Research Article

Boundary Value Problem for Nonlinear Implicit Generalized Hilfer-Type Fractional Differential Equations with Impulses

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This article deals with some existence, uniqueness, and Ulam-Hyers-Rassias stability results for a class of boundary value problem for nonlinear implicit fractional differential equations with impulses and generalized Hilfer Fractional derivative. The results are obtained using the Banach contraction principle and Krasnoselskii’s and Schaefer’s fixed-point theorems.

1. Introduction

Differential equations of fractional order have been recently proved to be a powerful tool to study many phenomena in various fields of science and engineering such as electrochemistry, finance, hydrology, electromagnetics, and viscoelasticity. There are numerous books and articles focused on linear and nonlinear initial and boundary value problems for fractional differential equations involving different kinds of fractional derivatives, see, for example, [1–6]. Impulsive fractional differential equations have been considered by many authors (see, for instance, [7–12]). Recent results involving different fractional derivatives can be found in [13–21] and the references therein.

Ulam was the first who raise the concept of stability of functional equations [22]. In 1941, Hyers [23] provided the first answer to Ulam’s question. Thereafter, this type of stability is called the Ulam-Hyers stability. In 1978, Rassias [24] was able to make a remarkable generalization of Ulam-Hyers stability of mappings by considering variables.

Considerable attention has been given to the study of the Ulam-Hyers and Ulam-Hyers-Rassias stability of all kinds of functional equations; one can see the monograph of Abbas et al. [3] and the paper by Rus [25] who discussed the Ulam-Hyers stability for operational equations (see also [26–29]).

Recently, in [30], Harikrishnan et al. investigated existence theory and different kinds of stability in the sense of Ulam, for the following initial value problem with nonlinear generalized Hilfer-type fractional differential equation and impulses:

\[ \begin{align*}
\left( \rho D^{\alpha,\beta} u \right)(t) & = f(t, u(t)), t \in I \setminus \{t_1, \ldots, t_m\}, I := [0, b], \\
\Delta^\rho \mathcal{I}^{1-\gamma} u(t) & \big|_{t=t_k} = L_k(u(t_k)), k = 1, \ldots, m, \\
\rho \mathcal{I}^{1-\gamma} u(0) & = u_0,
\end{align*} \]

where \( \rho D^{\alpha,\beta} \) and \( \rho \mathcal{I}^{1-\gamma} \) are a generalized Hilfer fractional derivative of order \( \alpha \in (0, 1) \) and type \( \beta \in [0, 1] \) and generalized fractional integral of order \( 1 - \gamma \) with \( \gamma = \alpha + \beta - \alpha \beta \), respectively; \( 0 = t_0 < t_1 < \cdots < t_m < t_{m+1} = b < \infty \), \( u(t_k) = \lim_{\epsilon \to 0^+} u(t_k + \epsilon) \), and \( u(t_k) \) represent the right and left hand limits of \( u(t) \) at \( t = t_k \); \( \Delta^\rho \mathcal{I}^{1-\gamma} u(t) \big|_{t=t_k} = \rho \mathcal{I}^{1-\gamma} u(t_k) - \rho \mathcal{I}^{1-\gamma} u(t_k) \); \( f \)}
In this section, we introduce notations, definitions, and preliminary facts which are used throughout this paper. Let $L_k : \mathbb{R} \rightarrow \mathbb{R} ; k = 1, \ldots, m$ are given continuous functions.

Motivated by the works mentioned above, in this paper, we establish existence and uniqueness results to the boundary value problem with nonlinear implicit generalized Hilfer-type fractional differential equation and impulses:

\begin{equation}
\left( {}^{a}D_{t_k}^{\alpha, \beta} u \right)(t) = f \left( t, u(t), \left( {}^{a}D_{t_k}^{\alpha, \beta} u \right)(t) \right), \; t \in J_k, \; k = 0, \ldots, m, \tag{2}
\end{equation}

\begin{equation}
\left( {}^{a}\mathcal{J}_{t_k}^{1-\gamma} u \right)(t_k^+) = \left( {}^{a}\mathcal{J}_{t_k}^{1-\gamma} u \right)(t_k^-) + L_k(u(t_k^-)), \; k = 1, \ldots, m, \tag{3}
\end{equation}

\begin{equation}
c_1 \left( {}^{a}\mathcal{J}_{a^+}^{1-\gamma} u \right)(a^+) + c_2 \left( {}^{a}\mathcal{J}_{a^+}^{1-\gamma} u \right)(b) = c_3, \tag{4}
\end{equation}

where $D_{t_k}^{\alpha, \beta}$ and $\mathcal{J}_{t_k}^{1-\gamma}$ are generalized Hilfer fractional derivative of order $\alpha \in (0, 1)$ and type $\beta \in [0, 1]$ and generalized fractional integral of order $1 - \gamma$ ($\gamma = \alpha + \beta - \alpha \beta$), respectively; $c_1, c_2, c_3$ are real with $c_1 + c_2 \neq 0$; $J_k := (t_{k-1}, t_k], \; k = 0, \ldots, m$; $a = t_0 < t_1 < \cdots < t_m < t_{m+1} = b < \infty$; \(u(t_k^-) = \lim_{\epsilon \to 0^-} u(t_k + \epsilon)\) and \(u(t_k^+) = \lim_{\epsilon \to 0^+} u(t_k - \epsilon)\) represent the right and left hand limits of $u(t)$ at $t = t_k$; $f : (a, b] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a given function; and $L_k : \mathbb{R} \rightarrow \mathbb{R}, \; k = 1, \ldots, m$, are given continuous functions.

The present paper is organized as follows. In Section 2, some notations are introduced and we recall some preliminaries about generalized Hilfer fractional derivative and auxiliary results. In Section 3, three results for problems (2)-(4) are presented which are based on the Banach contraction principle and Krasnoselskii’s and Schaefer’s fixed-point theorems. In Section 4, we discuss the Ulam-Hyers-Rassias stability for problems (2)-(4). Finally, we give examples to illustrate the applicability of our main results.

2. Preliminaries

In this section, we introduce notations, definitions, and preliminary facts which are used throughout this paper. Let $0 < a < b, \; J = [a, b]$.

By $C$, we denote the Banach space of all continuous functions from $J$ into $\mathbb{R}$ with the norm

\begin{equation}
\|u\|_{C} = \sup \{ |u(t)| : t \in J \}. \tag{5}
\end{equation}

We consider the weighted spaces of continuous functions

\begin{equation}
C_{\gamma \phi}(J) = \left\{ u : (a, b] \rightarrow \mathbb{R} : \left( \frac{t^\alpha - a^\alpha}{\rho} \right)^{1-\gamma} u(t) \in C(J, \mathbb{R}) \right\}, \; 0 \leq \gamma < 1, \tag{6}
\end{equation}

\begin{equation}
C_{\gamma \phi}^n(J) = \left\{ u \in C^{n+1}(J) : u^{(n)} \in C_{\gamma \phi}(J) \right\}, \; n \in \mathbb{N}, C_{\gamma \phi}^0(J) = C_{\gamma \phi}(J), \tag{6}
\end{equation}

\begin{equation}
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\end{equation}

with the norms

\begin{equation}
\|u\|_{C_{\gamma \phi}} = \sup_{t \in J} \left( \frac{t^\alpha - a^\alpha}{\rho} \right)^{1-\gamma} u(t), \tag{7}
\end{equation}

\begin{equation}
\|u\|_{C_{\gamma \phi}^n} = \sum_{k=0}^{n-1} \|u^{(k)}\|_{C_{\gamma \phi}} + \|u^{(n)}\|_{C_{\gamma \phi}}. \tag{8}
\end{equation}

Consider the Banach space $PC(J) = \{ u : (a, b] \rightarrow \mathbb{R} : u(t) \in \mathbb{C}(Jk), \; k = 0, \ldots, m \}$, and there exist $u(t_k^-)$ and $\left( {}^{a}\mathcal{J}_{t_k}^{1-\gamma} u \right)(t_k^+), \; k = 0, \ldots, m$, with $u(t_k^-) = u(t_k^+), \; 0 \leq \gamma < 1$.

Also, we consider the weighted space

\begin{equation}
PC_{\gamma \phi}(J) = \left\{ u(t) : \left( \frac{t^\alpha - a^\alpha}{\rho} \right)^{1-\gamma} u(t) \in PC(J) \right\}, \; 0 \leq \gamma < 1, \tag{9}
\end{equation}

\begin{equation}
PC_{\gamma \phi}^n(J) = \left\{ u \in PC^{n+1} : u^{(n)} \in PC_{\gamma \phi}(J) \right\}, \; n \in \mathbb{N}, \tag{10}
\end{equation}

\begin{equation}
PC_{\gamma \phi}^0(J) = PC_{\gamma \phi}(J), \tag{11}
\end{equation}

with the norm

\begin{equation}
\|u\|_{PC_{\gamma \phi}} = \sup_{t \in J} \left( \frac{t^\alpha - a^\alpha}{\rho} \right)^{1-\gamma} u(t), \; k = 0, \ldots, m. \tag{12}
\end{equation}

Consider the space $X_p^c(a, b)(c \in \mathbb{R}, 1 \leq p \leq \infty)$ of those complex-valued Lebesgue measurable functions $f$ on $[a, b]$ for which $\|f\|_{X_p^c} < \infty$, where the norm is defined by

\begin{equation}
\|f\|_{X_p^c} = \left( \int_a^b |t^\alpha f(t)|^p \frac{dt}{t} \right)^{1/p}, \; 1 \leq p < \infty, c \in \mathbb{R}. \tag{13}
\end{equation}

In particular, when $c = 1/p$, the space $X_p^c(a, b)$ coincides with the $L_p(a, b)$ space: $X_p^c(a, b) = L_p(a, b)$.

