Research Article


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In our current era, a new rapidly spreading pandemic disease called coronavirus disease (COVID-19), caused by a virus identified as a novel coronavirus (SARS-CoV-2), is becoming a crucial threat for the whole world. Currently, the number of patients infected by the virus is expanding exponentially, but there is no commercially available COVID-19 medication for this pandemic. However, numerous antiviral drugs are utilized for the treatment of the COVID-19 disease. Identification of the appropriate antivirus medicine to treat the infection of COVID-19 is still a complicated and uncertain decision. This study’s key objective is to develop a novel approach called $q$-rung orthopair probabilistic hesitant fuzzy rough set ($q$-ROPHFRS), which incorporates the $q$-rung orthopair fuzzy set, probabilistic hesitant fuzzy set, and rough set structures. New $q$-ROPHFR aggregation operators have been established: the $q$-ROPHFR Einstein weighted averaging ($q$-ROPHFREWA) operator and the $q$-ROPHFR Einstein weighted geometric ($q$-ROPHFREWG) operator. In this study, we explored some basic features of the developed operators. Afterward, to demonstrate the viability and feasibility of the established decision-making approach in real-world applications, a case study related to selecting drugs for COVID-19 pandemic is addressed. Furthermore, a comprehensive comparison with the $q$-rung orthopair probabilistic hesitant fuzzy rough TOPSIS technique is also presented to illustrate the benefits of the new framework. The obtained results confirm the reliability and effectiveness of the proposed approach for finding uncertainty in real-world decision-making.

1. Introduction

Wuhan, China, was faced with a dangerous challenge in December 2019, which distorted the health of humans and created global instability. The pneumonia cases were caused by a new virus known as coronavirus 2019 (COVID-19), caused by a virus identified as a novel coronavirus (SARS-CoV-2), is becoming a crucial threat for the whole world. Currently, the number of patients infected by the virus is expanding exponentially, but there is no commercially available COVID-19 medication for this pandemic. However, numerous antiviral drugs are utilized for the treatment of the COVID-19 disease. Identification of the appropriate antivirus medicine to treat the infection of COVID-19 is still a complicated and uncertain decision. This study’s key objective is to develop a novel approach called $q$-rung orthopair probabilistic hesitant fuzzy rough set ($q$-ROPHFRS), which incorporates the $q$-rung orthopair fuzzy set, probabilistic hesitant fuzzy set, and rough set structures. New $q$-ROPHFR aggregation operators have been established: the $q$-ROPHFR Einstein weighted averaging ($q$-ROPHFREWA) operator and the $q$-ROPHFR Einstein weighted geometric ($q$-ROPHFREWG) operator. In this study, we explored some basic features of the developed operators. Afterward, to demonstrate the viability and feasibility of the established decision-making approach in real-world applications, a case study related to selecting drugs for COVID-19 pandemic is addressed. Furthermore, a comprehensive comparison with the $q$-rung orthopair probabilistic hesitant fuzzy rough TOPSIS technique is also presented to illustrate the benefits of the new framework. The obtained results confirm the reliability and effectiveness of the proposed approach for finding uncertainty in real-world decision-making.

Organization (WHO) recognized COVID-19 as a pandemic by March 2020. Several governments and organizations have been closed down and have implemented strict social distancing processes to prevent virus proliferation. According to a WHO report released on June 13, 2021, more than 176,396,104 cases of COVID-19 have been reported around the world, resulting in more than 3,810,989 deaths, and a total of 160,398,032 people have been recovered [2]. The virus that causes COVID-19 is primarily spread via the droplets created when someone infected with COVID-19 sneezes, coughs, or exhales. Coronavirus is more harmful to
those who have a low immune system, are elderly, have diabetes, or have medical problems, especially for those involving the lungs [3–6]. Virus propagation can be influenced by various factors, including population density, medical care facilities, climate, and others [7]. Coronaviruses are a vast family of viruses that can cause various diseases in both animals and humans. They mainly cause respiratory tract infections in humans, varying from an ordinary cold towards more severe illness disorders such as Middle East respiratory syndrome (MERS) and severe acute respiratory syndrome (SARS) [8, 9]. Phylogenetic and sequencing analyses have shown that COVID-19 is closely related to a collection of human and bat SARS-like coronaviruses [4, 10, 11]. COVID-19 is believed to have evolved from bats to a greater level of life chains [12–14]. The statistic is shown in Figure 1. Doctors, experts, or medical sections should implement an ideal plan, tests, or techniques for the COVID-19 treatment process to avoid further crisis expansion. The department in the process of establishing strategy must make quick and effective decisions. While making decisions in this situation, individuals are often bound logically instead of entirely reasonable. As a result, it is essential to identify appropriate multicriteria decision-making (MCDM) models that recognize human activities to provide individuals with practical ways of responding to emergencies. Dealing with uncertainty and unpredictable information in realistic circumstances has always been challenging. Several tools have been developed to address the complexities and conflicts encountered in real-life activities. Zadeh [15] explored a solution to such problems by establishing the foundations of fuzzy set (FS) theory, in which each element is assigned a membership degree ranging between 0 and 1. Atanassov [16] extended the idea of FS into intuitionistic FS (IFS) by introducing nonmembership (ψ(x)) to the membership (β(x)) of the FS, with the restriction that β(x) + ψ(x) ≤ 1.

Yager [17] introduced the Pythagorean FS (PF) theory, which relaxes the previously mentioned IFS condition to (β(x))² + (ψ(x))² ≤ 1. PF expressions are undoubtedly raising the interest of many researchers, especially in terms of their applications to DM. For example, Huang et al. [18] described a PF MULTIMOORA approach that utilizes a novel distance measure and a score function. They used this approach to evaluate disk productions and energy projects. Zhang and Xu [19] established the TOPSIS approach in a Pythagorean fuzzy environment and used it to assess the efficiency of private airline services.

Hesitancy is a natural phenomenon in the universe. Identifying the better alternatives having the same characteristics in daily life is complicated. Due to the uncertainty and hesitancy of the results, professional experts are experiencing difficulty in DM. To tackle hesitancy, Torra [20] developed the concept of hesitant FS (HFS). The HFS can be used to solve a variety of DM problems. Many authors used HFS to solve issues by aggregating operators (AOPs) in group DM (for detailed information, see [21–24]). Liao and Xu [25] identified generalized forms of the HF hybrid weighted averaging (HHFWA) operator, the HF hybrid weighted geometric (HHFWG) operator, generalized form of the quasi-HFHWA operator, and the generalized form of the quasi-HFHWG. Khan et al. [26] introduced the concept of Pythagorean HFS (PHFS). They established an evaluation method and identified operators for data aggregation. Xu and Zhou [27] identified a novel concept of probabilistic HF sets (PHFSs). Inspired by the power of PHFSs, researchers extensively investigated the idea of multiattribute decision-making (MADM) (see [28–30] for detailed information). Yager [31] established a new idea called q-rung orthopair FSs (q-ROFSs), in which the number of the qth exponent of support for membership and the qth exponent of support nonmembership is restricted to one, i.e., 

\[(β_q(x))^q + (ψ_q(x))^q \leq 1\]

and demonstrated that the q-ROFS is more general than the IFS and PFS. The q-ROFSs provide a broader range of fuzzy information and are the versatile and appropriate approach to deal with unpredictable situations. Yager and Alajlan [32] explored the fundamental properties of these q-ROFSs and discussed how they can be used in information representation. Subsequently, the authors in [33] put forward the notation of q-rung orthopair HF set (q-ROHFS) and explored the operational laws which exist for any two q-ROHFSs. Wang et al. [34] investigated the Heronian mean operators in MADM in a q-ROHFS framework. They also proposed the Hamacher norm-based AOPs under dual hesitant q-ROFSs and discussed their usefulness in DM problems. Wang et al. [35] established the AOPs based on Muirhead mean under dual hesitant q-rung orthopair fuzzy information. Hussain and Yang [36] measured the entropy for HF information using the Hausdorff metric and the structure of HF TOPSIS. The TOPSIS is a valuable information analysis tool developed by Hwang and Yoon [37]; it is also known as the approximate ideal solution. It investigates the appropriate approach in terms of relative closeness based on their distances from the positive ideal solution (PIS) and the negative ideal solution (NIS), ensuring that the shortest distance from the PIS and the farthest distance from the NIS are satisfied. This analysis method effectively eliminates decision information uncertainty while maintaining the validity and precision of decision-making by simply measuring the distance between PIS and NIS and ranking them accordingly. TOPSIS method is straightforward and simple to understand and analyze as compared to the ELECTRE method, VIKOR method, and other conventional methods, so it has been extensively studied and implemented by researchers.

In recent years, several authors have presented TOPSIS in various fuzzy information. For example, Boran et al. [38] used TOPSIS to identify the best supplier by using IF information. Chen and Tsao [39] suggested the TOPSIS technique based on interval-valued fuzzy information and addressed the experimental results. The authors in [40] established the extended TOPSIS method for q-ROHFSs and addressed their significance in DM. Li [41] proposed a TOPSIS-based nonlinear programming technique for MADM with interval-valued IFs in order to deal with uncertainty in real-world DM problems. The TOPSIS model for DM problems in interval-valued IF information was introduced by Park et al. [42]. The Dombi-based AOPs for PF information is formulated in [43]. Barukab et al. [44]
proposed the extended fuzzy TOPSIS method for spherical fuzzy information, which is based on the entropy measure. The aforesaid approach has been used by many other researchers; see [45–47] for more information. However, there are many research findings in applying the fuzzy TOPSIS method to solve MADM problems; the decision information used by these approaches is too old and restricted to manage increasingly challenging decision environments.

Pawlak [48] was the founder of exploring the dominating concept of rough set (RS) theory. The classical set theory which deals with inconsistent and imprecise information is extended by rough set theory. Recently, research on the rough set has progressed significantly, both in terms of theoretical implementations and theory itself. In recent decades, research has demonstrated the TOPSIS technique in a number of RS information. Su et al. [49] studied RS theory based on fuzzy TOPSIS on the serious game design assessment procedure. Khan et al. [50] implemented a rough set strategy and the TOPSIS method for selection of sites for food distribution. Lu and Zhao [51] investigated the improved TOPSIS method based on RS theory for selection of suppliers. A b–rough set model and its applications to DM using the TOPSIS approach have been discussed in [52]. The concept of RS has been expanded by several researchers around the world in different directions. Using the fuzzy relation rather than the crisp binary relation, Dubois and Prade [53] initiated the notion of fuzzy rough sets (FRSs). The hybrid structure of IFSs and RS, intuitionistic RS (IFR set), was introduced by Cornelis et al. [54]. Zhou and Wu [55] established a novel DM technique under the IFR environment to address their constructive and axiomatic analysis in detail by utilizing IFR approximations. Zhan et al. [56] presented the DM methodology under the IFR environment and explored their applications in real-world problems. Different extensions of the IFRS are being investigated [57, 58] to tackle the uncertainty in MCGDM problems. Chinram et al. [59] established the algebraic norm-based AOPs based on the EDAS technique under IFR information and discussed their applications in MAGDM.

In some real-life circumstances, there exist numerous cases when decision makers (DMs) have their strong points of view about ranking or rating of plans, projects, or political statements of a government. For example, let the administration of a university start megaprojects of the football ground to render his accomplishment and performance. The members of the university administration may rate their project highly by assigning positive membership= 0.9, whereas the others may rate the same project as a wastage of money and try to defame it by providing strongly opposite points of view. So, they assign negative membership= 0.7. In this situation, their sum $0.9 + 0.7 > 1$ and $(0.9)^2 + (0.7)^2 > 1$ but $(0.9)^q + (0.7)^q < 1$ for $q > 3$ so that it is neither IFN nor PFN but it is $q$-ROFN. Thus, Yager’s $q$-ROFNs are efficient to deal with vagueness in the data. $q$-runge orthopair probabilistic hesitant fuzzy rough set ($q$-ROPHFS), a hybrid intelligent structure of rough sets and $q$-ROPHFS, is an advanced classification strategy that has attracted researchers to address ambiguous and incomplete data. From the analysis, it is concluded that, in decision-making, AOP plays a significant role in aggregating the collective data from different sources to a single value. In accordance with the best available knowledge to date, the development of the AOP with the hybridization of the $q$-ROPHFS with a rough set is not observed in the $q$-ROF setting. As a result, the current $q$-ROPHF rough structure is inspired, and we define a list of Einstein aggregation operators depending on rough data, such as $q$-runge orthopair probabilistic hesitant fuzzy Einstein weighted averaging, Einstein ordered weighted averaging, Einstein hybrid weighted averaging, Einstein weighted geometric, Einstein ordered weighted geometric, and Einstein hybrid weighted geometric aggregation operators, under the Einstein $t$-norm and $s$-norm.

The description of the main objectives of the present work is as follows:

1. To introduce a novel idea of $q$-runge orthopair probabilistic hesitant fuzzy rough sets ($q$-ROPHFRSs) and investigate their basic operational laws.

2. Establish a list of AOPs based on Einstein $t$-norm and $t$-conorm and comprehensively explore the relevant properties.
(3) To develop a DM strategy for aggregating unpredictability in real-world DM problems employing suggested aggregation operators.

(4) In addition, a case study of drug selection for mild COVID-19 symptoms is described to demonstrate the applicability and utility of the established operators.

(5) Finally, a comparison with the q-ROPHFR-TOPSIS method is made to interpret the outcomes. The ranking of the obtained results is presented graphically.

2. Basic Terminologies

This section covers a variety of significant and fundamental concepts, i.e., fuzzy set (FS), intuitionistic FS (IFS), q-rung orthopair FS (q-ROFS), hesitant FS (HFS), q-rung orthopair HFS (q-ROHFS), q-rung orthopair probabilistic HFS (q-ROPHFS), rough sets (RSs), and q-rung orthopair FRS (q-ROFRS).

Definition 1. (see [15]). For a universal set Ω, an FS Q is presented as

\[ Q = \{ \langle x, \beta_Q(x) \rangle | x \in F \} \]

for each \( x \in F \), and the function \( \beta_Q(x) \) belongs to \([0, 1]\) that represent the degree of membership.

Definition 2. (see [16]). For a universal set Ω, an IFS \( \mathcal{F} \) over \( \Omega \) is described as

\[ \mathcal{F} = \{ \langle x, \beta_{\mathcal{F}}(x), \psi_{\mathcal{F}}(x) \rangle | x \in \Omega \} \]

For each \( x \in \mathcal{F} \), the functions \( \beta_{\mathcal{F}} : \Omega \rightarrow [0, 1] \) and \( \psi_{\mathcal{F}} : \Omega \rightarrow [0, 1] \) represent the membership and nonmembership, respectively, which must satisfy the property \( 0 \leq \beta_{\mathcal{F}}(x) + \psi_{\mathcal{F}}(x) \leq 1 \).

Definition 3. (see [60]). For a universal set Ω, an HFS A in Ω is represented mathematically as

\[ A = \{ \langle x, \beta_{\mathcal{A}}(x) \rangle | x \in \Omega \} \]

where \( \beta_{\mathcal{A}}(x) \) is a set of some values in \([0, 1]\) representing the degree of membership for the element \( x \in \Omega \) of the set \( A \).

