

## Research Article

# On a Quasi-Neutral Approximation of the Incompressible Navier-Stokes Equations

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This paper considers a pressureless Euler-Poisson system with viscosity in plasma physics in the torus  $\mathbf{T}^3$ . We give a rigorous justification of its asymptotic limit toward the incompressible Navier-Stokes equations via quasi-neutral regime using the modulated energy method.

## 1. Introduction

We will consider the following system:

$$\begin{aligned}\partial_t \mathbf{u}^\epsilon + (\mathbf{u}^\epsilon \cdot \nabla) \mathbf{u}^\epsilon &= \mu \Delta \mathbf{u}^\epsilon + \nabla \mathcal{V}^\epsilon, \\ \partial_t n^\epsilon + \operatorname{div} (n^\epsilon \mathbf{u}^\epsilon) &= 0, \\ \Delta \mathcal{V}^\epsilon &= \frac{n^\epsilon - 1}{\epsilon^2},\end{aligned}\tag{1.1}$$

for  $x \in \mathbf{T}^3$  and  $t > 0$ ,  $n^\epsilon \in \mathbb{R}$ ,  $\mathbf{u}^\epsilon \in \mathbb{R}^2$ .  $\epsilon$  is small parameter and  $\mu > 0$  is a constant viscosity coefficient. To solve uniquely the Poisson equation, we add the  $\int_{\mathbf{T}^3} n^\epsilon dx = 1$ . Passing to the limit when  $\epsilon \rightarrow 0$ , it is easy to see, at least at a very formal level, that  $(n^\epsilon, \mathbf{u}^\epsilon)$  tends to  $(n^{\text{NS}}, \mathbf{u}^{\text{NS}})$ , where  $n^{\text{NS}} = 1$  and

$$\begin{aligned}\partial_t \mathbf{u}^{\text{NS}} + (\mathbf{u}^{\text{NS}} \cdot \nabla) \mathbf{u}^{\text{NS}} &= \mu \Delta \mathbf{u}^{\text{NS}} + \nabla \mathcal{V}^{\text{NS}}, \\ \operatorname{div} \mathbf{u}^{\text{NS}} &= 0.\end{aligned}\tag{1.2}$$

In other words,  $\mathbf{u}^{\text{NS}}$  is a solution of the incompressible Navier-Stokes equations. The aim of this paper is to give a rigorous justification to this formal computation.

The Euler-Poisson system with viscosity (1.1) is a physical model involving dissipation see [1], which here could be regarded as a viscous approximation of Euler-Poisson. Formally, it is a kind of new approximation of the incompressible Navier-Stokes equations of viscous fluid in real world.

It should be pointed out that there have been a lot of interesting results about the topic on the quasi-neutral (or called zero-Debye length) limit, for the readers to see [2–5] for isentropic Euler-Poisson system, [6, 7] for nonisentropic Euler-Poisson system, [8–10] for Vlasov-Poisson system, [11, 12] for drift-diffusion system, [13] for Euler-Maxwell equations, and therein references. We also mention that the above limit has been studied in [14, 15]. But in this present paper, the convergence result and the method of its proof is different from that of [14, 15].

The main focus in this paper is on the use of modulated energy techniques and div-curl for studying incompressible fluids. And for that, we assume that  $n^\epsilon(x, \cdot)$  has total mass equal to 1 and the mean values of  $\mathbf{u}^\epsilon$  vanish, that is,  $\mathbf{m}(\mathbf{u}^\epsilon) = (1/(2\pi)^3) \int_{\mathbb{T}^3} \mathbf{u}^\epsilon dx = 0$ . We also restrict ourselves to the case of well-prepared initial data and the case of periodic torus. Indeed, the quasi-neutral limit is much more difficult without these assumptions.

In this note, we will use some inequalities in Sobolev spaces, such as basic Moser-type calculus inequalities, Young inequality, and Gronwall inequality.

The paper is organized as follows. In Section 2 we state our main result. Estimates and proofs are given in Section 3.

