

Research Article

The Modified Exponential Function Method for Beta Time Fractional Biswas-Arshed Equation

Yusuf Pandir ¹, Tolga Akturk ², Yusuf Gurefe ³, and Hussain Juya ^{3,4}

¹Department of Mathematics, Faculty of Science and Arts, Yozgat Bozok University, Yozgat, Turkey

²Department of Mathematics and Science Education, Faculty of Education, Ordu University, Ordu, Turkey

³Department of Mathematics, Faculty of Science, Mersin University, Mersin, Turkey

⁴Faculty of Information Technology and Communication, Department of Science, Kabul University, Kabul, Afghanistan

Correspondence should be addressed to Yusuf Gurefe; yusufgurefe@mersin.edu.tr and Hussain Juya; hjuya2021@gmail.com

Received 9 November 2022; Revised 16 December 2022; Accepted 5 April 2023; Published 27 April 2023

Academic Editor: Muhammad Nadeem

Copyright © 2023 Yusuf Pandir et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

In this study, the exact solutions of the Biswas-Arshed equation with the beta time derivative, which has an important role and physically means that it represents the pulse propagation in an optical fiber, nuclear, and particle physics, are obtained using the modified exponential function method. Exact solutions consisting of hyperbolic, trigonometric, rational trigonometric, and rational function solutions demonstrate the competence and relevance of the proposed method. In addition, the physical properties of the obtained exact solutions are shown by making graphical representations according to different parameter values. It is seen that the method used is an effective technique, since these solution functions obtained with all these cases have periodic function properties.

1. Introduction

Differential equations with fractional derivatives have been used very popularly in many fields of science recently, just like integer order derivative equations. It is used effectively in many branches of science such as health, biology, engineering, and stochastic models. Because such equations contain terms that represent many of the behaviors studied in these cases, each equation is defined as a mathematical model. To obtain the solutions of these mathematical models, there are various methods in the literature such as the improved Bernoulli sub-equation method [1], the trial equation method [2], the extended trial equation method [3], the G'/G method [4, 5], the extended tanh method [6], the Kudryashov method [7, 8], the generalized Kudryashov method [9], the new function method [10], the first integral method [11, 12], the differential transform method [13], the variational iteration method [14], the exp-function method [15, 16], the Adomian decomposition method [17], some numerical methods [18–22], the Chebyshev collocation method [23], the integral transform operator [24],

the Chebyshev-Tau method [25], the Taylor expansion method [26], the modified exponential function method [27, 28], and the new type F-expansion method [29].

In this study, the modified exponential function method was applied to obtain the exact solutions of the Biswas-Arshed equation with the beta time derivative.

The outline of this study can be expressed as follows: In the 2nd chapter, some information about the definitions and properties of the Atangana's beta derivative is given. In the third chapter, the modified exponential function method is introduced in detail with its features. In the fourth chapter, the analysis of the nonlinear fractional mathematical model with Atangana's derivative is given. In the last section, there is a conclusion that includes all the outputs presented in this article.

2. The Properties and Definition of Beta Derivative

Definition 1. Khalil et al. added a new fractional derivative term to the fractional derivative topic and brought it to the

literature [30]. Let us analyzed the conformable derivative function $g : [0, \infty)$ of the α order from type $t > 0, \alpha \in (0, 1)$ as follows:

$${}_0D_t^\alpha \{g(t)\} = \lim_{\varepsilon \rightarrow 0} \frac{g(t + \varepsilon t^{1-\alpha}) - g(t)}{\varepsilon}. \quad (1)$$

When g is α -differentiable in the interval of $(0, a), a > 0$ and $\lim_{\varepsilon \rightarrow 0^+} g^{(\alpha)}(t)$ consists, then it can be defined as $g^{(\alpha)}(0) = \lim_{\varepsilon \rightarrow 0^+} g^{(\alpha)}(t)$.

Definition 2. The beta derivative term is described by Atangana et al. as follows [31]:

$${}_0^A D_t^\alpha \{g(t)\} = \lim_{\varepsilon \rightarrow 0} \frac{g(t + \varepsilon(t + (1/\Gamma(\alpha)))^{1-\alpha}) - g(t)}{\varepsilon}. \quad (2)$$

The mathematical model used in the study that consists of the Atangana's fractional derivative is preferred because it provides some features of the basic derivative rules. According to all these cases, the various properties of the conformable derivative are as follows:

- (i) Let $h \neq 0$ and g be functions that are differentiable with respect to beta in the range $\beta \in (0, 1]$. Accordingly, the equation that can satisfy all the real numbers q and r is as follows:

$${}_0^A D_x^\alpha \{q g(x) + r h(x)\} = q {}_0^A D_x^\alpha \{g(x)\} + r {}_0^A D_x^\alpha \{h(x)\}. \quad (3)$$

- (ii) p is defined as any constant that satisfies the following equation:

$${}_0^A D_x^\alpha \{p\} = 0, \quad (4)$$

$${}_0^A D_x^\alpha \{g(x)h(x)\} = h(x) {}_0^A D_x^\alpha \{g(x)\} + g(x) {}_0^A D_x^\alpha \{h(x)\}, \quad (5)$$

$${}_0^A D_x^\alpha \left\{ \frac{g(x)}{h(x)} \right\} = \frac{h(x) {}_0^A D_x^\alpha \{g(x)\} - g(x) {}_0^A D_x^\alpha \{h(x)\}}{h^2(x)}. \quad (6)$$

If $\lambda = (x + (1/\Gamma(\alpha)))^{\alpha-1} \nu$ is written instead of λ in Equation (2) and $\nu \rightarrow 0$, when $\lambda \rightarrow 0$, is taken as follows

$${}_0^A D_x^\alpha \{g(x)\} = \left(x + \frac{1}{\Gamma(\alpha)} \right)^{1-\alpha} \frac{dg(x)}{dx}, \quad (7)$$

with

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha, \quad (8)$$

where δ is the constant, and therefore, the following equation is written:

$${}_0^A D_x^\alpha \{g(\eta)\} = \delta \frac{dg(\eta)}{d\eta}. \quad (9)$$

3. Properties of the Modified Exponential Function Method

In this section, the modified exponential function method, which is an efficient method used to obtain the wave solutions of the nonlinear mathematical model defined by Atangana derivatives, will be explained in detail.

The general form of the nonlinear fractional partial differential equation containing the solution function u with two variables and its beta derivatives is as follows:

$$P(u, |u|^2, {}_0^A D_t^\beta u, u_x, u_{xx}, u_{xx}, \dots) = 0, \quad (10)$$

where x and t represent space and time to which the function u given in the general form is dependent.

Let us take the traveling wave transform generated according to the independent variables in the general form of the nonlinear partial differential as follows:

$$u(x, t) = u(\eta), \eta = \left(x - \frac{\gamma}{\alpha} \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta \right), \quad (11)$$

where γ is any constant. When the derivative terms in Equation (10) are written instead of those obtained from the wave transformation (11), the general form of the following nonlinear ordinary differential equation is found:

$$N(u, u^2, u^3, u', u'', \dots) = 0. \quad (12)$$

The solution function of the nonlinear fractional differential equation considered in this study is as follows:

$$u(\eta) = \frac{\sum_{i=0}^q A_i [e^{-\vartheta(\eta)}]^i}{\sum_{j=0}^r B_j [e^{-\vartheta(\eta)}]^j} = \frac{A_0 + A_1 e^{-\vartheta} + \dots + A_q e^{-q\vartheta}}{B_0 + B_1 e^{-\vartheta} + \dots + B_r e^{-r\vartheta}}, \quad (13)$$

where $A_i, B_j, (0 \leq i \leq q, 0 \leq j \leq r)$ are constants and $\vartheta = \vartheta(\eta)$. The terms of derivative in Equation (12) are obtained from Equation (13). However, in this process, while the derivatives of the function u with respect to η are taken, the function ϑ and its derivative with respect to η are required. For this case, the following equation is used as

$$\vartheta'(\eta) = e^{-\vartheta(\eta)} + \mu e^{\vartheta(\eta)} + \lambda. \quad (14)$$

If Equation (14) is arranged, the following equation is obtained:

$$\frac{e^{\vartheta(\eta)}}{\mu e^{2\vartheta(\eta)} + \lambda e^{\vartheta(\eta)} + 1} d\vartheta = d\eta. \quad (15)$$

While integrating Equation (15) according to the functions

η and ϑ , the following family cases are obtained according to the states of the coefficients in the same equation [27, 28]:

Family 1. If $\mu \neq 0$ and $\lambda^2 - 4\mu > 0$,

$$\vartheta(\eta) = \ln \left(-\frac{\lambda}{2\mu} - \frac{\sqrt{\lambda^2 - 4\mu}}{2\mu} \tanh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} (\eta + E) \right) \right). \quad (16)$$

Family 2. If $\mu \neq 0$ and $\lambda^2 - 4\mu < 0$,

$$\vartheta(\eta) = \ln \left(-\frac{\lambda}{2\mu} + \frac{\sqrt{-\lambda^2 + 4\mu}}{2\mu} \tan \left(\frac{\sqrt{-\lambda^2 + 4\mu}}{2} (\eta + E) \right) \right). \quad (17)$$

Family 3. If $\mu = 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu > 0$,

$$\vartheta(\eta) = -\ln \left(\frac{\lambda}{e^{\lambda(\eta+E)} - 1} \right). \quad (18)$$

Family 4. If $\mu \neq 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu = 0$,

$$\vartheta(\eta) = \ln \left(-\frac{2\lambda(\eta + E) + 4}{\lambda^2(\eta + E)} \right). \quad (19)$$

Family 5. If $\mu = 0$, $\lambda = 0$, and $\lambda^2 - 4\mu = 0$,

$$\vartheta(\eta) = \ln(\eta + E), \quad (20)$$

where E, λ, μ are coefficients.

