COMMON FIXED POINT THEOREMS OF CONTRACTIVE-TYPE MAPPINGS

HEE SOO PARK and JEONG SHEOK UME

Received 10 April 2004

Using the concept of D -metric we prove some common fixed point theorems for generalized contractive mappings on a complete D -metric space. Our results extend, improve, and unify results of Fisher and Ćirić.

2000 Mathematics Subject Classification: 47H10.

1. Introduction. The Banach contraction mapping principle is well known. There are many generalizations of that principle to single- and multivalued mappings (see [1, 4, 5, 10, 11, 12]). The study of maps satisfying some contractive conditions has been the center of rigorous research activity since such mappings have many applications (see [2, 3, 9, 13, 14, 15]).

In 1998, Ćirić [6] proved a common fixed point theorem for nonlinear mappings on a complete metric space: let (X, d) be a complete metric space and $S, T : X \rightarrow X$ self-maps such that $d(STx, TSy) \leq \max\{\varphi_1[(1/2)(d(x, Sy) + d(y, Tx))], \varphi_2[d(x, Tx)], \varphi_3[d(y, Sy)], \varphi_4[d(x, y)]\}$ for all x, y in X , where $\varphi_i \in \Phi$ ($i = 1, 2, 3, 4$). If S or T is continuous, then S and T have a unique common fixed point. This result improved and extended a theorem of Fisher [8].

In this paper, using the concept of D -metric, we prove common fixed point theorems which extend, improve, and unify the corresponding theorems of Fisher [8] and Ćirić [6].

Throughout the paper, by Φ we denote the collection of functions $\varphi : [0, \infty) \rightarrow [0, \infty)$ which are continuous from the right, nondecreasing, and which satisfy the condition $\varphi(t) < t$ for all $t > 0$. We denote by $\mathbb{N}$ the set of all positive integers.

2. Preliminaries. Before proving the main theorem, we will introduce some definitions and lemmas.

DEFINITION 2.1 [7]. Let X be any nonempty set. A D -metric for X is a function $D : X \times X \times X \rightarrow \mathbb{R}$ such that

- (1) $D(x, y, z) \geq 0$ for all $x, y, z \in X$ and equality holds if and only if $x = y = z$,
- (2) $D(x, y, z) = D(x, z, y) = D(y, x, z) = D(y, z, x) = D(z, x, y) = D(z, y, x)$ for all $x, y, z \in X$,
- (3) $D(x, y, z) \leq D(x, y, a) + D(x, a, z) + D(a, y, z)$ for all $x, y, z \in X$.

If D is a D -metric for X , then the ordered pair (X, D) is called a D -metric space or the set X , together with a D -metric, is called a D -metric space. We note that to

a given ordinary metric space (X, d) there corresponds a D -metric space (X, D) , but the converse may not be true (see [Example 3.3](#)). In this sense the D -metric spaces are the generalizations of the ordinary metric space.

DEFINITION 2.2 [7]. A sequence $\{x_n\}$ of points of a D -metric space X converges to a point $x \in X$ if for an arbitrary $\varepsilon > 0$, there exists an $n_0 \in \mathbb{N}$ such that for all $n > m \geq n_0$, $D(x_m, x_n, x) < \varepsilon$.

DEFINITION 2.3 [7]. A sequence $\{x_n\}$ of points of a D -metric space X is said to be a D -Cauchy sequence if for an arbitrary $\varepsilon > 0$, there exists an $n_0 \in \mathbb{N}$ such that for all $p > n > m \geq n_0$, $D(x_m, x_n, x_p) < \varepsilon$.

DEFINITION 2.4 [7]. A D -metric space X is a complete D -metric space if every D -Cauchy sequence $\{x_n\}$ in X converges to a point x in X .

DEFINITION 2.5. A real-valued function f defined on a metric space X is said to be lower semicontinuous at a point t in X if $\lim_{x \rightarrow t} \inf f(x) = \infty$ or $\lim_{x \rightarrow t} \inf f(x) \geq f(t)$.

DEFINITION 2.6. A real-valued function f defined on a metric space X is said to be upper semicontinuous at a point t in X if $\lim_{x \rightarrow t} \sup f(x) = \infty$ or $\lim_{x \rightarrow t} \sup f(x) \leq f(t)$.

DEFINITION 2.7. Let $x_0 \in X$ and $\varepsilon > 0$ be given. Then the open ball $B(x_0, \varepsilon)$ in X centered at x_0 of radius ε is defined by

$$B(x_0, \varepsilon) = \left\{ y \in X \mid D(x_0, y, y) < \varepsilon \text{ if } y = x_0, \sup_{z \in X} D(x_0, y, z) < \varepsilon \text{ if } y \neq x_0 \right\}. \quad (2.1)$$

Then the collection of all open balls $\{B(x, \varepsilon) : x \in X\}$ defines the topology on X denoted by τ .

LEMMA 2.8 [7]. The D -metric for X is a continuous function on $X \times X \times X$ in the topology τ on X .

