

Research Article

The Existence of Positive Solutions for Fractional Differential Equations with Integral and Disturbance Parameter in Boundary Conditions

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We study the existence and nonexistence of the positive solutions for the integral boundary value problem of the fractional differential equations with the disturbance parameter a in the boundary conditions and the impact of the disturbance parameter a on the existence of positive solutions. By using the upper and lower solutions method, fixed point index theory and the Schauder fixed point theorem, we obtain sufficient conditions for that the problem has at least one positive solution, two positive solutions and no solutions. Under certain conditions, we also obtain the demarcation point which divides the disturbance parameters into two subintervals such that the boundary value problem has positive solutions for the disturbance parameter in one subinterval while no positive solutions in the other.

1. Introduction

In this paper, we are concerned with the existence and nonexistence of positive solutions for the boundary value problem of the fractional differential equations

$$\begin{aligned} -{}^C D^\delta u(t) &= f(t, u(t)), \quad t \in J, \\ m_1 u(0) - n_1 u'(0) &= 0, \\ m_2 u(1) + n_2 u'(1) &= \int_0^1 g(s) u(s) ds + a, \end{aligned} \quad (1)$$

where $J = [0, 1]$, $1 < \delta \leq 2$, $f \in C(J \times \mathbb{R}^+, \mathbb{R}^+)$, $m_i \geq 0$, $n_i \geq 0$, $m_i^2 + n_i^2 > 0$, $i = 1, 2$, $g \in C(J, \mathbb{R}^+)$, disturbance parameter $a \in \mathbb{R}^+$, and ${}^C D^\delta$ is the Caputo fractional derivative of order δ .

In the recent decades, since fractional differential equations have been applied widely and successfully in the description of complex dynamics, they have been regarded as a valuable tool being used in the fields to handle viscoelastic, physics, chemistry, electrical engineering, biology aspects, and so forth; see [1–12] and references therein. And besides, the boundary value problems for the differential equations

appear in many applications; see [13–16]. As a result, the boundary value problems for the fractional differential equations are one of the most active fields in the researches of nonlinear differential equations theories and plenty of meaningful achievements have been gained in the related fields; see [1–8, 17–29] and the references therein. Due to that the boundary value problems with the integral boundary conditions include two-, three-, and multipoint boundary value problems as special cases and they can better describe the actual phenomenon; more and more emphases have been put on the researches of them; see [19, 20, 30–34] and the references therein.

At the same time, while using the methods of the differential equations to solve the actual problems, it is inevitable that there always exists disturbance which will have great influence on the existence of the solutions. In paper [35, 36], the authors studied nonlinear nonlocal boundary value problem with nonhomogeneous boundary conditions

$$\begin{aligned} u''(t) + f(t, u(t), u'(t)) &= 0, \quad t \in (0, 1), \\ u(0) - \sum_{i=1}^m a_i u(t_i) &= \lambda_1, \end{aligned}$$

$$u(1) - \sum_{i=1}^m b_i u(t_i) = \lambda_2, \quad (2)$$

where they discussed the impact of disturbance parameters λ_1, λ_2 on the existence of the solution and obtained some meaningful conclusions. And then, the authors further studied the 2nth order nonlinear nonlocal boundary value problem with nonhomogeneous boundary conditions; see [37].

The purpose of this paper is to study the impact of the disturbance parameter a on the existence of positive solutions and obtain sufficient conditions for the boundary value problem (1) to have at least one positive solution, at least two solutions, and no solutions. Under certain conditions, we obtain that there exists a constant $a^* > 0$, which separates \mathbb{R}^+ into two disjoint subintervals $M = [0, a^*]$ and $N = (a^*, +\infty)$ such that the boundary value problem (1) has at least two positive solutions for each $a \in (0, a^*)$, at least one positive solution for $a = 0$ and $a = a^*$, and no positive solutions for $a \in N$. The main tools we applied are the upper and lower solutions method, fixed point index theory, and the Schauder fixed point theorem.

This paper is organized as follows. In Section 2, we introduce the basic definitions and the basic properties of the integral kernel. In Section 3, we study the comparison principles and the basic lemmas. In Section 4, we consider the existence and nonexistence of the positive solutions of the boundary value problem (1), and we study the impact of the disturbance parameter a on the existence of positive solutions.

2. Preliminaries

In this section, we give some basic definitions and lemmas which play an important role in our research.

Definition 1 (See [2, 3]). Let $\delta > 0$, for a function $u : (0, +\infty) \rightarrow \mathbb{R}$. The Riemann-Liouville fractional integral operator of order δ of u is defined by

$$I^\delta u(t) = \frac{1}{\Gamma(\delta)} \int_0^t (t-s)^{\delta-1} u(s) ds, \quad (3)$$

provided the integral exists.

The Caputo derivative of order δ for a function $u : (0, +\infty) \rightarrow \mathbb{R}$ is given by

$${}^C D^\delta u(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t \frac{u^{(n)}(s)}{(t-s)^{\delta+1-n}} ds, \quad (4)$$

provided the right side is pointwise defined on $(0, +\infty)$, where $n = [\delta] + 1$ and $n-1 < \delta < n$.

If $\delta = n$, then ${}^C D^\delta u(t) = u^{(n)}(t)$.

Definition 2. Let $AC[0, 1]$ be the space of functions u which are absolutely continuous on $[0, 1]$. We denote $AC^n[0, 1]$ by the set of functions u which have continuous derivatives up to order $n-1$ on $[0, 1]$ such that $u^{(n-1)} \in AC[0, 1]$. In particular, $AC^1[0, 1] = AC[0, 1]$.

Lemma 3 (See [2]). If $u \in AC^n[0, 1]$, then the Caputo fractional derivative ${}^C D^\delta u(t)$ exists almost everywhere on $[0, 1]$, where n is the smallest integer greater than or equal to δ .

Lemma 4 (See [2]). Suppose $\delta > 0$ and $u \in AC^n(J)$. Then

$$\begin{aligned} I^{\delta C} D^\delta u(t) &= u(t) + c_0 + c_1 t + c_2 t^2 + \cdots + c_{n-1} t^{n-1}, \\ c_k &= \frac{u^{(k)}(0)}{k!}, \quad k = 0, 1, 2, \dots, n-1, \end{aligned} \quad (5)$$

where n is the smallest integer greater than or equal to δ .

Definition 5. One says u is a solution of the boundary value problem (1) if $u \in AC^2(J)$, ${}^C D^\delta u(t) \in C(J)$ and satisfies (1). One says u is a positive solution of the boundary value problem (1) if u is a solution of the boundary value problem (1) and $u(t) \geq 0$ and $u(t) \not\equiv 0$ for $t \in J$.

Throughout this paper, we assume the following conditions hold.

(H1) $\rho > 0$, $\bar{g} > 0$ and $n_2((\delta-1)n_1 - (2-\delta)m_1) > 0$, where

$$\begin{aligned} \rho &= m_1 m_2 + m_1 n_2 + m_2 n_1, \\ \bar{g} &= \frac{1}{\rho - \int_0^1 (n_1 + m_1 s) g(s) ds}. \end{aligned} \quad (6)$$

(H2) There exists a function $c \in AC^2(J, (-\infty, 0])$ and ${}^C D^\delta c \in C(J)$ such that $m_1 c(0) - n_1 c'(0) = 0$, $m_2 c(1) + n_2 c'(1) \geq -1$ and $\int_0^1 g(s) c(s) ds \leq -2$.

(H3) $f(\cdot, u)$ is monotonically increasing with respect to u and $f \not\equiv 0$.

