

Research Article

Homotopy Analysis Solution for Magnetohydrodynamic Squeezing Flow in Porous Medium

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The aim of the present work is to analyze the magnetohydrodynamic (MHD) squeezing flow through porous medium using homotopy analysis method (HAM). Fourth-order boundary value problem is modeled through stream function $\psi(r, z)$ and transformation $\psi(r, z) = r^2 f(z)$. Absolute residuals are used to check the efficiency and consistency of HAM. Other analytical techniques are compared with the present work. It is shown that results of good agreement can be obtained by choosing a suitable value of convergence control parameter h in the valid region R_h . The influence of different parameters on the flow is argued theoretically as well as graphically.

1. Introduction

The squeezing movement normal to two plates is observed in many hydromechanical devices such as motors, engines, and hydraulic lifters, where compression/injection processes using pistons and clutches are found. Due to the utility of these devices, significant research effort is being made for their improvement. Other industrial applications include polymer processing, while medical applications include the modeling of synthetic transportation inside living bodies. As such, the study of squeezing effect, in addition to other properties such as magnetohydrodynamics (MHD) and porosity, has become one of the most active topics in fluid mechanics. The study of porosity effects after introduction of the modified Darcy Law [1] specifically contributed to oil and gas production industry, detection of ground water pollution due to leakage of chemicals from tanks and oil pipelines, ground water hydrology, and recovery of crude oil from pores of reservoir rocks [2–5]. These contributions and others [6, 7] are generally found in reservoir, chemical, civil, environmental, agricultural, and biomedical engineering.

These studies are typically modeled using small parameters in nonlinear differential equations which are expressed as series expansions. The exact solution using perturbation

methods is therefore not always possible and this poses a considerable challenge to researchers. A recently developed analytic method known as homotopy analysis method (HAM) by Liao in 1992, however, has given promising results as it does not require modeling of the small parameter [8]. In fact, in quite contrast, HAM provides a way to accelerate the series solution conversion in the form of auxiliary parameter. The equations are reduced by HAM to a set of linear ordinary differential equations based on the homotopy of topology. These sets of equations can then be computed by mathematical software like Mathematica, Maple, MATLAB, Octave, SageMath, or Maxima. Applications are found in various problems of science and engineering such as expression of skin friction coefficient and reduced Nusselt and Sherwood numbers [9–12]. Analytical tools like homotopy perturbation method (HPM), δ -expansion method, and Adomian decomposition method (ADM) are special cases of HAM [13].

Mabood and Khan [14, 15] successfully applied homotopy analysis method for the study of heat transfer on MHD stagnation point flow in porous medium and boundary layer flow and heat transfer over a permeable flat plate in a Darcian porous medium. Analytic solutions for unsteady two-dimensional and axisymmetric flows were presented by Rashidi et al. [16]. The study of heat and mass transfer in the

context of squeezing flow was performed by Mustafa et al. [17]. Kirubhashankar and Ganesh [18] analyzed electrically conducting MHD viscous flows. A two-dimensional MHD problem was approximated using homotopy perturbation method (HPM) by Siddiqui et al. [19, 20]. Unsteady flow of viscous fluid between porous plates is studied by Ganesh and Krishnambal [21] and Mohamed Ismail et al. [22]. Shevianian et al. [23, 24] successfully used HAM to study singular linear vibrational BVPs and MHD squeezing flow between two parallel disks. The same authors [25, 26] used predictor homotopy analysis method (PHAM) to investigate nonlinear reactive transport model and nanoboundary layer flows with nonlinear Navier boundary condition.

This work is an effort to investigate MHD squeezing flow of Newtonian fluid between two parallel plates passing through porous medium by homotopy analysis method. Using similarity transforms, the governing partial differential equations are converted to equivalent nonlinear ordinary differential equation and then solved using the mentioned scheme. Velocity profile of fluid is argued by varying various parameters involved.

2. Mathematical Model

In two dimensions, if cylindrical coordinates of the velocity \mathbf{u} of moving plates are $[u_r, 0, u_z]$, ∇ is defined to be $(\partial/\partial r, (1/r)(\partial/\partial\theta), \partial/\partial z)$, $\omega = \nabla \times \mathbf{u}$, $\Omega(r, z) = \partial u_z/\partial r - \partial u_r/\partial z$, $v = u_r^2 + u_z^2$, and ρ , p , and κ denote the density, pressure, and permeability, respectively, then, from momentum equation of steady squeezing flow in porous medium with MHD effect, r , θ , and z components are as follows.

r component is as follows:

$$\frac{\partial}{\partial r}(\rho v + p) - \rho \Omega u_z = -\left(\mu \frac{\partial \Omega}{\partial z} + A u_r\right). \quad (1)$$

θ component is as follows:

$$\begin{aligned} \frac{1}{r} \frac{\partial p}{\partial \theta} &= 0 \implies \\ \frac{\partial p}{\partial \theta} &= 0 \implies \\ p &= f(r, z). \end{aligned} \quad (2)$$

z component is as follows:

$$\frac{\partial}{\partial r}(\rho v + p) + \rho \Omega u_r = \frac{\mu}{r} \frac{\partial}{\partial r}(r \Omega) - \frac{\mu}{\kappa} u_z. \quad (3)$$

