Research Article

# On $\phi$-Recurrent Para-Sasakian Manifold Admitting Quarter-Symmetric Metric Connection 

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We obtained the relation between the Riemannian connection and the quarter-symmetric metric connection on a para-Sasakian manifold. Further, we study $\phi$-recurrent and concircular $\phi$-recurrent para-Sasakian manifolds with respect to quarter-symmetric metric connection.

## 1. Introduction

The idea of metric connection with torsion in a Riemannian manifold was introduced by Hayden [1]. Further, some properties of semisymmetric metric connection have been studied by Yano [2]. In [3], Golab defined and studied quarter-symmetric connection on a differentiable manifold with affine connection, which generalizes the idea of semisymmetric connection. Various properties of quarter-symmetric metric connection have been studied by many geometers like Rastogi [4,5], Mishra and Pandey [6], Yano and Imai [7], De et al. [8, 9], Pradeep Kumar et al. [10], and many others.

The notion of local symmetry of a Riemannian manifold has been weakened by many authors in several ways to a different extent. As a weaker version of local symmetry, Takahashi [11] introduced the notion of local $\phi$-symmetry on a Sasakian manifold. Generalizing the notion of $\phi$-symmetry, the authors De et al. [12] introduced the notion of $\phi$ recurrent Sasakian manifolds.

A linear connection $\tilde{\nabla}$ on an $n$-dimensional differentiable manifold is said to be a quarter-symmetric connection [3] if its torsion tensor $T$ is of the form

$$
\begin{equation*}
T(X, Y)=\tilde{\nabla}_{X} Y-\tilde{\nabla}_{Y} X-[X, Y]=\eta(Y) \phi X-\eta(X) \phi Y \tag{1.1}
\end{equation*}
$$

where $\eta$ is a 1-form and $\phi$ is a tensor of type $(1,1)$. In particular, if we replace $\phi X$ by $X$ and $\phi Y$ by $\Upsilon$, then the quarter-symmetric connection reduces to the semisymmetric connection [13]. Thus, the notion of quarter-symmetric connection generalizes the idea of the semisymmetric connection. And if quarter-symmetric linear connection $\widetilde{\nabla}$ satisfies the condition

$$
\begin{equation*}
\left(\tilde{\nabla}_{X} g\right)(Y, Z)=0 \tag{1.2}
\end{equation*}
$$

for all $X, Y, Z \in \mathcal{X}(M)$, where $X(M)$ is the Lie algebra of vector fields on the manifold $M$, then $\tilde{\nabla}$ is said to be a quarter-symmetric metric connection.

## 2. Preliminaries

An $n$-dimensional differentiable manifold $M$ is called an almost paracontact manifold if it admits an almost paracontact structure $(\phi, \xi, \eta)$ consisting of a $(1,1)$ tensor field $\phi$, a vector field $\xi$, and a 1 -form $\eta$ satisfying

$$
\begin{gather*}
\phi^{2} X=X-\eta(X) \xi,  \tag{2.1}\\
\eta(\xi)=1, \quad \phi \circ \xi=0, \quad \eta \circ \phi=0 . \tag{2.2}
\end{gather*}
$$

If $g$ is a compatible Riemannian metric with $(\phi, \xi, \eta)$, that is,

$$
\begin{gather*}
g(\phi X, \phi Y)=g(X, Y)-\eta(X) \eta(Y), \quad g(X, \xi)=\eta(X)  \tag{2.3}\\
g(X, \phi Y)=g(\phi X, Y) \tag{2.4}
\end{gather*}
$$

for all vector fields $X$ and $Y$ on $M$, then $M$ becomes a almost paracontact Riemannian manifold equipped with an almost paracontact Riemannian structure ( $\phi, \xi, \eta, g$ ).

An almost paracontact Riemannian manifold is called a para-Sasakian manifold if it satisfies

$$
\begin{equation*}
\left(\nabla_{X} \phi\right) Y=-g(X, Y) \xi-\eta(Y) X+2 \eta(X) \eta(Y) \xi \tag{2.5}
\end{equation*}
$$

where $\nabla$ denotes the operator of covariant differentiation. From the above equation it follows that

$$
\begin{equation*}
\nabla_{X} \xi=\phi X, \quad\left(\nabla_{X} \eta\right) Y=g(X, \phi Y)=\left(\nabla_{Y} \eta\right) X \tag{2.6}
\end{equation*}
$$

