

Research Article

Fractional Soliton Dynamics and Spectral Transform of Time-Fractional Nonlinear Systems: A Concrete Example

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In this paper, the spectral transform with the reputation of nonlinear Fourier transform is extended for the first time to a local time-fractional Korteweg-de Vries (tfKdV) equation. More specifically, a linear spectral problem associated with the KdV equation of integer order is first equipped with local time-fractional derivative. Based on the spectral problem with the equipped local time-fractional derivative, the local tfKdV equation with Lax integrability is then derived and solved by extending the spectral transform. As a result, a formula of exact solution with Mittag-Leffler functions is obtained. Finally, in the case of reflectionless potential the obtained exact solution is reduced to fractional n -soliton solution. In order to gain more insights into the fractional n -soliton dynamics, the dynamical evolutions of the reduced fractional one-, two-, and three-soliton solutions are simulated. It is shown that the velocities of the reduced fractional one-, two-, and three-soliton solutions change with the fractional order.

1. Introduction

Since the increasing interest on fractional calculus and its applications, dynamical processes and dynamical systems of fractional orders have attracted much attention. In 2010, Fujioka et al. [1] investigated soliton propagation of an extended nonlinear Schrödinger equation with fractional dispersion term and fractional nonlinearity term. In 2014, Yang et al. [2] used a local fractional KdV equation to model fractal waves on shallow water surfaces.

In the field of nonlinear mathematical physics, the spectral transform [3] with the reputation of nonlinear Fourier transform is a famous analytical method for constructing exact and explicit n -soliton solutions of nonlinear partial differential equations (PDEs). Since put forward by Gardner et al. in 1967, the spectral transform method has achieved considerable developments [4–26]. With the close attentions of fractional calculus and its applications [27–53], some of the natural questions are whether the existing methods like those in [54–70] in soliton theory can be extended to nonlinear

PDEs of fractional orders and what about the fractional soliton dynamics and integrability of fractional PDEs. As far as we know there are no research reports on the spectral transform for nonlinear PDEs of fractional orders. This paper is motivated by the desire to extend the spectral transform to nonlinear fractional PDEs and then gain more insights into the fractional soliton dynamics of the obtained solutions. For such a purpose, we consider the following local tfKdV equation:

$$D_t^{(\alpha)} u + 6uu_x + u_{xxx} = 0, \quad 0 < \alpha \leq 1. \quad (1)$$

Here we note that if $\alpha = 1$ then eq. (1) becomes the celebrated KdV equation $u_t + 6uu_x + u_{xxx} = 0$. In eq. (1), the local time-fractional derivative $D_t^\alpha u$ at the point $t = t_0$ is defined as [30]

$$\begin{aligned} D_t^{(\alpha)} u(x, t_0) &= \left. \frac{\partial^\alpha u(x, t)}{\partial t^\alpha} \right|_{t=t_0} \\ &= \lim_{t \rightarrow t_0} \frac{\Delta^\alpha (u(x, t) - u(x, t_0))}{(t - t_0)^\alpha}, \end{aligned} \quad (2)$$

where $\Delta^\alpha(u(x, t) - u(x, t_0)) \cong \Gamma(1 + \alpha)(u(x, t) - u(x, t_0))$; some useful properties [33] of the local time-fractional derivative have been used in this paper.

The rest of this paper is organized as follows. In Section 2, we derive the local tfKdV eq. (1) by introducing a linear spectral problem equipped with local time-fractional derivative. In Section 3, we construct fractional n -soliton solution of the local tfKdV eq. (1) by extending the spectral transform method. In Section 4, we investigate the dynamical evolutions of the obtained fractional one-soliton solution, two-soliton solution, and three-soliton solution. In Section 5, we conclude this paper.

2. Derivation of the Local tfKdV Equation

For the local tfKdV eq. (1), we have the following Theorem 1.