Here, $A = \mu/\kappa + \sigma B_0^2$ with B_0 as imposed magnetic field. Introducing stream function [27] $\psi(r, z)$ defined by

$$\begin{aligned} u_r(r, z) &= \frac{1}{r} \frac{\partial \psi}{\partial z}, \\ u_z(r, z) &= -\frac{1}{r} \frac{\partial \psi}{\partial r}, \end{aligned} \quad (4)$$

it can be easily proved that the continuity equation $\nabla \cdot \mathbf{u} = 0$ is satisfied. With the help of (4) and eliminating $(\partial/\partial r)(\rho v + p)$, (1) and (3) reduce to single PDE as follows:

$$\begin{aligned} \rho \left[\frac{\partial \psi}{\partial r} \frac{\partial}{\partial z} \left(\frac{\eta^2 \psi}{r^2} \right) - \frac{\partial \psi}{\partial z} \frac{\partial}{\partial r} \left(\frac{\eta^2 \psi}{r^2} \right) \right] \\ = -\frac{\mu}{r} \eta^4 \psi + \frac{\mu}{\kappa} \eta^2 \psi + \frac{\eta B_0^2}{r} \frac{\partial^2 \psi}{\partial z^2}. \end{aligned} \quad (5)$$

Here, $\eta = \partial^2/\partial r^2 - (1/r)(\partial/\partial r) + \partial^2/\partial z^2$. If the moving plates are separated by distance $2d$, then

$$\begin{aligned} u_r &= 0, \\ u_z &= -v, \\ &\text{at } z = d, \\ u_z &= 0, \\ \frac{\partial u_r}{\partial z} &= 0, \\ &\text{at } z = 0. \end{aligned} \quad (6)$$

Using transformation $\psi(r, z) = r^2 f(z)$, (5) reduces to single ODE as follows:

$$\begin{aligned} \frac{d^4}{dz^4} f(z) + \frac{2\rho}{\mu} f(z) \frac{d^3}{dz^3} f(z) - \frac{1}{\kappa} \frac{d^2}{dz^2} f(z) \\ - \frac{\sigma B_0^2}{\mu} \frac{d^2}{dz^2} f(z) = 0. \end{aligned} \quad (7)$$

The boundary conditions in (6) are transformed to

$$\begin{aligned} \frac{d^2}{dz^2} f(0) = 0, \quad f(0) = 0, \\ \frac{d}{dz} f(d) = 0, \quad f(d) = -\frac{u}{2}. \end{aligned} \quad (8)$$

Using nondimensional parameters $(2/u)f^* = f$, $dz^* = z$, $(u/\mu)R_{mp} = \rho d$, $m_h = \sigma d B_0/\mu$, and $m_p = h/\kappa$ and omitting * sign, (7) and (8) become

$$\begin{aligned} \frac{d^4}{dz^4} f(z) + R_{mp} f(z) \frac{d^3}{dz^3} f(z) - m_p \frac{d^2}{dz^2} f(z) \\ - m_h \frac{d^2}{dz^2} f(z) = 0, \end{aligned} \quad (9)$$

$$\begin{aligned} \frac{d^2}{dz^2} f(0) = 0, \quad f(0) = 0, \\ \frac{d}{dz} f(1) = 0, \quad f(1) = 1, \end{aligned} \quad (10)$$

where R_{mp} is Reynold and m_h, m_p are Hartmann numbers.

3. Application of HAM to Squeezing Flow

HAM logically contains some analytic techniques such as Adomian's decomposition method, Lyapunov's artificial small parameter method, and δ -expansion method. Thus, this technique can be regarded as a unified or generalized theory of these analytical techniques. Unlike other analytic techniques, the homotopy analysis method provides a simple way to control and adjust the convergence region and rate of solution series of nonlinear problems. Thus, this method is valid for nonlinear problems with strong nonlinearity. Homotopy analysis method provides great freedom to use base functions to express solutions of a nonlinear problem so that one can approximate a nonlinear problem more efficiently by means of better base functions [13].

In the present section, this technique is applied on (9) using boundary conditions (10). For solution expression polynomial base function $\{z^{2n+1} \mid n = 0, 1, 2, 3, \dots\}$ is used to determine $f(z)$ as follows:

$$f(z) = \sum_{m=0}^{\infty} b_n z^{2n+1}, \quad (11)$$

where b_n are constants. By rule of solution expression and according to conditions in (10), the initial guess of the problem is

$$f_0(z) = \frac{3z - z^3}{2}. \quad (12)$$

The auxiliary linear operator is chosen as

$$L[f(z)] = \frac{d^4}{dz^4} f(z) \quad (13)$$

with the property

$$L\left(C_1 \frac{z^3}{6} + C_2 \frac{z^2}{2} + C_3 z + C_4\right) = 0. \quad (14)$$

Here, C_i ($i = 1, 2, 3, 4$) are integration constants whose obtained values are

$$\begin{aligned} C_2 &= C_4 = 0, \\ C_1 &= -3, \\ C_3 &= 1.5. \end{aligned} \quad (15)$$

By rule of solution expression in (2.51) and by (2.39) in [13], the auxiliary function $H(z)$ is chosen to be $H(z) = 1$.

