Research Article

Frobenius’ Idea Together with Integral Bifurcation Method for Investigating Exact Solutions to a Water Wave Model of the Generalized mKdV Equation

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Received 19 May 2014; Accepted 30 July 2014

Academic Editor: Salvatore Alfonzetti

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By using Frobenius’ idea together with integral bifurcation method, we study a third order nonlinear equation of generalization form of the modified KdV equation, which is an important water wave model. Some exact traveling wave solutions such as smooth solitary wave solutions, nonsmooth peakon solutions, kink and antikink wave solutions, periodic wave solutions of Jacobian elliptic function type, and rational functions solution are obtained. And we show their profiles and discuss their dynamic properties aim at some typical solutions. Though the types of these solutions obtained in this work are not new and they are familiar types, they did not appear in any existing literatures because the equation $u_t + u_x + uu_{x} + \alpha uu_{xxx} + (1/3) \alpha(\alpha uu_{xxx} + 2uu_{x}x) + 3\mu\alpha^2 u^2 u_x + \gamma \mu \alpha^2 (u^2 u_{xxx} + uu_x^4 + 4uu_xu_{xxx}) + \lambda u^2 (u^2 u_{xxx} + 2u_x u_{xx}) = 0$ is very complex. Particularly, compared with the cited references, all results obtained in this paper are new.

1. Introduction

It has come to light that many problems in nonlinear science associated with mechanical, structural, aeronautical, oceanic, electrical, and control systems can be summarized as solving nonlinear partial differential equations (PDEs) which arise from important models with mathematical and physical significances. Finding their exact solutions has extensive applications in many scientific fields such as hydrodynamics, condensed matter physics, solid-state physics, nonlinear optics, neurodynamics, crystal dislocation, model of meteorology, water wave model of oceanography, and fibre-optic communication. The research methods for solving nonlinear PDEs deal with the inverse scattering transformation [1, 2], the Darboux transformation [3–5], the Bäcklund transformation [5–8], the bilinear method and multilinear method [9, 10], the classical and nonclassical Lie group approaches [11, 12], the Clarkson-Kruskal direct method [13–15], the mixing exponential method [16], the geometrical method [17, 18], the truncated Painlevé expansion [19, 20], the function expansion method (including tanh expansion method [21, 22], sine-cosine expansion method [23, 24], exp-function method [25], and multiple exp-function method [26]), the bifurcation theory of planar dynamical system [27, 28], the F-expansion method [29, 30], $G'/G$ method [31, 32], and the integral bifurcation method [33–36]. Among these available methods for solving nonlinear PDEs, some of them employed Frobenius’ idea directly or indirectly. Frobenius’ idea is also called Frobenius’ integrable decompositions [37]; it can reduce a partial differential equation (PDE) to an ordinary differential equation (ODE) under investigation for solution. Indeed, the F-expansion type methods indirectly employed Frobenius’ idea; crucial points of this method are to choose integrable ODE to start investigation for solution. In fact, the tanh function method and $G'/G$ method are special cases of such an idea or general Frobenius’ idea. Direct Frobenius’ idea was also used to establish the transformed rational function method [38] and to solve the KPP equation [39].
In this paper, we will employ Frobenius’ idea together with integral bifurcation method to investigate exact traveling wave solutions of the following integrable generalization of the modified KdV equation:

\[
\begin{align*}
\alpha u_{tt} + \beta u_{xxx} + \gamma u_{xxx} + \mu u_{xx} + \nu u_{x} + \frac{1}{3} \nu \alpha (u u_{xxx} + 2 u u_{x}) + 3 \mu \alpha^2 u^2 u_x + \\
+ \gamma \mu \alpha^2 (u^2 u_{xxx} + u_x + 4 u u_x u_{xx}) + \\
+ \gamma^2 \mu \alpha^2 (u_x u_{xxx} + 2 u_x u_{xx}) = 0,
\end{align*}
\] (1)

where \(\alpha, \beta, \mu, \) and \(\gamma\) are constants and \(0 < \alpha < 1\). The model (1) comes from the physical and asymptotic considerations via the methodology introduced by Fokas [40] in 1995; it can be regarded as a water wave model to describe the motion of water wave. It is worth to point out that the special case of (1),

\[
\begin{align*}
\alpha u_{tt} + \beta u_{xxx} + \gamma u_{xxx} + \mu u_{xx} + \\
+ \frac{1}{3} \nu \alpha (u u_{xxx} + 2 u u_{x}) + 3 \mu \alpha^2 u^2 u_x = 0,
\end{align*}
\] (2)

is also an important physical model. The above two equations were studied by many authors. Equation (2) was introduced by Fuchssteiner and Fokas in their previous works [41, 42] in 1981. The Lax pairs of (2) were given by Fokas in [40]. New Lax pairs and Darboux transformation of (2) were introduced by Yang and Rui in [43] recently. In [44], by using the bifurcation theory of dynamical system, the existence conditions of different kinds of traveling wave solutions of (2) were presented by Bi. In [45], by using the same method, Li and Zhang studied (1), the existence of solitary wave, kink and antikink wave solutions, uncountably infinite many smooth, and nonsmooth periodic wave solutions were discussed. However, exact travelling wave solutions of (1) were not obtained in [45] though the authors obtained some results of numerical simulation for smooth and nonsmooth periodic wave solutions were discussed. Moreover, the investigations on exact solutions of (1) are few in the existing literatures because (1) is more complex than (2). Therefore, in this paper, employing Frobenius’ idea together with integral bifurcation method, we will investigate different kinds of exact traveling wave solutions of (1).

The rest of this paper is organized as follows. In Section 2, by using Frobenius’ idea, we will derive ordinary differential equation (ODE) which is equivalent to (1). In Section 3, by using the integral bifurcation method combined with factoring technique, we will investigate different kinds of exact traveling wave solutions of (1) and discuss their dynamic properties when the integral constants satisfy different conditions. In Section 4, we will discuss different kinds of exact traveling wave solutions of (1) under the special case of the parameter \(\nu = 0\).

### 2. Direct Application of Frobenius’ Idea on Reducing the PDE (1) to an Integrable ODE

Frobenius’ idea is about changing a partial differential equation (PDE) into an ordinary differential equation (ODE) and then using integrable decomposition method to investigate its exact solutions. Thus, in this section, we first employ the direct Frobenius’ idea to change (1) into an integrable ordinary differential equation; see the following discussions.