For $y \in C(J)$, firstly we consider the boundary value problem

$$\begin{aligned} -{}^C D^\delta u(t) &= y(t), \quad t \in J, \\ m_1 u(0) - n_1 u'(0) &= 0, \end{aligned} \quad (7)$$

$$m_2 u(1) + n_2 u'(1) = \int_0^1 g(s) u(s) ds.$$

Lemma 6. Suppose (H1) holds. Then the boundary value problem (7) has the unique solution

$$u(t) = \int_0^1 H(t, s) y(s) ds, \quad (8)$$

where the function H is given by

$$H(t, s) = G(t, s) + h(t, s), \quad (9)$$

where

$$G(t, s)$$

$$= \frac{1}{\rho \Gamma(\delta)} \times \begin{cases} (n_1 + m_1 t) (m_2 (1-s)^{\delta-1} + n_2 (\delta-1) (1-s)^{\delta-2}) \\ - \rho (t-s)^{\delta-1}, & 0 \leq s < t \leq 1, \\ (n_1 + m_1 t) (m_2 (1-s)^{\delta-1} + n_2 (\delta-1) (1-s)^{\delta-2}), \\ & 0 \leq t \leq s < 1, \end{cases} \quad (10)$$

$$h(t, s) = \bar{g}(n_1 + m_1 t) \int_0^1 g(r) G(r, s) dr. \quad (11)$$

Proof. According to Lemma 4, ${}^C D^\delta u(t) = y(t)$ is equivalent to the following equation:

$$u(t) = -I^\delta y(t) + c_0 + c_1 t, \quad (12)$$

where $c_0 = u(0)$, $c_1 = u'(0)$.

By the boundary condition $m_1 u(0) - n_1 u'(0) = 0$ and $m_2 u(1) + n_2 u'(1) = \int_0^1 g(s) u(s) ds$, we can show

$$\begin{aligned} m_1 c_0 - n_1 c_1 &= 0, \\ m_2 c_0 + (m_2 + n_2) c_1 &= \int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1). \end{aligned} \quad (13)$$

Hence, we can obtain

$$\begin{aligned} c_0 &= \frac{n_1}{\rho} \left(\int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1) \right), \\ c_1 &= \frac{m_1}{\rho} \left(\int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1) \right). \end{aligned} \quad (14)$$

It follows the definition Riemann-Liouville fractional integral that

$$\begin{aligned} u(t) &= -\frac{1}{\Gamma(\delta)} \int_0^t (t-s)^{\delta-1} y(s) ds \\ &+ \frac{n_1 + m_1 t}{\rho \Gamma(\delta)} \\ &\times \left(\int_0^1 m_2 (1-s)^{\delta-1} y(s) ds \right. \\ &\quad \left. + \int_0^1 n_2 (\delta-1) (1-s)^{\delta-2} y(s) ds \right) \\ &+ \frac{n_1 + m_1 t}{\rho} \int_0^1 g(s) u(s) ds, \end{aligned} \quad (15)$$

that is,

$$u(t) = \int_0^1 G(t, s) y(s) ds + \frac{n_1 + m_1 t}{\rho} \int_0^1 g(s) u(s) ds. \quad (16)$$

We multiply by the function g on both sides of (16), integrate from 0 to 1,

$$\begin{aligned} \int_0^1 g(s) u(s) ds &= \int_0^1 g(s) \left(\int_0^1 G(s, r) y(r) dr \right) ds \\ &+ \frac{\int_0^1 g(s) u(s) ds}{\rho} \int_0^1 (n_1 + m_1 s) g(s) ds \\ &= \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) y(s) ds \\ &+ \frac{\int_0^1 g(s) u(s) ds}{\rho} \int_0^1 (n_1 + m_1 s) g(s) ds, \end{aligned} \quad (17)$$

and we can easily get

$$\begin{aligned} \int_0^1 g(s) u(s) ds &= \frac{\rho}{\rho - \int_0^1 (n_1 + m_1 s) g(s) ds} \\ &\times \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) y(s) ds \\ &= \rho \bar{g} \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) y(s) ds. \end{aligned} \quad (18)$$

So,

$$\begin{aligned} u(t) &= \int_0^1 G(t, s) y(s) ds + \frac{n_1 + m_1 t}{\rho} \\ &\cdot \rho \bar{g} \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) y(s) ds \\ &= \int_0^1 G(t, s) y(s) ds + \int_0^1 h(t, s) y(s) ds, \end{aligned} \quad (19)$$

where $h(t, s) = \bar{g}(n_1 + m_1 t) \int_0^1 g(r) G(r, s) dr$.

Hence,

$$u(t) = \int_0^1 H(t, s) y(s) ds. \quad (20)$$

It follows from (12) that

$$\begin{aligned} u'(t) &= -I^{\delta-1} y(t) \\ &+ \frac{m_1}{\rho} \left(\int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1) \right). \end{aligned} \quad (21)$$

We can obtain $u \in AC^2(J)$ and ${}^C D^\delta u(t) \in C(J)$. \square

Similarly, we can obtain the following lemma.

Lemma 7. Suppose (H1) holds and $a \in \mathbb{R}$. Then the boundary value problem

$$\begin{aligned} -{}^C D^\delta u(t) &= 0, \quad t \in J, \\ m_1 u(0) - n_1 u'(0) &= 0, \\ m_2 u(1) + n_2 u'(1) &= \int_0^1 g(s) u(s) ds + a \end{aligned} \quad (22)$$

has the unique solution

$$u^*(t) = \bar{g}a(n_1 + m_1 t). \quad (23)$$

Lemma 8. Suppose (H1) holds. Then the solution $u \in AC^2(J)$ and ${}^C D^\delta u(t) \in C(J)$ of the boundary value problem (1) is equivalent to the solution $u \in C(J)$ of the integral equation

$$u(t) = \int_0^1 H(t, s) f(s, u(s)) ds + \bar{g}a(n_1 + m_1 t), \quad t \in J. \quad (24)$$

Proof. If $u \in AC^2(J)$ and ${}^C D^\delta u(t) \in C(J)$ is the solution of the boundary value problem (1), by Lemma 4, $-{}^C D^\delta u(t) = f(t, u(t))$ is equivalent to the equation

$$u(t) = -I^\delta f(t, u(t)) + c_0 + c_1 t, \quad (25)$$

where $c_0 = u(0)$, $c_1 = u'(0)$.

For convenience, we denote $y(t) = f(t, u(t))$.

Similar to the proof of Lemma 6, we can obtain

$$\begin{aligned} c_0 &= \frac{n_1}{\rho} \left(\int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1) + a \right), \\ c_1 &= \frac{m_1}{\rho} \left(\int_0^1 g(s) u(s) ds + m_2 I^\delta y(1) + n_2 I^{\delta-1} y(1) + a \right). \end{aligned} \quad (26)$$

Substituting c_0 and c_1 into (25), we can obtain

$$\begin{aligned} u(t) &= \int_0^1 G(t, s) y(s) ds \\ &\quad + \frac{n_1 + m_1 t}{\rho} \int_0^1 g(s) u(s) ds + \frac{(n_1 + m_1 t)a}{\rho}. \end{aligned} \quad (27)$$

We multiply by the function g on both sides of (27), integrate from 0 to 1, and get

$$\begin{aligned} \int_0^1 g(s) u(s) ds &= \bar{g}\rho \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) y(s) ds \\ &\quad + \bar{g}a \int_0^1 (n_1 + m_1 s) g(s) ds. \end{aligned} \quad (28)$$

Since $\bar{g} = 1/(\rho - \int_0^1 (n_1 + m_1 s)g(s)ds)$, we have

$$u(t) = \int_0^1 H(t, s) y(s) ds + \bar{g}a(n_1 + m_1 t). \quad (29)$$

That is,

$$u(t) = \int_0^1 H(t, s) f(s, u(s)) ds + \bar{g}a(n_1 + m_1 t). \quad (30)$$

On the other hand, if $u \in C(J)$ is the solution of the integral equation (24), we have

$$\begin{aligned} u'(t) &= -\frac{1}{\Gamma(\delta-1)} \int_0^t (t-s)^{\delta-2} f(s, u(s)) ds \\ &\quad + \frac{m_1}{\rho\Gamma(\delta)} \int_0^1 (m_2(1-s)^{\delta-1} \\ &\quad \quad + n_2(\delta-1)(1-s)^{\delta-2}) \\ &\quad \quad \times f(s, u(s)) ds \\ &\quad + \bar{g}m_1 \int_0^1 \left(\int_0^1 g(r) G(r, s) dr \right) ds + \bar{g}am_1. \end{aligned} \quad (31)$$

It is easy to see that $u' \in AC(J)$.

