

Research Article

Application of Constant Proportional Caputo Fractional Derivative to Thermodiffusion Flow of MHD Radiative Maxwell Fluid under Slip Effect over a Moving Flat Surface with Heat and Mass Diffusion

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Thermal diffusion is a phenomenon where the concentration gradient or diffusive flux is created due to the temperature gradient. Thermal diffusion is induced because of the higher temperature and uneven distribution of the mixture. Formally, thermal diffusion is called the Soret effect, and it is a crucial factor in a number of natural occurrences like the separation of isotopes technique of purification. In this research paper, Maxwell fluid's flow in the vicinage of a flat plate is discussed by considering the effect of the thermodiffusion subject to the first-order slip at the boundary with the application of a constant proportional Caputo (CPC) fractional derivative. The effect of heat generalized heat and mass fluxes are considered, and this generalization of heat and mass fluxes is done by utilizing the CPC fractional derivative. After converting the current model's governing equations into a dimensionless form, the temperature, concentration, and velocity fields for the parametric modifications, the results are graphically illustrated. It becomes clear from the results discussion that the outcomes produced by the constant proportional derivative are more decaying than those obtained with the classical differential operator of order one.

1. Introduction

Thermodiffusion is a physical phenomenon that occurs in the mixture of different moving particles with an adverse response to the temperature gradient. In this phenomenon, the particles of smaller inertia tend to move in the region of higher temperature, while the particles with the greater inertia try to move in the area of lower temperature. Formally, this phenomenon is called the Soret effect and has many industrial and biological applications like isotope separation [1, 2]. Slippage of the flowing fluid over a flat surface is important in many complex flows of non-Newtonian fluids. Slip of the fluid occurs at the boundary when there is relative motion between fluid and boundary. This mechanical situation is addressed properly by the Robin-type boundary condition and specifically, it is known as the slip boundary condition. The slip effect is formulated by many theorists to address the different geometric situations for the boundary layer flows. Vieru et al. [3] explained the aspect of slip for second-grade fluid flow. Tahir et al. [4] considered Maxwell fluid motion over an oscillation surface. Jameel and Khan [5] discussed an impulsive flow over the flat plate. Hayat et al. [6] studied the Stokes flow for the slip condition. Imran et al. [7] applied the first order slip for the motion of the non-Newtonian fluid. Sajid et al. [8] explained the slippage motion of the rate-type fluid. Hayat et al. [9] studied the flow of Maxwell fluid between the plates under the influence of MHD and radiation. Ramesh et al. [10] studied the Maxwell fluid over a stretching sheet and discussed the impact of radiation on the motion of the fluid. Khan et al. [11] reported the flow of Maxwell fluid by taking into account the influence of radiation. Chen et al. [12] utilized the fractional derivatives boundary layer flow of Maxwell fluid on an unsteady stretching surface and obtained the results for the velocity. Over a vertical plate, Imran et al. [13] considered a slippage flow of a radiative fluid.

Opangua et al. [14] explained the effect of slip on the flow of coupled stressed fluid. Hayat and Asghar [15] and Hayat et al. [16, 17] considered the impact of heat transfer over the slippage flow of peristaltic fluid. Shakeel et al. [18] employed the slip effect to rate-type fluid over an accelerating plate. Shah et al. [19] applied the fractional calculus to get the generalized results for the unidirectional velocity for Maxwell fluid. Shah et al. [20] used the slip conditions at the boundary for MHD Carreau fluid through a porous regime. Freidoonimehr and Jafari [21] also employed slip conditions at the boundary for MHD nanofluid flow. Schneider [22] considered the motion of electrorheological suspensions and laid out the impact of wall slip on the rheological behavior of the suspension. Raza [23] stagnation point flow of Casson fluid by considering the impact of slip. Norouzi et al. [24] investigated the flow of Oldroyd-B fluid in the cylindrical domain by studying the effect of slip at the boundary. Fetecau et al. [25] discussed the flow of Newtonian fluid by taking into account the effect of slip at the edge of the flow. Khan et al. [26] applied the slip attribute to the viscous nanofluid flow and obtained the velocity field.

