Research Article

About the Existence Results of Fractional Neutral Integrodifferential Inclusions with State-Dependent Delay in Fréchet Spaces

Selvaraj Suganya,¹ Dumitru Baleanu,^{2,3} Siva Selvarasu,¹ and Mani Mallika Arjunan¹

¹Department of Mathematics, C. B. M. College, Kovaipudur, Coimbatore, Tamil Nadu 641 042, India

²Department of Mathematics and Computer Sciences, Faculty of Art and Sciences, Cankaya University, 06530 Ankara, Turkey

³Institute of Space Sciences, Magurele, Bucharest, Romania

Correspondence should be addressed to Dumitru Baleanu; dumitru@cankaya.edu.tr

Received 21 October 2015; Accepted 16 December 2015

Academic Editor: Hugo Leiva

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A recent nonlinear alternative for multivalued contractions in Fréchet spaces thanks to Frigon fixed point theorem consolidated with semigroup theory is utilized to examine the existence results for fractional neutral integrodifferential inclusions (FNIDI) with state-dependent delay (SDD). An example is described to represent the hypothesis.

1. Introduction

We are dealing in this paper with the existence of mild solutions for FNIDI with SDD in Fréchet spaces by making use of the fixed point theorem of Frigon [1, Corollary 3.5]. In Section 3 of this paper, we deliberate the neutral integrodifferential inclusions of fractional-order of the model

$$\begin{aligned} & \frac{d}{dt} [x(t) - \mathcal{G}(t, x_{\varrho(t, x_t)})] \\ & \in \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} \mathcal{A} [x(s) - \mathcal{G}(s, x_{\varrho(s, x_s)})] ds \\ & + \mathcal{F} \left(t, x_{\varrho(t, x_t)}, \int_0^t e(t, s, x_{\varrho(s, x_s)}) ds \right), \end{aligned} \quad (1)$$

a.e. $t \in \mathcal{J} = [0, +\infty)$,

$$x_0 = \varsigma \in \mathcal{B},$$

wherein $1 < \alpha < 2$ and $\mathcal{A} : D(\mathcal{A}) \subset \mathbb{E} \rightarrow \mathbb{E}$ is the generator of an integral resolvent family characterized on a complex Banach space $(\mathbb{E}, |\cdot|)$, the convolution integral within the equation is understood because of the Riemann-Liouville fractional integral (see [2]), $\mathcal{F} : \mathcal{J} \times \mathcal{B} \times \mathbb{E} \rightarrow \mathcal{P}(\mathbb{E})$ is

a multivalued map, $(\mathcal{P}(\mathbb{E}))$ is the family of nonempty subsets of $\mathbb{E}$, $e : \mathcal{J} \times \mathcal{J} \times \mathcal{B} \rightarrow \mathbb{E}$, $\mathcal{G} : \mathcal{J} \times \mathcal{B} \rightarrow \mathbb{E}$, and $\varrho : \mathcal{J} \times \mathcal{B} \rightarrow (-\infty, +\infty)$ are apposite functions, and $\mathcal{B}$ is theoretical phase space axioms characterized in Section 2.

For almost any continuous function x characterized on $(-\infty, b]$ and any $t \geq 0$, we designate by x_t the part of $\mathcal{B}$ characterized by $x_t(\theta) = x(t + \theta)$ for $\theta \leq 0$. Now, $x_t(\cdot)$ speaks to the historical backdrop of the state from every $\theta \in (-\infty, 0]$ likely the current time t .

The notion of a fractional derivative plays an important role in numerous technological innovation and scientific disciplines as the statistical modeling of frameworks and procedures in numerous fields, case in point, physical science, chemical industry, aerodynamics, electrodynamics of complex medium, and so forth. For information, we recommend the readers to refer to the treatise of Abbas et al. [3], Baleanu et al. [4], Podlubny [5], Diethelm [6], Kilbas et al. [7], and Zhou [8] and the papers of fractional differential and integrodifferential systems [9–12] and impulsive fractional differential systems [13–15] and the references cited therein.

We recall that the fractional differential inclusions (FDI) occur in the mathematical modeling of specific models in financial aspects, optimal control, and so forth and are usually

investigated by numerous writers; see, for instance, [16–18] and the references therein. Fractional equation with delay properties arises in several fields such as biological and physical ones with state-dependent delay or nonconstant delay. Nowadays, the existence results of mild solutions for such problems became very attractive and several researchers are working on it. Recently, several number of papers have been written on the fractional-order problems with state-dependent delay [19–23] and the sources therein. In particular, in [20, 21], the authors analyzed the existence results for neutral differential systems with SDD in Banach spaces, whereas in [19, 22] the authors investigate the same type of problems with SDD and impulsive conditions by utilizing appropriate fixed point theorem. Also, the integrodifferential systems are experienced in numerous ranges of science, the place where it is imperative to deal with aftereffect or delay (e.g., control theory, biology, ecology, and medicine). Particularly, one dependably depicts a model which has inherited qualities by integrodifferential systems in implementation; see, for instance, [23–25].

The beginning stage of this work is reflected in [26–30]. Particularly, in [26], Agarwal et al. acquired the existence of mild solutions for FIDE of the structure

$$x'(t) = \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} \mathcal{A}x(s) ds + f(t, x_{\varrho(t, x_t)}), \quad \text{a.e. } t \in \mathcal{J} = [0, b], \quad (2)$$

$$x(0) = \varsigma \in \mathcal{B},$$

in which $1 < \alpha < 2$ and $\mathcal{A} : D(\mathcal{A}) \subset \mathbb{X} \rightarrow \mathbb{X}$ is a linear densely described operator of sectorial kind on a complex Banach space $(\mathbb{X}, |\cdot|)$, whereas, in [30], the authors establish the existence results for FIDI of the model

$$x'(t) - \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} \mathcal{A}x(s) ds \in \mathcal{F}(t, x_{\varrho(t, x_t)}), \quad \text{a.e. } t \in \mathcal{J} = [0, \infty), \quad (3)$$

$$x_0 = \varsigma \in \mathcal{B},$$

where α and $\mathcal{A}$ are the same as those mentioned in model (1).

The existence of mild solutions for the division of FNIDI with SDD in Fréchet spaces of the structure (1) is by all accounts an unread point. By utilizing a few speculations as a part of [27, 30], our desire here is to yield the existence results for the above model (1) utilizing a nonlinear alternative for multivalued contractions as of late created by Frigon [1, Corollary 3.5].

