Research Article
About Some Families of Nonexpansive Mappings with respect to Renorming
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We characterize the family of nonexpansive mappings which are invariant under renormings and we also compare the families of nonexpansive mappings under two equivalent norms.

1. Introduction

A Banach space $(X, \| \cdot \|)$ satisfies the fixed point property (FPP) if every nonexpansive mapping $T : C \to C$ has a fixed point, where $C$ is a closed convex bounded subset of $X$. For a long time, it was an open problem if the fixed point property could be equivalent to the reflexivity. It was until 2008, when Lin [1] proved that there exists a nonreflexive Banach space with the FPP. Actually, Lin used a renorming $\| \cdot \|_L$ of the space $\ell_1$ such that $(\ell_1, \| \cdot \|_L)$ has the FPP. One year later, Domínguez-Benavides proved that every reflexive Banach space can be renormed to have the FPP [2]. After these two articles, the Fixed Point Property and Renorming Theory were clearly connected. However, not all nonreflexive Banach spaces can be renormed to have the FPP as it was proved in [3]; in this work it is proved that $\ell_1$, and $\ell_1(\Gamma)$ where $\Gamma$ is an uncountable set cannot be renormed to have the FPP.

Recently, many works have appeared to be looking for new examples of nonreflexive Banach spaces enjoying the FPP or trying to find some structure on families of equivalent norms with the FPP. In the first sense the works should be mentioned [4–7]. In the second way the works are remarkable [8, 9]. After Lin’s result, the question remains open: does reflexivity implies FPP? In this setting the relevant paper is [10]. The FPP under a renorming also has been studied for other kinds of mappings; for example, see [11, 12].

From the papers cited in the previous paragraph the FPP is not an isomorphic property. Moreover, the family of nonexpansive mappings could be changed after a renorming. For this reason, the aim of this paper is to say something about the following question.

What happened with the family of nonexpansive mappings with another equivalent norm?

In order to do that, we make the following assumptions.

Let $(X, \| \cdot \|)$ be a normed space and $C$ a nonempty subset of $X$; then for each $\| \cdot \|_L$-Lipschitz function $T : C \to C$ we denote by $K(T, \| \cdot \|)$ its Lipschitz constant with respect to $\| \cdot \|$ and by $\mathcal{N}(X)$ the collection of equivalent norms on $X$. For each $\| \cdot \|_0$ norm on $X$ we define

$$NE(C, \| \cdot \|_0) = \{ S : C \to C \mid K(S, \| \cdot \|_0) \leq 1 \}. \quad (1)$$

2. The Family of Nonexpansive Mappings over Every Renorming

In this section we will study some families of nonexpansive mappings over every renorming and we will characterize them. The first approximation is to characterize the set $\delta(C) = \bigcap\{ \mathcal{N}(X) \mid NE(C, \| \cdot \|) \}$, when $C$ is a convex, closed, and bounded set in $X$. It is worthwhile to mention that we prove that at least there are many elements in $NE(C, \| \cdot \|)$ as elements in $NE([0, 1], | \cdot |)$. Moreover, we show that their structure is similar.
For each \( x \in C \) we call \( f_x : C \to C \) the constant function \( x \) and we denote by \( I : C \to C \) the identity map. We define

\[
\mathcal{S}(C) = \text{conv}\left(\{f_x | x \in C\} \cup \{I\}\right).
\]  

**Remark 1.** It is clear that, for each norm \( \| \cdot \| \) on \( X, T \in NE(C, \| \cdot \|) \) for all \( T \in \mathcal{S}(C) \). It is easy to prove that each element \( T \in \mathcal{S}(C) \) is of the form \( T = y + \alpha I \), for some \( y \in X \) and \( 0 \leq \alpha \leq 1 \).

In the rest of this paper we will denote by \( \Re \) the scalar field \( \mathbb{R} \) or \( C \), associated with the normed space. In order to characterize the set \( \mathcal{S}(C) \) we will give the following theorem.

**Theorem 2.** Let \( C \) be a nonempty subset of a normed space \( X \) and \( T : C \to C \), then the next statements are equivalent.

(1) For each norm \( \| \cdot \| \) on \( X \) one has that \( T \in NE(C, \| \cdot \|) \).

(2) For each \( \| \cdot \| \in \mathfrak{R}(X) \) one has that \( T \in NE(C, \| \cdot \|) \).

(3) \( \| \cdot \| \in \mathfrak{R}(X) \) exists such that \( T \in NE(C, \| \cdot \|) \) and for each \( x, y \in C \), \( T - Ty \in \text{span}\{x - y\} \) holds.

(4) For each \( x, y \in C \) \( \alpha \in F \) exists with \( |\alpha| \leq 1 \) such that \( \alpha(x - y) = Tx - Ty \).

**Proof.** It is straightforward that (1) implies (2).

We are going to prove that (2) implies (3); in order to do this we proceed by contraposition. We may suppose that \( \| \cdot \| \in \mathfrak{R}(X) \) exist such that \( T \in NE(C, \| \cdot \|) \) and \( x, y \in C \) such that \( Tx - Ty \notin \text{span}\{x - y\} \).

Since \( Tx - Ty \notin \text{span}\{x - y\} \) then \( Y = \text{span}\{x - y, Tx - Ty\} \) has dimension 2 and then a projection \( P \) from \( X \) to \( Y \) exists that is \( \| \cdot \|_0 \)-bounded. Since \( Y \) is finite and dimensional and the set \{\( x - y, Tx - Ty\)\} is linear and independent, we can construct a norm \( \| \cdot \|_1 \) in \( Y \) such that \( \|x - y\|_1 \leq \|Tx - Ty\|_1 \); note that \( \|Tx - Ty\|_1 = \|x - y\|_1 \) could be as large as we desire. We consider the function \( \| \cdot \|_2 \) defined in \( X \) by \( \|x\|_2 = \|Px\|_1 + \|\|I - P\|\|x\|_0 \); it is easy to check that \( \| \cdot \|_2 \) is a norm on \( X \). Now we will prove that \( \| \cdot \|_2 \) is equivalent to \( \| \cdot \|_0 \). Since \( \| \cdot \|_0 \) and \( \| \cdot \|_2 \) are equivalent in \( Y \) then \( 0 < l \leq u \) the optimal constants exist such that

\[
l \|a\|_0 \leq \|a\|_2 \leq u \|a\|_0 \quad \text{for each } a \in Y.
\]

Since \( P \| \cdot \|_0 \)-bounded, we have for each \( z \in X \)

\[
\|z\|_2 = \|Pz\|_1 + \|\|I - P\|\|z\|_0 \leq u \|Pz\|_0 + \|\|I - P\|\|z\|_0 \leq (u \|P\| + \|\|I - P\|\|) \|z\|_0.
\]

On the other hand we have

\[
\|z\|_2 = \|Pz\|_1 + \|\|I - P\|\|z\|_0 \geq l \|Pz\|_0 + \|\|I - P\|\|z\|_0.
\]

There are two possibilities, \( l \geq 1 \) or \( l < 1 \). If \( l \geq 1 \) then

\[
\|z\|_2 \geq \|Pz\|_0 + \|\|I - P\|\|z\|_0 \geq l \|z\|_0.
\]

If \( l < 1 \) then

\[
\|z\|_2 \geq l \|Pz\|_0 + l \|\|I - P\|\|z\|_0 = l \|Pz\|_0 + l \|\|I - P\|\|z\|_0 \geq l \|z\|_0;
\]

thus \( \| \cdot \|_2 \) is equivalent to \( \| \cdot \|_0 \).

