The Effect of Viscosity on Performance of a Low Specific Speed Centrifugal Pump

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Abstract

Centrifugal pump delivery head and flow rate drop effectively during the pumping of viscous fluids. Several methods and correlations have been developed to predict reduction rate in centrifugal pump performance when handling viscous fluids, but their results are not in very good agreement with each other. In this study, a common industrial low specific speed pump, which is extensively used in different applications, is studied. The entire pump, including impeller, volute, pipes, front and rear sidewall gaps, and balance holes, is simulated in Computational Fluid Dynamics and 3D full Navier Stokes equations are solved. CFD results are compared with experimental data such as pump performance curves, static pressure in casing, and disk friction loss. Dimensionless angular velocity and leakage rate are investigated in sidewall gap and efficiency variation due to viscosity is studied. The results demonstrate that the behavior of the fluid in sidewall gap is strictly sensitive to viscosity. Increasing viscosity improves the volumetric efficiency by reducing internal leakage through wear rings and balance holes, causing, however, a significant fall in the disk and overall efficiency. Results lead to some recommendations for designing centrifugal pumps which may be used in transferring viscous fluids.

1. Introduction

Centrifugal pumps are usually capable of transferring liquids with viscosities lower than 520–760 cSt. The viscosity can be increased to 1000 cSt by using specific impellers. However, for a pump to be economically efficient, the maximum recommended liquid viscosity is 150 cSt [1]. For a small industrial pump with 100 mm impeller radius and 1450 rpm rotational speed, pumping liquid with 150 cSt corresponds to impeller Reynolds number of Re = 10³, while 520 and 760 cSt match Re = 2900 and 2000, respectively. Ippen [2] indicates that the expected efficiency, even for large pumps, for a Reynolds number of 5000 would be on the order of 30 percent.

Performance curves of centrifugal pumps which are presented in manufacturer documents are related to test with cold water. In addition, predicted performance of pumps for handling a viscous fluid is usually calculated by correction charts of some companies such as [3] and the viscosity diagram of Hydraulic Institute Standards [4]. In any pumping system, when water is substituted with a viscous fluid, the absorbed power increases while head and flow rate generated by the pump decrease. This phenomenon results from the reduction in the pump efficiency and is more evident in pumps with low specific speed in which viscosity plays a decisive role in disk friction loss. This kind of loss is the power absorbed for rotating the fluid between external surface of the impeller and internal wall of the casing. In this paper, a low specific centrifugal pump which was originally designed for water handling is investigated to analyze the influence of Reynolds number on efficiency due to pumping viscous fluid.

For a low specific speed centrifugal pump, some research on disk friction loss such as [5–7] was based on simplified model in which there is a rotating disk in a cylinder filled with viscous fluid, with or without radial inflow or outflow as shown in Figure 1. Littell and Eaton [8] measured turbulence characteristics of the boundary layer on an effectively infinite rotating disk in a quiescent environment. Debuchy et al.
[9, 10] presented new law relating the sidewall gap swirl ratio to the dimensionless flow coefficient in a rotor-stator system with superposed flow and, moreover, introducing an analytical modeling of the central core flow in a rotor-stator system with several preswirl conditions.

In recent years, some experimental and numerical investigations into viscosity effect on pump performance have been performed in real centrifugal pumps. Li [11–13] performed an experimental study on performance of centrifugal oil pump and studied numerically the effects of viscosity on centrifugal pump performance. Li [14] also investigated the effect of flow rate and viscosity on slip factor. He obtained the optimum number of blades for pumping liquid with different viscosity and showed some effects of viscosity on fluid regime inside the impeller and volute. Shojaeefard and Boyaghchi [15] accomplished CFD and experimental studies for viscosity effect on velocity in the impeller and indicated that when the blade outlet angle increases, the width of wake at the outlet of impeller decreases, leading to better pump performance in pumping viscous fluids. Nemdili and Hellmann [16] utilized a method to measure disk friction loss and tested disks without and with modified outlet sections with various numbers, angles, and widths. Gülich in 2003 [17] presented different correlations to estimate disk friction loss in closed turbomachine impellers. Juckelandt and Wurm [18] studied the effect of boundary layer on calculating losses in low specific speed pumps and presented some meshing guideline for these types of pumps.

