

Research Article

Bounding the Inefficiency of the Multiclass, Multicriteria C-Logit Stochastic User Equilibrium in a Transportation Network

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We derive the exact inefficiency upper bounds of the multiclass C-Logit stochastic user equilibrium (CL-SUE) in a transportation network. All travelers are classified on the basis of different values of time (VOT) into M classes. The multiclass CL-SUE model gives a more realistic path choice probability in comparison with the logit-based stochastic user equilibrium model by considering the overlapping effects between paths. To find efficiency loss upper bounds of the multiclass CL-SUE, two equivalent variational inequalities for the multiclass CL-SUE model, i.e., time-based variational inequality (VI) and monetary-based VI, are formulated. We give four different methods to define the inefficiency of the multiclass CL-SUE, i.e., to compare multiclass CL-SUE with multiclass system optimum, or to compare multiclass CL-SUE with multiclass C-Logit stochastic system optimum (CL-SSO), under the time-based criterion and the monetary-based criterion, respectively. We further investigate the effects of various parameters which include the degree of path overlapping (the commonality factor), the network complexity, degree of traffic congestion, the VOT of user classes, the network familiarity, and the total demand on the inefficiency bounds.

1. Introduction

Concerning the path choice behavior in networks, Wardrop proposed two basic principles: one is the user equilibrium (UE) and the other is the system optimum (SO) [1]. The UE principle shows that all used paths have minimum and equal travel cost (or time), and all unused paths have higher or equal travel cost (or time). In addition, the UE principle assumes that every traveler has a full understanding of the network information and chooses the travel path accordingly to minimize their own travel cost. Later, the researchers have extended the UE model in different aspects, such as boundedly rational UE [2–4], fuzzy UE [5–7], and prospect-based UE [8–10]. The concept of the boundedly rational user equilibrium (BRUE) was proposed in the 1980s. Lou et al. [3] investigated congestion pricing strategies in static networks with boundedly rational route choice behavior. Xuan et al. [4] studied mathematical formulation and solution sets of BRUE. Miralinaghi et al. [7] proposed an alternative approach for a traffic assignment problem that

further extends the applications of the fuzzy theory in route choice behavior and network traffic modelling. Xu et al. [10] proposed a conjecture on travelers' determination of reference points and encapsulates it into the prospect-based user equilibrium conditions. However, in practice, we cannot always assume that this assumption is true. More realistically, travelers who choose the same route may have different perceived travel times due to all kinds of unmeasured factors. Suppose that the perceived travel times are considered as independent and identical distributed (IID) Gumbel random variables [11], travelers' path choices for minimizing their perceived travel time will lead to the stochastic user equilibrium (SUE) state [12]. Concerning the path choice problem in the network, two disadvantages of the logit-based SUE model are as follows: (1) it cannot explain overlapping between paths and (2) it cannot explain the perception variance of travels of different lengths [13, 14].

To alleviate the above two disadvantages, some extended logit-based SUE models have been proposed in recent two

decades, such as C-Logit SUE (CL-SUE) model [13–16], generalized nested logit SUE (GNL-SUE) model [17], cross-nested logit SUE (CNL-SUE) model [18, 19], and paired combinatorial logit SUE (PCL-SUE) model [20]. Other significant theoretical achievements in [21, 22] have also made a contribution to overcoming the disadvantages of the logit-based SUE model. CL-SUE model proposed by Cascetta et al. [13] can solve the overlapping problem by using a commonality factor reflecting path overlapping to modify the systematic part of the utility function. Zhou et al. [14] further provided equivalent variational inequality (VI) and mathematical programming (MP) formulations for the CL-SUE model.

The CL-SUE model can overcome the disadvantages of the logit-based SUE model by considering the overlapping effects between paths and give a more realistic path choice probability. The SO state has the minimum inefficiency loss by definition. Therefore, the CL-SUE model is still inefficient compared with the SO model due to the users' selfish routing. Recently, quantifying and bounding the inefficiency of the equilibrium assignment in the transportation environment has aroused great research interest, while less attention has been paid to multiclass CL-SUE. Koutsopoulos and Papadimitriou first gave the concept of "price of anarchy (POA)" [23]. After that, the POA was first used in the traffic network by Roughgarden and Tardos [24]. In the next few years, other great theoretical achievements of POA proposed by Roughgarden [25–27] have greatly promoted the development of inefficiency in the transportation network. In recent years, the above works have been extensively investigated in many aspects [28–36]. Guo et al. [37] gave two efficiency loss bounds of the SUE against SO and stochastic system optimum (SSO) in a stochastic circumstance, respectively. Considering a transportation network with multiple classes of users, Yu et al. [38] studied the inefficiency of the multiclass SUE, which is the extension of research achievements in [37]. Based on the above main work, some researchers have also studied the inefficiency of the extended logit-based SUE. Yong et al. provided several efficiency loss upper bounds of the CL-SUE by considering the overlapping effects between paths [39], which is also the extension of research achievements in [37]. Zeng and Wang initially explored inefficiency upper bound of CNL-SUE in the taxed stochastic transportation network and further investigated inefficiency upper bounds for the low-degree travel time function [40]. For a transportation network with heterogeneous users who have different values of time (VOT), the network optimization usually has two objectives, i.e., minimizing total system travel time (TSTT) and minimizing total system travel cost (TSTC). Guo and Yang further measured the system optimal performance difference by the two different criteria, i.e., time-based criteria and monetary-based criteria [41]. Yu and Wang [42] derived the accurate inefficiency bounds of multiclass SUE with elastic travel demand by making full use of equivalent VI under time-based criterion and cost-based criterion, respectively. Han and Yang [43] have given several bounds for the inefficiency of the multiclass traffic

equilibrium assignment problem in the tolled network under the two different criteria, respectively. Huang et al. [44] further discussed the efficiency loss of the SUE where all travelers are classified into two main categories, one equipped with advanced traveler information systems (ATIS) and another unequipped. Yu et al. studied the inefficiency of the mixed equilibrium with heterogeneous users [45–47].

Different from the existing studies, this study extends the logit-based SUE to the multiclass CL-SUE. The purpose of our study was to derive four efficiency loss upper bounds of the multiclass CL-SUE. The two corresponding models, i.e., multiclass SO model and multiclass C-Logit stochastic system optimum (CL-SSO) model, should be mentioned before exploring the efficiency loss of the multiclass CL-SUE. The multiclass SO model that minimizes the TSTT has been widely used in the literature. In this article, the multiclass CL-SSO model that minimizes the total perceived travel time (TPPT) is established based on the work in [39, 48, 49]. Therefore, there are four kinds of ways to define the efficiency loss of the multiclass CL-SUE, i.e., comparing multiclass CL-SUE with multiclass SO, or comparing multiclass CL-SUE with multiclass CL-SSO, under the time-based criterion and the monetary-based criterion, respectively. The highlights of our research focus on these four situations. In recent years, the effects of various parameters (e.g., degree of traffic congestion and total traffic demand of the network) on the inefficiency upper bound has been widely studied, while paying less attention to commonality factor reflecting path overlapping. This paper studies the effects of commonality factor reflecting path overlapping on the efficiency loss of the multiclass CL-SUE. The result shows that the commonality factor reflecting path overlapping has a significant impact on the inefficiency upper bound.

The rest of this article is organized below. In Section 2, we have a brief review of multiclass SUE and CL-SUE models, and then formulate the equivalent VI formulations of the multiclass CL-SUE model under time-based criterion and monetary-based criterion, respectively. In Sections 3 and 4, we derive four inefficiency upper bounds by using the equivalent VI formulations of the multiclass CL-SUE. Section 5 discusses the effects of various parameters on the efficiency loss bounds. In Section 6, we summarize the main research findings of this paper in tabular form. We give a numerical example to illustrate our conclusions in Section 7. Finally, Section 8 provides some conclusions and analyses the further research directions.

2. Review of Multiclass SUE and CL-SUE Models

2.1. Multiclass SUE Model. Let $G(N, A)$ be a directed transportation network defined by a set N of nodes and a set A of directed links. All travelers are classified in terms of different VOT into M classes. Table 1 provides the notations used in the paper:

According to Table 1, the following relationships and constraints hold:

TABLE 1: Notations.

Notation	Description
W	The set of origin-destination (OD) pairs
R_w	The set of all feasible paths connecting OD pair $w \in W$
$\beta_m (\beta_m > 0)$	The average VOT for users of class m
d_w^m	The travel demand of user class m between OD pair $w \in W$
f_{rw}^m	The flow of user class m on path $r \in R_w, w \in W$
f	Path flow vector, $f = (f_{rw}^m, r \in R_w, w \in W, m = 1, 2, \dots, M)^T$
v_a^m	The flow of user class m on link $a \in A$
v_a	The total flow on link $a \in A$
v	Link flow vector, $v = (v_a^m, a \in A, m = 1, 2, \dots, M)^T$
δ_{ar}^w	The link-path incidence indicator, which is equal to 1 if path $r \in R_w$ uses link $a \in A$, and 0 otherwise
Ω_f	Set of feasible path flow vectors, $\Omega_f = \{f f_{rw}^m \geq 0, \sum_{r \in R_w} f_{rw}^m = d_w^m, \forall r \in R_w, \forall w \in W, m = 1, 2, \dots, M\}$
Ω_v	Set of feasible link flow vectors, $\Omega_v = \{v f \in \Omega_f, v_a^m = \sum_{w \in W} \sum_{r \in R_w} f_{rw}^m \delta_{ar}^w, v_a = \sum_{m=1}^M v_a^m, \forall a \in A, m = 1, 2, \dots, M\}$
$t_a(v_a)$	The travel time function on link $a \in A$, which is supposed to be separable, convex, differentiable, and monotonically increasing with v_a
$c_a^m(v_a)$	The actual travel time of user class m on link $a \in A$, which is assumed to be a monotonically increasing function of v_a
c_{rw}^m	The actual travel time of user class m on path $r \in R_w, w \in W$

$$\begin{aligned}
v_a^m &= \sum_{w \in W} \sum_{r \in R_w} f_{rw}^m \delta_{ar}^w, \forall a \in A, m = 1, 2, \dots, M, \\
v_a &= \sum_{m=1}^M v_a^m, \forall a \in A, m = 1, 2, \dots, M, \\
\sum_{r \in R_w} f_{rw}^m &= d_w^m, \forall w \in W, m = 1, 2, \dots, M, \\
f_{rw}^m &\geq 0, \forall r \in R_w, w \in W, m = 1, 2, \dots, M, \\
c_{rw}^m &= \sum_{a \in A} c_a^m \delta_{ar}^w, \forall r \in R_w, w \in W, m = 1, 2, \dots, M.
\end{aligned} \tag{1}$$

In a multiclass SUE model, assume that all users are utility-maximizers. Let U_{rw}^m denote the travel utility perceived by user class m on path $r \in R_w, w \in W$. Then, U_{rw}^m is given by

$$U_{rw}^m = -\theta C_{rw}^m = -\theta c_{rw}^m + \xi_{rw}^m, r \in R_w, w \in W, m = 1, 2, \dots, M, \tag{2}$$

where C_{rw}^m is the perceived travel time of user class m on path $r \in R_w, w \in W$, θ is a positive unit scaling parameter, $-\theta c_{rw}^m$ is the measured utility, and ξ_{rw}^m is a random term representing the user's perception error. Let P_{rw}^m be the probability of user class m choosing path $r \in R_w, w \in W$, then the utility maximization theory shows that

$$P_{rw}^m = \Pr(U_{rw}^m \geq U_{kw}^m, \forall k \in R_w), r \in R_w, w \in W. \tag{3}$$

P_{rw}^m has the two properties as follows:

$$\begin{aligned}
0 &\leq P_{rw}^m \leq 1, r \in R_w, w \in W, m = 1, 2, \dots, M, \\
\sum_{r \in R_w} P_{rw}^m &= 1, w \in W, m = 1, 2, \dots, M.
\end{aligned} \tag{4}$$

All random terms ξ_{rw}^m in (2) are supposed to be IID Gumbel random variables. Then, the path choice probability for user class m is given by

$$P_{rw}^m = \frac{\exp(-\theta c_{rw}^m)}{\sum_{l \in R_w} \exp(-\theta c_{lw}^m)}, r \in R_w, w \in W, m = 1, 2, \dots, M. \tag{5}$$

and f_{rw}^m can be obtained by

$$f_{rw}^m = d_w^m P_{rw}^m, r \in R_w, w \in W, m = 1, 2, \dots, M. \tag{6}$$

Similar to that done in Fisk [12], the multiclass logit-based SUE model can be formulated as an equivalent MP problem below.

$$\min_{f \in \Omega_f} Z(f) = \sum_{a \in A} \int_0^{v_a} t_a(w) dw + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m. \tag{7}$$

The equivalent VI of problem (7) is presented in the lemma below.