Definition 4. For a universal set Ω, a probabilistic HF set (PHFS) \( P \) in Ω is described mathematically as

\[ P = \{ \langle x, \beta_{\mathcal{P}}(x) / \delta_{\mathcal{P}}(x) \rangle | x \in \Omega \} \]

where \( \beta_{\mathcal{P}}(x) \) is a subset of \([0, 1]\) and \( \delta_{\mathcal{P}}(x) / \delta_{\mathcal{P}}(x) \) shows a membership grade of the element \( x \in \Omega \) to the set \( P \). And \( \delta_{\mathcal{P}}(x) \) shows the possibilities with the property that \( \delta_{\mathcal{P}}(x) \delta_{\mathcal{P}}(x) = 1 \).

Definition 5. (see [31]). For a universal set Ω, a q-ROFS \( \mathcal{F} \) over Ω is described mathematically as

\[ \mathcal{F} = \{ \langle x, \beta_{\mathcal{F}}(x), \psi_{\mathcal{F}}(x) \rangle | x \in \Omega \} \]

for each \( x \in \mathcal{F} \), the functions \( \beta_{\mathcal{F}} : \Omega \rightarrow [0, 1] \) and \( \psi_{\mathcal{F}} : \Omega \rightarrow [0, 1] \) denote the membership and nonmembership, respectively, which must satisfy \( (\psi_{\mathcal{F}}(x))^q + (\beta_{\mathcal{F}}(x))^q \leq 1 \) and \( (\min(\beta_{\mathcal{F}}(x))^q)^q \leq 1 \). For simplicity, we will use a pair \( \mathcal{F} = (\beta_{\mathcal{F}}, \psi_{\mathcal{F}}) \) to mean q-ROHS number (q-ROHFN).

Definition 6. (see [33]). For a universal set Ω, the mathematical representation of q-ROHFS \( \Xi \) is as follows:

\[ \Xi = \{ \langle x, \beta_{\mathcal{R}_h}(x), \psi_{\mathcal{R}_h}(x) | x \in \Omega \} \]

where \( \beta_{\mathcal{R}_h}(x) \) and \( \psi_{\mathcal{R}_h}(x) \) are sets of some values in \([0, 1]\). It is required to satisfy the following properties: \( \forall x \in \Omega \), \( \forall \omega_2(x) \in \beta_{\mathcal{R}_h}(x) \), \( \forall \gamma_2(x) \in \psi_{\mathcal{R}_h}(x) \) with \( (\max(\beta_{\mathcal{R}_h}(x)))^q + (\min(\beta_{\mathcal{R}_h}(x)))^q \leq 1 \) and \( (\min(\beta_{\mathcal{R}_h}(x)))^q \leq 1 \). For simplicity, we will use a pair \( \Xi = (\beta_{\mathcal{R}_h}, \psi_{\mathcal{R}_h}) \) to mean q-ROHS number (q-ROHFN).

Definition 7. (see [33]). Let \( \Xi_1 = (\beta_{\mathcal{R}_h}, \psi_{\mathcal{R}_h}) \) and \( \Xi_2 = (\beta_{\mathcal{R}_h}, \psi_{\mathcal{R}_h}) \) be two q-ROHFNs. Then, the basic set theoretic operations are as follows:

\[ (\Xi_1 \cup \Xi_2) = \left\{ \min(\omega_1, \omega_2), \min(\nu_1, \nu_2) \right\}, \]

\[ (\Xi_1 \cap \Xi_2) = \left\{ \max(\omega_1, \omega_2), \max(\nu_1, \nu_2) \right\}, \]

\[ (\Xi_1)^c = \left\{ \psi_{\mathcal{R}_h}, \beta_{\mathcal{R}_h} \right\}. \]

Definition 8. Let \( \Xi_1 = (\beta_{\mathcal{R}_h}, \psi_{\mathcal{R}_h}) \) and \( \Xi_2 = (\beta_{\mathcal{R}_h}, \psi_{\mathcal{R}_h}) \) be two q-ROHFNs where \( q > 2 \) and \( \gamma > 0 \) are any real number. Then, the operational laws based on Einstein t-norm and t-conorm can be defined as
For a universal set \( \Omega \), a \( q \)-ROPHFS \( \mathcal{F} \) is defined as

\[
\mathcal{F} = \left\{ \left( x, \frac{\beta_{h_3}(x) \psi_{h_3}(x)}{\partial_x} \right) \mid x \in \Omega \right\},
\]

where \( \beta_{h_3}(x)/\partial_x \) and \( \psi_{h_3}(x)/\partial_x \) are sets of some values in [0, 1] which denote the membership and nonmembership, respectively, \( \partial_x \) and \( \partial_x \) represent the possibilities of membership and nonmembership with the following property: \( 0 \leq \partial_x \leq \partial_x \leq 1 \) with \( \partial_x = 1 \) and \( \partial_x = 1 \) (\( p \) represents that the total elements exist in the \( q \)-ROPHFS). It is required to satisfy the following properties: \( \forall x \in \Omega, \forall \partial_x \in \beta_{h_3}(x) \) and \( \forall \psi_{h_3}(x) \) with \( (\max(\beta_{h_3}(x)))^p + (\min(\psi_{h_3}(x)))^p \leq 1 \) and \( (\min(\beta_{h_3}(x)))^p + (\max(\psi_{h_3}(x)))^p \leq 1 \). For simplicity, we will use a pair \( \mathcal{F} = (\beta_{h_3}/\partial_x, \psi_{h_3}/\partial_x) \) to mean a \( q \)-ROPHF number (\( q \)-ROPHFN).

**Definition 10.** Let \( \mathcal{F}_1 = (\beta_{h_3}/\partial_x, \psi_{h_3}/\partial_x) \) and \( \mathcal{F}_2 = (\beta_{h_3}/\partial_x, \psi_{h_3}/\partial_x) \) be two \( q \)-ROPHFNs. Then, the basic set theoretic operations are as follows:
\[ (1) \mathcal{Z}_1 \cup \mathcal{Z}_2 = \left\{ \begin{array}{l} \bigcup_{\omega, \phi \in \mathcal{Z}_1 \cup \mathcal{Z}_2} \max \left( \frac{\omega_1 \cdot \omega_2}{\delta_1 \cdot \delta_2} \right), \quad \bigcup_{\eta, \phi \in \mathcal{Z}_1 \cup \mathcal{Z}_2} \min \left( \frac{\eta_1 \cdot \eta_2}{\delta_1 \cdot \delta_2} \right) \end{array} \right\}, \]

\[ (2) \mathcal{Z}_1 \ominus \mathcal{Z}_2 = \left\{ \begin{array}{l} \bigcup_{\omega, \phi \in \mathcal{Z}_1 \ominus \mathcal{Z}_2} \max \left( \frac{\omega_1 \cdot \omega_2}{\delta_1 \cdot \delta_2} \right), \quad \bigcup_{\eta, \phi \in \mathcal{Z}_1 \ominus \mathcal{Z}_2} \min \left( \frac{\eta_1 \cdot \eta_2}{\delta_1 \cdot \delta_2} \right) \end{array} \right\}, \]

\[ (3) \mathcal{Z}_1' = \left[ \frac{\psi_{\mathcal{Z}_1}}{\delta_1} \right]. \]

**Definition 11.** Let \( \mathcal{Z}_1 = (\beta_{\mathcal{Z}_1}, \delta_{\mathcal{Z}_1}) \) and \( \mathcal{Z}_2 = (\beta_{\mathcal{Z}_2}, \delta_{\mathcal{Z}_2}) \) be two q-RoPHFNs and \( q > 2 \epsilon \in \mathbb{Z}^* \) and \( \gamma > 0 \) be any real number.

Then, the operational laws based on Einstein t-norm and t-conorm can be defined as

\[ (1) \mathcal{Z}_1 \cup \mathcal{Z}_2 = \left\{ \begin{array}{l} \bigcup_{\omega, \phi \in \mathcal{Z}_1 \cup \mathcal{Z}_2} \max \left( \frac{\omega_1 \cdot \omega_2}{\delta_1 \cdot \delta_2} \right), \quad \bigcup_{\eta, \phi \in \mathcal{Z}_1 \cup \mathcal{Z}_2} \min \left( \frac{\eta_1 \cdot \eta_2}{\delta_1 \cdot \delta_2} \right) \end{array} \right\}, \]

\[ (2) \mathcal{Z}_1 \ominus \mathcal{Z}_2 = \left\{ \begin{array}{l} \bigcup_{\omega, \phi \in \mathcal{Z}_1 \ominus \mathcal{Z}_2} \max \left( \frac{\omega_1 \cdot \omega_2}{\delta_1 \cdot \delta_2} \right), \quad \bigcup_{\eta, \phi \in \mathcal{Z}_1 \ominus \mathcal{Z}_2} \min \left( \frac{\eta_1 \cdot \eta_2}{\delta_1 \cdot \delta_2} \right) \end{array} \right\}, \]

\[ (3) \mathcal{Z}_1' = \left[ \frac{\psi_{\mathcal{Z}_1}}{\delta_1} \right]. \]

**Definition 12.** Let \( \Omega \) be the universal set and \( \mathbb{N} \subseteq \Omega \times \Omega \) be a (crisp) relation. Then,

1. \( \mathbb{N} \) is reflexive if \( \hat{g} \in \mathbb{N} \) for each \( \hat{g} \in \Omega \)
2. \( \mathbb{N} \) is symmetric if \( \forall g, a \in \Omega \) and \( (g, a) \in \mathbb{N} \), then \( (a, g) \in \mathbb{N} \)
3. \( \mathbb{N} \) is transitive if \( \forall g, a, b \in \Omega \), \( (g, a) \in \mathbb{N} \), and \( (a, b) \in \mathbb{N} \) implies \( (g, b) \in \mathbb{N} \)

**Definition 13.** (see [48]). Let \( \Omega \) be a universal set and \( \mathbb{N} \) be any relation on \( \Omega \). Define a set-valued mapping \( \mathbb{N}^* : \Omega \rightarrow M(\Omega) \) by \( \mathbb{N}^* (\hat{a}) = \{ a \in \Omega | (\hat{g}, a) \in \mathbb{N} \} \), for \( \hat{g} \in \Omega \) where \( \mathbb{N}^* (\hat{g}) \) is called a successor neighborhood of the element \( \hat{g} \) with respect to relation \( \mathbb{N} \). The pair \( (\Omega, \mathbb{N}) \) is called the (crisp) approximation space. Now, for any set \( b \subseteq \Omega \), the lower and upper approximation of \( b \) with respect to the approximation space \( (\Omega, \mathbb{N}) \) is defined as
\[ \mathcal{N}(\hat{a}) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \subseteq b \right\}, \]
\[ \overline{\mathcal{N}}(\hat{a}) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \cap b \neq \emptyset \right\}. \] (12)

The pair \((\mathcal{N}(\hat{a}), \overline{\mathcal{N}}(\hat{a}))\) is called the rough set, and both \(\mathcal{N}(\hat{a}), \overline{\mathcal{N}}(\hat{a})\): \(M(\Omega) \rightarrow M(\Omega)\) are upper and lower approximation operators.

**Definition 14.** (see [59]). Let \(\Omega\) be the universal set and \(\mathcal{N} \in (\Omega \times \Omega)\) be an intuitionistic fuzzy relation. Then,

1. \(\mathcal{N}\) is reflexive if \(\omega_{\mathcal{N}}(\hat{g}, \hat{g}) = 1\) and \(\nu_{\mathcal{N}}(\hat{g}, \hat{g}) = 0, \forall \hat{g} \in \Omega\),
2. \(\mathcal{N}\) is symmetric if \(\forall (\hat{g}, a) \in \Omega \times \Omega, \omega_{\mathcal{N}}(\hat{g}, a) = \omega_{\mathcal{N}}(a, \hat{g})\) and \(\nu_{\mathcal{N}}(\hat{g}, a) = \nu_{\mathcal{N}}(a, \hat{g})\),
3. \(\mathcal{N}\) is transitive if \(\forall (\hat{g}, b) \in \Omega \times \Omega, \omega_{\mathcal{N}}(\hat{g}, b) = \bigvee_{a \in \Omega} \left[ \omega_{\mathcal{N}}(\hat{g}, a) \land \omega_{\mathcal{N}}(a, b) \right], \nu_{\mathcal{N}}(\hat{g}, b) = \bigwedge_{a \in \Omega} \left[ \nu_{\mathcal{N}}(\hat{g}, a) \land \nu_{\mathcal{N}}(a, b) \right]. \) (13)

**Definition 15.** Let \(\Omega\) be the universal set. Then, any \(\mathcal{N} \in q-RFS(\Omega \times \Omega)\) is called a \(q\)-run rough relation. The pair \((\Omega, \mathcal{N})\) is said to be \(q\)-run approximation space. Now, for any \(b \in q-RFS(\Omega)\), the upper and lower approximations of \(b\) with respect to the \(q\)-RF approximation space \((\Omega, \mathcal{N})\) are two \(q\)-RFSs, which are denoted by \(\overline{\mathcal{N}}(b)\) and \(\mathcal{N}(b)\) and are defined as

\[ \overline{\mathcal{N}}(b) = \left\{ \hat{g} \in \Omega \mid \overline{\mathcal{N}}^{\prime}(\hat{g}) \subseteq b \right\}, \]
\[ \mathcal{N}(b) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \cap b \neq \emptyset \right\}. \] (14)

where

\[ \omega_{\overline{\mathcal{N}}(b)}^{\prime}(\hat{g}) = \bigvee_{a \in \Omega} \left[ \omega_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \omega_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \nu_{\overline{\mathcal{N}}(b)}^{\prime}(\hat{g}) = \bigwedge_{a \in \Omega} \left[ \nu_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \nu_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \omega_{\mathcal{N}(b)}^{\prime}(\hat{g}) = \bigwedge_{a \in \Omega} \left[ \omega_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \omega_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \nu_{\mathcal{N}(b)}^{\prime}(\hat{g}) = \bigvee_{a \in \Omega} \left[ \nu_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \nu_{\mathcal{N}}^{\prime}(a, b) \right], \]

such that

\[ 0 \leq \left( \omega_{\overline{\mathcal{N}}(b)}^{\prime}(\hat{g}) \right)^{q} + \left( \nu_{\mathcal{N}(b)}^{\prime}(\hat{g}) \right)^{q} \leq 1, \]
\[ 0 \leq \left( \omega_{\mathcal{N}(b)}^{\prime}(\hat{g}) \right)^{q} + \left( \nu_{\overline{\mathcal{N}}(b)}^{\prime}(\hat{g}) \right)^{q} \leq 1. \] (16)

As \((\mathcal{N}(b), \overline{\mathcal{N}}(b))\) are \(q\)-RFSs, \(\mathcal{N}(b), \overline{\mathcal{N}}(b)\): \(q-RFS(\Omega) \rightarrow q-RFS(\Omega)\) are upper and lower approximation operators. The pair

\[ \mathcal{N}(b) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \subseteq b \right\}, \]
\[ \overline{\mathcal{N}}(b) = \left\{ \hat{g} \in \Omega \mid \overline{\mathcal{N}}^{\prime}(\hat{g}) \subseteq b \right\}, \] (17)

is known as the \(q\)-run rough set. For simplicity,

\[ \mathcal{N}(b) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \subseteq b \right\}, \]
\[ \overline{\mathcal{N}}(b) = \left\{ \hat{g} \in \Omega \mid \overline{\mathcal{N}}^{\prime}(\hat{g}) \subseteq b \right\} \] (18)

is represented as \((\mathcal{N}(b), \overline{\mathcal{N}}(b))\) and is known as a \(q\)-RFRV.

