

Research Article On Some Properties of Whyburn Spaces

Abdelwaheb Mhemdi^[b],¹ Sami Lazaar,² and Khedidja Dourari³

¹Prince Sattam Bin Abdulaziz University, College of Sciences and Humanities in Aflaj, Al-Kharj, Saudi Arabia ²Taibah University, Medina, Saudi Arabia

³Tunis El Manar University, Tunis, Tunisia

Correspondence should be addressed to Abdelwaheb Mhemdi; a.mhemdi@psau.edu.sa

Received 23 November 2021; Revised 25 December 2021; Accepted 8 January 2022; Published 9 February 2022

Academic Editor: Ahmed Mostafa Khalil

Copyright © 2022 Abdelwaheb Mhemdi et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

1. Introduction

Alexandroff space is a topological space such that its collection of open sets is closed under arbitrary intersection. In 1937, Alexandroff introduced these spaces with the name of "Diskrete Räume" [1]. In [2], Steiner has named them principal spaces. Alexandroff spaces are used and applied in different domains like geometry, theoretical physics, and diverse branches of computer sciences. After that, Alexandroff spaces played an important role in digital topology (cofinite spaces) (see [3–6]).

The specialization quasiorder of an Alexandroff space is defined by

$$x \le y \Longleftrightarrow x \in \{y\}. \tag{1}$$

Now, if \leq is a quasiorder on space *X* then the set of all supersets \mathscr{B} : = { $x \uparrow$: $x \in X$ } ($x \uparrow$: = { $y \in X$: $x \leq y$ }.) forms a basis of an Alexandroff topology Y (\leq) on *X*. In this case, the closure $\overline{\{x\}}$ is exactly the downset $x \downarrow$: = { $y \in X$: $y \leq x$ }. We denote by $v(x) = x \uparrow$ the minimal neighborhood of *x*. For more information on Alexandroff spaces you can see [7–13].

In [14], Echi introduced a particular class of Alexandroff spaces named primal spaces. (X, τ) is called a primal space if there exists a map $f: X \longrightarrow X$ such that $\tau = Y(f)$, where Y(f) is the collection of all f-invariant subsets of X (for more information see [14, 15]). In [16], the authors characterized maps f such that the primal space (X, Y(f)) is submaximal or door.

This paper is devoted to characterizing Alexandroff spaces which are submaximal, door, *n*-resolvable, Whyburn, and weakly Whyburn. Some useful examples are presented

and commented and finally, all results on primal spaces are deduced. In the first section of this paper, we will give characterizations of Alexandroff spaces to be a submaximal, door, and *n*-resolvable. The second section is devoted to introducing and characterizing topological spaces, called quasi-Whyburn spaces, such that their T_0 -refections are Whyburn. Particularly, the case of Alexandroff spaces is totally deduced in this particular class of spaces.

2. Submaximal, Door, and *n*-Resolvable Alexandroff Spaces

We know that a submaximal space is a topological space in which all dense subsets are open.

The following theorem characterizes submaximal spaces [17].

Theorem 1. A topological space X is submaximal if and only if for every $Y \subseteq X$, the subset $\overline{Y} \setminus Y$ is closed equivalently for every $Y \subseteq X$ and the subset $\overline{Y} \setminus Y$ is closed and discrete.

Now, before giving the first main result of this section, some useful examples are presented and commented.

Example 1

(1) Let *a*, *b*, *c*, and *d* be distinct points and $X = \{a, b, c, d\}$ equipped with the topology $\tau = \{\emptyset, X, \{a, b, c\}, \{b\}, \{c\}, \{b, c, d\}, \{b, c\}\}$. We can find the specialization quasiorder as follows: $\overline{\{a\}} = \{a\}, \overline{\{d\}} = \{d\}$, $\overline{\{b\}} = \{a, b, d\}$, and $\overline{\{c\}} = \{a, c, d\}$ so that $a \le b, d \le b$, $a \le c$, and $d \le c$.

We have (X, τ) is an Alexandroff space which is submaximal.

(2) Consider the set N of natural numbers and for each n ∈ N, let O_n = {0, 1, 2, ..., n}. We equip the space N with the topology τ = {Ø, N, {1}} ∪ {O_n, n ∈ N}.

