# Neutral Slant Submanifolds of a Para-Kähler Manifold 

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#### Abstract

We define and study both neutral slant and semineutral slant submanifolds of an almost para-Hermitian manifold and, in particular, of a para-Kähler manifold. We give characterization theorems for neutral slant and semi-neutral slant submanifolds. We also investigate the integrability conditions for the distributions involved in the definition of a semi-neutral slant submanifold when the ambient manifold is a para-Kähler manifold.


## 1. Introduction

The geometry of slant submanifolds was initiated by Chen, as a generalization of both holomorphic and totally real submanifolds in complex geometry [1, 2]. Since then, many mathematicians have studied these submanifolds. Slant submanifolds have been studied by many geometers in various manifolds [3-5]. In particular, Papaghiuc [6] introduced semislant submanifolds. Lotta $[7,8]$ defined and studied slant submanifolds in contact geometry. Cabrerizo et al. studied slant, semislant, and bislant submanifolds in contact geometry [9, 10]. Recently, Arslan et al. [11] studied these submanifolds in the setting of neutral Kähler manifolds.

In this paper we define and study both neutral slant and semineutral slant submanifolds of an almost para-Hermitian manifold and, in particular, of a para-Kähler manifold. The paper is organized as follows. In Section 2, we review some formulas and definitions for an almost para-Hermitian manifold and their submanifolds. In Section 3, we define neutral slant submanifolds for an almost para-Hermitian manifold and give theorem for a neutral slant submanifold. In the last section, we define and study semineutral slant submanifolds of an almost para-Hermitian manifold. We give theorems for a semineutral slant submanifold. In the last part of Section 4, we obtain that the distributions are integrable and their leaves are totally geodesic in semineutral slant submanifold under the condition $\nabla f=0$. Finally, the paper contains some examples.

## 2. Preliminaries

An almost para-Hermitian manifold $(\bar{M}, g, J)$ is a smooth manifold endowed with an almost paracomplex structure $J$ and a pseudo-Riemannian metric $g$ compatible in the sense that

$$
\begin{equation*}
J^{2}=I, \quad g(J X, Y)+g(X, J Y)=0, \quad X, Y \in \Gamma(T \bar{M}) \tag{1}
\end{equation*}
$$

where $\Gamma(T M)$ is the module of differentiable vector fields on $M$. It follows that the metric $g$ is neutral; that is, it has signature $(m, m)$, and the eigenbundles $T \bar{M}^{ \pm}$are totally isotropic with respect to $g$.

An almost para-Hermitian manifold $\bar{M}$ is called a paraKähler manifold if

$$
\begin{equation*}
\left(\bar{\nabla}_{X} J\right) Y=0, \quad \forall X, Y \in \Gamma(T \bar{M}) \tag{2}
\end{equation*}
$$

where $\bar{\nabla}$ is the Levi-Civita connection on $\bar{M}[12,13]$.
Let $M$ be an isometrically immersed submanifold of an almost para-Hermitian manifold $\bar{M}$. We denote the LeviCivita connections on $M$ and $\bar{M}$ by $\nabla$ and $\bar{\nabla}$, respectively. Then, the Gauss and Weingarten formulas are given by

$$
\begin{align*}
& \bar{\nabla}_{X} Y=\nabla_{X} Y+h(X, Y) \\
& \bar{\nabla}_{X} N=-A_{N} X+\nabla_{X}^{\perp} N \tag{3}
\end{align*}
$$

for any $X, Y \in \Gamma(T M)$ and $N \in \Gamma\left(T M^{\perp}\right)$, where $\nabla^{\perp}$ is the connection in the normal bundle $T M^{\perp}, h$ is the second fundamental form of $M$, and $A_{N}$ is the shape operator. The second fundamental form $h$ and the shape operator $A_{N}$ are related by

$$
\begin{equation*}
g\left(A_{N} X, Y\right)=g(h(X, Y), N) \tag{4}
\end{equation*}
$$

where the induced pseudo-Riemannian metric on $M$ is denoted by the same symbol $g$.

Let us consider that $M$ is an immersed submanifold of an almost para-Hermitian manifold $\bar{M}$. For any $X \in \Gamma(T M)$ and $N \in \Gamma\left(T M^{\perp}\right)$, we put

$$
\begin{align*}
& J X=f X+\omega X  \tag{5}\\
& J N=B N+C N \tag{6}
\end{align*}
$$

where $f X$ (resp., $\omega X$ ) is tangential (resp., normal) part of $J X$ and $B N$ (resp., CN) is tangential (resp., normal) part of $J N$. From (1) and (5), we have

$$
\begin{equation*}
g(f X, Y)=-g(X, f Y) \tag{7}
\end{equation*}
$$

for any $X, Y \in \Gamma(T M)$.
The submanifold $M$ is said to be invariant if $\omega$ is identically zero; that is, $J X=f X \in \Gamma(T M)$, for any $X \in$ $\Gamma(T M)$. On the other hand, $M$ is said to be anti-invariant submanifold if $f$ is identically zero; that is, $J X=\omega X \in$ $\Gamma\left(T M^{\perp}\right)$, for any $X \in \Gamma(T M)$.