Definition 1 [31]. Generalized Hilfer fractional integral.

Let $\alpha \in \mathbb{R}_+, \; c \in \mathbb{R}$, and $g \in X_p^c(a, b)$. A generalized Hilfer fractional integral of order $\alpha$ is defined by

\begin{equation}
\left( {}^{a}\mathcal{J}_{a^+}^{\gamma} + g \right)(t) = \int_a^t g^{\alpha-1} \left( \frac{t^\alpha - g^\alpha}{\rho} \right)^{1-\gamma} \frac{g(s)}{\Gamma(\alpha)} ds, \; t > a, \; \rho > 0, \tag{14}
\end{equation}

where $\Gamma(\cdot)$ is the Euler gamma function defined by $\Gamma(\alpha) = \int_0^{\infty} e^{-t} t^{\alpha-1} dt$, $\alpha > 0$.

Definition 2 [31]. Generalized Hilfer fractional derivative.
Let $a \in \mathbb{R}_+ \setminus \mathbb{N}$ and $\rho > 0$. A generalized Hilfer fractional derivative $\rho D_a^\alpha$, of order $\alpha$ is defined by

$$(\rho D_a^\alpha + g)(t) = \delta_a^n(\rho D_a^{\alpha-n} g)(t)$$

$$= \left(1 - \rho \frac{d}{dt}\right)^n a^\alpha \frac{g(s)}{\Gamma(n+\alpha)} ds, \quad t > a, \rho > 0,$$

where $n = [\alpha] + 1$ and $\delta_a^n = (t^{1-\rho}(d/dt))^n$.

**Theorem 3** [31]. Let $0 < a < b < \infty$, $0 < \alpha < b < \infty$, and $0 < a < \beta < \infty$. Then, for $g \in X_a^\alpha(a,b)$, the semigroup property is valid, i.e.,

$$\left(\rho D_a^\alpha + \rho D_b^\beta + g\right)(t) = \left(\rho D_a^\alpha + g\right)(t).$$

**Lemma 4** [31, 32]. Let $\alpha > 0$, and $0 \leq \gamma < 1$. Then, $\rho D_a^\alpha$ is bounded from $PC_{\gamma}(J)$ into $PC_{\gamma}(J)$.

**Lemma 5** [32]. Let $0 < a < b < \infty$, $\alpha > 0$, $0 < \gamma < 1$, and $u \in PC_{\gamma}(J)$. If $\alpha > 1 - \gamma$, then $\rho D_a^\alpha$ is continuous on $J$ and

$$(\rho D_a^\alpha u)(t) = \lim_{t \to a} (\rho D_a^\alpha u)(t) = 0.$$ 

**Lemma 6** [33]. Let $t > a$. Then, for $\alpha > 0$ and $\beta > 0$, we have

$$\left[\rho D_a^\alpha \left(\frac{\rho - a^\alpha}{\rho}\right) \right](t) = \frac{\Gamma(\beta)}{\Gamma(\alpha + \beta)} \left(\frac{t^{\alpha + \beta - 1}}{\rho^\beta}\right) \quad \text{for all } t \in (a, b].$$

**Lemma 7** [32]. Let $\alpha > 0$, $0 < \gamma < 1$, and $g \in PC_{\gamma}(a,b)$. Then,

$$(\rho D_a^\alpha + \rho D_b^\gamma)(t) = g(t), \quad \text{for all } t \in (a,b].$$

**Lemma 8** [32]. Let $0 < a < 1$, $0 \leq \gamma < 1$. If $g \in PC_{\gamma}(a,b)$ and $\rho D_a^{\gamma-a} g \in PC_{\gamma}(a,b)$, then

$$(\rho D_a^\alpha + \rho D_b^\gamma)(t) = g(t) = \left(\rho D_a^\gamma g\right)(t), \quad \text{for all } t \in (a,b].$$

**Definition 9** [32]. Let order $\alpha$ and type $\beta$ satisfy $n - 1 < \alpha < n$ and $0 \leq \beta < 1$, with $n \in \mathbb{N}$. A generalized Hilfer fractional derivative to $t$, with $\rho > 0$ of a function $g \in PC_{\gamma}(a,b)$, is defined by

$$\left(\rho D_a^\alpha + g\right)(t) = \left(\rho D_a^\alpha(\rho D_a^{\alpha-n} g)(t)\right)$$

$$= \left(1 - \rho \frac{d}{dt}\right)^n a^\alpha \frac{g(s)}{\Gamma(n+\alpha)}, \quad \text{for all } t \in (a,b].$$
PC_{γ,p}(f)$. Then, $u \in PC_{γ,p}(f)$ is a solution of the differential equation:

$$
\left(\rho D_t^γ u(t)\right)(t) = f(t, u(t), D_t^β u(t)), \text{ for each } t \in J_k, k = 0, \ldots, m, 0 < a < 1, 0 \leq β \leq 1,
$$

if and only if $u$ satisfies the following Volterra integral equation:

$$
u(t) = \frac{\left(\rho f_{t}^{-\gamma} u(t)\right)}{Γ(γ)} \left(\frac{t^{α} - τ^{α}}{ρ}\right)^{γ-1} + \frac{1}{Γ(α)} \int_{τ}^{t} \left(\frac{t^{α} - s^{α}}{ρ}\right)^{α-1} s^{α-1} f(s, u(s), D_t^β u(s)) ds,
$$

where $γ = α + β - αβ$.

**Theorem 14** (Banach’s fixed-point theorem). Let $D$ be a nonempty closed subset of a Banach space $E$; then, any contraction mapping $N$ of $D$ into itself has a unique fixed point.

**Theorem 15** (Schaefer’s fixed-point theorem). Let $E$ be a Banach space and $N : E \rightarrow E$ be a completely continuous operator. If the set

$$
D = \{ u \in E : u = λNu, \text{ for some } λ \in (0, 1) \},
$$

is bounded, then $N$ has a fixed point.

**Theorem 16** (Krasnoselskii’s fixed-point theorem). Let $D$ be a closed, convex, and nonempty subset of a Banach space $E$ and the operators $A, B$ such that

1. $Ax + By \in D$, for all $x, y \in D$
2. $A$ is compact and continuous
3. $B$ is a contraction mapping

Then, there exists $z \in D$ such that $z = Az + Bz$.

Now, we consider the Ulam stability for problems (2)–(4) that will be used in Section 4. Let $u \in PC_{γ,p}(f)$, $ε > 0$, $τ > 0$, and $θ : (a, b) \rightarrow [0, \infty)$ be a continuous function.

We consider the following inequality:

$$
\left| \left(\rho D_t^γ u(t)\right)(t) - f(t, u(t), \left(\rho D_t^β u(t)\right)(t)) \right| \leq εθ(t), t \in J_k, k = 0, \ldots, m,
$$

and

$$
\left| \left(\rho f_{t}^{-\gamma} u(t)\right)(t) - \left(\rho f_{t}^{-\gamma} u\right)(t) - L_k(u(t)) \right| \leq εr, k = 1, \ldots, m.
$$

**Definition 17** (Ulam-Hyers-Rassias (U-H-R) stability). Problems (2)–(4) are Ulam-Hyers-Rassias (U-H-R) stable with respect to $(θ, τ)$ if there exists a real number $a_{f,m,θ} > 0$ such that for each $ε > 0$ and each solution $u \in PC_{γ,p}(f)$ of inequality (27), there exists a solution $w \in PC_{γ,p}(f)$ of (1)–(3) with

$$
|u(t) - w(t)| \leq a_{f,m,θ}(θ(t) + τ), t \in (a, b).
$$

**Remark 18** (Ulam-Hyers-Rassias stability). A function $u \in PC_{γ,p}(f)$ is a solution of inequality (27) if and only if there exist $σ \in PC_{γ,p}(f)$ and a sequence $σ_k, k = 0, \ldots, m$, such that

1. $|σ(t)| ≤ εθ(t)$ and $|σ_k|≤ ετ, t \in J_k, k = 1, \ldots, m$,
2. $\left(\rho D_t^γ u\right)(t) = f(t, u(t), D_t^β u(t)) + σ(t), t \in J_k, k = 0, \ldots, m$,
3. $\left(\rho D_t^γ u\right)(t) = f(t, u(t), D_t^β u(t)) + σ_k, k = 1, \ldots, m$,

**3. Existence of Solutions**

We consider the following linear fractional differential equation:

$$
\left(\rho D_t^γ u\right)(t) = ψ(t), t \in J_k, k = 0, \ldots, m,
$$

where $0 < α < 1$, $0 ≤ β ≤ 1$, and $ρ > 0$, with the conditions

$$
\left(\rho f_{t}^{-\gamma} u\right)(t) = \left(\rho f_{t}^{γ} u\right)(t) + L_k(u(t)), \quad k = 1, \ldots, m,
$$

and

$$
c_1 \left(\rho f_{t}^{γ} u\right)(a) + c_2 \left(\rho f_{t}^{γ} u\right)(b) = c_3,
$$

where $γ = α + β - αβ$ and $c_1, c_2, c_3 \in \mathbb{R}$ with

$$
c_1 + c_2 \neq 0,
$$

$$
\xi_1 = \frac{c_2}{c_1 + c_2},
$$

$$
\xi_2 = \frac{c_3}{c_1 + c_2},
$$

and

$$
p^* = \sup \left\{ \left(\frac{t_k^α - t_{k-1}^α}{ρ}\right)^{γ-1} : k = 1, \ldots, m \right\}.
$$
Theorem 19. Let $\gamma = \alpha + \beta - \alpha \beta$, where $0 < \alpha < 1$ and $0 \leq \beta \leq 1$. If $\psi : [a, b] \rightarrow \mathbb{R}$ is a function such that $\psi(\cdot) \in C_{\psi}(J)$, then $u \in PC_{\psi}(J)$ satisfies problems (29)–(31) if and only if it satisfies (34).

