## Research Article

# Long Term Behavior for a Class of Stochastic Delay Lattice Systems in $X_{\rho}$ Space 

Yijin Zhang ${ }^{(1), 2}$ and Zongbing Lin $\mathbb{C D}^{\mathbf{3}}$<br>${ }^{1}$ School of Mathematics, Sichuan University, Chengdu, Sichuan 610065, China<br>${ }^{2}$ Key Lab of Intelligent Analysis and Decision on Complex Systems, Key Laboratory of Industrial Internet of Things and Networked Control, Ministry of Education, Chongqing University of Posts and Telecommunications, Chongqing 400065, China<br>${ }^{3}$ School of Mathematics and Computer Science, Panzhihua University, Panzhihua 617000, China<br>Correspondence should be addressed to Yijin Zhang; 2273354482@qq.com

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In this paper, we focus on the asymptotic behavior of solutions to stochastic delay lattice equations with additive noise and deterministic forcing. We first show the existence of a continuous random dynamical system for the equations. Then we investigate the pullback asymptotical compactness of solutions as well as the existence and uniqueness of tempered random attractor in $X_{\rho}$ space. Finally, ergodicity of the systems is achieved.

## 1. Introduction

We explore the asymptotic behavior of a class of stochastic lattice systems with time delay driven by additive white noise:

$$
\begin{align*}
\frac{d u_{i}}{d t}= & v\left(u_{i-1}-2 u_{i}+u_{i+1}\right)-\lambda u_{i}+F_{i}\left(u_{i}\right)+f_{i}\left(u_{i}(t-\rho)\right) \\
& +g_{i}+\varepsilon a_{i} \frac{d w_{i}}{d t}, \quad t>\tau \tag{1}
\end{align*}
$$

with initial data

$$
\begin{equation*}
u_{i}(\tau+s)=u_{\tau, i}(s), \quad s \in[-\rho, 0] \tag{2}
\end{equation*}
$$

where $i \in \mathbb{Z}, \mathbb{Z}$ denotes the integer set, $\tau \in \mathbb{R}^{+} . u=\left(u_{i}(s)\right)_{i \in \mathbb{Z}}$ is a sequence in $X_{\rho}$ space (defined later), $v, \lambda$, and $\varepsilon$ are positive constants, $\varepsilon$ is the intensity of noise, $F(u)=\left(F_{i}\left(u_{i}\right)\right)_{i \in \mathbb{Z}}$ is a superlinear source term, $f(u(t-\rho))=\left(f_{i}\left(u_{i}(t-\rho)\right)\right)_{i \in \mathbb{Z}}$ is a nonlinear function satisfying certain structural conditions and capturing the time delay $\rho \geq 0, g=\left(g_{i}\right)_{i \in \mathbb{Z}} \in X$ (defined later), $a=\left(a_{i}\right)_{i \in \mathbb{Z}} \in X, w=\left(w_{i}\right)_{i \in \mathbb{Z}}$ is a two-side real valued Wiener process on a probability space.

Lattice differential equations are widely adopted in physics, biology, and engineering such as pattern formation, propagation of nerve pulses, electric circuits, and so on, see, e.g.,
([1-7]). Stochastic lattice dynamical systems (SLDS) arise naturally, while random influences or uncertainties (called noises) are taken into account. These noises may play an important role as intrinsic phenomena rather than just compensation of defects in deterministic models [8].

The theory of attractors is a powerful tool to depict the asymptotic dynamics of an infinite-dimensional system. Random attractor is an important concept to describe asymptotic behavior for a random dynamical system and to capture the essential dynamics with possibly extremely wide fluctuations. Until now, random attractors have been investigated by many researchers, e.g., in [9-13] for autonomous stochastic equations, and in [14-21] for nonautonomous stochastic ones.

Lots of work have been done regarding the existence of global random attractors for SLDS with white noises of infinite sequences, see e.g., [22-29] and the references therein. Note that the stochastic equations considered in these papers do not contain nonlinearity with time delay. The differential equations with delays arise, for instance, from population dynamics where a time lag or after-effect is involved.

As far as we are aware, it seems that there are very few works in the literature dealing with random attractors of stochastic lattice equations containing nonlinearity with time delay except [30-33].

In the present paper, we consider the stochastic delay lattice equations with superlinear nonlinearity (delay terms). More precisely, we first prove the existence and uniqueness of tempered random attractors of equation (1). Then we show the ergodicity of the systems.

Denote

$$
\begin{equation*}
\ell^{p}=\left\{u=\left(u_{i}\right)_{i \in \mathbb{Z}}: \sum_{i \in \mathbb{Z}}\left|u_{i}\right|^{p}<\infty \quad u_{i} \in \mathbb{R}, p \geq 1\right\} \tag{3}
\end{equation*}
$$

Let $X:=\ell^{2}(\mathbb{Z})\left(\ell^{p}: p=2\right)$. It is known that $X$ is a Hilbert space with the inner product $(u, v)=\sum_{i \in \mathbb{Z}} u_{i} v_{i}$, and the norm $\|u\|_{X}^{2}=\sum_{i \in \mathbb{Z}}\left|u_{i}\right|^{2}$, where $u=\left(u_{i}\right)_{i \in \mathbb{Z}}, v=\left(v_{i}\right)_{i \in \mathbb{Z}} \in X$. Then we define a Banach space by $X_{\rho}:=\mathscr{C}([-\rho, 0], X)$ with the norm

$$
\begin{equation*}
\|u\|_{X_{\rho}}=\sup _{s \in[-\rho, 0]}\|u(s)\|_{X}, \quad \forall u=(u(s))_{s \in[-\rho, 0]} \in X_{\rho} . \tag{4}
\end{equation*}
$$

In the sequel, we use $\|\cdot\|$ and $(\cdot, \cdot)$ to denote the norm and inner product of $X$, respectively. The norm of $\ell^{p}$ is written as $\|\cdot\|_{\ell^{p}}(p \neq 2)$.

The letters $C$ and $C_{i}(i=1,2, \cdots)$ are general positive constants, taking different values from line to line. Since their values are not significant, we do not care about their values and relationship between one and another.

This paper is organized as follows. In Section 2, we recall some basic concepts and already known results related to random dynamical systems and random attractors. In Section 3, we show that the stochastic delay lattice differential equation (1) generates an infinite dimensional random dynamical system. The existence of the global random attractor is given in Section 4. Finally, the proof of ergodicity of the systems is finished in Section 5.