3.1. Zeroth-Order Deformation Equation. Using the homotopy introduced in [13], zeroth-order deformation equation is given by

$$(1 - q) L[\phi(z; q) - f_0(z)] = qhH(z) N[\phi(z; q)], \quad (16)$$

where N is a nonlinear operator defined by

$$\begin{aligned} N[\phi(z; q)] &= \frac{d^4 \phi(z; q)}{dz^4} + R_{mp} \phi(z; q) \frac{d^3 \phi(z; q)}{dz^3} \\ &\quad - m_p \frac{d^2 \phi(z; q)}{dz^2} - m_h \frac{d^2 \phi(z; q)}{dz^2}. \end{aligned} \quad (17)$$

From here, the zeroth-order problem obtained is

$$(1 - q) L[\phi(z; q) - f_0(z)] = qhH(z) N[\phi(z; q)], \quad (18)$$

$$\begin{aligned} \frac{d^2 \phi(0; q)}{dz^2} &= 0, \quad \phi(0; q) = 0, \\ \frac{d\phi(1; q)}{dz} &= 0, \quad \phi(1; q) = 1. \end{aligned} \quad (19)$$

Here, q is an embedding parameter and h is a nonzero auxiliary parameter. It is observed that,

at $q = 0$,

$$\phi(0; q) = f_0(z); \quad (20)$$

at $q = 1$,

$$\phi(1; q) = f(z). \quad (21)$$

Hence, when q varies from 0 to 1, then $\phi(z; q)$ varies from $f_0(z)$ to $f(z)$. By Maclaurin's expansion, $\phi(z; q)$ can be expressed as

$$\phi(z; q) = f_0(z) + \sum_{n=1}^{\infty} f_n(z) q^n. \quad (22)$$

The value of the auxiliary parameter h is chosen in such a way that the series in (18) converges at $q = 1$; that is,

$$f(z) = f_0(z) + \sum_{n=1}^{\infty} f_n(z), \quad (23)$$

where $f_n(z) = (1/n!)(\partial^n f(z; q)/\partial z^n)|_{q=0}$.

3.2. nth-Order Deformation Equation. Differentiate (18) and (19) n -times with respect to q and put $q = 0$ to get n th-order deformation equation as follows:

$$L[f_n(z) - \chi_n f_{n-1}(z)] = hH(z) R_n(f_{n-1}), \quad (24)$$

$$\begin{aligned} \frac{d^2 f_n(0)}{dz^2} &= 0, \quad f_n(0) = 0, \\ \frac{df_n(1)}{dz} &= 0, \quad f_n(1) = 0. \end{aligned} \quad (25)$$

Equation (24) reduces to

$$f_n(z) = \chi_n f_{n-1}(z) + hL^{-1}[H(z) R_n(f_{n-1})], \quad (26)$$

TABLE 1: Absolute residuals keeping $m_h = m_p = 0.5$ and $R_{mp} = 1$.

z	Absolute residuals for different order HAM solutions				
	5th order	10th order	15th order	20th order	25th order
0.0	0	0	0	0	0
0.1	9.5367×10^{-9}	7.7605×10^{-14}	0	5.5511×10^{-17}	0
0.2	3.2067×10^{-8}	3.0953×10^{-13}	2.2210×10^{-16}	2.2210×10^{-16}	2.2210×10^{-16}
0.3	1.6171×10^{-7}	9.2082×10^{-13}	4.4410×10^{-16}	2.2210×10^{-16}	2.2210×10^{-16}
0.4	5.3675×10^{-7}	2.1336×10^{-12}	0	0	0
0.5	1.3172×10^{-6}	3.5714×10^{-12}	0	4.4410×10^{-16}	0
0.6	1.8889×10^{-6}	2.8302×10^{-12}	4.4410×10^{-16}	8.8820×10^{-16}	4.4410×10^{-16}
0.7	2.0711×10^{-7}	5.1026×10^{-12}	4.4410×10^{-16}	4.4410×10^{-16}	4.4410×10^{-16}
0.8	5.7686×10^{-6}	2.1931×10^{-11}	0	4.4410×10^{-16}	1.3323×10^{-15}
0.9	1.3705×10^{-5}	3.2338×10^{-11}	4.4410×10^{-16}	8.8820×10^{-16}	0
1.0	1.2902×10^{-5}	2.8715×10^{-12}	2.2205×10^{-15}	4.4410×10^{-16}	4.4410×10^{-16}

where

$$L^{-1} = C_1 \frac{x^3}{6} + C_2 \frac{x^2}{2} + C_3 x + C_4 + \iiint (\cdot) dz dz dz \tag{27}$$

$$R_n (f_{n-1}) = f_{n-1}^{iv} + R_{mp} \sum_{k=0}^{n-1} f_k f_{n-1-k}''' - (m_h + m_p) f_{n-1}'' \tag{28}$$

$$\chi_n = \begin{cases} 0, & n \leq 0 \\ 1, & n > 0. \end{cases} \tag{29}$$

4. Exact Solution in Case of Zero Reynold Number

In this section, a special case is studied when the Reynold number is zero and hence (9) becomes a linear differential equation. The exact solution obtained using boundary conditions in (10) is given by

$$f(z) = - \frac{e^{-\sqrt{M}z} \left(\sqrt{M}z \left(-e^{\sqrt{M}z} \right) - \sqrt{M}z e^{\sqrt{M}z+2\sqrt{M}} + e^{2\sqrt{M}z+\sqrt{M}} - e^{\sqrt{M}} \right)}{\sqrt{M}e^{2\sqrt{M}} + \sqrt{M} - e^{2\sqrt{M}} + 1} \tag{30}$$

