A Note on the Waiting-Time Distribution in an Infinite-Buffer $GI^{[X]} /C-MSP/1$ Queueing System

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This paper deals with a batch arrival infinite-buffer single server queue. The interbatch arrival times are generally distributed and arrivals are occurring in batches of random size. The service process is correlated and its structure is presented through a continuous-time Markovian service process ($C\text{-MSP}$). We obtain the probability density function (p.d.f.) of actual waiting time for the first and an arbitrary customer of an arrival batch. The proposed analysis is based on the roots of the characteristic equations involved in the Laplace-Stieltjes transform (LST) of waiting times in the system for the first, an arbitrary, and the last customer of an arrival batch. The corresponding mean sojourn times in the system may be obtained using these probability density functions or the above LSTs. Numerical results for some variants of the interbatch arrival distribution (Pareto and phase-type) have been presented to show the influence of model parameters on the waiting-time distribution. Finally, a simple computational procedure (through solving a set of simultaneous linear equations) is proposed to obtain the “$R$” matrix of the corresponding $GI/M/1$-type Markov chain embedded at a prearrival epoch of a batch.

1. Introduction

In recent years, analysis of queueing processes with nonrenewal arrival and service processes has been carried out to model data transmission of complex computer and communication networks. The traditional queueing analysis using Poisson processes is not powerful enough to capture the dependence involved in the arrival (service) process. The performance analysis of such bursty and correlated type of the arrival (service) processes may be done through some analytically tractable processes, namely, Markovian arrival process ($C\text{-MAP}$) and Markovian service process ($C\text{-MSP}$); see Lucantoni et al. [1], Gupta and Banik [2], and references therein. The two processes $C\text{-MAP}$ and $C\text{-MSP}$ are convenient representations of a versatile Markovian point process or N-process; see Neuts [3] and Ramaswami [4]. Chaudhry et al. [5] obtain stationary system-length distributions for the infinite-buffer batch arrival $GI/C\text{-MSP}/1$ queues at various epochs using roots. Further, Singh et al. [6] have shown that it is beneficial to use roots rather than the matrix-geometric/matrix-analytic methods in terms of computation time. For further details on the roots method, the readers are referred to the related references in Chaudhry et al. [7].

One may note that Grassmann [8] shows the relation between the characteristics roots and the corresponding eigenvalues of the possible quasi birth-death (QBD) process in connection with the computation of the waiting-time distribution in an $E_n/E_m/1$ queueing model. For further details on the relationships between the characteristics roots of a Markov chain and the corresponding “$G$” matrix of $M/G/1$-type Markov chain or “$R$” matrix of $GI/M/1$-type Markov chain one may see Gail et al. [9].

In this paper we obtain the explicit closed-form expressions for the Laplace-Stieltjes transform (LST) of waiting-time distribution. For analytic purpose, we start our work with associated prearrival epoch probability distribution;
see Chaudhry et al. [5] for details. After that we consider characteristic equations involved in the Laplace-Stieltjes transforms (LST’s) waiting-time distribution for the first and an arbitrary customer of an arrival batch. Once the roots of these characteristic equations are found, it becomes easy to obtain the stationary waiting-time distribution for the first and an arbitrary customer of an arrival batch. Also, a simple computational procedure based on the solution of a set of linear simultaneous equations has been proposed to compute the R matrix of the corresponding GI/M/1-type Markov chain embedded at a prearrival epoch of a batch. It is well-known that the determination of the “R” matrix can be done through the minimal nonnegative solution of a nonlinear matrix equation; see Neuts [10] for details. Finally, it may be remarked here that the same queueing model has been dealt with in [5]. But in both the queueing models, corresponding probability density functions of actual waiting time for the first/ an arbitrary customer have not been derived. It is needless to mention here that probability density functions of the waiting times are important for obtaining statistical measures of Quality of Service (QoS) requirement of a queueing system. Thus, the present work is a nontrivial extension of [5].

2. Description of the Model: GI\(X\)/C-MSP/1/∞ Queue and the Analysis of the Stationary Distribution of Waiting Time

We assume a renewal input single server queueing system where the customers arrive in batches of random size X whose probability mass function is given by \(P(X = i) = g_i\), \(i = 1, 2, \ldots\), and mean batch size \(E(X) = \sum_{i=1}^{\infty} i g_i = \overline{g}\). Let \(G(z) = \sum_{i=0}^{\infty} g_i z^i\) be the probability generating function of \(g_i\). The interbatch arrival times are independent identically distributed (i.i.d.) random variables with distribution function \(F(x)\), probability density function \(f(x)\) with \(x > 0\), and Laplace-Stieltjes transform (LST) \(A^*(s)\), where \(\Re(s) \geq 0\). Then, \(1/A = -A^{-1}(0)\); i.e., \(1/A\) is the mean interbatch arrival time, where \(A^{-1}(\theta)\) is the j-th \((j \geq 1)\) derivative of \(A^*(s)\) at \(s = \theta\).

A single server is serving the customers according to a continuous-time Markovian service process (C-MSP) with matrix representation \((L_0, L_1)\). For a detailed discussion on C-MSP, the readers are referred to Chaudhry et al. [5]. Let us denote \(L(z) = L_0 + L_1 z\) with \(L = L(1) = L_0 + L_1\) being an irreducible infinitesimal generator of the underlying Markov chain \([J(t)]\). The mean stationary service rate \(\mu^*\) of the C-MSP is given by \(\mu^* = \overline{e}_L\), where \(\overline{e} = \overline{[e_1, e_2, \ldots, e_m]}\) is the probability row vector which can be computed from \(\overline{e}L = 0\) with \(\overline{e}1 = 1\), where \(e\) is a column vector of ones with an appropriate dimension. The customers are served singly according to a C-MSP with an average stationary service rate \(\mu^*\). The offered load \(\rho\) is given by \(\rho = \lambda \overline{g}/\mu^*\).

