

Research Article

A Two-Stage Three-Machine Flow Shop Assembly Problem Mixed with a Controllable Number and Sum-of-Processing Times-Based Learning Effect by Simulated Annealing Algorithms

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The two-stage assembly scheduling problem is widely used in industrial and service industries. This study focuses on the two-stage three-machine flow shop assembly problem mixed with a controllable number and sum-of-processing times-based learning effect, in which the job processing time is considered to be a function of the control of the truncation parameters and learning based on the sum of the processing time. However, the truncation function is very limited in the two-stage flow shop assembly scheduling settings. Thus, this study explores a two-stage three-machine flow shop assembly problem with truncated learning to minimize the makespan criterion. To solve the proposed model, we derive several dominance rules, lemmas, and lower bounds applied in the branch-and-bound method. On the other hand, three simulated annealing algorithms are proposed for finding approximate solutions. In both the small and large size number of job situations, the SA algorithm is better than the JS algorithm in this study. All the experimental results of the proposed algorithm are presented on small and large job sizes, respectively.

1. Introduction

For decades, scheduling models usually assumed that the processing time of the job is known and fixed [1]. But, in a real production system, both the efficiency of the machine and the skill of the worker can increase with the working time, thereby reducing the actual work processing time with the development of production. Many researchers indicated certain types of learning effects, such as [2] in the position-based learning effect and [3] in the time-dependent learning effect. This topic continues to attract a lot of research interest [4–6].

On the other hand, Biskup, Kuo and Yang [2, 3], and Kuolamas and Kyparisis [7] introduced models that involve a learning effect on two-machine scheduling or flow shop scheduling settings following the same or different learning ideas. There are a multitude of studies related to two-machine scheduling or flow shop scheduling settings with the learning effect consideration, including [8–11] and [12]. Besides, there are some two-stage models also with the

learning effect consideration. Wu et al. [13] adopted the learning model developed by Biskup [2] to solve a two-stage flow shop scheduling problem with three machines to minimize the makespan. They devised three simulated annealing (SA) algorithms and three cloud theory-based SA algorithms. Adopting the learning model in [3, 14], a branch-and-bound (B&B) algorithm is devised incorporating six (hybrid) particle swam optimization (PSO) methods to solve the two-stage flow shop assembly scheduling problem to minimize the total job completion time.

Most studies using the learning model are applied in the single-machine or flow shop setting. However, the two-stage assembly scheduling problem is relatively unexplored. Recently, Wu et al. and Zou et al. [15, 16] considered positionbased learning in connection with a two-stage assembly scheduling problem. They proposed different versions of simulated annealing and cloud theory-based simulated annealing to solve this problem. Moreover, Wu et al. [17] considered this problem with general learning effects. They developed and evaluated the performances of six hybrid particle swarm optimizations (PSO). Wu et al. [18] have conducted the research about a combined approach for twoagent scheduling with a sum-of-processing-times-based learning effect. To the best of our knowledge, no other research considers the two-stage assembly scheduling problem with learning effects. Table 1 presents a comparative study of existing models to solve the considered scheduling problem. Many studies claim that most of the productive items in manufacturing systems may be formulated in a two-stage assembly scheduling model. However, the literature neglects accumulated learning experience in solving a two-stage assembly scheduling problem. In fact, the sum-of-processing times-based learning model is pertinent to process manufacturing in which an initial setup is often followed by a lengthy uninterrupted production process. Motivated by this observation, this study introduces the 2-stage 3-machine assembly problem with a sum-of-processing times of already processed jobs learning to minimize the makespan criterion. This model assumes that there are two machines in the first stage and an assembly machine in the second stage. This study first provides some dominances and a lower bound applied in the branch-and-bound method for an optimal solution. Three heuristics modified from Johnson's rule with and without improving by an interchange pairwise method are, then, separately applied in three simulated annealing algorithms for finding near-optimal solutions. Finally, the statistical results of the three proposed algorithms are evaluated and reported.

2. Problem Statement

The considered two-stage assembly scheduling problem is formally described in this section. We assume a series of ngiven jobs to be processed on three machines. The main idea of the studied problem is executing n given jobs on three

TABLE 1: Small size number of jobs parameters.

Parameter	n - 10 m - 3
1 drameter	n = 10, m = 5
T_i	10 ⁻³
T_{f}	10^{-8}
c_f	0.95
Ň _r	10
β	0.2
α_1	-0.1
α_2	-0.1
α_3	-0.2

machines in two stages. Each job has strictly more than two operations. For the operations of the n job, the first stage is performed in a parallel way in two machines. The operation processing of the second stage only begins when the operations of the first stage are completed. All jobs are available at time zero. Each job j is decomposed on three tasks as follows: the ordinary processing times (without learning effect) of job j are a_j , b_j , and c_j on machines M_1 , M_2 , and M_3 , respectively. Other assumptions are no machine can process more than one job at a time; no idle time is allowed on machines M_1 and M_2 ; and once a job has begun processing, it cannot be interrupted.

Following the works of Kuo and Yang [3] and Liu et al. [19], the real processing times of J_j , if J_j scheduling on the position r of a job sequence S, are considered as $a_j \max\{\alpha, (1 + \sum_{k=1}^{r-1} a_{[k]})^{a_1}\}, b_j \max\{\alpha, (1 + \sum_{k=1}^{r-1} b_{[k]})^{a_2}\},$ and $c_j \max\{\alpha, (1 + \sum_{k=1}^{r-1} c_{[k]})^{a_3}\}$ on machines M_1, M_2 , and M_3 , respectively, where α denotes the controllable parameter with $\alpha < 0$, and a_1, a_2, a_3 denote the learning indices for M_1 , M_2 , and M_3 . For a schedule S, the finishing time of a job, say J_j , to be scheduled on the rth position (in S) on machine M_3 is defined, and denoted, as $C_{3[r]}(S)$:

$$C_{3[r]}(S) = \max\left\{t_1 + a_j \max\left\{\alpha, \left(1 + \sum_{k=1}^{r-1} a_{[k]}\right)^{a_1}\right\}, t_2 + b_j \max\left\{\alpha, \left(1 + \sum_{k=1}^{r-1} b_{[k]}\right)^{a_2}\right\}, t_3\right\} + c_j \max\left\{\alpha, \left(1 + \sum_{k=1}^{r-1} c_{[k]}\right)^{a_3}\right\},$$
(1)

where t_1 , t_2 , and t_3 are denoted as the beginning times of J_j on machines M_1 , M_2 , and M_3 in S, respectively. The optimal criterion of this study is to find a scheduled S to minimize the makespan (or $C_{3[n]}(S)$).

3. Lower Bounds and Some Lemmas

This section proposes some useful lower bounds used in a branch-and-bound method. Before deriving the lower bounds, we define some notations. Suppose t_1 , t_2 , and t_3 denote the starting time of the first job in $s_{\rm US}$ on all three machines. Then, we assume that $s_{\rm PS}$ are the partially

scheduled k jobs and s_{US} are the remaining unscheduled (n-k) jobs. $a_{(1)} \le a_{(2)} \le \cdots \le a_{(n-k)}$, $b_{(1)} \le b_{(2)} \le \cdots \le b_{(n-k)}$, and $c_{(1)} \le c_{(2)} \le \cdots \le c_{(n-k)}$ denote increasing sequences of $a_1, a_2, \ldots, a_{n-k}$; $b_1, b_2, \ldots, b_{n-k}$; and $c_1, c_2, \ldots, c_{n-k}$ in σ_{US} , respectively. Notably, a_i, b_i, c_i are not necessarily from the same job, and s_{spt1} , s_{spt2} , and s_{spt3} are three subsequences of n jobs n increasing sequences of $a_1, a_2, \ldots, a_{n-k}$; $b_1, b_2, \ldots, b_{n-k}$; and $c_1, c_2, \ldots, c_{n-k}$ in s_{US} , respectively.