Making a traveling wave transformation \(u(x, t) = u(\xi)\) with \(\xi = x - ct\), (1) can be reduced to the following ordinary differential equation (ODE):

\[
\begin{align*}
(1 - c) \frac{du}{d\xi} + (\beta - c\nu) \frac{d^3 u}{d\xi^3} + \alpha \nu \frac{du}{d\xi} + \\
+ \frac{1}{3} \nu \alpha \left[ \frac{d^2 u}{d\xi^2} + \frac{1}{2} \left( \frac{du}{d\xi} \right)^2 \right] + \\
+ \mu \alpha^2 \left[ u^3 + \nu \alpha^2 \left( u^2 \frac{du}{d\xi} + u \left( \frac{du}{d\xi} \right)^2 \right) \right] + \\
+ \nu^2 \alpha^2 \left( \frac{du}{d\xi} \right)^2 + g = 0,
\end{align*}
\] (3)

where \(c\) is wave velocity which moves along the direction of \(x\)-axis and \(c \neq 0\). Equation (3) can be rewritten as

\[
\begin{align*}
(1 - c) \frac{du}{d\xi} + (\beta - c\nu) \frac{d^3 u}{d\xi^3} + \frac{1}{2} \alpha u^2 + \\
+ \frac{1}{3} \nu \alpha \left[ \frac{d^2 u}{d\xi^2} + \frac{1}{2} \left( \frac{du}{d\xi} \right)^2 \right] + \\
+ \mu \alpha^2 u^3 + \nu \alpha^2 \left( u^2 \frac{du}{d\xi} + u \left( \frac{du}{d\xi} \right)^2 \right) + \\
+ \nu^2 \alpha^2 \left( \frac{du}{d\xi} \right)^2 = 0.
\end{align*}
\] (4)

Integrating (4) once, we obtain

\[
\begin{align*}
(1 - c) u + (\beta - c\nu) \frac{d^2 u}{d\xi^2} + \frac{1}{2}\alpha u^2 + \\
+ \frac{1}{3} \nu \alpha \left[ \frac{d^2 u}{d\xi^2} + \frac{1}{2} \left( \frac{du}{d\xi} \right)^2 \right] + \\
+ \mu \alpha^2 u^3 + \nu \alpha^2 \left( u^2 \frac{du}{d\xi} + u \left( \frac{du}{d\xi} \right)^2 \right) + \\
+ \nu^2 \alpha^2 \left( \frac{du}{d\xi} \right)^2 = g,
\end{align*}
\] (5)

where \(g\) is an integral constant. Employing direct Frobenius’ idea, we need not change (5) into a 2-dimensional planar system as the method in [33–36], we can directly integrate (5) again; see the following calculus.
Multiplying $du/d\xi$ to the both sides of (5) yields

\[
(1-c) \frac{du}{d\xi} + (\beta - cv) \frac{d^2u}{d\xi^2} + \frac{1}{2} \frac{du^2}{d\xi^2} + \frac{1}{2} \frac{du}{d\xi}^3 \\
+ \frac{1}{3} \frac{\nu}{\alpha} \left[ \frac{du}{d\xi} \frac{d^2u}{d\xi^2} + \frac{1}{2} \left( \frac{du}{d\xi} \right)^3 \right] \\
+ \mu \frac{u}{\alpha} \frac{d^3u}{d\xi^3} + \nu \mu \frac{\alpha^2}{\nu} \left[ \frac{du}{d\xi} \frac{d^2u}{d\xi^2} + \left( \frac{du}{d\xi} \right)^3 \right] \\
+ \mu \nu \frac{\alpha^2}{\nu^2} \left[ \left( \frac{du}{d\xi} \right)^3 \frac{d^2u}{d\xi^2} \right] = g \frac{du}{d\xi}.
\]

Integrating (6) once, we obtain

\[
- gu + \frac{1}{2} (1-c) u^2 + \frac{1}{2} (\beta - cv) \left( \frac{du}{d\xi} \right)^2 + \frac{1}{6} \alpha u^3 \\
+ \frac{1}{3} \frac{\nu}{\alpha} \left( \frac{du}{d\xi} \right)^2 + \frac{1}{4} \mu \frac{u}{\alpha} u^4 + \frac{1}{4} \frac{\nu \mu}{\nu^2} \left( \frac{du}{d\xi} \right)^4 \\
+ \frac{1}{2} \nu \frac{\mu}{\nu} \left( \frac{du}{d\xi} \right)^2 = h,
\]

where $h$ is another arbitrary integral constant. When $\nu \neq 0$, (7) can be rewritten as

\[
- \frac{4h}{\nu} - \frac{4g}{\nu} u + \frac{2}{3} (1-c) u^2 + \frac{2\alpha}{3\nu} u^4 + \nu \frac{\mu}{\nu} u^4 \\
+ \frac{2(\beta - cv)}{\nu} \left( \frac{du}{d\xi} \right)^2 + \frac{2\alpha}{3} \left( \frac{du}{d\xi} \right)^2 \\
+ \frac{2\mu}{\nu} \frac{\alpha}{\nu} \left( \frac{du}{d\xi} \right)^2 + \mu \frac{\alpha}{\nu} \left( \frac{du}{d\xi} \right)^4 = 0.
\]

### 3. Different Kinds of Exact Traveling Wave Solutions of (1)

In this section, by using the integral bifurcation method combined with factoring technique as in [36], we will investigate different kinds of exact traveling wave solutions of (1) and discuss their dynamic properties via (7) and (8).

#### 3.1. Hyperbolic Function Solutions and Periodic Wave Solutions of (1) as the Two Integral Constants $g \neq 0$ and $h \neq 0$.

When $\nu (\nu - \mu) > 0$ and $h = (324\nu \nu^2 \mu (c - 1)^2 + \mu 648c \nu^2 - 648\nu \nu + 324 \beta^2 + 36c - 36\nu - 324c \nu^2 + \nu) + 36\nu (\beta - cv)/1296 \nu^3 (\nu - \mu) \alpha^2 \nu^2 \neq 0$, $g = (18(\nu (c - 1) + 1)/108 \nu \nu^2 \mu^2 \neq 0$, (8) can be decomposed in the following form:

\[
\left[ r_0 + r_1 u + r_2 u^2 + \mu \left( \frac{du}{d\xi} \right)^2 \right] \\
\times \left[ s_0 + s_1 u + s_2 u^2 + \alpha \left( \frac{du}{d\xi} \right)^2 \right] = 0,
\]

where the coefficients $r_0$, $r_1$, $r_2$, $s_0$, $s_1$, and $s_2$ are defined by the following expressions:

\[
r_0 = \frac{\nu \left[ \alpha \nu \mu (1-c) \nu - \mu \right] - \nu \nu \mu \alpha^2 \nu (\nu - \mu)}{\nu^3 \mu}, \quad r_1 = \frac{\nu \nu \mu \alpha^2 \nu (\nu - \mu)}{3 \nu^2 \mu}, \quad r_2 = 1 - \frac{\nu \nu \mu \alpha^2 \nu (\nu - \mu)}{\nu \nu \mu \alpha^2 \nu (\nu - \mu)}.
\]

Thus (9) can be reduced to the following two ordinary differential equations:

\[
r_0 + r_1 u + r_2 u^2 + \mu \left( \frac{du}{d\xi} \right)^2 = 0,
\]

\[
s_0 + s_1 u + s_2 u^2 + \alpha \left( \frac{du}{d\xi} \right)^2 = 0,
\]

where the coefficients $r_0$, $r_1$, $r_2$, $s_0$, $s_1$, and $s_2$ are given by (10).

