

Research Article

Some Results on Super Quasi-Einstein Manifolds

Shyamal Kumar Hui¹ and Richard S. Lemence^{2,3}

¹ Nikhil Banga Sikshan Mahavidyalaya, Bishnupur, 722122 West Bengal, Bankura, India

² Institute of Mathematics College of Science, University of the Philippines Diliman,
 Quezon City 1101, Philippines

³ Academic Production, Ochanomizu University, 2-1-1 Otsuka, Bunkyo-ku, Tokyo 112-8610, Japan

Correspondence should be addressed to Richard S. Lemence, rslemence@gmail.com

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This paper deals with the study of super quasi-Einstein manifolds admitting W_2 -curvature tensor. The totally umbilical hypersurfaces of $S(QE)_n$ are also studied. Among others, the existence of such a manifold is ensured by a nontrivial example.

1. Introduction

It is well known that a Riemannian manifold (M^n, g) ($n > 2$) is Einstein if its Ricci tensor S of type $(0, 2)$ is of the form $S = ag$, where a is a constant, which turns into $S = (r/n)g$, r being the scalar curvature (constant) of the manifold. Let (M^n, g) ($n > 2$) be a Riemannian manifold. Let $U_S = \{x \in M : S \neq (r/n)g \text{ at } x\}$, then the manifold (M^n, g) is said to be quasi-Einstein manifold [1–12] if on $U_S \subset M$, we have

$$S - ag = bA \otimes A, \quad (1.1)$$

where A is a 1-form on U_S and a, b are some functions on U_S . It is clear that the 1-form A as well as the function b are nonzero at every point on U_S . From the above definition, it follows that every Einstein manifold is quasi-Einstein. In particular, every Ricci-flat manifold (e.g., Schwarzschild spacetime) is quasi-Einstein. The scalars a, b are known as the associated scalars of the manifold. Also, the 1-form A is called the associated 1-form of the manifold defined by $g(X, \rho) = A(X)$ for any vector field X , ρ being a unit vector field, called the generator of the manifold. Such an n -dimensional quasi-Einstein manifold is denoted by $(QE)_n$. The quasi-Einstein manifolds have also been studied by De and Ghosh [13], Shaikh et al. [14], and Shaikh and Patra [15].

As a generalization of quasi-Einstein manifold, Chaki [16] introduced the notion of generalized quasi-Einstein manifolds. A Riemannian manifold (M^n, g) ($n > 2$) is said to be generalized quasi-Einstein manifold if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the following:

$$S(X, Y) = ag(X, Y) + bA(X)A(Y) + c[A(X)B(Y) + A(Y)B(X)], \quad (1.2)$$

where a, b , and c are scalars of which $b \neq 0$, $c \neq 0$, A, B are nonzero 1-forms such that $g(X, \rho) = A(X)$, $g(X, \mu) = B(X)$ for all X and ρ, μ are two unit vector fields mutually orthogonal to each other. In such a case, a, b , and c are called the associated scalars, A, B are called the associated 1-forms, and ρ, μ are the generators of the manifold. Such an n -dimensional manifold is denoted by $G(QE)_n$.

In [17], Chaki also introduced the notion of super quasi-Einstein manifold. A Riemannian manifold (M^n, g) ($n > 2$) is called super quasi-Einstein manifold if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the following:

$$S(X, Y) = ag(X, Y) + bA(X)A(Y) + c[A(X)B(Y) + A(Y)B(X)] + dD(X, Y), \quad (1.3)$$

where a, b, c , and d are nonzero scalars, A, B are two nonzero 1-forms such that $g(X, \rho) = A(X)$, $g(X, \mu) = B(X)$ for all vector fields X , and ρ, μ are unit vectors such that ρ is perpendicular to μ and D is a symmetric $(0, 2)$ tensor with zero trace, which satisfies the condition $D(X, \rho) = 0$ for all vector fields X . Here, a, b, c , and d are called the associated scalars, A, B are the associated 1-forms of the manifold, and D is called the structure tensor. Such an n -dimensional manifold is denoted by $S(QE)_n$. The super quasi-Einstein manifolds have also been studied by Debnath and Konar [18], Özgür [19], and many others.