In the following section, we obtain the actual waiting-time distribution for the first customer and an arbitrary customer of an arrival batch. In order to get the actual waiting-time distributions, we first obtain the prearrival epoch probability distribution of system-length at a prearrival epoch. For this, we proceed exactly in the same way as that discussed by Chaudhry et al. [5]. Let \(\pi_j^\ast(n)\) represent the prearrival epoch probability distribution of an arrival batch when there are \(n (\geq 1)\) customers in the system and the server is busy in phase \(j\). Also, let \(\pi_j^\ast(0)\) be the prearrival epoch probability that the system is empty while the server is idle in phase \(j\). Let \(\pi_j^\ast(n) (n \geq 1)\) be the row vector whose j-th \((1 \leq j \leq m)\) component is \(\pi_j^\ast(n)\). Also, let us assume \(\pi^\ast(z) = \sum_{n=0}^{\infty} \pi^\ast(n) z^n\) with \(\pi_j^\ast(z)\) being the j-th \(1 \leq j \leq m\) component of \(\pi^\ast(z)\). As presented in [5], \(\pi_j^\ast(z)\) is an analytic function of \(z\) for \(|z| \leq 1\). Thus, we have

\[
\pi_j^\ast(z) = \sum_{i=1}^{m} \frac{k_{ij}}{1 - y_i z}, \quad 1 \leq j \leq m, \tag{1}
\]

where \(k_{ij}\) are constants to be determined. Here, \(y_j (1 \leq i \leq m\overline{r})\) are the m\(\overline{r}\) roots inside the unit circle of the equation \(\det\left[I_{m\overline{r}} - G(z^{-1})\right]S(z) = 0\) with \(\overline{r}\) being the maximum size of an arrival batch, where \(S(z) = \sum_{n=0}^{\infty} S_n z^n = A^*(L(z))\) with \(|z| \leq 1\). The procedure of obtaining \(S_n\) is available in literature; e.g., see Appendix 2 of [5]. One may note that the computation of \(S(z)\) using above relation may be cumbersome. However, the following numerical scheme may be efficient and is given by \(S(z) = \lim_{\nu \to -\infty} \sum_{n=0}^{\infty} S_n z^n\), where \(S_n\) may be obtained as proposed in [5]. The equation \(\det\left[I_{m\overline{r}} - G(z)S(z^{-1})\right] = 0\) has m\(\overline{r}\) roots \(y\) inside the unit circle. That is, the equation \(\det\left[I_{m\overline{r}} - G(z)S(z^{-1})\right] = 0\) has m\(\overline{r}\) roots \(1/y\) outside the unit circle. Now, comparing the coefficient of \(z^n\) from both sides of (1), one may have the explicit values of \(\pi_j^\ast(n)\) \((1 \leq j \leq m, n \geq 0)\) in terms of \(y_j (1 \leq i \leq m\overline{r})\) and \(k_{ij} (1 \leq i \leq m\overline{r}, 1 \leq j \leq m)\); see Chaudhry et al. [5] for a detailed procedure.

3. Waiting-Time Analysis

In the following we obtain the probability density function (p.d.f.) of actual waiting time for the first and an arbitrary customer of an arrival batch. Let the \((i, j)\)-th entry of \(\phi_s\) be the LST of the service times of a total of \(k (\geq 1)\) customers and the corresponding phase change of the underlying Markov chain is from \(i\) to \(j\). The probability that the service of a customer is completed in the interval \((x, x + dx]\) along with phase changes is given by the matrix \(e^{\lambda x}L_1 dx + o(dx)\), where \(o(x)\) represents a function of \(x\) such that \(o(x)/x \to 0\) as \(x \to 0\). Since the LST of total service time of \(k\) customers \(\phi_k^s\) is the product of their individual LST each of service times \(\phi_1^s\) of those \(k\) customers, therefore,

\[
\phi_1^s(s) = \sum_{j=0}^{\infty} e^{-s\gamma_j} e^{\lambda x L_1 dx} = (sL_m - L_0)^{-1} L_1 \tag{2}
\]

and \(\phi_k^s(s) = \phi_1^s(s)^k, \quad k \geq 2,\)

where \(\Re(s) \geq 0\). Let \(W_r(x) = [W_{F_1}(x), W_{F_2}(x), \ldots, W_{F_{m\overline{r}}}(x)], x \geq 0\), denote the row vector of order \(m\), where \(W_{F_r}(x) (1 \leq r \leq m)\) represents the stationary joint probability that the first customer of an arrival batch has to wait up to a maximum of \(x\) units of time before getting served.
with the service process being in phase \( r \). The first customer in an arrival batch waits in the system at most \( x \) time units if and only if he sees upon arrival \( n \geq 0 \) customers ahead of him and so he has to wait for \((n+1)\) service completions including itself in the interval \((0, x)\). Similarly, we denote \( W_A^r(x) = [W_{A1}(x), W_{A2}(x), \ldots, W_{Am}(x)] \), \( x \geq 0 \), and \( W_L^r(x) = [W_{L1}(x), W_{L2}(x), \ldots, W_{Lm}(x)] \), \( x \geq 0 \), as probability vectors whose \( r \)-th component \( W_{Ai}(x) (1 \leq r \leq m) \) of \( W_A^r(x) \) denotes the stationary joint probability that an arbitrary customer in an arrival batch has to wait in the system a maximum of \( x \) units of time before departing the system with the service process being in phase \( r \). The \( r \)-th component \( W_{Lr}(x) (1 \leq r \leq m) \) of \( W_L^r(x) \) denotes the stationary joint probability that the last customer in an arrival batch has to wait in the system at most \( x \) units of time before getting served and departing the system with the phase of the service process being \( j \). Let \( W_F^r(s) = [W_{F1}^r(s), W_{F2}^r(s), \ldots, W_{Fn}^r(s)] \) be the LST of \( W_F^r(x) \). Similarly, let \( W_A^r(s) = [W_{A1}^r(s), W_{A2}^r(s), \ldots, W_{Am}^r(s)] \) and \( W_L^r(s) = [W_{L1}^r(s), W_{L2}^r(s), \ldots, W_{Lm}^r(s)] \) be the LSTs of \( W_A^r(x) \) and \( W_L^r(x) \), respectively. Hereafter, we need to define a random variable \( J \) which denotes the number of customers before an arbitrary customer in a batch. Following Chaudhry and Templeton [7], one may write \( g_r = P(J = r) = (1/g_r) \sum_{i=r+1} g_i, r \geq 0 \). Therefore, the LST of the waiting-time distribution after a little algebraic manipulation (see Chaudhry et al. [5]) may be derived as

