

Review Article

A Review of Existing Microgrid Architectures

Lubna Mariam, Malabika Basu, and Michael F. Conlon

Electrical Power Research Centre (EPRC), School of Electrical and Electronic Engineering, Dublin Institute of Technology, Kevin Street, Dublin 8, Ireland

Correspondence should be addressed to Malabika Basu; mbasu@ieee.org

Received 13 December 2012; Revised 28 February 2013; Accepted 2 March 2013

Academic Editor: Keat Teong Lee

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The future electricity network must be flexible, accessible, reliable, and economic according to the worldwide smartgrid initiative. This is also echoed by the Sustainable Energy Authority of Ireland (SEAI) and European Electricity Grid Initiative (EEGI). In order to facilitate these objectives and to reduce green house gas (GHG) emission, research on various configurations of microgrid (μ G) system is gaining importance, particularly with high penetration of renewable energy sources. Depending on the resource availability, geographical locations, load demand, and existing electrical transmission and distribution system, μ G can be either connected to the grid or can work in an autonomous mode. Storage can also be a part of the μ G architecture. This paper presents a critical literature review of various μ G architectures. The benefits of grid-connected or isolated μ G with storage have also been identified.

1. Introduction

The term microgrid (μ G) refers to the concept of single electrical power subsystems associated with a small number of distributed energy resources (DERs), both renewable and/or conventional sources, including photovoltaic, wind power, hydro, internal combustion engine, gas turbine, and micro-turbine together with a cluster of loads [1, 2]. The application of individual distributed energy resources as microgeneration can cause problems such as local voltage rise, the potential to exceed thermal limits of certain lines and transformers, islanding and have high capital cost [3]. Microgrid can be a better solution for these problems. In a μ G system, the DERs must be equipped with proper power electronic interfaces (PEIs) and control to ensure the flexibility to operate as a single aggregated system maintaining the power quality and energy output [4]. From the grid point of view, the main advantage of a μ G is that it is treated as a controlled entity within the power system which can operate as a single load. From customers' point of view, μ Gs are beneficial because they can meet their electrical and heat requirement locally, supply uninterruptible power, improve power quality (PQ), reduce feeder loss, and provide voltage support. Furthermore μ Gs can reduce environmental pollution and global warming by utilizing low-carbon technology [4].

One of the major aims of μ G is to combine benefits of nonconventional/renewable low-carbon generation technologies and high efficient combined heat and power (CHP) systems. The choice of a distributed generator mainly depends on the climate and topology of the region. Sustainability of a μ G system depends on the energy scenario, strategy, and policy of that country and it varies from region to region. These topics are beyond the scope of this review.

This paper critically reviews the existing and simulated μ G systems demonstrated in European regions by classifying their architecture based on integration with the grid, distribution system, communication system, energy resource, and storage. A short description of the advantages and disadvantages of the widely available and feasible distributed generators (DGs) is provided. The benefits of storage and the existing storage devices have been identified. The advantages and disadvantages of different distribution systems are also presented.

2. Basic μ G Architecture

The basic architecture of a μ G system is presented in Figure 1, which shows that a μ G system generally consists of distributed generation (DG) resource, storage systems, distribution systems, and communication and control systems.

