

Research Article

Regular Functions with Values in Ternary Number System on the Complex Clifford Analysis

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We define a new modified basis \hat{t} which is an association of two bases, e_1 and e_2 . We give an expression of the form $z = x_0 + i\overline{z_0}$, where x_0 is a real number and $\overline{z_0}$ is a complex number on three-dimensional real skew field. And we research the properties of regular functions with values in ternary field and reduced quaternions by Clifford analysis.

1. Introduction

The noncommutative three-dimensional real field \mathbb{R}^3 of the hypercomplex numbers is called a ternary number system \mathbb{T} . The quaternions are represented by the form $z = \sum_{j=0}^{3} e_j x_j$, where x_j (j = 0, ..., 3) are real numbers on four dimensional real field \mathbb{R}^4 . Fueter [1] has given a definition of quaternionic functions in \mathbb{R}^4 and Deavours [2] and Sudbery [3] have developed theories of quaternionic analysis. Naser [4] investigated some properties of hyperholomorphic functions and Koriyama et al. [5] researched properties of hyperholomorphic functions and holomorphic functions in quaternionic analysis. Nôno [6] obtained several results for regular functions which have a complex number form in quaternion analysis. Cho [7] researched some properties of Euler's formula and De moivre's formula for quaternions. Sangwine and Bihan [8] obtained some results for the quaternionic polar representation with a complex modulus and complex argument inspired by the cayley-dickson form. Fueter [9] obtained some properties of the three variables which are called the Fueter variables and researched the fact that structures lead to the set of all Fueter-regular functions in the general cases of Clifford analysis. By Brackx et al. [10], the theory of Fueter-regularity has been developed and generalized as quaternionic variables for theories of Clifford-valued regular functions.

Lim and Shon [11–13] researched the existence of hyperconjugate harmonic functions of octonion variables, properties of dual quaternion functions, and regularity of functions with values in a noncommutative subalgebra of complex matrix algebras.

We consider that ternary numbers are generated by a new basis \hat{i} and give some properties of regular functions with values in T. Also, we represent the corresponding Euler's formula for the form $z = x_0 + \hat{i}\overline{z_0}$ and investigate calculating rules for regular functions in Clifford analysis. We research new representations of Fueter variables in reduced quaternions with \hat{i} and some characteristics of regularity of functions on the Fueter variable system.

2. Preliminaries

The ternary number system \mathbb{T} is a three dimensional noncommutative and associative real field by three bases e_0 , e_1 , and e_2 with the following rules:

$$e_1^2 = e_2^2 = -1, \qquad e_1 e_2 = -e_2 e_1,$$

 $\overline{e_0} = e_0, \qquad \overline{e_j} = -e_j \quad (j = 1, 2).$
(1)

The element e_0 is the identity of \mathbb{T} and e_1 identifies the imaginary unit $\sqrt{-1}$ in the complex field. We consider an association of two bases e_1 and e_2 as follows:

$$\hat{i} := \frac{ae_1 + be_2}{\sqrt{a^2 + b^2}} = \alpha e_1 + \beta e_2 \quad \text{with } \hat{i}^2 = -1,$$
 (2)

where $\alpha := a/\sqrt{a^2 + b^2}$, $\beta := b/\sqrt{a^2 + b^2}$, and *a*, *b* are real numbers except both zeros.

$$z = x_0 + e_1 x_1 + e_2 x_2$$

= $x_0 + \hat{i} \overline{z_0}$, (3)

where x_j (j = 0, 1, 2) are real variables, $\overline{z_0} = \gamma(x_1 - x_2e_1e_2)$, and $\gamma := \alpha + \beta e_1e_2$.

We define the ternary number system

$$\mathbb{T} := \left\{ z \mid z = x_0 + \hat{i}\overline{z_0} \right\}.$$
(4)

The conjugate number z^* of z in \mathbb{T} is given by the form:

$$z^* = x_0 - \hat{i}\overline{z_0}.$$
 (5)

And the norm |z| of z and the inverse z^{-1} of z are given by the following forms:

$$|z| = \sqrt{zz^*} = \sqrt{x_0^2 + \overline{z_0}z_0} = \sqrt{\sum_{j=0}^2 x_j^2},$$

$$z^{-1} = \frac{z^*}{|z|^2} \quad (z \neq 0),$$
(6)

where $z_0 = \overline{\gamma}(x_1 + x_2e_1e_2)$ and $\overline{\gamma} = \alpha - \beta e_1e_2$.

