Dynamic mechanical assessment of muscle hyperalgesia in humans: The dynamic algometer

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BACKGROUND: Musculoskeletal pain is often associated with a nonhomogeneous distribution of mechanical hyperalgesia. Consequently, new methods able to detect this distribution are needed.

OBJECTIVE: To develop and test a new method for assessing muscle hyperalgesia with high temporal and spatial resolution that provides complementary information compared with information obtained by traditional static pressure algometry.

METHODS: The dynamic pressure algometer was tested bilaterally on the tibialis anterior muscle in 15 healthy subjects and compared with static pressure algometry. The device consisted of a wheel that was rolled over the muscle tissue with a fixed velocity and different predefined forces. The pain threshold force was determined and pain intensity to a fixed-force stimulation was continuously rated on a visual analogue scale while the wheel was rolling over the muscle. The pressure pain sensitivity was evaluated before, during, and after muscle pain and hyperalgesia induced unilaterally by either injection of hypertonic saline (0.5 mL, 6%) into the tibialis anterior or eccentric exercise evoking delayed-onset muscle soreness (DOMS).

RESULTS: The intraclass correlation coefficient was >0.88 for the dynamic thresholds; thus, the method was reliable. Compared with baseline, both techniques detected hyperalgesia at the saline injection site and during DOMS (P<0.05). The dynamic algometer also detected the widespread, patchy distribution of sensitive loci during DOMS, which was difficult to evaluate using static pressure algometry.

DISCUSSION AND CONCLUSION: The present study showed that dynamic pressure algometry is a reliable tool for evaluating muscle hyperalgesia (threshold and pain rating) with high temporal and spatial resolution. It can be applied as a simple clinical bedside test and as a quantitative tool in pharmacological profiling studies.

Key Words: Hyperalgesia; Muscle pain; Pressure assessment

Musculoskeletal pain is often associated with scattered distribution of tenderness or mechanical hyperalgesia (eg, myofascial trigger points [1]). Generally, pressure hyperalgesia has been observed in many different patient populations (eg, whiplash, fibromyalgia and osteoarthritis [2-4]). Localized experimentally induced muscle hyperalgesia in healthy subjects can be generated by injections of algic substances (5) and after eccentric exercise inducing delayed-onset muscle soreness (DOMS) (6-8).

The most common tool to assess mechanical hyperalgesia is pressure algometry. A pressure algometer is a force gauge with a well-defined probe area in which the pressure needed to evoke pain can be recorded. Pressure algometry has been used for assessing musculoskeletal hyperalgesia in myofascial pain syndrome, tension-type headache, fibromyalgia and arthritis (9-12), enables the variability related to manual pressure application to be controlled (13), and has proven to be a valid and reproducible method (14-17). However, pressure algometry is applied to a localized area and requires many measurements to map sensitivity along a muscle (6) and eventually construct a pressure sensitivity map (18), which is an appropriate pain assessment in multiple clinical conditions. For example, with regard to neuropathic pain, it is well known that dynamic stroking of the skin (eg, by a brush with a given force applied at a given velocity over a distance on the skin [19,20]) is a way to provoke pain (alldynia) that cannot be assessed by a static stimulus applied to one fixed position. Furthermore, a recent study showed that persistent and constant pain can be caused by the rolling of a 1.75 kg custom-designed marble roll on the lower leg due to the slow adaptation properties of sensitized nociceptors (21). This study confirms the necessity to develop new tools for more dynamic musculoskeletal pain assessments that provide additional high-resolution temporal and spatial information about the head of the patient and its use as an additional tool in pharmacological profiling studies.