Hence, $u \in AC^2(J)$ and ${}^C D^\delta u \in C(J)$.

We can easily verify that u satisfies the boundary value problem (1).

Therefore, $u \in AC^2(J)$ and ${}^C D^\delta u(t) \in C(J)$ is the solution of the boundary value problem (1). \square

Lemma 9. Suppose (H1) holds. Then the functions G , h , and H have the following properties;

- (1) $G \in C([0, 1] \times [0, 1])$, $0 \leq G(t, s) \leq (((m_1 + n_1)(m_2 + n_2(\delta-1)))/\Gamma(\delta)\rho)(1-s)^{\delta-2}$ for $(t, s) \in [0, 1] \times [0, 1]$ and there exists a constant $0 < \gamma_1 < 1$ such that for $s \in [0, 1]$

$$\min_{t \in J} G(t, s) \geq \gamma_1 \max_{t \in J} G(t, s); \quad (32)$$

- (2) $h(t, s) \geq 0$ for $(t, s) \in [0, 1] \times [0, 1]$ and there exists a constant $0 < \gamma_2 < 1$ such that for $s \in [0, 1]$

$$\min_{t \in J} h(t, s) = \gamma_2 \max_{t \in J} h(t, s); \quad (33)$$

- (3) $H(t, s) \geq 0$ for $(t, s) \in [0, 1] \times [0, 1]$ and for $s \in [0, 1]$

$$\min_{t \in J} H(t, s) \geq \gamma \max_{t \in J} H(t, s), \quad (34)$$

where $\gamma = \min\{\gamma_1, \gamma_2\}$.

Proof. (1) By the expression of $G(t, s)$, it is easy to see $G \in C([0, 1] \times [0, 1])$.

Since (H1) holds, we can show that for $(t, s) \in [0, 1] \times [0, 1]$

$$G(t, s) \leq \frac{(n_1 + m_1)(m_2 + n_2(\delta-1))}{\rho\Gamma(\delta)}(1-s)^{\delta-2}. \quad (35)$$

For $0 \leq t \leq s < 1$, it follows

$$\begin{aligned} G(t, s) &\geq \frac{n_1 n_2 (\delta-1)(1-s)^{\delta-2}}{\rho\Gamma(\delta)} \\ &\geq \frac{n_2(1-s)^{\delta-2}}{\rho\Gamma(\delta)} (n_1(\delta-1) - (2-\delta)m_1). \end{aligned} \quad (36)$$

For $0 \leq s < t \leq 1$, by (10), we have

$$\begin{aligned} \frac{\partial G(t, s)}{\partial t} &= \frac{1}{\rho \Gamma(\delta)} \left(m_1 (m_2 (1-s)^{\delta-1} \right. \\ &\quad \left. + n_2 (\delta-1) (1-s)^{\delta-2}) \right. \\ &\quad \left. - \rho (\delta-1) (t-s)^{\delta-2} \right), \end{aligned} \quad (37)$$

$$\frac{\partial^2 G(t, s)}{\partial t^2} = \frac{1}{\rho \Gamma(\delta)} \left(-\rho (\delta-1) (\delta-2) (t-s)^{\delta-3} \right) > 0.$$

It is easy to see that

$$\begin{aligned} \max_{t \in [s, 1]} \frac{\partial G(t, s)}{\partial t} &= \frac{\partial G(t, s)}{\partial t} \Big|_{t=1} \\ &= \frac{1}{\rho \Gamma(\delta)} \left(m_1 (m_2 (1-s)^{\delta-1} + n_2 (\delta-1) (1-s)^{\delta-2}) \right. \\ &\quad \left. - \rho (\delta-1) (1-s)^{\delta-2} \right) \\ &= \frac{m_2 (1-s)^{\delta-2}}{\rho \Gamma(\delta)} \left(m_1 (1-s) - (m_1 + n_1) (\delta-1) \right). \end{aligned} \quad (38)$$

(H1) implies that $(m_1 + n_1)(\delta-1) > m_1$. By (38), we have $\max_{t \in [s, 1]} (\partial G(t, s)/\partial t) \leq 0$. Hence,

$$\begin{aligned} \min_{t \in [s, 1]} G(t, s) &= G(1, s) \\ &= \frac{n_2 (1-s)^{\delta-2}}{\rho \Gamma(\delta)} \left((n_1 + m_1) (\delta-1) - m_1 (1-s) \right) \\ &\geq \frac{n_2 (1-s)^{\delta-2}}{\rho \Gamma(\delta)} \left((n_1 + m_1) (\delta-1) - m_1 \right). \end{aligned} \quad (39)$$

For $(t, s) \in [0, 1] \times [0, 1]$, we can show that

$$G(t, s) \geq \frac{n_2 (1-s)^{\delta-2}}{\rho \Gamma(\delta)} \left((n_1 + m_1) (\delta-1) - m_1 \right) > 0 \quad (40)$$

from (36) and (39).

We denote $\gamma_1 = n_2((n_1 + m_1)(\delta-1) - m_1)/(n_1 + m_1)(m_2 + n_2(\delta-1))$. It is obvious that $0 < \gamma_1 < 1$.

By (35) and (39), for $(t, s) \in [0, 1] \times [0, 1]$, we have

$$\begin{aligned} \min_{t \in J} G(t, s) &\geq \frac{n_2 ((n_1 + m_1) (\delta-1) - m_1)}{\rho \Gamma(\delta)} (1-s)^{\delta-2} \\ &\geq \frac{n_2 ((n_1 + m_1) (\delta-1) - m_1)}{\rho \Gamma(\delta)} \\ &\quad \cdot \frac{\rho \Gamma(\delta)}{(n_1 + m_1) (m_2 + n_2 (\delta-1))} \\ &\quad \cdot G(t, s) = \gamma_1 G(t, s). \end{aligned} \quad (41)$$

Hence, $\min_{t \in J} G(t, s) \geq \gamma_1 \max_{t \in J} G(t, s)$.

(2) By the expression of $h(t, s)$, see (11), it is easy to see $h(t, s) \geq 0$ for $(t, s) \in [0, 1] \times [0, 1]$ and

$$\min_{t \in J} h(t, s) = \gamma_2 \max_{t \in J} h(t, s) \quad \text{for } s \in [0, 1], \quad (42)$$

where $\gamma_2 = n_1/(n_1 + m_1)$.

(3) By (1) and (2), we have $H(t, s) \geq 0$ for $(t, s) \in [0, 1] \times [0, 1]$ and

$$\begin{aligned} \min_{t \in J} H(t, s) &= \min_{t \in J} (G(t, s) + h(t, s)) \\ &\geq \min_{t \in J} G(t, s) + \min_{t \in J} h(t, s) \\ &\geq \gamma_1 \max_{t \in J} G(t, s) + \gamma_2 \max_{t \in J} h(t, s) \\ &\geq \gamma \left(\max_{t \in J} G(t, s) + \max_{t \in J} h(t, s) \right) \\ &\geq \gamma \max_{t \in J} H(t, s). \end{aligned} \quad (43)$$

□

For the sake of the reader, we state the fixed point index theorem and Schauder's fixed point theorem which will be used later.

