

Research Article

On the Exact Values of HZ-Index for the Graphs under Operations

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Topological index (TI) is a function from the set of graphs to the set of real numbers that associates a unique real number to each graph, and two graphs necessarily have the same value of the TI if these are structurally isomorphic. In this note, we compute the HZ – index of the four generalized sum graphs in the form of the various Zagreb indices of their factor graphs. These graphs are obtained by the strong product of the graphs G and $D_k(G)$, where $D_k \in \{S_k, R_k, Q_k, T_k\}$ represents the four generalized subdivision-related operations for the integral value of $k \geq 1$ and $D_k(G)$ is a graph that is obtained by applying D_k on G . At the end, as an illustration, we compute the HZ – index of the generalized sum graphs for exactly $k = 1$ and compare the obtained results.

1. Introduction

A structural formula of a chemical compound is represented by a molecular graph, where atoms and bonds between atoms are represented by the vertices and edges of the molecular graphs, respectively. A topological index (TI) is a mathematical tool which associates a real number to a graph under certain conditions. For two graphs, a TI remains constant if the graphs are isomorphic (see [1–3]). These are used to study different physical attributes, biological activities, and chemical reactivities such as viscosity, critical temperatures (boiling, freezing, melting, and flash points) [4, 5], vapor pressure, surface tension, stability, weight, density, solubility, and connectivity [6–8] in the field of chemical engineering, pharmaceutical industries, and drugs discoveries. TIs are also used in the subject of cheminformatics to study the quantitative structural activity and property relationships (see [9–11]).

In 1947, the very first TI is introduced by Winer to check the critical temperature of paraffin [12]. Trinajstić and Gutman (1972) [13] defined the first and second Zagreb indices that are used to compute the different structure base characteristics of the molecular graphs. After that, many degree, distance, and polynomials based TIs came into existence but the degree-based indices got more attention of the researchers (see [14–16]). For various results on TIs of

different graphs, see [17–20]. In 2008, Zhou and Trinajstić defined the general sum connectivity (GSC) index and discussed its various properties [21]. Shirdel et al. [22] studied the concept of hyper-Zagreb index (HZ – index) as a particular case of the GSC index. In addition, the results for the index HZ under the operation of Cartesian, composition, join, and disjunction of graphs can be found in [23–25].

On the other hand, for the studies of the complex graphs, operations for graphs play a key role. Yan et al. (2007) defined four types of operations related to the subdivision of G and computed the Wiener indices of the derived graphs $D_1(G)$, where $D_1 \in \{S_1, R_1, Q_1, T_1\}$ [26]. Taeri et al. (2009) gave the construction of the D_1 -sum graphs $G_{D_1} + H$ (Cartesian product of $F_1(G)$ and H) and computed their Wiener indices, where H and G are assumed to be two connected graphs [27]. Furthermore, Deng et al. [28], Akhter and Imran [29], Chu et al. [30], and Liu et al. [31] computed the various indices of these graphs with the help of the Cartesian product.

Liu et al. (2019) [32] extended these operations for any integral value of k and obtained the generalized derived graphs $D_k(G)$ of the graph G , where $D_k \in \{S_k, R_k, Q_k, T_k\}$. Moreover, using the concept of Cartesian product of graphs, they constructed the generalized sum graphs or D_k -sum graphs (denoted by $G_{D_k} + H$) and computed their first and second Zagreb indices.

Javaid et al. (2021) [33] redefined these graphs using strong product and computed their Zagreb indices (first and second). In this development, we compute hyper-Zagreb indices (HZ – index) for these graphs in terms of various degree-based TIs of their factor graphs, where these generalized sum graphs are obtained with the help of strong product. The remaining paper is settled as follows. Section 2 contains the notations and key concepts which are utilized in methodology, Section 3 deals main results, and Section 4 covers examples and conclusion.

2. Preliminaries

This section explains the basic definitions and terminologies.

Definition 1. Let $G = (V(G), E(G))$ be a (molecular) graph with $V(G)$ and $E(G)$ as sets of vertices and edges, respectively. The degree of a vertex $v \in V(G)$ is the number of edges which are incident on v and denoted by $d(v)$.

Definition 2 (see [13, 34]). For a graph G , the first, second, and forgotten Zagreb indices are defined as follows: $M_1(G) = \sum_{z \in V(G)} d^2(z) = \sum_{zt \in E(G)} [d(z) + d(t)]$, $M_2(G) = \sum_{zt \in E(G)} [d(z) \times d(t)]$, and $F(G) = \sum_{z \in V(G)} d^3(z) = \sum_{zt \in E(G)} [d^2(z) + d^2(t)]$.

These indices have been used to find the various properties of molecular graphs such as entropy, π -electron energy, and heat capacity. These are also used in the studies of the molecular structural relationships such as QSPR and QSAR [13, 35–37]. However, the hyper-Zagreb index of a graph (G) (given below) is studied by Shirdel et al. in 2013 [22]:

$$HZ(G) = \sum_{yz \in E(G)} [d(y) + d(z)]^2. \tag{1}$$

Definition 3 (see [32]). For some integral value of $k \geq 1$, the graphs obtained by the generalized subdivision-related operations are defined as follows:

- (i) $S_k(G)$ is a graph that is obtained by inserting k vertices in each edge of G
- (ii) $R_k(G)$ is a graph obtained from $S_k(G)$ by joining the vertices which are adjacent in G
- (iii) $Q_k(G)$ is a graph obtained from $S_k(G)$ by joining the new vertices which are on the incident edges in G for each of its vertex
- (iv) $T_k(G)$ is obtained from $S_k(G)$ after using both R_k and Q_k , respectively

For $k = 3$, see Figure 1.

Definition 4 (see [33]). Let G_1 and G_2 be two graphs, $D_k \in \{S_k, R_k, Q_k, T_k\}$ be generalized subdivision-related operations, and $D_k(G_1)$ be a graph obtained using D_k on G_1 having edge-set $E(D_k(G_1))$ and vertex-set $V(D_k(G_1))$. The generalized sum graph $G_1 \boxtimes_{D_k} G_2$ under the operation of strong product is a graph having vertex-set $V(G_1 \boxtimes_{D_k} G_2) = V(D_k(G_1)) \times V(G_2) = (V(G_1) \cup k(E(G_1))) \times V(G_2)$ such that two vertices (r_1, s_1) and (r_2, s_2) of $V(G_1 \boxtimes_{D_k} G_2)$ are adjacent iff $[r_1 = r_2$ in $V(G_1)$ and s_1 is adjacent to s_2 in $E(G_2)]$ or $[s_1 = s_2$ in $V(G_2)$ and s_1 is adjacent to s_2 in $E(G_1)]$ or $[r_1$ is adjacent to r_2 in $E(D_k(G_1))$ and s_1 is adjacent to s_2 in $E(G_2)]$, where $k \geq 1$ is a positive integer. For more explanation, see Figures 2 and 3.