Solving (11) under the conditions $r_2 < 0$ and $q = 4r_0 r_2 - r_2^2 > 0$, we obtain two hyperbolic function solutions of (1) as follows:

\[
u \mu \alpha \nu \mu (1-c) \nu - \mu \left(\frac{\nu \nu \mu \alpha^2 \nu (\nu - \mu)}{\nu^3 \mu} \right) \pm r_1 + r_2 u^2 + \mu \left( \frac{du}{d\xi} \right)^2 = 0.
\]

Similarly, solving (12) under the conditions $s_2 < 0$ and $\bar{q} = 4s_0 s_2 - s_2^2 > 0$, we obtain two periodic wave solutions of (1) as follows:

\[
u \mu \alpha \nu \mu (1-c) \nu - \mu \left(\frac{\nu \nu \mu \alpha^2 \nu (\nu - \mu)}{\nu^3 \mu} \right) \pm s_1 + s_2 u^2 + \alpha \left( \frac{du}{d\xi} \right)^2 = 0.
\]
3.2. Hyperbolic Function Solutions and Periodic Wave Solutions of (1) as the Two Integral Constants \( g = 0 \) and \( h \neq 0 \).

When \( \nu^2 - \mu \nu > 0 \) and \( g = 0, h = (18 \mu \nu - 18 \mu \beta - \nu^2) / 1296 \omega^2 \nu (\nu - \mu) \neq 0, c = 1 - (1/18 \mu) \), (8) can be decomposed in the following form:

\[
\left[ \frac{\nu \gamma - \mu \beta - \nu/18}{\nu \gamma (\nu - \mu + \sqrt{\nu^2 - \mu \nu})} + \frac{\alpha (\nu - \mu + \sqrt{\nu^2 - \mu \nu})}{3 \mu^2 \sqrt{\nu^2 - \mu \nu}} \right] u
\]

\[
+ \frac{\alpha^2}{\mu} \left( 1 - \frac{\sqrt{\nu^2 - \mu \nu}}{\nu} \right) u^2 + \alpha^2 \left( \frac{du}{d\xi} \right)^2 = 0
\]  

Equation (17) can be reduced to the following two ordinary differential equations:

\[
\left[ \frac{\nu \gamma - \mu \beta - \nu/18}{\nu \gamma (\nu - \mu + \sqrt{\nu^2 - \mu \nu})} + \frac{\alpha (\nu - \mu + \sqrt{\nu^2 - \mu \nu})}{3 \mu^2 \sqrt{\nu^2 - \mu \nu}} \right] u
\]

\[
+ \frac{\alpha^2}{\mu} \left( 1 - \frac{\sqrt{\nu^2 - \mu \nu}}{\nu} \right) u^2 + \alpha^2 \left( \frac{du}{d\xi} \right)^2 = 0
\]

or

\[
\left[ \frac{\mu \gamma - \mu \beta - \nu/18}{\nu \gamma (\nu - \mu + \sqrt{\nu^2 - \mu \nu})} + \frac{\nu - \mu + \sqrt{\nu^2 - \mu \nu}}{3 \alpha \sqrt{\nu^2 - \mu \nu}} \right] u
\]

\[
+ \left( \mu + \frac{\mu \gamma}{\nu - \sqrt{\nu^2 - \mu \nu}} \right) u^2 + \mu^2 \left( \frac{du}{d\xi} \right)^2 = 0
\]

Solving (18), we obtain two hyperbolic function solutions and two periodic wave solutions of (1) as follows:

\[
u = \frac{\mu \gamma}{\nu \gamma (\nu - \mu + \sqrt{\nu^2 - \mu \nu})} \]

\[
\times \left[ \alpha \Omega_3 \sinh (\omega_3 \xi) + \frac{\alpha (\nu - \mu + \sqrt{\nu^2 - \mu \nu})}{3 \mu^2 \sqrt{\nu^2 - \mu \nu}} \right], \quad (20)
\]
\[
\Omega_4 = \sqrt{\frac{[36 (v - \beta) - y] \sqrt{v^2 - \mu v} + [36 v (v - \beta) - v^2 / \mu - y]}{v - \mu - \sqrt{v^2 - \mu v}},}
\]

\[
\omega_4 = \frac{1}{\mu} \sqrt{\mu + \mu \sqrt{v^2 - \mu v}}, \quad \xi = x - \left(1 - \frac{1}{18 \mu}\right)t.
\]

(25)

3.3. Hyperbolic Function Solutions and Periodic Wave Solutions of (1) as the Two Integral Constants \(g \neq 0\) and \(h = 0\). When \(v^2 - \mu v > 0\) and \(g = (v + 18 \mu (\beta - y)) / 108 \alpha \mu^2 \sqrt{v^2 - \mu v} \neq 0, h = 0, c = (v + 18 \mu (\beta - \mu) + 18 \sqrt{v^2 - \mu v}) / 18 \nu (v - \mu + \sqrt{v^2 - \mu v}), (8)\) can be decomposed in the following form:

\[
\left[\begin{array}{c}
18 \mu (v - \beta) - y \\
9 \gamma \mu^2 \left(v - \mu + \sqrt{v^2 - \mu v}\right) - \frac{\alpha (v - \mu + \sqrt{v^2 - \mu v})}{3 \mu^2 \sqrt{v^2 - \mu v}} \alpha^2 (v - \sqrt{v^2 - \mu v}) u + \frac{\alpha^2 (v - \sqrt{v^2 - \mu v}) u^2 + \alpha^2 \left(\frac{du}{d\xi}\right)^2}{v \mu}
\end{array}\right] \\
\times \left[\begin{array}{c}
sin\left(\frac{v + \sqrt{v^2 - \mu v}}{\mu v}\right) + 1
\end{array}\right] = 0.
\]

(26)

Similarly, solving (26) we obtain four hyperbolic function solutions and four periodic wave solutions of (1) as follows:

\[
u = \pm \frac{\mu v}{2 \alpha^2 (v - \sqrt{v^2 - \mu v})}
\]

\[
\times \left[\begin{array}{c}
\frac{\alpha \Omega_5}{3 \mu v} \sinh (\omega_5 \xi) + \frac{\alpha (v - \mu - \sqrt{v^2 - \mu v})}{3 \mu^2 \sqrt{v^2 - \mu v}}
\end{array}\right],
\]