## 2. Preliminaries

In the following, we recall some basic concepts on random dynamical systems and pullback attractors which are mentioned in [8, 22].

Let $\chi$ be a Banach space and $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$ be a metric dynamical system, $(\chi, d)$ a complete separable metric space with Borel $\sigma$-algebra $\mathscr{B}(\chi)$. Suppose $\mathscr{D}$ is a collection of some families of nonempty subsets of $\chi$.

Definition 1. A mapping $\Phi: \mathbb{R}^{+} \times \mathbb{R} \times \Omega \times \chi \rightarrow \chi$ is called a continuous random dynamical system (RDS) on $\chi$ over $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$ if for all $\omega \in \Omega$ and $t, s \in \mathbb{R}^{+}$,
(i) $\Phi(\cdot, \cdot, \cdot): \mathbb{R}^{+} \times \Omega \times \chi \rightarrow \chi$ is $\left(\mathscr{B}\left(\mathbb{R}^{+}\right) \times \mathscr{F} \times \mathscr{B}(\chi), \mathscr{B}(\chi)\right)$-measurable;
(ii) $\Phi(0, \omega, \cdot)$ is the identity on $\chi$;
(iii) $\Phi(t+s, \omega, \cdot)=\Phi\left(t, \theta_{s} \omega, \cdot\right) \circ \Phi(s, \omega, \cdot)$;
(iv) $\Phi(t, \omega, \cdot): \chi \rightarrow \chi$ is continuous.

Definition 2. A family $K=\{K(\omega): \omega \in \Omega\} \in \mathscr{D}$ is called a $\mathscr{D}$ -pullback absorbing set for $\Phi$ if for all $\omega \in \Omega$ and for every $D \in \mathscr{D}$, there exists $T=T(D, \omega)>0$ such that

$$
\begin{equation*}
\Phi\left(t, \theta_{-t} \omega, D\left(\theta_{-t} \omega\right)\right) \subseteq K(\omega) \quad \text { for all } t \geq T \tag{5}
\end{equation*}
$$

If, in addition, for all $\omega \in \Omega, K(\omega)$ is a closed nonempty subset of $\chi$ and $K$ is measurable in $\omega$ with respect to $\mathscr{F}$, then we say $K$ is a closed measurable $\mathscr{D}$-pullback absorbing set for $\Phi$.

Definition 3. The random dynamical system $\Phi$ is said to be $\mathscr{D}$-pullback asymptotically compact in $\chi$ if for $\omega \in \Omega$, the sequence

$$
\begin{equation*}
\left\{\Phi\left(t_{n}, \theta_{-t_{n}} \omega, x_{n}\right)\right\}_{n=1}^{\infty} \text { has a convergent subsequence in } \chi \tag{6}
\end{equation*}
$$

whenever $t_{n} \rightarrow \infty$, and $x_{n} \in B\left(\theta_{-t_{n}} \omega\right)$ with $\{B(\omega): \omega \in \Omega\} \in \mathscr{D}$.

Definition 4. A family $\mathscr{A}=\{\mathscr{A}(\omega): \omega \in \Omega\} \in \mathscr{D}$ is called a $\mathscr{D}$-pullback attractor for $\Phi$ if for every $\omega \in \Omega$,
(i) $\mathscr{A}$ is measurable in $\omega$ with respect to $\mathscr{F}$ and $\mathscr{A}(\omega)$ is compact in $\chi$;
(ii) $\mathscr{A}$ is invariant: $\Phi(t, \omega, \mathscr{A}(\omega))=\mathscr{A}\left(t, \theta_{t} \omega\right), \forall t \geq 0$;
(iii) $\mathscr{A}$ attracts every member of $\mathscr{D}$ : for every $D \in \mathscr{D}$,

$$
\begin{equation*}
\lim _{t \rightarrow \infty} d_{\chi}\left(\Phi\left(t, \theta_{-t} \omega, D\left(\theta_{-t} \omega\right)\right), \mathscr{A}(\omega)\right)=0 \tag{7}
\end{equation*}
$$

where $d_{\chi}$ is the Hausdorff semi-distance in $\chi$.
We borrow the following result for random dynamical systems from $[28,34]$ and omit its proof.

Proposition 5. Let $\mathscr{D}$ be an inclusion closed collection of some families of nonempty subsets of $\chi$, and $\Phi$ be a continuous RDS on $\chi$ over $\mathbb{R}$ and $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$. Then $\Phi$ has a $\mathscr{D}$-pullback attractor $\mathscr{A}$ in $\mathscr{D}$ if $\Phi$ is $\mathscr{D}$-pullback asymptotically compact in $\chi$ and $\Phi$ has a closed measurable $\mathscr{D}$-pullback absorbing set $K$ in $\mathscr{D}$. The $\mathscr{D}$-pullback attractor $\mathscr{A}$ is unique and is given $b y$, for each $\omega \in \Omega$,

$$
\begin{equation*}
\mathscr{A}(\omega)=\bigcap_{\kappa \geq t_{K}(\omega)} \overline{\bigcup_{t \geq \kappa} \Phi\left(t, \theta_{-t} \omega, K\left(\theta_{-t} \omega\right)\right)} \tag{8}
\end{equation*}
$$

## 3. RDSs for Stochastic Delay Lattice Systems

In this section, we first state some assumptions that will be used throughout this paper. Then we illustrate the existence of RDSs for stochastic delay lattice systems.

From now on, the functions $F, f$ are assumed to satisfy the following conditions with positive constants $p, \alpha_{1}, \alpha_{2}, C_{f}, L_{f}$, $L_{F}$, and $p \geq 2$.
$\left(A_{1}\right) \quad$ For all $s, t, \beta_{1, i}, \beta_{2, i} \in \mathbb{R}$,

$$
\begin{equation*}
F_{i}(s) s \leq-\alpha_{1}|s|^{p}+\beta_{1, i} \tag{9}
\end{equation*}
$$

$$
\begin{equation*}
\left|F_{i}(s)\right| \leq \alpha_{2}|s|^{p-1}+\beta_{2, i}, \tag{10}
\end{equation*}
$$

and $\sum_{i \in \mathbb{Z}} \beta_{1, i}<\infty, \sum_{i \in \mathbb{Z}} \beta_{2, i}<\infty$. $F$ also possesses the local Lipschitz condition, i.e., for any bounded interval $I \subset \mathbb{R}$, there exists a positive constant $L_{F}$, such that for every $s, t \in I$,

$$
\begin{equation*}
\left|F_{i}(t)-F_{i}(s)\right| \leq L_{F}|t-s|, \tag{11}
\end{equation*}
$$