Theorem 1. *The local tfKdV eq. (1) is a Lax system, which can be derived from the linear spectral problem equipped with a local time-fractional evolution equation:*

$$\phi_{xx} = (\eta - u)\phi, \quad \eta = -k^2, \quad (3)$$

$$D_t^{(\alpha)}\phi = (u_x + \vartheta)\phi + (4k^2 - 2u)\phi_x, \quad (4)$$

where $\phi = \phi(x, t)$ and $u = u(x, t)$ are all differentiable functions with respect to x and t , the spectral parameter η is independent of t , and ϑ is an arbitrary constant.

Proof. Taking the time-fractional derivative of eq. (3) yields

$$D_t^{(\alpha)}\phi_{xx} = -\phi D_t^{(\alpha)}u - (u + k^2)D_t^{(\alpha)}\phi, \quad (5)$$

Substituting eq. (4) into eq. (5), we have

$$D_t^{(\alpha)}\phi_{xx} = -[D_t^{(\alpha)}u + (u_x + \vartheta)(u + k^2)]\phi - (4k^2 - 2u)(u + k^2)\phi_x, \quad (6)$$

Taking the derivative of eq. (4) with respect to x twice gives

$$(D_t^{(\alpha)}\phi)_{xx} = u_{xxx}\phi - (3u_x - \vartheta)\phi_{xx} + (4k^2 - 2u)\phi_{xxx}, \quad (7)$$

With the help of eq. (3), from eq. (7) we have

$$(D_t^{(\alpha)}\phi)_{xx} = [u_{xxx} + (5u - k^2)u_x - \vartheta(u + k^2)]\phi - (4k^2 - 2u)(u + k^2)\phi_x. \quad (8)$$

On the other hand, at the arbitrary point $t = t_0$ we have

$$D_t^\alpha\phi_{xx}(x, t_0) = \lim_{t \rightarrow t_0} \frac{\Delta^\alpha(\phi_{xx}(x, t) - \phi_{xx}(x, t_0))}{(t - t_0)^\alpha}, \quad (9)$$

$$(D_t^\alpha\phi(x, t_0))_{xx} = \lim_{t \rightarrow t_0} \frac{\Delta^\alpha(\phi(x, t) - \phi(x, t_0))_{xx}}{(t - t_0)^\alpha}.$$

Finally, using eqs. (6), (8), and (9) we arrive at eq. (1). Thus, we finish the proof. The process of proof shows that eq. (1) is a Lax integrable system. \square

3. Local Fractional Spectral Transform

Since the local tfKdV eq. (1) is a local time-fractional system, the orders of the derivatives with respect to space variable x are integers. So, all the existing results about the spectral problem (3), a part of the Lax pair for the classical KdV equation, can be translated to the local tfKdV eq. (1).

For the direct scattering problem, we translate some necessary results and definitions [9] to the local tfKdV eq. (1).

Lemma 2. *If the real potential $u(x)$ defined in the whole real axis $-\infty < x < \infty$ and its various derivatives are differentiable functions which vanishes rapidly as $x \rightarrow \pm\infty$ and satisfies*

$$\int_{-\infty}^{+\infty} |x^j u(x)| dx < +\infty, \quad (j = 0, 1, 2), \quad (10)$$

then the linear spectral problem (3) has a set of basic solutions called Jost solutions $\phi^+(x, k)$ and $\phi^-(x, k)$, and they are not only bounded for all values of x but also analytic for $\text{Im } k > 0$ and continuous for $\text{Im } k \geq 0$ and have the following asymptotic properties:

$$\phi^+(x, k) \rightarrow e^{ikx}, \quad (x \rightarrow +\infty), \quad (11)$$

$$\phi^-(x, k) \rightarrow e^{-ikx}, \quad (x \rightarrow -\infty). \quad (12)$$

Lemma 3. *Define the Wronskian*

$$W(\phi^+(x, k), \phi^-(x, k)) = \phi_x^+(x, k)\phi^-(x, k) - \phi^+(x, k)\phi_x^-(x, k), \quad (13)$$

and let

$$\phi^-(x, k) = a(k)\phi^+(x, -k) + b(k)\phi^+(x, k). \quad (14)$$

Then

$$a(k) = \frac{1}{2ik}W(\phi^-(x, k), \phi^+(x, k)), \quad (15)$$

$$b(k) = \frac{1}{2ik}W(\phi^+(x, -k), \phi^-(x, k)),$$

where $a(k)$ is analytic for $\text{Im } k > 0$ and continuous for $\text{Im } k \geq 0$, $b(k)$ is defined only on the real axis $\text{Im } k = 0$, and the analytic function $a(k)$ has a finite number of simple zeros $k_m = i\kappa_m$ ($\kappa_m > 0, m = 1, 2, \dots, n$).