### 3. Construction of \(q\)-Rung Orthopair Hesitant Fuzzy Rough Sets

In this section, we propose the notion of \(q\)-ROHFRS which is the hybrid structure of the rough set and \(q\)-ROFS. We also introduce the new accuracy and score functions to rank the \(q\)-ROHFRS and also put forward its basic operational laws.

**Definition 16.** Let \(\Omega\) be the universal set. Then, any subset \(\mathcal{N} \in q-RROHFS(\Omega \times \Omega)\) is said to be a \(q\)-RHF relation. The pair \((\Omega, \mathcal{N})\) is called the \(q\)-ROH approximation space. For any \(b \in q-RROHFS(\Omega)\), the upper and lower approximations of \(b\) with respect to the \(q\)-ROH approximation space \((\Omega, \mathcal{N})\) are two \(q\)-ROHFSs, which are denoted by \(\overline{\mathcal{N}}(b)\) and \(\mathcal{N}(b)\) and defined as

\[ \overline{\mathcal{N}}(b) = \left\{ \hat{g} \in \Omega \mid \overline{\mathcal{N}}^{\prime}(\hat{g}) \subseteq b \right\}, \]
\[ \mathcal{N}(b) = \left\{ \hat{g} \in \Omega \mid \mathcal{N}^{\prime}(\hat{g}) \subseteq b \right\}, \] (19)

where

\[ \beta_{\mathcal{N}}^{\prime}(\hat{g}) = \bigwedge_{a \in \Omega} \left[ \beta_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \beta_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \psi_{\mathcal{N}}^{\prime}(\hat{g}) = \bigvee_{a \in \Omega} \left[ \psi_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \psi_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \beta_{\overline{\mathcal{N}}}(\hat{g}) = \bigvee_{a \in \Omega} \left[ \beta_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \beta_{\mathcal{N}}^{\prime}(a, b) \right], \]
\[ \psi_{\overline{\mathcal{N}}}(\hat{g}) = \bigwedge_{a \in \Omega} \left[ \psi_{\mathcal{N}}^{\prime}(\hat{g}, a) \land \psi_{\mathcal{N}}^{\prime}(a, b) \right], \] (20)

such that

\[ 0 \leq \left( \max \left( \beta_{\mathcal{N}}^{\prime}(\hat{g}) \right) \right)^{q} + \left( \min \left( \psi_{\mathcal{N}}^{\prime}(\hat{g}) \right) \right)^{q} \leq 1, \]
\[ 0 \leq \left( \min \left( \beta_{\overline{\mathcal{N}}}(\hat{g}) \right) \right)^{q} + \left( \max \left( \psi_{\overline{\mathcal{N}}}(\hat{g}) \right) \right)^{q} \leq 1. \] (21)

As \((\mathcal{N}(b), \overline{\mathcal{N}}(b))\) are \(q\)-ROHFSs, \(\overline{\mathcal{N}}(b), \mathcal{N}(b): q-RROHFS(\Omega) \rightarrow q-RFS(\Omega)\) are upper and lower approximation operators. The pair
\[ N(b) = (N(b), \overline{N}(b)) = \left\{ \hat{g}, \left( \beta_{h_{\|b\|}}(\hat{g}), \psi_{h_{\|b\|}}(\hat{g}) \right), \left( \beta_{\overline{h}_{\|b\|}}(\hat{g}), \psi_{\overline{h}_{\|b\|}}(\hat{g}) \right) \mid \hat{g} \in b \right\} \]  

(22)

will be called \( q \)-ROHFRS. For simplicity,

\[ N(b) = \left\{ \hat{g}, \left( \beta_{h_{\|b\|}}(\hat{g}), \psi_{h_{\|b\|}}(\hat{g}) \right), \left( \beta_{\overline{h}_{\|b\|}}(\hat{g}), \psi_{\overline{h}_{\|b\|}}(\hat{g}) \right) \mid \hat{g} \in b \right\} \]  

(23)

is represented as \( N(b) = ((\xi, \eta), (\overline{\beta}, \overline{\psi})) \) and is known as \( q \)-ROHFVR.

**Definition 17.** Let \( N(b_1) = (N(b_1), \overline{N}(b_1)) \) and \( N(b_2) = (N(b_2), \overline{N}(b_2)) \) be two \( q \)-ROHFRSs. Then,

1. \( N(b_1) \cup N(b_2) = \{ (N(b_1) \cup N(b_2)), (\overline{N}(b_1) \cup \overline{N}(b_2)) \} \)
2. \( N(b_1) \cap N(b_2) = \{ (N(b_1) \cap N(b_2)), (\overline{N}(b_1) \cap \overline{N}(b_2)) \} \)
3. \( N(b_1) \oplus N(b_2) = \{ (N(b_1) \oplus N(b_2)), (\overline{N}(b_1) \oplus \overline{N}(b_2)) \} \)
4. \( N(b_1) \otimes N(b_2) = \{ (N(b_1) \otimes N(b_2)), (\overline{N}(b_1) \otimes \overline{N}(b_2)) \} \)

For comparing/ranking two or more \( q \)-ROHFRVs, the score function will be utilized, whereas the accuracy function will be used when the score values are equal. The accuracy function will be used when the score values are equal.

**Definition 18.** The score function for \( q \)-ROHFVR \( N(b) = (N(b), \overline{N}(b)) = ((\xi, \eta), (\overline{\beta}, \overline{\psi})) \) is given as

\[ G_0(N(b)) = \frac{1}{4} \left( 2 + \frac{1}{M_3} \sum_{\omega \in \beta_{\|b\|}} \{ \omega_h \} + \frac{1}{N_3} \sum_{\overline{\omega} \in \beta_{\|b\|}} \{ \overline{\omega}_h \} - \frac{1}{M_3} \sum_{\omega \in \beta_{\|b\|}} \{ \omega_h \} - \frac{1}{N_3} \sum_{\overline{\omega} \in \beta_{\|b\|}} \{ \overline{\omega}_h \} \right) \]  

(24)

where \( M_3 \) and \( N_3 \) are the number of elements in \( \beta_{h} \) and \( \psi_{\overline{h}} \), respectively.

**Definition 19.** Suppose \( N(b_1) = (N(b_1), \overline{N}(b_1)) \) and \( N(b_2) = (N(b_2), \overline{N}(b_2)) \) are two \( q \)-ROHFRVs. Then,

1. If \( G_0(N(b_1)) > G_0(N(b_2)) \), then \( N(b_1) > N(b_2) \)
2. If \( G_0(N(b_1)) < G_0(N(b_2)) \), then \( N(b_1) < N(b_2) \)
3. If \( G_0(N(b_1)) = G_0(N(b_2)) \), then
   a. If \( \mathcal{R}(N(b_1)) > \mathcal{R}(N(b_2)) \), then \( N(b_1) > N(b_2) \)
   b. If \( \mathcal{R}(N(b_1)) < \mathcal{R}(N(b_2)) \), then \( N(b_1) < N(b_2) \)
   c. If \( \mathcal{R}(N(b_1)) = \mathcal{R}(N(b_2)) \), then \( N(b_1) = N(b_2) \)

4. **Construction of \( q \)-Rung Orthopair Probabilistic Hesitant Fuzzy Rough Sets**

This section deals with the notion of \( q \)-ROHFRS which is the hybrid structure of the rough set and \( q \)-ROPHFS. We also establish the new score and accuracy functions to rank the \( q \)-ROPHFRS and also discuss the operational laws.

**Definition 20.** Let \( \Omega \) be the universal set. Then, any subset \( \mathcal{N} \in q - \text{ROPHFS}(\Omega \times \Omega) \) is said to be a \( q \)-rung probabilistic HF relation. The pair \( (\Omega, N) \) is called the \( q \)-ROPHF approximation space. If for any \( b \in q - \text{ROPHFS}(\Omega) \), the upper and lower approximations of \( b \) with respect to the \( q \)-ROPHF approximation space \( (\Omega, N) \) are two \( q \)-ROPHFSs, which are denoted by \( \overline{N}(b) \) and \( N(b) \) and defined as

\[ N(b) = \left\{ \frac{\beta_{h_{\|b\|}} (\hat{g})}{\delta_{h_{\|b\|}}}, \frac{\psi_{h_{\|b\|}} (\hat{g})}{\delta_{h_{\|b\|}}} \mid \hat{g} \in \Omega \right\}, \]  

(26)

\[ \overline{N}(b) = \left\{ \frac{\beta_{\overline{h}_{\|b\|}} (\hat{g})}{\delta_{\overline{h}_{\|b\|}}}, \frac{\psi_{\overline{h}_{\|b\|}} (\hat{g})}{\delta_{\overline{h}_{\|b\|}}} \mid \hat{g} \in \Omega \right\}. \]
where
\[
\begin{align*}
\beta_{h_1}(\hat{g}) &= \bigvee_{k \in \mathbb{N}} \left[ \psi_{h_1}(\hat{g}, k) \right] \\
\delta_{h_1}(\hat{g}) &= \bigwedge_{k \in \mathbb{N}} \left[ \psi_{h_1}(\hat{g}, k) \right]
\end{align*}
\]

such that
\[
0 \leq \left( \max \left( \beta_{h_1}(\hat{g}) \right) \right)^q + \left( \min \left( \delta_{h_1}(\hat{g}) \right) \right) \leq 1,
\]
\[
0 \leq \left( \max \left( \delta_{h_1}(\hat{g}) \right) \right)^q + \left( \min \left( \beta_{h_1}(\hat{g}) \right) \right) \leq 1.
\]

As \( (\overline{\mathbb{N}}(b), \mathbb{N}(b)) \) are \( q \)-ROPHFSs, \( \overline{\mathbb{N}}(b), \mathbb{N}(b): q \)-ROPHFSs \( \Omega \longrightarrow q \)-RFSs \( \Omega \) are upper and lower approximation operators. The pair
\[
(\mathbb{N}(b), \overline{\mathbb{N}}(b))
\]
will be called \( q \)-runge orthopair HFRS. For simplicity,
\[
\mathbb{N}(b) = \left\{ \hat{g} \left| \beta_{h_1}(\hat{g}) \delta_{h_1}(\hat{g}) \right\} \right. \cup \left. \left( \beta_{h_1}(\hat{g}) \delta_{h_1}(\hat{g}) \right) \hskip0.5cm \hat{g} \in b \right\}
\]
is represented as \( \mathbb{N}(b) = ((\xi / \partial \eta / \partial), (\beta / \delta, \psi / \delta)) \) and known as \( q \)-ROPHFRV.

Definition 21. Let \( \mathbb{N}(b_1) = (\mathbb{N}(b_1), \overline{\mathbb{N}}(b_1)) \) and \( \mathbb{N}(b_2) = (\mathbb{N}(b_2), \overline{\mathbb{N}}(b_2)) \) be two \( q \)-ROPHFRSs. Then,
\[
\begin{align*}
(1) \mathbb{N}(b_1) \cup \mathbb{N}(b_2) &= \left\{ (\mathbb{N}(b_1) \cup \mathbb{N}(b_2)), \right. \\
(\overline{\mathbb{N}}(b_1) \cup \overline{\mathbb{N}}(b_2)) \left. \right\}
\end{align*}
\]
\[
(2) \mathbb{N}(b_1) \cap \mathbb{N}(b_2) = \left\{ (\mathbb{N}(b_1) \cap \mathbb{N}(b_2)), \right. \\
(\overline{\mathbb{N}}(b_1) \cap \overline{\mathbb{N}}(b_2)) \left. \right\}
\]
\[
(3) \mathbb{N}(b_1) \oplus \mathbb{N}(b_2) = \left\{ (\mathbb{N}(b_1) \oplus \mathbb{N}(b_2)), \right. \\
(\overline{\mathbb{N}}(b_1) \oplus \overline{\mathbb{N}}(b_2)) \left. \right\}
\]
\[
(4) \mathbb{N}(b_1) \otimes \mathbb{N}(b_2) = \left\{ (\mathbb{N}(b_1) \otimes \mathbb{N}(b_2)), \right. \\
(\overline{\mathbb{N}}(b_1) \otimes \overline{\mathbb{N}}(b_2)) \left. \right\}
\]
\[
(5) \mathbb{N}(b_1) \subseteq \mathbb{N}(b_2) = \left\{ (\mathbb{N}(b_1) \subseteq \mathbb{N}(b_2)), \right. \\
(\overline{\mathbb{N}}(b_1) \subseteq \overline{\mathbb{N}}(b_2)) \left. \right\}
\]

Definition 22. The score function for \( q \)-ROPHFRV
\[
\mathbb{N}(b) = \left( (\xi / \partial \eta / \partial), (\beta / \delta, \psi / \delta) \right)
\]
is given as
\[
G_{\phi}(N(b)) = \frac{1}{4} \left[ \frac{1}{M_{\phi}} \sum_{\omega \in \beta_{h_{1}}} \sum_{\delta \in \beta_{h_{2}}} \left( \omega \times \delta \right) + \frac{1}{N_{\phi}} \sum_{\eta \in \beta_{h_{1}}} \sum_{\epsilon \in \beta_{h_{2}}} \left( \eta \times \epsilon \right) \right] - \frac{1}{M_{\phi}} \sum_{\omega \in \beta_{h_{1}}} \sum_{\delta \in \beta_{h_{2}}} \left( \omega \times \delta \right) - \frac{1}{N_{\phi}} \sum_{\eta \in \beta_{h_{1}}} \sum_{\epsilon \in \beta_{h_{2}}} \left( \eta \times \epsilon \right) \right]
\]

(32)

The accuracy function for \(q\)-RolphFRV
\[N(b) = (N(b_1), N(b_2)) = ((\xi/\delta, \eta/\partial), (\beta/\delta, \psi/\partial))\] is given as

\[
\mathfrak{A}(N(b)) = \frac{1}{4} \left[ \frac{1}{M_{\phi}} \sum_{\omega \in \beta_{h_{1}}} \sum_{\delta \in \beta_{h_{2}}} \left( \omega \times \delta \right) + \frac{1}{N_{\phi}} \sum_{\eta \in \beta_{h_{1}}} \sum_{\epsilon \in \beta_{h_{2}}} \left( \eta \times \epsilon \right) \right] + \left( \frac{1}{M_{\phi}} \sum_{\omega \in \beta_{h_{1}}} \sum_{\delta \in \beta_{h_{2}}} \left( \omega \times \delta \right) + \frac{1}{N_{\phi}} \sum_{\eta \in \beta_{h_{1}}} \sum_{\epsilon \in \beta_{h_{2}}} \left( \eta \times \epsilon \right) \right)
\]

(33)

where \(M_{\phi}\) and \(N_{\phi}\) represent the number of elements in \(\beta_{h_{1}}\)
and \(\beta_{h_{2}}\), respectively.

