

Research Article

Structural Damage Information Fusion Based on Soft Computing

Haoxiang He, Weiming Yan, and Ailin Zhang

*Beijing Laboratory of Earthquake Engineering and Structural Retrofit,
Beijing University of Technology, Beijing 100124, China*

Correspondence should be addressed to Haoxiang He, hhx7856@163.com

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The significance of information fusion for structural health monitoring and damage detection is introduced. The three levels of information fusion for multisensors are described. For the complex in the structural health monitoring, the distributed multisensor information fusion is more suitable and the structure is discussed. In the damage information fusion for character level, the concept for structural integral support vector machine damage detection matrix, damage self-information, and damage information entropy are presented. For a complex structure, it can be divided into multiple substructures in order to simplify the difficult for health monitoring, the data acquisition and support vector machine are established for each substructure in order to form integral damage detection matrix. In the damage information fusion for decision level, the methods based on fuzzy set theory, material element theory, and fuzzy neural network are proposed. The results given by a numerical example about space structure show that all the methods are valid and effective.

1. Introduction

Civil structures are inevitable to suffer from environmental corrosion, long-term fatigue effects, or natural disasters, and then the damage accumulates during long service period. Therefore, intelligent health monitoring and damage diagnosis for structures become an important technology to study [1]; detecting and predicting the structural damage in time is necessary for future engineering. Detecting structural damage state by its dynamic characteristics, such as frequencies, mode shapes, and frequency-domain transfer function, is an important method. However, the damage detection method based on vibration testing has respective limitation. The research achievement based on soft computing is needed to be introduced to the damage detection and monitoring study.

Structural health monitoring (SHM) is defined as “the use of in-situ, non-destructive sensing and analysis of structural characteristics, including the structural response, for detecting changes that may indicate damage or degradation in the structure.” One essence of a well-designed SHM system

is the ability to provide advance warning to the bridge owners and managers when abnormality is about to occur or is occurring. In general, an SHM system has the potential to provide both damage detection and condition assessment of a structure. A typical SHM system includes three major components: a sensor system, a data processing system (including data acquisition, transmission, and storage), and a health evaluation system (including diagnostic algorithms and information management).

Housner summarized types of sensors used for structural control applications in civil engineering which was similar to SHM in nature [1]. Typically kinematic quantities (e.g., strain, displacement, and acceleration) and environmental quantities (e.g., temperature, humidity, wind, etc.) are the two categories of quantities that are critical to any SHM system. The most common types of sensors used in SHM applications include displacement sensors, strain sensors, vibrating wire sensors, accelerometers, force sensors, and temperature sensors. Numerous research projects and technical reviews have shown that conventional sensors are easily

affected by changes in external factors such as temperature, humidity, cable length, magnetic, or electric fields, and so forth. These factors make it difficult to obtain stable and reliable readings on a long-term basis. These problems are gradually overcome as more advanced sensing technology is developed.

Structural health monitoring (SHM) is a multidisciplinary and integrated technology; hence it is difficult to resolve many practical problems for large and complex structures merely based on vibration testing. Improving the finite element updating technology for health monitoring and state evaluation, combining modern signal analysis technology and soft computing theory, mining structural characteristic data deeply, and realizing the real time, online dynamic monitoring, and control, is the developmental direction for SHM.

The health monitoring, damage detection, and decision problem are very complex for large and complex engineering structure, which need multiclass and multiple sensors to collect different signals simultaneously; thus, a multisensor system is established. Information fusion or data fusion is one of the key technologies of the multisensor system. Information fusion is the merging of information from disparate sources with differing conceptual, contextual, and typographical representations, and it involves the combination of information into a new set of information towards reducing uncertainty. The main objective of employing fusion is to produce a fused result that provides the most detailed and reliable information possible [2]. Fusing multiple information sources together also produces a more efficient representation of the data. Generally, Information fusion aims to take full advantage of different time and space, multisensor information resources, automatically analyze, integrate, control, and use the information under certain criteria to get the consistent describe of the measured object, in order to complete the necessary task on decision-making and estimated.

Information fusion can be performed at three different processing levels which are data level fusion, feature-level fusion, and decision-level fusion according to the stage at which the fusion takes place.

Data level fusion, which is a low level fusion, is the registration and combination of the raw data from multiple-source data into a single data. Feature level information fusion is the extraction, registration, association, and comprehensive analysis on the data which reflect the system characterization, increasing the dimensions to describe the structural status or characteristics before features are merged together; hence, the knowledge about the system status is more accurate or complete. Decision-level fusion combines the results from multiple algorithms to yield a final precise or definite decision according to the prior diagnosis knowledge, the diagnosis sample database and the intelligent decision-making system. In conclusion, the flow chart of the information fusion levels of SHM system is shown in Figure 1.

The structure of the multisensor information fusion system can be divided into two types: centralized structure and distributed structure according to the method for information collection, fusion, and decision. In the centralized

fusion system, the original monitoring data from multisensor is transferred to the fusion center without analysis, and then the data is analyzed by the center and makes a final decision by data combination, filter, and feature extraction according to certain criteria and algorithms. However, in the distributed fusion system, the local decision is made by the decision points from a group of sensors if the performance and precision is ensured. Then the monitor is composed of multisensor and local decision points simultaneously. The various local decisions are transferred to fusion center to make the final decision. The model of distributed parallel structure for fusion system is shown as Figure 2. For the distributed fusion technology, the information from each sensor must be analyzed preliminary and make a local decision, and the final decision is made at a higher level, so the amount of transmission data is less and the requirements of the transmission network is relaxed and the processing speed of the fusion center is higher for the distributed multisensor information fusion system. For SHM system, the sensors layout and wiring is complex, the amount of data is large, thus the centralized fusion system is not suitable. Hence, the distributed multisensor information fusion structure is adopted and mainly studied in this paper.