Now we have

\[
\|x - y\|_2 = \|P(x - y)\|_1 + \|\|I - P\|\|x - y\|_0 = \|x - y\|_1 < \|Tx - Ty\|_1
\]

\[
= \|P(Tx - Ty)\|_1 + \|\|I - P\|\|(Tx - Ty)\|_0 = \|Tx - Ty\|_2;
\]

that is, \( T \notin NE(C, \| \cdot \|_2) \).

Now we prove that (3) implies (4). Let \( x, y \in C \); if \( Tx = Ty \) the proof is over because \( \alpha = 0 \) is the required constant; then without loss of generality we may assume that \( Tx \neq Ty \); hence \( x \neq y \) and since \( Tx - Ty \in \text{span}\{x - y\} \) then \( \alpha \in F \) exist such that \( \alpha(x - y) = Tx - Ty \); thus

\[
\|x - y\|_0 \geq \|Tx - Ty\|_0 = |\alpha| \|x - y\|_0.
\]

Therefore \( |\alpha| \leq 1 \).

Now we show that (4) implies (1). Let \( \| \cdot \| \) be a norm on \( X \) and \( x, y \in C \); then \( \alpha \in F \) exists with \( |\alpha| \leq 1 \) such that \( \alpha(x - y) = Tx - Ty \); therefore

\[
\|x - y\| \geq |\alpha| \|x - y\| = \|Tx - Ty\|.
\]

Thus \( T \in NE(C, \| \cdot \|) \).

**Remark 3.** Note that \( K(T, \| \cdot \|_2) \) could be arbitrary large, since in the proof of (2) implying (3) in the previous theorem we can take \( \|Tx - Ty\|_1 \rightarrow \|x - y\|_1 \) as large as we want.

**Lemma 4.** Let \( C \) be a nonempty subset of a normed space, \( T : C \to C \), and \( x, y, z \in C \) are distinct such that, for each \( \alpha \in F \), and \( z \neq ax + (1 - \alpha)y \), \( \alpha_{x,y}, \alpha_{x,z}, \alpha_{y,z} \in F \) exist with

\[
\alpha_{x,y}(x - y) = Tx - Ty,
\]

\[
\alpha_{x,z}(x - z) = Tx - Tz,
\]

\[
\alpha_{y,z}(y - z) = Ty - Tz;
\]

then \( \alpha_{x,y} = \alpha_{x,z} = \alpha_{y,z} \).

**Proof.** From (11) it follows that

\[
\alpha_{y,z}(y - z) = \alpha_{x,z}(x - z) - \alpha_{x,y}(x - y)
\]

Let \( \text{span}_R \{x - y, x - z\} = \{r_1(x - y) + r_2(x - z) | r_1, r_2 \in R\} \). Since the set \{\( x - y, x - z \)\} is linearly independent, then we can define the operator \( R : \text{span}\{x - y, x - z\} \to \text{span}_R \{x - y, x - z\} \) by \( R(\alpha(x - y) + \beta(x - z)) = \Re(\alpha)(x - y) + \Re(\beta)(x - z) \) for each \( \alpha, \beta \in F \). It is clear that \( R \) is a real linear projection,

\[
R(\alpha w) = \Re(\alpha) R(w),
\]

for each \( \alpha \in F, \ w \in \text{span}_R \{x - y, x - z\} \),
and \( y - z \in \text{span}_R \{x - y, x - z\} \). For this and (12) we have
\[
\text{Re}(\alpha_{x,y})(y - z) = \text{Re}(\alpha_{x,z}) R(y - z)
\]
\[
= R(\alpha_{x,z}(y - z))
\]
\[
= R(\alpha_{x,z}(x - z) - \alpha_{x,y}(x - y))
\]  
\[
= \text{Re}(\alpha_{x,z})(x - z)
\]
\[
- \text{Re}(\alpha_{x,y})(x - y).
\]  
We define the linear operator \( \phi : \text{span}_R \{x - y, x - z\} \to R^2 \) by \( \phi(x - y) = (1, 0) = e_1 \) and \( \phi(x - z) = (0, 1) = e_2 \); then
\[
\text{Re}(\alpha_{x,y}) e_1 = \phi(\text{Re}(\alpha_{x,y})(x - y)),
\]
\[
\text{Re}(\alpha_{x,z}) e_2 = \phi(\text{Re}(\alpha_{x,z})(x - z));
\]  
thus
\[
\text{Re}(\alpha_{x,z}) e_2 - \text{Re}(\alpha_{x,y}) e_1
\]
\[
= \phi(\text{Re}(\alpha_{x,z})(x - z) - \text{Re}(\alpha_{x,y})(x - y))
\]
\[
= \phi(\text{Re}(\alpha_{x,z})(y - z))
\]
\[
= \phi(\text{Re}(\alpha_{x,z})[(x - z) - (x - y)])
\]
\[
= \text{Re}(\alpha_{x,z})(e_2 - e_1).
\]  
We consider the triangles in \( \mathbb{R}^2 \):
\[
\triangle 0 e_1 e_2,
\]
\[
\triangle 0 \text{Re}(\alpha_{x,y}) e_1 \text{Re}(\alpha_{x,z}) e_2.
\]  
Since
\[
\text{Re}(\alpha_{x,y}) e_1 \in \text{span}_R \{e_1\},
\]
\[
\text{Re}(\alpha_{x,z}) e_2 \in \text{span}_R \{e_2\},
\]
\[
\text{Re}(\alpha_{x,z}) e_2 - \text{Re}(\alpha_{x,y}) e_1 \in \text{span} \{e_2 - e_1\},
\]
then the triangles are similar; thus
\[
\text{Re}(\alpha_{x,y}) = \text{Re}(\alpha_{x,z}) = \text{Re}(\alpha_{x,y}).
\]  
In a similar way we prove that \( \text{Im}(\alpha_{x,y}) = \text{Im}(\alpha_{x,z}) = \text{Im}(\alpha_{y,z}) \), by considering the operator \( R(\alpha(x - y) + \beta(x - z)) = \text{Im}(\alpha)(x - y) + \text{Im}(\beta)(x - z) \).

Then \( \alpha_{x,y} = \alpha_{x,z} = \alpha_{y,z} \).

\textbf{Theorem 5.} Under assumptions of Theorem 2 and if \( C \) has at most two elements or for each distinct \( x, y \in C \), \( z \in C \) exists such that, for each \( \alpha \in \mathbb{F}, z \neq ax + (1 - \alpha)y \), then the statement,
\[
(T) \quad T = y + \alpha l \text{ for some } \alpha \in \mathbb{F} \text{ with } |\alpha| \leq 1 \text{ and } y \in X,
\]
is equivalent to each statement in that theorem.

\textbf{Proof.} The statement (A) implies that (1) in Theorem 2 is obvious.