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The speed of the wheel was visually presented to the experimenter control-encoder (Bournes, USA) with a sensitivity of 64 pulses/revolution to a width of 5 mm. The wheel movement was recorded via a digital 5000 g) controlled by springs. The wheel had a diameter of 35 mm and different forces (450 g, 600 g, 800 g, 1300 g, 1500 g, 2100 g, 3400 g, 6000 g) were applied to the anterior muscle of both legs (Figure 1). The dynamic pressure algometer consists of a wheel through which the experimenter could apply eight different forces (450 g, 600 g, 800 g, 1300 g, 1500 g, 2100 g, 3400 g, 6000 g) controlled, with a force gradient of 0.3 kg/s (max force 20 kg). The subject pressed a button to indicate the pressure pain threshold (PPT). PPT was defined as the point at which a sensation of pressure changed into a sensation of pain. PPT measurements were performed with a 1.0 cm² probe on all the nine points. For each assessment, the measurement was repeated three times and the mean of these measurements was used in further calculations. An interval of minimum 30 s was kept between each PPT assessment.

Figure 1) A The dynamic pressure algometer. This device consists of a wheel that applies a specific force determined by a spring within the handle. The experimenter moves the algometer along the desired muscle at a constant velocity of 10 mm/s. An encoder is attached to the wheel and used to measure the distance (in cm) covered during the measurement, while the pain sensitivity is recorded by a electronic visual analogue scale. B Map of the sites for static pressure pain thresholds and dynamic pressure pain thresholds lines evaluated on the tibialis anterior muscle. The point of hypertonic saline injection is indicated in black.

manifestations of muscle hyperalgesia. The current study addresses this issue, using the concept of applying a moving pressure stimulus to a musculoskeletal structure in a standardized and quantitative manner. Consequently, the aims of the present study were: to evaluate a new assessment tool, the dynamic pressure algometer; to compare traditional static versus dynamic pressure algometry; and to apply the novel tool to assess quantitatively experimentally induced muscle hyperalgesia provoked by an exogenous (injection of hypertonic saline) and an endogenous (postexercise muscle soreness) pain model.

METHODS

Subjects
Fifteen healthy subjects (age range 23 to 32 years, mean [± SD] body mass index 23.4±1.1 kg/m², eight women) participated in the study. The recruited subjects were all students at Aalborg University (Aalborg, Denmark). The participants had no pain or other medical problems, were not taking any medications and did not engage in any major physical activity two days before the experiment. Written informed consent was obtained from each subject before inclusion in the study. The study was conducted in accordance with the Declaration of Helsinki and approved by the local ethics committee (N-2012-0030).

Dynamic pressure algometry
The dynamic pressure pain threshold (DPT) was assessed using the dynamic pressure algometer along three lines marked on the tibialis anterior muscle of both legs (Figure 1). The dynamic algometer consisted of a wheel through which the experimenter could apply eight different forces (450 g, 600 g, 800 g, 1300 g, 1500 g, 2100 g, 3400 g, 6000 g) controlled by springs. The wheel had a diameter of 35 mm and a width of 5 mm. The wheel movement was recorded via a digital encoder (Bournes, USA) with a sensitivity of 64 pulses/revolution to measure the distance covered during the rolling stimulation. The speed of the wheel was visually presented to the experimenter controlling the speed manually to approximately 10 mm/s. The wheel was moved on three parallel lines (6 cm) on the tibialis anterior muscle, with starting points 5 cm from the origin of the muscle and distance between the lines equal to 1.5 cm (Figure 1B). The lower weight was used first and increased until the subject perceived a sensation of pain after stimulation of the 6 cm lines. The assessment was repeated three times. The weight of the wheel, which induced pain for at least two of the three stimuli, was defined as the DPT. After the DPT assessment, the subject continuously scored the pain intensity during rolling stimula-
tion on the three lines with the DPT intensity on an electronic visual analogue scale (VAS) on which 0 cm indicated ‘no pain’ and 10 cm indicated ‘maximal pain’. The rolling distance and the VAS scores were sampled at 10 Hz, indicating a measurement step of 0.1 cm. The stimulus-response curve (VAS versus distance) was constructed, and the area under the curve (VAS-distance area) was extracted in MATLAB (Mathworks, USA).

