Research Article

The Simplified Tikhonov Regularization Method for Identifying the Unknown Source for the Modified Helmholtz Equation

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This paper discusses the problem of determining an unknown source which depends only on one variable for the modified Helmholtz equation. This problem is ill-posed in the sense that the solution (if it exists) does not depend continuously on the data. The regularization solution is obtained by the simplified Tikhonov regularization method. Convergence estimate is presented between the exact solution and the regularization solution. Moreover, numerical results are presented to illustrate the accuracy and efficiency of this method.

1. Introduction

Inverse source problems arise in many branches of science and engineering, for example, heat conduction, crack identification, electromagnetic theory, geophysical prospecting, and pollutant detection. For the heat source identification, there has been a large number of research results for different forms of heat source [1–6]. To the author’s knowledge, there were few papers for identifying the unknown source on the modified Helmholtz equation which is pointed out in [7] by regularization method.

In this paper, we consider the following inverse problem: to find a pair of functions \((u(x, y), f(x))\) satisfying

\[
\Delta u(x, y) - k^2 u(x, y) = f(x), \quad 0 < x < \pi, \quad 0 < y < +\infty,
\]

\[
u(0, y) = u(\pi, y) = 0, \quad 0 \leq y < +\infty,
\]
\[ u(x, 0) = 0, \quad 0 \leq x \leq \pi, \]
\[ u(x, y) \big|_{y \to \infty} \text{ bounded}, \quad 0 \leq x \leq \pi, \]
\[ u(x, 1) = g(x), \quad 0 \leq x \leq \pi, \]

(1.1)

where \( f(x) \) is the unknown source depending only on one spatial variable, \( u(x, 1) = g(x) \) is the supplementary condition, and the constant \( k > 0 \) is the wave number. In applications, input data \( g(x) \) can only be measured, and there will be measured data function \( g^\delta(x) \) which is merely in \( L^2(0, \pi) \) and satisfies

\[ \| g - g^\delta \|_{L^2(0, \pi)} \leq \delta, \]

(1.2)

where the constant \( \delta > 0 \) represents a noise level of input data.

It is easy to derive a solution of problem (1.1) by the method of separation of variables

\[ u(x, y) = -\sum_{n=1}^{\infty} \frac{1 - e^{-\sqrt{n^2 + k^2} y}}{n^2 + k^2} f_n X_n, \]

(1.3)

where

\[ X_n = \sqrt{\frac{2}{\pi}} \sin nx, \quad (n = 1, 2, \ldots) \]

(1.4)

is an orthogonal basis in \( L^2(0, \pi) \), and

\[ f_n = \sqrt{\frac{2}{\pi}} \int_{0}^{\pi} f(x) \sin nx \, dx. \]

(1.5)

By the supplementary condition, we define the operator \( K : f \to g \), then we have

\[ g(x) = K f(x) = -\sum_{n=1}^{\infty} \frac{1 - e^{-\sqrt{n^2 + k^2} y}}{n^2 + k^2} f_n X_n. \]

(1.6)

It is easy to see that \( K \) is a linear compact operator and the singular values \( \{ \sigma_n \}_{n=1}^{\infty} \) of \( K \) satisfy

\[ \sigma_n = \frac{1 - e^{-\sqrt{n^2 + k^2}}}{n^2 + k^2}, \]

(1.7)

\[ \mathbf{g}_n = \frac{1 - e^{-\sqrt{n^2 + k^2}}}{n^2 + k^2} f_n(X_n, X_n), \]

that is,

\[ f_n = \sigma_n^{-1} \mathbf{g}_n, \]

(1.8)
where
\[ g_n = \sqrt{\frac{2}{\pi}} \int_0^\pi g(x) \sin nx \, dx. \]  
(1.9)

Therefore,
\[ f(x) = K^{-1} g(x) = \sum_{n=1}^\infty \frac{1}{\sigma_n} (g, X_n) X_n = -\sum_{n=1}^\infty \frac{n^2 + k^2}{1 - e^{-\sqrt{n^2 + k^2}}} \sigma_n X_n. \]  
(1.10)