We define the addition and multiplication of two ternary numbers $z = x_0 + \hat{i}\overline{z_0}$ and $w = y_0 + \hat{i}\overline{w_0}$ as follows:

$$z + w = (x_0 + y_0) + \hat{i} (\overline{z_0} + \overline{w_0}),$$

$$zw = (x_0 y_0 - z_0 \overline{w_0}) + \hat{i} (x_0 \overline{w_0} + \overline{z_0} y_0).$$
(7)

Theorem 1. Let z be an arbitrary number in \mathbb{T} . Then the corresponding Euler formula for z is

$$e^{z} = e^{x_{0}} \left(\cos \left| z_{0} \right| + \frac{z_{0}}{\left| z_{0} \right|} \widehat{i} \sin \left| z_{0} \right| \right).$$
(8)

Moreover, taking logarithms of both sides, one obtains the equation as follows:

$$\ln z = \ln |z| + \frac{z_0}{|z_0|} \hat{i} \cos^{-1} \left(\frac{x_0}{|z|}\right).$$
(9)

Proof. For the number $z = x_0 + \hat{i}\overline{z_0}$ in \mathbb{T} , we get $|\hat{i}\overline{z_0}| = |\overline{z_0}| = |z_0|$ and $((z_0/|z_0|)\hat{i})^2 = -1$. Then,

$$e^{z} = e^{x_{0} + \hat{i}\overline{z_{0}}} = e^{x_{0}} e^{(\hat{i}\overline{z_{0}}/|\hat{i}\overline{z_{0}}|)|\hat{i}\overline{z_{0}}|}$$

= $e^{x_{0}} \left(\cos |z_{0}| + \frac{z_{0}}{|z_{0}|} \hat{i} \sin |z_{0}| \right).$ (10)

From

$$z = |z| \left(\frac{x_0}{|z|} + \frac{z_0}{|z_0|} \hat{i} \frac{|z_0|}{|z|} \right)$$
$$= |z| \left\{ \cos \left(\cos^{-1} \left(\frac{x_0}{|z|} \right) \right)$$
$$+ \frac{z_0}{|z_0|} \hat{i} \sin \left(\cos^{-1} \left(\frac{x_0}{|z|} \right) \right) \right\},$$
(11)

we have

$$\ln z = \ln |z| + \frac{z_0}{|z_0|} \hat{i} \cos^{-1} \left(\frac{x_0}{|z|}\right).$$
(12)

We consider the following differential operators:

$$D := \frac{1}{2} \sum_{j=0}^{2} \overline{e_{j}} \frac{\partial}{\partial x_{j}} = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} - \hat{i} \frac{\partial}{\partial z_{0}} \right),$$

$$D^{*} = \frac{1}{2} \sum_{j=0}^{2} e_{j} \frac{\partial}{\partial x_{j}} = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} + \hat{i} \frac{\partial}{\partial z_{0}} \right),$$
(13)

where $\partial/\partial z_0 = \gamma(\partial/\partial x_1 - e_1e_2(\partial/\partial x_2))$ and $\partial/\partial \overline{z_0} = \overline{\gamma}(\partial/\partial x_1 + e_1e_2(\partial/\partial x_2))$. Then the Laplacian operator is

$$4\Delta := DD^* = D^*D = \frac{\partial^2}{\partial x_0^2} + \frac{\partial^2}{\partial z_0 \partial \overline{z_0}} = \sum_{j=0}^2 \frac{\partial^2}{\partial x_j^2}.$$
 (14)

Let Ω be an open set in \mathbb{R}^3 . The function f(z) that is defined by the following form in Ω with values in \mathbb{T} :

$$f: \Omega \longrightarrow \mathbb{T}$$
(15)

satisfies

$$z = (x_0, \overline{z_0}) \in \Omega \longmapsto f(z) = u_0(x_0, \overline{z_0}) + \widehat{if_0}(x_0, \overline{z_0}) \in \mathbb{T},$$
(16)

where u_i (j = 0, 1, 2) are real-valued functions and

$$f_0 = \overline{\gamma} \left(u_1 + u_2 e_1 e_2 \right), \qquad \overline{f_0} = \gamma \left(u_1 - u_2 e_1 e_2 \right) \tag{17}$$

are complex-valued functions with values in \mathbb{T} .

Remark 2. The operators *D* and D^* act for the function f(z) on \mathbb{T} as follows:

$$Df = \frac{1}{2} \left\{ \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) + \hat{i} \left(\frac{\partial \overline{f_0}}{\partial x_0} - \frac{\partial u_0}{\partial z_0} \right) \right\},$$

$$D^* f = \frac{1}{2} \left\{ \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) + \hat{i} \left(\frac{\partial \overline{f_0}}{\partial x_0} + \frac{\partial u_0}{\partial z_0} \right) \right\},$$

$$fD = \frac{1}{2} \left\{ \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial \overline{f_0}}{\partial x_0} - \frac{\partial u_0}{\partial z_0} \right) \right\},$$

$$fD^* = \frac{1}{2} \left\{ \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial f_0}{\partial z_0} \right) + \hat{i} \left(\frac{\partial \overline{f_0}}{\partial x_0} + \frac{\partial u_0}{\partial z_0} \right) \right\}.$$
(18)

3. Properties of Regular Functions with Values in **T**

Definition 3. Let Ω be an open set in \mathbb{R}^3 . A function $f(z) = u_0(x_0, \overline{z_0}) + i \overline{f_0}(x_0, \overline{z_0})$ is said to be L(R)-regular in Ω , if the following two conditions are satisfied:

(i) u_0 and f_0 are continuously differential functions on Ω ;

(ii)
$$D^* f(z) = 0$$
 ($f(z)D^* = 0$) on Ω .