3. Main Results

The main developments are covered by this section.

Theorem 1. For $k \geq 1$, the HZ-index of $G_1 \boxtimes_{S_k} G_2$ is

$$\begin{aligned} HZ(G_1 \boxtimes_{S_k} G_2) &= 8e_{G_1} M_1(G_2) + n_{G_1} HZ(G_2) + 4e_{G_2} M_1(G_1) + 4e_{G_1} HZ(G_2) + M_1(G_1) HZ(G_2) + 4M_1(G_1) M_1(G_2) \\ &\quad + n_{G_2} HZ S_1(G_1) + 4e_{G_2} M_1 S_1(G_1) + 2e_{G_1} M_1(G_2) + 4e_{G_2} HZ S_1(G_2) + 2M_1(G_2) M_1 S_1(G_1) \\ &\quad + M_1(G_2) HZ S_1(G_1) + 16(k-1)e_{G_1} [n_{G_2} + M_1(G_2) + 4e_{G_2}] + HZ_1 G_1 F(G_2) + 2M_1(G_2) HZ S_1(G_1) \\ &\quad + 2M_1(G_2) M_1(S(G_1)) + 2F(G_2) M_1(S(G_1)) + 16e_{G_1} e_{G_2} + 4e_{G_1} F(G_2) + 2e_{G_2} M_1(G_1) \\ &\quad + 4(k-1)e_{G_1} [8e_{G_2} + 2HZ(G_2) + 8M_1(G_2)]. \end{aligned} \tag{2}$$

Proof. Let the degree of a vertex $(r, s) \in G_1 \boxtimes_{S_k} G_2$ be denoted by $d(r, s)$:

$$\begin{aligned} HZ(G_1 \boxtimes_{S_k} G_2) &= \sum_{(r_1, s_1)(r_2, s_2) \in E(G_1 \boxtimes_{S_k} G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\ &= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 + \sum_{r_1, r_2 \in E(S_k(G_1))} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\ &\quad + \sum_{r_1, r_2 \in E(S_k(G_1))} \sum_{s_1, s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_A + \sum_B + \sum_C. \end{aligned} \tag{3}$$

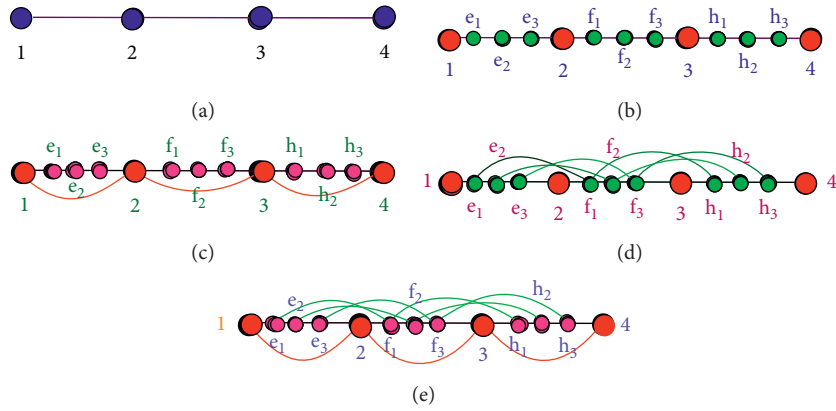


FIGURE 1: (a) $G_1 \cong P_4$, (b) $S_3(P_4)$, (c) $R_3(P_4)$, (d) $Q_3(P_4)$ and (e) $T_3(P_4)$.

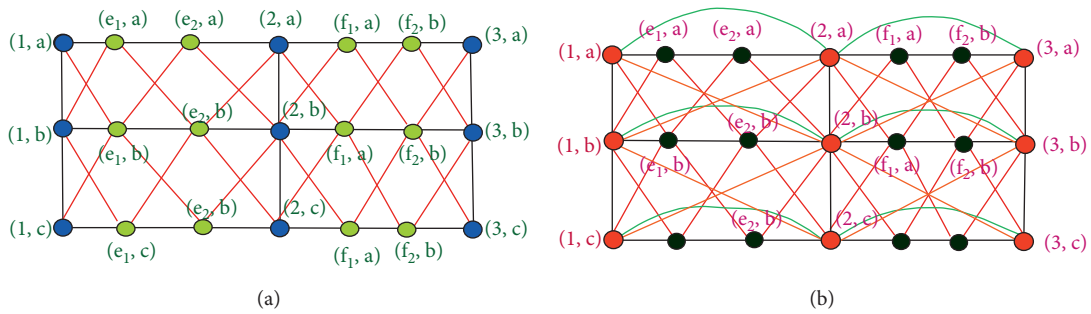


FIGURE 2: (a) $P_3 \boxtimes_{S_2} P_3$ and (b) $P_3 \boxtimes_{R_2} P_3$.

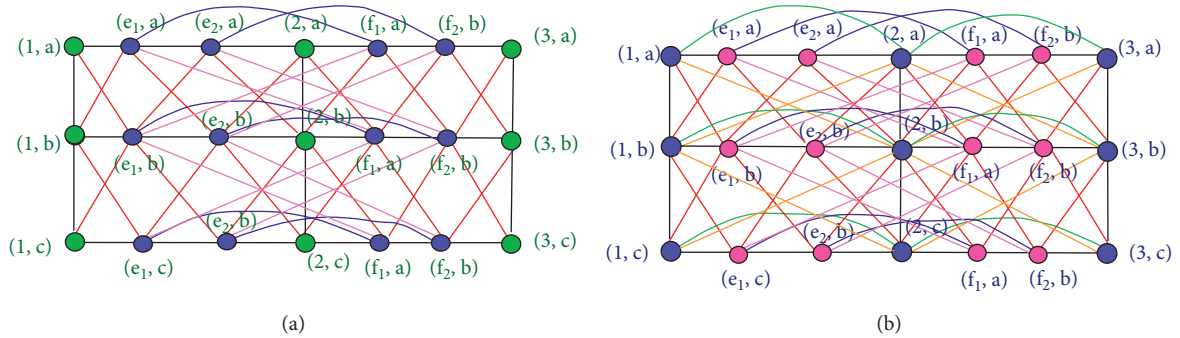


FIGURE 3: (a) $P_3 \boxtimes_{Q_2} P_3$ and (b) $P_3 \boxtimes_{T_2} P_3$.