Lemma 10 (See [38]). *Let P be a cone of a real Banach space E , Ω be a bounded open set in E , and $\theta \in \Omega$. Suppose $A : P \cap \bar{\Omega} \rightarrow P$ is a completely continuous operator. If $Au \neq \rho u$ for any $u \in \partial\Omega \cap P$ and $\rho \geq 1$, then*

$$i(A, \Omega \cap P, P) = 1. \quad (44)$$

Lemma 11 (Schauder's fixed point theorem, see [39]). *Let E be a real Banach space, and let $\Omega \subset E$ be nonempty closed bounded and convex; $A : \Omega \rightarrow \Omega$ compact. Then A has a fixed point.*

3. Comparison Principle and the Existence of Solutions

Definition 12. Let $\alpha \in AC^2(J)$ and ${}^C D^\delta \alpha \in C(J)$. One says that α is a lower solution of the boundary value problem (1), if

$$\begin{aligned} -{}^C D^\delta \alpha(t) &\leq f(t, \alpha(t)) + p_\alpha(t), \quad t \in J, \\ m_1 \alpha(0) - n_1 \alpha'(0) &= 0, \end{aligned} \quad (45)$$

where

$$p_\alpha(t) = \begin{cases} 0, & t \in [0, 1] \\ m_2 \alpha(1) + n_2 \alpha'(1) \leq \int_0^1 g(s) \alpha(s) ds + a, & t \in (0, 1) \\ ({}^C D^\delta c(t)) \left(\int_0^1 g(s) \alpha(s) ds + a - m_2 \alpha(1) - n_2 \alpha'(1) \right), & t \in (0, 1) \\ m_2 \alpha(1) + n_2 \alpha'(1) > \int_0^1 g(s) \alpha(s) ds + a, & t \in (0, 1) \end{cases} \quad (46)$$

Let $\beta \in AC^2(J)$ and ${}^C D^\delta \beta \in C(J)$. We say that β is an upper solution of the boundary value problem (1), if

$$\begin{aligned} -{}^C D^\delta \beta(t) &\geq f(t, \beta(t)) + q_\beta(t), \quad t \in J, \\ m_1 \beta(0) - n_1 \beta'(0) &= 0, \end{aligned} \quad (47)$$

where

$$q_\beta(t) = \begin{cases} 0, \\ m_2 \beta(1) + n_2 \beta'(1) \geq \int_0^1 g(s) \beta(s) ds + a, \\ ({}^C D^\delta c(t)) \left(\int_0^1 g(s) \beta(s) ds \right. \\ \quad \left. + a - m_2 \beta(1) - n_2 \beta'(1) \right), \\ m_2 \beta(1) + n_2 \beta'(1) < \int_0^1 g(s) \beta(s) ds + a, \end{cases} \quad (48)$$

where $c(t)$ is defined in (H2).

The following comparison principle will play a very important role in our main results analysis.

Lemma 13. Let (H1) hold. Suppose that $u \in AC^2(J)$, ${}^C D^\delta u \in C(J)$, and satisfies

$$\begin{aligned} -{}^C D^\delta u(t) &\geq 0, \\ m_1 u(0) - n_1 u'(0) &= 0, \\ m_2 u(1) + n_2 u'(1) &\geq \int_0^1 g(s) u(s) ds. \end{aligned} \quad (49)$$

Then $u(t) \geq 0$ for $t \in J$.

Proof. Denote

$$-{}^C D^\delta u(t) = y(t), \quad (50)$$

then $y(t) \geq 0$ for $t \in J$. Let $a \geq 0$ such that

$$m_2 u(1) + n_2 u'(1) = \int_0^1 g(s) u(s) ds + a. \quad (51)$$

By Lemma 8, we can get that the boundary value problem

$$\begin{aligned} -{}^C D^\delta u(t) &= y(t), \quad t \in J, \\ m_1 u(0) - n_1 u'(0) &= 0, \\ m_2 u(1) + n_2 u'(1) &= \int_0^1 g(s) u(s) ds + a \end{aligned} \quad (52)$$

has unique solution

$$u(t) = \int_0^1 H(t, s) y(s) ds + u^*(t), \quad (53)$$

where $u^*(t) = \bar{g}a(n_1 + m_1 t)$ and $t \in J$.

It follows that $u(t) \geq 0$ for $t \in J$ from Lemma 9. \square

Lemma 14. Let (H1) and (H2) hold. Suppose that $u \in AC^2(J)$, ${}^C D^\delta u \in C(J)$, and satisfies

$$\begin{aligned} -{}^C D^\delta u(t) - ({}^C D^\delta c(t)) \\ \times \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) &\geq 0, \\ m_1 u(0) - n_1 u'(0) &= 0, \\ m_2 u(1) + n_2 u'(1) &< \int_0^1 g(s) u(s) ds. \end{aligned} \quad (54)$$

Then $u(t) \geq 0$ for $t \in J$.

Proof. Let

$$\begin{aligned} v(t) = u(t) + c(t) \left(\int_0^1 g(s) u(s) ds \right. \\ \left. - m_2 u(1) - n_2 u'(1) \right). \end{aligned} \quad (55)$$

Since (H2) holds, we have $c(t) \leq 0$ for $t \in J$, $m_1 c(0) - n_1 c'(0) = 0$, $m_2 c(1) + n_2 c'(1) \geq -1$, and $\int_0^1 g(s) c(s) ds \leq -2$.

Hence, by (54), we have

$$\begin{aligned} u(t) &\geq v(t), \quad \text{for } t \in J, \\ -{}^C D^\delta v(t) &= -{}^C D^\delta u(t) - ({}^C D^\delta c(t)) \\ &\times \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \geq 0, \\ m_1 v(0) - n_1 v'(0) &= m_1 u(0) - n_1 u'(0) \\ &+ \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \\ &\times (m_1 c(0) - n_1 c'(0)) \\ &= m_1 u(0) - n_1 u'(0) = 0, \\ m_2 v(1) + n_2 v'(1) &= m_2 u(1) + n_2 u'(1) \\ &+ \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \\ &\times (m_2 c(1) + n_2 c'(1)) \end{aligned}$$

$$\begin{aligned}
 &\geq m_2 u(1) + n_2 u'(1) \\
 &\quad - \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \\
 &= (-2) \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \\
 &\quad + \int_0^1 g(s) u(s) ds \\
 &\geq \int_0^1 g(s) c(s) ds \\
 &\quad \times \left(\int_0^1 g(s) u(s) ds - m_2 u(1) - n_2 u'(1) \right) \\
 &\quad + \int_0^1 g(s) u(s) ds \\
 &= \int_0^1 g(s) v(s) ds.
 \end{aligned} \tag{56}$$

In view of Lemma 13, $v(t) \geq 0$ for $t \in J$, which implies that $u(t) \geq 0$. \square

We can easily obtain the following lemma from the definition of u^* , where u^* is defined by Lemma 7.

Lemma 15. Suppose (H1) holds. u is a positive solution of the boundary value problem (1) if and only if $w = u - u^*$ is a positive solution of the boundary value problem

$$\begin{aligned}
 -^C D^\delta w(t) &= f(t, w(t) + u^*(t)), \quad t \in J, \\
 m_1 w(0) - n_1 w'(0) &= 0, \\
 m_2 w(1) + n_2 w'(1) &= \int_0^1 g(s) w(s) ds.
 \end{aligned} \tag{57}$$

Let $E = C(J)$ be the Banach space with the norm $\|u\| = \max_{t \in J} |u(t)|$,

$$P = \{u \in E : u(t) \geq 0 \text{ for } t \in J\}, \tag{58}$$

and let

$$P_0 = \{u \in E : u(t) \geq 0, u(t) \geq \gamma \|u\| \text{ for } t \in J\} \tag{59}$$

be cones in E , and $P_0 \subset P$, where γ is defined by Lemma 9.

Lemma 16. Suppose (H1) holds. If w is a positive solution of the boundary value problem (57), then

$$\min_{t \in J} w(t) \geq \gamma \|w\|. \tag{60}$$

Proof. By Lemma 6, we can show that the solution w of the boundary value problem (57) satisfies

$$w(t) = \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds. \tag{61}$$

In view of Lemma 9(3),

$$\begin{aligned}
 \min_{t \in J} w(t) &= \min_{t \in J} \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\
 &\geq \int_0^1 \gamma \max_{t \in J} H(t, s) f(s, w(s) + u^*(s)) ds \\
 &\geq \gamma \max_{t \in J} \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\
 &= \gamma \max_{t \in J} w(t) = \gamma \|w\|.
 \end{aligned} \tag{62}$$

\square

We define $T : P \rightarrow E$ by

$$Tw(t) = \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds. \tag{63}$$

By Lemma 16, we have $T : P \rightarrow P_0$. Since f and H are nonnegative, then u is a positive solution of (1) if and only if $w \in P$ is a fixed point of the operator T .

