Oscillations for Neutral Functional Differential Equations

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We will consider a class of neutral functional differential equations. Some infinite integral conditions for the oscillation of all solutions are derived. Our results extend and improve some of the previous results in the literature.

1. Introduction

During the past few decades, neutral differential equations have been studied extensively and the oscillatory theory for these equations is well developed; see [1–19] and the references cited therein. In fact, the developments of oscillation theory for the neutral differential equations began in 1986 with the appearance of the paper of Ladas and Sficas [15]. A survey of the most significant efforts in this theory can be found in the excellent monographs of Győri and Ladas [12] and Agarwal et al. [1].

Consider the first-order neutral differential equations of the form

\[ [r(t)(x(t) + p x(t - \tau ))]' + q(t) x(t - \sigma ) = 0, \quad t \geq t_0, \]

(1)

where

\[ r, q \in C \left([t_0, \infty), (0, \infty)\right), \]

\[ p \in \mathbb{R}, \quad \tau \in (0, \infty), \quad \sigma \in \mathbb{R}^+. \]

(2)

There are numerous numbers of oscillation criteria obtained for oscillation of all solutions of (1). In particular, many various sufficient conditions for oscillation are established in [3–5, 9–15, 18, 19]. In reviewing the literature, (1) is much studied in the case when

\[ \int_{t_0}^{\infty} q(t) \, dt = \infty, \]

(3)

which has been considered as an essential condition for the oscillation.

However, Yu et al. [19] considered (1) when \( r(t) \equiv 1, p = -1 \) in the case when (3) does not hold (in this case (1) is said to have integrally small coefficients).

In [9], Gopalsamy et al. studied (1) when \( r(t) \equiv 1, -1 \leq p \leq 0 \) and proved that every solution of (1) is oscillatory if

\[ \lim_{{t \to \infty}} \inf \int_{{t-\sigma}}^{t} q(s) \, ds > 1 + p. \]

(4)

In [5], some finite integral conditions for oscillation of all solutions of (1) when \( r(t) \equiv 1 \) are given under less restrictive hypothesis on \( p \). See also Grammatikopoulos et al. [10], Ladas and Sficas [15], and Al-Amri [4].

Recently, Ahmed et al. [2, 3] investigated the oscillation behaviour of (1) and obtained some new oscillation results. Additional results on the oscillation behaviour of (1) can also be found in the articles of Kulenović et al. [14], Kubiaczyk and Saker [13], and Greaf et al. [11].

In [18], infinite integral conditions for oscillation of all solutions of (1) in the case when \( r(t) \equiv 1 \) are obtained when the coefficient \( p \) takes some different ranges. A primary purpose of this paper is to further study the oscillation of solutions of (1). Our results extend and generalize some of the relevant results in [1–19].

Define the functions \( \varepsilon(t) \) and \( \omega(t) \) as follows:

\[ \varepsilon(t) = x(t) + px(t - \tau), \]

(5)

\[ \omega(t) = z(t) + pz(t - \tau). \]

(6)

If \( x(t) \) is an eventually positive solution of the equation

\[ (x(t) + px(t - \tau))' + q(t) x(t - \sigma) = 0, \]

(7)
then $z(t)$ and $w(t)$ are also solutions of (7). Furthermore, $z(t)$ is a differentiable solution, while $w(t)$ is twice differentiable. (see Győri and Ladas [12]).

As usual, a solution of (1) is said to be oscillatory if it has arbitrarily large zeros and nonoscillatory if it is either eventually positive or eventually negative. Equation (1) is said to be oscillatory if all its solutions are oscillatory.

In the sequel, unless otherwise specified, when we write a functional inequality, we assume that it holds for all sufficiently large $t$.

2. Auxiliary Lemmas

To specify the proofs of our main results, we need the following essential lemmas.

**Lemma 1** (see [12]). Assume that (3) holds. Let $x(t)$ be an eventually positive solution of (7). Then

(a) $z(t)$ is a decreasing function and either

$$\lim_{t \to \infty} z(t) = -\infty,$$

or

$$\lim_{t \to \infty} z(t) = 0.$$

(b) The following statements are equivalent:

(i) Equation (8) holds;

(ii) $p < -1$;

(iii) $\lim_{t \to \infty} x(t) = \infty$;

(iv) $w(t) > 0, w'(t) > 0, w''(t) > 0$.

