Research Article

On Approximate Controllability of Second-Order Neutral Partial Stochastic Functional Integrodifferential Inclusions with Infinite Delay and Impulsive Effects

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We discuss the approximate controllability of second-order impulsive neutral partial stochastic functional integrodifferential inclusions with infinite delay under the assumptions that the corresponding linear system is approximately controllable. Using the fixed point strategy, stochastic analysis, and properties of the cosine family of bounded linear operators combined with approximation techniques, a new set of sufficient conditions for approximate controllability of the second-order impulsive partial stochastic integrodifferential systems are formulated and proved. The results in this paper are generalization and continuation of the recent results on this issue. An example is provided to show the application of our result.

1. Introduction

Impulsive effects exist widely in many evolution processes in which states are changed abruptly at certain moments of time, involving fields such as physics, chemical technology, population dynamics, biotechnology, and economics; see [1–4] and the references therein. However, in addition to impulsive effects, stochastic effects likewise exist in real systems. A lot of dynamical systems have variable structures subject to stochastic abrupt changes, which may result from abrupt phenomena such as stochastic failures and repairs of the components, changes in the interconnections of sub-systems, sudden environment changes, and other areas of science. Therefore, it is necessary and important to consider the impulsive stochastic dynamical systems. Particularly, the authors in [5–7] studied the existence of mild solutions for a class of abstract impulsive neutral stochastic functional differential and integrodifferential equations with infinite delay in Hilbert spaces.

The concept of controllability leads to some very important conclusions regarding the behavior of linear and nonlinear dynamical systems. In the case of infinite-dimensional systems, two basic concepts of controllability can be distinguished. There are exact and approximate controllability. However, the concept of exact controllability is usually too strong [8]. Therefore, approximate controllability problems for deterministic and stochastic dynamical systems in infinite dimensional spaces are well developed using different kind of approaches (see [9, 10]). Stochastic control theory is a stochastic generalization of classic control theory. So significant progress has been made in the approximate controllability of linear and nonlinear stochastic systems in Banach spaces (see, e.g., [9–12]). Several papers [13–16] have appeared on the approximate controllability of nonlinear impulsive stochastic differential systems in Hilbert spaces.

In many cases, it is advantageous to treat the second-order stochastic differential equations directly rather than to convert them to first-order systems. The second-order stochastic differential equations are the right model in continuous time to account for integrated processes that can be made stationary. Recently, based on the fixed point theory, the existence and approximate controllability of mild solutions for various second-order stochastic partial differential equations and impulsive stochastic partial differential equations have been extensively studied. For example, Ren and Sun [17], Cui and Yan [18], and Mahmudov and McKibben [19] proved the approximate controllability of second-order
neutral stochastic evolution differential equations. Muthukumar and Balasubramaniam [20] established sufficient conditions for the approximate controllability of a class of second-order nonlinear stochastic functional differential equations of McKean-Vlasov type. Balasubramaniam and Muthukumar in [21] discussed the approximate controllability of second-order neutral stochastic distributed implicit functional differential equations with infinite delay. Sakthivel et al. in [21] discussed the approximate controllability of second-order neutral stochastic distributed implicit functional differential equations with infinite delay, which is expressed in the form of (1). In order to fill this gap, this paper studies this interesting problem. We derive the sufficient conditions for the approximate controllability of system (1) by using the fixed point theorem for multivalued mapping due to Dhage [28] with stochastic analysis and properties of the cosine family of bounded linear operators combined with approximation techniques. The obtained result can be seen as a contribution to this emerging field. Moreover, the operators \( I_k, I_k \) are continuous but without imposing completely continuous and Lipschitz condition. The results shown are also new for deterministic second-order systems with impulses.

The rest of this paper is organized as follows. In Section 2, we introduce some notations and necessary preliminaries. Section 3 verifies the existence of solutions for impulsive stochastic control system (1). In Section 4 we establish the approximate controllability of impulsive stochastic control system (1). Finally in Section 5, an example is given to illustrate our results.

2. Preliminaries

Let \( (\Omega, \mathcal{F}, P) \) be a complete probability space equipped with a normal filtration \( \mathcal{F}_t, t \in [0, b] \). Let \( H \) and \( K \) be the separable Hilbert spaces and let \( \omega \) be a \( Q \)-Weiner process on \( (\Omega, \mathcal{F}_t, P) \) with the covariance operator \( Q \) such that \( \text{tr} Q < \infty \). We assume that there exists a complete orthonormal system \( \{e_n\}_{n=1}^{\infty} \) in \( K \), a bounded sequence of nonnegative real numbers \( \{\lambda_n\}_{n=1}^{\infty} \) such that \( Qe_n = \lambda_n e_n \), and a sequence \( \beta_i \) of independent Brownian motions such that

\[
\langle \omega(t), e \rangle = \sum_{n=1}^{\infty} \frac{1}{\lambda_n} \langle e_n, e \rangle \beta_n(t), \quad e \in K, \quad t \in J,
\]

and \( \mathcal{F}_t = \mathcal{F}_t^w \), where \( \mathcal{F}_t^w \) is the \( \sigma \)-algebra generated by \( \{w(s) : 0 \leq s \leq t\} \). Let \( L^2_0 = L^2(Q^{1/2} K ; H) \) be the space of all Hilbert-Schmidt operators from \( Q^{1/2} K \) to \( H \) with the inner product \( \langle \psi, \vartheta \rangle_{L^2_0} = \text{Tr}(\psi Q \vartheta^*) \). Let \( L^p(\mathcal{F}_t, H) \) be the Banach space of all \( \mathcal{F}_t \)-measurable \( p \)th power integrable random variables with values in the Hilbert space \( H \). Let \( C([0, b]; L^2(\mathcal{F}_t, H)) \) be the Banach space of continuous maps from \([0, b] \) into \( L^2(\mathcal{F}_t, H) \) satisfying the condition \( \sup_{t \in J} \|x(t)\|_H^2 < \infty \).

We use the notations that \( \mathcal{P}(H) \) is the family of all subsets of \( H \). We let introduce the following notations:

\[
\mathcal{P}_d(H) = \{x \in \mathcal{P}(H) : x \text{ is closed}\}, \quad \mathcal{P}_{bd}(H) = \{x \in \mathcal{P}(H) : x \text{ is bounded}\}, \quad \mathcal{P}_{cv}(H) = \{x \in \mathcal{P}(H) : x \text{ is convex}\}, \quad \mathcal{P}_{cp}(H) = \{x \in \mathcal{P}(H) : x \text{ is compact}\}.
\]
Consider $H_d : P(H) \times P(H) \to \mathbb{R}^+ \cup \{\infty\}$ given by

$$H_d (\tilde{A}, \tilde{B}) = \max \left\{ \sup_{a \in \tilde{A}} d (\tilde{a}, B), \sup_{b \in \tilde{B}} d (\tilde{a}, \tilde{b}) \right\}, \tag{4}$$

where $d (\tilde{a}, \tilde{b}) = \inf_{\tilde{a} \in \tilde{A}} d (\tilde{a}, \tilde{b})$ and $d (\tilde{a}, B) = \inf_{\tilde{b} \in B} d (\tilde{a}, \tilde{b})$. Then $(P_{bd}(H), H_d)$ is a metric space and $(P_d(H), H_d)$ is a generalized metric space.

In what follows, we briefly introduce some facts on multivalued analysis. For more details, one can see [29, 30].

A multivalued map $\Phi : H \to P(H)$ is convex (closed) valued if $G(H)$ is convex (closed) for all $x \in H$. $\Phi$ is bounded on bounded sets if $\Phi(D) = \bigcup_{x \in D} \Phi(x)$ is bounded in $H$ for any bounded set $D$ of $H$; that is, $\sup_{x \in D} \|\Phi(y)\|_H : y \in \Phi(x)) < \infty$.

$\Phi$ is called upper semicontinuous (u.s.c., in short) on $H$, if, for any $x \in H$, the function $\Phi(x)$ is a nonempty, closed subset of $H$ and if, for each open set $B$ of $H$ containing $\Phi(x)$, there exists an open neighborhood $N$ of $x$ such that $\Phi(N) \subseteq B$.

$\Phi$ is said to be completely continuous if $(\Phi(D)$ is relatively compact for every bounded subset $D$ of $H$. If the multivalued map $\Phi$ is completely continuous with nonempty compact values, then $\Phi$ is u.s.c. if and only if $\Phi$ has a closed graph; that is, $x_n \to x_*$, $y_n \to y_*$, and $y_n \in \Phi(x_n)$ imply $y_* \in \Phi(x_*)$.

$\Phi$ is said to be completely continuous if $(\Phi(D)$ is relatively compact for every bounded subset $D \subseteq H$.

A multivalued map $\Phi : J \to P_d$ is said to be measurable if, for each $x \in H$, the function $\Phi : J \to \mathbb{R}^n$ defined by $\Phi(t) = \{x \in \Phi(t) : x \in \Phi(t)\}$ is measurable.

In this paper, $\Phi$ is the infinitesimal generator of a strongly continuous cosine function of bounded linear operators $(C(t))_{t \in \mathbb{R}}$ on $H$. The corresponding strongly continuous cosine sine family $(S(t))_{t \in \mathbb{R}} \subseteq L(H)$ is defined by $S(t)x = \int_0^t C(s)x \, ds$, $t \in \mathbb{R}, x \in H$. The generator $A : H \to H$ of $(C(t))_{t \in \mathbb{R}}$ is given by $Ax = (d^2/dt^2)C(t)x|_{t=0}$ for all $x \in D(A) = \{x \in H : C(x) \in C^1(\mathbb{R}, H)\}$. It is well known that the infinitesimal generator $A$ is a closed densely defined operator on $H$. As usual we denote by $[D(A)]$ the domain of operator $A$ endowed with the graph norm \[ \|x\|_{\Gamma} = \|x\|_H + \|Ax\|_{\Gamma}, x \in D(A). \] Moreover, the notation $\varepsilon$ stands for the space formed by the vectors $x \in H$ for which $C(x)$ is of class $C^1$ on $\mathbb{R}$. It was proved by Kisyński [31] that \varepsilon endowed with the norm \[ \|x\|_{\varepsilon} = \|x\|_H + \sup_{0 \leq s \leq t} \|\partial_s C(t)x\|_H, x \in \varepsilon, \] is a Banach space. Such cosine and corresponding sine families and their generators satisfy the following properties.

\textbf{Lemma 1} (see [32]). Suppose that $A$ is the infinitesimal generator of a cosine family of operators $(C(t)) : t \in \mathbb{R}$. Then, the following hold:

\begin{enumerate}[(a)]
  \item \textbf{There exist} $\bar{M}_1 \geq 1$ and $\alpha \geq 0$ such that $\|C(t)\|_H \leq \bar{M}_1 e^{\alpha t}$ and hence $\|S(t)\|_H \leq \bar{M}_1 e^{\alpha t}$.
  \item \textbf{Consider} $A \int_0^t S(u)x \, du = [C(t) - C(u)]x$ for all $0 \leq s \leq t < \infty$.
  \item \textbf{There exists} $\bar{M}_2 \geq 1$ such that $\|S(t) - S(t)\|_H \leq \bar{M}_2 \int_0^t e^{\alpha s} \, ds$ for all $0 \leq r < s < \infty$.
\end{enumerate}

The existence of solutions of the second-order linear abstract Cauchy problem

\[ x''(t) = Ax(t) + F(t), \quad t \in J, \]
\[ x(0) = z_0, \]
\[ x'(0) = z_1, \tag{5} \]

where $h : J \to H$ is an integrable function, has been discussed in [33]. Similarly, the existence of solutions for semilinear second-order abstract Cauchy problem has been treated in [32]. We only mention here that the function $x(\cdot)$ given by

\[ x(t) = C(t)z_0 + S(t)z_1 + \int_0^t S(t-s)F(s)ds, \quad t \in J, \tag{6} \]

is called a mild solution of (5) and if $z_1 \in E$, the function $x(t)$ is continuously differentiable and

\[ x'(t) = AS(t)z_0 + C(t)z_1 + \int_0^t C(t-s)F(s)ds, \quad t \in J. \tag{7} \]

A function $x : [\mu, \tau] \to H$ is said to be normalized piecewise continuous function on $[\mu, \tau]$ if $x$ is piecewise continuous and left continuous on $(\mu, \tau]$. We denote by $PBC([\mu, \tau], H)$ the space formed by the normalized piecewise continuous, $\mathcal{F}_\tau$-adapted measurable processes from $[\mu, \tau]$ into $H$. In particular, we introduce the space $PBC$ formed by all $\mathcal{F}_\tau$-adapted measurable, $H$-valued stochastic processes\[ x(t) : t \in [0, b] \] such that $x$ is continuous at $t \neq t_k$, $x(t_k) = x(t_k^-)$ and $x(t_k^+)$ exists for $k = 1, 2, \ldots, m$. Similarly, $PBC^1$ formed by all $\mathcal{F}_\tau$-adapted measurable, $H$-valued stochastic processes $x(t) : t \in [0, b]$ such that $x$ is continuous at $t \neq t_k$, $x(t_k) = x(t_k^-)$ and $x(t_k^+)$ exists for $k = 1, 2, \ldots, m$.