Proof. Assume $u$ satisfies (29)–(31). If $t \in I_0$, then

$$\left( \frac{\rho}{1} F_{\alpha} u \right)(t) = \psi(t). \quad (35)$$

Lemma 20. implies that

$$u(t) = \frac{\left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(a^+)}{F(y)} \left( \frac{t^\rho - a^\rho}{\rho} \right)^{-\gamma - 1} + \frac{1}{F(\alpha)} \int_{t_1}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds. \quad (36)$$

If $t \in J_1$, then Lemma 13 implies

$$u(t) = \frac{\left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(t_1^+)}{F(y)} \left( \frac{t^\rho - t_1^\rho}{\rho} \right)^{-\gamma - 1} + \frac{1}{F(\alpha)} \int_{t_1}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

$$= \frac{\left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(t_1) + L_1(u(t_1))}{F(y)} \left( \frac{t^\rho - t_1^\rho}{\rho} \right)^{-\gamma - 1} + \frac{1}{F(\alpha)} \int_{t_1}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

$$= \left( \frac{t^\rho - t_1^\rho}{\rho} \right)^{-\gamma - 1} \left[ \left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(a^+) + L_1(u(t_1)) \right] + \frac{1}{F(\alpha)} \int_{t_1}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

$$= \left( \frac{t^\rho - t_1^\rho}{\rho} \right)^{-\gamma - 1} \left[ \left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(a^+) + L_1(u(t_1)) \right] + \frac{1}{F(\alpha)} \int_{t_1}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

If $t \in J_2$, then Lemma 13 implies

$$u(t) = \frac{\left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(t_2)}{F(y)} \left( \frac{t^\rho - t_2^\rho}{\rho} \right)^{-\gamma - 1} + \frac{1}{F(\alpha)} \int_{t_2}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

Repeating the process in this way, the solution $u(t)$ for $t \in J_k$, $k = 1, \cdots, m$, can be written as

$$u(t) = \frac{1}{F(y)} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{-\gamma - 1} \left[ \left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(a^+) + \sum_{i=1}^k L_i(u(t_i^-)) \right] + \frac{1}{F(\alpha)} \int_{t_k}^t \left( \frac{t^\rho - s^\rho}{\rho} \right)^{-\gamma - 1} s^{\rho - 1} \psi(s) ds$$

(39)

Applying $\frac{\rho}{1} F_{\alpha}^{-1}$ on both sides of (39), using Lemma 6 and taking $t = b$, we obtain

$$\left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(b) = \left( \frac{\rho}{1} F_{\alpha}^{-1} u \right)(a^+) + \sum_{i=1}^m L_i(u(t_i^-))$$

$$+ \sum_{i=1}^m \left( \frac{\rho}{1} F_{\alpha}^{-1} \psi \right)(t_i)$$

(40)
Multiplying both sides of (40) by $c_2$ and using condition (31), we obtain

$$c_3 - c_1 \left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) = c_2 \left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) + \sum_{i=1}^{m} L_i(u(t_i^-)) + c_2 \sum_{i=1}^{m} \left( \rho J_{(t_i,\gamma_i]}^{1-\gamma} \psi \right)(t_i) + c_2 \left( \rho J_{(t_m,\gamma_m]}^{1-\gamma} \psi \right)(b),$$

which implies that

$$\left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) = \xi_2 - \xi_1 \sum_{i=1}^{m} L_i(u(t_i^-)) - \xi_1 \sum_{i=1}^{m} \left( \rho J_{(t_i,\gamma_i]}^{1-\gamma} \psi \right)(t_i) - \xi_1 \left( \rho J_{(t_m,\gamma_m]}^{1-\gamma} \psi \right)(b).$$

Substituting (42) into (39) and (36), we obtain (34).

Reciprocally, applying $\rho J_{\alpha}^{1-\gamma}$ on both sides of (34) and using Lemma 6 and Theorem 3, we get

Next, taking the limit $t \to a^+$ of (43) and using Lemma 5, with $1 - \gamma < 1 - \gamma + \alpha$, we obtain

$$\left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) = \xi_2 - \xi_1 \sum_{i=1}^{m} L_i(u(t_i^-)) - \xi_1 \sum_{i=1}^{m} \left( \rho J_{(t_i,\gamma_i]}^{1-\gamma} \psi \right)(t_i) - \xi_1 \left( \rho J_{(t_m,\gamma_m]}^{1-\gamma} \psi \right)(b).$$

Now, taking $t = b$ in (43), we get

$$\left( \rho J_{\alpha}^{1-\gamma} u \right)(b) = \xi_2 + (1 - \xi_1) \left( \sum_{i=1}^{m} L_i(u(t_i^-)) + \sum_{i=1}^{m} \left( \rho J_{(t_i,\gamma_i]}^{1-\gamma} \psi \right)(t_i) + \left( \rho J_{(t_m,\gamma_m]}^{1-\gamma} \psi \right)(b) \right).$$

From (44) and (45), we find that

$$c_1 \left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) + c_2 \left( \rho J_{\alpha}^{1-\gamma} u \right)(b) = c_3,$$

which shows that the boundary condition $c_1 \left( \rho J_{\alpha}^{1-\gamma} u \right)(a^+) + c_2 \left( \rho J_{\alpha}^{1-\gamma} u \right)(b) = c_3$ is satisfied. Next, apply operator $\rho D^\gamma_{\alpha} u$ on both sides of (34), where $k = 0, \cdots, m$. Then, from Lemma 6 and Lemma 12, we obtain

$$\left( \rho D^\gamma_{\alpha} u \right)(t) = \left( \rho D^\gamma_{\alpha} \psi \right)(t).$$
that is, (29) holds. Also, we can easily show that
\[(p^{1-\gamma} u)({t_i}) = (p^{1-\gamma} u)({t_k}) + L_k(u(t_k)), k = 1, \cdots, m.\] (52)

This completes the proof.

As a consequence of Theorem 19, we have the following result.

**Lemma 21.** Let \(\gamma = \alpha + \beta - \alpha\beta\), where \(0 < \alpha < 1\) and \(0 \leq \beta \leq 1\); let \(f: (a, b) \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}\) be a function such that \(f(\cdot, u(\cdot), w(\cdot)) \in C_{\gamma, p}(J)\) for any \(u, w \in PC_{\gamma, p}(J)\). If \(u \in PC_{\gamma, p}^\ast(J)\), then \(u\) satisfies problems (22)–(44) if and only if \(u\) is the fixed point of the operator \(\Psi: PC_{\gamma, p}(J) \to PC_{\gamma, p}(J)\) defined by

\[
\Psi u(t) = \frac{1}{(1-\gamma)\Gamma(\gamma)} \int_0^t (t-s)^{\gamma-1} \left[ \xi_1 - \xi_1 \sum_{i=1}^m L_i(u(t_i^-)) - \xi_1 \sum_{i=1}^m \left( p^{1-\gamma} u(t_i^-) \right) h_i(t) \right] dt \tag{53}
\]

where \(h: (a, b) \to \mathbb{R}\) is a function satisfying the functional equation

\[
h(t) = f(t, u(t), h(t)). \tag{54}
\]

Assume that the function \(f: (a, b) \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}\) is continuous and satisfies the following conditions:

(H1). The function \(f: (a, b) \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}\) be such that

\[
f(\cdot, u(\cdot), w(\cdot)) \in PC_{\gamma, p}^\ast(1-\alpha), \text{ for any } u, w \in PC_{\gamma, p}(J). \tag{55}
\]

(H2). There exist constants \(K > 0\) and \(0 < M < 1\) such that

\[
|f(t, u, w) - f(t, \bar{u}, \bar{w})| \leq K|u - \bar{u}| + M|w - \bar{w}|, \tag{56}
\]

for any \(u, \bar{u}, w, \bar{w} \in \mathbb{R}\) and \(t \in (a, b)\). (H3). There exists a constant \(l^* > 0\) such that

\[
|L_k(u) - L_k(\bar{u})| \leq l^*|u - \bar{u}|, \tag{57}
\]

for any \(u, \bar{u} \in \mathbb{R}\) and \(k = 1, \cdots, m\).