$\left(A_{2}\right) \quad f: \mathbb{R} \rightarrow \mathbb{R}$ is continuous and for all $\left(u_{i}\right)_{i \in \mathbb{Z}},\left(v_{i}\right)_{i \in \mathbb{Z}} \in \ell^{2}$,

$$
\begin{gather*}
\left|f_{i}\left(u_{i}\right)-f_{i}\left(v_{i}\right)\right| \leq L_{f}\left|u_{i}-v_{i}\right|  \tag{12}\\
\left|f_{i}\left(u_{i}\right)\right|^{2} \leq C_{f}^{2}\left|u_{i}\right|^{2}+\left|\eta_{i}\right|^{2} \tag{13}
\end{gather*}
$$

where $\left(\eta_{i}\right)_{i \in \mathbb{Z}} \in X$, and $C_{\eta}$ is a constant satisfying $\sum_{i \in \mathbb{Z}}\left|\eta_{i}\right|^{2}=C_{\eta}$.
$\left(A_{3}\right)$ We also need this assumption:

$$
\begin{equation*}
\lambda \geq 2 \sqrt{2} C_{f} . \tag{14}
\end{equation*}
$$

$\left(A_{4}\right) \quad$ For sufficiently large $\lambda>0$, there is a positive constant $\epsilon$ small enough, such that

$$
\begin{equation*}
\lambda-\epsilon-\frac{4}{\lambda} C_{f}^{2} e^{\epsilon \rho} \geq 0 \tag{15}
\end{equation*}
$$

$\left(A_{5}\right) \quad$ We can choose a positive constant $\vartheta$ such that

$$
\begin{equation*}
\frac{3 \lambda}{2}-\vartheta-\frac{8}{\lambda} C_{f}^{2} e^{\vartheta \rho} \geq 0 \tag{16}
\end{equation*}
$$

For convenience, we now formulate system (1) as stochastic differential equations in $X_{\rho}$. Denote by $B, B^{*}$, and $A$ the linear operators from $X_{\rho}$ into $X_{\rho}$ in the following way: for any $u=\left(u_{i}\right)_{i \in \mathbb{Z}} \in X_{\rho}$,

$$
\begin{equation*}
(B u)_{i}=u_{i+1}-u_{i}, \quad\left(B^{*} u\right)_{i}=u_{i-1}-u_{i}, \tag{17}
\end{equation*}
$$

and

$$
\begin{equation*}
(A u)_{i}=-u_{i-1}+2 u_{i}-u_{i+1} . \tag{18}
\end{equation*}
$$

Then we have $A=B B^{*}=B^{*} B, \quad\left(B^{*} u, v\right)=(u, B v)$, and $(A u, u) \geq 0$ for all $u, v \in X_{\rho}$.

In the sequel, we consider the probability space ( $\Omega, \mathscr{F}, P$ ) where

$$
\begin{equation*}
\Omega=\{\omega \in \mathscr{C}(\mathbb{R}, X): \omega(0)=0\} \tag{19}
\end{equation*}
$$

$\mathscr{F}$ is the Borel $\sigma$-algebra induced by the compact-open topology of $\Omega$, and $\mathscr{F}_{0}$ is the Borel $\sigma$-algebra on $\Omega$. $P$ is the corresponding Wiener measure on $(\Omega, \mathscr{F})$.

Let us recall a filtration over the parametric space $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$

$$
\begin{equation*}
\mathscr{F}_{t_{0}}^{t}=\sigma\left\{W\left(t_{2}\right)-W\left(t_{1}\right): t_{0} \leq t_{1} \leq t_{2} \leq t\right\} \tag{20}
\end{equation*}
$$

which is the smallest $\sigma$-algebra generated by random variable $W\left(t_{2}\right)-W\left(t_{1}\right)$ for every $t_{0} \leq t_{1} \leq t_{2} \leq t$. This $\sigma$-algebra has the property: $\theta_{h}^{-1} \mathscr{F}_{t_{0}}^{t}=\mathscr{F}_{t_{0}+h}^{t+h}$. So $W(t)$ is adapted to $\mathscr{F}_{t_{0}}^{t}$.

There is a classical group $\left\{\theta_{t}\right\}_{t \in \mathbb{R}}$ acting on $(\Omega, \mathscr{F}, P)$, which is defined by

$$
\begin{equation*}
\theta_{t} \omega(\cdot)=\omega(\cdot+t)-\omega(t), \quad \omega \in \Omega, t \in \mathbb{R} \tag{21}
\end{equation*}
$$

Then $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$ is a parametric dynamical system (see [9] for more details).

Let $e^{i} \in X, i \in \mathbb{Z}$ denote the element having 1 at position $i$ and all the other components 0 . We have

$$
\begin{equation*}
\sum_{i \in \mathbb{Z}} a_{i} e^{i} w_{i}(t)=W(t) \quad \text { with } \quad\left(a_{i}\right)_{i \in \mathbb{Z}} \in X \tag{22}
\end{equation*}
$$

is the white noise taking valus in $X$ defined on the probability space $(\Omega, \mathscr{F}, P)$.

Then problem (1) and (2) can be written as the following abstract form:

$$
\begin{equation*}
\frac{d u}{d t}+v A u+\lambda u=F(u)+f(u(t-\rho))+g+\varepsilon \frac{d W}{d t}, \quad t<\tau \tag{23}
\end{equation*}
$$

with the initial conditions

$$
\begin{equation*}
u(\tau+s)=u_{\tau}(s), \quad s \in[-\rho, 0] . \tag{24}
\end{equation*}
$$

Next, we define a continuous RDS for lattice system (1) and (2) in $X_{\rho}$. This can be achieved by transferring the stochastic lattice system into a deterministic one with random parameters in a standard manner. Let $z\left(\theta_{t} \omega\right)$ satisfies the one-dimensional stochastic differential equation

$$
\begin{equation*}
d z\left(\theta_{t} \omega\right)+\alpha z\left(\theta_{t} \omega\right) d t=d w(t) \tag{25}
\end{equation*}
$$