Lemma 1. *If the link time function, $t_a(v_a)$, $a \in A$ is differentiable, convex, separable, and monotonically increasing with link flow v_a , a multiclass logit-based SUE model with fixed OD demand is equivalent to the following VI, i.e., find $\vec{f} \in \Omega_f$, such that*

$$\sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \left(c_{rw}^m(\vec{f}) + \frac{1}{\theta} \ln \vec{f}_{rw}^m \right) (f_{rw}^m - \vec{f}_{rw}^m) \geq 0, \forall f \in \Omega_f. \tag{8}$$

The disadvantages of the multiclass SUE model have been found by some researchers. One of the disadvantages is that it cannot explain the overlapping effects between different paths, which means that the unrealistic path choice probability is given.

2.2. Multiclass CL-SUE Model. Cascetta et al. [13] proposed a CL-SUE model, which can overcome the disadvantages of the logit-based SUE by using a commonality factor reflecting path

overlapping to modify the systematic part of the utility function. Similar to the work of Cascetta et al. [13], the multiclass CL-SUE model can be established. Then, the path choice probability of the multiclass CL-SUE model is provided by

$$P_{rw}^m = \frac{\exp(-\theta(c_{rw}^m + cf_{rw}))}{\sum_{l \in R_w} \exp(-\theta(c_{lw}^m + cf_{lw}))}, r \in R_w, w \in W, m = 1, 2, \dots, M, \quad (9)$$

where cf_{rw} is a commonality factor of path $r \in R_w, w \in W$. In this paper, the form of the commonality factor [13] is used as follows:

$$cf_{rw} = \beta_0 \ln \sum_{l \in R_w} \left(\frac{L_{rl}^w}{\sqrt{L_r^w \cdot L_l^w}} \right)^{\gamma_0}, \forall r \in R_w, w \in W, \quad (10)$$

where β_0 and γ_0 are the parameters; L_{rl}^w denotes the common length of paths r and l between the OD pair $w \in W$; and L_r^w and L_l^w denote the lengths of paths r and l between the OD pair $w \in W$, respectively. The length can be regarded as the free-flow travel time [14]. And f_{rw}^m is provided by

$$f_{rw}^m = d_w^m P_{rw}^m, r \in R_w, w \in W, m = 1, 2, \dots, M. \quad (11)$$

Similar to that done in Zhou et al. [14], the multiclass CL-SUE model can be formulated as an equivalent MP problem below.

$$\begin{aligned} \min_{f \in \Omega_f} Z(f) &= \sum_{a \in A} \int_0^{v_a} t_a(\omega) d\omega + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m \\ &+ \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m cf_{rw}. \end{aligned} \quad (12)$$

into (14), VI (13) can be obtained according to equation $\sum_{w \in W} \sum_{r \in R_w} \sum_{m \in M} 1/\theta (f_{rw}^m - \bar{f}_{rw}^m) = \sum_{w \in W} 1/\theta (d_w - \bar{d}_w) = 0$.

Under the time-based criterion, $c_a^m(v_a)$ is given by

$$c_a^m(v_a) = t_a(v_a), a \in A, m = 1, 2, \dots, M. \quad (16)$$

By contrast, under the monetary-based criterion, $c_a^m(v_a)$ can be given by

To find efficiency loss upper bounds of the multiclass CL-SUE, the equivalent VI of problem (12) is presented in the lemma below.

Lemma 2. *If the link time function, $t_a(v_a)$, $a \in A$ is differentiable, convex, separable, and monotonically increasing with link flow v_a , a multiclass CL-SUE model with fixed OD demand is equivalent to the following VI, i.e., find $\bar{f} \in \Omega_f$, such that*

$$\sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \left(c_{rw}^m(\bar{f}) + \frac{1}{\theta} \ln \bar{f}_{rw}^m + cf_{rw} \right) (f_{rw}^m - \bar{f}_{rw}^m) \geq 0, \forall f \in \Omega_f. \quad (13)$$

Proof of Lemma 2. Since $t_a(v_a)$ is monotonically increasing and Ω_f is compact, the objective function (12) is strictly convex. Hence, the path flow solution of the problem (12) is unique. The necessary and sufficient condition, which can guarantee that $\bar{f} \in \Omega_f$ is the unique optimal solution of problem (12), is provided as follows:

$$[\nabla_f Z(\bar{f})]^T (f - \bar{f}) \geq 0, \text{ for any } f \in \Omega_f. \quad (14)$$

Using $v_a = \sum_{m=1}^M v_a^m = \sum_{w \in W} \sum_{r \in R_w} \sum_{m \in M} f_{rw}^m \delta_{ar}^w$ and substituting

$$[\nabla_f Z(\bar{f})]^T = \left[\dots, \frac{1}{\theta} + \frac{1}{\theta} \ln \bar{f}_{rw}^m + \sum_{a \in A} t_a(\bar{v}_a) \delta_{ar}^w + cf_{rw}, \dots \right] = \left[\dots, \frac{1}{\theta} + \frac{1}{\theta} \ln \bar{f}_{rw}^m + c_{rw}^m(\bar{f}) + cf_{rw}, \dots \right]. \quad (15)$$

$$c_a^m(v_a) = \beta_m t_a(v_a), a \in A, m = 1, 2, \dots, M. \quad (17)$$

Substituting (16) and (17) into (13), respectively, and using (1), we can get the following time-based VI and monetary-based VI, respectively.

$$\begin{aligned} &\sum_{a \in A} t_a(\bar{v}) (v_a - \bar{v}_a) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M (\ln \bar{f}_{rw}^m + \theta cf_{rw}) (f_{rw}^m - \bar{f}_{rw}^m) \geq 0, \forall f \in \Omega_f, \\ &\sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\bar{v}) (v_a^m - \bar{v}_a^m) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M (\ln \bar{f}_{rw}^m + \theta cf_{rw}) (f_{rw}^m - \bar{f}_{rw}^m) \geq 0, \forall f \in \Omega_f. \end{aligned} \quad (18)$$

3. Bounding the Inefficiency of the Multiclass CL-SUE Compared with the Multiclass SO

3.1. *Time Units.* The multiclass SO problem in time units that minimizes the TSTT is presented as follows:

$$\min_{v \in \Omega_v} \sum_{a \in A} t_a(v_a) v_a. \quad (19)$$

Let $\hat{v} \in \Omega_v$ be the link flow solution of problem (19), the corresponding path flow solution is denoted by $\hat{f} \in \Omega_f$. Let $\bar{v}^t \in \Omega_v$ be the link flow solution of the VI (18), the corresponding path flow solution is denoted by $\bar{f}^t \in \Omega_f$. The efficiency loss of the multiclass CL-SUE compared with the multiclass SO under time-based criterion is defined as

$$\rho_{\text{CL-SUE}}^t = \frac{T_{\text{CL-SUE}}^t}{T_{\text{SO}}^t}, \quad (20)$$

where $T_{\text{CL-SUE}}^t = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c_{rw}^m (\bar{f}^t) \bar{f}_{rw}^{m,t} = \sum_{a \in A} t_a(\bar{v}_a^t) \bar{v}_a^t$ is the TSTT at the multiclass CL-SUE and $T_{\text{SO}}^t = \sum_{a \in A} t_a(\hat{v}_a) \hat{v}_a$ is the TSTT at the multiclass SO. Clearly, $\rho_{\text{CL-SUE}}^t \geq 1$.

Setting $\bar{f} = \bar{f}^t$ and $f = \hat{f}$ in VI (18), we can obtain inequality as follows:

$$\begin{aligned} & \sum_{a \in A} t_a(\bar{v}_a^t) (\hat{v}_a - \bar{v}_a^t) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \left(\ln \bar{f}_{rw}^{m,t} + \theta c f_{rw} \right) \\ & \cdot \left(\hat{f}_{rw}^m - \bar{f}_{rw}^{m,t} \right) \geq 0. \end{aligned} \quad (21)$$

This leads to

$$\begin{aligned} T_{\text{CL-SUE}}^t & \leq T_{\text{SO}}^t + \sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a)) \hat{v}_a \\ & + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \left(\ln \bar{f}_{rw}^{m,t} + \theta c f_{rw} \right) \left(\hat{f}_{rw}^m - \bar{f}_{rw}^{m,t} \right). \end{aligned} \quad (22)$$

Now, we begin to find the upper bound of the term $\sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a)) \hat{v}_a$ in (22). To achieve this, we give the same way which has been used in [37]. For completeness, a brief introduction is given here. Because $t_a(v_a)$ is increasing, we have $(t_a(\bar{v}_a^t) - t_a(v_a)) v_a \leq 0$ for $v_a \geq \bar{v}_a^t$. Hence, we just need to pay attention to $(t_a(\bar{v}_a^t) - t_a(v_a)) v_a$ for $v_a < \bar{v}_a^t$. As shown in Figure 1, let $t_a(\bar{v}_a^t) \bar{v}_a^t$ denote the area of the large rectangle and $(t_a(\bar{v}_a^t) - t_a(v_a)) v_a$ denote the area of the blue rectangle.

Next, an upper bound of the ratio $((t_a(\bar{v}_a^t) - t_a(v_a)) v_a) / (t_a(\bar{v}_a^t) \bar{v}_a^t)$ needs to be determined. To complete this, for each link time function $t_a = t_a(z_a)$ and nonnegative link flow $z_a \geq 0$, we let

$$\gamma_a(t_a, z_a) = \max_{v_a \geq 0} \frac{(t_a(z_a) - t_a(v_a)) v_a}{t_a(z_a) z_a}, a \in A. \quad (23)$$

Since $(t_a(z_a) - t_a(v_a)) v_a \leq t_a(z_a) v_a$ when $0 \leq v_a \leq z_a$ and $(t_a(z_a) - t_a(v_a)) v_a \leq 0$ when $v_a > z_a$, we can obtain

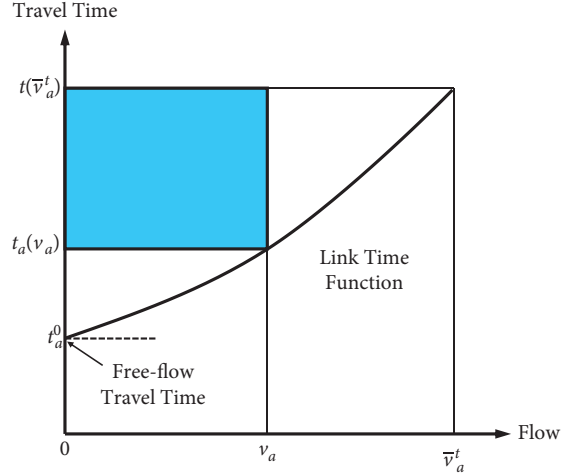


FIGURE 1: Geometric illustration of the definition of $\gamma(\varphi)$.