Now we show that (4) of Theorem 2 implies (A). If \( C = \{x\} \) then \( Tx = 0 + 1Ix; \) if \( C = \{x, y\} \) with \( x \neq y \) and \( \alpha \) is such that \( \alpha(x - y) = Tx - Ty \) then \( Tz = w + \alpha z \) with \( w = Ty - ay \) for each \( z \in C \). We suppose that for each distinct \( x, y \in C \) exists such that, for each \( \alpha \in \mathbb{F}, z \neq ax + (1 - \alpha)y \). For each \( x, y \in C \) let \( \alpha_{x,y} \in \mathbb{F} \) such that
\[
\alpha_{x,y}(x - y) = Tx - Ty.
\]  
It is clear that \( \alpha_{x,y} = \alpha_{y,x} \). Let \( x, y \in C \) with \( x \neq y \). It is enough to prove that, for each distinct \( z_1, z_2 \in C, \alpha_{z_1,z_2} = \alpha_{x,y} \). Let \( z_1, z_2 \in C \); we may suppose without loss of generality that the following cases are exhaustive.

(i) \( \alpha_1, \alpha_2 \in \mathbb{F} \) exist such that
\[
z_1 = \alpha_1 x + (1 - \alpha_1) y,
\]
\[
z_2 = \alpha_2 x + (1 - \alpha_2) y.
\]  
(ii) \( \alpha_1 \in \mathbb{F} \) exists such that
\[
z_1 = \alpha_1 x + (1 - \alpha_1) y,
\]
and for each \( \alpha_2 \in \mathbb{F} \)
\[
z_2 \neq \alpha_2 x + (1 - \alpha_2) y.
\]  
(iii) For each \( \alpha_1, \alpha_2 \in \mathbb{F} \)
\[
z_1 \neq \alpha_1 x + (1 - \alpha_1) y,
\]
\[
z_2 \neq \alpha_2 x + (1 - \alpha_2) y.
\]  
We assume (i) and \( z_1 \neq x \); then by hypothesis \( z \in C \) exist such that for each \( \alpha \in \mathbb{F} \)
\[
z \neq ax + (1 - \alpha)y,
\]
\[
z \neq ax + (1 - \alpha)z_1,
\]
\[
z \neq az_1 + (1 - \alpha)z_2;
\]  
then by Lemma 4
\[
\alpha_{x,y} = \alpha_{x,z} = \alpha_{z,y},
\]
\[
\alpha_{x,z_1} = \alpha_{x,z} = \alpha_{z_1,y},
\]
\[
\alpha_{z_1,z_2} = \alpha_{z_1,z} = \alpha_{z_2,y};
\]  
Thus \( \alpha_{x,y} = \alpha_{z_1,z_2} = \alpha_{z_1,z} = \alpha_{z_2,y} \).

We suppose (ii), \( z_1 \neq x \), and \( z_1 \neq y \); then for each \( \alpha \in \mathbb{F} \)
\[
z_2 \neq ax + (1 - \alpha)z_1;
\]  
thus by Lemma 4
\[
\alpha_{x,y} = \alpha_{x,z_1} = \alpha_{z_1,y},
\]
\[
\alpha_{x,z_1} = \alpha_{x,z_2} = \alpha_{z_2,z_1}.
\]  
Then \( \alpha_{z_1,z_2} = \alpha_{x,y} \).
We suppose (iii) and we may assume that for each $\alpha \in \mathbb{F}$
\[ x \neq \alpha z_1 + (1 - \alpha) z_2; \] (29)
then by Lemma 4
\[ \alpha_{x,y} = \alpha_{x,z_1} = \alpha_{z_1,y}, \]
\[ \alpha_{x,z_2} = \alpha_{z_2,x} = \alpha_{x,y}, \] (30)
Then $\alpha_{x,z_2} = \alpha_{x,z_1} = \alpha_{x,y};$ hence $\alpha_{x,z_2} = \alpha_{x,y}$ for each distinct $z_1, z_2 \in C.$

Remark 6. If $C$ is a nonempty subset of a normed space $(X, \| \cdot \|)$, in such a way that it lies inside a one-dimensional affine subspace of $X$, then $D \subset \mathbb{F}$ and a surjective isometry $\phi : (C, \| \cdot \|) \to (D, | \cdot |)$ exist. If, additionally, $C$ is convex, then $\phi$ can be affine. To prove this, we may suppose that $C$ has at least two points. Let $x, y \in C$ with $x \neq y$ and $s = \| x - y \|$; then we define $\phi : (C, \| \cdot \|) \to (F, | \cdot |)$ by $\phi(z) = \alpha_{x}s,$ where $\alpha_{x}$ is the unique element in $F$ such that $z = \alpha_{x}x + (1 - \alpha_{x})y;$ it is not hard to check that $\phi$ is a surjective isometry from $C$ to $D = \phi(C)$, and if $C$ is convex, then $\phi$ is affine.

It is not hard to prove that the set $D$ and the isometry $\phi$ can be constructed independent of the norm in $C$; for this it is sufficient to consider the renorming $r| \cdot |$ on $F$ with $r = \| x - y \|,$ $\phi : C \to F$ defined by $\phi(z) = \alpha_{x}$, and $D = \phi(C)$.

Theorem 7. Under assumptions of Theorem 2 and if $x, y \in C$ exist such that for each $z \in \alpha \in \mathbb{F}$ exists with $z = ax + (1 - \alpha)y,$ then (1) to (4) in Theorem 2 are equivalent to each of the following statements.

(B) For each norm $\| \cdot \|$ on $X, D \subset C, f \in NE(F, \| \cdot \|)$, and a surjective isometry $\phi : (C, \| \cdot \|) \to (D, | \cdot |)$ exist with $T = \phi^{-1}f|\phi\|.$

(C) $D \subset C$, a surjective function $\phi : C \to D,$ and $f \in NE(F, \| \cdot \|)$ exist with $T = \phi^{-1}f|\phi\|$, and for each norm $\| \cdot \|$ on $X, r| \cdot | \in \mathfrak{K}(F)$ exist such that $\phi$ is a $\| \cdot \|$ to $r| \cdot |$-isometry.

Proof. First we prove that (B) implies (1) of Theorem 2. Let $\| \cdot \|$ be a norm on $X$; then $D \subset C, f \in NE(F, \| \cdot \|)$, and a surjective isometry $\phi : (C, \| \cdot \|) \to (D, | \cdot |)$ exist with $T = \phi^{-1}f|\phi\|$, and $f|D = \phi|\phi\|^{-1};$ it is not hard to prove that $T$ is a $\| \cdot \|$-Lipschitz function with $K(T, \| \cdot \|) \leq K(f, | \cdot |) \leq 1$; therefore $T \in NE(C, \| \cdot \|)$.

Now we prove that (1) of Theorem 2 implies (B). Let $\| \cdot \|$ be a norm on $X$ and $x, y \in C$ such that for each $z \in \alpha \in \mathbb{F}$ exist with $z = \alpha x + (1 - \alpha) y;$ by Remark 6 $D \subset C$ and a surjective isometry $\phi : (C, \| \cdot \|) \to (D, | \cdot |)$ exist; we define $g = \phi|\phi\|^{-1};$ thus $K(g, | \cdot |) = K(T, \| \cdot \|) \leq 1$ and by Kirschbraun’s Theorem [13,14], an extension $f : (F, | \cdot |) \to (D, | \cdot |)$ of $g$ exists such that $K(f, | \cdot |) = K(g, | \cdot |) \leq 1$.