(c) The following statements are equivalent:

(i) Equation (9) holds;

(ii) $p > -1$;

(iii) $\lim_{t \to \infty} x(t) = 0$;

(iv) $w(t) > 0, w'(t) < 0, w''(t) > 0$.

**Lemma 2** (see [16]). Assume that

$$\lim_{t \to \infty} \sup \int_{t_i}^{t_i + \sigma} p_i(s) ds > 0,$$

for some $i$. (10)

If $x(t)$ is an eventually positive solution of the delay differential equation

$$x'(t) + \sum_{i=1}^{n} p_i(t) x(t - \tau_i) = 0,$$

(11)

then, for the same $i$,

$$\lim_{t \to \infty} \inf \frac{x(t - \tau_i)}{x(t)} < \infty.$$ (12)

3. Main Results

In this section, we establish some infinite integral conditions for all solutions of (1) to oscillate. We assume that condition (3) holds.

**Theorem 5.** Let conditions (2) and (3) hold with $-1 \leq p \leq 0$,

$$\int_{t_i}^{t_i + \sigma} q(s) r(s - \sigma) ds > 0,$$

(18)

$$\int_{t_0}^{\infty} \left[ \frac{q(t)}{r(t - \sigma)} \ln \left( e^{\int_{t_i}^{t_i + \sigma} \frac{q(s)}{r(s - \sigma)} ds} \right) \right] dt = \infty.$$ (19)

Then every solution of (1) is oscillatory.

**Proof.** Assume that (1) has a nonoscillatory solution on $[t_0, \infty)$. Then, without loss of generality, there is a $t_1 \in [t_0, \infty)$, sufficiently large, so that $x(t_1) > 0, x(t_1 - \sigma) > 0$ and $x(t_1) > x(t_1 - \sigma) > 0$ on $[t_1, \infty)$. Set $z(t)$ to be defined as in (5). Then by Lemma 1, it follows that

$$z(t) > 0.$$ (20)

As $x(t) > z(t)$, it follows from (1) that

$$(r(t) z(t))' + q(t) z(t - \sigma) \leq 0.$$ (21)

Dividing the last inequality by $r(t) > 0$, we obtain

$$z'(t) + \frac{r'(t)}{r(t)} z(t) + \frac{q(t)}{r(t)} z(t - \sigma) \leq 0.$$ (22)