2. Theoretical Analysis

The power consumption of a pump can be defined as

$$P_s = \frac{\rho g Q H}{\eta_v \eta_h} + P_{df} + P_m,$$  

where $\rho$ is fluid density, $Q$ is pump flow rate, $H$ is pump delivery head, $\eta_v$ is volumetric efficiency, $\eta_h$ is hydraulic efficiency, $P_{df}$ is disk friction loss, and $P_m$ is mechanical loss.

By increasing the viscosity the power balance will change in the following way:

(i) With growing the friction factor, the internal leakage through wear rings decreases.

(ii) With increasing Reynolds number, hydraulic efficiency increases.

(iii) Disk friction losses on the impeller sidewalls grow along with the increasing viscosity.

(iv) The mechanical losses are independent of the viscosity of the fluid.

2.1. Disk Friction Loss. The wall shear stress occurring on surfaces of a rotating disk in a casing full of fluid can be written as follows:

$$\tau = \frac{\rho c_f r^2 \omega^2}{2},$$  

where $c_f$ is friction coefficient, $r$ is radius, and $\omega$ is angular velocity of disk. The resultant torque applied to a surface element is

$$dM = r \times dF = r \times \tau dA = \pi \rho c_f r^4 \omega^2 dr.$$  

The friction power of the disk will be

$$P_{df} = \omega \times \int_{r_1}^{r_2} dM = \frac{\pi \rho c_f R^5 \omega^3}{5} \cdot \left(1 - \frac{r_1^5}{R^5}\right),$$  

where $R$ is impeller outer radius.

2.2. Hydraulic Effect. Theoretical head of a centrifugal pump is the sum of the useful head, $H_w$, and the hydraulic losses. It can be demonstrated that the theoretical head, $H_{th}$, is essentially the same when a pump operates with water (subscript $w$) or with viscous fluid (subscript $V$). Hydraulic losses are considered to consist of friction losses, $Z_R$, and mixing losses, $Z_M$ [19]:

$$H_{th} = H_w + Z_{R,v} + Z_{M,v} = H_r + Z_{R,v} + Z_{M,v}.$$  

Friction loss is the term that changes with viscosity; hence, the head correction factor in viscous pumping can be calculated through the following formula [19]:

$$f_H = \frac{H_r}{H_w} = \frac{\eta_{h,v}}{\eta_{h,w}} = 1 - \alpha \left(\frac{C_{f,v}}{C_{f,w}} - 1\right),$$  

where $\alpha$ is the fraction of friction losses to the head and can be defined mostly on geometric features. The correlation which can be used to calculate this fraction for a wide range of specific speed is [19]

$$\alpha = \frac{Z_{R,v}}{H_w} = 0.058 + 0.09 \left(\frac{\eta_v - 30}{30}\right)^2.$$  

More detailed procedure to calculate $C_f$ and $f_H$ can be found in [17, 19].
Table 1: Main dimensions of the investigated pump.

<table>
<thead>
<tr>
<th>Dimension</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Impeller rated diameter (mm)</td>
<td>200</td>
</tr>
<tr>
<td>Impeller full diameter (mm)</td>
<td>209</td>
</tr>
<tr>
<td>Impeller outlet width, $b_2$ (mm)</td>
<td>4.2</td>
</tr>
<tr>
<td>Blade outlet angle, $\beta_2$ (deg)</td>
<td>20</td>
</tr>
<tr>
<td>Number of blades</td>
<td>6</td>
</tr>
<tr>
<td>Number of balance holes</td>
<td>6</td>
</tr>
<tr>
<td>Shroud thickness at impeller tip (mm)</td>
<td>3.7</td>
</tr>
<tr>
<td>Volute base circle diameter (mm)</td>
<td>210</td>
</tr>
<tr>
<td>Suction nozzle diameter (mm)</td>
<td>50</td>
</tr>
<tr>
<td>Discharge nozzle diameter (mm)</td>
<td>40</td>
</tr>
<tr>
<td>Impeller suction eye diameter (mm)</td>
<td>61</td>
</tr>
<tr>
<td>Wear ring radial clearance (mm)</td>
<td>0.4</td>
</tr>
<tr>
<td>Diameter of balance holes (mm)</td>
<td>7</td>
</tr>
<tr>
<td>Hub thickness at impeller tip (mm)</td>
<td>4.1</td>
</tr>
</tbody>
</table>