We prove that (B) implies (C). By Remark 6 $D \subset C$ and a surjective $\phi : C \to D$ exist such that, for each norm $\| \cdot \|$ on $X, r| \cdot | \in \mathfrak{K}(F)$ exist so that $\phi : (C, \| \cdot \|) \to (D, r| \cdot |)$ is an isometry. We define $g = \phi|\phi\|^{-1};$ by (A) we have that $T \in NE(C, \| \cdot \|)$; thus $g \in NE(D, r| \cdot |).$ Since the Lipschitz constant of a function defined from a subset of $F$ to itself is independent of the norm on $F,$ then $g \in NE(D, | \cdot |).$ Hence again by Kirschbraun’s Theorem, an extension $f : (F, | \cdot |) \to (D, | \cdot |)$ exists with $K(f, | \cdot |) = K(g, | \cdot |) \leq 1.$

Now we prove that (C) implies (B). Let $\| \cdot \|$ be a norm on $X$; then $r| \cdot | \in \mathfrak{K}(F)$ exist such that $\phi$ is a $\| \cdot \|$ to $r| \cdot |$-isometry. We define $D' = rD, \psi = r\phi,$ and $g = \psi|\psi\|^{-1};$ it is clear that $\psi : (C, \| \cdot \|) \to (D', | \cdot |)$ is an isometry; thus $K(g, | \cdot |) = K(T, \| \cdot \|) \leq 1;,$ then again by Kirschbraun’s Theorem the conclusion follows.

Corollary 8. Let $(X, \| \cdot \|)$ be a normed space and $C$ a nonempty, convex, closed, and bounded subset of $X$; then

(1) if $x, y \in C$ exist such that for each $z \in \alpha \in \mathbb{F}$ exists with $z = ax + (1 - \alpha)y,$ then $D \in \mathbb{F}$ and a surjective
isometry $\phi : (C, \| \cdot \|) \to (D', | \cdot |)$ exist in such a way that for each $T \in \delta'(C) \in NE(D', \| \cdot \|)$ exist with $K(f, | \cdot |) = K(T, \| \cdot \|), \theta,$ and $T = \psi^{-1}f\psi;$(2) if for each $x, y \in C \subset C$ exist such that, for each $\alpha \in \mathbb{F}, z \neq ax + (1 - \alpha)y,$ then $\delta'(C) = \{ T' : C \to C | T' = y + \alpha \}$ for some $x \in X$ and $|\alpha| \leq 1.$

In general $\delta'(C)$ is not equal to $\delta(C);$ for instance we take $C = [-1, 1]$ with the absolute value norm and $T : [-1, 1] \to [-1, 1]$ the operator defined by $Tx = -x;$ then by Remark 7 $T \notin \delta'(C)$ and by Corollary 8 $T \in \delta'(C).

Remark 9. It is important to note that if $C$ is convex, closed, and bounded, then each element in $\delta'(C)$ has a fixed point; to check this we consider the following two cases.

(1) If $C$ lies inside a one-dimensional affine subspace of $X,$ then by Schauder’s Theorem the conclusion is clear.

(2) We suppose that for each $x, y \in C$ such that, for each $\alpha \in \mathbb{F}, z \neq ax + (1 - \alpha)y.$ Let $T \in \delta'(C);$ then by Theorem 5 $T \in \mathfrak{K}(C)$ for some $\alpha \in \mathbb{F}$ with $|\alpha| \leq 1$ and $y \in X;$ then $z \in C$ exists such that $\{ x, y \}$ is linearly independent; let $Y = \text{span}(z, y)$ and $C_1 = Y \cap C;$ it is not hard to prove that $T(C_1) \subset C_1;$ thus again by Schauder’s Theorem, $T|_{C_1}$ has a fixed point.

Corollary 10. Let $(X, \| \cdot \|)$ be a normed space and $C$ a nonempty, convex, closed, and bounded subset of $X$ such that for each $x, y \in C \subset C$ exist with $z \neq ax + (1 - \alpha)y;$ then for each $T \in NE(C, \| \cdot \|)$ \ $\delta'(C), \| \cdot \| \in \mathfrak{K}(X)$ exists with $T \notin NE(C, \| \cdot \|).$

In particular if $T$ is a nonlinear operator or an operator without fixed points, then a renorming $\| \cdot \|_1$ of $X$ exists in such a way that $T$ is not a $\| \cdot \|_1$-nonexpansive operator and by Remark 3, $K(T, \| \cdot \|_1)$ is large as one desires.

Theorem 11. Under assumptions of Theorem 2, the following statements are equivalent to each statement in that theorem.

(D) For each of the norms $\| \cdot \|$ and $\| \cdot \|_1$ on $X, K(T, \| \cdot \|) = K(T, \| \cdot \|_1) \leq 1.$

(E) For each $\| \cdot \|$ and $\| \cdot \|_1 \in \mathfrak{K}(X), K(T, \| \cdot \|) = K(T, \| \cdot \|_1) \leq 1.$

Proof. It is clear that (D) implies (E); now we prove that (E) implies (3) of Theorem 2. For this we proceed by
contraposition; hence we may suppose that \( \| \cdot \| \in \mathcal{N}(X) \) exist with \( K(T, \| \cdot \|) \leq 1 \) and \( x, y \in C \) such that \( Tx - Ty \notin \text{span}(x - y) \); there exists \( \| \cdot \|_1 \in \mathcal{N}(X) \) with \( K(T, \| \cdot \|_1) > 1 \), by using Remark 3 and similar arguments of the proof of (2) implying (3) in Theorem 2.

We prove that (3) of Theorem 2 implies (D). We have the following two cases.

(i) For each \( x, y \in C \) exist such that, for each \( \alpha \in \mathbb{F} \), \( z \neq \alpha x + (1 - \alpha)y \).

(ii) \( x, y \in C \) exist such that for each \( z \in C \) exist with \( z = \alpha x + (1 - \alpha)y \).

We suppose (i); then by Theorem 5, \( T = y + \alpha f \) for some \( y \in X \) and \( |\alpha| \leq 1 \); thus for each norm the Lipschitz constant of \( T \) is \( |\alpha| \).

Now we assume (ii); then by (C) in Theorem 7 and the fact that the Lipschitz constant of functions defined from subsets of \( F \) to itself is independent of the norm on \( F \), we have \( K(T, \| \cdot \|_1) = K(T, \| \cdot \|) \leq 1 \) for each of the norms \( \| \cdot \| \) and \( \| \cdot \|_1 \) on \( X \).

3. Comparing Families of Nonexpansive Mappings

Now, we will compare the families of nonexpansive mappings by given conditions in which the families are different. Before that, to prove the two theorems in this section we need to prove two technical lemmas.