In many cases, the sources of structural health information are sensors or other devices that allow for perception or measurement of changing environment [3–5]. The current technology and method on multisensor information fusion is numerous, but the information fusion algorithms in SHM can be classified into three different groups. First, fusion based on probabilistic models, second, fusion based on least-squares techniques, and, third, intelligent fusion.

The probabilistic model methods are Bayesian reasoning, evidence theory, robust statistics, and recursive operators [6–9]. There has been a substantial amount of research work conducted in the area of decision fusion, most of which is built around Bayes theory. The basic strategy is that if the prior probabilities and conditional probabilities are determined in advance, then the posteriori probabilities (and hence optimal decisions) can be estimated using Bayes formula. A Bayesian network is used to combine probabilistic reasoning with time-dependent parameters. As an extension to Bayes theory, the Dempster-Shafer evidence theory uses belief and plausibility functions to quantify evidence and uncertainty. Dempster-Shafer evidence theory models how the uncertainty of a given hypothesis or discourse diminishes as pieces of evidence accumulate during the reasoning process. One important aspect of this theory is that reasoning or decision making can be carried out with incomplete or conflicting pieces of evidence.

The least-squares techniques are Kalman filtering, optimal theory, regularization, and uncertainty ellipsoids. The method that is the most widely used or data fusion in engineering applications is the Kalman filters [10]. This filter is often used to combine all measurement data (e.g., for fusing data from different sensors) to get an optimal estimate in a statistical sense, if the system can be described with a linear model and both the system error and the sensor error can be modeled as Gaussian noise, then the Kalman filter will provide a unique statistically optimal estimate for the

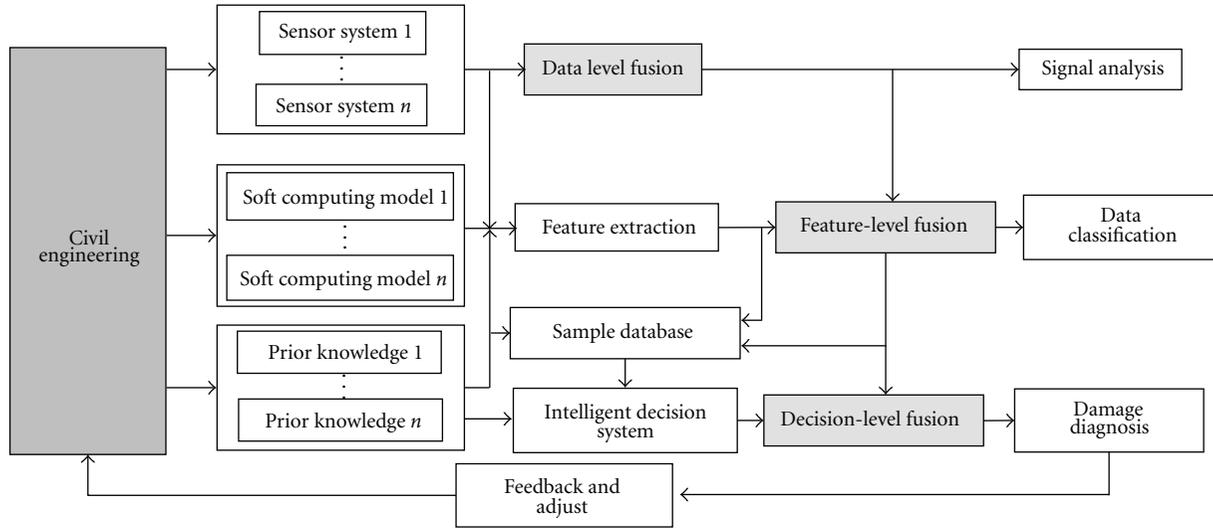


FIGURE 1: Flow chart of information fusion levels of SHM system.

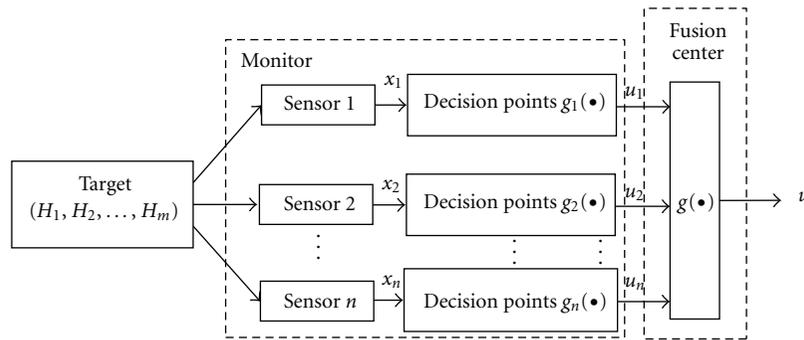


FIGURE 2: Model of distributed fusion structure.

fused data. This means that under certain conditions the Kalman filter is able to find the best estimates based on the “correctness” of each individual measurement.

The intelligent fusion methods are fuzzy logic, neural networks and genetic algorithms. D-S evidence theory is efficient method processing uncertain information in data fusion, but the combination result may be unacceptable if the evidences highly conflict with each other. In the presented work, a modified combination rule of D-S theory is proposed to solve the problem of evidences with conflict, which is related evidence focus to the amount of useful information of evidences. Fuzzy logic provides a new tool to solve the uncertain problem and describe the fuzzy characteristics of target. Especially, fuzzy logic is fit for describing and processing the uncertain information from multiple sensors [11]. An artificial neural network (ANN) is a massively parallel distributed processor that can be used to model highly complex and nonlinear stochastic problems. The ANN is formed of smaller units called neurons and is trained through a learning process, while interneuron connection strengths, known as synaptic weights, are used to store the knowledge. So part of data fusion could be realized by neural networks when the multiple data is inputted [12–14].

In recent years, the methods such as the fuzzy logic system, artificial neural networks, and other soft computing methods develop rapidly, which provides a solid theoretical basis for information intelligence fusion. In this paper, the support vector machine method, the fuzzy sets, the artificial neural network and the matter-element theory are introduced and used, combined with some of the concepts of information theory, and multilevel information fusion for the structural damage diagnosis is studied.