3. Geometry of the Pump

The investigated pump (Figure 2) is a single-stage, end-suction volute pump with a specific speed of $n_s = 10.3$ at BEP of full diameter impeller and $n_s = 12.8$ at rated impeller. The pump is a back pull-out construction with a six-blade closed impeller and six balance holes so as to reduce the axial thrust. At the design point, the hydraulic specifications of the pump at best efficiency point of rated impeller are $Q = 9 \text{ m}^3/\text{h}$, $H = 10.1 \text{ m}$, $\eta = 46\%$, $N = 1450 \text{ rpm}$, and $P = 0.55 \text{ kW}$ and impeller Reynolds number for pumping water is $Re = 1.5 \times 10^6$. More detailed dimensions can be found in Table 1.

4. Numerical Simulation

The commercial CFD code ANSYS CFX was employed for the numerical simulation of the pump fluid domain (Figure 3) which utilizes a cell-centered control volume with identical nodes for velocity and pressure. A blending factor is computed locally, which is used for the spatial discretization method of the convective terms implemented with a hybrid scheme. The flow was assumed to be at steady state and incompressible and isothermal. Turbulence effects were modeled, using the $k-\omega$ SST procedure with adiabatic wall boundary conditions. This turbulent method, according to several scholars [17, 20], is considered as the best choice for modeling of flow in centrifugal pumps since it has shown a good compromise between accuracy and computational effort even for the region of impeller sidewall gap [21]. Results of similar research such as [15, 18] demonstrate satisfactory results with $k-\omega$ SST model. Moreover, in order to model transition, we benefited the Langtry and Menter correlation and the “Gamma Theta Model” in this simulation.

To achieve an improved mesh quality, for the regions which are located near walls, the structured mesh was used, whereas unstructured mesh was employed for areas away from the wall to properly cover the complex geometry (Figure 4). Therefore, a better conformity between the mesh domain and the complicated geometry has been obtained. The unstructured mesh constitutes six-sided pyramid and wedge-shaped elements.

Orthogonal quality, aspect ratio, and skewness were inspected during the grid generation process, to be in appropriate range. The grids between rotating and stationary parts such as impeller and volute or suction pipe and impeller were adjoined by means of frozen rotor interface. Mass flow rate with flow direction and constant pressure were implemented for inlet and outlet boundary conditions, respectively.

5. Experimental Setup

A closed loop test rig fulfilling the requirements of ISO 9906 [22] was used in order to measure the experimental parameters of the pump. Figure 5 presents a schematic view of the test setup in which the fluid is drawn from the tank (1) with $2.1 \text{ m}^3$ net volume and after passing through a gate valve (2) and suction pipe (1.5m length and 40mm inside diameter) it enters the investigated pump (4) and then returns the tank through the discharge pipe (4m length and 50mm inside diameter). There is a Transverse baffle inside the tank to reduce liquid slosh and ensure the fluid streams into the suction pipe smoothly. The pump is coupled to an AC electric motor (5) whose rated power and speed are 3kW and 1450 rpm, respectively. Pump head is calculated by using pressure transducers with accuracy of 0.25% of the full scale in (3) and (7). The flow rate is adjusted by means of a globe valve (8) located in discharge line of the pump. Steady state flow rate is measured by a magnetic flow meter (9) with the accuracy of 0.5%. To calculate power, the torque and speed of the motor are measured via a torque meter (6) and tachometer, whose accuracies are 0.3% and 0.1% respectively.

To determine the pressure field in the sidewall gap and validate numerical results, peripheral distribution of static pressure is measured by means of pressure transducer with accuracy of 0.25% of the full scale. The signals from the transducers are digitalized by a data acquisition device and, with capturing enough samples, the data are averaged arithmetically. The uncertainties of flow rate, head, power,
and efficiency are approximately 0.5%, 0.3%, 0.5%, and 1%, respectively.

6. Results and Discussion

To validate the CFD simulation, in Table 2, at BEP condition, the results of dimensionless steady state, static pressure, and $p^* = \frac{p}{\rho \omega^2 R^2}$ distribution on the casing wall, around the impeller at $r = 107$ mm for water are shown. The volute is divided into 6 sectors in which there are four holes in the casing wall of each sector. The static pressure was measured in each point and then averaged in each sector. CFD results were also averaged in each sector and are compared to relevant measurements. Volute tongue is located at $\theta = 77^\circ$ in which the pressure fluctuation is greater than the other locations. Experimental data and CFD results are in agreement and the averaged error is about 2%. Results of pumping oil with $\nu = 90$ cSt are also in the same range of error.