Consider

$$\begin{aligned}
& \sum_A = \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 \\
& = \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [2d(r) + d(s_1) + d(s_2) + d(r)(d(s_1) + d(s_2))]^2 \\
& = \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [4d(r)(d(s_1) + d(s_2)) + (d^2(s_1) + d(s_2) + 2d(s_1)d(s_2)) + 4d^2(r) + 2d(r)(d^2(s_1) + d^2(s_2) \\
& \quad + 2d(s_1)d(s_2)) + d^2(r)(d^2(s_1) + d^2(s_2) + 2d(s_1)d(s_2)) + 4d^2(r)(d(s_1) + d(s_2))] \\
& = 8e_{G_1}M_1(G_2) + n_{G_1}HZ(G_2) + 4e_{G_2}M_1(G_1) + 4e_{G_1}HZ(G_2) + M_1(G_1)HZ(G_2) + 4M_1(G_1)M_1(G_2), \\
& \sum_B = \sum_{r_1, r_2 \in E(S_k(G_1))} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 = \sum_{\substack{r_1 \in V(G_1), \\ r_2 \in V(S_k(G_1) - G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
& \quad + \sum_{\substack{r_1, r_2 \in \\ V(S_k(G_1) - G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 = \sum_{B_1} + \sum_{B_2}, \\
& \sum_{B_1} = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
& = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [(d(r_1) + d(r_2)) + d(s) + (d(r_1) + d(r_2))d(s)]^2 \tag{4} \\
& = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [(d^2(r_1) + d^2(r_2) + 2d(r_1)d(r_2)) + 2d(s)(d(r_1) + d(r_2)) + d^2(s) \\
& \quad + 2d(s)(d^2(r_1) + d^2(r_2) + 2d(r_1)d(r_2)) + 2d^2(s)(d(r_1) + d(r_2)) + d^2(s)(d^2(r_1) + d^2(r_2))] \\
& = n_{G_2}HZS_1(G_1) + 4e_{G_2}M_1S_1(G_1) + 2e_{G_1}M_1(G_2) + 4e_{G_2}HZS_1(G_1) + 2M_1(G_2)M_1S_1(G_1) \\
& \quad + M_1(G_2)HZS_1(G_1), \\
& \sum_{B_2} = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1, s_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
& = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [d(r_1) + d(r_1)d(s) + d(r_2) + d(r_2)d(s)]^2 \\
& = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [4 + 4d(s)]^2 = \sum_{\substack{r_1, r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V(S_k(G_1) - V(G_1))}} \sum_{s \in V(G_2)} [16 + 16d^2(s) + 32d(s)].
\end{aligned}$$

Since in this case $|E(S_k(G_1))| = (k - 1)|E(G_1)|$, we have

$$\begin{aligned}
 &= \sum_{s \in V(G_2)} 16(k - 1)e_{G_1} [1 + d^2(s) + 2d(s)] \\
 \sum_C &= \sum_{r_1 r_2 \in E(S_k(G_1))} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1 \in V(G_1), r_2 \in ((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &+ \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{C_1} + \sum_{C_2}, \\
 \sum_{C_1} &= \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1 \in V(G_1), r_2 \in ((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, z_1) + d(r_2, s_2)]^2 \\
 &= \sum_{\substack{r_1 \in V(G_1), \\ r_2 \in V((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [(d(r_1) + d(r_2)) + d(s_1) + d(r_1)d(s_1) + d(r_2)d(s_2)]^2 \\
 &= \text{HZ } G_1 F(G_2) + 2M_1(G_2)\text{HZ } S_1(G_1) + 2M_1(G_2)M_1(S(G_1)) \\
 &+ 2F(G_2)M_1(S(G_1)) + 16e_{G_1}e_{G_2} + 4e_{G_1}F(G_2) + 2e_{G_2}M_1(G_1), \\
 \sum_{C_2} &= \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [4 + 2(d(s_1) + d(s_2))]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(S_k(G_1)) \\ r_1, r_2 \in V((S_k(G_1)) - V(G_1))}} \sum_{s_1 s_2 \in V(G_2)} [16 + 4(d(z_1) + d(z_2))^2 + 16(d(z_1) + d(z_2))] \\
 &= 4(k - 1)e_{G_1} [8e_{G_2} + 2\text{HZ}(G_2) + 8M_1(G_2)].
 \end{aligned} \tag{5}$$

Hence, we obtained our required result. \square

Theorem 2. For $k \geq 1$, the HZ-index of $G_1 \boxtimes_{R_k} G_2$ is

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{R_k} G_2) &= 8[n_{G_2} + 6e_{G_2}]F(G_1) + [n_{G_1} + 20e_{G_1}]F(G_2) + 8F(G_1)F(G_2) + 24e_{G_2}M_1(G_1) + 36e_{G_1}M_1(G_2) \\
 &+ 24M_1(G_1)M_1(G_2) + 24F(G_1)M_1(G_2) + 8n_{G_2}e_{G_1} + 8(k - 1)e_{G_1}[n_{G_2} + F(G_2) + 4e_{G_2} + 3M_1(G_2)] \\
 &+ 48e_{G_1}e_{G_2} + 12F(G_2)M_1(G_1) + 2[M_2(G_2)[4e_{G_1} + n_{G_1}] + k[n_{G_2} + 6e_{G_2} + 3M_1(G_2) + 2M_2(G_2)]] \\
 &\times \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) + \sum_{v \in V(G_1)} r d_{G_1}(u) d_{G_1}(v) + \sum_{v \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{u \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right] \\
 &+ M_1(G_1)[5e_2 + 5M_1(G_2) + 5M_2(G_2)] + k[M_3(G_1) + 2M_2(G_1)][6e_{G_2} + 3M_1(G_2) + 2M_2(G_2) + n_{G_2}] \\
 &+ 2e_{G_1}M_1(G_2).
 \end{aligned} \tag{6}$$

Proof. Let the degree of a vertex $(r, s) \in G_1 \boxtimes_{R_k} G_2$ be denoted by $d(r, s)$:

$$\begin{aligned}
\text{HZ}(G_1 \boxtimes_{R_k} G_2) &= \sum_{(r_1, s_1)(r_2, s_2) \in E(G_1 \boxtimes_{R_k} G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
&\cdot \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 + \sum_{s \in V(G_2)} \sum_{r_1, r_2 \in E(R_k(G_1))} [d(r_1, s) + d(r_2, s)]^2 \\
&+ \sum_{r_1, r_2 \in E(R_k(G_1))} \sum_{s_1, s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_A + \sum_B + \sum_C, \\
\sum_A &= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 \\
&= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [2d(r) + d(s_1) + 2d(r)d(s_1) + 2d(r) + d(s_2) + 2d(r)d(s_2)]^2 \\
&= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [4d(r) + d(s_1) + d(s_2) + 2d(r)(d(s_1) + d(s_2))]^2 \\
&= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [(4d^2(r) + 1 + 4d(r))(d^2(s_1) + d^2(s_2) + 2d(s_1)d(s_2)) + (8d(r) + 16d^2(r)) \\
&\quad \times (d(s_1) + d(s_2)) + 16d^2(r)] \\
&= \text{HZ}G_2 [4M_1(G_1) + n_{G_1} + 8e_{G_1}] + 16M_1(G_2) [e_{G_1} + M_1(G_1)] + 16M_1(G_1)e_{G_2}
\end{aligned}$$