For any $X \in \Gamma(T M)$, by a direct calculation, we have

$$
\begin{align*}
& X=f^{2} X+B \omega X, \quad \text { that is, } I=f^{2}+B \omega  \tag{8}\\
& \omega f X+C \omega X=0, \quad \text { that is, } \omega f+C \omega=0 \tag{9}
\end{align*}
$$

Similarly, for any $N \in \Gamma\left(T M^{\perp}\right)$, we have

$$
\begin{align*}
& N=\omega B N+C^{2} N, \quad \text { that is, } I=\omega B+C^{2}, \\
& f B N+B C N=0, \quad \text { that is, } f B+B C=0 . \tag{10}
\end{align*}
$$

Now, let $M$ be an immersed submanifold of an almost para-Kähler manifold $\bar{M}$. For any $X, Y \in \Gamma(T M)$, from $\bar{\nabla}_{X} J Y=J\left(\bar{\nabla}_{X} Y\right)$, taking into account (3), (5), and (6), then we have

$$
\begin{align*}
\nabla_{X} f Y & +h(X, f Y)-A_{\omega Y} X+\nabla_{X}^{\perp} \omega Y  \tag{11}\\
& =f \nabla_{X} Y+\omega \nabla_{X} Y+B h(X, Y)+C h(X, Y)
\end{align*}
$$

Comparing the tangential and normal components of (11), respectively, we get

$$
\begin{gather*}
\left(\nabla_{X} f\right) Y=A_{\omega Y} X+B h(X, Y)  \tag{12}\\
\left(\nabla_{X} \omega\right) Y=\operatorname{Ch}(X, Y)-h(X, f Y) \tag{13}
\end{gather*}
$$

where the covariant derivations of $f$ and $\omega$ are, respectively, defined by

$$
\begin{align*}
& \left(\nabla_{X} f\right) Y=\nabla_{X} f Y-f \nabla_{X} Y, \\
& \left(\nabla_{X} \omega\right) Y=\nabla_{X}^{\perp} \omega Y-\omega \nabla_{X} Y, \tag{14}
\end{align*}
$$

for any $X, Y \in \Gamma(T M)$.

Let $M$ be a submanifold of a para-Hermitian manifold $\bar{M}$. A tangent vector $X \in T M$ is said to be spacelike (resp., timelike) if $g(X, X)>0$ (resp., $g(X, X)<0$ ). If $X$ is a spacelike vector (resp., timelike), we have $\|X\|=\sqrt{g(X, X)}$ (resp., $\|X\|=\sqrt{-g(X, X)}$ ) [11].

## 3. Neutral Slant Submanifolds of Almost Para-Hermitian Manifolds

In this section, we study neutral slant immersions of an almost para-Hermitian manifold $\bar{M}$. First, we present definition of a neutral slant submanifold of an almost paraHermitian manifold following Chen's [1] definition for a Hermitian manifold. Let $M$ be a semi-Riemannian manifold isometrically immersed in an almost para-Hermitian manifold $\bar{M}$. For each nonzero spacelike vector $X$ tangent to $M$ at $x$, the angle $\theta(X), 0 \leq \theta(X) \leq \pi / 2$ between $J X$ and $T_{x} M$ is called the Wirtinger angle of $X$. Then, $M$ is said to be neutral slant if the angle $\theta(X)$ is a constant, which is independent of the choice of $x \in M$ and $X \in \Gamma(T M)$. The angle $\theta$ of a neutral slant immersion is called the slant angle of the immersion. Thus, the invariant and anti-invariant immersions are neutral slant immersions with slant angle $\theta=0$ and $\theta=\pi / 2$, respectively. A neutral slant immersion which is neither invariant nor anti-invariant is called a proper neutral slant immersion.

We note that our definition is quite different from Chen's definition for slant submanifold [1], and the slant submanifold is given by Arslan et al. [11].

Next we give a useful characterization of neutral slant submanifolds in an almost para-Hermitian manifold.

Theorem 1. Let $M$ be a submanifold of a para-Hermitian manifold $\bar{M}$. Then,
(i) $M$ is neutral slant if and only if there exists a constant $\lambda \in[0,1]$ such that $f^{2}=\lambda I$. Furthermore, in this case, if $\theta$ is the slant angle of $M$, it satisfies $\lambda=\cos ^{2} \theta$;
(ii) $M$ is a neutral slant submanifold if and only if there exists a constant $\lambda \in[0,1]$ such that $B^{2} \omega=\lambda I$. Furthermore, in this case, if $\theta$ is the slant angle of $M$, it satisfies $\lambda=\sin ^{2} \theta$.

Proof. (i) Suppose that $M$ is a neutral slant submanifold. For any $X \in \Gamma(T M)$, we can write

$$
\begin{equation*}
\cos \theta(X)=\frac{\|f X\|}{\|J X\|} \tag{15}
\end{equation*}
$$

where $\theta(X)$ is the slant angle. By using (7), (15), and (1), we get

$$
\begin{align*}
g\left(f^{2} X, X\right) & =-g(f X, f X) \\
& =-\cos ^{2} \theta(X) g(J X, J X)  \tag{16}\\
& =\cos ^{2} \theta(X) g(X, X)
\end{align*}
$$

for all $X \in \Gamma(T M)$. Since $g$ is a neutral metric, from (16), we have

$$
\begin{equation*}
f^{2} X=\cos ^{2} \theta(X) X, \quad X \in \Gamma(T M) \tag{17}
\end{equation*}
$$