Remark 4. The left equation (ii) of Definition 3 is equivalent to the following:

$$\frac{\partial u_0}{\partial x_0} = \frac{\partial \overline{f_0}}{\partial \overline{z_0}}, \qquad \frac{\partial \overline{f_0}}{\partial x_0} = -\frac{\partial u_0}{\partial z_0}.$$
 (19)

The equations in (19) are called the corresponding Cauchy-Riemann system for f(z) in \mathbb{T} . The right equation (ii) of Definition 3 is equivalent to (19). When the function $f(z) = u_0(x_0, \overline{z_0}) + i \overline{f_0}(x_0, \overline{z_0})$ is a L-regular function on $\Omega \subset \mathbb{R}^3$, simply we say that f(z) is a regular function on $\Omega \subset \mathbb{R}^3$. In this case, we often say that f(z) is a biregular function on $\Omega \subset \mathbb{R}^3$.

Remark 5. Let Ω be an open set in \mathbb{R}^3 and let f(z) be a regular function on Ω . Then we can replace the corresponding Cauchy-Riemann system in \mathbb{R}^3 as follows:

$$\frac{\partial u_0}{\partial x_0} = \frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2}, \qquad \frac{\partial u_1}{\partial x_2} = \frac{\partial u_2}{\partial x_1},
\frac{\partial u_0}{\partial x_1} = -\frac{\partial u_1}{\partial x_0}, \qquad \frac{\partial u_0}{\partial x_2} = -\frac{\partial u_2}{\partial x_0},$$
(20)

where u_j (j = 0, 1, 2) are real-valued functions.

Theorem 6. Let Ω be an open set in \mathbb{R}^3 and let f be a regular function on Ω . Then the derivative f' of f defined by Df is

$$f' = \frac{\partial f}{\partial x_0} = -\hat{i}\frac{\partial f}{\partial z_0}$$
(21)

on Ω.

Proof. By the definition of regular function with values in \mathbb{T} , we have

$$Df = \frac{1}{2} \left\{ \left(\frac{\partial u_0}{\partial x_0} + \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) + \hat{i} \left(\frac{\partial \overline{f_0}}{\partial x_0} - \frac{\partial u_0}{\partial z_0} \right) \right\}$$

$$= \frac{\partial u_0}{\partial x_0} + \hat{i} \frac{\partial \overline{f_0}}{\partial x_0} = \frac{\partial f}{\partial x_0}$$
(22)

on Ω . And

$$Df = \frac{\partial f_0}{\partial \overline{z_0}} - \hat{i}\frac{\partial u_0}{\partial z_0} = -\hat{i}\left(\frac{\partial}{\partial z_0}\hat{i}\overline{f_0} + \frac{\partial u_0}{\partial z_0}\right) = -\hat{i}\frac{\partial f}{\partial z_0}$$
(23)

Theorem 7. Let Ω be an open set in \mathbb{R}^3 and let $f = u_0 + i \overline{f_0}$ be a function with values in \mathbb{T} . Suppose that $\partial f / \partial x_0$ and $\partial f / \partial z_0$ exist and are continuous on Ω . If

$$\frac{\partial f}{\partial x_0} = -\hat{i}\frac{\partial f}{\partial z_0} \tag{24}$$

on Ω , then f is regular on Ω .

Proof. Since
$$\partial f / \partial x_0 = -\hat{i} (\partial f / \partial z_0)$$
, we have

$$\frac{\partial f}{\partial x_0} = \frac{\partial u_0}{\partial x_0} + \hat{i} \frac{\partial f_0}{\partial x_0}.$$
(25)

Hence, we have $D^* f = 0$ and then f is regular on Ω .

Definition 8. Let Ω be an open set in \mathbb{R}^3 . A function $f = u_0 + i \overline{f_0}$ is said to be harmonic on Ω if all its components u_0 and $\overline{f_0}$ of f are harmonic on Ω .

Proposition 9. Let Ω be an open set in \mathbb{R}^3 . If the function f is regular on Ω , then f is harmonic on Ω .

Proof. Since *f* is regular function on Ω , we have

$$DD^* \overline{f_0} = \frac{1}{4} \left\{ \left(\frac{\partial}{\partial x_0} \frac{\partial \overline{f_0}}{\partial x_0} + \frac{\partial}{\partial \overline{z_0}} \frac{\partial \overline{f_0}}{\partial z_0} \right) + \hat{i} \left(\frac{\partial}{\partial x_0} \frac{\partial \overline{f_0}}{\partial z_0} - \frac{\partial}{\partial z_0} \frac{\partial \overline{f_0}}{\partial x_0} \right) \right\} = 0.$$
(26)

Similarly, we can prove that $DD^*u_0 = 0$. So, we obtain the result.