Lemma 4. *For the linear spectral problem (3), there exists a constant b_m , such that*

$$\phi^-(x, i\kappa_m) = b_m\phi^+(x, i\kappa_m), \quad (16)$$

$$\int_{-\infty}^{+\infty} c_m^2 \phi^{+2}(x, i\kappa_m) dx = 1, \quad c_m^2 = -\frac{ib_m}{a_k(i\kappa_m)}. \quad (17)$$

Definition 5. The constant c_m satisfying eq. (17) is named the normalization constant for the eigenfunction $\phi^+(x, i\kappa_m)$, and $c_m\phi^+(x, i\kappa_m)$ is named normalization eigenfunction.

Definition 6. The set

$$\left\{ k (\text{Im } k = 0), R(k) = \frac{b(k)}{a(k)}, i\kappa_m, c_m, m = 1, 2, \dots, n \right\} \quad (18)$$

is named the scattering data of the linear spectral problem (3).

Lemma 7. *If the eigenfunction $\phi(x, k)$ satisfies the linear spectral problem (3), then*

$$P = D_t^{(\alpha)} \phi - (u_x + \vartheta) \phi - (4k^2 - 2u) \phi_x \quad (19)$$

solves eq. (3) as well.

Proof. A direct computation on eq. (19) tells that

$$P_{xx} = D_t^{(\alpha)} \phi_{xx} - u_{xxx} \phi - (4k^2 - 2u) \phi_{xxx} + (3u_x - \vartheta) \phi_{xx}. \quad (20)$$

With the help of eqs. (3) and (20), we have

$$P_{xx} + (k^2 + u) P = -\phi (D_t^{(\alpha)} u + 6uu_x + u_{xxx}) = 0. \quad (21)$$

Thus, the proof is finished. \square

For the time dependence of the scattering data, we have the following Theorem 8.

Theorem 8. *If the time evolution of $u(x, t)$ obeys the local tfKdV eq. (1), then the scattering data (18) for the linear spectral problem (3) possess the following time dependences:*

$$D_t^{(\alpha)} \kappa_m(t) = 0, \quad (22)$$

$$D_t^{(\alpha)} c_m(t) = 4\kappa_m^3(t) c_m(t),$$

$$D_t^{(\alpha)} a(k) = 0, \quad (23)$$

$$D_t^{(\alpha)} b(k) = 8ik^3(t) b(k).$$

Proof. Substituting eqs. (12) and (14) into eq. (3) and using the asymptotic properties of eqs. (11) and (12) as $x \rightarrow +\infty$ and $x \rightarrow -\infty$, respectively, we have

$$(\vartheta - 4ik^3) e^{-ikx} = 0, \quad (24)$$

$$\begin{aligned} D_t^{(\alpha)} a(k) e^{-ikx} + D_t^{(\alpha)} b(k) e^{ikx} \\ = \vartheta (a(k) e^{-ikx} + b(k) e^{ikx}) \\ + 4k^2 (-ika(k) e^{-ikx} + ikb(k) e^{ikx}). \end{aligned} \quad (25)$$

Namely,

$$\vartheta = 4ik^3, \quad (26)$$

$$D_t^{(\alpha)} a(k) = a(k) (\vartheta - 4ik^3) = 0, \quad (27)$$

$$D_t^{(\alpha)} b(k) = b(k) (\vartheta + 4ik^3) = 8ik^3 b(k). \quad (28)$$

It is easy to see that all the zeros of $a(k)$ are independent of t because of $D_t^{(\alpha)} a(k) = 0$. Therefore, we arrive at $D_t^{(\alpha)} \kappa_m(t) = 0$.