After determining the function ϑ in Equation (13) according to the conditions stated above, another step that needs to be done is to determine the upper bounds in Equation (13). For this, the balance procedure must be used. In other words, there is a relationship between q and r , which is analyzed as the upper boundary, with the balancing of the highest order derivative term in the nonlinear ordinary differential equation and the highest order nonlinear term. Then, appropriate values are determined to provide this correlation. In this way, the boundaries of Equation (13) are stated. Then, the terms of derivative required in Equation (12) are obtained from Equation (13) and written in their place. The system of algebraic equations consisting of the coefficients of the function ϑ in this equation is obtained. The coefficients in the form of $A_0, A_1, A_2, \dots, A_q$ and $B_0, B_1, B_2, \dots, B_r$ are found together with the solution of this system of equations. Then, the obtained coefficients are written in Equation (13). The functions ϑ determined according to the family conditions are also put in their place. It is checked that these functions, which are obtained together with the necessary mathematical operations, provide the nonlinear mathematical model with beta derivatives. Finally, the graphs simulating the physical behavior of wave solutions satisfying the equation are obtained according to the appropriate parameters.

4. Analysis of the Nonlinear Mathematical Model with the Beta Time Derivative

In this section, the traveling wave solutions satisfying the Biswas-Arshed equation with the beta time derivative will be analyzed by using the modified exponential function method. The Biswas-Arshed equation physically means that it represents the pulse propagation in an optical fiber. The Biswas-Arshed equation with the beta time derivative is as follows [32, 33]:

$$i_0^A D_t^\beta \{u\} + a_1 u_{xx} + a_{20}^A D_t^\beta \{u_x\} + i(b_1 u_{xxx} + b_{20}^A D_t^\beta \{u_{xx}\}) - i(\sigma(|u|^2 u)_x + \tau u(|u|^2)_x + \zeta |u|^2 u_x) = 0, \quad (21)$$

where $a_1, a_2, b_1, b_2, \sigma, \tau$, and ζ are arbitrary constants. Here, the functions $u_{xx}, u_{xxx}, {}^A D_t^\beta \{u_x\}$, and ${}^A D_t^\beta \{u_{xx}\}$ are, respectively, given as the group velocity, the third order, spatiotemporal dispersions, and spatiotemporal third-order dispersions whereas $u = u(x, t)$ is defined as a complex-valued function. Also, $(|u|^2 u)_x$ is the self-steepening term and $(|u|^2)_x$ and $|u|^2 u_x$ are the terms of nonlinear dispersions. To solve the nonlinear fractional differential equation, firstly using the wave transform given below, this equation is reduced to a system of nonlinear ordinary differential equations. For this, let us consider the traveling wave transform in the form

$$u(x, t) = \phi(\eta) e^{i\varphi(x,t)},$$

$$\eta = x - \frac{\rho}{\beta} \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta, \quad (22)$$

$$\varphi(x, t) = -\kappa x + \frac{w}{\beta} \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta + \wp,$$

where ρ, κ, w , and \wp are constants. When the terms containing derivatives required in Equation (21) are obtained from the wave transform (22) and written in their place, we get the following system of nonlinear ordinary differential equations:

$$(2\kappa\rho b_2 - 3\kappa b_1 + w b_2 + \rho a_2 - a_1)\phi'' + (\kappa^3 b_1 - \kappa^2 w b_2 + \kappa^2 a_1 - \kappa w a_2 + w)\phi + (\kappa\sigma + \kappa\zeta)\phi^3 = 0, \quad (23a)$$

$$(\rho b_2 - b_1)\phi''' + (-\kappa^2 \rho b_2 + 3\kappa^2 b_1 - 2\kappa w b_2 - \kappa \rho a_2 + 2\kappa a_1 - w a_2 + \rho)\phi' + (3\sigma + 2\tau + \zeta)\phi^2 \phi' = 0. \quad (23b)$$

By equating the coefficients of Equation (23b) to zero, the following results are obtained:

$$\begin{aligned} \rho &= \frac{b_1}{b_2}, \\ \sigma &= -\frac{2}{3}\tau - \frac{1}{3}\zeta, \\ w &= \frac{2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1}{b_2(2\kappa b_2 + a_2)}. \end{aligned} \tag{24}$$

A nonlinear ordinary differential equation is obtained by substituting the values in Equation (24) into Equation (23a) as follows:

$$\begin{aligned} &\left(-\kappa b_1 + \frac{2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1}{2\kappa b_2 + a_2} + \frac{b_1 a_2}{b_2} - a_1\right)\phi'' \\ &+ \left(\kappa^3 b_1 - \frac{(\kappa^2 b_2 - \kappa a_2 + 1)(2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)}{b_2(2\kappa b_2 + a_2)} + \kappa^2 a_1\right)\phi \\ &+ \left(\frac{2\kappa}{3}(\zeta - \tau)\right)\phi^3 = 0. \end{aligned} \tag{25}$$

When the balance procedure is applied to Equation (25), the following balance relation is obtained between the term ϕ'' with the highest order derivative and the term ϕ^3 with the highest order nonlinear term:

$$3n - 3m = n - m + 2 \Rightarrow n = m + 1. \tag{26}$$

For $m = 1$, we obtain $n = 2$. In this case, it is assumed that the solution function determined according to Equation (13) is as follows:

$$\phi(\eta) = \frac{\psi}{\omega} = \frac{A_0 + A_1 e^{-\vartheta} + A_2 e^{-2\vartheta}}{B_0 + B_1 e^{-\vartheta}}. \tag{27}$$

The derivative terms required for Equation (25) are obtained from Equation (27) as follows:

$$u'(\eta) = \frac{\psi' \omega - \psi \omega'}{\omega^2}, \tag{28}$$

$$u''(\eta) = \frac{\left(\psi'' \omega^3 + \psi' \omega' \omega^2 - (\psi' \omega' \omega^2 + \psi \omega'' \omega^2)\right) - 2\omega \omega' (\psi' \omega - \psi \omega')}{\omega^4}. \tag{29}$$

The system of algebraic equations, observed by substituting the terms obtained in Equations ((27)–(29)) into Equation (25), is solved by using the Mathematica program, and thus, the following coefficients are obtained by this way. In addition, two different cases of solutions such as Case 1 and Case 2, where each case consists of five different solution families, are given below. Now, let us consider these solution cases.

Case 1.

$$\begin{aligned} A_0 &= -\lambda B_0 \sqrt{\frac{3b_1}{2\kappa b_2(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}}, \\ A_1 &= -(2B_0 + \lambda B_1) \sqrt{\frac{3b_1}{2\kappa b_2(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}}, \\ A_2 &= -B_1 \sqrt{\frac{6b_1}{\kappa b_2(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}}, \\ a_1 &= \frac{b_1(2 - 4\kappa a_2 + (a_2^2 + b_2)(2\kappa^2 - \lambda^2 + 4\mu))}{b_2(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}. \end{aligned} \tag{30}$$

When the coefficients obtained above are, respectively, substituted in Equations (27) and (22), the following wave solutions are found according to the family states.

Family 1. When $\mu \neq 0$ and $\lambda^2 - 4\mu > 0$,

$$\begin{aligned} u_{1,1}(x, t) &= \Theta_1 \left(-\lambda + \frac{4\mu}{\lambda + \sqrt{\lambda^2 - 4\mu} \tanh \left[\left(\sqrt{\lambda^2 - 4\mu}/2 \right) \left(x - (b_1/\beta b_2)(t + (1/(\Gamma(\beta))))^\beta + E \right) \right]} \right) \\ &\times e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \vartheta)}, \end{aligned} \tag{31}$$