Note that \( 1/\sigma_n = O(n^2) \) as \( n \to \infty \), thus the exact data function \( g(x) \) must satisfy the property that \( (g, X_n) \) decays rapidly as \( O(n^{-2}) \). As for the measured data function \( g^\delta(x) \) is only in \( L^2(0, \pi) \), we cannot expect the coefficient \( g^\delta \) of \( g^\delta(x) \) has the same decay rate. Thus, the problem (1.1) is ill posed. It is impossible to gain the unknown source using classical methods. In the following sections, we will use the simplified Tikhonov method to deal with the ill posed problem. Before doing that, we impose an a priori bound on the unknown source; that is,
\[ \|f(\cdot)\|_{H^p(0,\pi)} \leq E, \quad p > 0, \]  
(1.11)

where \( E > 0 \) is a constant and \( \| \cdot \|_{H^p(0,\pi)} \) denotes the norm in Sobolev space which is defined by [8] as follows:
\[ \|f(\cdot)\|_{H^p(0,\pi)} = \left( \sum_{n=1}^\infty \left( 1 + n^2 \right)^p \left| (f, X_n) \right|^2 \right)^{1/2}. \]  
(1.12)

The simplified Tikhonov regularization method was based on the Tikhonov regularization method. Skillfully simplifying the filter gained by the Tikhonov regularization, a better regularization approximation solution of the inverse problem was obtained. This idea initially came from Carasso, the author who modified the filter gained by the Tikhonov regularization method and obtained the order optimal error estimate in [9]. By this method, Fu [10] considered the inverse heat conduction problem on a general sideways parabolic equation, and Cheng et al. [11, 12] considered the spherically symmetric inverse problem.

This paper is organized as follows. Section 2 gives some auxiliary results. Section 3 gives a simplified Tikhonov regularization solution and error estimation. Section 4 gives two examples to illustrate the accuracy and efficiency of this methods. Section 5 puts an end to this paper with a brief conclusion.

### 2. Some Auxiliary Results

Now, we give some important Lemmas, which are very useful for our main conclusion.

**Lemma 2.1.** For \( n \geq 1 \) and \( k \) is a positive constant, there holds
\[ \frac{1}{1 - e^{-\sqrt{n^2 + k^2}}} \leq 2. \]  
(2.1)
Lemma 2.2. For $0 < \alpha < 1$, there holds the following inequalities:

$$
\sup_{n \geq 1} \left( 1 - \frac{1}{1 + \alpha^2 n^4} \right) \left( 1 + n^2 \right)^{-p/2} \leq \max\{ \alpha^2, \alpha^{p/2} \},
$$

$$
\sup_{n \geq 1} \frac{n^2 + k^2}{\left( 1 - e^{-\sqrt{n^2 + k^2}} \right) \left( 1 + \alpha^2 n^4 \right)} \leq \frac{2}{\alpha} + 2k^2.
$$

Proof. Let

$$
G(n) := \left( 1 - \frac{1}{1 + \alpha^2 n^4} \right) \left( 1 + n^2 \right)^{-p/2}.
$$

The proof of (2.2) can be separated from two cases.

Case 1. For large values of $n$, that is, $n \geq n_0 := 1/\sqrt{\alpha}$, we get

$$
G(n) \leq \left( 1 + n^2 \right)^{-p/2} \leq n^{-p} \leq n_0^{-p} = \alpha^{p/2}.
$$

Case 2. $1 \leq n < n_0$, we obtain

$$
G(n) = \frac{\alpha^2 n^4}{1 + \alpha^2 n^4} \left( 1 + n^2 \right)^{-p/2} \leq \alpha^2 n^4 \left( 1 + n^2 \right)^{-p/2} \leq \alpha^2 n^{4-p}.
$$