\[
W_F^r(s) = \sum_{n=0}^{\infty} \pi^r(n) \phi_1^{n+1} = \pi^r(\phi_1(s)) \phi_1(s),
\]

\[
W_A^r(s) = \sum_{n=0}^{\infty} \pi^r(n) \sum_{j=0}^{\infty} g_j \phi_1^{n+j} = \frac{1}{g}
\]

\[
\cdot \pi^r(\phi_1(s)) (I_m - G(\phi_1(s))) (I_m - \phi_1(s))^{-1} \phi_1(s),
\]

\[
W_L^r(s) = \sum_{n=0}^{\infty} \pi^r(n) \sum_{j=1}^{\infty} \phi_1^{n+j} = \pi^r(\phi_1(s))
\]

\[
\cdot G(\phi_1(s)),
\]

with \( \Re(s) \geq 0 \). One can find component-wise mean waiting times in the system of the above three types

\[
(W_F = [W_{F1}, W_{F2}, \ldots, W_{Fn}]), \quad (W_A = [W_{A1}, W_{A2}, \ldots, W_{Am}]), \quad \text{and} \quad W_L = [W_{L1}, W_{L2}, \ldots, W_{Lm}],
\]

by differentiating the above formulae and putting \( s = 0 \). They are obtained after a little algebraic manipulation; see Chaudhry et al. [5] for explicit formulae of \( W_F, W_A, \) and \( W_L \). Using Little’s law, we can obtain mean sojourn time as \( W_{FL} = L_s/\lambda \), where \( L_s \) is the mean stationary system-length obtained in [5] and one may note that \( W_{FL} = W_F \) e while performing numerical computation. Also, one may simplify (3) as stated below. First combine the roots \( \gamma_i^r (1 \leq i \leq m^r) \) and \( [\phi_1(s)]^m \), yielding a geometric series, which are then summed over \( n \). As a consequence of the formula regarding geometric series, this sum is \( [I_m - \gamma \phi_1(s)]^{-1} \), and this expression is expanded, using the adjoint matrix and determinants (see also [9], (35), and Section A.1 for a proof of formula (6) given below).

\[
W_F^r(s) = \sum_{n=0}^{\infty} \pi^r(n) [\phi_1(s)]^n \phi_1(s)
\]

\[
= \sum_{n=0}^{\infty} \left[ \sum_{i=1}^{m^r} \sum_{j=1}^{m^r} \sum_{k=1}^{m^r} \sum_{l=1}^{m^r} \sum_{m=1}^{m^r} \right] \phi_1(s)]^n
\]

\[
\cdot \phi_1(s) = \left[ k_{11}, k_{12}, \ldots, k_{1m^r} \right] \left[ \begin{array}{c}
\text{adj} [I_m - \gamma_1 \phi_1(s)] \\
\text{det}[I_m - \gamma_1 \phi_1(s)]
\end{array} \right]
\]\n
\[
\cdot \phi_1(s) + \cdots
\]

\[
+ \left[ k_{m^r1}, k_{m^r2}, \ldots, k_{m^r m^r} \right] \left[ \begin{array}{c}
\text{adj} [I_m - \gamma_m m^r \phi_1(s)] \\
\text{det}[I_m - \gamma_m m^r \phi_1(s)]
\end{array} \right]
\]

\[
\cdot \phi_1(s),
\]

with \( \Re(s) \geq 0 \). In the following, we develop a numerical scheme for inverting the above LSTs component-wise. Let us first look at the \( r \)-th component of the LST given by formula (3) which is further simplified as (6). The right-hand side of (3) involves \( \pi^r(\phi_1(s)) \phi_1(s) \) which is further simplified as the right-hand side of (6). Both LSTs (3) and (6) are analytic in the region \( \Re(s) \geq 0 \). Therefore (as \( \phi_1(s) \) is the LST of the transition probability matrix of the underlying Markov chain of C-MSP), the \( r \)-th (\( 1 \leq r \leq m \)) component of \( \pi^r(\phi_1(s)) \phi_1(s) \) may be written as a rational function in \( s \), which is evident from the right-hand side of (6). Now, taking into account the zeros of the denominator of each \( m^r \) terms in the right-hand side of (6), we obtain \( m^r \) characteristic equations; namely,

\[
\text{det}[I_m - \gamma_1 \phi_1(s)] = 0, \quad 1 \leq j \leq m^r.
\]

Also, each element of the matrix \( \phi_1(s) = ([I_m - L_0]^{-1} L_1 = \text{adj}[sI_m - L_0] L_1/det[sI_m - L_0]) \) has denominator \( \text{det}[sI_m - L_0] \) which has \( m \) zeros in the region \( \Re(s) < 0 \) (see similar proof of Theorem 7.3 of [5]). As a result, \( \text{det}[I_m - \gamma_1 \phi_1(s)] (1 \leq j \leq m^r) \) has denominator \( \text{det}[sI_m - L_0] \) which has \( m^r \) zeros in the region \( \Re(s) < 0 \) for each \( j (1 \leq j \leq m^r) \). After canceling the common zeros of the numerator and the denominator of \( \text{det}[I_m - \gamma_1 \phi_1(s)] \times \text{det}[sI_m - L_0] (1 \leq j \leq m\) also has \( m^r \) zeros in the region \( \Re(s) < 0 \) for each \( j (1 \leq j \leq m^r) \). Let us define \( \tilde{s}_{ij} (1 \leq i \leq m, 1 \leq j \leq m^r) \) as the zeros of the denominator of each component of \( \pi^r(\phi_1(s)) \phi_1(s) \) in the region \( \Re(s) < 0 \). Also, it may be noted here that none of these zeros \( \tilde{s}_{ij} (1 \leq i \leq m, 1 \leq j \leq m^r) \) is equal to a zero of \( \text{det}[sI_m - L_0] \). Therefore, one may finally note that the denominator of the \( r \)-th component of the LST \( W_F^r(s) \) given by formula (3) which has \( m^r \) zeros: \( \tilde{s}_{ij} (1 \leq i \leq m, 1 \leq j \leq m^r) \)
with \( \Re(s) < 0 \). One may finally obtain the \( r \)th \((1 \leq r \leq m)\) component of \( W^* \) by using partial fractions as follows:

\[
W^*_r(s) = \sum_{i=1}^{m} \sum_{j=1}^{m} \frac{C^*_r}{s - \tilde{s}_j},
\]