In an $n$-dimensional para-Sasakian manifold $M$, the following relations hold $[14,15]$ :

$$
\begin{gather*}
\eta(R(X, Y) Z)=g(X, Z) \eta(Y)-g(Y, Z) \eta(X)  \tag{2.7}\\
R(X, Y) \xi=\eta(X) Y-\eta(Y) X  \tag{2.8}\\
S(X, \xi)=-(n-1) \eta(X)  \tag{2.9}\\
S(\phi X, \phi Y)=S(X, Y)+(n-1) \eta(X) \eta(Y) \tag{2.10}
\end{gather*}
$$

for any vector fields $X, Y$, and $Z$, where $R$ and $S$ are the Riemannian curvature tensor and the Ricci tensor of $M$, respectively.

A para-Sasakian manifold $M$ is said to be $\eta$-Einstein if its Ricci tensor $S$ is of the form

$$
\begin{equation*}
S(X, Y)=a g(X, Y)+b \eta(X) \eta(Y) \tag{2.11}
\end{equation*}
$$

for any vector fields $X$ and $Y$, where $a$ and $b$ are some functions on $M$.
Definition 2.1. A para-Sasakian manifold is said to be locally $\phi$-symmetric if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} R\right)(X, Y) Z\right)=0 \tag{2.12}
\end{equation*}
$$

for all vector fields $X, Y, Z, W$ orthogonal to $\xi$. This notion was introduced for Sasakian manifold by Takahashi [11].

Definition 2.2. A para-Sasakian manifold is said to be locally concircular $\phi$-symmetric if

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} \bar{C}\right)(X, Y) Z\right)=0 \tag{2.13}
\end{equation*}
$$

for all vector fields $X, Y, Z, W$ orthogonal to $\xi$. Where the concircular curvature tensor $\bar{C}$ is given by [16]

$$
\begin{equation*}
\bar{C}(X, Y) Z=R(X, Y) Z-\frac{r}{n(n-1)}[g(Y, Z) X-g(X, Z) Y] \tag{2.14}
\end{equation*}
$$

where $R$ is the Riemannian curvature tensor and $r$ is the scalar curvature.
Definition 2.3. A para-Sasakian manifold is said to be $\phi$-recurrent if there exists a nonzero 1-form $A$ such that

$$
\begin{equation*}
\phi^{2}\left(\left(\nabla_{W} R\right)(X, Y) Z\right)=A(W) R(X, Y) Z \tag{2.15}
\end{equation*}
$$

where $A$ is a 1 -form and it is defined by

$$
\begin{equation*}
A(W)=g(W, \rho) \tag{2.16}
\end{equation*}
$$

and $\rho$ is a vector field associated with the 1 -form $A$.

## 3. Quarter-Symmetric Metric Connection

Let $\tilde{\nabla}$ be a linear connection and $\nabla$ a Riemannian connection of an almost contact metric manifold $M$ such that

$$
\begin{equation*}
\tilde{\nabla}_{X} Y=\nabla_{X} Y+U(X, Y) \tag{3.1}
\end{equation*}
$$

where $U$ is a tensor of type $(1,1)$. For $\widetilde{\nabla}$ to be a quarter-symmetric metric connection in $M$, then we have [3]

$$
\begin{gather*}
U(X, Y)=\frac{1}{2}\left[T(X, Y)+T^{\prime}(X, Y)+T^{\prime}(Y, X)\right]  \tag{3.2}\\
g\left(T^{\prime}(X, Y), Z\right)=g(T(Z, X), Y) \tag{3.3}
\end{gather*}
$$

From (1.1) and (3.3), we get

$$
\begin{equation*}
T^{\prime}(X, Y)=\eta(X) \phi Y-g(\phi X, Y) \xi \tag{3.4}
\end{equation*}
$$

Using (1.1) and (3.4) in (3.2), we obtain

$$
\begin{equation*}
U(X, Y)=\eta(Y) \phi X-g(\phi X, Y) \xi \tag{3.5}
\end{equation*}
$$

Thus a quarter-symmetric metric connection $\tilde{\nabla}$ in a para-Sasakian manifold is given by

$$
\begin{equation*}
\tilde{\nabla}_{X} Y=\nabla_{X} Y+\eta(Y) \phi X-g(\phi X, Y) \xi \tag{3.6}
\end{equation*}
$$

Hence (3.6) is the relation between Riemannian connection and the quarter-symmetric metric connection on a para-Sasakian manifold.