Let

$$z(t) = \exp \left( -\int_{t_0}^{t} \frac{r'(s)}{r(s)} ds \right) y(t).$$ (23)
This implies that \( y(t) > 0 \). Substituting in (22) yields
\[
y'(t) + \frac{q(t)}{r(t-\sigma)}y(t-\sigma) \leq 0, \quad t \geq t_0. \tag{24}
\]
So by Lemma 4, we have that the delay differential equation
\[
y'(t) + \frac{q(t)}{r(t-\sigma)}y(t-\sigma) = 0, \quad t \geq t_0 \tag{25}
\]
has an eventually positive solution as well. Let
\[
\lambda(t) = -\frac{y'(t)}{y(t)}. \tag{26}
\]
Then \( \lambda(t) \) is positive and continuous, and there exists \( t_1 \geq t_0 \) such that \( y(t_1) > 0 \), and
\[
y(t) = y(t_1) \exp \left( -\int_{t_1}^{t} \lambda(s) \, ds \right). \tag{27}
\]
Furthermore, \( \lambda(s) \) satisfies the generalized characteristic equation
\[
\lambda(t) = \overline{Q}(t) \exp \left( \int_{t-\sigma}^{t} \lambda(s) \, ds \right), \tag{28}
\]
where
\[
\overline{Q}(t) = \frac{q(t)}{r(t-\sigma)}. \tag{29}
\]
Let
\[
Y(t) = \int_{t-\sigma}^{t} \overline{Q}(s) \, ds. \tag{30}
\]
Therefore
\[
\lambda(t) = \overline{Q}(t) \exp \left( \frac{1}{Y(t)} \int_{t-\sigma}^{t} \lambda(s) \, ds \right). \tag{31}
\]
Applying the inequality (cf. Erbe et al. [8, page 32]),
\[
e^{ax} \geq x + \frac{\ln(ea)}{a} \quad \forall x, a > 0, \tag{32}
\]
to (31), we have
\[
\lambda(t) \geq \overline{Q}(t) \left( \frac{1}{Y(t)} \int_{t-\sigma}^{t} \lambda(s) \, ds + \frac{\ln(eY(t))}{Y(t)} \right), \tag{33}
\]
or
\[
\lambda(t) \left( \int_{t-\sigma}^{t} \overline{Q}(s) \, ds \right) - \overline{Q}(t) \int_{t-\sigma}^{t} \lambda(s) \, ds \geq \overline{Q}(t) \left( \ln e \int_{t-\sigma}^{t} \overline{Q}(s) \, ds \right). \tag{34}
\]
Then, for \( B > T \), we have
\[
\int_{T}^{B} \lambda(t) \left( \int_{t-\sigma}^{t} \overline{Q}(s) \, ds \right) \, dt - \int_{T}^{B} \overline{Q}(t) \int_{t-\sigma}^{t} \lambda(s) \, ds \, dt \geq \int_{T}^{B} \overline{Q}(t) \left( \ln e \int_{t-\sigma}^{t} \overline{Q}(s) \, ds \right) \, dt. \tag{35}
\]
By interchanging the order of integration, we get
\[
\int_{T}^{B} \overline{Q}(t) \left( \int_{t-\sigma}^{t} \lambda(s) \, ds \right) \, dt \geq \int_{T}^{B-\sigma} \left( \int_{t}^{t+\sigma} \overline{Q}(t) \lambda(s) \, dt \right) \, ds. \tag{36}
\]
Hence
\[
\int_{T}^{B} \overline{Q}(t) \left( \int_{t-\sigma}^{t} \lambda(s) \, ds \right) \, dt \geq \int_{T}^{B-\sigma} \lambda(t) \left( \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt. \tag{37}
\]
Then
\[
\int_{T}^{B} \overline{Q}(t) \left( \int_{t-\sigma}^{t} \lambda(s) \, ds \right) \, dt \geq \int_{T}^{B-\sigma} \lambda(t) \left( \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt. \tag{38}
\]
From (35) and (38), we find that
\[
\int_{T}^{B} \lambda(t) \left( \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt \geq \int_{T}^{B-\sigma} \overline{Q}(t) \left( \ln e \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt. \tag{39}
\]
However, using Lemma 3, it follows that
\[
\int_{t}^{t+\sigma} \overline{Q}(s) \, ds < 1 \tag{40}
\]
eventually. Therefore, from (40) in (39), we get
\[
\int_{T}^{B} \lambda(t) \, dt \geq \int_{T}^{B-\sigma} \overline{Q}(t) \ln e \left( \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt. \tag{41}
\]
That is,
\[
\frac{y(B-\sigma)}{y(B)} \geq \int_{T}^{B} \overline{Q}(t) \ln e \left( \int_{t}^{t+\sigma} \overline{Q}(s) \, ds \right) \, dt, \tag{42}
\]
which implies by condition (19) that
\[
\lim_{t \to \infty} \frac{y(t-\sigma)}{y(t)} = \infty. \tag{43}
\]
On the other hand, from Lemma 2, we have
\[
\lim_{t \to \infty} \frac{y(t-\sigma)}{y(t)} < \infty. \tag{44}
\]
This is a contradiction with (43). The proof is complete. \( \square \)

**Example 6.** Consider the equation
\[
\left[ e^{t+1} \left( x(t) - \frac{1}{2} x(t-2) \right) \right]' + e^{-1} \left[ \frac{1 + t}{t} \right] x(t-1) = 0, \tag{45}
\]
\( t \geq e, \)
where
\[ r(t) = e^{r(t+1)}, \quad q(t) = e^{r(t-1)} \left[ 1 + \frac{t}{t} \right], \]
\[ p = -\frac{1}{2}, \quad \sigma = 1, \quad \tau = 2. \]  

(46)

Observe that
\[ \frac{q(t)}{r(t - \sigma)} = e^{r(t-1)} \left( 1 + \frac{1}{t} \right) e^{r(t+1)} = 1. \]

(47)

Then
\[
\int_{t_0}^{\infty} \left[ \frac{q(s)}{r(s - \sigma)} \ln \left( e \int_{t}^{s} \frac{q(s')}{r(s' - \sigma)} ds' \right) \right] dt
= \int_{e}^{\infty} \left[ \frac{1}{e} \left( 1 + \frac{1}{t} \right) \ln \left( e \int_{t}^{s+1} \frac{1}{e} \left( 1 + \frac{1}{s} \right) ds \right) \right] dt
\geq \frac{1}{e} \int_{e}^{\infty} \ln \left( 1 + \ln \left( 1 + \frac{1}{t} \right) \right) = \infty.
\]

(48)

All conditions of Theorem 5 are satisfied. Then all solutions of (45) oscillate.