Definition 12. Let \( X \) be vectorial space endowed with two norms \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) and \( C \) a subset of \( X \). One will say that \( \| \cdot \|_1 \) is collinear to \( \| \cdot \|_2 \) in \( C \), if there exists \( \lambda > 0 \) such that \( \| x \|_1 = \lambda \| x \|_2 \) for all \( x \in C \). We can omit the subset \( C \) if the context is clear.

Remark 13. It is clear that the collinearity between norms is an equivalent relation. Let \( T : C \rightarrow C \); note that \( K(T, \| \cdot \|_1) = K(T, \| \cdot \|_2) \) if \( \| \cdot \|_1 \) is collinear to \( \| \cdot \|_2 \) in \( C - C \).

Lemma 14. Let \( X \) be a normed space. If \( C \) is a nontrivial convex subset of \( X \) with \( 0 \in C \) and \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) are two norms over \( X \) such that they are not collinear in \( C \), then \( x, y \in C \setminus \{0\} \) exist such that \( \| x \|_1 = \| y \|_1 \) and \( \| y \|_2 > \| x \|_2 \).

Proof. Since \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) are not collinear in \( C \), then it is false that \( \lambda > 0 \) exists such that for all \( x \in C \) we have \( \| x \|_2 = \lambda \| x \|_2 \); that is, the function \( f(x) = \| x \|_2 / \| x \|_2 \) defined on \( C \setminus \{0\} \) is not constant; thus \( x' \), \( y' \in C \setminus \{0\} \) exist such that \( \| x' \|_1 / \| x' \|_2 > \| y' \|_1 / \| y' \|_2 \).

If \( \| x' \|_1 = \| y' \|_1 \) then we concluded the proof. Else, we call \( x \) the element in \( \{x', y'\} \) such that \( \| x \|_1 = \min(\| x' \|_1, \| y' \|_1) \); if \( x = x' \) then take \( y = (\| x \|_2 / \| y' \|_2) y' \), so \( \| y \|_1 = \| x \|_1 \); since \( C \) is convex and \( 0 \in C \) we have that \( y \in C \). Therefore \( \| x \|_1 = \| y \|_1 \) and \( \| y \|_2 / \| y \|_2 = \| y' \|_1 / \| y' \|_2 \); thus \( \| x \|_2 < \| y \|_2 \).

If \( x = y' \) the proof is similar.

Lemma 15. Let \( X \) be a normed space, \( C \) a nonempty subset of \( X \), \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) norms over \( X \); then the following statements are equivalent.

(1) \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) are collinear in \( C - C \).

(2) For each \( y \in C \) the norms \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) are collinear in \( C - y \).

Proof. It is clear that (1) implies (2); thus we are going to show that (2) implies (1). We may suppose without loss of generality that \( C \) have at least two elements. For each \( y \in C \) we define \( \lambda_y > 0 \) as the scalar such that

\[
\| x - y \|_1 = \lambda_y \| x - y \|_2 \quad \forall x \in C.
\]

Let \( y_0 \in C \); then for all \( x \in C \) we have that \( \| x - y_0 \|_1 = \lambda_y \| x - y_0 \|_2 \) and \( \| x - y_0 \|_1 = \lambda_y \| x - y_0 \|_2 \); since \( C \) has more than one element we have \( \lambda_x = \lambda_y \) for all \( x \in C \); that is \( \| x - y \|_1 = \lambda_y \| x - y \|_2 \) for all \( x, y \in C \) and then \( \| \cdot \|_1 \) and \( \| \cdot \|_2 \) which conclude the proof.

Definition 16. Given normed spaces \( X_1, X_2, Y_1 \) and \( Y_2 \) and for \( i = 1, 2 \), \( C_1 \subseteq X_i \) and \( D_i \subseteq Y_i \) being convex, one calls that \( T : C_1 \rightarrow C_2 \) and \( S : D_1 \rightarrow D_2 \) are isometrically affine equivalent, in symbols \( T = S \), if affine surjective isometries \( \phi_i : C_1 \rightarrow D_i \) for \( i = 1, 2 \), exist, such that \( T = \phi_2^{-1} S \phi_1 \) and \( S = \phi_2 T \phi_1^{-1} \).

The intuition is that two operators are isometrically affine equivalent if they have essentially the same transformation.

\[
\begin{array}{ccc}
C_1 & \xrightarrow{T} & C_2 \\
\phi_1 & & \phi_2 \\
D_1 & \xrightarrow{S} & D_2
\end{array}
\]

The following lemma summarizes some properties of the isometrically affine relation.

Lemma 17. Let \( T = S \); then one has the following.

(1) \( T \) is continuous if and only if \( S \) is continuous; moreover \( T \) and \( S \) have the same modulus of continuity \( \omega(t) \); hence the affine isometry relation preserves uniform continuity and the Lipschitzian property with the same Lipschitz constant.

(2) \( T \) is affine if and only if \( S \) is affine.

The previous lemma allows us to translate properties of real functions to functions defined between arbitrary Banach spaces; this provides us with elements to ensure the existence of operators with desired properties.

Theorem 18. Let \((X, \| \cdot \|)\) be a normed space, \(C\) be a nontrivial convex subset of \(X\), and \(f\) be a function; then we have the following.

(1) If \( f = g \) with \( g : ([0,1], | \cdot |) \rightarrow ([0,1], | \cdot |) \) is Lipschitzian and \( x, y \in C \) and \( x \neq y \), then \( T : C \rightarrow C \) exists as Lipschitzian such that \( K(T, \| \cdot \|) = K(f, | \cdot |) \) and \( T_{\{x,y\}} = f \).
(2) If \( f = g \) with \( g : ([0,1],|\cdot|) \to (\mathbb{R},|\cdot|) \) is Lipschitzian, then \( x, y \in C, x \neq y, \) and \( T : C \to C \) exist as Lipschitzian such that \( K(T,\|\cdot\|) = K(f,|\cdot|) \) and \( T|_{[x,y]} = f \).

**Proof.** We suppose the hypothesis of (1). Since \( C \) is convex, then \( [x, y] \subset C \), and since all norms in \( R \) are collinear, then the Lipschitz constant \( k \) of \( g \) is independent of the norm in \( R \).

We consider the operator \( \phi : [0,1] \to [x, y] \) defined by \( \phi t = rt + (1 - r)y \) for each \( r \in [0,1] \) and we provide the metric space \([0,1]\) with the norm \( |r|_0 = \|x - y\| |r| \) for each \( r \in [0,1] \). It is concluded from definition that \(([0,1],|\cdot|_0)\) is \( \phi \)-isometric to the space \(([x, y],\|\cdot\|)\). It is known that \(([0,1],|\cdot|_0)\) is a metric space with the binary intersection property and metrically convex; then \( ([x, y],\|\cdot\|) \) have the same properties.

We call \( h : [x, y] \to [x, y] \) the operator defined by \( h = \phi \phi^{-1} \); hence \( h = g \) and \( g = f \); thus by Lemma 17 we have \( K(h,\|\cdot\|) = k \); then by Definition 1.3 and Proposition 1.4 of [15], an extension \( T : C \to [x, y] \subset C \) of \( h \) exists with \( K(T,\|\cdot\|) = K(h,\|\cdot\|) \); then \( T|_{[x,y]} = f \) and for Lemma 17 \( T \) and \( f \) have the same Lipschitz constant.