A relation between the curvature tensor of $M$ with respect to the quarter-symmetric metric connection $\tilde{\nabla}$ and the Riemannian connection $\nabla$ is given by

$$
\begin{align*}
\tilde{R}(X, Y) Z= & R(X, Y) Z+3 g(\phi X, Z) \phi Y-3 g(\phi Y, Z) \phi X+\eta(Z)[\eta(X) Y-\eta(Y) X]  \tag{3.7}\\
& -[\eta(X) g(Y, Z)-\eta(Y) g(X, Z)] \xi
\end{align*}
$$

where $\tilde{R}$ and $R$ denote the Riemannian curvatures of the connections $\tilde{\nabla}$ and $\nabla$, respectively. From (3.7), it follows that

$$
\begin{equation*}
\tilde{S}(Y, Z)=S(Y, Z)+2 g(Y, Z)-(n+1) \eta(Y) \eta(Z) \tag{3.8}
\end{equation*}
$$

where $\widetilde{S}$ and $S$ are the Ricci tensors of the connections $\tilde{\nabla}$ and $\nabla$, respectively.
Contracting (3.8), we get

$$
\begin{equation*}
\tilde{r}=r+(n-1) \tag{3.9}
\end{equation*}
$$

where $\tilde{r}$ and $r$ are the scalar curvatures of the connections $\tilde{\nabla}$ and $\nabla$, respectively.

## 4. $\phi$-Recurrent Para-Sasakian Manifold with respect to Quarter-Symmetric Metric Connection

A para-Sasakian manifold is called $\phi$-recurrent with respect to the quarter-symmetric metric connection if its curvature tensor $\widetilde{R}$ satisfies the condition

$$
\begin{equation*}
\phi^{2}\left(\left(\widetilde{\nabla}_{W} \widetilde{R}\right)(X, Y) Z\right)=A(W) \widetilde{R}(X, Y) Z \tag{4.1}
\end{equation*}
$$

By virtue of (2.1) and (4.1), we have

$$
\begin{equation*}
\left(\widetilde{\nabla}_{W} \widetilde{R}\right)(X, Y) Z-\eta\left(\left(\widetilde{\nabla}_{W} \widetilde{R}\right)(X, Y) Z\right) \xi=A(W) \widetilde{R}(X, Y) Z \tag{4.2}
\end{equation*}
$$

From which, it follows that

$$
\begin{equation*}
g\left(\left(\tilde{\nabla}_{W} \tilde{R}\right)(X, Y) Z, U\right)-\eta\left(\left(\widetilde{\nabla}_{W} \widetilde{R}\right)(X, Y) Z\right) g(\xi, U)=A(W) g(\widetilde{R}(X, Y) Z, U) \tag{4.3}
\end{equation*}
$$

Let $\left\{e_{i}\right\}, i=1,2, \ldots, n$ be an orthonormal basis of the tangent space at any point of the manifold. Then putting $X=U=e_{i}$ in (4.3) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \tilde{S}\right)(Y, Z)-\sum_{i=1}^{n} \eta\left(\left(\tilde{\nabla}_{W} \tilde{R}\right)\left(e_{i}, Y\right) Z\right) \eta\left(e_{i}\right)=A(W) \widetilde{S}(Y, Z) \tag{4.4}
\end{equation*}
$$

The second term of (4.4) by putting $Z=\xi$ takes the form

$$
\begin{align*}
g\left(\left(\tilde{\nabla}_{W} \tilde{R}\right)\left(e_{i}, Y\right) \xi, \xi\right)= & g\left(\tilde{\nabla}_{W} \tilde{R}\left(e_{i}, Y\right) \xi, \xi\right)-g\left(\tilde{R}\left(\tilde{\nabla}_{W} e_{i}, Y\right) \xi, \xi\right) \\
& -g\left(\widetilde{R}\left(e_{i}, \tilde{\nabla}_{W} Y\right) \xi, \xi\right)-g\left(\widetilde{R}\left(e_{i}, Y\right) \tilde{\nabla}_{W} \xi, \xi\right) \tag{4.5}
\end{align*}
$$

On simplification we obtain

$$
\begin{equation*}
g\left(\left(\tilde{\nabla}_{W} \tilde{R}\right)\left(e_{i}, Y\right) Z, \xi\right)=0 \tag{4.6}
\end{equation*}
$$

Therefore (4.4) can be written in the form

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \tilde{S}\right)(Y, Z)=A(W) \widetilde{S}(Y, Z) \tag{4.7}
\end{equation*}
$$

Replacing $Z$ by $\xi$ in the above relation, then using (3.8) and (2.9), we have