If $0 < p \leq 4$, above inequality becomes into

$$
G(n) \leq \alpha^2 n^{4-p} < \alpha^2 n_0^{4-p} = \alpha^{p/2}.
$$

If $p > 4$, we get

$$
G(n) \leq \alpha^2 n^{4-p} \leq \alpha^2.
$$

Combining (2.4) with (2.6) and (2.7), the first inequality equation is obtained. Let

$$
B(n) := \frac{n^2 + k^2}{\left( 1 - e^{-\sqrt{n^2 + k^2}} \right) \left( 1 + \alpha^2 n^4 \right)}
$$

$$
= \frac{n^2}{\left( 1 - e^{-\sqrt{n^2 + k^2}} \right) \left( 1 + \alpha^2 n^4 \right)} + \frac{k^2}{\left( 1 - e^{-\sqrt{n^2 + k^2}} \right) \left( 1 + \alpha^2 n^4 \right)}
$$

$$
:= H(n) + J(n).
$$
Using Lemma 1, we obtain

\[ H(n) \leq \frac{2n^2}{1 + \alpha^2 n^4}. \tag{2.9} \]

Let

\[ L(n) := \frac{2n^2}{1 + \alpha^2 n^4}, \tag{2.10} \]

then

\[ L'(n) = \frac{4n(1 - \alpha^2 n^4)}{(1 + \alpha^2 n^4)^2}. \tag{2.11} \]

Setting \( L'(n) = 0 \), we can obtain \( n_1 = 1/\sqrt{\alpha} \). It is easy to see that \( n_1 = 1/\sqrt{\alpha} \) is a unique maximal value point of \( L(n) \).

So,

\[ L(n) \leq \frac{2n_1^2}{1 + \alpha^2 n_1^4} \leq 2n_1^2 = \frac{2}{\alpha}, \tag{2.12} \]

\[ J(n) \leq \frac{k^2}{1 - e^{-\alpha n_1 k}} \leq 2k^2. \]

So, we get

\[ B(n) \leq \frac{2}{\alpha} + 2k^2. \tag{2.13} \]

This completes the proof. \( \square \)

### 3. A Simplified Tikhonov Regularization Method

Since problem (1.1) is an ill-posed problem, we give an approximate solution of \( f(x) \) by a Tikhonov regularization method which minimizes the quantity

\[ \| K f^\delta - g^\delta \|^2 + \alpha^2 \| f^\delta \|^2. \tag{3.1} \]

Then, by Theorem 2.12 in [8], the unique solution of the minimization problem (3.1) is equal to solve the following normal equation:

\[ K^* K f^\delta(x) + \alpha^2 f^\delta(x) = K^* g^\delta(x), \tag{3.2} \]

that is,

\[ f^\delta(x) = \left[ K^* K + \alpha^2 I \right]^{-1} K^* g^\delta(x). \tag{3.3} \]
Because $K$ is a linear self-adjoint compact operator, that is, $K^* = K$, we have the equivalent form

$$f^\delta(x) = \left[K^2 + \alpha^2I\right]^{-1}Kg^\delta(x). \quad (3.4)$$

We define function of a compact self-adjoint operator $K$ by the spectral mapping theorem in the following way.

**Definition 3.1 (see[13]).** If $f(x)$ is a real-valued continuous function on the spectrum $\sigma(K)$, we define $f(K)$ by

$$f(K)x = \sum_n f(\lambda_n)(x, \omega_n)\omega_n, \quad (3.5)$$

where $K$ is a compact self-adjoint, $\lambda_n \in \sigma(K)$, and $\omega_n$ are the corresponding orthogonal eigenvectors.