(H4). There exist functions \(p_1, p_2, p_3 \in C(J, \mathbb{R}_+\) with

\[
p_1^* = \sup_{t \in J} p_1(t), \tag{58}
\]

\[
p_2^* = \sup_{t \in J} p_2(t), \tag{59}
\]

\[
p_3^* = \sup_{t \in J} p_3(t) < 1, \tag{60}
\]

such that

\[
|f(t, u, w)| \leq p_1(t) + p_2(t)|u| + p_3(t)|w|, \text{ for } t \in (a, b), u, w \in \mathbb{R}. \tag{59}
\]

(H5). The functions \(L_k: \mathbb{R} \to \mathbb{R}\) are continuous, and there exist constants \(\Phi_1, \Phi_2 > 0\) such that

\[
|L_k(u)| \leq \Phi_1|u|/\Phi_2, \text{ for each } u \in \mathbb{R}, k = 1, \cdots, m. \tag{60}
\]

We are now in a position to state and prove our existence result for problems (22)–(44) based on Banach’s fixed point.

**Theorem 22.** Assume (H1)–(H3) hold. If

\[
L := (|\xi_1| + 1) \left( \frac{m\rho^* p^*}{\Gamma(\gamma)} + \frac{mK}{(1-M)\Gamma(1-\alpha)} \left( \frac{(b^\rho - a^\rho)^\alpha}{\rho} \right) \right) < 1,
\]

then problems (22)–(44) have a unique solution in \(PC_{\gamma, p}(J)\) \(\subseteq PC_{\gamma, p}^\ast(J)\).

**Proof.** The proof will be given in two steps.

Step 1. We show that the operator \(\Psi\) defined in (53) has a unique fixed point \(u^*\) in \(PC_{\gamma, p}(J)\). Let \(u, w \in PC_{\gamma, p}(J)\) and \(t \in (a, b)\); then, we have

\[
|\Psi u(t) - \Psi w(t)| \leq \frac{(t^\rho - t^\rho_k)^{\gamma-1}}{\Gamma(\gamma)} \left[ |\xi_1| \sum_{i=1}^m L_i(u(t_i^-)) - L_i(w(t_i^-)) | + |\xi_1| \right. \times \left( p^{1-\gamma} u(t_i^-) |h(s) - g(s)| |(b) + |\xi_1| \sum_{i=1}^m \left( p^{1-\gamma} u(t_i^-) |h(s) - g(s)| (t_i) \right) + \sum_{a \in J, t < a} \left( p^{1-\gamma} u(t_i^-) |h(s) - g(s)| (t_i) \right) + \left( p^{1-\gamma} u(t_i^-) |h(s) - g(s)| (t_i) \right), \right. \right. \tag{62}
\]

where \(h, g \in C_{\gamma, p}(J)\) such that

\[
h(t) = f(t, u(t), h(t)), \tag{63}
\]

\[
g(t) = f(t, w(t), g(t)).
\]

By (H2), we have

\[
|h(t) - g(t)| = |f(t, u(t), h(t)) - f(t, w(t), g(t))| \leq K|u(t) - w(t)| + M|h(t) - g(t)|. \tag{64}
\]
Then,
\[ |h(t) - g(t)| \leq \frac{K}{1 - M} |u(t) - w(t)|. \]

Therefore, for each \( t \in (a, b) \),
\[
|\Psi u(t) - \Psi w(t)| \\
\leq \frac{(t^\rho - t_k^\rho)}{\Gamma(y) \rho^{y-1}} \left[ |\xi_1| m \rho^* + \frac{|\xi_1| K}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} \right] (b) \\
+ \frac{mK|\xi_1|}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} (t_k) \\
+ \frac{mK|\xi_1|}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} (t).
\]

(65)

Thus,
\[
|\Psi u(t) - \Psi w(t)| \\
\leq \frac{(t^\rho - t_k^\rho)}{\Gamma(y) \rho^{y-1}} \left[ |\xi_1| m \rho^* + \frac{|\xi_1| K}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} \right] (b) \\
+ \frac{mK|\xi_1|}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} (t_k) \\
+ \frac{mK|\xi_1|}{1 - M} \left( \rho \mathcal{F}_{t_k}^{1-y} \left( \frac{t^\rho - t_k^\rho}{\rho} \right) \right)^{-1} (t).
\]

(66)

By Lemma 6, we have
\[
|\Psi u(t) - \Psi w(t)| \\
\leq \frac{1}{\Gamma(y)} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{y-1} \left[ |\xi_1| m \rho^* + \frac{|\xi_1| K \Gamma(y)}{(1 - M) \Gamma(1 - a)} \right] (b) \\
+ \frac{mK|\xi_1|}{1 - M} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a-1} (t_k) \\
+ \frac{mK \Gamma(y)}{(1 - M) \Gamma(1 - a)} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a-1} (t) \\
+ \|u - w\|_{PC_{\gamma^*}} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a+y-1}.
\]

(67)

Hence,
\[
\left| \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{1-y} (\Psi u(t) - \Psi w(t)) \right| \\
\leq \left[ (|\xi_1| + 1) \left( \frac{m \rho^*}{\Gamma(y)} + \frac{mK K \Gamma(y)}{(1 - M) \Gamma(1 + a)} \right) \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a} \right] (b) \\
+ \frac{K}{(1 - M) \Gamma(1 + a)} \left( \frac{|\xi_1|}{\Gamma(y)} \right) \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a} \\
\times \|u - w\|_{PC_{\gamma^*}}.
\]

(69)

which implies that
\[
\|\Psi u - \Psi w\|_{PC_{\gamma^*}} \\
\leq \left[ (|\xi_1| + 1) \left( \frac{m \rho^*}{\Gamma(y)} + \frac{mK K \Gamma(y)}{(1 - M) \Gamma(1 + a)} \right) \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a} \right] (b) \\
+ \frac{K}{(1 - M) \Gamma(1 + a)} \left( \frac{|\xi_1|}{\Gamma(y)} \right) \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a} \\
\times \|u - w\|_{PC_{\gamma^*}}.
\]

(70)

By (61), the operator \( \Psi \) is a contraction. Hence, by Theorem 14, \( \Psi \) has a unique fixed point \( u^* \in PC_{\gamma^*}(J) \).

Step 2. We show that such a fixed point \( u^* \in PC_{\gamma^*}(J) \) is actually in \( PC_{\gamma^*}(J) \).

Since \( u^* \) is the unique fixed point of operator \( \Psi \) in \( PC_{\gamma^*}(J) \), then for each \( t \in I_k \), with \( k = 0, \ldots, m \), we have
\[
u^*(t) = \frac{1}{\Gamma(y)} \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{y-1} \left[ \xi_2 - \xi_1 \sum_{i=1}^{m} \int_{u(t_i)}^{u(t_{i+1})} \mathcal{F}_{t_i}^{1-y} h(t) \right] (t_k) \\
+ \frac{K}{(1 - M) \Gamma(1 + a)} \left( \frac{|\xi_1|}{\Gamma(y)} \right) \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{a} (t_k) \\
+ \sum_{i \neq I_1} \mathcal{F}_{t_i}^{1-y} h(t_i) + \mathcal{F}_{t_1}^{1-y} h(t).
\]

(71)

where \( h \in C_{\gamma^*}(J) \) such that
\[ h(t) = f(t, u^*(t), h(t)). \]

Applying \( \mathcal{D}_{t_1}^{\gamma^*} \) to both sides and by Lemma 6 and Lemma 12, we get
\[ \mathcal{D}_{t_1}^{\gamma^*} u^*(t) = \left( \mathcal{D}_{t_1}^{\gamma^*} \mathcal{F}_{t_1}^{1-y} f(s, u^*(s), h(s)) \right)(t) \]
\[ = \mathcal{D}_{t_1}^{(1+y)} f(s, u^*(s), h(s))(t). \]

(72)

Since \( \gamma \geq \alpha \), by (H1), the right-hand side is in \( PC_{\gamma^*}(J) \) and thus, \( \mathcal{D}_{t_1}^{\gamma^*} u^* \in PC_{\gamma^*}(J) \) which implies that \( u^* \in PC_{\gamma^*}(J) \).
As a consequence of Steps 1 and 2 together with Theorem 22, we can conclude that problems (22)–(44) have a unique solution in $PC_{p, r}(J)$.

Our second result is based on Schaefer’s fixed-point theorem.

**Theorem 23.** Assume (H1), (H4), and (H5) hold. If

\[
[(\xi_1) + 1] \left( \frac{m \Phi_p \gamma^*}{\Gamma(y)} + \frac{m \rho^2 (b^p - a^p)^a}{(1 - p_3)^\Gamma(1 + \alpha) \rho^a} \right) \\
+ \left( \frac{[\xi_1]}{\Gamma(1 + \alpha)} + \frac{\Gamma(y)}{\Gamma(y + \alpha)} \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right) \right) < 1,
\]

(74)

then problems (22)–(44) have at least one solution in $PC_{p, r}(J) \subset PC^\alpha_{p, r}(J)$.

**Proof.** We shall use Schaefer’s fixed-point theorem to prove in several steps that the operator $\Psi$ defined in (53) has a fixed point.