$0 \leq \gamma_a(t_a, z_a) \leq 1$. Let φ denote a class of link time functions, we define

$$\gamma(\varphi) = \max_{t_a \in \varphi, z_a \geq 0} \gamma_a(t_a, z_a) \quad (24)$$

With definitions (23) and (24), the lemma is given as follows:

Lemma 3. Let \bar{v}^t be link flow at the multiclass CL-SUE and v denote an arbitrary nonnegative link flow. Then,

$$\sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(v_a)) v_a \leq \gamma(\varphi) T_{\text{CL-SUE}}^t. \quad (25)$$

Proof of Lemma 3. Setting $z_a = \bar{v}_a^t$ in (23) and (24), we then obtain

$$\begin{aligned} \sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(v_a)) v_a & \leq \sum_{a \in A} \gamma_a(t_a, \bar{v}_a^t) t_a(\bar{v}_a^t) \bar{v}_a^t \\ & \leq \sum_{a \in A} \gamma(\varphi) t_a(\bar{v}_a^t) \bar{v}_a^t = \gamma(\varphi) T_{\text{CL-SUE}}^t. \end{aligned} \quad (26)$$

This completes the proof.

Let $v_a = \hat{v}_a$, we have

$$\sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a)) \hat{v}_a \leq \sum_{a \in A} \gamma(\varphi) t_a(\bar{v}_a^t) \bar{v}_a^t = \gamma(\varphi) T_{\text{CL-SUE}}^t. \quad (27)$$

We now begin to seek the upper bound on the third term of the right-hand side of (22). To achieve this, we give the lemma which has been proved in [39] below.

Lemma 4. The maximization problem is considered as follows:

$$\max F(x, y) = \sum_{i=1}^n (y_i - x_i) (\ln x_i + \theta c f_i), \quad (28)$$

subject to

$$\begin{aligned} \sum_{i=1}^n x_i &= d, \\ \sum_{i=1}^n y_i &= d, \end{aligned} \quad (29)$$

$$x_i, y_i \geq 0, i = 1, 2, \dots, n,$$

where $d > 0$ is a constant. $F_{\max} = kd$ is the maximum value of $F(x, y)$, where k solves equation $k \exp(k+1) = \sum_{i=1, i \neq j}^n \exp(\theta(cf_j - cf_i))$ and $j = \arg \max_i (cf_i, i = 1, 2, \dots, n)$.

From Lemma 4, we have

$$\sum_{r \in R_w} \left(\ln \bar{f}_{rw}^{m,t} + \theta c f_{rw} \right) \left(\hat{f}_{rw}^m - \bar{f}_{rw}^{m,t} \right) \leq k_w^{\text{CL-SUE}} d_w^m, \quad (30)$$

where $k_w^{\text{CL-SUE}}$ solves the equation $k \exp(k+1) = \sum_{r=1, r \neq j}^{|R_w|} \exp(\theta(cf_{jw} - cf_{rw}))$ with $j = \arg \max_r (cf_{rw}, r \in R_w)$, $w \in W$, and $|R_w|$ is the number of paths connecting OD pair $w \in W$. Substituting (27) and (30) into (22), it yields

$$T_{\text{CL-SUE}}^t \leq T_{\text{SO}}^t + \gamma(\varphi) T_{\text{CL-SUE}}^t + \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M k_w^{\text{CL-SUE}} d_w^m. \quad (31)$$

Let $D = \sum_{w \in W} \sum_{m=1}^M d_w^m$ denote the total traffic demand, $\bar{k} = \sum_{w \in W} \sum_{m=1}^M (d_w^m/D) k_w^{\text{CL-SUE}}$ be the average of $k_w^{\text{CL-SUE}}$, and $w \in W$. Then, we can rewrite (31) as

$$T_{\text{CL-SUE}}^t \leq T_{\text{SO}}^t + \gamma(\varphi) T_{\text{CL-SUE}}^t + \frac{1}{\theta} \bar{k} D. \quad (32)$$

In addition, we further define $\bar{c} = T_{\text{SO}}^t/D$ as the actual average travel time of all travelers at multiclass SO. Then, the theorem is presented as follows:

Theorem 1. *Let φ denote a class of differentiable, separable, convex, and monotonically increasing link time functions $t_a(v_a)$. Let $T_{\text{CL-SUE}}^t$ be the TSTT at the multiclass CL-SUE and T_{SO}^t be the TSTT at the multiclass SO under time-based criterion. Then,*

$$\rho_{\text{CL-SUE}}^t = \frac{T_{\text{CL-SUE}}^t}{T_{\text{SO}}^t} \leq \left(\frac{1}{1 - \gamma(\varphi)} \right) \left(1 + \frac{\bar{k}}{\theta \bar{c}} \right). \quad (33)$$

Furthermore, we can have the following corollary by comparing the efficiency loss upper bounds of the multiclass CL-SUE and the multiclass SUE.

Corollary 1. *In a transportation network, the efficiency loss upper bound against the multiclass SO by the multiclass CL-SUE under time-based criterion is not less than that by the multiclass SUE.*

Proof of Corollary 1. Let $\vec{v} \in \Omega_v$ be link flow solution of the VI (8), the corresponding path flow solution is denoted by

$\vec{f} \in \Omega_f$. $T_{\text{SUE}}^t = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c_{rw}^m(\vec{f}) \vec{f}_{rw}^m = \sum_{a \in A} t_a(\vec{v}_a) \vec{v}_a$ is the TSTT at the multiclass SUE. The inefficiency upper bound of the multiclass SUE against the multiclass SO under time-based criterion was given by Yu et al. [38], i.e.,

$$\rho_{\text{SUE}}^t = \frac{T_{\text{SUE}}^t}{T_{\text{SO}}^t} \leq \left(\frac{1}{1 - \gamma(\varphi)} \right) \left(1 + \frac{\bar{k}}{\theta \bar{c}} \right), \quad (34)$$

where $\bar{k} = \sum_{w \in W} \sum_{m=1}^M (d_w^m/D) k_w^{\text{SUE}}$ is the average of k_w^{SUE} , $w \in W$, and k_w^{SUE} solves the equation $k \exp(k+1) = |R_w| - 1, w \in W$.

We can see that the difference between (33) and (34) is only dependent upon the difference between \bar{k} and \bar{k} , or $k_w^{\text{CL-SUE}}$ and k_w^{SUE} . $k_w^{\text{CL-SUE}}$ is the solution of $k \exp(k+1) = \sum_{r=1, r \neq j}^{|R_w|} \exp(\theta(cf_{jw} - cf_{rw}))$ with $j = \arg \max_r (cf_{rw}, r \in R_w)$, $w \in W$. We always have $\sum_{r=1, r \neq j}^{|R_w|} \exp(\theta(cf_{jw} - cf_{rw})) \geq |R_w| - 1$, when $j = \arg \max_r (cf_{rw}, r \in R_w)$, $w \in W$. Since $f(k) = k \exp(k+1)$ is a nondecreasing function of k , we can obtain $k_w^{\text{CL-SUE}} \geq k_w^{\text{SUE}}$, which implies that $\bar{k} \geq \bar{k}$. Hence, the upper bound (33) is not less than the upper bound (34). This completes the proof.

The above analyses show that the commonality factor reflecting path overlapping has a significant impact on the inefficiency upper bound (33). Therefore, it is meaningful to study the efficiency loss of the multiclass CL-SUE model, which provides a more realistic upper bound than the multiclass SUE model by considering the path overlapping problem. \square

3.2. Monetary Units. The multiclass SO problem in monetary units that minimizes the TSTC is presented as follows:

$$\min_{v \in \Omega_v} \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(v_a) v_a^m. \quad (35)$$

Let $\vec{v} \in \Omega_v$ be link flow solution of problem (35), the corresponding path flow solution is denoted by $\vec{f} \in \Omega_f$. Let $\vec{v}^c \in \Omega_v$ be link flow solution of the VI (18), the corresponding path flow solution is denoted by $\vec{f}^c \in \Omega_f$. The efficiency loss of the multiclass CL-SUE compared with the multiclass SO under monetary-based criterion is defined as

$$\rho_{\text{CL-SUE}}^c = \frac{T_{\text{CL-SUE}}^c}{T_{\text{SO}}^c}, \quad (36)$$

where $T_{\text{CL-SUE}}^c = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c_{rw}^m(\vec{f}^c) \vec{f}_{rw}^{m,c} = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\vec{v}_a^c) \vec{v}_a^{m,c}$ is the TSTC at the multiclass CL-SUE and $T_{\text{SO}}^c = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\vec{v}_a) \vec{v}_a^m$ is the TSTC at the multiclass SO. Clearly, $\rho_{\text{CL-SUE}}^c \geq 1$.

Setting $\vec{f} = \vec{f}^c$ and $f = \vec{f}$ in VI (18), we can obtain inequality as follows:

$$\sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\bar{v}_a^c) (\bar{v}_a^m - \bar{v}_a^{m,c}) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M (\ln \bar{f}_{rw}^{m,c} + \theta c f_{rw}) (\bar{f}_{rw}^m - \bar{f}_{rw}^{m,c}) \geq 0. \quad (37)$$

This leads to

$$T_{\text{CL-SUE}}^c \leq T_{\text{SO}}^c + \sum_{a \in A} \sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a)) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M (\ln \bar{f}_{rw}^{m,c} + \theta c f_{rw}) (\bar{f}_{rw}^m - \bar{f}_{rw}^{m,c}). \quad (38)$$

To derive the upper bound of the term $\sum_{a \in A} \sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a))$ in (38), we need to define a new parameter [43]. For each link time function $t_a = t_a(z_a)$,

nonnegative link flow $z_a \geq 0$, and the VOT $\beta_m, m = 1, 2, \dots, M$, we define

$$\gamma_a(z_a, t_a, \beta) = \frac{1}{\left(\sum_{m=1}^M \beta_m z_a^m\right) t_a(z_a)} \max_{v_a^m \geq 0} \left\{ \left(\sum_{m=1}^M \beta_m v_a^m\right) (t_a(z_a) - t_a(v_a)) \right\}. \quad (39)$$

Here, suppose that $0/0 = 0$ always holds. For guaranteeing $\gamma_a(z_a, t_a, \beta) < 1$, we further define

$$\bar{\gamma}(\varphi, \beta) = \sup_{t_a \in \varphi, a \in A_1} \max_{\bar{v}_a^{m,c} \geq 0} \gamma_a(z_a, t_a, \beta), \quad (40)$$

where $A_1 = \{a \in A \mid \gamma_a(z_a, t_a, \beta) < 1\}$.

Define

$$\tilde{\gamma}(\varphi, \beta) = \sup_{t_a \in \varphi} g(z_a, t_a, \beta). \quad (41)$$

And

$$g(z_a, t_a, \beta) = \max_{v_a^m \geq 0, a \notin A_1} h(x) = \frac{\sum_{m=1}^M \beta_m v_a^m (t_a(z_a) - t_a(v_a))}{\sum_{m=1}^M \beta_m v_a^m t_a(v_a)}. \quad (42)$$

Hence, we can obtain $\bar{\gamma}(\varphi, \beta) > -1$. Furthermore, $h(x) \rightarrow -1$ when $v_a^m \rightarrow +\infty$ and $h(x) \rightarrow +\infty$ when $v_a^m \rightarrow 0, m = 1, 2, \dots, M$.