Additionally, by using the ideas of Kuo and Yang [3] and Liu et al. [19], a lower bound for a subsequent can be yielded as follows:

$$C_{[k+1]}(s) = \max\left\{t_{1} + a_{[k+1]} \max\left[\alpha, \left(1 + \sum_{i=1}^{k} a_{[i]}\right)^{a_{1}}\right], t_{2} + b_{[k+1]} \max\left[\alpha, \left(1 + \sum_{i=1}^{k} b_{[i]}\right)^{a_{2}}\right], t_{3}\right\}$$

$$+ c_{[k+1]} \max\left[\alpha, \left(1 + \sum_{i=1}^{k} c_{[i]}\right)^{a_{3}}\right]$$

$$\geq t_{1} + a_{[k+1]} \frac{\alpha + \left(1 + \sum_{i=1}^{k} a_{[i]}\right)^{a_{1}}}{2} + c_{[k+1]} \frac{\alpha + \left(1 + \sum_{i=1}^{k} c_{[i]}\right)^{a_{3}}}{2}$$

$$C_{[k+2]}(s) \geq t_{1} + a_{[k+1]} \frac{\alpha + \left(1 + \sum_{i=1}^{k} a_{[i]}\right)^{a_{1}}}{2} + a_{[k+2]} \frac{\alpha + \left(1 + \sum_{i=1}^{k} a_{[i]}\right)^{a_{1}}}{2} + c_{[k+2]} \frac{\alpha + \left(1 + \sum_{i=1}^{k} c_{[i]}\right)^{a_{3}}}{2}$$

$$\vdots$$

$$(2)$$

$$C_{[k+n_1]}(s) \ge t_1 + \sum_{j=1}^{n_1} a_{[k+i]} \frac{\alpha + \left(1 + \sum_{i=1}^{k+j-1} a_{[i]}\right)^{a_1}}{2} + c_{[k+n_1]} \frac{\alpha + \left(1 + \sum_{i=1}^{k+n_1-1} c_{[i]}\right)^{a_3}}{2}$$

lower $bd_1 = t_1 + \sum_{j=1}^{n_1} a_{(n-j+1)} \frac{\alpha + \left(1 + \sum_{i=1}^{k+j-1} a_{(i)}\right)^{a_1}}{2} + c_{(1)} \frac{\alpha + \left(1 + \sum_{i=1}^{n-1} c_{(i)}\right)^{a_3}}{2}.$

In a similar way,

lower
$$bd_2 = t_2 + \sum_{j=1}^{n_1} b_{(n-j+1)} \frac{\alpha + \left(1 + \sum_{i=1}^{k+j-1} b_{(i)}\right)^{a_2}}{2}$$

+ $c_{(1)} \frac{\alpha + \left(1 + \sum_{i=1}^{n-1} c_{(i)}\right)^{a_3}}{2}$, (3)
lower $bd_3 = t_3 + \sum_{j=1}^{n_1} c_{(n-j+1)} \frac{\alpha + \left(1 + \sum_{i=1}^{k+j-1} c_{(i)}\right)^{a_3}}{2}$,

lower $bd = \max\{\text{lower } bd_1, \text{lower } bd_2\}$.

In what follows, we will propose four properties used in a branch-and-bound to improve its search power. Before deriving our properties, we first give four useful lemmas which will be used in the proof of Property 1.

Lemma 1. If $y \ge x > 0$, T > 0, and e < 0, then $y(T + x)^e \ge x(T + y)^e$.

Lemma 2. If $\lambda \ge 1$, $0 \le t$, and e < 0, then $\lambda [1 - (1 + t)^e] \ge 1 - (1 + \lambda t)^e$.

Lemmas 1 and 2 have been proved by Kuo and Yang and Liu et al. [3, 19], respectively.

Lemma 3. If $y \ge x > 0$, T > 0, e < 0, and $0 < \alpha < 1$, then $y \cdot \max\{\alpha, (T + x)^e\} \ge x \cdot \max\{\alpha, (T + y)^e\}$.

Proof. Note that $(T + x)^e \ge (T + y)^e$.

Case 1. As $\alpha > (T + x)^e$,

$$y \cdot \max\{\alpha, (T+x)^e\} = y \cdot \alpha,$$

$$x \cdot \max\{\alpha, (T+y)^e\} = x \cdot \alpha.$$
(4)

So, the inequality holds.

Case 2. As
$$(T + x)^e \ge \alpha > (T + y)^e$$
,
 $y \cdot \max\{\alpha, (T + x)^e\} = y \cdot (T + x)^e$,
 $x \cdot \max\{\alpha, (T + y)^e\} = x \cdot \alpha$.
(5)

The inequality holds.

Case 3. As
$$(T + y)^e \ge \alpha$$
,
 $y \cdot \max\{\alpha, (T + x)^e\} = y \cdot (T + x)^e$,
 $x \cdot \max\{\alpha, (T + y)^e\} = x \cdot (T + y)^e$.
(6)

From Lemma 1, the inequality holds.

Lemma 4. If $\lambda \ge 1$, $t \ge 0$, e < 0, and $0 < \beta < 1$, then $\lambda [\max\{\beta, 1\} - \max\{\beta, (1 + t)^e\}] \ge \max\{\beta, 1\} - \max\{\beta, (1 + \lambda t)^e\}.$

Proof. Note that $(1 + \lambda t) \ge 1 + t > 0$; thus, $(1 + \lambda t)^e \le (1 + t)^e \le 1$ because e < 0.

Case 1. As
$$\beta \le (1 + \lambda t)^e \le 1$$
,
 $\lambda [\max{\{\beta, 1\}} - \max{\{\beta, (1 + t)^e\}}] = \lambda [1 - (1 + t)^e],$
 $\max{\{\beta, 1\}} - \max{\{\beta, (1 + \lambda t)^e\}} = 1 - (1 + \lambda t)^e.$
(7)

From Lemma 2, the inequality holds.

Case 2. As $(1 + \lambda t)^{e} < \beta < (1 + t)^{e} \le 1$, $\lambda [\max{\{\beta, 1\}} - \max{\{\beta, (1 + t)^{e}\}}] = \lambda [1 - (1 + t)^{e}],$ $\max{\{\beta, 1\}} - \max{\{\beta, (1 + \lambda t)^{e}\}} = 1 - \beta,$ (8)

which is less than $1 - (1 + \lambda t)^e$. From Lemma 2, the equality holds.

Case 3. As
$$(1 + t)^{e} \le \beta < 1$$
,
 $\lambda [\max{\{\beta, 1\}} - \max{\{\beta, (1 + t)^{e}\}}] = \lambda [1 - \beta],$
 $\max{\{\beta, 1\}} - \max{\{\beta, (1 + \lambda t)^{e}\}} = 1 - \beta.$
(9)

The equality holds because $\lambda \ge 1$.