## 2. Main Result

Throughout the paper, we will denote by  $C$  a number independent of  $\epsilon$ , which actually may change from line to line. Moreover  $(\cdot, \cdot)$  and  $\|\cdot\|$  stand for the usual  $L^2$  scalar product and norm,  $\|\cdot\|_s$  is the usual  $H^s$  Sobolev norm, and  $\|\cdot\|_{s,\infty}$  is the usual  $W^{s,\infty}$  norm.

The study of the asymptotic behavior of the sequence  $(\mathbf{u}^\epsilon, n^\epsilon)$ , as  $\epsilon$  goes to zero, leads to the statement of our main result.

**Theorem 2.1.** *Let  $\mathbf{u}^{\text{NS}}$  be a solution of the incompressible Euler equations (1.2) such that  $\mathbf{u}^{\text{NS}} \in ([0, T], H^{s+3}(\mathbb{T}^3))$  and  $\int_{\mathbb{T}^3} \mathbf{u}^{\text{NS}} dx = 0$  for  $s > (5/2)$ . Assume that  $(n_0^\epsilon, \mathbf{u}_0^\epsilon)$  be a sequence of initial data such that  $\int_{\mathbb{T}^3} n_0^\epsilon dx = 1$ ,  $\int_{\mathbb{T}^3} \mathbf{u}_0^\epsilon dx = 0$  and*

$$\begin{aligned} \left\| \mathbf{u}_0^\epsilon - \mathbf{u}_0^{\text{NS}} \right\|_{s+1} &\leq C\epsilon, \\ \|n_0^\epsilon - 1\|_s &\leq C\epsilon^2 \end{aligned} \quad (2.1)$$

*with  $\mathbf{u}_0^{\text{NS}} = \mathbf{u}^{\text{NS}}|_{t=0}$ . Then there is a sequence  $(n^\epsilon, \mathbf{u}^\epsilon) \in C([0, T], H^s \times H^{s+1}(\mathbb{T}^3))$  of solutions to (1.1) with initial data  $(n_0^\epsilon, \mathbf{u}_0^\epsilon)$  belonging to  $C([0, T_\epsilon], H^s \times H^{s+1}(\mathbb{T}^3))$  with  $\liminf_{\epsilon \rightarrow 0} T_\epsilon \geq T$ . Moreover for any  $T_1 < T$  and  $\epsilon$  small enough,*

$$\begin{aligned} \left\| \mathbf{u}^\epsilon(t) - \mathbf{u}^{\text{NS}}(t) \right\|_s &\leq C\epsilon, \\ \|n^\epsilon(t) - 1\|_s &\leq C\epsilon^2, \end{aligned} \quad (2.2)$$

*for any  $0 \leq t \leq T_1$ .*

### 3. Proof of the Theorem

If  $(\mathbf{u}^\epsilon, n^\epsilon)$  is a solution to system (1.1), we introduce

$$\begin{aligned}\mathbf{u}^\epsilon &= \mathbf{u}^{\text{NS}} + \epsilon \mathbf{u}, \\ n^\epsilon &= 1 + \epsilon^2 \left( n + \Delta \mathcal{V}^{\text{NS}} \right), \\ \mathcal{V}^\epsilon &= \mathcal{V}^{\text{NS}} + \mathcal{V}.\end{aligned}\tag{3.1}$$

Since the pressure  $\mathcal{V}^{\text{NS}}$  in the incompressible Navier-Stokes equation is given by

$$\Delta \mathcal{V}^{\text{NS}} = \nabla \mathbf{u}^{\text{NS}} : \nabla \mathbf{u}^{\text{NS}},\tag{3.2}$$

where,  $\nabla \mathbf{u} : \nabla \mathbf{v} = \sum_{i,j=1}^3 (\partial_{x_i} \mathbf{u} / \partial_{x_j}) (\partial_{x_j} \mathbf{v} / \partial_{x_i})$ . Then the vector  $(\mathbf{u}^1, n^1, \mathcal{V}^1)$  solves the system