In this paper, we always assume that $PBC$ is endowed with the norm \[ \|x\|_{PBC} = \sup_{0 \leq t \leq b} [\|x(t)\|_H + \|\partial_t x(t)\|_H]^{1/2}. \]

Then $PBC, \|\cdot\|_{PBC}$ is a Banach space. Next, for $x \in PBC^1$, we represent by $x'(t)$ the right derivative at $t \in (0, b]$ and by $x'(t)$ the right derivative at zero. It is easy to see that $PBC^1$ is provided with the norm \[ \|x\|_{PBC^1} = \|x\|_{PBC} + \|x'\|_{PBC} \] being a Banach space.

In this paper, we assume that the phase space $(\mathcal{B}, \|\cdot\|_{\mathcal{B}})$ is a seminormed linear space of $\mathcal{F}_0$-measurable functions mapping $(-\infty, 0]$ into $H$ and satisfying the following fundamental axioms due to Hale and Kato (see, e.g., [34]).

\begin{enumerate}[(A)]
  \item If $x : (-\infty, a + b) \to H$, $b > 0$, such that $x|_{[a, a+b]} \in PBC^1([a, a+b], H)$ and $x_a \in \mathcal{B}$, then for every $t \in [a, a+b]$ the following conditions hold:
    \begin{enumerate}[(i)]
      \item $x_a$ is in $\mathcal{B}$;
      \item \[\|x(t)\|_H \leq H\|x_a\|_{\mathcal{B}};\]
      \item \[\|x|_{\mathcal{B}} \leq K(t - a)\|x_a\|_{\mathcal{B}} + M(t - a)^s, t \in [a, a+b], \]
    \end{enumerate}
\end{enumerate}
(B) For the function $x(\cdot)$ in (A), the function $t \to x_t$ is continuous from $[\sigma, \sigma + b]$ into $\mathcal{B}$.

(C) The space $\mathcal{B}$ is complete.

Example 2. The phase space $\mathcal{PC}_e \times L^p(\mathcal{H}, H)$. Let $r \geq 0$, $1 \leq p < +\infty$ and let $\mathcal{H} : (-\infty, -r) \to \mathbb{R}$ be a nonnegative measurable function which satisfies conditions (h-5) and (h-6) in the terminology of Hino et al. [35]. Briefly, this means that $\mathcal{H}$ is locally integrable and there is a nonnegative, locally bounded function $\gamma$ on $(-\infty, -r]$ such that $\mathcal{H}(\xi + r) \leq \gamma(\xi)\mathcal{H}(\xi)$ for all $\xi \leq 0$ and $\xi \in (-\infty, -r) \setminus N_T$, where $N_T \subseteq (-\infty, -r)$ is a set whose Lebesgue measure is zero. We denote by $\mathcal{PC}_e \times L^p(\mathcal{H}, H)$ the set consisting of all classes of functions $\phi : (-\infty, 0] \to \mathcal{H}$ such that $\phi|_{[-\tau, 0]} \in \mathcal{PC}_e([-\tau, 0], H)$, $\phi(\cdot)$ is Lebesgue measurable on $(-\infty, -r)$, and $\mathcal{H}\|\phi\|^p$ is Lebesgue integrable on $(-\infty, -r)$. The seminorm is given by

$$\|\phi\|_{\mathcal{B}} = \sup_{-\tau \leq \tau \leq 0} \mathcal{H}(\tau) + \left( \int_{-\infty}^0 \mathcal{H}(\tau)\|\phi\|^p d\tau \right)^{1/p}. \quad (8)$$

The space $\mathcal{B} = \mathcal{PC}_e \times L^p(\mathcal{H}, H)$ satisfies axioms (A)–(C). Moreover, when $r = 0$ and $p = 2$, we can take $\mathcal{H} = 1$, $M(t) = \gamma(-t)^{1/2}$, and $K(t) = 1 + \left( \int_0^t \mathcal{H}(\tau)d\tau \right)^{1/2}$, for $t \geq 0$ (see [35, Theorem 1.3.8] for details).

Remark 3 (see [4]). In retarded functional differential equations without impulses, the axioms of the abstract phase space $\mathcal{B}$ include the continuity of the function $t \to x_t$. Due to the impulsive effect, this property is not satisfied in impulsive delay systems and, for this reason, has been eliminated in our abstract description of $\mathcal{B}$.

Remark 4. In the rest of this paper $M_0$ and $K_0$ are the constants defined by $M_0 = \sup_{t \in J} M(t)$ and $K_0 = \sup_{t \in J} K(t)$.

For $x \in \mathcal{PC}_e$, we denote by $\tilde{x}_x(k) = 0, 1, \ldots, m$, the unique continuous function $\tilde{x}_x \in C([t_k, t_{k+1}]; H)$ such that

$$\tilde{x}_x(t) := \begin{cases} x(t) & \text{for } t \in (t_k, t_{k+1}], \\ x(t_k^+) & \text{for } t = t_k. \end{cases} \quad (9)$$

Moreover, for $B \subseteq \mathcal{PC}_e$ we denote by $\tilde{B}_x$, $k = 0, 1, \ldots, m$, the set $\tilde{B}_x = \{\tilde{x}_x : x \in B\}$. The notation $B_\tau(x, H)$ stands for the closed ball with center at $x$ and radius $\tau > 0$ in $H$.

Lemma 5. A set $B \subseteq \mathcal{PC}_e$ is relatively compact in $\mathcal{PC}_e$ if and only if the set $\tilde{B}_x$ is relatively compact in $C([t_k, t_{k+1}]; L_2(\Omega, H))$, for every $k = 0, 1, \ldots, m$.

Furthermore, we need the following result.

Lemma 6 (see [36]). Let $\nu : J \to H$ be an integrable function such that $\nu \in \mathcal{PC}_e$. Then the function $\nu(t) = \int_0^t C(t - s)\nu(s)ds$ belongs to $\mathcal{PC}_e$, the function $s \to A\nu(t - s)\nu(s)$ is integrable on $[0, t]$, $t \in J$, and $\nu(t) = \nu(t) + A\int_0^t S(t - s)\nu(s)ds = \nu(t) + \int_0^t A\nu(t - s)\nu(s)ds$, $t \in J$.

Let $x_{\nu}(x_{\nu}; u)$ be the state value of system (1) at terminal time $b$ corresponding to the control $u$ and the initial value $x_0 = \varphi(t) \in \mathcal{B}$. Introduce the set

$$\mathcal{B}(b, x_0) = \{x_{\nu}(x_{\nu}; u)(0) : u(\cdot) \in L^p(J, U)\} \quad (10)$$

which is called the reachable set of system (1) at terminal time $b$, and its closure in $H$ is denoted by $\overline{\mathcal{B}}(b, x_0)$.

Now we give the definitions of mild solutions and approximate controllability for system (1).

Definition 7. An $\mathcal{F}_1$,-adapted stochastic process $x : (-\infty, b] \to H$ is called a mild solution of system (1) if $x_0 = \varphi \in \mathcal{B}$, $x'(t) = \varphi$, $x|_{t \in J} \in \mathcal{PC}_e$, and the impulsive conditions $\Delta x(t_k) = I_k(x_{t_k}, x'(t_k))$ and $\Delta x'(t_k) = I_k(x_{t_k}, x'(t_k))$, $k = 1, \ldots, m$, are satisfied and

(i) $x(t)$ is adapted to $\mathcal{F}_1$, $t \geq 0$.

(ii) $x(t) \in H$ has càdlàg paths on $t \in J$ a.s. and, for each $t \in J$, $x(t)$ satisfies the integral equation

$$x(t) = C(t) \varphi(0) + S(t) \left[ \varphi - g(0, \varphi, \varphi) \right] + \int_0^t C(t - s)g(s, x_s, x'_s(s))ds + \int_0^t S(t - s)Bu(s)ds + \int_0^t S(t - s)f(s)d\omega(s) + \sum_{t_0 < t_k < t} C(t - t_k)I_k(x_{t_k}, x'(t_k)) + \sum_{t_0 < t_k < t} S(t - t_k)I_k(x_{t_k}, x'(t_k)), \quad t \in J, \quad (11)$$

where $f \in S_{F \bar{x}} = \{f \in L^p(K, H) : f(t) \in F(t, x,t, x'(t)), \int_0^t h(t, s, x_s, x'_s(s))ds \text{ a.e. } t \in J\}$.

Definition 8. System (1) is said to be approximately controllable on the interval $J$ if $\overline{\mathcal{B}}(b, x_0) = H$.

It is convenient at this point to define operators

$$\Gamma_b^t = \int_t^b \delta_s(b - s)BB^*S^*(b - s)ds, \quad 0 \leq t < b, \quad (12)$$

$$\Gamma_0^b = \int_0^b S(b - s)BB^*S^*(b - s)ds,$$

$$R(a, \Gamma_0^b) = \left( aI + \Gamma_0^b \right)^{-1} \text{ for } a > 0,$$

where $B^*$ denotes the adjoint of $B$ and $S'(t)$ is the adjoint of $S(t)$. It is straightforward that the operator $\Gamma_0^b$ is a linear bounded operator.
Lemma 9. Assumption (SI) holds if and only if $aR(a, b) \to 0$, $0 \leq \tau < s \leq b$, as $a \to 0^+$ in the strong operator topology.

The proof of this lemma is a straightforward adaptation of the proof of [9, Theorem 2].

Lemma 10 (see [10]). For any $\bar{x}_b \in L^p(F_b, H)$ there exists $\tilde{\phi} \in L^p_{\omega}(\Omega; L^2(0,b, L^2_H))$ such that $\bar{x}_b = E\bar{x}_b + \int_0^b \tilde{\phi}(s)dw(s)$.

Now for any $a > 0$ and $\bar{x}_b \in L^p(F_b, H)$ we define the control function

$$u^a_c(t) = B^*S^*(b-t)(aI + b\tilde{m})^{-1}[E\bar{x}_b + \int_0^b \tilde{\phi}(s)dw(s)]$$

$$- S(b)[\phi - g(0, \varphi, \varphi)] - B^*S^*(b-t)$$

$$- B^*S^*(b-t) \int_0^b (aI + b\tilde{m})^{-1} S(b-s) f(s)dw(s)$$

$$- B^*S^*(b-t) \int_0^b (aI + b\tilde{m})^{-1} S(b-s) g(s, x, x')(s)ds$$

$$\cdot \sum_{k=1}^m C(b-t_m) l_k(x_{i_k}, x'(t_k)) - B^*S^*(b-t)(aI)$$

$$+ b\tilde{m}^{-1} \sum_{k=1}^m S(b-t_m) l_k(x_{i_k}, x'(t_k)),$$

where $f \in S_{Fx}$ is a measurable function such that $f(t) \in F(t, x, x'(t))$, and $\int_0^b h(t, x, x, x'(s))ds = a.e. t \in F$.

Lemma 11. Let $x : (-\infty, b) \to H$ be an $F_t$-adapted measurable process such that $F_0$-adapted process $x_0 = \varphi(t) \in L^2(\Omega; \mathcal{B})$ and $x(\cdot) \in \mathcal{B}^1(I, H)$; then

$$\|x(\cdot)\|_{\mathcal{B}} \leq M_b E\|\varphi\|_{\mathcal{B}} + K_b sup E\|x(\cdot)\|_{H}.$$  

Lemma 12 (see [37]). For any $p \geq 1$ and for arbitrary $L^p_0(K, H)$-valued predictable process $\varphi(\cdot)$,

$$\sup_{x \in [0,\omega]} E\left\|\sum_{t \in [0,\omega]} \int_0^t (\varphi(v)\varphi(v))^{1/p} dv \right\|_{H}^p$$

$$\leq (p(2p-1))^p \left( \sum_{t \in [0,\omega]} E\|\varphi(s)\|_{L^2_H}^{2p} \right)^{1/p},$$

$$t \in [0,\omega).$$

The consideration of this paper is based on the following fixed point theorem due to Dhage [28].

Lemma 13. Let $H$ be a Hilbert space, and let $\Phi_1 : H \to \mathcal{P}_{c, cv}(H)$ and $\Phi_2 : H \to \mathcal{P}_{c, cv}(H)$ be two multivalued operators satisfying that

(a) $\Phi_1$ is a contraction

(b) $\Phi_2$ is completely continuous.

Then either

(i) the operator inclusion $x \in \Phi_1 + \Phi_2$ has a solution or

(ii) the set $G = \{ x \in H : x = \lambda \Phi_1 x + \lambda \Phi_2 x \}$ is unbounded for $\lambda \in (0, 1)$.