Proposition 10. Let Ω be an open set in \mathbb{R}^3 and let $f = u_0 + \hat{i} f_0$ and $g = v_0 + \hat{i} \overline{g_0}$ be regular functions on Ω . Then the following properties hold:

- (i) $f\alpha$ is regular on Ω , if α is any ternary constant;
- (ii) αf is not regular on Ω , if α is any ternary constant;
- (iii) $f \pm g$ is regular on Ω ;
- (iv) fg is not regular on Ω . Moreover, if g is a real-valued function, then fg is regular on Ω .

Proof. It is sufficient to show the second condition of Definition 3.

(i) Let α be a ternary constant with $\alpha = a_0 + \hat{i}\overline{\alpha_0}$, where

$$\alpha_0 = \frac{c_1 a_1 + c_2 a_2}{\sqrt{c_1^2 + c_2^2}} + \frac{c_2 a_1 - c_1 a_2}{\sqrt{c_1^2 + c_2^2}} e_1 e_2$$
(27)

and a_0 , a_1 , a_2 , c_1 , and c_2 are real numbers. Then the equation

$$D^{*}(f\alpha) = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} + \hat{i} \frac{\partial}{\partial z_{0}} \right)$$

$$\times \left\{ (u_{0}a_{0} - f_{0}\overline{\alpha_{0}}) + \hat{i} \left(u_{0}\overline{\alpha_{0}} + \overline{f_{0}}a_{0} \right) \right\}$$

$$= \frac{1}{2} \left(\left(\frac{\partial u_{0}}{\partial x_{0}}a_{0} - \frac{\partial f_{0}}{\partial x_{0}}\overline{\alpha_{0}} - \frac{\partial u_{0}}{\partial \overline{z_{0}}}\overline{\alpha_{0}} - \frac{\partial \overline{f_{0}}}{\partial \overline{z_{0}}}a_{0} \right)$$

$$+ \hat{i} \left(\frac{\partial u_{0}}{\partial x_{0}}\overline{\alpha_{0}} + \frac{\partial \overline{f_{0}}}{\partial x_{0}}a_{0} + \frac{\partial u_{0}}{\partial z_{0}}a_{0} - \frac{\partial f_{0}}{\partial \overline{z_{0}}}\overline{\alpha_{0}} \right) \right)$$

$$= 0.$$
(28)

Hence, $f\alpha$ is regular on Ω .

(ii) Since

$$D^{*}(\alpha f) = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} + \hat{i} \frac{\partial}{\partial z_{0}} \right)$$

$$\times \left\{ \left(a_{0}u_{0} - \alpha_{0}\overline{f_{0}} \right) + \hat{i} \left(a_{0}\overline{f_{0}} + \overline{\alpha_{0}}u_{0} \right) \right\}$$

$$= \frac{1}{2} \left(\left(a_{0}\frac{\partial u_{0}}{\partial x_{0}} - \alpha_{0}\frac{\partial\overline{f_{0}}}{\partial x_{0}} - \overline{\alpha_{0}}\frac{\partial f_{0}}{\partial x_{0}} - \frac{\partial u_{0}}{\partial z_{0}}\alpha_{0} \right)$$

$$+ \hat{i} \left(a_{0}\frac{\partial\overline{f_{0}}}{\partial x_{0}} + \overline{\alpha_{0}}\frac{\partial u_{0}}{\partial x_{0}} + a_{0}\frac{\partial u_{0}}{\partial z_{0}} - \alpha_{0}\frac{\partial\overline{f_{0}}}{\partial z_{0}} \right) \right)$$
(29)

is not zero, αf is not always regular on Ω .

(iii) Since

$$D^{*}(f \pm g) = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} + \hat{i} \frac{\partial}{\partial z_{0}} \right) \left\{ (u_{0} \pm v_{0}) + \hat{i} \left(\overline{f_{0}} \pm \overline{g_{0}} \right) \right\}$$
$$= \frac{1}{2} \left(\left(\frac{\partial u_{0}}{\partial x_{0}} \pm \frac{\partial v_{0}}{\partial x_{0}} - \frac{\partial \overline{f_{0}}}{\partial \overline{z_{0}}} \mp \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right)$$
$$+ \hat{i} \left(\frac{\partial u_{0}}{\partial z_{0}} \pm \frac{\partial v_{0}}{\partial z_{0}} + \frac{\partial \overline{f_{0}}}{\partial x_{0}} a_{0} \pm \frac{\partial \overline{g_{0}}}{\partial x_{0}} \right) \right) = 0, \tag{30}$$

 $f \pm g$ is regular on Ω .