Definition 23. Suppose \(N(b_1) = (N(b_1), N(b_2))\) and \(N(b_2) = (N(b_1), N(b_2))\) are two \(q\)-RolphFRVs. Then,

1. If \(G_{\phi}(N(b_1)) > G_{\phi}(N(b_2))\), then \(N(b_1) > N(b_2)\)
2. If \(G_{\phi}(N(b_1)) < G_{\phi}(N(b_2))\), then \(N(b_1) < N(b_2)\)
3. If \(G_{\phi}(N(b_1)) = G_{\phi}(N(b_2))\), then
   a. If \(\mathfrak{A}(N(b_1)) > \mathfrak{A}(N(b_2))\), then \(N(b_1) > N(b_2)\)
   b. If \(\mathfrak{A}(N(b_1)) < \mathfrak{A}(N(b_2))\), then \(N(b_1) < N(b_2)\)
   c. If \(\mathfrak{A}(N(b_1)) = \mathfrak{A}(N(b_2))\), then \(N(b_1) = N(b_2)\)

5. \(q\)-Rung Orthopair Probabilistic Hesitant Fuzzy Rough Aggregation Operators

In this section, we propose a new idea of \(q\)-RolphF rough AOPs by embedding the notions of the RS and \(q\)-RolphF AOPs to get aggregation concepts of \(q\)-RolphFREWA and \(q\)-RolphFREWGA. Furthermore, some fundamental properties of the notion are discussed.

5.1. \(q\)-Rung Orthopair Probabilistic Hesitant Fuzzy Rough Einstein Weighted Averaging Operator

Definition 24. Let \(N(b_t) = (N(b_1), N(b_2), \ldots, N(b_n))\) be the collection of \(q\)-RolphFRVs. Then, the \(q\)-RolphFREWA operator is determined by

\[
q - \text{RolphFREWA}(N(b_1, N(b_2, \ldots, N(b_n))) = \left( \frac{\sum_{t=1}^{n} \gamma_t N(b_t)}{\sum_{t=1}^{n} \gamma_t}, \frac{\sum_{t=1}^{n} \gamma_t N(b_t)}{\sum_{t=1}^{n} \gamma_t} \right),
\]

(34)

where \(\gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T\) are the weight vector such that \(\sum_{t=1}^{n} \gamma_t = 1 \) and \(0 \leq \gamma_t \leq 1\) and \(\delta_{h_1}\) and \(\delta_{h_2}\) are probabilistic terms such that \(\Phi_{h_1}, \delta_{h_1} = 1\) and \(\Phi_{h_2}, \delta_{h_2} = 1\).

Theorem 1. Let \(N(b_t) = (N(b_1), N(b_2), \ldots, N(b_n))\) be the collection of \(q\)-RolphFRVs. Then, the \(q\)-RolphFREWA operator is defined by
\[ q - \text{ROPHREWA}(N(b_1), N(b_2), \ldots, N(b_n)) \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]
\[ U_{\omega_h} \in \beta_{h_{(n)}}^{0}, \delta_h \in \partial_{h_{(n)}} \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]
\[ U_{\omega'_h} \in \psi_{h_{(n)}}^{0}, \delta_h \in \partial_{h_{(n)}} \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]
\[ U_{\omega''_h} \in \psi_{h_{(n)}}^{0}, \delta_h \in \partial_{h_{(n)}} \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]
\[ (N(b_1) \otimes N(b_2)) \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]
\[ q - \text{ROPHREWG}(N(b_1), N(b_2)) \]
\[ = \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]

where \( \gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T \) are the weight vector such that \( 0 \leq \gamma_i \leq 1 \) and \( \omega_h, \delta_h \) are probabilistic terms such that \( \sum_{i=1}^{n} \gamma_i = 1 \) and \( \sum_{i=1}^{n} \delta_h = 1 \).

**Proof.** We will prove the aforesaid theorem by utilizing mathematical induction. Suppose \( n = 2 \). Then,

\[ \left( \sum_{i=1}^{n} \gamma_i N(b_i), 0 \right), \]

and the result is true for \( n = 2 \). Now, suppose the result is true for \( n = k \).
Next, we shall show that the result is true for $n = k + 1$.

$$q - \text{ROPHFREWA}(N(b_1), N(b_2), \ldots, N(b_k))$$

$$= \left( \frac{k}{t = 1} \gamma, N(b_t), \frac{k}{t = 1} \gamma, N(b_t) \right)$$

$$= \left( \bigcup_{\omega_{b_t} \in \beta_{\rho_{2(t)}}, \delta_{b_t} \in \delta_{\rho_{2(t)}}} \left( \bigcap_{t = 1}^{k} \left( 1 + \omega_{b_t} \right)^{\frac{q_t}{r}} - \bigcap_{t = 1}^{k} \left( 1 - \omega_{b_t} \right)^{\frac{q_t}{r}} \right) \bigcup_{t = 1}^{k} \left( 1 + \omega_{b_t} \right)^{\frac{q_t}{r}} + \bigcup_{t = 1}^{k} \left( 1 - \omega_{b_t} \right)^{\frac{q_t}{r}} \right),$$

$$= \left( \bigcup_{\nu_{b_t} \in \psi_{\rho_{2(t)}}, \tilde{\delta}_{b_t} \in \delta_{\rho_{2(t)}}} \left( \bigcap_{t = 1}^{k} \left( 1 + \nu_{b_t} \right)^{\frac{q_t}{r}} - \bigcap_{t = 1}^{k} \left( 1 - \nu_{b_t} \right)^{\frac{q_t}{r}} \right) \bigcup_{t = 1}^{k} \left( 1 + \nu_{b_t} \right)^{\frac{q_t}{r}} + \bigcup_{t = 1}^{k} \left( 1 - \nu_{b_t} \right)^{\frac{q_t}{r}} \right),$$

$$= \left( \bigcup_{\tau_{b_t} \in \psi_{\rho_{2(t)}}, \delta_{b_t} \in \delta_{\rho_{2(t)}}} \left( \bigcap_{t = 1}^{k} \left( 1 + \tau_{b_t} \right)^{\frac{q_t}{r}} - \bigcap_{t = 1}^{k} \left( 1 - \tau_{b_t} \right)^{\frac{q_t}{r}} \right) \bigcup_{t = 1}^{k} \left( 1 + \tau_{b_t} \right)^{\frac{q_t}{r}} + \bigcup_{t = 1}^{k} \left( 1 - \tau_{b_t} \right)^{\frac{q_t}{r}} \right)$$
Theorem 2. Let $\mathcal{N}(b_i) = (\mathcal{N}(b_i), \overline{\mathcal{N}}(b_i)) (t = 1, 2, 3, \ldots, n)$ be the collection of $q$-ROPHFRVs, $y = (y_1, y_2, \ldots, y_n)^T$ be the weight vector such that $y_t \in \{0, 1\}$ and $\alpha_{h_i}^t y_t = 1$, and $\partial_{h_i}$ and $\partial_{h_i}^t$ be probabilistic terms such that $\alpha_{h_i}^t \partial_{h_i}^t = 1$ and $\alpha_{h_i}^t \partial_{h_i} = 1$. Then, the $q$-ROPHFRWA operator satisfies the following properties:

1. Idempotency: if $\mathcal{N}(b_i) = \mathcal{F}(b)$ for $t = 1, 2, 3, \ldots, n$ where

$$\mathcal{F}(b) = (\alpha(b), \overline{\mathcal{F}}(b)) = \left( \frac{b_{h_i}(x)}{\partial_{h_i}(x)} \frac{d_{h_i}(x)}{\partial_{h_i}(x)} \left( \frac{b_{h_i}(x)}{\partial_{h_i}(x)} \frac{d_{h_i}(x)}{\partial_{h_i}(x)} \right) \right),$$

then

$$q - \text{ROPHFRWG}(\mathcal{N}(b_1), \mathcal{N}(b_2), \ldots, \mathcal{N}(b_n)) = \mathcal{F}(b).$$

2. Boundedness: let $(\mathcal{N}(b))_{\min} = (\min, \overline{\mathcal{N}}(b_i))$ and $(\mathcal{N}(b))_{\max} = (\max, \overline{\mathcal{N}}(b_i))$. Then,

$$(\mathcal{N}(b))_{\min} \leq q - \text{ROPHFRWG}(\mathcal{N}(b_1), \mathcal{N}(b_2), \ldots, \mathcal{N}(b_n)) \leq (\mathcal{N}(b))_{\max}.$$  

3. Monotonicity: suppose $\mathcal{F}(b) = (\alpha(b), \overline{\mathcal{F}}(b))$ $(t = 1, 2, \ldots, n)$ is another collection of $q$-ROPHFRVs such that $\alpha(b) \leq \mathcal{N}(b_i)$ and $\mathcal{F}(b) \leq \overline{\mathcal{N}}(b_i)$. Then,

$$q - \text{ROPHFRWG}(\mathcal{F}(b_1), \mathcal{F}(b_2), \ldots, \mathcal{F}(b_n)) \leq q - \text{ROPHFRWG}(\mathcal{N}(b_1), \mathcal{N}(b_2), \ldots, \mathcal{N}(b_n)).$$

Proof.

1. Idempotency: as $\mathcal{N}(b_i) = \mathcal{F}(b)$ (for all $t = 1, 2, 3, \ldots, n$) where $\mathcal{F}(b) = (\alpha(b), \overline{\mathcal{F}}(b)) = ((b_{h_i}(x) / \partial_{h_i}(x), d_{h_i}(x) / \partial_{h_i}(x)), \alpha_{h_i}^t / \partial_{h_i}(x), \partial_{h_i} / \partial_{h_i}(x))$, it follows that

$$q - \text{ROPHFRA}(\mathcal{N}(b_1), \mathcal{N}(b_2), \ldots, \mathcal{N}(b_n))$$

$$= \left( \prod_{t=1}^n \mathcal{N}(b_i) \prod_{t=1}^n \overline{\mathcal{N}}(b_i) \right)$$

$$= \left( \prod_{t=1}^n \mathcal{F}(b) \prod_{t=1}^n \overline{\mathcal{F}}(b) \right)$$

$$= \left( \prod_{t=1}^n \mathcal{F}(b) \prod_{t=1}^n \overline{\mathcal{F}}(b) \right)$$

$$= \left( \prod_{t=1}^n \mathcal{F}(b) \prod_{t=1}^n \overline{\mathcal{F}}(b) \right)$$

for all $t$, $((\alpha(b), \overline{\mathcal{F}}(b)) = ((b_{h_i}(x) / \partial_{h_i}(x), d_{h_i}(x) / \partial_{h_i}(x)), \alpha_{h_i}^t / \partial_{h_i}(x), \partial_{h_i} / \partial_{h_i}(x))$. It follows that
\[
\begin{align*}
\left(\bigcup_{b_n \in \mathcal{B}_{\Pi(\eta)}} \delta_{\eta} \otimes \delta_{\eta}\right) & \left(\sqrt{2} \otimes_{t=1}^{n} \left(\left(\frac{1}{2} \cdot (b_n)^q \right)^{\gamma^T} \right) \right) / \left(\sqrt{2} \otimes_{t=1}^{n} \left(2 \cdot (d_n)^q \right)^{\gamma^T} \right) + \left(\left(\frac{1}{2} \cdot (d_n)^q \right)^{\gamma^T} \right) / \left(\sqrt{2} \otimes_{t=1}^{n} \left(1 \cdot (b_n)^q \right)^{\gamma^T} \right) + \left(\left(\frac{1}{2} \cdot (b_n)^q \right)^{\gamma^T} \right) / \left(\sqrt{2} \otimes_{t=1}^{n} \left(1 \cdot (b_n)^q \right)^{\gamma^T} \right),
\end{align*}
\]

Hence, \( q \)-ROPHREW \( (N(b_1), N(b_2), \ldots , \)
\( N(b_n)) = \pi(b) \).

(2) Boundedness:
(N(b))^+ = \left( \min_t \left\{ \frac{\omega_h}{\delta_h} \right\}, \max_t \left\{ \frac{v_h}{\delta_h} \right\} \right),
(45)

\text{and } N(v_i) = \{ [\xi \partial_{\xi}, \eta \partial_{\eta}, (\beta_i \partial_{h_i}, \varphi_i / \delta_{h_i})] \} \text{ to prove that}

(N(b))^+ \leq q - ROHFREWG(N(v_1), N(v_2), \ldots, N(v_n)) \leq (N(b))^+.
(46)

Let \( f(y) = \sqrt{1 - y^3} \) for \( y \in [0, 1] \). Then, \( f'(y) = -2y/(1 + y)^3 \sqrt{(1 - y^3)/(1 + y^3)^{3/2}} < 0 \). Thus, \( f(y) \) is a decreasing function over \([0, 1]\). Since \( \{\omega_{h_{max}}\} \leq \{\omega_h\} \leq \{\omega_{h_{max}}\} \) for all \( i \),
\( g(\omega_{h_{max}}) \leq g(\omega_h) \leq g(\omega_{h_{max}}) \) for \( t = 1, 2, 3, \ldots, n \), i.e.,

\[
\frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}} \leq \frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}},
\]

\[
\leq \frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}},
\]

\[
\leq \frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}}.
\]

(47)

and let \( y = (y_1, y_2, \ldots, y_n)^T \) be the weight vector such that \( y_i \in [0, 1] \) and \( \prod_{i=1}^{n} \gamma_i = 1 \) and \( \delta_{h_i} \) be the probabilistic term such that \( \phi_{t=1}^{n} \delta_{h_i} = 1 \); we have

\[
\frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}} \leq \frac{\sqrt{\prod_{i=1}^{n} \left( 1 - \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right) \left( 1 + \frac{\omega_{h_{max}}^3}{\omega_{h}^3} \right)^{\gamma_i}}}{\prod_{i=1}^{n} \frac{\omega_{h_{max}}}{\omega_{h}}}.
\]

(48)
In a similar way, we can show that
\[
\frac{\partial h_{\text{max}}}{\delta_{\text{max}}} \leq \frac{\sqrt{\sum_{t=1}^{n} \left( 2 - \left( \frac{v_{\text{max}}}{v_{h_t}} \right)^3 \right)^2}}{\sum_{t=1}^{n} \partial_{h_t}} \leq \frac{\sqrt{\sum_{t=1}^{n} \left( 2 - \left( \frac{v_{\text{max}}}{v_{h_t}} \right)^3 \right)^3}}{\sum_{t=1}^{n} \partial_{h_t}}
\]
(50)

Again, let \( g(x) = \sqrt{(2 - x^3)/x^3} \), \( x \in (0, 1] \); then, \( g'(x) = (2 - x^2)x^{-2}x^2 \leq 0 \). So, \( g(x) \) is a decreasing function on \((0, 1]\). Since

\[
\frac{\sqrt{\sum_{t=1}^{n} \left( 2 - \left( \frac{v_{\text{max}}}{v_{h_t}} \right)^3 \right)^3}}{\sum_{t=1}^{n} \partial_{h_t}} \leq \frac{\sqrt{\sum_{t=1}^{n} \left( 2 - \left( \frac{v_{\text{max}}}{v_{h_t}} \right)^3 \right)^3 \Phi_{v_{\text{max}}}}}{\sum_{t=1}^{n} \partial_{h_t}} \leq \frac{\sqrt{\sum_{t=1}^{n} \left( 2 - \left( \frac{v_{\text{max}}}{v_{h_t}} \right)^3 \right)^3 \Phi_{v_{\text{max}}}}}{\sum_{t=1}^{n} \partial_{h_t}}
\]
(52)
Similarly, we can show that
\[ \frac{\nabla_{n_{min}}}{\delta_{n_{max}}} \leq \frac{\nabla_{n_{min}}}{\delta_{n_{max}}} \left( \frac{1}{\nabla_{n_{max}}} \left( 2 - \left( \frac{\nabla_{n}}{\delta_{n}} \right)^3 \right) \right) \]
(53)

Thus, from equations (48), (49), (52), and (53), we have
\[ (N(b))^{-} \leq q \text{ - ROPHFREWG}(N(b_1), N(b_2), \ldots, N(b_n)) \leq (N(b))^+. \]
(54)

(3) Monotonicity: the proof is similar to the proof of (2).