2. Feature-Level Fusion for Damage Information Based on Soft Computing Method

2.1. Damage Diagnosis Matrix. Traditional modal analysis technique for structural damage identification is often difficult to obtain satisfactory results for large complex structures. The intelligent methods such as support vector machine (SVM) can effectively improve the accuracy of structural damage identification [15]. The original structure can be divided into multiple substructures, and then the detail damage can be identified using support vector machine (SVM) for each substructure [16]. If the number of the

components in the substructure is still large, the feature-level fusion for damage information can be carried out by the making full use of the multiple sensors placed on the substructure.

For example, a space structure is divided into multiple substructures according to the specific forms, then the signals from each substructure are collected and the support vector machine is trained and established. Thus, an integrated damage diagnosis matrix having n substructures and sensors based SVM is as follows:

$$\text{SDM} = \begin{bmatrix} S_{11} & S_{12} & \dots & S_{1n} \\ S_{21} & S_{22} & \dots & S_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ S_{n1} & S_{n2} & \dots & S_{nn} \end{bmatrix}, \quad (1)$$

where the elements S_{ij} on the i th row and the j th column mean the analysis result from the SVM for the j sensor in the i monitoring region, reflecting the diagnosis information on damage degree and location for structural components. When the signals from the sensors in each substructure are used only to diagnose the damage in its own region, the SDM has the simplest form as a diagonal matrix. In this case, there is no effective fusion for each signal. The corresponding nondiagonal elements will increase in the SDM if the signals from the sensors in different regions are fused and combined. Limited to the number of sensors, the SDM with information fusion function cannot be full matrix or symmetric matrix.

2.2. Self-Information and Damage Information Entropy.

Information is any kind of event that affects the state of a dynamic system. Conceptually, information is the message (utterance or expression) being conveyed. For structural health monitoring, the information refers to the changes in health status under the influence of the external environment.

In information theory, entropy is a measure of the uncertainty associated with a random variable, which quantifies the expected value of the information contained in a message [17]. Equivalently, the Shannon entropy is a measure of the average information content one is missing when one does not know the value of the random variable. Shannon's entropy represents an absolute limit on the best possible lossless compression of any communication, under certain constraints: treating messages to be encoded as a sequence of independent and identically distributed random variables.

Named after Boltzmann's H -theorem, Shannon denoted the entropy H of a random variable X and probability uncton $p(X)$ as

$$H(X) = - \int p(x) \log p(x) dx, \quad (2)$$

The possible damage status in large structure is random and various, only when the signals collected by the sensors are analyzed by the health monitoring system, the uncertainty about the structural damage is eliminated and the damage information is obtained. In this paper, a concept of structural damage self-information and damage information entropy is

presented based on the Shannon information theory. In the damage prediction set, if the event number is x , the damage self-information of the component is defined as

$$I_{(x)} = -\log p(x) = -\log \left(\frac{1}{m} \sum_{l=1}^m S_l(x) \right), \quad (3)$$

where the $p(x)$ is the predict-damage probability for the component x , $S_l(x)$ is the predict value for the component x in the integrated damage diagnosis matrix SDM, if damage occurs, the value is 1, otherwise the value is 0, and m is the number of sensors which participate in predicting damage for component x .

The damage information entropy for component x is defined as the weighted average value of the self-information:

$$H(X_i) = CE_{p(x)}[I(x)] = -\frac{1}{m} \sum_{l=1}^m c_l p(x) \log p(x), \quad (4)$$

where C is the weight coefficient, the discrete value c_l can be obtained from 0 to 1 according to the location of the sensors and monitoring accuracy, and m is the number of sensors which participate in predicting damage for component x . The damage self-information represents the damage uncertainty for the corresponding component, and the damage probability is larger and the total information demand is lower if the self-information value is smaller. The damage information entropy is weighted average uncertainty from information source. The information fusion based on the intelligent damage diagnosis matrix can reduce the damage information entropy, and identify the location and degree of structural damage.

3. Decision-Level Fusion for Damage Information Based on Fuzzy Set

3.1. Damage Information Fusion Model Based on Fuzzy Set.

In many practical cases, the structural damage is a fuzzy and vague state because there are no obvious and clear grading marks in the actual health status. Thus, it is more scientific and objective for structural damage according to fuzzy set theory by introducing the concept of fuzzy subset and fuzzy membership. In classical set theory, the membership of elements in a set is assessed in binary terms according to a bivalent condition—an element either belongs or does not belong to the set. By contrast, fuzzy set theory permits the gradual assessment of the membership of elements in a set; this is described with the aid of a membership function valued in the real unit interval $[0, 1]$. Fuzzy sets generalize classical sets, since the indicator functions of classical sets are special cases of the membership functions of fuzzy sets, if the latter only take values 0 or 1. The fuzzy decision fusion method is realize the integration fusion by using fuzzy transform principle and maximum membership principle and considering the various factors relevant to the evaluation objects. In the fusion process, the factors constitute the factor set as $U = \{U_1, U_2, \dots, U_m\}$ according to different extent, and the decision is expressed as the decision set as $V = \{V_1, V_2, \dots, V_n\}$.

First, the sing factor decision is made for the single factor u_i ($i = 1, 2, \dots, m$) in the factor set U , then the membership degree r_{ij} in the decision degree v_j ($j = 1, 2, \dots, n$) is determined according to u_i . Thus, the sing factor decision set for the factor u_i is obtained as $r_i = \{r_{i1}, r_{i2}, \dots, r_{in}\}$, which is the fuzzy subset of the decision set. Hence, considering all the m factors, the general fuzzy decision matrix is constructed as

$$R = \begin{bmatrix} r_1 \\ \vdots \\ r_m \end{bmatrix} = \begin{bmatrix} r_{11} & \dots & r_{1n} \\ \vdots & \ddots & \vdots \\ r_{m1} & \dots & r_{mn} \end{bmatrix} \quad (5)$$

R is the fuzzy relationship between factor domain and decision domain, and r_{ij} is the membership degree. Multi-factor decision should consider the weighted grade for each factor in the fusion process, and the fuzzy subset $A = \{a_1, a_2, \dots, a_m\}$ is the weighted set in factor domain U , where a_i ($a \leq a_i \leq 1$) is the weight value of the single factor u_i in the total decision. When A and R is determined, the fusion is carried out by fuzzy transformation $B = A \circ R$, and B is equivalent fuzzy subset in the evaluation set V , the element b_j ($j = 1, 2, \dots, n$) is the fusion result for grade v_j , and \circ is the fuzzy synthesis operator.