OR

$$\begin{aligned}
&= 8e_{G_2}M_1(G_1) + n_{G_1}F(G_2) + 4M_1(G_1)F(G_2) + 8e_{G_1}M_1(G_2) + 8M_1(G_1)M_1(G_2) + 8e_{G_1}F(G_2) \\
&\quad + 2[4M_1(G_1)[e_{G_2} + M_1(G_2) + M_2(G_2)] + 4e_{G_1}[M_1(G_2) + 2M_2(G_2)] + M_2(G_2)n_{G_1}], \\
\sum_B &= \sum_{r_1, r_2 \in E(R_k(G_1))} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 = \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
&\quad + \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 + \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
&= \sum_{B_1} + \sum_{B_2} + \sum_{B_3}, \\
\sum_{B_1} &= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
&= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s \in V(G_2)} [d(r_1) + d(s) + d(r_1)d(s) + d(r_2) + d(s) + d(r_2)d(s)]^2 \\
&= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s \in V(G_2)} [d(r_1) + d(r_2) + 2d(s) + d(s)(d(r_1) + d(r_2))]^2 \\
&= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s \in V(G_2)} [4d^2(r_1) + 4d^2(s) + 4d(4d^2(r_2) + 8d(r_1)d(s) + 8d(r_1)d(r_2) + 8d(s)d(r_2)) \\
&\quad + 4d^2(s)(d^2(r_1) + d^2(r_2) + 2d(s)d^2(r_1)) + 8d(s_1)(d^2(r_1) + d^2(r_2) + 2d(s)d^2(r_1)) + 8d^2(s_1)(d(r_1) + d(r_2))] \\
&= 4e_{G_1}M_1(G_2) + [4n_{G_2} + 4M_1(G_2) + 16e_{G_2}]\text{HZ}(G_1) + 16e_{G_2}M_1(G_1) + 8M_1(G_1)M_1(G_2).
\end{aligned}$$

OR

$$\begin{aligned}
&= 4n_{G_2}F(G_1) + 2e_{G_1}M_1(G_2) + 4M_1(G_2)F(G_1) + 8e_{G_2}M_1(G_1) + 4M_1(G_1)M_1(G_2) + 16e_{G_2}F(G_1) \\
&\quad + 2[4M_2(G_1)[n_{G_2} + 4e_{G_2} + M_1(G_2)] + 2M_1(G_1)[M_1(G_2) + 2e_{G_2}] + e_{G_1}M_1(G_2)],
\end{aligned}$$

$$\begin{aligned}
 \sum_{B_2} &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [d(r_1) + d(r_2) + d(s) + (d(r_1) + d(r_2))d(s)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [2d(r_1) + 3d(s) + 2d(r_1)d(s) + 2]^2 \\
 &= 4n_{G_2}F(G_1) + 18e_{G_1}M_1(G_2) + 8e_{G_1}n_{G_2} + 40e_{G_2}M_1(G_1) + 48e_{G_1}e_{G_2} + 8n_{G_2}M_1(G_1) \\
 &\quad + 4F(G_1)M_1(G_2) + 12M_1(G_1)M_1(G_2) + 16e_{G_2}F(G_1), \\
 \sum_{B_3} &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [d(r_1, s) + d(r_2, s)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [d(r_1) + d(r_1)d(s) + d(r_2) + d(r_2)d(s)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [4 + 4d(s)]^2 = \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{seV(G_2)} [16 + 16d^2(s) + 32d(s)] \\
 &= \sum_{seV(G_2)} 16(k-1)e_{G_1}[1 + d^2(s) + 2d(s)] = 16(k-1)e_{G_1}[n_{G_2} + M_1(G_2) + 4e_{G_2}], \\
 \sum_C &= \sum_{r_1 r_2 \in E(R_k(G_1))} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &\quad + \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &\quad + \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(R_k(G_1)) - V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{C_1} + \sum_{C_2} + \sum_{C_3}, \\
 \sum_{C_1} &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [d(r_1) + d(s_1) + d(r_1)d(s_1) + d(r_2) + d(s_2) + d(r_2)d(s_2)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(R_k(G_1)) \\ r_1, r_2 \in V(G_1)}} \sum_{s_1 s_2 \in V(G_2)} [(d(r_1) + d(s_1) + d(r_1)d(s_1))^2 + (d(r_1) + d(s_2) + d(r_2)d(s_2))^2] \\
 &\quad + 2[4d(r_1)d(r_2) + 2[d(r_1)d(s_2) + d(r_2)d(s_1)] + d(s_1)d(s_2)] \\
 &\quad + 4d(r_1)d(r_2)d(s_1)d(s_2) + 4d(r_1)d(r_2)[d(s_1) + d(s_2)] + 2[d(r_1) + d(r_2)]d(s_1)d(s_2) \\
 &= 8e_{G_2}F(G_1) + 2e_{G_1}F(G_2) + 4F(G_1)F(G_2) + 4M_1(G_1)M_1(G_2) + 4M_1(G_1)F(G_2) + 8M_1(G_2)F(G_1) \\
 &\quad + 2[8M_2(G_1)e_{G_2} + 2M_1(G_1)M_1(G_2) + 2M_2(G_2)e_{G_1} + 8M_2(G_1)[M_2(G_2) + M_1(G_2)] + 4M_1(G_1)M_2(G_2)],
 \end{aligned}$$