(27)

\[
u = \pm \frac{\mu v}{2 \alpha^2 (v - \sqrt{v^2 - \mu v})}
\]

\[
\times \left[\begin{array}{c}
\frac{\alpha \Omega_6}{3 \mu v} \sin (\omega_6 \xi) + \frac{\alpha (v - \mu - \sqrt{v^2 - \mu v})}{3 \mu^2 \sqrt{v^2 - \mu v}}
\end{array}\right].
\]

(28)

where the \(\Omega_5, \Omega_6, \omega_5, \omega_6,\) and \(\xi\) are defined by

\[
\Omega_5 = \sqrt{\frac{72 \mu v (v - \beta) - (3 v^2 - \mu v) + 72 \mu (\beta - y) + 3 v \sqrt{v^2 - \mu v}}{\mu (v - \mu + \sqrt{v^2 - \mu v})}},
\]

\[
\omega_5 = \sqrt{\frac{\mu - \sqrt{v^2 - \mu v}}{\mu v}},
\]

\[
\Omega_6 = \sqrt{\frac{72 \mu v (v - \beta) - (3 v^2 - \mu v) + 72 \mu (\beta - y) + 3 v \sqrt{v^2 - \mu v}}{\mu (v - \mu + \sqrt{v^2 - \mu v})}},
\]

\[
\omega_6 = \sqrt{-\frac{\sqrt{v^2 - \mu v} - \nu}{\mu v}},
\]

(29)

\[
\xi = x - \frac{(v + 18 \nu (\beta - \mu) + 18 \sqrt{v^2 - \mu v})}{18 \nu (v - \mu + \sqrt{v^2 - \mu v})} t,
\]

(31)

(32)

3.4. Hyperbolic Function Solutions, Periodic Wave Solutions, and Rational Function Solution of (1) as the Two Integral Constants \(g = h = 0\). (i) When \(\mu = \nu, \beta > \nu\) and \(g = h = 0, c = \beta / \nu, (8)\) can be decomposed in the following form:

\[
\left[\begin{array}{c}
\alpha (1 + \sqrt{1 + 18 (\beta - \nu) v}) u + \frac{\alpha^2 (1 + \sqrt{1 + 18 (\beta - \nu) v})}{v} u^2 + \frac{\alpha^2 \left(\frac{du}{d\xi}\right)^2}{v}
\end{array}\right]

\times \left[\begin{array}{c}
\frac{1 - \sqrt{1 + 18 (\beta - \nu)}}{3 \alpha} u + \nu u^2 + \mu^2 \left(\frac{du}{d\xi}\right)^2
\end{array}\right] = 0.
\]
Solving (32) we obtain four hyperbolic function solutions and four periodic wave solutions of (1) as follows:

\[ u = \pm \frac{1 + \sqrt{1 + 18 (\beta - \gamma)}}{6\alpha \nu} \left[ \sinh \left( \frac{\xi}{\sqrt{\nu}} \right) \mp 1 \right], \quad (\nu < 0 < \beta), \]  
\[ u = \pm \frac{1 + \sqrt{1 + 18 (\beta - \gamma)}}{6\alpha \nu} \left[ \sin \left( \frac{\xi}{\sqrt{\nu}} \right) \right] \pm 1, \quad (\beta > \nu > 0), \]  
\[ u = \pm \frac{1 + \sqrt{1 + 18 (\beta - \gamma)}}{6\alpha \nu} \left[ \sinh \left( \frac{\sqrt{-\xi}}{\mu} \right) \right] \mp 1, \quad (\nu < 0 < \beta), \]  
\[ u = \pm \frac{1 + \sqrt{1 + 18 (\beta - \gamma)}}{6\alpha \nu} \left[ \sin \left( \frac{\sqrt{-\xi}}{\mu} \right) \right] \mp 1, \quad (\beta > \nu > 0), \]

where \( \xi = x - (\beta/\gamma)t \).

(ii) When \( \mu = -\nu/18(\beta - \gamma), \beta > \nu \) and \( g = h = 0, c = \beta/\gamma \), (8) can be decomposed in the following form:

\[
\left[ Au - \frac{\alpha \nu A}{6(\beta - \gamma)} u^2 + \alpha^2 \left( \frac{d u}{d \xi} \right)^2 \right] 
\times \left[ Bu - \frac{\nu B}{6(\beta - \gamma)} u^2 + \mu^2 \left( \frac{d u}{d \xi} \right)^2 \right] = 0,
\]

where \( A = 6\alpha(\beta - \nu)[18(\beta - \gamma) - 3\sqrt{36(\beta - \gamma)^2 + 2(\beta - \gamma)}/\gamma^2], \)
\( B = (18(\beta - \gamma) + 3\sqrt{36(\beta - \gamma)^2 + 2(\beta - \gamma)})/54\alpha(\beta - \gamma). \)

Solving (37) we obtain two hyperbolic function solutions and two periodic wave solutions of (1) as follows:

\[ u = \frac{6(\beta - \gamma)}{\alpha \nu} \cos^2 \left( \frac{1}{2} \sqrt{\frac{\nu A}{6\alpha(\beta - \gamma)}} \xi \right), \quad (0 < \beta < \nu, A > 0), \]
\[ u = \frac{6(\beta - \gamma)}{\alpha \nu} \cosh^2 \left( \frac{1}{2} \sqrt{\frac{\nu A}{6\alpha(\beta - \gamma)}} \xi \right), \quad (\nu < 0 < \beta, A < 0), \]

where \( \xi = x - (\beta/\gamma)t \) and \( A, B \) have been given above.

Solving (42), we obtain a hyperbolic function solution, a periodic wave solution, and a rational function solution as follows:

\[ u = \frac{3(\beta - \nu)}{\alpha \nu} \cos^2 \left( \frac{1}{2} \sqrt{\frac{\nu A}{\gamma}} \xi \right), \quad (\nu > 0), \]
\[ u = \frac{3(\beta - \nu)}{\alpha \nu} \cosh^2 \left( \frac{1}{2} \sqrt{\frac{\nu A}{\gamma}} \xi \right), \quad (\nu < 0), \]
\[ u = -\frac{1}{6\alpha \mu^2} \xi^2, \quad (0 < \beta < \nu, B > 0), \]

where \( \xi = x - (\beta/\gamma)t \) and \( A, B \) have been given above.

All the above exact solutions which were obtained by us are smooth travelling wave solutions including smooth periodic wave solutions and smooth hyperbolic function solutions. In order to show the dynamical profiles of periodic wave solutions, as examples, we plot the graphs of solutions (14) and (38) for \( \alpha = 0.5, \beta = 0.8, \mu = 1.2, t = 0.1 \), which are shown in Figures 1(a) and 1(b).