Similarly, substituting eq. (16) into eq. (3) and using the asymptotic property of eq. (11) as $x \rightarrow +\infty$, we have

$$D_t^{(\alpha)} b_m(t) = (\vartheta + 4\kappa_m^3(t)) b_m(t) = 8\kappa_m^3(t) b_m(t). \quad (29)$$

In view of eqs. (17) and (28), we obtain

$$D_t^{(\alpha)} (c_m^2(t)) = -\frac{D_t^{(\alpha)} (ib_m(t))}{a_k(i\kappa_m)} = 8\kappa_m^3(t) c_m^2(t), \quad (30)$$

which can be finally reduced to the second term of eq. (22). Then we finish the proof. \square

For the inverse scattering problem, we have the following Theorem 9.

Theorem 9. *The local tfKdV eq. (1) has an exact solution of the form*

$$u(x, t) = 2 \frac{d}{dx} K(x, x, t), \quad (31)$$

where $K(x, y, t)$ satisfies the Gelfand-Levitan-Marchenko (GLM) integral equation:

$$\begin{aligned} K(x, y, t) + F(x + y, t) \\ + \int_x^\infty K(x, z, t) F(x + z, t) dz = 0, \end{aligned} \quad (32)$$

with

$$F(x, t) = \frac{1}{2\pi} \int_{-\infty}^\infty R(k, t) e^{ikx} dk + \sum_{m=1}^n c_m^2 e^{i\kappa_m x}, \quad (33)$$

and $R(k, t)$, c_m , and κ_m are determined by eqs. (22) and (23).

Proof. The process of the proof of Theorem 9 is similar to that of the classical KdV equation [9] with integer order, and the only differences are the scattering data. To avoid unnecessary repetition, we omit it here. \square

For the fractional n -soliton solution, we have the following Theorem 10.

Theorem 10. *In the case of reflectionless potential, the local tfKdV eq. (1) has fractional n -soliton solution of the form*

$$u(x, t) = 2 \frac{d^2}{dx^2} \ln (\det D(x, t)), \quad (34)$$

where

$$\begin{aligned} D(x, t) &= (d_{jm}(x, t))_{n \times n}, \\ d_{jm}(x, t) &= \delta_{jm} + \frac{c_j(t) c_m(t)}{\kappa_j(0) + \kappa_m(0)} e^{-(\kappa_j(0) + \kappa_m(0))x}, \end{aligned} \quad (35)$$

$$c_j(t) = c_j(0) E_\alpha(4\kappa_j^3(0) t^\alpha), \quad (36)$$

$$c_m(t) = c_m(0) E_\alpha(4\kappa_m^3(0) t^\alpha).$$

In eq. (36), $E_\alpha(\cdot)$ is the Mittag-Leffler function [33].

Proof. Firstly, we further determine the scattering data. Solving eqs. (22) and (23) yields

$$\begin{aligned}\kappa_m(t) &= \kappa_m(0), \\ c_m(t) &= c_m(0) E_\alpha \left(4\kappa_m^3(0) t^\alpha \right),\end{aligned}\quad (37)$$

$$\begin{aligned}a(k, t) &= a(k, 0), \\ b(k, t) &= b(k, 0) E_\alpha \left(8i\kappa^3(0) t^\alpha \right).\end{aligned}\quad (38)$$

Secondly, we let $R(k, t) = 0$. In this case of reflectionless, eq. (32) reduces to

$$\begin{aligned}K(x, y, t) &+ \sum_{m=1}^n c_m^2(t) e^{-\kappa_m(0)(x+y)} \\ &+ \sum_{m=1}^n c_m^2(t) e^{-\kappa_m(0)y} \int_x^\infty K(x, z, t) e^{-\kappa_m(0)z} dz \\ &= 0.\end{aligned}\quad (39)$$

Suppose that eq. (39) has a separation solution

$$K(x, y, t) = \sum_{j=1}^n c_j(t) h_j(x) e^{-\kappa_j(0)y}, \quad (40)$$

where $h_j(x)$ is an undetermined function which can be determined by the substitution of eq. (40) into eq. (39). With the determined function $h_j(x)$, we have

$$K(x, y, t) = \frac{d}{dx} \ln(\det D(x, t)). \quad (41)$$

Finally, from eqs. (31), (37), (38), and (41) we obtain eq. (34). Therefore, the proof is over. \square

4. Fractional Soliton Dynamics

In order to gain more insights into the soliton dynamics of the obtained fractional n -soliton solution (34), we consider the cases of $n = 1, 2, 3$.