6. \( q \)-Rung Orthopair Probabilistic Hesitant Fuzzy Rough Einstein Weighted Geometric Aggregation Operator

In this section, the \( q \)-ROPHFREWG aggregation operator is introduced, and the key characteristics of the proposed operators are demonstrated.

Definition 25. Let \( N(b_t) = (N(b_t), \overline{N}(b_t)) (t = 1, 2, 3, 4, \ldots, n) \) be the collection of \( q \)-ROPHFRVs. Then, \( q \)-ROPHFREWG operator is determined as
\[ q \text{ - ROPHFREWG}(N(b_1), N(b_2), \ldots, N(b_n)) = \left( \bigotimes_{t=1}^{n} (N(b_t))^\gamma_t, \bigotimes_{t=1}^{n} (\overline{N}(b_t))^\gamma_t \right), \]
(55)

where \( \gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T \) is the weight vector such that \( \overline{\Theta}_{t=1}^n \gamma_t = 1 \) and \( 0 \leq \gamma_t \leq 1 \) and \( \delta_{b_t} \) and \( \overline{\delta}_{b_t} \) are probabilistic terms such that \( \overline{\Theta}_{t=1}^n \delta_{b_t} = 1 \) and \( \overline{\Theta}_{t=1}^n \overline{\delta}_{b_t} = 1 \).

Theorem 3. Let \( N(b_t) = (N(b_t), \overline{N}(b_t)) (t = 1, 2, 3, \ldots, n) \) be the collection of \( q \)-ROPHFRVs with the weight vector \( \gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T \) such that \( \overline{\Theta}_{t=1}^n \gamma_t = 1 \) and \( 0 \leq \gamma_t \leq 1 \). Then, the \( q \)-ROPHFREWG operator is described as

\[ q \text{ - ROPHFREWG}(N(b_1), N(b_2), \ldots, N(b_n)) = \left( \bigotimes_{t=1}^{n} (N(b_t))^\gamma_t, \bigotimes_{t=1}^{n} (\overline{N}(b_t))^\gamma_t \right), \]
(56)
where $\gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T$ is the weight vector such that $\gamma_i \geq 1$ and $0 \leq \gamma_i \leq 1$ and $\delta_{h_i}$ and $\partial_{h_i}$ are probabilistic terms such that $\gamma_i \geq 1$ and $\partial_i \geq 1$.

\[ \begin{align*}
q \text{- ROPHFREWG}(N(b_1), N(b_2), N(b_3), \ldots, N(b_k)) &= \left( \bigotimes_{i=1}^{k} N(b_i) \right)^H = \left( \bigotimes_{i=1}^{k} (N(b_i))_i \right)^H \\
&= \left( \left( \bigotimes_{i=1}^{k} \partial_i \bigotimes_{i=1}^{k} \delta_i \bigotimes_{i=1}^{k} \partial_i \right)^H \right). \\
&= \left( \left( \bigotimes_{i=1}^{k} \partial_i \bigotimes_{i=1}^{k} \delta_i \bigotimes_{i=1}^{k} \partial_i \right)^H \right) = \left( \left( \bigotimes_{i=1}^{k} \partial_i \bigotimes_{i=1}^{k} \delta_i \bigotimes_{i=1}^{k} \partial_i \right)^H \right). \\
&= \left( \left( \bigotimes_{i=1}^{k} \partial_i \bigotimes_{i=1}^{k} \delta_i \bigotimes_{i=1}^{k} \partial_i \right)^H \right).
\end{align*} \]
Furthermore, we are going to show that the result holds for \( n = k + 1 \).

\[
q - \text{ROPHFREW}(\mathbb{N}(b_1), \mathbb{N}(b_2), \ldots, \mathbb{N}(b_n)) = \left( \bigotimes_{t=1}^k \left( (\mathbb{N}(b_t))^\gamma \right) \right) \otimes (\mathbb{N}(b_{k+1}))^{w_{k+1}},
\]

\[
\begin{align*}
U_{\mathbb{N}_{q_{(1)}}, \mathbb{N}_{q_{(2)}}} \left( \frac{\bigotimes_{t=1}^{k+1} \left( \mathbb{N}(b_t) \right)^{w_{t-1}}}{\bigotimes_{t=1}^{k+1} \left( \mathbb{N}(b_t) \right)^{w_{t-1}}} \right) = \left( \bigotimes_{t=1}^{k+1} \left( \mathbb{N}(b_t) \right) \right)^{w_{k+1}}.
\end{align*}
\]

Hence, the result holds for \( n = k + 1 \). Thus, the result is true for all \( n \geq 1 \). \( \square \)

**Theorem 4.** Let \( \mathbb{N}(b_t) = (\mathbb{N}(b_t), \mathbb{N}(b_t)) \) \((t = 1, 2, 3, \ldots, n)\) be the collection of \( q \)-ROPHFRVs, \( \gamma = (\gamma_1, \gamma_2, \ldots, \gamma_n)^T \) be the weight vector such that \( \gamma_t \in (0, 1) \) with the property that

\[
\gamma \bullet \mathbb{N} = 1, \quad \text{and} \quad \gamma \bullet \mathbb{N} = 1 \quad \text{and} \quad \gamma \bullet \mathbb{N} = 1.
\]

Then, the \( q \)-ROPHFRG operator satisfies the following properties:

1. **Idempotency:** if \( \mathbb{N}(b_t) = \mathbb{X}(\mathbb{X}) \) for \( t = 1, 2, 3, \ldots, n \)

\[
\mathbb{X} = \left( \left( \mathbb{X}(b_t) \right)^{w_{t-1}} \right) \otimes (\mathbb{X}(b_{k+1}))^{w_{k+1}},
\]

then

\[
q - \text{ROPHFREW}(\mathbb{N}(b_1), \mathbb{N}(b_2), \ldots, \mathbb{N}(b_n)) = \mathbb{X}.
\]

2. **Boundedness:** let \( \mathbb{N}(b_t) = (\mathbb{N}(b_t), \mathbb{N}(b_t)) \quad \text{and} \quad \mathbb{N}(b_t) = (\mathbb{N}(b_t), \mathbb{N}(b_t)) \). Then,

\[
\mathbb{N}(b_t) \leq q - \text{ROPHFREW}(\mathbb{N}(b_1), \mathbb{N}(b_2), \ldots, \mathbb{N}(b_n)) \leq \mathbb{N}(b_t)
\]

Proof:

1. **Idempotency:** as \( \mathbb{N}(b_t) = \mathbb{X}(\mathbb{X}) \) (for all \( t = 1, 2, 3, \ldots, n \)) where \( \mathbb{X}(b_t) = (\mathbb{X}(b_t), \mathbb{X}(b_t)) \) it follows that

\[
\mathbb{X} = \left( \left( \mathbb{X}(b_t) \right)^{w_{t-1}} \right) \otimes (\mathbb{X}(b_{k+1}))^{w_{k+1}},
\]

then

\[
q - \text{ROPHFREW}(\mathbb{N}(b_1), \mathbb{N}(b_2), \ldots, \mathbb{N}(b_n)) = \mathbb{X}.
\]
\[ q - \text{ROPHFREWG}(\mathbb{N}(b_1), \mathbb{N}(b_2), \ldots, \mathbb{N}(b_n)) \]
\[ = \left( \bigotimes_{t=1}^{n} (\mathbb{N}(b_t))^{\gamma_t}, \bigotimes_{t=1}^{n} (\overline{\mathbb{R}}(b_t))^{\gamma_t} \right) \]
\[ = \left\{ \begin{array}{l}
\left( 2 \bigotimes_{t=1}^{n} (\overline{\mathbb{R}}(b_t))^{\gamma_t} \right) / \left( \bigotimes_{t=1}^{n} (2 - \overline{\mathbb{R}}(b_t))^{\gamma_t} + \bigotimes_{t=1}^{n} (\overline{\mathbb{R}}(b_t))^{\gamma_t} \right), \\
\end{array} \right. \]
\[ = \left\{ \begin{array}{l}
\left( \bigotimes_{t=1}^{n} (1 + \mathbb{N}(b_t))^{\gamma_t} - \bigotimes_{t=1}^{n} (1 - \mathbb{N}(b_t))^{\gamma_t} \right) / \left( \bigotimes_{t=1}^{n} (2 + \mathbb{N}(b_t))^{\gamma_t} + \bigotimes_{t=1}^{n} (1 - \mathbb{N}(b_t))^{\gamma_t} \right), \\
\end{array} \right. \]
\[ = \left\{ \begin{array}{l}
\left( \bigotimes_{t=1}^{n} (1 + \mathbb{N}(b_t))^{\gamma_t} - \bigotimes_{t=1}^{n} (1 - \mathbb{N}(b_t))^{\gamma_t} \right) / \left( \bigotimes_{t=1}^{n} (1 + \overline{\mathbb{R}}(b_t))^{\gamma_t} + \bigotimes_{t=1}^{n} (1 - \overline{\mathbb{R}}(b_t))^{\gamma_t} \right), \\
\end{array} \right. \]
\[ = \left\{ \begin{array}{l}
\left( \bigotimes_{t=1}^{n} (1 + \overline{\mathbb{R}}(b_t))^{\gamma_t} - \bigotimes_{t=1}^{n} (1 - \overline{\mathbb{R}}(b_t))^{\gamma_t} \right) / \left( \bigotimes_{t=1}^{n} (1 + \overline{\mathbb{R}}(b_t))^{\gamma_t} + \bigotimes_{t=1}^{n} (1 - \overline{\mathbb{R}}(b_t))^{\gamma_t} \right), \\
\end{array} \right. \]
\[ \text{for all } t, \text{ and } \mathbb{N}(b_t) = \overline{\mathbb{R}}(b_t) = (\overline{\mathbb{R}}(b_t), \overline{\mathbb{R}}(b_t)), \]
Hence,
\[ (N(b_1), N(b_2), \ldots, N(b_n)) = \mathcal{R}(b). \]

(2) Boundedness:
\[
(N(b))^* = \begin{cases} 
\sup_t \left\{ \frac{\partial h_t}{\partial h_t}, \max_t \left\{ \frac{v_t}{\partial h_t} \right\} \right\}, \\
\inf_t \left\{ \frac{\partial h_t}{\partial h_t}, \min_t \left\{ \frac{v_t}{\partial h_t} \right\} \right\}, \\
\sup_t \left\{ \frac{\partial h_t}{\partial h_t}, \max_t \left\{ \frac{v_t}{\partial h_t} \right\} \right\}, \\
\inf_t \left\{ \frac{\partial h_t}{\partial h_t}, \min_t \left\{ \frac{v_t}{\partial h_t} \right\} \right\},
\end{cases}
\]
and \(N(b) = [(\xi / \partial_x, \eta / \partial_x), (\beta_t / \partial_x, \gamma_t / \partial_x)]\) to prove that
\[
(N (b))^* \leq q - ROPHFREW(N (b_1), N (b_2), \ldots, N (b_n)) 
\leq (N (b))^*.
\]

Let \(g(x) = \sqrt{2 - x^2/x^2}, x \in (0, 1]\); then,
g\((x) = -2/x^4(2 - x^3/x^3)^2 < 0.\) So, \(g(x)\) is a decreasing function on \((0, 1].\) Since
\[
\left\{ \frac{\partial h_{max}}{h_{max}} \right\} \leq \left\{ \frac{\partial h_b}{h_b} \right\} \leq \left\{ \frac{\partial h_{min}}{h_{min}} \right\}
\]
for all \(t,\) let \(g(\partial h_{max}) \leq g(\partial h_b) \leq g(\partial h_{min}) (t = 1, 2, 3, \ldots, n),\) i.e.,
\[
\sqrt{\frac{2 - (\partial h_{max})^3}{(\partial h_{max})^3}} \leq \sqrt{\frac{2 - (\partial h_b)^3}{(\partial h_b)^3}} \leq \sqrt{\frac{2 - (\partial h_{min})^3}{(\partial h_{min})^3}}.
\]
and let \(y = (y_1, y_2, \ldots, y_n)^T\) be the weight vector such that \(y_i \in [0,1]\) and \(\theta_{t,i}^n y = 1\) and \(h_t\) be the probabilistic term such that \(\theta_{t,i}^n h_t = 1.\) We have

\[
\begin{align*}
\ell &\equiv \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{max}}{h_{max}} \right)^3 \right) y_t^n \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_b}{h_b} \right)^3 \right) y_t^n \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{min}}{h_{min}} \right)^3 \right) y_t^n, \\
\ell &\leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{max}}{h_{max}} \right)^3 \right) \theta_{t,i}^n y_t^n \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_b}{h_b} \right)^3 \right) \theta_{t,i}^n y_t^n \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{min}}{h_{min}} \right)^3 \right) \theta_{t,i}^n y_t^n.
\end{align*}
\]

\[
\begin{align*}
\ell &\leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{max}}{h_{max}} \right)^3 \right) \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_b}{h_b} \right)^3 \right) \leq \frac{1}{n} \sum_{t=1}^{n} \left( 2 - \left( \frac{\partial h_{min}}{h_{min}} \right)^3 \right).\end{align*}
\]
Similarly, we can show that
\[
\frac{\partial \mu^m}{\partial h_{\max}} \leq \left( \frac{1}{n} \sum_{t=1}^{n} \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \right) \leq \frac{\partial \mu^m}{\partial h_{\max}} \leq \left( \frac{1}{n} \sum_{t=1}^{n} \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \right)
\] (71)