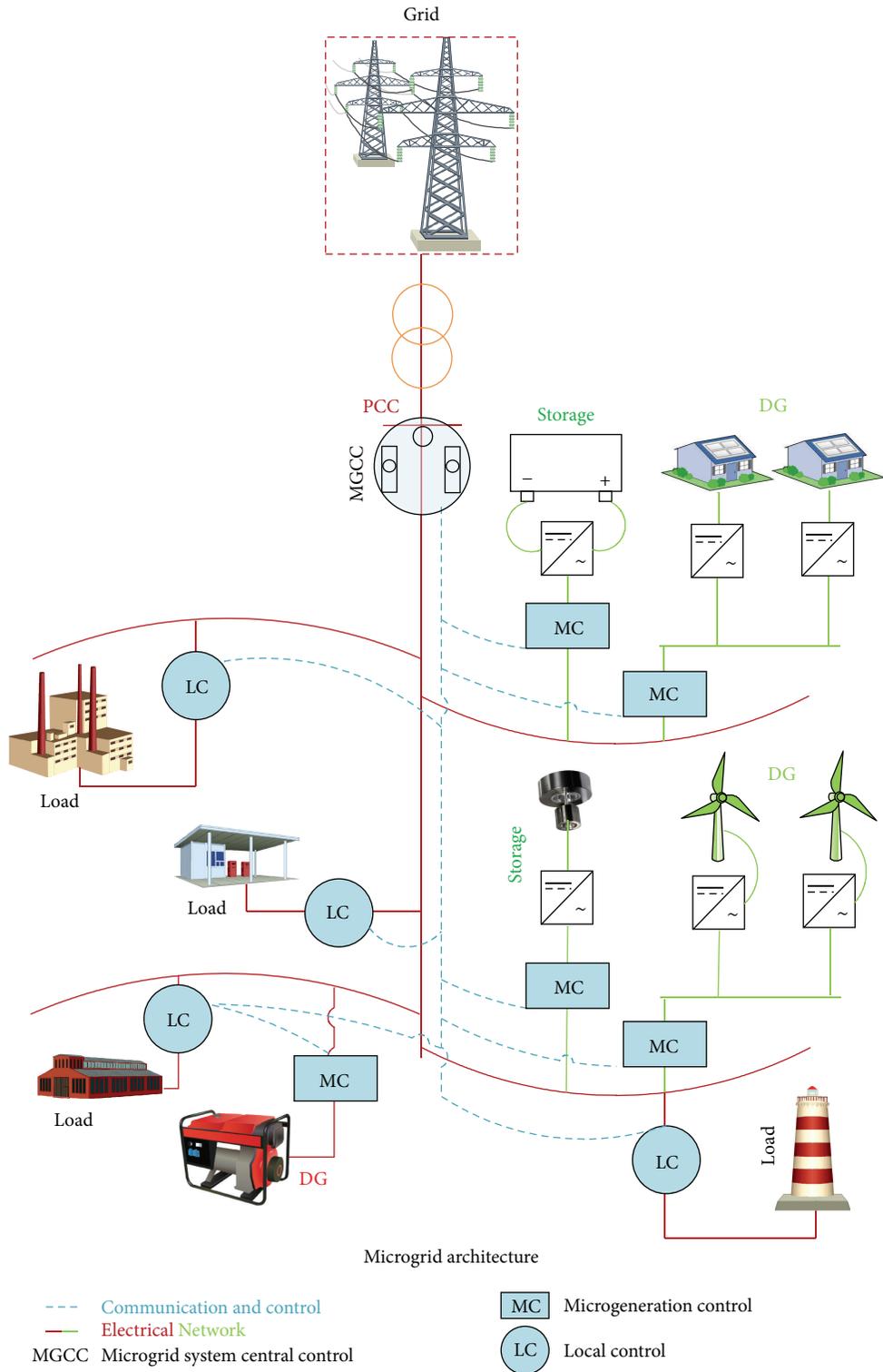


FIGURE 1: A simple microgrid architecture.

2.1. *Distributed Generation (DG) Sources.* Distributed generation technologies applicable for μ G may include emerging technologies such as—wind turbine, solar PV, microhydropower, diesel, and some well-established technologies like single-phase and three-phase induction generators, synchronous generators driven by IC engines [9]. Combined

heat and power (CHP) acts as a total system when heating is also used with electricity. Different kinds of sources are being used in CHP systems such as microturbines (generally driven by natural gas, hydrogen, and biogas), Stirling engines, and IC engines. CHP system allows optimum usage of energy by capturing the excess heat, thereby achieving efficiency

TABLE 1: Typical characteristics of common DG sources [5, 6].