**Theorem 7.** Let conditions (2) and (3) hold with \(-1 < p \), \( r(t) \equiv r > 0 \), \( \sigma > \tau \). Assume further that \( q(t) \) is \( \tau \)-periodic; \( \frac{1}{r(1 + p)} \int_{t}^{t+\sigma - \tau} q(s) ds > 0 \); \( \int_{t_0}^{\infty} \left[ \frac{q(t)}{r(1 + p)} \ln \left( e \int_{t}^{t+\sigma - \tau} \frac{q(s)}{r(s - \sigma)} ds \right) \right] dt = \infty. \)

(49)

(50)

Then every solution of (1) is oscillatory.

**Proof.** Assume that (1) has a nonoscillatory solution on \([t_0, \infty)\). Then, without loss of generality, there is a \( t_1 \in [t_0, \infty) \), sufficiently large, so that \( x(t) > 0 \), \( x(t - \tau) > 0 \) and \( x(t - \sigma) > 0 \) on \([t_1, \infty)\). Let \( z(t) \) and \( w(t) \) be defined as in (5) and (6). It is easily seen, by direct substituting, that \( z(t) \) and \( w(t) \) are also solutions of (1) when \( p \) and \( r \) are constants; that is
\[ rz'(t) + prz'(t - \tau) + q(t)z(t - \sigma) = 0, \]
\[ rw'(t) + prw'(t - \tau) + q(t)w(t - \sigma) = 0. \]

(51)

(52)

By Lemma 1, we have that \( z(t) \) is decreasing and \( w(t) > 0 \). Also, we have indeed that
\[ w'(t) = -\frac{1}{r} q(t) z(t - \sigma) - \frac{1}{r} q(t) z(t - \sigma - \tau) \]
\[ = -\frac{1}{r} q(t - \tau) z(t - \sigma - \tau) = w'(t - \tau). \]

(53)

Then
\[ w'(t) \geq w'(t - \tau). \]

Using (54) in (52) implies that
\[ r(1 + p) w'(t - \tau) + q(t) w(t - \sigma) \leq 0. \]

(55)

As \( p > -1 \), we have \( 1 + p > 0 \). Then
\[ w'(t - \tau) + \frac{1}{r(1 + p)} q(t) w(t - \sigma) \leq 0. \]

(56)

In view of the \( \tau \)-periodicity of \( q(t) \), (56) implies that
\[ w'(t) + \frac{1}{r(1 + p)} q(t) w(t - (\sigma + \tau)) \leq 0. \]

(57)

As \( w(t) \) is positive solution, so by Lemma 4, the delay differential equation
\[ w'(t) + \frac{1}{r(1 + p)} q(t) w(t - (\sigma + \tau)) = 0 \]
has an eventually positive solution as well. Let
\[ \lambda(t) = \frac{y'(t)}{y(t)}. \]

(59)

Then \( \lambda(t) \) is positive and continuous, and there exists \( t_1 \geq t_0 \) such that \( y(t_1) > 0 \), and
\[ y(t) = y(t_1) \exp \left( -\int_{t_1}^{t} \lambda(s) ds \right). \]

(60)

Furthermore, \( \lambda(s) \) satisfies the generalized characteristic equation
\[ \lambda(t) = \overline{Q}_1(t) \exp \left( \int_{t-\sigma+\tau}^{t} \lambda(s) ds \right), \]

(61)

where
\[ \overline{Q}_1(t) = \frac{q(t)}{r(1 + p)}. \]

(62)

Let
\[ Y_1(t) = \int_{t}^{t+\sigma - \tau} \overline{Q}_1(s) ds. \]

(63)

Therefore
\[ \lambda(t) = \overline{Q}_1(t) \exp \left( \frac{1}{Y_1(t)} \int_{t-\sigma+\tau}^{t} \lambda(s) ds \right). \]

(64)

Applying the inequality (32) to (64), we have
\[ \lambda(t) \geq \overline{Q}_1(t) \left( \frac{1}{Y_1(t)} \int_{t-\sigma+\tau}^{t} \lambda(s) ds + \ln \left( \frac{\exp(Y_1(t))}{Y_1(t)} \right) \right). \]

(65)
or
\[
\lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right) - Q_1(t) \int_{t-\tau}^{t-\sigma} \lambda(s)\,ds \\
\geq Q_1(t) \left( \ln e \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right).
\]