(iv) Since

$$D^{*}(fg) = \frac{1}{2} \left(\frac{\partial}{\partial x_{0}} + \hat{i} \frac{\partial}{\partial z_{0}} \right)$$

$$\times \left\{ (u_{0}v_{0} - f_{0}\overline{g_{0}}) + \hat{i} \left(u_{0}\overline{g_{0}} + \overline{f_{0}}v_{0} \right) \right\}$$

$$= \frac{1}{2} \left(\left(\frac{\partial u_{0}}{\partial x_{0}} - \frac{\partial \overline{f_{0}}}{\partial \overline{z_{0}}} \right) v_{0} + u_{0} \left(\frac{\partial v_{0}}{\partial x_{0}} - \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right) \right)$$

$$- \left(\frac{\partial f_{0}}{\partial x_{0}} + \frac{\partial u_{0}}{\partial \overline{z_{0}}} \right) \overline{g_{0}} - \left(f_{0} \frac{\partial \overline{g_{0}}}{\partial x_{0}} + \overline{f_{0}} \frac{\partial v_{0}}{\partial \overline{z_{0}}} \right)$$

$$+ \hat{i} \left\{ \left(\frac{\partial u_{0}}{\partial x_{0}} - \frac{\partial f_{0}}{\partial z_{0}} \right) \overline{g_{0}} + u_{0} \left(\frac{\partial \overline{g_{0}}}{\partial x_{0}} + \frac{\partial v_{0}}{\partial z_{0}} \right) \right\}$$

$$+ \left(\frac{\partial \overline{f_{0}}}{\partial x_{0}} - \frac{\partial f_{0}}{\partial z_{0}} \right) v_{0}$$

$$+ \left(\frac{\partial \overline{f_{0}}}{\partial x_{0}} - f_{0} \frac{\partial \overline{g_{0}}}{\partial z_{0}} \right) \right\}$$

$$= \frac{1}{2} \left(- \left(f_{0} \frac{\partial \overline{g_{0}}}{\partial x_{0}} + \overline{f_{0}} \frac{\partial v_{0}}{\partial \overline{z_{0}}} \right) + \hat{i} \left(\overline{f_{0}} \frac{\partial v_{0}}{\partial x_{0}} - f_{0} \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right) \right)$$

$$(31)$$

is not zero, fg is not always regular on Ω .

Theorem 11. Let Ω be an open set in \mathbb{R}^3 and let f and g be regular functions on Ω . Then we have the following equations:

$$2D^*(fg) = (D^*f)g + f\frac{\partial g}{\partial x_0} + \hat{i}\left(u_0\frac{\partial g}{\partial z_0} + \hat{i}\overline{f_0}\frac{\partial g}{\partial \overline{z_0}}\right). \quad (32)$$

$$2D(fg) = (Df)g + f\frac{\partial g}{\partial x_0} - \hat{i}\left(u_0\frac{\partial g}{\partial z_0} + \hat{i}\overline{f_0}\frac{\partial g}{\partial \overline{z_0}}\right). \quad (33)$$

Proof. From the proof of Proposition 10, we have the following equations:

$$2D^{*}(fg) = \left\{ \left(\frac{\partial u_{0}}{\partial x_{0}} - \frac{\partial \overline{f_{0}}}{\partial \overline{z_{0}}} \right) + \hat{i} \left(\frac{\partial \overline{f_{0}}}{\partial x_{0}} + \frac{\partial u_{0}}{\partial z_{0}} \right) \right\} \left(v_{0} + \hat{i}\overline{g_{0}} \right)$$
$$- \left(f_{0} \frac{\partial \overline{g_{0}}}{\partial x_{0}} + \overline{f_{0}} \frac{\partial v_{0}}{\partial \overline{z_{0}}} \right) + \hat{i} \left(\overline{f_{0}} \frac{\partial v_{0}}{\partial x_{0}} - f_{0} \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right)$$
$$= \left\{ \left(\frac{\partial u_{0}}{\partial x_{0}} - \frac{\partial \overline{f_{0}}}{\partial \overline{z_{0}}} \right) + \hat{i} \left(\frac{\partial \overline{f_{0}}}{\partial x_{0}} + \frac{\partial u_{0}}{\partial \overline{z_{0}}} \right) \right\} \left(v_{0} + \hat{i}\overline{g_{0}} \right)$$
$$+ u_{0} \left(\frac{\partial v_{0}}{\partial x_{0}} - \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right) - \left(f_{0} \frac{\partial \overline{g_{0}}}{\partial x_{0}} + \overline{f_{0}} \frac{\partial v_{0}}{\partial \overline{z_{0}}} \right)$$
$$+ \hat{i} u_{0} \left(\frac{\partial \overline{g_{0}}}{\partial x_{0}} + \frac{\partial v_{0}}{\partial \overline{z_{0}}} \right) + \hat{i} \left(\overline{f_{0}} \frac{\partial v_{0}}{\partial x_{0}} - f_{0} \frac{\partial \overline{g_{0}}}{\partial \overline{z_{0}}} \right)$$
$$= \left(D^{*} f \right) g + f \frac{\partial g}{\partial x_{0}} + \hat{i} \left(u_{0} \frac{\partial g}{\partial z_{0}} + \overline{i} \overline{f_{0}} \frac{\partial g}{\partial \overline{z_{0}}} \right).$$
(34)

Similarly, we can prove (33).