Characteristics	Solar	Wind	Microhydro	Diesel	CHP
Availability	Geographical location dependent	Geographical location dependent	Geographical location dependent	Any time	Dependent on source
Output power	DC	AC	AC	AC	AC
GHG emission	None	None	None	High	Dependent on source
Control	Uncontrollable	Uncontrollable	Uncontrollable	Controllable	Dependent on source
Typical interface	Power electronic converter (DC-DC-AC)	Power electronic converter (AC-DC-AC)	Synchronous or induction generator	None	Synchronous generator
Power flow control	MPPT & DC link voltage controls (+P, \pm Q)	MPPT, pitch & torque control (+P, \pm Q)	Controllable (+P, \pm Q)	Controllable (+P, \pm Q)	AVR and governor (+P, \pm Q)

values of more than 80%, compared to that of about 35% for conventional power plants [14]. Table 1 shows some typical characteristics of commonly used DG sources.

2.1.1. Photovoltaic (PV) System. Solar PV generation involves the generation of electricity from solar energy. Due to enormous improvement in inverter technologies, PV generation is now preferred worldwide as Distributed Energy Resources (DERs). The major advantages of a PV system are

- (i) the sustainable nature of solar energy,
- (ii) positive environmental impact,
- (iii) longer life time and silent operation.

Although photovoltaic (PV) cells can be effectively used as DERs in μ G systems, they have some disadvantages including

- (i) high installation cost,
- (ii) low energy efficiency,
- (iii) restriction to certain locations and weather dependence.

It has been reported that small PV installations are more cost effective than the larger ones [4]. As the nature of PV generation is DC power, a suitable type of power converter must be employed to convert the DC voltage to AC voltage. Some applications of PV system are [15]

- (i) space programs,
- (ii) remote locations where grid electricity is difficult to get,
- (iii) lighting road signs and road light,
- (iv) roof projects for home lighting and heating.

2.1.2. Wind Turbines (WT). Wind turbine converts wind energy into electrical energy using the wind energy conversion systems (WECSs). Wind energy has been popular for decades. Usually induction generators are used in WECSs. The main part of the wind turbine is the tower, the rotor, and the nacelle. The nacelle accommodates the mechanical transmission and the generator. Wind turbine captures the kinetic energy of wind flow through rotor blades and transfers

the energy to the induction generator through the gearbox. The generator shaft is driven by the wind turbine to generate electric power. Wind turbines may have horizontal axis or vertical axis configuration. The average commercial turbine size was 300 kW until the mid 1990s, but recently machines of larger capacity, up to 5 MW and more, have been developed and installed [16].

2.1.3. Micro-Hydropower System. Micro-hydropower system uses the energy of flowing water to produce mechanical or electrical energy. This energy generation system depends on the topography and annual precipitation of the area. The system suffers from large variation of water flow due to uneven rainfall and results in a variation in generation [17]. Run-of-river system is often used in micro-hydropower systems which do not require large storage reservoir. A portion of the river water is diverted to a water-conveyance channel to rotate a turbine or a water wheel that spins a shaft. The motion of the shaft can be used for mechanical power such as pumping water or can be used to power a generator to generate electricity.

2.2. Storage Systems. One of the main criteria of successful operation of μ G is the inclusion of energy storage devices, which balances the short-term power and energy demand with generation. Generally the μ G power systems have storage through the generator inertia. When a new load comes online, it can result in a slight change in system frequency depending on its size [18]. Lasseter in [2] concluded that a system with several micro sources designed to operate in an island mode must provide some storage option to ensure energy balance. In case of some micro sources (such as fuel cells and microturbines), with large time constants in the range of 10 to 200s, storage devices are very important to balance the power following system disturbance and/or significant load changes [18]. In the case of sudden system changes, these devices can act as an AC voltage source. Because of their physical limitations, they have limited energy storage capacity. The backup energy storage devices should be included in μ G systems to ensure uninterrupted power supply. Suitable storage devices for μ G system include batteries, flywheels and supercapacitors [19]. According to a report by Zpryme in [20], battery-energy storage technology will be in highest demand over the next 5 years. Table 2 summarizes some basic