(8)

where \( C^*_r(1 \leq i \leq m, 1 \leq j \leq m\tilde{r}, 1 \leq r \leq m)\) are constants to be evaluated and \( \Re(s) \geq 0 \). It may be remarked here that while making partial fractions, we have assumed that the roots \( \tilde{s}_j \) are distinct. To get the unknown constants, we use the required number of linear equations after substituting any positive values of \( s \) \((\Re(s) > 0)\) in (8). Finally, we equate the component-wise \( W^*_r(s) \) from (3) with (8) under the same positive values of \( s \). One may note that, as normalizing conditions, the component-wise values of \( W^*_r(0) \) and the components of \( W^*_r \) must be included in the set of linear equations to get the above constants. These components may be obtained by putting \( s = 0 \) in (8) and we may use \( W^*_r = -W^{*_1}\big|_{s=0} \) where \( W^{*_1} \) is the first differentiation of \( W^*_r(s) \) with respect to \( s \). After that, taking inverse Laplace transform of (8), component-wise explicit closed-form expression of probability density function (p.d.f.) \( w^*_r(x) \) is given by

\[
w^*_r(x) = \sum_{i=1}^{m} \sum_{j=1}^{m} C^*_r e^{s_i x},
\]

(9)

\( 1 \leq i \leq m, 1 \leq j \leq m\tilde{r}, 1 \leq r \leq m, \)

with \( x > 0 \). Finally, the p.d.f. of waiting time of the first customer may be obtained from \( w_m(x) = \sum_{i=1}^{m} w^*_r(x) \). From this, we can get \( W^*_r(u) = \int_{0}^{u} w^*_r(x)dx, (1 \leq r \leq m) \), and \( W^*_r = \int_{0}^{\infty} w^*_r(x)dx \).

Similar to the procedure followed earlier, we consider the zeros of the denominator of each element of the matrix \((I_m - G(\phi(1)))\) in (4). As discussed earlier, the denominator of each element of \( \phi(1) \) has \( m \) zeros in the region \( \Re(s) < 0 \) which may be obtained by solving \( \text{det}(I_m - L_m) = 0 \). This implies that, given maximum arrival batch size \( \tilde{r} \), \( m \) zeros of the denominator of each element of the matrix \((I_m - G(\phi(1)))\) are repeated up to \( \tilde{r} \) times. Let the \( m \) roots of \( \text{det}(I_m - L_m) = 0 \) be denoted by \( \tilde{s}_j (1 \leq i \leq m) \). Therefore, the denominator of each element of the matrix \((I_m - G(\phi(1)))\) has repeated roots \( \tilde{s}_j (1 \leq i \leq m) \) with multiplicity \( \tilde{r} \). Also, we have to investigate the zeros of the denominator of each element of the matrix \((I_m - \phi(1))^{-1}\). These zeros may be obtained by using \( \text{det}(I_m - \phi(1)) \). It can also be shown that there will be \( m\tilde{r} \) zeros of the numerator of \( \text{det}(I_m - \phi(1)) \) in the region \( \Re(s) \leq 0 \) (since \( s = 0 \) is root of the equation \( \text{det}(I_m - \phi(1)) = 0 \)). Also, there are \( m\tilde{r} \) zeros of the denominator (which is equal to \( \text{det}(I_m - \phi(1))^{-1} \)) of \( \text{det}(I_m - \phi(1)) \) in the region \( \Re(s) < 0 \) and they are \( \tilde{s}_j (1 \leq i \leq m) \) with multiplicity \( \tilde{r} \) each. After canceling the common zeros of the numerator and the denominator of \( \text{det}(I_m - \phi(1)) \), one is left with \( (m - 1) \) zeros of the numerator of \( \text{det}(I_m - \phi(1)) \) in the region \( \Re(s) < 0 \). Let these \( (m - 1) \) roots of the numerator of \( \text{det}(I_m - \phi(1)) \) be denoted by \( \tilde{r}_j (1 \leq i \leq m - 1) \), where \( \Re(\tilde{r}_j) < 0 \). Lastly, the roots of the denominator of each element of the matrix \( \phi(1) \) in the right-hand side of (4) are also \( \tilde{r}_j (1 \leq i \leq m) \). Finally, if we consider all the roots (with \( \Re(s) < 0 \)) of denominators involved in each element of the vector and matrices occurring in the right-hand side of (4), we reach the following conclusion: \( \tilde{r}_j (1 \leq i \leq m) \) roots repeated in the region \( \Re(s) < 0 \) with multiplicity \( (\tilde{r} - 1) \) occur in the denominator of each component of \( W^*_r(s) \) in (4). On the other hand \( \tilde{s}_j (1 \leq i \leq m \tilde{r}) \) and \( \tilde{r}_j (1 \leq i \leq m - 1) \) are the roots in the region \( \Re(s) < 0 \) that occur in the denominator of each component of \( W^*_r(s) \) in (4). Following this conclusion, after using partial fractions, we may write the \( r \)-th \((1 \leq r \leq m)\) component of \( W^*_r(s) \) in (4) which also has factor \( \phi^* \) as follows:

\[
W^*_r(s) = \sum_{i=1}^{\tilde{r} - 1} \sum_{j=1}^{m} \frac{C^*_r}{s - \tilde{s}_j} + \sum_{i=1}^{m\tilde{r}} \frac{D^*_r}{s - \tilde{s}_j} + \sum_{i=1}^{m - 1} \frac{H^*_r}{s - \tilde{r}_j},
\]