3.2. Damage Information Fusion Based on Fuzzy Set. Considering the various damage factors of the key components, the damage decision in the structural health monitoring should use one or multilevel fuzzy fusion. According to the precision and accuracy of all kinds of sensor, the factor fuzzy vector can be determined by the expert experience or analytic hierarchy process, and the membership function is Gaussian model.

Taking a space structure as an example, the change of deflection and the change of strain, predicts damage values by SVM and modal curvature rate is the main parameters accurately reflect the structural damage information and these are easy to collect. Therefore, these parameters of the key components are monitored. The structural health status is divided into 4 grades: intact, minor damage, moderate damage, and severe damage. The evaluation and grade index are shown in Table 1.

After the fuzzy damage subset is determined, the membership value for the specific damage status in each damage grade can be calculated. In order to meet the requirements of project design, the quantitative description of damage degree is needed. To highlight the dominance hierarchy, the comprehensive damage index for decision making is suggested as

$$\text{GFD} = \frac{\sum_{i=1}^4 b_i^k Da_i}{\sum_{i=1}^4 b_i^k}, \quad (6)$$

where b_i is the membership value of the i -level damage and Da_i is the median value in the i -level damage. K is the comprehensive adjustment index, and it is recommended that k is taken as 2.

4. Decision-Level Fusion for Damage Information Based on Matter-Element Model

The matter-element analysis theory was put forward by Cai Wen to solve the incompatible problems in the 1980s [18]. The theoretical system had been established from the initial matter-element analysis to extension engineering theory. The basic content of matter-element analysis is as follows. Firstly, define the class intervals of each evaluation indicator. Then, calculate the single index correlation degree to determine the damage status by single indicator. Finally, the comprehensive damage grades of all indicators are gained by model integration. Therefore, the evaluation results of matter-element analysis are more reasonable and accurate than other methods.

A given thing is named N , whose characteristic C is valued X . The orderly ternary group $R = (N, C, X)$ is the basic element for describing things, which is named matter-element for short. One thing has a number of characteristics. If thing N has n characteristics C_1, C_2, \dots, C_n and the corresponding values are X_1, X_2, \dots, X_n , the matter-element can be expressed as the following:

$$R = \begin{bmatrix} N & C_1 & X_1 \\ & C_2 & X_2 \\ & \vdots & \vdots \\ & C_n & X_n \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \\ \vdots \\ R_n \end{bmatrix}. \quad (7)$$

If the thing has m levels with $N_{01}, N_{02}, \dots, N_{0m}$, the matter-element R_{0j} is

$$R_{0j} = (N_{0j}, C_i, X_{0ji}) = \begin{bmatrix} N_{0j} & C_1 & X_{0j1} \\ & C_2 & X_{0j2} \\ & \vdots & \vdots \\ & C_n & X_{0jn} \end{bmatrix} = \begin{bmatrix} N_{0j} & C_1 & \langle a_{0j1}, b_{0j1} \rangle \\ & C_2 & \langle a_{0j2}, b_{0j2} \rangle \\ & \vdots & \vdots \\ & C_n & \langle a_{0jn}, b_{0jn} \rangle \end{bmatrix}, \quad (8)$$

where N_{0j} is the j th elevation level ($j = 1, 2, \dots, m$); c_i is the i th evaluation indicator; X_{0ji} is the j th-level value range of c_i , that is, the classical domain. The range of X_{0ji} is interval $\langle a_{0ji}, b_{0ji} \rangle$, which can be recorded as $X_{0ji} = \langle a_{0ji}, b_{0ji} \rangle$, $i = 1, 2, \dots, n$.

According to the classical domain, the section domain (R_p) is

$$R_p = (P, C_i, X_{pi}) = \begin{bmatrix} P & C_1 & X_{p1} \\ & C_2 & X_{p2} \\ & \vdots & \vdots \\ & C_n & X_{pn} \end{bmatrix} = \begin{bmatrix} P & C_1 & \langle a_{p1}, b_{p1} \rangle \\ & C_2 & \langle a_{p2}, b_{p2} \rangle \\ & \vdots & \vdots \\ & C_n & \langle a_{pn}, b_{pn} \rangle \end{bmatrix}, \quad (9)$$

TABLE 1: Grade index for structural damage state.

Parameter	N1 (intact)	N2 (minor damage)	N3 (moderate damage)	N4 (severe damage)
Change of deflection (mm)	a1-a2	a2-a3	a3-a4	a4-a5
Change of strain (ε)	b1-b2	b2-b3	b3-b4	b4-b5
Predict damage values by SVM	c1-c2	c2-c3	c3-c4	c4-c5
Modal curvature rate	d1-d2	d2-d3	d3-d4	d4-d5

where P is the whole evaluation levels, and the X_{pi} is the value range of C_i . All that is the P section domain, which can be recorded as $X_{pi} = \langle a_{pi}, b_{pi} \rangle$, $i = 1, 2, \dots, n$. Obviously, X_{0ji} belongs to X_{pi} .

The matter-element of evaluation object can be expressed as:

$$R_0 = (P_0, C_i, V_i) = \begin{bmatrix} P_0 & C_1 & V_1 \\ & C_2 & V_2 \\ & \vdots & \vdots \\ & C_n & V_n \end{bmatrix}. \quad (10)$$

The equation is called evaluation matter-element of P_0 . V_i is the specific value of indicator C_i of the evaluation object.