Here, $M = m_h + m_p$. Homotopy analysis solution is also derived in this case. The operator N in (17) becomes

$$N [\phi(z; q)] = \frac{d^4 \phi(z; q)}{dz^4} - m_p \frac{d^2 \phi(z; q)}{dz^2} - m_h \frac{d^2 \phi(z; q)}{dz^2} \tag{31}$$

and for n th-order deformation equation R_n in (28) becomes

$$R_n (f_{n-1}) = f_{n-1}^{iv} - (m_h + m_p) f_{n-1}'' \tag{32}$$

In Table 4, comparison of exact solution with fifth- and tenth-order HAM solutions is made with the help of absolute error.

5. Convergence of HAM Solution

Solution obtained by homotopy analysis method in (23) contains auxiliary parameter h which adjusts and controls the convergence. There is great freedom to choose the auxiliary parameter. For influence of h on the solution, the convergence

of $f^{(n)}(0)$, where n is odd, is considered. The valid region R_h of h for which $f'(0)$ converges is shown for different order solutions in Figure 1. The curve $f'(0)$ versus h is said to be h -curve. From Figure 1, it is observed that R_h increases with the increase of approximation order. For fifth-order solution, the valid region for h is $-1.6 \leq h \leq -0.3$. It is obvious from Figure 2 that when m_h, m_p increase further, the valid region moves towards the right. Figures 3 and 4 are constructed to examine R_h for increasing m_h, m_p , and R_{mp} .

6. Results and Discussion

Analytic solution, using homotopy analysis method, of magnetohydrodynamics squeezing flow through porous medium is studied. Four figures (Figures 1–4) are constructed, for various values of Reynold and Hartmann numbers, to examine the valid region R_h which has a vital role in convergence of analytic solution. Table 1 shows different order absolute residuals for HAM solutions and it is clear to see that as the order of approximation increases further, the solution converges to exact solution. Fifth-order absolute residuals for various

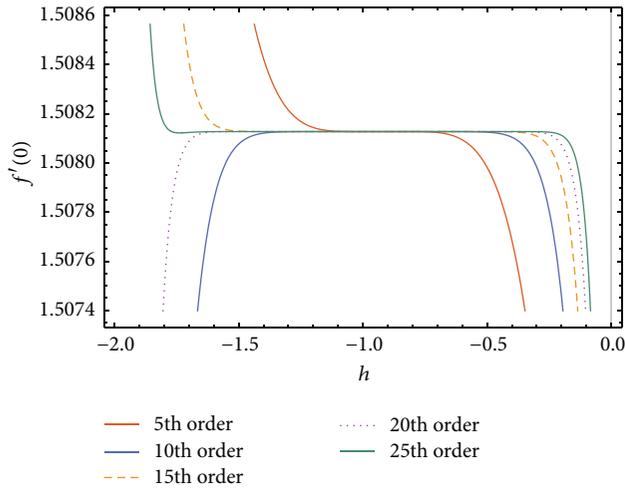


FIGURE 1: h -curve of different order solutions for $m_h = 0.3$, $m_p = 0.7$, and $R_{mp} = 1$.

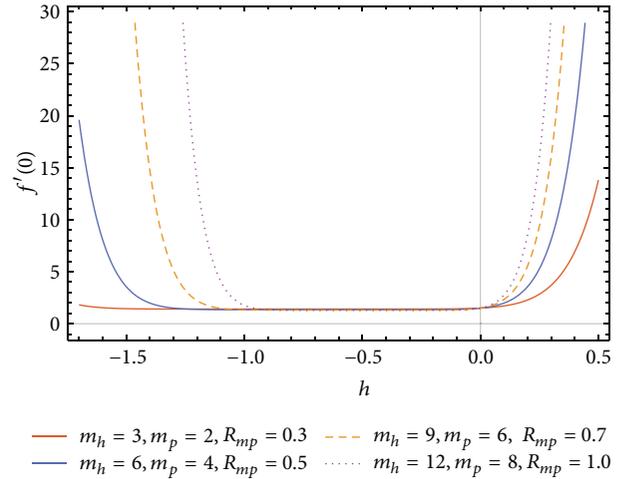


FIGURE 4: h -curve of tenth-order solution for various m_h , m_p , and R_{mp} .