Figure 6 presents the comparison between CFD results and experimental data including dimensionless head, $\psi = \frac{gH}{\omega^2 R^2}$, and efficiency versus dimensionless flow rate, $\varphi = \frac{Q}{\omega b_2 R^2}$, where $b_2$ is impeller outlet width and $R$ is impeller outer radius. As it is shown there is a good agreement between CFD and experimental data even in part load and overload regions. The BEP is located in $\varphi = 0.39$ with the head of $\psi = 0.43$. 
Pump performance curve for oil with $v = 90$ cSt ($Re = 17 \times 10^3$) resulting from different method is plotted in Figure 7. The analytic curve is based on calculating the $H_v$ based on value of $f_{H_v}$ from (6) and as it is shown the analytic method is not close to experiments in this matter and may be used for estimation or finding the trend of changing.

The graph published in [3] to calculate the influence of viscosity introduces the procedure yielding the correction factors ($f_Q$ and $f_{H_v}$) as a function of flow rate, head, kinematic viscosity, rotational speed, and also the significant influence of the specific speed, $n_s$. This method is based on measurements with $n_s$ from 6.5 to 45 and viscosity even up to 4000 cSt. Since this method does not take into account the influence of the ratio of the actual flow rate to the flow at the BEP ($q^*$), the results in low flow rate are different from experimental data; however, near BEP it shows accurate results. Thus, this method seems to overpredict the amount of losses for viscous oils and therefore is more cautious method.

CFD curve is obtained from simulating flow in 6 operating points and as it is shown the agreement between the CFD results and experimental data is acceptable especially in lower flow rates. The largest error as expected has occurred in overload condition which is less than 10% in $\varphi = 0.42$

It has been shown in Figure 7 that in low flow rate the effect of viscosity on pump head is smaller than in higher flow rate; therefore, shut-off head of pump with viscous liquid does not differ much from that with water. In this point of view, part load is more preferable than overload in pump selection procedure for delivering viscous fluids. The designer may choose a larger pump, so the operating point will locate in the left side of BEP and thus the effect of viscosity on pump performance will decrease. Table 3 demonstrates the influence of operating point location, at 3 constant absolute flow rate ($q^* = \varphi/\varphi_{BEP}$) on head reduction ($\Delta H^* = (H_w - H_v)/H_w$) based on experimental data.

Figure 8 illustrates the efficiency and absorbed power curve for water and viscous fluid with $v = 90$ cSt ($Re = 17 \times 10^3$) and $\rho = 880$ kg/m$^3$. Based on experimental results, correction factor for flow rate in BEP which is equal to the shift in BEP location due to viscosity is about $f_Q = 0.8$ and efficiency drop in this point is near $f_{\eta} = 0.58$, while Figure 7 shows that the head coefficient reduction compared to water curve is approximately $f_{H^*} = 0.82$. Since the head and flow rate are reduced and the density of the oil is 88% of the

### Table 2: Results of averaged static pressure $p^*$ on casing wall at BEP in six sectors around the impeller ($r = 107$ mm).

<table>
<thead>
<tr>
<th>Sector</th>
<th>CFD</th>
<th>Exp.</th>
<th>Error%</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.390</td>
<td>0.379</td>
<td>2.9%</td>
</tr>
<tr>
<td>2</td>
<td>0.409</td>
<td>0.397</td>
<td>3.0%</td>
</tr>
<tr>
<td>3</td>
<td>0.403</td>
<td>0.403</td>
<td>0%</td>
</tr>
<tr>
<td>4</td>
<td>0.407</td>
<td>0.404</td>
<td>0.7%</td>
</tr>
<tr>
<td>5</td>
<td>0.408</td>
<td>0.403</td>
<td>1.9%</td>
</tr>
<tr>
<td>6</td>
<td>0.405</td>
<td>0.393</td>
<td>2.9%</td>
</tr>
</tbody>
</table>

Figure 6: Comparison of CFD and test results for water.

Figure 7: Comparison of resultant $\psi-\varphi$ curve from different methods ($v = 90$ cSt).