Case 4. As $\beta \ge 1$,

$$\lambda \left[\max\{\beta, 1\} - \max\{\beta, (1+t)^e\} \right] = \lambda \left[\beta - \beta\right] = 0,$$

$$\max\{\beta, 1\} - \max\{\beta, (1+\lambda t)^e\} = \beta - \beta = 0.$$
 (10)

In summary, the inequality always holds for the given conditions.

To show max{ β , 1} – max{ β , $(1 + \lambda t)^e$ } = $\beta - \beta = 0$ is no less than S_2 , it suffices to show $C_{3j}(S_1) \leq C_{3i}(S_2)$.

 $\begin{array}{ll} Property \ 1. \ \text{If} & a_i < a_j, b_i < b_j, c_i > c_j, & t_3 > \max\{t_1 + a_j \\ \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]})^{e_1}, t_2 + b_j \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{e_2}\}\}\}, \\ \text{and} \ t_1 + a_i \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]})^{e_1}\} + a_j \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]} + a_i)^{e_1}\} > \max\{t_2 + b_i \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{e_2}\} + b_j \max \quad \{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{e_2}\}, t_3 + c_i \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} k - 1c_{[i]})^{e_3}\}\}, \text{ then } S_1 \\ \text{is no less than } S_2. \end{array}$

Proof. For a job sequence S, if the job J_j is assigned to the r^{th} position of S, then according to the definition of the completion time of a job,

$$C_{3[r]}(S) = \max\left\{t_1 + a_j \max\left\{\alpha, \left(1 + \sum_{i=1}^{r-1} a_{[i]}\right)^{e_1}\right\}, t_2 + b_j \max\left\{\alpha, \left(1 + \sum_{i=1}^{r-1} b_{[i]}\right)^{e_2}\right\}, t_3\right\} + c_j \max\left\{\alpha, \left(1 + \sum_{i=1}^{r-1} c_{[i]}\right)^{e_3}\right\}$$
(11)

To simplify the proof, let $TA = (1 + \sum_{i=1}^{k-1} a_{[i]})^{e_1}$, $TB = (1 + \sum_{i=1}^{k-1} b_{[i]})^{e_2}$, and $TC = (1 + \sum_{i=1}^{k-1} c_{[i]})^{e_3}$. Then,

 $C_{3j}(S_{1}) = \max\{t_{1} + a_{i}\max\{\alpha, (TA)^{e_{1}}\} + a_{j}\max\{\alpha, (TA + a_{i})^{e_{1}}\}, t_{2} + b_{i}\max\{\alpha, (TB)^{e_{2}}\} + b_{j}\max\{\alpha, (TB + b_{i})^{e_{2}}\}, \\ \max\{t_{3}, t_{1} + a_{i}\max\{\alpha, (TA)^{e_{1}}\}, b_{i}\max\{\alpha, (TB)^{e_{2}}\}\} + c_{i}\max\{\alpha, (TC)^{e_{3}}\}\} + c_{j}\max\{\alpha, (TC + c_{i})^{e_{3}}\}, \\ C_{3i}(S_{2}) = \max\{t_{1} + a_{j}\max\{\alpha, (TA)^{e_{1}}\} + a_{i}\max\{\alpha, (TA + a_{j})^{e_{1}}\}, t_{2} + b_{j}\max\{\alpha, (TB)^{e_{2}}\} + b_{i}\max\{\alpha, (TB + b_{j})^{e_{2}}\}, \\ \max\{t_{3}, t_{1} + a_{j}\max\{\alpha, (TA)^{e_{1}}\}, b_{j}\max\{\alpha, (TB)^{e_{2}}\}\} + c_{j}\max\{\alpha, (TC)^{e_{3}}\}\} + c_{i}\max\{\alpha, (TC + c_{j})^{e_{3}}\}.$ (12)

Using the given conditions $a_i < a_j, b_i < b_j$, and $t_3 > \max\{t_1 + a_j \max\{\alpha, (TA)^{e_1}, t_2 + b_j \max\{\alpha, (TB)^{e_2}\}\}\}$, one has

 $C_{3j}(S_{1}) = \max\{t_{1} + a_{i}\max\{\alpha, (TA)^{e_{1}}\} + a_{j}\max\{\alpha, (TA + a_{i})^{e_{1}}\}, t_{2} + b_{i}\max\{\alpha, (TB)^{e_{2}}\} + b_{j}\max\{\alpha, (TB + b_{i})^{e_{2}}\}, t_{3} + c_{i}\max\{\alpha, (TC)^{e_{3}}\}\} + c_{j}\max\{\alpha, (TC + c_{i})^{e_{3}}\}, C_{3i}(S_{2}) = \max\{t_{1} + a_{j}\max\{\alpha, (TA)^{e_{1}}\} + a_{i}\max\{\alpha, (TA + a_{j})^{e_{1}}\}, t_{2} + b_{j}\max\{\alpha, (TB)^{e_{2}}\} + b_{i}\max\{\alpha, (TB + b_{j})^{e_{2}}\}, t_{3} + c_{j}\max\{\alpha, (TC)^{e_{3}}\}\} + c_{i}\max\{\alpha, (TC + c_{j})^{e_{3}}\}.$ (13)

Applying the given condition,

$$t_{1} + a_{i} \max\{\alpha, (TA)^{e_{1}}\} + a_{j} \max\{\alpha, (TA + a_{i})^{e_{1}}\} > \max\{t_{2} + b_{i} \max\{\alpha, (TB)^{e_{2}}\} + b_{j} \max\{\alpha, (TB + b_{i})^{e_{2}}\},$$

$$t_{3} + c_{i} \max\{\alpha, (TC)^{e_{3}}\}\},$$
(14)

and then,

$$C_{3j}(S_1) = t_1 + a_i \max\{\alpha, (TA)^{e_1}\} + a_j \max\{\alpha, (TA + a_i)^{e_1}\} + c_i \max\{\alpha, (TC + c_j)^{e_3}\},$$
(15)

$$C_{3i}(S_2) = t_1 + a_j \max\{\alpha, (TA)^{e_1}\} + a_i \max\{\alpha, (TA + a_j)^{e_1}\} + c_i \max\{\alpha, (TC + c_j)^{e_3}\}.$$
(16)

Equation (16) holds by showing $t_1 + a_j \max\{\alpha, (TA)^{e_1}\} + a_i \max\{\alpha, (TA + a_j)^{e_1}\} > [t_1 + a_i \max\{\alpha, (TA)^{e_1}\} + a_j \max\{\alpha, (TA + a_i)^{e_1}\}].$

$$a_{j} \max\{\alpha, (TA)^{e_{1}}\} + a_{i} \max\{\alpha, (TA + a_{j})^{e_{1}}\} - a_{i} \max\{\alpha, (TA)^{e_{1}}\} - a_{j} \max\{\alpha, (TA + a_{i})^{e_{1}}\}\}$$

$$= a_{j} [\max\{\alpha, (TA)^{e_{1}}\} - \max\{\alpha, (TA + a_{i})^{e_{1}}\}] - a_{i} [\max\{\alpha, (TA)^{e_{1}}\} - \max\{\alpha, (TA + a_{i})^{e_{1}}\}],$$

$$= a_{i} (TA)^{e_{1}} \cdot \left\{\frac{a_{j}}{a_{i}} \left[\max\{\frac{\alpha}{(TA)^{e_{1}}}, 1\} - \max\{\frac{\alpha}{(TA)^{e_{1}}}, \left(1 + \frac{a_{i}}{(TA)^{e_{1}}}\right)^{e_{1}}\}\right]\right] - \left[\max\{\frac{\alpha}{(TA)^{e_{1}}}, 1\}\right]$$

$$-\max\left\{\frac{\alpha}{(TA)^{e_{1}}}, \left(1 + \frac{a_{j}}{a_{i}} \frac{a_{i}}{(TA)^{e_{1}}}\right)^{e_{1}}\right\}\right]\right\},$$

$$= a_{i} (TA)^{e_{1}} \cdot \{\lambda [\max\{\beta, 1\} - \max\{\beta, (1 + t)^{e_{1}}\}] - [\max\{\beta, 1\} - \max\{\beta, (1 + \lambda t)^{e_{1}}\}]\},$$

$$(17)$$

where $\lambda = (a_j/a_i) \ (>1), \quad \beta = (\alpha/(TA)^{e_1}) \ (>0), \text{ and } b_j \max t = (a_i/(TA)^{e_1}) \ (>0).$ Applying Lemma 4, $\sum_{i=1}^{k-1} a_{[i]} \sum_{i=1}^{k-1} a_{[i]} \sum_{i=1}^{$