When $n = 1$, we have

$$\det D(x, t) = 1 + \frac{c_1^2(0) E_\alpha \left(8\kappa_1^3(0) t^\alpha \right)}{2\kappa_1(0)} e^{-2\kappa_1(0)x}, \quad (42)$$

and we, hence, obtain, from eq. (34), the fractional one-soliton solution:

$$\begin{aligned}u &= 2\kappa_1^2(0) \\ &\cdot \operatorname{sech}^2 \left[\kappa_1(0)x - \frac{1}{2} \ln \frac{c_1^2(0) E_\alpha \left(8\kappa_1^3(0) t^\alpha \right)}{2\kappa_1(0)} \right].\end{aligned}\quad (43)$$

Similarly, when $n = 2$ we obtain the fractional two-soliton solution:

$$\begin{aligned}u &= 2 \ln \left[1 + \frac{c_1^2(0) E_\alpha \left(8\kappa_1^3(0) t^\alpha \right)}{2\kappa_1(0)} e^{-2\kappa_1(0)x} \right. \\ &+ \frac{c_2^2(0) E_\alpha \left(8\kappa_2^3(0) t^\alpha \right)}{2\kappa_2(0)} e^{-2\kappa_2(0)x} \\ &+ \frac{c_1^2(0) c_2^2(0) (\kappa_1(0) - \kappa_2(0))^2 E_\alpha \left(8\kappa_1(0) t^\alpha \right) E_\alpha \left(8\kappa_2^3(0) t^\alpha \right)}{4\kappa_1(0) \kappa_2(0) (\kappa_1(0) + \kappa_2(0))^2} \\ &\left. \cdot e^{-2(\kappa_1(0) + \kappa_2(0))x} \right]_{xx}.\end{aligned}\quad (44)$$

When $n = 3$, we obtain the fractional three-soliton solution:

$$\begin{aligned}u &= 2 \ln \left[1 + \frac{c_1^2(0) E_\alpha \left(8\kappa_1^3(0) t^\alpha \right)}{2\kappa_1(0)} e^{-2\kappa_1(0)x} + \frac{c_2^2(0) E_\alpha \left(8\kappa_2^3(0) t^\alpha \right)}{2\kappa_2(0)} e^{-2\kappa_2(0)x} + \frac{c_3^2(0) E_\alpha \left(8\kappa_3^3(0) t^\alpha \right)}{2\kappa_3(0)} e^{-2\kappa_3(0)x} \right. \\ &+ \frac{c_1^2(0) c_2^2(0) (\kappa_1(0) - \kappa_2(0))^2 E_\alpha \left(8\kappa_1(0) t^\alpha \right) E_\alpha \left(8\kappa_2^3(0) t^\alpha \right)}{4\kappa_1(0) \kappa_2(0) (\kappa_1(0) + \kappa_2(0))^2} e^{-2(\kappa_1(0) + \kappa_2(0))x} \\ &+ \frac{c_1^2(0) c_3^2(0) (\kappa_1(0) - \kappa_3(0))^2 E_\alpha \left(8\kappa_1(0) t^\alpha \right) E_\alpha \left(8\kappa_3^3(0) t^\alpha \right)}{4\kappa_1(0) \kappa_3(0) (\kappa_1(0) + \kappa_3(0))^2} e^{-2(\kappa_1(0) + \kappa_3(0))x} \\ &+ \frac{c_2^2(0) c_3^2(0) (\kappa_2(0) - \kappa_3(0))^2 E_\alpha \left(8\kappa_2(0) t^\alpha \right) E_\alpha \left(8\kappa_3^3(0) t^\alpha \right)}{4\kappa_2(0) \kappa_3(0) (\kappa_2(0) + \kappa_3(0))^2} e^{-2(\kappa_2(0) + \kappa_3(0))x} \\ &+ \frac{c_1^2(0) c_2^2(0) c_3^2(0) (\kappa_1(0) - \kappa_2(0))^2 (\kappa_1(0) - \kappa_3(0))^2 (\kappa_2(0) - \kappa_3(0))^2}{8\kappa_1(0) \kappa_2(0) \kappa_3(0) (\kappa_1(0) + \kappa_2(0))^2 (\kappa_1(0) + \kappa_3(0))^2 (\kappa_2(0) + \kappa_3(0))^2} E_\alpha \left(8\kappa_1(0) t^\alpha \right) E_\alpha \left(8\kappa_2(0) t^\alpha \right) E_\alpha \left(8\kappa_3^3(0) t^\alpha \right) \\ &\left. \cdot t^\alpha \right]_{xx}.\end{aligned}\quad (45)$$