Theorem 17. Suppose (H1), (H2), and (H3) hold and there exist a nonnegative lower solution α and an upper solution β of the boundary value problem (1) such that $\alpha \leq \beta$. Then the boundary value problem (1) has at least one solution u such that $\alpha \leq u \leq \beta$.

Proof. Let

$$F(t, u) = \begin{cases} f(t, \beta(t)), & u > \beta(t), \\ f(t, u), & \alpha(t) \leq u \leq \beta(t), \\ f(t, \alpha(t)), & u < \alpha(t). \end{cases} \tag{64}$$

We consider the boundary value problem

$$\begin{aligned}
 -^C D^\delta u(t) &= F(t, u(t)), \quad t \in J, \\
 m_1 u(0) - n_1 u'(0) &= 0,
 \end{aligned} \tag{65}$$

$$m_2 u(1) + n_2 u'(1) = \int_0^1 g(s) u(s) ds + a.$$

By Lemma 15, u is a positive solution of the boundary value problem (65) if and only if $w = u - u^*$ is a positive solution of the following boundary value problem:

$$\begin{aligned}
 -^C D^\delta w(t) &= F(t, w(t) + u^*(t)), \quad t \in J, \\
 m_1 w(0) - n_1 w'(0) &= 0,
 \end{aligned} \tag{66}$$

$$m_2 w(1) + n_2 w'(1) = \int_0^1 g(s) w(s) ds.$$

We define $\hat{T} : P \rightarrow E$ by

$$\hat{T}w(t) = \int_0^1 H(t, s) F(s, w(s) + u^*(s)) ds. \tag{67}$$

Then w is a solution of (66) if and only if w is a fixed point of the operator \hat{T} . It is easy to see $\hat{T} : P \rightarrow P_0$.

Next we can prove that \hat{T} is completely continuous.

Let $D \subset P$ be a bounded set, and there exists a constant $M_0 > 0$ such that $\|w\| \leq M_0$ for $w \in D$. Because F is continuous, there exists a constant $M_1 > 0$ such that $\max_{s \in J, w \in D} |F(s, w(s) + u^*(s))| \leq M_1$. We have

$$|\hat{T}w(t)| \leq M_1 \int_0^1 H(t, s) ds \leq M_1 \max_{t \in J} \int_0^1 H(t, s) ds. \quad (68)$$

So $\hat{T}(D)$ is uniformly bounded.

We denote

$$\begin{aligned} G_1(t, s) &= \frac{1}{\rho\Gamma(\delta)} (n_1 + m_1 t) \\ &\quad \times (m_2(1-s)^{\delta-1} + n_2(\delta-1)(1-s)^{\delta-2}), \\ G_2(t, s) &= \frac{1}{\Gamma(\delta)} \begin{cases} -(t-s)^{\delta-1}, & 0 \leq s \leq t \leq 1, \\ 0, & 0 \leq t < s \leq 1, \end{cases} \\ z(s) &= \frac{1}{\rho\Gamma(\delta)} \\ &\quad \times (m_2(1-s)^{\delta-1} + n_2(\delta-1)(1-s)^{\delta-2}) \\ &\quad + \bar{g} \int_0^1 g(r) G(r, s) dr. \end{aligned} \quad (69)$$

Hence,

$$\begin{aligned} H(t, s) &= G(t, s) + h(t, s) \\ &= G_1(t, s) + G_2(t, s) + h(t, s) \\ &= (n_1 + m_1 t) z(s) + G_2(t, s), \end{aligned} \quad (70)$$

where $h(t, s)$ is defined by (11).

Since $G_2(t, s)$ is continuous on $J \times J$, we have G_2 which is uniformly continuous on $J \times J$. It implies that for any $\varepsilon > 0$, there exists $\delta_1 > 0$, when $t_1, t_2 \in J$; whenever $|t_2 - t_1| < \delta_1$ and $s \in J$, we can obtain

$$|G_2(t_2, s) - G_2(t_1, s)| < \frac{\varepsilon}{2M_1}. \quad (71)$$

By (H1), it is easy to see $\int_0^1 z(s) ds \neq 0$. We take $0 < \delta_0 \leq \min\{\delta_1, \varepsilon/(2M_1(m_1 + 1) \int_0^1 z(s) ds)\}$.

Therefore, as $t_1, t_2 \in J$, whenever $|t_2 - t_1| < \delta_0$ and $u \in D$, we can show that

$$\begin{aligned} &|\hat{T}w(t_2) - \hat{T}w(t_1)| \\ &= \left| \int_0^1 (H(t_2, s) - H(t_1, s)) F(s, w(s) + u^*(s)) ds \right| \\ &\leq M_1 \int_0^1 |H(t_2, s) - H(t_1, s)| ds \\ &\leq M_1 \int_0^1 m_1 |t_2 - t_1| z(s) ds \\ &\quad + M_1 \int_0^1 |G_2(t_2, s) - G_2(t_1, s)| ds < \varepsilon. \end{aligned} \quad (72)$$

Thus, we have proved \hat{T} is equicontinuous.

By Arzela-Ascoli theorem, we know that $\hat{T}(D)$ is relatively compact.

We can easily show that \hat{T} is continuous since F is continuous. Hence, \hat{T} is completely continuous.

Since F is bounded and \hat{T} is completely continuous, we can get \hat{T} has at least one fixed point w by Schauder fixed point theorem, that is, there exists a solution w of the boundary value problem (66).

Then $u = w + u^*$ is a solution of the boundary value problem (65).

Finally, we prove $\alpha(t) \leq u(t) \leq \beta(t)$, for $t \in J$.

We can prove that if each solution u of the boundary value problem (65) satisfies $\alpha(t) \leq u(t) \leq \beta(t)$ for $t \in J$, then u is a solution of the boundary value problem (1).

Let $v(t) = u(t) - \alpha(t)$, for $t \in J$.

If $m_2\alpha(1) + n_2\alpha'(1) \leq \int_0^1 g(s)\alpha(s)ds + a$, since $f(t, u)$ is monotonically increasing with respect to u and α is a lower solution of (1), we have

$$\begin{aligned} -{}^C D^\delta v(t) &= -{}^C D^\delta u(t) + {}^C D^\delta \alpha(t) \\ &\geq F(t, u(t)) - f(t, \alpha(t)) \geq 0, \end{aligned}$$

$$\begin{aligned} &m_1 v(0) - n_1 v'(0) \\ &= m_1 u(0) - n_1 u'(0) - (m_1 \alpha(0) - n_1 \alpha'(0)) = 0, \\ &m_2 v(1) + n_2 v'(1) \\ &= (m_2 u(1) + n_2 u'(1)) - (m_2 \alpha(1) + n_2 \alpha'(1)), \\ &\geq \left(\int_0^1 g(s) u(s) ds + a \right) - \left(\int_0^1 g(s) \alpha(s) ds + a \right) \\ &= \int_0^1 g(s) v(s) ds. \end{aligned} \quad (73)$$

It follows that $v(t) \geq 0$ on J from Lemma 13.