**Step 1.** $\Psi$ is continuous. Let $\{u_n\}$ be a sequence such that $u_n \to u$ in $PC_{p, r}(J)$. Then, for each $t \in (a, b]$, we have

\[
\left| (\Psi(u_n))(t) - (\Psi(u))(t) \right| \leq \frac{1}{\Gamma(y)} \\
\times \left| \xi_1 \right| \sum_{i=1}^{m} |L_i(u_n(t_i)) - L_i(u(t_i))| + \left| \xi_1 \right| \\
\times \left( \frac{p^\gamma - p^\gamma}{\rho} \right) \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} \\
\times \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} (t)
\]

(75)

where $h_n, h \in C_{p, r}(J)$ such that

\[
\begin{align*}
    h_n(t) &= f(t, u_n(t), h_n(t)) \\
    h(t) &= f(t, u(t), h(t)).
\end{align*}
\]

Since $u_n \to u$, then we get $h_n(t) \to h(t)$ as $n \to \infty$, for each $t \in (a, b]$, and since $f$ and $L_k$ are continuous, then we have

\[
\| \Psi u_n - \Psi u \|_{PC_{p, r}} \to 0 \text{ as } n \to \infty.
\]

(77)

**Step 2.** We show that $\Psi$ maps bounded set into bounded set of $PC_{p, r}(J)$. For $\eta > 0$, there exists a positive constant $r$ such that for $u \in B_{\eta} = \{ u \in PC_{p, r}(J): \| u \|_{PC_{p, r}} \leq \eta \}$, we have

\[
\| \Psi(u) \|_{PC_{p, r}} \leq r.
\]

By (H4) and from (53), we have for each $t \in J, k = 0, \ldots, m$,

\[
\left| \left( \frac{p^\gamma - p^\gamma}{\rho} \right) \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} \right| (t)
\]

(78)

which implies that

\[
\| h \|_{PC_{p, r}} \leq p_1 \left( \frac{(b^p - a^p)^a}{\rho} \right)^{1 - \gamma} + p_2 \eta + p_3 \| h \|_{PC_{p, r}} \\
\]

(79)

Then,

\[
\| h \|_{PC_{p, r}} \leq \frac{p_1 \left( \frac{(b^p - a^p)^a}{\rho} \right)^{1 - \gamma} + p_2 \eta + p_3 \| h \|_{PC_{p, r}}}{1 - p_3} = \Lambda.
\]

(80)

Thus, (53) implies

\[
\begin{align*}
\left( \frac{p^\gamma - p^\gamma}{\rho} \right) \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} (t) \\
\leq \frac{1}{\Gamma(y)} \\
\times \left[ \xi_1 \right] \sum_{i=1}^{m} |L_i(u(t_i))| + \left| \xi_1 \right| \\
\times \left( \frac{p^\gamma - p^\gamma}{\rho} \right) \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} (t) \\
\times \left( \frac{\rho^2 - (b^p - a^p)^a}{1 - p_3} \right)^{1 - \gamma} (t)
\end{align*}
\]

(81)
By Lemma 6, we have
\[
\|\Psi u\|_{PC_{\gamma \rho}} \leq (\xi_1 + 1) \left( \frac{m(\Phi_1 p \gamma + \Phi_2)}{\Gamma(y)} + \frac{m\Lambda}{\Gamma(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right) \\
+ A \left( \frac{\xi_1}{\Gamma(1 + \alpha)} + \frac{\Gamma(y)}{\Gamma(y + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right) \\n+ \frac{\Lambda \Gamma(y)}{\Gamma(y + \alpha)} \left( \frac{e_1 - t_k^\rho}{\rho} \right)^\alpha - \left( \frac{e_2 - t_k^\rho}{\rho} \right)^\alpha .
\]
(82)

Step 3. $\Psi$ maps bounded sets into equicontinuous sets of $PC_{\gamma \rho}$.

Let $e_1, e_2 \in J, e_1 < e_2 B_\eta$, be a bounded set of $PC_{\gamma \rho}$ as in Step 2, and let $u \in B_\eta$.

Then,
\[
\left| \left( \frac{e_1^\rho - t_k^\rho}{\rho} \right)^{1-\gamma} (\Psi u)(e_1) - \left( \frac{e_1^\rho - t_k^\rho}{\rho} \right)^{1-\gamma} (\Psi u)(e_2) \right| \\
\leq \frac{1}{\Gamma(y)} \left[ \sum_{\epsilon_1, \epsilon_2, \epsilon_3} |L_k(u(\epsilon_1))| + \sum_{\epsilon_1, \epsilon_2, \epsilon_3} \left( \rho \tilde{f}_{\epsilon_1, \epsilon_2, \epsilon_3} + \rho \tilde{f}_{\epsilon_1, \epsilon_2, \epsilon_3} \right) |h(s)| \right] \\
+ \frac{\Lambda \Gamma(y)}{\Gamma(y + \alpha)} \left( \frac{e_1 - t_k^\rho}{\rho} \right)^\alpha - \left( \frac{e_2 - t_k^\rho}{\rho} \right)^\alpha .
\]
(83)

As $e_1 \to e_2$, the right-hand side of the above inequality tends to zero. From Steps 1 to 3 with Arzela-Ascoli theorem, we conclude that $\Psi : PC_{\gamma \rho} \to PC_{\gamma \rho}$ is continuous and completely continuous.

Step 4. A priori bound. Now it remains to show that the set
\[
G = \{ u \in PC_{\gamma \rho} : u = \lambda \Psi^*(u), \text{ for some } 0 < \lambda^* < 1 \},
\]
(84)
is bounded. Let $u \in G$, then $u = \lambda^* \Psi^*(u)$ for some $0 < \lambda^* < 1$.

By (H4), we have for each $t \in J$
\[
\left| \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{1-\gamma} h(t) \right| = \left| \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{1-\gamma} f(t, u(t), h(t)) \right| \\
\leq \left( \frac{t^\rho - t_k^\rho}{\rho} \right)^{1-\gamma} \left( |p_1(t) + p_2(t)|u(t)| + p_3(t)|h(t)| \right),
\]
which implies that
\[
\|h\|_{PC_{\gamma \rho}} \leq \left( \frac{b^\rho - a^\rho}{\rho} \right)^{1-\gamma} + p_2^* \|u\|_{PC_{\gamma \rho}} + p_3^* \|h\|_{PC_{\gamma \rho}},
\]
(86)
then
\[
\|h\|_{PC_{\gamma \rho}} \leq \frac{p_1^* \left( \left( \frac{b^\rho - a^\rho}{\rho} \right)^{1-\gamma} + p_2^* \|u\|_{PC_{\gamma \rho}} + p_3^* \|h\|_{PC_{\gamma \rho}} \right)}{1 - p_3^*}.
\]
(87)

This implies, by (53) and (H5) and by letting the estimation of Step 2, that for each $t \in J$, we have
\[
\|u\|_{PC_{\gamma \rho}} \leq (\xi_1 + 1) \left( \frac{m(\Phi_1 p \gamma + \Phi_2)}{\Gamma(y)} + \frac{m\Lambda}{\Gamma(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right) \\
+ \frac{mp_1^* \left( \left( \frac{b^\rho - a^\rho}{\rho} \right)^{1-\gamma} + p_2^* \|u\|_{PC_{\gamma \rho}} + p_3^* \|h\|_{PC_{\gamma \rho}} \right)}{1 - p_3^*}
\]
(88)

By (74), we have
\[
\|u\|_{PC_{\gamma \rho}} \leq \left[ (\xi_1 + 1) \left( \frac{m(\Phi_1 p \gamma + \Phi_2)}{\Gamma(y)} + \frac{m\Lambda}{\Gamma(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right) \\
+ \frac{mp_1^* \left( \left( \frac{b^\rho - a^\rho}{\rho} \right)^{1-\gamma} + p_2^* \|u\|_{PC_{\gamma \rho}} + p_3^* \|h\|_{PC_{\gamma \rho}} \right)}{1 - p_3^*} \right] \|u\|_{PC_{\gamma \rho}} \\
+ \frac{\xi_1}{\Gamma(1 + \alpha)} \left( \frac{m\Phi_1}{\Gamma(y)} + \frac{mp_1^* \left( b^\rho - a^\rho \right)^{1-\gamma}}{1 - p_3^*} \right) \|u\|_{PC_{\gamma \rho}} \\
+ \frac{\xi_1}{\Gamma(y + \alpha)} \left( \frac{mp_2^* \left( b^\rho - a^\rho \right)^{1-\gamma}}{1 - p_3^*} \right) \|u\|_{PC_{\gamma \rho}} \\
+ \frac{\xi_1}{\Gamma(1 + \alpha)} \left( \frac{mp_3^* \left( b^\rho - a^\rho \right)^{1-\gamma}}{1 - p_3^*} \right) \|h\|_{PC_{\gamma \rho}} \\
+ \frac{\xi_1}{\Gamma(y + \alpha)} \left( \frac{mp_2^* \left( b^\rho - a^\rho \right)^{1-\gamma}}{1 - p_3^*} \right) \|h\|_{PC_{\gamma \rho}} - R.
\]
(89)
As a consequence of Theorem 15 and using Step 2, we deduce that $\Psi$ has a fixed point which is a solution of problems (2)–(4).