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \tilde{S}\right)(Y, \xi)=-2(n-1) A(W) \eta(Y) \tag{4.8}
\end{equation*}
$$

We know that

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \tilde{S}\right)(Y, \xi)=\tilde{\nabla}_{W} \tilde{S}(Y, \xi)-\tilde{S}\left(\tilde{\nabla}_{W} Y, \xi\right)-\widetilde{S}\left(Y, \tilde{\nabla}_{W} \xi\right) \tag{4.9}
\end{equation*}
$$

Using (3.8), (2.6) and (2.9) in the above relation, we get

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \widetilde{S}\right)(Y, \xi)=-4(n-1) g(Y, \phi W)-2 S(Y, \phi W)+4 g(Y, \phi W) \tag{4.10}
\end{equation*}
$$

In view of (4.8) and (4.10), we obtain

$$
\begin{equation*}
-4(n-1) g(Y, \phi W)-2 S(Y, \phi W)+4 g(Y, \phi W)=-2(n-1) A(W) \eta(Y) \tag{4.11}
\end{equation*}
$$

Replacing $Y$ by $\phi Y$ in (4.11) and then using (2.3) and (2.10), we have

$$
\begin{equation*}
S(Y, W)=-2(n-2) g(Y, W)+(n-3) \eta(Y) \eta(W) \tag{4.12}
\end{equation*}
$$

Hence, we can state the following.
Theorem 4.1. If para-Sasakian manifold is $\phi$-recurrent with respect to quarter-symmetric metric connection then it is an $\eta$-Einstein manifold with respect to Riemannian connection.

## 5. Concircular $\phi$-Recurrent Para-Sasakian Manifold with respect to Quarter-Symmetric Metric Connection

A concircular $\phi$-recurrent para-Sasakian manifold with respect to the quarter-symmetric metric connection is defined by

$$
\begin{equation*}
\phi^{2}\left(\left(\tilde{\nabla}_{W} \tilde{\bar{C}}\right)(X, Y) Z\right)=A(W) \tilde{\bar{C}}(X, Y) Z \tag{5.1}
\end{equation*}
$$

where $\tilde{\bar{C}}$ is a concircular curvature tensor with respect to the quarter-symmetric metric connection given by

$$
\begin{equation*}
\widetilde{\bar{C}}(X, Y) Z=\tilde{R}(X, Y) Z-\frac{\tilde{r}}{n(n-1)}[g(Y, Z) X-g(X, Z) Y] \tag{5.2}
\end{equation*}
$$

By virtue of (2.1) and (5.1), we have

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \stackrel{\overline{\bar{C}}}{)}(X, Y) Z-\eta\left(\left(\tilde{\nabla}_{W} \frac{\tilde{\bar{C}}}{}\right)(X, Y) Z\right) \xi=A(W) \stackrel{\tilde{\bar{C}}}{ }(X, Y) Z\right. \tag{5.3}
\end{equation*}
$$

from which it follows that

$$
\begin{equation*}
g\left(\left(\tilde{\nabla}_{W} \frac{\tilde{\bar{C}}}{}\right)(X, Y) Z, U\right)-\eta\left(\left(\tilde{\nabla}_{W} \frac{\tilde{\bar{C}}}{}\right)(X, Y) Z\right) g(\xi, U)=A(W) g(\stackrel{\tilde{\bar{C}}}{ }(X, Y) Z, U) \tag{5.4}
\end{equation*}
$$

where

$$
\begin{align*}
\left(\tilde{\nabla}_{W} \tilde{\bar{C}}\right)(X, Y) Z= & \left(\left(\nabla_{W} R\right)(X, Y) Z\right)+6[g(\phi Y, Z) g(W, X)-g(\phi X, Z) g(W, Y)] \xi \\
& +6[\eta(Y) g(W, Z)+\eta(Z) g(W, Y)] \phi X \\
& -6[\eta(X) g(W, Z)+\eta(Z) g(W, X)] \phi Y \\
& +2[\eta(Y) g(X, Z)-\eta(X) g(Y, Z)] \phi W \\
& +6[\eta(X) g(\phi Y, Z)-\eta(Y) g(\phi X, Z)] W \\
& +12 \eta(W) \eta(Z)[\eta(X) \phi Y-\eta(Y) \phi X]+\eta(Z)[g(W, Y) X-g(W, X) Y] \\
& +2 \eta(W) \eta(Z)[\eta(X) Y-\eta(Y) X] \\
& +12 \eta(W)[\eta(Y) g(\phi X, Z)-\eta(X) g(\phi Y, Z)] \xi \\
& +\eta(W)[\eta(Y) g(X, Z)-\eta(X) g(Y, Z)] \xi+\eta(Z)[g(\phi W, X) Y-g(\phi W, Y) X] \\
& +g(W, Z)[\eta(Y) X-\eta(X) Y]+[g(W, X) g(Y, Z)-g(W, Y) g(X, Z)] \xi \\
& -[g(\phi W, X) g(Y, Z)-g(\phi W, Y) g(X, Z)] \xi+g(\phi W, Z)[\eta(X) Y-\eta(Y) X] \\
& -\frac{\nabla_{W} r}{n(n-1)}[g(Y, Z) X-g(X, Z) Y] . \tag{5.5}
\end{align*}
$$