 $\max\{\alpha, (TA)^{e_1}\} + a_j \max\{\alpha, (TA + a_i)^{e_1}\}\]$ follows and, thus, completes the claim.

Finally, one needs to show that $C_{3i}(S_2) - C_{3j}(S_1) \ge 0$ to fulfill the proof. From equations (15) and (16), one obtains, applying $a_i < a_j, c_i > c_j$ and the fact $(TA + a_j)^{e_1} < (TA + a_i)^{e_1}$ and $(TC + c_j)^{e_3} > (TC + c_i)^{e_3}$, that all three terms of $C_{3i}(S_2) - C_{3j}(S_1)$ are greater than or equal to 0, i.e., $C_{3i}(S_2) - C_{3j}(S_1) \ge 0$.

The details of the proofs of Property 2-4 are omitted because they can be obtained in a similar way to Property 1.

 $\begin{array}{l} Property \ 2. \ \ \mathrm{If} \ a_i < a_j, b_i < b_j, c_i > c_j, \\ t_3 > \max\{t_1 + a_j \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]})^{a_1}, \ t_2 + b_j \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{a_2}\}\}\}, \ \ \mathrm{and} \ \ t_2 + b_i \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{a_2}\} + \end{array}$

$$\begin{split} b_j \max \left\{ \alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]} + b_i)^{a_2} \right\} > \max \left\{ t_1 + a_i \max \left\{ \alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]})^{a_1} \right\} + a_j \max \left\{ \alpha, \ (1 + \sum_{i=1}^{k-1} a_{[i]} + a_i)^{a_1} \right\}, t_3 + c_i \max \left\{ \alpha, \ (1 + \sum_{i=1}^{k-1} c_{[i]})^{a_3} \right\} \right\}, \text{ then } S_1 \text{ is no less than } S_2. \end{split}$$

Property 3. If $a_i < a_j, b_i < b_j, c_i > c_j$,

 $\begin{array}{l} t_1 + a_i \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} a_{[i]} \right)^{a_1} \right\} > \max \left\{ t_3, t_2 + b_j \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} b_{[i]} \right)^{a_2} \right\} \right\}, & \text{and} & a_j \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} a_{[i]} \right)^{a_1} \right\} + c_j \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} c_{[i]} \right)^{a_3} \right\} > a_i \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} a_{[i]} \right)^{a_1} \right\} + c_i \max \left\{ \alpha, \left(1 + \sum_{i=1}^{k-1} c_{[i]} \right)^{a_3} \right\}, & \text{then } S_1 \text{ is no less than } S_2. \end{array}$

Property 4. If $a_i < a_j, b_i < b_j, c_i > c_j$,

$$\begin{split} t_2 + b_i \max &\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{a_2}\} > \max \{t_3, t_1 + a_j \ \max\{\alpha, \\ (1 + \sum_{i=1}^{k-1} a_{[i]})^{a_1}\}\}, \text{ and } b_j \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{a_2}\} + c_j \ \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} c_{[i]})^{a_3}\} > b_i \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} b_{[i]})^{a_2}\} + c_i \ \max\{\alpha, \ (1 + \sum_{i=1}^{k-1} c_{[i]})^{a_3}\}, \text{ then } S_1 \text{ is no less than } S_2. \end{split}$$

4. Heuristics and Metaheuristics

This section validates the performance levels of nine algorithms, namely, JS_max, JS_min, JS_mean, JS_maxpi, JS_minpi, JS_meanpi, SA_max, SA_min, and SA_mean. Note that all algorithms were developed in FORTRAN and executed on a computer with a 3.00-GHz Intel® Core™i9-10980XE CPU and 16-GB RAM. Our experiments are divided into two parts. The first part is dedicated to the small size instances, and the second is devoted to the large size instances. For the two cases, we randomly generated the normal processing times from uniform distribution U (1, 100) on M1, M2, and M3 by fixing an individual seed for each case. The factor β would be set at 0.2, 0.4, and 0.6. The learning effect would be set at -0.1, -0.1, and -0.2, and the computational results for each small and large size instances are shown. This section describes the considered two-stage assembly scheduling problem.

4.1. Small Size Number of Jobs. The parameters of the small size number of jobs are selected as the number of work pieces (*n*) at 10, number of machines (*m*) of 3, and the final temperature (Tf) is fixed to 10^{-8} , β is 0.2, α_1 is -0.1, α_2 is -0.1, and α_3 is -0.2. The selections of other parameters are shown in Table 1.

As a result of parameter selection, the starting temperature (T_i) is 10^{-3} , cooling coefficient is 0.95, and the number of tests (N_r) of Johnson's algorithm is 10.

Next, the parameter selection process is explained in detail.

We select the parameter starting temperature (T_i) . The range is from 10^{-4} to 10^4 at 10 times the interval, and the cooling coefficient (c_f) is fixed at 0.95. The number of tests of Johnson's algorithm (N_r) is 5, and there are also generated data and parameters defined before selecting parameters.

By observing Figure 1, it is obvious that only the initial temperature (T_i) is changed. In this range, it can be observed that the AEP is relatively low at 10^{-3} , so the initial temperature (T_i) is 10^{-3} .

After fixing the starting temperature (T_i) to 10^{-3} , we select the parameter cooling coefficient (c_f) , ranging from 0.05 to 0.95 with 0.05 intervals, and fix the number of tests (N_r) of the Johnson's algorithm as 5. There are also generated data and parameters defined before selecting the parameters.

By selecting the parameter of the cooling coefficient (c_f) , the overall decline in its value is obvious. It becomes flat after reaching 0.80, so we choose a lower value in this part. The cooling coefficient (c_f) is fixed at 0.95. After fixing the starting temperature (T_i) to 10^{-3} and the cooling coefficient (Cf) to 0.95 (please see Figure 2), we select the parameter Johnson's algorithm test times (N_r) with a range of 1 to 20 and the interval of 1 and see the difference. The generated data and parameters are fixed and defined before selecting the parameters.

When selecting the parameter Johnson's algorithm test times (N_r) , we can see from Figure 3 that although it



FIGURE 1: Parameter selection starting temperature (T_i) change.