The Alexandroff space \mathbb{N}, τ is not submaximal. In fact, $\mathbb{N} \setminus \{2\}$ is a dense subset which is not open.

The previous examples give a motivation to investigate conditions allowing Alexandroff spaces to be submaximal.

The answer is given by the following theorem.

Theorem 2. Let X be an Alexandroff space. Then, the following statements are equivalent:

- (1) X is submaximal
- (2) The specialization quasiorder is an order and every chain in its graph has a length less than or equal to 2

Proof

(i) [(1)⇒(2)]. Suppose that X is submaximal. If x, y are two elements of X satisfying x ≤ y and y ≤ x then x ∈ y and y ∈ x, which imply that {x} = {y}. Using the fact that every submaximal space is T₀, we deduce that x = y and then the specialization quasiorder is an order.

Now, suppose that $\underline{x < y < z}$. If $Y = \{x, z\}$, then $y \in \overline{Y \setminus Y}$ and $x \in \overline{y \subseteq \overline{Y \setminus Y}}$. Since $x \notin \overline{Y \setminus Y}$ then it is not closed.

(ii) $[(2) \Longrightarrow (1)]$. If *Y* is a subset of *X*, we denote $Y_c = \{a \in Y : \overline{\{a\}} \neq \{a\}\}$. Using 2), for every $a \in Y \setminus Y_c$ and for any $b \in \overline{\{a\}} \setminus \{a\}$, $\{b\}$ is closed. Since *X* is an Alexandroff space, then

$$\overline{Y} = \bigcup_{a \in Y} \overline{\{a\}}$$
$$= A \cup \left(\bigcup_{a \in Y - Y_c} \overline{\{a\}} \setminus \{a\} \right),$$
(2)

so that $\overline{Y} \setminus Y$ is closed and then X is submaximal. \Box

Corollary 1 (see [14], Theorem 4.1)

If (X, f) is a flow in set, then (X, Y(f)) is a submaximal space if and only if $f^2 = f$.

Definition 1. Let X be a topological space. X is called a door space if any subset of X is open or closed.

Now, we state straightforward remarks.

Remark 1

 The example cited in Example 1 (1)provides a space that is not a door. Indeed, the subset {a, c} is neither open nor closed. (2) Let X be the set {(1/n), nN*} ∪ {0} equipped with the topology defined as follows: for each x ∈ X \{0}, v(x) = {x} and v(0) = X.

Hence, every subset of X not containing 0 is open. Yet, every subset of X containing 0 is closed.

Therefore, X is an Alexandroff door space.

Considering Alexandroff door spaces, the second main result of this section is given by the following theorem. But, first, we need to recall increasing and decreasing sets.

The increasing hull of a set A in a quasiordered set (X, \leq) is $i(A) = \{x \in X : x \geq a \text{ for some } a \in A\}$. A set A is increasing if A = i(A). The set $i(\{x\})$ may be written as i(x). Decreasing hulls and decreasing sets are defined dually. The closed sets in an Alexandroff space are just the decreasing sets for the specialization quasiorder, and the open sets are just the increasing sets.

Theorem 3. Let X be an Alexandroff space and \leq is its specialization order. Then, the following statements are equivalent:

- (1) X is a door space
- (2) The length of every chain in the graph of ≤ is not greater than 2 and all chains of length 2 contain a common point which must be a maximal point M or a minimal point m

Proof

(i) [(2)⇒(1)]. Suppose that the common point is a minimal point *m*. Let *Y* be a nonclosed subset of *X*. So that *Y* is not decreasing in (*X*, ≤) equivalently there is *x* ∈ *Y* such that *x* ∈ *i*(*m*) and *m* ∉ *A*. Since a subset which not contains *m* is increasing, therefore, it is open.

We work dually if the common point is a maximal point.

(ii) [(1)⇒(2)]. By contradiction suppose that either there exist *a* < *b* < *d* or *a* < *b* and *c* < *d* of length 2 with no common point. In these cases, we have always {*a*, *d*} is not increasing and not decreasing, thus it is not open and not closed which is a contradiction. This fact completes the proof.