Again, let \( f(y) = \sqrt{1 - y^2} / 1 + y^n, y \in [0, 1] \). Then, \( f(y) = -2y / (1 + y)^3 \sqrt{(1 - y^2) / (1 + y^3)^2} < 0 \). Thus, \( f(y) \) is a decreasing function over \([0, 1]\). Since \( \{ h_{\max} \} \leq \{ h_t \} \leq \{ h_{\max} \} \) for all \( t \), \( g(h_{\max}) \leq g(h_t) \leq g(h_{\max})(t = 1, 2, 3, \ldots, n) \), i.e.,

\[
\left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \leq \left( \frac{1}{n} \sum_{t=1}^{n} \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \right) \leq \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}}
\] (72)

and let \( y = (y_1, y_2, \ldots, y_n)^T \) be the weight vector such that \( y_t \in [0, 1] \) and \( \sum_{t=1}^{n} y_t = 1 \) and \( \bar{h}_t \) be the probabilistic term such that \( \sum_{t=1}^{n} \bar{h}_t = 1 \); we have

\[
\left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \leq \left( \frac{1}{n} \sum_{t=1}^{n} \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \right) \leq \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}}
\] (73)

In a similar way, we can show that

\[
\left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \leq \left( \frac{1}{n} \sum_{t=1}^{n} \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}} \right) \leq \left( 1 - \left( \frac{h_{\max}}{h_t} \right)^3 / \left( \frac{h_{\max}}{\bar{h}_t} \right)^3 \right)^{\frac{3}{1}}
\] (74)
where
\[
\Phi_n \triangleq 3 \Theta_{i=1}^n (2 - (y_i h)^3)^{y_i} / (y_i h)^3, \quad (75)
\]
\[
\leq y_{h_{\max}} / y_{h_{\min}}.
\]

Thus, from equations (70), (71), (74), and (75), we have
\[
(N(b))^- \leq q - ROPHFREW (N(b_1), N(b_2), \ldots, N(b_n)) \leq (N(b))^+.
\]

(3) Monotonicity: the proof is similar to the proof of (2).

\[
M = \left[ N(b_{ij}) \right]_{mn}
\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]

where
\[
N(b) = \left\{ \hat{g} \in \Omega \mid y_{h_{(0)}} / y_{h_{(0)}}, \psi_{h_{(0)}} (\hat{g}) \right\},
\]
\[
N(b_{ij}) = \left\{ \hat{g} \in \Omega \mid y_{h_{(0)}} / y_{h_{(0)}}, \psi_{h_{(0)}} (\hat{g}) \right\},
\]
\[
(\hat{g})^q\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]
\[
= \left[ (N(b_{11}), N(b_{12}), \ldots, N(b_{1n})) (N(b_{21}), N(b_{22}), \ldots, N(b_{2n})) \ldots (N(b_{m1}), N(b_{m2}), \ldots, N(b_{mn})) \right]
\]

such that
\[
0 \leq \left( \max (\beta_{h_{(0)}} (\hat{g})) \right)^q + \left( \min (\psi_{h_{(0)}} (\hat{g})) \right)^q \leq 1,
\]

are the q-ROPHFR values. The main steps for MAGDM are as follows.

Construct the experts’ evaluation matrices as

\[
(\hat{g})^q\]

where \( \hat{j} \) shows the number of experts.

7. Multiattribute Decision-Making Methodology

Herein, we develop an algorithm for addressing uncertainty in MAGDM under q-ROHFR information. Consider a DM problem with a set \( \{ A_1, A_2, \ldots, A_n \} \) of \( n \) alternatives and a set of \( n \) attributes \( \{ X_1, X_2, \ldots, X_n \} \) with \( (y_1, y_2, \ldots, y_n)^T \) being the weight vector; that is, \( y_i \neq 0,1 \). Also, \( \delta_{h_i} \) and \( \partial_{h_i} \) are probabilistic terms such that \( \Phi^k = 1 \) and \( \Phi^k = 1 \) with the property that \( 0 \leq \delta_{h_i} \) and \( \partial_{h_i} \leq 1 \). To test the reliability of \( k \)th alternative \( A_k \) under the attribute \( c_i \), let \( \{ D_1, D_2, \ldots, D_n \} \) be a set of decision makers (DMs). The expert evaluation matrix is described as
Evaluate the normalized experts’ matrices $(\mathbf{N})^{\hat{\gamma}}$ as

$$(\mathbf{N})^{\hat{\gamma}} = \begin{cases} (\mathbf{N}(b_{ij}) = (\mathbf{N}(b_{ij}), \mathbf{N}(b_{ij})) & \text{if for the benefit type,} \\ (\mathbf{N}(b_{ij}))^{c} = ((\mathbf{N}(b_{ij}))^{c}, (\mathbf{N}(b_{ij}))^{c}) & \text{if for the cost type.} \end{cases}$$

(81)

The weight information of the attributes is determined by using the Shannon entropy measure in the following way. The entropy measure corresponding to each attribute is

$$\text{EN}(N_j) = \text{EN}(N_{j1}, N_{j2}, N_{j3}, \ldots, N_{jm})$$

$$= \frac{-1}{\ln(n)} \sum_{i=1}^{n} \left( h_{ji} \ln(h_{ji}) \times \delta_{h_{ji}} + h_{ji} \ln(h_{ji}) \times \delta_{h_{ji}} + y_{h_{ji}} \ln(y_{h_{ji}}) \times \delta_{h_{ji}} + y_{h_{ji}} \ln(y_{h_{ji}}) \times \delta_{h_{ji}} \right), \quad j = 1, 2, 3, \ldots, m.$$  

(82)

Then,

$$\gamma(N_j) = \frac{1 - \text{EN}(N_j)}{\sum_{j=1}^{m} 1 - \text{EN}(N_j)}.$$  

(83)

Thus, weights of attributes are found as

$$\gamma(N_j) = (\gamma(N_1), \gamma(N_2), \ldots, \gamma(N_m))^T.$$  

(84)

Compute the $q$-ROPHFRVs for each considered alternative with respect to the given list of criteria/attributes by utilizing the proposed aggregation information. Find the ranking of alternatives based on the score function as

$$G_{q}(N(\mathbf{b})) = \frac{1}{4} \left( 2 + \frac{1}{M_{\mathbf{a}}} \sum \limits_{\beta_{\mathbf{a}}, \mathbf{b} \in \mathcal{P}(\mathbf{a})} \left( \omega_{\mathbf{a}} \times \delta_{\mathbf{a}} \right) + \frac{1}{N_{\mathbf{a}}} \sum \limits_{\beta_{\mathbf{a}}, \mathbf{b} \in \mathcal{P}(\mathbf{a})} \left( \omega_{\mathbf{a}} \times \delta_{\mathbf{a}} \right) \frac{1}{M_{\mathbf{a}}} \sum \limits_{\beta_{\mathbf{a}}, \mathbf{b} \in \mathcal{P}(\mathbf{a})} \left( \omega_{\mathbf{a}} \times \delta_{\mathbf{a}} \right) \right).$$

(85)

Rank all the alternative scores in the descending order. The alternative having a larger value will be superior/best.

The algorithm steps/flowchart of the decision-making technique are shown in Figure 3.

8. Numerical Example

To strengthen our developed operators, we consider a numerical MCGDM example of drug selection for the treatment of COVID-19.

8.1. Case Study (Drug Selection for the Treatment of COVID-19). Nowadays, an overwhelming majority of the world is fighting against an epidemic called coronavirus. Coronavirus is a new virus that has recently been identified in humans and is officially named COVID-19. Corona corresponds to the virus’s external surface, which has crown-like spikes [61]. Common symptoms of infection are fever, cough, fatigue, shortness of breath, and breathing difficulties [12, 62–65]. Regularly washing hands and covering the nose and mouth while coughing or sneezing are standard suggestions for preventing infection spread. The COVID-19 virus is spread mostly by mouth droplets or nasal discharge when the infected individual coughs or sneezes. Avoid close contact with anyone who is coughing or sneezing and has respiratory symptoms. The moderate symptoms of COVID-19 infections are likely to be prevented by several known antiviral medications [66]. In the case of antiviral medications, up to now, there are no specific medicines developed for the disease. However, different medicines are used for experimental purposes to benefit COVID-19 patients, and laboratory testing indicates that any combination of drugs...
could be effective against COVID-19. The combination of lopinavir/ritonavir and interferon-beta (LPV/RTV-IFNb) reduced viral masses slightly without impacting other clinical factors. Remdesivir (GS-5734), a nucleotide analog prodrug, was earlier tested for SARS, MERS, and Ebola [67]. Remdesivir has been demonstrated to be safe and beneficial for patients with mild COVID-19 symptoms, according to an experimental investigation [68]. Hydroxychloroquine (HCQ) and chloroquine (CQ) are widely used antimalarial drugs that stimulate immunomodulatory responses and also used to avoid autoimmune disorders. Wang et al. [69] testified that HCQ was found to be more stimulating than CQ in vitro. The potential effectiveness of these drugs in regulating cytokine discharge syndrome in patients has been investigated from the global pandemic of COVID-19. Even though there is no effective treatment for COVID-19, all antiviral medicines should be investigated further in clinical testing. According to a WHO report released on June 13, 2021, more than 176,396,104 cases of COVID-19 have been reported worldwide, resulting in more than 3,810,989 deaths. A total of 160,398,032 people have been recovered [2]. The most common symptoms and signs reported by COVID-19 patients are fever (83%–99%), shortness of breath (31%–40%), fatigue (44%–70%), anorexia (40%–84%), cough (59%–82%), sputum production (28%–33%), and myalgia (11%–35%) [70–74].

Here, we proposed four medicines as alternatives for the treatment of COVID-19 patients, namely, LPV/RTV-IFNb ($A_1$), remdesivir ($A_2$), LPV/RTV ($A_3$), and favipiravir ($A_4$). Antiviral medications should be selected not only for their effect on symptoms but also for their effectiveness and possible side effects. Therefore, we take four parameters, cough ($x_1$), fatigue ($x_2$), fever ($x_3$), and shortness of breath ($x_4$). For selection of optimal medicine, information is presented as $q$-ROPHFR information. The corresponding weight vector for criteria is $\gamma = (0.13, 0.27, 0.29, 0.31)^T$. The following computations are performed to address the MCDM problem using the established methodology for evaluating alternatives.

The information of the professional expert is given in Tables 1 and 2 in the form of $q$-ROPHFRS.

In this problem, only one expert is considered for collection of uncertain information. So, we do not need to find the collected information.

Aggregation information of the alternative under the given list of attributes is evaluated using proposed aggregation operators which are as follows.

**Case 1.** Aggregation information using the EWA operator is shown in Table 3.

**Case 2.** Aggregation information using the $q$-ROHFREWG operator is presented in Table 4.
### Table 1: Expert information.

<table>
<thead>
<tr>
<th></th>
<th>$x_1$</th>
<th>$x_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$((0.1/0.3, 0.2/0.5, 0.5/0.2), (0.3/0.6, 0.4/0.4))$</td>
<td>$((0.5/0.4, 0.7/0.6), (0.5/0.7, 0.6/0.3))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.8/1) (0.4/0.5, 0.6/0.5))$</td>
<td>, $(0.4/0.5, 0.6/0.5) (0.7/0.3, 0.9/0.7))$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$((0.6/0.7, 0.7/0.3), (0.7/0.5, 0.9/0.5))$</td>
<td>$((0.2/0.2, 0.4/0.1), (0.5/0.7) (0.5/1.0))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.3/0.2, 0.5/0.8) (0.6/1))$</td>
<td>, $(0.6/0.3, 0.7/0.7) (0.3/1))$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$((0.4/0.3, 0.5/0.6, 0.6/0.1), (0.6/0.1, 0.7/0.9))$</td>
<td>$((0.1/1.0) (0.5/0.5, 0.6/0.5))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.9/1) (0.5/1))$</td>
<td>, $(0.4/0.3, 0.6/0.4, 0.7/0.3) (0.5/0.2, 0.7/0.8))$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$((0.4/1) (0.5/0.5, 0.6/0.5))$</td>
<td>$((0.4/0.4, 0.5/0.6) (0.4/1))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.3/0.7, 0.4/0.3) (0.8/1))$</td>
<td>, $(0.1/0.6, 0.2/0.4) (0.2/0.2, 0.3/0.8))$</td>
</tr>
</tbody>
</table>

### Table 2: Expert information.

<table>
<thead>
<tr>
<th></th>
<th>$x_3$</th>
<th>$x_4$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$((0.4/1), (0.3/0.2, 0.7/0.8))$, $(0.5/1), (0.9/1))$</td>
<td>$((0.6/1), (0.7/1)), (0.6/0.4, 0.8/0.2, 0.9/0.4), (0.7/0.7, 0.9/0.3))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.5/1, (0.9/1))$</td>
<td>, $(0.6/0.4, 0.8/0.2, 0.9/0.4), (0.7/0.7, 0.9/0.3)$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$((0.8/1), (0.4/0.6, 0.5/0.2, 0.7/0.2))$, $(0.2/0.6, 0.5/0.4), (0.4/0.3, 0.5/0.7))$</td>
<td>$((0.8/1), (0.5/1))$, $(0.7/1.0), (0.1/0.5, 0.3/0.3, 0.4/0.2))$</td>
</tr>
<tr>
<td></td>
<td>, $(0.3/1), (0.7/0.6, 0.8/0.4)$, $(0.7/0.4, 0.7/0.6, 0.8/0.4)$</td>
<td>, $(0.3/0.2, 0.6/0.8), (0.8/1))$, $(0.7/1), (0.3/1))$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$((0.3/1), (0.7/0.7, 0.8/0.3))$, $(0.7/1), (0.6/1))$</td>
<td>$((0.6/0.2, 0.7/0.4, 0.9/0.4), (0.3/0.3, 0.4/0.7)$, $(0.2/0.2, 0.7/0.8), (0.7/0.4, 0.8/0.2, 0.9/0.4))$</td>
</tr>
</tbody>
</table>