Let $\left\{e_{i}\right\}, i=1,2, \ldots, n$ be an orthonormal basis of the tangent space at any point of the manifold. Then putting $X=U=e_{i}$ in (5.4) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{align*}
\left(\nabla_{W} S\right)(Y, Z)= & \frac{\nabla_{W} r}{n} g(Y, Z)+(n+4) \eta(Z) g(\phi W, Y)+(n+3) \eta(Y) g(\phi W, Z) \\
& +(2 n-3) \eta(W) \eta(Y) \eta(Z)-(n-1) \eta(Y) g(W, Z) \\
& -\frac{\nabla_{W} r}{n(n-1)}[g(Y, Z)-\eta(Y) \eta(Z)]+A(W) S(Y, Z)  \tag{5.6}\\
& -A(W)\left\{(n+1) \eta(Y) \eta(Z)+\frac{r-(n+1)}{n} g(Y, Z)\right\}
\end{align*}
$$

Replacing $Z$ by $\xi$ in (5.6) and using (2.9), we have

$$
\begin{align*}
\left(\nabla_{W} S\right)(Y, \xi)= & \frac{\nabla_{W} r}{n} \eta(Y)+(n+4) g(\phi W, Y)+(n-2) \eta(W) \eta(Y) \\
& -A(W) \eta(Y)\left[2 n+\frac{r-(n+1)}{n}\right] \tag{5.7}
\end{align*}
$$

We know that

$$
\begin{equation*}
\left(\nabla_{W} S\right)(Y, \xi)=\nabla_{W} S(Y, \xi)-S\left(\nabla_{W} Y, \xi\right)-S\left(Y, \nabla_{W} \xi\right) \tag{5.8}
\end{equation*}
$$

Using (2.6) and (2.9) in the above relation, it follows that

$$
\begin{equation*}
\left(\nabla_{W} S\right)(Y, \xi)=-(n-1)[g(\phi W, Y)]-S(Y, \phi W) \tag{5.9}
\end{equation*}
$$

In view of (5.7) and (5.9), we obtain

$$
\begin{align*}
S(Y, \phi W)= & -(n-1) g(\phi W, Y)-\frac{\nabla_{W} r}{n} \eta(Y)-(n+4) g(\phi W, Y) \\
& -(n-2) \eta(W) \eta(Y)+A(W) \eta(Y)\left[2 n+\frac{r-(n+1)}{n}\right] \tag{5.10}
\end{align*}
$$

Replacing $Y$ by $\phi Y$ in (5.10) and then using (2.3) and (2.10), we obtain

$$
\begin{equation*}
S(Y, W)=-(2 n+3) g(W, Y)+(n+4) \eta(W) \eta(Y) \tag{5.11}
\end{equation*}
$$

This leads to the following theorem.
Theorem 5.1. If para-Sasakian manifold is concircular $\phi$-recurrent with respect to quarter-symmetric metric connection then it is an $\eta$-Einstein manifold with respect to Riemannian connection.

Now from (5.3), we have

$$
\begin{equation*}
\left(\tilde{\nabla}_{W} \frac{\tilde{\bar{C}}}{)}(X, Y) Z=\eta\left(\left(\tilde{\nabla}_{W} \frac{\tilde{\bar{C}}}{}\right)(X, Y) Z\right) \xi+A(W) \stackrel{\tilde{\bar{C}}}{ }(X, Y) Z\right. \tag{5.12}
\end{equation*}
$$