The correlation degree ($K_j(v_i)$) between evaluation index and evaluation level is calculated based the classical domain and section domain:

$$K_j(v_i) = \begin{cases} \frac{-\rho(v_i, X_{0ji})}{|X_{0ji}|}, & (v_i \in X_{0ji}) \\ \frac{\rho(v_i, X_{0ji})}{\rho(v_i, X_{pi}) - \rho(v_i, X_{0ji})}, & (v_i \notin X_{0ji}), \end{cases} \quad (11)$$

where $\rho(v_i, X_{0ji}) = |v_i - 0.5(a_{0ji} + b_{0ji})| - 0.5(b_{0ji} - a_{0ji})$; $|X_{0ji}| = |a_{0ji} - b_{0ji}|$, ($i = 1, 2, \dots, n$; $j = 1, 2, \dots, m$), $\rho(v_i, X_{pi}) = |v_i - 0.5(a_{pi} + b_{pi})| - 0.5(b_{pi} - a_{pi})$. $\rho(v_i, X_{0ji})$, $\rho(v_i, X_{pi})$ are, respectively, the distances between v_i and classical domain X_{0ji} and section domain X_{pi} . In fact, correlation degree $K_j(v_i)$ expresses the ownership between index and the level j , which equals to the subjection degree in fuzzy sets of Fuzzy theory. The value range of subjection degree in fuzzy math is the closed interval $[0, 1]$, but the one of correlation degree is the entire range of real axis. If $K_j(v_i) = \max K_j(v_i)$, $j \in (1, 2, \dots, m)$, the evaluation indicator v_i belongs to level j .

The correlation degree ($K_j(P_0)$) of evaluation object and its corresponding grade can be calculated by

$$K_j(P_0) = \sum_{i=1}^n a_i K_j(v_i), \quad (12)$$

where a_i is the weight of the corresponding index c_i , and $\sum a_i = 1$. $K_j(P_0)$ is the combined value of the correlation degree when considering the importance of indexes, and it expresses the correlation degree between evaluation object P_0 and its corresponding grade j . If $K_j(P_0) = \max K_j(P_0)$, $j \in (1, 2, \dots, m)$, P_0 belongs to level j .

The value of the correlation degree in the real axis expresses the subjection degree between the evaluated object and a certain grade. The logic value of the correlation degree in matter-element model is in the real axis $(-\infty, +\infty)$ rather than the closed interval $[0, 1]$ in Fuzzy Math. Thus, it has more abundant connotation than that in Fuzzy Math and it can reveal more variant information. If $K_j(P_0) > 0$, the evaluation object is in line with the requirements of a certain grade standard, and the degree of the accordance increases with its value. If $-1 < K_j(P_0) < 0$, the evaluation object is not in line with the requirements of a certain grade standard, but it has the condition to transform into that grade, and its greater value makes it easier to transform. If $K_j(P_0) < -1$, the evaluation object is not in line with the requirements of a certain grade standard, but it does not have the condition to transform into that grade, and its smaller value indicates the bigger gap between evaluated object and evaluation criteria.

Compared with the analysis with fuzzy decision-making methods, the thinking, concept of the matter-element method, is the same. However, the matter-element analysis theory for structural damage information fusion concept is clear, and the selection of the correlation function is more flexibility.

5. Decision-Level Fusion Based on Fuzzy Neural Network Damage Information

A fuzzy neural network (FNN) is a learning machine that finds the parameters of fuzzy sets, by exploiting approximation techniques from neural networks. The FNN model makes use of two artificial intelligent (AI) techniques: fuzzy logic and artificial neural network (ANN). Both neural networks and fuzzy systems have some characteristics in common. They can be used for solving a problem if there does not exist any mathematical model of the given problem. Neural networks can only work if the problem is expressed by a sufficient amount of observed examples. These observations are used to train the black box. On the one hand no prior knowledge about the problem needs to be given. On the other hand, however, it is not straightforward to extract comprehensible rules from the neural network's structure. On the contrary, a fuzzy system demands linguistic rules instead of learning examples as prior knowledge. Furthermore the input and output variables have to be described linguistically. If the knowledge is incomplete, wrong or contradictory, then the fuzzy system must be modified. Since there is not any formal approach for it, the modification is performed in a heuristic way. This is usually very time consuming and error-prone.

Compared to a common neural network, connection weights and propagation and activation functions of fuzzy neural networks differ a lot. The integrated system, called FNN, will possess the advantages of both ANN system and fuzzy system. On the neural side, more and more transparency is pursued and obtained either by restructuring an ANN to improve its performance or by a possible interpretation of the weight matrix following the learning stage. On the fuzzy side, the development of methods allowing automatic tuning of the parameters with the data collected from real-life examples decrease the subjectivity of the fuzzy system. Thus, ANN system can improve its transparency, making it closer to fuzzy logic system, while fuzzy logic system can self-adapt, making it closer to ANN system.

In this paper, a typical five-layer FNN structure is chosen for the markup estimation. It consists of an input layer with identified input factors, a fuzzy layer with membership functions, a rule layer with the collected rules for markup estimation, a back propagation (BP) hidden layer and an output layer with one node which is the estimated markup percentage. The function and calculation process of each layer is discussed below:

- (1) layer 1 reads real number input variables X_i ($i = 1, 2, \dots, n$), the evaluated value of each identified influencing factor for markup estimation,
- (2) layer 2 fuzzifies X_i according to the membership functions. Every input value X_i has m membership degree $\mu_{A_i^j}(X_i)$ ($j = 1, 2, \dots, m$), which represent the characteristic of the influencing factor:

$$\mu_{A_i^j}(X_i) = f(a_i^j, b_i^j), \quad (13)$$

where $\mu_{A_i^j}$ is the membership degree of X_i , $f(a_i^j, b_i^j)$ is the membership function, a_i^j and b_i^j are the parameters of the membership function,

- (3) layer 3 calculates μ_j , the active degree of the j th rule according to the relevant fuzzy inference rules collected for markup estimation:

$$\mu_j = \mu_{A_1^j}(X_1)\mu_{A_2^j}(X_2)\dots\mu_{A_n^j}(X_n), \quad (14)$$

- (4) layer 4 is a hidden layer using normal BP rules in ANN, the mapping between the fuzzy input and the fuzzy output is established, and
- (5) layer 5 defuzzifies the final output M of such a neural fuzzy system with centroid defuzzification equation as follows:

$$M = \frac{\sum_{j=1}^M \mu_j w_j}{\sum_{j=1}^M \mu_j}, \quad (15)$$

where w_j is the markup percentage from the j th rule, M is the final estimated markup percentage.