Let $\lambda=\cos ^{2} \theta$. Then it is obvious that $\lambda \in[0,1]$.
Conversely, let us assume that there exists a constant $\lambda \in$ $[0,1]$ such that $f^{2}=\lambda I$ is satisfied. From (7), (17), and (1), we get

$$
\begin{align*}
\cos \theta(X) & =\frac{g(J X, f X)}{\|J X\|\|f X\|}=-\frac{g\left(X, f^{2} X\right)}{\|J X\|\|f X\|} \\
& =-\lambda \frac{g\left(X, J^{2} X\right)}{\|J X\|\|f X\|}=\lambda \frac{g(J X, J X)}{\|J X\|\|f X\|}, \tag{18}
\end{align*}
$$

for all $X \in \Gamma(T M)$. Thus we have

$$
\begin{equation*}
\cos \theta(X)=\frac{\lambda\|J X\|}{\|f X\|} \tag{19}
\end{equation*}
$$

Since $\cos \theta(X)=\|f X\| /\|J X\|$, then by using the last equation we obtain $\cos ^{2} \theta(X)=\lambda$, which implies that $\theta(X)$ is a constant and so $M$ is a neutral slant.
(ii) From (8) and (i), we have (ii).

Corollary 2. Let $M$ be a neutral slant submanifold of an almost para-Hermitian manifold $\bar{M}$ with slant angle $\theta$. Then, for any $X, Y \in \Gamma(T M)$, we have

$$
\begin{align*}
& g(f X, f Y)=-\cos ^{2} \theta g(X, Y)  \tag{20}\\
& g(\omega X, \omega Y)=-\sin ^{2} \theta g(X, Y) \tag{21}
\end{align*}
$$

Proof. From Theorem 1(i) and (7), we get

$$
\begin{align*}
g(f X, f Y) & =-g\left(f^{2} X, Y\right)  \tag{22}\\
g(f X, f Y) & =-\cos ^{2} \theta g(X, Y)
\end{align*}
$$

for any $X, Y \in \Gamma(T M)$. On the other hand, from (1), (5), and (20), we obtain

$$
\begin{align*}
& g(J X, J Y)=g(f X+\omega X, f Y+\omega Y) \\
& -g(X, Y)=g(f X, f Y)+g(\omega X, \omega Y) \tag{23}
\end{align*}
$$

This completes the proof.
Now, we give some examples of the neutral slant submanifolds in almost para-Hermitian manifolds inspirited by Chen [1].

Note that given a semi-Euclidean space $R_{n}^{2 n}$ with coordinates $\left(x_{1}, \ldots, x_{2 n}\right)$ on $R_{n}^{2 n}$, we can naturally choose an almost paracomplex structure $J$ on $R_{n}^{2 n}$ as follows:

$$
\begin{equation*}
J\left(\frac{\partial}{\partial x_{2 i}}\right)=\frac{\partial}{\partial x_{2 i-1}}, \quad J\left(\frac{\partial}{\partial x_{2 i-1}}\right)=\frac{\partial}{\partial x_{2 i}} \tag{24}
\end{equation*}
$$

where $i=1, \ldots, n$. Let $R_{n}^{2 n}$ be a semi-Euclidean space of signature $(+,-,+,-, \ldots)$ with respect to the canonical basis $\left(\partial / \partial x_{1}, \ldots, \partial / \partial x_{2 n}\right)$.

Example 3. Consider a submanifold $M$ in $R_{2}^{4}$ given by

$$
\begin{equation*}
\varphi(u, v)=(u \cos \alpha, v, u \sin \alpha, 0) . \tag{25}
\end{equation*}
$$

It is easy to see that $M$ is a neutral slant submanifold with the slant angle $\alpha$.

Example 4. Consider a submanifold $M$ in $R_{2}^{4}$ given by

$$
\begin{equation*}
x(u, v)=(u \sin \alpha, v \cos \beta, u \cos \alpha, v \sin \beta) \tag{26}
\end{equation*}
$$

where $\alpha$ and $\beta$ are constant. Then $M$ is a neutral slant submanifold with the slant angle $\cos \theta=|\sin (\alpha+\beta)|$.

Remark 5. Consider $M_{p}^{2 p}$ a neutral submanifold of an almost para-Hermitian manifold ( $\bar{M}, g, J$ ), in fact a neutral manifold $\bar{M}_{n}^{2 n}$, with

$$
\begin{equation*}
|g(f X, J X)| \leq\|f X\|\|J X\| \tag{27}
\end{equation*}
$$

$M$ is called a neutral slant submanifold if the Wirtinger angle between $J X$ and $T_{x} M$ is constant, for all $X \in T_{x} M$ a spacelike vector field and all $x \in M$. It is well defined, because that angle can be measured as usual, it the same angle between $J X$ and $f X$, and they both are timelike vector fields.

In fact, if that conditions hold, it would be the same angle between $J Y$ and $T_{x} M$ for $Y \in T_{x} M$ a timelike vector, both $J Y$ and $f Y$ would be spacelike vector fields. This condition is equivalent to

$$
\begin{equation*}
|g(f X, f X)| \leq|g(J X, J X)| \tag{28}
\end{equation*}
$$

or $\|f X\| \leq\|J X\|$, in fact it is equivalent to Theorem 1 condition $f^{2} X=\cos ^{2} \theta I$.

## 4. Semineutral Slant Submanifolds of Almost Para-Hermitian Manifolds

Definition 6. Let $(\bar{M}, g)$ be an almost para-Hermitian manifold with an almost paracomplex structure $J$. A differentiable distribution on $\bar{M}$ is called a neutral slant distribution if for each $p \in \bar{M}$ and each nonzero spacelike vector $X \in$ $\Gamma\left(D_{p}\right)$, the angle $\theta_{p}$ between $J X$ and $D_{p}$ is a constant, that is, independent of the choice of $p \in \bar{M}$ and $X \in \Gamma\left(D_{p}\right)$. In this case, we call the constant angle $\theta_{p}$ the slant angle of the distribution $D_{p}$.