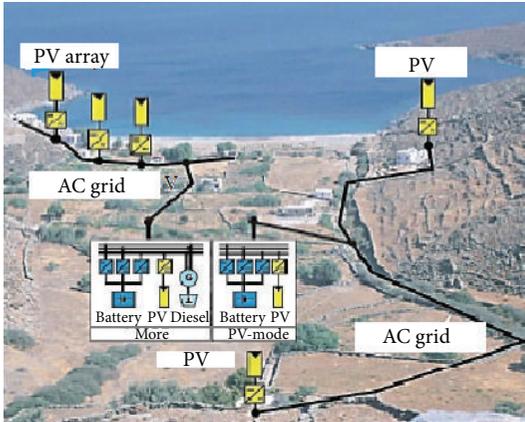
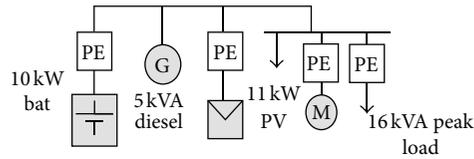


FIGURE 2: μ G system with PV, diesel, and storage [7].

features about these three storage devices. The table shows that the three storage devices show the same efficiency around 90 to 95%. Whereas in terms of current price, battery is less expensive than the other two. Besides that battery has high negative environmental impact whereas the other two have lesser impact on the environment. Life time of flywheel and supercapacitor is more than 10 years but battery has 5 years at best and it needs servicing each year.

Another storage option can be fuel cell that converts chemical energy of a fuel directly into electrical energy. They can be described as batteries which never discharge as long as hydrogen and oxygen are continuously provided. The output of the generator is 1kW–10 MW. Electrical efficiency is 30–60% and overall efficiency is 80–85%. Moreover, they can use a variety of fuels such as natural gas, propane, landfill gas, anaerobic digester gas, diesel, naphtha, methanol, and hydrogen [21, 22].

Figures 2 and 3 present two μ G configurations with and without storage system. Figure 2 presents Kythnos μ G which is located in a remote island in Greece. In this μ G, solar PV system and diesel are used as DG sources and battery as storage system. This μ G is isolated and electrifies 12 houses in the island. Figure 3 presents Ramea integrated wind-diesel project in Canada. Wind energy and diesel have been used as DG sources in this μ G. The important feature of this μ G is that it is grid connected and it does not have any storage system.

2.3. *Distribution Systems.* The distribution network can be classified as three types:

- (i) DC line,
- (ii) 60/50 Hz AC line (line frequency),
- (iii) high-frequency AC (HFAC).

TABLE 2: Basic features of suitable storage devices in μ G system [7].

Basic features	Battery	Flywheel	Supercapacitor
Continuous power (W/kg)	50–100	200–500	500–2000
Typical backup time	5–30 min	10–30 sec	10–30 sec
Losses at standby	Very low	Variable	High
Environmental impact	Medium-high	Low	Low
Maintenance	1/year	1/5 years	None
Charging efficiency (%)	75–95	90	85–95
Current energy price (\$/kWh)	150–800	3000–4000	4000–5000
Service life (year)	5	20	>10

2.3.1. *DC Line.* As most of the DERs generate DC power and the DC distribution system has no power quality problems, research on DC μ G system is getting importance. But most of the loads are operated in AC system; hence, DC distribution system may not be popular yet. Figure 4 shows a DC μ G system.

2.3.2. *AC Line (Line Frequency).* μ Gs are generally line frequency μ Gs. The DERs are connected in a common bus in the μ G. The DC current from DERs is transformed to 50 Hz AC by a suitable inverter and then transmitted to the load side. Figure 5 shows an AC μ G system.

2.3.3. *High Frequency AC (HFAC).* There are many ways to connect distributed energy sources in μ G system. Using HFAC to transmit electricity in μ G is a new concept which is still at the developmental stage. In HFAC μ G, the DERs are connected to a common bus. The electricity generated by the DERs is transformed to 500 Hz AC by power electronics devices and is transmitted to the load side; it is again converted to 50 Hz AC by an AC/AC converter.

The load is connected to the distribution network, which can guarantee an effective interaction between μ G and distribution network. At higher frequency the harmonics of higher order are filtered thus limiting PQ problems. But disadvantage is that HFAC improves line reactance and increases power loss [23]. Figure 6 shows a HFAC μ G system.