3.5. Peakon Solutions under Some Special Parametric Condition. The expression in the right side of (8) cannot be reduced to a form of \( [au^2 - b(du/d\xi)^2] = 0 \) by using the factoring technique because this equation contains the terms \(-4h/\nu - (4g/\nu)u + 2(2\alpha/3)^2u + 2(2\alpha/3)u(du/d\xi)^2 \). Thus, the peakon solutions of (1) such as Camassa-Holm’s form \( re^{-\xi^2} \) cannot be obtained by direct integral method together with factoring technique as in [36]. However, the research works given by Li et al. in [45] show that the peakon solutions of (1) exist though they did not obtain exact peakon solutions of this equation. Indeed, the existence of peakon solution of (1) is proved by Li via analysis of phase portraits in this paper. We notice that the terms \( u^3 \) and \( u(du/d\xi)^2 \) are kindred terms when \( u = re^{-\xi^2} \). Thus we assume that (1) has peakon solutions of the form \( u = re^{-\xi^2} \) or \( u = s + re^{-\xi^2} \).
(a) When \( g \neq 0 \) and \( h \neq 0 \), we suppose that (8) has a peakon solution as the following form:

\[
u = s + re^{-\delta|\xi|}, \quad (46)
\]

where the parameters \( s \), \( r \), and \( \delta \) can be determined further in the below discussions. We define \( s + re^{-\delta|\xi|} = s + r \exp(-\delta \sqrt{\xi^2}) \) when \( \xi \neq 0 \); particularly \( u = s + r = \text{(constant)} \) when \( \xi = 0 \), and obviously \( u = s + r \) is a constant solution which satisfies (1).

When \( \xi \neq 0 \), substituting (46) (i.e. \( u = s + r \exp(-\delta \sqrt{\xi^2}) \)) into (8) we obtain

\[
C_0 + C_1 \exp(-\delta \sqrt{\xi^2}) + C_2 \exp(-2\delta \sqrt{\xi^2}) + C_3 \exp(-3\delta \sqrt{\xi^2}) + C_4 \exp(-4\delta \sqrt{\xi^2}) = 0,
\]

where coefficients \( C_0 \), \( C_1 \), \( C_2 \), \( C_3 \), and \( C_4 \) satisfy

\[
C_0 = \frac{4h}{\nu} - \frac{4gs}{\nu} + \frac{2ax^3}{3\nu} + \frac{2(1 - c)s^2}{\nu} + \frac{\mu \alpha^2 s^4}{\nu},
\]

\[
C_1 = \frac{4(1 - c)rs}{\nu} + \frac{2ar s}{\nu} - \frac{4gr}{\nu} + \frac{4\mu \alpha^2 r^3 s}{\nu},
\]

\[
C_2 = \frac{2(1 - c)r^2}{\nu} + \frac{2ar^2 s}{\nu} + \frac{6\mu \alpha^2 r^2 s^2}{\nu} + \frac{2\mu \alpha^2 r^2 s^2 \delta^2}{\nu} + \frac{2(\beta - c)\nu r^2 \delta^2}{\nu} + \frac{2ar^2 s \delta^2}{3},
\]

\[
C_3 = \frac{\mu \alpha^2 r^4}{\nu} + 2\mu \alpha^2 r^4 \delta^2 + \mu \alpha^2 r^4 \delta^4,
\]

\[
C_4 = \frac{\mu \alpha^2 r^4}{\nu} + 2\mu \alpha^2 r^4 \delta^2 + \mu \alpha^2 r^4 \delta^4.
\]

Let the coefficients of every terms of exp-function (including the term of constant) in (47) as zero; it follows

\[
C_0 = 0, \quad C_1 = 0, \quad C_2 = 0, \quad C_3 = 0, \quad C_4 = 0.
\]

Solving the above group of equations yields

\[c = \frac{\left(y^2 - 3\nu y + 36\nu^2 y - 36\beta \nu y\right)}{36\nu^2 \left(\mu - y - \sqrt{\nu^2 - \mu y}\right)}\]

\[g = \frac{\left(y^2 + \nu y - 36\nu^2 y + 36\beta \nu y\right)}{216\nu^2 \left(\mu - y - \sqrt{\nu^2 - \mu y}\right)}\]

\[h = \frac{\left(3y^2 + \nu y - 2\nu y + 72\beta \nu y \right)}{5184\nu^2 \left(\mu - y - \sqrt{\nu^2 - \mu y}\right)}\]

\[r = r(\text{free parameter}), \quad s = -\frac{1}{6\nu\mu}, \quad \delta = \sqrt{\frac{\nu^2 - \mu y - \nu}{\mu y}}, \quad (50)\]
where \( v < 0 < \mu \). Thus, when the constants \( c, g, \) and \( h \) satisfy the above conditions, (1) has a peakon solution as follows:

\[
u = -\frac{1}{6\alpha\mu} + r \exp \left( -\frac{\sqrt{v^2 - \mu v - v}}{\mu v} |x - ct| \right), \tag{51}\]

where \( r \) is an arbitrary nonzero constant and \( c \) is given above.

(b) When \( g = h = 0 \) and \( \beta \) can be regarded as a free parameter, we suppose that (8) has a peakon solution as the following form:

\[
u = \bar{r} e^{-\bar{\delta} |\xi|}, \tag{52}\]

where the parameters \( \bar{r}, \bar{\delta} \) can be determined further in the below discussions.

When \( \xi \neq 0 \), substituting (52) (i.e., \( u = \bar{r} e^{-\bar{\delta} \sqrt{\xi^2}} \)) into (8) we obtain

\[
A \exp \left( -2\delta \sqrt{\xi^2} \right) + B \exp \left( -3\delta \sqrt{\xi^2} \right) + C \exp \left( -4\delta \sqrt{\xi^2} \right) = 0, \tag{53}\]

where coefficients \( A, B, \) and \( C \) satisfy

\[
A = \frac{2}{\nu} \frac{(1 - c) \bar{r}^3}{\nu} + \frac{2(\beta - cv) \bar{r}^3 \bar{\delta}^2}{\nu},
\]

\[
B = \frac{2\alpha r^3}{3\nu} + \frac{2}{3} \alpha r^3 \bar{\delta}^2,
\]

\[
C = \frac{\mu r^4}{\nu} + 2\mu r^4 \bar{\delta}^2 + \mu^2 r^4 \bar{\delta}^4.
\]

Let the coefficients of every terms of exp-function in (53) as zero; it follows

\[
A = 0, \quad B = 0, \quad C = 0. \tag{55}\]

Solving the above group of equations yields

\[
\beta = \mu = v < 0, \quad \bar{\delta} = \frac{1}{\sqrt{-v}}, \quad \bar{r} = \bar{r}, \quad c = c. \tag{56}\]

Thus, when the constants \( g = h = 0 \) and \( \beta = \mu = v, \bar{\delta} = 1/\sqrt{-v} \), (1) has a peakon solution as follows:

\[
u = \bar{r} \exp \left( -\frac{1}{\sqrt{-v}} |x - ct| \right), \tag{57}\]

where \( \bar{r} \) and \( c \) are arbitrary nonzero constants.