Let $v_a = \bar{v}_a$ and $z_a = \bar{v}_a^c$ in definition (39), we then have

$$\sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a)) \leq \gamma_a(\bar{v}_a^c, t_a, \beta) \sum_{m=1}^M \beta_m \bar{v}_a^{m,c} t_a(\bar{v}_a^c). \quad (43)$$

Thus, we can obtain

$$\sum_{a \in A} \sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a)) = \sum_{a \in A_1} \sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a)) + \sum_{a \notin A_1} \sum_{m=1}^M \beta_m \bar{v}_a^m (t_a(\bar{v}_a^c) - t_a(\bar{v}_a)) \leq \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{SO}}^c. \quad (44)$$

From Lemma 4, the upper bound on the last term of the right-hand side of (38) can be provided by

$$\sum_{r \in R_w} (\ln \bar{f}_{rw}^{m,c} + \theta c f_{rw}) (\bar{f}_{rw}^m - \bar{f}_{rw}^{m,c}) \leq k_w^{\text{CL-SUE}} d_w^m. \quad (45)$$

Substituting (44) and (45) into (38), it yields

$$T_{\text{CL-SUE}}^c \leq T_{\text{SO}}^c + \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{SO}}^c + \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M k_w^{\text{CL-SUE}} d_w^m. \quad (46)$$

In the same way, let $D = \sum_{w \in W} \sum_{m=1}^M d_w^m$ denote the total traffic demand, $\bar{k} = \sum_{w \in W} \sum_{m=1}^M (d_w^m / D) k_w^{\text{CL-SUE}}$ denote the average of $k_w^{\text{CL-SUE}}$, and $w \in W$. Then, we can rewrite (46) as

$$T_{\text{CL-SUE}}^c \leq T_{\text{SO}}^c + \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{SO}}^c + \frac{1}{\theta} \bar{k} D. \quad (47)$$

Furthermore, we define $\tilde{c} = T_{\text{SO}}^c / D$ as the actual average travel cost of all travelers at multiclass SO. Then, the theorem is presented as follows.

Theorem 2. Let φ denote a class of differentiable, separable, convex, and monotonically increasing link time functions $t_a(v_a)$. Let $T_{\text{CL-SUE}}^c$ be the TSTC at the multiclass CL-SUE and T_{SO}^c be the TSTC at the multiclass SO under monetary-based criterion. Then,

$$\rho_{\text{CL-SUE}}^c = \frac{T_{\text{CL-SUE}}^c}{T_{\text{SO}}^c} \leq \frac{1 + \bar{\gamma}(\varphi, \beta) + \bar{k}/\theta\bar{c}}{1 - \bar{\gamma}(\varphi, \beta)}. \quad (48)$$

4. Bounding the Inefficiency of the Multiclass CL-SUE Compared with the Multiclass CL-SSO

Before analyzing the inefficiency of the multiclass CL-SUE against the multiclass CL-SSO, we first give a brief introduction to the corresponding multiclass CL-SSO model. Considering commonality factor reflecting path overlapping, we establish the multiclass CL-SSO model, which is the extension of research achievements in [39, 48]. The

definition of SSO given by Maher et al. [48] states that the SSO problem is to minimize the TPTT. Therefore, the multiclass CL-SSO problem is also to minimize the TPTT. For the multiclass CL-SUE model, the TPTT in the transportation network can be provided by (the process of proof is shown in Appendix A)

$$F(f) = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m (c_{rw}^m(f) + c f_{rw}) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \quad (49)$$

Substituting (16) and (17) into (49), respectively, and in view of (1), the minimization of TPTT can be formulated as the following minimization problem under time-based criterion and monetary-based criterion, respectively.

$$\min_{f \in \Omega_f} F^t(f) = \sum_{a \in A} t_a(v_a) v_a + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} f_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \quad (50)$$

$$\min_{f \in \Omega_f} F^c(f) = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(v_a) v_a^m + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} f_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \quad (51)$$

Let $\hat{f} \in \Omega_f$ be path flow solution of problem (50), the corresponding link flow solution is denoted by $\hat{v} \in \Omega_v$. Then, the minimum TPTT is denoted by $F_{\text{CL-SSO}}^t = F^t(\hat{f})$. Let $\tilde{f} \in \Omega_f$ be path flow solution of problem (51), the

corresponding link flow solution is denoted by $\tilde{v} \in \Omega_v$. Then, the minimum total perceived travel cost (TPTC) is denoted by $F_{\text{CL-SSO}}^c = F^c(\tilde{f})$. They are given by

$$F_{\text{CL-SSO}}^t = \sum_{a \in A} t_a(\hat{v}_a) \hat{v}_a + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \hat{f}_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \hat{f}_{rw}^m \ln \hat{f}_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \quad (52)$$

$$F_{\text{CL-SSO}}^c = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\tilde{v}_a) \tilde{v}_a^m + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \tilde{f}_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \tilde{f}_{rw}^m \ln \tilde{f}_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \quad (53)$$

Correspondingly, let $F_{\text{CL-SUE}}^t$ and $F_{\text{CL-SUE}}^c$ denote the TPTT and the TPTC at the multiclass CL-SUE, respectively. Then, we have

$$F_{\text{CL-SUE}}^t = \sum_{a \in A} t_a(\bar{v}_a^t) \bar{v}_a^t + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \bar{f}_{rw}^{m,t} + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \bar{f}_{rw}^{m,t} \ln \bar{f}_{rw}^{m,t} - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m, \quad (54)$$

$$F_{\text{CL-SUE}}^c = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\bar{v}_a^c) \bar{v}_a^{m,c} + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \bar{f}_{rw}^{m,c} + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \bar{f}_{rw}^{m,c} \ln \bar{f}_{rw}^{m,c} - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m.$$

By definition, we easily have $F_{\text{CL-SUE}}^t \geq F_{\text{CL-SSO}}^t$ and $F_{\text{CL-SUE}}^c \geq F_{\text{CL-SSO}}^c$. However, it can be found from (52)–(54) that $F_{\text{CL-SSO}}^t, F_{\text{CL-SSO}}^c, F_{\text{CL-SUE}}^t$, and $F_{\text{CL-SUE}}^c$ may be negative, which implies that the ratio $F_{\text{CL-SUE}}^t/F_{\text{CL-SSO}}^t$ and $F_{\text{CL-SUE}}^c/F_{\text{CL-SSO}}^c$ may be meaningless. Therefore, instead of using the ratio $F_{\text{CL-SUE}}^t/F_{\text{CL-SSO}}^t$ and $F_{\text{CL-SUE}}^c/F_{\text{CL-SSO}}^c$, we use the terms $F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t \geq 0$ and $F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c \geq 0$ to quantify the absolute inefficiency of the multiclass CL-SUE against the multiclass CL-SSO under time-based

criterion and monetary-based criterion, respectively. They are defined as

$$\begin{aligned}\rho_{\text{CL-SUE/CL-SSO}}^t &= F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t, \\ \rho_{\text{CL-SUE/CL-SSO}}^c &= F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c.\end{aligned}\quad (55)$$

4.1. Time Units. Setting $\bar{f} = \bar{f}^t$ and $f = \hat{f}$ in VI (18), we can obtain inequality as follows:

$$\sum_{a \in A} t_a(\bar{v}_a^t)(\hat{v}_a - \bar{v}_a^t) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \left(\ln \bar{f}_{rw}^{m,t} + \theta c f_{rw} \right) (\hat{f}_{rw}^m - \bar{f}_{rw}^{m,t}) \geq 0. \quad (56)$$

This leads to

$$\begin{aligned}\sum_{a \in A} t_a(\bar{v}_a^t)\hat{v}_a + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \bar{f}_{rw}^{m,t} + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \bar{f}_{rw}^{m,t} \ln \bar{f}_{rw}^{m,t} &\leq \sum_{a \in A} t_a(\hat{v}_a)\hat{v}_a + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \hat{f}_{rw}^m \\ &+ \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \hat{f}_{rw}^m \ln \hat{f}_{rw}^m + \sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a))\hat{v}_a \\ &+ \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \hat{f}_{rw}^m (\ln \bar{f}_{rw}^{m,t} - \ln \hat{f}_{rw}^m).\end{aligned}\quad (57)$$

Thus,

$$F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t \leq \sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a))\hat{v}_a + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \hat{f}_{rw}^m (\ln \bar{f}_{rw}^{m,t} - \ln \hat{f}_{rw}^m). \quad (58)$$

We can get the upper bound of the term $\sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a))\hat{v}_a$ in (58) from Lemma 3. Let $v_a = \hat{v}_a$, we can obtain inequality below.

$$\sum_{a \in A} (t_a(\bar{v}_a^t) - t_a(\hat{v}_a))\hat{v}_a \leq \gamma(\varphi) T_{\text{CL-SUE}}^t. \quad (59)$$

The upper bound on the last term of the right-hand side of (58) is equal to zero from Gibbs' inequality. Therefore, the following inequality holds:

$$\sum_{r \in R_w} \hat{f}_{rw}^m (\ln \bar{f}_{rw}^{m,t} - \ln \hat{f}_{rw}^m) \leq 0, w \in W, m \in M. \quad (60)$$

Here, $\sum_{r \in R_w} \hat{f}_{rw}^m (\ln \bar{f}_{rw}^{m,t} - \ln \hat{f}_{rw}^m) = 0$ if and only if $\bar{f}_{rw}^{m,t} = \hat{f}_{rw}^m$. Substituting (59) and (60) into (58), the following theorem can be obtained.

Theorem 3. Let φ denote a class of differentiable, separable, convex, and monotonically increasing link time functions $t_a(v_a)$. Then, the absolute inefficiency of the multiclass CL-SUE against the multiclass CL-SSO under time-based criterion, $\rho_{\text{CL-SUE/CL-SSO}}^t$, is upper bounded, i.e.,

$$\rho_{\text{CL-SUE/CL-SSO}}^t = F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t \leq \gamma(\varphi) T_{\text{CL-SUE}}^t. \quad (61)$$

We now begin to discuss the tightness of the bound given in (61) and provide Corollary 2 (the similar process of proof is shown in Guo et al. [37]).

Corollary 2. $F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t = \gamma(\varphi) T_{\text{CL-SUE}}^t$ if and only if $\gamma(\varphi) = 0$.

Corollary 2 It states that the upper bound (61) is tight if and only if $\gamma(\varphi) = 0$ (without traffic congestion). Here, we have $\bar{f}^t = f$ and $F_{\text{CL-SUE}}^t = F_{\text{CL-SSO}}^t$. However, traffic

congestion is a common phenomenon in a realistic transportation network. As a result, we always have $F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t < \gamma(\varphi)T_{\text{CL-SUE}}^t$, which means that the upper bound (61) is usually not tight in most cases.

4.2. *Monetary Units.* Setting $\bar{f} = \bar{f}^c$ and $f = \tilde{f}$ in VI (18), we can obtain the inequality as follows:

$$\sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\bar{v}_a^c) (\tilde{v}_a^m - \bar{v}_a^{m,c}) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M (\ln \bar{f}_{rw}^{m,c} + \theta c f_{rw}) (\tilde{f}_{rw}^m - \bar{f}_{rw}^{m,c}) \geq 0. \quad (62)$$

This leads to

$$\begin{aligned} \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\bar{v}_a^c) \bar{v}_a^{m,c} + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \bar{f}_{rw}^{m,c} + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \bar{f}_{rw}^{m,c} \ln \bar{f}_{rw}^{m,c} &\leq \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\tilde{v}_a) \tilde{v}_a^m + \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c f_{rw} \tilde{f}_{rw}^m \\ &+ \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \tilde{f}_{rw}^m \ln \tilde{f}_{rw}^m \\ &+ \sum_{a \in A} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a)) \\ &+ \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \tilde{f}_{rw}^m (\ln \bar{f}_{rw}^{m,c} - \ln \tilde{f}_{rw}^m). \end{aligned} \quad (63)$$

Thus,

$$F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c \leq \sum_{a \in A} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a)) + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M \tilde{f}_{rw}^m (\ln \bar{f}_{rw}^{m,c} - \ln \tilde{f}_{rw}^m). \quad (64)$$

We can get the upper bound of the term $\sum_{a \in A} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a))$ in (64) by applying the definitions (39)–(42). Let v_a be \tilde{v}_a and z_a be \bar{v}_a^c , then we have

$$\sum_{a \in A} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a)) = \sum_{a \in A_1} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a)) + \sum_{a \notin A_1} \sum_{m=1}^M \beta_m \tilde{v}_a^m (t_a(\bar{v}_a^c) - t_a(\tilde{v}_a)) \leq \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{CL-SSO}}^c, \quad (65)$$

where $T_{\text{CL-SSO}}^c = \sum_{a \in A} \sum_{m=1}^M \beta_m t_a(\tilde{v}_a) \tilde{v}_a^m$ is the TSTC at the multiclass CL-SSO.