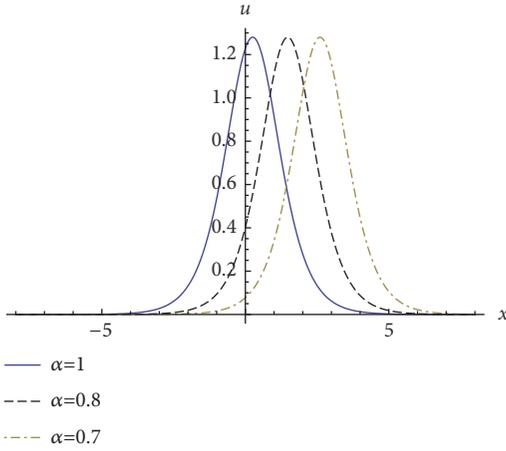


FIGURE 1: Fractional one-solitons determined by solution (43) at time $t = 1$.

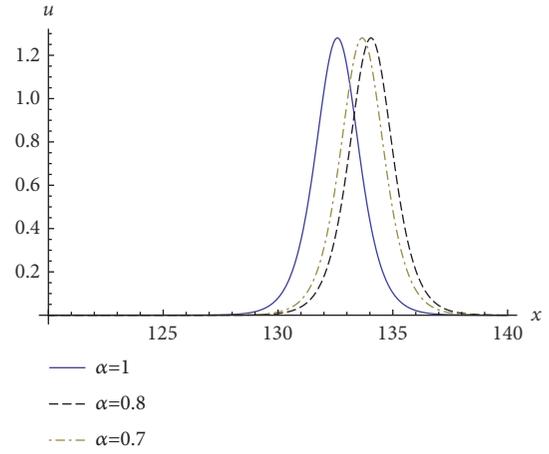


FIGURE 3: Fractional one-solitons determined by solution (43) at time $t = 80$.

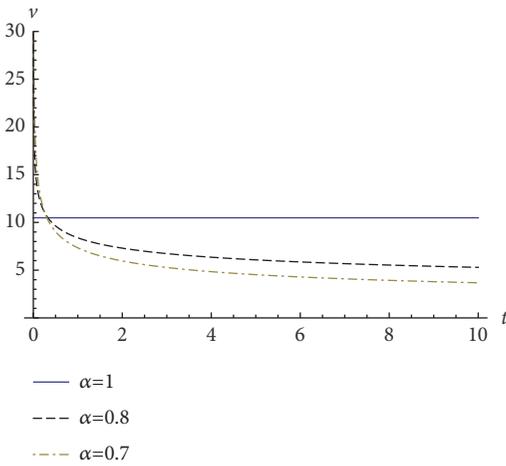


FIGURE 2: Velocity images of fractional one-solitons determined by solution (43).

In Figure 1, we simulate the fractional one-soliton solution (43) with different values of α , where the parameters are selected as $\kappa_1(0) = 0.8$ and $c_1(0) = 0.2$. With the help of velocity images in Figure 2 and the formula of velocity

$$v = 32\alpha\kappa_1^5(0)t^{\alpha-1}, \quad (46)$$

we can see that the bell-shaped solitons have different velocities depending on the values of α . At the initial stage, the smaller the value of α is selected, the faster the soliton propagates. But soon it was the opposite; for more details see Figures 3 and 4.