3. Existence of Solutions for Impulsive Stochastic Control System

In this section, we prove the existence of solutions for impulsive stochastic control system (I). We make the following hypotheses:

(H1) $A$ is the infinitesimal generator of a strongly continuous cosine family $C(t) : t \geq 0$ on $H$ and the corresponding sine family $S(t) : t \geq 0$ satisfies the conditions $\|C(t)\|_{H} \leq M e^{at}$, $\|S(t)\|_{H} \leq M e^{-bt}$, and $\|AS(t)\|_{H} \leq M e^{-bt}$, $t \geq 0$ for some constants $M, \alpha, \beta, \gamma$.

(H2) $C(t)$, $t > 0$, is compact.

(H3) The function $g : J \times \mathcal{B} \times H \to H$ is continuous and there exist $L_g > 0$ such that

$$E\|g(t, \psi, \psi, y)\|_{H} \leq L_g \left( \|t - t_1\| + \|\psi_1 - \psi_2\|_{\mathcal{B}} + E\|y_1 - y_2\|_{H} \right),$$

$$t \in J, \psi \in \mathcal{B}, y \in H,$

$$\forall t_1 \in J, \psi_1 \in \mathcal{B}, y_1 \in H, \quad i = 1, 2,$$

$$E\|g(t, \psi, y)\|_{H} \leq L_g \left( \|\psi\|_{\mathcal{B}} + E\|y\|_{H} + 1 \right),$$

$$t \in J, \psi \in \mathcal{B}, y \in H,$

with $L_g[M \rho b \rho^{-1}(p\rho)^{-1} + M \rho b \rho^{-1}(p\rho)^{-1} + M \rho^2 b \rho^{-1}(p\rho)^{-1}]< 1$.

(H4) The function $h : J \times J \times \mathcal{B} \times H \to H$ satisfies the following conditions:

(i) For each $(t, s) \in J \times J$ the function $h(t, s, \cdot, \cdot) : \mathcal{B} \times H \to H$ is continuous and, for each $(\psi, y) \in \mathcal{B} \times H$, the function $h(\cdot, \cdot, \psi, y) : J \times J \to H$ is strongly measurable.

(ii) There exists a continuous function $m_h : J \times J \to [0, \infty), such that

$$E\|h(t, \psi, \psi, y)\|_{H} \leq m_h(t, \psi, \psi) \Theta_h \left( \|\psi\|_{\mathcal{B}} + E\|y\|_{H} \right).$$

(18)
for a.e. \( t, s \in J, (\psi, y) \in B \times H \), where
\[
\Theta_h : [0, \infty) \to (0, \infty)
\]
is a continuous nondecreasing function.

(H5) The multivalued map \( F : J \times B \times H \times H \to \mathcal{P}_{bd, cl, cv}(L(K, H)) \) satisfies the following conditions:

(i) For each \( t \in J \), the function \( F(t, \cdot, \cdot, \cdot) : B \times H \times H \to \mathcal{P}_{bd, cl, cv}(L(K, H)) \) is u.s.c. and, for each \((\psi, y) \in B \times H \times H \), the function \( F(\cdot, \cdot, \cdot) \) is measurable and the set

\[
S_{F, \psi} = \left\{ f \in L^p(J, L(K, H)) : f(t) \in F(t, \psi_t, \psi'_t, s) \right\}
\]
is nonempty.

(ii) There exist a continuous function \( m_f : J \to [0, \infty) \) and a continuous nondecreasing function \( \Theta_f : [0, \infty) \to (0, \infty) \) such that

\[
\| F(t, \psi, y, z) \|_{L^p} \leq m_f(t) \Theta_f \left( \| \psi \|_{L^p} + \| y \|_{L^p} + \| z \|_{L^p} \right),
\]
a.e. \( t \in J, \psi \in B, y, z \in H \), with

\[
\int_1^\infty \frac{1}{1 + s + \Theta_f(s) + \Theta_f(s)} \, ds = \infty,
\]
where

\[
\| F(t, \psi, y, z) \|_{L^p} = \sup \left\{ \| f \|_{L^p} : f \in F(t, \psi, y, z) \right\}.
\]

(H6) The functions \( I_k, J_k : \mathcal{B} \times H \to H \) are continuous and there are constants \( c_k, d_k, k = 1, 2, \ldots, m, j = 1, 2, 3, 4 \) such that

\[
0 \leq \limsup_{t \to 1} \sup_{\| f \|_{L^p} \leq 1} \frac{E \| I_k (\psi, y) \|_{L^p}^p}{\| \psi \|_{L^p}^p + E \| y \|_{L^p}^p} \leq c_k,
\]

\[
0 \leq \limsup_{t \to 1} \sup_{\| f \|_{L^p} \leq 1} \frac{E \| J_k (\psi, y) \|_{L^p}^p}{\| \psi \|_{L^p}^p + E \| y \|_{L^p}^p} \leq d_k
\]
for every \( \psi \in B \), \( y \in H \).

Lemma 14 (see [38]). Let \( J \) be a compact interval and let \( H \) be a Hilbert space. Let \( F \) be a multivalued map satisfying (H5) and let \( \Gamma \) be a linear continuous operator from \( L^p(J, H) \) to \( C(J, H) \). Then the operator \( \Gamma + \mathcal{S} : C(J, H) \to \mathcal{P}_{pc, cv}(C(J, H)) \) is a closed graph in \( C(J, H) \times C(J, H) \).

Remark 15. In what follows, we set \( M_1 = \| B \|_{H}, M_\ast = M \max \{ 1, e^{-\alpha}, e^{-\beta}, e^{-\gamma} \} \), and \( N_\ast = \max \{ 1, e^{ab}, e^{\beta b}, e^{\gamma b} \} \).

Theorem 16. If assumptions (H1)–(H6) are satisfied, further, suppose that, for all \( a > 0 \), system (1) has at least one mild solution on \( J \), provided that

\[
\begin{align*}
&12^{p-1} L_g \\
&+ \left( 10^{p-1} K_0^p + 12^{p-1} \right) m^{p-1} M_2^p \sum_{k=1}^m (c_k + d_k) \right) N_\ast^p < 1.
\end{align*}
\]

Proof. Let \( \mathcal{B}_0 = \{ x : (-\infty, b] \to H; x_0 = 0, x_j \in \mathcal{P}C^1, x'(0) = g(0, \phi, \psi) \} \) endowed with the norm of \( \mathcal{P}C^1 \). Thus \( \mathcal{B}_0 \) is a Banach space. Now we can define the multivalued map \( \Phi : \mathcal{B}_0 \to \mathcal{P}(\mathcal{B}_0) \) by \( \Phi x \) the set of \( \rho \in \mathcal{B}_0 \) such that

\[
\rho(t) = \left\{ \begin{array}{ll}
0, & t \in (-\infty, 0), \\
\int_0^t C(t-s) g(s, x(s, t), x'(s)) \, ds + \int_0^t S(t-s) B u_r(s) \, ds + \int_0^t S(t-s) \int_0^s \frac{C(t-s) I_k(s) x(s, t)}{d_{x,s}^k} \, ds + \sum_{k=1}^m C(t-t_k) I_k(s) x(s, t_k) + \sum_{k=1}^m S(t-t_k) J_k(s) x(s, t_k), & t \in J,
\end{array} \right.
\]

where

\[
\begin{align*}
u_t^b (t) &= B^* S^* (b-t) \left( a I + 1_b^b \right)^{-1} E x_b \\
&+ \int_0^b \Phi (s) \, dw (s) - C (b) \varphi (0) \\
&- S (b) \left[ \varphi - g (0, \varphi, \psi) \right] - B^* S^* (b-t) \\
&\cdot \left( a I + 1_b^b \right)^{-1} C (b-s) g (s, x(s, t), x'(s)) \, ds
\end{align*}
\]
and $f \in S_{F_{\mathbb{X}}} = \{ f \in L^p(L(K, H)) : f(t) \in F(t, \bar{x}, \bar{x}', \int_0^t h(t, s, x(t), x'(s)) \, ds) \, a.e., t \in J \}$, and $\bar{x} : (-\infty, 0) \to H$ is such that $\bar{x}_0 = \varphi$ and $\bar{x} = x$ on $J$. In what follows, we aim to show that the operator $\Phi$ has a fixed point, which is a solution of problem (1).

Let $\{ \sigma_n : n \in \mathbb{N} \}$ be a decreasing sequence in $(0, t_1) \subset (0, b)$ such that $\lim_{n \to \infty} \sigma_n = 0$. To prove the above theorem, we consider the following problem:

\[
\begin{aligned}
&d \left[ x'(t) - g \left( t, x(t), x'(t) \right) \right] \\
&\in [Ax(t) + Bu(t)] \, dt \\
&+ F \left( t, x(t), x'(t), \int_0^t h(t, s, x(s), x'(s)) \, ds \right) \, dw(t),
\end{aligned}
\]

where

\[
u^u_n(t) = B^* S^* (b - t) \left( aI + \Gamma_0^p \right)^{-1} E \bar{\mathbb{X}}_b + \int_0^b \tilde{g} (s) \, dw(s) - C (b) \varphi (0) \\
- S (b) \left[ \Phi - g (0, \varphi, \Phi) \right] - B^* S^* (b - t) \\
\cdot \int_0^b \left( aI + \Gamma_0^p \right)^{-1} C (b - s) g \left( s, \bar{x}, \bar{x}'(s) \right) ds \\
- B^* S^* (b - t) \int_0^b \left( aI + \Gamma_0^p \right)^{-1} S (b - s) f (s) \, dw(s)
\]

\[
(A_n x)(t) = \begin{cases} 0, & t \in (-\infty, 0), \\ \int_0^t C (t - s) g \left( s, \bar{x}, \bar{x}'(s) \right) ds, & t \in J, \end{cases}
\]

\[
(Y_n x)(t) = \begin{cases} 0, & t \in (-\infty, 0), \\ \int_0^t \left[ S (t - s) Bu(t) \right] ds + \int_0^t S (t - s) f (s) \, dw(s) + \sum_{x(t) \in \mathbb{X}_n \cup \mathbb{X}_n(t)} C (t - t_k) \left[ \Phi - g (0, \varphi, \Phi) \right] S (t - s) f (s) \, dw(s) \\
+ \sum_{x(t) \in \mathbb{X}_n \cup \mathbb{X}_n(t)} S (t - s) S (\sigma_n) I_k \left( \bar{x}, \bar{x}'(s) \right), & t \in J.
\end{cases}
\]

It is clear that $\Phi_n = A_n + Y_n$. The problem of finding mild solutions of (27) is reduced to find the solutions of the operator inclusion $x \in A_n(x) + Y_n(x)$. In what follows, we show that operators $A_n$ and $Y_n$ satisfy the conditions of Lemma 13.

**Step 1.** $A_n$ is a contraction on $B_b^0$.

We will show that the problem has at least one mild solution $x_n \in B_b^0$.

For fixed $n \in \mathbb{N}$, set the multivalued map $\Phi_n : B_b^0 \to \mathcal{P}(B_b^0)$ by $\Phi_n x$ the set of $\rho_n \in B_b^0$ such that

\[
\begin{aligned}
&\rho_n(t) = 0, \\
&\int_0^t \left[ C (t - s) g \left( s, \bar{x}, \bar{x}'(s) \right) ds + \int_0^t S (t - s) f (s) \, dw(s) + \sum_{x(t) \in \mathbb{X}_n \cup \mathbb{X}_n(t)} C (t - t_k) \left[ \Phi - g (0, \varphi, \Phi) \right] S (t - s) f (s) \, dw(s) \\
&+ \sum_{x(t) \in \mathbb{X}_n \cup \mathbb{X}_n(t)} S (t - s) S (\sigma_n) I_k \left( \bar{x}, \bar{x}'(s) \right), & t \in J.
\end{aligned}
\]

It is easy to see that the fixed point of $\Phi_n$ is a mild solution of the Cauchy problem (27).