### Table 3: Aggregated information using $q$-ROPHREWA.

<table>
<thead>
<tr>
<th></th>
<th>$x_1$</th>
<th>$x_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$[0.4934/0.12, 0.5659/0.18, 0.4946/0.2, 0.5668/0.3, 0.5143/0.08, 0.5817/0.12], 0.4529/0.084, 0.5784/0.336, 0.4766/0.036, 0.6069/0.144,$</td>
<td>$[0.5932/0.12, 0.6759/0.06, 0.7406/0.12, 0.5777/0.28, 0.6647/0.14, 0.7320/0.28]), 0.7111/0.105, 0.7732/0.045, 0.7651/0.245, 0.8277/0.105,$</td>
</tr>
<tr>
<td></td>
<td>0.4697/0.056, 0.5986/0.224, 0.4941/0.024, 0.6277/0.096</td>
<td>0.7441/0.105, 0.8067/0.045, 0.7986/0.245, 0.8609/0.105</td>
</tr>
<tr>
<td></td>
<td>$[0.7074/0.14, 0.7160/0.07, 0.7252/0.49, 0.7074/0.06, 0.7160/0.03, 0.7252/0.21], [0.4913/0.03, 0.5234/0.1, 0.5787/0.1, 0.5120/0.03, 0.5452/0.1, 0.6021/0.1]$</td>
<td>$[0.5584/0.036, 0.5915/0.024, 0.5944/0.084, 0.6235/0.056, 0.5714/0.144, 0.6030/0.096, 0.6057/0.336, 0.6336/0.224$,</td>
</tr>
<tr>
<td></td>
<td>, $[0.2555/0.15, 0.3579/0.09, 0.3911/0.06, 0.2733/0.35, 0.3824/0.21, 0.4176/0.21]$</td>
<td>$[0.2916/0.6, 0.4384/0.24, 0.3201/0.12, 0.4518/0.48, 0.3556/0.02, 0.4707/0.08], 0.6584/0.03, 0.6864/0.02, 0.6890/0.03, 0.7176/0.02,$</td>
</tr>
<tr>
<td></td>
<td>, $0.6716/0.27, 0.6998/0.18, 0.7025/0.27, 0.7312/0.18</td>
<td>, $0.6968/0.18, 0.7310/0.12, 0.7211/0.24, 0.7522/0.18, 0.7408/0.12, 0.7695/0.12,$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$[0.2694/0.14, 0.4423/0.04, 0.4752/0.02, 0.2980/0.56, 0.4423/0.16, 0.5228/0.08)$</td>
<td>$[0.4659/0.08, 0.5233/0.16, 0.6769/0.16, 0.4899/0.12, 0.5424/0.24, 0.6876/0.24], [0.4475/0.105, 0.4879/0.245, 0.4689/0.045, 0.5109/0.105,$</td>
</tr>
<tr>
<td></td>
<td>, $0.4586/0.105, 0.4999/0.245, 0.4805/0.045, 0.5233/0.105</td>
<td>, $0.4784/0.084, 0.5990/0.336, 0.4811/0.056, 0.6006/0.224, 0.4852/0.036, 0.6032/0.144, 0.4879/0.024, 0.6048/0.144$,</td>
</tr>
<tr>
<td></td>
<td>, $0.4967/0.08, 0.5217/0.04, 0.5478/0.08, 0.5503/0.32, 0.5773/0.16, 0.6052/0.32$</td>
<td>, $0.4967/0.08, 0.5217/0.04, 0.5478/0.08, 0.5503/0.32, 0.5773/0.16, 0.6052/0.32$</td>
</tr>
</tbody>
</table>


Score values of all alternatives under developed AOPs are presented in Table 5.
Rank the alternatives \( A_i (t = 1, 2, \ldots, 4) \) which is enclosed in Table 6.

From the above computations, we concluded that alternative \( A_2 \) is the finest alternative among others, and therefore, it is highly recommended (Figure 4).

### 9. Reliability and Validity Test

In practice, selecting the perfect option from the group’s decision matrices is a challenging task. The approach for analyzing the reliability and validity of DM systems was developed by Wang and Garg [75]. The testing procedure is as follows:

Test step 1: if we substitute the normalized element for the worse element of the alternative by presenting the appropriate alternative with no modification and also with no altering the comparable position of each decision criterion, the appropriate and effective MAGDM technique is to do so.

Test step 2: the transitive property must be satisfied using an efficient and appropriate MAGDM approach.

Test step 3: when a MAGDM problem is reduced to a minor one, a combined alternative rating should be similar to the original rating of the undecomposed problem. To rank the alternative, we utilize the same methods adopted in the MAGDM problem on minor issues. The MAGDM problem was reduced to a smaller one in order to achieve the best result, and the same suggested DM technique has been used. The appropriate and effective MAGDM technique is that if we apply the same procedure to a small problem, the result would be the same as the MAGDM problem.

#### 9.1. Validity Test for the Proposed DM Methodology

Utilizing the competency of the aforementioned test, we check the appropriation and validation of our established approach (Tables 7 and 8). The \( q \)-ROPHFPR information is enclosed in Tables 9 and 10 as follows:

Test step 1: we substitute the worse element of the alternative by presenting the appropriate alternative with no modification and also with no altering the comparable position of each decision criterion, in this step. Table 11 encloses the updated decision matrix.

Now, we calculate the combined values of each alternative under criteria weight \((0.13, 0.27, 0.29, 0.31)^T\) using the proposed list of \( q \)-rung orthopair probabilistic hesitant fuzzy rough aggregation operators as follows:

Case I: aggregated information using \( q \)-ROPHFRWA operators is enclosed in Table 12.

Case II: aggregated information using \( q \)-ROPHFRWG operators is enclosed in Table 13.

Score values of all alternatives under developed aggregation operators are presented in Table 13.

Rank the alternatives \( A_i (t = 1, 2, \ldots, 4) \) which is enclosed in Table 14.

We get again the same alternative \( A_2 \) by using test step 1, which is also obtained by applying our proposed method.

We are now testing the validity test steps 2 and 3 to demonstrate that the proposed approach is reliable and relevant. To this end, we first transformed the MAGDM problem into three smaller subproblems such as \( \{A_2, A_1, A_4\} \), \( \{A_1, A_4, A_3\} \), and \( \{A_2, A_4, A_3\} \). We now implement our suggested decision-making approach to the smaller problems that have been transformed and give us the ranking of alternatives as \( A_2 > A_1 > A_4 \), \( A_1 > A_4 > A_3 \), and \( A_2 > A_4 > A_3 \), respectively. We analyzed that \( A_2 > A_1 > A_4 \) is the same as the standard decision-making approach results when assigning detailed ranking (Figure 5).

### 10. Comparison Analysis

#### 10.1. TOPSIS Methodology Based on \( q \)-Rung Orthopair Probabilistic Hesitant Fuzzy Rough Information

Hwang and Yoon proposed the TOPSIS technique for the ideal solution, which allows policymakers to compare the PIS and NIS. TOPSIS is based on the assumption that the best alternative would be the closest to the ideal and the furthest away from the perfect negative solution [76, 77]. The main parts of the method are as follows.

Let \( b = \{A_1, A_2, A_3, \ldots, A_n\} \) be the set of alternatives and \( C = \{X_1, X_2, X_3, \ldots, X_n\} \) be a set of criteria. The decision matrix of the expert is presented as

\[
M = \left[ \begin{array}{ccc}
N(\text{\( b_{i1}^j \))} & N(\text{\( b_{i2}^j \))} & \cdots & N(\text{\( b_{in}^j \))} \\
(\text{\( b_{11}^j \))} & N(\text{\( b_{12}^j \))} & \cdots & N(\text{\( b_{1n}^j \))} \\
(\text{\( b_{21}^j \))} & N(\text{\( b_{22}^j \))} & \cdots & N(\text{\( b_{2n}^j \))} \\
\vdots & \vdots & \ddots & \vdots \\
(\text{\( b_{i1}^j \))} & N(\text{\( b_{i2}^j \))} & \cdots & N(\text{\( b_{in}^j \))}
\end{array} \right] \quad (85)
\]
### Table 4: Aggregated information using $q$-ROPHFREWG.

<table>
<thead>
<tr>
<th>Operators</th>
<th>$G_0 (A_1)$</th>
<th>$G_0 (A_2)$</th>
<th>$G_0 (A_3)$</th>
<th>$G_0 (A_4)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>0.4061/0.12, 0.4479/0.18, 0.4429/0.2, 0.4880/0.3, 0.4971/0.08, 0.5465/0.12</td>
<td>0.5370/0.084, 0.6272/0.336, 0.5640/0.036, 0.6466/0.144, 0.5424/0.056, 0.6310/0.224, 0.5689/0.024, 0.6502/0.096</td>
<td>0.5653/0.12, 0.6226/0.06, 0.6519/0.12, 0.5335/0.28, 0.5887/0.14, 0.6170/0.28, 0.7662/0.105, 0.8334/0.045, 0.8260/0.245, 0.8759/0.105, 0.7751/0.105, 0.8397/0.045, 0.8326/0.245, 0.8806/0.105</td>
<td>0.5492/0.14, 0.6505/0.07, 0.6864/0.49, 0.5492/0.06, 0.6505/0.03, 0.6864/0.21, 0.5156/0.03, 0.5366/0.1, 0.6031/0.1, 0.5933/0.3, 0.6909/0.1, 0.6608/0.1</td>
</tr>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>0.4256/0.036, 0.5497/0.024, 0.4458/0.084, 0.5744/0.056, 0.4545/0.144, 0.5851/0.096, 0.4759/0.336, 0.6108/0.224</td>
<td>0.3795/0.15, 0.3973/0.09, 0.4201/0.06, 0.4169/0.35, 0.4317/0.21, 0.4512/0.21</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Table 5: Score values.

<table>
<thead>
<tr>
<th>Operators</th>
<th>$G_0 (A_1)$</th>
<th>$G_0 (A_2)$</th>
<th>$G_0 (A_3)$</th>
<th>$G_0 (A_4)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>0.5078</td>
<td>0.5176</td>
<td>0.5173</td>
<td>0.5044</td>
</tr>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>0.4989</td>
<td>0.5066</td>
<td>0.5018</td>
<td>0.4867</td>
</tr>
</tbody>
</table>

### Table 6: Ranking of the alternatives.

<table>
<thead>
<tr>
<th>Operators</th>
<th>Score</th>
<th>Best alternative</th>
</tr>
</thead>
<tbody>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>$G_0 (A_2) &gt; G_0 (A_3) &gt; G_0 (A_4) &gt; G_0 (A_1)$</td>
<td>$A_2$</td>
</tr>
<tr>
<td>$q$-ROPHFREWGA</td>
<td>$G_0 (A_2) &gt; G_0 (A_3) &gt; G_0 (A_4) &gt; G_0 (A_1)$</td>
<td>$A_2$</td>
</tr>
</tbody>
</table>

Figure 4: Alternatives using EWA and EWG operators.
Table 7: Expert information.

<table>
<thead>
<tr>
<th></th>
<th>$X_1$</th>
<th>$X_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$\begin{pmatrix} ((0.1/0.3, 0.2/0.5, 0.5/0.2), (0.3/0.6, 0.4/0.4)), \ ((0.8/1), (0.4/0.5, 0.6/0.5)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.5/0.4, 0.7/0.6), (0.5/0.7, 0.6/0.3)), \ ((0.4/0.3, 0.5/0.7), (0.7/0.3, 0.9/0.7)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$\begin{pmatrix} ((0.6/0.7, 0.7/0.3), (0.7/0.5, 0.9/0.5)), \ ((0.3/0.2, 0.5/0.8), (0.6/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.2/0.2, 0.4/0.1, 0.5/0.7), (0.5/1)), \ ((0.6/0.3, 0.7/0.7), (0.3/1)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$\begin{pmatrix} ((0.4/0.3, 0.5/0.6, 0.6/0.1), (0.6/0.1, 0.7/0.9)), \ ((0.9/1), (0.5/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.1/1.0), (0.5/0.5, 0.6/0.5)), \ ((0.4/0.3, 0.6/0.4, 0.7/0.3), (0.5/0.2, 0.7/0.8)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\begin{pmatrix} ((0.4/1), (0.5/0.5, 0.6/0.5)), \ ((0.3/0.7, 0.4/0.3), (0.8/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.4/0.4, 0.5/0.6), (0.4/1)), \ ((0.1/0.6, 0.2/0.4), (0.2/0.2, 0.3/0.8)) \end{pmatrix}$</td>
</tr>
</tbody>
</table>

Table 8: Expert information.

<table>
<thead>
<tr>
<th></th>
<th>$X_3$</th>
<th>$X_4$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$\begin{pmatrix} ((0.4/1), (0.3/0.2, 0.7/0.8)), \ ((0.5/1), (0.9/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.6/1), (0.7/1)), \ ((0.6/0.4, 0.8/0.2, 0.9/0.4), (0.7/0.7, 0.9/0.3)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$\begin{pmatrix} ((0.8/1), (0.4/0.6, 0.5/0.2, 0.7/0.2)), \ ((0.2/0.6, 0.5/0.4), (0.4/0.3, 0.5/0.7)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.8/1), (0.5/1)), \ ((0.7/1.0, 0.1/0.5, 0.3/0.3, 0.4/0.2) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$\begin{pmatrix} ((0.3/1), (0.7/0.6, 0.8/0.4)), \ ((0.7/0.6, 0.8/0.4), (0.1/0.7, 0.4/0.2, 0.7/0.1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.3/0.2, 0.6/0.8), (0.8/1)), \ ((0.7/1), (0.3/1)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\begin{pmatrix} ((0.3/1), (0.7/0.7, 0.8/0.3)), \ ((0.7/1), (0.6/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.6/0.2, 0.7/0.4, 0.9/0.4), (0.3/0.3, 0.4/0.7)), \ ((0.2/0.2, 0.7/0.8), (0.7/0.4, 0.8/0.2, 0.9/0.4)) \end{pmatrix}$</td>
</tr>
</tbody>
</table>

Table 9: Updated expert information.

<table>
<thead>
<tr>
<th></th>
<th>$X_1$</th>
<th>$X_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$\begin{pmatrix} ((0.1/0.3, 0.2/0.5, 0.5/0.2), (0.3/0.6, 0.4/0.4)), \ ((0.8/1), (0.4/0.5, 0.6/0.5)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.5/0.7, 0.6/0.3), \ (0.5/0.4, 0.7/0.6), (0.7/0.3, 0.9/0.7), \ (0.4/0.3, 0.5/0.7), (0.5/1.0)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$\begin{pmatrix} ((0.6/0.7, 0.7/0.3), \ (0.7/0.5, 0.9/0.5), \ (0.3/0.2, 0.5/0.8), \ (0.6/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.2/0.2, 0.4/0.1, 0.5/0.7), \ (0.3/1), \ (0.6/0.3, 0.7/0.7), \ (0.1/0.1), \ (0.5/0.5, 0.6/0.5)) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$\begin{pmatrix} ((0.4/0.3, 0.5/0.6, 0.6/0.1), \ (0.5/1), \ (0.9/1)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.4/0.3, 0.6/0.4, 0.7/0.3), \ (0.5/0.2, 0.7/0.8) \end{pmatrix}$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\begin{pmatrix} ((0.5/0.5, 0.6/0.5), \ (0.4/1), \ (0.8/1), \ (0.3/0.7, 0.4/0.3)) \end{pmatrix}$</td>
<td>$\begin{pmatrix} ((0.4/0.4, 0.5/0.6), \ (0.4/1), \ (0.1/0.6, 0.2/0.4), \ (0.2/0.2, 0.3/0.8) \end{pmatrix}$</td>
</tr>
</tbody>
</table>
### Table 10: Updated expert information.