Static pressure algometry
Pressure stimulation on the nine sites along the tibialis anterior muscle (Figure 1B) was applied perpendicularly to the skin surface by computer-controlled pressure algometry with a mechanical footplate (Aalborg University, Denmark). The pressure stimulation was force controlled, with a force gradient of 0.3 kg/s (max force 20 kg). The pressure-intensity profile was monitored by asking the subject to rate the pain using an electronic VAS every 30 s. The scores were between 0 cm (‘no pain’) and 10 cm (‘maximal pain’). The maximum VAS score and pain duration were extracted.

Exogenous muscle hyperalgesia model: Saline-induced pain
Sterile hypertonic saline (0.5 mL, 6%) was injected intramuscularly into the right tibialis anterior muscle because this is known to induce muscle pain and hyperalgesia (22). The saline was injected into the muscle belly of the tibialis anterior approximately one-third of the distance from the lateral tibial condyle and the talocrural joint, corresponding to point 5 in Figure 1B. Sterile hypertonic saline (0.5 mL, 6%) was injected over approximately 10 s after the skin had been cleaned with alcohol. The injection was performed using a 2 mL plastic syringe with a disposable needle (27 G). The pain-intensity profile was monitored by asking the subject to rate the pain using an electronic VAS every 30 s. The scores were between 0 cm (‘no pain’) and 10 cm (‘maximal pain’). The maximum VAS score and pain duration were extracted.

Endogenous muscle hyperalgesia model: DOMS
Three sets of right ankle eccentric plantar flexion were performed with 20 s rest in between. The subject stood on a 13 cm high metal platform with the heel of the right leg on the edge of the platform with the mid-foot extending over the edge (8). The palms of the subject were placed on the wall at shoulder level for support only. The subject performed a slow plantar flexion of the ankle allowing the forefoot to descend until the toes touched a soft foam cushion (2 cm thick) placed below the platform. Then the subject returned to the initial starting position (7). Subjects repeated this process 20 times per set. A seven-point Likert scale was used to assess soreness (1 = no soreness; 7 = unbearable soreness) one day after the exercise (23).

Protocol
The experiment was performed on two consecutive days. On the first day, the origin of the tibialis anterior muscle was located by palpation on both legs. DPTs and PPTs at baseline were measured. Exogenous muscle hyperalgesia was then induced by saline injection into the right tibialis anterior muscle, and DPTs and PPTs were remeasured 5 min after pain had disappeared (approximately 15 min after injection). Pilot experiments had shown that it was not possible to evaluate pain due to dynamic stimulation during the hypertonic saline effect because subjects were not able to distinguish between the pain due to the injection and the pain due to the stimulation per se. Following the assessments after saline-induced muscle pain, there was a 10 min break with complete rest. After the rest, the subject performed eccentric
exercise with the right tibialis anterior muscle to induce DOMS. On the second day, the pain sensitivity was monitored bilaterally using the same methods as at baseline of day 1.

Data analysis and statistics
The data are presented as means and SEM. All analyses were performed using STATISTICA (StatSoft Inc, USA). Based on previous studies with similar parameters reflecting the pressure pain sensitivity (24,25), approximately 15 participants were sufficient to assess the method's validity in the current study design.