FIGURE 2: Parameter selection cooling coefficient (c_f) change.

fluctuates up and down, its AEP value is actually very low, so we choose a lower value in this part. Johnson's algorithm test times (N_r) is 10. It shows when the number of work pieces of the B&B algorithm is 12. The results of finding the best solution in a few cases cannot be found, so only a few values (in the Fs column) are recorded. From the viewpoint of the number of nodes and CPU time, the difference in the number of jobs can also be clearly seen.

Table 2 uses the β values of 0.2, 0.4, and 0.6 to distinguish the table. It can be seen regardless of whether the number of work pieces is 8, 10, or 12, the smaller the β value, the greater the number of nodes. Also, there is no best solution for the CPU time.

Table 3 is a table distinguished by three different situations of $\alpha_1, \alpha_2, \alpha_3$. It can be observed that regardless of whether the number of work pieces is 8, 10, or 12, the



FIGURE 3: Parameter selection of Johnson's algorithm test times (N_r) change.

TABLE 2: Different β for the mean of nodes and CPU time.

Para	meter	Node	CPU time
Ν	β	Mean	Mean
	0.2	9871	0.11
8	0.4	4474	0.05
	0.6	2825	0.03
	0.2	751491	10.33
10	0.4	262445	3.89
	0.6	196723	3.13
	0.2	51984213	978.76
12	0.4	27751022	585.76
	0.6	16943700	327.17

TABLE 3: Different β for the mean of nodes and CPU time.

14		Parameter		Node	CPU time
n	α_1	α_2	α ₃	Mean	Mean
	-0.1	-0.1	-0.1	4448	0.06
8	-0.1	-0.1	-0.2	7860	0.08
	-0.2	-0.2	-0.1	4861	0.05
	-0.1	-0.1	-0.1	281133	3.71
10	-0.1	-0.1	-0.2	608118	8.73
	-0.2	-0.2	-0.1	321109	4.91
	-0.1	-0.1	-0.1	22327360	467.04
12	-0.1	-0.1	-0.2	41700559	775.61
	-0.2	-0.2	-0.1	32651016	649.04

number of nodes and CPU time for finding the best solution for the second case are all more than the third case, and the third case is more than the first case.

The simulation result for the small size number of jobs from the total mean at the bottom shows that the SA-related algorithm performs better in the small size number of jobs.

Table 4 has β values of 0.2, 0.4, and 0.6, and no obvious features are noted.

Table 6 compares nine algorithms in total. There are three changes in the number of jobs (*n*) and β and 2 changes in $\alpha_1, \alpha_2, \alpha_3$.

third case.

Before comparing algorithms, normality verification is carried out on the data. If the data is normal, you can use the average of the algorithm to compare pairwise.

The residuals are not in line with the normal state, so they cannot be compared using means. We instead use the Kruskal–Wallis test to observe whether the medians of the data are the same (please see Table 7). If they are not the same, we can use the median of the algorithm to make pairwise comparisons and observe the calculations for the difference in the median between methods.

The null hypothesis is that the median of each group is the same, where the *P* value <0.05, so the null hypothesis is rejected, meaning the median of each group is not the same and multiple comparative analysis can be performed to show the difference between each group (please see Table 8).

Figure 4 is a box diagram of the nine algorithms scored by nonparametric statistics. Clearly, the results of the SArelated algorithms under the small size number of jobs are superior.

Table 9 shows the results of the pairwise comparison. We take the significance level of 0.05 as the standard. The JS_max algorithm and the JS_mean algorithm are grouped into one group, the JS_mean algorithm is divided into a group with the JS_maxpi algorithm, and the JS_maxpi algorithm is divided into a group with the SA-related algorithms are all divided into a group. From this, it can be seen that the SA algorithm is a relatively better group for the small size number of jobs, followed by the JS_meanpi Algorithm, JS_maxpi algorithm, JS_max algorithm, and finally, the JS_minpi algorithm and JS_min algorithm. There are two key points clearly observed in the grouping. First, the JS algorithm with pi is better. Second, the result obtained by mean is better than max, and max is better than min.

4.2. Large Size Number of Jobs. The parameters of the large size number of jobs are selected when the number of work pieces (*n*) is 10, the number of machines (*m*) is 3, and the final temperature (T_f) is fixed to 10^{-8} , β is 0.2, α_1 is -0.1, α_2 is -0.1, and α_3 is -0.2. The selections of other parameters are shown in Table 10.

From the summary of Tables 11 and 12, the SA algorithm is the best in calculating the RPD. However, the CPU_time shows that the SA algorithm takes a relatively long time. With pi or without pi, the JS algorithm clearly shows that the solution with pi to the run out of RPD is slightly inferior to the solution without pi. The JS algorithm with pi for the CPU_time is the fastest.

Table 13 shows the residual error in the large size number of jobs is not in line with the normal state, so we also

Para	meter	JS_max	JS_min	JS_mean	JS_maxpi	JS_minpi	JS_meanpi	SA_max	SA_min	SA_mean
N	β	Mean	Mean	Mean	Mean	Mean	Mean	Mean	Mean	Mean
	0.2	2.92	6.69	1.96	1.81	4.43	1.15	0.10	0.09	0.08
8	0.4	2.87	7.77	2.50	1.78	5.51	1.61	0.07	0.09	0.05
	0.6	2.25	7.21	2.01	1.43	5.07	1.29	0.07	0.08	0.06
	0.2	1.95	5.94	1.67	1.21	4.18	1.12	0.05	0.06	0.05
10	0.4	2.09	6.70	1.60	1.33	4.95	1.01	0.06	0.06	0.06
	0.6	1.59	6.11	1.38	1.09	4.40	0.93	0.07	0.10	0.08
	0.2	1.70	5.99	1.36	1.04	4.75	0.88	0.11	0.08	0.10
12	0.4	1.59	5.93	1.40	0.97	4.59	0.93	0.05	0.09	0.08
	0.6	1.32	6.24	1.26	0.92	4.88	0.95	0.10	0.09	0.10
Mear	ı	2.03	6.51	1.68	1.28	4.75	1.10	0.08	0.08	0.07

TABLE 4: Simulation result for β values.

TABLE 5: Simulation result for α values.

	Para	ameter		JS_max	JS_min	JS_mean	JS_maxpi	JS_minpi	JS_meanpi	SA_max	SA_min	SA_mean
п	α_1	α2	α ₃	Mean	Mean	Mean	Mean	Mean	Mean	Mean	Mean	Mean
	-0.1	-0.1	-0.1	2.10	7.14	1.72	1.26	5.15	1.07	0.06	0.08	0.05
8	-0.1	-0.1	-0.2	1.89	5.52	1.80	1.32	3.82	1.11	0.05	0.07	0.04
	-0.2	-0.2	-0.1	4.04	9.01	2.95	2.43	6.04	1.88	0.13	0.11	0.10
	-0.1	-0.1	-0.1	1.57	6.13	1.42	0.98	4.53	0.98	0.05	0.06	0.06
10	-0.1	-0.1	-0.2	1.48	4.52	1.37	1.04	3.20	0.93	0.06	0.06	0.07
	-0.2	-0.2	-0.1	2.58	8.10	1.87	1.60	5.79	1.15	0.07	0.10	0.06
	-0.1	-0.1	-0.1	1.37	6.41	1.23	0.90	4.91	0.85	0.11	0.14	0.10
12	-0.1	-0.1	-0.2	1.09	4.32	0.99	0.79	3.55	0.76	0.03	0.02	0.02
	-0.2	-0.2	-0.1	2.15	7.43	1.80	1.24	5.76	1.15	0.12	0.09	0.15
Mea	n			2.03	6.51	1.68	1.28	4.75	1.10	0.08	0.08	0.07

TABLE 6: Small size number of jobs analysis variable.