In 1970, Pokhariyal and Mishra [20] introduced new tensor fields, called W_2 and E tensor fields, in a Riemannian manifold and studied their properties. According to them, a W_2 -curvature tensor on a manifold (M^n, g) ($n > 2$) is defined by

$$W_2(X, Y)Z = R(X, Y)Z + \frac{1}{n-1} [g(X, Z)QY - g(Y, Z)QX], \quad (1.4)$$

where Q is the Ricci operator, that is, $g(QX, Y) = S(X, Y)$ for all X, Y . In this connection, it may be mentioned that Pokhariyal and Mishra [20, 21] and Pokhariyal [22] introduced some new curvature tensors defined on the line of Weyl projective curvature tensor.

The W_2 -curvature tensor was introduced on the line of Weyl projective curvature tensor, and by breaking W_2 into skew-symmetric parts, the tensor E has been defined. Rainich conditions for the existence of the nonnull electrovariance can be obtained by W_2 and E if we replace the matter tensor by the contracted part of these tensors. The tensor E enables to extend Pirani formulation of gravitational waves to Einstein space [23, 24]. It is shown that [20] except the vanishing of complexion vector and property of being identical in two spaces which are in geodesic correspondence, the W_2 -curvature tensor possesses the properties almost similar to the Weyl projective curvature tensor. Thus, we can very well use W_2 -curvature tensor in various physical and geometrical spheres in place of the Weyl projective curvature tensor.

The W_2 -curvature tensor has also been studied by various authors in different structures such as De and Sarkar [25], Matsumoto et al. [26], Pokhariyal [23, 24, 27],

Shaikh et al. [28], Shaikh et al. [29], Taleshian and Hosseinzadeh [30], Tripathi and Gupta [31], Venkatesha et al. [32], and Yıldız and De [33].

Motivated by the above studies, in Section 3, we study W_2 -curvature tensor of a super quasi-Einstein manifold. It is proved that if in an $S(QE)_n$ ($n > 2$) the associated scalars are constants, the structure tensor is of Codazzi type and the generators ρ and μ are vector fields with the associated 1-forms A and B not being the 1-forms of recurrences, then the manifold is W_2 -conservative.

Recently, Özen and Altay [34] studied the totally umbilical hypersurfaces of weakly and pseudosymmetric spaces. Again, Özen and Altay [35] also studied the totally umbilical hypersurfaces of weakly concircular and pseudoconcircular symmetric spaces. In this connection, it may be mentioned that Shaikh et al. [36] studied the totally umbilical hypersurfaces of weakly conharmonically symmetric spaces. Section 4 deals with the study of totally umbilical hypersurfaces of $S(QE)_n$. It is proved that the totally umbilical hypersurfaces of $S(QE)_{n+1}$ are $S(QE)_n$ if and only if the hypersurface is a totally geodesic hypersurface.

Finally, in the last section, the existence of super quasi-Einstein manifold is ensured by a nontrivial example.

2. Preliminaries

In this section, we will obtain some formulas of $S(QE)_n$, which will be required in the sequel. Let $\{e_i : i = 1, 2, \dots, n\}$ be an orthonormal frame field at any point of the manifold, then setting $X = Y = e_i$ in (1.3) and taking summation over i , $1 \leq i \leq n$, we obtain

$$r = na + b, \quad (2.1)$$

where r is the scalar curvature of the manifold.

Also from (1.3), we have

$$S(X, \rho) = (a + b)A(X) + cB(X), \quad (2.2)$$

$$S(\rho, \rho) = (a + b), \quad (2.3)$$

$$S(X, \mu) = aB(X) + cA(X) + dD(X, \mu), \quad (2.4)$$

$$S(\mu, \mu) = a + dD(\mu, \mu), \quad (2.5)$$

$$S(\rho, \mu) = c. \quad (2.6)$$

3. W_2 -Curvature Tensor of $S(QE)_n$

Let a manifold M be an $S(QE)_n$ ($n > 2$), which is W_2 -flat, then from (1.4), we get

$$R(Y, Z, U, V) = \frac{1}{n-1} [g(Z, U)S(Y, V) - g(Y, U)S(Z, V)]. \quad (3.1)$$

Setting $U = \rho$ and $V = \mu$ in (3.1) and using (2.2) and (2.4), we obtain

$$R(Y, Z, \rho, \mu) = \frac{a}{n-1} [A(Z)B(Y) - A(Y)B(Z)] + \frac{d}{n-1} [A(Z)D(Y, \mu) - A(Y)D(Z, \mu)]. \quad (3.2)$$