2. Preliminary Notions

Below, we briefly present the mathematical tools required in this paper.

Let $C([0, n], \mathbb{E})$, $n \in \mathbb{N}$, be the Banach space of all continuous functions from $\mathcal{J}_n = [0, n]$ into $\mathbb{E}$ making use of the standard norm

$$\|x\|_n = \sup \{|x(t)| : 0 \leq t \leq n\}. \quad (4)$$

Allow $B(\mathbb{E})$ to be the space of all bounded linear operators $\mathcal{N} : \mathbb{E} \rightarrow \mathbb{E}$, having the common supremum norm

$$\|\mathcal{N}\|_{B(\mathbb{E})} = \sup \{|\mathcal{N}(x)| : |x| = 1\}. \quad (5)$$

A measurable function $x : \mathcal{J}_n \rightarrow \mathbb{E}$ is Bochner integrable if and only if $|x|$ is Lebesgue integrable (to get extra insights about Bochner integral, see the treatise of Yosida [31]).

Let $L^1(\mathcal{J}_n, \mathbb{E})$ signify the Banach space of all measurable functions $x : \mathcal{J}_n \rightarrow \mathbb{E}$ which are Bochner integrable making use of the norm

$$\|x\|_{L^1} = \int_0^n |x(t)| dt \quad \forall x \in L^1(\mathcal{J}_n, \mathbb{E}). \quad (6)$$

Recognize the space

$$\mathcal{V}_{+\infty} = \{x : (-\infty, +\infty) \rightarrow \mathbb{E} : x|_{\mathcal{J}} \in C(\mathcal{J}, \mathbb{E}), x_0 \in \mathcal{B}\}, \quad (7)$$

where $x|_{\mathcal{J}}$ is the restraint of x to $\mathcal{J}$.

We expect that the phase space $(\mathcal{B}, \|\cdot\|_{\mathcal{B}})$ is a seminormed linear space of functions mapping $(-\infty, 0]$ into $\mathbb{E}$ and fulfilling the subsequent elementary adages as a result of Hale and Kato (find illustration in [32–34]).

(P_1) If $x : (-\infty, n) \rightarrow \mathbb{E}$ is continuous on $\mathcal{J}_n$ and $x_0 \in \mathcal{B}$, then for every $t \in \mathcal{J}_n$ the going hand in hand circumstances hold the following:

- (i) x_t is in $\mathcal{B}$;
- (ii) $|x(t)| \leq H\|x_t\|_{\mathcal{B}}$;
- (iii) $\|x_t\|_{\mathcal{B}} \leq \mathcal{D}_1(t) \sup\{|x(s)| : 0 \leq s \leq t\} + \mathcal{D}_2(t)\|x_0\|_{\mathcal{B}}$, where $H > 0$ is a constant and $\mathcal{D}_1(\cdot) : [0, +\infty) \rightarrow [0, +\infty)$ is continuous, $\mathcal{D}_2(\cdot) : [0, +\infty) \rightarrow [0, +\infty)$ is locally bounded, and $\mathcal{D}_1, \mathcal{D}_2$ are independent of $x(\cdot)$.

(P_2) For function $x(\cdot)$ in (P_1), x_t is a $\mathcal{B}$ -valued continuous function on $\mathcal{J}_n$.

(P_3) The space $\mathcal{B}$ is complete.

Designate $\mathcal{D}_1^* = \sup\{\mathcal{D}_1(t) : t \in \mathcal{J}_n\}$ and $\mathcal{D}_2^* = \sup\{\mathcal{D}_2(t) : t \in \mathcal{J}_n\}$.

The next step is to review some known results from the fractional calculus.

The Laplace transformation of a function $f \in L_{\text{loc}}^1(\mathbb{R}^+, \mathbb{E})$ is determined by

$$\mathcal{L}(f)(\lambda) = \widehat{s}(\lambda) = \int_0^\infty e^{-\lambda t} f(t) dt, \quad \text{Re}(\lambda) > \omega, \quad (8)$$

if the integral is definitely convergent for $\text{Re}(\lambda) > \omega$. With a specific end goal to give an operator hypothetical methodology, we review the subsequent definition [2].

Definition 1. Let $\mathcal{A} : D(\mathcal{A}) \subset \mathbb{E} \rightarrow \mathbb{E}$ be a closed and linear operator on a Banach space $\mathbb{E}$. One addresses $\mathcal{A}$ as the generator of an integral resolvent if one can find $\omega > 0$ and

a strongly continuous function $\mathcal{S} : \mathbb{R}^+ \rightarrow B(\mathbb{E})$ to ensure that

$$\left(\frac{1}{\hat{s}(\lambda)} I - \mathcal{A} \right)^{-1} x = \int_0^\infty e^{-\lambda t} \mathcal{S}(t) x dt, \quad (9)$$

$$\operatorname{Re} \lambda > \omega, \quad x \in \mathbb{E}.$$

For this situation, $\mathcal{S}(t)$ is known as the integral resolvent family produced by $\mathcal{A}$. For extra points of interest regarding this, we refer the reader to [35, Proposition 3.1 and Lemma 2.2].

Remark 2. The uniqueness and uniform continuity of the resolvent are long-familiar (see Benchohra and Litimein [30], Pruss [36]).

Before we complete this section, we display some long-familiar outcomes from multivalued research.

Indicate the following:

$$\begin{aligned} \mathcal{P}(X) &= \{Y \subset X : Y \neq \emptyset\}, \\ \mathcal{P}_d(X) &= \{Y \in \mathcal{P}(X) : Y \text{ closed}\}, \\ \mathcal{P}_b(X) &= \{Y \in \mathcal{P}(X) : Y \text{ bounded}\}, \\ \mathcal{P}_{cp}(X) &= \{Y \in \mathcal{P}(X) : Y \text{ compact}\}, \\ \mathcal{P}_{cp,c}(X) &= \{Y \in \mathcal{P}(X) : Y \text{ compact and convex}\}. \end{aligned} \quad (10)$$

Proposition 3 (see [37, Proposition III.4]). *If Γ_1 and Γ_2 are compact valued measurable multifunctions, then the multifunction $t \rightarrow \Gamma_1(t) \cap \Gamma_2(t)$ is measurable. If (Γ_n) is a sequence of compact valued measurable multifunctions, then $t \rightarrow \cap \Gamma_n(t)$ is measurable, and if $\cup \Gamma_n(t)$ is compact, then $t \rightarrow \cup \Gamma_n(t)$ is measurable.*

Remark 4. The definitions of measurable, admissible contraction, metric space, and nonlinear alternative fixed point theorem [1, Corollary 3.5] are classical in multivalued analysis; hence, we keep off it.