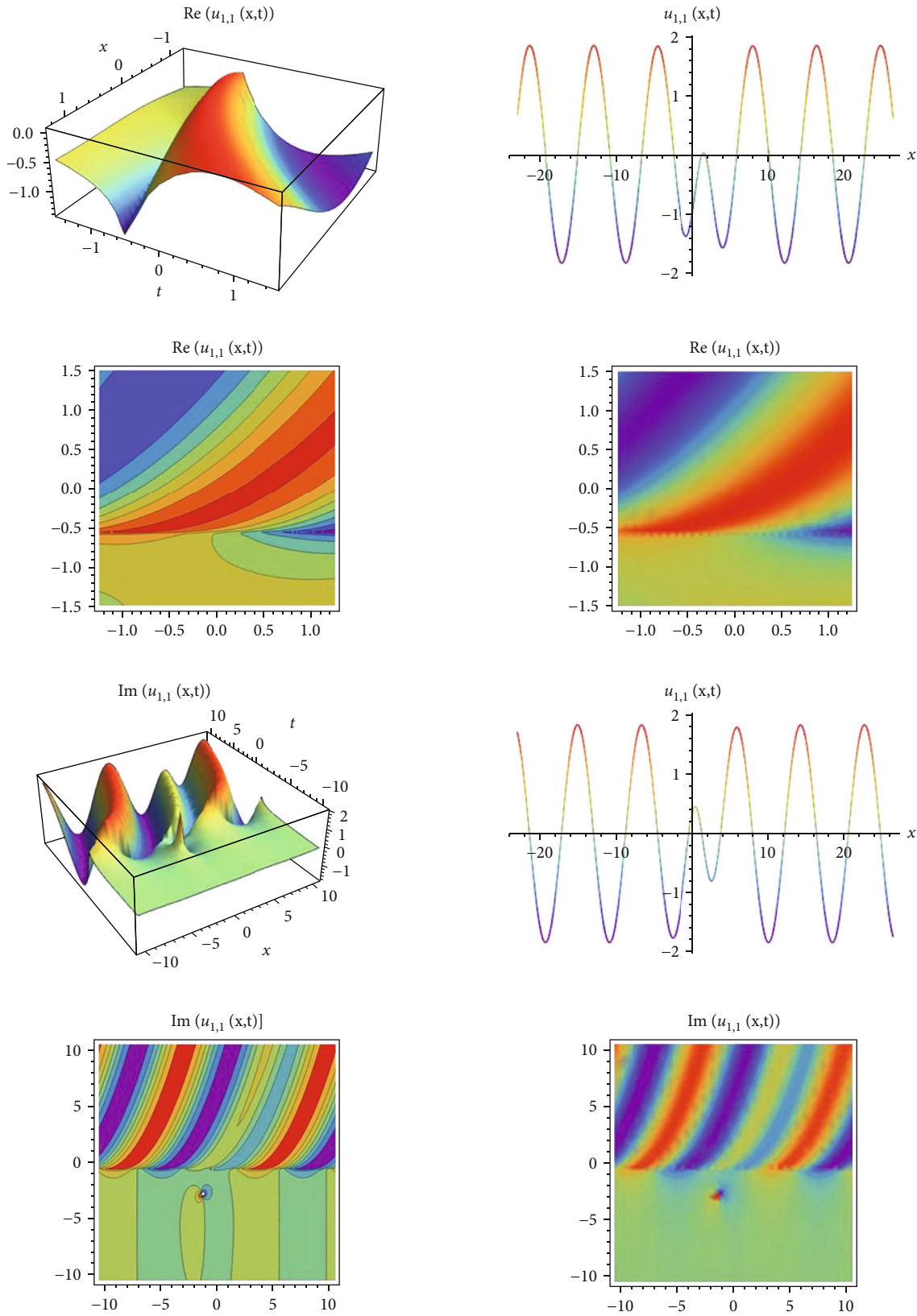


FIGURE 1: The graphs simulating the behavior of the model (31) for the values of $\delta = 0.96$, $\lambda = 3$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 2$, $a_2 = 3.6$, $b_2 = 2.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -1.10702$, $A_1 = -5.44284$, $A_2 = -3.13655$, $a_1 = 2.81046$, $\omega = 0.730188$, $\rho = 1.04167$, and $t = 1$.

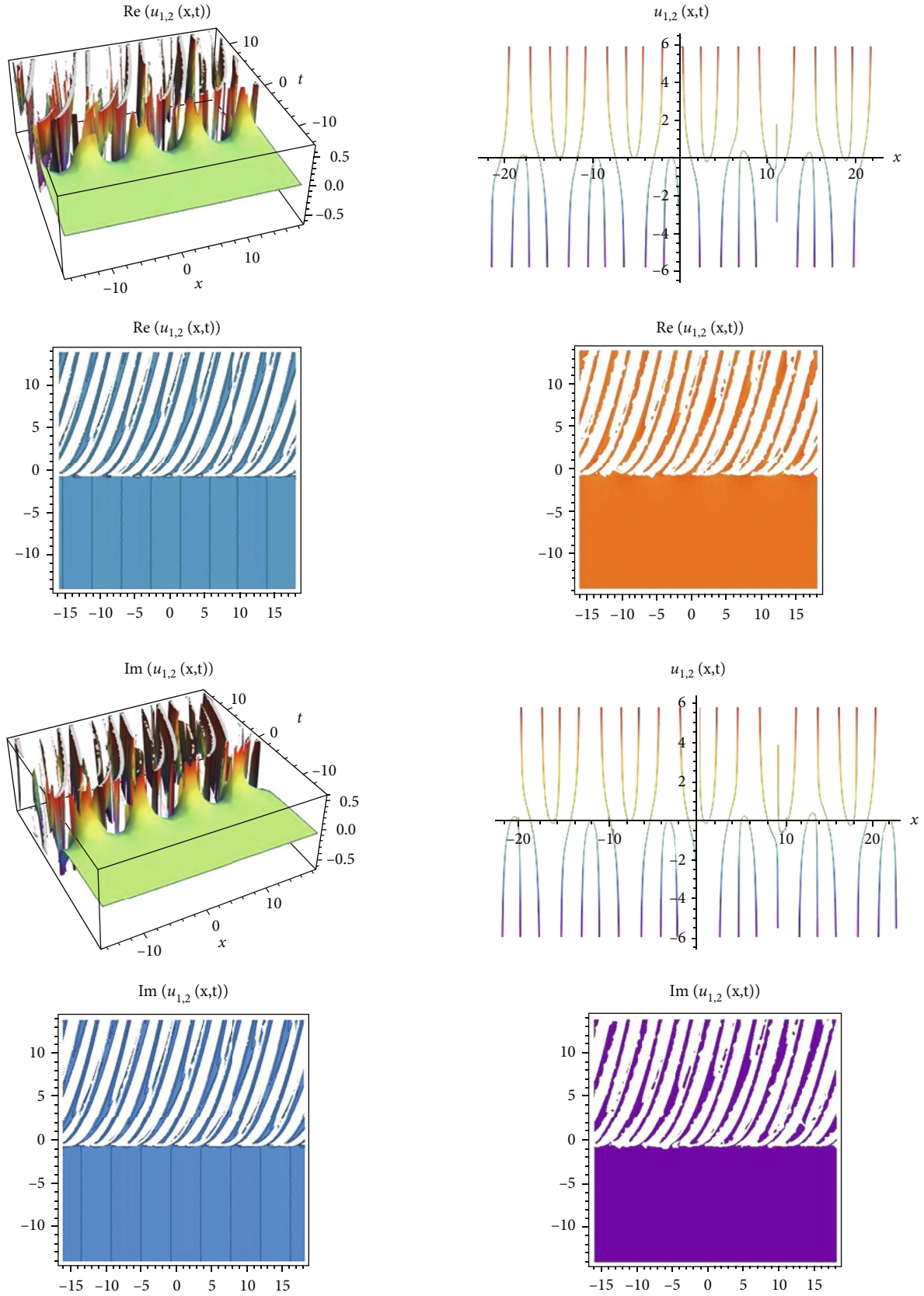


FIGURE 2: The graphs simulating the behavior of the model (32) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.45$, $\tau = 0.21$, $\mu = 3$, $a_2 = 3.6$, $b_2 = 2.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -0.215706$, $A_1 = -1.13245$, $A_2 = -0.916749$, $a_1 = 4.58403$, $\omega = 1.09968$, $\rho = 1.04167$, and $t = 1$.

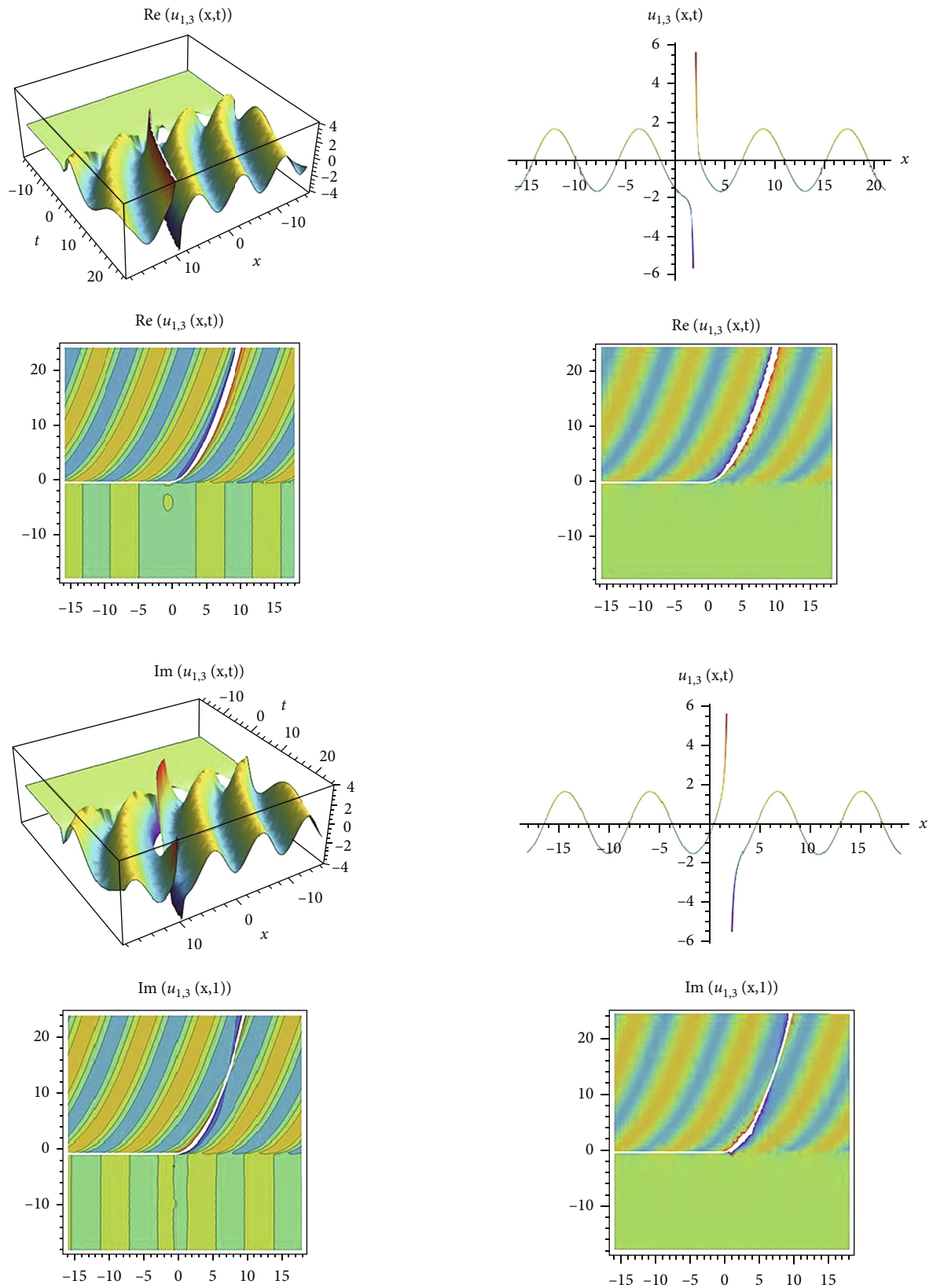


FIGURE 3: The graphs simulating the behavior of the model (33) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 0$, $a_2 = 3.6$, $b_2 = 2.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -0.322547$, $A_1 = -1.69337$, $A_2 = -1.37083$, $a_1 = 4.13233$, $\omega = 1.00558$, $\rho = 1.04167$, and $t = 1$.