Again, plugging $U = \mu$ and $V = \rho$ in (3.1) and using (2.2) and (2.4), we get

$$R(Y, Z, \mu, \rho) = \frac{a+b}{n-1} [A(Y)B(Z) - A(Z)B(Y)]. \quad (3.3)$$

From (3.2) and (3.3), we have

$$A(Z) [bB(Y) - dD(Y, \mu)] = A(Y) [bB(Z) - dD(Z, \mu)], \quad (3.4)$$

that is,

$$A(Z)E(Y) = A(Y)E(Z), \quad (3.5)$$

where $E(Y) = g(Y, \sigma) = bB(Y) - dD(Y, \mu)$ for all Y . From (3.5), we may conclude that the two vector fields ρ and σ are codirectional, provided $E \neq 0$.

If $E(Y) = 0$, then we have

$$D(Y, \mu) = \frac{b}{d}B(Y) = \frac{b}{d}g(Y, \mu) \quad \text{since } \delta \neq 0, \quad (3.6)$$

which implies that b/d is an eigenvalue of the tensor D corresponding to the eigenvector σ . Thus, we have the following result.

Theorem 3.1. *Let a manifold M be a W_2 -flat $S(QE)_n$ ($n > 2$) such that b/d is not an eigenvalue of the tensor D corresponding to the eigenvector σ defined by $E(Y) = g(Y, \sigma) = bB(Y) - dD(Y, \mu)$, then the vector fields ρ and σ corresponding to the 1-forms A and E , respectively, are codirectional.*

From (1.4), we get that

$$(\operatorname{div} W_2)(Y, Z)U = (\operatorname{div} R)(Y, Z)U + \frac{1}{2(n-1)} [dr(Z)g(Y, U) - dr(Y)g(Z, U)], \quad (3.7)$$

where “div” denotes the divergence.

Again, it is known that in a Riemannian manifold, we have

$$(\operatorname{div} R)(Y, Z)U = (\nabla_Y S)(Z, U) - (\nabla_Z S)(Y, U). \quad (3.8)$$

Consequently, by virtue of the above relation, (3.7) takes the form

$$(\operatorname{div} W_2)(Y, Z)U = (\nabla_Y S)(Z, U) - (\nabla_Z S)(Y, U) + \frac{1}{2(n-1)} \{dr(Z)g(Y, U) - dr(Y)g(Z, U)\}. \quad (3.9)$$

We now consider the associated scalars a, b, c , and d as constants, then (2.1) yields that the scalar curvature r is constant, and hence $dr(X) = 0$ for all X . Consequently, (3.9) yields

$$(\operatorname{div} W_2)(Y, Z)U = (\nabla_Y S)(Z, U) - (\nabla_Z S)(Y, U). \quad (3.10)$$

Since a, b, c , and d are constants, we have from (1.3) that

$$\begin{aligned} (\nabla_Y S)(Z, U) = & b[(\nabla_Y A)(Z)A(U) + A(Z)(\nabla_Y A)(U)] \\ & + c[(\nabla_Y A)(Z)B(U) + A(Z)(\nabla_Y B)(U) \\ & + (\nabla_Y A)(U)B(Z) + A(U)(\nabla_Y B)(Z)] + d(\nabla_Y D)(Z, U). \end{aligned} \quad (3.11)$$