Let $M$ be an immersed submanifold of an almost paraHermitian manifold $\bar{M}$ and $D$ a differentiable distribution on $M$. We denote the orthogonal distribution to $D$ on $M$ by $D^{\perp}$. Then, for all $X \in \Gamma(T M)$, we write

$$
\begin{equation*}
J X=P_{1} f X+P_{2} f X+\omega X \tag{29}
\end{equation*}
$$

where $P_{1}$ and $P_{2}$ are orthogonal projections on $D$ and $D^{\perp}$, respectively.

Next, we will give a sufficient and necessary condition for a distribution to be slant.

Theorem 7. Let $M$ be a submanifold of an almost paraHermitian manifold $\bar{M}$ and $D$ a differentiable distribution on
M. Then $D$ is a neutral slant distribution if and only if there exists a constant $\lambda \in[0,1]$ such that

$$
\begin{equation*}
\left(P_{1} f\right)^{2}=\lambda I \tag{30}
\end{equation*}
$$

Furthermore, in such case, if $\theta$ is the slant angle of $D$ then $\lambda=\cos ^{2} \theta$.

Proof. We suppose that $D$ is a neutral slant distribution on $M$. Then, from (29), we have

$$
\begin{align*}
\cos \theta(X) & =\frac{g\left(J X, P_{1} f X\right)}{\|J X\|\left\|P_{1} f X\right\|} \\
& =-\frac{g\left(X,\left(P_{1} f\right)^{2} X\right)}{\|J X\|\left\|P_{1} f X\right\|}=\frac{\left\|P_{1} f X\right\|}{\|J X\|} \tag{31}
\end{align*}
$$

which implies that

$$
\begin{equation*}
\left\|P_{1} f X\right\|=\cos \theta(X)\|J X\| \tag{32}
\end{equation*}
$$

for any $X \in \Gamma(D)$. By using (29), (32), and (1), we have

$$
\begin{align*}
g\left(X,\left(P_{1} f\right)^{2} X\right) & =-g\left(P_{1} f X, P_{1} f X\right) \\
& =-\cos ^{2} \theta(X) g(J X, J X)  \tag{33}\\
& =\cos ^{2} \theta(X) g(X, X), \quad \forall X \in \Gamma(D) .
\end{align*}
$$

Since $g$ is a neutral metric, we obtain

$$
\begin{equation*}
\left(P_{1} f\right)^{2} X=\cos ^{2} \theta(X) X, \quad \forall X \in \Gamma(D) \tag{34}
\end{equation*}
$$

If we put $\lambda=\cos ^{2} \theta$, then we have (30).
Conversely, let $\lambda \in[0,1]$ be a constant such that (30) is satisfied. Then, from (1) we have

$$
\begin{align*}
\cos \theta(X) & =\frac{g\left(J X, P_{1} f X\right)}{\|J X\|\left\|P_{1} f X\right\|} \\
& =-\frac{g\left(X,\left(P_{1} f\right)^{2} X\right)}{\|J X\|\left\|P_{1} f X\right\|}=-\lambda \frac{g(X, X)}{\|J X\|\left\|P_{1} f X\right\|}, \tag{35}
\end{align*}
$$

for any $X \in \Gamma(D)$. Thus we get

$$
\begin{equation*}
\cos \theta(X)=\frac{\lambda\|J X\|}{\left\|P_{1} f X\right\|} \tag{36}
\end{equation*}
$$

On the other hand, since $\cos \theta(X)=\left\|P_{1} f X\right\| /\|J X\|$, then we obtain $\cos ^{2} \theta=\lambda$, which implies that $\theta$ is a constant and $D$ is a neutral slant distribution. This completes the proof.

Definition 8. $M$ is called a bineutral slant submanifold of an almost para-Hermitian manifold $\bar{M}$ if there exist two orthogonal distributions $D_{1}$ and $D_{2}$ on $M$ such that
(i) $T M$ admits the orthogonal direct decomposition $T M=D_{1} \oplus D_{2} ;$
(ii) $D_{i}$ is a neutral slant distribution with slant angle $\theta_{i}$ for $i=1,2$.

Given a bineutral slant submanifold $M$, we can write, for any $X \in \Gamma(T M)$,

$$
\begin{equation*}
X=P_{1} X+P_{2} X \tag{37}
\end{equation*}
$$

where $P_{i}$ denotes the component of $X$ in $D_{i}$ for any $i=1,2$. In particular, if $X \in \Gamma\left(D_{i}\right)$, then we obtain $X_{i}=P_{i} X$. If we define $f_{i}=P_{i} \circ f$, then we have

$$
\begin{equation*}
J X=f_{1} X+f_{2} X+\omega X \tag{38}
\end{equation*}
$$

for any $X \in \Gamma(T M)$.
We note that semi-invariant submanifolds are particular cases of bineutral slant submanifolds with slant angles $\theta_{1}=0$ and $\theta_{2}=\pi / 2$.

Theorem 9. Let $M$ be a bineutral slant submanifold with angles $\theta_{1}=\theta_{2}=\theta$. If $g(J X, Y)=0$, for any $X \in \Gamma\left(D_{1}\right)$ and $Y \in \Gamma\left(D_{2}\right)$, then $M$ is slant with angle $\theta$.