$$\begin{aligned}\partial_t \mathbf{u} + \mathbf{u}^{\text{NS}} \cdot \nabla \mathbf{u} &= \frac{\nabla \mathcal{V}}{\epsilon} - \epsilon (\mathbf{u} \cdot \nabla) \mathbf{u} - (\mathbf{u} \cdot \nabla) \mathbf{u}^{\text{NS}} + \mu \Delta \mathbf{u}, \\ \partial_t n + \mathbf{u}^{\text{NS}} \cdot \nabla n &= -\frac{\text{div } \mathbf{u}}{\epsilon} - \epsilon \text{div} \left( \left( n + \Delta \mathcal{V}^{\text{NS}} \right) \mathbf{u} \right) - \partial_t \Delta \mathcal{V}^{\text{NS}} - \mathbf{u}^{\text{NS}} \cdot \nabla \Delta \mathcal{V}^{\text{NS}}, \\ \Delta \mathcal{V} &= n.\end{aligned}\tag{3.3}$$

As in [16], we make the following change of unknowns:

$$d = \text{div } \mathbf{u}, \quad \mathbf{c} = \text{curl } \mathbf{u}.\tag{3.4}$$

By using the last equation and taking the curl and the divergence of the first equation in (3.5), we get the following system:

$$\begin{aligned}\partial_t d + \mathbf{u}^{\text{NS}} \cdot \nabla d &= \frac{n}{\epsilon} - \epsilon (\mathbf{u} \cdot \nabla) d - \epsilon \nabla \mathbf{u} : \nabla \mathbf{u} - \nabla \mathbf{u} : \nabla \mathbf{u}^{\text{NS}} + \mu \Delta d, \\ \partial_t \mathbf{c} + \mathbf{u}^{\text{NS}} \cdot \nabla \mathbf{c} &= -\epsilon (\mathbf{u} \cdot \nabla) \mathbf{c} - \epsilon (\mathbf{c} \cdot \nabla) \mathbf{u} - (\mathbf{c} \cdot \nabla) \mathbf{u}^{\text{NS}} \\ &\quad + \text{curl} \left( \nabla \mathbf{u}^{\text{NS}} \cdot \mathbf{u} - \mathbf{u} \cdot \nabla \mathbf{u}^{\text{NS}} \right) - \epsilon d \mathbf{c} + \mu \Delta \mathbf{c}, \\ \partial_t n + \mathbf{u}^{\text{NS}} \cdot \nabla n &= -\frac{d}{\epsilon} - \epsilon (\mathbf{u} \cdot \nabla) n - \epsilon \left( n + \Delta \mathcal{V}^{\text{NS}} \right) d - \mathbf{u} \cdot \nabla \Delta \mathcal{V}^{\text{NS}} - \left( \partial_t + \mathbf{u}^{\text{NS}} \cdot \nabla \right) \Delta \mathcal{V}^{\text{NS}}.\end{aligned}\tag{3.5}$$

This last system can be written as a singular perturbation of a quasilinear symmetrizable hyperbolic system. Setting  $\mathbb{W}^\epsilon = (d, \mathbf{c}, n)^T$  yields

$$\partial_t \mathbb{W}^\epsilon + A(t, x, \partial_x) \mathbb{W}^\epsilon = \frac{1}{\epsilon} K \mathbb{W}^\epsilon - \epsilon B(t, x, \partial_x) \mathbb{W}^\epsilon + S(\mathbb{W}^\epsilon) + \mu N(\mathbb{W}^\epsilon) + R,\tag{3.6}$$