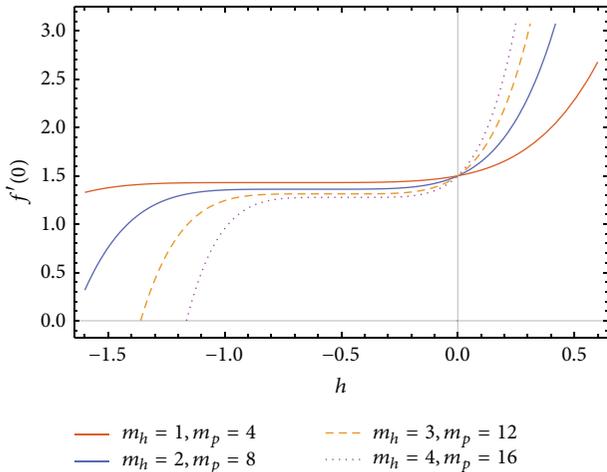


FIGURE 2: h -curve of fifth-order solution for various m_h and m_p and $R_{mp} = 1$.

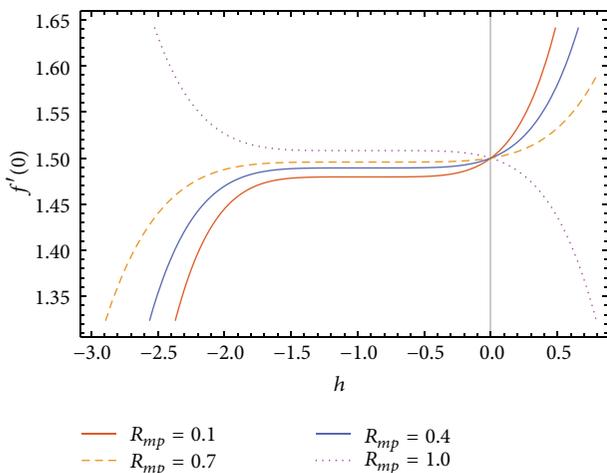


FIGURE 3: h -curve of fifth-order solution for various R_{mp} and $m_h = 0.6$ and $m_p = 0.4$.

values of R_{mp} and for fixed values of m_h , m_p are displayed in Table 2. Table 3 is constructed to display tenth-order absolute residuals for different values of m_h , m_p , and h while keeping Reynold number fixed. Exact solution is obtained in case of zero Reynold number when the differential equation in (9) becomes linear. Fifth- and tenth-order HAM solutions are compared with this exact solution in Table 4 using the concept of absolute error. Keeping h and Reynold and Hartmann numbers fixed, Table 5 displays different order HAM solutions. Table 6 shows important information about the consistency and efficiency of HAM by means of average absolute residuals for fifth-order approximation. Convergence of the present technique is given in Table 7 for different order approximations by means of $f'(0)$, $|f'''(0)|$, $f''(0)$, and $|f^{vii}(0)|$. As $f^n(0)$ becomes zero for even n , odd order derivatives are taken to study the convergence of the technique used. Comparison of different analytical techniques and one numerical Mathematica command NDSolve with the present work is displayed in Table 8 which shows that results obtained by HAM are in high agreement. One can refine these results by selecting suitable h in the valid region R_h . The rapid convergence of HAM can also be seen in Figure 5 which shows the residuals of various analytical schemes.

7. Conclusion

All tables (Tables 1–8) show the efficiency and consistency of the mentioned scheme. The valid region R_h can be more refined to choose such value of h for which the obtained solution converges rapidly which is the beauty of the present analytic technique. It is also observed that while increasing the value of Hartmann numbers (Figures 2 and 4), the valid region moves towards the right. Table 3 also tells the same story. The influences of different parameters on the velocity profile are displayed in Figures 6–9 and the following observations are made:

- (1) Velocity of fluid in porous medium and the Reynold number R_{mp} are inversely proportional to each other;

TABLE 2: Absolute residuals for different R_{mp} keeping m_h and m_p fixed.

z	Fifth-order absolute residuals				
	$R_{mp} = 0.1$	$R_{mp} = 0.3$	$R_{mp} = 0.5$	$R_{mp} = 0.7$	$R_{mp} = 0.9$
0.1	1.2301×10^{-10}	1.3902×10^{-9}	2.2210×10^{-9}	9.1597×10^{-11}	8.9372×10^{-9}
0.2	9.2250×10^{-10}	2.2645×10^{-9}	2.2210×10^{-9}	5.9589×10^{-10}	6.5040×10^{-9}
0.3	2.8005×10^{-9}	2.1661×10^{-9}	4.4410×10^{-10}	4.7810×10^{-10}	3.1478×10^{-8}
0.4	5.5909×10^{-9}	6.2185×10^{-10}	2.2210×10^{-9}	1.2061×10^{-9}	9.3540×10^{-8}
0.5	8.2828×10^{-9}	2.9842×10^{-9}	2.2210×10^{-8}	2.0999×10^{-9}	3.0340×10^{-7}
0.6	8.8277×10^{-9}	8.9656×10^{-9}	4.4410×10^{-8}	3.2913×10^{-9}	6.0391×10^{-7}
0.7	3.9394×10^{-9}	1.6855×10^{-8}	4.4410×10^{-8}	1.4133×10^{-8}	4.0297×10^{-7}
0.8	1.1760×10^{-8}	2.4190×10^{-8}	2.2210×10^{-10}	3.2937×10^{-8}	1.1930×10^{-7}
0.9	4.9318×10^{-8}	2.7364×10^{-8}	4.4410×10^{-9}	1.0928×10^{-8}	4.0659×10^{-7}
1.0	1.3750×10^{-7}	2.5064×10^{-8}	2.2205×10^{-8}	1.3853×10^{-7}	5.5660×10^{-6}