This equation has a random fixed point in the sense of random dynamical systems generating a stationary solution known as the stationary Ornstein-Uhlenbeck process (see [9] for more details)

$$
\begin{equation*}
z(\omega)=-\alpha \int_{-\infty}^{0} e^{\alpha s} \omega(s) d s \tag{26}
\end{equation*}
$$

In fact, we have that there exists a $\left(\theta_{t}\right)_{t \in \mathbb{R}}$-invariant subset $\{\tilde{\Omega}\} \subseteq \Omega$ of full measure such that $z\left(\theta_{t} \omega\right)$ is continuous in $t$ for every $\omega \in \tilde{\Omega}$, and the random variable $|z(\omega)|$ is tempered. Let $\tilde{\mathscr{F}}$ and $\tilde{P}$ be the restrictions of $\mathscr{F}$ and $P$, respectively. We will define a continuous RDS for lattice system (1) and (2) in $X_{\rho}$ over $\mathbb{R}$ and $\left(\tilde{\Omega}, \tilde{\mathscr{F}}, \tilde{P},\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$. For convenience, from now on, we will abuse the notation slightly and write the space $(\tilde{\Omega}, \tilde{\mathscr{F}}, \tilde{P})$ as $(\Omega, \mathscr{F}, P)$.

Given a bounded nonempty subset $D$ of $X_{\rho}$, the Hausdorff semidistance between $D$ and the origin in $X_{\rho}$ is denoted by $\|D\|=\sup _{\psi \in D}\|\psi\|$. Let $D=\{D(\omega): \omega \in \Omega\}$ be a family of nonempty subsets of $X_{\rho}$. Such a $D$ is said to be tempered in $X_{\rho}$ if for every $\gamma>0$,

$$
\begin{equation*}
\lim _{t \rightarrow-\infty} e^{\gamma t}\left\|D\left(\theta_{t} \omega\right)\right\|=0 \tag{27}
\end{equation*}
$$

Throughout the rest of this paper, we always use $\mathscr{D}$ to denote the collection of all families of tempered nonempty subsets of $X_{\rho}$.

The system (23) may be rewritten as an integral equation in $X_{\rho}$,

$$
u(t)=u_{\tau}(0)+\int_{\tau}^{t}(-v A u(r)-\lambda u(r)+F(u(r))+f(u(r-\rho))+g) d r
$$

$$
\begin{equation*}
+\varepsilon W(t)-\varepsilon W(\tau), \quad t \geq \tau, w \in \Omega \tag{28}
\end{equation*}
$$

Theorem 6. Let $T>0$, then the following three properties hold:
(1) Equation (28) possesses a unique solution $u\left(t, u_{\tau}\right) \in \mathscr{L}^{2}(\Omega, \mathscr{C}([0, T], X)) ;$
(2) We have the following estimate, for every $\omega \in \Omega$ :

$$
\begin{align*}
& \sup _{t \in[\tau, T]}\|u(t)\|^{2} \leq C\left(\left\|u_{\tau}(0)-\varepsilon W(\tau)\right\|^{2}+\varepsilon^{2} \sup _{t \in[\tau, T]}\|W(t)\|^{2}\right. \\
& \left.\quad+\int_{\tau}^{T}\left(\|W(r)\|^{2}+\|W(r)\|_{\ell^{p}}^{p}+\|W(r)\|_{\ell^{1}}+\|g\|^{2}\right) d r\right) \tag{29}
\end{align*}
$$

(3) The solution of (28) depends continuously on the initial data $u_{\tau}$, that is to say, for all $\omega \in \Omega$, the mapping $u_{\tau} \in X \mapsto u\left(\cdot, \omega, u_{\tau}\right) \in \mathscr{C}([0, T], X)$ is continuous.

Proof.
(1) $\operatorname{Set} z(t)=u(t)-\varepsilon W(t)$.For every $\omega \in \Omega$, equation (28) has a solution $u \in \mathscr{L}^{2}(\Omega, \mathscr{C}([\tau, T], X))$ if and only if

$$
z(t)=u_{\tau}(0)+\int_{\tau}^{t}(-v A z(r)-\lambda z(r)+F(z(r)+\varepsilon W(r))+f(z(r-\rho)
$$

$$
\begin{equation*}
+\varepsilon W(r-\rho))+g-v \varepsilon A W(r)-\lambda \varepsilon W(r)) d r-\varepsilon W(\tau) \tag{30}
\end{equation*}
$$

has a solution $z \in \mathscr{L}^{2}(\Omega, \mathscr{C}([\tau, T], X))$ for every $t \in[0, T]$ and every $\omega \in \Omega$. For each fixed $\omega \in \Omega$, (30) becomes a deterministic equation. As we know, it has a local solution $z \in \mathscr{C}\left(\left[\tau, T_{\max }\right], X\right)$, where $\left[\tau, T_{\max }\right]$ is the maximal interval of the existence of the solution. Next we prove this local solution is a global one.

Suppose $\omega \in \Omega$, from (30) we have

$$
\begin{align*}
\|z(t)\|^{2}= & \left\|u_{\tau}(0)-\varepsilon W(\tau)\right\|^{2}+2 \int_{\tau}^{t}\left[-v(A z(r), z(r))-\lambda\|z(r)\|^{2}\right. \\
& +(F(z(r)+\varepsilon W(r)), z(r))+(f(z(r-\rho)+\varepsilon W(r-\rho)), z(r)) \\
& +(g, z(r))-v \varepsilon(A W(r), z(r))-\lambda \varepsilon(W(r), z(r))] d r . \tag{31}
\end{align*}
$$

By the assumption $\left(A_{1}\right)$ and Young's inequality, we obtain

$$
\begin{align*}
& (F(z(r)+\varepsilon W(r)), z(r)) \\
& \quad=(F(z(r)+\varepsilon W(r)), z(r)+\varepsilon W(r))-(F(z(r)+\varepsilon W(r)), \varepsilon W(r)) \\
& \quad \leq \sum_{i \in \mathbb{Z}}\left(-\alpha_{1}\left|z_{i}+\varepsilon a_{i} e^{i} w_{i}(r)\right|^{p}+\beta_{1, i}\right) \\
& \quad+\varepsilon \sum_{i \in \mathbb{Z}}\left(\left(\alpha_{2}\left|z_{i}+\varepsilon a_{i} e^{i} w_{i}(r)\right|^{p-1}+\beta_{2, i}\right)\left|a_{i} e^{i} w_{i}(r)\right|\right)  \tag{32}\\
& \quad \leq \sum_{i \in \mathbb{Z}} \beta_{1, i}+C_{1} \sum_{i \in \mathbb{Z}}\left|a_{i} e^{i} w_{i}(r)\right|^{p} \varepsilon \sum_{i \in \mathbb{Z}}\left(\beta_{2, i}\left|a_{i} e^{i} w_{i}(r)\right|\right) \\
& \quad \leq C_{2}\left(1+\|W(r)\|_{\ell^{p}}^{p}+\|W(r)\|_{\ell^{1}}\right)
\end{align*}
$$