We now assume that the structure tensor D of such as $S(QE)_n$ is of Codazzi type [37], then for all vector fields Y, Z , and U , we have

$$(\nabla_Y D)(Z, U) = (\nabla_Z D)(Y, U). \quad (3.12)$$

By virtue of (3.11) and (3.12), (3.10) yields

$$\begin{aligned} (\operatorname{div} W_2)(Y, Z)U = & b[(\nabla_Y A)(Z)A(U) + A(Z)(\nabla_Y A)(U) \\ & - (\nabla_Z A)(Y)A(U) - A(Y)(\nabla_Z A)(U)] \\ & + c[(\nabla_Y A)(Z)B(U) + A(Z)(\nabla_Y B)(U) \\ & + (\nabla_Y A)(U)B(Z) + A(U)(\nabla_Y B)(Z) \\ & - (\nabla_Z A)(Y)B(U) - A(Y)(\nabla_Z B)(U) \\ & - (\nabla_Z A)(U)B(Y) - A(U)(\nabla_Z B)(Y)]. \end{aligned} \quad (3.13)$$

Now, if the generators ρ and μ of the manifold are recurrent vector fields [38], then we have $\nabla_Y \rho = \pi_1(Y)\rho$ and $\nabla_Y \mu = \pi_2(Y)\mu$, where π_1 and π_2 are called the 1-forms of recurrence such that π_1 and π_2 are different from A and B . Consequently, we get

$$\begin{aligned} (\nabla_Y A)(Z) &= g(\nabla_Y \rho, Z) = g(\pi_1(Y)\rho, Z) = \pi_1(Y)A(Z), \\ (\nabla_Y B)(Z) &= g(\nabla_Y \mu, Z) = g(\pi_2(Y)\mu, Z) = \pi_2(Y)B(Z). \end{aligned} \quad (3.14)$$

In view of (3.14), (3.13) turns into

$$\begin{aligned} (\operatorname{div} W_2)(Y, Z)U = & 2b\pi_1(Y)A(Z)A(U) \\ & + c[\{\pi_1(Y) + \pi_2(Y)\}\{A(Z)B(U) + A(U)B(Z)\} \\ & - \{\pi_1(Z) + \pi_2(Z)\}\{A(Y)B(U) + A(U)B(Y)\}]. \end{aligned} \quad (3.15)$$

Since $g(\rho, \rho) = g(\mu, \mu) = 1$, it follows that $(\nabla_Y A)(\rho) = g(\nabla_Y \rho, \rho) = 0$, and hence (3.14) reduces to $\pi_1(Y) = 0$ for all Y . Similarly, we have $\pi_2(Y) = 0$. Hence, from (3.15), we have $(\operatorname{div} W_2)(Y, Z)U = 0$, that is, the manifold under consideration is W_2 -conservative [39]. Hence, we can state the following.

Theorem 3.2. Suppose that a manifold M is an $S(QE)_n$ ($n > 2$) such that associated scalars are constants and the structure tensor is of Codazzi type. If the generators ρ and μ corresponding to the associated 1-forms A and B are not being the 1-forms of recurrences, then the manifold is W_2 -conservative.

4. Totally Umbilical Hypersurfaces of $S(QE)_n$

Let (\bar{V}, \bar{g}) be an $(n+1)$ -dimensional Riemannian manifold covered by a system of coordinate neighbourhoods $\{U, y^\alpha\}$. Let (V, g) be a hypersurface of (\bar{V}, \bar{g}) defined in a locally coordinate system by means of a system of parametric equation $y^\alpha = y^\alpha(x^i)$, where Greek indices take values $1, 2, \dots, n+1$ and Latin indices take values $1, 2, \dots, n$. Let N^α be the components of a local unit normal to (V, g) , then we have

$$\begin{aligned} g_{ij} &= \bar{g}_{\alpha\beta} y_i^\alpha y_j^\beta, \\ \bar{g}_{\alpha\beta} N^\alpha y_j^\beta &= 0, \quad \bar{g}_{\alpha\beta} N^\alpha N^\beta = e = 1, \\ y_i^\alpha y_j^\beta g^{ij} &= \bar{g}^{\alpha\beta} - N^\alpha N^\beta, \quad y_i^\alpha = \frac{\partial y^\alpha}{\partial x^i}. \end{aligned} \quad (4.1)$$

The hypersurface (V, g) is called a totally umbilical hypersurface [40, 41] of (\bar{V}, \bar{g}) if its second fundamental form Ω_{ij} satisfies

$$\Omega_{ij} = H g_{ij}, \quad y_{i,j}^\alpha = g_{ij} H N^\alpha, \quad (4.2)$$

where the scalar function H is called the mean curvature of (V, g) given by $H = (1/n) \sum g^{ij} \Omega_{ij}$. If, in particular, $H = 0$, that is,

$$\Omega_{ij} = 0, \quad (4.3)$$

then the totally umbilical hypersurface is called a totally geodesic hypersurface of (\bar{V}, \bar{g}) .