TABLE 3: Absolute residuals for different values of m_h , m_p and h keeping $R_{mp} = 1$.

z	Tenth-order absolute residuals				
	$m_h = 0.5$	$m_h = 2.5$	$m_h = 3.5$	$m_h = 4.5$	$m_h = 5.5$
	$m_p = 2.5$	$m_p = 3.5$	$m_p = 5.5$	$m_p = 7.5$	$m_p = 9.5$
	$h = -0.905$	$h = -0.81$	$h = -0.76$	$h = -0.702$	$h = -0.652$
0.1	1.7770×10^{-12}	5.2593×10^{-11}	2.0127×10^{-8}	3.2010×10^{-7}	1.7200×10^{-6}
0.2	2.2357×10^{-12}	2.7173×10^{-10}	3.7920×10^{-8}	6.4820×10^{-7}	3.9832×10^{-6}
0.3	6.6970×10^{-12}	6.7927×10^{-10}	5.0219×10^{-8}	8.4460×10^{-7}	5.8732×10^{-6}
0.4	1.2603×10^{-11}	1.0666×10^{-9}	5.3527×10^{-8}	5.7542×10^{-7}	4.2189×10^{-6}
0.5	2.1863×10^{-11}	1.0404×10^{-9}	4.8000×10^{-8}	4.9288×10^{-7}	5.2428×10^{-6}
0.6	3.3222×10^{-11}	2.0734×10^{-10}	4.8612×10^{-8}	2.0817×10^{-6}	2.2440×10^{-5}
0.7	3.7364×10^{-11}	1.7351×10^{-9}	1.1400×10^{-7}	2.0580×10^{-6}	2.9649×10^{-5}
0.8	2.6140×10^{-11}	5.6690×10^{-9}	4.1453×10^{-7}	6.0343×10^{-6}	3.7432×10^{-5}
0.9	3.5145×10^{-12}	1.6370×10^{-8}	1.4760×10^{-6}	3.9871×10^{-5}	3.6410×10^{-4}
1.0	2.8584×10^{-11}	5.7388×10^{-8}	5.2801×10^{-6}	1.5630×10^{-4}	1.5182×10^{-3}

TABLE 4: Absolute errors of fifth- and tenth-order HAM solutions when $R_{mp} = 0$.

z	Absolute errors when $R_{mp} = 0$		
	Exact solution	Fifth-order AE	Tenth-order AE
0.0	0	0	0
0.1	0.147171	$7.58785506649317 \times 10^{-10}$	0
0.2	0.291618	$1.39478356642186 \times 10^{-9}$	$3.33066907387546 \times 10^{-16}$
0.3	0.430586	$1.80948145356296 \times 10^{-9}$	$8.32667268468867 \times 10^{-16}$
0.4	0.561271	$1.94815263920844 \times 10^{-9}$	$7.77156117237609 \times 10^{-16}$
0.5	0.680780	$1.81075676675135 \times 10^{-9}$	$4.44089209850062 \times 10^{-16}$
0.6	0.786113	$1.45204859247627 \times 10^{-9}$	$2.22044604925031 \times 10^{-16}$
0.7	0.874125	$9.70818092582703 \times 10^{-10}$	$5.55111512312578 \times 10^{-16}$
0.8	0.941500	$4.90335771985428 \times 10^{-10}$	$7.77156117237609 \times 10^{-16}$
0.9	0.984713	$1.33847599670389 \times 10^{-10}$	$1.11022302462515 \times 10^{-16}$
1.0	1.000000	$2.22044604925031 \times 10^{-16}$	$2.22044604925030 \times 10^{-16}$

AE = |exact solution – HAM solution|.

- that is, increasing Reynold number (when density of fluid increases) results in the decrease in velocity of fluid while keeping Hartmann number fixed as shown in Figure 6.
- (2) Figure 7 shows that while increasing m_h (i.e., increasing the imposed magnetic effect) and keeping m_p , R_{mp} fixed, the velocity of fluid increases.

- (3) The same effect is studied in Figure 8 by increasing m_p (i.e., when the permeability decreases) and keeping m_h and R_{mp} fixed.
- (4) Increasing Hartmann and Reynold numbers together, it is observed from Figure 9 that the velocity of fluid increases. It is concluded that Hartmann number is more influential as compared to Reynold number.