The upper bound on the last term of the right-hand side of (64) is equal to zero from Gibbs' inequality. Therefore, the following inequality holds:

$$\sum_{r \in R_w} \tilde{f}_{rw}^m (\ln \bar{f}_{rw}^{m,c} - \ln \tilde{f}_{rw}^m) \leq 0, w \in W, m \in M. \quad (66)$$

Here, $\sum_{r \in R_w} \tilde{f}_{rw}^m (\ln \bar{f}_{rw}^{m,c} - \ln \tilde{f}_{rw}^m) = 0$ if and only if $\bar{f}_{rw}^{m,c} = \tilde{f}_{rw}^m$. Substituting (65) and (66) into (64), we can obtain the theorem as follows.

Theorem 4. Let φ denote a class of differentiable, separable, convex, and monotonically increasing link time functions $t_a(v_a)$. Then, the absolute inefficiency of the multiclass CL-SUE against the multiclass CL-SSO under monetary-based criterion, $\rho_{\text{CL-SUE/CL-SSO}}^c$, is upper bounded, i.e.,

$$\begin{aligned} \rho_{\text{CL-SUE/CL-SSO}}^c &= F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c \\ &\leq \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{CL-SSO}}^c. \end{aligned} \quad (67)$$

Next, we will discuss the tightness of the bound given in (67) and provide Corollary 3 as follows.

Corollary 3. $F_{CL-SUE}^c - F_{CL-SSO}^c = \bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c$ if and only if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$.

Proof of Corollary 3. Firstly, if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$, we can obtain $F_{CL-SUE}^c - F_{CL-SSO}^c \leq 0$ from Theorem 4. According to the definition of the multiclass CL-SSO, we have $F_{CL-SUE}^c \geq F_{CL-SSO}^c$. Hence, we can obtain $F_{CL-SUE}^c = F_{CL-SSO}^c$, which means that $F_{CL-SUE}^c - F_{CL-SSO}^c = 0$. Since $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$, we have $\bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c = 0$. Therefore, $F_{CL-SUE}^c - F_{CL-SSO}^c = \bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c$ if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$. Secondly, we assume that $F_{CL-SUE}^c - F_{CL-SSO}^c = \bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c$ holds. From the specific derivation process of (67), $F_{CL-SUE}^c - F_{CL-SSO}^c = \bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c$ implies that inequality (66) takes equality; i.e., $\bar{f}^c = f$. Since $\bar{f}^c = \tilde{f}$, we can have $\bar{v}^c = \tilde{v}$, $F_{CL-SUE}^c = F_{CL-SSO}^c$, and $T_{CL-SUE}^c = T_{CL-SSO}^c$. With definitions (39)–(42), if $\bar{v}^c = \tilde{v}$ holds, we can obtain $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$. The proof is completed.

Corollary 3 shows that the upper bound (67) is tight if and only if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$. The expression $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$ means that the multiclass CL-SUE state is equivalent to the multiclass CL-SSO state. Here, we have $\bar{f}^c = f$, $\bar{v}^c = \tilde{v}$, $F_{CL-SUE}^c = F_{CL-SSO}^c$, and $T_{CL-SUE}^c = T_{CL-SSO}^c$, which are usually not satisfied in a realistic transportation network. As a result, we always have $F_{CL-SUE}^c - F_{CL-SSO}^c < \bar{\gamma}(\varphi, \beta) T_{CL-SUE}^c + \tilde{\gamma}(\varphi, \beta) T_{CL-SSO}^c$, which means that the upper bound (67) is usually not tight in most cases. \square

5. Effects of Parameters on the Inefficiency Bounds

This section discusses the effects of various parameters on the upper bounds (33), (48), (61), and (67), namely, $\gamma(\varphi)$, $\bar{\gamma}(\varphi, \beta)$, $\tilde{\gamma}(\varphi, \beta)$, \bar{k} , θ , \bar{c} , and $\bar{\tau}$.

$\gamma(\varphi) \in [0, 1]$ is a dimensionless coefficient defined only by the class of link time functions. Both the upper bounds (33) and (61) are monotonically increasing functions of $\gamma(\varphi)$. Consider a widely used class of link travel time functions, $t_a(v_a) = t_a^0 + \alpha_a(v_a)^p$, $a \in A$, where $t_a^0 \geq 0$ denotes free-flow travel time on link $a \in A$, $\alpha_a \geq 0$ is a constant, and $p \geq 0$ reflects the degree of traffic congestion. Roughgarden [27] provided a specific expression of $\gamma(\varphi)$ as follows:

$$\gamma(\varphi) = \left(\frac{p}{p+1} \right) \left(\frac{1}{p+1} \right)^{1/p}. \quad (68)$$

Equation (68) shows that $\gamma(\varphi) \rightarrow 0$ when $p \rightarrow 0$ (without traffic congestion) and $\gamma(\varphi) \rightarrow 0$ when $p \rightarrow +\infty$ (with severe congestion). When $p = 1$ and 4, $\gamma(\varphi) = 0.25$ and 0.535, respectively. So, the upper bounds (33) and (61) are both monotonically increasing functions of p . When the value of p can be reduced, we will have more space to improve the congestion in the traffic network by driving the multiclass CL-SUE state to the multiclass SO or the multiclass CL-SSO state.

Both $\bar{\gamma}(\varphi, \beta)$ and $\tilde{\gamma}(\varphi, \beta)$ are dimensionless coefficients depending on the class of link time functions and VOT β .

Both the upper bounds (48) and (67) are monotonically increasing functions of $\bar{\gamma}(\varphi, \beta)$ and $\tilde{\gamma}(\varphi, \beta)$.

Recall that k_w^{CL-SUE} solves the equation $k \exp(k+1) = \sum_{r=1, r \neq j}^{|R_w|} \exp(\theta(cf_{jw} - cf_{rw}))$ with $j = \arg \max r(cf_{rw}, r \in R_w)$, $w \in W$, and $\bar{k} = \sum_{w \in W} \sum_{m=1}^M (d_w^m/D) k_w^{CL-SUE}$. So, \bar{k} is a dimensionless coefficient, which increases with the relative values of the commonality factors of paths and the number of feasible paths. Hence, \bar{k} can reflect the degree of network complexity. Let $j' = \arg \min r(cf_{rw}, r \in R_w)$, $w \in W$, then we have $k_w^{CL-SUE} \exp(k_w^{CL-SUE} + 1) \leq (|R_w| - 1) \exp(\theta(cf_{jw} - cf_{j'w}))$. If each OD pair has only one available path in a transportation network, i.e., $|R_w| = 1$, we can obtain $k_w^{CL-SUE} = 0$ and thus $\bar{k} = 0$. When $|R_w| = 1$, we have $\rho_{CL-SUE}^c \leq (1 - \gamma(\varphi))^{-1}$ and $\rho_{CL-SUE}^c \leq (1 + \tilde{\gamma}(\varphi, \beta)) / (1 - \bar{\gamma}(\varphi, \beta))$. When $|R_w| > 1$, the value of k_w^{CL-SUE} (and hence \bar{k}) is greatly limited only if values of θ and cf_{rw} are given (the similar discussion is shown in Guo et al. [37]). Even though the effect is small, both the upper bounds (33) and (48) are increasing with the degree of network complexity.

Parameter θ is the perception error of travel time, which can reflect the degree of network familiarity. Both the upper bounds (33) and (48) decrease with θ . When $\theta \rightarrow +\infty$, we have $\rho_{CL-SUE}^c \leq (1 - \gamma(\varphi))^{-1}$ and $\rho_{CL-SUE}^c \leq (1 + \tilde{\gamma}(\varphi, \beta)) / (1 - \bar{\gamma}(\varphi, \beta))$, which are the results of the standard multiclass UE problem under time-based criterion and monetary-based criterion, respectively.

Theorems 1 and 2 show that the upper bound (33) decreases with \bar{c} and the upper bound (48) decreases with $\bar{\tau}$, respectively. Since $\bar{c} = T_{SO}^t/D$ and $\bar{\tau} = T_{SO}^c/D$, both the upper bounds (33) and (48) will increase when the total demand, D , goes up.

Finally, the results of the above discussions are summarized in Table 2.

6. Summary of the Main Research Findings

In Sections 3 and 4, we have derived four inefficiency bounds of the multiclass CL-SUE, and given four theorems. In this section, we provide a table to summarize the main research findings of four theorems in this article. These findings are shown in Table 3.

7. Numerical Example

The Nguyen and Dupuis network [50] shown in Figure 2 is used to further illustrate the above conclusions. The network consists of 19 links, 13 nodes, 25 paths, and 4 OD pairs. All users are classified on the basis of different VOTs into three main classes. Let $\beta_1 = 1.0$ (¥/min) (denoted by “1”) be VOT for users of class 1, $\beta_2 = 2.0$ (¥/min) (denoted by “2”) be VOT for users of class 2, and $\beta_3 = 3.0$ (¥/min) (denoted by “3”) be VOT for users of class 3. As shown in Figure 2, the network has 4 OD pairs: 1 \rightarrow 2 (denoted by “ w_1 ”), 1 \rightarrow 3 (denoted by “ w_2 ”), 4 \rightarrow 2 (denoted by “ w_3 ”), and 4 \rightarrow 3 (denoted by “ w_4 ”). Suppose that the traffic demand is $d_{w_1}^1 = 120$, $d_{w_1}^2 = 200$, $d_{w_1}^3 = 80$, $d_{w_2}^1 = 240$, $d_{w_2}^2 = 400$,

TABLE 2: Effects of various parameters on the upper bounds.

	Congestion degree	$\bar{\gamma}(\varphi, \beta)$	$\tilde{\gamma}(\varphi, \beta)$	Network complexity	Network familiarity	Total demand
Bound (33)	+	No	No	+	—	+
Bound (48)	No	+	+	+	—	+
Bound (61)	+	No	No	No	No	No
Bound (67)	No	+	+	No	No	No

TABLE 3: The main research findings of four theorems.