2.4. *Power Quality Issue Related to Distribution Systems.* Power quality in μ G system has become an important issue as the penetration of DG systems either connected to the grid or μ G increases. Solar, wind, micro-hydro, and diesel are the most leading sources of DG systems and therefore power quality problems related to these DG systems have been identified in [8, 24] and shown in Table 3. The table shows that most commonly used renewable energy sources (RESs) such as solar PV and wind energy systems can have almost all the PQ problems such as voltage sag/swell, over/under voltage, voltage and current harmonics, and flicker. Because of the varying nature of wind and sun, the abrupt changes in wind condition (velocity, direction, turbulence, etc.), and



Ramea wind-diesel project

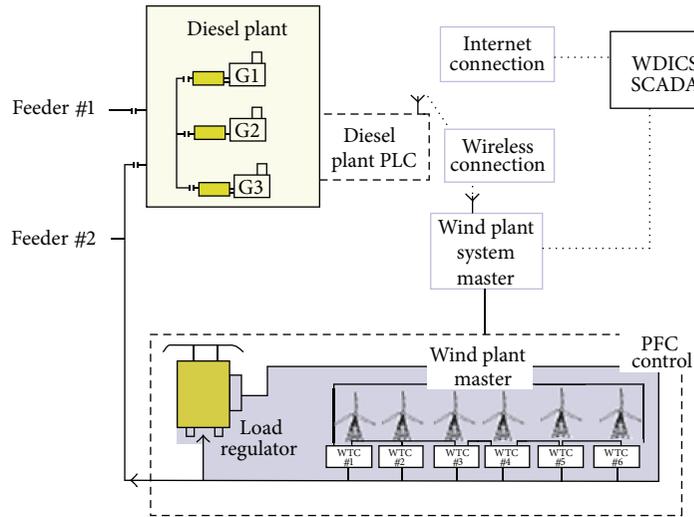


FIGURE 3: Microgrid system with wind and diesel (without storage) [7].

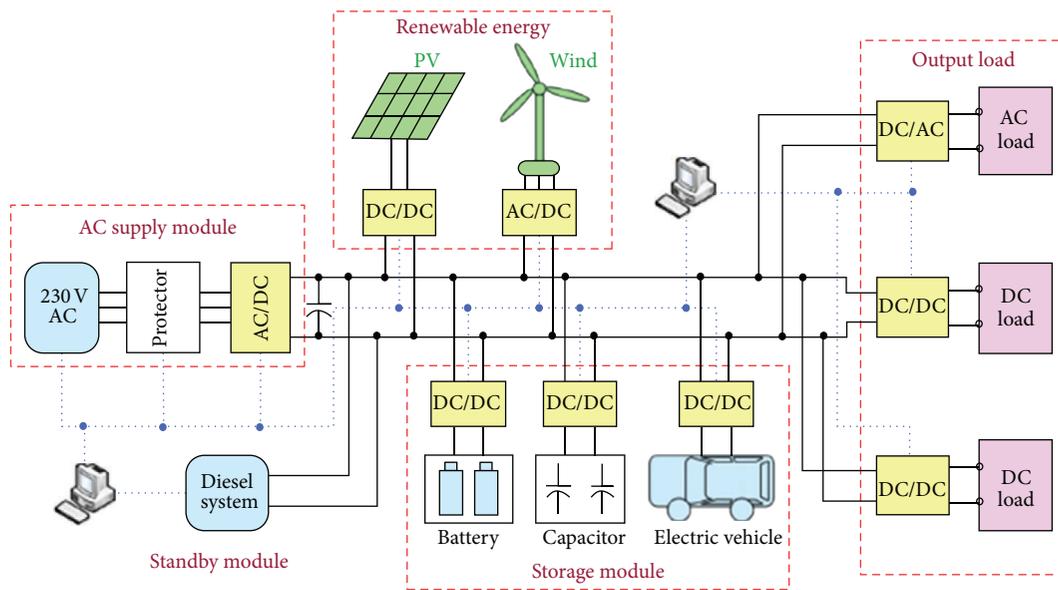


FIGURE 4: DC microgrid system [7].