Khan et al. [27] discussed the impact of the transfer of heat on the flow of Maxwell fluid. Chu et al. [28] studied nanofluid flow with four different types of nanoparticles, which are subject to the nonhomogenous source of heat, and applied the numerical technique to obtain the approximated solutions. Alqahtani et al. [29] did a detailed analysis of the impact of radiation on the flow of nanofluid. Puneeth et al. [30] explained the effect of convection on nanofluid's flow over a sheet. Alharbi et al. [31] illustrated the effect of the bioconvective hydromagnetic flow of Oldroyd-B nanofluid over a stretching surface having pores. Khan et al. [32] took under consideration the unsteady flow of hybrid nanofluid on a radiated porous surface subject to the magnetic field. Qaiser et al. [33] investigated the effects of active energy and entropy for nanofluid flow subject to viscous dissipation and cross-diffusion. Some other investigations related to nanofluid flow in different physical situations have been done [33–39].

The Maxwell fluid model is suitable for momentum, heat, and mass transfer phenomena as it captures relaxation time effects. Khan et al. [40] discussed the generalized conclusions for the flow of Maxwell fluid by taking into consideration the modified Fick's and Fourier laws for mass and heat transfer, respectively. Khan et al. [41] utilized the Cattaneo–Christov mechanism for the heat transfer of Maxwell fluid through a closed path. Tang et al. [42] discussed the flow of Maxwell fluid subject to uniform heat flux and thermal radiation by applying the fractional derivative. Mansoor et al. [43] also considered the Maxwell fluid's flow, and the effect of chemical reaction over the velocity field is explained.

The fractional derivatives are flexible and nonlocal because the order of the fractional derivatives can be any real number. Due to nonlocality and flexibility, the fractional derivatives are suitable for approximating real data values with more reliability than classical derivatives for the effect of global interactions (nonlocality of space) and memory (nonlocality of time). Nowadays, fractional calculus is applied efficiently to explain the complex flow phenomenon. There are different approaches to the fractional derivative used by mathematicians [44–47], and a recent development in the fractional is the constant proportional Caputo (CPC) derivative proposed by Baleanu et al. [48].

The thermodiffusion, formally known as the Soret effect, occurs when a concentration gradient is generated due to a temperature gradient. This effect is significant for complex mixtures containing different species of diverse sizes and polarities, for example, in the petroleum system. The principal interest of this article is to widen the research work done in [25] by taking the flow of Maxwell fluid, and the flow modeling is done with a fractional derivative of the recent approach, namely the constant Caputo fractional derivative. The graphical illustration of field variables is done by using MATHCAD software. In addition to this, the slip at the boundary is analyzed with other parameters. Such work addressing the thermodiffusion effect for Maxwell fluid's flow with CPC fractional derivative is yet to be reported in the literature.

2. Mathematical Description

Considered Maxwell fluid flowing over a vertical plate. The vertical plate is situated in the *xz*-plane in a way that the *y*-axis becomes normal to the place of the plate, as indicated in Figure 1. At first, the plate with the fluid is not moving; after the time t > 0, the plate starts moving with the velocity $V_0f(t)$, and by considering the slip effect over the plate fluid also move. Under the assumption, the Maxwell fluid flow model in mathematical form is as follows [25, 27]:

$$\rho\left(\lambda_{1}\frac{\partial}{\partial t}+1\right)\frac{\partial u}{\partial t}=\mu\frac{\partial^{2}u}{\partial y^{2}}+g(\rho\beta_{T})\left(1+\lambda_{1}\frac{\partial}{\partial t}\right)[T-T_{\infty}]$$
$$+g(\rho\beta_{C})\left(1+\lambda_{1}\frac{\partial}{\partial t}\right)[C-C_{\infty}]-\left(1+\lambda_{1}\frac{\partial}{\partial t}\right)B_{0}^{2}\sigma u,$$
(1)

$$k\frac{\partial^2 T}{\partial y^2} - \frac{\partial q_r}{\partial y} - Q_0[T - T_\infty] - \left(\rho c_p\right)\frac{\partial T}{\partial t} = 0, \qquad (2)$$



FIGURE 1: Flow geometry.

$$D_m \frac{\partial^2 C}{\partial y^2} + \frac{D_m k_T}{T_m} \frac{\partial^2 T}{\partial y^2} - \frac{\partial C}{\partial t} = 0, \qquad (3)$$

and related conditions

for
$$t = 0 \Rightarrow u = 0, T = T_{\infty}, \quad C = C_{\infty},$$
 (4)

$$u - \gamma_1 \frac{\partial u}{\partial y}\Big|_{y=0} = V_0 f(t), \quad T = T_w, \quad C = C_w, \quad y = 0,$$
(5)

$$u \to 0, T \to T_{\infty}, \quad C \to C_{\infty}, \quad y \to \infty.$$
 (6)