		Class level information
Class	Levels	Values
Algorithm	9	JS_max, JS_maxpi, JS_mean, JS_meanpi, JS_min, JS_minpi, SA_max, SA_mean, and SA_min
Ν	3	8 10 12
β	3	0.2 0.4 0.6
α_1	2	-0.1 -0.2
α_2	2	-0.1 -0.2
α ₃	2	-0.1 -0.2

TABLE 7: Normality test of residual error of the GLM model in the small size number of jobs.

		Normality test		
Test	Sta	tistics	P val	ue
Shapiro-Wilk	W	0.936652	$\Pr < W$	< 0.0001
Kolmogorov–Smirnov	D	0.086882	$\Pr < D$	< 0.0100
Cramer-von Mises	W-Sq	0.532874	$\Pr < W$ -Sq	< 0.0050
Anderson-Darling	A-Sq	3.734124	PR < A-Sq	< 0.0050

TABLE 8: Kruskal-Wallis verification of the small size number of jobs.

	Kruskal–Wallis test	
Chi-square	DF	Pr > ChiSq
214.5511	8	< 0.0001

use the same method as the small size number of jobs to compare the relationship between the algorithms.

In the Kruskal–Wallis test, the null hypothesis is rejected as with the small size number of jobs, meaning the median of each group is not the same and multiple comparison analysis



FIGURE 4: Scoring box of the nine algorithms.

 TABLE 9: Pairwise comparison of nine algorithms for the small size number of jobs.

	Small n	
Algorithm	Statistic	P value
JS_max vs. JS_min	8.5999	< 0.0001
JS_max vs. JS_mean	1.8843	0.9218
JS_max vs. JS_maxpi	5.3095	0.0054
JS_max vs. JS_minpi	7.7925	< 0.0001
JS_max vs. JS_meanpi	6.9494	< 0.0001
JS_max vs. SA_max	8.9241	< 0.0001
JS_max vs. SA_min	8.9268	< 0.0001
JS_max vs. SA_mean	8.9231	< 0.0001
JS_min vs. JS_mean	8.7717	< 0.0001
JS_min vs. JS_maxpi	8.8692	< 0.0001
JS_min vs. JS_minpi	5.0645	0.0103
JS_min vs. JS_meanpi	8.8938	< 0.0001
JS_min vs. SA_max	8.9239	< 0.0001
JS_min vs. SA_min	8.9267	< 0.0001
JS_min vs. SA_mean	8.9229	< 0.0001
JS_mean vs. JS_maxpi	4.3435	0.0547
JS_mean vs. JS_minpi	8.6249	< 0.0001
JS_mean vs. JS_meanpi	5.9589	0.0008
JS_mean vs. SA_max	8.9246	< 0.0001
JS_mean vs. SA_min	8.9273	< 0.0001
JS_mean vs. SA_mean	8.9236	< 0.0001
JS_maxpi vs. JS_minpi	8.7224	< 0.0001
JS_maxpi vs. JS_meanpi	1.7866	0.9418
JS_maxpi vs. SA_max	8.9243	< 0.0001
JS_maxpi vs. SA_min	8.9270	< 0.0001
JS_maxpi vs. SA_mean	8.9233	< 0.0001
JS_minpi vs. JS_meanpi	8.8449	< 0.0001
JS_minpi vs. SA_max	8.9239	< 0.0001
JS_minpi vs. SA_min	8.9267	< 0.0001

TABLE 9: Continued.

	Small <i>n</i>	
Algorithm	Statistic	P value
JS_minpi vs. SA_mean	8.9229	< 0.0001
JS_meanpi vs. SA_max	8.9244	< 0.0001
JS_meanpi vs. SA_min	8.9272	< 0.0001
JS_meanpi vs. SA_mean	8.9234	< 0.0001
SA_max vs. SA_min	0.6278	1.0000
SA_max vs. SA_mean	0.4790	1.0000
SA_min vs. SA_mean	1.1795	0.9959

TABLE 10: Parameter selection of the large size number of jobs.

Parameter	n = 90, m = 3
T_i	10 ⁻³
T_{f}	10^{-8}
c_f	0.95
Ń _r	90
β	0.2
α_1	-0.1
α_2	-0.1
α ₃	-0.2

can be performed to show the differences between each group (please see Table 14).

Figure 5 is a box diagram of nine algorithms scored by nonparametric statistics. The figure shows clear differences among SAs and others under the large size number of jobs.

Table 15 shows the results of the pairwise comparison. If the P value value is greater than 0.05, it means the effect between the pair is not significant, but they are correlative. In