Now we are going to prove (2). Let \( f \) be a function such that \( g \) exists as above; then optimal \( r, s \in R \) exist such that \( g([0,1]) \subset [r, s] \subset R \). There are two possibilities:

\[
\begin{align*}
s - r &\leq 1 \\
or s - r &> 1.
\end{align*}
\]

If \( s - r \leq 1 \) then we can choose \( r' \leq r \leq s \leq s' \) such that \( s' - r' = 1 \); thus \( [r, s] \subset [r', s'] \); we define the operator \( \phi : ([0,1],|\cdot|) \to ([r', s'],|\cdot|) \) by \( \phi t = rt' + (1 - t)s' \); it is clear that \( \phi \) is an isometry; then the operator \( h = \phi \phi^{-1} g = \phi^{-1} g \) is Lipschitzian satisfies \( h = f \) which is the hypothesis of (1); thus without loss of generality, we may suppose that \( s - r > 1 \).

We fix distinct \( x, y \in C \), for each \( t \in [0,1] \); we call \( a_t = tr + (1 - t)s \) and define a norm on \([r, s] \) by \( |a_t - b|_a = \|x - y\| |t - p| \) for each \( t, p \in [0,1] \); we chose \( a, b \in [r, s] \) such that \( a < b \) and \( b - a = 1 \), and we define a norm on \([0,1]\) by \( |t|_1 = |a - b|_a |t| \) for each \( t \in [0,1] \); we consider the operators \( \phi : ([0,1],|\cdot|) \to ([x, y],\|\cdot\|) \) defined by \( \phi (t) = t \phi (1 - t)s \) which are surjective affine isometries.

Thus the operator \( h = \phi \phi^{-1} \) satisfies \( h : [\phi_2(a), \phi_2(b)] \to [x, y] \) and \( h = g = f \); then by Lemma 17 \( h \) and \( f \) have the same Lipschitz constant \( k \) and again by Definition 1.3 and Proposition 1.4 of [15], an extension \( T : C \to [x, y] \subset C \) of \( h \) exists with the same Lipschitz constant.

**Corollary 19.** Let \((X,\|\cdot\|)\) be a normed space and \( C \subset X \) be a nontrivial convex; then a nonaffine operator always exists in \( NE(C,\|\cdot\|) \).

**Proof.** Let \( f \in Lip([0,1]) \) be a nonaffine function such that \( K(f,|\cdot|) \leq 1 \) and distinct \( x, y \in C \); then by Theorem 18, an operator \( T : C \to C \) exists with \( K(T,\|\cdot\|) = K(f,|\cdot|) \leq 1 \) and \( T|_{[x,y]} = f \); thus by Lemma 17 \( T \) is a nonaffine operator.

From Remark 13 given a nonempty subset \( C \) of a normed space \( X \) and two collinear norms \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) in \( C - C \), we have that \( NE(C,\|\cdot\|_1) = NE(C,\|\cdot\|_2) \). Now, we prove the reciprocal of the previous statement.

**Remark 20.** It is important to note that the collinearity of two norms \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) on \( C \) does not necessarily imply that, for each \( T : C \to C \), \( K(T,\|\cdot\|_1) = K(T,\|\cdot\|_2) \).

Let \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) be, respectively, the euclidean and the one norm on \( R^2 \); then we define

\[
\|(x, y)\|_2 = \begin{cases} 
\|(x, y)\|_1, & \text{if } \text{sign}(xy) = 1 \\
\|(x, y)\|_1, & \text{if } \text{sign}(xy) = -1
\end{cases}
\]

for each \( (x, y) \in R^2 \), \( C = \{(x, y) \mid \|(x, y)\|_2 \leq 1\} \), and the rotation on \( R^2 \) determined by the matrix \((\cos(\pi/2) - \sin(\pi/2)\cos(\pi/2))\). It is clear that \( S(C) \subset C, K(S,\|\cdot\|_2) = 1 \), and \( K(S,\|\cdot\|_2) > 1 \); since \( \|\cdot\|_2 \) and \( \|\cdot\|_2 \) are collinear in the first quadrant, then they are collinear on \( C + (1,1) \). Let \( T \to S + (1,1) \); then \( T : C + (1,1) \to C + (1,1) \) with \( \|\cdot\|_2 \) and \( \|\cdot\|_2 \) collinear on \( C + (1,1) \), but \( K(T,\|\cdot\|_2) = K(S,\|\cdot\|_2) \neq K(S,\|\cdot\|_1) = K(T,\|\cdot\|_1) \).

**Theorem 21.** Let \( X \) be a normed space and \( C \subset X \) a nontrivial convex subset of \( X \). If \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) are not collinear in \( C - C \), then the following statements are equivalent.

(1) \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) are not collinear in \( C - C \).

(2) \( NE(C,\|\cdot\|_1) \neq NE(C,\|\cdot\|_2) \).

(3) \( T \in NE(C,\|\cdot\|_1) \setminus NE(C,\|\cdot\|_2) \) and \( S \in NE(C,\|\cdot\|_2) \setminus NE(C,\|\cdot\|_1) \) exist.

(4) Nonaffine mappings \( T, S \) with \( T \in NE(C,\|\cdot\|_1) \setminus NE(C,\|\cdot\|_2) \) and \( S \in NE(C,\|\cdot\|_2) \setminus NE(C,\|\cdot\|_1) \) exist.

**Proof.** It is clear that we only need to prove that (1) implies (4). We suppose (1); then by Lemma 15 \( y \in C \) exists such that \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) are not collinear in \( C - y \); thus without loss of generality we may assume that \( 0 \in C \).

Since \( \|\cdot\|_1 \) and \( \|\cdot\|_2 \) are not collinear in \( C \) and \( 0 \in C \), then by Lemma 14 \( x, y \in C \setminus \{0\} \) exist such that

\[
\|x\|_1 = \|y\|_1, \quad \|x\|_2 < \|y\|_2.
\]

Without loss of generality we may assume that \( \|x\|_1 = \|y\|_1 = 1 \).

Let \( \alpha_0 \in ([\|x\|_2,\|y\|_2],1) \); then \( z = \alpha_0 y \) satisfies \( \|z\|_2 < \|z\|_2 < \|y\|_2 \); we define the operator \( f : [0,x] \to [0,y] \) by

\[
f(ax) = \begin{cases} 
\alpha y, & \text{if } 0 \leq \alpha \leq \alpha_0 \\
z, & \text{if } \alpha_0 \leq \alpha \leq 1.
\end{cases}
\]
Since
\[ f((1 - \alpha_0)0 + \alpha_0x) = z = \alpha_0y \neq \alpha_0(\alpha_0y) = (1 - \alpha_0)0 + \alpha_0f(x), \]
then \( f \) is nonaffine.

We affirm that \( K(f, \| \cdot \|_1) = 1 \); in fact, let \( \alpha, \beta \in [0, 1] \); then by symmetry we only have the following three cases.

(i) \( 0 \leq \alpha, \beta \leq \alpha_0 \); then
\[ \|f(\alpha x) - f(\beta x)\|_1 = \|\alpha y - \beta y\|_1 = |\alpha - \beta| \|y\|_1, \]  

(ii) \( \alpha_0 \leq \alpha, \beta \leq 1 \), then \( \|f(\alpha x) - f(\beta x)\|_1 = \|z - z\|_1 = 0 \leq \|\alpha x - \beta x\|_1 \).