The radiated flux from Equation (2) is approximated by using the Roseland approach [49, 50] for the minor temperature difference between the temperature of the fluid and the free stream temperature [51, 52].

$$k[N_r+1]\left(\frac{\partial^2}{\partial y^2} - \left(\rho c_p\right)\frac{\partial}{\partial t}\right)T(y,t) = Q_0[T(y,t) - T_\infty],$$
(7)

where $N_r = \frac{16\sigma_1 T_{\infty}^3}{3kk_1}$ is the radiation parameter. Nondimensional relations [25]

$$u^{*} = \frac{u}{V_{0}}, \quad y^{*} = \frac{yV_{0}}{\nu}, \quad t^{*} = \frac{V_{0}^{2}}{\nu}t, \quad C^{*} = \frac{C - C_{\infty}}{C_{w} - C_{\infty}}, \quad T^{*} = \frac{T - T_{\infty}}{T_{w} - T_{\infty}},$$
$$Q^{*} = \frac{\nu Q_{0}}{(\rho c_{p})V_{0}^{2}}, \quad \gamma_{1}^{*} = \frac{V_{0}}{\nu}\gamma_{1}, \quad f^{*}(t^{*}) = f\left(\frac{\nu}{V_{0}^{2}}t^{*}\right), \quad \lambda = \frac{V_{0}^{2}}{\nu}\lambda_{1},$$
(8)

with $V_0 = [\nu g \beta_T (T_w - T_\infty)]^{1/3}$ is specific velocity, and after using Equations (1)–(7) and Equation (8) dimensionless model takes the following form:

$$\left(\lambda\frac{\partial}{\partial t}+1\right)\frac{\partial u}{\partial t}=\frac{\partial^2 u}{\partial y^2}+\left(1+\lambda\frac{\partial}{\partial t}\right)[T-Mu+NC],$$
(9)

$$\frac{\partial T}{\partial t} = \frac{1}{\Pr_{\text{eff}}} \frac{\partial^2 T}{\partial y^2} - QT, \qquad (10)$$

$$\operatorname{ScSr}\frac{\partial^2 T}{\partial y^2} = \operatorname{Sc}\frac{\partial C}{\partial t} - \frac{\partial^2 C}{\partial y^2},\tag{11}$$

and corresponding dimensionless initial conditions and boundary conditions

$$u = 0, T = 0, C = 0, t = 0,$$
 (12)

$$f(t) = u - \gamma_1 \frac{\partial u}{\partial y}|_{y=0}, \quad T = 1, C = 1, y = 0,$$
(13)

$$u \to 0, T \to 0, C \to 0, y \to \infty,$$
 (14)

$$N = \frac{\rho \beta_C [C_w - C_\infty]}{\rho \beta_T [T_w - T_\infty]}, \quad \Pr_{\text{eff}} = \frac{\Pr}{Nr + 1}, \quad M = \frac{\nu \sigma B_0^2}{\rho V_0^2}, \\ \text{Sc} = \frac{\nu}{D_m}, \quad \text{Sr} = \frac{D_m k_T [T_w - T_\infty]}{\nu T_m [C_w - C_\infty]}, \quad Q = \frac{\nu Q_0}{\rho c_p V_0^2},$$
(15)

where N is the ratio of the thermal Grashof number to the mass Grashof number, Pr_{eff} effective Prandtl number, M is a nondimensional magnetic parameter, Sc is the Schmidt number, Q is the nondimensional heat generation parameter, and Sr is the Soret effect parameter.