Corollary 2 (see [16], Theorem 4.3)

If (X, f) is a flow in set, then (X, Y(f)) is a door space if and only if $|f(Fix(f)^c)| \le 1$.

Now, we will give a study of n – resolvable Alexandroff spaces.

First, let us recall the definition of n – resolvable spaces. If X is a topological space, then it is called n – resolvable (n > 1) if there exist n-many mutually disjoint dense sets of X. A 2-resolvable space is called a resolvable space. Hewitt added also the condition "has no isolated points" to the definition of resolvable spaces. Also, a topological space is n – resolvable if and only if it is the union of n-many mutually disjoint dense subsets. Stone [18] characterizes Alexandroff spaces which are *n*-resolvable in the following theorem.

Theorem 4 (see [18]). Let (X, \leq) be a quasiordered set. Then, we have equivalence between the following statements:

(1) X admit a partition into n mutually disjoint cofinal sets

(2) $\forall x \in X$, $x \uparrow$ has at least n elements

We note that, for every subset Y of an Alexandroff space X, we have equivalence between the following items:

(1) Y is dense in X

- (2) $X = \overline{Y} = \downarrow Y$
- (3) $\forall x \in X, \exists a \in Y \text{ such that } x \leq a$
- (4) *Y* is cofinal in (X, \leq)

This allows us to rephrase Stone's result as follows.

Theorem 5. Let (X, τ) be an Alexandroff space and \leq is its specialization quasiorder. Then, the following statements are equivalent:

(1) " \leq " is n-resolvable

- (2) $\forall x \in X, x \uparrow$ contains at least n elements
- (3) There is no maximal element in (X, \leq)
- (4) (X, τ) has no isolated points

We recall that the T_0 -reflection of a topological space X is the quotient space denoted by $T_0(X)$: = X/ ~ obtained from the equivalence relation defined on X by $x \sim y$ if and only if $\overline{\{x\}} = \overline{\{y\}}$.

Corollary 3. Let X be an Alexandroff space. Then the following statements are equivalent:

- (1) X is n-resolvable
- (2) $\forall x \in X, x \uparrow$ contains at least n distinct points
- (3) Every maximal element x in the T₀-refection T₀(X) arises from a cycle x = x₁ < x₂ < x₃ < ··· < x_n < x_n + 1 = x containing at least n distinct points x_i

Now, we shed some light on interesting examples.

Example 2

- (1) Consider the set \mathbb{Z} of all integers with the usual order \leq . For any integer $n \geq 2$ let $A_k = \{j \in \mathbb{Z}: j = k \mod n\}$. Then $A_0, A_1, \ldots, A_{n-1}$ are mutually disjoint dense sets of the Alexandroff space $(\mathbb{Z}, Y(\leq))$, showing that this space is *n*-resolvable for every $n \geq 2$. Indeed, it is obvious that $n\uparrow$ is infinite for each $n \in \mathbb{Z}$.
- (2) Let ≤ be the inverse order of N where N is the set of all natural numbers. In the Alexandroff space (N, Y(≤)), every set A of X is dense if and only if 0 ∈ A. Therefore, (N, Y(≤)) is not a resolvable space. In fact, we note that |0↑| = 1.

3. Alexandroff Spaces Which Are Whyburn and Quasi-Whyburn Spaces

Let *X* be a topological space and *F* be a subset of *X*. Then, *F* is called almost closed if and only if $\overline{F} \setminus F = \{x\}$ for some $x \in X$. We use the notation $F \longrightarrow x$.

The notion of Whyburn spaces was first introduced as accessibility spaces by G.T. Whyburn in his famous paper [19]. Hence, a Whyburn space is a topological space *X* satisfying

$$Y \subseteq X,$$

$$\overline{Y} \neq Y,$$

$$\in \overline{Y} \setminus Y \Longrightarrow \exists B \subseteq Y \text{ s.t. } \overline{B} \setminus Y = \{x\}.$$
(3)

A topological space X is called weakly Whyburn [20] if

х

$$Y \subseteq X,$$

$$\overline{Y} \neq Y \Longrightarrow \exists B \subseteq Y \text{ s.t. } \overline{B} \setminus Y \text{ is a singleton.}$$
(4)

We denote the class of all Whyburn spaces (resp., weakly Whyburn spaces) by AP-spaces (resp., WAP-spaces) [21–23].