For the fractional two-solitons and three-solitons determined, respectively, by solutions (44) and (45), similar features shown in Figures 5–7 are observed. In Figures 5 and 6, we select the parameters as $\kappa_1(0) = 0.5$, $c_1(0) = 1.5$, $\kappa_2(0) = 1$, and $c_2(0) = -0.2$. While the parameters in Figure 7 are selected as $\kappa_1(0) = 1$, $c_1(0) = 1$, $\kappa_2(0) = 1.1$, $c_2(0) = 0.5$, $\kappa_3(0) = 1.3$, $c_3(0) = 2$.

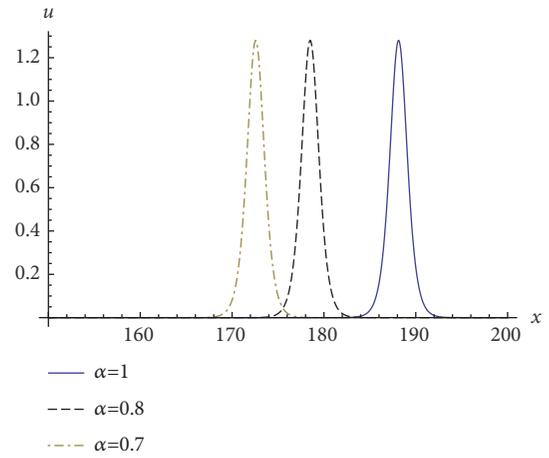


FIGURE 4: Fractional one-solitons determined by solution (43) at time $t = 195$.

5. Conclusion

In summary, we have derived and solved the local tfKdV eq. (1) in the fractional framework of the spectral transform method. This is due to the linear spectral problem (3) equipped with the local time-fractional evolution (4). As for the fractional derivatives, there are many definitions [33] except the local fractional derivative, such as Grünwald–Letnikov fractional derivative, Riemann–Liouville fractional derivative and Caputo’s fractional derivative. Generally speaking, whether or not the spectral transform can be extended to some other nonlinear evolution equations with another type of fractional derivative depends on whether fractional derivative has the good properties required by the spectral transform method. To the best of our knowledge, combined with the Mittag-Leffler functions the obtained exact solution (31), the fractional n -soliton solution (34), and its special cases, the fractional one-, two-, and three-soliton solutions (43)–(45), are all new, and they have not been reported in literature. It is graphically shown that the fractional order of the local tfKdV eq. (1) influences