Remark 5. For primary and surplus points on Fréchet spaces, we refer the reader to [30].

For each $x \in \mathcal{V}_{+\infty}$, specify the set of selections for $\mathcal{F}$ by

$$\begin{aligned} S_{\mathcal{F},x} &= \left\{ v \in L^1(\mathcal{J}, \mathbb{E}) : v(t) \right. \\ &\quad \left. \in \mathcal{F} \left(t, x_{\varrho(t,x_t)}, \int_0^t e(t,s, x_{\varrho(s,x_s)}) ds \right) \text{ for a.e. } t \right. \\ &\quad \left. \in \mathcal{J} \right\}. \end{aligned} \quad (11)$$

For surplus points of benefit on multivalued maps, think about the treatise of Castaing and Valadier [37] and Graef et al. [38].

3. The Main Results

In this part, we prove the existence outcomes for the structure (1). To commence, we delineate the mild solution for the structure (1).

Definition 6. One affirms that the function $x : (-\infty, +\infty) \rightarrow \mathbb{E}$ is a mild solution of the model (1) if $x(t) = \zeta(t)$ for all $t \leq 0$, the constraint of $x(\cdot)$ to the period $[0, \infty)$ is continuous and one can find $v(\cdot) \in L^1(J, \mathbb{E})$, in a way that $v(t) \in \mathcal{F}(t, x_{\varrho(t,x_t)}, \int_0^t e(t,s, x_{\varrho(s,x_s)}) ds)$ a.e. $t \in [0, \infty)$, and x fulfills the consecutive integral equation:

$$\begin{aligned} x(t) &= \mathcal{S}(t) [\zeta(0) - \mathcal{G}(0, \zeta(0))] + \mathcal{G}(t, x_{\varrho(t,x_t)}) \\ &\quad + \int_0^t \mathcal{S}(t-s) v(s) ds \end{aligned} \quad (12)$$

for every $t \in [0, +\infty)$.

Set

$$\mathcal{R}(\varrho^-) = \{\varrho(s, \varsigma) : (s, \varsigma) \in \mathcal{J} \times \mathcal{B}, \varrho(s, \varsigma) \leq 0\}. \quad (13)$$

We generally expect that $\varrho : \mathcal{J} \times \mathcal{B} \rightarrow (-\infty, b]$ is continuous. Moreover, we make the subsequent assumption:

(H_ς) function $t \rightarrow \varsigma_t$ is continuous from $\mathcal{R}(\varrho^-)$ into $\mathcal{B}$ and we can find a continuous and bounded function $L^\varsigma : \mathcal{R}(\varrho^-) \rightarrow (0, \infty)$ in a way that

$$\|\varsigma_t\|_{\mathcal{B}} \leq L^\varsigma(t) \|\varsigma\|_{\mathcal{B}} \quad \text{for every } t \in \mathcal{R}(\varrho^-). \quad (14)$$

Lemma 7 (see [21, Lemma 3.1]). *If $x : (-\infty, b] \rightarrow \mathbb{X}$ is a function to ensure that $x_0 = \varsigma$, then*

$$\begin{aligned} \|x_s\|_{\mathcal{B}} &\leq (\mathcal{D}_2^* + L^\varsigma) \|\varsigma\|_{\mathcal{B}} \\ &\quad + \mathcal{D}_1^* \sup \{|x(\theta)| : \theta \in [0, \max\{0, s\}]\}, \end{aligned} \quad (15)$$

$s \in \mathcal{R}(\varrho^-) \cup \mathcal{J}_n$,

where $L^\varsigma = \sup_{t \in \mathcal{R}(\varrho^-)} L^\varsigma(t)$.

The successive hypotheses will be required in whatever is left of this paper.

(H1) The solution operator $\mathcal{S}(t)_{t \in \mathcal{J}}$ is compact for $t \geq 0$, and we can find $\mathcal{M} > 0$ in a way that

$$\|\mathcal{S}(t)\|_{B(\mathbb{E})} \leq \mathcal{M} \quad \text{for every } t \in \mathcal{J}. \quad (16)$$

(H2)

(i) The multivalued map $\mathcal{F} : \mathcal{J} \times \mathcal{B} \times \mathbb{E} \rightarrow \mathcal{P}_{cp,c}(\mathbb{E})$ is Carathéodory and there is certainly function $\vartheta \in L^1_{loc}(\mathcal{J}, \mathbb{R}^+)$ and a continuous nondecreasing function $\odot : \mathbb{R}^+ \rightarrow (0, \infty)$ in a way that

$$\begin{aligned} |\mathcal{F}(t, u, y)| &\leq \vartheta(t) \odot (\|u\|_{\mathcal{B}} + \|y\|), \\ &\quad \text{for every } (t, u, y) \in \mathcal{J} \times \mathcal{B} \times \mathbb{E}. \end{aligned} \quad (17)$$

- (ii) For all $\mathcal{R} > 0$, we can find $\wp_{\mathcal{R}} \in L^1_{\text{loc}}(\mathcal{J}, \mathbb{R}^+)$ to ensure that

$$H_d(\mathcal{F}(t, u, y), \mathcal{F}(t, \bar{u}, \bar{y})) \leq \wp_{\mathcal{R}}(t) (\|u - \bar{u}\|_{\mathcal{B}} + \|y - \bar{y}\|), \quad (18)$$

in which $t \in \mathcal{J}$, in addition to, for all $u, \bar{u} \in \mathcal{B}$ in conjunction with $\{\|u\|_{\mathcal{B}}, \|\bar{u}\|_{\mathcal{B}}\} \leq \mathcal{R}$, $y, \bar{y} \in \mathbb{E}$ joined with

$$d(0, \mathcal{F}(t, 0, 0)) \leq \wp_{\mathcal{R}}(t) \quad \text{a.e. } t \in \mathcal{J}. \quad (19)$$

(H3)

- (i) There is a function $m \in L^1_{\text{loc}}(\mathcal{J}, \mathbb{R}^+)$ and a continuous nondecreasing function $\Omega : \mathbb{R}^+ \rightarrow (0, \infty)$ to ensure that

$$|e(t, s, u)| \leq m(s) \Omega(\|u\|_{\mathcal{B}}) \quad \forall (t, s, u) \in \mathcal{J} \times \mathcal{J} \times \mathcal{B}. \quad (20)$$

- (ii) There is a constant $C_1 > 0$ in a way that

$$\left| \int_0^t [e(t, s, u) - e(t, s, \bar{u})] ds \right| \leq C_1 \|u - \bar{u}\|_{\mathcal{B}}, \quad (21)$$

for $(t, s) \in \mathcal{J}$, $(u, \bar{u}) \in \mathcal{B}$.