3.1. Quasi-Whyburn Spaces. A continuous map q from a topological space X to a topological space Y is said to be a quasihomeomorphism if $U \mapsto q^{-1}(U)$ defines a bijection between the collection of all open sets of Y and the collection of all open sets of X [24].

We can see easily that the canonical surjection $\mu_X: X \longrightarrow T_0(X)$ is a quasihomeomorphism. More precisely, μ_X is an onto quasihomeomorphism, and in this case, the following results are useful.

Lemma 1 (see [25]). Let μ : $X \longrightarrow Y$ be continuous onto the map. Then, μ is a quasihomeomorphism if and only if μ is an open map and $q^{-1}(q(A)) = A$ for every open subset A of X; equivalently, μ is a closed map and $q^{-1}(q(A)) = A$ for every closed subset A of X.

Lemma 2 (see [16]). A quasihomeomorphism $\mu: X \longrightarrow Y$ is onto if and only if $\mu^{-1}(\overline{A}) = \overline{\mu^{-1}(A)}$ for every subset A of Y.

If *X* is a topological space, $x \in X$, and $Y \subseteq X$, we take the notations in [16]. In that paper, authors denote by $d_0(x)$ the subset $\{y \in X: \{x\} = \{y\}\}$ and by $d_0(Y)$ the union of $d_0(a)$ for all $a \in Y$.

Using these notations, we can find the following properties:

(i) $d_0(Y) = \mu_X^{-1}(\mu_X(Y))$ (ii) $d_0(d_0(Y)) = d_0(Y)$ (iii) $Y \subseteq d_0(Y) \subseteq \overline{Y}$ and $\overline{d_0(Y)} = \overline{Y}$ (iv) If Y is open or closed, then $d_0(Y) = Y$

Now, we introduce the notions of d_0 -closed subsets, in a given topological space, and quasi-Whyburn spaces as follows.

Definition 2. Let A be a subset of a topological space X. Then,

- (i) A is called d_0 -closed if $d_0(A)$ is closed, that is, if $d_0(A) = \overline{A}$
- (ii) If the T_0 -reflection of X is a Whyburn space, X is called a quasi-Whyburn space or a QAP-space (or also a T_0 -Whyburn space)

The following theorem gives a characterization of quasi-Whyburn spaces.

Theorem 6. If X is a topological space, then we have equivalence between the following statements:

- (1) X is a QAP-space
- (2) For all non- d_0 -closed subsets A of X and for all $x \in \overline{A} \setminus d_0(A)$, there is a subset B of X such that $d_0(B) \subseteq d_0(A)$ with $\overline{B} \setminus d_0(B) = d_0(x)$

Proof. (1) \Longrightarrow (2). Let *A* be a <u>non-d</u>₀-closed subset of *X* and $x \in \overline{A} \setminus d_0(A)$. Then, $\mu_X(x) \in \overline{\mu_X(A)} \setminus \mu_X(A)$. By hypothesis, there is $B \subseteq X$ such that $\mu_X(B) \subseteq \mu_X(A)$ (which is equivalent to $d_0(B) \subseteq d_0(A)$) satisfying $\mu_X(B) \longrightarrow \mu_X(x)$. Now, applying μ_X^{-1} , we have

$$d_{0}(x) = \mu_{X}^{-1} \left(\overline{\mu_{X}(B)} \setminus \mu_{X}(B) \right)$$

= $\mu_{X}^{-1} \left(\overline{\mu_{X}(B)} \right) \setminus \mu_{X}^{-1} \left(\mu_{X}(B) \right)$
= $\overline{\mu_{X}^{-1}} \left(\mu_{X}(B) \right) \setminus \mu_{X}^{-1} \left(\mu_{X}(B) \right)$
= $\overline{d_{0}(B)} \setminus d_{0}(B) = \overline{B} \setminus d_{0}(B).$ (5)