In order to show the dynamical profiles of peakon solutions (51) and (57), we plot the graphs of them for \( \alpha = 0.5, \beta = 0.8, \mu = 0.2, r = 5, c = 4, t = 0.1 \), which are shown in Figures 2(a) and 2(b).

4. Different Kinds of Exact Solutions under the Special Case \( v = 0 \)

Under the special case of parameter \( v = 0 \), (7) can be rewritten as

\[
h - gu + \frac{1}{2} (1 - c) u^2 + \frac{1}{6} a u^3 + \frac{1}{4} \mu \alpha^2 u^4 + \frac{1}{2} \beta \left( \frac{du}{dt} \right)^2 = 0. \tag{58}\]

Solving (58) in different kinds of parametric conditions, we obtain different kinds of exact traveling wave solutions including solitary wave solutions and kink wave solutions; see the below discussions.
4.1. Different Kinds of Exact Traveling Wave Solutions for the Constants \(g = h = 0\). When two integral constants \(g, h\) are both zero (i.e., \(g = h = 0\)), (58) can be reduced to

\[
\left(\frac{du}{d\xi}\right)^2 = \frac{c-1}{\beta} u^2 - \frac{\alpha}{3\beta} u^3 - \frac{\mu\alpha^2}{2\beta} u^4.
\]  

(59)

Under different parametric conditions solving (59), we obtain a series of exact traveling wave solutions as follows:

\[
u = \frac{6(c-1) \text{sech}^2 \left(\frac{(1/2)\sqrt{(c-1)/\beta}\xi}{2\alpha + 9\alpha\mu(c-1)}\right)}{1 \pm \tanh \left(\frac{(1/2)\sqrt{(c-1)/\beta}\xi}{2\alpha + 9\alpha\mu(c-1)}\right)},
\]  

(60)

where \(c > 1\), \(\beta > 0\), and \(\xi = x - ct\):

\[
u = \frac{6(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \sin \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(61)

where \(c > 1\), \(\beta > 0\), \(\mu < -1/18(c-1)\), and \(\xi = x - ct\):

\[
u = \frac{6(c-1)}{\alpha \left[1 + \sqrt{18\mu(c-1)} \cos \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(62)

where \(c < 1\), \(\beta > 0\), \(\mu > -1/18(c-1)\), and \(\xi = x - ct\):

\[
u = \frac{3(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \cos \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(63)

where \(c < 1\), \(\beta > 0\), \(\mu < -1/18(c-1)\), and \(\xi = x - ct\):

\[
u = \frac{3(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \sin \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(64)

where \(c < 1\), \(\beta > 0\), \(\mu < 0\), and \(\xi = x - ct\):

\[
u = \frac{3(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \sin \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(65)

where \(c > 1\), \(\beta > 0\), \(\mu < 0\), and \(\xi = x - ct\):

\[
u = \frac{3(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \cos \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(66)

Under different parametric conditions solving (60), we obtain a series of exact traveling wave solutions as follows:

\[
u = \frac{6(c-1) \text{sech}^2 \left(\frac{(1/2)\sqrt{(c-1)/\beta}\xi}{2\alpha + 9\alpha\mu(c-1)}\right)}{1 \pm \tanh \left(\frac{(1/2)\sqrt{(c-1)/\beta}\xi}{2\alpha + 9\alpha\mu(c-1)}\right)},
\]  

(67)

where \(c < 1\), \(\beta > 0\), \(\mu < 0\), and \(\xi = x - ct\):

\[
u = \frac{6(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \cos \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(68)

where \(c > 1\), \(\beta > 0\), \(\mu < 0\), and \(\xi = x - ct\):

\[
u = \frac{3(c-1)}{\alpha \left[1 - \sqrt{18\mu(c-1)} \sin \left(\frac{(c-1)/\beta\xi}{2}\right)\right]},
\]  

(69)

where \(\beta > 0\), \(\mu < 0\), and \(\xi = x - (1 - (1/18\mu))t\).

Among these exact travelling wave solutions obtained in Section 4.1, it is worth pointing that the solutions (60) and (63) describe smooth solitary waves and the solution (67) describes kink wave and antikink wave (Figure 4). In order to show the dynamic profiles of solutions (60) and (63), we plot their graphs for \(\alpha = 0.5, \beta = 0.8, c = 5\), and \(t = 0.1\), which are shown in Figures 3(a) and 3(b).

4.2. Exact Traveling Wave Solutions for the Constants \(g \neq 0\) and \(h = 0\). When \(g \neq 0\) and \(h = 0\), (58) can be reduced to

\[-gu + \frac{1}{2} (1-c) u^2 + \frac{1}{6} \alpha u^3 + \frac{1}{4} \mu^2 u^4 + \frac{1}{2} \beta \left(\frac{du}{d\xi}\right)^2 = 0.
\]  

(69)

If \(\beta\mu < 0\), then (69) can be rewritten as

\[
\frac{du}{\sqrt{u \left[u^3 + (2/3\alpha\mu) u^2 - (2(1-c)/\mu^2) u - (4g/\mu^2)\right]}} = \pm \alpha \sqrt{-\frac{\mu}{2\beta}} d\xi.
\]  

(70)

By using factoring method, (70) can be rewritten in the following two forms:

\[
\frac{du}{\sqrt{(u-0)(u-z_0)(u-z_1)(u-z_1)}} = \pm \alpha \sqrt{-\frac{\mu}{2\beta}} d\xi,
\]  

(71)

\[
\text{where } z_0, z_1, \text{ and } z_1 \text{ are roots of the equation } u^3 + (2/3\alpha\mu) u^2 - (2(1-c)/\mu^2) u - (4g/\mu^2) = 0 \text{ and the } z_0 \text{ is real root; the } z_1, z_1 \text{ are conjugate complex roots. } z_0, z_1, \text{ and } z_1 \text{ can be expressed by the parameters } \alpha, \mu, \beta, \text{ and } g. \text{ and here we would like to point out that the expression of } z_1, z_1 \text{ depends on the parameters } \alpha, \mu, \beta, \text{ and } g.
\]
Figure 3: The graphs of profiles for smooth solitary wave solutions defined by (60) and (63) under different parametric values: (a) $\mu = 0.7$; (b) $\mu = 2$.