3. Classical Solution of the Model

3.1. Temperature. Equation (10) is reduced to an ordinary differential equation as follows:

$$Pr_{\rm eff}q\overline{T}(y,q) + Q\overline{T}(y,q) = \frac{\partial^2\overline{T}(y,q)}{\partial y^2}.$$
 (16)

Equation (16) is solved by conditions given below:

$$T(\infty, q) = 0, \overline{T}(0, q) = q^{-1}, \tag{17}$$

and solution transformed for temperature is as follows:

$$\overline{T}(y,q) = \frac{1}{q} e^{\left[-y\sqrt{Pr_{\text{eff}}}\sqrt{Q+q}\right]}.$$
(18)

3.2. Concentration. Equation (11), by using the Laplace transform, is reduced to an ODE as follows:

$$\operatorname{Scq}\overline{C}(y,q) = \frac{\partial^2 \overline{C}(y,q)}{\partial y^2} + \operatorname{Sr}\frac{\partial^2 \overline{T}(y,q)}{\partial y^2}.$$
 (19)

Equation (19) is solved by the conditions as follows:

$$C(\infty, q) = 0, \overline{C}(0, q) = q^{-1}.$$
(20)

The solutions are given below:

$$\overline{C}(y,q) = \frac{1}{q} \exp\left(-y\sqrt{Scq}\right) + \frac{ScSrPr_{eff}(Q+q)}{\left[(Pr_{eff} - Sc)q + QPr_{eff}\right]q} \exp\left[-y\sqrt{Scq}\right] . \quad (21)$$
$$-\frac{ScSrPr_{eff}(Q+q)\exp\left[-y\sqrt{Pr}_{eff}(Q+q)\right]}{q[q(Pr_{eff} - Sc) + Pr_{eff}Q]}$$

3.3. Velocity Field. Equation (9), by using the Laplace transform, is reduced to the following:

$$\begin{bmatrix} 1 + \lambda \left(\frac{k_1(\alpha)}{q} + k_0(\alpha)\right) q^{\alpha} \end{bmatrix} q \overline{u}(y, q) = \frac{\partial^2 \overline{u}(y, q)}{\partial y^2} \\ + \begin{bmatrix} 1 + \lambda \left(\frac{k_1(\alpha)}{q} + k_0(\alpha)\right) q^{\alpha} \end{bmatrix} \\ \times [\overline{T}(q, y) - M \overline{u}(q, y) + N \overline{C}(q, y)].$$
(22)

Equation (22) is solved by the following transformed condition:

$$\overline{u}(\infty,q) = 0, \overline{u}(0,q) - \gamma \frac{\partial \overline{u}(y,q)}{\partial y}\Big|_{y=0} = f(q),$$
(23)

and its solution is as follows:

$$\overline{u}(y,q) = \frac{F(q)e^{-y\sqrt{[1+\lambda q][M+q]}}}{1+\gamma_1\sqrt{[1+\lambda q][M+q]}} + \frac{[1+\lambda q]\left[1+\gamma_1\sqrt{Pr_{\text{eff}}(Q+q)}\right]}{[Pr_{\text{eff}}(Q+q)-(M+q)(1+\lambda q)]q} \\
\times \left[1 - \frac{N\text{Sc}\text{Sr}\text{Pr}_{\text{eff}}(Q+q)}{[Pr_{\text{eff}} - \text{Sc}]q + QPr_{\text{eff}}}\right] \left[\frac{e^{-y\sqrt{[1+\lambda q][M+q]}}}{1+\gamma_1\sqrt{[1+\lambda q][M+q]}} - \frac{e^{-y\sqrt{Pr}_{\text{eff}}(Q+q)}}{1+\gamma_1\sqrt{Pr}_{\text{eff}}[Q+q]}\right] \\
+ \frac{N(\lambda q+1)[1+\gamma_1\sqrt{\text{Sc}q}]}{[\text{Sc}q - (q+M)[\lambda q+1]]q} \left[1 + \frac{\text{Sc}\text{Pr}_{\text{eff}}\text{Sr}[Q+q]}{q(Pr_{\text{eff}} - \text{Sc}) + QPr_{\text{eff}}}\right] \\
\times \left[\frac{e^{-y\sqrt{[\lambda q+1][M+q]}}}{1+\gamma_1\sqrt{[\lambda q+1][M+q]}} - \frac{e^{-y\sqrt{\text{Sc}q}}}{1+\gamma_1\sqrt{\text{Sc}q}}\right].$$
(24)