The parameters that need to be tuned are $\mu_{A_i^j}(X_i)$ of the input membership functions and the real numbers w_j from

the consequent part of the inference rules. Assume that M_d is the desired output of the FNN system. The objective function to be minimized is defined by

$$E = \frac{1}{2}(M - M_d)^2, \quad (16)$$

where E is the mean square error between the actual output and the desired output, M is the actual output and M_d is the desired output.

The back propagation (BP) learning rule, which is usually used in ANN training process, is adopted as a training method of the FNN system. The parameter learning algorithm for the above fuzzy logic rules are derived and shown below:

$$\frac{\partial E}{\partial a_i^j} = \frac{\mu_j(X)}{\sum_{j=1}^M \mu_j(X)} (M - M_d) \frac{w_j - M}{\mu_{A_i^j}(X_i)} \frac{\partial \mu_{A_i^j}(X_i)}{\partial a_i^j}, \quad (17)$$

$$\frac{\partial E}{\partial b_i^j} = \frac{\mu_j(X)}{\sum_{j=1}^M \mu_j(X)} (M - M_d) \frac{w_j - M}{\mu_{A_i^j}(X_i)} \frac{\partial \mu_{A_i^j}(X_i)}{\partial b_i^j}, \quad (18)$$

$$\frac{\partial E}{\partial w_j} = \frac{\mu_j(X)}{\sum_{j=1}^M \mu_j(X)} (M - M_d). \quad (19)$$

Based on above equations, the parameters a_i^j , b_i^j , and w_j could be adjusted in the following seven steps [16].

Step 1. The fuzzy logic rules for markup estimation are collected and the input factors and the parameters of the membership functions are identified.

Step 2. The input-output training data (X_1, \dots, X_n, M_d) are input and the membership degree of each input variable is calculated according to the defined membership functions.

Step 3. Fuzzy reasoning is performed for the input data (X_1, \dots, X_n) . The membership value of μ_j of each inference rule and the output of fuzzy reasoning Y are then calculated.

Step 4. Tuning of the real number w_j of the consequent part is performed by using (19).

Step 5. The fuzzy reasoning conducted in Step 3 is repeated.

Step 6. Tuning of the parameters a_i^j and b_i^j is done by substituting the tuned real number w_j obtained in Step 4, the output M , the membership value μ_j , and output data M_d into (17) and (18).

Step 7. The objective function (or the inference error) (16) is calculated, and Step 3 through Step 6 are repeated until its change $\Delta E = E(t) - E(t - 1)$ is less than a desired threshold value.

6. Simulation Example

The damage detection and damage data fusion of a single-layer spherical lattice dome is studied in order to validate the information fusion methods in this paper. The diameter of

TABLE 2: Grade index for element 105 damage state.

Parameter	N1 (intact)	N2 (minor damage)	N3 (moderate damage)	N4 (severe damage)
Change of deflection (mm)	0–3	3–8	8–15	15–30
Change of strain (ϵ)	0–0.001	0.001–0.003	0.003–0.008	0.008–0.02
Predict damage values by SVM	0–0.05	0.05–0.1	0.1–0.5	0.5–1
Modal curvature rate	0–0.1	0.1–0.25	0.25–0.6	0.6–1

the lamella dome is 30 meters, and the height is 15 meters. The material is seamless steel pipe. The external diameter of the circumferential pipes is 0.18 meter and the thickness is 0.005 meter. The external diameter of the radial pipes and the oblique pipes is 0.2 meter, and the thickness is 0.006 meter. The supports are all fixed hinges. The dead load is 200 Kg/m². The dome is divided into four regions by its symmetry, which is showed in Figure 3. Five vertical acceleration sensors adapting signal amplifier at the terminal are located at the top center and the middle joints in each region, and the locations are showed by hollow circles in Figure 3.

The four regions are considered independent, but the sensor in each region has the sensibility to the damage not only in its own region but also to the regions, and the total support vector machines damage diagnosis matrix SDM has the following form:

$$\text{SDM} = \begin{bmatrix} S_{11} & S_{12} & S_{13} & S_{14} \\ 0 & S_{22} & 0 & 0 \\ 0 & 0 & S_{33} & 0 \\ 0 & 0 & 0 & S_{44} \end{bmatrix}. \quad (20)$$

The finite element program ANSYS is used for structural damage simulation under ambient vibration. The vibration is simulated by discrete white noise in three orthogonal directions, and the acceleration amplitude at the supports is 2×10^{-3} m/s². The sampling interval is 0.05 second and the duration is 200 seconds. The elements' damages are simulated by the descendent of Young's modulus in some key elements and the damage ratios is 50%, the model is simulated under five group of ambient vibration waves, respectively. The damage element number is 29, 105, 126, 32, and 91, as shown in Figure 3. Wavelet packet decomposition is applied to the structural response signals under ambient vibration, and feature vectors are obtained by feature extraction method with energy-damage state in [16]. Four group of feature vectors are used for training and classification as the inputs of the tighten support vector machine. For each S_{ij} in SDM, the SVM method is used to a single-layer dome for damage diagnosis. The structural damage location and degree can be detected and classified. For example, when the element 105 damaged, the diagnosis matrix SDM is as follows:

$$\text{SDM} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0.5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}. \quad (21)$$

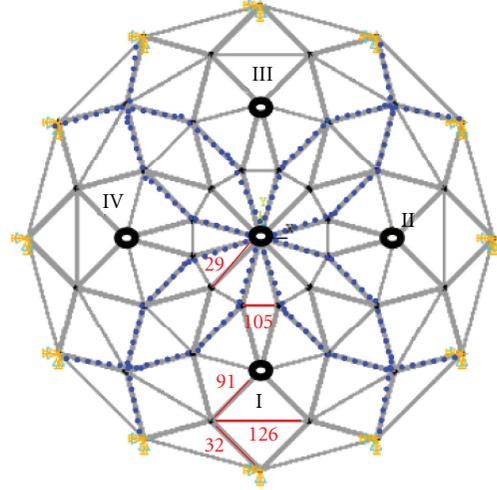


FIGURE 3: The of layout graph of the spherical lattice shell and the numbering and zones.

