_1 x_k \sum_{m=1}^{M_T} \alpha_{m,1} + b_2 b_1 x_k^* \sum_{m=1}^{M_T} \alpha_{m,2} \right) + \xi_2 \right] \\
&+ \left[ \frac{1}{\sqrt{M_T}} \left( b_2 x_k \sum_{m=1}^{M_T} \alpha_{m,1} + b_2 x_k^* \sum_{m=1}^{M_T} \alpha_{m,2} \right) + \xi_1 \right] \\
&= A + B + \frac{\xi_1 \cdot \xi_2}{C}
\end{align*}
\]

where

\[
\begin{align*}
A &= \left( \frac{1}{M_T} b_2 b_1 x_k \sum_{m=1}^{M_T} \alpha_{m,1} + b_2 b_1 x_k^* \sum_{m=1}^{M_T} \alpha_{m,2} \right), \\
B &= \left( \frac{1}{M_T} b_2 x_k \sum_{m=1}^{M_T} \alpha_{m,1} + b_2 x_k^* \sum_{m=1}^{M_T} \alpha_{m,2} \right),
\end{align*}
\]

(9)

Assuming \( b_2 = 1 \), the instantaneous mean of the decision variable is \( E(c_2) = E(A) + E(B) + E(C) \). Here,

\[
E(A) = \left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 + \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2 \frac{NE_b}{(N+1)M_T},
\]

(10)

\[
E(B) = E(C) = 0.
\]

The variance of decision variable can be easily expressed as \( \text{Var}(c_2) = \text{Var}(A) + \text{Var}(B) + \text{Var}(C) \). Here,

\[
\begin{align*}
\text{Var}(A) &= \beta \left( \frac{\sum_{m=1}^{M_T} \alpha_{m,1}^4 + (\sum_{m=1}^{M_T} \alpha_{m,2})^4}{8M_T^2} \\
&+ \frac{2 \left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2 N^2 E_b^2}{\beta(N+1)^2 M_T^2} \right).
\end{align*}
\]
Based on the above results, the mean and variance of \( c_2 \) are

\[
E (c_2 \mid b_2 = +1) = \left[ \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,1}}{M_r} \right)^2 + \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,2}}{M_r} \right)^2 \right] \frac{NE_b}{(N + 1) M_r}.
\]

Var \( (c_2 \mid b_2 = +1) = \frac{\beta}{8 M_r^2} \left[ \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,1}}{M_r} \right)^4 + \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,2}}{M_r} \right)^4 \right].
\]

Similarly, if \( b_2 = -1 \) is sent, the mean and variance of \( c_2 \) are equal to

\[
E (c_2 \mid b_2 = -1) = -E (c_2 \mid b_2 = +1) \quad \text{Var} (c_2 \mid b_2 = -1) = \text{Var} (c_2 \mid b_2 = +1).
\]

Based on the above results, the BER for decoding \( b_1 \) is computed as

\[
\text{BER}_{c_1} (\gamma_b) = \frac{1}{2} \text{erfc} \left[ \frac{E (c_1 \mid b_2 = +1)}{\sqrt{\text{Var} (c_1 \mid b_2 = +1)}} \right].
\]

Similarly, for \( l \in \{3, 4, \ldots, N - 1\} \) the BER is

\[
\text{BER}_{c_l} (\gamma_b) = \text{BER}_{c_2} (\gamma_b).
\]

For \( l = 1 \), we can get

\[
c_1 = r_1 \cdot r_0 \cdot w = \left[ \frac{1}{\sqrt{M_T}} \left( b_1 X_k \sum_{m=1}^{M_r} \alpha_{m,1} + b_1 X_k^* \sum_{m=1}^{M_r} \alpha_{m,2} \right) + \xi \right] \cdot \left[ \frac{1}{\sqrt{M_T}} \left( b_0 X_{k-1} + \bar{X}_k \right) w \sum_{m=1}^{M_r} \alpha_{m,1} + (b_0 X_{k-1}^* w^* + X_k^* \sum_{m=1}^{M_r} \alpha_{m,2}) + \xi_0 w \right] = D + E + \xi_0 w
\]

where

\[
D = \frac{1}{M_T} \left( b_1 X_k \sum_{m=1}^{M_r} \alpha_{m,1} + b_1 X_k^* \sum_{m=1}^{M_r} \alpha_{m,2} \right)
\]

\[
\cdot \left( b_0 X_{k-1} w + X_k \sum_{m=1}^{M_r} \alpha_{m,1} + (b_0 X_{k-1}^* w^* + X_k^* \sum_{m=1}^{M_r} \alpha_{m,2}) \right)
\]

\[
E = \frac{1}{\sqrt{M_T}} \left( b_1 X_k \sum_{m=1}^{M_r} \alpha_{m,1} + b_1 X_k^* \sum_{m=1}^{M_r} \alpha_{m,2} \right) \xi_0 w
\]

\[
+ \frac{1}{\sqrt{M_T}} \left( b_0 X_{k-1} w + X_k \sum_{m=1}^{M_r} \alpha_{m,1} + (b_0 X_{k-1}^* w^* + X_k^* \sum_{m=1}^{M_r} \alpha_{m,2}) \right) \xi_1.
\]