Proof. Since $g(J X, Y)=0$, for any $X \in \Gamma\left(D_{1}\right)$ and $Y \in \Gamma\left(D_{2}\right)$, we have $g(f X, Y)=0$; that is, $f X \in \Gamma\left(D_{1}\right)$. Similarly, for $Y \in \Gamma\left(D_{2}\right)$, we find. Then for any $X \in \Gamma(T M), X$ can be written as follows: $X=X_{1}+X_{2}$ such that $X_{1} \in \Gamma\left(D_{1}\right)$ and $X_{2} \in \Gamma\left(D_{2}\right)$ and $\cos ^{2} \theta_{1}=\left\|f X_{1}\right\|^{2} /\left\|J X_{1}\right\|^{2}, \cos ^{2} \theta_{2}=$ $\left\|f X_{2}\right\|^{2} /\left\|J X_{2}\right\|^{2}$. Since $\theta_{1}=\theta_{2}=\theta$, we get

$$
\begin{equation*}
\frac{g(f X, f X)}{g(J X, J X)}=\frac{g\left(f X_{1}, f X_{1}\right)+g\left(f X_{2}, f X_{2}\right)}{g\left(J X_{1}, J X_{1}\right)+g\left(J X_{2}, J X_{2}\right)}=\cos ^{2} \theta \tag{39}
\end{equation*}
$$

which gives assertion of the theorem.
Now, as a generalization of semi-invariant submanifolds, we can define semineutral slant submanifolds of an almost para-Hermitian manifold.

Definition 10. $M$ is called a semineutral slant submanifold of an almost para-Hermitian manifold $\bar{M}$ if there exist two orthogonal distributions $D_{1}$ and $D_{2}$ on $M$ such that
(i) $T M$ admits the orthogonal direct sum $T M=D_{1} \oplus D_{2}$,
(ii) the distribution $D_{1}$ is invariant; that is, $J\left(D_{1}\right)=D_{1}$,
(iii) the distribution $D_{2}$ is neutral slant with slant angle $\theta \neq 0$.

In this case, we call $\theta$ the slant angle of submanifold $M$.
It is obvious that the invariant and anti-invariant distributions of a semineutral slant submanifold are neutral slant distributions with the slant angles $\theta=0$ and $\theta=\pi / 2$, respectively.

Now, let $M$ be a semineutral slant submanifold of an almost para-Hermitian manifold $\bar{M}$. Let $M$ be a semislant submanifold with $d_{1} \operatorname{dim}\left(D_{1}\right)$ and $d_{2} \operatorname{dim}\left(D_{2}\right)$. Then we have the following particular cases.
(i) If $d_{2}=0$, then $M$ is an invariant submanifold.
(ii) If $d_{1}=0$ and $\theta=\pi / 2$, then $M$ is an anti-invariant submanifold.
(iii) If $d_{1}=0$ and $\theta \neq \pi / 2$, then $M$ is a proper neutral slant submanifold with slant angle $\theta$.
(iv) If $d_{1} \cdot d_{2} \neq 0$ and $\theta \neq \pi / 2$, then $M$ is a proper semineutral slant submanifold.

We now give an example of bineutral slant submanifolds.
Example 11. Let $x(u, v, t, s)=(u \sin \alpha, v, u \cos \alpha, 0, s, t \sin \beta$, $0, t \cos \beta$ ), where $\alpha$ and $\beta$ are constant. Then, $M$ is a $4-$ dimensional submanifold of $\bar{M}=R_{4}^{8}$.

By defining

$$
\begin{align*}
& D_{1}=\left\langle\sin \alpha \frac{\partial}{\partial x_{1}}+\cos \alpha \frac{\partial}{\partial x_{3}}, \frac{\partial}{\partial x_{2}}\right\rangle,  \tag{40}\\
& D_{2}=\left\langle\frac{\partial}{\partial x_{5}}, \sin \beta \frac{\partial}{\partial x_{6}}+\cos \beta \frac{\partial}{\partial x_{8}}\right\rangle,
\end{align*}
$$

we have that $T M=D_{1} \oplus D_{2}$ and $D_{1}, D_{2}$ are neutral slant with slant angles $\cos ^{-1}(|\sin \alpha|)$ and $\cos ^{-1}(|\sin \beta|)$, respectively. Thus $M$ is a bineutral slant submanifold of $\bar{M}$.

Now, let $M$ be a semineutral slant submanifold of an almost para-Hermitian manifold $\bar{M}$ and $P_{i},(i=1,2)$, denoting the orthogonal projections on $D_{i},(i=1,2)$. Then, for any $X \in \Gamma(T M)$, applying $J$ to (37), we have

$$
\begin{equation*}
J X=f P_{1} X+f P_{2} X+\omega P_{2} X \tag{41}
\end{equation*}
$$

where

$$
\begin{equation*}
J P_{1} X=f P_{1} X, \quad \omega P_{1} X=0 \tag{42}
\end{equation*}
$$

From (41) and (42), we have

$$
\begin{equation*}
f X=J P_{1} X+f P_{2} X \tag{43}
\end{equation*}
$$

By putting $Y=P_{1} Y$ in (20) and $Y=P_{2} Y$ in (21), we get

$$
\begin{array}{ll}
g\left(f X, f P_{1} Y\right)=-\cos ^{2} \theta g\left(X, P_{1} Y\right), & X, Y \in \Gamma(T M), \\
g\left(\omega X, \omega P_{2} Y\right)=-\sin ^{2} \theta g\left(X, P_{2} Y\right), & X, Y \in \Gamma(T M), \tag{44}
\end{array}
$$

respectively.
We give a characterization for the semineutral slant submanifolds of an almost para-Hermitian manifold.