### Table 3: Effect of operating point location on reduction of pump head for three viscous fluids $a = 35$ cSt ($Re = 43 \times 10^3$), $b = 64$ cSt ($Re = 24 \times 10^3$), and $c = 90$ cSt ($Re = 17 \times 10^3$).

<table>
<thead>
<tr>
<th>$q^*$</th>
<th>$\Delta H^*(a)$</th>
<th>$\Delta H^*(b)$</th>
<th>$\Delta H^*(c)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.5</td>
<td>0.07</td>
<td>0.12</td>
<td>0.14</td>
</tr>
<tr>
<td>0.65</td>
<td>0.11</td>
<td>0.17</td>
<td>0.20</td>
</tr>
<tr>
<td>0.8</td>
<td>0.12</td>
<td>0.20</td>
<td>0.26</td>
</tr>
<tr>
<td>1.1</td>
<td>0.25</td>
<td>0.32</td>
<td>0.38</td>
</tr>
</tbody>
</table>

Figure 8: Influence of viscosity on efficiency and shaft power.
When centrifugal pump handles water instead of oil, Reynolds number and leakage flow rate through rings \( \varphi_G \) increase, while both of them are major parameters that affect \( K \). In case of water, dimensionless local angular velocity rises towards the inner radius up to 0.9, whereas for oil (90 cSt) it is less than 0.6. Similar measurement has been taken by Schubert [24] which demonstrates the influence of the leakage flow and Reynolds number on angular velocity. Test result of Hergt and Prager [25] for a centrifugal pump with leakage rate of \( \varphi_G = 0.0008 \) is reported in Figure 12 which shows good agreement with water curve.

Figure 13 compares the influence of decreasing Reynolds number by means of viscous fluid on pump efficiencies at BEP which includes positive effect on volumetric efficiency and negative effect on disk friction and hydraulic efficiencies. According to results of CFD, in case of pumps operating with water (Re = \( 1.5 \times 10^6 \)), volumetric efficiency is about 75%, hydraulic efficiency is 77%, and disk friction efficiency is near 84% and thus overall efficiency is about 47%. By decreasing the Reynolds number to Re = \( 17 \times 10^5 \) in case of pumps operating with oil having 90 cSt viscosity, values change significantly. The volumetric efficiency improves around 20% whereas the hydraulic efficiency reduces by 14% and disk friction efficiency drops by 38% and accordingly the overall efficiency reduces approximately by 21%.

If pumping highly viscous liquid (\( \nu > 90 \text{ cSt} \)) with this pump is intended, it seems that, in Reynolds number smaller than 15000, volumetric efficiency cannot be improved noticeably, while disk friction efficiency will continue to drop dramatically and accordingly the total efficiency will degrade more.

The amount of efficiency data versus oil viscosity is summarized in Table 4. Enhancing the volumetric efficiency is more significant in lower viscosities. For example, when the viscosity increases from 1 to 35 cSt, the volumetric efficiency grows by 14%; however, it grows by just 5% from 35 to 90 cSt. A similar dependency takes place for disk friction efficiency but the rate of reduction is larger in both ranges, that is, 26% drop for viscosity from 1 to 35 cSt and 13% for 35 to 90 cSt. Furthermore, CFD results show that, in case of pumping water, the ratio of disk friction power to shaft power is about 15%, but when the viscosity of fluid is 90 cSt, this
ratio intensely grows up to more than 50%. Consequently, when the viscosity increases, although hydraulic losses due to friction and turbulent dissipation in all components increase, the main reason for degrading the efficiency is disk friction loss which occurs in sidewall gaps.

7. Conclusions

In this paper, the effects of decreasing Reynolds number due to change in viscosity on centrifugal pump performance were studied for a low specific speed pump. The results of CFD agreed well with experimental data in BEP region; however, in overload conditions, the accuracy of CFD was limited. Considering the experimental and numerical investigations, the following conclusions can be made:

(i) In part-load region, the effect of viscosity on pump performance is smaller than that in BEP and overload regions. For 90 cSt oil, head coefficient reduces by just 14% in constant flow rate of $0.5Q_{BEP,w}$ while for $1.1Q_{BEP,w}$ it drops by approximately 38%.

(ii) With decreasing the Reynolds number, the leaked flow through wear rings and balance holes decreases and thus the volumetric efficiency increases remarkably. For wear rings with 0.4 mm clearance, the volumetric efficiency improves by approximately 20%.