So, we obtain

$$f^\delta(x) = -\sum_{n=1}^\infty \frac{(n^2 + k^2)\left(1 - e^{-\sqrt{n^2 + k^2}}\right)\left(1 + \alpha^2\right)}{\alpha^2}\left(1 - e^{-\sqrt{n^2 + k^2}}\right)\left(1 + \alpha^2\right)g^\delta(x, X_n)X_n$$

$$= \sum_{n=1}^\infty \frac{(n^2 + k^2)\left(1 - e^{-\sqrt{n^2 + k^2}}\right)}{\alpha^2}\left(1 + \alpha^2\right)g^\delta(x, X_n)X_n \quad (3.6)$$

$$= \sum_{n=1}^\infty \frac{(n^2 + k^2)\left(1 - e^{-\sqrt{n^2 + k^2}}\right)}{\alpha^2}\left(1 - e^{-\sqrt{n^2 + k^2}}\right)\left(1 + \alpha^2\right)g^\delta(x, X_n)X_n.$$  

Comparing (1.10) with (3.6), we can find that the procedure consists in replacing the unknown $g(x)$ with an appropriately filtered noisy data $g^\delta(x)$. The filter in (3.6) attenuates the coefficient $g_n^\delta$ of $g^\delta(x)$ in a manner consistent with the goal of minimizing quantity (3.1). By this idea, we can use a much better filter $1/(1 + \alpha^2 n^4)$ to replace the filter $1/(1 + \alpha^2 ((n^2 + k^2)/(1 - e^{-\sqrt{n^2 + k^2}})^2)$ and give another approximation $f_\alpha^\delta(x)$ of the solution $f(x)$.

We define a regularization approximate solution of problem (1.1) for noisy data $g^\delta(x)$ which is called the simplified Tikhonov regularized solution of problem (1.1) as follows:

$$f_\alpha^\delta(x) := -\sum_{n=1}^\infty \frac{n^2 + k^2}{\alpha^2}\left(1 + \alpha^2 n^4\right)g^\delta(x, X_n)X_n. \quad (3.7)$$
Theorem 3.2. Let $f^\delta_\alpha(x)$ be the simplified Tikhonov approximation of the solution $f(x)$ of problem (1.1). Let $g^\delta(x)$ be measured data at $y = 1$ satisfying (1.2), and let priori condition (1.11) hold for $p > 0$. If one selects
\[ \alpha = \left( \frac{\delta}{E} \right)^{2/(p+2)}, \]  
(3.8)
then the following estimate holds:
\[
\left\| f(\cdot) - f^\delta_\alpha(\cdot) \right\|_{L^2(0,\pi)} \leq 2\delta^{p/(p+2)}E^{2/(p+2)} \left( 1 + \frac{1}{2} \max \left\{ 1, \left( \frac{\delta}{E} \right)^{4/(p+2)} \right\} \right) + 2k^2\delta. \tag{3.9}
\]
Proof. Due to the triangle inequality, we have
\[
\left\| f - f^\delta_\alpha \right\|_{L^2(0,\pi)}
= \left\| - \sum_{n=1}^{\infty} \frac{n^2 + k^2}{1 - e^{-\sqrt{n^4 + k^2}}} (g, X_n) X_n \right\|_{L^2(0,\pi)}
\leq \left\| - \sum_{n=1}^{\infty} \frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left( 1 - e^{-\sqrt{n^4 + k^2}} \right)} (g^\delta, X_n) X_n \right\|_{L^2(0,\pi)}
+ \left\| \sum_{n=1}^{\infty} \frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left( 1 - e^{-\sqrt{n^4 + k^2}} \right)} (g, X_n) X_n \right\|_{L^2(0,\pi)}
\leq \left\| \sum_{n=1}^{\infty} \frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left( 1 - e^{-\sqrt{n^4 + k^2}} \right)} (g^\delta, X_n) X_n \right\|_{L^2(0,\pi)}
+ \left\| \sum_{n=1}^{\infty} \frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left( 1 - e^{-\sqrt{n^4 + k^2}} \right)} (g, X_n) X_n \right\|_{L^2(0,\pi)}
= \left\| \sum_{n=1}^{\infty} \frac{n^2 + k^2}{1 - e^{-\sqrt{n^4 + k^2}}} (g, X_n) X_n \left( 1 - \frac{1}{1 + \alpha^2 n^4} \right) \right\|_{L^2(0,\pi)}
\]
\[
\frac{\sum_{n=1}^{\infty} \frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left(1 - e^{-\sqrt{n^2 + k^2}}\right)} \left|f - f^\delta, X_n\right|}{\left\|f - f^\delta, X_n\right\|_{L^2(0, \pi)}} + \sup_{n \geq 1} \left(\frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left(1 - e^{-\sqrt{n^2 + k^2}}\right)}\right) \left\|\sum_{n=1}^{\infty} \left(g - g^\delta, X_n\right) X_n\right\|_{L^2(0, \pi)} \leq \sup_{n \geq 1} \left(\frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left(1 - e^{-\sqrt{n^2 + k^2}}\right)}\right) \left\|\sum_{n=1}^{\infty} \left(g - g^\delta, X_n\right) X_n\right\|_{L^2(0, \pi)} \leq \sup_{n \geq 1} \left(\frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left(1 - e^{-\sqrt{n^2 + k^2}}\right)}\right) \delta + \sup_{n \geq 1} \left(\frac{n^2 + k^2}{(1 + \alpha^2 n^4) \left(1 - e^{-\sqrt{n^2 + k^2}}\right)}\right) \delta \leq \max\left\{\alpha^2, \alpha^{(p/2)}\right\} E + \frac{2}{\alpha} \delta + 2k^2 \delta = \max\left\{\left(\frac{\delta}{E}\right)^{4/(p+2)}, \left(\frac{\delta}{E}\right)^{p/(p+2)}\right\} E + 2\left(\frac{\delta}{E}\right)^{-2/(p+2)} \delta + 2k^2 \delta = 2\delta^{p/(p+2)} E^{2/(p+2)} \left(1 + \frac{1}{2} \max\left\{1, \left(\frac{\delta}{E}\right)^{4-p/(p+2)}\right\}\right) + 2k^2 \delta.
\]