Theorem 12. Let $M$ be an immersed submanifold of an almost para-Hermitian manifold $\bar{M}$. Then $M$ is a semineutral slant submanifold if and only if there exists a constant $\lambda \in[0,1)$ such that $D=\left\{X \in T M \mid f^{2} X=\lambda X\right\}$ is a distribution. Furthermore, in this case, $\lambda=\cos ^{2} \theta$, where $\theta$ denotes slant angle of $M$.

Proof. Let $M$ be a semineutral slant submanifold and $T M=$ $D_{1} \oplus D_{2}$, where $D_{1}$ is invariant and $D_{2}$ is neutral slant. We put $\lambda=\cos ^{2} \theta$, where $\theta$ denotes slant angle of $M$. For any $X \in \Gamma(D)$, if $X \in \Gamma\left(D_{1}\right)$, then we have

$$
\begin{equation*}
X=J^{2} X=f^{2} X=\lambda X \tag{45}
\end{equation*}
$$

which implies that $\lambda=1$. But this is a contradiction that $\lambda \in$ $[0,1)$. Therefore we obtain $D \subseteq D_{2}$. On the other hand, since $D_{2}$ is a neutral slant distribution, it follows from Theorem 7
that $f^{2} X=\left(f P_{2}\right)^{2} X=\lambda X$, which means that $D_{2} \subseteq D$. Thus $D=D_{2}$ is a distribution.

Conversely, we can consider the orthogonal direct decomposition $T M=D \oplus D^{\perp}$. It is obvious that $f D \subseteq D$, from which we have $g(J X, Y)=-g(X, J Y)=-g(X, f Y)=0$ for any $X \in \Gamma\left(D^{\perp}\right)$ and $Y \in \Gamma(D)$. Hence $D^{\perp}$ is an invariant distribution. Finally, Theorem 7 imply that $D$ is a neutral slant distribution, with slant angle $\theta$ satisfying $\lambda=\cos ^{2} \theta$.

We can easily present some examples of the above situation.

Example 13. $x(u, v, t, r)=(u, 0, u, v \sin \theta, 0, v \cos \theta, t, s)$, $\theta \neq \pi / 2$ defines a four-dimensional proper semineutral slant submanifold $M$, with slant angle $\cos ^{-1}(|\sin \theta / \sqrt{2}|)$, in $R_{4}^{8}$.

Moreover, it is easy to see that

$$
\begin{gather*}
X_{1}=\frac{\partial}{\partial x_{7}}, \quad X_{3}=\frac{\partial}{\partial x_{1}}+\frac{\partial}{\partial x_{3}}, \\
X_{2}=\frac{\partial}{\partial x_{8}}, \quad X_{4}=\sin \theta \frac{\partial}{\partial x_{4}}+\cos \theta \frac{\partial}{\partial x_{6}} \tag{46}
\end{gather*}
$$

from a local orthogonal frame of $T M$. Then, we can define $D_{1}=\operatorname{Span}\left\{X_{1}, X_{2}\right\}$ and $D_{2}=\operatorname{Span}\left\{X_{3}, X_{4}\right\}$.

Example 14. $x(u, v, t, s)=(u, v, t \sin \alpha, s \cos \beta, t \cos \alpha$, $s \sin \beta, 0,0$ ) defines a four-dimensional proper semineutral slant submanifold $M$, with slant angle $\cos \theta=|\sin (\alpha+\beta)|$, in $R_{4}^{8}$, where $\alpha$ and $\beta$ are constant.

Moreover it is easy to see that

$$
\begin{array}{ll}
X_{1}=\frac{\partial}{\partial x_{1}}, & X_{3}=\sin \alpha \frac{\partial}{\partial x_{3}}+\cos \alpha \frac{\partial}{\partial x_{5}} \\
X_{2}=\frac{\partial}{\partial x_{2}}, & X_{4}=\cos \beta \frac{\partial}{\partial x_{4}}+\sin \beta \frac{\partial}{\partial x_{6}} \tag{47}
\end{array}
$$

from a local orthogonal frame of $T M$. Then we can define $D_{1}=\operatorname{Span}\left\{X_{1}, X_{2}\right\}$ and $D_{2}=\operatorname{Span}\left\{X_{3}, X_{4}\right\}$.

Then, it is easy to show that all conditions of Theorem 12 are satisfied.

Next, we will give useful characterizations for integrable conditions of distributions.

Theorem 15. Let $M$ be a semineutral slant submanifold of a para-Kähler manifold $\bar{M}$. Then we have the following:
(a) the distribution $D_{1}$ is integrable if and only if

$$
\begin{equation*}
h(X, f Y)=h(f X, Y) \tag{48}
\end{equation*}
$$

for any $X, Y \in \Gamma\left(D_{1}\right)$,
(b) the distribution $D_{2}$ is integrable if and only if

$$
\begin{equation*}
P_{1}\left(\nabla_{X} f P_{2} Y-\nabla_{Y} f P_{2} X\right)=P_{1}\left(A_{\omega P_{2} Y} X-A_{\omega P_{2} X} Y\right) \tag{49}
\end{equation*}
$$

for any $X, Y \in \Gamma\left(D_{2}\right)$.