where

$$\begin{aligned}
 A(t, x, \partial_x) &= \text{diag}(\mathbf{u}^{\text{NS}} \cdot \nabla, \mathbf{u}^{\text{NS}} \cdot \nabla I_3, \mathbf{u}^{\text{NS}} \cdot \nabla), B(t, x, \partial_x) = \text{diag}(\mathbf{u} \cdot \nabla, \mathbf{u} \cdot \nabla I_3, \mathbf{u} \cdot \nabla), \\
 K &= \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \quad N(\mathbb{W}^\epsilon) = \begin{pmatrix} \Delta d \\ \Delta \mathbf{c} \\ 0 \end{pmatrix}, \quad R = \begin{pmatrix} 0 \\ 0 \\ -(\partial_t + \mathbf{u}^{\text{NS}} \cdot \nabla) \Delta \mathcal{U}^{\text{NS}} \end{pmatrix}, \\
 S(\mathbb{W}^\epsilon) &= \begin{pmatrix} -\epsilon \nabla \mathbf{u} : \nabla \mathbf{u} - \nabla \mathbf{u} : \nabla \mathbf{u}^{\text{NS}} \\ -\epsilon(\mathbf{c} \cdot \nabla) \mathbf{u} - (\mathbf{c} \cdot \nabla) \mathbf{u}^{\text{NS}} + \text{curl}(\nabla \mathbf{u}^{\text{NS}} \cdot \mathbf{u} - \mathbf{u} \cdot \nabla \mathbf{u}^{\text{NS}}) - \epsilon d \mathbf{c} \\ -\epsilon(n + \Delta \mathcal{U}^{\text{NS}})d - \mathbf{u} \cdot \nabla \Delta \mathcal{U}^{\text{NS}} \end{pmatrix}.
 \end{aligned} \tag{3.7}$$

For  $|\alpha| \leq s$  with  $s > d/2$ , we set

$$\begin{aligned}
 \mathcal{E}_{\alpha, s}^\lambda(t) &= \frac{1}{2} \left( \|\partial_x^\alpha d\|^2 + \|\partial_x^\alpha \mathbf{c}\|^2 + \|\partial_x^\alpha n\|^2 \right), \\
 \mathcal{E}_s^\lambda(t) &= \sum_{|\alpha| \leq s} \mathcal{E}_{\alpha, s}^\lambda(t).
 \end{aligned} \tag{3.8}$$

Before performing the energy estimate, we apply the operator  $\partial_x^\alpha$  for  $\alpha \in \mathbb{N}^3$  with  $|\alpha| \leq s$  to (3.6), to obtain

$$\begin{aligned}
 \partial_t \partial_x^\alpha \mathbb{W}^\epsilon + A(t, x, \partial_x) \partial_x^\alpha \mathbb{W}^\epsilon &= \frac{1}{\epsilon} K \partial_x^\alpha \mathbb{W}^\epsilon - \epsilon B(t, x, \partial_x) \partial_x^\alpha \mathbb{W}^\epsilon + \partial_x^\alpha S(\mathbb{W}^\epsilon) + \mu \partial_x^\alpha N(\mathbb{W}^\epsilon) \\
 &\quad + [\partial_x^\alpha, A(t, x, \partial_x)] \mathbb{W}^\epsilon - \epsilon [\partial_x^\alpha, B(t, x, \partial_x)] \mathbb{W}^\epsilon + \partial_x^\alpha R.
 \end{aligned} \tag{3.9}$$

Now, we proceed to perform the energy estimates for (3.9) in a classical way by taking the scalar product of system (3.9) with  $\partial_x^\alpha \mathbb{W}^\epsilon$ .

Let us start the estimate of each term. First, since  $A(t, x, \partial_x)$  is symmetric and  $\text{div } \mathbf{u}^{\text{NS}} = 0$ , we have that

$$(A(t, x, \partial_x) \partial_x^\alpha \mathbb{W}^\epsilon, \partial_x^\alpha \mathbb{W}^\epsilon) = - \int_{\mathbb{T}^3} \text{div } \mathbf{u}^{\text{NS}} \left( |\partial_x^\alpha d|^2 + |\partial_x^\alpha \mathbf{c}|^2 + |\partial_x^\alpha n|^2 \right) dx = 0. \tag{3.10}$$

Next, since  $K$  is skew-symmetric, we have that

$$\frac{1}{\epsilon} (K \partial_x^\alpha \mathbb{W}^\epsilon, \partial_x^\alpha \mathbb{W}^\epsilon) = 0. \tag{3.11}$$

By integration by parts, we have

$$-\epsilon (B(t, x, \partial_x) \partial_x^\alpha \mathbb{W}^\epsilon, \partial_x^\alpha \mathbb{W}^\epsilon) = \epsilon \int_{\mathbb{T}^3} \text{div } \mathbf{u} |\partial_x^\alpha \mathbb{W}^\epsilon|^2 dx \leq \|\text{div } \mathbf{u}\|_{0, \infty} \mathcal{E}_s^\epsilon(t) \leq (\mathcal{E}_s^\epsilon(t))^{3/2}. \tag{3.12}$$

For later estimates in this paper, we recall some results on Moser-type calculus inequalities in Sobolev spaces [17, 18].