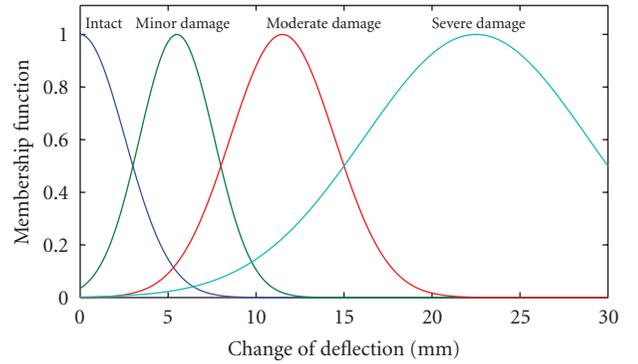


FIGURE 4: Membership grade of the change of deflection.

Therefore, the predicted damage probability of element 105 is $p(x) = 0.75$, the damage self-information is 0.125, and the damage entropy is 0.031. The damage in element 105 is likely to be 50%. Hence, it is clear that the damage self-information and entropy can accurately indicate the damage information in element 105. The similar results can be obtained for other damaged element. Considering the mechanical properties and usage of element 105, the grade index about damage state is listed in Table 2.

TABLE 3: Normal output of FNN for different damage grade.

Parameter	N1 (intact)	N2 (minor damage)	N3 (moderate damage)	N4 (severe damage)
Fuzzy normal output	0–0.1	0.1–0.3	0.3–0.6	0.6–1

Consider the importance and calculation accuracy of the grade index about damage state in the factor domain, the weight value matrix of the change of deflection, the change of strain, predict damage values by SVM and modal curvature rate is $A = [0.2, 0.25, 0.4, 0.15]$. The real simulation result of element 105 is $[9.17 \text{ mm}, 0.0018, 0.5, 0.38]$. Damage information fusion based on fuzzy set is carried out for element 105, the membership function is established according to the method previously described and specified index in Table 2. For example, the membership function of the change of deflection is shown in Figure 4.

The fuzzy relation matrix is calculated according to (5) and combined with the weight value matrix, the fuzzy damage vector is

$$B = A \circ R = [0.2, 0.25, 0.4, 0.15]$$

$$\times \begin{bmatrix} 0.002 & 0.225 & 0.735 & 0.112 \\ 0.110 & 0.967 & 0.209 & 0.057 \\ 0 & 0 & 0.5 & 0.5 \\ 0 & 0 & 0.955 & 0.191 \end{bmatrix} \quad (22)$$

$$= [0.028, 0.246, 0.549, 0.265].$$

It can be seen from the fuzzy damage vector B that the maximum membership value belongs to the moderate damage, so the medium damage is judged to occur, which is consistent with the actual situation. According to (6), the comprehensive damage index for decision making is 0.541, thus the damage state of element 105 is accurately quantified.

According to Table 2, the grade index range for element in various damage degrees is the domain of classical matter-element:

$$R_{01} = \begin{bmatrix} \text{intact} & \text{change of deflection} & \langle 0, 3 \rangle \\ & \text{change of strain} & \langle 0, 0.001 \rangle \\ & \text{SVM value} & \langle 0, 0.05 \rangle \\ & \text{model curvature rate} & \langle 0, 0.1 \rangle \end{bmatrix} \cdots R_{05}$$

$$= \begin{bmatrix} \text{severe damage} & \text{change of deflection} & \langle 15, 30 \rangle \\ & \text{change of strain} & \langle 0.008, 0.02 \rangle \\ & \text{SVM value} & \langle 0.5, 1 \rangle \\ & \text{model curvature rate} & \langle 0.6, 1 \rangle \end{bmatrix} \quad (23)$$

Referring to Table 2, the correlation degree is calculated according to (11) and (12), and the results are shown in Figure 5. The value for moderate damage is the maximum, so the element is judged as a medium damage, and the conclusion is as same as the final result from fuzzy fusion decision.

Damage simulation is carried out for element 105, and 2 of training samples are simulated for each damage grade in Table 1, and the normal output of FNN for different damage grades is listed in Table 3. A four inputs and one output fuzzy

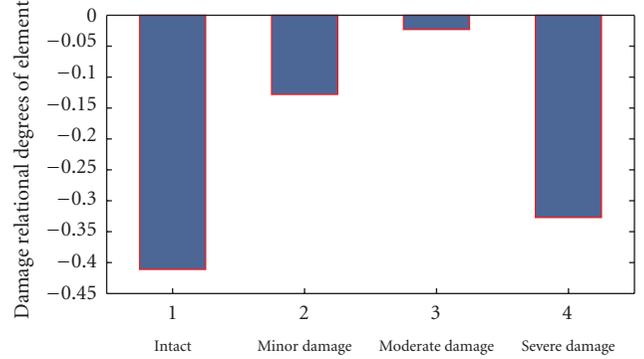


FIGURE 5: Damage relational degrees of element by matter-element method.

neural network is established based on the training samples, in which there are four Gaussian membership functions for each input, the network topology of the FNN model is shown in Figure 6. All the 80 samples are input to the neural network is trained to generate the fuzzy neural network. On the other hand, another new 30 test samples, which include the actual damage vector $[9.17, 0.0018, 0.5, 0.38]$, are used as the input to verify the accuracy. The Root-mean-square error during training and test is shown in Figure 7 and the membership grade of deflection variation after training by FNN is shown as Figure 8. The output curve is shown as Figure 9, and the output is 0.520, belong to the medium damage range. It shows that fuzzy neural network also apply to structural damage information fusion and has certain reasoning prediction function.