(iii) \( 0 \leq \alpha < \alpha_0 < \beta \leq 1 \); then
\[ \|f(\alpha x) - f(\beta x)\|_1 = \|\alpha y - \alpha y\|_1 = |\alpha - \alpha_0| \|x\|_1, \]
\[ < |\alpha - \beta| \|x\|_1 = \|\alpha x - \beta x\|_1. \]

Now we prove that \( K(f, \| \cdot \|_2) > 1 \); for this we have
\[ \|f(0) - f(x)\|_2 = \|0 - z\|_2 = \|z\|_2 > \|0\|_2 = \|0 - x\|_2. \]  

Since \( \|x\|_1 = \|y\|_1 = 1 \), then the sets \([0, x]\) and \([0, y]\) are affine \( \| \cdot \|_1 \)-isometric; then by Remark 6, they are affine isometric to \((0, 1], \| \cdot \|_1 \) and \( g : ((0, 1], \| \cdot \|_1) \to (0, 1], \| \cdot \|_1) \) exists with \( f = g; \) thus by Theorem 18 an extension \( T : C \to (0, 1] \subset C \) of \( f \) exists, with the same \( \| \cdot \|_1 \)-Lipschitz constant that means \( K(T, \| \cdot \|_1) = 1 \); thus \( T \in NE(C, \| \cdot \|_1), \) but \( T \) is \( \| \cdot \|_2 \)-Lipschitz and \( K(T, \| \cdot \|_2) \geq K(f, \| \cdot \|_2) > 1 \). Then \( T \notin NE(C, \| \cdot \|_2). \)

In a similar way we prove the existence of \( S \in NE(C, \| \cdot \|_2) \setminus NE(C, \| \cdot \|_1), \) by exchanging the order of the norms and applying Lemma 14.

**Corollary 25.** Let \( X \) be a normed space, and \( C \subset X \) such that for each \( x, y \in C \) exists with \( z = \alpha x + (1 - \alpha) y \) for each \( \alpha \in F; \) then for each norm \( \| \cdot \| \) on \( X, NE(C, \| \cdot \|) \neq \delta'\).\( (C). \)

**Corollary 26.** The nonexpansive operators constructed in the proof of Lemma 15 do not belong to \( \delta'\).\( (C). \)

### 4. Examples

In the present section we support the theoretical results of the previous ones by providing some examples.

In general, given a Banach space \( X \) and a convex subset \( C \) of \( X \), it is hard to construct examples of nontrivial nonexpansive operators from \( C \) to \( C \); by trivial we understand the elements in the sets \( \delta(C), \delta' (C) \) or more general affine mappings from \( C \) to itself. In this sense, when a new Banach space is studied to know some of its geometric properties, for instance, the FPP, then it is natural to ask for the existence of some nontrivial nonexpansive operators defined in that space. An example of last situation is the renorming \( \| \cdot \|_2 \) of \( \ell_1 \) studied by Lin [1], for which at the moment in the literature only few examples of nonexpansive mappings exist.

**Example 27.** Let \( (\ell_1, \| \cdot \|_1) \) be the Banach space of absolutely summable series of real numbers endowed whit the norm \( \|x\|_1 = \sum_{n=1}^{\infty} |x_n| \). It is well known that \( \|x\|_1 \) does not have the FPP; the classical example is the right-shift operator \( R \) defined from \( C \) to \( C \), where
\[ C = \text{conv} \{ e_n \mid n \in \mathbb{N} \}. \]
\[ R(x_1, x_2, \ldots) = (0, x_1, x_2, \ldots) \ldots \]

For each \( k \in \mathbb{N} \) let \( \gamma_k \) be the seminorm in \( \ell_1 \) defined by \( \gamma_k((x_n)) = \sum_{n=k}^{\infty} |x_n|, \) thus the \( \| \cdot \|_2 \) norm in \( \ell_1 \) is defined by
\[ \|x\|_2 = \sup_k \gamma_k(x_n) \text{ where } \gamma_k = \frac{1}{1 + 8^k}. \]

Now we construct some examples of nontrivial \( \| \cdot \|_2 \)-nonexpansive operators defined from \( C \) to itself such that they are not \( \| \cdot \|_1 \)-nonexpansive and the opposite.

Let
\[ g_1 = e_1, \]
\[ g_2 = \left( 1 - \frac{1}{y_2} \right) e_1 + \frac{1}{y_2} e_2, \]
\[ g_3 = \left( 1 - \frac{1}{y_2} \right) e_1 + \left( \frac{1}{y_2} - \frac{1}{y_3} \right) e_2 + \frac{1}{y_3} e_3, \]

then \( \|g_1\|_2 = \|g_2\|_2 = \|g_3\|_1 = 1 \) and \( g_1, g_2, g_3 \in C. \)

As in Lemma 15, we consider the set \( C - g_2 \) and define
\[ x' = g_1 - g_2 = \frac{1}{y_2}(e_1 - e_2), \]
\[ y' = g_3 - g_2 = \frac{1}{y_3}(e_3 - e_2). \]
then \( \|x'\|_1 = 2(\gamma_1/\gamma_2) \) and \( \|y'\|_1 = 2(\gamma_1/\gamma_3) \); since \( 2\gamma_1 \geq \gamma_2, 2\gamma_2 \geq \gamma_3 \) and \( \gamma_1 \neq \gamma_2 \) we have
\[
\|x'\|_L = \gamma_1 \frac{\gamma_2}{\gamma_2} = \gamma_1 \|x'\|_1,
\]
\[
\|y'\|_L = \max \left\{ \gamma_2 \frac{\gamma_1}{\gamma_3}, \gamma_2 \frac{\gamma_1}{\gamma_3}, \gamma_1 \right\} = 2 \gamma_1 \frac{\gamma_2}{\gamma_3} = \gamma_2 \|y'\|_1;
\]
(45)
hence \( \|\cdot\|_1 \) and \( \|\cdot\|_L \) are not collinear in \( C - g_2 \); in fact, by Lemma 15, they are not collinear in \( C - C \).

Now we make the construction of Lemma 14 in this particular case. It is clear that
\[
\left\| \frac{x'}{\gamma_1} \right\|_L = \frac{1}{\gamma_1} > \frac{1}{\gamma_2} = \left\| \frac{y'}{\gamma_2} \right\|_L.
\]
(46)
Since \( \gamma_3 \geq \gamma_1 \), then \( \|y'\|_L \leq \|x'\|_L \); thus we define \( x = y' \) and \( y = (\|y'\|_L/\|x'\|_L)x' \); then by (46)
\[
\|x\|_L = \|y\|_L,
\]
\[
\|y\|_L = \left\| \frac{\|y'\|_L}{\|x'\|_L} \right\| \|x'\|_L < \left\| \frac{\|y'\|_L}{\|y\|_L} \right\| \|y\|_L = \|y\|_L.
\]
(47)
We get \( \alpha_0 \in (\|y\|_L/\|x\|_1,1) \); then \( z = \alpha_0, x \in [0,x] \) and \( \|y\|_L < \|z\|_L < \|x\|_L \). We consider the function \( f : [0,y] \to [0,x] \) defined by
\[
f(\alpha y) = \begin{cases} \alpha x, & \text{if } 0 \leq \alpha \leq \alpha_0, \\ z, & \text{if } \alpha_0 \leq \alpha \leq 1; \end{cases}
\]
(48)
then by the same argument of the proof of Theorem 21, the existence of a nonaffine mapping \( T \in NE(C,\|\cdot\|_L) \setminus NE(C,\|\cdot\|_1) \) follows.