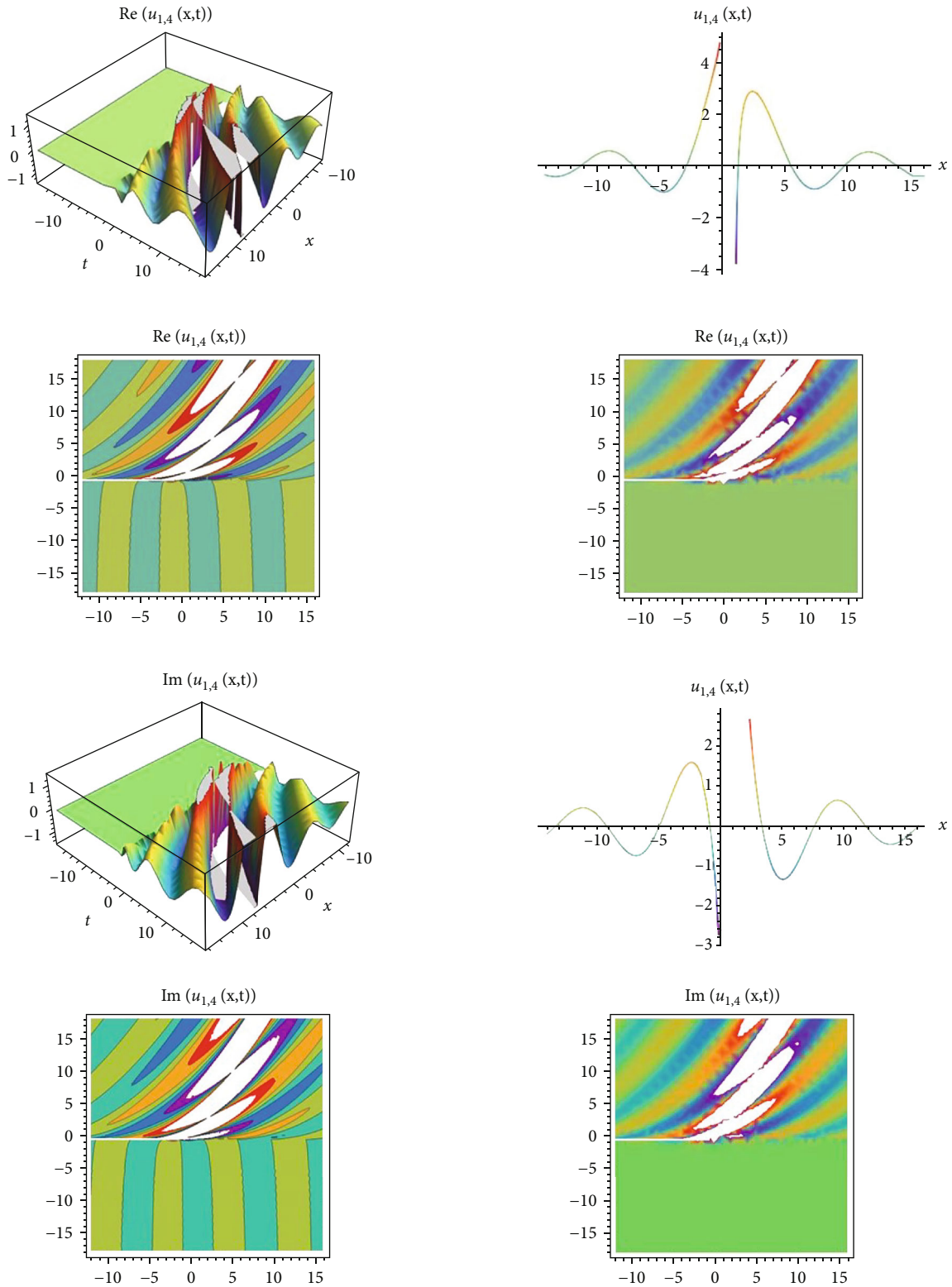


FIGURE 4: The graphs simulating the behavior of the model (34) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.45$, $\tau = 0.21$, $\mu = 1$, $a_2 = 3.6$, $b_2 = 2.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -1.15011$, $A_1 = -6.03807$, $A_2 = -4.88796$, $a_1 = 8.4127$, $\omega = 1.89732$, $\rho = 1.04167$, and $t = 1$.

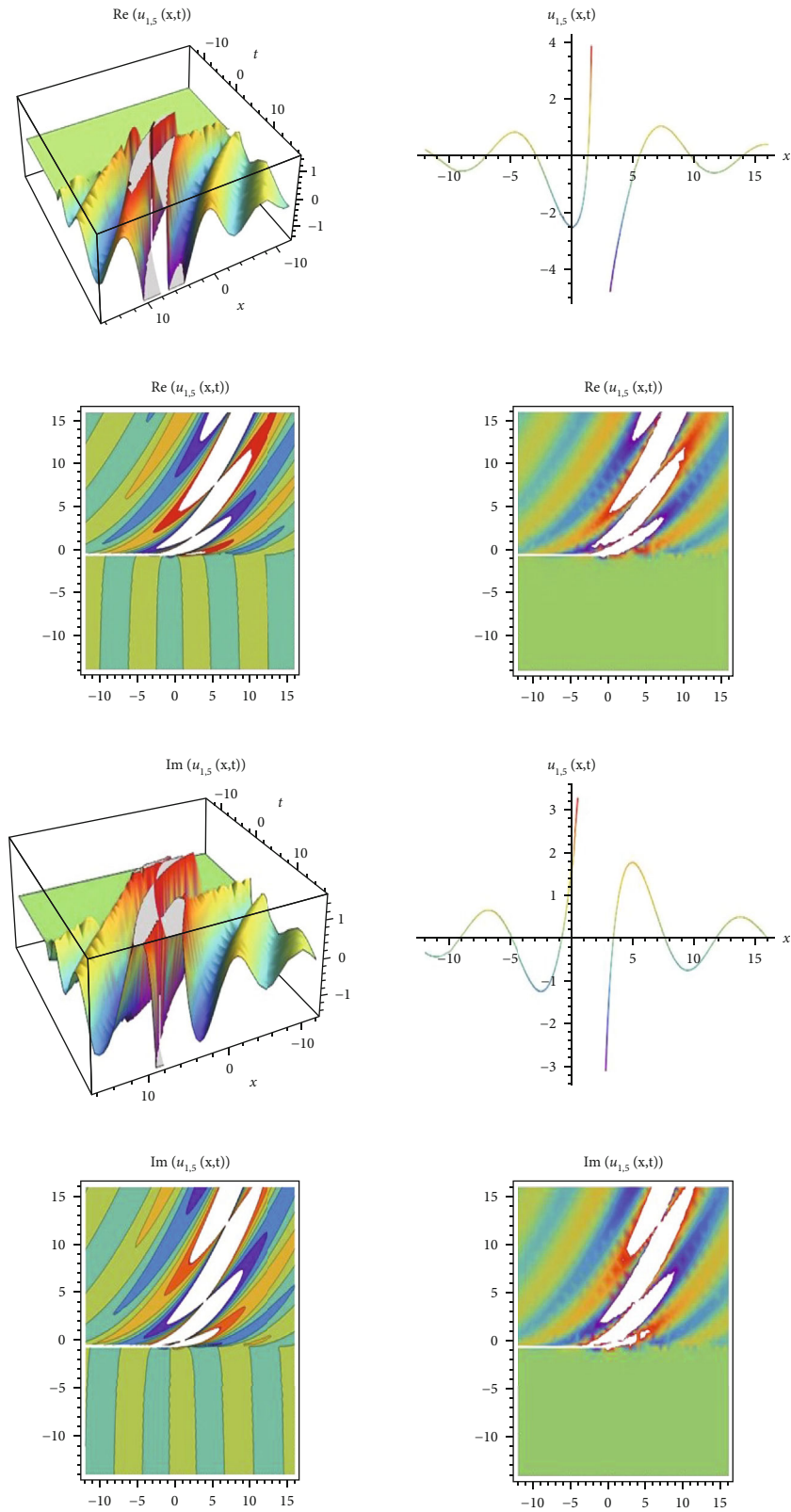


FIGURE 5: The graphs simulating the behavior of the model (35) for the values of $\delta = 0.96$, $\lambda = 0$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.45$, $\tau = 0.21$, $\mu = 0$, $a_2 = 3.6$, $b_2 = 2.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = 0$, $A_1 = -1.15011$, $A_2 = -4.88796$, $a_1 = 8.4127$, $\omega = 1.89732$, $\rho = 1.04167$, and $t = 1$.