The proof is complete. \(\Box\)

Remark 3.3. If \(0 < P \leq 4\),

\[
\left\|f(\cdot) - f^\delta(\cdot)\right\|_{L^2(0, \pi)} \leq 3\delta^{p/(p+2)} E^{2/(p+2)} + 2k^2 \delta \to 0, \quad \text{as } \delta \to 0. \tag{3.11}
\]

If \(P > 4\),

\[
\left\|f(\cdot) - f^\delta(\cdot)\right\|_{L^2(0, \pi)} \leq 2\delta^{p/(p+2)} E^{2/(p+2)} + \delta^{4/(p+2)} E^{(p-2)/(p+2)} + 2k^2 \delta \to 0, \quad \text{as } \delta \to 0. \tag{3.12}
\]

Hence, \(f^\delta(\cdot)\) can be viewed as the approximation of the exact solution \(f(\cdot)\).
4. Numerical Example

From (1.10), we know that

\[
(Kf)(x) = \sum_{n=1}^{\infty} \frac{1 - e^{-\sqrt{n^2 + k^2}}}{n^2 + k^2} (f, X_n) X_n
\]

\[
= \int_0^\pi 2 \sum_{n=1}^{\infty} \frac{1 - e^{-\sqrt{n^2 + k^2}}}{n^2 + k^2} f(s) \sin(ns) \sin(nx) ds = g(x).
\]

We use trapezoid's rule to approach the integral and do an approximate truncation for the series by choosing the sum of the front \(M + 1\) terms. After considering an equidistant grid \(0 = x_1 < \cdots < x_{M+1} = \pi\), \((x_i = (i-1)/M\pi, i = 1, \ldots, M + 1)\), we get

\[
\frac{2}{\pi} \sum_{i=1}^{M+1} \sum_{n=1}^{N} \frac{1 - e^{-\sqrt{n^2 + k^2}}}{n^2 + k^2} f(x_i) \sin(nx_i) \sin(nx_j) h = g(x_j),
\]

where

\[
h = \frac{\pi}{M}.
\]