Proof. From (2), we get

$$
\begin{equation*}
\bar{\nabla}_{X} J Y=J \bar{\nabla}_{X} Y \tag{50}
\end{equation*}
$$

for all $X, Y \in \Gamma(T \bar{M})$.
(a) By using Gauss-Weingarten formulas, (5), and (6) in (50), we have

$$
\begin{align*}
& \nabla_{X} f Y+h(X, f Y)  \tag{51}\\
& \quad=f \nabla_{X} Y+\omega \nabla_{X} Y+B h(X, Y)+C h(X, Y)
\end{align*}
$$

for any $X, Y \in \Gamma\left(D_{1}\right)$. From (41) and (51), we obtain

$$
\begin{align*}
\nabla_{X} f Y+h(X, f Y)= & f P_{1} \nabla_{X} Y+f P_{2} \nabla_{X} Y+\omega P_{2} \nabla_{X} Y  \tag{52}\\
& +B h(X, Y)+\operatorname{Ch}(X, Y)
\end{align*}
$$

By equating the normal part of the last equation, we have

$$
\begin{equation*}
h(X, f Y)=\omega P_{2} \nabla_{X} Y+\operatorname{Ch}(X, Y) \tag{53}
\end{equation*}
$$

If we change the role of $X$ and $Y$ in (53), we write

$$
\begin{equation*}
h(f X, Y)=\omega P_{2} \nabla_{Y} X+C h(Y, X) \tag{54}
\end{equation*}
$$

Since $h$ is symmetric, from (53) and (54), we get

$$
\begin{equation*}
h(X, f Y)-h(f X, Y)=\omega P_{2}[X, Y], \quad \forall X, Y \in \Gamma\left(D_{1}\right) \tag{55}
\end{equation*}
$$

Assume that the distribution $D_{1}$ is integrable. Then, for any $X, Y \in \Gamma\left(D_{1}\right)$, we have $[X, Y] \in \Gamma\left(D_{1}\right)$ which implies that $\omega P_{2}[X, Y]=0$. Thus from (55) we obtain (48).

Conversely, if (48) is satisfied, then from (55), we have $\omega P_{2}[X, Y]=0$, for any $X, Y \in \Gamma\left(D_{1}\right)$, which implies that $P_{2}[X, Y]=0$. Then we conclude that $[X, Y] \in \Gamma\left(D_{1}\right)$.
(b) From (41) and Gauss-Weingarten formulae, we have

$$
\begin{align*}
\bar{\nabla}_{X} J Y= & \nabla_{X} J P_{1} Y+h\left(X, J P_{1} Y\right)+\nabla_{X} f P_{2} Y+h\left(X, f P_{2} Y\right) \\
& -A_{\omega P_{2} Y} X+\nabla_{X}^{\perp} \omega P_{2} Y \tag{56}
\end{align*}
$$

for all $X, Y \in \Gamma(T M)$. On the other hand, by using (5) and (6), we write

$$
\begin{equation*}
J \bar{\nabla}_{X} Y=f \nabla_{X} Y+\omega \nabla_{X} Y+B h(X, Y)+C h(X, Y) \tag{57}
\end{equation*}
$$

By using (56) and (57) in (50), we get

$$
\begin{align*}
& \nabla_{X} f P_{2} Y+h\left(X, f P_{2} Y\right)-A_{\omega P_{2} Y} X+\nabla_{X}^{\perp} \omega P_{2} Y  \tag{58}\\
& \quad=f \nabla_{X} Y+\omega \nabla_{X} Y+B h(X, Y)+\operatorname{Ch}(X, Y)
\end{align*}
$$

for any $X, Y \in \Gamma\left(D_{2}\right)$. Since $h$ is symmetric we obtain

$$
\begin{equation*}
f[X, Y]=\nabla_{X} f P_{2} Y-\nabla_{Y} f P_{2} X+A_{\omega P_{2} X} Y-A_{\omega P_{2} Y} X \tag{59}
\end{equation*}
$$

which gives

$$
\begin{align*}
P_{1} f[X, Y]= & P_{1}\left\{\nabla_{X} f P_{2} Y-\nabla_{Y} f P_{2} X\right\} \\
& -P_{1}\left\{A_{\omega P_{2} Y} X-A_{\omega P_{2} X} Y\right\} . \tag{60}
\end{align*}
$$

Let the distribution $D_{2}$ be integrable. Then $P_{1} f[X, Y]=0$, for all $X, Y \in \Gamma\left(D_{2}\right)$, and hence from (60), the equation (49) is obvious.

Conversely, if (49) is satisfied then $P_{1} f[X, Y]=0$; that is, $[X, Y] \in \Gamma\left(D_{2}\right)$ for any $X, Y \in \Gamma\left(D_{2}\right)$. This completes the proof.

Definition 16. Let $M$ be a semi-invariant submanifold of an almost para-Hermitian manifold $\bar{M}$. Then we say that
(i) $M$ is $D_{1}$-geodesic if

$$
\begin{equation*}
h(X, Y)=0, \quad \forall X, Y \in \Gamma\left(D_{1}\right) \tag{61}
\end{equation*}
$$

(ii) $M$ is $D_{2}$-geodesic if

$$
\begin{equation*}
h(X, Y)=0, \quad \forall X, Y \in \Gamma\left(D_{2}\right) \tag{62}
\end{equation*}
$$

(iii) $M$ is mixed geodesic if

$$
\begin{equation*}
h(X, Y)=0, \quad \forall X \in \Gamma\left(D_{1}\right), Y \in \Gamma\left(D_{2}\right) . \tag{63}
\end{equation*}
$$