LEMMA 2.9 [6]. If $\varphi_1, \varphi_2 \in \Phi$, then there is some $\varphi \in \Phi$ such that $\max\{\varphi_1(t), \varphi_2(t)\} \leq \varphi(t)$ for all $t > 0$.

LEMMA 2.10. Let (X, D) be a D -metric space. Let $g : X \times X \rightarrow X$ be a mapping and let $S, T : X \rightarrow X$ be mappings such that

$$\begin{aligned} & \max\{D(STx, TSy, g(STx, TSy)), D(TSy, STx, g(TSy, STx))\} \\ & \leq \max\left\{\varphi_1\left[\frac{1}{2}(D(x, Sy, g(x, Sy)) + D(y, Tx, g(y, Tx)))\right], \right. \\ & \quad \varphi_2[D(x, Tx, g(x, Tx))], \varphi_3[D(y, Sy, g(y, Sy))], \\ & \quad \left. \varphi_4[D(x, y, g(x, y))]\right\} \end{aligned} \quad (2.2)$$

for all $x, y \in X$, where $\varphi_i \in \Phi$ ($i = 1, 2, 3, 4$),

$$x = y \implies D(x, y, g(x, y)) = 0, \quad (2.3)$$

and

$$\begin{aligned} & \max \{D(x, z, g(x, z)), D(x, y, g(x, z)), D(y, z, g(x, z))\} \\ & \leq D(x, y, g(x, y)) + D(y, z, g(y, z)) \end{aligned} \quad (2.4)$$

for all $x, y, z \in X$. The sequence $\{x_n\}$ is defined by $x_0 \in X$, $x_{2n+1} = Tx_{2n}$, and $x_{2n+2} = Sx_{2n+1}$ for every $n \in \mathbb{N} \cup \{0\}$. Then

- (I) for an arbitrary $\varepsilon > 0$, there exists a positive integer L such that $L \leq n < m$ implies $\max\{D(x_n, x_m, g(x_n, x_m)), D(x_m, x_n, g(x_m, x_n))\} < \varepsilon$,
 (II) a sequence $\{x_n\}_{n=0}^\infty$ is a D -Cauchy sequence.

PROOF. Let $M = \max\{D(x_0, x_1, g(x_0, x_1)), D(x_1, x_2, g(x_1, x_2)), D(x_2, x_1, g(x_2, x_1))\}$. Since all φ_i are nondecreasing functions by (2.2), (2.3), and (2.4),

$$\begin{aligned} & \max \{D(x_2, x_3, g(x_2, x_3)), D(x_3, x_2, g(x_3, x_2))\} \\ & = \max \{D(STx_0, TSx_1, g(STx_0, TSx_1)), D(TSx_1, STx_0, g(TSx_1, STx_0))\} \\ & \leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_0, Sx_1, g(x_0, Sx_1)) + D(x_1, Tx_0, g(x_1, Tx_0))) \right], \right. \\ & \quad \varphi_2 [D(x_0, Tx_0, g(x_0, Tx_0))], \varphi_3 [D(x_1, Sx_1, g(x_1, Sx_1))], \\ & \quad \left. \varphi_4 [D(x_0, x_1, g(x_0, x_1))] \right\} \\ & \leq \max \{ \varphi_1(M), \varphi_2(M), \varphi_3(M), \varphi_4(M) \} \\ & \leq \varphi(M), \end{aligned} \quad (2.5)$$

where $\varphi \in \Phi$. Such φ exists from an extended version of Lemma 2.9. Therefore, we have $\max\{D(x_2, x_3, g(x_2, x_3)), D(x_3, x_2, g(x_3, x_2))\} \leq \varphi(M)$. Again, from (2.2), (2.3), and (2.4), we get

$$\begin{aligned} & \max \{D(x_3, x_4, g(x_3, x_4)), D(x_4, x_3, g(x_4, x_3))\} \\ & = \max \{D(TSx_1, STx_2, g(TSx_1, STx_2)), D(STx_2, TSx_1, g(STx_2, TSx_1))\} \\ & \leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_2, Sx_1, g(x_2, Sx_1)) + D(x_1, Tx_2, g(x_1, Tx_2))) \right], \right. \\ & \quad \varphi_2 [D(x_2, Tx_2, g(x_2, Tx_2))], \varphi_3 [D(x_1, Sx_1, g(x_1, Sx_1))], \\ & \quad \left. \varphi_4 [D(x_2, x_1, g(x_2, x_1))] \right\} \\ & \leq \max \{ \varphi_1(M), \varphi_2[\varphi(M)], \varphi_3(M), \varphi_4(M) \} \\ & \leq \varphi(M). \end{aligned} \quad (2.6)$$