Let $\bar{\varphi} : (-\infty, 0) \to H$ be the extension of $(-\infty, 0)$ such that $\bar{\varphi}(\theta) = \varphi(0) = 0$ on $J$. Now, we consider the following multivalued operators $\Lambda_n$ and $Y_n$ defined by

\[
\begin{aligned}
&\Delta x (t_k) = C(\sigma_n) I_k \left( \bar{x}, \bar{x}'(t_k) \right), & k = 1, \ldots, m, \\
&\Delta x'(t_k) = S(\sigma_n) I_k \left( \bar{x}, \bar{x}'(t_k) \right), & k = 1, \ldots, m, \\
x_0 = \varphi \in \mathcal{B}, \hspace{1cm} x'(0) = \phi.
\end{aligned}
\]

(27)

(28)

(29)
\[
- g(s,(\tilde{\mathbf{x}}^*),s'((\tilde{\mathbf{x}}^*'))) \| ds \|_H^p \leq M^p E \int_0^t e^{-\alpha(t-s)} \| g(s,(\tilde{\mathbf{x}}^*),s'((\tilde{\mathbf{x}}^*'))) \|_H^p \| ds \\
- g(s,(\tilde{\mathbf{x}}^*),s'((\tilde{\mathbf{x}}^*'))) \| ds \|_H^p \leq M^p L_g b^{p-1} \int_0^t e^{-\rho(t-s)} \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p ds \\
+ E \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p ds \\
\leq M^p L_g b^{p-1} \int_0^t e^{-\rho(t-s)} \bigg[ \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p \bigg] ds \\
\leq \sup_{s \in [0,b]} E \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p \\
- (\tilde{\mathbf{x}}^*)' \|_H^p + \sup_{s \in [0,b]} E \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p \\
- x^* \|_H^p + \sup_{s \in [0,b]} E \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_H^p \] \\
\quad \text{(since } \tilde{\mathbf{x}} = x \text{ on } J) \\
\leq M^p L_g b^{p-1} (p\alpha)^{-1} \big[ 2^{p-1} K_b^p + 1 \big] \| x^* - x^* \|_{P^{p}}. \\
\] 

By Lemma 6, we have 
\[
\Lambda_n'(t) = g(t,x_n,x_n' \tilde{\mathbf{x}}' (t)) \\
+ \int_0^t \tilde{u}(t-s) g(s,\tilde{x_n},\tilde{x}' (s)) \| ds, \quad t \in J. \\
\] 

Similarly, for any \( t \in [0,b] \), we have 
\[
E \| (\Lambda_n'x^*) (t) - (\Lambda_n'x_n^*) (t) \|_{H^p} \leq 2^{p-1} E \| g(t, \tilde{\mathbf{x}}^*), (\tilde{\mathbf{x}}^*)' (t) - g(t, (\tilde{\mathbf{x}}^*)', (\tilde{\mathbf{x}}^*)') (t) \|_{H^p} \\
+ 2^{p-1} E \int_0^t \tilde{u}(t-s) \bigg[ g(s,\tilde{\mathbf{x}}^*), (\tilde{\mathbf{x}}^*)' (s) - g(s, (\tilde{\mathbf{x}}^*)', (\tilde{\mathbf{x}}^*)') (s) \bigg] \| ds \|_{H^p} \\
\leq 2^{p-1} \| (\tilde{\mathbf{x}}^*)', (\tilde{\mathbf{x}}^*)' \|_{H^p} + E \| (\tilde{\mathbf{x}}^*)' (t) \|_{H^p} \\
\quad + 2^{p-1} M^p L_g b^{p-1} \int_0^t e^{-\rho(t-s)} \bigg[ \| (\tilde{\mathbf{x}}^*)', (\tilde{\mathbf{x}}^*)' \|_{H^p} \bigg] ds \\
\quad + E \| (\tilde{\mathbf{x}}^*)' - (\tilde{\mathbf{x}}^*)' \|_{H^p} ds \\
\leq 2^{p-1} L_g \bigg[ 2^{p-1} K_b^p + 1 \bigg] \| x^* - x^* \|_{P^{p}}. \\
\] 

Taking supremum over \( t \), it follows that 
\[
\| \Lambda_n x^* - \Lambda_n^* \|_{P^{p}} \leq L_0 \| x^* - x^* \|_{P^{p}}, \\
\] 

where \( L_0 = L_g M^p b^{p-1} (p\alpha)^{-1} + 2^{p-1} [1 + M^p b^{p-1} (p\alpha)^{-1}] (2^{p-1} K_b^p + 1) < 1 \). Hence, \( \Lambda_n \) is a contraction on \( P^{p} \).

**Step 2.** \( Y_n \) has compact, convex values and it is completely continuous.

(1) \( Y_n x \) is convex for each \( x \in P^{p} \).

In fact, if \( \tilde{\mathbf{p}_n}^1, \tilde{\mathbf{p}_n}^2 \) belong to \( Y_n x \), then there exist \( f_1, f_2 \in S_{\mathbb{E},x} \) such that 
\[
\tilde{\mathbf{p}_n}^1 (t) = \int_0^t S(t-s) B \left[ B^* S^* (b-s) \left( aI + I_n \right) \right] (E\tilde{x}_b) \| + \int_0^b \tilde{\phi} (\eta) dw (\eta) - C (b) \varphi (0) \\
- S (b) \left[ \phi - g (0, \varphi, \psi) \right] - B^* S^* (b-s) \\
\quad - \int_0^b (aI + I_n) \left[ C (b-\eta) g (\eta, \tilde{x}_n, \tilde{x}' (\eta)) \right] d\eta \\
\]
\[-B^*S^* (b - s)\]
\[
\cdot \int_0^b (aI + 1_{\eta}^b)^{-1} S (b - \eta) f_i(\eta) \, dw(\eta) \]
\[-B^*S^* (b - s) \left( (aI + 1_{\eta}^b)^{-1} \right) \]
\[
\sum_{k=1}^m C (b - t_k) C (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) - B^* S^* (b - s) \left( (aI + 1_{\eta}^b)^{-1} \right) \]
\[
\cdot \int_0^b (aI + 1_{\eta}^b)^{-1} C (b - \eta) C (\sigma_n) \int_0^b \bar{x}_\eta \left( \eta, \bar{x} (\eta) \right) \, d\eta \]
\[-B^* S^* (b - s) \left( (aI + 1_{\eta}^b)^{-1} \right) \sum_{k=1}^m C (b - t_k) C (\sigma_n) \cdot I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) - B^* S^* (b - s) \left( (aI + 1_{\eta}^b)^{-1} \right) \]
\[
\sum_{k=1}^m S (b - t_k) S (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) \]
\[
+ \int_0^t S (t - s) [\lambda f_1 (s) + (1 - \lambda) f_2 (s)] \, dw(s) \]
\[
+ \sum_{0 < t_k < t} C (t - t_k) C (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) + \sum_{0 < t_k < t} S (t - t_k) S (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) \]
\[
\cdot x_i = \lambda \frac{\rho}{\lambda} + (1 - \lambda) \frac{\rho}{\lambda} \in \mathcal{Y} \cap x. \]

(2) \( \mathcal{Y} \) maps bounded sets into bounded sets in \( \mathcal{B}_0 \).

Indeed, it is enough to show that there exists a positive constant \( L \) such that, for each \( \rho \in \mathcal{Y}, x \in B(0, \mathcal{B}_0) = \{ x \in \mathcal{B}_0 : \| x \|_{\mathcal{B}_0} \leq r \}, \) one has \( \| \rho \|_{\mathcal{B}_0} \leq L. \) If \( \rho \in \mathcal{Y}, x \), then there exists \( f \in \mathcal{S}_F \) such that, for each \( t \in J, \)

\[
\rho_n (t) = \int_0^t S (t - s) Btu(s) \, ds \]
\[
+ \int_0^t S (t - s) f(s) \, ds \]
\[
+ \sum_{0 < t_k < t} C (t - t_k) C (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) \]
\[
+ \sum_{0 < t_k < t} S (t - t_k) S (\sigma_n) I_k \left( \bar{x}_{t_k}, \bar{x}' (t_k) \right) \]
\[ E \| \bar{\phi} \|_H^p \leq 4^{p-1} E \int_0^1 S(t-s) B \left\{ B^* S^* (b-s) (aI + \Gamma_0^b)^{-1} \left[ E\bar{\phi}(t) + \int_0^b \bar{\phi} (\eta) \, d\eta (\eta) - C(b) \varphi(0) - S(b) \{ \varphi - g(0, \varphi, \phi) \} \right] \right\} \]

\[ - B^* S^* (b-s) \int_0^b (aI + \Gamma_0^b)^{-1} C(b-a) g(\eta, \bar{x}_n, \bar{x}' (\eta)) \, d\eta - B^* S^* (b-s) \int_0^b (aI + \Gamma_0^b)^{-1} S(b-\eta) f_1 (\eta) \, d\eta \]

\[ + B^* S^* (b-s) (aI + \Gamma_0^b)^{-1} \sum_{k=1}^m C(b-t_k) C(\sigma_n) I_k (\bar{x}_1, \bar{x} (t)) \]

\[ + B^* S^* (b-s) (aI + \Gamma_0^b)^{-1} \sum_{k=1}^m S(t-t_k) S(\sigma_n) I_k (\bar{x}_1, \bar{x} (t)) \}ds \right\|_H^p + 4^{p-1} E \left\| \int_0^1 S(t-s) f (s) \, d\eta (s) \right\|_H^p \]

\[ \leq 20^{p-1} M^p e^{pR_g} \left( \frac{1}{a^p} M^p e^{-p\theta \bar{b}} \int_0^t e^{2p \theta s} \left\{ 4^{p-1} \left[ \| E\bar{x}_b \|_H^p + C_p \left[ \int_0^b \| E\bar{\phi} (\eta) \|_H^p \right]^{2/p} d\eta \right]^{p/2} \right. \right. \]

\[ + M^p e^{-p\theta \bar{b}} \left[ E \| \varphi(0) \|_{L^p} + 2^{p-1} \left[ \| \varphi \|_{L^p} + \| g(0, \varphi, \phi) \|_{L^p} \right] \right] \left. \right. \]

\[ + C_p M^p \left[ \int_0^b e^{-p\theta (b-\eta)} E \| f(\eta) \|_{L^p}^{2/p} d\eta \right]^{p/2} + m^{-1} M^p \sum_{k=1}^m e^{-p\theta (b-\eta)} E \| I_k (\bar{x}_1, \bar{x} (t_k)) \|_{l^p}^p \]

\[ + m^{-1} M^p \sum_{k=1}^m e^{-p\theta (b-\eta)} e^{-p\theta \sigma} E \| I_k (\bar{x}_1, \bar{x} (t_k)) \|_{l^p}^p \]
\[ \cdot M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (\zeta_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] + (4m)^{p-1} M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (d_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] + (4m)^{p-1} M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (d_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] + (4m)^{p-1} M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (d_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] + (4m)^{p-1} M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (d_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] + (4m)^{p-1} M^2 \sum_{k=1}^{m} e^{-\rho x(t-t_k)} e^{-\rho a_k} [C_1 + (d_k + \epsilon_k) \left( \left\| \bar{x}_{t_k} \right\|_{L^p} + E \left\| \bar{x}'(t_k) \right\|_{L^p} \right)] \]

\[ + M^p e^{-\rho b} \left[ E \left\| \phi(0) \right\|_{L^p} \right] \]

\[ + M^p e^{-\rho b} \left[ E \left\| \phi(0) \right\|_{L^p} \right] \]

\[ + M^p e^{-\rho b} \left[ E \left\| \phi(0) \right\|_{L^p} \right] \]
(3) \( \mathcal{Y}_n \) is a compact multivalued map.

To this end, we decompose \( \mathcal{Y}_n \) by \( \mathcal{Y}_n = \Gamma_1 \mathcal{Y}_n \), where the map \( \Gamma_1^n : B_r(0, \mathcal{R}^b_0) \rightarrow \mathcal{P}(\mathcal{R}^b_0) \) is defined by \( \Gamma_1^n \) and the set \( \bar{\mathcal{Y}}_n \in \mathcal{R}^b_0 \) such that

\[
\bar{\mathcal{Y}}_n^1(t) = \int_0^t S(t - s) Bu_x(s) \, ds 
+ \int_0^t S(t - s) f(s) \, dw(s) ,
\]

and the map \( \Gamma_2^n : B_r(0, \mathcal{R}^b_0) \rightarrow \mathcal{P}(\mathcal{R}^b_0) \) is defined by \( \Gamma_2^n \), and the set \( \bar{\mathcal{Y}}_n \in \mathcal{R}^b_0 \) such that

\[
\bar{\mathcal{Y}}_n(t) = \sum_{0 < t_k < t} C(t - t_k) C(\sigma_1) I_k(\mathcal{X}_1, \mathcal{X}', (t_k)) 
+ \sum_{0 < t_k < t} S(t - t_k) S(\sigma_1) I_k(\mathcal{X}_1, \mathcal{X}', (t_k)).
\]