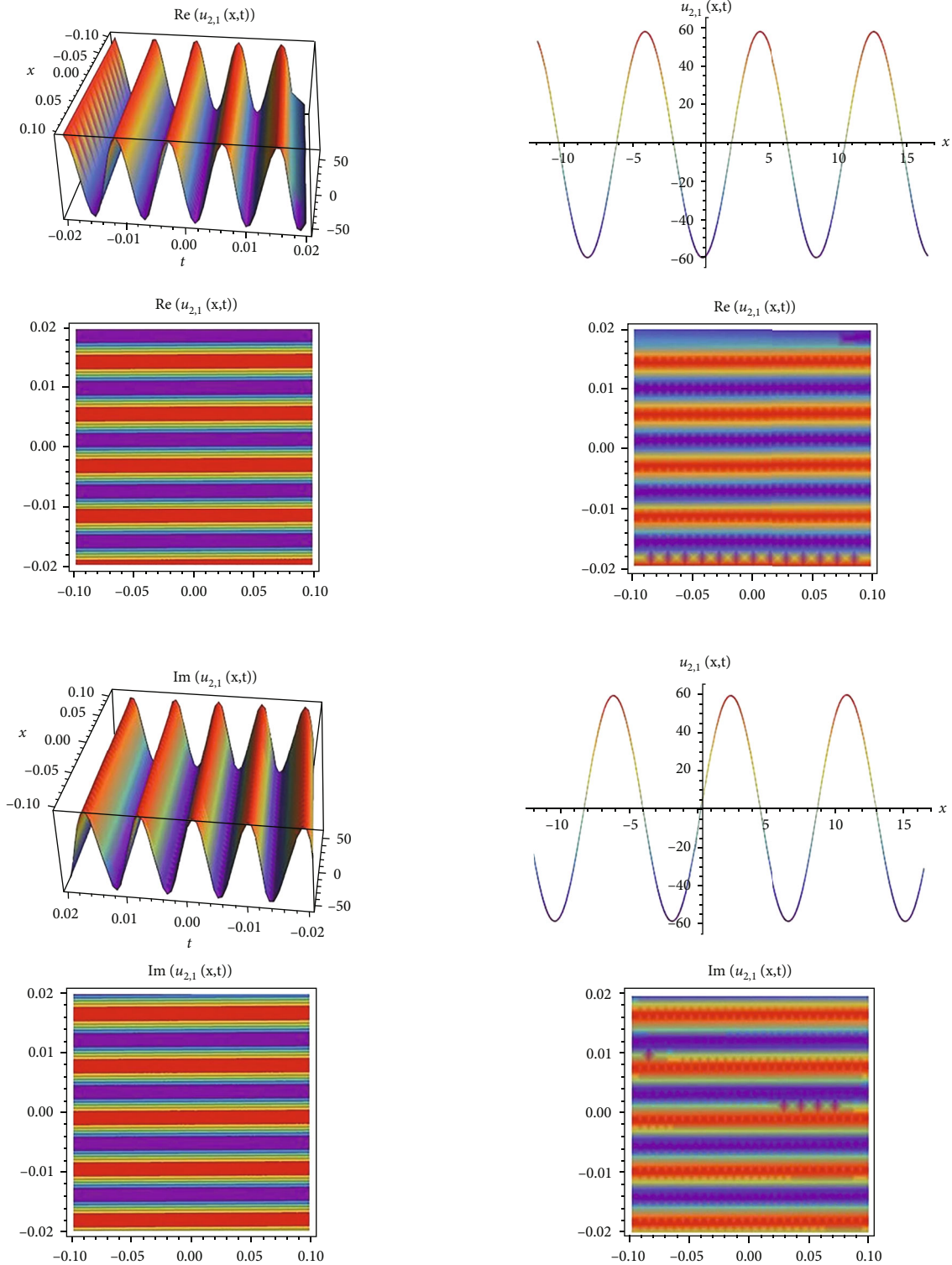


FIGURE 6: The graphs simulating the behavior of the model (37) for the values of $\delta = 0.96$, $\lambda = 3$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 2$, $a_2 = 0.6$, $b_2 = 0.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -11.8153$, $A_1 = -50.215$, $A_2 = 0$, $a_1 = 429.477$, $\omega = 542.055$, $\rho = 6.25$, and $t = 1$.

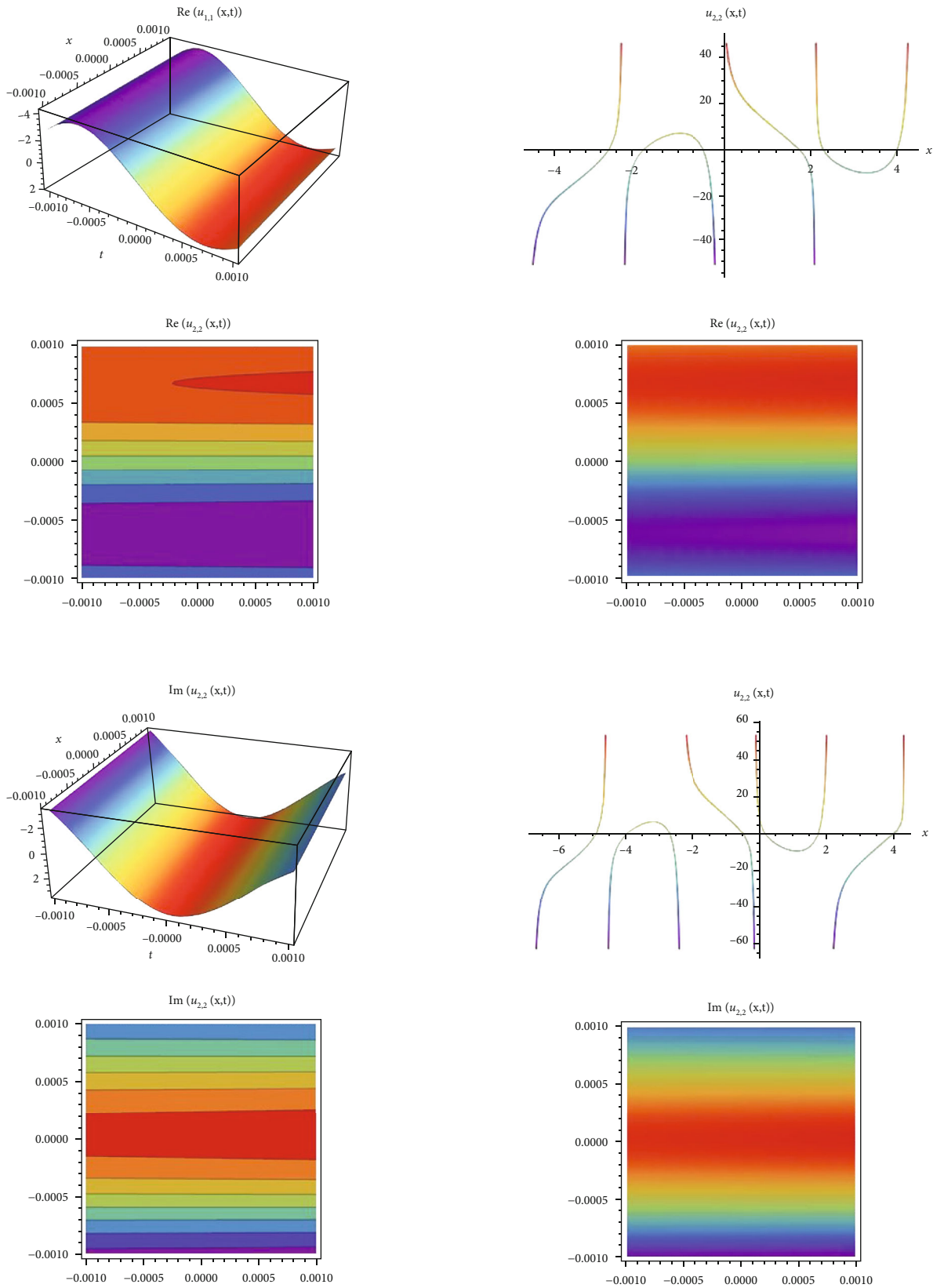


FIGURE 7: The graphs simulating the behavior of the model (38) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 3$, $a_2 = 0.6$, $b_2 = 0.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -21.5605$, $A_1 = -91.6323$, $A_2 = 0$, $a_1 = -1442.39$, $\omega = -1797.78$, $\rho = 6.25$, and $t = 1$.