												2										
	P	aramet	er		JS_n	лах	JS_n	nin	JS_m	ean	JS_m;	axpi	JS_m	inpi	JS_me	anpi	SA_r	nax	SA_n	in	SA_m	ean
Ν	β	α_1	α_2	α_3	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max
		-0.1	-0.1	-0.1	0.22	1.61	2.07	7.92	0.24	1.76	0.26	1.70	2.19	7.92	0.26	1.76	0.11	1.56	0.10	1.45	0.10	1.00
	0.2	-0.1	-0.1	-0.2	0.17	0.97	1.73	6.50	0.21	2.31	0.21	1.04	1.83	7.78	0.23	2.33	0.08	0.77	0.10	1.35	0.06	0.80
		-0.2	-0.2	-0.1	0.20	1.73	1.74	6.41	0.22	1.91	0.24	1.97	1.88	6.50	0.25	1.94	0.06	0.60	0.09	0.83	0.07	0.68
		-0.1	-0.1	-0.1	0.19	1.13	1.84	7.15	0.22	1.47	0.23	1.20	1.95	7.40	0.25	1.48	0.08	1.11	0.06	1.06	0.05	0.28
60	0.4	-0.1	-0.1	-0.2	0.18	1.11	1.68	6.18	0.18	1.42	0.22	1.14	1.80	7.11	0.21	1.44	0.07	0.67	0.07	1.91	0.07	0.65
		-0.2	-0.2	-0.1	0.15	0.96	1.83	6.74	0.16	1.49	0.19	1.02	1.95	7.02	0.19	1.53	0.07	0.64	0.08	1.44	0.07	1.17
		-0.1	-0.1	-0.1	0.16	1.34	2.01	6.79	0.19	1.36	0.20	1.38	2.15	7.30	0.21	1.39	0.07	0.53	0.12	1.90	0.05	0.34
	0.6	-0.1	-0.1	-0.2	0.18	1.40	2.09	6.77	0.20	1.49	0.23	1.50	2.22	8.56	0.22	1.50	0.09	0.68	0.11	1.84	0.06	0.58
		-0.2	-0.2	-0.1	0.16	0.95	1.99	7.17	0.19	1.18	0.20	1.02	2.12	11.54	0.21	1.19	0.08	0.51	0.06	1.06	0.07	0.57
Mean					0.1	8	1.8	6	0.2	0	0.2	2	2.(11	0.2	3	0.0	8	0.0	6	0.07	
		-0.1	-0.1	-0.1	0.13	0.97	1.48	6.35	0.13	0.99	0.15	1.03	1.53	6.77	0.14	1.02	0.06	0.67	0.08	1.00	0.05	0.41
	0.2	-0.1	-0.1	-0.2	0.12	1.02	1.10	5.01	0.12	1.03	0.14	1.04	1.15	5.02	0.14	1.04	0.06	0.46	0.07	0.98	0.07	0.77
		-0.2	-0.2	-0.1	0.14	1.01	1.40	6.47	0.16	1.18	0.17	1.09	1.44	6.48	0.18	1.21	0.08	0.68	0.10	1.61	0.07	0.63
		-0.1	-0.1	-0.1	0.14	0.88	1.39	4.97	0.15	0.87	0.16	0.92	1.45	5.01	0.17	0.88	0.07	0.71	0.08	1.01	0.08	0.78
90	0.4	-0.1	-0.1	-0.2	0.14	0.96	1.35	5.11	0.14	1.03	0.16	0.98	1.40	5.34	0.15	1.07	0.07	0.88	0.07	0.86	0.05	0.17
		-0.2	-0.2	-0.1	0.11	0.89	1.51	5.61	0.11	0.85	0.13	0.90	1.56	5.61	0.13	0.87	0.05	0.47	0.07	0.89	0.05	0.66
		-0.1	-0.1	-0.1	0.10	0.66	1.41	4.87	0.12	0.97	0.13	0.73	1.46	4.87	0.14	0.99	0.06	0.40	0.10	0.69	0.06	0.61
	0.6	-0.1	-0.1	-0.2	0.16	0.98	1.52	4.88	0.17	1.22	0.18	0.99	1.56	4.89	0.18	1.24	0.06	0.65	0.08	0.87	0.08	0.93
		-0.2	-0.2	-0.1	0.14	0.87	1.44	5.23	0.17	1.26	0.17	0.88	1.50	5.52	0.19	1.30	0.07	0.76	0.09	0.90	0.08	0.78
Mean					0.1	3	1.4	0	0.1	4	0.1	5	1.4	15	0.1	9	0.0	7	0.0	~	0.07	
		-0.1	-0.1	-0.1	0.11	09.0	1.09	3.84	0.12	0.58	0.12	0.62	1.12	3.95	0.13	0.63	0.06	0.50	0.09	0.88	0.06	0.56
	0.2	-0.1	-0.1	-0.2	0.10	0.70	1.12	3.58	0.10	0.75	0.11	0.71	1.16	3.71	0.11	0.76	0.04	0.51	0.10	0.61	0.05	0.58
		-0.2	-0.2	-0.1	0.07	0.49	1.14	3.66	0.08	0.50	0.09	0.53	1.18	4.27	0.09	0.51	0.05	0.48	0.07	0.76	0.05	0.49
		-0.1	-0.1	-0.1	0.07	0.61	1.11	4.31	0.08	0.58	0.09	0.65	1.15	4.40	0.09	0.59	0.04	0.39	0.07	0.85	0.05	0.40
120	0.4	-0.1	-0.1	-0.2	0.09	0.71	1.15	4.41	0.10	1.06	0.11	0.79	1.18	4.41	0.11	1.08	0.06	0.76	0.09	0.88	0.05	0.42
		-0.2	-0.2	-0.1	0.12	0.70	1.13	3.86	0.14	0.93	0.13	0.73	1.17	3.87	0.15	0.94	0.07	0.67	0.10	1.01	0.07	0.68
		-0.1	-0.1	-0.1	0.08	0.61	1.01	3.61	0.10	0.88	0.10	0.62	1.06	3.61	0.11	0.88	0.05	0.47	0.08	1.18	0.05	0.25
	0.6	-0.1	-0.1	-0.2	0.09	0.71	1.04	3.82	0.10	0.67	0.11	0.74	1.06	3.83	0.11	0.68	0.04	0.64	0.10	0.75	0.04	0.23
		-0.2	-0.2	-0.1	0.09	0.64	1.15	3.54	0.10	0.57	0.11	0.67	1.18	3.55	0.11	0.59	0.06	0.62	0.08	0.61	0.05	0.39
Mean					0.0	6	1.1	0	0.1	0	0.1	1	1.1	4	0.1	1	0.0	5	0.0	6	0.05	
Total 1	nean				0.1	3	1.4	9	0.1.	5	0.1	6	1.5	53	0.1	6	0.0	7	0.0	6	0.06	

TABLE 11: RPD summary of the large size number of jobs.

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							Ľ	ABLE 12	: CPU_t	ime sum	ımary of	the larg	e size nu	umber of	f jobs.							
	l	Paramet	ter		JS_n	лах	JS_r	nin	JS_m	lean	JS_m	ıaxpi	JS_m	inpi	JS_me	anpi	SA_r	nax	SA_r	nin	SA_m	ean
и	β	α_1	α_2	α_3	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max	Mean	Max
		-0.1	-0.1	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.00	0.00	0.00	0.19	0.20	0.19	0.20	0.19	0.22
	0.2	-0.1	-0.1	-0.2	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.02	0.00	0.00	0.00	0.00	0.19	0.20	0.19	0.20	0.19	0.22
		-0.2	-0.2	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.02	0.00	0.00	0.19	0.20	0.19	0.22	0.19	0.20
		-0.1	-0.1	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.02	0.00	0.02	0.00	0.00	0.19	0.20	0.19	0.22	0.19	0.20
60	0.4	-0.1	-0.1	-0.2	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.00	0.00	0.02	0.19	0.20	0.19	0.20	0.19	0.20
		-0.2	-0.2	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.00	0.00	0.00	0.19	0.20	0.19	0.20	0.19	0.20
		-0.1	-0.1	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.02	0.00	0.00	0.00	0.00	0.19	0.20	0.19	0.22	0.19	0.20
	0.6	-0.1	-0.1	-0.2	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.00	0.00	0.00	0.19	0.20	0.19	0.20	0.19	0.20
		-0.2	-0.2	-0.1	0.02	0.03	0.02	0.03	0.02	0.03	0.00	0.00	0.00	0.02	0.00	0.02	0.19	0.20	0.19	0.20	0.19	0.20
Mear					0.02		0.02		0.02		0.00		0.00		0.00		0.19		0.19		0.19	
		-0.1	-0.1	-0.1	0.06	0.08	0.06	0.08	0.06	0.06	0.00	0.00	00.00	0.00	0.00	0.00	0.28	0.30	0.28	0.30	0.28	0.30
	0.2	-0.1	-0.1	-0.2	0.06	0.06	0.06	0.08	0.06	0.06	0.00	0.02	00.00	0.02	0.00	0.00	0.28	0.30	0.29	0.31	0.28	0.30
		-0.2	0.2	-0.1	0.06	0.08	0.06	0.06	0.06	0.08	0.00	0.00	0.00	0.02	0.00	0.00	0.28	0.30	0.28	0.30	0.28	0.30
		-0.1	-0.1	-0.1	0.06	0.06	0.06	0.08	0.06	0.06	0.00	0.02	00.00	0.02	0.00	0.00	0.28	0.30	0.29	0.31	0.28	0.30
90	0.4	-0.1	-0.1	-0.2	0.06	0.06	0.06	0.08	0.06	0.06	0.00	0.00	00.00	0.00	0.00	0.02	0.28	0.30	0.28	0.30	0.28	0.30
		-0.2	-0.2	-0.1	0.06	0.06	0.06	0.08	0.06	0.08	0.00	0.02	00.00	0.00	0.00	0.00	0.28	0.30	0.29	0.31	0.28	0.30
		-0.1	-0.1	-0.1	0.06	0.08	0.06	0.06	0.06	0.06	0.00	0.02	0.00	0.02	0.00	0.02	0.28	0.30	0.28	0.30	0.28	0.31
	0.6	-0.1	-0.1	-0.2	0.06	0.06	0.06	0.06	0.06	0.08	0.00	0.02	0.00	0.02	0.00	0.02	0.28	0.30	0.28	0.31	0.28	0.30
		-0.2	-0.2	-0.1	0.06	0.08	0.06	0.08	0.06	0.08	0.00	0.00	0.00	0.00	0.00	0.00	0.28	0.30	0.28	0.33	0.28	0.30
Mear					0.0	9	0.0)6	0.0	90	0.0	00	0.0	0	0.0	0	0.2	8	0.2	8	0.28	
		-0.1	-0.1	-0.1	0.13	0.14	0.13	0.14	0.13	0.14	0.00	0.02	0.00	0.00	0.00	0.02	0.38	0.39	0.38	0.41	0.38	0.41
	0.2	-0.1	-0.1	-0.2	0.13	0.14	0.13	0.14	0.13	0.14	0.00	0.00	00.00	0.00	0.00	0.02	0.38	0.39	0.38	0.41	0.38	0.39
		-0.2	-0.2	-0.1	0.13	0.14	0.13	0.14	0.13	0.14	0.00	0.02	00.00	0.00	0.00	0.02	0.38	0.41	0.38	0.39	0.38	0.39
		-0.1	-0.1	-0.1	0.13	0.14	0.13	0.14	0.13	0.14	0.00	0.00	0.00	0.02	0.00	0.00	0.38	0.39	0.38	0.41	0.38	0.41
120	0.4	-0.1	-0.1	-0.2	0.14	0.14	0.14	0.14	0.14	0.14	0.00	0.00	00.0	0.02	0.00	0.02	0.39	0.41	0.39	0.42	0.39	0.42
		-0.2	-0.2	-0.1	0.14	0.16	0.14	0.14	0.14	0.14	0.00	0.00	00.0	0.02	0.00	0.02	0.39	0.41	0.39	0.42	0.39	0.41
		-0.1	-0.1	-0.1	0.14	0.16	0.14	0.14	0.14	0.14	0.00	0.00	0.00	0.02	0.00	0.02	0.39	0.41	0.39	0.39	0.39	0.41
	0.6	-0.1	-0.1	-0.2	0.14	0.14	0.14	0.14	0.14	0.16	0.00	0.02	0.00	0.02	0.00	0.00	0.39	0.41	0.39	0.44	0.39	0.42
		-0.2	-0.2	-0.1	0.14	0.16	0.14	0.16	0.14	0.16	0.00	0.00	0.00	0.02	0.00	0.00	0.39	0.42	0.39	0.42	0.39	0.41
Mear					0.1	4	0.1	3	0.1	3	0.(00	0.0	0	0.0	0	0.3	80	0.3	8	0.38	~
Total	mean				0.0	2	0.0	20	0.0	2	0.0	00	0.0	0	0.0	0	0.2	8	0.2	6	0.29	