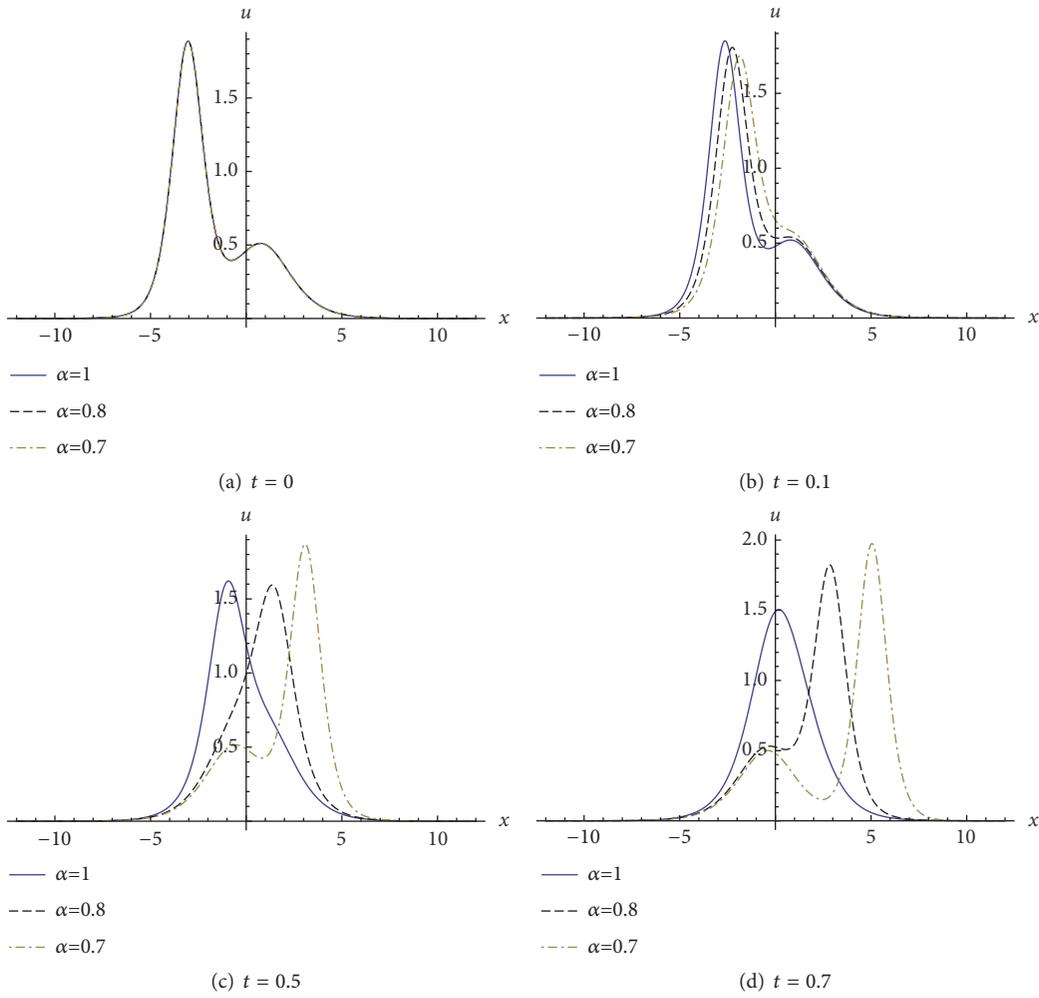


FIGURE 5: Dynamical evolutions of fractional two-solitons determined by solution (44) at different times.

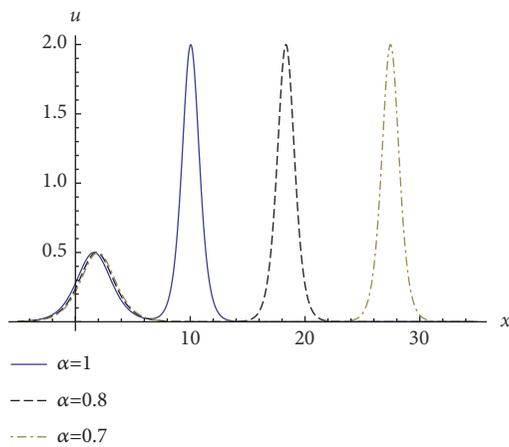


FIGURE 6: Fractional two-solitons determined by solution (44) at $t = 3$.

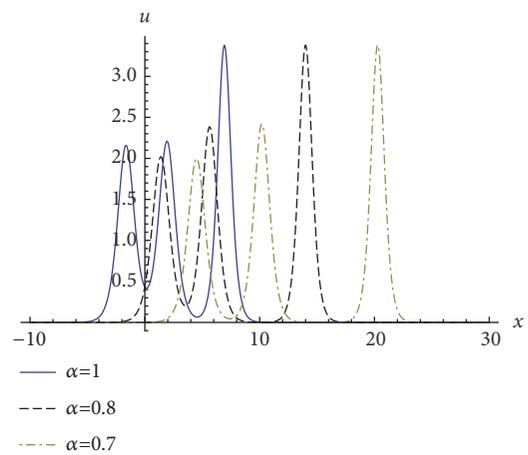


FIGURE 7: Fractional three-solitons determined by solution (45) at $t = 1$.

the velocity of the fractional one-soliton solution (43) with Mittag-Leffler function in the process of propagations. More importantly, the fractional scheme of the spectral transform

presented in this paper for constructing n -soliton solution of the local tfKdV eq. (1) can be extended to some other integrable local time-fractional PDEs.

Data Availability

The data in the paper are available from the corresponding author upon request.

Conflicts of Interest

The authors declare that there are no conflicts of interest regarding the publication of this article.

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