Using the obtained relations $\max\{D(x_2, x_3, g(x_2, x_3)), D(x_3, x_2, g(x_3, x_2))\} \leq \varphi(M)$ and $\max\{D(x_3, x_4, g(x_3, x_4)), D(x_4, x_3, g(x_4, x_3))\} \leq \varphi(M)$, from (2.2), (2.3), and (2.4),

we get

$$\begin{aligned}
 & \max \{D(x_4, x_5, g(x_4, x_5)), D(x_5, x_4, g(x_5, x_4))\} \\
 &= \max \{D(STx_2, TSx_3, g(STx_2, TSx_3)), D(TSx_3, STx_2, g(TSx_3, STx_2))\} \\
 &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_2, Sx_3, g(x_2, Sx_3)) + D(x_3, Tx_2, g(x_3, Tx_2))) \right], \right. \\
 &\quad \varphi_2 [D(x_2, Tx_2, g(x_2, Tx_2))], \varphi_3 [D(x_3, Sx_3, g(x_3, Sx_3))], \\
 &\quad \left. \varphi_4 [D(x_2, x_3, g(x_2, x_3))] \right\} \\
 &\leq \max \{ \varphi_1 [\varphi(M)], \varphi_2 [\varphi(M)], \varphi_3 [\varphi(M)], \varphi_4 [\varphi(M)] \} \\
 &\leq \varphi^2(M).
 \end{aligned} \tag{2.7}$$

Similarly, again from (2.2), (2.3), and (2.4), we get

$$\begin{aligned}
 & \max \{D(x_5, x_6, g(x_5, x_6)), D(x_6, x_5, g(x_6, x_5))\} \\
 &= \max \{D(TSx_3, STx_4, g(TSx_3, STx_4)), D(STx_4, TSx_3, g(STx_4, TSx_3))\} \\
 &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_4, Sx_3, g(x_4, Sx_3)) + D(x_3, Tx_4, g(x_3, Tx_4))) \right], \right. \\
 &\quad \varphi_2 [D(x_4, Tx_4, g(x_4, Tx_4))], \varphi_3 [D(x_3, Sx_3, g(x_3, Sx_3))], \\
 &\quad \left. \varphi_4 [D(x_4, x_3, g(x_4, x_3))] \right\} \\
 &\leq \max \{ \varphi_1 [\varphi(M)], \varphi_2 [\varphi^2(M)], \varphi_3 [\varphi(M)], \varphi_4 [\varphi(M)] \} \\
 &\leq \varphi^2(M).
 \end{aligned} \tag{2.8}$$

In general, by induction, we get

$$\max \{D(x_n, x_{n+1}, g(x_n, x_{n+1})), D(x_{n+1}, x_n, g(x_{n+1}, x_n))\} \leq \varphi^{[n/2]}(M) \tag{2.9}$$

for $n \geq 2$, where $[n/2]$ stands for the greatest integer not exceeding $n/2$. Since $\varphi \in \Phi$, by Singh and Meade [13, Lemma 1], it follows that $\varphi^n(M) \rightarrow 0$ as $n \rightarrow +\infty$ for every $M > 0$. Thus, we obtain

$$\max \{D(x_n, x_{n+1}, g(x_n, x_{n+1})), D(x_{n+1}, x_n, g(x_{n+1}, x_n))\} \rightarrow 0 \quad \text{as } n \rightarrow \infty. \tag{2.10}$$

Suppose that (I) does not hold. Then there exists an $\varepsilon > 0$ such that for each $i \in \mathbb{N}$, there exist positive integers n_i, m_i , with $i \leq n_i < m_i$, satisfying

$$\begin{aligned}
 & \varepsilon \leq \max \{D(x_{n_i}, x_{m_i}, g(x_{n_i}, x_{m_i})), D(x_{m_i}, x_{n_i}, g(x_{m_i}, x_{n_i}))\}, \\
 & \max \{D(x_{n_i}, x_{m_i-1}, g(x_{n_i}, x_{m_i-1})), D(x_{m_i-1}, x_{n_i}, g(x_{m_i-1}, x_{n_i}))\} < \varepsilon \quad \text{for } i = 1, 2, \dots
 \end{aligned} \tag{2.11}$$

Set

$$\begin{aligned}
 \varepsilon_i &= \max \{D(x_{n_i}, x_{m_i}, g(x_{n_i}, x_{m_i})), D(x_{m_i}, x_{n_i}, g(x_{m_i}, x_{n_i}))\}, \\
 \rho_i &= \max \{D(x_i, x_{i+1}, g(x_i, x_{i+1})), D(x_{i+1}, x_i, g(x_{i+1}, x_i))\} \quad \text{for } i = 1, 2, \dots
 \end{aligned} \tag{2.12}$$

Then we have

$$\begin{aligned}
 \varepsilon &\leq \varepsilon_i \\
 &= \max \{D(x_{n_i}, x_{m_i}, g(x_{n_i}, x_{m_i})), D(x_{m_i}, x_{n_i}, g(x_{m_i}, x_{n_i}))\} \\
 &\leq \max \{D(x_{n_i}, x_{m_{i-1}}, g(x_{n_i}, x_{m_{i-1}})), D(x_{m_{i-1}}, x_{n_i}, g(x_{m_{i-1}}, x_{n_i}))\} \\
 &\quad + \max \{D(x_{m_{i-1}}, x_{m_i}, g(x_{m_{i-1}}, x_{m_i})), D(x_{m_i}, x_{m_{i-1}}, g(x_{m_i}, x_{m_{i-1}}))\} \\
 &< \varepsilon + \rho_{m_{i-1}}, \quad i = 1, 2, \dots
 \end{aligned} \tag{2.13}$$