4. Generalization with CPC

In this section, the flow model is generalized by introducing the generalized constitutive relations for momentum, heat, and mass fluxes. The generalization is made by newly developed fractional derivative, known as CPC fractional derivative denoted by $^{CPC}D_t^{\alpha}$ and defined as follows [48]:

$${}^{\rm CPC}D_t^{\alpha}f(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t [k_1(\alpha)f(s) + k_0(\alpha)f'(\tau)](t-s)^{-\alpha}ds ,$$
(25)

and its Laplace transform is defined as follows [48]:

$$\pounds\{{}^{\mathrm{CPC}}D_t^{\alpha}f(t)\} = \left(\frac{k_1(\alpha)}{q} + k_0(\alpha)\right)q^{\alpha}\overline{f}(q) - k_0(\alpha)q^{\alpha-1}f(0).$$
(26)

The momentum equation

$$\left(\lambda\frac{\partial}{\partial t}+1\right)\frac{\partial u}{\partial t}=\frac{\partial\tau_{\alpha}(y,t)}{\partial y}+\left(\lambda\frac{\partial}{\partial t}+1\right)[T-Mu+NC],$$
(27)

where $\tau_{\alpha}(y, t)$ is the shared stress is given by the following generalized constitutive relation

$$\tau_{\alpha}(y,t) = {}^{\text{CPC}} D_t^{\alpha} \frac{\partial u(y,t)}{\partial y}.$$
(28)

The equation for the temperature profile in generalized form is as follows:

$$Pr_{\rm eff} \frac{\partial T(y,t)}{\partial t} = -\frac{\partial q_{\beta}(y,t)}{\partial y} - Pr_{\rm eff}QT(y,t), \qquad (29)$$



FIGURE 2: Inverse of temperature (a) and concentration (b) fields.

and $q_{\beta}(y, t)$ is given in the equation below:

$$q_{\beta}(y,t) = -^{\text{CPC}} D_t^{\beta} \frac{\partial T(y,t)}{\partial y}.$$
(30)

The diffusion balance in terms of generalized mass flux is as follows:

$$\operatorname{Sc}\frac{\partial C(y,t)}{\partial t} = -\frac{\partial q_{\gamma}(y,t)}{\partial y} + \operatorname{ScSr}\frac{\partial^2 T(y,t)}{\partial y^2}, \quad (31)$$

where the generalized mass flux is as follows:

$$q_{\gamma}(y,t) = -^{\text{CPC}} D_t^{\gamma} \frac{\partial C(y,t)}{\partial y}.$$
 (32)

Using the generalized constitutive relations for stress, heat flux, and mass flux from Equations (28), (30), and (32) into Equations (27), (29), and (31), respectively

$$\left(\lambda\frac{\partial}{\partial t}+1\right)\frac{\partial u}{\partial t} = \frac{\partial\left[C^{\text{PC}}D_t^{\alpha}\frac{\partial u(y,t)}{\partial y}\right]}{\partial y} + \left(\lambda\frac{\partial}{\partial t}+1\right)[T(y,t) - Mu(y,t) + NC(y,t)],$$
(33)

$$\frac{\partial T(y,t)}{\partial t} = -\frac{1}{Pr_{\text{eff}}} \frac{\partial \left[-^{\text{CPC}} D_t^{\beta} \frac{\partial T(y,t)}{\partial y}\right]}{\partial y} - QT(y,t), \quad (34)$$

and

$$\operatorname{Sc}\frac{\partial C}{\partial t} = -\frac{\partial \left[-^{\operatorname{CPC}}D_t^{\gamma}\frac{\partial C(y,t)}{\partial y}\right]}{\partial y} + \operatorname{ScSr}\frac{\partial^2 T}{\partial y^2}.$$
(35)

5. Generalized Solution to the Problem

5.1. Generalized Temperature Field. Equation (34) is transformed as below:

$$q\overline{T}(y,q) = \frac{1}{Pr_{\text{eff}}} \left(\frac{k_1(\beta)}{q} + k_0(\beta) \right) q^{\beta} \frac{\partial^2 \overline{T}(y,q)}{\partial y^2} - Q\overline{T}(y,q), \quad y > 0.$$
(36)

Equation (36) is solved under the conditions in Equation (17) is as follows:

$$\overline{T}(y,q) = \frac{1}{q} \exp\left[-y \sqrt{\frac{Pr_{\text{eff}}q^{1-\beta}(q+Q)}{[k_1(\beta)+k_0(\beta)q]}}\right].$$
(37)

In Equation (37), the expressions under the root are complicated, and it is not an easy task to invert the Laplace transform. Therefore, the inversion of the Laplace is obtained by executing Stehfest's algorithm [53] and Tzou's [54], and the outcomes of the algorithms are presented in Figure 2(a).