Our third result is based on Krasnoselskii’s fixed-point theorem.

**Theorem 24.** Assume (H1), (H4), and (H5) hold. If

\[
(\|\xi\| + 1) \left( \frac{m\Phi_1 p^*}{\Gamma(\gamma)} + \frac{m p^*_2 (b^\rho - a^\rho)^a}{(1 - p^*_2)\Gamma(1 + \alpha)\rho^a} \right) + \frac{p^*_2 |\xi| (b^\rho - a^\rho)^a}{(1 - p^*_2)\Gamma(1 + \alpha)\rho^a} < 1,
\]

then problems ((2))–((4)) have at least one solution in $PC_{\gamma^*}(f) \subset PC_{\gamma^*}(f)$.

**Proof.** Consider the set

\[
B_\eta = \left\{ u \in PC_{\gamma^*}(f): \|u\|_{PC_{\gamma^*}} \leq \eta \right\}, \tag{91}
\]

where

\[
\eta \geq (|\xi| + 1) \left( (m\Phi_2/\Gamma(\gamma)) + (m\Phi_2/\Gamma(1 + \alpha))(b^\rho - a^\rho)^a + \Lambda(|\xi|/\Gamma(1 + \alpha)) + (\Gamma(y)/\Gamma(y + \alpha))(b^\rho - a^\rho)^a |\xi|/\Gamma(y) \right) \frac{1}{1 - (|\xi| + 1)(m\Phi_1 p^*/\Gamma(\gamma))}. \tag{92}
\]

We define the operators $Q_1$ and $Q_2$ on $B_\eta$ by

\[
Q_1 u(t) = \frac{1}{\Gamma(\gamma)} \left( \frac{t^\gamma - t^\gamma_k}{\rho} \right)^{-1} \left[ \xi_2 - \xi_2 \sum_{i=1}^{m} L_i(u(t_i)) - \xi_1 \sum_{i=1}^{m} \left( r \int_{(t_{i-1})}^{t_{i}} \xi \int_{(t_{i-1})}^{(t_{i+1})} h \right)(b) - \sum_{a \in A} \sum_{j=1}^{m} L_k(u(t_k)) + \frac{m}{\Gamma(1 + \alpha)} \left( b^\rho - a^\rho \right)^a |\xi|/\Gamma(y) \right], \tag{93}
\]

\[
Q_2 u(t) = \rho \int_{t_k}^{t} h(t), \tag{94}
\]

where $k = 0, \cdots, m$, and $h: (a, b) \to \mathbb{R}$ be a function satisfying the functional equation

\[
h(t) = f(t, u(t), h(t)). \tag{95}
\]

Then, the fractional integral equation (53) can be written as operator equation

\[
\Psi u(t) = Q_1 u(t) + Q_2 u(t), \quad u \in PC_{\gamma^*}(f). \tag{96}
\]

The proof will be given in several steps.

**Step 1.** We prove that $Q_1 u + Q_2 u \in B_\eta$, for any $u, z \in B_\eta$.

By (H4), (H5), and Lemma 6, for each $t \in (a, b)$, we have

\[
\|Q_1 u + Q_2 u\|_{PC_{\gamma^*}} \leq \|Q_1 u\|_{PC_{\gamma^*}} + \|Q_2 u\|_{PC_{\gamma^*}} \leq (|\xi| + 1) \left( \frac{m\Phi_2}{\Gamma(\gamma)} + \frac{m\Phi_2}{\Gamma(1 + \alpha)} \left( b^\rho - a^\rho \right)^a \right) + \Lambda \left( \frac{|\xi|}{\Gamma(1 + \alpha)} + \frac{1}{\Gamma(y + \alpha)} \right) \frac{b^\rho - a^\rho}{\rho} \frac{|\xi|}{\Gamma(y)}. \tag{97}
\]

Since

\[
\eta \geq (|\xi| + 1) \left( (m\Phi_2/\Gamma(\gamma)) + (m\Phi_2/\Gamma(1 + \alpha))(b^\rho - a^\rho)^a + \Lambda(|\xi|/\Gamma(1 + \alpha)) + (\Gamma(y)/\Gamma(y + \alpha))(b^\rho - a^\rho)^a + (|\xi|/\Gamma(y)) \right) \frac{1}{1 - (|\xi| + 1)(m\Phi_1 p^*/\Gamma(\gamma))}, \tag{98}
\]
we have
\[ \|Q_1y + Q_2z\|_{\mathcal{P}C_{\gamma,\rho}} \leq \eta, \quad (99) \]
which infers that \( Q_1u + Q_2w \in B_\eta \).

Step 2. \( Q_1 \) is a contraction.

Let \( u, w \in \mathcal{P}C_{\gamma,\rho}(J) \) and \( t \in (a, b] \).

By (H4), we have
\[
|h(t) - g(t)| = |f(t, u(t), h(t)) - f(t, w(t), g(t))| \\
\leq p_2(t) |u(t) - w(t)| + p_3(t) |h(t) - g(t)|.
\]

Then,
\[
|h(t) - g(t)| \leq \frac{p_2(t)}{1 - p_3(t)} |u(t) - w(t)| \leq \frac{p_2(t)}{1 - p_3(t)} |u(t) - w(t)|,
\]
where \( p_1^* = \sup_{t \in J} p_1(t), \ p_2^* = \sup_{t \in J} p_2(t), \) and \( h, g \in C_{\gamma,\rho}(J) \) such that
\[
h(t) = f(t, u(t), h(t)),
\]
\[
g(t) = f(t, w(t), g(t)).
\]

Then, by (H5), we have
\[
|Q_1y(t) - Q_2z(t)| \\
\leq \frac{1}{I(\gamma)} \left( \frac{t^\rho - t_1^\rho}{\rho} \right)^{\gamma - 1} \|u - w\|_{\mathcal{P}C_{\gamma,\rho}} \\
\times \left[ \frac{m\Phi p^*}{I(\gamma)} + \frac{m\Phi p^*}{(1 - p^* )I(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \\
+ \frac{mp_2^* |\xi|_1 I(\gamma)}{(1 - p^* )I(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right].
\]

Hence,
\[
\|Q_1u - Q_1w\|_{\mathcal{P}C_{\gamma,\rho}} \\
\leq \left[ (|\xi|_1 + 1) \left( \frac{m\Phi p^*}{I(\gamma)} + \frac{mp_2^* |\xi|_1}{(1 - p^* )I(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right) \\
+ \frac{p_2^* |\xi|_1}{(1 - p^* )I(1 + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha \right] \|u - w\|_{\mathcal{P}C_{\gamma,\rho}}.
\]

By (90), the operator \( Q_1 \) is a contraction.

Step 3. \( Q_2 \) is continuous and compact.

The continuity of \( Q_2 \) follows from the continuity of \( f \).

Next, we prove that \( Q_2 \) is uniformly bounded on \( B_\eta \).

Let \( u \in \mathcal{P}C_{\gamma,\rho}(J) \).

By Lemma 6, we have
\[
\|Q_2u\|_{\mathcal{P}C_{\gamma,\rho}} \leq \frac{\Lambda I(\gamma)}{I(\gamma + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha.
\]

This means that \( Q_2 \) is uniformly bounded on \( B_\eta \). Next, we show that \( Q_2B_\eta \) is equicontinuous. Let any \( w \in B_\eta \) and \( a < \epsilon_1 < \epsilon_2 < b \). Then,
\[
\left| \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right|^{1 - \gamma} \left( Q_2z(\epsilon_1) - \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right)^{1 - \gamma} \left( Q_2z(\epsilon_2) - \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right)^{1 - \gamma} \\
\leq \frac{\Lambda I(\gamma)}{I(\gamma + \alpha)} \left( \frac{b^\rho - a^\rho}{\rho} \right)^\alpha.
\]

Note that
\[
\left| \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right|^{1 - \gamma} \left( Q_2z(\epsilon_1) - \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right)^{1 - \gamma} \left( Q_2z(\epsilon_2) - \frac{\epsilon_1^\rho - \epsilon_2^\rho}{\rho} \right)^{1 - \gamma} \rightarrow 0 \text{ as } \epsilon_1 \rightarrow \epsilon_2.
\]

This shows that \( Q_2B_\eta \) is equicontinuous. Therefore, \( Q_2B_\eta \) is relatively compact. By \( \mathcal{P}C_{\gamma,\rho} \)-type Arzela-Ascoli theorem, \( Q_2 \) is compact. As a consequence of Theorem 16, we deduce that \( \Psi \) has at least a fixed point \( u^* \in \mathcal{P}C_{\gamma,\rho}(J) \) and by the same way of the proof of Theorem 22, we can easily show that \( u^* \in P C_{\gamma,\rho}(J) \). Using Lemma 21, we conclude that problems (2)–(4) have at least one solution in the space \( \mathcal{P}C_{\gamma,\rho}(J) \).

4. Ulam-Hyers-Rassias Stability

Now, we are concerned with the Ulam-Hyers-Rassias stability of our problems (2)–(4).