If $m_2\alpha(1) + n_2\alpha'(1) > \int_0^1 g(s)\alpha(s)ds + a$, we have

$$\begin{aligned}
 & -{}^C D^\delta v(t) - ({}^C D^\delta c(t)) \\
 & \quad \times \left(\int_0^1 g(s)v(s)ds - m_2v(1) - n_2v'(1) \right) \\
 & = -{}^C D^\delta u(t) - ({}^C D^\delta c(t)) \\
 & \quad \times \left(\int_0^1 g(s)u(s)ds - m_2u(1) - n_2u'(1) \right) \\
 & \quad - \left(-{}^C D^\delta \alpha(t) - ({}^C D^\delta c(t)) \right. \\
 & \quad \quad \times \left. \left(\int_0^1 g(s)\alpha(s)ds - m_2\alpha(1) - n_2\alpha'(1) \right) \right) \\
 & \geq F(t, u(t)) - ({}^C D^\delta c(t)) \\
 & \quad \times \left(\int_0^1 g(s)u(s)ds - m_2u(1) - n_2u'(1) \right) \\
 & \quad - \left(f(t, \alpha(t)) + ({}^C D^\delta c(t)) \right. \\
 & \quad \quad \times \left. \left(\int_0^1 g(s)\alpha(s)ds + a - m_2\alpha(1) - n_2\alpha'(1) \right) \right. \\
 & \quad \quad \left. \left. - ({}^C D^\delta c(t)) \left(\int_0^1 g(s)\alpha(s)ds \right. \right. \right. \\
 & \quad \quad \quad \left. \left. \left. - m_2\alpha(1) - n_2\alpha'(1) \right) \right) \right) \\
 & = F(t, u(t)) - f(t, \alpha(t)).
 \end{aligned} \tag{74}$$

By (H3), we can get $F(t, u(t)) - f(t, \alpha(t)) \geq 0$, that is,

$$\begin{aligned}
 & -{}^C D^\delta v(t) - ({}^C D^\delta c(t)) \\
 & \quad \times \left(\int_0^1 g(s)v(s)ds - m_2v(1) - n_2v'(1) \right) \geq 0.
 \end{aligned} \tag{75}$$

So,

$$\begin{aligned}
 & m_1v(0) - n_1v'(0) \\
 & = (m_1u(0) - n_1u'(0)) - (m_1\alpha(0) - n_1\alpha'(0)) = 0, \\
 & m_2v(1) + n_2v'(1) \\
 & = m_2u(1) + n_2u'(1) - (m_2\alpha(1) + n_2\alpha'(1)) \\
 & < \int_0^1 g(s)u(s)ds + a - \left(\int_0^1 g(s)\alpha(s)ds + a \right) \\
 & = \int_0^1 g(s)v(s)ds.
 \end{aligned} \tag{76}$$

It follows that $v(t) \geq 0$ on J from Lemma 14.

Hence, we show $\alpha(t) \leq u(t)$ on J .

Similarly, we can get $u(t) \leq \beta(t)$ on J .

Therefore, each solution u of the boundary value problem (65) satisfies $\alpha(t) \leq u(t) \leq \beta(t)$ for $t \in J$. That is, $F(t, u(t)) = f(t, u(t))$, and u is a solution of the boundary value problem (1). \square

Theorem 18. Suppose (H1), (H2), and (H3) hold:

(1) if there exists a constant $\bar{a} > 0$ such that the boundary value problem

$$\begin{aligned}
 & -{}^C D^\delta u(t) = f(t, u(t)), \quad t \in J, \\
 & m_1u(0) - n_1u'(0) = 0, \\
 & m_2u(1) + n_2u'(1) = \int_0^1 g(s)u(s)ds + \bar{a}
 \end{aligned} \tag{77}$$

has a positive solution $\bar{u}(t)$, then for each a with $0 \leq a \leq \bar{a}$, the boundary value problem (1) has a positive solution u and $u^* \leq u \leq \bar{u}$, where $u^*(t) = \bar{g}a(n_1 + m_1t)$ for $t \in J$;

(2) if there exists a constant $\bar{a} > 0$ such that the boundary value problem (77) does not have positive solutions, then for each $a > \bar{a}$, the boundary value problem (1) does not have positive solutions.

Proof. (1) Let $\bar{u}^*(t) = \bar{g}a(n_1 + m_1t)$ for $t \in J$. By Lemma 15, $w = \bar{u} - \bar{u}^*$ is a positive solution of the boundary value problem

$$\begin{aligned}
 & -{}^C D^\delta w(t) = f(t, w(t) + \bar{u}^*(t)), \quad t \in J, \\
 & m_1w(0) - n_1w'(0) = 0,
 \end{aligned} \tag{78}$$

$$m_2w(1) + n_2w'(1) = \int_0^1 g(s)w(s)ds,$$

which implies $\bar{u}^* \leq \bar{u}$.

Since $\bar{u}^*(t) = \bar{g}a(n_1 + m_1t) > \bar{g}a(n_1 + m_1t) = u^*(t)$, we take $\alpha = u^*$ and $\beta = \bar{u}$.

We can easily verify that α and β are a lower solution and an upper solution of the boundary value problem (1) and $\alpha \leq \beta$.

By Theorem 17, we have that the boundary value problem (1) has a positive solution u and $u^* \leq u \leq \bar{u}$.

(2) If there exists a constant $a_0 > \bar{a}$ such that the boundary value problem (77) has a positive solution, by (1), we can show that for each a with $0 \leq a \leq a_0$, the boundary value problem (1) has a positive solution. So, the boundary value problem (1) has a positive solution, for $a = \bar{a}$, which is a contradiction.

Therefore, if there exists a constant $\bar{a} > 0$ such that the boundary value problem (77) does not have positive solutions, then for each $a > \bar{a}$, the boundary value problem (1) does not have positive solutions. \square

4. Impact of Disturbance Parameter a on the Existence of Solutions

For convenience, we give the following notations:

$$\begin{aligned} f^\infty &= \limsup_{u \rightarrow +\infty} \max_{t \in J} \frac{f(t, u)}{u}, & f_\infty &= \liminf_{u \rightarrow +\infty} \min_{t \in J} \frac{f(t, u)}{u}, \\ f^0 &= \limsup_{u \rightarrow 0} \max_{t \in J} \frac{f(t, u)}{u}, & f_0 &= \liminf_{u \rightarrow 0} \min_{t \in J} \frac{f(t, u)}{u}. \end{aligned} \quad (79)$$

We can see that $\int_0^1 \max_{t \in J} H(t, s) ds \neq 0$ from (H1) and we denote $\eta = 1/(\int_0^1 \max_{t \in J} H(t, s) ds)$.

Lemma 19. Suppose that (H1) holds, $f_\infty > \eta/\gamma^2$, and $\Omega \subseteq [0, +\infty)$ is a bounded set. Then for each $a \in \Omega$, there exists a constant τ such that the solution u of the boundary value problem (1) satisfies $\|u\| < \tau$.

Proof. Since $\Omega \subseteq [0, +\infty)$ is a bounded set, there exists a constant σ such that each $a \in \Omega$, and we have $0 \leq a \leq \sigma$.

Since $f_\infty > \eta/\gamma^2$, there exists a constant $r > 0$ such that

$$f(t, u) > \frac{\eta}{\gamma^2} u \quad (80)$$

for any $t \in J$, and $u \geq r$.

By Lemma 15, u is a positive solution of the boundary value problem (1) if and only if $w = u - u^*$ is a positive solution of the boundary value problem (57).

In view of Lemma 16, $\min_{t \in J} w(t) \geq \gamma \|w\|$. We can get $\|w\| \leq r/\gamma$. Otherwise, if $\|w\| > r/\gamma$, we have

$$|w(t) + u^*(t)| \geq |w(t)| \geq \gamma \|w\| \geq r \quad (81)$$

for $t \in J$. Hence,

$$\begin{aligned} w(t) &= \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\ &> \frac{\eta}{\gamma^2} \int_0^1 H(t, s) |w(s) + u^*(s)| ds \\ &\geq \frac{\eta}{\gamma^2} \cdot \gamma^2 \|w\| \int_0^1 \max_{t \in J} H(t, s) ds \\ &= \|w\|, \end{aligned} \quad (82)$$

which is a contradiction.

We take $\tau = (r/\gamma) + \bar{g}\sigma(n_1 + m_1) + 1$, then

$$\|u\| \leq \|w\| + \|u^*\| \leq \frac{r}{\gamma} + \bar{g}\sigma(n_1 + m_1) < \tau. \quad (83)$$

□

Theorem 20. Suppose (H1) holds. If one of the following conditions is satisfied, then the boundary value problem (1) does not have positive solutions:

- (1) $f_0 > \eta/\gamma^2$, $a \geq 0$ and a is small enough;
- (2) $f_\infty > \eta/\gamma^2$, $a > 0$ and a is large enough;
- (3) there exist constants $K_1 \geq 0$ and $K_2 \geq \eta/\gamma^2$ such that

$$f(t, u) > K_1 + K_2 u \quad (84)$$

for $(t, u) \in J \times [0, +\infty)$, and $a \geq 0$.