It follows from assumption $\left(A_{2}\right)$ and Young's inequality that

$$
\begin{align*}
& (f(z(r-\rho)+\varepsilon W(r-\rho)), z(r)) \leq \frac{\lambda}{8}\|z(r)\|^{2}+\frac{4}{\lambda} C_{f}^{2} \sum_{i \in \mathbb{Z}}\left|z_{i}(r-\rho)\right|^{2} \\
& \quad+\frac{4}{\lambda}\left(C_{f} \varepsilon\right)^{2} \sum_{i \in \mathbb{Z}}\left|a_{i} e^{i} w_{i}(r-\rho)\right|^{2}+\frac{2}{\lambda} C_{\eta} . \tag{33}
\end{align*}
$$

Utilizing Young's inequality, we gain the following three inequalities:

$$
\begin{equation*}
(g, z(r)) \leq \frac{\lambda}{8}\|z(r)\|^{2}+\frac{2}{\lambda}\|g\|^{2} \tag{34}
\end{equation*}
$$

$$
\begin{gather*}
-v \varepsilon(A W(r), z(r)) \leq \frac{\lambda}{8}\|z(r)\|^{2}+\frac{2}{\lambda}(v \varepsilon)^{2}\|A\|^{2}\|W(r)\|^{2},  \tag{35}\\
-\lambda \varepsilon(W(r), z(r)) \leq \frac{\lambda}{8}\|z(r)\|^{2}+\frac{2}{\lambda}(\lambda \varepsilon)^{2}\|W(r)\|^{2} \tag{36}
\end{gather*}
$$

By (31)-(36), we get
$\|z(t)\|^{2} \leq\left\|u_{\tau}(0)-\varepsilon W(\tau)\right\|^{2}-\lambda \int_{\tau}^{t}\|z(r)\|^{2} d r$

$$
\begin{align*}
& +\frac{8}{\lambda} C_{f}^{2} \int_{\tau-\rho}^{t-\rho}\|z(r)\|^{2} d r+\frac{8}{\lambda}\left(C_{f} \varepsilon\right)^{2} \int_{\tau-\rho}^{t-\rho}\|W(r)\|^{2} d r \\
& +\frac{4}{\lambda} C_{\eta}(t-\tau)+\frac{4}{\lambda} \int_{\tau}^{t}\|g\|^{2} d r+\frac{4}{\lambda}(v \varepsilon)^{2} \int_{\tau}^{t}\|A\|^{2}\|W(r)\|^{2} d r \\
& +\frac{4}{\lambda}(\lambda \varepsilon)^{2} \int_{\tau}^{t}\|W(r)\|^{2} d r+2 C_{2} \int_{\tau}^{t}\left(1+\|W(r)\|_{\ell^{\rho}}^{p}+\|W(r)\|_{\ell^{1}}\right) d r \tag{37}
\end{align*}
$$

where
$\frac{8}{\lambda} C_{f}^{2} \int_{\tau-\rho}^{t-\rho}\|z(r)\|^{2} d r \leq \frac{8}{\lambda} C_{f}^{2} \int_{\tau-\rho}^{t}\|z(r)\|^{2} d r$

$$
\begin{align*}
& =\frac{8}{\lambda} C_{f}^{2}\left(\int_{\tau-\rho}^{t}\|z(r)\|^{2} d r+\int_{\tau}^{t}\|z(r)\|^{2} d r\right) \\
& \leq \frac{8}{\lambda} C_{f}^{2}\left(\rho \sup _{r \in[\tau-\rho, \tau]}\|z(r)\|+\int_{\tau}^{t}\|z(r)\|^{2} d r\right) . \tag{38}
\end{align*}
$$

By the similar way, we receive

It follows from (37)-(39) and assumption $\left(A_{3}\right)$ that

$$
\begin{align*}
\|z(t)\|^{2} \leq & C_{2}\left\|u_{\tau}(0)-\varepsilon W(\tau)\right\|^{2} \\
& +C_{1} \int_{\tau}^{t}\left(\|W(r)\|^{2}+\|W(r)\|_{e^{p}}^{p}+\|W(r)\|_{e^{1}}+\|g\|^{2}+1\right) d r \tag{40}
\end{align*}
$$

where $C_{1}, C_{2}$ are positive constants depending on $v, \lambda, \varepsilon, \rho,_{C f}, C_{\eta}, \sup _{r \in[\tau-\rho, \tau]}\|z(r)\|, \sup _{r \in[\tau-\rho, \tau]}\|W(r)\|$. This tells us that $\|z(t)\|$ is bounded by a continuous function, hence there exists a global solution on any $[\tau, T]$. For every $\omega \in \Omega$,

$$
\begin{align*}
\sup _{t \in[\tau, T]}\|z(t)\|^{2} \leq & C\left(\left\|u_{\tau}(0)-\varepsilon W(\tau)\right\|^{2}+\int_{\tau}^{T}\left(\|W(r)\|^{2}\right.\right.  \tag{41}\\
& \left.\left.+\|W(r)\|_{\ell^{p}}^{p}+\|W(r)\|_{\ell^{1}}+\|g\|^{2}\right) d r\right) .
\end{align*}
$$