Data passed the Kolmogorov-Smirnov test for normal distribution. The baseline DPTs were analyzed using a two-way repeated-measures ANOVA (RM-ANOVA) with the factors leg (left and right) and position (lines A, B, C). The VAS-distance area was analyzed using a three-way RM-ANOVA with the factors pain paradigm (baseline, injection, DOMS), leg (left and right) and position (lines A, B, C). PPTs were analyzed using a three-way RM-ANOVA with the factors pain paradigm (baseline, injection, DOMS), leg (left and right) and points (1 to 9). The Neuman-Keuls (NK) post hoc test was used when factors were significant. A Pearson's correlation analysis was used to assess relationships among PPTs and the corresponding VAS score from rolling stimulation at the same point in the experimental pain paradigm. The intrarater reliability was tested using a two-way mixed intraclass correlation coefficient (ICC) with absolute agreement (2.1), comparing the DPTs and VAS-distance area on leg and position. The results were interpreted according to established grading criteria: ICC <0.20 = poor, 0.21 to 0.40 = fair, 0.41 to 0.60 = moderate, 0.61 to 0.80 = good and 0.81 to 1.00 = very good (26). The sensitivity distribution was mapped, indicating a 15% pain sensitivity increase or decrease compared with baseline. P<0.05 was considered to be statistically significant.

RESULTS

DPTs
The DPTs detected at baseline were not significantly different, regardless of the leg or the assessment line being evaluated (Figure 2). For the left leg, mean (± SE) DPT values of 2.30±0.11 kg, 2.28±0.11 kg and 2.36±0.10 kg were observed for lines A, B and C, respectively. Similarly, for the right leg, mean DPT values of 2.58±0.12 kg, 2.54±0.12 kg and 2.62±0.13 kg were observed for lines A, B and C, respectively. The ICC coefficient was 0.88 for both legs.

Saline-induced muscle pain and DOMS
The maximum VAS score after injection of hypertonic saline was 7.6±2 cm and the pain duration was 450±60 s. All participants subjected to saline-induced muscle pain experienced local pain and two subjects reported that the pain referred to the corresponding ankle (data not shown). The Likert scale indicated that all the subjects developed DOMS one day after the eccentric exercise, with a mean score of 2.1±0.9.

Dynamic pressure algometry after induction of experimental muscle hyperalgesia
Before saline-induced pain, the VAS-distance area was, on average, 0.004±0.003 cm² during rolling mechanical stimulation with an intensity equal to the DPT level. The peak VAS during rolling mechanical stimulation was 2.2±0.2 cm at a position corresponding to the injection site of hypertonic saline (Figure 3). ANOVA of the VAS-distance area demonstrated a significant interaction among pain paradigm, leg and line position (F₄=9.1, P<0.01). Five minutes post-pain, the VAS-distance area corresponding to the line of the injection site on the right leg was significantly higher compared with the other two lines and with the other leg (NK: P<0.03).
The VAS peak at the dynamic pressure threshold on the DOMS leg was 2.0±0.4 cm over the muscle belly (line B, distance 3 cm equivalent to point 5) while no pain was felt on the unaffected leg (Figure 4A and 4B). The VAS-distance area one day after eccentric exercise showed a significant increase in the response from the DOMS leg compared with the corresponding area at baseline, regardless of the line of stimulation (NK: P<0.01).

Static PPTs
The ANOVA of PPTs showed a significant interaction among pain paradigm, leg and assessment site (F 16=15.6; P<0.05). The PPT obtained 5 min after saline-induced pain at the injection site was significantly decreased compared with the measurement at baseline and on the other leg (NK: P<0.03; Figure 5). The PPTs obtained after DOMS were significantly lower than the PPTs at baseline or on the unexercised leg, regardless of the point of stimulation (NK: P<0.05; Figure 5).

At baseline, the VAS score after rolling stimulation measured at the sites for PPT assessments correlated with the PPTs for all nine points (R=0.86, P<0.05). Five minutes after saline-induced pain, the most sensitive site was point 5 (the muscle belly) while the least sensitive site was point 9 (the most distal point from the tibial tuberosity). In the DOMS leg, PPTs and corresponding VAS scores after rolling stimulation did not correlate for any assessment points (P>0.10). The most sensitive site was point 5 for both the pressure algometry (Figure 6) and dynamic algometry (Figure 7) assessments. However, the VAS related to dynamic pain assessment showed the presence of sensitive loci, non-visible with the pressure algometry measurement (Figure 7).