TABLE 5: Different order solutions keeping $m_h = m_p = 0.5$, $R_{mp} = 1$, and $h = -0.97$.

z	Different order HAM solutions				
	1st order	3rd order	5th order	15th order	25th order
0.0	0	0	0	0	0
0.1	0.15034713893	0.15029407026	0.15029422756	0.15029422727	0.15029422694
0.2	0.29758357211	0.29748028081	0.29748058054	0.29748058002	0.29748057936
0.3	0.43861285278	0.43846608333	0.43846649504	0.43846649440	0.43846649341
0.4	0.57036617920	0.57018808886	0.57018856454	0.57018856394	0.57018856267
0.5	0.68981403459	0.68962312433	0.68962359743	0.68962359707	0.68962359568
0.6	0.79397520822	0.79379541675	0.79379580965	0.79379580971	0.79379580853
0.7	0.87992232433	0.87977913949	0.87977938815	0.87977938864	0.87977938832
0.8	0.94478300617	0.94469588175	0.94469597496	0.94469597563	0.94469597737
0.9	0.98573580197	0.98570687775	0.98570688141	0.98570688178	0.98570688792
1.0	0.99999999999	1.00000000000	1.00000000000	1.00000000000	1.0000001530

TABLE 6: Average absolute residuals for various values of m_h, m_p, R_{mp} , and h .

Fifth-order average absolute residuals					
m_h	m_p	R_{mp}	h	Solution	Residual
0.3	0.7	1.0	-0.972	0.6896235970708491	$3.385181024 \times 10^{-12}$
1.2	0.8	0.7	-0.685	0.5614010061254293	$5.195453594 \times 10^{-7}$
3.0	2.0	0.5	-0.773	0.8625404743084730	$1.845019426 \times 10^{-8}$
3.5	4.5	0.9	-0.851	0.6537531470383126	$9.278417177 \times 10^{-8}$
6.0	4.0	1.0	-0.597	0.7562438682896610	$5.552400535 \times 10^{-5}$
10.0	5.0	1.5	-0.656	0.7456786847598219	$1.257868035 \times 10^{-5}$
12.0	8.0	2.0	-0.590	0.6266880364547981	$2.172601809 \times 10^{-5}$
15.0	10.0	2.5	-0.520	0.7309895729856828	$4.155602273 \times 10^{-4}$

TABLE 7: Convergence of HAM for different order approximations.

Approximation order	$f'(0)$	$ f'''(0) $	$f^v(0)$	$ f^{(vii)}(0) $
1	0.00866	3.11432	1.45499	8.729999
3	0.00812	3.11177	1.58119	15.22983
5	0.00812	3.11178	1.58118	15.25585
7	0.00812	3.11178	1.58118	15.25593
10	0.00812	3.11178	1.58118	15.25593
15	0.00812	3.11178	1.58118	15.25593
20	0.00812	3.11178	1.58118	15.25593
25	0.00812	3.11178	1.58118	15.25595

TABLE 8: Comparison of HAM with numerical and other analytical techniques.

z	Absolute residuals for numerical and different analytical schemes					
	NDSolve	DTM	DJM	ADM	OHAM	HAM
0	3.47×10^{-3}	0	0	0	0	0
0.1	3.20×10^{-4}	2.36×10^{-13}	2.86×10^{-12}	3.20×10^{-5}	1.51×10^{-7}	0
0.2	2.02×10^{-4}	1.21×10^{-10}	3.56×10^{-10}	2.51×10^{-4}	2.72×10^{-7}	2.22×10^{-16}
0.3	4.57×10^{-5}	4.62×10^{-9}	5.81×10^{-9}	8.30×10^{-4}	3.31×10^{-7}	4.44×10^{-16}
0.4	5.67×10^{-5}	6.11×10^{-8}	4.09×10^{-8}	2.00×10^{-3}	3.05×10^{-7}	0
0.5	1.51×10^{-5}	4.51×10^{-7}	1.79×10^{-7}	3.51×10^{-3}	1.75×10^{-7}	0
0.6	3.45×10^{-5}	2.31×10^{-6}	5.78×10^{-7}	5.70×10^{-3}	6.62×10^{-8}	4.44×10^{-16}
0.7	5.07×10^{-7}	9.12×10^{-6}	1.50×10^{-6}	8.33×10^{-3}	4.05×10^{-7}	4.44×10^{-16}
0.8	4.56×10^{-5}	3.00×10^{-5}	3.25×10^{-6}	1.12×10^{-2}	8.08×10^{-7}	4.44×10^{-16}
0.9	1.20×10^{-4}	8.50×10^{-5}	6.17×10^{-6}	1.41×10^{-2}	1.23×10^{-6}	0
1.0	6.99×10^{-4}	2.20×10^{-4}	1.03×10^{-5}	1.64×10^{-2}	1.61×10^{-6}	2.22×10^{-15}

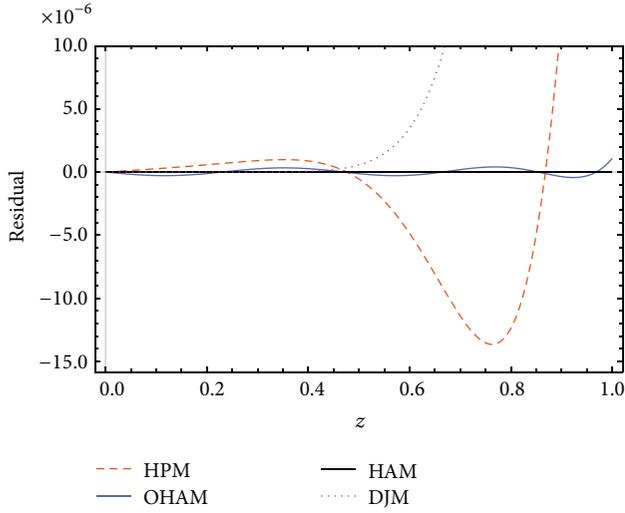


FIGURE 5: Comparison of HAM with other analytical schemes through residual.