Proof. (1) If there exists $a \geq 0$ and a is small enough such that the boundary value problem (1) has a positive solution u , we have that $w = u - u^*$ is a positive solution of the boundary value problem (57) by Lemma 15, and $\min_{t \in J} w(t) \geq \gamma \|w\|$ by Lemma 16.

Because $\liminf_{u \rightarrow 0} \min_{t \in J} (f(t, u)/u) = f_0$, there exists a constant $r_1 > 0$ such that

$$f(t, u) > \frac{\eta u}{\gamma^2} \quad (85)$$

for any $t \in J$, and $0 < u \leq r_1$.

We take $a \geq 0$ and a is small enough such that

$$0 < |w(t) + u^*(t)| = w(t) + \bar{g}a(n_1 + m_1 t) \leq r_1 \quad (86)$$

for $t \in J$. Hence,

$$\begin{aligned} w(t) &= \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\ &> \frac{\eta}{\gamma^2} \cdot \gamma \int_0^1 \max_{t \in J} H(t, s) (w(s) + u^*(s)) ds \\ &\geq \frac{\eta}{\gamma^2} \cdot \gamma^2 \|w\| \int_0^1 \max_{t \in J} H(t, s) ds \\ &= \|w\|, \end{aligned} \quad (87)$$

which is a contradiction.

(2) If there exists a constant $\hat{a} > 0$ and \hat{a} is large enough such that the boundary value problem (1) has a positive solution \hat{u} , we have that $\hat{w} = \hat{u} - \hat{u}^*$ is a positive solution by Lemma 15.

By $\liminf_{u \rightarrow +\infty} \min_{t \in J} (f(t, u)/u) = f_\infty$, there exists a constant $r_2 > 0$ such that

$$f(t, u) > \frac{\eta u}{\gamma^2} \quad (88)$$

for any $t \in J$, and $u \geq r_2$. We take $\hat{a} > r_2/\bar{g}n_1$, then

$$|\hat{w}(t) + \hat{u}^*(t)| \geq |\hat{u}^*(t)| = \bar{g}\hat{a}(n_1 + m_1 t) \geq r_2 \quad (89)$$

for $t \in J$. Hence,

$$\begin{aligned} \hat{w}(t) &= \int_0^1 H(t, s) f(s, \hat{w}(s) + \hat{u}^*(s)) ds \\ &> \frac{\eta}{\gamma^2} \cdot \gamma \int_0^1 \max_{t \in J} H(t, s) (\hat{w}(s) + \hat{u}^*(s)) ds \\ &\geq \frac{\eta}{\gamma^2} \cdot \gamma^2 \|\hat{w}\| \int_0^1 \max_{t \in J} H(t, s) ds \\ &= \|\hat{w}\|, \end{aligned} \quad (90)$$

which is a contradiction.

(3) Since there exist constants $K_1 \geq 0$ and $K_2 \geq \eta/\gamma^2$ such that

$$f(t, u) > K_1 + K_2 u \quad (91)$$

for $(t, u) \in J \times [0, +\infty)$, we have

$$\begin{aligned} w(t) &= \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\ &> \gamma \int_0^1 \max_{t \in J} H(t, s) (K_1 + K_2 (w(s) + u^*(s))) ds \\ &\geq K_2 \gamma^2 \|w\| \int_0^1 \max_{t \in J} H(t, s) ds \\ &\geq \|w\|, \end{aligned} \quad (92)$$

which is a contradiction. \square

Theorem 21. Suppose (H1) holds.

- (1) If $0 \leq f^0 < \eta$, then the boundary value problem (1) has at least one positive solution when $a \geq 0$ and a is small enough.
- (2) If $0 \leq f^\infty < \eta$, then the boundary value problem (1) has at least one positive solution when $a \geq 0$.

Proof. (1) Because $\limsup_{u \rightarrow 0} \max_{t \in J} (f(t, u)/u) = f^0$, there exists a constant $r_1 > 0$ such that

$$f(t, u) < \eta u \quad (93)$$

for any $t \in J$, and $0 < u \leq r_1$.

Let $D = \{w \in P : \|w + u^*\| \leq r_1\}$, where $u^*(t) = \bar{g}a(n_1 + m_1 t)$ for $t \in J$. So $\bar{g}a n_1 \leq u^*(t) \leq \bar{g}a(n_1 + m_1)$ for $t \in J$.

Let $0 \leq a < r_1/\bar{g}a(n_1 + m_1)$, then $D \neq \emptyset$.

For any $w \in D$, we have

$$\begin{aligned} 0 \leq Tw(t) &= \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\ &\leq \eta \int_0^1 \max_{t \in J} H(t, s) |w(s) + u^*(s)| ds \\ &\leq \|w + u^*\| \eta \cdot \frac{1}{\eta} \\ &\leq r_1. \end{aligned} \quad (94)$$

That is $T(D) \subset D$. By the Schauder fixed point theorem, we can get that T has at least one fixed point on D . In view of Lemma 15, $u = w + u^*$ is a positive solution of the boundary value problem (1).

(2) Since $\limsup_{u \rightarrow +\infty} \max_{t \in J} (f(t, u)/u) = f^\infty$, there exist constants $\bar{r}_2 > 0$ and $\epsilon > 0$ such that

$$f(t, u) < (f^\infty + \epsilon) u \quad (95)$$

for any $t \in J$ and $u \geq \bar{r}_2$, where ϵ satisfies $f^\infty + \epsilon < \eta$.

Let $M = \max_{(t, u) \in J \times [0, \bar{r}_2]} f(t, u)$. We have

$$f(t, u) \leq M + (f^\infty + \epsilon) u \quad \text{for } (t, u) \in J \times [0, +\infty). \quad (96)$$

We choose $r_2 > \max\{\bar{r}_2, M/(\eta - (f^\infty + \epsilon))\}$ and $D = \{w \in P : \|w + u^*\| \leq r_2\}$, where $u^*(t) = \bar{g}a(n_1 + m_1 t)$ for $t \in J$. Then, for any $w \in D$,

$$\begin{aligned} 0 \leq Tw(t) &= \int_0^1 H(t, s) f(s, w(s) + u^*(s)) ds \\ &\leq \int_0^1 \max_{t \in J} H(t, s) (M + (f^\infty + \epsilon) |w(s) + u^*(s)|) ds \\ &\leq (M + \|w + u^*\| (f^\infty + \epsilon)) \cdot \frac{1}{\eta} \\ &\leq ((\eta - (f^\infty + \epsilon)) r_2 + r_2 (f^\infty + \epsilon)) \cdot \frac{1}{\eta} \\ &= r_2. \end{aligned} \quad (97)$$

That is $T(D) \subset D$. By the Schauder fixed point theorem, we can get that T has at least one fixed point on D . In view of Lemma 15, $u = w + u^*$ is a positive solution of the boundary value problem (1). \square

Theorem 22. Suppose that (H1), (H2), and (H3) hold. If $0 \leq f^0 < \eta$ and $f_\infty > \eta/\gamma^2$, then there exists a constant $a^* \in (0, +\infty)$ with the following properties.

- (1) a^* separates $[0, +\infty)$ into two disjoint subintervals $M = [0, a^*]$ and $N = (a^*, +\infty)$.
- (2) The boundary value problem (1) has at least two positive solutions for each $a \in (0, a^*)$, has at least one positive solution for $a = 0$ and $a = a^*$, and does not have positive solutions for each $a \in N$.

Proof. We have the following four steps to prove the conclusions of Theorem 22.

Step 1. Let

$$\Lambda = \{a \in [0, +\infty) : \text{The boundary value problem has at least one positive solution}\}. \quad (98)$$

By Theorem 21(1), we have $\Lambda \neq \emptyset$.

For each $\bar{a} \in \Lambda$, denote

$$A(\bar{a}) = \{a : 0 \leq a \leq \bar{a}\}. \quad (99)$$

Then, in view of Theorem 18, $A(\bar{a}) \subseteq \Lambda$ if and only if $\bar{a} \in \Lambda$.