(10)

where \( C^*_r (1 \leq i, r \leq m, 1 \leq n \leq \tilde{r} - 1) \), \( D^*_r (1 \leq i, r \leq m, 1 \leq i \leq m\tilde{r}) \), and \( H^*_r (1 \leq r \leq m, 1 \leq i \leq m - 1) \) are constants to be evaluated and \( \Re(s) \geq 0 \). It may be remarked here that while making partial fractions, we have assumed that the roots \( \tilde{r}_j \) and \( \tilde{s}_j \) are distinct. If they are repeated, a slight modification in partial fraction will be needed. Also, throughout the above discussions of roots, we discard any roots of the denominator of the above LSTs (3)-(5) in the region \( \Re(s) \geq 0 \). The roots of the denominator with \( \Re(s) \geq 0 \) must be canceled with numerator as the LSTs are analytic in the region \( \Re(s) \geq 0 \).

Now to obtain the unknown constants, we use the required number of linear equations after substituting any positive values of \( s \) in (10). Finally, we equate the components of \( W^*_r(s) \) from (4) with the corresponding component of (10) under the same positive values of \( s \). One may note that, as normalizing conditions, the component-wise values of \( W^*_r(0) \) and the components of \( W^*_r \) must be included in the set of linear equations to get the above constants. These components may be obtained by putting \( s = 0 \) in (10) and we may use \( W^*_r = -W^{*_1}\big|_{s=0} \), where \( W^{*_1}(s) \) is the first differentiation of \( W^*_r(s) \) with respect to \( s \). After that, taking inverse Laplace transform of (10), component-wise explicit closed-form expression of probability density function (p.d.f.) \( w^*_r(x) \) is given by

\[
w^*_r(x) = \sum_{i=1}^{\tilde{r} - 1} \sum_{j=1}^{m} \frac{C^*_r x^{j}}{(m - 1)!} + \sum_{i=1}^{m\tilde{r}} \frac{D^*_r x^{j}}{(m - 1)!} + \sum_{i=1}^{m - 1} \frac{H^*_r x^{j}}{(m - 1)!},
\]

(11)

with \( x > 0 \). Finally, the p.d.f. of waiting time of an arbitrary customer may be obtained by \( w^*_m(x) = \sum_{i=1}^{m} w^*_r(x) \). Further, let us denote the component-wise and total distribution function of the waiting-time distribution of an arbitrary
customer of an arrival batch by \( W_A(u) = \int_0^u w_A(x)dx \), \( 1 \leq r \leq m \), and \( W_A(u) = \int_0^u w_A(x)dx \). It may be finally noted that \( \lim_{z \to \infty} W_A(z) = \) the component-wise p.d.f. of waiting times in the system.

In Figure 1, we have plotted the component-wise densities along with the total waiting-time density \( \w_A(x) \) as given in (10). Finally, using inverse Laplace-transforms we have obtained the component-wise p.d.f. of waiting times in the system of an arbitrary customer in a PH\(^X\)/C-MSP/1/\( \infty \) queueing system using the numerical scheme presented in Section 3. The PH-type interbatch arrival time is given by \( \alpha = [0.35 \ 0.65] \) and \( T = \left[ \begin{array}{cc} -1.183 \ 2.423 \\ 1.367 \ -2.896 \end{array} \right] \) with \( \lambda = 0.032317 \). The batch size distribution is given by \( g_1 = 0.0, g_2 = 0.0, g_3 = 0.5, \) and \( g_4 = 0.5, g_5 = 0.0 \) with mean batch size \( \Psi = 3.5 \). The C-MSP matrices having positive lag-1 correlation coefficient 0.271908 as

\[
\begin{bmatrix}
-0.5424095190 & 0.0037279000 & 0.0000000000 \\
0.0043492170 & -0.0229887200 & 0.0006213170 \\
0.0000000000 & 0.012426330 & -2.2696700720
\end{bmatrix}
\]

with stationary mean service rate \( \mu^* = 0.500000 \) and \( \rho = 0.226216 \). The characteristic roots to obtain the system-length distribution at a prearrival epoch are calculated through the nonlinear algebraic equation:

\[
\det \left( \mathbf{I}_m z^\mathbf{I} - \left[ \begin{array}{c} g_1 z^{\mathbf{I}-1} + g_2 z^{\mathbf{I}-2} + g_3 z^{\mathbf{I}-3} + g_4 \end{array} \right] \mathbf{S}(z) \right) = 0,
\]

where \( m = 3, \mathbf{I} = 4 \) and \( g_j (i \geq 1) \) are given above and \( \mathbf{S}(z) \) may be obtained by (12); see Theorem 7.5 of [5]. The \( m\mathbf{I} = 12 \) roots of (14) inside \( |z| < 1 \) are evaluated and the corresponding \( k_{ij} (1 \leq i \leq 12, 1 \leq j \leq 3) \) values are calculated using Section 2 where the prearrival epoch probabilities are derived. Details of the characteristic equations and their roots used for the evaluation of waiting-time densities are available with the authors and may be supplied upon specific request to the authors. After computation of the required roots, we construct partial fractions for each component of \( \mathbf{W}_A(z) \) as given in (10). Finally, using inverse Laplace-transforms we obtain component-wise p.d.f. of waiting times in the system.