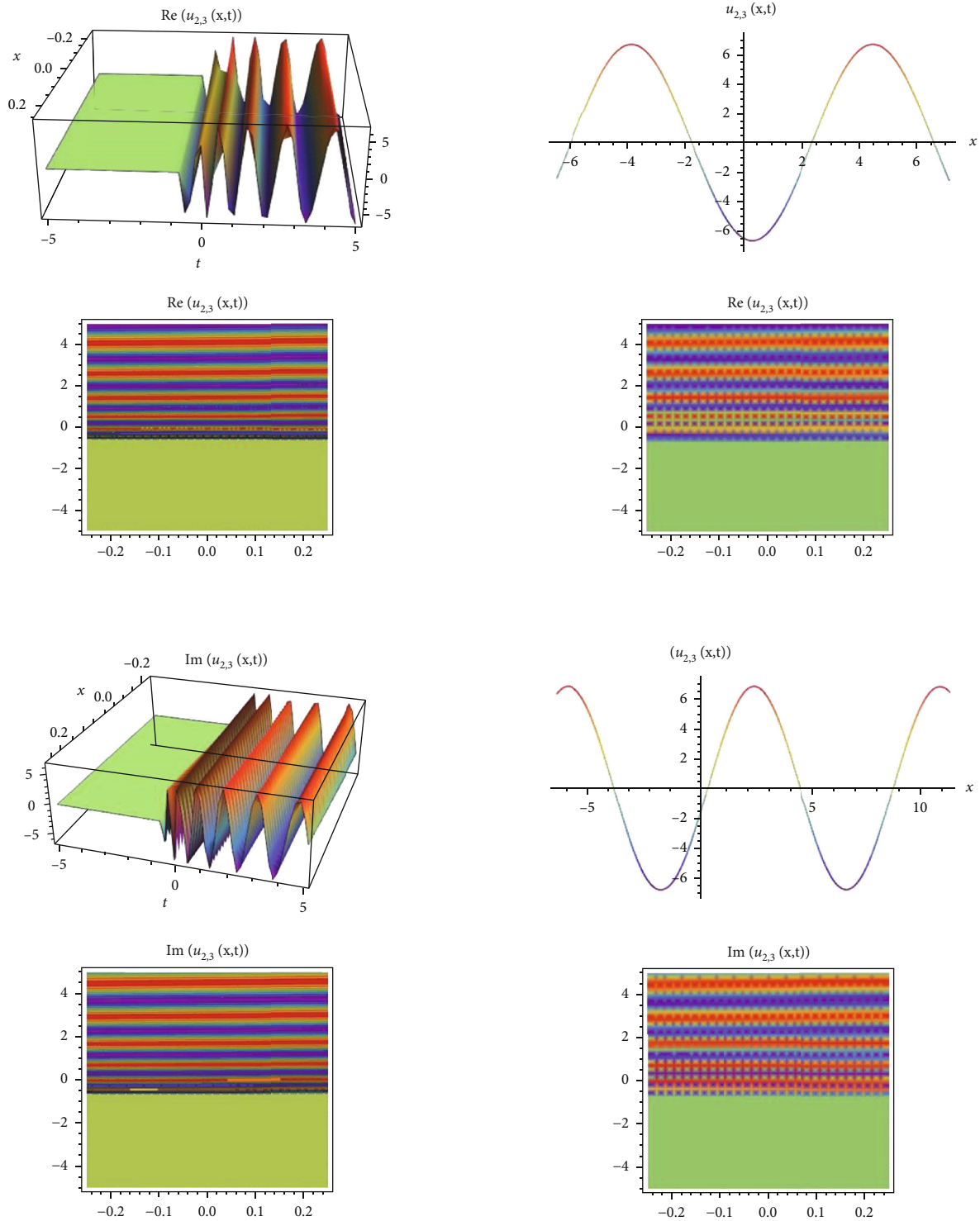


FIGURE 8: The graphs simulating the behavior of the model (39) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 0$, $a_2 = 0.6$, $b_2 = 0.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = 1.32803$, $A_1 = 5.64414$, $A_2 = 0$, $a_1 = 2.62566$, $\omega = 8.49041$, $\rho = 6.25$, and $t = 1$.

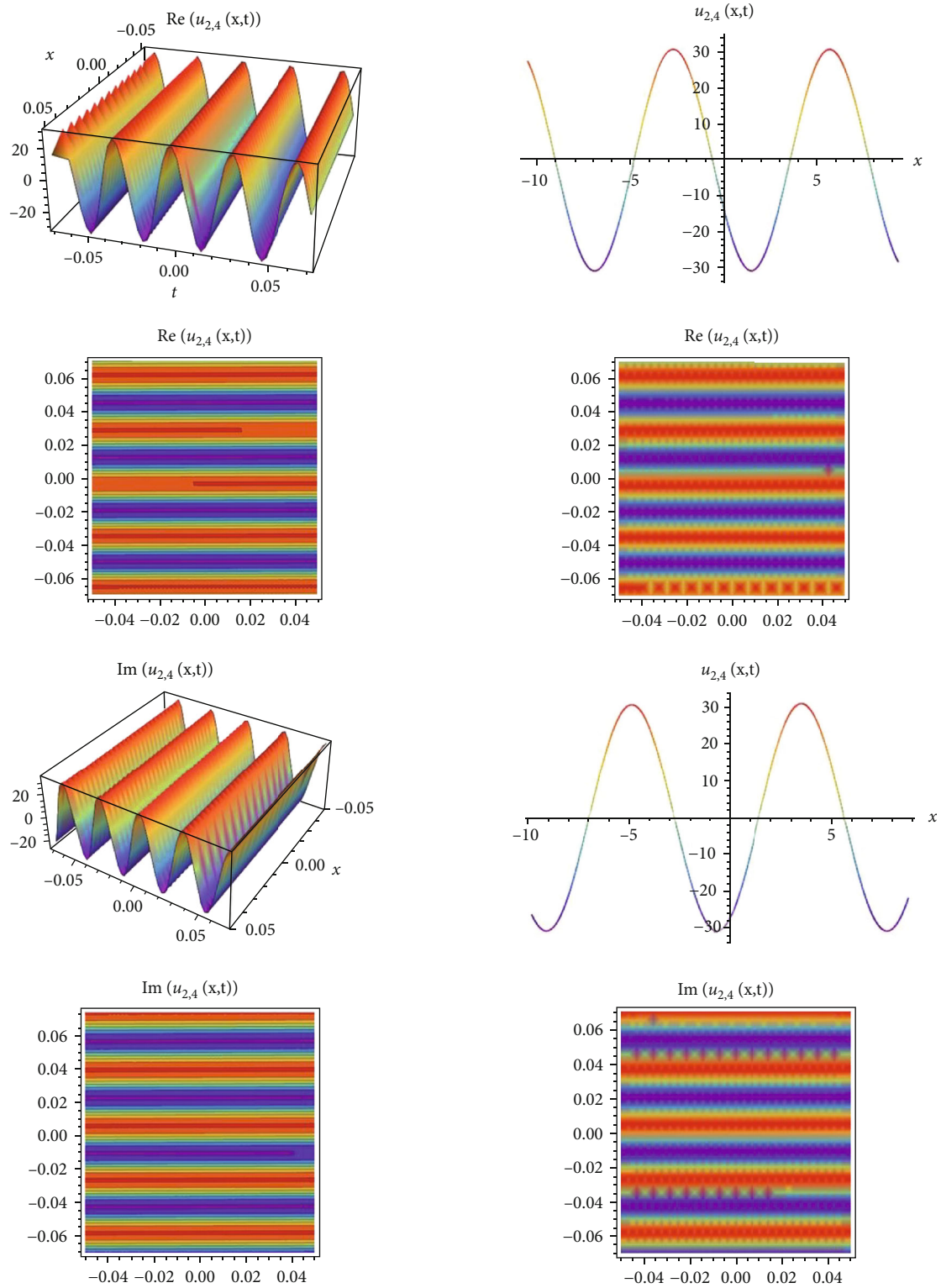


FIGURE 9: The graphs simulating the behavior of the model (40) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 1$, $a_2 = 0.6$, $b_2 = 0.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = -6.15292$, $A_1 = -26.1499$, $A_2 = 0$, $a_1 = 114.403$, $\omega = 148.212$, $\rho = 6.25$, and $t = 1$.