Figure 10: Influence of leakage flow on impeller suction regime. Right: water; left: viscous fluid.

Figure 11: Leakage rate through front wear rings versus viscosity and Reynolds number.

Figure 12: Effect of Reynolds number on dimensionless fluid rotational angular velocity.

Table 4: The effect of oil viscosity on pump efficiency, based on CFD results.

<table>
<thead>
<tr>
<th>Oil Viscosity</th>
<th>1 cSt</th>
<th>35 cSt</th>
<th>64 cSt</th>
<th>90 cSt</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\eta_f$</td>
<td>0.75</td>
<td>0.89</td>
<td>0.92</td>
<td>0.94</td>
</tr>
<tr>
<td>$\eta_h$</td>
<td>0.77</td>
<td>0.69</td>
<td>0.66</td>
<td>0.63</td>
</tr>
<tr>
<td>$\eta_{df}$</td>
<td>0.84</td>
<td>0.58</td>
<td>0.50</td>
<td>0.45</td>
</tr>
<tr>
<td>$\eta_m$</td>
<td>0.98</td>
<td>0.98</td>
<td>0.98</td>
<td>0.98</td>
</tr>
<tr>
<td>$\eta_t$</td>
<td>0.47</td>
<td>0.35</td>
<td>0.30</td>
<td>0.26</td>
</tr>
</tbody>
</table>
if the impeller Reynolds number reduces to $17 \times 10^3$ from $1.5 \times 10^6$.

(iii) The dimensionless rotational angular velocity in the sidewall gap drops effectively by decreasing the Reynolds number resulting in greater drag on impeller. 10% and 30% reduction occurs in outer and inner radii, respectively, when decreasing viscosity from $1.5 \times 10^6$ to $17 \times 10^3$.

(iv) Disk friction power increases from 15% of total shaft power to more than 50% when water is replaced with 90 cst fluid. Therefore, although volumetric efficiency improves, the overall efficiency of pump decreased by 21%.

(v) In case of pumping oils, use of expeller for limiting thrust load and very tight wear ring clearance for improving volumetric efficiency should be avoided. Impeller balance holes with optimum rear and front ring clearance may be utilized to prevent undesirable hydraulic and mechanical effects.

**Nomenclature**

- $b_2$: Impeller outlet width
- $C_f$: Friction coefficient
- $D$: Impeller outlet diameter
- $f_{H}$: Viscosity correction factor for head
- $f_{Q}$: Viscosity correction factor for flow rate
- $f_{\eta}$: Viscosity correction factor for efficiency
- $H$: Delivery head
- $K$: Rotation of fluid in impeller sidewall gap = $\beta/\omega$
- $n_t$: Pump specific speed
- $p$: Pressure
- $p^*$: Dimensionless pressure = $p/\rho \omega^2 R^2$
- $P_{df}$: Disk friction power
- $P_i$: Shaft power
- $P_m$: Mechanical power
- $P_u$: Useful hydraulic power
- $Q$: Volume flow rate
- $R$: Impeller outer radius
- $r$: Radius
- $R^*$: Dimensionless radius = $r/R$
- $Re$: Reynolds number = $\omega R^2/\nu$
- $Z_R$: Hydraulic friction losses
- $Z_M$: Hydraulic mixing losses
- $q_0$: Dimensionless leak flow = $Q/\pi \omega R^3$
- $\alpha$: Fraction of friction losses to the head
- $\beta$: Angular velocity of the fluid
- $\nu$: Kinematic viscosity
- $\rho$: Fluid density
- $\psi$: Head coefficient = $gH/\omega^2 R^2$
- $\varphi$: Flow coefficient = $Q/\omega b_2 R^4$
- $\pi$: Power coefficient = $P/\omega^2 b_2 R^4$
- $\eta_i$: Pump overall efficiency
- $\eta_v$: Pump volumetric efficiency
- $\eta_h$: Pump hydraulic efficiency
- $\eta_m$: Pump mechanical efficiency
- $\eta_{df}$: Pump disk friction efficiency

**Subscripts**

- $v$: Viscous fluid
- $w$: Water
- th: Theoretical
- BEP: Best efficiency point of pump.

**Competing Interests**

The authors declare that they have no competing interests.

**References**


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