(2) \Longrightarrow (1). Conversely, let $A \subseteq X$ such that $\mu_X(A)$ is not closed in $\underline{T}_0(X)$ and consider a point x in X with $\mu_X(x) \in \overline{\mu_X(A)} \setminus \mu_X(A)$. Then, $x \in \overline{A} \setminus d_0(A)$ with A non- d_0 -closed. So, by hypothesis, there is a subset B of X such that $d_0(B) \subseteq d_0(A)$ (which is equivalent to $\mu_X(B) \subseteq \mu_X(\underline{A})$) satisfying $\overline{B} \setminus d_0(B) = d_0(x)$. Thus, $\mu_X^{-1}(\{\mu_X(x)\}) = \overline{\mu_X^{-1}}(\mu_X(B)) = \mu_X^{-1}(\mu_X(B)) = \mu_X^{-1}(\mu_X(B)) = \mu_X^{-1}(\mu_X(B)) = \mu_X^{-1}(\mu_X(B)) = \mu_X^{-1}(\mu_X(B))$. Therefore, $\mu_X(B) \longrightarrow \mu_X(x)$.

Definition 3. A topological space X is called quasiweakly Whyburn space (or T_0 -weakly Whyburn space) and denoted by *QWAP*-space if its T_0 -reflection is a weakly Whyburn space.

The proof of the following result is similar to that of Theorem 6.

Theorem 7. If X is a topological space, then we have equivalence between the following statements:

- (1) X is a QWAP-space
- (2) For all non-d₀-closed subset A of X, there is a subset B of X with d₀(B)⊆d₀(A) and B\d₀(A) = d₀(x), for some x ∈ X

3.2. Alexandroff Spaces Which Are Whyburn and Quasi-Whyburn Spaces

Theorem 8. If X is an Alexandroff space, then we have equivalence between the following statements:

(i) X is Whyburn
(ii)
$$\forall x \in X, |\downarrow x| \le 2$$

Proof. Suppose that *X* is Whyburn and there exists $x \in X$ such that $(\downarrow x) \setminus \{x\}$ contains two distinct elements *y* and *z*. Since $\{x\}$ is not closed and $y \in \overline{\{x\}} \setminus \{x\}$, there exists $B \subset \{x\}$ such that $\overline{B} \setminus \{x\} = \{y\}$. Yet, in that case, $B = \{x\}$, which leads to a contradiction because $(\downarrow x) \setminus \{x\}$ contains also *z*.

Conversely, suppose that each element of *X* has at most 2 predecessors.

Let $Y \subseteq X$ such that $\overline{Y} \neq Y$. Using the fact that X is Alexandroff, we have

$$\overline{Y} = \bigcup [\downarrow t \colon t \in Y]. \tag{6}$$

Let $x \in \overline{Y} \setminus Y$ and $t \in Y$ satisfying $x \in \downarrow t$. Since $|\downarrow t| \le 2$, then $\downarrow t = \{t, x\}$. If we take $B = \{t\}$, we can see that $B \subset Y$ and $\overline{B} \setminus Y = \{x\}$. We deduce that X is a Whyburn space. \Box

Corollary 4. Let (X, P(f)) be a functionally Alexandroff space. Then, we have equivalence between the following statements:

(*i*)
$$(X, P(f))$$
 is a Whyburn space
(*ii*) $\forall x \in X, f^2(x) \in \{x, f(x)\}$

Example 3

(1) Consider a given set $X = \{a, b, c, d\}$.

Let $\tau = \{\emptyset, X, \{a, b, c\}, \{b\}, \{c\}, \{b, d, c\}, \{b, c\}\}$ be an Alexandroff topology on *X*.

Suppose that X is Whyburn. Since $\{b\}$ is not closed, then there exists $B \subset \{b\}$ such that $\overline{B} \setminus \{b\} = \{a\}$. This is an impossible fact because $\overline{B} \setminus \{b\} = \{a, d\}$. Therefore, this Alexandroff space is not Whyburn.

(2) Let $X = \mathbb{Z} \cup \{\infty\}$. The topology on X satisfying $\overline{\{n\}} = \{n, \infty\}$, for every $n \in \mathbb{Z}$ and $\overline{\{\infty\}} = \{\infty\}$ is an Alexandroff topology.