$$\begin{aligned}
\sum_{C_2} &= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V((R_k(G_1))^{-V}(G_1))}} \sum_{s_1, s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
&= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V((R_k(G_1))^{-V}(G_1))}} \sum_{s_1, s_2 \in V(G_2)} [d(r_1) + d(s_1) + d(r_1)d(s_1) + d(r_2) + d(r_2)d(s_2)]^2 \\
&= \sum_{\substack{r_1, r_2 \in E(R_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V((R_k(G_1))^{-V}(G_1))}} \sum_{s_1, s_2 \in V(G_2)} [(d(r_1) + d(s_1) + d(r_1)d(s_1))^2 + (d(r_2) + d(r_2)d(s_2))^2] \\
&\quad + 2[(d(r_1) + d(s_1) + d(r_1)d(s_1))(d(r_2) + d(r_2)d(s_2))] \\
&= 8e_{G_2}F(G_1) + 32e_{G_1}e_{G_2} + 4F(G_1)F(G_2) + 4M_1(G_1)M_1(G_2) + 8F(G_1)M_1(G_2) \\
&\quad + 2e_{G_1}F(G_2) + 4M_1(G_1)F(G_2) + 8e_{G_1}F(G_2) + 16e_{G_1}M_1(G_2) + 8e_{G_1}[M_1(G_2) + M_2(G_2)] \\
&\quad + 2[M_2(R_1(G_1)) - 4M_2(G_1)][2e_{G_2} + 2M_1(G_2) + 2M_2(G_2)], \\
\sum_{C_3} &= \sum_{\substack{r_1, r_2 \in E((R_k(G_1))) \\ r_1, r_2 \in V((R_k(G_1))^{-V}(G_1))}} \sum_{s_1, s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
&= \sum_{\substack{r_1, r_2 \in E((R_k(G_1))) \\ r_1, r_2 \in V((R_k(G_1))^{-V}(G_1))}} \sum_{s_1, s_2 \in V(G_2)} [d(r_1) + d(r_2) + d(r_1)d(s_1) + d(r_2)d(s_2)]^2 \\
&= [(2 + 2d(s_1))^2 + (2 + 2d(s_2))^2 + 2[2 + 2d(s_1)](2 + 2d(s_2))] \\
&= 8(k-1)e_{G_1}[2e_{G_2} + F(G_2) + 2M_1(G_2)] + 16(k-1)e_{G_1}[e_{G_2} + M_1(G_2) + M_2(G_2)].
\end{aligned} \tag{7}$$

Hence, we reached at our required result. \square

Theorem 3. For $k \geq 1$, the HZ-index of $G_1 \boxtimes_{Q_k} G_2$ is

$$\begin{aligned}
\text{HZ}(G_1 \boxtimes_{R_k} G_2) &= 2(k-1)[F(G_1) + 2M_2(G_1)][3n_{G_2} + 5M_1(G_1) + 14e_{G_2} + F(G_2)] \\
&\quad + k[n_{G_2} + 6e_{G_2} + 3M_1(G_2) + F(G_2)] \\
&\quad \left[M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) + \sum_{u \in V(G_1)} d^2(u) \sum_{v \in N(u)} d(v) \right] + 6e_{G_2}M_1(G_1) \\
&\quad + 10e_{G_2}F(G_2) + 3F(G_1)F(G_2) + 6M_1(G_1)M_1(G_2) + F(G_2)[n_{G_1} + 3M_1(G_1) + 6e_{G_2} + 4M_2(G_1)] \\
&\quad + F(G_1)[n_{G_2} + 7M_1(G_2)] + 6e_{G_2}M_2(G_1) + 8M_2(G_1)[e_{G_2} + M_1(G_2)] + 2[k[n_{G_2} + 6e_{G_2} + 3M_1(G_2) \\
&\quad + 2M_2(G_2)]] \frac{1}{2} \sum_{u \in V(G_1)} d_{G_1}^4(v) - d_{G_1}^3(v) + \sum_{u \in V(G_1)} td_{G_1}(u)d_{G_1}(v) + \sum_{u \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{u \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) \\
&\quad - 2M_2(G_1)] + M_2(G_2)[4e_{G_1} + n_{G_1}] + 2e_{G_1}M_1(G_2) + M_1(G_1)[5e_2 + 5M_1(G_2) + 5M_2(G_2)] \\
&\quad + k[M_3(G_1) + 2M_2(G_1)][6e_{G_2} + 3M_1(G_2) + 2M_2(G_2) + n_{G_2}]].
\end{aligned} \tag{8}$$

Proof. Let the degree of a vertex $(r, s) \in G_1 \boxtimes_{Q_k} G_2$ be denoted by $d(r, s)$:

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{Q_k} G_2) &= \sum_{(r_1, s_1)(r_2, s_2) \in E(G_1 \boxtimes_{Q_k} G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
 &= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 + \sum_{s \in V(G_2)} \sum_{r_1, r_2 \in E(Q_k(G_1))} [d(r_1, s) + d(r_2, s)]^2 \\
 &\quad + \sum_{r_1, r_2 \in E(Q_k(G_1))} \sum_{s_1, s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_A + \sum_B + \sum_C, \\
 \sum_A &= \sum_{r \in V(G_1)} \sum_{s_1, s_2 \in E(G_2)} [d(r, s_1) + d(r, s_2)]^2 \\
 &= 8e_1 M_1(G_2) + n_1 \text{HZ}(G_2) + 4e_2 M_1(G_1) + 4e_1 \text{HZ}(G_2) + M_1(G_1) \text{HZ}(G_2) + 4M_1(G_1) M_1(G_2)
 \end{aligned}$$

OR

$$\begin{aligned}
 &= 2|E(H_2)|M_1(H_1) + |V(H_1)|F(H_2) + M_1(H_1)F(H_2) \\
 &\quad + 4|E(H_1)|M_1(H_2) + 2M_1(H_1)M_1(H_2) + 4|E(H_1)|F(H_2) \\
 &\quad + 2[M_1(G_1)e_{G_2} + M_1(G_1)[M_1(G_2) + M_2(G_2)] + 2e_{G_1}[M_1(G_2) + 2M_2(G_2)] + M_2(G_2)n_{G_1}], \quad (9)
 \end{aligned}$$

$$\begin{aligned}
 \sum_B &= \sum_{s \in V(G_2)} \sum_{r_1, r_2 \in E(Q_k(G_1))} [d(r_1, s) + d(r_2, s)]^2 \\
 &\quad + \sum_{s \in V(G_2)} \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)) \\ r_1, r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1, s) + d(r_2, s)]^2 \\
 \sum_{B_1} &= \sum_{s \in V(G_2)} \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1, s) + d(r_2, s)]^2 \\
 &= \sum_{s \in V(G_2)} \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1) + d(s) + d(r_1)d(r) + d(r_2) + d(r_2)d(s)]^2 \\
 &= \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)) \\ s_1 \in V(H_1), s_2 \in V(Q_k(H_1)) - H_1}} \sum_{s \in V(G_2)} [(d(r_1) + d(s) + d(r_1)d(s))^2 (d(r_2) + d(r_2)d(s))^2 \\
 &\quad + 2[d(r_1) + d(s) + d(r_1)d(s)][d(r_2) + d(s) + d(r_2)d(s)]].
 \end{aligned}$$

Consider $r_1 \in V(G_1)$ and $d^2(r_1)$ occurs $d(r_1)$ times. Thus,

$$D_1 = \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)), \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} d^3(r_1) = F(G_1). \quad (10)$$