Figure 4: The graphs of profiles for kink wave and antikink wave solutions defined by (67) with “+” and “−”.

omitting their expressions because they are very complex. But we can always obtain their values by using computer once the parameters $\alpha$, $\mu$, $c$, and $g$ are fixed on concrete values. For example, taking $\alpha = 0.8$, $c = 5$, $\mu = -5$, $g = -4$, we get $z_0 = 1.204421920$, $z_1 = -0.6855442934 + 1.918696998i$, and $\overline{z_1} = -0.6855442934 - 1.918696998i$; taking $\alpha = 0.8$, $c = 5$, $\mu = -5$, $g = 4$, we get $z_0 = -1.276547333$, $z_1 = 0.5549403329 + 1.899690937i$, and $\overline{z_1} = 0.5549403329 + 1.899690937i$. 
Solving (71) and (72), we obtain two periodic wave solutions of (1) as follows:

\[\begin{align*}
u &= z_0 |z_1| \left[ cn(\tilde{\omega}_1, m_1) + 1 \right] \\
&\times \left( |z_1| |cn(\tilde{\omega}_1, m_1) + 1 \right) \\
&\times \sqrt{z_0^2 - 2z_0 \cdot Re(z_1) + |z_1|^2 [cn(\tilde{\omega}_1, m_1) + 1]}^{-1},
\end{align*}\]

(73)

where

\[\tilde{\omega}_1 = \alpha \sqrt{\mu |z_1| \sqrt{z_0^2 - 2z_0 \cdot Re(z_1) + |z_1|^2}} / 2\beta,\]

\[m_1 = \frac{1}{2} \left[ 2|z_1|^2 - 2z_0 \cdot Re(z_1) + 2|z_1| \sqrt{z_0^2 - 2z_0 \cdot Re(z_1) + |z_1|^2} \right].\]

(74)

If \( \beta \mu > 0 \), then (69) can be rewritten as

\[\begin{align*}
du &= \mu u^3 + (2/3\mu \alpha) u^2 - (2(c - 1)/\mu \alpha^2) u - (4g/\mu \alpha^2)] \\
= \pm \sqrt{\frac{\mu}{2\beta}} d\xi.
\end{align*}\]

(75)

By using factoring method, (75) can be rewritten in the following two forms:

\[\begin{align*}
\frac{du}{\sqrt{(0 - u)(u - z_0)(u - z_1)(u - z_1)}} &= \pm \alpha \sqrt{\frac{\mu}{2\beta}} d\xi, \\
(z_0 < 0)
\end{align*}\]

(76)

or

\[\begin{align*}
\frac{du}{\sqrt{(z_0 - u)(u - 0)(u - z_1)(u - z_1)}} &= \pm \alpha \sqrt{\frac{\mu}{2\beta}} d\xi, \\
(z_0 > 0)
\end{align*}\]

(77)

where \( z_0, z_1, \) and \( z_1 \) are same as the above case.

Solving (76) and (77), we obtain two periodic wave solutions of (1) as follows:

\[u = z_0 |z_1| [1 + cn(\tilde{\omega}_2, m_2)] \\
\times \left( |z_1| [1 + cn(\tilde{\omega}_2, m_2)] \\
+ \sqrt{z_0^2 - 2z_0 \cdot Re(z_1) + |z_1|^2 [1 - cn(\tilde{\omega}_2, m_2)]} \right)^{-1},
\]

(78)

4.3. Exact Traveling Wave Solutions for the Constants \( g \neq 0 \) and \( h \neq 0 \). When \( g \neq 0 \) and \( h \neq 0 \), (81) can be rewritten as

\[\begin{align*}
du &= \frac{\mu u^2}{2\beta} \left[ u^4 + \frac{2}{3\mu \alpha} u^3 - \frac{2(c - 1)}{\mu \alpha^2} u^2 \\
&\quad - \frac{4g}{\mu \alpha^2} u - \frac{4h}{\mu \alpha^2} \right]^{1/2} \\
&= \pm \sqrt{\frac{\mu}{2\beta}} d\xi.
\end{align*}\]

(81)

The types of solutions of (81) contain many cases due to the roots of the quartic equation \( u^4 + (2/3\mu \alpha) u^3 - (2(c - 1)/\mu \alpha^2) u^2 - (4g/\mu \alpha^2) u - (4h/\mu \alpha^2) = 0 \) which is in (81) and have many possibilities, but all solutions of (1) under different kinds of cases are periodic solutions of Jacobi elliptic function type such as the forms of solutions (73), (78), and (79). For convenience to discuss, here we only consider one case which this quartic equation has four real roots. Obviously, we can always obtain the real roots of this quartic equation by using computer once the parameters \( \alpha, \beta, \mu, c, g, \) and \( h \) are fixed on concrete values. Supposing \( \phi_1, \phi_2, \phi_3, \) and \( \phi_4 \) are four real roots of this quartic equation, we will obtain different kinds of periodic wave solutions of Jacobian elliptic function type for (1); see the following discussions.

Case 1. Under \( \beta \mu < 0 \), respectively, taking different root of the \( \phi_1, \phi_2, \phi_3, \) and \( \phi_4 \) as initial value to integrate (81) yields

\[\begin{align*}
\int^\xi_{\phi_1} \left( \frac{d\tilde{u}}{\sqrt{(\tilde{u} - \phi_1)(\tilde{u} - \phi_2)(\tilde{u} - \phi_3)(\tilde{u} - \phi_4)}} \right) &= \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\tilde{\xi},
\end{align*}\]

(82)

where \( u > \phi_1 > \phi_2 > \phi_3 > \phi_4 \) and

\[\begin{align*}
\int^\phi_{\phi_1} \left( \frac{d\tilde{u}}{\sqrt{(\phi_1 - \tilde{u})(\phi_2 - \tilde{u})(\phi_3 - \tilde{u})(\phi_4 - \tilde{u})}} \right) &= \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\phi d\tilde{\xi},
\end{align*}\]

(83)
where \( \phi_1 > \phi_2 > u \geq \phi_3 > \phi_4 \) and
\[
\int_{\phi_1}^{\phi_2} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\phi_2 - \bar{u})(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(84)

where \( \phi_1 > \phi_2 \geq u \geq \phi_3 > \phi_4 \) and
\[
\int_{u}^{\phi_2} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\phi_2 - \bar{u})(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(85)

where \( \phi_1 > \phi_2 > u > \phi_3 > \phi_4 > u \).