Taking the limit as $i \rightarrow +\infty$, we get $\lim \varepsilon_i = \varepsilon$. On the other hand, by (2.2), (2.3), and (2.4),

$$\begin{aligned}
 \varepsilon_i &= \max \{D(x_{n_i}, x_{m_i}, g(x_{n_i}, x_{m_i})), D(x_{m_i}, x_{n_i}, g(x_{m_i}, x_{n_i}))\} \\
 &\leq \max \{D(x_{n_i}, x_{n_{i+1}}, g(x_{n_i}, x_{n_{i+1}})), D(x_{n_{i+1}}, x_{n_i}, g(x_{n_{i+1}}, x_{n_i}))\} \\
 &\quad + \max \{D(x_{n_{i+1}}, x_{n_{i+2}}, g(x_{n_{i+1}}, x_{n_{i+2}})), D(x_{n_{i+2}}, x_{n_{i+1}}, g(x_{n_{i+2}}, x_{n_{i+1}}))\} \\
 &\quad + \max \{D(x_{n_{i+2}}, x_{m_{i+2}}, g(x_{n_{i+2}}, x_{m_{i+2}})), D(x_{m_{i+2}}, x_{n_{i+2}}, g(x_{m_{i+2}}, x_{n_{i+2}}))\} \\
 &\quad + \max \{D(x_{m_{i+2}}, x_{m_{i+1}}, g(x_{m_{i+2}}, x_{m_{i+1}})), D(x_{m_{i+1}}, x_{m_{i+2}}, g(x_{m_{i+1}}, x_{m_{i+2}}))\} \\
 &\quad + \max \{D(x_{m_{i+1}}, x_{m_i}, g(x_{m_{i+1}}, x_{m_i})), D(x_{m_i}, x_{m_{i+1}}, g(x_{m_i}, x_{m_{i+1}}))\} \\
 &= \rho_{n_i} + \rho_{n_{i+1}} + \max \{D(x_{n_{i+2}}, x_{m_{i+2}}, g(x_{n_{i+2}}, x_{m_{i+2}})), \\
 &\quad D(x_{m_{i+2}}, x_{n_{i+2}}, g(x_{m_{i+2}}, x_{n_{i+2}}))\} \\
 &\quad + \rho_{m_{i+1}} + \rho_{m_i} \quad \text{for } i = 1, 2, \dots
 \end{aligned} \tag{2.14}$$

We will now analyze the term $\max \{D(x_{n_i+2}, x_{m_i+2}, g(x_{n_i+2}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+2}, g(x_{m_i+2}, x_{n_i+2}))\}$ based on the parity of the subscripts.

CASE 1. $n_i + 2$ is even and $m_i + 2$ is odd. From (2.2), (2.3), and (2.4), we have

$$\begin{aligned}
 &\max \{D(x_{n_i+2}, x_{m_i+2}, g(x_{n_i+2}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+2}, g(x_{m_i+2}, x_{n_i+2}))\} \\
 &= \max \{D(STx_{n_i}, TSx_{m_i}, g(STx_{n_i}, TSx_{m_i})), D(TSx_{m_i}, STx_{n_i}, g(TSx_{m_i}, STx_{n_i}))\} \\
 &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_{n_i}, Sx_{m_i}, g(x_{n_i}, Sx_{m_i})) + D(x_{m_i}, Tx_{n_i}, g(x_{m_i}, Tx_{n_i}))) \right], \right. \\
 &\quad \varphi_2 [D(x_{n_i}, Tx_{n_i}, g(x_{n_i}, Tx_{n_i}))], \varphi_3 [D(x_{m_i}, Sx_{m_i}, g(x_{m_i}, Sx_{m_i}))], \\
 &\quad \left. \varphi_4 [D(x_{n_i}, x_{m_i}, g(x_{n_i}, x_{m_i}))] \right\} \\
 &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (\varepsilon_i + \rho_{m_i} + \varepsilon_i + \rho_{n_i}) \right], \varphi_2 (\rho_{n_i}), \varphi_3 (\rho_{m_i}), \varphi_4 (\varepsilon_i) \right\} \\
 &\leq \varphi (\varepsilon_i + \rho_{m_i} + \rho_{n_i}).
 \end{aligned} \tag{2.15}$$

Therefore, we have

$$\max \{D(x_{n_i+2}, x_{m_i+2}, g(x_{n_i+2}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+2}, g(x_{m_i+2}, x_{n_i+2}))\} \leq \varphi(k_i), \tag{2.16}$$

where $k_i = \varepsilon_i + \rho_{m_i} + \rho_{n_i}$. Substituting (2.16) into (2.14), taking the limit as $i \rightarrow +\infty$, and using the right continuity of φ , we get

$$\varepsilon = \lim_{i \rightarrow \infty} \varepsilon_i \leq \lim_{k_i \rightarrow \varepsilon^+} \varphi(k_i) = \varphi(\varepsilon) < \varepsilon, \quad (2.17)$$

which is a contradiction.