Lemma 17. Let $M$ be a mixed-geodesic semineutral slant submanifold of a para-Kähler manifold $\bar{M}$. Then the distribution $D_{1}$ is integrable if and only if

$$
\begin{equation*}
J A_{N} X=-A_{N} J X \tag{64}
\end{equation*}
$$

for any $X \in \Gamma\left(D_{1}\right)$ and $N \in \Gamma\left(T^{\perp} M\right)$.
Proof. Since $M$ is a mixed-geodesic submanifold, from (4) we find that $A_{N} X$ has no component on $D_{2}$. By using (4) and (1), we obtain

$$
\begin{gather*}
g\left(J A_{N} X, Y\right)=-g\left(A_{N} X, J Y\right)=-g(h(X, J Y), N), \\
g\left(A_{N} J X, Y\right)=g(h(J X, Y), N) . \tag{65}
\end{gather*}
$$

Thus, we can write

$$
\begin{equation*}
g\left(J A_{N} X+A_{N} J X, Y\right)=g(h(J X, Y)-h(X, J Y), N) \tag{66}
\end{equation*}
$$

for all $X, Y \in \Gamma\left(D_{1}\right)$. Taking into account Theorem 15(a) and the last equation, the proof is completed.

Theorem 18. Let $M$ be a semineutral slant submanifold of a para-Kähler manifold $\bar{M}$. If $\nabla \omega=0$, then $M$ is a mixedgeodesic submanifold. Furthermore,
(a) if $X, Y \in \Gamma\left(D_{1}\right)$, then either $M$ is a $D_{1}$-geodesic submanifold or $h(X, Y)$ is an eigenvector of $C^{2}$ with the eigenvalue 1,
(b) if $X, Y \in \Gamma\left(D_{2}\right)$, then either $M$ is a $D_{2}$-geodesic submanifold or $h(X, Y)$ is an eigenvector of $C^{2}$ with the eigenvalue $\cos ^{2} \theta$.

Proof. If $\nabla \omega=0$, then from (13) we get $C h(X, Y)=h(X, f Y)$, for all $X, Y \in \Gamma(T M)$. Since $D_{1}$ is an invariant and $D_{2}$ is a neutral slant distribution with the slant angle $\theta$, we obtain

$$
\begin{align*}
C^{2} h(X, Y) & =C h(X, f Y)=h\left(X, f^{2} Y\right) \\
& =h\left(X, \cos ^{2} \theta Y\right)=\cos ^{2} \theta h(X, Y),  \tag{67}\\
C^{2} h(X, Y) & =C^{2} h(Y, X)=\operatorname{Ch}(Y, f X) \\
& =h\left(Y, f^{2} X\right)=h(Y, X)=h(X, Y),
\end{align*}
$$

for any $X \in \Gamma\left(D_{1}\right), Y \in \Gamma\left(D_{2}\right)$. By using (67) we get

$$
\begin{equation*}
\sin ^{2} \theta h(X, Y)=0 \tag{68}
\end{equation*}
$$

which implies that $h(X, Y)=0$, for any $X \in \Gamma\left(D_{1}\right), Y \in$ $\Gamma\left(D_{2}\right)$, that is, $M$ is mixed-geodesic. Similarly, we obtain

$$
\begin{equation*}
C^{2} h(X, Y)=h(X, Y) \tag{69}
\end{equation*}
$$

for all $X, Y \in \Gamma\left(D_{1}\right)$, and

$$
\begin{equation*}
C^{2} h(X, Y)=\cos ^{2} \theta h(X, Y) \tag{70}
\end{equation*}
$$

for all $X, Y \in \Gamma\left(D_{2}\right)$. This completes the proof.
Proposition 19. Let $M$ be a semineutral slant submanifold of a para-Kähler manifold $\bar{M}$. Then $\nabla \omega=0$ if and only if

$$
\begin{equation*}
A_{C N} Z=-A_{N} f Z \tag{71}
\end{equation*}
$$

for all $Z \in \Gamma(T M), N \in \Gamma\left(T^{\perp} M\right)$.
Proof. From (13) and (1), we get

$$
\begin{align*}
g\left(\left(\nabla_{X} \omega\right) Z, N\right) & =g(C h(X, Z)-h(X, f Z), N) \\
& =-g(h(X, Z), C N)-g(h(X, f Z), N) \tag{72}
\end{align*}
$$

for any $X, Z \in \Gamma(T M), N \in \Gamma\left(T^{\perp} M\right)$. Taking into account (4), we get

$$
\begin{equation*}
g\left(\left(\nabla_{X} \omega\right) Z, N\right)=-g\left(A_{C N} Z+A_{N} f Z, X\right) \tag{73}
\end{equation*}
$$

which completes the proof.
Proposition 20. Let $M$ be a semineutral slant submanifold of a para-Kähler manifold $\bar{M}$. Then $\nabla f=0$ if and only if

$$
\begin{equation*}
A_{\omega P_{2} Y} Z=A_{\omega P_{2} Z} Y \tag{74}
\end{equation*}
$$

for all $Y, Z \in \Gamma(T M)$.
Proof. From (12) and (1) we have

$$
\begin{align*}
g\left(\left(\nabla_{X} f\right) Y, Z\right) & =g\left(A_{\omega Y} X+B h(X, Y), Z\right) \\
& =g\left(A_{\omega P_{2} Y} X, Z\right)-g\left(h(X, Y), \omega P_{2} Z\right)  \tag{75}\\
& =g\left(A_{\omega P_{2} Y} X, Z\right)-g\left(A_{\omega P_{2} Z} X, Y\right),
\end{align*}
$$

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