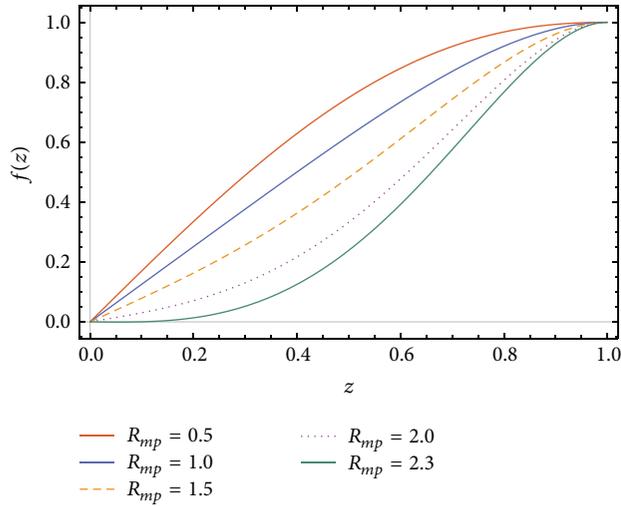


FIGURE 6: Velocity profile for different values of R_{mp} with $m_h = m_p = 0.5$.

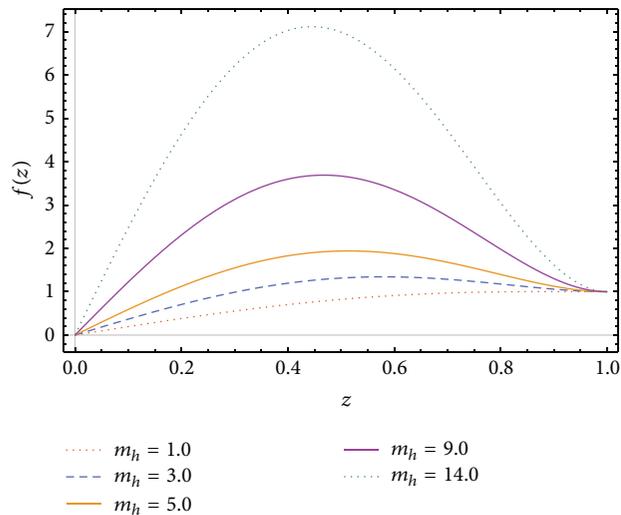


FIGURE 7: Velocity profile for different values of m_h with $m_p = R_{mp} = 1$.

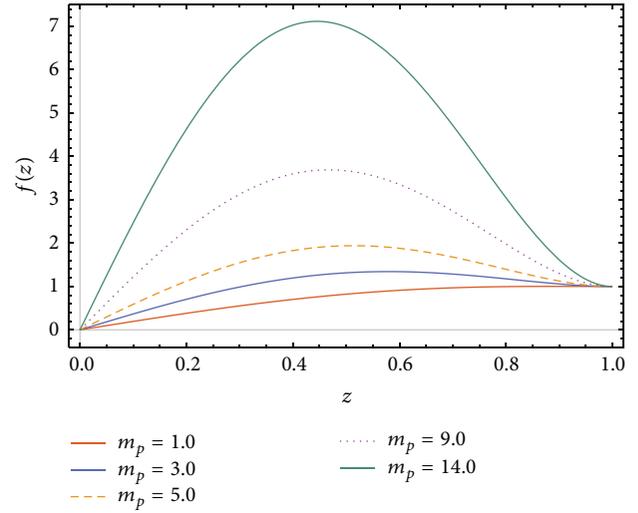


FIGURE 8: Velocity profile for different values of m_p with $m_h = R_{mh} = 1$.

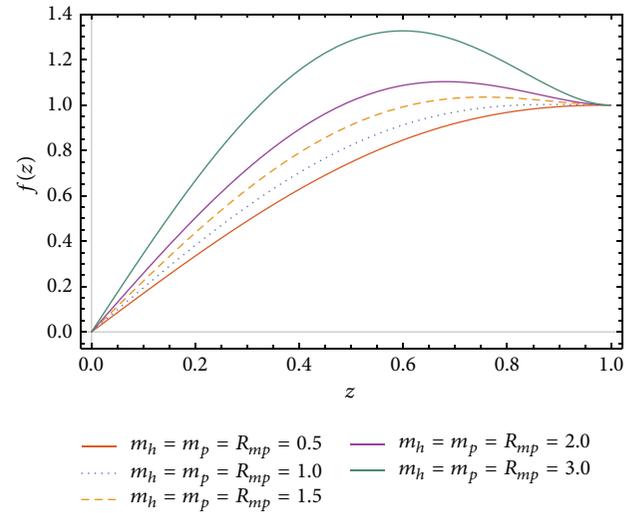


FIGURE 9: Velocity profile for equal values of $m_p, m_h,$ and R_{mp} .

Competing Interests

The authors declare that they have no competing interests.

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