CASE 2. Both $n_i + 2$ and $m_i + 2$ are odd. Then, we have

$$\begin{aligned} & \max \{D(x_{n_i+2}, x_{m_i+2}, g(x_{n_i+2}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+2}, g(x_{m_i+2}, x_{n_i+2}))\} \\ & \leq \max \{D(x_{n_i+2}, x_{n_i+1}, g(x_{n_i+2}, x_{n_i+1})), D(x_{n_i+1}, x_{n_i+2}, g(x_{n_i+1}, x_{n_i+2}))\} \\ & \quad + \max \{D(x_{n_i+1}, x_{m_i+2}, g(x_{n_i+1}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+1}, g(x_{m_i+2}, x_{n_i+1}))\} \\ & = \rho_{n_i+1} + \max \{D(x_{n_i+1}, x_{m_i+2}, g(x_{n_i+1}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+1}, g(x_{m_i+2}, x_{n_i+1}))\}. \end{aligned} \quad (2.18)$$

Since $n_i + 1$ is even and $m_i + 2$ is odd, from Case 1, we have

$$\begin{aligned} & \max \{D(x_{n_i+1}, x_{m_i+2}, g(x_{n_i+1}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+1}, g(x_{m_i+2}, x_{n_i+1}))\} \\ & = \max \{D(STx_{n_i-1}, TSx_{m_i}, g(STx_{n_i-1}, TSx_{m_i})), \\ & \quad D(TSx_{m_i}, STx_{n_i-1}, g(TSx_{m_i}, STx_{n_i-1}))\} \\ & \leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_{n_i-1}, Sx_{m_i}, g(x_{n_i-1}, Sx_{m_i})) + D(x_{m_i}, Tx_{n_i-1}, g(x_{m_i}, Tx_{n_i-1}))) \right], \right. \\ & \quad \varphi_2 [D(x_{n_i-1}, Tx_{n_i-1}, g(x_{n_i-1}, Tx_{n_i-1}))], \varphi_3 [D(x_{m_i}, Sx_{m_i}, g(x_{m_i}, Sx_{m_i}))], \\ & \quad \left. \varphi_4 [D(x_{n_i-1}, x_{m_i}, g(x_{n_i-1}, x_{m_i}))] \right\} \\ & \leq \max \left\{ \varphi_1 \left[\frac{1}{2} (\rho_{n_i-1} + \varepsilon_i + \rho_{m_i} + \varepsilon_i) \right], \varphi_2 (\rho_{n_i-1}), \varphi_3 (\rho_{m_i}), \varphi_4 (\rho_{n_i-1} + \varepsilon_i) \right\} \\ & \leq \varphi(\varepsilon_i + \rho_{m_i} + \rho_{n_i-1}). \end{aligned} \quad (2.19)$$

Therefore, we get

$$\max \{D(x_{n_i+1}, x_{m_i+2}, g(x_{n_i+1}, x_{m_i+2})), D(x_{m_i+2}, x_{n_i+1}, g(x_{m_i+2}, x_{n_i+1}))\} \leq \varphi(l_i), \quad (2.20)$$

where $l_i = \varepsilon_i + \rho_{m_i} + \rho_{n_i-1}$. Hence, substituting (2.20) into (2.18), then putting (2.18) into (2.14), and taking the limit as $i \rightarrow +\infty$, we have

$$\varepsilon = \lim_{i \rightarrow \infty} \varepsilon_i \leq \lim_{l_i \rightarrow \varepsilon^+} \varphi(l_i) = \varphi(\varepsilon) < \varepsilon, \quad (2.21)$$

which is a contradiction. In a similar manner, we get (2.17) and (2.21) for the cases in which $n_i + 2$ and $m_i + 2$ are both even, and $n_i + 2$ is odd and $m_i + 2$ is even. That is, all cases lead to a contradiction. Therefore (I) holds.

We claim that $\{x_n\}$ is D -Cauchy. Let n, m, p ($n < m < p$) be any positive integers. Then, by [Definition 2.1](#) and (2.4),

$$\begin{aligned} D(x_n, x_m, x_p) &\leq D(x_n, x_m, g(x_n, x_m)) + D(x_n, x_p, g(x_n, x_m)) + D(x_m, x_p, g(x_n, x_m)) \\ &\leq D(x_n, x_m, g(x_n, x_m)) + 2D(x_n, x_m, g(x_n, x_m)) + 2D(x_m, x_p, g(x_m, x_p)) \\ &= 3D(x_n, x_m, g(x_n, x_m)) + 2D(x_m, x_p, g(x_m, x_p)). \end{aligned} \quad (2.22)$$

Since $\lim_{n \rightarrow \infty} D(x_n, x_m, g(x_n, x_m)) = 0$, we have $\lim_{n \rightarrow \infty} D(x_n, x_m, x_p) = 0$. Thus $\{x_n\}$ is a D -Cauchy sequence. $\square$

