Corrigendum

Corrigendum to “A Wearable Robotic Device Based on Twisted String Actuation for Rehabilitation and Assistive Applications”

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In the article titled “A Wearable Robotic Device Based on Twisted String Actuation for Rehabilitation and Assistive Applications” [1], in the “4.2. TSA Design Validation” section, the text reading “The maximum deformation with the maximum load of 80 N is $\Delta X_{\max} \approx 1.08 \cdot 10^{-4}$ m indicating the compliant frame deformation is within the goal working region $\Delta d < 0.12$ mm and can be considered linear.” should be corrected as follows.

“The maximum deformation with the maximum load of 80 N is $\Delta X_{\max} \approx 2.34 \cdot 10^{-4}$ m indicating the compliant frame deformation is within the goal working region $\Delta d < 0.12$ mm and can be considered linear.”

References

- [1] M. Hosseini, R. Meattini, G. Palli, and C. Melchiorri, “A wearable robotic device based on twisted string actuation for rehabilitation and assistive applications,” *Journal of Robotics*, vol. 2017, Article ID 3036468, 11 pages, 2017.