We let

$$k = e_1 e_2 \frac{1}{2} dz_0 \wedge d\overline{z_0} + e_2 \alpha dx_0 \wedge d\overline{z_0} - e_1 \beta dx_0 \wedge d\overline{z_0}.$$
(35)

Theorem 12. Let Ω be an open set in \mathbb{R}^3 and U be any domain in Ω with smooth boundary bU such that $U \subset \Omega$. If $f = u_0 + i \overline{f_0}$ is a regular function on Ω , then

$$\int_{bU} kf = 0, \tag{36}$$

where kf is the ternary product of the form k on the function f(z).

Proof. Since the function $f = u_0 + e_1 \alpha \overline{f_0} + e_2 \beta \overline{f_0}$ exists, we have

$$kf = \left(e_1e_2\frac{1}{2}u_0 - e_2\frac{1}{2}\alpha\overline{f_0} + e_1\frac{1}{2}\beta\overline{f_0}\right)dz_0 \wedge d\overline{z_0}$$
$$+ \left(e_2\alpha u_0 - e_1\beta u_0\right)dx_0 \wedge d\overline{z_0}$$
$$+ \left(-e_1e_2\alpha^2\overline{f_0} - e_1e_2\beta^2\overline{f_0}\right)dx_0 \wedge dz_0.$$
(37)

))

Then

$$d (kf) = e_1 e_2 \left(\frac{\partial u_0}{\partial x_0} - \alpha^2 \frac{\partial \overline{f_0}}{\partial \overline{z_0}} - \beta^2 \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) dV + e_2 \left(-\alpha \frac{\partial \overline{f_0}}{\partial x_0} - \alpha \frac{\partial u_0}{\partial z_0} \right) dV + e_1 \left(\beta \frac{\partial \overline{f_0}}{\partial x_0} + \beta \frac{\partial u_0}{\partial z_0} \right) dV + \left(-\alpha \beta \frac{\partial \overline{f_0}}{\partial \overline{z_0}} + \alpha \beta \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) dV = \left\{ e_1 e_2 \left(\frac{\partial u_0}{\partial x_0} - \frac{\partial \overline{f_0}}{\partial \overline{z_0}} \right) - e_2 \alpha \left(\frac{\partial \overline{f_0}}{\partial x_0} + \frac{\partial u_0}{\partial z_0} \right) + e_1 \beta \left(\frac{\partial \overline{f_0}}{\partial x_0} + \frac{\partial u_0}{\partial z_0} \right) \right\} dV,$$
(38)

where $dV = dx_0 \wedge dz_0 \wedge d\overline{z_0}$ in *U*, and by the corresponding Cauchy-Riemann system for f(z) in \mathbb{T} , d(kf) = 0. By Stokes theorem, we obtain the result.

Remark 13. Since

$$\left(\widehat{i}\overline{z_{0}}\right)^{k} = \begin{cases} (-1)^{k/2} (|z_{0}|)^{k}, & k: \text{ even} \\ (-1)^{[k/2]} \widehat{i} (|z_{0}|)^{k-1} \overline{z_{0}}, & k: \text{ odd,} \end{cases}$$
(39)

we have

$$z^{n} = \sum_{k=0}^{n} \alpha(k) x_{0}^{n-k} |z_{0}|^{[k/2]} \overline{z_{0}}^{\delta_{k}}, \qquad (40)$$

where

$$\alpha(k) = \begin{cases} \binom{n}{k} (-1)^{k/2}, & k: \text{ even} \\ \binom{n}{k} (-1)^{[k/2]} \hat{i}, & k: \text{ odd}, \end{cases}$$

$$\delta_k = \begin{cases} 0, & k: \text{ even} \\ 1, & k: \text{ odd}. \end{cases}$$
(41)

And [k/2] is the greatest integer that is less than or equal to k/2.

Theorem 14. Let f be a homogeneous polynomial of degree n with respect to the variables x_0 and $\overline{z_0}$. If f is regular on Ω , then

$$f(z) = \frac{1}{n!} \frac{\partial^n f(z)}{\partial x_0^n} z^n,$$
(42)

$$f(z) = \left(-\hat{i}\right)^n \frac{1}{n!} \frac{\partial^n f(z)}{\partial z_0^{n-r} \partial \overline{z_0}^r} z^n, \tag{43}$$

where *r* is a nonnegative integer.