<table>
<thead>
<tr>
<th></th>
<th>$\lambda_3$</th>
<th>$\lambda_4$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$\left( \begin{array}{c} (0.4/1), \ (0.3/0.2, 0.7/0.8) \ (0.5/1), \ (0.9/1) \ (0.8/1), \ (0.4/0.6, 0.5/0.2, 0.7/0.2) \end{array} \right)$</td>
<td>$\left( \begin{array}{c} (0.7/1), \ (0.6/1) \ (0.7/0.7, 0.9/0.3), \ (0.6/0.4, 0.8/0.2, 0.9/0.4) \ (0.5/1), \ (0.8/1) \end{array} \right)$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$\left( \begin{array}{c} (0.2/0.6, 0.5/0.4), \ (0.4/0.3, 0.5/0.7) \ (0.7/0.6, 0.8/0.4), \ (0.3/1) \ (0.7/0.6, 0.8/0.4) \end{array} \right)$</td>
<td>$\left( \begin{array}{c} (0.1/0.5, 0.3/0.3, 0.4/0.2), \ (0.7/1.0) \ (0.3/0.2, 0.6/0.8), \ (0.8/1) \ (0.3/1) \end{array} \right)$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$\left( \begin{array}{c} (0.1/0.7, 0.4/0.2, 0.7/0.1), \ (0.7/0.6, 0.8/0.4) \end{array} \right)$</td>
<td>$\left( \begin{array}{c} (0.6/0.2, 0.7/0.4, 0.9/0.4), \ (0.3/0.3, 0.4/0.7), \ (0.2/0.2, 0.7/0.8), \ (0.7/0.4, 0.8/0.2, 0.9/0.4) \end{array} \right)$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\left( \begin{array}{c} (0.7/0.7, 0.8/0.3), \ (0.3/1) \ (0.6/1), \ (0.7/1) \end{array} \right)$</td>
<td>$\left( \begin{array}{c} {} \ {} \ {} \ {} \end{array} \right)$</td>
</tr>
</tbody>
</table>

### Table 11: Updated aggregated information using q-ROPHREWA.

<table>
<thead>
<tr>
<th></th>
<th>$\lambda_3$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_1$</td>
<td>$\left( \begin{array}{c} [0.5452/0.21, 0.5714/0.09, 0.5462/0.35, 0.5723/0.15, 0.5623/0.14, 0.5869/0.06], \ 0.4295/0.048, 0.5499/0.192, 0.4734/0.072, 0.6030/0.288, \ 0.4455/0.032, 0.5694/0.128, 0.4908/0.048, 0.6238/0.192 \ {0.6746/0.21, 0.7704/0.09, 0.7600/0.49, 0.8297/0.21, \ 0.6219/0.06, 0.6824/0.03, 0.7130/0.06, 0.5879/0.14, 0.6467/0.07, 0.6765/0.14, \ 0.6531/0.06, 0.7150/0.03, 0.6765/0.06, 0.6181/0.14, 0.6785/0.07, 0.7090/0.14 \ [0.6377/0.7, 0.6377/0.3], \ 0.4540/0.03, 0.4842/0.02, 0.5363/0.02, 0.5425/0.03, 0.5771/0.01, \ 0.6361/0.01, 0.5747/0.21, 0.6106/0.07, 0.6716/0.07, 0.4735/0.06, \ 0.5047/0.02, 0.5585/0.02, 0.5648/0.03, 0.6004/0.01, \ 0.6608/0.01, 0.5979/0.21, 0.6348/0.21, 0.6969/0.07 \ 0.2377/0.06, 0.2780/0.036, 0.3207/0.024, 0.3622/0.04, 0.3816/0.024, 0.4062/0.016, \ 0.2972/0.24, 0.3249/0.144, 0.3577/0.096, 0.3921/0.16, 0.4088/0.096, 0.4305/0.064, \ {0.5633/0.09, 0.5988/0.21, 0.5884/0.21, 0.6249/0.49 } \end{array} \right)$</td>
</tr>
<tr>
<td>$A_2$</td>
<td>$\left( \begin{array}{c} [0.5191/0.012, 0.5827/0.048, 0.3833/0.008, 0.6342/0.032, \ 0.5400/0.108, 0.5991/0.432, 0.5997/0.072, 0.6477/0.08, \ 0.4935/0.15, 0.5189/0.15, 0.5078/0.3, 0.5338/0.03, 0.5202/0.05, 0.5466/0.05 } \end{array} \right)$</td>
</tr>
<tr>
<td>$A_3$</td>
<td>$\left( \begin{array}{c} [0.5238/0.3, 0.5447/0.06, 0.6242/0.03, 0.5694/0.28, 0.5869/0.08, \ 0.6559/0.04, 0.6040/0.21, 0.6194/0.06, 0.6812/0.03 \ [0.5186/0.12, 0.5427/0.08, 0.5696/0.48, 0.5954/0.32] \end{array} \right)$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\left( \begin{array}{c} [0.5872/0.028, 0.6242/0.056, 0.7373/0.056, 0.6379/0.012, 0.6687/0.024, \ 0.7664/0.024, 0.6022/0.042, 0.6372/0.084, 0.4757/0.084, 0.8503/0.018, \ 0.6797/0.036, 0.7738/0.036, 0.5983/0.028, 0.6338/0.056, 0.7435/0.056, \ 0.6471/0.012, 0.6768/0.024, 0.7718/0.024, 0.6127/0.042, \ 0.6464/0.084, 0.7517/0.084, 0.6590/0.018, 0.6876/0.036, 0.7790/0.036 \ [0.3368/0.3, 0.3682/0.7] \end{array} \right)$</td>
</tr>
<tr>
<td>$A_4$</td>
<td>$\left( \begin{array}{c} [0.5180/0.12, 0.6243/0.48, 0.5203/0.08, 0.6258/0.32], \ 0.4571/0.056, 0.4805/0.028, 0.5049/0.056, 0.5073/0.024, \ 0.5327/0.112, 0.5592/0.224, 0.4740/0.024, \ 0.4981/0.012, 0.5232/0.024, 0.5257/0.024, 0.5517/0.048, 0.5789/0.096 \end{array} \right)$</td>
</tr>
</tbody>
</table>
where \( \overline{\mathbf{n}}(b_{ij}) = \left\{ \hat{\beta}_{\delta_{b_{ij}}}(\hat{g}), \check{\delta}_{\delta_{b_{ij}}}(\check{g}) \right\} \) \(\delta_{b_{ij}} \in \Omega\) and
\( \overline{\mathbf{n}}(b) = \left\{ \hat{\beta}_{\delta_{b}}(\hat{g}), \check{\delta}_{\delta_{b}}(\check{g}) \right\} \) \(\delta_{b} \in \Omega\).

Secondly, normalize the data defined by DMs since the decision matrix may have some benefit and cost criteria all

Table 12: Updated aggregated information using \(q\)-ROPHFREWG.

<table>
<thead>
<tr>
<th>Operators</th>
<th>(G_{\odot}(A_1))</th>
<th>(G_{\odot}(A_2))</th>
<th>(G_{\odot}(A_3))</th>
<th>(G_{\odot}(A_4))</th>
</tr>
</thead>
<tbody>
<tr>
<td>(q)-ROPHFREWA (test)</td>
<td>0.5392</td>
<td>0.5392</td>
<td>0.4852</td>
<td>0.4898</td>
</tr>
<tr>
<td>(q)-ROPHFREWG (test)</td>
<td>0.5291</td>
<td>0.5299</td>
<td>0.4633</td>
<td>0.4739</td>
</tr>
</tbody>
</table>

Table 13: Score values.

<table>
<thead>
<tr>
<th>Operators</th>
<th>(G_{\odot}(A_1))</th>
<th>(G_{\odot}(A_2))</th>
<th>(G_{\odot}(A_3))</th>
<th>(G_{\odot}(A_4))</th>
</tr>
</thead>
<tbody>
<tr>
<td>(q)-ROPHFREWA (test)</td>
<td>0.5392</td>
<td>0.5392</td>
<td>0.4852</td>
<td>0.4898</td>
</tr>
<tr>
<td>(q)-ROPHFREWG (test)</td>
<td>0.5291</td>
<td>0.5299</td>
<td>0.4633</td>
<td>0.4739</td>
</tr>
</tbody>
</table>

Table 14: Ranking of the alternatives.

<table>
<thead>
<tr>
<th>Operators</th>
<th>Score</th>
<th>Best alternative</th>
</tr>
</thead>
<tbody>
<tr>
<td>(q)-ROPHFREWA (test)</td>
<td>(G_{\odot}(A_1) &gt; G_{\odot}(A_2) &gt; G_{\odot}(A_3) &gt; G_{\odot}(A_4))</td>
<td>(A_1)</td>
</tr>
<tr>
<td>(q)-ROPHFREWG (test)</td>
<td>(G_{\odot}(A_1) &gt; G_{\odot}(A_2) &gt; G_{\odot}(A_3) &gt; G_{\odot}(A_4))</td>
<td>(A_2)</td>
</tr>
</tbody>
</table>

ROHF rough values. Also, \(\delta_{b_i} \in [0, 1]\), \(\Phi_{\nu} \delta_{b_i} = 1\), and \(\check{\delta}_{b_i} \in [0, 1]\), \(\Phi^\nu \check{\delta}_{b_i} = 1\).
together, as shown in Equation (86), where $\hat{J}$ represents the number of experts.

Evaluate the normalized experts’ matrices $(N)^{\hat{J}}$ as

\[
(N)^{\hat{J}} = \begin{cases} 
\mathcal{N}(b_{ij}) = \left(\mathcal{N}(b_{i1}), \mathcal{N}(b_{i2})\right) & \text{if for benefit,} \\
\left(\mathcal{N}(b_{i1})^\prime, \mathcal{N}(b_{i2})^\prime\right) & \text{if for cost.}
\end{cases}
\]

(86)

Based on the score value, we determine the PIS and the NIS. Herein, the PIS and NIS are denoted as $\Upsilon^+ = (\tau^+_{1i}, \tau^+_{2i}, \tau^+_{3i}, \ldots, \tau^+_{ni})$ and $\Upsilon^- = (\tau^-_{1i}, \tau^-_{2i}, \tau^-_{3i}, \ldots, \tau^-_{ni})$, respectively. For PIS $\Upsilon^+$, it can be computed by the formula

\[
\Upsilon^+ = (\max_{t} \text{score}(\tau^+_{1i}), \max_{t} \text{score}(\tau^+_{2i}), \max_{t} \text{score}(\tau^+_{3i}), \ldots, \max_{t} \text{score}(\tau^+_{ni})).
\]

(87)

Likewise, the NIS is calculated by the formula as follows:

\[
\Upsilon^- = (\min_{t} \text{score}(\tau^-_{1i}), \min_{t} \text{score}(\tau^-_{2i}), \min_{t} \text{score}(\tau^-_{3i}), \ldots, \min_{t} \text{score}(\tau^-_{ni})).
\]

(88)

Afterward, find the geometric distance between all the alternatives and PI $\Upsilon^+$ as follows:

\[
d(\alpha_{ij}, \Upsilon^+) = \frac{1}{8} \left( \left( \frac{1}{\# h} \sum_{s=1}^{\# h} \left( \overline{\partial}_{ij(s)} \times \hat{\partial}_{ij(s)} \right)^2 - \left( \overline{\partial}_{ij(s)} \times \hat{\partial}_{ij(s)}^\prime \right)^2 \right) + \left( \overline{\partial}_{ij(s)} \times \hat{\partial}_{ij(s)} \right)^2 - \left( \overline{\partial}_{ij(s)} \times \hat{\partial}_{ij(s)}^\prime \right)^2 \right)
\]

\[
+ \left( \frac{1}{\# \delta} \sum_{s=1}^{\# \delta} \left( \overline{\varphi}_{ij(s)} \times \hat{\varphi}_{ij(s)} \right)^2 - \left( \overline{\varphi}_{ij(s)} \times \hat{\varphi}_{ij(s)}^\prime \right)^2 \right) + \left( \overline{\varphi}_{ij(s)} \times \hat{\varphi}_{ij(s)} \right)^2 - \left( \overline{\varphi}_{ij(s)} \times \hat{\varphi}_{ij(s)}^\prime \right)^2 \right) \right).
\]

(89)
where \( t = 1, 2, 3, \ldots, n \) and \( j = 1, 2, 3, \ldots, m \). \( s \) is a positive number which represents the number of elements contained in \( q \)-ROPHFRS. Analogously, the geometric distance between all the alternatives and \( NI \; Y^- \) is as follows:

\[
d_{tj, Y^-} = \frac{1}{8} \left( \sum_{i=1}^{\#_h} \left( \bar{a}_{tj(s)} \times \bar{d}_{j(s)} \right)^2 - \left( \bar{a}_{t(s)} \times \bar{d}_{j(s)} \right)^2 \right)
\]

\[
+ \left( \sum_{i=1}^{\#_g} \left( \bar{v}_{tj(s)} \times \bar{d}_{e_{j(s)}} \right)^2 - \left( \bar{v}_{t(s)} \times \bar{d}_{e_{j(s)}} \right)^2 \right)
\]

where \( t = 1, 2, 3, \ldots, n \) and \( j = 1, 2, 3, \ldots, m \).

The relative closeness indices for all DMs of the alternatives are calculated as follows:

\[
RC_{tj} = \frac{d_{tj, Y^+}}{d_{tj, Y^-} + d_{tj, Y^+}}
\]

The ranking orders of alternatives can be determined, and the most desirable alternative having minimum distance is chosen.

### 11. Implementation of the Methodology

A numerical example relevant to “drug selection for the treatment of COVID-19 disease” is given below to validate the usefulness of our approach.

#### Table 15: Score values of expert information.

<table>
<thead>
<tr>
<th>( \chi_1 )</th>
<th>( \chi_2 )</th>
<th>( \chi_3 )</th>
<th>( \chi_4 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( A_1 )</td>
<td>0.6142</td>
<td>0.4600</td>
<td>0.4225</td>
</tr>
<tr>
<td>( A_2 )</td>
<td>0.3825</td>
<td>0.4196</td>
<td>0.6412</td>
</tr>
<tr>
<td>( A_3 )</td>
<td>0.5538</td>
<td>0.4213</td>
<td>0.5567</td>
</tr>
<tr>
<td>( A_4 )</td>
<td>0.3725</td>
<td>0.4400</td>
<td>0.5087</td>
</tr>
</tbody>
</table>

The DM information in the form of \( q \)-ROPHFRNs is given in Tables 1 and 2. PIS and NIS are computed in Table 13. Compute the distance measure of the PIS and NIS.

| \( 0.3799 \) | \( 0.2158 \) | \( 0.4174 \) | \( 0.4971 \) |
|\( 0.4038 \) | \( 0.4301 \) | \( 0.5054 \) | \( 0.2434 \) |

The relative closeness indices for all DM of the alternatives are calculated.

| \( 0.4848 \) | \( 0.3341 \) | \( 0.4523 \) | \( 0.6713 \) |

From ranking of the alternative, it could be seen that \( A_2 \) has the minimum distance (Figure 6). Hence, \( A_2 \) is the best alternative (Tables 15–17).
12.1. Limitation. A number of included studies were limited in terms of data availability and methodological quality. Therefore, the reported findings should be interpreted cautiously within that context. Furthermore, our study was limited to the articles published in English. Considering the epicenter of COVID-19, Chinese literature should be included in future systematic reviews. We will continue to monitor the literature, and this method will be updated when new evidence emerges.

### Data Availability

The data used in the manuscript are hypothetical and can be used by anyone by just citing this article.

### Conflicts of Interest

The authors declare no conflicts of interest about the publication of the research article.

### Acknowledgments

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### References


[40] Y. Wang, Z. Shan, and L. Huang, “The extension of TOPSIS method for multi-attribute decision-making with q-Rung