**Lemma 3.1.** *Let  $s \geq 1$  be an integer. Suppose  $u \in H^s(\mathbf{T}^3)$ ,  $\nabla u \in L^\infty(\mathbf{T}^3)$ , and  $v \in H^{s-1}(\mathbf{T}^3) \cap L^\infty(\mathbf{T}^3)$ . Then for all multi-indexes  $|\alpha| \leq s$ , one has  $(\partial_x^\alpha(uv) - u\partial_x^\alpha v) \in L^2(\mathbf{T}^3)$  and*

$$\|\partial_x^\alpha(uv) - u\partial_x^\alpha v\| \leq C_s \left( \|\nabla u\|_{0,\infty} \|D^{|\alpha|-1}v\| + \|D^{|\alpha|}u\| \|v\|_{0,\infty} \right), \quad (3.13)$$

where

$$\|D^h u\| = \sum_{|\alpha|=h} \|\partial_x^\alpha u\|, \quad \forall h \in \mathbb{N}. \quad (3.14)$$

Moreover, if  $s \geq 3$ , then the embedding  $H^{s-1}(\mathbf{T}^3) \hookrightarrow L^\infty(\mathbf{T}^3)$  is continuous and one has

$$\|uv\|_{s-1} \leq C_s \|u\|_{s-1} \|v\|_{s-1}, \quad \|\partial_x^\alpha(uv) - u\partial_x^\alpha v\| \leq C_s \|u\|_s \|v\|_{s-1}. \quad (3.15)$$

By using basic Moser-type calculus inequalities and Sobolev's lemma, we have

$$(\partial_x^\alpha S(\mathbb{W}^\epsilon), \partial_x^\alpha \mathbb{W}^\epsilon) \leq C \mathcal{E}_s^\epsilon(t) + C \epsilon (\mathcal{E}_s^\epsilon(t))^{3/2}. \quad (3.16)$$

After a direct calculation, one gets

$$\mu(\partial_x^\alpha N(\mathbb{W}^\epsilon), \partial_x^\alpha \mathbb{W}^\epsilon) = -\mu \int_{\mathbf{T}^3} \left( |\nabla \partial_x^\alpha d|^2 + |\nabla \partial_x^\alpha \mathbf{c}|^2 \right) dx. \quad (3.17)$$

To estimate the commutator, we have

$$\begin{aligned} & ([\partial_x^\alpha, A(t, x, \partial_x)] \mathbb{W}^\epsilon, \partial_x^\alpha \mathbb{W}^\epsilon) \\ &= \int \left( [\partial_x^\alpha, \mathbf{u}^{\text{NS}} \cdot \nabla] d \partial_x^\alpha d + [\partial_x^\alpha, \mathbf{u}^{\text{NS}} \cdot \nabla] \mathbf{c} \partial_x^\alpha \mathbf{c} + [\partial_x^\alpha, \mathbf{u}^{\text{NS}} \cdot \nabla] n \partial_x^\alpha n \right) dx \\ &\leq C \left( \|\mathbf{u}^{\text{NS}}\|_s \|\nabla d\|_{0,\infty} + \|\mathbf{u}^{\text{NS}}\|_{0,\infty} \|\nabla d\|_{s-1} \right) \|d\|_s \\ &\quad + C \left( \|\mathbf{u}^{\text{NS}}\|_s \|\nabla \mathbf{c}\|_{0,\infty} + \|\mathbf{u}^{\text{NS}}\|_{0,\infty} \|\nabla \mathbf{c}\|_{s-1} \right) \|\mathbf{c}\|_s \\ &\quad + C \left( \|\mathbf{u}^{\text{NS}}\|_s \|\nabla n\|_{0,\infty} + \|\mathbf{u}^{\text{NS}}\|_{0,\infty} \|\nabla n\|_{s-1} \right) \|n\|_s \\ &\leq C \mathcal{E}_s(t). \end{aligned} \quad (3.18)$$