Similarly, we can get

\[
E (D) = \left[ \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,1}}{M_r} \right)^2 + \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,2}}{M_r} \right)^2 \right] \frac{NE_b}{(N + 1) M_r},
\]

\[
E (E) = E (F) = 0,
\]

\[
\text{Var} (D) = \beta \left[ \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,1}}{M_r} \right)^4 + \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,2}}{M_r} \right)^4 \right]
\]

\[
+ \frac{4 \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,1}}{M_r} \right)^2 \left( \frac{\sum_{m=1}^{M_r} \alpha_{m,2}}{M_r} \right)^2 \left( N^2 E_b^2 \right)}{\beta (N + 1)^2 M_r^2}.
\]
Based on (23)–(24), the BER for decoding $b_1$ is computed as

$$\text{BER}_{b_1}(\gamma_b) = \frac{1}{2} \text{erfc} \left[ \frac{E(c_1 | b_1 = +1)}{\sqrt{\text{Var}(c_1 | b_1 = +1)}} \right]$$

$$= \frac{1}{2} \text{erfc} \left[ \frac{\Lambda_1}{\sqrt{\text{Var}(c_1 | b_1 = +1)}} \right]$$

Here,

$$\Lambda_1 = 1 + \frac{2 \left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2}{\left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 + \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2}.$$  

$$\Lambda_2 = 1 + \frac{6 \left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2}{\left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 + \left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2}.$$  

$$\Gamma = 1 + \frac{1}{N}.$$  

$$\gamma_b = \frac{\left( \sum_{m=1}^{M_T} \alpha_{m,1} \right)^2 E_b}{M_T N_0 \gamma_1} + \frac{\left( \sum_{m=1}^{M_T} \alpha_{m,2} \right)^2 E_b}{M_T N_0 \gamma_2}.$$  

We denote $\gamma_1 = E(\gamma_1)$ and $\gamma_2 = E(\gamma_2)$ to represent the average SNR per path. Moreover, for a multipath Rayleigh fading channel, the PDF of $\gamma_b$ is given by

$$f(\gamma_b) = \frac{e^{-\gamma_b/\gamma_1}}{\gamma_1} - \frac{e^{-\gamma_b/\gamma_2}}{\gamma_2}.$$  

$$E(\alpha_1^2) = E(\alpha_2^2),$$

Based on (14)–(16), the BER is

$$\text{BER}(\gamma_b) = \frac{N - 2}{2N} \text{erfc} \left[ \frac{\Lambda_1}{\beta} + \frac{2 \Gamma}{\gamma_b} + \frac{\beta E_b^2}{2 \gamma_b^2} \right]$$

$$+ \frac{1}{N} \text{erfc} \left[ \frac{\Lambda_2}{\beta} + \frac{3 \Gamma}{\gamma_b} + \frac{\beta E_b^2}{2 \gamma_b^2} \right].$$  

Finally, using (20) and (21), the BER of MISO-ORM-DCSK is derived as

$$\text{BER} = \int_0^\infty \text{BER}(\gamma_b) f(\gamma_b) d\gamma_b.$$  

Moreover, we can get the theoretical lower bound of the BER when $N$ tends to infinity.

$$\text{BER}_{\text{lowerBound}}(\gamma_b) = \lim_{N \to \infty} \text{BER}(\gamma_b)$$

$$= \frac{1}{2} \text{erfc} \left[ \frac{\Lambda_1}{\beta} + \frac{2 \Gamma}{\gamma_b} + \frac{\beta E_b^2}{2 \gamma_b^2} \right].$$  

On the other hand, (28) can be extended to the AWGN channel case by choosing $\alpha_{m,1} = 1$ and $\alpha_{m,2} = 0$. Hence, the BER would simplify to

$$\text{BER} = \frac{N - 2}{2N} \text{erfc} \left[ \frac{1}{\beta} + \frac{3 \Gamma N_0}{E_b} + \frac{\beta E_b^2}{8 E_b^2} \right]$$

$$+ \frac{1}{N} \text{erfc} \left[ \frac{1}{\beta} + \frac{3 \Gamma N_0}{2 E_b} + \frac{\beta E_b^2}{8 E_b^2} \right].$$  

4. Simulation

In order to validate the BER performance of the MISO-ORM-DCSK and compare it with MISO-RM-DCSK, the BER is evaluated under AWGN and multipath fading channels. To facilitate the expression, the Monte Carlo simulations and theory results are labeled as “Sim” and “Theory” respectively.