4. Numerical Results

Using the results formulated in the previous section, some numerical results are presented in this section. Although numerical calculations were carried out with high precision, due to lack of space the results have been reported to 6 decimal places. Since various distributions can be either represented or approximated by PH-distribution, we take interbatch arrival time distribution to be of PH-type having the representation \( (\alpha, \mathbf{T}) \), where \( \alpha \) and \( \mathbf{T} \) are of dimension \( \nu \). Then using the procedure adopted by Chaudhry et al. [5], \( \mathbf{S}(z) \) can be derived as follows:

\[
\mathbf{S}(z) = (\mathbf{I}_m \otimes \mathbf{z}) (\mathbf{L}(z) \oplus \mathbf{T})^{-1} (\mathbf{I}_m \otimes \mathbf{T}_e),
\]

with \( \mathbf{L}(z) \oplus \mathbf{T} = (\mathbf{L}(z) \otimes \mathbf{I}_e) + (\mathbf{I}_m \otimes \mathbf{T}) \), where \( \otimes \) and \( \oplus \) are Kronecker product and sum, respectively. For the derivation of \( \mathbf{S}(z) \), see Theorem 7.5 in [5]. For more discussion on the derivation of \( \mathbf{S}(z) \), see [5]. Numerical computations were performed on a PC having Intel(R) Core i5 processor @1.8 GHz with 4 GB DDR3 RAM using MAPLE 2015.

4.1. The Waiting-Time Analysis of a PH\(^X\)/C-MSP/1/\( \infty \) Queueing System. In Figure 1, we have computed and plotted the component-wise p.d.f. of waiting times in the system of an arbitrary customer in a PH\(^X\)/C-MSP/1/\( \infty \) queueing system using the numerical scheme presented in Section 3. The PH-type interbatch arrival time is given by \( \alpha = [0.35 \ 0.65] \) and \( T = \left[ \begin{array}{cc} -1.183 \ 2.423 \\ 1.367 \ -2.896 \end{array} \right] \) with \( \lambda = 0.032317 \). The batch size distribution is given by \( g_1 = 0.0, g_2 = 0.0, g_3 = 0.5, \) and \( g_4 = 0.5, g_5 = 0.0 \) with mean batch size \( \Psi = 3.5 \). The C-MSP matrices having positive lag-1 correlation coefficient 0.271908 as

\[
\begin{bmatrix}
-0.5424095190 & 0.0037279000 & 0.0000000000 \\
0.0043492170 & -0.0229887200 & 0.0006213170 \\
0.0000000000 & 0.012426330 & -2.2696700720
\end{bmatrix}
\]

with stationary mean service rate \( \mu^* = 0.500000 \) and \( \rho = 0.226216 \). The characteristic roots to obtain the system-length distribution at a prearrival epoch are calculated through the nonlinear algebraic equation:

\[
\det \left( \mathbf{I}_m z^\mathbf{I} - \left[ \begin{array}{c} g_1 z^{\mathbf{I}-1} + g_2 z^{\mathbf{I}-2} + g_3 z^{\mathbf{I}-3} + g_4 \end{array} \right] \mathbf{S}(z) \right) = 0,
\]

where \( m = 3, \mathbf{I} = 4 \) and \( g_j (i \geq 1) \) are given above and \( \mathbf{S}(z) \) may be obtained by (12); see Theorem 7.5 of [5]. The \( m\mathbf{I} = 12 \) roots of (14) inside \( |z| < 1 \) are evaluated and the corresponding \( k_{ij} (1 \leq i \leq 12, 1 \leq j \leq 3) \) values are calculated using Section 2 where the prearrival epoch probabilities are derived. Details of the characteristic equations and their roots used for the evaluation of waiting-time densities are available with the authors and may be supplied upon specific request to the authors. After computation of the required roots, we construct partial fractions for each component of \( \mathbf{W}_A(z) \) as given in (10). Finally, using inverse Laplace-transforms we obtain component-wise p.d.f. of waiting times in the system. In Figure 1, we have plotted the above three component-wise densities along with the total waiting-time density function \( \w_A(x) \) against \( x \). Figure 1 shows that component-wise density of waiting time behaves significantly different from that of \( \w_A(x) \). Also, in Figure 2, we have plotted the corresponding component-wise distribution function as well as total distribution function against time. Similar behaviour may be observed in the case of DFs, which is what is expected.

4.2. The Waiting-Time Analysis of a Pareto\(^X\)/C-MSP/1/\( \infty \) Queueing System. In Figure 3, we have repeated similar experiment as given in above figures; i.e., we plotted component-wise p.d.f.s against time in a Pareto\(^X\)/C-MSP/1/\( \infty \)
queue, where \textit{Pareto} stands for Pareto distribution whose probability density function and distribution functions are given by \( a(x) = \alpha a^\alpha / (a + x)^{\alpha + 1} \), \( \alpha = 0.3 \), \( a = 2.3 \), \( x \geq 0 \), and \( A(x) = 1 - a^\alpha / (a + x)^\alpha \), \( x > 0 \), respectively, with shape parameter \( \alpha \) and scale parameter \( a \). Batch size distribution is taken arbitrary with probability generating function \( G(z) = 0.1z^2 + 0.1z^3 + 0.8z^4 \) and mean batch size \( \overline{\gamma} = 3.7 \). The service matrices having positive lag-1 correlation coefficient 0.018690 are taken as

\[
\begin{bmatrix}
-2.156750 & 0.007125 & 0.00 \\
0.149625 & -0.171000 & 0.007125 \\
0.007125 & 0.007125 & -2.443000
\end{bmatrix},
\]

(15)

with \( \mu^* = 1.540543 \) and \( \overline{\pi} = [0.343750 \ 0.328125 \ 0.328125] \). One may note that the moments do not exist for this case of Pareto interbatch arrival time distribution. From this Pareto distribution function \( A(x) \) (through equating \( A(x) = 0.5 \)), we calculate median which is equal to 20.882547.