It follows that Λ is a bounded set from $f_\infty > \eta/\gamma^2$ and Theorem 20(2).

Let $M = \bigcup_{\bar{a} \in \Lambda} A(\bar{a})$, then M is a bounded set. Hence, the set M has the supremum; we denote $a^* = \sup M$ and we have $a^* > 0$ from Theorem 21.

Step 2. We prove that the boundary value problem (1) has at least one positive solution when $a = a^*$.

Since $a^* = \sup M$, there exist $\{a_k\} \subset M$ and $a_k < a^*$ such that $a_k \rightarrow a^*$ as $k \rightarrow +\infty$.

Let u_k be a solution of the boundary value problem (1) with a replaced by a_k . By Lemma 8, the boundary value problem (1) with $a = a_k$ is equivalent to

$$u_k(t) = \int_0^1 H(t, s) f(s, u_k(s)) ds + \bar{g}a_k(n_1 + m_1 t), \quad k = 1, 2, \dots \quad (100)$$

In view of Lemma 9, $\{u_k\}$ is uniformly bounded and equicontinuous. By Arzela-Ascoli, $\{u_k\}$ has a convergent subsequence; we also denote $\{u_{k_m}\}$, and $\{u_{k_m}\}$ converge to u .

By Lebesgue dominated convergence theorem, we can get

$$u(t) = \int_0^1 H(t, s) f(s, u(s)) ds + \bar{g}a^*(n_1 + m_1 t). \quad (101)$$

Hence, u is a positive solution of the boundary value problem (1) with $a = a^*$.

Step 3. By Theorem 18, when $0 \leq a \leq a^*$, the boundary value problem (1) has at least one positive solution. That is, $M = [0, a^*]$.

Let $N = (a^*, +\infty)$. Then a^* separates $[0, +\infty)$ into two disjoint subintervals $M = [0, a^*]$ and $N = (a^*, +\infty)$; we have that the boundary value problem (1) has at least one positive solution for each $a \in M$ and does not have positive solutions for each $a \in N$.

Step 4. We prove the boundary value problem (1) has at least two positive solutions when $a \in (0, a^*)$.

For each $a \in (0, a^*)$, there exist $\underline{a}, \bar{a} \in M$, such that $0 < \underline{a} < a < \bar{a}$.

Let \bar{u} be a solution of the boundary value problem (1) with a replaced by \bar{a} . By Theorem 18, the boundary value problem (1) has a positive solution u_1 with $u_1 \leq \bar{u}$.

Similarly, let \underline{u} be a solution of the boundary value problem (1) with a replaced by \underline{a} and $\underline{u} \leq u_1$. Hence, $\underline{u} \leq u_1 \leq \bar{u}$.

In fact, we can easily show that $\underline{u} < u_1 < \bar{u}$ from $\underline{a} < a < \bar{a}$ and (H1).

Let $\alpha = \underline{u}$ and $\beta = \bar{u}$. We can easily verify α and β are a lower solution and an upper solution of the boundary value problem (1), respectively, and $\alpha < \beta$.

We choose $\hat{a} \in N$, then $a < a^* < \hat{a}$.

Define $K : [a, \hat{a}] \times P \rightarrow E$ by

$$K(\kappa, u) = \bar{g}\kappa(n_1 + m_1 t) + \int_0^1 H(t, s) f(s, u(s)) ds. \quad (102)$$

Let

$$F(t, u) = \begin{cases} f(t, \beta(t)), & u > \beta(t), \\ f(t, u), & \alpha(t) \leq u \leq \beta(t), \\ f(t, \alpha(t)), & u < \alpha(t), \end{cases} \quad (103)$$

and define $\widehat{K} : [a, \hat{a}] \times P \rightarrow E$ by

$$\widehat{K}(\kappa, u) = \bar{g}\kappa(n_1 + m_1 t) + \int_0^1 H(t, s) F(s, u(s)) ds. \quad (104)$$

Similar to the proof of Theorem 17, we can prove K and \widehat{K} are completely continuous for each $\kappa \in [a, \hat{a}]$. By Lemma 8, u is a positive solution of the boundary value problem (1) if and only if $u = K(a, u)$.

By Lemma 19, there exists a constant τ such that the fixed point u of K satisfies $\|u\| < \tau$ for each $\kappa \in [a, \hat{a}]$.

Let

$$\Omega = \{u \in P : \|u\| < \tau, \alpha(t) < u < \beta(t), t \in J\}. \quad (105)$$

Clearly, Ω is a nonempty open-bounded subset of P .

Since F is bounded, there exists a constant $R > \tau > 0$ such that $|\widehat{K}(\kappa, u)| < R$ for any $(\kappa, u) \in [a, \hat{a}] \times P$. Let $B(\theta, R) = \{u \in E : \|u\| < R\}$; it is obvious that $\Omega \subset P \cap B(\theta, R)$ and $u \neq \mu \widehat{K}u$ for $u \in P \cap \partial B(\theta, R)$, and $\mu \in [0, 1]$. Hence, by Lemma 10, for each $\kappa \in [a, \hat{a}]$, we have

$$i(\widehat{K}(\kappa, u), P \cap B(\theta, R), P) = 1. \quad (106)$$

Because \widehat{K} does not have a fixed point on $P \cap (\overline{B(\theta, R)} \setminus \Omega)$, then for each $\kappa \in [a, \hat{a}]$,

$$i(\widehat{K}(\kappa, u), P \cap (B(\theta, R) \setminus \overline{\Omega}), P) = 0. \quad (107)$$

We notice that $\widehat{K}|_{\Omega} = K$, by the excision property of the fixed point index, (106) and (107), for each $\kappa \in [a, \hat{a}]$, we have

$$\begin{aligned} i(K(\kappa, u), P \cap \Omega, P) &= i(\widehat{K}(\kappa, u), P \cap B(\theta, R), P) \\ &\quad - i(\widehat{K}(\kappa, u), P \cap (B(\theta, R) \setminus \overline{\Omega}), P) = 1. \end{aligned} \quad (108)$$

Since $\hat{a} \in N$, we have $K(\hat{a}, u) \neq u$ for any $u \in P$. So,

$$i(K(\hat{a}, u), P \cap B(\theta, R), P) = 0. \quad (109)$$

We define $H : [0, 1] \times P \cap \overline{B(\theta, R)} \rightarrow E$ by

$$H(t, u) = K((1-t)a + t\hat{a}, u). \quad (110)$$

It is obvious that H is completely continuous.

We can prove $H(t, u) \neq u$ for $(t, u) \in [0, 1] \times P \cap \partial B(\theta, R)$.

Otherwise, if there exists $(t_0, u_0) \in [0, 1] \times P \cap \partial B(\theta, R)$ such that $H(t_0, u_0) = u_0$, that is

$$K((1-t_0)a + t_0\hat{a}, u_0) = u_0, \quad \|u_0\| = R. \quad (111)$$

Hence, u_0 is a solution of the boundary value problem (1) with a replaced by $\kappa = (1-t_0)a + t_0\hat{a}$. We can get $\|u_0\| < \tau$, which is a contradiction.

According to the homotopy invariance of the fixed point index and (109), it follows that

$$\begin{aligned} i(K(a, u), P \cap B(\theta, R), P) &= i(H(0, u), P \cap B(\theta, R), P) \\ &= i(H(1, u), P \cap B(\theta, R), P) \\ &= i(K(\hat{a}, u), P \cap B(\theta, R), P) = 0. \end{aligned} \quad (112)$$

By the additivity property of the fixed point index, (108) and (112), we obtain

$$i(K(a, u), P \cap B(\theta, R) \setminus \overline{\Omega}, P) = -1. \quad (113)$$

Therefore, the boundary value problem (1) has a solution u_2 in $P \cap (B(\theta, R) \setminus \overline{\Omega})$ and $u_1 \neq u_2$ from $u_1 \in \Omega$. That is, the boundary value problem (1) has at least two positive solutions. \square

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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