(H4)

- (i) Function $\mathcal{G}(t, \cdot)$ is continuous on $\mathcal{J}$, and there are certainly positive constants c_1, c_2 in a way that

$$|\mathcal{G}(t, u)| \leq c_1 \|u\|_{\mathcal{B}} + c_2, \quad \text{for every } (t, u) \in \mathcal{J} \times \mathcal{B}. \quad (22)$$

- (ii) For every $\mathcal{R} > 0$, there is a function $\tilde{\wp}_{\mathcal{R}}(t) \in L^1_{\text{loc}}(\mathcal{J}, \mathbb{R}^+)$ in a way that

$$|\mathcal{G}(t, u) - \mathcal{G}(t, \bar{u})| \leq \tilde{\wp}_{\mathcal{R}}(t) \|u - \bar{u}\|_{\mathcal{B}}, \quad (23)$$

$t \in \mathcal{J}$, $u, \bar{u} \in \mathcal{B}$ with $\{\|u\|_{\mathcal{B}}, \|\bar{u}\|_{\mathcal{B}}\} \leq \mathcal{R}$.

For each $n \in \mathbb{N}$, we delineate, in $\mathcal{V}_{+\infty}$, the family of semi-norms by

$$\|x\|_n = \sup \left\{ e^{-\tau L_n^*(t)} |x(t)| : t \in [0, n] \right\}, \quad (24)$$

in which $L_n^*(t) = \int_0^t \wp_n^*(s) ds$, $\wp_n^*(t) = \max\{\tilde{\wp}_n(t) \mathcal{D}_1^*, \tilde{\wp}(t)\}$, $\tilde{\wp}(t) = \mathcal{M} \wp_n(t) (1 + C_1) \mathcal{D}_1^*$, and $\wp_n^* = \sup\{\wp_n^*(t) : t \in [0, n]\}$ and accept that $(\wp_n^* + 1/\tau) < 1$ and $\wp_n, \tilde{\wp}_n$ are a function from (H2)(ii) and (H4)(ii) appropriately.

Theorem 8. *Expect that (H1)–(H4) and (H_c) hold, and believe that $\mu = 1 - c_1 \mathcal{D}_1^* > 0$ and*

$$\int_C^{+\infty} \frac{ds}{\wp(s) + \Omega(s)} > \int_0^n v(s) ds \quad \text{for } n \in \mathbb{N}, \quad (25)$$

in which $C = c_n + (\mathcal{D}_1^*/\mu)[\mathcal{M}|\mathcal{G}(0, \varsigma(0))| + c_1 c_n + c_2]$. At that point, model (1) has a mild solution on $(-\infty, +\infty)$.

Proof. We will transmute the structure (1) into a fixed point problem. Recognize the multivalued operator $\Upsilon : \mathcal{V}_{+\infty} \rightarrow \mathcal{P}(\mathcal{V}_{+\infty})$ specified by $\Upsilon(h) = \{h \in \mathcal{V}_{+\infty}\}$ with

$$h(t) = \begin{cases} \varsigma(t), & t \leq 0; \\ \mathcal{S}(t) [\varsigma(0) - \mathcal{G}(0, \varsigma(0))] + \mathcal{G}(t, x_{\varrho(t, x_t)}) + \int_0^t \mathcal{S}(t-s) v(s) ds, & t \in \mathcal{J}, \end{cases} \quad (26)$$

where $v \in S_{\mathcal{F}, x_{\varrho(s, x_s)}}$. For $\varsigma \in \mathcal{B}$, we express function $y(\cdot) : (-\infty, +\infty) \rightarrow \mathbb{E}$ by

$$y(t) = \begin{cases} \varsigma(t), & t \leq 0; \\ \mathcal{S}(t) \varsigma(0), & t \in \mathcal{J}, \end{cases} \quad (27)$$

and then $y_0 = \varsigma$. For every function $z \in \mathcal{V}_{+\infty}$ with $z_0 = 0$, we designate by $\tilde{z}$ the function clear by

$$\tilde{z}(t) = \begin{cases} 0, & t \leq 0; \\ z(t), & t \in \mathcal{J}. \end{cases} \quad (28)$$

If $x(\cdot)$ fulfills (12), we are able to decompose it as $x(t) = z(t) + y(t)$, $t \in \mathcal{J}$, which suggests that $x_t = z_t + y_t$, for each $t \in \mathcal{J}$, and also the function $z(\cdot)$ fulfills

$$z(t) = \mathcal{G}(t, z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)}) - \mathcal{S}(t) \mathcal{G}(0, \varsigma(0)) + \int_0^t \mathcal{S}(t-s) v(s) ds, \quad t \in \mathcal{J}, \quad (29)$$

where $v(s) \in \mathcal{S}_{\mathcal{F}, z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)}}$.

Let $\mathcal{V}_{+\infty}^0 = \{z \in \mathcal{V}_{+\infty} : z(0) = 0 \in \mathcal{B}\}$. For any $z \in \mathcal{V}_{+\infty}^0$, we sustain

$$\begin{aligned} \|z\|_{+\infty} &= \sup \{|z(s)| : 0 \leq s < +\infty\} + \|z_0\|_{\mathcal{B}} \\ &= \sup \{|z(s)| : 0 \leq s < +\infty\}. \end{aligned} \quad (30)$$

Along these lines, $\mathcal{V}_{+\infty}^0$ is a Banach space with the norm $\|\cdot\|_{+\infty}$. We delimit the operator $\bar{Y} : \mathcal{V}_{+\infty}^0 \rightarrow \mathcal{P}(B_{+\infty}^0)$ by $\bar{Y}(z) = \{h \in \mathcal{V}_{+\infty}^0\}$ with

$$h(t) = \mathcal{G}\left(t, z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)}\right) - \mathcal{S}(t) \mathcal{G}(0, \varsigma(0)) + \int_0^t \mathcal{S}(t-s) v(s) ds, \quad t \in \mathcal{J}, \quad (31)$$

where $v(s) \in S_{\mathcal{F}, \mathcal{Z}_{\varrho(s, z_s + y_s)} + \mathcal{Y}_{\varrho(s, z_s + y_s)}}$.