The Padé approximation [4/5] of (16) is given as follows:

\[
A^*(s) \approx 1.0 - 0.303449s + 104.611371s^2 + 16.029743s^3 + 790.04091s^4 \\
1.0 + 20.503315s + 189.254931s^2 + 998.209224s^3 + 3069.401520s^4 + 4521.877843s^5.
\]

(17)
4.3. Comparison of the Numerical Results Obtained through Roots and Matrix-Geometric Method. In this section we made a thorough numerical comparison of our results with that of Samanta [12] and our computed results are appended in Table 1. For this comparison, we have obtained component-wise waiting-time distribution function (using the procedure discussed in Section 3) of an infinite-buffer \( G_I/C_{-}MSP/1 \) queueing model with parameters given in Table 2 of [12]. For the same queueing model, we have obtained waiting-time (in system) distribution function (using the procedure discussed in Section 3) which was presented in Table 2 of [12] using matrix-geometric method. As expected, in both the above cases, the results were matched up to six decimal places against Table 2 of [12]. In Table 1, we have presented first seven and the last values of the distribution function. For this experiment, \( C\)-MSP service matrices with positive lag-1 correlation coefficient 0.5381025 are taken as

\[
L_0 = \begin{bmatrix}
-15.449000 & 0.116000 & 0.052000 & 0.000000 \\
0.092000 & -5.069000 & 0.000000 & 0.062000 \\
0.000000 & 0.213000 & -4.832000 & 4.430000 \\
0.059000 & 5.033000 & 0.000000 & -5.321000
\end{bmatrix},
\]

\[
L_1 = \begin{bmatrix}
15.068000 & 0.157000 & 0.000000 & 0.056000 \\
0.123000 & 0.047000 & 4.745000 & 0.000000 \\
0.084000 & 0.000000 & 0.000000 & 0.105000 \\
0.051000 & 0.000000 & 0.077000 & 0.101000
\end{bmatrix},
\]

with stationary mean service rate \( \mu^* = 5.388016 \) and \( \pi = [0.264645 \ 0.253046 \ 0.254961 \ 0.227348] \). The interarrival time is phase-type whose representation was taken as

\[
\alpha = [0.22 \ 0.33 \ 0.45],
\]

\[
T = \begin{bmatrix}
-7.423 & 0.000 & 3.812 \\
8.542 & -9.942 & 1.000 \\
5.210 & 0.000 & -8.640
\end{bmatrix},
\]

with \( \lambda = 3.198147 \) which gives \( \rho = 0.593567 \). It may be noted here that for an infinite-buffer \( G_I/C_{-}MSP/1 \) queue the expression for LST of waiting-time distribution of an arriving customer is the same as \( W_0^*(s) = W_A(s) \) which is given in (3) and for the sake of notational convenience we may denote this as \( W_A(s) \).

In Figures 5 and 6, we have plotted the probability densities and distribution functions, respectively, against time for the queueing model discussed in Table 1.

5. Conclusion

In this paper, we analyze the waiting-time distribution of the \( GI^{(X)}/C_{-}MSP/1/\infty \) queue and obtain steady-state probability distribution of the waiting time of the first customer and an arbitrary customer of an arrival batch. The proposed method is based on the roots of a characteristic equation involved in finding probability distribution at a prearrival epoch. After that, we use prearrival epoch probabilities and the roots of a set of characteristic equations involved in the LSTs of the waiting time for the first customer and an arbitrary customer of an arrival batch. Besides the computational advantages in terms of time, this method has other advantages over the matrix-geometric method in the sense that it is accurate even if one does not use all the roots. For example, the values of the distribution function presented in Table 1 of the previous section may be obtained (with an accuracy of up to 6 decimal places) by just using the first 8 roots from the list of \( m^2 = 16 \) roots. As a consequence, we may obtain good approximate
matrix equation. Similar procedure may be used to obtain the computed through the nonnegative solution of a nonlinear method for computation of the 

Section A.2. This procedure may serve as an alternative type Markov chain with a desired level of accuracy; see

can compute the "matrix of the corresponding set-up timewith or without vacation(s). These problems may attract researchers' attention in the future.

Appendix

A. A Proof and Some Additional Numerical Results Related to the Paper Using Roots

A.1. Proof of Formula (6) of the Paper

\[ W_{f}^n (s) = \sum_{n=0}^{\infty} \pi (n) [\phi_1 (s)]^n \phi_1 (s) \]

\[ = \sum_{n=0}^{\infty} \left[ k_{11}^{n} \gamma_1 \sum_{i=1}^{m} \left( \sum_{j=1}^{m} \sum_{k=1}^{m} \cdots \right) \right] [\phi_1 (s)]^n \phi_1 (s) \]

\[ + \sum_{n=0}^{\infty} \left[ k_{21}^{n} \gamma_2 \cdots \right] [\phi_1 (s)]^n \phi_1 (s) + \cdots \]

\[ + \sum_{n=0}^{\infty} \left[ k_{m1}^{n} \gamma_m \cdots \right] [\phi_1 (s)]^n \phi_1 (s) \]

(A.1)

which yields the result (6).

A.2. Demonstration of a Simple Computational Procedure for "R" Matrix (Used in Matrix-Geometric Method) Related to the Queueing Model GI/C-MSP/1/∞ of the Paper Using Roots. As discussed by Neuts [10], the stationary probabilities at an embedded prearrival epoch in a GI/M/1-type Markov chain may be obtained in matrix-geometric forms. That is, for a GI/M/1-type Markov chain Neuts [10] showed that there exists a nonnegative matrix "R" with appropriate dimension such that the stationary probability vectors at an embedded prearrival epoch are given by \( \pi (s) / \pi (0) R^n, n \geq 0, \) where the matrix "R" has spectral radius < 1 in case of a positive recurrent Markov chain and the matrix "R" may be computed as a nonnegative solution of a nonlinear matrix equation (see below). Gail et al. [9] proved that the eigenvalues of the "R" matrix are related to the characteristic roots of the

waiting-time distribution using less number of roots. Finally, we discuss a simple computational procedure (based on the solution of a set of simultaneous linear equations) which can compute the "R" matrix of the corresponding GI/M/1-type Markov chain with a desired level of accuracy; see Section A.2. This procedure may serve as an alternative method for computation of the R matrix which is usually computed through the nonnegative solution of a nonlinear matrix equation. Similar procedure may be used to obtain the
corresponding GI/M/1-type Markov chain. In the following a simple computation procedure for obtaining the "R" matrix as a solution of a set of simultaneous linear equations has been proposed for GI/C-MSP/1/oo and GI/\[X]/C-MSP/1/oo queueing models.