Let

$$D_2 = \sum_{\substack{r_1, r_2 \in E(Q_k(G_1)), \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} d^2(s_2), \quad (11)$$

as $s_2 = uv \in E(G_1)$ and $d^2(s_2)$ occurs two times. Therefore,

$$\begin{aligned}
 D_2 &= 2 \sum_{s_2=uv \in E(G_1)-V(G_1)} [d(u) + d(v)]^2 = 2 \sum_{uv \in E(G_1)} [d^2(u) + d^2(v) + 2d(u)d(v)] = 2[F(G_1) + 2M_2(G_1)], \\
 \sum_{B_1} &= n_{G_2}F(G_1) + 2e_{G_1}M_1(G_2) + M_1(G_2)F(G_1) + 4e_{G_2}[M_1(G_1) + F(G_1)] + 2M_1(G_1)M_1(G_2) \\
 &\quad + 2n_{G_2}[F(G_1) + 2M_2(G_1)] + 2M_1(G_2)[F(G_1) + 2M_2(G_1)] + 8e_{G_2}[F(G_1) + 2M_2(G_1)] \\
 &\quad + 2[M_3(G_1) + 2M_2(G_1)][n_{G_2} + 4e_{G_2} + M_1(G_2)] + 2M_1(G_1)[2e_{G_2} + M_1(G_2)], \\
 \sum_{B_2} &= \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 r_2 \in V(Q_k(G_1))-V(G_1)}} \sum_{s \in V(G_2)} [d(r_1, s) + d(r_2, s)]^2.
 \end{aligned} \tag{12}$$

Now, assume $\Sigma_{B_2} = \Sigma_{B_3} + \Sigma_{B_4}$ as follows:

$$\begin{aligned}
 \sum_{B_3} &= \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 r_2 \in V(Q_k(G_1))-V(G_1)}} \sum_{s \in V(G_2)} [(d(r_1) + d(r_1)d(s))^2 + (d(r_2) + d(r_2)d(s))^2 \\
 &\quad + 2[(d(r_1) + d(r_1)d(s))(d(r_2) + d(r_2)d(s))]] \\
 &= 2(k-1)[(F(G_1) + 2M_2(G_1))(n_{G_2} + M_1(G_2) + 4e_{G_2}) + (M_3(G_1) + 2M_2(G_1))(n_{G_2} + 4e_{G_2} + M_1(G_2))], \\
 \sum_{B_4} &= \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 r_2 \in V(Q_k(G_1))-V(G_1)}} \sum_{s \in V(G_2)} [d(r, s_1) + d(r, s_2)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 r_2 \in V(Q_k(G_1))-V(G_1)}} \sum_{s \in V(G_2)} [d(r_1) + d(r_1)d(s) + d(r_2) + d(r_2)d(s)]^2 \\
 &= \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 r_2 \in V(Q_k(G_1))-V(G_1)}} \sum_{s \in V(G_2)} [d(r_1)^2 + d(r_2)^2 + d(s)^2(d(r_1)^2 + d(r_2)^2) + 2d(s)(d(r_1)^2 + d(r_2)^2)] \\
 &\quad + 2[(d(r_1) + d(r_1)d(s))(d(r_2) + d(r_2)d(s))], \\
 D_3 &= \sum_{\substack{r_1 r_2 \in E(Q(G_1)) \\ r_1 r_2 \in V(Q(G_1))-V(G_1)}} [d^2(r_1) + d^2(r_2)].
 \end{aligned} \tag{13}$$

In D_3 , coefficient of

$$d^2(u) = 2 \binom{2}{d_{G_1}(u)} + \sum_{v \in N(u)} d(v) - d(u) = d^2(u) - 2d(u) + \sum_{v \in N(u)} d(v). \tag{14}$$

Therefore,

$$\sum_{u \in V(G_1)} d^2(u) = M_4(G_1) - 2F(G_1) + \sum_{u \in V(G_1)} d^2(u) \sum_{v \in N(u)} d(v). \tag{15}$$

For coefficient of $d(u)d(v)$, let $r_1r_2 \in E(Q(G_1))$ with $r_1 = uv$ and $r_2 = wz$. As $r_1r_2 \in E(Q(G_1))$, we have either $v = w$ or $z = u = w$ or z . So, uv is adjacent to all those vertices in G_1

which are adjacent to u and v . Consequently, the number of such $d(u)d(v)$ is $(d(u) + d(v) - 2)$. Therefore,

$$\begin{aligned} 2 \sum_{uv \in E(G_1)} d(u)d(v) &= 2 \sum_{uv \in E(G_1)} (d(u) + d(v) - 2)dudv \\ &= 2 \sum_{uv \in E(G_1)} (d(u) + d(v))d(u)d(v) - 4 \sum_{uv \in E(G_1)} d(u)d(v) = 2M_2(G_1) - 4M_2(G_1), \end{aligned} \tag{16}$$

so

$$\begin{aligned} D_3 &= M_4(G_1) - 2F(G_1) + \sum_{u \in V(G_1)} d^2(u) \sum_{v \in N(u)} d(v) + 2M_2(G_1) - 4M_2(G_1), \\ \sum_{B_4} &= (k) [n_{G_2} + 4e_{G_2} + M_1(G_2)] \left[M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) + \sum_{u \in V(H_1)} d^2(u) \sum_{v \in N(u)} d(v) \right] \\ &+ 2 \left[(k) [n_{G_2} + 4e_{G_2} + M_1(G_2)] \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) + \sum_{uv \in V(G_1)} td_{G_1}(u)d_{G_1}(v) \right] \right. \\ &\left. + \sum_{v \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{v \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right], \end{aligned} \tag{17}$$

where t is the number of neighbors which are common vertices of u and v in (G_1) .

$$\begin{aligned} \sum_C &= \sum_{r_1r_2 \in E(Q_k(G_1))} \sum_{s_1s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{\substack{r_1r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} \sum_{s_1s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\ &+ \sum_{\substack{r_1r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} \sum_{s_1s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 = \sum_{C_1} + \sum_{C_2}, \\ \sum_{C_1} &= \sum_{\substack{r_1r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} \sum_{s_1s_2 \in V(G_2)} [d(r_1, s_1) + d(r_2, s_2)]^2 \\ &= \sum_{\substack{r_1r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} \sum_{s_1s_2 \in V(G_2)} [d(r_1) + d(s_1) + d(r_1)d(s_1) + d(r_2) + d(s_2) + d(r_2s_2)]^2 \\ &= \sum_{\substack{r_1r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} \sum_{s_1s_2 \in V(G_2)} [(d(r_1) + d(s_1) + d(r_1)d(s_1))^2 + (d(r_2) + d(r_2)d(s_2))^2] \end{aligned}$$

$$\begin{aligned}
& + 2[d(r_1, s_1)d(r_2, s_2)] \\
= & 6[e_{G_2} + M_1(G_2)]F(G_1) + 3F(G_1)F(G_2) + 2M_1(G_1)M_1(G_2) + 2[e_{G_1} + M_1(G_1) + 2M_2(G_1)]F(G_2) + 8M_2(G_1) \quad (18) \\
& \times [e_{G_2} + M_1(G_2)] + 2[[M_3(G_1) + 2M_2(G_1)][2e_{G_2} + 2M_1(G_2) + 2M_2(G_2)] + 2M_1(G_1)[2M_2(G_2) + M_1(G_2)]].
\end{aligned}$$