Clearly, for any nonempty subset *A* of *X*, we have $\overline{A} = A \cup \{\infty\}$; then, the condition $x \in \overline{A} \setminus A$ means that $x = \infty$, and thus, $A \longrightarrow x$. We observe that, in this case, for every $n \in \mathbb{Z}$, $|\downarrow n| = |\{n, \infty\}| = 2$ and $|\downarrow \infty| = |\{\infty\}| = 1$. One can illustrate this situation in Figure 1.

Remark 2

Let (X, τ) be the Alexandroff space cited in Example 1 (1) and suppose that it is Whyburn. Since {b} is not closed, then there exists B⊆{b} such that B̄\{b} = {a}. This is an impossible fact because B̄\{b} = {a, d}.

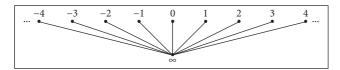


FIGURE 1: Alexandroff topology.

Therefore, this Alexandroff space is not Whyburn. Moreover, for the same reason, we note that the space cited in Example 1 (2) is not Whyburn.

(2) The example cites in Remark 1 (2) provides a Whyburn space.

Proposition 1. Let X be an Alexandroff space. Then, X is weakly Whyburn if and only if X is Whyburn.

Proof. Clearly, any Whyburn space is weakly Whyburn.

Conversely, suppose that X is a WAP-space and there exists $x \in X$ such that $|\downarrow x| > 2$.

If we take $Y = \{x\}$, then Y is not closed, which implies that there exists $B \subset Y$ such that $|\overline{B} \setminus Y| = 1$. Thus, $B = \{x\}$, and so $|\overline{B} \setminus Y| > 1$ which is a contradiction.

Corollary 5. *Let X be a Whyburn space. Then, the following statements are equivalent:*

- (1) X is an Alexandroff space
- (2) X is a primal space

Proof. It is enough to see that an Alexandroff Whyburn space is a functionally Alexandroff space. Hence, by Theorem 8, $|\downarrow x| > 2$ for any $x \in X$. Two cases arise as follows:

- (a) If $|\downarrow x| = 1$, we take f(x) = x, and thus $\overline{\{x\}} = \downarrow x = \{x\} = \{f^n(x), n \in \mathbb{N}\}.$
- (b) If $|\downarrow x| = 2$, then $\downarrow x = \{x, y\}$, and in this case, we take f(x) = y. So, $\overline{\{x\}} = \downarrow x = \{x, y\} = \{x, f(x)\} = \{f^n(x), n \in \mathbb{N}\}$. Indeed, $f^2(x) \in \{x, f(x)\}$ since $f^2(x) = f(f(x)) = f(y)$ which is equivalent, by the construction of f.
 - (i) y, if $|\downarrow y| = 1$, and thus $f^2(x) = f(x)$
 - (ii) z, if $|\downarrow y| = 2$, and thus $z \in \downarrow y \setminus \{y\} \subseteq \downarrow x \setminus \{y\} = \{x\}$, and consequently, $f^2(x) = x$

Theorem 9. Let X be an Alexandroff space. Then, the following statements are equivalent:

- (i) X is a QAP-space
- (ii) $\forall x \in X \text{ and } \forall y, z \in \downarrow x, \text{ we have } (\downarrow x = \downarrow y) \lor (\downarrow x = \downarrow z) \lor (\downarrow y = \downarrow z)$

Proof. The first remark that X is Alexandroff if and only if $T_0(X)$ is Alexandroff and for any $x, y \in X$; we have $x \le y \Longrightarrow \mu_X(x) \le \mu_X(y)$.

(i) (i) \Longrightarrow (ii). Let $x \in X$ and $y, z \in \downarrow x$. Then, $\mu_X(z), \mu_X(y) \in \downarrow \mu_X(x)$. Now, using Theorem 8, we get

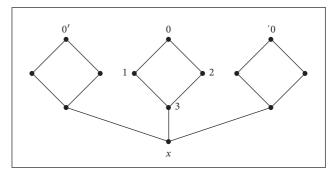


FIGURE 2: QAP-space.

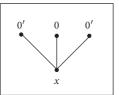


FIGURE 3: Functionally Alexandroff space.

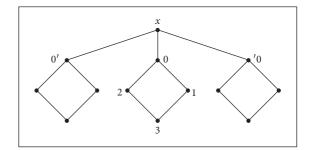


FIGURE 4: X is not a QAP-space.