First, we explain this computational procedure for computing the R matrix in the case of GI/C-MSP/1/oo queueing model presented in Table I. Following [10], the stationary probability vectors at an embedded Markov prearrival epoch are given below. Since we have assumed \( \rho = \lambda / \mu < 1 \) and the Markov chain \( \xi_t \) is irreducible, there exists the minimal nonnegative solution \( R = [R_{ij}]_{m \times m} \) (m = 4) of the matrix equation \( R = \sum_{k=0}^{\infty} R^k S_k \), where \( R \) is strictly positive and of spectral radius less than one. The matrix \( R \) can be calculated by an iterative scheme given below:

\[
R(i + 1) = \left( S_0 + \sum_{k=2}^{\infty} R^k \right) (1 - S_i)^{-1}, \quad (A.2)
\]

where \( R(i) \) is the value of \( R \) at the \( i \)th iteration. The invariant probability vector of the Markov chain \( \xi_k \) is obtained by

\[
\pi^-(k) = \pi^-(0) R^k, \quad k \geq 0, \quad (A.3)
\]

where \( \pi^-(0) \) is obtained by solving the left eigenvector of the matrix \( B[R] = \sum_{k=1}^{\infty} R^{k-1} S_k \) with the normalizing condition \( \pi^-(0)[I_m - R]^T e = 1 \). Now we obtain the roots of the characteristics equation \( \det[I_m - R(\lambda)] = 0 \), as \( \gamma_1 = 0.180975, \gamma_2 = 0.944434, \gamma_3 = 0.278271 + 0.075281i, \) and \( \gamma_4 = 0.278271 - 0.075281i \). Thereafter, we get the stationary probability vectors \( \pi^-(n), n \geq 0 \), at an embedded prearrival epoch using the roots \( \gamma_1, \gamma_2, \gamma_3, \) and \( \gamma_4 \). One may note that in this case the \( R \) has dimension 4 \( \times \) 4, i.e., 16 unknown elements, and they may be obtained by solving the following 16 simultaneous linear equations derived from (A.3) as follows:

\[
\begin{align*}
\pi^-(1) &= \pi^-(0) R, \quad (A.4) \\
\pi^-(2) &= \pi^-(1) R, \quad (A.5) \\
\pi^-(3) &= \pi^-(2) R, \quad (A.6) \\
\pi^-(4) &= \pi^-(3) R. \quad (A.7)
\end{align*}
\]

Equating \( \pi^-(i), i = 1, 2, 3, 4 \), and (A.4)-(A.7) component-wise, we obtain the 16 simultaneous equations with 16 elements of the \( R \) matrix as variables. After solving these 16 simultaneous linear equations with 16 unknown elements of the matrix \( R \), we obtain the \( R \) matrix as follows:

\[
R = \begin{bmatrix}
0.182617 & 0.005479 & 0.004615 & 0.002830 \\
0.061297 & 0.431499 & 0.157426 & 0.090092 \\
0.131600 & 0.228110 & 0.590780 & 0.335155 \\
0.102322 & 0.318496 & 0.209492 & 0.477055
\end{bmatrix}. \quad (A.8)
\]

The correctness of the \( R \) matrix is checked by computing the eigenvalues of \( R \) given in (A.8) and the eigenvalues are obtained as 0.180975, 0.944434, 0.278271 + 0.075281i, and 0.278271 - 0.075281i which are exactly the same as the characteristic roots. Also, we obtained \( R \) matrix using iterative scheme (A.2) and found that the \( R \) matrix is exactly the same as that given in (A.8) after 150 iterations.

Next, we investigate the same computational procedure for computing the \( R \) matrix in the case of GI/[X]/C-MSP/1/oo queueing model presented in Section 4.1. It may be noted here that for the case of GI/[X]/C-MSP/1/oo queueing model as discussed by Neuts [10] (Remarks on bottom of pg. 189), the \( R = [R_{ij}]_{m \times m} \) (m = 3, \( \bar{r} = 4 \)) may be solved by the following set of simultaneous linear equations.

\[
\begin{align*}
\pi^-(4 \times k), \pi^-(4 \times k + 1), \pi^-(4 \times k + 2), \\
\pi^-(4 \times k + 3) &= [\pi^-(4 \times (k - 1))], \\
\pi^-(4 \times (k - 1) + 1), \pi^-(4 \times (k - 1) + 2), \\
\pi^-(4 \times (k - 1) + 3)] R, \quad 1 \leq k \leq 12.
\end{align*}
\]

One may note that for this case the \( R \) matrix obtained in this manner has a spectral radius less than

\[
\begin{bmatrix}
0.081741 & 0.001970 & \cdots & 0.000968 \\
0.009819 & 0.309779 & \cdots & 0.002166 \\
0.001323 & 0.000346 & \cdots & 0.002384 \\
0.026384 & 0.004028 & \cdots & 0.049990
\end{bmatrix}. \quad (A.10)
\]

Here the eigenvalues of the \( R \) matrix are not the same as the characteristics roots in this case. The eigenvalues of \( R \) are given by 0.027661, 0.046758, 0.070065, 0.111779, 0.163563, 0.833729, 0.046207 + 0.023748i, 0.046207 - 0.023748i, 0.067628 + 0.035876i, 0.067628 - 0.035876i, 0.196019 + 0.246307i, and 0.196019 - 0.246307i. Also, we have checked that this \( R \) satisfies any of the following equations:

\[
\begin{align*}
\pi^-(4 \times k), \pi^-(4 \times k + 1), \pi^-(4 \times k + 2), \\
\pi^-(4 \times k + 3) &= [\pi^-(0), \pi^-(1), \pi^-(2), \pi^-(3)] [\pi^-(4 \times k + 1) + 2], \\
\pi^-(4 \times k + 3)] R, \quad 1 \leq k \geq 0.
\end{align*}
\]

Therefore, by the above simple computational procedure, one may compute the \( R \) matrix of the corresponding GI/[X]/M/1-type using the stationary probabilities (obtained through characteristic roots) at an embedded prearrival epoch.

**Data Availability**

The data used to support the findings of this study are available from the corresponding author upon request.
Conflicts of Interest

The authors declare that they have no conflicts of interest.

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