5.2. Generalized Concentration Field. From Equation (35)

Equation (38) is solved under the transformed boundary conditions in Equation (20) as follows:

$$\operatorname{Scq}\overline{C}(y,q) = \left(\frac{k_1(\gamma)}{q} + k_0(\gamma)\right)q^{\gamma}\frac{\partial^2\overline{C}(y,q)}{\partial y^2} + \operatorname{ScSr}\frac{\partial^2\overline{T}(y,q)}{\partial y^2}, \quad y > 0.$$
(38)

$$\overline{C}(y,q) = \frac{1}{q} \exp\left[-y\sqrt{\frac{\mathrm{Sc}q^{2-\gamma}}{[k_{1}(\gamma) + k_{0}(\gamma)q]}}\right] + \frac{\mathrm{Sc}\mathrm{Sr}\mathrm{Pr}_{\mathrm{eff}}(Q+q)q^{1-\gamma}}{[(Pr_{\mathrm{eff}} - \mathrm{Sc})q + QPr_{\mathrm{eff}}][k_{1}(\gamma) + k_{0}(\gamma)q]q} \exp\left[-y\sqrt{\frac{\mathrm{Sc}q^{2-\gamma}}{[k_{1}(\gamma) + k_{0}(\gamma)q]}}\right] .$$

$$-\frac{\mathrm{Sc}\mathrm{Sr}\mathrm{Pr}_{\mathrm{eff}}(Q+q)q^{1-\gamma}}{[(Pr_{\mathrm{eff}} - \mathrm{Sc})q + QPr_{\mathrm{eff}}][k_{1}(\gamma) + k_{0}(\gamma)q]q} \exp\left[-y\sqrt{\frac{Pr_{\mathrm{eff}}q^{1-\gamma}(q+Q)}{[k_{1}(\gamma) + k_{0}(\gamma)q]}}\right].$$
(39)

Equation (39) is inverted by algorithms and shown in Figure 2(b) [53, 54].

5.3. *Generalized Velocity Field*. Equation (33) is reduced to an ODE by using Laplace transform as follows:

$$(1+\lambda q)q\overline{u} = \left(\frac{k_1(\alpha)}{q} + k_0(\alpha)\right)q^{\alpha}\frac{\partial^2\overline{u}}{\partial y^2} + [\lambda q + 1]\left[\overline{T} - M\overline{u} + N\overline{C}\right],$$
(40)

$$\frac{\partial^{2}\overline{u}(y,q)}{\partial y^{2}} - \frac{(1+\lambda q)(q^{2-\alpha}+M)}{[k_{1}(\alpha)+k_{0}(\alpha)q]}\overline{u}(y,q) \\
= -\frac{(1+\lambda q)q^{1-\alpha}}{[k_{1}(\alpha)+k_{0}(\alpha)q]} \left[\overline{T}(y,t) + N\overline{C}(y,q)(y,q)\right].$$
(41)

Equation (41) is solved subject to the condition in Equation (23) as follows:

$$\begin{split} \overline{u}(y,q) &= \frac{F(q) \exp\left[-y \sqrt{\frac{[\lambda q+1](q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}\right]}{1 + \gamma_1 \sqrt{\frac{(1+\lambda q)(q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}} + \frac{(1+\lambda q) \left(1 + \gamma_1 \sqrt{\frac{Pr_{eff}q^{1-\beta}(q+Q)}{[k_1(\beta) + k_0(\beta)q]}}\right)}{[(q+Q) Pr_{eff} - (M+q^{2-\beta})(1+\lambda q)]q} \\ &\times \left[1 - \frac{NSCSrPr_{eff}(Q+q)q^{-\beta}}{[(Pr_{eff} - Sc)q + QPr_{eff}][k_1(\beta) + k_0(\beta)q]}\right] \\ &\times \left[\frac{\exp\left(-y \sqrt{\frac{(1+\lambda q)(q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}\right)}{1 + \gamma_1 \sqrt{\frac{(1+\lambda q)(q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}} - \frac{\exp\left(-y \sqrt{\frac{Pr_{eff}q^{1-\beta}(q+Q)}{[k_1(\beta) + k_0(\beta)q]}}\right)}{1 + \gamma_1 \sqrt{\frac{Pr_{eff}q^{1-\beta}(q+Q)}{[k_1(\beta) + k_0(\beta)q]}}}\right] \\ &+ \frac{N[\lambda q+1]\left[1 + \gamma_1 \sqrt{\frac{Scq^{2-\alpha}}{[k_1(\alpha) + k_0(\alpha)q]}}\right]}{q[Scq - (q+M)(\lambda q+1)]} \left[1 + \frac{ScPr_{eff}Sr(Q+q)q^{-\gamma}}{[q[Pr_{eff} - Sc] + QPr_{eff}][k_1(\gamma) + k_0(\gamma)q]}\right]} \\ &\times \left[\frac{\exp\left(-y \sqrt{\frac{(1+\lambda q)(q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}\right)}}{1 + \gamma_1 \sqrt{\frac{Scq^{2-\gamma}}{[k_1(\gamma) + k_0(\gamma)q]}}}\right] \left[1 + \frac{ScPr_{eff}Sr(Q+q)q^{-\gamma}}{[q[Pr_{eff} - Sc] + QPr_{eff}][k_1(\gamma) + k_0(\gamma)q]}\right]}\right] \\ &\times \left[\frac{\exp\left(-y \sqrt{\frac{(1+\lambda q)(q^{2-\alpha} + M)}{[k_1(\alpha) + k_0(\alpha)q]}}\right)}}{1 + \gamma_1 \sqrt{\frac{Scq^{2-\gamma}}{[k_1(\gamma) + k_0(\gamma)q]}}} - \frac{\exp\left(-y \sqrt{\frac{Scq^{2-\gamma}}{[k_1(\gamma) + k_0(\gamma)q]}}\right)}{1 + \gamma_1 \sqrt{\frac{Scq^{2-\gamma}}{[k_1(\gamma) + k_0(\gamma)q]}}}\right]. \end{split}$$

Equation (42) in its present form cannot invert in the domain, so its inverse is obtained numerically by the suitable algorithm known as Stehfest's algorithm [53] and Tzou's [54], and the outcomes of this process are presented in and presented in Figures 3(a) and 3(b) for no-slip condition and slip conditions.

6. Results and Discussion

The motion of Maxwell fluid on a flat surface is discussed by considering the effect of the thermodiffusion subject to the first-order slip at the boundary. The effect of heat generation and radiation is also considered with the effect of the



FIGURE 3: Inverse of the velocity field for (a) for no slip and (b) for slip.



FIGURE 4: Velocity for variation of α (a) for no slip and (b) for slip N = 0.5, Pr = 1.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$.

magnetic field of constant magnitude. The generalized heat and mass fluxes are considered, and generalization is made by considering the new hybrid fractional derivative. The graphical illustrations for different parametric values are done using the same graphics of velocity against *y*.

The primary goal of this research is to study the objectivity of the fractional parameter over the velocity field. For this purpose, Figures 4(a) and 4(b) are plotted, and the impact of a fractional parameter over the flow is explained for slip and no slip. The outlines of profiles present an elevating trend for enhancing values of fractional parameters, and this peak in the velocity profiles is seen because of the power law kernel of fractional derivative. In the case of the CPC fractional derivative, the kernel of the operator obeys the power law. Moreover, the subjectivity of velocity for the variation of the other parameter is also explained graphically. The parameter is referred to the relative effect of bouncy forces. Figures 5 and 6 show the effect on the velocity of Maxwell fluid for both positive and negative values. The positive value of N means there is a supporting bouncy for the fluid flow, and the negative value means there is an opposing bouncy to the fluid flow. The results of positive values over fluid velocity is addressed in Figure 7. As Q > 0 refers to the heat absorption and more energy in the flow domain due to this fluid motion increases for the growing values of Q as shown in Figure 7. The negative value of Q refers to the heat generation in the flow domain, and some energy is lost due to this fluid velocity decreases, which is revealed in Figure 8.

In Figure 9, the influence of Sc is discussed, and a decreasing trend is seen against the elevating value of Sc because for the elevating value of Sc, momentum diffusivity is dominant; therefore, the velocity field decreases for the increasing values of Sc. The Soret effect Sr over the velocity field is seen in Figure 10, and from the outline of Figure 10, it



FIGURE 5: Effect of *N* positive (a) and negative (b) over velocity with no slip $\alpha = 0.5$, Pr = 1.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$.