Now, assume $\Sigma_{C_2} = \Sigma_{C_3} + \Sigma_{C_4}$ as follows:

$$\begin{aligned}
\Sigma_{C_3} &= \sum_{s_1 s_2 \in V(G_2)} \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
&= \sum_{s_1 s_2 \in V(G_2)} \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1 \in V(G_1), r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1) + d(r_1)d(s_1) + d(r_2) + d(r_2)d(s_2)]^2 \\
&= \sum_{t_1 t_2 \in E(H_2)} \sum_{\substack{s_1 s_2 \in E(Q_k(H_1)) \\ s_1, s_2 \in V(Q_k(H_1)) - H_1}} [(d(s_1) + d(s_1)d(t_1))^2 + (d(s_2) + d(s_2)d(t_2))^2] \\
&\quad + 2[(d(r_1) + d(r_1)d(s)) (d(r_2) + d(r_2)d(s))] \\
&= 2(k-1)[(F(G_1) + 2M_2(G_1))][2e_{G_2} + F(G_2) + 2M_1(G_2)] + 2(k-1)[2e_{G_2} + 2M_1(G_2) + 2M_2(G_2)][M_3(G_1) + 2M_2(G_1)], \\
\Sigma_{C_4} &= \sum_{s_1 s_2 \in V(G_2)} \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1, r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1, s_1) + d(r_2, s_2)]^2 \\
&= \sum_{s_1 s_2 \in V(G_2)} \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1, r_2 \in V(Q_k(G_1)) - V(G_1)}} [d(r_1) + d(r_2) + d(r_1)d(s_1) + d(r_2)d(s_2)]^2 \\
&= \sum_{s_1 s_2 \in V(G_2)} \sum_{\substack{r_1 r_2 \in E(Q_k(G_1)) \\ r_1, r_2 \in V(Q_k(G_1)) - V(G_1)}} [(d(r_1) + d(r_1)d(s_1))^2 + (d(r_2) + d(r_2)d(s_2))^2] \\
&\quad + 2[(d(r_1) + d(r_1)d(s)) (d(r_2) + d(r_2)d(s))] \\
&= (k)[2e_{G_2} + F(G_2) + 2M_1(G_2)] \left[M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) + \sum_{u \in V(G_1)} d^2(u) \sum_{v \in N(u)} d(v) \right] \\
&\quad + (2k)[2e_{G_2} + 2M_1(G_2) + 2M_2(G_2)] \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) + \sum_{uv \in E(G_1)} td_{G_1}(u)d_{G_1}(v) \right. \\
&\quad \left. + \sum_{u \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{u \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right],
\end{aligned} \tag{19}$$

where t is the number of neighbors which are common vertices of u and v in (G_1) .

Theorem 4. For $k \geq 1$, the HZ-index of $G_1 \boxtimes_{T_k} G_2$ is

Thus, we arrive at our desired result. \square

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{T_k} G_2) &= 2(k-1)[F(G_1) + 2M_2(G_1)][n_{G_2} + 3M_1(G_2) + 6e_{G_2} + F(G_2)] + k[n_{G_2} \\
 &+ 6e_{G_2} + 3M_1(G_2) + F(G_2)][M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) \\
 &+ \sum_{u \in V(G_1)} d^2(u) \sum_{v \in N(u)} dv] + [F(G_1) + 2M_2(G_1)][2n_{G_2} + 6M_1(G_2) + 12e_{G_2} + 2F(G_2)] \\
 &+ 4F(G_1)[2n_{G_2} + 6M_1(G_2) + 12e_{G_2} + 2F(G_2)] + F(G_2)[n_{G_1} + 12M_1(G_1) \\
 &+ 12e_{G_2}] + 12e_{G_1}M_1(G_2) + 16e_{G_2}M_1(G_1) + 20M_1(G_1)M_1(G_2)] \\
 &+ 2 \left[k[n_{G_2} + 6e_{G_2} + 3M_1(G_2)2M_2(G_2)] \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) + \sum_{uv \in E(G_1)} d_{G_1}(u)d_{G_1}(v) \right. \right. \\
 &\left. \left. + \sum_{v \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{u \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right] + M_2(G_1)[4n_{G_2} + 24e_{G_2} + 8M_2(G_2) + 12M_1(G_2)] \right] \\
 &+ k[M_3(G_1) + 2M_2(G_1)][6e_{G_2} + n_{G_2} + 3M_1(G_2) + 2M_2(G_2)] + 5M_1(G_2)e_{G_1} \\
 &+ M_2(G_2)[10e_{G_1} + n_{G_1}] + M_1(G_1)[10e_{G_2} + 11M_1(G_2) + 10M_2(G_2)].
 \end{aligned} \tag{20}$$

4. Applications and Discussion

(i) S_1 -sum:

Using $k = 1$, in Theorems 1–4, the results are obtained for the generalized D_1 -sum graphs as follows:

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{S_1} G_2) &= [n_{G_2} + 3M_1(G_2) + 6e_{G_2}]F(G_1) + [n_{G_1} + 3M_1(G_1) + 14e_{G_1}]F(G_2) + 6e_{G_2}M_1(G_1) + 30e_{G_1}M_1(G_2) \\
 &+ 6M_1(G_1)M_1(G_2) + 48e_{G_1}e_{G_2} + F(G_1)F(G_2) + 8n_{G_2}e_{G_1} + 2[[M_2(G_1) + 4e_{G_1}][5e_{G_2} + 3M_1(G_2) \\
 &+ 2M_2(G_2) + n_{G_2}] + 14e_{G_1}M_1(G_2) + M_2(G_2)][12e_{G_1} + n_{G_1}] + M_1(G_1)[e_{G_2} + M_1(G_2) + M_2(G_2)] \\
 &+ 8e_{G_1}e_{G_2}].
 \end{aligned} \tag{21}$$

TABLE 1: Hyper-Zagreb index of F_1 -sum path graphs.