Theorem 25. Assume that in addition to (H1)–(H3) and (61), the following hypothesis holds:
(H6). There exist a nondecreasing function \( \theta \in PC_{\gamma \varphi}(J) \) and \( \lambda_0, \tilde{\lambda}_0 > 0 \) such that for each \( t \in (a, b] \), we have

\[
(\rho \mathcal{F}_{\alpha}^a \theta)(t) \leq \lambda_0 \theta(t) \tag{110}
\]

and

\[
(\rho \mathcal{F}_{\alpha}^{1-\gamma} \theta)(t) \leq \tilde{\lambda}_0 \theta(t) \tag{111}
\]

Then, Equation (2) is U-H-R stable with respect to \((\theta, \tau)\).

**Proof.** Consider the operator \( \Psi \) defined in (53). Let \( u \in P \quad \text{C}_{\gamma \varphi}(J) \) be a solution of inequality (27), and let us assume that \( w \) is the unique solution of the problem

\[
\begin{align*}
\left( \rho D_{\alpha}^{\alpha \beta} \psi \right)(t) &= f(t, w(t), \left( \rho D_{\alpha}^{\alpha \beta} \psi \right)(t)) ; t \in J_k, k = 0, \ldots, m, \\
\left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+) &= \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^-) + L_k(w(t_k^-)), k = 1, \ldots, m, \\
c_1 \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(a^+) + c_2 \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(b) &= c_3, \\
\left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(a^+) &= \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(a^+).
\end{align*}
\]

By Lemma 21, we obtain for each \( t \in (a, b] \)

\[
u(t) = \frac{1}{\Gamma(\gamma)} \left( t^\gamma - t_k^\gamma \right)^{-1} \left[ \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(a^+) + \sum_{a < t < c} L_k(w(t)) \right] + \sum_{a < t < c} \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+), t \in J_k, k = 0, \ldots, m, \tag{112}
\]

where \( h : (a, b] \rightarrow \mathbb{R} \) is a function satisfying the functional equation

\[
h(t) = f(t, w(t), h(t)). \tag{114}
\]

Since \( u \) is a solution of inequality (27), by Remark 2.18, we have

\[
\begin{align*}
\left( \rho D_{\alpha}^{\alpha \beta} \psi \right)(t) &= f(t, u(t), \left( \rho D_{\alpha}^{\alpha \beta} \psi \right)(t)) + \sigma(t), t \in J_k, k = 0, \ldots, m, \\
\left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+) &= \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^-) + L_k(u(t_k^-)) + \sigma_k, k = 1, \ldots, m.
\end{align*}
\]

Clearly, the solution of (115) is given by

\[
u(t) = \frac{1}{\Gamma(\gamma)} \left( t^\gamma - t_k^\gamma \right)^{-1} \left[ \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(a^+) + \sum_{a < t < c} L_k(u(t_k^-)) \right] + \sum_{a < t < c} \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+), t \in J_k, k = 0, \ldots, m, \tag{116}
\]

where \( g : (a, b] \rightarrow \mathbb{R} \) is a function satisfying the functional equation

\[
g(t) = f(t, u(t), g(t)). \tag{117}
\]

Hence, for each \( t \in (a, b] \), we have

\[
\begin{align*}
|u(t) - w(t)| &\leq \frac{1}{\Gamma(\gamma)} \left( t^\gamma - t_k^\gamma \right)^{-1} \left[ \sum_{a < t < c} L_k(u(t_k^-)) - L_k(w(t_k^-)) \right] \\
&+ \sum_{a < t < c} \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+), t \in J_k, k = 0, \ldots, m, \tag{119}
\end{align*}
\]

Thus,

\[
||u - w||_{PC_{\gamma \varphi}} \leq \frac{1}{\Gamma(\gamma)} \left[ \sum_{a < t < c} L_k(u(t_k^-)) - L_k(w(t_k^-)) \right] \\
+ \sum_{a < t < c} \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+), t \in J_k, k = 0, \ldots, m, \tag{120}
\]

By (H2) and Lemma 6, for \( t \in (a, b] \), we have

\[
||u - w||_{PC_{\gamma \varphi}} \leq \frac{1}{\Gamma(\gamma)} \left[ \sum_{a < t < c} L_k(u(t_k^-)) - L_k(w(t_k^-)) \right] \\
+ \sum_{a < t < c} \left( \rho \mathcal{F}_{\alpha}^{1-\gamma} \psi \right)(t_k^+), t \in J_k, k = 0, \ldots, m, \tag{120}
\]
Thus,
\[
\|u - w\|_{PC_{\gamma'}} \leq \frac{1}{\Gamma(\gamma)} \left( m\epsilon + (m\lambda_\gamma + 1) \epsilon \lambda_\gamma \delta(t) \right) + \left[ \frac{ml^* p^*}{\Gamma(\gamma)} + K \left( \frac{m}{\Gamma(1 + \alpha)} + \frac{\Gamma(\gamma)}{\Gamma(\lambda + \alpha)} \right) \right] \frac{(\rho^\alpha - \alpha^\alpha)^{\alpha^\alpha}}{\rho} .
\]

Then, by (61), we have
\[
\|u - w\|_{PC_{\gamma'}} \leq a_\theta \epsilon (\theta + \delta(t)),
\]
where
\[
a_\theta = \frac{1}{\Gamma(\gamma)} \left( m + (m\lambda_\gamma + 1) \lambda_\gamma \right) \left[ 1 - \frac{ml^* p^*}{\Gamma(\gamma)} + K \left( \frac{m}{\Gamma(1 + \alpha)} + \frac{\Gamma(\gamma)}{\Gamma(\lambda + \alpha)} \right) \right] \frac{(\rho^\alpha - \alpha^\alpha)^{\alpha^\alpha}}{\rho} .
\]

Hence, Equation (2) is U-H-R stable with respect to (\theta, \tau).

5. Examples

Example 1. Consider the following impulsive BVP of generalized Hilfer fractional differential equation
\[
\left( 1^{1/2} D_{t_c}^{1/2,0} u \right) (t) = \frac{1}{97e^{1/2}} \left( 1 + |u(t)| + \left| 1^{1/2} D_{t_c}^{1/2,0} u(t) \right| \right) + \frac{\ln \left( \epsilon + \sqrt{t} \right)}{\epsilon^2 \sqrt{t - 1}}, \text{ for each } t \in J_0 \cup J_1,
\]
\[
\begin{align*}
\left( 1^{1/2} \mathcal{J}_{t_c}^{1/2,0} (e^x) \right) (e^x) &- \left( 1^{1/2} \mathcal{J}_{t_c}^{1/2,0} u \right) (e^x) = \left| \frac{u(e^x)}{3 + |u(e^x)|} \right|, \\
3^{1/2} \mathcal{J}_{t_c}^{1/2,0} u \left( 1^+ \right) - 2 \left( 1^{1/2} \mathcal{J}_{t_c}^{1/2,0} u \right) (3) &\equiv 0,
\end{align*}
\]
where \( J_0 = (1, e], J_1 = (e, 3], t_0 = 1, \) and \( t_1 = e. \)

Set
\[
f(t, u, w) = \frac{1}{97e^{1/2}} \left( 1 + |u(t)| + |w(t)| \right) + \frac{\ln \left( \epsilon + \sqrt{t} \right)}{\epsilon^2 \sqrt{t - 1}}, \text{ for each } t \in (1, 3], u, w \in \mathbb{R}.
\]

We have
\[
PC_{\gamma'}^{q}((1, 3]) = PC_{\gamma'}^{q} \left( (1, 3] \right) = \left\{ g : (1, 3] \to \mathbb{R} : \sqrt{2} \left( \sqrt{t - t_c} \right)^{1/2} g \in PC((1, 3]) \right\}.
\]

with \( \gamma = \alpha = 1/2, \rho = 1/2, \beta = 0, \) and \( k \in \{0, 1\}. \) Clearly, the continuous function \( f \in PC_{\gamma'}^{q}((1, 3]). \)

Hence, the condition (H1) is satisfied.

For each \( u, \dot{u}, \ddot{u}, \epsilon \in \mathbb{R} \text{ and } t \in (1, 3], \)
\[
|f(t, u, \dot{u}, \ddot{u}) - f(t, \dot{u}, \ddot{u})| \leq \frac{1}{97e^{1/2}} \left( |u(t)| + |w(t)| \right) \leq \frac{1}{97e^{1/2}} \left( |u(t)| + |w(t)| \right).
\]

Hence, condition (H2) is satisfied with \( K = 1/97e^{1/2}. \)
And let
\[
L_1(u) = \frac{u}{3 + u}, u \in [0, \infty).
\]

Let \( u, w \in [0, \infty). \) Then, we have
\[
|L_1(u) - L_1(w)| = \left| \frac{u}{3 + u} - \frac{w}{3 + w} \right| = \frac{3|u - w|}{(3 + u)(3 + w)} \leq \frac{1}{3} |u - w|,
\]
and so the condition (H3) is satisfied and \( l^* = 1/3. \)

A simple computation shows that condition (61) of Theorem 22 is satisfied, for
\[
L = \frac{1}{2\pi} \left( 2 \frac{2}{\Gamma(3/2)} + \frac{\sqrt{2} (\sqrt{3} - 1)^{1/2}}{(97e^{1/2} - 1)\Gamma(3/2)} + \frac{\sqrt{2} (\sqrt{3} - 1)^{1/2}}{(97e^{1/2} - 1)} \right) - 0.52720987569 < 1.
\]

Then, problems (124)–(126) have a unique solution in \( PC_{\gamma'}^{q}((1, 3]) \subset PC_{\gamma'}^{q}((1, 3]). \)

Also, hypothesis (H6) is satisfied with \( \delta(t) = \epsilon^5, \tau = 1, \) and \( \lambda_\theta = \lambda_\gamma = 2/(\Gamma(3/2)). \) Indeed, for each \( t \in J_0 \cup J_1, \) we get
\[
\left( \mathcal{J}_{t_c}^{1/2,0} \theta \right) (t) \leq \frac{2\epsilon^5}{\Gamma(3/2)} \lambda_\theta \delta(t) = \lambda_\theta \delta(t).
\]

Consequently, Theorem 25 implies that Equation (124) is U-H-R stable.