7. Conclusion

Structural health monitoring is a multidisciplinary and integrated technology, especially applied in complex civil engineering. For a SHM system, various types and large number sensors are used, since the damage and status change is hard to be detected only by one type of sensor and few method, the damage information fusion is a critical need for SHM system. The damage information fusion includes data level fusion, feature-level fusion and decision-level fusion. The data level fusion is solved by the statistic method, signal filter technology and other preliminary method. For feature-level fusion, the integrated damage diagnosis matrix is presented and the concept of damage self-information and damage information entropy is defined, and the information for different sensors belong to the same type is integrated to detect the damage degree for one target or component. For decision-level fusion, three methods based on fuzzy set theory, matter-element theory and fuzzy neural network,

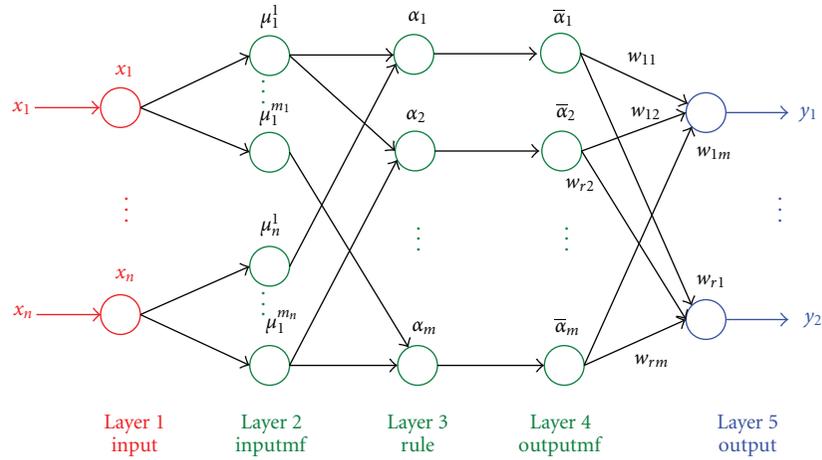


FIGURE 6: The network topology of the FNN model.

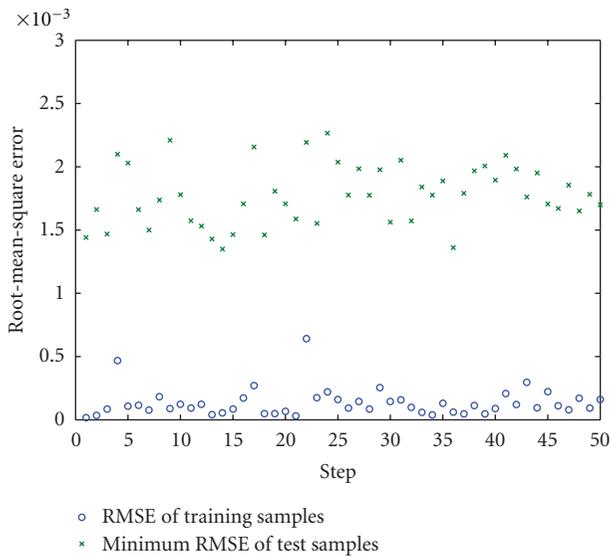


FIGURE 7: Root-mean-square error during training and test.

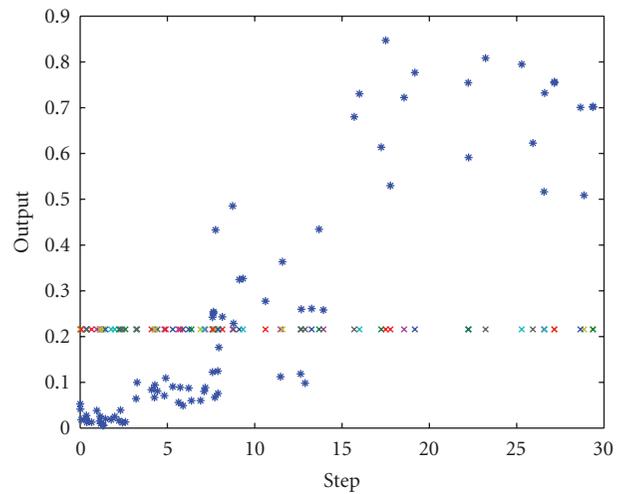


FIGURE 9: Output curve of FNN.

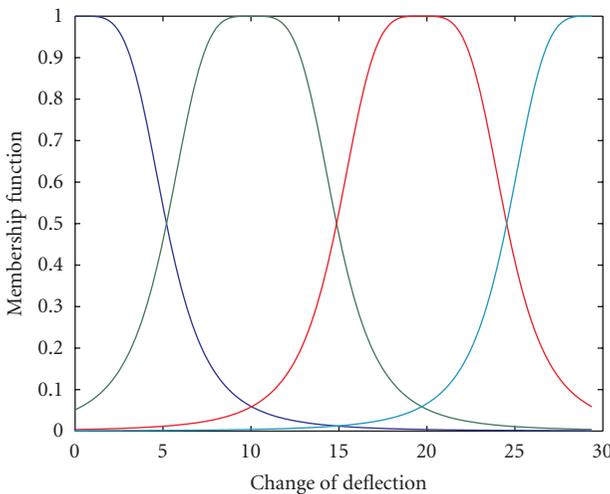


FIGURE 8: Membership grade of deflection variation after training by FNN.

respectively, is presented. All the method can obtain a final result by the different information from various types of sensors. A single-layer spherical lattice dome is studied in order to validate the information fusion methods in this paper. The result shows that all the information fusion methods have high accuracy and feasibility.

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