

Corrigendum

Corrigendum to “Cartesian Control of Sit-to-Stand Motion Using Head Position Feedback”

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In the article titled “Cartesian Control of Sit-to-Stand Motion Using Head Position Feedback” [1], similarity with the methodology used and an amount of text overlap has been identified with the authors’ previously published article:

Rafique S, Najam-ul-Islam M, Shafique M, Mahmood A. Neuro-fuzzy control of sit-to-stand motion using head position tracking. *Measurement and Control*. 2020;53(7-8):1342–1353. doi:10.1177/0020294020938079 [2].

The authors apologise for not making this clear in the article and wish to acknowledge this related study.

References

- [1] S. Rafique, M. Najam-ul-Islam, M. Shafique, and A. Mahmood, “Cartesian Control of Sit-to-Stand Motion Using Head Position Feedback,” *Applied Bionics and Biomechanics*, vol. 2020, Article ID 1979342, 13 pages, 2020.
- [2] S. Rafique, M. Najam-ul-Islam, M. Shafique, and A. Mahmood, “Neuro-fuzzy control of sit-to-stand motion using head position tracking,” *Measurement and Control*, vol. 53, no. 7-8, pp. 1342–1353, 2020.