$[n_1, n_2]$	$\text{HZ}(P_{n_1} \boxtimes_{S_1} P_{n_2})$	$\text{HZ}(P_{n_1} \boxtimes_{R_1} P_{n_2})$	$\text{HZ}(P_{n_1} \boxtimes_{Q_1} P_{n_2})$	$\text{HZ}(P_{n_1} \boxtimes_{T_1} P_{n_2})$
(3, 3)	4144	11870	8834	16168
(4, 4)	11040	30260	24500	47180
(5, 5)	21232	62122	46516	89230
(6, 6)	33696	99344	75416	145204
(7, 7)	51384	147638	110384	212318

(ii) R_1 -sum:

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{R_1} G_2) &= 8[n_{G_2} + 6e_{G_2}]F(G_1) + [n_{G_1} + 20e_{G_1}]F(G_2) + 8F(G_1)F(G_2) + 24e_{G_2}M_1(G_1) + 36e_{G_1}M_1(G_2) \\
 &\quad + 24M_1(G_1)M_1(G_2) + 24F(G_1)M_1(G_2) + 8n_{G_2}e_{G_1} + 48e_{G_1}e_{G_2} + 12F(G_2)M_1(G_1) \\
 &\quad + 2[2M_1(G_1)[4e_{G_2} + 6M_1(G_2) + 2M_2(G_2)] + 4e_{G_1}[3M_1(G_2) + 3M_2(G_2) + 4e_{G_2}] \tag{22} \\
 &\quad + [M_2(R_1(G_1)) - 4M_2G_1][6e_{G_2} + 3M_1(G_2) + 2M_2(G_2) + n_{G_2}] + e_{G_1}M_1(G_2) \\
 &\quad + 4M_2(G_1)[n_{G_2} + 6e_{G_2} + 3M_1(G_2)] + M_2(G_2)[n_{G_1} + 2e_{G_1}].
 \end{aligned}$$

(iii) Q_1 -sum:

$$\begin{aligned}
 \text{HZ}(G_1 \boxtimes_{Q_1} G_2) &= 2 \left[[n_{G_2} + 6e_{G_2} + 3M_1(G_2) + 2M_2(G_2)] \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) + \sum_{uv \in E(G_1)} td_{G_1}(u)d_{G_1}(v) \right. \right. \\
 &\quad \left. \left. + \sum_{v \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{ue \in V(G_1) \\ uve \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right] + M_2(G_2)[4e_{G_1} + n_{G_1}] + 2e_{G_1}M_1(G_2) + M_1(G_1) \right] \\
 &\quad \times [5e_2 + 5M_1(G_2) + 5M_2(G_2)] + [M_3(G_1) + 2M_2(G_1)][6e_{G_2} + 3M_1(G_2) + 2M_2(G_2) + n_{G_2}] \\
 &\quad + [n_{G_2} + e_{G_2} + 3M_1(G_2) + F(G_2)] \left[M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) + \sum_{u \in V(G_1)} d^2(u) \right. \\
 &\quad \left. \times \sum_{v \in N(u)} d(v) \right] + 6e_{G_2}M_1(G_1) + 10e_{G_2}F(G_2) + 3F(G_1)F(G_2) + 6M_1(G_1)M_1(G_2) + F(G_2)[n_{G_1} \\
 &\quad + 3M_1(G_1) + 6e_{G_2} + 4M_2(G_1)] + F(G_1)[n_{G_2} + 7M_1(G_2)] + 6e_{G_2}M_2(G_1) + 8M_2(G_1)[e_{G_2} + M_1(G_2)]. \tag{23}
 \end{aligned}$$

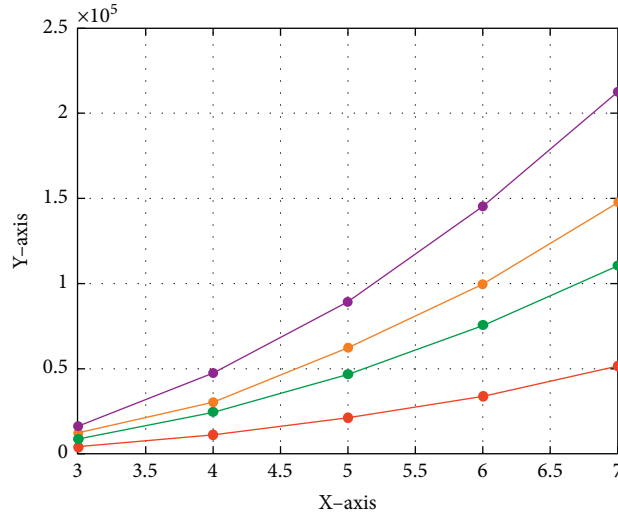


FIGURE 4: Graphical representation of $HZ(P_{n_1} \boxtimes_{S_1} P_m)$, $HZ(P_{n_1} \boxtimes_{R_1} P_m)$, $HZ(P_{n_1} \boxtimes_{Q_1} P_m)$, and $HZ(P_{n_1} \boxtimes_{T_1} P_m)$ in red, green, orange, and purple colour, respectively.

(iv) T_1 -sum:

$$\begin{aligned}
 HZ(G_1 \boxtimes_{T_1} G_2) &= [n_{G_2} + 6e_{G_2} + 3M_1(G_2) + F(G_2)] \left[M_4(G_1) - 2F(G_1) + 2M_2(G_1) - 4M_2(G_1) + \sum_{u \in V(G_1)} d^2(u) \right. \\
 &\quad \times \left. \sum_{v \in N(u)} d(v) \right] + [F(G_1) + 2M_2(G_1)] [2n(G_2) + 6M_1(G_2) + 12e_{G_2} + 2F(G_2)] + 4F(G_1) [2n_{G_2} \\
 &\quad + 6M_1(G_2) + 12e_{G_2} + 2F(G_2)] + F(G_2) [n_{G_1} + 12M_1(G_1) + 12e_{G_2}] + 12e_{G_1}M_1(G_2) + 16e_{G_2}M_1(G_1) \\
 &\quad + 20M_1(G_1)M_1(G_2) + 2 \left[[n_{G_2} + 6e_{G_2} + 3M_1(G_2) + 2M_2(G_2)] \left[\frac{1}{2} \sum_{v \in V(G_1)} (d_{G_1}^4(v) - d_{G_1}^3(v)) \right. \right. \\
 &\quad \left. \left. + \sum_{uv \in E(G_1)} td_{G_1}(u)d_{G_1}(v) + \sum_{v \in V(G_1)} d_{G_1}^2(v) \sum_{\substack{u \in V(G_1) \\ uv \in E(G_1)}} d_{G_1}(u) - 2M_2(G_1) \right] + [M_3(G_1) + 2M_2(G_1)] \right. \\
 &\quad \times [6e_{G_2} + n_{G_2} + 3M_1(G_2) + 2M_2(G_2)] + 5M_1(G_2)e_{G_1} + M_1(G_1) [10e_{G_2} + 11M_1(G_2) + 10M_2(G_2)] \\
 &\quad \left. + M_2(G_2) [10e_{G_1} + n_{G_1}] + M_2(G_1) [4n_{G_2} + 24e_{G_2} + 8M_2(G_2) + 12M_1(G_2)] \right]. \tag{24}
 \end{aligned}$$

Now, we present tabular form in Table 1 and graphical representation in Figure 4 of path graphs for $k = 1$.

Finally, we close this section with the comment that the problem is still open for other topological indices and product of graphs, in particular the general randic index of F_k -sum graphs under corona product.

Data Availability

The data are included within this paper and are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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