First, \( \Gamma_1^n(B_r(0, \mathcal{R}^b_0)) \) is a compact multivalued map. We begin by showing that \( \Gamma_1^n(B_r(0, \mathcal{R}^b_0)) \) is equicontinuous. Let \( 0 < \tau_1 < \tau_2 \leq b \). Then, we have, for each \( x \in B_r(0, \mathcal{R}^b_0) \),
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\[ + 6^{p-1} C_p \Theta_f (r^{**}) \left[ \int_0^{\tau_1-\varepsilon} \|S (r_2-s) - S (r_1-s)\|_H^p \, m_f (s) \, ds \right]^{2/p} + 12^{p-1} C_p M^p \Theta_f (r^{**}) \left[ \frac{2^p \left( \frac{p-1}{p-2} \right)}{p-2} \right]^{1/p^2} \]

\[ + \int_{\tau_1-\varepsilon}^{\tau_1} e^{-\beta (r_2-s)} m_f (s) \, ds + 6^{p-1} C_p M^p \Theta_f (r^{**}) \left[ \frac{2^p \left( \frac{p-1}{p-2} \right)}{p-2} \right]^{1/p^2} \int_{\tau_1-\varepsilon}^{\tau_1} e^{-\beta (r_2-s)} m_f (s) \, ds, \]

where

\[ E \left[ \|u^2 (s)\|_H^p \right] \leq 5^{p-1} M^p e^{-p\beta} \frac{1}{a^p} \]

\[ \cdot M_1^p b^p N_1^p \left\{ 4^{p-1} \left[ \|E \bar{\eta}\|_H^p \right] + C_p b^{p/2-1} \int_0^b \|\bar{\eta}\|_H^p \, d\eta \right\} + M_1^p e^{-pab} \left[ \|\tilde{\phi}(0)\|_H^p \right] + 2^{p-1} \left[ \|\tilde{\phi}\|_H^p + \|g (0, \phi, \phi)\|_H^p \right] + M_1^p b^{p-1} L_g (r^*) \]

\[ + r + 1 \int_0^b e^{-p(a-\eta)} d\eta \]

\[ + 5^{p-1} C_p M^p b^{p/2-1} \Theta_f (r** \right) \int_0^b e^{-p(r-\eta)} m_f (\eta) \, d\eta \]

\[ + m^{p-1} M^p e^{-pab} e^{-p\gamma} N_2^p \sum_{k=1}^m \left[ C_1 \right] \]

\[ + \left( \xi_k + \epsilon_k \right) (r^* + r) \]

\[ =: M_2. \]

The fact of the compactness of \( S(t) \) for \( t > 0 \) implies the continuity in the uniform operator topology, so as \( \tau_2 - \tau_1 \to 0 \), with \( \epsilon \) being sufficiently small, the right-hand side of the above inequality is independent of \( x \in B_p (0, \mathcal{B}_0^p) \) and tends to zero. The equicontinuities for the cases \( \tau_1 < \tau_2 \leq 0 \) or \( \tau_1 \leq 0 \leq \tau_2 \leq b \) are very simple. Thus the set \( \{ \Gamma_n^1 : x \in B_p (0, \mathcal{B}_0^p) \} \) eqocountinuous.

We now prove that \( \Gamma_n^1 (B_p (0, \mathcal{B}_0^p)) \) is relatively compact for every \( t \in [0, b] \). Let \( 0 < t \leq s \leq b \) be fixed and let \( \epsilon \) be a real number satisfying \( 0 < \epsilon < t \). For \( x \in B_p (0, \mathcal{B}_0^p) \), we define \( \tilde{\gamma}_{\epsilon, x} (t) = \int_0^{t-\epsilon} S (t-s) B u^2 (s) \, d s \)

\[ + \int_0^{t-\epsilon} S (t-s) f (s) \, d w (s), \]

where \( f \in S_{E \overline{\Xi}} \). Using the compactness of \( S(t) \) for \( t > 0 \), we deduce that the set \( U_n^1 (t) = \{ \tilde{\gamma}_n^1 (t) : x \in B_p (0, \mathcal{B}_0^p) \} \) is relatively compact in \( H \) for every \( \epsilon, 0 < \epsilon < t \). Moreover, for every \( x \in B_p (0, \mathcal{B}_0^p) \) we have

\[ E \left[ \|u^2_n (t) - \tilde{u}_{\epsilon, x} (t)\|_H^p \right] \leq 2^{p-1} E \left[ \int_{t-\epsilon}^t S (t-s) B u^2 (s) \, d s \right]^{2/p} + 2^{p-1} E \left[ \int_{t-\epsilon}^t S (t-s) f (s) \, d w (s) \right]^{2/p} \]

\[ \leq 2^{p-1} M^p E \left[ \int_{t-\epsilon}^t e^{-p\beta (t-s)} B u^2 (s) \, d s \right]^{2/p} + 2^{p-1} C_p M^p \left[ \int_{t-\epsilon}^t e^{-p\beta (t-s)} E \left[ f (s)^p \right]^{2/p} \, d s \right]^{2/p} \]

\[ \leq 2^{p-1} M^p M_1^p \left[ \int_{t-\epsilon}^t e^{-p\beta (t-s)} \, d s \right]^{2/p} \int_{t-\epsilon}^t e^{-p\beta (t-s)} M_2 d s + 2^{p-1} C_p M^p \left[ \int_{t-\epsilon}^t e^{-p\beta (t-s)} M_2 d s \right]^{2/p} \]

\[ \cdot \Theta_f \left[ \|\bar{\eta}\|_H^p + \|\bar{\eta}'(s)\|_H^p \right] + b^{p-1} \int_0^{t-\epsilon} m_h (s, r) \, d r \left[ \|\bar{\eta}\|_H^p + \|\bar{\eta}'(r)\|_H^p \right] \]

\[ \leq 2^{p-1} M^p M_1^p \beta^{1-p} \int_{t-\epsilon}^t e^{-p\beta (t-s)} M_2 d s + 2^{p-1} C_p M^p \Theta_f (r**) \left[ \frac{2^p \left( \frac{p-1}{p-2} \right)}{p-2} \right]^{1/p^2} \int_{t-\epsilon}^t e^{-p\beta (t-s)} m_f (s) \, d s. \]

There are relatively compact sets arbitrarily close to the set \( W(t) = \{ (\Gamma_n^1 x) (t) : x \in B_p (0, \mathcal{B}_0^p) \} \), and \( W(t) \) is a relatively compact in \( H \). Hence, the Arzelá-Ascoli theorem shows that \( \Gamma_n^1 \) is a compact multivalued map.
Secondly, $\Gamma_n^2(B_1(0,\mathcal{S}_k^0))$ is a compact multivalued map. We begin by showing that $\Gamma_n^2(B_1(0,\mathcal{S}_k^0))$ is equicontinuous. For each $x \in B_1(0,\mathcal{S}_k^0)$, $t \in (0, b)$ is fixed, $t \in [t_j, t_{j+1}]$, and $\vec{y}^n = \Gamma_n^2 x$, such that

$$\vec{y}^n(t) = \sum_{0 < t_k < t} C(t-t_k) C(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right)$$

$$+ \sum_{0 < t_k < t} S(t-t_k) S(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right).$$

(52)

Next, for $r_1 \leq s < t \leq r_2$, $\varepsilon > 0$, we have, using the property of compact operator,

$$E \left[ \left\| \vec{y}^n(t_2) - \vec{y}^n(t_1) \right\|_H \right] = \frac{m}{2} \sum_{k=1}^m E \left[ \left\| C(t_2-t_k) - C(t_1-t_k) \right\| C(\sigma_n) \right]$$

(53)

$$\cdot \left( \vec{x}_k, \vec{x}' (t_k) \right) \left\|_H \right. + (2m)^{p-1}$$

As $t_2 - t_1 \to 0$, the right-hand side of the above inequality tends to zero independently of $x$ due to the sets $C(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right) : x \in B_1(0,\mathcal{S}_k^0)$, $C(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right) : x \in B_1(0,\mathcal{S}_k^0)$ which are relatively compact in $H$ and the strong continuity of $C(\cdot), S(\cdot)$. So $[\vec{y}^n_i(t)], i = 1, 2, \ldots, m$, are equicontinuous.

Now we prove that $[\vec{y}^n_i(t)], i = 1, 2, \ldots, m$, is relatively compact for every $t \in [0, b]$.

From the following relations

$$\left[ \vec{y}^n_i(t) \right] = \sum_{0 < t_k < t} C(t-t_k) C(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right)$$

$$+ \sum_{0 < t_k < t} S(t-t_k) S(\sigma_n) I_k \left( \vec{x}_k, \vec{x}' (t_k) \right) \in (2m)^{p-1}$$

$$\cdot \sum_{k=1}^m C(t-t_k) C(\sigma_n) I_k \left( B_1\{0, \mathcal{S}_k^0\}, B_r [0, H]\right)$$

$$+ (2m)^{p-1}$$

$$\cdot \sum_{k=1}^m S(t-t_k) S(\sigma_n) I_k \left( B_1\{0, \mathcal{S}_k^0\}, B_r [0, H]\right),$$

we conclude that $[\vec{y}^n_i(t)], i = 1, 2, \ldots, m$, is relatively compact for every $t \in [t_j, t_{j+1}]$. By Lemma 5, we infer that $\Gamma_n^2(B_1(0,\mathcal{S}_k^0))$ is relatively compact. Moreover, using the continuity of the operators $C(t), S(t)$, for all $t \in [0, b]$, we conclude that operator $\Gamma_n^2$ is also a compact multivalued map.

(4) $\mathcal{Y}_n$ has a closed graph.

Let $x^{(j)} \to x^* \in \mathcal{Y}_n$, $x^{(j)} \in B_1(0,\mathcal{S}_k^0)$, and $\vec{y}^{(j)} \to \vec{y}^\ast$. From axiom (A), it is easy to see that $(x^{(j)})_k \to x^*$ uniformly for $s \in (-\infty, b]$ as $j \to \infty$. We prove that $\vec{y}^\ast \in \mathcal{Y}_n$. Now $\vec{y}^{(j)} \in \mathcal{Y}_n$ means that there exists $f^{(j)} \in S_{x^{(j)}}$ such that, for each $t \in [0, b]$,

$$\vec{y}^{(j)}(t) \rightarrow \int_0^t S(t-s) B u^{(j)}(s) ds$$

$$+ \int_0^t S(t-s) f^{(j)}(s) dw (s)$$

$$+ \sum_{0 < t_k < t} C(t-t_k) S(\sigma_n) I_k \left( \left( x^{(j)}, x' \right)' (t_k) \right),$$

(55)

$$t \in J.$$
\[
+ \sum_{0 < t_k < t} S(t-t_k)J_k\left(\begin{array}{c}
\vec{x}^+(t_k) \\
\vec{x}^-(t_k)
\end{array}\right),
\]
t \in J,
(57)

where

\[
u_{\lambda}^m(t) = B^*S^*(b-t)\left( (aI + \Gamma b) \right)^{-1} E\tilde{x}_b
+ \int_0^b \tilde{\phi}(s) \, dw(s) - C(b)\varphi(0) - S(b)
\]
\[
\cdot \left[ \varphi - g(0, \varphi, \psi) \right] - B^*S^*(b-t)\left( (aI + \Gamma b) \right)^{-1} C(b)\varphi(0)
\]
\[
\cdot C(b-s)g\left( (\vec{x}^+, (\vec{x}^-)'(s) \right) ds - B^*S^*(b-t)\left( (aI + \Gamma b) \right)^{-1}
\]
\[
\cdot L_k\left(\begin{array}{c}
\vec{x}^+(t_k) \\
\vec{x}^-(t_k)
\end{array}\right) - B^*\delta^*_a(b-t)(aI + \Gamma b) + L_k\left(\begin{array}{c}
\vec{x}^+(t_k) \\
\vec{x}^-(t_k)
\end{array}\right).
\]

Since \( g, L_k, j_k, k = 1, 2, \ldots, m \), are continuous, we obtain that

\[
\left\| \tilde{p}_n^{(j)} - \int_0^t S(t-s) B \left[ B^*S^*(b-s) (aI + \Gamma b) \right]^{-1} E\tilde{x}_b \right. 
\]
\[
\cdot \left. \int_0^b \tilde{\phi}(\eta) \, dw(\eta) - C(b)\varphi(0) - S(b) \right\|
\]
\[
- \sum_{0 < t_k < t} S(t-t_k)J_k\left(\begin{array}{c}
\vec{x}^+(t_k) \\
\vec{x}^-(t_k)
\end{array}\right)
\]
\[
- \sum_{0 < t_k < t} S(t-t_k)J_k\left(\begin{array}{c}
\vec{x}^+(t_k) \\
\vec{x}^-(t_k)
\end{array}\right)
\]
\[
- \left( \tilde{p}_n^{(j)} - \int_0^t S(t-s) B \left[ B^*S^*(b-s) (aI + \Gamma b) \right]^{-1} E\tilde{x}_b \right.
\]
\[
\cdot \left. \int_0^b \tilde{\phi}(\eta) \, dw(\eta) - C(b)\varphi(0) - S(b) \right\|
\]
\[
\rightarrow 0
\]
as \( j \rightarrow \infty \).
(59)

Consider the linear continuous operator \( \Gamma : L^p(J, H) \rightarrow C(J, H) \),

\[
\Gamma (f)(t) = \int_0^t S(t-s) f(s) \, dw(s) + \int_0^t S(t-s) f(s) \, dw(s)
\]
\[
\cdot \left[ \int_0^b \left( aI + \Gamma b \right)^{-1} S(b-\eta) f(\eta) \, d\eta \right] ds.
\]

From Lemma 14, it follows that \( \Gamma \circ S_F \) is a closed graph operator. Also, from the definition of \( \Gamma \), we have that, for every \( t \in [0, b] \),

\[
\tilde{p}_n^{(j)} - \int_0^t S(t-s) B \left[ B^*S^*(b-s) (aI + \Gamma b) \right]^{-1} E\tilde{x}_b
\]
\[
+ \int_0^b \tilde{\phi}(\eta) \, dw(\eta) - C(b)\varphi(0) - S(b)
\]
\[
\cdot [\phi - g(0, \varphi, \phi)] - B^* S^*(b-s) \int_0^b (aI + \Gamma_b^b)^{-1} \\
\cdot C(b-\eta) g(\eta, (x(t))^\top, (\bar{x})^\top) d\eta \\
- B^* S^*(b-s) (aI + \Gamma_b^b)^{-1} \sum_{k=1}^m C(b-t_k) C(\sigma_n) \\
\cdot I_k \left( (x(t))^\top, (\bar{x})^\top \right) - B^* \delta^* (b-s) (aI + \Gamma_b^b)^{-1} \\
\cdot \int_0^b (aI + \Gamma_b^b)^{-1} S(t-s) f^*(s) dw(s) \\
+ \int_0^t S(t-s) (BB^* S^*(b-s) \\
\cdot \left( \int_0^b (aI + \Gamma_b^b)^{-1} S(b-\eta) f^*(\eta) d\eta \right) ds.
\]

(62)

Therefore, \( Y_n \) is a completely continuous multivalued map, u.s.c. with convex closed, compact values.