Proof. Since f(z) is a homogeneous polynomial, then

$$f(z) = \frac{1}{n} \frac{\partial f(z)}{\partial x_0} z.$$
(44)

Also, since $\partial f(z)/\partial x_0$ is a homogeneous polynomial of degree n-1, we have

$$\frac{\partial f(z)}{\partial x_0} = \frac{1}{n-1} \frac{\partial^2 f(z)}{\partial x_0^2} z.$$
(45)

Then we have

$$f(z) = \frac{1}{n(n-1)} \frac{\partial^2 f(z)}{\partial x_0^2} z^2.$$
 (46)

Continuing this process, we can get the result (42). Similarly, we obtain the result (43). \Box

4. Properties of Regular Functions with Values in $\mathbb{T}(\mathbb{C})$

We define the number system

$$\mathbb{T}(\mathbb{C}) = \left\{ z \mid z = \hat{i}\gamma \left(z_1 - e_1 e_2 z_2 \right) \right\},\tag{47}$$

where $z_1 = x_1 - (1/2)e_1x_0$ and $z_2 = x_2 - (1/2)e_2x_0$. The non-commutative multiplication of two numbers $z = iy(z_1 - e_1e_2z_2)$ and $w = iy(w_1 - e_1e_2w_2)$ is defined by

$$zw = -\{(z_1w_1 + z_2w_2) + e_1e_2(\overline{z_2}w_1 - \overline{z_1}w_2)\},\$$

$$wz = -\{(w_1z_1 + w_2z_2) + e_1e_2(\overline{w_2}z_1 - \overline{w_1}z_2)\}.$$
(48)

The conjugate number z^* of z in $\mathbb{T}(\mathbb{C})$ is given by the following:

$$z^* = -\hat{i}\gamma\left(\overline{z_1} - e_1e_2\overline{z_2}\right). \tag{49}$$

And the norm |z| of z and the inverse z^{-1} of z are given by the following forms:

$$|z| = \sqrt{zz^*} = \sqrt{z^*z}$$

= $\sqrt{(z_1\overline{z_1} + z_2\overline{z_2}) + e_1e_2(\overline{z_2\overline{z_1}} - \overline{z_1\overline{z_2}})}$
= $\sqrt{\sum_{j=0}^2 x_j^2},$
 $z^{-1} = \frac{z^*}{|z|^2} \quad (z \neq 0).$ (50)

We consider the following differential operators:

$$D = -\frac{1}{2}\hat{i}\gamma \left(D_{z_1} - e_1e_2D_{z_2}\right), \qquad D^* = \frac{1}{2}\hat{i}\gamma \left(D_{\overline{z_1}} - e_1e_2D_{\overline{z_2}}\right), \tag{51}$$

where

$$D_{z_1} = \frac{1}{2}e_1\frac{\partial}{\partial x_0} + \frac{\partial}{\partial x_1}, \qquad D_{z_2} = \frac{1}{2}e_2\frac{\partial}{\partial x_0} + \frac{\partial}{\partial x_2}.$$
 (52)

$$4\Delta := DD^* = D^*D = \sum_{j=0}^2 \frac{\partial^2}{\partial x_j^2}.$$
 (53)

Let *G* be an open set in \mathbb{C}^2 . The function f(z) that is defined by the following form in *G* with values in $\mathbb{T}(\mathbb{C})$:

$$f:G \to \mathbb{T}(\mathbb{C}) \tag{54}$$

satisfies

$$z = (z_1, z_2) \in G \longmapsto f(z) = f(z_1, z_2)$$

= $\hat{i}\gamma (f_1(z_1, z_2) - e_1e_2f_2(z_1, z_2)),$ (55)

where $f_1 = u_1 - (1/2)e_1u_0$ and $f_2 = u_2 - (1/2)e_2u_0$ are complex-valued functions with values in $\mathbb{T}(\mathbb{C})$ and u_j (j = 0, 1, 2) are real-valued functions.

Remark 15. The operators D and D^* act for a function f(z) on $\mathbb{T}(\mathbb{C})$ as follows:

$$Df = -\hat{i}^{2} \left\{ \left(D_{z_{1}}f_{1} + D_{z_{2}}f_{2} \right) + e_{1}e_{2} \left(D_{\overline{z_{2}}}f_{1} - D_{\overline{z_{1}}}f_{2} \right) \right\},$$

$$D^{*}f = \hat{i}^{2} \left\{ \left(D_{\overline{z_{1}}}f_{1} + D_{\overline{z_{2}}}f_{2} \right) + e_{1}e_{2} \left(D_{z_{2}}f_{1} - D_{z_{1}}f_{2} \right) \right\}.$$

(56)