Theorem	The upper bounds	Main research findings
Theorem 1	$\rho_{\text{CL-SUE}}^t = T_{\text{CL-SUE}}^t / T_{\text{SO}}^t \leq (1 / (1 - \gamma(\varphi))) (1 + \bar{k} / (\theta \bar{c}))$	(1) The upper bound (33) depends on four parameters, namely, $\gamma(\varphi)$, \bar{k} , θ , and \bar{c} .(2) Corollary 1: in a transportation network, the efficiency loss upper bound against the multiclass SO by the multiclass CL-SUE under time-based criterion is not less than that by the multiclass SUE. Corollary 1 shows that the multiclass CL-SUE model provides a more realistic upper bound than the multiclass SUE model by considering the path overlapping problem.
Theorem 2	$\rho_{\text{CL-SUE}}^c = T_{\text{CL-SUE}}^c / T_{\text{SO}}^c \leq (1 + \bar{\gamma}(\varphi, \beta) + \bar{k} / (\theta \bar{c})) / (1 - \bar{\gamma}(\varphi, \beta))$	(1) The upper bound (48) depends on five parameters, namely, $\bar{\gamma}(\varphi, \beta)$, $\tilde{\gamma}(\varphi, \beta)$, \bar{k} , θ , and \bar{c} .(2) Similar to the proof of Corollary 1, we can find that the efficiency loss upper bound against the multiclass SO by the multiclass CL-SUE under monetary-based criterion is not less than that by the multiclass SUE.
Theorem 3	$\rho_{\text{CL-SUE/CL-SSO}}^t = F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t \leq \gamma(\varphi) T_{\text{CL-SUE}}^t$	(1) The upper bound (61) depends on two parameters, namely, $\gamma(\varphi)$ and $T_{\text{CL-SUE}}^t$. The commonality factor reflecting path overlapping has no impact on the inefficiency upper bound (61).(2) Corollary 2 ($F_{\text{CL-SUE}}^t - F_{\text{CL-SSO}}^t = \gamma(\varphi) T_{\text{CL-SUE}}^t$ if and only if $\gamma(\varphi) = 0$). It states that the upper bound (61) is tight if and only if $\gamma(\varphi) = 0$ (without traffic congestion), which means that the upper bound (61) is usually not tight in most cases.
Theorem 4	$\rho_{\text{CL-SUE/CL-SSO}}^c = F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c \leq \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{CL-SSO}}^c$	(1) The upper bound (67) depends on four parameters, namely, $\bar{\gamma}(\varphi, \beta)$, $\tilde{\gamma}(\varphi, \beta)$, $T_{\text{CL-SUE}}^c$, and $T_{\text{CL-SSO}}^c$. The commonality factor reflecting path overlapping has no impact on the inefficiency upper bound (67).(2) Corollary 3 ($F_{\text{CL-SUE}}^c - F_{\text{CL-SSO}}^c = \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \tilde{\gamma}(\varphi, \beta) T_{\text{CL-SSO}}^c$ if and only if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$): It shows that the upper bound (67) is tight if and only if $\bar{\gamma}(\varphi, \beta) = \tilde{\gamma}(\varphi, \beta) = 0$, which means that the upper bound (67) is usually not tight in most cases.

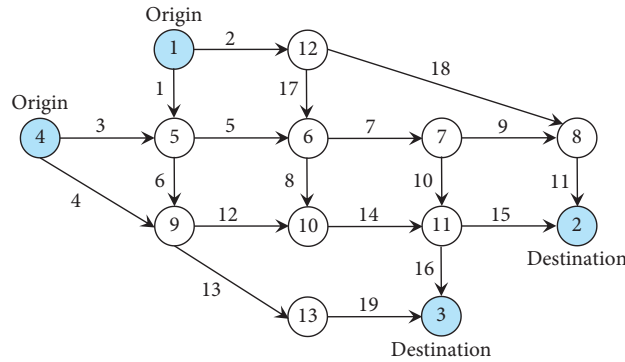


FIGURE 2: Nguyen and Dupuis network.

TABLE 4: Parameters of links.

Link no.	Free-flow travel time	Capacity	Link no.	Free-flow travel time	Capacity
1	7	900	11	10	700
2	8	700	12	10	700
3	9	700	13	9	600
4	14	900	14	8	700
5	5	800	15	9	700
6	9	600	16	8	700
7	5	900	17	7	300
8	13	500	18	15	700
9	5	300	19	11	700
10	9	400			

$d_{w_2}^3 = 160$, $d_{w_3}^1 = 180$, $d_{w_3}^2 = 300$, $d_{w_3}^3 = 120$, $d_{w_4}^1 = 60$, $d_{w_4}^2 = 100$, and $d_{w_4}^3 = 40$. Assume that parameters $\theta = 0.5$, $\beta_0 = 1$, and $\gamma_0 = 1$.

The link time functions use the following BPR (Bureau of Public Road) form, with free-flow travel time t_a^0 and link capacity C_a provided in Table 4:

$$t_a(v_a) = t_a^0 \left[1 + 0.15 \times \left(\frac{v_a}{C_a} \right)^4 \right]. \quad (69)$$

The relationship between paths and nodes in the network is shown in Table 5. The commonality factor cf_{rw} can be calculated by (10). In this paper, the free-flow travel time is used instead of length to calculate cf_{rw} . The results are also shown in Table 5.

The link flow, path flow, and path cost solutions of the multiclass CL-SUE model are shown in Tables 6 and 7 by solving VI (18), respectively. The link flow solutions of the multiclass SO and CL-SSO models are shown in Table 8 by solving the minimization problems (19), (35), (50), and (51).

From Tables 6 and 7, we can obtain $T_{CL-SUE}^t = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c_{rw}^m(\bar{f}^t) \bar{f}_{rw}^{m,t} = 86316.9550$, $T_{CL-SUE}^c = \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M c_{rw}^m(\bar{f}^c) \bar{f}_{rw}^{m,c} = 171413.1091$, $F_{CL-SUE}^t = 74528.8734$, and $F_{CL-SUE}^c = 144177.3510$. From Table 8, we can obtain $T_{SO}^t = 77678.1637$, $T_{SO}^c = 146623.4458$, $T_{CL-SUE}^c = 145869.2905$, $F_{CL-SSO}^t = 74296.2072$, and $F_{CL-SSO}^c = 143566.4683$. Thus, we have $\rho_{CL-SUE}^t = T_{CL-SUE}^t / T_{SO}^t = 1.1112$, $\rho_{CL-SUE}^c = T_{CL-SUE}^c / T_{SO}^c = 1.1691$, $\rho_{CL-SUE/CL-SSO}^t = F_{CL-SUE}^t - F_{CL-SSO}^t = 232.6662$, and $\rho_{CL-SUE/CL-SSO}^c = F_{CL-SUE}^c - F_{CL-SSO}^c = 610.8827$.

For the link time function with $p = 4$ in this example, it is easy to obtain that $\gamma(\varphi) = 0.535$. Since k_{w}^{CL-SUE} is the solution of $k \exp(k+1) = \sum_{r=1, r \neq j}^{|R_w|} \exp(\theta(cf_{jw} - cf_{rw}))$ with $j = \arg \max_r (cf_{rw}, r \in R_w)$, $w \in W$, then we can obtain $k_{w_1}^{CL-SUE} = 1.0767$, $k_{w_2}^{CL-SUE} = 0.9412$, $k_{w_3}^{CL-SUE} = 0.8441$, and $k_{w_4}^{CL-SUE} = 0.9469$. Hence, we can have $\bar{k} = 0.9397$ by $\bar{k} = \sum_{w \in W} \sum_{m=1}^M (d_w^m / D) k_w^{CL-SUE}$ and $D = \sum_{w \in W} \sum_{m=1}^M d_w^m$. We can also obtain $\bar{c} = 38.8391$ and $\tilde{c} = 73.3117$ by $\bar{c} = T_{SO}^t / D$ and $\tilde{c} = T_{SO}^c / D$, respectively.

From Table 7, we can have $\bar{v}_1^{1,c} = 222.2$, $\bar{v}_1^{2,c} = 392.4$, $\bar{v}_1^{3,c} = 159.5$, and $\bar{v}_1^c = 774.1$. Based on definition $\gamma_a(z_a, t_a, \beta) = [1 / ((\sum_{m=1}^M \beta_m z_a^m) t_a(z_a))] \max_{v_a^m \geq 0} \{ (\sum_{m=1}^M \beta_m v_a^m) (t_a(z_a) - t_a$

TABLE 5: Parameters between four OD pairs.

OD pair	Path no.	Node sequence	The value of cf_{rw}
1-2	1	1-12-8-2	0.8202
	2	1-5-6-7-8-2	1.1226
	3	1-5-6-7-11-2	1.2437
	4	1-5-6-10-11-2	1.2105
	5	1-5-9-10-11-2	1.0206
	6	1-12-6-7-8-2	1.1621
	7	1-12-6-7-11-2	1.2744
	8	1-12-6-10-11-2	1.2439
1-3	9	1-5-9-13-3	0.5843
	10	1-5-6-7-11-3	1.0851
	11	1-5-6-10-11-3	1.1507
	12	1-5-9-10-11-3	1.0777
	13	1-12-6-7-11-3	0.9550
	14	1-12-6-10-11-3	1.0409
4-2	15	4-9-10-11-2	0.8153
	16	4-5-6-7-8-2	0.7551
	17	4-5-6-7-11-2	1.0217
	18	4-5-6-10-11-2	1.0704
	19	4-5-9-10-11-2	1.0592
4-3	20	4-9-13-3	0.6606
	21	4-9-10-11-3	0.9540
	22	4-5-9-13-3	0.9012
	23	4-5-6-7-11-3	0.8922
	24	4-5-6-10-11-3	1.0088
	25	4-5-9-10-11-3	1.1190

$(v_a))$ and $t_1(v_1) = 7[1 + 0.15 \times (v_1/900)^4]$, we can obtain $\gamma_1(z_1, t_1, \beta) = (\max_{v_a^m \geq 0} \{ (1 \cdot v_1^1 + 2 \cdot v_1^2 + 3 \cdot v_1^3) [7.5748 - 7(1 + 0.15(v_1/900)^4)] \}) / ((1 \cdot 222.17 + 2 \cdot 392.44 + 3 \cdot 159.53) \cdot 7.5748)$. When $v_1^1 = 0$, $v_1^2 = 0$, $v_1^3 = 517.7044$, and $v_1 = 517.7044$, the above optimization problem reaches at the maximum $\gamma_1(z_1, t_1, \beta) = 0.0635$. By the same way, we obtain $\gamma_2(z_2, t_2, \beta) = 0.0173$, $\gamma_3(z_3, t_3, \beta) = 0.0212$, $\gamma_4(z_4, t_4, \beta) = 0.0029$, $\gamma_5(z_5, t_5, \beta) = 0.0253$, $\gamma_6(z_6, t_6, \beta) = 0.1694$, $\gamma_7(z_7, t_7, \beta) = 0.0179$, $\gamma_8(z_8, t_8, \beta) = 0.000012$, $\gamma_9(z_9, t_9, \beta) = 0.2739$, $\gamma_{10}(z_{10}, t_{10}, \beta) = 0.0027$, $\gamma_{11}(z_{11}, t_{11}, \beta) = 0.1540$, $\gamma_{12}(z_{12}, t_{12}, \beta) = 0.0007$, $\gamma_{13}(z_{13}, t_{13}, \beta) = 0.3058$, $\gamma_{14}(z_{14}, t_{14}, \beta) = 0.0015$, $\gamma_{15}(z_{15}, t_{15}, \beta) = 0.0014$, $\gamma_{16}(z_{16}, t_{16}, \beta) = 0.0003$, $\gamma_{17}(z_{17}, t_{17}, \beta) = 0.0002$, $\gamma_{18}(z_{18}, t_{18}, \beta) = 0.0099$, and $\gamma_{19}(z_{19}, t_{19}, \beta) = 0.2002$. Then, we have $\bar{\gamma}(\varphi, \beta) = 0.3058$ and $\bar{\gamma}(\varphi, \beta) = 0$. Thus, bound (33) becomes $\rho_{CL-SUE}^t = 1.1112 \leq (1/(1-\gamma(\varphi)))(1+\bar{k}/\theta\bar{c}) = 2.2546$ according to Theorem 1.

TABLE 6: Path results of the multiclass CL-SUE model.