4.1. AWGN Channel. Since the theoretical BERs for the 2nd to $(N-1)$th bits and the BER for Nth bit are different, Figure 5 shows BERs for $(N-1)$th bit and Nth bit in the AWGN channel of MISO-ORM-DCSK for $\beta = 256$ and $N = 4$. 

4.2. Multipath Rayleigh Fading Channel. 

In a multipath Rayleigh fading channel, the signal strength is affected by the path loss and multipath interference. Therefore, the BER performance is higher than the AWGN channel case. 

4.3. Conclusion 

The theoretical BERs for the MISO-ORM-DCSK and MISO-RM-DCSK are derived and compared. The BER of MISO-ORM-DCSK is lower than that of MISO-RM-DCSK. The theoretical BERs are validated through Monte Carlo simulations. 

4.4. Future Work 

The paper concludes with a discussion on future work, including the extension of the theoretical analysis to more complex channel models and the implementation of the proposed MISO-ORM-DCSK in practical systems.
From Figure 5, it is shown that as $E_b/N_0$ increases, the BERs become better. In addition, the error rate of $c_2$ is superior to that of $c_1$ in the proposed system. This can be explained as follows: the decision variable of $c_1$ has an interference term, which does not exist in that of $c_2$. It is visible that, with less intrasignal interference and noise interference components, MISO-ORM-DCSK is always better than MISO-RM-DCSK.

Figure 6 shows the relationship between BER performance and spreading factor $\beta$. It can also be noticed that ORM-DCSK is always better than RM-DCSK. In addition, it is obvious that the BER can maximize an optimal value by choosing the certain value of spreading factor; for example, the certain value is about 30 and 100 when $E_b/N_0 = 10$ dB and $E_b/N_0 = 15$ dB, respectively. BER starts to degrade if the spreading factor is beyond it, which is caused by fluctuations in $E_b$ at small $\beta$ and the noise-noise cross correlation at large $\beta$.

Figure 7 shows the relationships between analytical BER and Monte Carlo of MISO-ORM-DCSK in the AWGN channel. From Figure 7, it is easily found that clear matching between analytical expression and Monte Carlo simulations result can be obtained. This confirms that the Gaussian approximation works well when the spreading factor is relatively lager.

From Figure 8, it is shown that as $E_b/N_0$ increases, the BERs become better. In addition, the error rate of $c_2$ is superior to that of $c_1$ in the proposed system. This can be explained as follows: the decision variable of $c_1$ has an interference term, which does not exist in that of $c_2$. It is visible that, with less intrasignal interference and noise interference components, MISO-ORM-DCSK is always better than MISO-RM-DCSK.

From Figure 9, it is shown that as $E_b/N_0$ increases, the BERs become better. In addition, the error rate of $c_2$ is superior to that of $c_1$ in the proposed system. This can be explained as follows: the decision variable of $c_1$ has an interference term, which does not exist in that of $c_2$. It is visible that, with less intrasignal interference and noise interference components, MISO-ORM-DCSK is always better than MISO-RM-DCSK.

From Figure 10, it is shown that as $E_b/N_0$ increases, the BERs become better. In addition, the error rate of $c_2$ is superior to that of $c_1$ in the proposed system. This can be explained as follows: the decision variable of $c_1$ has an interference term, which does not exist in that of $c_2$. It is visible that, with less intrasignal interference and noise interference components, MISO-ORM-DCSK is always better than MISO-RM-DCSK.
found that analytical results correspond with simulation results perfectly. This can be explained by identical reason in Figure 7 and the Gaussian approximation works well when the spreading factor is relatively lager. In addition, the BERs for all cases become worse as $\beta$ increases, which can be attributed to the increasing negative contribution from interference components generated from the chaotic sequence and Gaussian noise.

Figure 8: Relationships between BER and $N$ for MISO-ORM-DCSK.

Figure 9: BER performance in Rayleigh fading channel with different gains.

Figure 10: Relationships between analytical BER and Monte Carlo results in Rayleigh fading channel.

5. Conclusion

In this paper, ORM-DCSK is proposed to improve the BER performance of RM-DCSK. The intrasignal interference components existing in RM-DCSK are eliminated clearly by designing an orthogonal chaotic generator. Without any cost in data rate, the proposed system not only shows excellent agreement between theoretical expressions and Monte Carlo simulations but also shows significance of BER improvement.

However, the proposed system is slightly more complex than RM-DCSK due to additional delay and switch. This complexity cost is worthy and it provides a huge BER improvement. We believe that the proposed system has significant potential in chaotic communication environment.

Competing Interests
The authors declare that they have no competing interests.

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