It is vindicated that the operator $\bar{Y}$ has a fixed point if and only if $\bar{Y}$ has a fixed point. As a result, let us demonstrate that $\bar{Y}$ has a fixed point $z \in \mathcal{V}_{+\infty}^0$.

Remark 9. (i) By condition (P_1) and Lemma 7 in the above discussion, we have the subsequent estimates:

$$\begin{aligned} & \left\| z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)} \right\|_{\mathcal{B}} \\ & \leq \left\| z_{\varrho(s, z_s + y_s)} \right\|_{\mathcal{B}} + \left\| y_{\varrho(s, z_s + y_s)} \right\|_{\mathcal{B}} \\ & \leq \mathcal{D}_1^* |z(s)| + (\mathcal{D}_2^* + L^{\varsigma}) \|z_0\|_{\mathcal{B}} + \mathcal{D}_1^* |y(s)| \\ & \quad + (\mathcal{D}_2^* + L^{\varsigma}) \|\varsigma\|_{\mathcal{B}} \\ & \leq \mathcal{D}_1^* |z(s)| + \mathcal{D}_1^* \mathcal{M}H \|\varsigma\|_{\mathcal{B}} + (\mathcal{D}_2^* + L^{\varsigma}) \|\varsigma\|_{\mathcal{B}} \\ & \leq \mathcal{D}_1^* |z(s)| + (\mathcal{D}_2^* + L^{\varsigma} + \mathcal{D}_1^* \mathcal{M}H) \|\varsigma\|_{\mathcal{B}} \\ & \leq \mathcal{D}_1^* |z(s)| + c_n, \end{aligned} \quad (32)$$

where $c_n = (\mathcal{D}_2^* + L^{\varsigma} + \mathcal{D}_1^* \mathcal{M}H) \|\varsigma\|_{\mathcal{B}}$.
(ii)

$$\begin{aligned} |v(t) - \bar{v}(t)| & \leq \wp_n(t) \left[\left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right. \\ & \quad \left. + C_1 \left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right] \leq \wp_n(t) \\ & \quad \cdot [\mathcal{D}_1^* |z(t) - \bar{z}(t)| + C_1 \mathcal{D}_1^* |z(t) - \bar{z}(t)|] \leq \wp_n(t) \\ & \quad \cdot (1 + C_1) \mathcal{D}_1^* |z(t) - \bar{z}(t)|; \end{aligned} \quad (33)$$

(iii)

$$\begin{aligned} |h(t) - \bar{h}(t)| & \leq \left| \mathcal{G}\left(t, z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)}\right) \right. \\ & \quad \left. - \mathcal{G}\left(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + y_{\varrho(t, \bar{z}_t + y_t)}\right) \right| \\ & \quad + \int_0^t \|\mathcal{S}(t-s)\|_{B(\mathbb{E})} |v(s) - \bar{v}(s)| ds \leq \tilde{\wp}_n(t) \\ & \quad \cdot \mathcal{D}_1^* |z(t) - \bar{z}(t)| \\ & \quad + \mathcal{M} \int_0^t \wp_n(s) (1 + C_1) \mathcal{D}_1^* |z(s) - \bar{z}(s)| ds \\ & \leq \tilde{\wp}_n(t) \mathcal{D}_1^* |z(t) - \bar{z}(t)| \\ & \quad + \int_0^t \bar{\wp}_n(s) |z(s) - \bar{z}(s)| ds \leq \left[\tilde{\wp}_n(t) \mathcal{D}_1^* e^{\tau L_n^*(t)} \right] \\ & \quad \cdot \left[e^{-\tau L_n^*(t)} |z(t) - \bar{z}(t)| \right] \end{aligned}$$

$$\begin{aligned} & + \int_0^t \left[\bar{\wp}_n(s) e^{\tau L_n^*(s)} \right] \left[e^{-\tau L_n^*(s)} |z(s) - \bar{z}(s)| \right] ds \\ & \leq \wp_n^*(t) e^{\tau L_n^*(t)} \|z - \bar{z}\|_n \\ & + \int_0^t \left[\wp_n^*(s) e^{\tau L_n^*(s)} \right] \|z - \bar{z}\|_n ds \leq \left(\wp_n^* + \frac{1}{\tau} \right) \\ & \cdot e^{\tau L_n^*(t)} \|z - \bar{z}\|_n. \end{aligned} \quad (34)$$

Presenting $n \in \mathbb{N}$, z is ought to be a solution of the inclusion $z \in \lambda \bar{Y}(z)$ for many $\lambda \in (0, 1)$ and there may be $v \in S_{\mathcal{F}, \mathcal{Z}_{\varrho(s, z_s + y_s)} + \mathcal{Y}_{\varrho(s, z_s + y_s)}}$ in a way that, for any $t \in \mathcal{J}_n$, we maintain

$$\begin{aligned} |z(t)| & \leq \|\mathcal{S}(t)\|_{B(\mathbb{E})} |\mathcal{G}(0, \varsigma(0))| + \left| \mathcal{G}\left(t, z_{\varrho(t, z_t + y_t)} \right. \right. \\ & \quad \left. \left. + y_{\varrho(t, z_t + y_t)}\right) \right| + \int_0^t \|\mathcal{S}(t-s)\|_{B(\mathbb{E})} \left| \mathcal{F}\left(s, z_{\varrho(s, z_s + y_s)} \right. \right. \\ & \quad \left. \left. + y_{\varrho(s, z_s + y_s)}\right) \right| ds \\ & \leq \mathcal{M} |\mathcal{G}(0, \varsigma(0))| + c_1 \left\| z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)} \right\|_{\mathcal{B}} \\ & \quad + c_2 + \mathcal{M} \int_0^t \vartheta(s) \odot \left(\left\| z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)} \right\|_{\mathcal{B}} \right. \\ & \quad \left. + \int_0^s m(\tau) \Omega \left(\left\| z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)} \right\|_{\mathcal{B}} \right) d\tau \right) ds. \end{aligned} \quad (35)$$