FIGURE 6: Effect of *N* positive (a) and negative (b) over velocity in the presence of slip, $\alpha = 0.5$, Pr = 1.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$.



FIGURE 7: Effect of positive Q over velocity (a) for no slip and (b) for slip $\alpha = 0.5$, Pr = 1.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$.



FIGURE 8: Effect of negative *Q* over velocity (a) for no slip and (b) for slip $\alpha = 0.5$, Pr = 1.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$.



FIGURE 9: Effect of Sc over velocity (a) for no slip and (b) for slip N = 0.5, Pr = 1.5, Q = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$, $\alpha = 0.5$.



FIGURE 10: Effect of Sr over velocity (a) for no slip and (b) for slip N = 0.5, Pr = 1.5, Sc = 0.5, Q = 0.5, M = 0.5, $\lambda = 2.5$, $\alpha = 0.5$.



FIGURE 11: Effect of Pr_{eff} over velocity (a) for no slip and (b) for slip N = 0.5, Q = 0.5, Sc = 0.5, Sr = 1.5, M = 0.5, $\lambda = 2.5$, $\alpha = 0.5$.



FIGURE 12: Velocity for Sr variation (a) for no slip and (b) for slip N = 0.5, Q = 0.5, Sr = 1.5, Pr = 1.5, $\lambda = 2.5$, $\alpha = 0.5$.



FIGURE 13: Velocity comparison with Fetecau et al. [25] (a) for no slip and (b) for slip N = 0.5, Q = 0.5, Sc = 0.5, Sr = 1.5, M = 0.5, Pr = 1.5.

is revealed that elevating Sr accelerates the fluid flow. In Figure 11, the subjectivity of effective Pr_{eff} is illustrated, and from Figure 11, it is evident that the flow velocity falls for ascending values Pr_{eff} . A larger value of Pr_{eff} refers to the more momentum diffusivity in the flow domain, which slows down the velocity of the fluid. Figure 12 is sketched to observe the potentness of magnetic parameter M. The pattern of Figure 12 reveals the decreasing trend for the elevating value of M. The effects of a magnetic field in the flow creates some resistive force that opposes the fluid flow that is why fluid velocity decreases for the increasing values of a magnetic parameter.

As it is stated, our prime motive was to make advancements in the research work done by Fetecau et al. [25] for a bigger class of fluid, namely Maxwell fluid. Moreover, it also includes an additional aspect of fractional instead of ordinary derivative. Therefore, the obtained result for velocity is also compared with the result of velocity obtained in [25] graphically. For this purpose, the velocity profiles are sketched in Figure 13 by letting the Maxwell parameter $\lambda = 0$ and fractional parameter $\alpha = 1$ for both slip and nonslip. The overlapping graphic profiles show the validation of our obtained result for velocity.

7. Conclusions

Thermodiffusion is a physical phenomenon that occurs because of the higher temperature and slanting distribution of the mixture. Thermodiffusion results in the isotope separation. In the present study, analytical results for mass and heat transfer flow of Maxwell fluid over a flat plate are considered by taking the effect of the first order slip at the boundary with the fractional derivative, which is known as the CPC fractional derivative. The impacts of radiation and generation of heat are also taken into consideration, along with the effect of a magnetic field of constant magnitude. The pearlized results for velocity, concentration, and temperature are obtained. The graphical illustrations are done using the same graphics of velocity for both cases, slip and no-slip effects. Moreover, this research work may extend to more complex fluids like Oldroyd-B fluid. The conclusions given below are drawn for the present research study.

- The fluid flows with an increasing velocity for the variation of α, β, γ, and Sr.
- (2) Velocity for Sc, and slip parameter γ_1 is a decreasing function.
- (3) For positive *N* velocity exhibits an enhancing posture the decerned trend for a negative value of *N*.
- (4) For positive *Q* fluid speeds up, and the negative fluid flow slows down.
- (5) The application of the CPC fractional derivative is a far better choice to obtain the generalized solution of the velocity field.
- (6) The advantage of the fractional model is nonlocality and flexibility, which is why one can fit the data according to desired results by the variation of the order of fractional derivatives.

Nomenclature

er
deriva-
Grashof
ıber

 σ : Current density.

Data Availability

The data used to support the findings of this study are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that there are no conflicts of interest regarding the publication of this paper.

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