3. Main results. Now we will prove the following fixed point theorems for a complete D -metric space.

THEOREM 3.1. *Let (X, D) be a complete D -metric space. Let $g : X \times X \rightarrow X$ be a function and let S and T be self-maps on X satisfying (2.2), (2.3), and (2.4) of [Lemma 2.10](#). For any sequences $\{u_n\}, \{v_n\}$ in X such that $\lim_{n \rightarrow \infty} u_n = \alpha$ and $\lim_{n \rightarrow \infty} v_n = \beta$, $\lim_{n \rightarrow \infty} D(u_n, v_n, g(u_n, v_n)) = D(\alpha, \beta, g(\alpha, \beta))$ for some α, β in X .*

If S or T is continuous, then S and T have a unique common fixed point.

PROOF. Let the sequence $\{x_n\}$ be defined by $x_0 \in X$, $x_{2n+1} = Tx_{2n}$, and $x_{2n+2} = Sx_{2n+1}$ for every $n \in \mathbb{N} \cup \{0\}$. Then, by [Lemma 2.10\(II\)](#), it follows that $\{x_n\}$ is a D -Cauchy sequence. Since X is a complete D -metric space, $\{x_n\}$ is convergent to a limit u in X . Suppose that S is continuous. Then

$$u = \lim_{n \rightarrow \infty} x_{2n+2} = \lim_{n \rightarrow \infty} Sx_{2n+1} = S\left(\lim_{n \rightarrow \infty} x_{2n+1}\right) = Su. \quad (3.1)$$

This implies that u is a fixed point of S . From (2.2), (2.3), and (2.4), we get $D(u, Su, g(u, Su)) = 0$ and

$$\begin{aligned} D(u, Tu, g(u, Tu)) &= D(u, TSu, g(u, TSu)) \\ &\leq D(u, x_{2n+2}, g(u, x_{2n+2})) + D(STx_{2n}, TSu, g(STx_{2n}, TSu)) \\ &\leq D(u, x_{2n+2}, g(u, x_{2n+2})) \\ &\quad + \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_{2n}, Su, g(x_{2n}, Su)) + D(u, Tx_{2n}, g(u, Tx_{2n}))) \right], \right. \\ &\quad \varphi_2 [D(x_{2n}, Tx_{2n}, g(x_{2n}, Tx_{2n}))], \varphi_3 [D(u, Su, g(u, Su))], \\ &\quad \left. \varphi_4 [D(x_{2n}, u, g(x_{2n}, u))] \right\}. \end{aligned} \quad (3.2)$$

Taking the limit when n tends to infinity, by hypothesis, we get $D(u, Tu, g(u, Tu)) = 0$. Thus, we have $u = Su = Tu$. Therefore, u is the common fixed point of S and T . The proof for T continuous is similar.

We will now show that u is unique. Suppose that v is also a common fixed point of S and T . Then, from (2.2), (2.3), and (2.4),

$$\begin{aligned}
 & \max\{D(u, v, g(u, v)), D(v, u, g(v, u))\} \\
 &= \max\{D(STu, TSv, g(STu, TSv)), D(TSv, STu, g(TSv, STu))\} \\
 &\leq \max\left\{\varphi_1\left[\frac{1}{2}(D(u, Sv, g(u, Sv)) + D(v, Tu, g(v, Tu)))\right], \right. \\
 &\quad \left.\varphi_2[D(u, Tu, g(u, Tu))], \varphi_3[D(v, Sv, g(v, Sv))], \varphi_4[D(u, v, g(u, v))]\right\} \\
 &= \max\left\{\varphi_1\left[\frac{1}{2}(D(u, v, g(u, v)) + D(v, u, g(v, u)))\right], \right. \\
 &\quad \left.\varphi_2[D(u, u, g(u, u))], \varphi_3[D(v, v, g(v, v))], \varphi_4[D(u, v, g(u, v))]\right\} \\
 &\leq \varphi(\max\{D(u, v, g(u, v)), D(v, u, g(v, u))\}).
 \end{aligned} \tag{3.3}$$

We write $\max\{D(u, v, g(u, v)), D(v, u, g(v, u))\} \leq \varphi(\max\{D(u, v, g(u, v)), D(v, u, g(v, u))\})$, which implies that $\max\{D(u, v, g(u, v)), D(v, u, g(v, u))\} = 0$, that is, $u = v$. Therefore, the common fixed point of S and T is unique. $\square$

REMARK 3.2. Let X be a complete metric space with a metric d . If we take $D(x, y, z) = \max\{d(x, y), d(x, z), d(y, z)\}$ and $g(x, y) = x$ for all $x, y, z \in X$, then Theorem 3.1 is Ćirić's [6, Theorem 2] which has extended a theorem of Fisher [8].

The following example shows that a D -metric is a proper extension of a metric d .