From Remark 9(i), we have

$$\begin{aligned} |z(t)| & \leq \mathcal{M} |\mathcal{G}(0, \varsigma(0))| + c_1 \mathcal{D}_1^* |z(t)| + c_1 c_n + c_2 \\ & \quad + \mathcal{M} \int_0^t \vartheta(s) \odot \left(\mathcal{D}_1^* |z(s)| + c_n \right. \\ & \quad \left. + \int_0^s m(\tau) \Omega \left(\mathcal{D}_1^* |z(s)| + c_n \right) d\tau \right) ds \\ & \leq \frac{1}{\mu} [\mathcal{M} |\mathcal{G}(0, \varsigma(0))| + c_1 c_n + c_2] + \frac{\mathcal{M}}{\mu} \int_0^t \vartheta(s) \\ & \quad \cdot \odot \left(\mathcal{D}_1^* |z(s)| + c_n \right. \\ & \quad \left. + \int_0^s m(\tau) \Omega \left(\mathcal{D}_1^* |z(s)| + c_n \right) d\tau \right) ds. \end{aligned} \quad (36)$$

Thus,

$$\begin{aligned} \mathcal{D}_1^* |z(t)| + c_n & \leq c_n + \frac{\mathcal{D}_1^*}{\mu} [\mathcal{M} |\mathcal{G}(0, \varsigma(0))| + c_1 c_n \\ & \quad + c_2] + \frac{\mathcal{M} \mathcal{D}_1^*}{\mu} \int_0^t \vartheta(s) \odot \left(\mathcal{D}_1^* |z(s)| + c_n \right. \\ & \quad \left. + \int_0^s m(\tau) \Omega \left(\mathcal{D}_1^* |z(s)| + c_n \right) d\tau \right) ds. \end{aligned} \quad (37)$$

We conceive function β characterized by

$$\beta(t) = \sup \{ \mathcal{D}_1^* |z(s)| + c_n : 0 \leq s \leq b \}, \quad (38)$$

$$0 \leq t < +\infty.$$

Permit $t^* \in [0, t]$ in a way that $\beta(t) = \mathcal{D}_1^* |z(t^*)| + c_n \|\zeta\|_{\mathcal{B}}$. Because of the aforementioned inequality, we maintain, for $t \in \mathcal{J}_n$,

$$\begin{aligned} \beta(t) &\leq c_n + \frac{\mathcal{D}_1^*}{\mu} [\mathcal{M} |\mathcal{G}(0, \zeta(0))| + c_1 c_n + c_2] \\ &\quad + \frac{\mathcal{M} \mathcal{D}_1^*}{\mu} \\ &\quad \cdot \int_0^t \vartheta(s) \odot \left(\beta(s) + \int_0^s m(\tau) \Omega(\beta(\tau)) d\tau \right) ds. \end{aligned} \quad (39)$$

Allow us to occupy the right-hand part of the overhead inequality as $w(t)$. Then, we sustain $\beta(t) \leq w(t)$ for all $t \in [0, n]$. Through the significance of ν , we get

$$w(0) = c_n + \frac{\mathcal{D}_1^*}{\mu} [\mathcal{M} |\mathcal{G}(0, \zeta(0))| + c_1 c_n + c_2] = C. \quad (40)$$

This leads us to the accompanying inequality for $t \in \mathcal{J}_n$,

$$\begin{aligned} w(t) &\leq c_n + \frac{\mathcal{D}_1^*}{\mu} [\mathcal{M} |\mathcal{G}(0, \zeta(0))| + c_1 c_n + c_2] \\ &\quad + \frac{\mathcal{M} \mathcal{D}_1^*}{\mu} \\ &\quad \cdot \int_0^t \vartheta(s) \odot \left(w(s) + \int_0^s m(\tau) \Omega(w(\tau)) d\tau \right) ds, \end{aligned} \quad (41)$$

where

$$\begin{aligned} w'(t) &\leq \frac{\mathcal{M} \mathcal{D}_1^*}{\mu} \vartheta(t) \odot \left(w(t) + \int_0^t m(s) \Omega(w(s)) ds \right). \end{aligned} \quad (42)$$

Next, we weigh the function

$$\omega(t) = w(t) + \int_0^t m(s) \Omega(w(s)) ds. \quad (43)$$

Then we bring forth $\omega(0) = w(0) = C$ and $w(t) \leq \omega(t)$ for all $t \in \mathcal{J}_n$. Applying the nondecreasing character of $\odot$, we receive

$$\begin{aligned} \omega'(t) &= w'(t) + m(t) \Omega(w(t)) \\ &\leq \frac{\mathcal{M} \mathcal{D}_1^*}{\mu} \vartheta(t) \odot (\omega(t)) + m(t) \Omega(\omega(t)), \end{aligned} \quad (44)$$

$$\text{a.e. } t \in \mathcal{J}_n.$$

We characterize the function $\nu(t) = \max\{(\mathcal{M} \mathcal{D}_1^* / \mu) \vartheta(t), m(t)\}$, $t \in \mathcal{J}_n$, which suggests that

$$\frac{\omega'(t)}{\odot(\omega(t)) + \Omega(\omega(t))} \leq \nu(t). \quad (45)$$

From condition (25), we acquire

$$\begin{aligned} \int_{\omega(0)=C}^{\omega(t)} \frac{ds}{\odot(s) + \Omega(s)} &\leq \int_0^t \nu(s) ds \leq \int_0^n \nu(s) ds \\ &< \int_C^{+\infty} \frac{ds}{\odot(s) + \Omega(s)}. \end{aligned} \quad (46)$$

Subsequently, for every $t \in \mathcal{J}_n$, we have a constant Λ_{n_*} in a way that $\omega(t) \leq \Lambda_{n_*}$ and, consequently, $\beta(t) \leq \Lambda_{n_*}$. Due to the fact that $\|z\|_n \leq \beta(t)$, we certainly have $\|z\|_n \leq \Lambda_{n_*}$. Fix

$$\mathcal{U} = \left\{ z \in \mathcal{V}_{+\infty}^0 : \sup_{0 \leq t \leq n} |z(t)| \leq \Lambda_{n_*} + 1, \forall n \in \mathbb{N} \right\}. \quad (47)$$