Path no.	The multiclass CL-SUE											
	Path flow						Path cost					
	Time-based			Monetary-based			Time-based			Monetary-based		
	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$
1	85.0	141.6	56.6	96.8	197.1	79.9	33.5	33.5	33.5	33.5	67.0	100.5
2	21.1	35.2	14.1	10.3	1.9	0.1	32.8	32.8	32.8	32.8	65.6	98.4
3	1.5	2.6	1.0	2.5	0.1	0.0	36.4	36.4	36.4	36.4	72.8	109.2
4	0.8	1.4	0.6	0.8	0.0	0.0	44.4	44.4	44.4	44.2	88.3	132.5
5	0.6	0.9	0.4	0.7	0.0	0.0	51.9	51.9	51.9	50.8	101.5	152.3
6	9.9	16.5	6.6	6.7	0.8	0.0	35.3	35.3	35.3	35.3	70.6	105.9
7	0.7	1.2	0.5	1.6	0.0	0.0	38.9	38.9	38.9	38.9	77.8	116.7
8	0.4	0.6	0.3	0.5	0.0	0.0	46.9	46.9	46.9	46.6	93.3	139.9
9	160.5	267.5	107.0	141.3	362.5	157.1	56.2	56.2	56.2	57.6	115.3	172.9
10	30.1	50.2	20.1	40.5	23.2	2.2	34.6	34.6	34.6	34.6	69.3	103.9
11	16.8	28.1	11.2	13.9	2.6	0.1	42.6	42.6	42.6	42.4	84.8	127.2
12	12.2	20.4	8.2	12.0	2.1	0.1	50.1	50.1	50.1	49.0	98.0	147.0
13	13.0	21.6	8.6	23.9	8.6	0.5	37.1	37.1	37.1	37.1	74.3	111.4
14	7.3	12.2	4.9	8.3	1.0	0.0	45.1	45.1	45.1	44.9	89.8	134.6
15	34.2	56.9	22.8	55.2	80.0	23.0	44.7	44.7	44.7	44.5	89.1	133.6
16	126.3	210.5	84.2	87.1	205.0	95.6	34.1	34.1	34.1	34.2	68.3	102.5
17	9.9	16.5	6.6	23.0	12.5	1.3	37.8	37.8	37.8	37.8	75.5	113.3
18	5.5	9.2	3.7	7.8	1.4	0.1	45.7	45.7	45.7	45.5	91.0	136.5
19	4.1	6.9	2.7	7.0	1.1	0.0	53.3	53.3	53.3	52.1	104.2	156.4
20	49.0	81.7	32.7	48.0	98.0	39.9	48.9	48.9	48.9	51.4	102.8	154.2
21	3.4	5.6	2.3	3.7	0.5	0.0	42.9	42.9	42.9	42.8	85.6	128.3
22	5.9	9.8	3.9	6.1	1.4	0.1	57.6	57.6	57.6	59.0	118.0	177.0
23	0.9	1.4	0.6	1.3	0.1	0.0	36.0	36.0	36.0	36.0	72.0	108.0
24	0.5	0.8	0.3	0.5	0.0	0.0	44.0	44.0	44.0	43.8	87.5	131.2
25	0.4	0.7	0.3	0.5	0.0	0.0	51.5	51.5	51.5	50.4	100.7	151.1

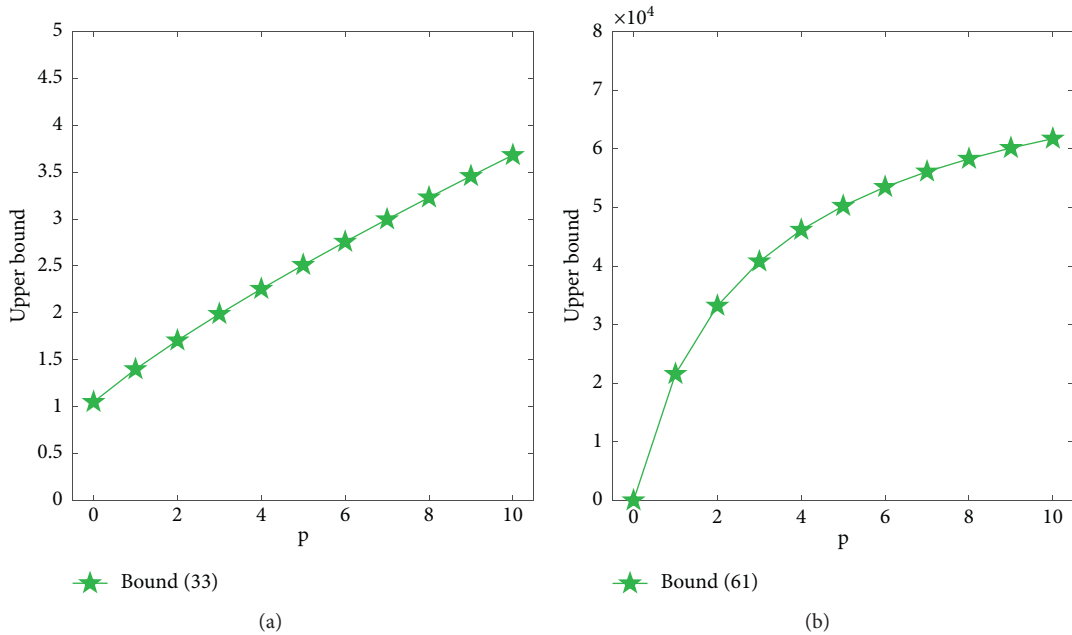
TABLE 7: Link results of the multiclass CL-SUE model.

Link no.	The multiclass CL-SUE					
	Link flow					
	Time-based			Monetary-based		
	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$
1	243.8	406.3	162.5	222.2	392.4	159.5
2	116.2	193.7	77.5	137.8	207.6	80.5
3	153.5	255.8	102.3	133.1	221.5	97.1
4	86.5	144.2	57.7	106.9	178.5	62.9
5	213.6	355.9	142.4	187.8	246.8	99.4
6	183.7	306.2	122.5	167.5	367.1	157.2
7	213.5	355.8	142.3	197.0	252.2	99.8
8	31.4	52.3	20.9	31.8	5.1	0.2
9	157.3	262.2	104.9	104.0	207.7	95.7
10	56.1	93.6	37.4	92.9	44.5	4.1
11	242.3	403.8	161.5	200.9	404.8	175.6
12	54.8	91.4	36.6	79.0	83.7	23.1
13	215.4	359.0	143.6	195.4	461.9	197.1
14	86.2	143.6	57.5	110.9	88.8	23.2
15	57.7	96.2	38.5	99.2	95.2	24.4
16	84.6	141.0	56.4	104.6	38.1	3.0
17	31.3	52.1	20.9	41.0	10.5	0.6
18	85.0	141.6	56.6	96.8	197.1	79.9
19	215.4	359.0	143.6	195.4	461.9	197.1

Bound (48) becomes $\rho_{\text{CL-SUE}}^c = 1.1691 \leq 1 + \bar{\gamma}(\varphi, \beta) + \bar{k}/\theta\bar{c}/1 - \bar{\gamma}(\varphi, \beta) = 1.4774$ according to Theorem 2. Bound (61) becomes $\rho_{\text{CL-SUE/CL-SSO}}^c = 232.6662 \leq \gamma(\varphi)T_{\text{CL-SUE}}^t = 46179.5710$ according to Theorem 3. Bound (67) becomes $\rho_{\text{CL-SUE/CL-SSO}}^c = 610.8827 \leq \bar{\gamma}(\varphi, \beta) T_{\text{CL-SUE}}^c + \bar{\gamma}(\varphi, \beta) T_{\text{CL-SSO}}^c = 52418.1288$ according to Theorem 4.

TABLE 8: Link results of the multiclass SO and CL-SSO models.

Link no.	The multiclass SO						The multiclass CL-SSO					
	Link flow						Link flow					
	Time-based			Monetary-based			Time-based			Monetary-based		
	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$	$m=1$	$m=2$	$m=3$
1	287.1	478.6	191.4	282.6	471.0	188.4	255.4	425.7	170.3	255.4	428.8	171.8
2	72.9	121.4	48.6	77.4	129.0	51.6	104.6	174.3	69.7	104.7	171.2	68.2
3	70.7	117.9	47.1	87.0	145.1	58.0	111.7	186.2	74.5	111.9	171.7	68.0
4	169.3	282.1	112.9	153.0	254.9	102.0	128.3	213.8	85.5	128.1	228.3	92.0
5	212.1	353.6	141.4	238.0	396.7	158.7	217.3	362.1	144.8	217.6	365.4	146.5
6	145.7	242.9	97.1	131.6	219.4	87.7	149.9	249.8	99.9	149.7	235.1	93.3
7	212.1	353.6	141.4	238.0	396.7	158.7	239.3	398.8	159.5	239.6	401.0	160.0
8	0.0	0.0	0.0	0.0	0.0	0.0	8.5	14.1	5.7	8.5	6.3	2.4
9	117.9	196.4	78.6	123.9	206.5	82.6	106.7	177.9	71.2	106.7	179.9	71.9
10	94.3	157.1	62.9	114.1	190.2	76.1	132.5	220.9	88.3	132.9	221.1	88.1
11	190.7	317.9	127.1	201.3	335.5	134.2	180.9	301.4	120.6	180.8	309.2	124.2
12	109.3	182.1	72.9	98.7	164.5	65.8	98.1	163.5	65.4	98.2	152.5	60.8
13	205.7	342.9	137.1	185.9	309.8	123.9	180.1	300.1	120.0	179.7	310.9	124.5
14	109.3	182.1	72.9	98.7	164.5	65.8	106.6	177.7	71.1	106.7	158.8	63.2
15	109.3	182.1	72.9	98.7	164.5	65.8	119.2	198.6	79.4	119.2	190.8	75.8
16	94.3	157.1	62.9	114.1	190.2	76.1	120.0	199.9	80.0	120.4	189.1	75.5
17	0.0	0.0	0.0	0.0	0.0	0.0	30.5	50.8	20.3	30.6	41.9	15.9
18	72.9	121.4	48.6	77.4	129.0	51.6	74.1	123.5	49.4	74.1	129.4	52.3
19	205.7	342.9	137.1	185.9	309.8	123.9	180.1	300.1	120.0	179.7	310.9	124.5

FIGURE 3: Bound (33) and bound (61) as a function of p .

In summary, the numerical results show that Theorems 1–4 are correct and valid.

Next, we will select three representative parameters for sensitivity analysis. The sensitivities of the upper bounds with respect to parameters $\gamma(\varphi)$, \bar{k} , and θ are addressed in the following. According to the above results, we can obtain $\gamma(\varphi) = 0.535$, $\bar{\gamma}(\varphi, \beta) = 0.3058$, $\bar{\gamma}(\varphi, \beta) = 0$, $\bar{k} = 0.9397$,

$\theta = 0.5$, $\bar{c} = 38.8391$, $\tilde{c} = 73.3117$, and $T_{\text{CL-SUE}}^t = 86316.9550$. Since (33) and (68), it is easy to know that bound (33) as a function of p and the function expression is $\rho_{\text{CL-SUE}}^t(p) = 1.0484(1 - (p/(p+1))(1/(p+1))^{1/p})^{-1}$. By the same way, we can obtain the other five function expressions: (1) bound (33) as a function of \bar{k} and the function expression is $\rho_{\text{CL-SUE}}^t(\bar{k}) = 1/0.465(1 + \bar{k}/19.4196)$; (2) bound

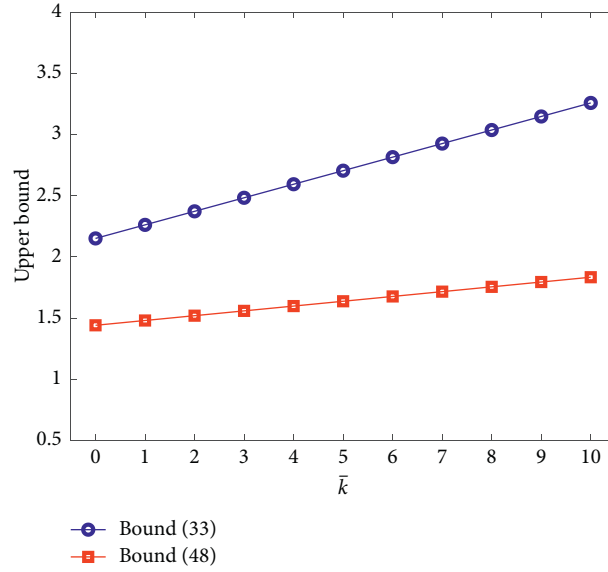


FIGURE 4: Bound (33) and bound (48) as a function of \bar{k} .