We define a commutative multiplication of two numbers $z = \hat{i}\gamma(z_1 - e_1e_2z_2)$ and $w = \hat{i}\gamma(w_1 - e_1e_2w_2)$ by

$$z \odot w = w \odot z = \frac{1}{2} (zw + wz)$$

= $\frac{1}{2} \hat{i}^2 \{ (z_1w_1 + z_2w_2 + w_1z_1 + w_2z_2) + e_1e_2 (\overline{z_2}w_1 - \overline{z_1}w_2 + \overline{w_2}z_1 - \overline{w_1}z_2) \}.$ (57)

Remark 16. The operators *D* and D^* act for a function f(z) on $\mathbb{T}(\mathbb{C})$ as follows:

$$\begin{split} D \odot f &= \frac{1}{2} \left(Df + fD \right) \\ &= \left\{ \left(D_{z_1} f_1 + D_{z_2} f_2 \right) \\ &+ \frac{1}{2} e_1 e_2 \left(D_{\overline{z_2}} f_1 - D_{\overline{z_1}} f_2 \right) \\ &+ \overline{f_2} D_{z_1} - \overline{f_1} D_{z_2} \right) \right\} \\ &= \left\{ \left(D_{z_1} f_1 + D_{z_2} f_2 + \frac{1}{2} \frac{\partial u_0}{\partial x_0} \right) \\ &+ \frac{1}{2} e_1 e_2 \left(D_{\overline{z_2}} f_1 - D_{\overline{z_1}} f_2 \right) \\ &+ D_{z_1} \overline{f_2} - D_{z_2} \overline{f_1} \right) \right\}, \end{split}$$

$$D^* \odot f = \frac{1}{2} \left(D^* f + f D^* \right)$$

= $-\left\{ \left(D_{\overline{z_1}} f_1 + D_{\overline{z_2}} f_2 \right) + \frac{1}{2} e_1 e_2 \left(D_{z_2} f_1 - D_{z_1} f_2 + \overline{f_2} D_{\overline{z_1}} - \overline{f_1} D_{\overline{z_2}} \right) \right\}$
= $-\left\{ \left(D_{\overline{z_1}} f_1 + D_{\overline{z_2}} f_2 - \frac{1}{2} \frac{\partial u_0}{\partial x_0} \right) + \frac{1}{2} e_1 e_2 \left(D_{z_2} f_1 - D_{z_1} f_2 + D_{\overline{z_1}} \overline{f_2} - D_{\overline{z_2}} \overline{f_1} \right) \right\}.$

Definition 17. Let *G* be a domain in \mathbb{C}^2 . A function $f = i \gamma (f_1 - e_1 e_2 f_2)$ is said to be dot-regular in *G* if the following two conditions are satisfied:

(i) f₁ and f₂ are differential functions in G,
(ii) D^{*} ⊙ f = 0 in G.

Remark 18. The above equation (ii) of Definition 17 is equivalent as follows:

$$D_{\overline{z_1}}f_1 + D_{\overline{z_2}}f_2 = \frac{1}{2}\frac{\partial u_0}{\partial x_0},$$

$$D_{z_2}f_1 - D_{z_1}f_2 = D_{\overline{z_2}}\overline{f_1} - D_{\overline{z_1}}\overline{f_2}.$$
(59)

Theorem 19. Let G be an open set in \mathbb{C}^2 and let f be a dotregular function on G. Then the derivative f' of f defined by $D \odot f$ is

$$f' = 2\hat{i}\gamma \left(D_{\overline{z_1}} - D_{z_1}\right)f = 2e_1\left(D_{\overline{z_1}} - D_{z_1}\right)f,$$

$$f' = -2\hat{i}\gamma \left(D_{z_2} - D_{\overline{z_2}}\right)f = 2e_2\left(D_{\overline{z_2}} - D_{z_2}\right)f.$$
(60)

Proof. By the definition of a dot-regular function with values in $\mathbb{T}(\mathbb{C})$, we have

$$D \odot f = \left(D_{\overline{z_1}} f_1 + D_{\overline{z_2}} f_2 + e_1 \frac{\partial u_1}{\partial x_0} + e_2 \frac{\partial u_2}{\partial x_0} + \frac{3}{2} \frac{\partial u_0}{\partial x_0} \right)$$
$$+ \frac{1}{2} e_1 e_2 \left(D_{z_2} f_1 - D_{z_1} f_2 + D_{\overline{z_1}} \overline{f_2} \right)$$
$$- D_{\overline{z_2}} \overline{f_1} - 2 e_2 \frac{\partial u_1}{\partial x_0} + 2 e_1 \frac{\partial u_2}{\partial x_0} \right)$$
$$= 2 \hat{i} \gamma \left(D_{\overline{z_1}} - D_{z_1} \right) f$$
(61)

on G. And, similarly, we have

$$D \odot f = -2\hat{i}\gamma \left(D_{z_2} - D_{\overline{z_2}}\right)f \tag{62}$$

on G.

(58)

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