Taking expectation on both sides of the above inequality, we known that $z(t) \in \mathscr{L}^{2}(\Omega, \mathscr{C}([\tau, T], X))$. It implies that (28) has a global solution $u(t) \in \mathscr{L}^{2}(\Omega, \mathscr{C}([\tau, T], X))$.
(2) By (41) and $z(t)=u(t)-\varepsilon W(t)$, for every $\omega \in \Omega$, we can conclude (29).
(3) Let $u_{\tau, Y_{1}}(s), u_{\tau, Y}(s) \in X_{\rho},\left\|u_{\tau, Y_{1}}(s)\right\|,\left\|u_{\tau, Y}(s)\right\|<r_{0}$ for some $r_{0}>0$, and $Y_{1}(t)=: u\left(t, u_{\tau, Y_{1}}(s)\right), Y(t)=: u\left(t, u_{\tau, Y}(s)\right)$ be the corresponding solutions of (28). Then it follows from (28) that

$$
\begin{align*}
\left\|Y_{1}(t)-Y(t)\right\|^{2}= & \left\|u_{\tau, Y_{1}}(s)-u_{\tau, Y}(s)\right\|^{2}+2 \int_{\tau}^{t}\left[-v\left(A\left(Y_{1}(r)-Y(r)\right), Y_{1}(r)-Y(r)\right)\right. \\
& -\lambda\left\|Y_{1}(r)-Y(r)\right\|^{2}+\left(F\left(Y_{1}(r)\right)-F(Y(r)), Y_{1}(r)-Y(r)\right)(42 \\
& \left.+\left(f\left(Y_{1}(r-\rho)\right)-f(Y(r-\rho)), Y_{1}(r)-Y(r)\right)\right] d r .
\end{align*}
$$

Set

$$
\begin{align*}
R= & C\left(r_{0}^{2}+\varepsilon^{2} \sup _{t \in[\tau, T]}\|W(t)\|^{2}+\int_{\tau}^{T}\left(\|W(r)\|^{2}+\|W(r)\|_{\ell^{p}}^{p}\right.\right. \\
& \left.\left.+\|W(r)\|_{\ell^{1}}+\|g\|^{2}\right) d r\right) \tag{43}
\end{align*}
$$

By the assumption of local Lipschitz condition of $F$, we know there exists a constant $L_{R}$ such that on the ball $B(0, R)$,

$$
\begin{equation*}
\left\|F\left(Y_{1}(r)\right)-F(Y(r))\right\| \leq L_{R}\left\|Y_{1}(r)-Y(r)\right\| . \tag{44}
\end{equation*}
$$

So

$$
\begin{equation*}
\left(F\left(Y_{1}(r)\right)-F(Y(r)), Y_{1}(r)-Y(r)\right) \leq L_{R}\left\|Y_{1}(r)-Y(r)\right\|^{2} \tag{45}
\end{equation*}
$$

By Schwarz inequality, Young's inequality and the assumption $\left(A_{2}\right)$, we get

$$
\begin{align*}
& \int_{\tau}^{t}\left(f\left(Y_{1}(r-\rho)\right)-f(Y(r-\rho)), Y_{1}(r)-Y(r)\right) d r \\
& \quad \leq \frac{1}{2} \int_{\tau}^{t}\left(\left\|f\left(Y_{1}(r-\rho)\right)-f(Y(r-\rho))\right\|^{2}+\left\|Y_{1}(r)-Y(r)\right\|^{2}\right) d r \\
& \quad \leq \frac{1}{2} \int_{\tau}^{t}\left(L_{f}^{2}\left\|Y_{1}(r-\rho)-Y(r-\rho)\right\|^{2}+\left\|Y_{1}(r)-Y(r)\right\|^{2}\right) d r \\
& \quad \leq \frac{1}{2} \int_{\tau}^{t}\left(L_{f}^{2}+1\right)\left\|Y_{1}(r)-Y(r)\right\|^{2} d r+C_{1}, \tag{46}
\end{align*}
$$

where $C_{1}=(1 / 2) \int_{\tau-\rho}^{\tau} L_{f}^{2}\left\|Y_{1}(r)-Y(r)\right\|^{2} d r$. Therefore, we infer

$$
\begin{align*}
& \left\|Y_{1}(t)-Y(t)\right\|^{2} \leq\left(\rho L_{f}^{2}+1\right)\left\|u_{\tau, Y_{1}}(s)-u_{\tau, Y}(s)\right\|^{2} \\
& \quad+\left(2 L_{R}+L_{f}^{2}-2 \lambda+1\right) \int_{\tau}^{t}\left\|Y_{1}(r)-Y(r)\right\|^{2} d r \tag{47}
\end{align*}
$$

By Gronwall's inequality, we find
$\left\|Y_{1}(t)-Y(t)\right\|^{2} \leq\left\|u_{\tau, Y_{1}}(s)-u_{\tau, Y}(s)\right\|^{2} e^{\left|2 L_{R}+L_{f}^{2}-2 \lambda+1\right|(t-\tau)} \quad, t \in[\tau, T]$.

Hence

$$
\begin{equation*}
\sup _{t \in[\tau, T]}\left\|Y_{1}(t)-Y(t)\right\|^{2} \leq\left\|u_{\tau, Y_{1}}(s)-u_{\tau, Y}(s)\right\|^{2} e^{\left|2 L_{R}+L_{f}^{2}-2 \lambda+1\right|(T-\tau)} \tag{49}
\end{equation*}
$$

This inequality implies the uniqueness and continuous dependence on the initial data of the solution of (30). This proof is completed.

Similar to the proof of the Theorem 7 in [8] with minor modifications, we can prove.

Theorem 7. System (27) generates a continuous RDS $(\Phi(t, s))_{t \geq \tau} \operatorname{over}\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}_{t \in \mathbb{R}}\right)$ and $\mathbb{R}$, where

$$
\begin{equation*}
\Phi\left(t, s, \omega, u_{\tau}(s)\right)=u\left(t, s, \omega, u_{\tau}(s)\right) \quad s \in[-\rho, 0] \tag{50}
\end{equation*}
$$

for each $t \geq \tau, \omega \in \Omega$.

## 4. Existence of Pullback Attractors

This section is devoted to the proof of existence of tempered pullback attractors for the systems (1) and (2) in $X_{\rho}$. We first show the existence of the absorbing set for the system (23). Then we make uniform estimate on the tails of solutions of systems (1) and (2). Finally we derive the theorem for the existence of the tempered pullback attractors.