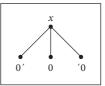


FIGURE 5: $T_0(X)$ is not a functionally Alexandroff space.

$$(\mu_X(x) = \mu_X(y)) \lor (\mu_X(x) = \mu_X(z)) \lor (\mu_X(z) = \mu_X(y)).$$
 Therefore, $(\downarrow x = \downarrow y) \lor (\downarrow x = \downarrow z) \lor (\downarrow y = \downarrow z)$

(ii) (ii) \Longrightarrow (i). Let $x \in X$. By Theorem 8, it is enough to see that $|\downarrow \mu_X(x)| \le 2$. In this case, suppose that $\downarrow \mu_X(x) \supseteq \{\mu_X(x), \mu_X(y), \mu_X(z)\}$. Then, $y, z \in \downarrow x$, and thus, by hypothesis, the family $\{\mu_X(x), \mu_X(y), \mu_X(z)\}$ is not pairwise distinct, as desired. \Box

Example 4

(1) Figure 2shows the following: $\downarrow x = \{x\}$ and $\downarrow 0 = \downarrow 1 = \downarrow 2 = \downarrow 3 = \{0, 1, 2, 3, x\}$. Let $a, b \in \downarrow t$, then two cases arise as follows:

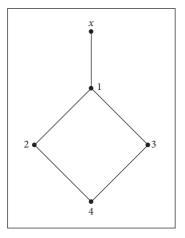


FIGURE 6: X is a QAP-space.



FIGURE 7: $T_0(X)$ is a functionally Alexandroff space.

- (i) If $t \neq x$, then necessary $\downarrow a = \downarrow t$ or $\downarrow b = \downarrow t$
- (ii) If t = x, then $a, b \in \downarrow t$ means that a = b = t and thus $\downarrow a = \downarrow b = \downarrow t$
- (2) Figure 4 shows the following: $\downarrow x = X$, $\downarrow 0 = \{0, 1, 2, 3\}$, and $\downarrow 0' = \{0', 1', 2', 3'\}$. Then, $1, 1' \in \downarrow x$, but $\{\downarrow 0, \downarrow 0', \downarrow x\}$ is a family of pairwise distinct elements. Therefore, X is not a QAP-space.

 $T_0(X)$ is defined by Figure 5which is not a functionally Alexandroff space.

(3) Figure 6 shows the following:

 $\downarrow x = X, \downarrow 4 = \downarrow 1 = \downarrow 2 = \downarrow 3 = \{1, 2, 3, 4\}$, and thus, for any $a, b, c \in X$, we have $(\downarrow a = \downarrow b) \lor (\downarrow a = \downarrow c) \lor (\downarrow b = \downarrow c)$. Therefore, *X* is a *QAP*-space.

 $T_0(X)$ is defined by Figure 7 which is a functionally Alexandroff space.

Theorem 10. Let X be an Alexandroff space. Then, the following statements are equivalent:

- (i) X is a QWAP-space
- (ii) X is a QAP-space

Proof. Using Proposition 1 and the fact that a topological space is Alexandroff if and only if its T_0 -reflection is Alexandroff. We get it immediately.

$$X \text{ is a QWAP - space} \Longrightarrow T_0(X) \text{ is a WAP - space}$$

$$\iff T_0(X) \text{ is a AP - space}$$

$$\iff X \text{ is a QAP - space.}$$

$$\square$$

Data Availability

The data set can be accessed upon request.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

Acknowledgments

This project was supported by the Deanship of Scientific Research at Prince Sattam bin Abdulaziz University under the research project 2020/01/16 517.