Evidently, $\mathcal{U}$ is a closed subset of $\mathcal{V}_{+\infty}^0$. We should demonstrate that $\bar{\gamma} : \mathcal{U} \rightarrow \mathcal{P}(\mathcal{V}_{+\infty}^0)$ is a contraction and an admissible operator. Initially, we evaluate that $\bar{\gamma}$ is a contraction. In fact, consider $z, \bar{z} \in \mathcal{V}_{+\infty}^0$ and $h \in \bar{\gamma}(z)$. Then, there may be $\nu(t) \in \mathcal{F}(t, z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)}, \int_0^t e(t, s, z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)}) ds)$ such that

$$\begin{aligned} h(t) &= \mathcal{G}(t, z_{\varrho(t, z_t + y_t)} + y_{\varrho(t, z_t + y_t)}) - \mathcal{S}(t) \mathcal{G}(0, \zeta(0)) \\ &\quad + \int_0^t \mathcal{S}(t-s) \nu(s) ds, \quad \text{for every } t \in \mathcal{J}_n. \end{aligned} \quad (48)$$

From the hypotheses (H2)(ii) and (H3)(ii), we sustain

$$\begin{aligned} H_d \left(\mathcal{F} \left(t, z_{\varrho(t, z_t + y_t)} \right. \right. \\ \left. \left. + y_{\varrho(t, z_t + y_t)}, \int_0^t e \left(t, s, z_{\varrho(s, z_s + y_s)} + y_{\varrho(s, z_s + y_s)} \right) ds \right), \right. \\ \left. \mathcal{F} \left(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right. \right. \\ \left. \left. + y_{\varrho(t, \bar{z}_t + y_t)}, \int_0^t e \left(t, s, \bar{z}_{\varrho(s, \bar{z}_s + y_s)} + y_{\varrho(s, \bar{z}_s + y_s)} \right) ds \right) \right) \\ \leq \wp_n(t) \left[\left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} + C_1 \left\| z_{\varrho(t, z_t + y_t)} \right. \right. \\ \left. \left. - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right]. \end{aligned} \quad (49)$$

As a result, there is $w \in \mathcal{F}(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + y_{\varrho(t, \bar{z}_t + y_t)}, \int_0^t e(t, s, \bar{z}_{\varrho(s, \bar{z}_s + y_s)} + y_{\varrho(s, \bar{z}_s + y_s)}) ds)$ so that

$$\begin{aligned} |\nu(t) - w| &\leq \wp_n(t) \left[\left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right. \\ &\quad \left. + C_1 \left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right]. \end{aligned} \quad (50)$$

Recognize $\mathcal{U}_* : [0, n] \rightarrow \mathcal{P}(\mathbb{E})$ specified by

$$\begin{aligned} \mathcal{U}_*(t) &= \{ w \in \mathbb{E} : |\nu(t) - w| \leq \wp_n(t) \\ &\quad \cdot \left[\left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right. \\ &\quad \left. + C_1 \left\| z_{\varrho(t, z_t + y_t)} - \bar{z}_{\varrho(t, \bar{z}_t + y_t)} \right\|_{\mathcal{B}} \right] \}. \end{aligned} \quad (51)$$

Considering the fact that the multivalued operator $V_*(t) = \mathcal{U}_*(t) \cap \mathcal{F}(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + \gamma_{\varrho(t, \bar{z}_t + y_t)}, \int_0^t e(t, s, \bar{z}_{\varrho(s, \bar{z}_s + y_s)} + \gamma_{\varrho(s, \bar{z}_s + y_s)}) ds)$ is measurable (see Proposition 3), there is function $\bar{v}(t)$, which is a measurable choice for V_* . So, $\bar{v}(t) \in \mathcal{F}(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + \gamma_{\varrho(t, \bar{z}_t + y_t)}, \int_0^t e(t, s, \bar{z}_{\varrho(s, \bar{z}_s + y_s)} + \gamma_{\varrho(s, \bar{z}_s + y_s)}) ds)$, and, from Remark 9(ii), we specify

$$|\nu(t) - \bar{v}(t)| \leq \wp_n(t) (1 + C_1) \mathcal{D}_1^* |z(t) - \bar{z}(t)|. \quad (52)$$

For every $t \in [0, n]$, give us a chance to characterize

$$\begin{aligned} \bar{h}(t) &= \mathcal{G}(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + \gamma_{\varrho(t, \bar{z}_t + y_t)}) - \mathcal{S}(t) \mathcal{G}(0, \varsigma(0)) \\ &+ \int_0^t \mathcal{S}(t-s) \bar{v}(s) ds. \end{aligned} \quad (53)$$

Again, from Remark 9(iii), we now have

$$\begin{aligned} |h(t) - \bar{h}(t)| &\leq \left| \mathcal{G}(t, z_{\varrho(t, z_t + y_t)} + \gamma_{\varrho(t, z_t + y_t)}) \right. \\ &\quad \left. - \mathcal{G}(t, \bar{z}_{\varrho(t, \bar{z}_t + y_t)} + \gamma_{\varrho(t, \bar{z}_t + y_t)}) \right| \\ &+ \int_0^t \|\mathcal{S}(t-s)\|_{B(\mathbb{E})} |\nu(s) - \bar{v}(s)| ds \leq \left(\wp_n^* \right. \\ &\quad \left. + \frac{1}{\tau} \right) e^{\tau L_n^*(t)} \|z - \bar{z}\|_n. \end{aligned} \quad (54)$$

As a result

$$\|h - \bar{h}\|_n \leq \left(\wp_n^* + \frac{1}{\tau} \right) \|z - \bar{z}\|_n. \quad (55)$$