EXAMPLE 3.3. Let d be a metric on $\mathbb{R}$. Define the function $\varphi : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ by $\varphi(x, y) = (x - y)^2$ for all $x, y \in \mathbb{R}$. Then, clearly, φ is not metric since $\varphi(2, 1/2) > \varphi(2, 1) + \varphi(1, 1/2)$. Let $G, H : \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be functions such that $G(x, y, z) = \max\{d(x, y), d(x, z), d(y, z)\}$ and $H(x, y, z) = \max\{\varphi(x, y), \varphi(x, z), \varphi(y, z)\}$ for all $x, y, z \in \mathbb{R}$. Then, clearly, G and H are D -metric for $\mathbb{R}$. But H is a D -metric that is a proper extension of the metric d . Therefore, a D -metric space is a proper extension of a metric space.

COROLLARY 3.4. Let (X, D) be a complete D -metric space. Let $g : X \times X \rightarrow X$ be a function and let S and T be self-maps on X satisfying

$$\begin{aligned}
 & \max\{D(STx, TSy, g(STx, TSy)), D(TSy, STx, g(TSy, STx))\} \\
 &\leq c \cdot \max\left\{\frac{1}{2}[D(x, Sy, g(x, Sy)) + D(y, Tx, g(y, Tx))], \right. \\
 &\quad \left.D(x, Tx, g(x, Tx)), D(y, Sy, g(y, Sy)), D(x, y, g(x, y))\right\}
 \end{aligned} \tag{3.4}$$

for all $x, y \in X$, where $x = y$ implies $D(x, y, g(x, y)) = 0$ and $\max\{D(x, z, g(x, z)), D(x, y, g(x, y)), D(y, z, g(y, z))\} \leq D(x, y, g(x, y)) + D(y, z, g(y, z))$ for all $x, y, z \in X$.

For any sequences $\{u_n\}, \{v_n\}$ in X such that $\lim_{n \rightarrow \infty} u_n = \alpha$ and $\lim_{n \rightarrow \infty} v_n = \beta$, $\lim_{n \rightarrow \infty} D(u_n, v_n, g(u_n, v_n)) = D(\alpha, \beta, g(\alpha, \beta))$ for some α, β in X .

If S or T is continuous, then S and T have a unique common fixed point.

PROOF. The proof follows by taking $\varphi_i(t) = c \cdot t$ with $0 < c < 1$ ($i = 1, 2, 3, 4$) in [Theorem 3.1](#). $\square$

We will prove the following corollary using another condition instead of continuity in [Theorem 3.1](#).

COROLLARY 3.5. Let (X, D) be a complete D -metric space. Let $g : X \times X \rightarrow X$ be a function, let S and T be self-maps on X satisfying (2.2), (2.3), and (2.4) of [Lemma 2.10](#), and, for each $u \in X$ with $u \neq Su$ or $u \neq Tu$, let

$$\inf \{D(x, u, g(x, u)) + D(x, Sx, g(x, Sx)) + D(y, Ty, g(y, Ty)) : x, y \in X\} > 0. \quad (3.5)$$

For any sequences $\{a_n\}$ and $\{b_n\}$ in X such that $\lim_{n \rightarrow \infty} a_n = u$ and $\lim_{n \rightarrow \infty} b_n = v$, the following conditions hold:

- (1) $\lim_{n \rightarrow \infty} D(a_n, b_n, g(a_n, b_n)) = D(u, v, g(u, v))$,
- (2) $\lim_{m \rightarrow \infty} D(a_n, b_m, g(a_n, b_m)) = D(a_n, v, g(a_n, v))$ for each $n \in \mathbb{N}$,
- (3) $\lim_{m \rightarrow \infty} D(b_m, a_n, g(b_m, a_n)) = D(v, a_n, g(v, a_n))$ for each $n \in \mathbb{N}$.

Then S and T have a unique common fixed point.

PROOF. From [Lemma 2.10](#)(I) and (II), the sequence $\{x_n\}$ defined by $x_0 \in X$, $x_{2n+1} = Tx_{2n}$, and $x_{2n+2} = Sx_{2n+1}$ for every $x \in \mathbb{N} \cup \{0\}$ is a D -Cauchy sequence. Since X is a complete D -metric space, there exists $u \in X$ such that $\{x_n\}$ converges to u . Then we have

$$\begin{aligned} & D(x_{2n+1}, x_{2m+2}, g(x_{2n+1}, x_{2m+2})) \\ &= D(TSx_{2n-1}, STx_{2m}, g(TSx_{2n-1}, STx_{2m})) \\ &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_{2m}, Sx_{2n-1}, g(x_{2m}, Sx_{2n-1})) + D(x_{2n-1}, Tx_{2m}, g(x_{2n-1}, Tx_{2m}))) \right], \right. \\ &\quad \varphi_2 [D(x_{2m}, Tx_{2m}, g(x_{2m}, Tx_{2m}))], \varphi_3 [D(x_{2n-1}, Sx_{2n-1}, g(x_{2n-1}, Sx_{2n-1}))], \\ &\quad \left. \varphi_4 [D(x_{2m}, x_{2n-1}, g(x_{2m}, x_{2n-1}))] \right\} \\ &\leq \max \left\{ \varphi_1 \left[\frac{1}{2} (D(x_{2m}, x_{2n}, g(x_{2m}, x_{2n})) + D(x_{2n-1}, x_{2m+1}, g(x_{2n-1}, x_{2m+1}))) \right], \right. \\ &\quad \varphi_2 [D(x_{2m}, x_{2m+1}, g(x_{2m}, x_{2m+1}))], \varphi_3 [D(x_{2n-1}, x_{2n}, g(x_{2n-1}, x_{2n}))], \\ &\quad \left. \varphi_4 [D(x_{2m}, x_{2n-1}, g(x_{2m}, x_{2n-1}))] \right\}. \end{aligned} \quad (3.6)$$