Now we prove the existence of a nonaffine mapping \( S \in NE(C,\|\cdot\|_L) \setminus NE(C,\|\cdot\|_1) \). From (46) it follows that
\[
\left\| \frac{x'}{\|x'\|_L} \right\|_L = \gamma_1 \frac{\gamma_2}{\gamma_2} = \left\| \frac{y'}{\|y'\|_L} \right\|_L.
\]
(49)
Since \( \gamma_1/\gamma_2 \leq \gamma_2/\gamma_3 \), then \( \|x''\|_L \leq \|y''\|_L \); hence we define \( x = x'' \) and \( y = (\|y''\|_L/\|x''\|_L)y'' \); thus by (49)
\[
\|x\|_L = \|y\|_L,
\]
\[
\|y\|_L = \left\| \frac{\|y''\|_L}{\|x''\|_L} \right\| \|y''\|_L < \left\| \frac{\|y''\|_L}{\|y\|_L} \right\| \|y\|_L = \|y\|_L.
\]
(50)
Let \( \lambda_0 \in (\|y\|_L/\|x\|_1,1) \); hence \( w = \lambda_0 x \) satisfies \( \|y\|_1 < \|w\|_1 < \|x\|_1 \); we define the function \( g : [0,y] \to [0,x] \),
\[
g(\lambda y) = \begin{cases} \lambda x, & \text{if } 0 \leq \lambda \leq \lambda_0, \\ w, & \text{if } \lambda_0 \leq \lambda \leq 1; \end{cases}
\]
(51)
then again by the same argument of the proof of Theorem 21, we ensure the existence of a nonaffine mapping \( S \in NE(C,\|\cdot\|_L) \setminus NE(C,\|\cdot\|_1) \).

**Remark 28.** Let \( y = (\gamma_k) \) be a nondecreasing sequence in \((0,1) \) such that \( y_k \to 1 \); then by [7], the renorming
\[
\|x_n\|_y = \sup k y_k (x_n)
\]
(52)
of \( (\ell_\gamma,\|\cdot\|_L) \) has the FPP. Note that the previous example is valid for each renorming \( ||\cdot||_y \) in which
(i) \( y_1 \neq y_2 \),
(ii) \( 2\gamma_1 \geq \gamma_2 \) and \( 2\gamma_2 \geq \gamma_3 \),
(iii) \( \gamma_1/\gamma_2 \leq \gamma_2/\gamma_3 \).

**Example 29.** Now we characterize the family of nonexpansive mappings \( T : C \to C \) over any renorming, where \( C \) is as in Example 27; that is, we characterize the set \( \delta^C \). The next calculations are effortless if we consider the equality
\[
C = \{(x_n) : (\gamma_1) \leq 1, \sum x_n = 1 \}.
\]
(53)
It is clear that \( C \) does not lie inside a one-dimensional affine subspace of \( \ell_1 \); then by Corollary 8, for each \( T \in \delta^C \), \((\gamma_n) \in \ell_1 \) and \( |\gamma| \leq 1 \) exist such that \( T(x_n) = (\gamma_n) + \gamma (x_n) \) for each \( (x_n) \in C \).

We affirm that each entry of \((\gamma_n) \) is nonnegative and \( 0 \leq \lambda \leq 1 \); for this, if \( y_k \leq 0 \) for some \( k \in \mathbb{N} \) then the \( k \)-entry of \( T e_{k+1} \) is \( y_k \); hence for each \( k \in \mathbb{N} \) we have \( y_k \geq 0 \). If \( 0 \leq \lambda < 1 \), then the \( k \)-entry of \( T e_k \) is \( y_k + \lambda < 0 \); hence \( 0 \leq \lambda \leq 1 \).

Let \((x_n) \in C \); then
\[
1 = \|T(x_n)\|_1 = \| (\gamma_n) + \lambda (x_n) \| = \sum |\gamma_n + \lambda x_n| = \sum y_n + \lambda \sum x_n
\]
(54)
thus \( 0 \leq \lambda \leq 1 \) and \((\gamma_n) \in (1 - \lambda)C \), which agrees with the notation of Remark 1 \( \delta^C \subset (\gamma_n) + \lambda I \) \( 0 \leq \lambda \leq 1 \) and \((\gamma_n) \in (1 - \lambda)C \); the proof of the other contention is a direct calculation; thus
\[
\delta^C \subset (\gamma_n) + \lambda I \subset (1 - \lambda)C.
\]
(55)
In this case \( \delta^C = \delta^C \); for this, let \( 0 \leq \lambda \leq 1 \) and \((\gamma_n) \in (1 - \lambda)C \); thus \((1 - \lambda)^{-1} (\gamma_n) \in C \); then \( T = (1 - \lambda)(1 - \lambda)^{-1} (\gamma_n) + \lambda I \in \delta^C \).

**Example 30.** Let \((X,\|\cdot\|)\) be a normed space and \( B \) its unit ball. We characterize the set \( \delta^B \). By Corollary 8, for each \( T \in \delta^B \), \( y \in X \) and \( |\lambda| \leq 1 \) exist with \( T x = y + \lambda x \) for each \( x \in B \); we affirm that \( |\lambda| \leq 1 \) and \( y \in (1 - |\lambda|)B \); in fact, let \( |\lambda| \leq 1 \), \( y \in (1 - |\lambda|)B \), and \( x \in B \); then
\[
||Tx|| = ||y + \lambda x|| \leq ||y|| + ||\lambda|| ||x|| \leq (1 - |\lambda|) + |\lambda|
\]
(56)
1;

hence, with notation of Remark 1, \( T = y + \lambda I \mid |\lambda| \leq 1 \) and \( y \in (1 - |\lambda|)B \subset \delta^B \). Now we prove the other
contention. Let $|\lambda| \leq 1$ and $y \notin (1-|\lambda|)B$; then $\|y\| > 1 - |\lambda|$; we define $x = \lambda^{-1}(\lambda/\|y\|)y$; thus $x \in B$; since
\[
\|y + \lambda x\| = \|y + \frac{\lambda}{\|y\|}y\| = \left(1 + \frac{|\lambda|}{\|y\|}\right)\|y\|
\]
and $|\lambda| > 1 - |\lambda| + |\lambda| = 1$.
\[
(57)
\]
then $y + \lambda x \notin B$; hence
\[
\mathcal{S}^*(B) = \{T = y + \lambda I \mid |\lambda| \leq 1, y \in (1 - |\lambda|)B\}.
\]
\[
(58)
\]
Competing Interests
The authors declare that there is no conflict of interests regarding the publication of this paper.

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