Being practically equivalent to the connection gotten by exchanging the parts of z and $\bar{z}$, it takes after that

$$H_d(\bar{Y}(z), \bar{Y}(\bar{z})) \leq \left(\wp_n^* + \frac{1}{\tau} \right) \|z - \bar{z}\|_n, \quad (56)$$

demonstrating that $\bar{Y}$ is a contraction for all $n \in \mathbb{N}$ and, from the second aspect of [30, Theorem 3.4], we realize that $\bar{Y}$ is likewise admissible contraction operator. With the decision of $\mathcal{U}$, there is no $z \in \partial \mathcal{U}$ in a way that $z = \lambda \bar{Y}(z)$ for many $\lambda \in (0, 1)$. From the nonlinear alternative fixed point theorem thanks to Frigon [1, Corollary 3.5], we realize that the operator $\bar{Y}$ has a fixed point z^* . This intimates that $x^*(t) = z^*(t) + y(t)$, $t \in (-\infty, +\infty)$, is a fixed point of the operator Y , which is a mild solution of the structure (1). $\square$

4. Illustrative Example

To exemplify our theoretical results, we treat the FNIDI with SDD of the structure

$$\begin{aligned} &\frac{\partial}{\partial t} [u(t, \xi) - g(t, u(t - \sigma(u(t, 0)), \xi))] \\ &\in \int_t^0 \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} \left(\frac{\partial^2}{\partial \xi^2} - r \right) [u(s, \xi) \end{aligned}$$

$$\begin{aligned} &- g(s, u(s - \sigma(u(s, 0)), \xi))] ds + \left[f_1 \left(t, \right. \right. \\ &\quad \left. \left. u(t - \sigma(u(t, 0)), \xi) \right), \right. \\ &\quad \left. \int_0^t \eta(t, s, u(s - \sigma(u(s, 0)), \xi)) ds \right), f_2 \left(t, \right. \\ &\quad \left. u(t - \sigma(u(t, 0)), \xi) \right), \\ &\quad \left. \int_0^t \eta(t, s, u(s - \sigma(u(s, 0)), \xi)) ds \right) \Big], \\ &\quad t \in [0, \infty), \quad \xi \in [0, \pi], \\ &u(t, 0) = u(t, \pi) = 0, \quad t \in [0, \infty), \\ &u(\theta, \xi) = u_0(\theta, \xi), \quad \theta \in (-\infty, 0], \quad \xi \in [0, \pi], \end{aligned} \quad (57)$$

where $1 < \alpha < 2$, $(u_0, \sigma) \in C(\mathbb{R}[0, \infty))$, $L_\xi = (\partial^2 / \partial \xi^2 - r)$, $r > 0$ stands for the operator with respect to the special variable ξ , $f_1, f_2 : \mathcal{F} \times \mathcal{B} \times \mathbb{E} \rightarrow \mathbb{R}$ are measurable in t and continuous in x , $g : \mathcal{F} \times \mathcal{B} \rightarrow \mathbb{R}$, and $\eta : \mathcal{F} \times \mathcal{F} \times \mathcal{B} \rightarrow \mathbb{R}$ are appropriate functions. We expect that, for each $t \geq 0$, $f_1(t, \cdot, \cdot)$ is lower semicontinuous (i.e., the set $\{x \in \mathcal{B}, y \in \mathbb{E} : f_1(t, x, y) > \nu\}$ is open for all $\nu \in \mathbb{R}$) and accept that, for each $t \geq 0$, $f_2(t, \cdot, \cdot)$ is upper semicontinuous (i.e., the set $\{x \in \mathcal{B}, y \in \mathbb{E} : f_2(t, x, y) < \nu\}$ is open for each $\nu \in \mathbb{R}$).

Recognize $\mathbb{E} = L^2([0, \pi], \mathbb{R})$ and the operator $\mathcal{A} : L_\xi : D(\mathcal{A}) \subset \mathbb{E} \rightarrow \mathbb{E}$ with domain

$$D(\mathcal{A}) = \{u \in \mathbb{E} : u'' \in \mathbb{E}, u(0) = u(\pi) = 0\}. \quad (58)$$

Clearly, $\mathcal{A}$ is densely defined in $\mathbb{E}$ and is sectorial. Hence, $\mathcal{A}$ is a generator of a solution operator on $\mathbb{E}$. For the phase space, we pick $\mathcal{B} = C_\gamma = \{\varsigma \in C((-\infty, 0] : \mathbb{X}) : \lim_{\theta \rightarrow -\infty} e^{\gamma\theta} \varsigma(\theta) \text{ exists in } \mathbb{X}\}$ invested with the norm

$$|\varsigma| = \sup_{-\infty < \theta \leq 0} e^{\gamma\theta} |\varsigma(\theta)|. \quad (59)$$

Here, we note the phase space C_γ satisfying conditions (P_1) , (P_2) , and (P_3) . Set

$$\begin{aligned} x(t)(\xi) &= u(t, \xi), \quad t \geq 0, \quad \xi \in [0, \pi], \\ \varsigma(0)(\xi) &= u_0(\theta, \xi), \quad t \geq 0, \quad \theta \leq 0, \\ \mathcal{G}(t, \varsigma)(\xi) &= g(t, \varsigma(0, \xi)), \quad t \geq 0, \quad \xi \in [0, \pi], \\ \mathcal{F}(t, \varsigma, x)(\xi) &= \left[f_1 \left(t, \varsigma(0, \xi), \int_0^t \eta(t, s, \varsigma(0, \xi)) ds \right), \right. \\ &\quad \left. f_2 \left(t, \varsigma(0, \xi), \int_0^t \eta(t, s, \varsigma(0, \xi)) ds \right) \right], \\ &\quad t \geq 0, \quad \xi \in [0, \pi], \end{aligned} \quad (60)$$

$$e(t, s, \varsigma)(\xi) = \eta(t, s, \varsigma(0, \xi)),$$

$$\varrho(t, \varsigma) = t - \sigma(\varsigma(0, 0)).$$

The multivalued map $\mathcal{F}$ is u.s.c. with compact convex values. Thus, (H1) and (H2) are fulfilled.

Presently, the existence of mild solutions can be reasoned from an immediate utilization of Theorem 8. In the perspective of phase space C_γ with the above examination, we have the accompanying results.

Corollary 10. *Let $\varsigma \in \mathcal{B} = C_\gamma$ be continuous and bounded. Then, there is certainly at least one mild solution of the model (57) on $(-\infty, +\infty)$.*

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

Acknowledgment

The fourth author would like to dedicate this paper, with love and respect, to his doctoral supervisor Professor A. Anguraj, P.S.G. College of Arts & Science, Coimbatore 641014, India, on the occasion of his 54th birthday.

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