Theorem 8. There exists a $\theta_{t}$-invariant set $\Omega^{\prime} \subset \Omega$ with full $\mathbb{P}$ measure and an absorbing set $K(\omega), \omega \in \Omega^{\prime}$, for $\Phi\left(t, s, \omega, u_{\tau}(s)\right)$, that is to say, there is an absorbing time $T=T(D, \omega)>0$, for each $D \in \mathscr{D}, \omega \in \Omega^{\prime}$ and $t \geq T$ such that

$$
\begin{equation*}
\Phi\left(t, \theta_{-t} \omega, D\left(\theta_{-t} \omega\right)\right) \subset K(\omega) \tag{51}
\end{equation*}
$$

what is more, $K \in \mathscr{D}$.
Proof. We apply an Ornstein-Uhlenbeck process on metric dynamical system $\left(\Omega, \mathscr{F}, P,\left\{\theta_{t}\right\}\right)$ in $X$. Suppose

$$
\begin{gather*}
z\left(\theta_{t} \omega\right)=:-\lambda \int_{-\infty}^{0} e^{\lambda s} \theta_{t} \omega(s) d s \quad t>\tau, \lambda>0  \tag{52}\\
d z+\lambda z d t=d w(t) \quad t>\tau \tag{53}
\end{gather*}
$$

Moreover, there is a $\theta_{t}$-invariant set $\Omega^{\prime} \subset \Omega$ with full $\mathbb{P}$ measure such that, for all $\omega \in \Omega^{\prime}$, (1) the mapping $t \rightarrow y\left(\theta_{t} \omega\right)$ is continuous; (2) the random variable $\|y(\omega)\|$ is tempered.

Set $v(t)=u(t)-\varepsilon y\left(\theta_{t} \omega\right)$, where $u(t)$ is a solution of (23). We have

$$
\begin{align*}
\frac{d v}{d t}= & -v A v-\lambda v+F\left(v(t)+\varepsilon y\left(\theta_{t} \omega\right)\right)+f(t, v(t-\rho)  \tag{54}\\
& \left.+\varepsilon y\left(\theta_{t-\rho} \omega\right)\right)+g-v \varepsilon A y\left(\theta_{t} \omega\right), \quad t>\tau
\end{align*}
$$

with the initial conditions

$$
\begin{equation*}
v(\tau+s)=v_{\tau}(s), \quad s \in[-\rho, 0] . \tag{55}
\end{equation*}
$$

Taking the inner product of (54) with $v(t)$, we can obtain

$$
\begin{align*}
\frac{1}{2} \frac{d}{d t}\|v\|^{2}+v(A v, v)+\lambda\|v\|^{2}= & (F(v+\varepsilon y), v) \\
& +\left(f\left(t, v(t-\rho)+\varepsilon y\left(\theta_{t-\rho} \omega\right)\right), v\right) \\
& +(g, v)-v \varepsilon(A y, v) \tag{56}
\end{align*}
$$

By using the assumption $\left(A_{1}\right)$ and Young's inequality, we arrive at

$$
\begin{align*}
(F(v+\varepsilon y), v)= & (F(v+\varepsilon y), v+\varepsilon y)-(F(v+\varepsilon y), \varepsilon y) \\
\leq & \sum_{i \in \mathbb{Z}}\left(-\alpha_{1}\left|v_{i}+\varepsilon y_{i}\right|^{p}+\beta_{1, i}\right) \\
& +\sum_{i \in \mathbb{Z}}\left(\left(\alpha_{2}\left|v_{i}+\varepsilon y_{i}\right|^{p-1}+\beta_{2, i}\right) \varepsilon\left|y_{i}\right|\right) \\
\leq & C\left(1+\|y\|_{e^{p}}^{p}+\|y\|_{e^{1}}\right) \tag{57}
\end{align*}
$$

where $C$ is a positive constant depending only on $\varepsilon, p, \alpha_{1}, \alpha_{2}, \sum_{i \in \mathbb{Z}} \beta_{1, i}, \sum_{i \in \mathbb{Z}} \beta_{2, i}$.

$$
\begin{align*}
& \text { Young's inequality and the assumption }\left(A_{2}\right) \text { also yield } \\
& \begin{array}{l}
\left(f\left(v(t-\rho)+\varepsilon y\left(\theta_{t-\rho} \omega\right)\right), v\right) \\
\leq \frac{1}{\lambda}\left\|f\left(v(t-\rho)+\varepsilon y\left(\theta_{t-\rho} \omega\right)\right)\right\|^{2}+\frac{\lambda}{4}\|v\|^{2} \\
\leq \frac{\lambda}{4}\|v\|^{2}+\frac{1}{\lambda} \sum_{i \in \mathbb{Z}}\left(C_{f}^{2}\left|v_{i}(t-\rho)+\varepsilon y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right|^{2}+\left|\eta_{i}\right|^{2}\right) \\
\leq \frac{\lambda}{4}\|v\|^{2}+\frac{2}{\lambda} C_{f}^{2}\|v(t-\rho)\|^{2}+\frac{2}{\lambda}\left(C_{f} \varepsilon\right)^{2} \sum_{i \in \mathbb{Z}}\left|y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right|^{2}+\frac{1}{\lambda} C_{\eta}, \\
\quad(g, v) \leq \frac{\lambda}{8}\|v\|^{2}+\frac{2}{\lambda}\|g\|^{2}, \\
-v \varepsilon(A y, v) \leq \frac{\lambda}{8}\|v\|^{2}+\frac{2}{\lambda}(v \varepsilon)^{2}\|A\|^{2}\|y\|^{2} .
\end{array}
\end{align*}
$$

Using (56)-(60), we have

$$
\begin{align*}
& \frac{d}{d t}\left(e^{\epsilon t}\|v\|^{2}\right)+(\lambda-\epsilon) e^{\epsilon t}\|v\|^{2} \\
& \quad \leq e^{\epsilon t}\left[2 C\left(1+\|y\|_{e^{p}}^{p}+\|y\|_{e^{1}}\right)+\frac{4}{\lambda} C_{f}^{2}\|v(t-\rho)\|^{2}\right. \\
& \left.\quad+\frac{4}{\lambda}\left(C_{f} \varepsilon\right)^{2}\left\|y\left(\theta_{t-\rho} \omega\right)\right\|^{2}+\frac{2}{\lambda} C_{\eta}+\frac{4}{\lambda}\|g\|^{2}+\frac{4}{\lambda}(v \varepsilon)^{2}\|A\|^{2}\|y\|^{2}\right] . \tag{61}
\end{align*}
$$