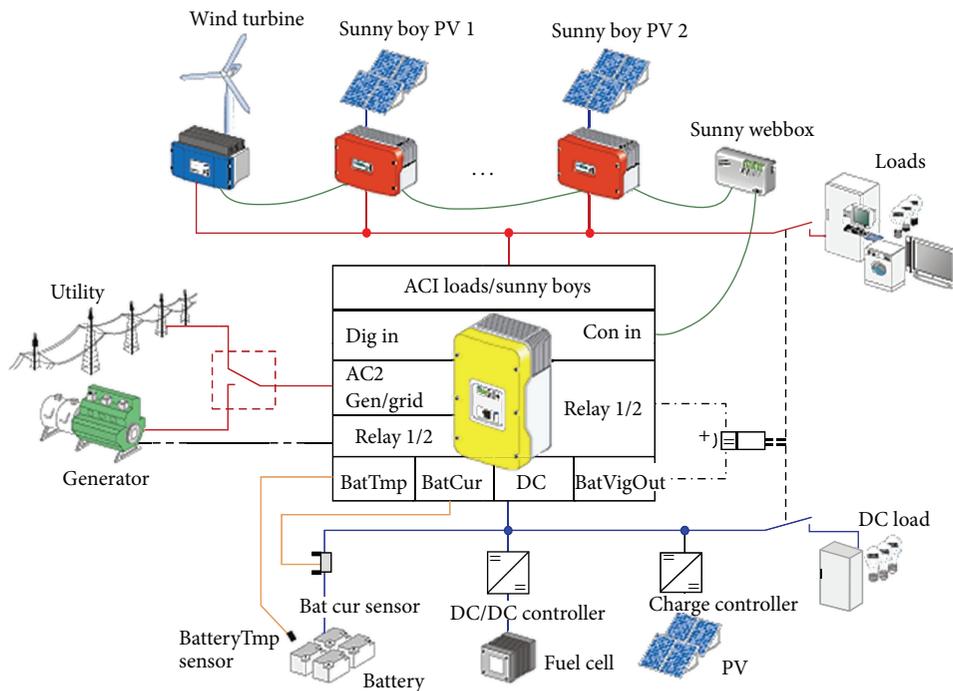


FIGURE 5: AC microgrid system [7].

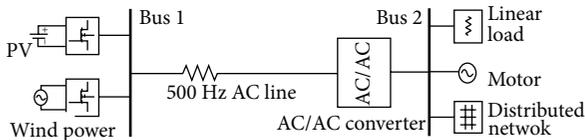


FIGURE 6: HFAC microgrid schematic chart [23].

solar radiation (due to cloud cover), the electrical output voltage can have a direct impact if not conditioned through the integration devices properly and thus causes PQ problem. Comparing to this, small/micro-hydro has lesser PQ problems. Main advantage of these RESs is they are pollution free. Conventional source diesel also has lesser power quality problems such as voltage, sag/swell, over/under voltage and flicker. Main disadvantage of this source is that it emits CO_2 which pollutes the environment. So more research emphasis should be given to improve PQ problems in integrating RE sources.

2.5. Communication Systems. For power control and protection, communication systems are very important. The basic communication methods so far used in the existing μG testbeds are: power-line carrier, broadband over power line, leased telephone line, global system for mobile (GSM) communication, LAN/WAN/Internet (TCP/IP), wireless radio communication, optic fiber, WiFi 802.11b (range of a few 100 meters; speed 5–10 Mbps), WiMAX 802.16 (range 10–30 miles; speed 75 Mbps), and ZigBee/IEEE 802.15.4 (for automated metering system) [9].

TABLE 3: PQ problems related to DG systems [8].