Respectively, completing the above integrals in (82), (83), (84), and (85), we obtain four periodic wave solutions of Jacobian elliptic function type of (1) as follows:
\[
u = \frac{(\phi_1\phi_2 - \phi_3\phi_4)\text{sn}^2(\Omega_1, k_1) + (\phi_1\phi_3 - \phi_1\phi_2)}{(\phi_1 - \phi_3)\text{sn}^2(\Omega_1, k_1)} + (\phi_1 - \phi_2),
\]
\[
u = \frac{(\phi_1\phi_2 - \phi_3\phi_4)\text{sn}^2(\Omega_1, k_1) + (\phi_2\phi_3 - \phi_1\phi_2)}{(\phi_1 - \phi_2)\text{sn}^2(\Omega_1, k_1) + (\phi_1 - \phi_2)},
\]
\[
u = \frac{(\phi_2\phi_3 - \phi_3\phi_4)\text{sn}^2(\Omega_1, k_1) + (\phi_1\phi_3 - \phi_1\phi_2)}{(\phi_1 - \phi_3)\text{sn}^2(\Omega_1, k_1)} + (\phi_1 - \phi_2),
\]
\[
u = \frac{(\phi_1\phi_2 - \phi_3\phi_4)\text{sn}^2(\Omega_1, k_1) + (\phi_1\phi_3 - \phi_1\phi_2)}{(\phi_1 - \phi_3)\text{sn}^2(\Omega_1, k_1) + (\phi_1 - \phi_2)},
\]
(86)

where \( \Omega_1 = \pm(\alpha/2)\sqrt{-\mu(\phi_1 - \phi_2)(\phi_2 - \phi_3)/2\beta} \) and \( k_1 = \sqrt{(\phi_2 - \phi_3)(\phi_1 - \phi_2)/(\phi_1 - \phi_3)(\phi_2 - \phi_3)} \).

Case 2. Under \( \beta_2 > 0 \), respectively, taking different root of the \( \phi_1, \phi_2, \phi_3, \) and \( \phi_4 \) as initial value to integrate (81) yields
\[
\int_{\phi_1}^{\phi_2} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\bar{u} - \phi_2)(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(87)

where \( \phi_1 > u \geq \phi_2 > \phi_3 > \phi_4 \) and
\[
\int_{u}^{\phi_2} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\bar{u} - \phi_2)(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(88)

where \( \phi_1 \geq u > \phi_2 > \phi_3 > \phi_4 \) and
\[
\int_{u}^{\phi_3} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\phi_2 - \bar{u})(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(89)

where \( \phi_1 > \phi_2 > \phi_3 > u \geq \phi_4 \) and
\[
\int_{\phi_1}^{\phi_3} \frac{d\bar{u}}{(\phi_1 - \bar{u})(\phi_2 - \bar{u})(\bar{u} - \phi_3)(\bar{u} - \phi_4)} = \pm \alpha \sqrt{\frac{\mu}{2\beta}} \int_0^\xi d\overline{\xi},
\]
(90)

where \( \phi_1 > \phi_2 > \phi_3 \geq u > \phi_4 \).

Similarly completing the above integrals in (87), (88), (89), and (90), we obtain another four periodic wave solutions of Jacobian elliptic function type of (1) as follows:
\[
u = \frac{(\phi_1\phi_4 - \phi_1\phi_3)\text{sn}^2(\Omega_1, k_2) + (\phi_2\phi_3 - \phi_1\phi_4)}{(\phi_1 - \phi_2)\text{sn}^2(\Omega_2, k_2) + (\phi_2 - \phi_4)},
\]
\[
u = \frac{(\phi_1\phi_3 - \phi_1\phi_2)\text{sn}^2(\Omega_1, k_2) + (\phi_2\phi_3 - \phi_1\phi_2)}{(\phi_1 - \phi_2)\text{sn}^2(\Omega_2, k_2) + (\phi_2 - \phi_4)},
\]
\[
u = \frac{(\phi_2\phi_3 - \phi_2\phi_4)\text{sn}^2(\Omega_1, k_2) + (\phi_3\phi_4 - \phi_2\phi_3)}{(\phi_3 - \phi_4)\text{sn}^2(\Omega_2, k_2) + (\phi_4 - \phi_2)},
\]
\[
u = \frac{(\phi_3\phi_4 - \phi_1\phi_2)\text{sn}^2(\Omega_1, k_2) + (\phi_2\phi_3 - \phi_1\phi_2)}{(\phi_3 - \phi_4)\text{sn}^2(\Omega_2, k_2) + (\phi_4 - \phi_2)},
\]
(91)

where \( \Omega_2 = \pm(\alpha/2)\sqrt{-\mu(\phi_1 - \phi_2)(\phi_2 - \phi_3)/2\beta} \) and \( k_2 = \sqrt{(\phi_2 - \phi_3)(\phi_1 - \phi_2)/(\phi_1 - \phi_3)(\phi_2 - \phi_3)} \).

In Sections 4.2 and 4.3, all the exact solutions obtained by us are periodic solutions of Jacobian elliptic function types. As an example, we plot the graphs of profiles of the solutions (78) and (79) for \( \alpha = 0.3, \beta = 0.8, c = 1, \mu = 2, \) and \( t = 0.1, \) which are shown in Figures 5(a) and 5(b).

5. Conclusions

Though Frobenius’ idea is a well-known general method, it can solve some very complex PDE models with highly nonlinear terms and high order terms such as (1) when it combines with the integral bifurcation method. In this work, by using Frobenius’ idea together with integral bifurcation method, we study the third order nonlinear wave model (1). Under different kinds of parametric conditions, we obtain eight types of exact travelling wave solutions including the smooth solitary wave solutions (60), (63), and (65), the nonsmooth peakon wave solutions (51) and (57), the kink wave and antikink wave solutions (67) and (68), the smooth periodic wave solutions of trigonometric function type (14), (16), (21), (24), (28), (31), (34), (36), (38), (40), and (43), the nonsmooth periodic wave solutions of trigonometric function type (62), (64), and (66), the periodic wave solutions of Jacobian elliptic function type (78), (86), (91), and (92), the hyperbolic function solutions (13), (15), (20), (23), (27), (30), (33), (35), (44), and (61), and the rational function solution (45). Though the types of these solutions obtained in this work are not new and they are familiar types, the results of (1) obtained by us in this paper did not appear in any existing literatures. Particularly, compared with reference [45], all results obtained in this paper are new. Among these solutions obtained in this paper, some of them have direct
(a) Periodic wave defined by (78)  

(b) Periodic wave defined by (79)

Figure 5: The graphs of profiles for periodic wave solutions of Jacobin elliptic function types defined by (78) and (79) under different parametric values: (a) $g = 4$; (b) $g = -4$.

physical applications. For example, using the smooth solitary wave solutions, nonsmooth peakon wave solutions, and kink and antikink wave solutions, we can explain lots of motion phenomena for wave wave; indeed (1) is just a very important water wave model.

Conflict of Interests

The author declares that there is no conflict of interests regarding the publication of this paper.

Acknowledgments

This work is supported by the Natural Science Foundation of China under Grant no. 11361023, the Natural Science Foundation of Scientific and Technical Committee of Chongqing City under Grant no. cstc2014jcyjA00014, the Natural Science Foundation of Chongqing Normal University under Grant no. 13XLR20, and the Program Foundation of Chongqing Innovation Team Project in University under Grant no. KJTD201308.

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