**Example 4.1.** It is easy to see that the function \(u(x, y) = (1 - e^{-\sqrt{xy}}) \sin kx\) and the function \(f(x) = -2k^2 \sin kx\) are the exact solutions of the problem (1.1). Consequently, the data function is \(g(x) = (1 - e^{-\sqrt{xy}}) \sin kx\), and

\[
\|f(\cdot)\|_{H^p(0,\pi)} = \left( \sum_{n=1}^{\infty} \left(1 + n^2 \right)^p |f, X_n|^2 \right)^{1/2} = \left(1 + k^2 \right)^{p/2} k^2 \sqrt{2\pi}.
\]

Adding a random distributed perturbation to each data function, we obtain vector \(g^\delta\); that is,

\[
g^\delta = g + \epsilon \text{ randn(size}(g)).
\]

The function “randn(\cdot)” generates arrays of random numbers whose elements are normally distributed with mean 0, variance \(\sigma^2 = 1\), and standard deviation \(\sigma = 1\). “Randn(size(g))”
returns an array of random entries that is the same size as $g$. The total noise level $\delta$ can be measured in the sense of root mean square error (RMSE) according to

$$\delta = \left\| g^{\delta} - g \right\|_2 = \left( \frac{1}{M+1} \sum_{n=1}^{M+1} (g_n - g^{\delta}_n)^2 \right)^{1/2}. \quad (4.6)$$

Using $g^{\delta}$ as data function, we obtain the computed approximation $f^{\delta}_a(x)$ by using (3.7). The relative error is given as follows:

$$\text{rerr}(f) := \left\| f^{\delta}_a - f \right\|_2 \left\| f \right\|_2,$$  \quad (4.7)

where $\left\| \cdot \right\|_2$ is defined by (4.6).

Tables 1-2 show $M$ and $N$ have small influence on the relative error when they become larger. So, we will always take $M = 100$ and $n = 7$ in the following examination.

**Test 1**

We choose $p = 1/2, p = 1, p = 2$ and $p = 3$ in Tables 3, 4, 5, and 6 to compute the parameters $\delta, \alpha$, and $\text{rerr}(f)$, respectively.

These tables indicate that parameter $\delta, \alpha$, and $\text{rerr}(f)$ all depend on the perturbation $\varepsilon$. $\delta, \alpha$, and $\text{rerr}(f)$ decrease with the decrease of $\varepsilon$. These are consistent with our regularization methods. In addition, $\text{rerr}(f)$ decreases with the increase of $p$ at first, but it ceases decreasing when $p$ reaches to some extent. This means that $\text{rerr}(f)$ does not decrease for stronger “smoothness” assumptions on the exact solution $f(x)$.

**Test 2**

Figure 1 shows the comparison between the exact solution $f(x)$ and the regularization solution $f^{\delta}_a(x)$ for $k = 1, k = 2, k = 3$, and $k = 4$ with the perturbation $\varepsilon = 0.1, \varepsilon = 0.01$, and $\varepsilon = 0.001$ with Example 4.1.
Table 5: $\delta$, $\alpha$ and $\text{rerr}(f)$ with $p = 2$, $k = 2$ and $E = 50.1326$.

<table>
<thead>
<tr>
<th>$\varepsilon$</th>
<th>$10^{-1}$</th>
<th>$10^{-2}$</th>
<th>$10^{-3}$</th>
<th>$10^{-4}$</th>
<th>$10^{-5}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\delta$</td>
<td>0.0300</td>
<td>0.0151</td>
<td>0.0028</td>
<td>0.0014</td>
<td>$2.8037 \times 10^{-4}$</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>0.0245</td>
<td>0.0174</td>
<td>0.0075</td>
<td>0.0052</td>
<td>0.0024</td>
</tr>
<tr>
<td>$\text{rerr}(f)$</td>
<td>0.0300</td>
<td>0.0105</td>
<td>0.0036</td>
<td>$9.2789 \times 10^{-4}$</td>
<td>$3.7118 \times 10^{-4}$</td>
</tr>
</tbody>
</table>

Table 6: $\delta$, $\alpha$, and $\text{rerr}(f)$ with $p = 3$, $k = 2$ and $E = 112.0998$.