This gives

$$
\begin{align*}
\left(\left(\nabla_{W} R\right)(X, Y) Z\right)= & \eta\left(\left(\nabla_{W} R\right)(X, Y) Z\right) \xi+6[\eta(Y) g(W, Z)-\eta(Z) g(W, Y)] \phi X \\
& +6[\eta(X) g(W, Z)+\eta(Z) g(W, X)] \phi Y+2[\eta(X) g(Y, Z)-\eta(Y) g(X, Z)] \phi W \\
& -6[\eta(X) g(\phi Y, Z)-\eta(Y) g(\phi X, Z)] W-2 \eta(W) \eta(Z)[\eta(X) Y-\eta(Y) X] \\
& +12 \eta(W) \eta(Z)[\eta(Y) \phi X-\eta(X) \phi Y]-\eta(Z)[g(W, Y) X-g(W, X) Y] \\
& +\eta(Z)[g(\phi W, Y) X-g(\phi W, X) Y]+\eta(Z)[\eta(X) g(W, Y)-\eta(Y) g(W, X)] \xi \\
& +\eta(Z)[\eta(Y) g(\phi W, X)-\eta(X) g(\phi W, Y)] \xi-g(W, Z)[\eta(Y) X-\eta(X) Y] \\
& +g(\phi W, Z)[\eta(Y) X-\eta(X) Y]+6 \eta(W)[\eta(X) g(\phi Y, Z)-\eta(Y) g(\phi X, Z)] \xi \\
& +\frac{\nabla_{W} r}{n(n-1)}[g(Y, Z) X-g(X, Z) Y-\eta(X) g(Y, Z) \xi+\eta(Y) g(X, Z) \xi] \\
& +A(W) R(X, Y) Z+3 A(W)[g(\phi X, Z) \phi Y-g(\phi Y, Z) \phi X] \\
& +A(W) \eta(Z)[\eta(X) Y-\eta(Y) X]-A(W)[\eta(X) g(Y, Z)-\eta(Y) g(X, Z)] \xi \\
& -\frac{r+(n-1)}{n(n-1)} A(W)[g(Y, Z) X-g(X, Z) Y] . \tag{5.13}
\end{align*}
$$

Now from (5.13) and Bianchi's second identity, we have

$$
\begin{align*}
A(W) & \eta(R(X, Y) Z)+A(X) \eta(R(Y, W) Z)+A(Y) \eta(R(W, X) Z) \\
= & \frac{(n+1)(n-1)+r}{n(n-1)} A(W)[\eta(X) g(Y, Z)-\eta(Y) g(X, Z)] \\
& +\frac{(n+1)(n-1)+r}{n(n-1)} A(X)[\eta(Y) g(W, Z)-\eta(W) g(Y, Z)]  \tag{5.14}\\
& +\frac{(n+1)(n-1)+r}{n(n-1)} A(Y)[\eta(W) g(X, Z)-\eta(X) g(W, Z)]
\end{align*}
$$

By virtue of (2.7), we obtain from (5.14) that

$$
\begin{align*}
A(W) & {[g(X, Z) \eta(Y)-g(Y, Z) \eta(X)] } \\
& +A(X)[g(Y, Z) \eta(W)-g(W, Z) \eta(Y)] \\
& +A(Y)[g(W, Z) \eta(X)-g(X, Z) \eta(W)] \\
= & \frac{(n+1)(n-1)+r}{n(n-1)} A(W)[\eta(X) g(Y, Z)-\eta(Y) g(X, Z)]  \tag{5.15}\\
& +\frac{(n+1)(n-1)+r}{n(n-1)} A(X)[\eta(Y) g(W, Z)-\eta(W) g(Y, Z)] \\
& +\frac{(n+1)(n-1)+r}{n(n-1)} A(Y)[\eta(W) g(X, Z)-\eta(X) g(W, Z)]
\end{align*}
$$

Putting $Y=Z=e_{i}$ in (5.15) and taking summation over $i, 1 \leq i \leq n$, we get

$$
\begin{equation*}
A(W) \eta(X)=A(X) \eta(W) \tag{5.16}
\end{equation*}
$$

for all vector fields $X, W$. Replacing $X$ by $\xi$ in (5.16), we get

$$
\begin{equation*}
A(W)=\eta(W) \eta(\rho) \tag{5.17}
\end{equation*}
$$

for any vector field $W$.
Hence from (5.16) and (5.17), we can state the following.
Theorem 5.2. In a concircular $\phi$-recurrent para-Sasakian manifold with respect to quarter-symmetric metric connection, the characteristic vector field $\xi$ and the vector field $\rho$ associated to the 1-form $A$ are in codirectional and the 1-form $A$ is given by (5.17).

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