Thus, we obtain $\lim_{n \rightarrow \infty} D(x_{2n+1}, u, g(x_{2n+1}, u)) = 0$. Assume that $u \neq Su$ or $u \neq Tu$.

Then, by hypothesis, we have

$$\begin{aligned}
 0 &< \inf \{D(x, u, g(x, u)) + D(x, Sx, g(x, Sx)) + D(y, Ty, g(y, Ty)) : x, y \in X\} \\
 &\leq \inf \{D(x_{2n+1}, u, g(x_{2n+1}, u)) + D(x_{2n+1}, Sx_{2n+1}, g(x_{2n+1}, Sx_{2n+1})) \\
 &\quad + D(x_{2n+2}, Tx_{2n+2}, g(x_{2n+2}, Tx_{2n+2})) : n \in \mathbb{N}\} \\
 &= \inf \{D(x_{2n+1}, u, g(x_{2n+1}, u)) + D(x_{2n+1}, x_{2n+2}, g(x_{2n+1}, x_{2n+2})) \\
 &\quad + D(x_{2n+2}, x_{2n+3}, g(x_{2n+2}, x_{2n+3})) : n \in \mathbb{N}\} \\
 &= 0.
 \end{aligned} \tag{3.7}$$

This is a contradiction. Therefore, we have $u = Su = Tu$.

On the other hand, we can prove the existence of a unique common fixed point of S and T by a method similar to that of [Theorem 3.1](#). $\square$

ACKNOWLEDGMENT. This work was supported by Korea Research Foundation Grant (KRF-2003-015-C00039).

REFERENCES

- [1] D. W. Boyd and J. S. W. Wong, *On nonlinear contractions*, Proc. Amer. Math. Soc. **20** (1969), 458-464.
- [2] J. L. C. Camargo, *An application of a fixed-point theorem of D. W. Boyd and J. S. W. Wong*, Rev. Mat. Estadíst. **6** (1988), 25-29.
- [3] S. K. Chatterjea, *Applications of an extension of a theorem of Fisher on common fixed point*, Pure Math. Manuscript **6** (1987), 35-38.
- [4] Lj. B. Ćirić, *A generalization of Banach's contraction principle*, Proc. Amer. Math. Soc. **45** (1974), 267-273.
- [5] ———, *A new fixed-point theorem for contractive mappings*, Publ. Inst. Math. (Beograd) (N.S.) **30(44)** (1981), 25-27.
- [6] ———, *Common fixed points of nonlinear contractions*, Acta Math. Hungar. **80** (1998), no. 1-2, 31-38.
- [7] B. C. Dhage, *Generalised metric spaces and mappings with fixed point*, Bull. Calcutta Math. Soc. **84** (1992), no. 4, 329-336.
- [8] B. Fisher, *Some results on fixed points*, Acta Math. Acad. Sci. Hungar. **33** (1979), no. 3-4, 289-292.
- [9] O. Hadžić, *Some applications of a common fixed point theorem*, Studia Univ. Babeş-Bolyai Math. **28** (1983), 67-74.
- [10] A. Meir and E. Keeler, *A theorem on contraction mappings*, J. Math. Anal. Appl. **28** (1969), 326-329.
- [11] H. K. Pathak, *Fixed point theorems for weak compatible multi-valued and single-valued mappings*, Acta Math. Hungar. **67** (1995), no. 1-2, 69-78.
- [12] B. E. Rhoades, *A comparison of various definitions of contractive mappings*, Trans. Amer. Math. Soc. **226** (1977), 257-290.
- [13] S. P. Singh and B. A. Meade, *On common fixed point theorems*, Bull. Austral. Math. Soc. **16** (1977), no. 1, 49-53.
- [14] M. Turinici, *Multivalued contractions and applications to functional-differential equations*, Acta Math. Acad. Sci. Hungar. **37** (1981), no. 1-3, 147-151.

- [15] A. Wieczorek, *Applications of fixed-point theorems in game theory and mathematical economics*, Wiadom. Mat. **28** (1988), no. 1, 25–34.

Hee Soo Park: Department of Applied Mathematics, Changwon National University, Changwon 641-773, Korea

E-mail address: pheesoo@changwon.ac.kr

Jeong Sheok Ume: Department of Applied Mathematics, Changwon National University, Changwon 641-773, Korea

E-mail address: jsume@changwon.ac.kr