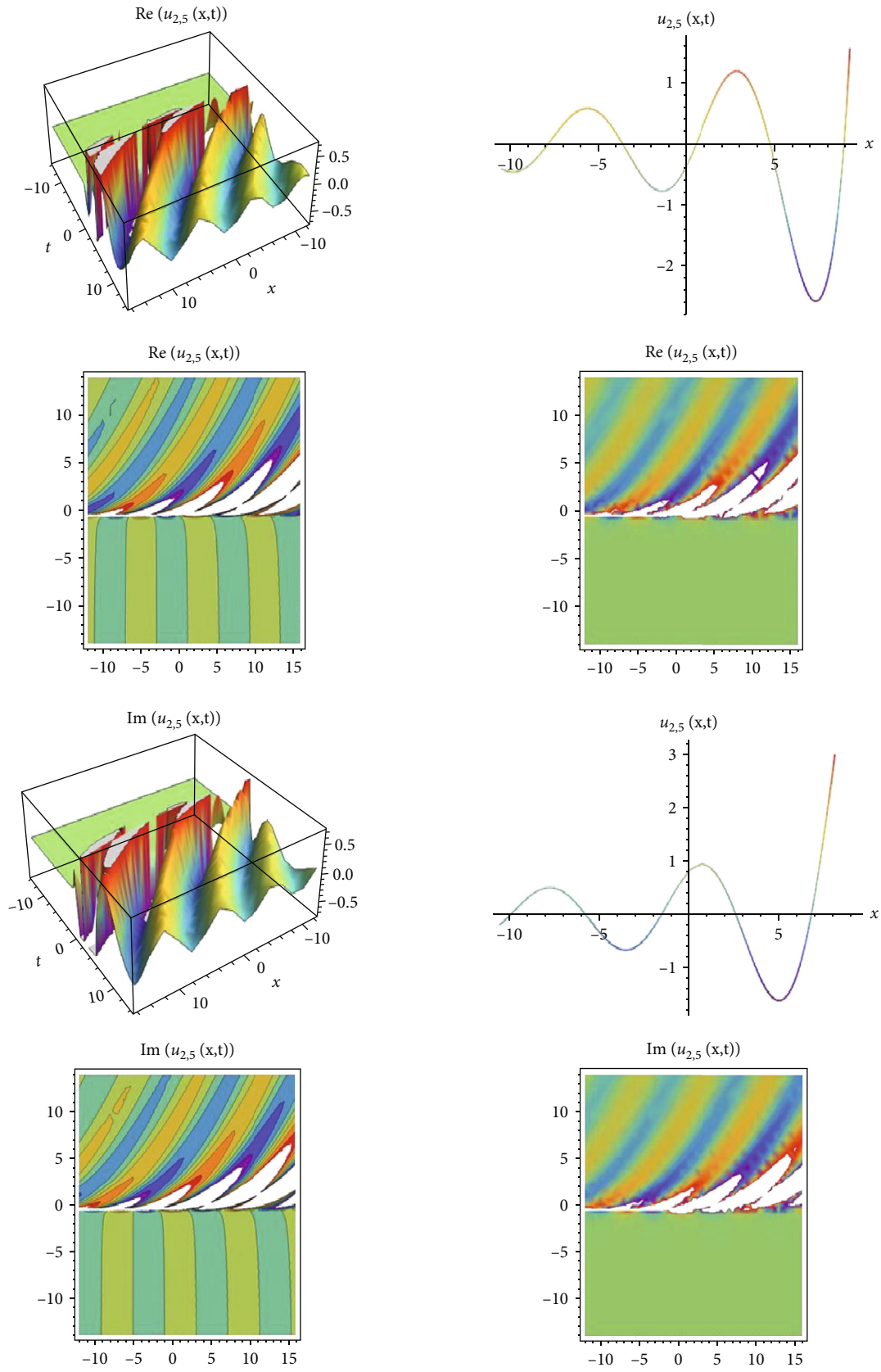


FIGURE 10: The graphs simulating the behavior of the model (41) for the values of $\delta = 0.96$, $\lambda = 2$, $b_1 = 2.5$, $B_0 = 0.2$, $\kappa = 0.75$, $\zeta = 0.21$, $\tau = 0.45$, $\mu = 1$, $a_2 = 0.6$, $b_2 = 0.4$, $B_1 = 0.85$, $E = 0.65$, $\beta = 0.5$, $A_0 = 0$, $A_1 = 1.89321$, $A_2 = 0$, $a_1 = -2.83602$, $\omega = 1.66331$, $\rho = 6.25$, and $t = 1$.

where $\Theta_1 = \sqrt{3b_1/(2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$.

Family 2. When $\mu \neq 0$ and $\lambda^2 - 4\mu < 0$,

$$u_{1,2}(x, t) = \Theta_1 \left(-\lambda + \frac{4\mu}{\lambda - \sqrt{-\lambda^2 + 4\mu} \tanh \left[\left(\sqrt{-\lambda^2 + 4\mu}/2 \right) \left(x - (b_1/\beta b_2)(t + (1/(\Gamma(\beta))))^\beta + E \right) \right]} \right) \times e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \varphi)}, \tag{32}$$

where $\Theta_1 = \sqrt{3b_1/(2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$.

Family 3. When $\mu = 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu > 0$,

$$u_{1,3}(x, t) = \Theta_2 \coth \left[\frac{1}{2} \lambda \left(x - \frac{b_1}{\beta b_2} \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta + E \right) \right] e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \varphi)}, \tag{33}$$

where $\Theta_2 = \lambda \sqrt{3b_1/(2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2)a_2))}$.

Family 5. When $\mu = 0$, $\lambda = 0$, and $\lambda^2 - 4\mu = 0$,

Family 4. When $\mu \neq 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu = 0$,

$$u_{1,4}(x, t) = \frac{\Theta_3 e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \varphi)}}{(2 + \lambda(x - (b_1/\beta b_2)(t + (1/(\Gamma(\beta))))^\beta + E))}, \tag{34}$$

$$u_{1,5}(x, t) = -\frac{\Theta_4 e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \varphi}}{x - (b_1/\beta b_2)(t + (1/(\Gamma(\beta))))^\beta + E}, \tag{35}$$

where $\Theta_3 = \lambda \sqrt{6b_1/(b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$.

where $\Theta_4 = \sqrt{3b_1/(b_2\kappa^2(\zeta - \tau)(-2 + \kappa a_2))}$.

Case 2.

$$A_0 = \frac{\sqrt{3b_1}(\lambda B_0 - 2\mu B_1)}{\sqrt{2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}},$$

$$A_1 = -\frac{\sqrt{3b_1}b_2 \left((B_0^2 - \mu B_1^2) + \sqrt{b_1}b_2(B_0^2 - \lambda B_0 B_1 + \mu B_1^2) \right)}{(2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))^{1/2} B_0},$$

$$A_2 = 0,$$

$$a_1 = \frac{2\mu\sqrt{b_1}\sqrt{\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}b_2(a_2 + 2\kappa b_2)\sqrt{\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)}b_2^2(b_2 - 2\mu B_1 + \mu B_1^2) + (\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)b_1 b_2)(\lambda B_0 - 2\mu B_1) \left(\frac{(-4\kappa + a_2(2(5\kappa^2 + \mu) + \kappa a_2(-8\kappa^2 + 2\lambda^2 - 8\mu + \kappa(2\kappa^2 - \lambda^2 + 4\mu)a_2)) + B_0^2 - 2\mu a_2 + 2\kappa b_2)B_0 B_1 + \kappa(-4\kappa^2 + 2\lambda^2 - 4\mu + \kappa(2\kappa^2 - \lambda^2 + 4\mu)a_2)b_2}{+2\mu^2(a_2 + 2\kappa b_2)B_1^2} \right)}{(\kappa(\zeta - \tau)(-2 + \kappa a_2)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2)^2 b_2^2 B_0^2 (\lambda B_0 - 2\mu B_1))}. \tag{36}$$

Let us investigate the wave solutions of the following family of solutions according to another set of coefficients obtained by solving the system of algebraic equations.

Family 1. If $\mu \neq 0$ and $\lambda^2 - 4\mu > 0$, then

$$u_{2,1}(x, t) = \frac{\Theta_2 \mu (2B_0 - \lambda B_1) + \Theta_1 (\lambda B_0 - 2\mu B_1) \left(\lambda + \sqrt{\lambda^2 - 4\mu} \tanh \left[\left(\sqrt{\lambda^2 - 4\mu}/2 \right) (\eta + E) \right] \right)}{2\mu B_1 - B_0 \left(\lambda + \sqrt{\lambda^2 - 4\mu} \tanh \left[\left(\sqrt{\lambda^2 - 4\mu}/2 \right) (\eta + E) \right] \right)} \times e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/(\Gamma(\beta))))^\beta + \varphi)}, \tag{37}$$

where $\eta = x - (b_1/\beta b_2)(t + (1/\Gamma(\beta)))^\beta$, $\Theta_1 = \sqrt{3b_1/(2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$, and $\Theta_2 = \sqrt{6b_1/(b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$.

Family 2. If $\mu \neq 0$ and $\lambda^2 - 4\mu < 0$, then

$$u_{2,2}(x, t) = \frac{(\Theta_1 - \Theta_2\mu(B_0^2 - \mu B_1^2) + (B_0^2 - \lambda B_0 B_1 + \mu B_1^2))}{B_0(\lambda B_0 - 2\mu B_1) \left(-\lambda + \sqrt{-\lambda^2 + 4\mu} \tan \left[\left(\sqrt{-\lambda^2 + 4\mu}/2 \right) \left(x - (b_1/\beta b_2)(t + (1/\Gamma(\beta)))^\beta + E \right) \right] \right)} \times e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/\Gamma(\beta)))^\beta + \varphi)} \tag{38}$$

where $\Theta_1 = \sqrt{3b_1/(2b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$ and $\Theta_2 = \sqrt{6b_1/(b_2\kappa(\zeta - \tau)(-4\kappa + (2\kappa^2 - \lambda^2 + 4\mu)a_2))}$.

Family 3. If $\mu = 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu > 0$, then

$$u_{2,3}(x, t) = \frac{\Theta_1 \lambda \left(B_0 - \lambda B_1 + B_0 e^{\lambda(x - (b_1/\beta b_2)(t + (1/\Gamma(\beta)))^\beta + E)} \right)}{-B_0 + \lambda B_1 + B_0 e^{\lambda(x - (b_1/\beta b_2)(t + (1/\Gamma(\beta)))^\beta + E)}} e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/\Gamma(\beta)))^\beta + \varphi)} \tag{39}$$

Family 4. If $\mu \neq 0$, $\lambda \neq 0$, and $\lambda^2 - 4\mu = 0$, then

$$u_{2,4}(x, t) = \Theta_1 \left(\begin{array}{l} -\lambda^2 (B_0^2 - \lambda B_0 + \mu B_1^2) \left((E + x)\beta b_2 - b_1 \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta \right) + \\ i\beta b_2 \left(\frac{\lambda(4 + (E + x)\lambda)B_0^2 - 4(2 + (E + x)\lambda)\mu B_0 B_1 + (E + x)\lambda^2 \mu B_1^2}{\lambda B_0^2 - 4\mu B_0 B_1 + \lambda \mu B_1^2} \right) - \\ -\lambda b_1 \left(\lambda B_0^2 - 4\mu B_0 B_1 + \lambda \mu B_1^2 \left(t + \frac{1}{\Gamma(\beta)} \right)^\beta \right) \end{array} \right) \times e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/\Gamma(\beta)))^\beta + \varphi)} \tag{40}$$

Family 5. If $\mu = 0$, $\lambda = 0$, and $\lambda^2 - 4\mu = 0$, then

$$u_{2,5}(x, t) = \frac{\Theta_4 B_0 e^{i(-\kappa x + ((2\kappa^2 b_1 b_2 + 2\kappa a_1 b_2 - \kappa a_2 b_1 + b_1)/(\beta b_2(2\kappa b_2 + a_2)))(t + (1/\Gamma(\beta)))^\beta + \varphi)}}{b_2 \left(B_1 + B_0 \left(x - (b_1/\beta b_2)(t + (1/\Gamma(\beta)))^\beta + E \right) \right)} \tag{41}$$

where $a_1 = (b_1((-1 + \kappa a_2)^2 + \kappa^2 b_2))/(\kappa(-2 + \kappa a_2)b_2)$ and $\Theta_4 = \sqrt{3b_1 b_2/(\kappa^2(\zeta - \tau)(-2 + \kappa a_2))}$.