Then, for \( B > T \), we have
\[
\int_{T}^{B} \lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt - \int_{T}^{B} Q_1(t) \int_{t}^{t+\tau-\sigma} \lambda(s)\,ds\,dt \\
\geq \int_{T}^{B} Q_1(t) \left( \ln e \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (67)

By interchanging the order of integration, we get
\[
\int_{T}^{B} Q_1(t) \left( \int_{t}^{t+\tau-\sigma} \lambda(s)\,ds \right)\,dt \\
\geq \int_{T}^{B} \lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (68)

Hence
\[
\int_{T}^{B} Q_1(t) \left( \int_{t}^{t+\tau-\sigma} \lambda(s)\,ds \right)\,dt \\
\geq \int_{T}^{B} \lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (69)

Then
\[
\int_{T}^{B} Q_1(t) \left( \int_{t}^{t+\tau-\sigma} \lambda(s)\,ds \right)\,dt \\
\geq \int_{T}^{B} \lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (70)

From (67) and (70), we find that
\[
\int_{B-\sigma+\tau}^{B} \lambda(t) \left( \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt \\
\geq \int_{T}^{B} Q_1(t) \left( \ln e \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (71)

However, using Lemma 3, it follows that
\[
\int_{t}^{t+\tau-\sigma} Q_1(s)\,ds < 1
\] (72)

eventually. Therefore, from (72) in (71), we get
\[
\int_{B-\sigma+\tau}^{B} \lambda(t)\,dt \geq \int_{T}^{B} Q_1(t) \left( \ln e \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt
\] (73)

or
\[
\frac{y(B-(\sigma-\tau))}{y(B)} \geq \int_{T}^{B} Q_1(t) \left( \ln e \int_{t}^{t+\tau-\sigma} Q_1(s)\,ds \right)\,dt.
\] (74)

which implies by condition (50) that
\[
\lim_{t \to \infty} \frac{y(t-(\sigma-\tau))}{y(t)} = \infty.
\] (75)

On the other hand, from Lemma 2, we have
\[
\lim_{t \to \infty} \frac{y(t-\sigma)}{y(t)} < \infty.
\] (76)

This is a contradiction with (75). The proof is complete. \(\square\)

**Example 8.** Consider the equation
\[
\left( x(t) - \frac{1}{2} x(t-\pi) \right)' + (1 + \cos 2t) x(t-2\pi) = 0, \quad t > 0,
\] (77)

where
\[
-1 \leq p = -\frac{1}{2}, \quad \sigma = 2\pi, \quad \tau = \pi,
\] (78)

\[
r(t) = 1, \quad q(t) = 1 + \cos 2t.
\]

Observe that
\[
\frac{1}{r(1+p)} \int_{t}^{t+\pi} q(s)\,ds = \frac{1}{1-1/2} \int_{t}^{t+\pi} (1 + \cos 2s)\,ds \\
= 2 \left[ \frac{s+1}{2} \sin 2s \right]_{t}^{t+\pi} \\
= 2 (t+\pi-t + \sin 2(t+\pi) - \sin 2t) \\
= 2(\pi+\sin 2t-\sin 2t) = 2\pi > 0.
\] (79)

Also,
\[
\int_{t}^{\infty} \left[ \frac{q(t)}{r(1+p)} \ln \left( e \int_{t}^{t+\pi} q(s)\,ds \right) \right]\,dt \\
= \int_{0}^{\infty} 2(1+\cos 2t) \ln \left( e \int_{t}^{t+\pi} (1 + \cos 2s)\,ds \right)\,dt \\
= \int_{0}^{\infty} 2(1+\cos 2t) \\
\times \left[ 1 + \ln \left( 2 \int_{t}^{t+\pi} (1 + \cos 2s)\,ds \right) \right] \,dt \\
= 2(1+\ln 2\pi) \int_{0}^{\infty} (1 + \cos 2t)\,dt \\
= 2(1+\ln 2\pi) \left( t + \frac{1}{2} \sin 2t \right)_{0}^{\infty} = \infty.
\] (80)

Then all conditions of Theorem 7 are satisfied and therefore all solutions of (77) oscillate.
Remark 9. Theorems 5 and 7 generalize and extend Theorems 3.1 and 3.2 of Saker and Elabbasy [18], respectively, and Theorem 6.4.3 in Győri and Ladas [12], where \( r(t) \equiv 1 \). See also the results of Ahmed et al. [2] and Kubiaczyk and Saker [13].

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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