The equation of Weingarten for (V, g) can be written as $N_{,j}^\alpha = -(H/n) y_j^\alpha$. The structure equations of Gauss and Codazzi [40, 41] for (V, g) and (\bar{V}, \bar{g}) are, respectively, given by

$$\begin{aligned} R_{ijkl} &= \bar{R}_{\alpha\beta\gamma\delta} F_{ijkl}^{\alpha\beta\gamma\delta} + H^2 G_{ijkl}, \\ \bar{R}_{\alpha\beta\gamma\delta} F_{ijk}^{\alpha\beta\gamma} N^\delta &= H_{,i} g_{jk} - H_{,j} g_{ik}, \end{aligned} \quad (4.4)$$

where R_{ijkl} and $\bar{R}_{\alpha\beta\gamma\delta}$ are curvature tensors of (V, g) and (\bar{V}, \bar{g}) , respectively, and

$$F_{ijkl}^{\alpha\beta\gamma\delta} = F_i^\alpha F_j^\beta F_k^\gamma F_l^\delta, \quad F_i^\alpha = y_i^\alpha, \quad G_{ijkl} = g_{il} g_{jk} - g_{ik} g_{jl}. \quad (4.5)$$

Also we have [40, 41]

$$\bar{S}_{\alpha\delta} F_i^\alpha F_j^\delta = S_{ij} - (n-1) H^2 g_{ij}, \quad (4.6)$$

$$\bar{S}_{\alpha\delta} N^\alpha F_i^\delta = (n-1) H_{,i}, \quad (4.7)$$

$$\bar{r} = r - n(n-1) H^2, \quad (4.8)$$

where S_{ij} and $\bar{S}_{\alpha\delta}$ are the Ricci tensors of (V, g) and (\bar{V}, \bar{g}) , respectively, and r and \bar{r} are the scalar curvatures of (V, g) and (\bar{V}, \bar{g}) , respectively.

In terms of local coordinates, the relation (1.3) can be written as

$$S_{ij} = ag_{ij} + bA_iA_j + c[A_iB_j + A_jB_i] + dD_{ij}. \quad (4.9)$$

Let (\bar{V}, \bar{g}) be an $S(QE)_{n+1}$, then we get

$$S_{\alpha\beta} = ag_{\alpha\beta} + bA_\alpha A_\beta + c[A_\alpha B_\beta + A_\beta B_\alpha] + dD_{\alpha\beta}. \quad (4.10)$$

Multiplying both sides of (4.10) by $F_{ij}^{\alpha\beta}$ and then using (4.6) and (4.9), we obtain $H = 0$, which implies that the hypersurface is a totally geodesic hypersurface.

Conversely, we now consider that the hypersurface (V, g) is totally geodesic hypersurface, that is,

$$H = 0. \quad (4.11)$$

In view of (4.11), (4.6) yields

$$\bar{S}_{\alpha\delta} F_i^\alpha F_j^\delta = S_{ij}. \quad (4.12)$$

Using (4.12) in (4.10), we have the relation (4.9). Thus, we can state the following.

Theorem 4.1. *The totally umbilical hypersurface of an $S(QE)_{n+1}$ is an $S(QE)_n$ if and only if the hypersurface is a totally geodesic hypersurface.*

Note that the theorem is a statement on the hypersurface based on the restrictions of the associated scalars and 1-forms coming from the manifold.

5. Example of a Super Quasi-Einstein Manifold

This section deals with a nontrivial example of $S(QE)_4$.