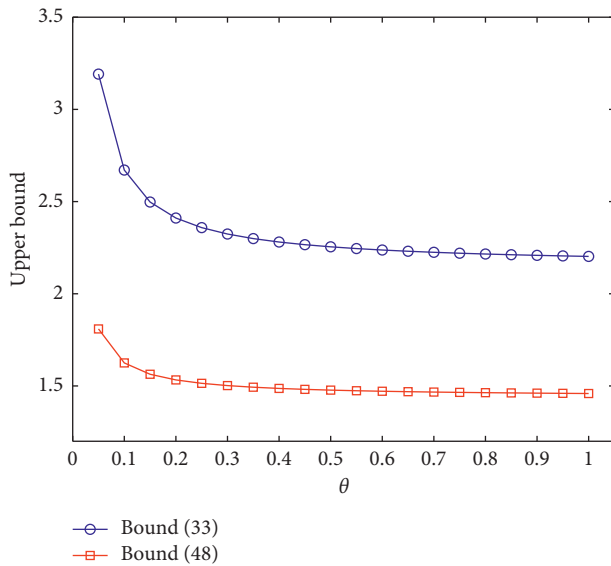


FIGURE 5: Bound (33) and bound (48) as a function of θ .

(33) as a function of θ and the function expression is $\rho_{\text{CL-SUE}}^t(\theta) = 1/0.465(1 + 0.0242/\theta)$; (3) bound (48) as a function of \bar{k} and the function expression is $\rho_{\text{CL-SUE}}^c(\bar{k}) = 1/0.6942(1 + \bar{k}/36.6559)$; (4) bound (48) as a function of θ and the function expression is $\rho_{\text{CL-SUE}}^c(\theta) = 1/0.6942(1 + 0.0128/\theta)$; and (5) bound (61) as a function of p and the function expression is $\rho_{\text{CL-SUE/CL-SSO}}^t(p) = 86317(p/(p+1))(1/(p+1))^{1/p}$. The following figures present the sensitivities of upper bounds subject to parameters p , \bar{k} , and θ (see Figures 3–5).

Figure 3 shows both bound (33) and bound (61) increase with p ; Figure 4 shows both bound (33) and bound (48) increase with \bar{k} , and bound (48) is always smaller than bound (33); and Figure 5 shows both bound (33) and bound (48) decrease with θ , and bound (48) is always smaller than

bound (33). Therefore, our sensitivity analysis results are consistent with the conclusions given in Section 5, which means that the conclusions given in Section 5 are valid.

8. Conclusions

We have derived four inefficiency bounds of the multiclass CL-SUE by making full use of equivalent VI formulations and provide some main conclusions as follows.

When comparing multiclass CL-SUE with multiclass SO, the upper bound under time-based criterion depends on the class of link time functions, the network complexity (including the commonality factor reflecting path overlapping and the number of feasible paths), the perception error of travel time, and the total demand. The upper bound will be underestimated in a realistic transportation network, if the commonality factor is not considered. By contrast, besides the factors mentioned above, the upper bound under monetary-based criterion is dependent upon the VOT of user classes.

When comparing multiclass CL-SUE with multiclass CL-SSO, the upper bound under monetary-based criterion depends on the class of link time functions and the VOT of user classes. However, the upper bound under time-based criterion only depends on the class of link time functions. Moreover, our research results suggest that the upper bound will increase when the degree of traffic congestion goes up. The upper bound is usually not tight in most cases because traffic congestion is inevitable, which means that there is more space to improve the congestion in the traffic network.

Furthermore, the effects of various parameters on the bounds have been further studied, especially the commonality factor. The results of the above discussions are shown in Table 2.

Our study can be further extended in two ways: (1) to explore more accurate upper bounds when more detailed network information is known and (2) to investigate the

inefficiency of the multiclass CL-SUE with elastic demand under different decision criteria.

Abbreviations

CL-SUE:	C-logit stochastic user equilibrium
VOT:	Values of time
VI:	Variational inequality
CL-SSO:	C-Logit stochastic system optimum
UE:	User equilibrium
SO:	System optimum
BRUE:	Boundedly rational user equilibrium
IID:	Independent and identical distributed
SUE:	Stochastic user equilibrium
GNL-SUE:	Generalized nested logit SUE
CNL-SUE:	Cross-nested logit SUE
PCL-SUE:	Paired combinatorial logit SUE
MP:	Mathematical programming
POA:	Price of anarchy
SSO:	Stochastic system optimum
TSTT:	Total system travel time
TSTC:	Total system travel cost
ATIS:	Advanced traveler information systems
TPTT:	Total perceived travel time
OD:	Origin-destination
TPTC:	Total perceived travel cost
BPR:	Bureau of public road.

Appendix

Now, we consider the simple network consisting of 2 nodes, n paths, and one OD pair with a demand d and with provided path flows f_r , $r \in \{1, 2, \dots, n\}$. Let u_1, u_2, \dots, u_n be

a user's perceived values of the path travel time and $f(u_1, u_2, \dots, u_n)$ denote the probability density function of the user's perceived travel time. The mean perceived path travel time c_1, c_2, \dots, c_n are functions of the path flows f_r . All users need to be assigned to paths to minimize their TPTT, by dividing the whole space of perceived travel time $u = (u_1, u_2, \dots, u_n)$ into mutually exclusive and exhaustive regions $\{B_r\}$ in an optimal manner. The region B_r is that within which $u_r - h_r < u_k - h_k$, $k \in \{1, 2, \dots, n\}$, where h_r should be given so that the proportion assigned by the above process to path r is f_r/d . Hence,

$$\int_{B_r} f(u_1, u_2, \dots, u_n) du_1 du_2 \dots du_n = p_r = \frac{f_r}{d}. \quad (A1)$$

With this assignment, the TPTT of the network with one OD pair is

$$F(f_1, f_2, \dots, f_r) = d \sum_r \int_{B_r} u_r f(u_1, u_2, \dots, u_n) du_1 du_2 \dots du_n. \quad (A2)$$

We suppose that only the means c_1, c_2, \dots, c_n are influenced by path flows f_r and the variances and covariances remain constant. Hence, the density function satisfies the condition below.

$$f(u_1 + h_1, u_2 + h_2, \dots, u_n + h_n; c_1, c_2, \dots, c_n) = f(u_1, u_2, \dots, u_n; c_1 - h_1, c_2 - h_2, \dots, c_n - h_n). \quad (A3)$$

Setting $w_r = u_r - h_r$ and denoting by Q_r the set of perceived path travel time for which path r is the optimum, (A2) can be rewritten as

$$\begin{aligned} F(f_1, f_2, \dots, f_r) &= d \sum_r \int_{Q_r} (w_r + h_r) f(w_1 + h_1, w_2 + h_2, \dots, w_n + h_n; c_1, c_2, \dots, c_n) dw_1 dw_2 \dots dw_n, \\ &= d \sum_r \int_{Q_r} (w_r + h_r) f(w_1, w_2, \dots, w_n; c_1 - h_1, c_2 - h_2, \dots, c_n - h_n) dw_1 dw_2 \dots dw_n, \\ &= d \sum_r \int_{Q_r} w_r f(w_1, w_2, \dots, w_n; c_1 - h_1, c_2 - h_2, \dots, c_n - h_n) dw_1 dw_2 \dots dw_n + d \sum_r h_r p_r, \\ &= dS(c_1 - h_1, c_2 - h_2, \dots, c_n - h_n) + \sum_r h_r f_r, \end{aligned} \quad (A4)$$

where S is the composite travel time. In the logit case, S is provided by a specific "logsum" expression:

$$\begin{aligned} S(c_1 - h_1, c_2 - h_2, \dots, c_n - h_n) \\ = -\frac{1}{\theta} \log \left(\sum_r \exp(-\theta(c_r - h_r)) \right). \end{aligned} \quad (A5)$$

Suppose that we have a multiple OD pair transportation network with multiple classes of users. The demand of user class m between OD pair $w \in W$ is

denoted by d_w^m . The flow of user class m on path $r \in R_w, w \in W$ is expressed by f_{rw}^m . Let c_{rw}^m denote the mean perceived travel time of user class m on path $r \in R_w, w \in W$. Therefore, the TPTT is given by

$$\begin{aligned} F(f) &= \sum_{w \in W} \sum_{m=1}^M d_w^m S_w^m (c_w^m - h_w^m) \\ &+ \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M h_{rw}^m f_{rw}^m. \end{aligned} \quad (A6)$$

Here, we have

$$S_w^m (c_w^m - h_w^m) = -\frac{1}{\theta} \log \left(\sum_r \exp(-\theta(c_{rw}^m - h_{rw}^m)) \right). \quad (A7)$$

In the C-Logit case, we suppose that $c_{rw}^m = c_{rw}^m + c f_{rw}$ is the mean perceived travel time, where c_{rw}^m is the actual travel time of user class m on path $r \in R_w, w \in W$ and $c f_{rw}$ is a commonality factor of path $r \in R_w, w \in W$. The path choice probability for user class m is given by

$$P_{rw}^m = \frac{\exp(-\theta(c_{rw}^m - h_{rw}^m))}{\sum_{l \in R_w} \exp(-\theta(c_{rl}^m - h_{rl}^m))}, r \in R_w, w \in W, m = 1, 2, \dots, M. \quad (A8)$$

Hence, we can obtain the values of h_{rw}^m and h_{lw}^m from

$$\ln \frac{f_{rw}^m}{f_{lw}^m} = -\theta(c_{rw}^m - h_{rw}^m - c_{lw}^m + h_{lw}^m), \quad (A9)$$

so that

$$h_{rw}^m - h_{lw}^m = c_{rw}^m - c_{lw}^m + \frac{1}{\theta} \ln \frac{f_{rw}^m}{f_{lw}^m}. \quad (A10)$$

Here, we can set any one of the h_{rw}^m to zero. Setting $h_{lw}^m = 0$, the value of h_{rw}^m is given by

$$h_{rw}^m = c_{rw}^m - c_{lw}^m + \frac{1}{\theta} \ln \frac{f_{rw}^m}{f_{lw}^m}. \quad (A11)$$

For any one OD pair w , we can have the following objective function:

$$F(f^m) = -\frac{1}{\theta} \sum_{m=1}^M d_w^m \ln \left(\sum_r \exp(-\theta(c_{rw}^m - h_{rw}^m)) \right) + \sum_{r \neq l} \sum_{m=1}^M f_{rw}^m \left(c_{rw}^m - c_{lw}^m + \frac{1}{\theta} \ln \frac{f_{rw}^m}{f_{lw}^m} \right). \quad (A12)$$

Substituting (A11) into (A12) and summing all OD pairs, the objective function for the multiclass CL-SSO is given as follows:

$$\begin{aligned} F(f) &= -\frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln \left(\sum_r \exp(-\theta(c_{rw}^m - h_{rw}^m)) \right) + \sum_{w \in W} \sum_{r \in R_w, r \neq l} \sum_{m=1}^M f_{rw}^m \left(c_{rw}^m - c_{lw}^m + \frac{1}{\theta} \ln \frac{f_{rw}^m}{f_{lw}^m} \right), \\ &= \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m c_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln \left(\sum_r \exp \left(-\theta \left(c_{lw}^m - \frac{1}{\theta} \ln \frac{f_{rw}^m}{f_{lw}^m} \right) \right) \right), \\ &= \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m c_{rw}^m + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \end{aligned} \quad (A13)$$

Substituting $c_{rw}^m = c_{rw}^m + c f_{rw}$ into (A13), we can obtain

$$\begin{aligned} F(f) &= \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m (c_{rw}^m(f) + c f_{rw}) \\ &\quad + \frac{1}{\theta} \sum_{w \in W} \sum_{r \in R_w} \sum_{m=1}^M f_{rw}^m \ln f_{rw}^m - \frac{1}{\theta} \sum_{w \in W} \sum_{m=1}^M d_w^m \ln d_w^m. \end{aligned} \quad (A14)$$

Data Availability

The data used to support the findings of this study are included within the article.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

Acknowledgments

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