DISCUSSION
The current study demonstrated that dynamic pressure algometry is a useful easy-to-use and reliable tool for quantitative evaluation of temporal and spatial aspects of dynamic muscle hyperalgesia (pain threshold and evoked pain ratings).
Eccentric exercise is a widely used method of endogenous pain induction. The hypertonic saline model has been used extensively to characterize the sensory and motor effects involved in muscle pain because the quality of the induced pain is comparable with acute clinical muscle pain and causes a dominant sensation of deep, diffuse pain with referred pain characteristics (14,33). The changes in the evoked somatosensory changes after experimental saline-induced pain are complex. Five minutes after saline-induced muscle pain, hyperalgesia to pressure was found 2 cm to 10 cm from the injection site, although it was not uniformly distributed (34,35). In addition, Qerama et al (36) observed decreases in PPTs at the injection site after the saline-induced pain had disappeared. In the present study, the stimulus response curve during dynamic algometry showed a peak in pain sensitivity at the point injected with hypertonic saline. This is in accordance with previous studies in which the injection site showed increased pain sensitivity 5 min after pain had disappeared (35). The other parts of the muscle and the other leg did not show hyperalgesia, in accordance with a previous study (22).

Dynamic pressure algometry after eccentric exercise
Eccentric exercise is a widely used method of endogenous pain induction in humans. Following this type of exercise, DOMS over the muscle tissue is present after 24 h to 48 h (17), allowing investigation of muscle hyperalgesia to be undertaken in this period. The mechanism underlying DOMS is likely related to ultrastructural tissue damage resulting in the release of algesic substances in the muscle and localized inflammatory processes (38).

Eccentric exercise is traditionally used to induce DOMS and can be utilized in both upper and lower limb muscles (30,39). Mechanical hyperalgesia is a hallmark of DOMS but is not evenly distributed over the affected muscle (8). The most commonly reported site of tenderness in DOMS is the mid-muscle belly region (30,39). Andersen et al (6) showed significantly decreased PPTs for muscle belly sites. Some variations in the spatial expression of hyperalgesia were found among test sites. In the present study, the site of hyperalgesia assessed by dynamic pressure algometry was spread along the tibialis anterior muscle, consistent with previous studies (6,8). While the muscle belly was a common site of maximal sensitivity, there was considerable variation in the spatial distribution among subjects. A widespread, patchy distribution of sensitive loci during DOMS has previously been demonstrated (30).

CONCLUSION
The developed dynamic pressure algometry is a new reliable and quantitative method for evaluating muscle hyperalgesia with high temporal and spatial resolution. This tool may provide complementary information compared with information achieved by traditional static pressure algometry. This method is easy to use as a clinical bedside test for examining patients with musculoskeletal pain and associated musculoskeletal hypersensitivity. The technique may also be used as a tool in pharmacological profiling studies. Further clinical studies are needed to investigate the diagnostic validity of possible differentiating responses to static and dynamic pressure algometry in different patient populations.

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Figure 6) Distribution of pressure pain threshold (n=15) changes assessed by the computer-controlled pressure algometer at the nine sites on the tibialis anterior muscle during delayed-onset muscle soreness. Open circles represent decreased sensitivity (15% increase of pressure pain threshold compared with baseline) and filled circles represent increased sensitivity (15% reduction of pressure pain threshold compared with baseline). × indicates the site of maximal sensitivity (i.e., the pressure pain threshold with the largest reduction) for each subject.

Figure 7) Distribution of pain sensitivity (visual analogue scale scores at the corresponding assessment site (n=15)) at the nine sites along the tibialis anterior muscle during delayed-onset muscle soreness. Open circles represent increased sensitivity (+15% compared with baseline) and filled circles represent decreased sensitivity (−15% compared with baseline). × indicates the site of maximal sensitivity (i.e., the visual analogue scale score with the largest increase) for each subject.
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