**Step 3.** We will show that the set \( G = \{ x \in \mathcal{R}_0^0 : x \in \lambda \Lambda_n x + \lambda Y_n x \text{ for some } \lambda \in (0,1) \} \) is bounded on \( J \).

Let \( x \in \mathcal{R}_0^0 \), and then there exists \( f \in \mathcal{S}_{F,x} \) such that we have

\[
x(t) = \lambda \int_0^t C(t-s) g(s, x_t, x'(s)) ds \\
+ \lambda \int_0^t S(t-s) Bu_t^x(s) ds \\
+ \lambda \int_0^t S(t-s) f(s) dw(s)
\]

(63)

It also follows from Lemma 6 that

\[
x'(t) = \lambda g(t, x_t, x'(t)) \\
+ \lambda \int_0^t AS(t-s) g(s, x_t, x'(s)) ds \\
+ \lambda \int_0^t C(t-s) Bu_t^x(s) ds \\
+ \lambda \int_0^t C(t-s) f(s) dw(s)
\]

(64)

This implies by (H1)–(H5) and (41) that for each \( t \in J \) we have
\[ E \| x ( t ) \| _{ p } \leq 5^{p-1} E \int _{ 0 } ^{ t } C ( t - s ) g ( s, \bar{x}, \bar{x}' ( s ) ) \, ds \left\| x \right\| _{ p } + 5^{p-1} E \int _{ 0 } ^{ t } S ( t - s ) B u _{ \bar{x} } ( s ) \, ds \left\| x \right\| _{ p } + 5^{p-1} E \int _{ 0 } ^{ t } S ( t - s ) \]  
\[ \cdot f ( s ) \, dw ( s ) \left\| x \right\| _{ p } + 5^{p-1} E \sum _{ 0 \leq t_k < t } C ( t - t_k ) C ( \sigma_n ) I_k ( \bar{x}_{t_k}, \bar{x}' ( t_k ) ) \left\| x \right\| _{ p } + 5^{p-1} E \sum _{ 0 \leq t_k < t } S ( t - t_k ) S ( \sigma_n ) \]  
\[ \cdot I_k ( \bar{x}_{t_k}, \bar{x}' ( t_k ) ) \left\| x \right\| _{ p } \leq 5^{p-1} M^p b^p L_g \int _{ 0 } ^{ t } e^{-p \alpha ( t - s )} \left\| x \right\| _{ p } + E \left\| x' ( s ) \right\| _{ p } ^{ 2 } + 1 \, ds + 20^{p-1} M^p e^{-p \alpha \beta} \frac{1}{\alpha \beta} \]  
\[ \cdot M^p e^{-p \beta b} M_t^p b^{p-1} \int _{ 0 } ^{ t } e^{p \alpha \beta s} \left\{ 4^{p-1} \left[ E \| \bar{x} \| _{ p } + C_P b^{p-1} \right] \int _{ 0 } ^{ b } E \| \varphi ( \eta ) \| _{ p } \, d \eta \right\} + M^p e^{-p \alpha b} \left[ E \| \varphi ( 0 ) \| _{ p } + 2^{p-1} \left[ \| \varphi \| _{ p } ^{ 2 } + E \| g ( 0, \varphi, \Phi ) \| _{ p } ^{ 2 } \right] \right] + M^p b^{p-1} L_g \int _{ 0 } ^{ b } e^{-p \alpha ( b - \eta )} \left\{ \| \bar{x} \| _{ p } + E \left\| x' ( \eta ) \right\| _{ p } ^{ 2 } + 1 \right\} \, d \eta + C_P M^p b^{p/2-1} \int _{ 0 } ^{ b } e^{-p \beta ( b - \eta )} m_f ( \eta ) \Theta_f \left( \| \bar{x} \| _{ p } + E \left\| x' ( \eta ) \right\| _{ p } ^{ 2 } \right) \, d \eta \]  
\[ + m^{p-1} M^2 \sum _{ k=1 } ^{ m } e^{-p \alpha ( b - t_k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \right] \]  
\[ + m^{p-1} M^2 \sum _{ k=1 } ^{ m } e^{-p \beta ( t-k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \right] \left\{ \left\| \bar{x} \right\| _{ p } + E \left\| x' ( s ) \right\| _{ p } ^{ 2 } + 1 \right\} \, ds + 5^{p-1} C_P M^p b^{p/2-1} \int _{ 0 } ^{ t } e^{-p \alpha ( t - s )} m_f ( s ) \]  
\[ \cdot \Theta_f \left( \| \bar{x} \| _{ p } + E \left\| x' ( s ) \right\| _{ p } ^{ 2 } + b^{p-1} \int _{ 0 } ^{ t } m_h ( s, \tau ) \Theta_h \left( \| \bar{x} \| _{ p } + E \left\| x' ( \tau ) \right\| _{ p } ^{ 2 } \right) \, d \tau \right) \, ds + ( M^p )^{p-1} \]  
\[ + M^2 \sum _{ k=1 } ^{ m } e^{-p \alpha ( t-k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \right] + ( M^p )^{p-1} M^2 \sum _{ k=1 } ^{ m } e^{-p \beta ( t-k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \right] \]  
\[ \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \]  

Similarly, for any \( t \in J \), we have

\[ E \left\| x' \right\| _{ p } \leq 6^{p-1} L_g \left\| \bar{x} \right\| _{ p } + E \left\| x' \right\| _{ p } ^{ 2 } + 1 + 6^{p-1} M^p b^{p-1} L_g \int _{ 0 } ^{ t } e^{-p \gamma ( t - s )} \left\| \bar{x} \right\| _{ p } + E \left\| x' ( s ) \right\| _{ p } ^{ 2 } + 1 \, ds \]  
\[ + 20^{p-1} M^p e^{-p \alpha \tau} \frac{1}{\alpha \tau} M^p e^{-p \beta b} M_t^p b^{p-1} \int _{ 0 } ^{ t } e^{p \alpha \tau} \left\{ 4^{p-1} \left[ E \| \bar{x} \| _{ p } + C_P b^{p-1} \right] \int _{ 0 } ^{ b } E \| \varphi ( \eta ) \| _{ p } \, d \eta \right\} + M^p e^{-p \alpha b} \left[ E \| \varphi ( 0 ) \| _{ p } ^{ 2 } + 2^{p-1} \left[ \| \varphi \| _{ p } ^{ 2 } + E \| g ( 0, \varphi, \Phi ) \| _{ p } ^{ 2 } \right] \right] + M^p b^{p-1} L_g \int _{ 0 } ^{ b } e^{-p \alpha ( b - \eta )} \left\{ \| \bar{x} \| _{ p } + E \left\| x' ( \eta ) \right\| _{ p } ^{ 2 } + 1 \right\} \, d \eta \]  
\[ + C_P M^p b^{p/2-1} \int _{ 0 } ^{ b } e^{-p \beta ( b - \eta )} m_f ( \eta ) \Theta_f \left( \| \bar{x} \| _{ p } + E \left\| x' ( \eta ) \right\| _{ p } ^{ 2 } \right) \, d \eta \]  
\[ + m^{p-1} M^2 \sum _{ k=1 } ^{ m } e^{-p \alpha ( b - t_k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \right] \]  
\[ + m^{p-1} M^2 \sum _{ k=1 } ^{ m } e^{-p \beta ( t-k )} e^{-p \beta \sigma_k} \left[ C_1 + ( d_k + \epsilon_k ) \left( \| \bar{x} \| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right) \right] \left\{ \left\| \bar{x} \right\| _{ p } + E \left\| x' ( t_k ) \right\| _{ p } ^{ 2 } \right\} \, ds + 5^{p-1} C_P M^p b^{p/2-1} \int _{ 0 } ^{ t } e^{-p \alpha ( t - s )} m_f ( s ) \]
\[ \cdot \Theta_f \left( \|x\|_H^p + E \|x'(s)\|_H^p + b^{p+1} \int_0^t m_h(s, \tau) \Theta_h \left( \|x\|_H^p + E \|x'(\tau)\|_H^p \right) d\tau \right) ds + (5m)^{p-1} M^{2p} \sum_{k=1}^m e^{-\gamma p(t-t_k)} \left[ C_1 \right. \\
+ \left. (c_k + \varepsilon_k) \left( \|x\|_H^p + E \|x' \|_H^p \right) \right] + (5m)^{p-1} M^{2p} \sum_{k=1}^m e^{-\alpha p(t-t_k)} \left[ C_1 + (d_k + \varepsilon_k) \left( \|x\|_H^p + E \|x' \|_H^p \right) \right]. \]

(66)

By Lemma II, it follows that
\[ \sup \left\{ \|x\|_H^p : 0 \leq s \leq t \right\} \leq 2^{p-1} (M_0 E \|\varphi\|_H^p)^p \]
\[ + 2^{p-1} K_2^p \sup \left\{ E \|x(s)\|_H^p : 0 \leq s \leq t \right\}, \]

(67)

Consider the function defined by
\[ \mu(t) = 2^{p-1} (M_k E \|\varphi\|_H^p)^p \]
\[ + 2^{p-1} K_2^p \sup \left\{ E \|x(s)\|_H^p : 0 \leq s \leq t \right\} \]
\[ + 2^{p-1} \sup \left\{ E \|x'(s)\|_H^p : 0 \leq s \leq t \right\}, \quad 0 \leq t \leq b, \]

(68)

where
\[ \|x\|_H^p + E \|x'(s)\|_H^p \leq \sup \left\{ \|x\|_H^p : 0 \leq s \leq t \right\} \]
\[ + \sup \left\{ E \|x'(s)\|_H^p : 0 \leq s \leq t \right\}. \]

(69)

For each \( t \in [0, b] \), we have
\[ E \|x(t)\|_H^p \leq 5^{p-1} M^p b^{p-1} L_g e^{-\rho_{a, s}} \int_0^t e^{\rho_{a, s}} \mu(s) ds \]
\[ + 20^{p-1} M^p e^{-\rho b} \frac{1}{a^p} \]
\[ \cdot M^p e^{-\rho b} M_1^{2p-1} \int_0^t e^{2p b} \left\{ \int E \|x\|_H^p \right\} \]
\[ + C_p b^{p-1} \int_0^b E \|\Phi(\eta)\|_H^p d\eta \]
\[ + M^p e^{-\rho b} \left[ E \|\phi(0)\|_H^p + 2^{p-1} \left\| \phi \|_H^p + \| g(0, \phi) \|_{L^1} \right\| \right] \]
\[ + M^p b^{p-1} L_g \int_0^b e^{-\rho b(\eta)} [\mu(\eta) + 1] d\eta \]
\[ + C_p M^p b^{p-1} \int_0^b E \|\Phi(\eta)\|_H^p d\eta \]
\[ + M^p e^{-\rho b} \left[ E \|\phi(0)\|_H^p + 2^{p-1} \left\| \phi \|_H^p + \| g(0, \phi) \|_{L^1} \right\| \right] \]
\[ + M^p b^{p-1} L_g \int_0^b e^{-\rho b(\eta)} [\mu(\eta) + 1] d\eta \]
\[ + C_p M^p b^{p-1} \int_0^b e^{-\rho b(\eta)} m_f(\eta) d\eta \]
\[ + \Theta_f \left( \mu(\eta) + b^{p-1} \int_0^\eta m_h(\eta, \nu) \Theta_h(\mu(\nu)) d\nu \right) d\eta \]
\[ + m^{p-1} M^{2p} \sum_{k=1}^m e^{-\alpha p(t-t_k)} \left[ C_1 + (c_k + \varepsilon_k) (\mu(\eta)) \right]. \]
+ m^{p-1} M^{2p} \sum_{k=1}^{m} e^{-p(b+1)} e^{-p\alpha_0} [C_1 + (d_k + \epsilon_k) (\mu (\eta))] \right) ds \\
+ 6^{p-1} C_p M^p b^{p/2-1} \int_0^t e^{-p(a-s)} m_f (s) \Theta_f \left( \mu (s) \right) ds \\
+ b^{p-1} \int_0^t m_h (s, \tau) \Theta_h (\mu (\tau)) d\tau + (6m)^{p-1} \\
\cdot M^{2p} \sum_{k=1}^{m} e^{-p(t-t_k)} e^{-p\alpha_0} [C_1 + (c_k + \epsilon_k) (\mu (s))] + (6m)^{p-1} \\
\cdot M^{2p} \sum_{k=1}^{m} e^{-p(t-t_k)} e^{-p\alpha_0} [C_1 + (d_k + \epsilon_k) (\mu (s))] .