		Normality test		
Hypothesis test	Sta	itistics	P val	ue
Shapiro-Wilk	W	0.916964	Pr < W	< 0.0001
Kolmogorov–Smirnov	D	0.120337	Pr < D	< 0.0100
Cramer-von Mises	W-Sq	0.862822	Pr < W-Sq	< 0.0050
Anderson-Darling	A-Sq	5.519845	PR < A-Sq	< 0.0050

TABLE 13: Normality test of residual error of the GLM model with the large size number of jobs.

TABLE 14: Kruskal-Wallis test of the small size number of jobs.

	Kruskal–Wallis test	
Chi-square	DF	Pr > ChiSq
204.1873	8	<0.0001



FIGURE 5: Scoring box of nine algorithms.

	1 -	D ' '	•		• •	1	1	C	.1 :	1	•	1		<i>c</i>		1
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										. 0					1.	

	Big n	
Algorithm	Statistic	P value
JS_max vs. JS_min	8.9219	<0.0001
JS_max JS_mean	1.5462	0.9754
JS_max JS_maxpi	2.6857	0.6144
JS_max JS_minpi	8.9231	< 0.0001
JS_max JS_meanpi	3.0313	0.4434
JS_max SA_max	8.2129	< 0.0001
JS_max vs. SA_min	6.3166	0.0003
JS_max SA_mean	8.4541	< 0.0001
JS_min JS_mean	8.9231	<0.0001

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TABLE 15: Continued.

	Big n	
Algorithm	Statistic	P value
JS_min JS_maxpi	8.9212	< 0.0001
JS_min JS_minpi	1.4563	0.9831
JS_min JS_meanpi	8.9238	< 0.0001
JS_min vs. SA_max	8.9450	< 0.0001
JS_min vs. SA_min	8.9414	< 0.0001
JS_min SA_mean	8.9677	< 0.0001
JS_mean JS_maxpi	1.2996	0.9920
JS_mean JS_minpi	8.9243	< 0.0001
JS_mean JS_meanpi	1.7044	0.9556
JS_mean SA_max	8.6226	< 0.0001
JS_mean SA_min	7.4503	< 0.0001
JS_mean SA_mean	8.7932	< 0.0001
JS_maxpi JS_minpi	8.9224	< 0.0001
JS_maxpi JS_meanpi	0.4543	1.0000
JS_maxpi SA_ma	8.8029	< 0.0001
JS_maxpi SA_min	8.1199	< 0.0001
JS_maxpi SA_mean	8.9094	<0.0001
JS_minpi JS_meanpi	8.9250	< 0.0001
JS_minpi SA_max	8.9462	<0.0001
JS_minpi SA_min	8.9426	<0.0001
JS_minpi SA_mean	8.9689	< 0.0001
JS_meanpi SA_max	8.8186	< 0.0001
JS_meanpi SA_min	8.2291	< 0.0001
JS_meanpi SA_mean	8.9242	< 0.0001
SA_max SA_min	5.8616	0.0011
SA_max SA_mean	1.4043	0.9866
SA_min SA_mean	6.7381	<0.0001

the pairwise comparison, JS_max and JS_mean are in the same group, JS_max and JS_maxpi are in the same group, JS_max and JS_meanpi are in the same group, JS_min and JS_minpi are in the same group, JS_mean and JS_meanpi are in the same group, and SA_max and the SA_mean are in the same group. The results of the SA algorithm and JS algorithms are also significant, so they would not be divided into the same group. The RPD summary of the large size number of jobs shows the solution of the SA algorithm is comparatively better. The SA algorithm is better than the JS algorithm in this case.

5. Conclusions

This study focuses on two-stage three-machine flow shop assembly problems mixed with a controllable number and sum-of-processing times-based learning effect, in which job processing time is considered to be a function of the control of the truncation parameter and learning based on the sum of the processing time. We derive several dominance rules, lemmas, and lower bounds applied in the branch-and-bound method. On the other hand, three simulated annealing algorithms are proposed for finding approximate solutions. Computational results show that the SA algorithm is relatively better for the small size number of jobs. In the large size number of jobs, the solution of the SA algorithm is comparatively better. Both in the small and large size number of jobs situation, the SA algorithm is better than the JS algorithm in this study. For future research, it would be interesting to develop more powerful dominance rules and a sharper lower bound on the optimal solution for mediumsize instances.

Data Availability

All data are available on request.

Conflicts of Interest

The author declares that there are no conflicts of interest regarding the publication of this paper.

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