Also, we have

$$\begin{aligned}
& -\epsilon([\partial_x^\alpha B(t, x, \partial_x)]\mathbb{W}^\epsilon, \partial_x^\alpha \mathbb{W}^\epsilon) \\
& = -\epsilon \int ([\partial_x, \mathbf{u} \cdot \nabla] d \partial_x^\alpha d + [\partial_x, \mathbf{u} \cdot \nabla] \mathbf{c} \partial_x^\alpha \mathbf{c} + [\partial_x, \mathbf{u} \cdot \nabla] n \partial_x^\alpha n) dx \\
& \leq C\epsilon(\|\mathbf{u}\|_s \|\nabla d\|_{0,\infty} + \|\mathbf{u}\|_{0,\infty} \|\nabla d\|_{s-1}) \|d\|_s \\
& \quad + C\epsilon(\|\mathbf{u}\|_s \|\nabla \mathbf{c}\|_{0,\infty} + \|\mathbf{u}\|_{0,\infty} \|\nabla \mathbf{c}\|_{s-1}) \|\mathbf{c}\|_s \\
& \quad + C\epsilon(\|\mathbf{u}\|_s \|\nabla n\|_{0,\infty} + \|\mathbf{u}\|_{0,\infty} \|\nabla n\|_{s-1}) \|n\|_s \\
& \leq C\epsilon(\mathcal{E}_s^\epsilon(t))^{3/2}.
\end{aligned} \tag{3.19}$$

Here, we have used the inequality

$$\|\mathbf{u}\|_s \leq C\|\nabla \mathbf{u}\|_{s-1} \leq C(\|d\|_{s-1} + \|\mathbf{c}\|_{s-1}). \tag{3.20}$$

Finally, the Young inequality gives

$$(\partial_x^\alpha R, \partial_x^\alpha \mathbb{W}^\epsilon) \leq \left\| \partial_t \Delta \mathcal{V}^{\text{NS}} + \mathbf{u}^{\text{NS}} \cdot \nabla \Delta \mathcal{V}^{\text{NS}} \right\|_s \|n\|_s \leq C(1 + \mathcal{E}_s^\epsilon(t)). \tag{3.21}$$

Notice that, to get the last line, we have used (3.2).

Now, we collect all the previous estimates (3.10)–(3.21) and we sum over  $\alpha$  to find

$$\frac{d}{dt} \mathcal{E}_s^\epsilon(t) \leq C \left( 1 + \mathcal{E}_s^\epsilon(t) + \epsilon(E_s^\epsilon)^{3/2}(t) \right). \tag{3.22}$$

We can conclude using a standard Gronwall's lemma, that if the solution  $(\mathbf{u}^{\text{NS}}, \mathcal{V}^{\text{NS}})$  of Navier-Stokes equations (1.2) is smooth on the time interval  $[0, T]$ , for any  $T_1 < T$  there exists  $\epsilon_0$  such that the sequence  $(\mathbb{W}^\epsilon)_{\epsilon < \epsilon_0}$  is bounded in  $C([0, T_1], H^s(\mathbf{T}^3))$ . Then we have

$$\begin{aligned}
\mathbb{W}^\epsilon &= (\operatorname{div} \mathbf{u}, \operatorname{curl} \mathbf{u}, n), \\
\mathbf{u}^\epsilon &= \mathbf{u}^{\text{NS}} + \epsilon \mathbf{u}, \\
n^\epsilon &= 1 + \epsilon^2 \left( n + \Delta \mathcal{V}^{\text{NS}} \right).
\end{aligned} \tag{3.23}$$

The assumptions that we have made on the initial data imply that  $(1/\epsilon)(\mathbf{u}^\epsilon - \mathbf{u}^{\text{NS}})$ ,  $(1/\epsilon^2)(n - 1)$  is bounded. This proves Theorem 2.1.

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