5. Conclusions

In this study, an effective technique, the modified exponential function method for the Biswas-Arshed equation with

the beta time derivative, was applied. It can be said that this method is an advantageous technique for obtaining wave solutions of nonlinear partial differential equations. This advantage can be explained as follows. The traveling wave solutions of the mathematical model contain periodic functions. By obtaining these functions, the behavior model obtained in a range can be generalized to an infinite range. In this study, a package program was used for all mathematical operations and graphics that simulate the behavior of the mathematical model and for all the operations related to showing that solution functions provide the mathematical model. Using the method, two case situations consisting of coefficients were analyzed. According to these situations, hyperbolic, trigonometric, and rational solution functions

belonging to the mathematical model were obtained. In addition, in the second case, the solution functions belonging to the mathematical model were obtained in a complex form. For this reason, while determining the graphs simulating the behaviors, they were examined separately as real and imaginary parts in Figures 1–10. When all these results are analyzed, it is concluded that obtaining periodic solution functions is of great importance, because such functions will allow to make comments about a desired range.

Data Availability

No data were used to support this study.

Conflicts of Interest

The authors declare that they have no competing interests.

Authors' Contributions

All authors read and approved the final manuscript.

References

- [1] J. Yang, A. Liu, and T. Liu, "Forced oscillation of nonlinear fractional differential equations with damping term," *Advances in Difference Equations*, vol. 2015, no. 1, p. 17, 2015.
- [2] C. S. Liu, "A new trial equation method and its applications," *Communications in Theoretical Physics*, vol. 45, no. 3, pp. 395–397, 2006.
- [3] Y. Pandir, Y. Gurefe, and E. Misirli, "The extended trial equation method for some time fractional differential equations," *Discrete Dynamics in Nature and Society*, vol. 2013, Article ID 491359, 13 pages, 2013.
- [4] M. A. Akbar, N. H. M. Ali, and E. M. E. Zayed, "Abundant exact traveling wave solutions of generalized Bretherton equation via improved (G'/G)-expansion method," *Communications in Theoretical Physics*, vol. 57, no. 2, pp. 173–178, 2012.
- [5] A. Akbulut, M. Kaplan, and F. Tascan, "Conservation laws and exact solutions of Phi-four (Phi-4) equation via the (G'/G, 1/G)-expansion method," *Zeitschrift für Naturforschung A*, vol. 71, no. 5, pp. 439–446, 2016.
- [6] M. A. Abdou, "The extended tanh method and its applications for solving nonlinear physical models," *Applied Mathematics and Computation*, vol. 190, no. 1, pp. 988–996, 2007.
- [7] P. N. Ryabov, D. I. Sinelshchikov, and M. B. Kochanov, "Application of the Kudryashov method for finding exact solutions of the high order nonlinear evolution equations," *Applied Mathematics and Computation*, vol. 218, no. 7, pp. 3965–3972, 2011.
- [8] M. Kaplan, A. Bekir, and A. Akbulut, "A generalized Kudryashov method to some nonlinear evolution equations in mathematical physics," *Nonlinear Dynamics*, vol. 85, no. 4, pp. 2843–2850, 2016.
- [9] S. T. Demiray, Y. Pandir, and H. Bulut, "Generalized Kudryashov method for time-fractional differential equations," *Abstract and Applied Analysis*, vol. 2014, Article ID 901540, 13 pages, 2014.
- [10] T. Akturk, Y. Gurefe, and Y. Pandir, "An application of the new function method to the Zhiber-Shabat equation," *International Journal of Optimization and Control: Theories & Applications (IJOCTA)*, vol. 7, no. 3, pp. 271–274, 2017.
- [11] B. Elma and E. Misirli, "Two reliable techniques for solving conformable space-time fractional PHI-4 model arising in nuclear physics via β -derivative," *Revista Mexicana de Física*, vol. 67, no. 5, article 050707, 2021.
- [12] H. Yépez-Martínez, J. F. Gómez-Aguilar, and A. Atangana, "First integral method for non-linear differential equations with conformable derivative," *Mathematical Modelling of Natural Phenomena*, vol. 13, no. 1, p. 22, 2018.
- [13] A. Arikoglu and I. Ozkol, "Solution of fractional differential equations by using differential transform method," *Chaos, Solitons & Fractals*, vol. 34, no. 5, pp. 1473–1481, 2007.
- [14] B. Batiha, M. S. M. Noorani, and I. Hashim, "Numerical solution of sine-Gordon equation by variational iteration method," *Physics Letters A*, vol. 370, no. 5–6, pp. 437–440, 2007.
- [15] A. Bekir, Ö. Güner, and A. C. Cevikel, "Fractional complex transform and exp-function methods for fractional differential equations," *Abstract and Applied Analysis*, vol. 2013, Article ID 426462, 8 pages, 2013.
- [16] A. Akbulut, M. Kaplan, and F. Tascan, "The investigation of exact solutions of nonlinear partial differential equations by using $\exp(-\Phi(\xi))$ method," *Optik*, vol. 132, pp. 382–387, 2017.
- [17] N. T. Shawagfeh, "Analytical approximate solutions for nonlinear fractional differential equations," *Applied Mathematics and Computation*, vol. 131, no. 2–3, pp. 517–529, 2002.
- [18] K. Diethelm and N. J. Ford, "Analysis of fractional differential equations," *Journal of Mathematical Analysis and Applications*, vol. 265, no. 2, pp. 229–248, 2002.
- [19] P. Kumar and O. P. Agrawal, "An approximate method for numerical solution of fractional differential equations," *Signal Processing*, vol. 86, no. 10, pp. 2602–2610, 2006.
- [20] N. J. Ford and A. C. Simpson, "The numerical solution of fractional differential equations: speed versus accuracy," *Numerical Algorithms*, vol. 26, no. 4, pp. 333–346, 2001.
- [21] A. Atangana and A. Akgül, "On solutions of fractal fractional differential equations," *Discrete & Continuous Dynamical Systems-S*, vol. 14, no. 10, pp. 3441–3457, 2021.
- [22] D. Baleanu, O. G. Mustafa, and R. P. Agarwal, "On the solution set for a class of sequential fractional differential equations," *Journal of Physics A: Mathematical and Theoretical*, vol. 43, no. 38, article 385209, 2010.
- [23] M. I. Syam and M. Al-Refai, "Fractional differential equations with Atangana-Baleanu fractional derivative: analysis and applications," *Chaos, Solitons & Fractals*, vol. 2, article 100013, 2019.
- [24] A. Atangana and I. Koca, "Chaos in a simple nonlinear system with Atangana-Baleanu derivatives with fractional order," *Chaos, Solitons & Fractals*, vol. 89, pp. 447–454, 2016.
- [25] N. Gurefe, E. G. Kocer, and Y. Gurefe, "Chebyshev-tau method for the linear Klein-Gordon equation," *International Journal of Physical Sciences*, vol. 7, no. 43, pp. 5723–5728, 2012.
- [26] T. Abdeljawad, "On conformable fractional calculus," *Journal of Computational and Applied Mathematics*, vol. 279, pp. 57–66, 2015.
- [27] Y. Pandir, Y. Gurefe, and T. Akturk, "New soliton solutions of the nonlinear Radhakrishnan-Kundu-Lakshmanan equation with the beta-derivative," *Optical and Quantum Electronics*, vol. 54, no. 4, pp. 1–21, 2022.
- [28] Y. Gurefe, Y. Pandir, and T. Akturk, "On the nonlinear mathematical model representing the Coriolis effect," *Mathematical*

Problems in Engineering, vol. 2022, Article ID 2504907, 12 pages, 2022.

- [29] Y. Pandir and H. H. Duzgun, "New exact solutions of the space-time fractional cubic Schrodinger equation using the new type F-expansion method," *Waves in Random and Complex Media*, vol. 29, no. 3, pp. 425–434, 2019.
- [30] R. Khalil, M. Al Horani, A. Yousef, and M. Sababheh, "A new definition of fractional derivative," *Journal of Computational and Applied Mathematics*, vol. 264, pp. 65–70, 2014.
- [31] A. Atangana, D. Baleanu, and A. Alsaedi, "New properties of conformable derivative," *Open Mathematics*, vol. 13, no. 1, pp. 889–898, 2015.
- [32] K. Hosseini, M. Mirzazadeh, M. Ilie, and J. F. Gómez-Aguilar, "Biswas-Arshed equation with the beta time derivative: optical solitons and other solutions," *Optik-International Journal for Light and Electron Optics*, vol. 217, article 164801, 2020.
- [33] T. Han, Z. Li, and J. Yuan, "Optical solitons and single traveling wave solutions of Biswas-Arshed equation in birefringent fibers with the beta-time derivative," *AIMS-Mathematics*, vol. 7, no. 8, pp. 15282–15297, 2022.