(70)

Since \( \lim_{n \to \infty} \sigma_n = 0 \), it follows that

\[
\mu (t) \leq 2^{p-1} (M_k E \|\varphi\|_{L^p})^p + 2^{p-1} K^p b E \|x (t)\|_{L^p}^p \\
+ 2^{p-1} E \|x' (t)\|_{L^p}^p \leq \bar{M} + 2^{p-1} L g \mu (t) \\
+ N_1 M^p b^{p-1} \int_0^t e^{p\delta s} \mu (s) ds \\
+ N_1 M^p e^{-p\delta s} N_1 \int_0^t e^{p\delta s} ds \\
+ N_1 M^p e^{-p\delta s} N_3 \int_0^t e^{p\delta s} ds \\
+ N_1 C_p M^p b^{p/2-1} e^{p\delta s} \int_0^t e^{p\delta s} m_f (s) ds \\
\cdot \Theta_f \left( \mu (s) \right) + b^{p-1} \int_0^t m_h (s, \tau) \Theta_h (\mu (\tau)) d\tau + (10^{p-1} K^p + 12^{p-1}) \\
\cdot m^{p-1} M^{2p} e^{-p\delta s} N_2 \sum_{k=1}^{m} (c_k + \epsilon_k) \mu (t) + (10^{p-1} K^p \\
+ 12^{p-1}) m^{p-1} M^{2p} e^{-p\delta s} N_2 \sum_{k=1}^{m} (d_k + \epsilon_k) \mu (t),

(71)

where

\[
\bar{M} = 2^{p-1} (M^p E \|\varphi\|_{L^p})^p + 12^{p-1} K^p L g \\
+ N_1 M^p C_p M^p C_1, \\
N_1 = (10^{p-1} K^p + 12^{p-1}), \\
\delta = \min \{ \alpha, \beta, \gamma \}, \\
N_2 = 2^{p-1} \frac{1}{a^p} M^p e^{-p\delta b} M^p b^{p-1} \left( 4^{p-1} \frac{E\bar{x}_h}{H^p} \right) + N_1 M^p b^{p/2-1} - e^{p\delta s} m_f (t) \Theta_f (\mu (t))

\]
\( + b^{p-1} \int_0^t m_h(t, s) \Theta_h(\mu(s)) \, ds \) \]
\begin{align*}
& \leq \frac{1}{1 - \bar{L}} \left[ N_1 M^p b^{p-1} L g e^{p \delta t} e^{-p \delta t} \zeta(t) \\
& + N_1 M^p N_2 e^{2p \delta t} + N_1 M^p N_3 e^{2p \delta t} e^{-p \delta t} \zeta(t) \\
& + N_1 C \rho M^p b^{\rho/2-1} e^{p \delta b} m_f(t) \Theta_f \left( e^{-p \delta b} \zeta(t) \right) \\
& + b^{p-1} \int_0^t m_h(t, s) \Theta_h \left( e^{-p \delta t} \zeta(s) \right) \, ds \right].
\end{align*}
(75)

Let \( \xi(t) = e^{-p \delta t} \zeta(t) + b^{p-1} \int_0^t m_h(t, s) \Theta_h(e^{-p \delta t} \zeta(s)) \, ds \); then \( \xi(0) = \zeta(0), e^{-p \delta t} \zeta(t) \leq \xi(t) \), and for each \( t \in J \) we have
\begin{align*}
(\xi(t))' &= -p \delta e^{-p \delta t} \xi(t) + e^{t} (t) e^{-p \delta t} + b^{p-1} m_h(t, t) \\
&\cdot \Theta_h \left( e^{-p \delta t} \zeta(t) \right) \\
&+ \frac{1}{1 - \bar{L}} \left[ N_1 M^p b^{p-1} L g \xi(t) + N_1 M^p N_2 e^{p \delta t} \\
&+ N_1 M^p N_3 e^{p \delta t} \xi(t) \right] + \frac{1}{1 - \bar{L}} \\
&\cdot N_1 C \rho M^p b^{\rho/2-1} m_f(t) \Theta_f \left( \xi(t) \right) + b^{p-1} m_h(t, t) \\
&\cdot \Theta_h \left( \xi(t) \right) \leq \bar{m}(t) \left[ (t + 1 + \Theta_f (\xi(t)) \right) \\
&+ \Theta_h (\xi(t)) \right], \quad t \in J,
\end{align*}
(76)

where
\begin{align*}
\bar{m}(t) &= \max \left\{ -p \delta \right\} \\
&+ \frac{1}{1 - \bar{L}} \left[ N_1 M^p b^{p-1} L g + N_1 M^p N_2 e^{p \delta t} \right], \frac{1}{1 - \bar{L}} \\
&\cdot N_1 M^2 N_3 e^{p \delta t} \frac{1}{1 - \bar{L}} \\
&\cdot K_b N_1 C \rho M^p b^{\rho/2-1} m_f(t), b^{p-1} m_h(t, t) \right\}.
\end{align*}
(77)

This implies that
\[
\int_{\xi(0)}^{\xi(t)} \frac{d \theta}{1 + \Theta_h (\theta) + \Theta_h (\theta)} \leq \int_0^b \bar{m}(t) \, dt < \infty.
\]  
(78)

This inequality shows that there is a constant \( \bar{K} \) such that \( \xi(t) \leq \bar{K}, t \in J \), and hence \( |x_n|_{p, \Omega(\bar{t})} \leq \mu(t) \leq e^{-p \delta t} \zeta(t) \leq \zeta(t) \leq \bar{K}, \) where \( \bar{K} \) depends only on \( M, \delta, p, C, K_b, b \), and \( b \) and on the functions \( m_f(\cdot), m_h(\cdot), \Theta_f(\cdot) \), and \( \Theta_h(\cdot) \). This indicates that \( G \) is bounded on \( J \). Consequently, by Lemma 13, we deduce that
\[ \Lambda_n + Y_n \) has a fixed point \( x_n \in \mathcal{R}_b^0 \), which is a mild solution of problem (27). Then, we have
\[
x_n(t) = \int_0^t C(t-s) g \left( s, x_{n,s}, x'_{n,s}(s) \right) \, ds \\
+ \int_0^t S(t-s) Bu_n^2 (s) \, ds \\
+ \int_0^t S(t-s) f(s) \, dw(s) \\
+ \sum_{0 < t_k < t} C(t-t_k) C(\sigma_n) I_k \left( \bar{x}_{n,t_k}, x_{n,t_k} \right) \\
+ \sum_{0 < t_k < t} S(t-t_k) S(\sigma_n) I_k \left( \bar{x}_{n,t_k}, x_{n,t_k} \right)
\]  
for \( t \in [0, b] \), and some \( f_n \in S_{F \Xi_n} \).

Next we will show that the set \( \{ x_n : n \in \mathbb{N} \} \) is relatively compact in \( \mathcal{R}_b^0 \). We consider the decomposition \( x_n = x_n^1 + x_n^2 \), where
\[
x_n^1(t) = \int_0^t C(t-s) g \left( s, x_{n,s}, x'_{n,s}(s) \right) \, ds \\
+ \int_0^t S(t-s) Bu_n^2 (s) \, ds \\
+ \int_0^t S(t-s) f(s) \, dw(s)
\]  
(80)

for some \( f_n \in S_{F \Xi_n} \), and
\[
x_n^2(t) = \sum_{0 < t_k < t} C(t-t_k) C(\sigma_n) I_k \left( \bar{x}_{n,t_k}, x_{n,t_k} \right) \\
+ \sum_{0 < t_k < t} S(t-t_k) S(\sigma_n) I_k \left( \bar{x}_{n,t_k}, x_{n,t_k} \right).
\]  
(81)

Step 4, \( \{ x_n^1 : n \in \mathbb{N} \} \) is relatively compact in \( \mathcal{R}_b^0 \).

(1) \( \{ x_n^1 : n \in \mathbb{N} \} \) is equicontinuous on \( J \).

For \( \varepsilon > 0, x_n \in B_0(0, \mathcal{R}_b^0) \), there exists a constant \( 0 < \bar{\eta} < \varepsilon \) such that, for all \( t \in (0, b] \) and \( \xi \in (0, \bar{\eta}] \) with \( t + \xi \leq b \), we have
\[
E \left\| x_n^1(t + \xi) - x_n^1(t) \right\|_{H^t} \leq \delta^{p-1} E \left\| \int_t^{t+\xi} C(t+\xi-s) \right\|_{H^t} \\
\cdot g \left( s, \bar{x}_{n,s}, \bar{x}'_{n,s} (s) \right) \, ds \right\|_{H^t} \\
+ \delta^{p-1} E \left\| \int_0^t \left[ C(t+\xi-s) - C(t-s) \right] \right\|_{H^t} \\
\cdot g \left( s, \bar{x}_{n,s}, \bar{x}'_{n,s} (s) \right) \, ds \right\|_{H^t} + \delta^{p-1} E \left\| \int_t^{t+\xi} S(t+\xi-s) \right\|_{H^t}
\]
Using the compact operator property, we can choose \( \xi \in (0, t) \) such that

\[
6^{p-1} \xi^{p-1} L^p \int_0^{t+\xi} e^{-\beta((t+\xi-s)/p)} M_2 ds < \frac{\varepsilon}{6},
\]

\[
6^{p-1} b^{p-1} \int_0^{t} \| C(t+\xi-s) - C(t-s) \|_H^p < \frac{\varepsilon}{6},
\]

\[
6^{p-1} M^p \int_0^{t+\xi} e^{-\beta((t+\xi-s)/p)} L_G (r^* + r + 1) ds < \frac{\varepsilon}{6},
\]

\[
6^{p-1} M^p \int_0^{t+\xi} e^{-\beta((t+\xi-s)/p)} L_G (r^*) \left[ \frac{2\delta (p-1)}{p-2} \right]^{1-p/2} e^{-\beta(t-s)} m_f (s) ds < \frac{\varepsilon}{6}.
\]
Combining the above inequality, one has \([x_n^2(t) : n \in \mathbb{N}]\) which is relatively compact in \(H\).

**Step 5.** \([x_n^2(t) : n \in \mathbb{N}]\) is relatively compact in \(B^0\).

1. For any \(\epsilon > 0\), \(0 < t < b\). Since \(C(\sigma_n), S(\sigma_n)\) are compact operators, we find that the sets \(W_1 = \{C(\sigma_n) \Delta_k(\overline{x}_n, \overline{x}_n(t_k)) : x_n \in B_r(0, \mathcal{B}^0)\}\) and \(W_2 = \{S(\sigma_n) \Delta_k(\overline{x}_n, \overline{x}_n(t_k)) : x_n \in B_r(0, \mathcal{B}^0)\}\) are relatively compact in \(H\). From the strong continuity of \((C(t))_{t \geq 0}\), for \(\epsilon > 0\), we can choose \(0 < \eta < b - t\) such that

\[
E \left\| (C(t + \xi) - C(t)) v_1 \right\|_H < \frac{\epsilon}{2(2m)^{p-1}}, \quad v_1 \in W_1,
\]

\[
E \left\| (S(t + \xi) - S(t)) v_2 \right\|_H < \frac{\epsilon}{2(2m)^{p-1}}, \quad v_2 \in W_2
\]

when \(|\xi| < \eta\). For each \(x_n \in B_r(0, \mathcal{B}^0)\), \(t \in (0, b)\) is fixed and \(t \in [t_k, t_{k+1}]\), such that

\[
E \left\| \left[ x_n^2(t_k) - x_n^2(t) \right] \right\|_H^p \leq 2^{p-1} E \sum_{0 < t_k \leq t} \left| C(t + \xi - t_k) - C(t - t_k) \right| C(\sigma_n)
\]

where \(B_r(0, \mathcal{B}^0)\) is a closed ball of radius \(r\). One has \([x_n^2(t_k) : k = 1, 2, \ldots, m]\) which is relatively compact for every \(t \in [t_k, t_{k+1}]\), and \([x_n^2(t) : n \in \mathbb{N}]\) is relatively compact in \(H\).