Example 2. Consider the following impulsive initial value problem of generalized Hilfer fractional differential equation:
\[
\left( 1^{1/2} D_{t_c}^{1/2,0} u \right) (t) = \frac{3 + |u(t)| + \left| 1^{1/2} D_{t_c}^{1/2,0} u(t) \right|}{53e^{-t^4} \left( 1 + |u(t)| + \left| 1^{1/2} D_{t_c}^{1/2,0} u(t) \right| \right)} , \text{ for each } t \in J_0 \cup J_1,
\]
\[
\begin{align*}
\end{align*}
\]
We have
\[
PC^{0(1-a)}_{\gamma,p}([1, 3]) = PC^{0(1-a)}_{\gamma,p}([1, 3])
\]
\[= \{ g : (1, 3) \to \mathbb{R} : (\sqrt{t-t_0}) g \in PC([1, 3]) \}, \]
with \( \gamma = \alpha = 1/2, \rho = 1, \beta = 0, \) and \( k \in \{ 0, 1 \} \). Clearly, the continuous function \( f \in PC^{0(1-a)}_{\gamma,p}([1, 3]) \).

Hence, condition (H4) is satisfied with \( p_1(t) = 3/53e^{-t/4}, p_2(t) = p_3(t) = 3/53e^{-t/4}, p_1^* = 3/53e, \) and \( p_2^* = p_3^* = 1/53e. \)

And let
\[
L_1(u) = \frac{u}{2 + u}, u \in [0, \infty). \tag{140}
\]

Let \( u \in [0, \infty) \). Then, we have
\[
|L_1(u)| \leq \frac{1}{2} |u| + 2, \tag{141}
\]
and so the condition (H5) is satisfied with \( \Phi_1 = 1/2 \) and \( \Phi_2 = 2. \)

The condition (74) of Theorem 23 is satisfied, for
\[
((\xi_1) + 1) \left( \frac{m \Phi_1 p^*}{G(\gamma)} + \frac{mp^*_1(b\rho - d\rho)^{\alpha}}{(1 - p_1^*)G(1 + \alpha)p^*} \right)
\]
\[+ \left( \frac{|\xi_1|}{G(1 + \alpha)} + \frac{\alpha}{G(\gamma + \alpha)} \right) p_2^* \frac{(b\rho - d\rho)^{\alpha}}{(1 - p_1^*)p^*} \]
\[= \left( \frac{1}{2} \sqrt{\frac{2}{\pi}} + \frac{\sqrt{2}}{53e - 1} \right) + \frac{\sqrt{2}}{53e - 1}
\]
\[= 0.22814541069 \leq 1. \tag{142}
\]

Then, problems ((134))–((136)) have at least one solution in \( PC^{0(1-a)}_{\gamma,p}([1, 3]) \). Also, hypothesis (H6) is satisfied with \( \theta(t) = t - 1, \tau = 1, \) and \( \lambda_0 = \lambda_0 = \sqrt{2/53} \). Indeed, for each \( t \in J_0 \cup J_1 \), we get
\[
(|^0G^{1/2}_{t_0}u|^1) (t) \leq \sqrt{2/53} (t - 1) = \lambda \theta(t) = \lambda \theta(t). \tag{143}
\]

Consequently, by a simple change of the constants \( I^*, K, \) and \( M \) from (H1) and (H2) to \( \Phi_1, p_1^*, \) and \( p_2^* \) from (H4) and (H5), Theorem 25 implies that Equation (134) is G.U.-H.-R.

\textbf{Example 3.} Consider the following impulsive antiperiodic boundary value problem of generalized Hilfer Fractional differential equation:
\[
\left( \frac{D^{1/2}_{t_k} u} \right) (t) = \frac{e^t + |u(t)| + |1D^{1/2}_{t_k} u(t)|}{\sqrt{77e^{-t/4}} (1 + |u(t)| + |1D^{1/2}_{t_k} u(t)|)}, \quad \text{for each } t \in J_k, k = 0, \ldots, 4, \tag{144}
\]
\[\left( \frac{^0G^{1/2}_{t_{k+1}} u} \right) (t_k^+) - \left( \frac{D^{1/2}_{t_k} u} \right) (t_k^-) = \frac{|u(t_k^+)|}{10k + |u(t_k^-)|}, \quad k = 1, \ldots, 4, \tag{145}
\]
\[
\left( \frac{^0G^{1/2}_{t_0} u} \right) (1) = \left( \frac{D^{1/2}_{t_0} u} \right) (2), \tag{146}
\]
where \( J_k = (t_k, t_{k+1}], \quad t_k = 1 + (k/5), \quad \text{for } k = 0, \ldots, 4, \quad m = 4, \quad a = t_0 = 1, \quad \text{and } b = t_5 = 2. \)

Set
\[
f(t, u, w) = \frac{e^t + |u| + |w|}{\sqrt{77e^{-t/4}} (1 + |u| + |w|)}, \quad t \in (1, 2], u, w \in \mathbb{R}. \tag{147}
\]

We have
\[
PC^{0(1-a)}_{\gamma,p}([1, 2]) = PC^{a}_{1/2,1}([1, 2])
\]
\[= \{ g : (1, 2) \to \mathbb{R} : (\sqrt{t-t_0}) g \in C([1, 2]) \}, \tag{148}
\]
with \( \gamma = \alpha = 1/2, \rho = 1, \beta = 0, \) and \( k = 0, \ldots, 4. \) Clearly, the continuous function \( f \in PC^{a}_{1/2,1}([1, 2]) \).

Hence, the condition (H1) is satisfied. For each \( u, w \in \mathbb{R} \) and \( t \in (1, 2], \)
\[
|f(t, u, w)| \leq \frac{1}{\sqrt{77e^{-t/4}}} \left( e^t + |u| + |w| \right). \tag{149}
\]

Hence, condition (H4) is satisfied with \( p_1(t) = e^t/77e^{-t/4}, \)
\[p_2(t) = p_3(t) = 1/77e^{-t/4}, \quad p_1^* = e^t/77, \quad \text{and } p_2^* = p_3^* = 1/77. \]
And let
\[ L_k(u) = \frac{u}{10^k + u}, \quad k = 1, \ldots, 4, \quad u \in [0, \infty). \] (150)

Let \( u \in (0, \infty) \). Then, we have
\[ L_k(u) = \frac{1}{10} |u| + 1, \quad k = 1, \ldots, 4, \] (151)
and so the condition (H5) is satisfied with \( \Phi_1 = 1/10 \) and \( \Phi_2 = 1 \).

The condition (90) of Theorem 24 is satisfied, for
\[
\left( |\xi_1 | + 1 \right) \left( \frac{m\Phi_1 \rho^a}{\Gamma(\gamma)} + \frac{mp^s_2 (b^p - a^p)^a}{(1-p_1^s) \Gamma(1+\alpha)\rho^a} \right)
+ \frac{p^s_2 |\xi_1| (b^p - a^p)^a}{(1-p_1^s) \Gamma(1+\alpha)\rho^a} = \frac{3\sqrt{5}}{5\sqrt{\pi}} + \frac{125}{1463 \Gamma(3/2)} < 1.
\] (152)

Then, problems ((144))–((146)) have at least one solution in \( PC_{1/2,1}([1, 2]) \). Also, hypothesis (H6) is satisfied with \( \theta(t) = (1 - t)^3 \), \( \tau = 1 \), and \( \lambda = \lambda = \Gamma(3)/\Gamma(7/2) \). Indeed, for each \( t \in J_k \), \( k = 0, \ldots, 4 \), we get
\[
(\rho J^{1/2} \theta) (t) \leq \frac{\Gamma(3)}{\Gamma(7/2)} (t - 1)^2 = \lambda \theta(t) = \lambda \theta(t).
\] (153)

The same as Example 2, Theorem 25 implies that Equation (144) is U-H-R stable.

6. Conclusion

In this paper, we are concerned with existence, uniqueness, and Ulam-Hyers-Rassias stability results for a class of boundary value problem for nonlinear implicit fractional differential equations with impulses and generalized Hilfer fractional derivative. We gave three results using the Banach contraction principle and Krasnoselskii’s and Schaefer’s fixed-point theorems. Two illustrative examples about the uniqueness and the stability were presented. An interesting extension of our research would be to address Ulam-Hyers-Mittag-Leffler stability for a class and coupled system of implicit fractional differential equations. This subject will be discussed in the forthcoming paper.

Data Availability

There is no data used during this research.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

References