PQ problems	Wind energy	Solar energy	Micro/small hydro	Diesel
Voltage sag/swell	•		•	•
Over/under voltage	•			•
Voltage unbalance		•		
Voltage transient	•			
Voltage harmonics	•	•	•	
Flicker	•	•		•
Current harmonics	•	•	•	
Interruption	•	•		

3. Existing μG Examples in Europe

This paper reviews different architectural structures of existing and simulated μG systems. Some of the existing μG systems in Europe are shown in Table 4. From the table it can be seen that the majority of existing testbeds in this region are AC μG s. Only one DC μG is present which is located in Italy. Table 4 shows that the majority of μG testbeds have implemented central controller system, and few of them have autonomous and agent-based system. Review showed that few testbeds have highlighted about power quality problem and implemented PQ devices to solve them. It was also found that different μG testbeds have implemented different communication systems such as LAN/WAN/Internet (TCP/IP), wireless radio communication, optic fiber, and WiFi.

TABLE 4: Existing examples of μ Gs in Europe.

Location	Power supply	DG source	Energy storage	μ G controller	PQ control	Communication	Reference
Bronsberg, The Netherlands	AC	PV	Battery	Central	None	GSM communication	[9]
Am Steinweg, Germany	AC	CHP, PV	Battery	Agent based	* PoMS	TCP/IP	[10]
CESI RICERCA DER, Italy	DC	PV, wind, diesel, CHP	Battery	Central	Flywheel	Combination of LAN ethernet, wireless, and power line	[11]
Bornholm, Denmark	AC	Diesel, wind	None	Autonomous	None	Optical fiber network	[12]
Kythnos, Greece	AC	PV, diesel	Battery	Central	None	Power line	[9]
CAT, Wales, UK	AC	Hydro, wind, PV	Battery	Central	None	Not discussed	[13]

* PoMS: power flow and power quality management system.

4. Findings of the Study

From the review of μ G architectures it was found that most of the testbeds are AC μ Gs. As the grid and most loads are AC, the AC μ G is easy to integrate with the grid. Maintaining the power quality is one of the critical tasks in AC systems. On the other hand, the main advantage in DC system is that there are few power quality problems and therefore less additional control or components are required. The application of DC μ G is very limited though due to unavailability of enough DC loads. HFAC μ G is a very new concept and is a possible way for integrating renewable energy sources to the μ G. One of the main advantages is that PQ problems are lesser in this system. The main problems of the HFAC μ G system is the complexity of the control devices, large voltage drop, and higher long distance power loss, which currently limits its practical implementation but could be researched upon.

The most commonly used DG sources in μ G systems are solar PV, wind, micro-hydro and diesel. RES are quite popular as DG sources in European regions along with conventional sources.

Power quality is a potential issue in μ G system. As the renewable DG sources are highly dependable on environment, variability of the resource introduces some PQ problems. Hence consideration of PQ performance for any μ G system is essential. Review of the test-beds shows that few μ G test-beds have implemented power quality devices. Therefore, further research is required to improve their PQ and reliability and thus increase the performance of μ G systems.

Storage system is one of the important options that a μ G should have for its successful and stable operation. Most of the existing test-beds have battery storage; some have capacitor banks and flywheels as storage devices. Some of the μ Gs have a combination of two or three storage units together and some do not have any storage units at all. From the review it was found that in most cases (except two), if there is no storage device, at least one controllable DG source is present at the system. If the system does not have any storage devices and only RES is present as DG source, then grid integration

is a very important option for that μ G system. Further study can be done on that regard.

5. Conclusion

DC μ G is not very popular in European regions though it has advantages regarding lesser PQ problems; more emphasis should be given to this system. The main barrier to expand this technology is lesser amount of DC loads. As technology has been advancing, more DC-compatible loads can be introduced to overcome this situation. Most of the existing AC μ G test beds have included batteries as storage devices though it is expensive; further technological improvement can help the system to become economically viable.

More penetration of RESs is expected in μ G systems as they are almost pollution-free and thus environment friendly. In that case potential effort should be given to solve PQ problems associated to the RE sources.

Combination of different RE systems along with storage has a potential future because it helps to store the clean energy whenever available. The advancement in storage and battery systems looks promising in terms of cost and technology. Though initial system cost and operation and maintenance cost (O&M) may be higher, considering the requirements of demand-side management and maximizing the use of available RESs, μ G with storage devices could be a viable option in the near future.

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