These facts imply the relatively compact of \([x_n(t) : n \in \mathbb{N}]\) in \(B^0\). Therefore, without loss of generality, we may suppose that

\[
x_n \to x_* \in \mathcal{B}^0 \quad \text{as} \quad n \to \infty.
\]

Obviously, \(x_* \in \mathcal{B}^0\), taking limits in (79) one has

\[
x_* (t) = \int_0^t C(t - s) g\left(s, \overline{x}_s, \overline{x}_s' (s) \right) ds + \int_0^t S(t - s) B u\left(\overline{x}_s' (s) \right) ds
\]

for \(t \in [0, b]\), and some \(f_\epsilon \in S_E[\overline{x}_s]\), which implies that \(x_*\) is a mild solution of the problem (1). The proof of Theorem 16 is complete.
4. Approximate Controllability of Impulsive Stochastic Control System

In this section, we present our main result on approximate controllability of system (1). To do this, we also need the following assumptions:

(B1) The function \( g : J \times \mathcal{B} \times H \rightarrow H \) is continuous and there exists a constant \( \tilde{C}_1 > 0 \) such that

\[
E \| g(t, \psi, y) \|_{L_h} \leq \tilde{C}_1
\]  

(92)

for \( 0 \leq t \leq b, (\psi, y) \in \mathcal{B} \times H \).

(B2) There exists a constant \( \tilde{C}_2 > 0 \) such that

\[
\| F(t, \psi, y, z) \|_{L^p_h} \leq \tilde{C}_2
\]  

(93)

for \( 0 \leq t \leq b, (\psi, y, z) \in \mathcal{B} \times H \times H \), where

\[
\| F(t, \psi, y, z) \|_{L^p_h} = \sup \{ E \| f \|_{L^p_h} : f \in F(t, \psi, y, z) \}.
\]  

(94)

**Theorem 17.** Assume that assumptions of Theorem 16 hold and, in addition, hypotheses (S1), (B1), and (B2) are satisfied. Then system (1) is approximately controllable on \( J \).

**Proof.** Let \( x^a(\cdot) \) be a fixed point of \( \Phi \) in \( \mathcal{B}^a \). By Theorem 16, any fixed point of \( \Phi \) is a mild solution of system (1). This means that there is \( x^a \in \Phi(x^a) \); that is, there is \( f^* \in S_{E, \mathcal{B}} \) such that

\[
x^a(t) = \int_0^t C(t-s) g \left( s, \mathcal{X}^a, (\mathcal{X}^a)'(s) \right) ds
+ \int_0^t S(t-s) Bu^a(s) ds
+ \int_0^t S(t-s) f(s) dw(s)
+ \sum_{0 \leq t_k < t} C(t-t_k) I_k \left( \mathcal{X}^a_{t_k}, (\mathcal{X}^a)'(t_k) \right)
+ \sum_{0 \leq t_k < t} S(t-t_k) I_k \left( \mathcal{X}^a_{t_k}, (\mathcal{X}^a)'(t_k) \right), \quad t \in J,
\]  

(95)

where

\[
u^a_x(t) = B^* S^* (b-t) \left( aI + I^b_x \right)^{-1} E \mathcal{X}_b
+ \int_0^b \tilde{\phi}(s) dw(s) - C(b) \varphi(0)
\]

and by using the stochastic Fubini theorem, it is easy to see that

\[
x^a(b) = \int_0^b C(b-s) g \left( s, \mathcal{X}^a, (\mathcal{X}^a)'(s) \right) ds
+ \int_0^b S(b-s) Bu^a(s) ds + \int_0^b S(b-s) f(s) dw(s)
+ \sum_{0 \leq t_k < b} C(b-t_k) I_k \left( \mathcal{X}^a_{t_k}, (\mathcal{X}^a)'(t_k) \right)
+ \sum_{0 \leq t_k < b} S(b-t_k) I_k \left( \mathcal{X}^a_{t_k}, (\mathcal{X}^a)'(t_k) \right)
- S(b) [\phi - g(0, \varphi, \psi)]
- B^* S^* (b-t) \left( aI + I^b_x \right)^{-1} E \mathcal{X}_b
\]

(96)

By conditions (B1) and (B2), we get that the sequences \( \{g(s, \mathcal{X}^a, (\mathcal{X}^a)'(s))\} \) and \( \{f(s)\} \) are uniformly bounded on \( J \). Thus there are subsequences, still denoted by \( \{g(s, \mathcal{X}^a, (\mathcal{X}^a)'(s))\} \) and \( \{f(s)\} \) that converge weakly to, say, \( g(s) \) in \( H \) and \( f^{**}(s) \) in \( L(K, H) \), respectively. The compactness of \( S(t), t > 0 \), implies that \( S(b-s) [g(s, \mathcal{X}^a, (\mathcal{X}^a)'(s)) -
\[ g(s) \to 0, S(b-s)[f(s) - f^{**}(s)] \to 0. \] On the other hand, by Lemma 9, for all \( t \in J, a(al + \Gamma b)^{-1} \to 0 \) strongly as \( a \to 0^+ \) and \( \|a(al + \Gamma b)^{-1}\| \leq 1 \). Therefore, by the Lebesque dominated convergence theorem it follows that

\[
E\|x^a (b) - x_b\|_H^2 \leq 8^{p-1}E \|a(al + \Gamma b)^{-1}\| \sum_{k=1}^m C(b-t_k) \left( x_k^a, (x^a)'(t_k) \right) \|_H^p + 8^{p-1} \|a(al + \Gamma b)^{-1}\| \sum_{k=1}^m S(b-t_k) \left( x_k^a, (x^a)'(t_k) \right) \|_H^p + 8^{p-1} \|a(al + \Gamma b)^{-1}\| \sum_{k=1}^m S(b-t_k) \left( x_k^a, (x^a)'(t_k) \right) \|_H^p \to 0 \quad \text{as} \quad a \to 0^+.
\]

So \( x^a (b) \to x_b \), which shows that system (1) is approximately controllable and the proof is complete. \( \square \)

### 5. Example

Consider the following impulsive partial stochastic neutral differential inclusions of the form

\[
d \left[ \frac{\partial}{\partial t} z(t, x) - \int_{-\infty}^t b_1(s-t) z(s, x) \, ds - b_2(s) z'(t, x) \right] \in \mathcal{D}^p \left[ \frac{\partial}{\partial t} z(t, x) \right] dt + \nu(t, x) \, dt
\]

where \((t_k) \in \mathbb{N}\) is a strictly increasing sequence of positive numbers and \(\bar{u}(\cdot)\) is a real function of bounded variation on \([0, b]\). \(\omega(t)\) denotes a standard cylindrical Wiener process in \(H\) defined on a stochastic space \((\Omega, \mathcal{F}, \mathbb{P})\).

Let \(H = L^2([0, \pi])\) with the norm \(\| \cdot \|_H\). Define the operator \(A\) by \(A\omega = \omega''\) with the domain

\[
D(A) := \{ \omega(\cdot) \in H : \omega, \omega' \text{ are absolutely continuous}, \omega'' \}
\]

It is well known that \(A\) is the infinitesimal generator of a strongly continuous cosine family \(\{C(t) : t \in \mathbb{R}\}\) in \(H\) and is given by

\[
C(t) \omega = \sum_{n=1}^{\infty} \cos(nt) \langle \omega, e^n \rangle e^n, \quad \omega \in H,
\]

where \(e^n(\theta) = \sqrt{2/\pi} \sin n\theta, \ i = 1, 2, \ldots\) is the orthogonal set of eigenvalues of \(A\). The associated sine family \(S(t)\) is compact and is given by

\[
S(t) \omega = \sum_{n=1}^{\infty} \frac{1}{n} \sin(nt) \langle \omega, e^n \rangle e^n, \quad \omega \in H.
\]

Additionally, we will assume the following:

(i) The functions \(b_i : \mathbb{R} \to \mathbb{R}, i = 1, 2\), are continuous, and \(\mathcal{L}_1 = (\int_{-\infty}^0 (b_1(s))^2 / \nu(s)^2 \, ds)^{1/2} < \infty\).
(ii) The functions $\omega_i : \mathbb{R}^4 \to \mathbb{R}$, $i = 1, 2$, are continuous and there exist continuous functions $a_j : \mathbb{R} \to \mathbb{R}$, $j = 1, 2, 3, 4$, such that

\[
\begin{align*}
|\omega_1(t, s, x, y)| &\leq a_1(t) a_2(s) |y|, & (t, s, x, y) \in \mathbb{R}^4, \\
|\omega_2(t, s, x, y)| &\leq a_3(t) a_4(s) |y|, & (t, s, x, y) \in \mathbb{R}^4
\end{align*}
\]  

(103)

with $\tilde{L}_1 = (\int_{-\infty}^{0}((a_1(s))^2/\tilde{h}(s))ds)^{1/2} < \infty$, $\tilde{L}_2 = (\int_{-\infty}^{0}((a_2(s))^2/\tilde{h}(s))ds)^{1/2} < \infty$.

(iii) The functions $\zeta_i, k_j : \mathbb{R} \to \mathbb{R}$, $i = 1, 2$, are continuous.

(iv) The functions $\eta_k, \tilde{k}_k : \mathbb{R} \to \mathbb{R}$, $k = 1, 2, \ldots, m$, are continuous, $\delta_k = (\int_{-\infty}^{0}((\eta_k(s))^2/\tilde{h}(s))ds)^{1/2} < \infty$, and $\tilde{\delta}_k = (\int_{-\infty}^{0}((\tilde{k}_k(s))^2/\tilde{h}(s))ds)^{1/2} < \infty$ for every $k = 1, 2, \ldots, m$.

Take $\mathcal{B} = \mathcal{D}_0 \times L^2(h, H)$ which is the space introduced in Example 2. Set $\psi(\theta)(x) = \psi(\theta, x) \in \mathcal{B}$, defining the maps $g : [0, b] \times \mathcal{B} \times H \to H$, $F : [0, b] \times \mathcal{B} \times H \times \mathcal{H} \to \mathcal{H}$ by

\[
g(t, \psi, \psi')(x) = \int_{-\infty}^{t} b_1(s) \psi(s, x) ds + b_2(t) \psi'(t, x),
\]

\[
f(t, \psi, \psi', B_1 \psi)(x) = \int_{-\infty}^{0} \omega_1(t, s, x, \psi(s, x)) ds + \zeta_1(t) \psi'(t, x) + B_1 \psi(x),
\]

\[
B_1 \psi(x) = \int_{0}^{t} \int_{0}^{s} \zeta_2(\tau) \omega_2(s, \tau, x, \psi(\tau, x)) d\tau ds + \int_{0}^{t} \zeta_3(s) \psi'(s, x) ds,
\]

\[
I_k(\psi, \psi')(x) = \int_{-\infty}^{0} \eta_k(s) \psi(s, x) ds + k_1(t_k) \psi'(t_k, x),
\]

\[
J_k(\psi, \psi')(x) = \int_{-\infty}^{0} \tilde{k}_k(s) \psi(s, x) ds + k_2(t_k) \psi'(t_k, x).
\]

Using these definitions, we can represent system (99) in the abstract form (1). Moreover, it is easy to see that $G$, $I_k$, and $J_k$ are continuous, and $G$, $I_k$, $J_k$, and $F$ are bounded linear operators with $E\|G\|_{L^p(L^2;L^2)} \leq L_G$, $E\|I_k\|_{L^p(L^2;L^2)} \leq \delta_k$, $E\|J_k\|_{L^p(L^2;L^2)} \leq \delta_k$, $E\|F\|_{L^p(L^2;L^2)} \leq L_F$, where $L_G = \tilde{L}_1 + \|b_2\|_{L^p} \delta_k$, $\delta_k = [\tilde{\delta}_k + \|k_2\|_{L^p}]^p$, $d_k = [\tilde{\delta}_k + \|k_2\|_{L^p}]^p$, and $L_F = [\|a_1\|_{L^\infty} \tilde{L}_1 + \|a_1\|_{L^\infty} + \|k_3\|_{L^p} + \|k_3\|_{L^p} \tilde{L}_2 + \|c_3\|_{L^p}]^p$. Further, we can impose some suitable conditions on the above-defined functions to verify the assumptions on Theorem 16. Therefore, assumptions (H1)–(H6), (B1), and (B2) all hold, and the associated linear system of (99) is not exactly controllable but it is approximately controllable. Hence by Theorems 16 and 17, system (99) is approximately controllable on $[0, b]$.

**Conflict of Interests**

The author declares that there is no conflict of interests regarding the publication of this paper.

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