Example 5.1. We define a Riemannian metric g on \mathbb{R}^4 by the formula

$$ds^2 = g_{ij} dx^i dx^j = (dx^1)^2 + e^{x^1} \left[e^{x^2} (dx^2)^2 + e^{x^3} (dx^3)^2 + e^{x^4} (dx^4)^2 \right], \quad (i, j = 1, 2, 3, 4). \quad (5.1)$$

Then, the only nonvanishing components of the Christoffel symbols, the curvature tensor, the Ricci tensor, and the scalar curvature are given by

$$\begin{aligned}
\Gamma_{22}^1 &= -\frac{1}{2}e^{x^1+x^2}, & \Gamma_{33}^1 &= -\frac{1}{2}e^{x^1+x^3}, & \Gamma_{44}^1 &= -\frac{1}{2}e^{x^1+x^4}, \\
\Gamma_{22}^2 &= \frac{1}{2} = \Gamma_{33}^3 = \Gamma_{44}^4 = \Gamma_{12}^2 = \Gamma_{13}^3 = \Gamma_{14}^4, \\
R_{1221} &= \frac{1}{4}e^{x^1+x^2}, & R_{1331} &= \frac{1}{4}e^{x^1+x^3}, & R_{1441} &= \frac{1}{2}e^{x^1+x^4}, \\
R_{2332} &= \frac{1}{4}e^{2x^1+x^2+x^3}, & R_{2442} &= \frac{1}{4}e^{2x^1+x^2+x^4}, & R_{3443} &= \frac{1}{4}e^{2x^1+x^3+x^4}, \\
S_{11} &= \frac{3}{4}, & S_{22} &= \frac{3}{4}e^{x^1+x^2}, & S_{33} &= \frac{3}{4}e^{x^1+x^3}, & S_{44} &= \frac{3}{4}e^{x^1+x^4}, & r &= 3
\end{aligned} \tag{5.2}$$

and the components which can be obtained from these by the symmetry properties. Therefore, \mathbb{R}^4 is a Riemannian manifold (M^4, g) of nonvanishing scalar curvature. We will now show that M^4 is an $S(QE)_4$, that is, it satisfies (1.3). Let us now consider the associated scalars as follows:

$$a = \frac{3}{4}, \quad b = 2e^{x^1}, \quad c = e^{x^1+x^3}, \quad d = \frac{1}{2e^{x^4}}. \tag{5.3}$$

In terms of local coordinate system, let us consider the 1-forms A and B and the structure tensor D as follows:

$$\begin{aligned}
A_i(x) &= \begin{cases} \frac{1}{2} & \text{for } i = 1, \\ \frac{1}{\sqrt{e^{x^1}}} & \text{for } i = 2, \\ 0 & \text{otherwise,} \end{cases} \\
B_i(x) &= \begin{cases} -\frac{1}{e^{x^3}} & \text{for } i = 1, \\ \frac{1}{e^{x^1}} & \text{for } i = 3, \\ 0 & \text{otherwise,} \end{cases} \\
D_{ij}(x) &= \begin{cases} e^{x^1+x^4} & \text{for } i = j = 1, \\ -4e^{x^4} & \text{for } i = j = 2, \\ -e^{x^3+x^4} & \text{for } i = 1, j = 3, \\ -\frac{2e^{x^3+x^4}}{\sqrt{e^{x^1}}} & \text{for } i = 2, j = 3, \\ 0 & \text{otherwise.} \end{cases}
\end{aligned} \tag{5.4}$$

In terms of local coordinate system, the defining condition (1.3) of an $S(QE)_n$ can be written as

$$S_{ij} = ag_{ij} + bA_iA_j + c[A_iB_j + A_jB_i] + dD_{ij}, \quad i, j = 1, 2, 3, 4. \tag{5.5}$$

By virtue of (5.3) and (5.4), it can be easily shown that the relation (5.5) holds for $i, j = 1, 2, 3, 4$. Therefore, (M^4, g) is an $S(QE)_4$, which is neither quasi-Einstein nor generalized quasi-Einstein. Hence, we can state the following.

Theorem 5.2. *Let (M^4, g) be a Riemannian manifold endowed with the metric given in (5.1), then (M^4, g) is an $S(QE)_4$ with nonvanishing scalar curvature which is neither quasi-Einstein nor generalized quasi-Einstein.*

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