<table>
<thead>
<tr>
<th>$\varepsilon$</th>
<th>$10^{-1}$</th>
<th>$10^{-2}$</th>
<th>$10^{-3}$</th>
<th>$10^{-4}$</th>
<th>$10^{-5}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\delta$</td>
<td>0.0293</td>
<td>0.0133</td>
<td>0.0028</td>
<td>0.0015</td>
<td>$2.8145 \times 10^{-4}$</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>0.0369</td>
<td>0.0269</td>
<td>0.0144</td>
<td>0.0111</td>
<td>0.0058</td>
</tr>
<tr>
<td>$\text{rerr}(f)$</td>
<td>0.0352</td>
<td>0.0135</td>
<td>0.0051</td>
<td>0.0024</td>
<td>$6.4392 \times 10^{-4}$</td>
</tr>
</tbody>
</table>

Figure 1: The exact solution $f(x)$ and its approximation $f^b_\delta(x)$: (a) $k = 1$, (b) $k = 2$, (c) $k = 3$, and (d) $k = 4$. 
Figure 2: The exact solution \( f(x) \) and its approximation \( f^\varepsilon_a(x) \) for \( k = 10 \): (a) \( p = 2 \), and (b) \( p = 3 \).

Figure 3: The exact solution \( f(x) \) and its approximation \( f^\varepsilon_a(x) \) for \( p = 2 \): (a) \( k = 3 \), and (b) \( k = 10 \).

Figure 1 indicates these regularized solutions approximate to the exact solution, as the amount of \( \varepsilon \) decreases, while the numerical results are not so good as the parameter \( k \) becomes larger.

**Test 3**

The unknown sources \( f(x) \) is given. The numerical test was constructed in the following way. First, we selected the solution \( f(x) \) and obtained the exact data function \( g(x) \) using (1.6). Then, we added a normally distributed perturbation to each data function giving vectors \( g_\varepsilon(x) \). Finally, we obtained the regularization solutions using (3.7).
Example 4.2. Consider a piecewise smooth source:

\[ f(x) = \begin{cases} 
0, & 0 \leq x \leq \frac{\pi}{4}, \\
\frac{4}{\pi}x - 1, & \frac{\pi}{4} < x \leq \frac{\pi}{2}, \\
3 - \frac{4}{\pi}x, & \frac{\pi}{2} < x \leq \frac{3\pi}{4}, \\
0, & \frac{3\pi}{4} < x \leq \pi.
\] (4.8)

In Example 4.2, since the direct problem with the heat source \( f(x) \) does not have an analytical solution, the data \( g(x) \) is obtained by solving the direct problem. Figures 2-3 show the comparisons between the exact solution and its computed approximation with different noise level for Example 4.2. It can be seen that as the amount of noise \( \varepsilon \) decreases, the regularized solutions approximate better the exact solution. In addition, even when \( k = 10 \), the regularized solutions still approximate the exact solution. From Figures 2-3, it can be seen that the numerical solution is less than that of Example 4.1. It is not difficult to see that the well-known Gibbs phenomenon and the recovered data near the nonsmooth points are not accurate. Taking into consideration the ill posedness of the problem, the results presented in Figures 2-3 are reasonable.

5. Conclusions

In this paper, we considered the inverse problem of determining the unknown source using the simplified Tikhonov regularization method for the modified Helmholtz equation. It was shown that with a certain choice of the parameter, a stability estimate was obtained. Meanwhile, the numerical example verified the efficiency and accuracy of this method.

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References


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