References

- P. Alexandroff, "Diskrete Räume," *Matematicheskii* Sbornik.vol. 44, no. 2, pp. 501–519, 1937.
- [2] A. K. Steiner, "The lattice of topologies: structure and complementation," *Transactions of the American Mathematical Society*, vol. 122, no. 2, pp. 379–398, 1966.
- [3] G. T. Herman, "On topology as applied to image analysis," *Computer Vision, Graphics, and Image Processing*, vol. 52, no. 3, pp. 409–415, 1990.
- [4] E. H. Kronheimer, "The topology of digital images," *Topology and Its Applications*, vol. 46, no. 3, pp. 279–303, 1992.
- [5] T. M. Al-shami, "Improvement of the approximations and accuracy measure of a rough set using somewhere dense sets," *Soft Computing*, vol. 25, no. 23, Article ID 14449, 2021.
- [6] T. M. Al-shami, "An improvement of rough sets' accuracy measure using containment neighborhoods with a medical application," *Information Sciences*, vol. 569, pp. 110–124, 2021.
- [7] P. Alexandroff, Combinatorial Topology, Dover, New York, USA, 2011.
- [8] P. Alexandroff and H. Hopf, *Topologie, Grundlehren der* mathematischen Wissenschaften, Springer, Berlin, 1935.
- [9] S. Lazaar, T. Richmond, and H. Sabri, "Homogeneous functionally Alexandroff spaces," *Bulletin of the Australian Mathematical Society*, vol. 1-9, 2017.
- [10] T. A. Richmond, "Quasiorders, principal topologies, and partially ordered partitions," *International Journal of Mathematics and Mathematical Sciences*, vol. 21, no. 2, pp. 221–234, 1998.
- [11] P. Uryshon, "Uber the mächtigkeit der zusammenhägenden Mengen," Mathematische Annalen, vol. 94, pp. 262–295, 1925.
- [12] C. Uzcategui and J. Vielma, "Alexandroff topologies viewed as closed sets in the Cantor cube," *Divulgaciones. Matmáticas.*vol. 13, no. 1, pp. 45–53, 2005.
- [13] W. T. Van Est and H. Freudenthal, "Trennung durch stetige funktionen in topologischen räumen," *Indagationes Mathematicae*, vol. 54, pp. 359–368, 1951.
- [14] O. Echi, "The categories of flows of Set and Top," *Topology and Its Applications*, vol. 159, no. 9, pp. 2357–2366, 2012.
- [15] S. Lazaar, H. Sabri, and R. Tahri, "Structural and numerical studies of some topological properties for Alexandroff spaces," *Bulletin of the Irish Mathematical Society*, vol. 48, 2021.
- [16] L. Dridi, S. Lazaar, and T. Turki, "F-door spaces and F-submaximal spaces," *Applied General Topology*, vol. 1, pp. 97–113, 2013.
- [17] G. Bezhanishvili, L. Esakia, and D. Gabelaia, "Some results on modal axiomatization and definability for topological spaces," *Studia Logica*, vol. 81, no. 3, pp. 325–355, 2005.

- [18] A. H. Stone, "On partitioning ordered sets into cofinal subsets," *Mathematika*, vol. 15, no. 2, pp. 217–222, 1968.
- [19] G. T. Whyburn, "Accessibility spaces," Proceedings of the American Mathematical Society, vol. 24, no. 1, pp. 181–185, 1970.
- [20] P. Simon, "On accumulation points," Cahiers de Topologie et Géométrie Différentielle Catégoriques, vol. 35, pp. 321–327, 1994.
- [21] A. Pultr and A. Tozzi, "Equationally closed subframes and representation of quotient spaces," *Cahiers de Topologie et Géométrie Différentielle Catégoriques*, vol. 34, pp. 167–183, 1993.
- [22] J. Pelant, M. G. Tkachenko, V. V. Tkachuk, and R. G. Wilson, "Pseudocompact Whyburn spaces need not be Frechet," *Proceedings of the American Mathematical Society*, vol. 131, no. 10, pp. 3257–3265, 2003.
- [23] V. V. Tkachuk and I. V. Yashchenko, "Almost closed sets and the topologies they determine," *Commentationes Mathematicae Universitatis Carolinae*, vol. 42, no. 2, pp. 395–405, 2011.
- [24] A. Grothendieck and J. Dieudonné, "Eléments de géométrie algébrique I: le langage des schemas," *Institut des Hautes Etudes Scientifiques Publications Mathématiques*, vol. 4, 1960.
- [25] O. Echi, "Quasi-homeomorphisms, goldspectral spaces and jacspectral spaces, bollettino della Unione matematica italiana. Serie VIII," Sezione B. Articoli di Ricerca Matematica.vol. 6, no. 8, pp. 489–507, 2003.