Integrating (61) from $\tau$ to $t$ and estimating the following terms, we find that

$$
\begin{align*}
& \frac{4}{\lambda} C_{f}^{2} \int_{\tau}^{t} e^{\epsilon r}\|v(r-\rho)\|^{2} d r \leq \frac{4}{\lambda} C_{f}^{2}\left(\int_{\tau-\rho}^{\tau} e^{\epsilon(r+\rho)}\|v(r)\|^{2} d r\right. \\
& \left.\quad+\int_{\tau}^{t} e^{\epsilon(r+\rho)}\|v(r)\|^{2} d r\right) \leq \frac{4}{\lambda} C_{f}^{2} \rho \sup _{r \in[\tau-\rho, \tau]} e^{\epsilon(r+\rho)}\|v(r)\|^{2} \\
& \quad+\frac{4}{\lambda} C_{f}^{2} \int_{\tau}^{t} e^{\epsilon(r+\rho)}\|v(r)\|^{2} d r \tag{62}
\end{align*}
$$

and similarly,
$\frac{4}{\lambda}\left(C_{f} \varepsilon\right)^{2} \int_{\tau}^{t} e^{\epsilon r}\left\|y\left(\theta_{r-\rho} \omega\right)\right\|^{2} d r \leq C_{1}+\frac{4}{\lambda}\left(C_{f} \varepsilon\right)^{2} \int_{\tau}^{t} e^{\epsilon(r+\rho)}\left\|y\left(\theta_{r} \omega\right)\right\|^{2} d r$.

It follows from (61)-(63) and the assumption $\left(A_{4}\right)$ that

$$
\begin{align*}
e^{\epsilon t}\|v(t)\|^{2} \leq & e^{\epsilon \tau}\|v(\tau)\|^{2}+C \int_{\tau}^{t} e^{\epsilon r}\left(1+\|y\|_{e^{p}}^{p}+\|y\|_{e^{1}}+\|y\|^{2}\right) d r+ \\
& +\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) e^{\epsilon t} . \tag{64}
\end{align*}
$$

Therefore,

$$
\begin{align*}
\left\|v\left(t, \omega, v_{\tau}(s, \omega)\right)\right\|^{2} \leq & \left\|v_{\tau}(s, \omega)\right\|^{2} e^{\varepsilon(\tau-t)}+C \int_{\tau}^{t} e^{\varepsilon(r-t)}\left(1+\left\|y\left(\theta_{r} \omega\right)\right\|_{e^{p}}^{p}\right. \\
& \left.+\left\|y\left(\theta_{r} \omega\right)\right\|_{\ell^{1}}+\left\|y\left(\theta_{r} \omega\right)\right\|^{2}\right) d r+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) . \tag{65}
\end{align*}
$$

Since $y\left(\theta_{t} \omega\right)$ is continuous and $\|y(\omega)\|$ is tempered, $\left(1+\|y\|_{\ell^{p}}^{p}+\|y\|_{\ell^{1}}+\|y\|^{2}\right)$ is tempered. From proposition 4.3.3 [13] P187, there is a tempered function $r(\omega)>0$ such that

$$
\begin{equation*}
1+\left\|y\left(\theta_{t} \omega\right)\right\|_{e^{p}}^{p}+\left\|y\left(\theta_{t} \omega\right)\right\|_{e^{1}}+\left\|y\left(\theta_{t} \omega\right)\right\|^{2} \leq r\left(\theta_{t} \omega\right) \leq r(\omega) e^{(\epsilon / 2)|t|} . \tag{66}
\end{equation*}
$$

In (65), with $\omega$ replaced by $\theta_{-t} \omega$, from (66), we have

$$
\begin{align*}
& \left\|v\left(t, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right\|^{2} \leq\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\|^{2} e^{\epsilon(\tau-t)} \\
& \quad+C \int_{\tau}^{t} e^{\epsilon(\tau-t)}\left(1+\left\|y\left(\theta_{r-t} \omega\right)\right\|_{\ell^{p}}^{p}+\left\|y\left(\theta_{r-t} \omega\right)\right\|_{\ell^{l^{\prime}}}+\left\|y\left(\theta_{r-t} \omega\right)\right\|^{2}\right) d \\
& \quad+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) \leq\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\|^{2} e^{-\epsilon(t-\tau)}  \tag{67}\\
& \quad+C \int_{\tau-t}^{0} e^{\epsilon \epsilon}\left(1+\left\|y\left(\theta_{\varsigma} \omega\right)\right\|_{\ell^{p}}^{p}\left\|y\left(\theta_{\varsigma} \omega\right)\right\|_{\ell^{l^{\prime}}}+\left\|y\left(\theta_{\varsigma} \omega\right)\right\|^{2}\right) d \varsigma \\
& \quad+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) \leq\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\|^{2} e^{-\epsilon(t-\tau)}+\frac{2 C r(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) .
\end{align*}
$$

Choose

$$
\begin{equation*}
R(\omega)=\frac{4 C r(\omega)}{\epsilon}+\frac{4}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right) \tag{68}
\end{equation*}
$$

Then, $R(\omega)$ is tempered and $\tilde{K}(\omega)=\left\{v \epsilon X_{\rho}:\|v\|^{2} \leq R(\omega)\right\}$ is an absorbing set for $v\left(t, \omega, v_{\tau}(s, \omega)\right)$. i.e., there is an absorbing time $T=T(D, \omega)>0$, for each $D \in \mathscr{D}, \omega \in \Omega^{\prime}$, and $t \geq T$ such that $v\left(t, \theta_{-t} \omega, D\left(\theta_{-t} \omega\right)\right) \subset \widetilde{K}(\omega)$. Furthermore, $K \in \mathscr{D}$.

Let

$$
\begin{equation*}
K(\omega)=\left\{u \in X_{\rho}:\|u\|^{2} \leq 2 R(\omega)+2(\varepsilon\|y(\omega)\|)^{2}\right\} \tag{69}
\end{equation*}
$$

Then $K(\omega)$ is an absorbing set for $\Phi\left(t, \omega, u_{\tau}(s)\right)$ because $\Phi\left(t, \omega, u_{\tau}(s)\right)=v\left(t, \omega, u_{\tau}(s)-\varepsilon y\left(\theta_{\tau} \omega\right)\right)+\varepsilon y\left(\theta_{t} \omega\right)$ and $K \in \mathscr{D}$. This completes the proof of the theorem.

In order to prove that the random dynamical system $\Phi\left(t, \omega, u_{\tau}(s, \omega)\right)$ is asymptotic compact, we require the following lemma.

Lemma 9. Let $K(\omega)$ be the absorbing set and $u_{\tau}(s, \omega) \in K(\omega)$ the initial data. Then for each $\eta>0$, there exist an absorbing time $T(\eta, \omega)>0$ and $N(\eta, \omega)>0$ such that for every $t \geq T(\eta, \omega)$, the solution of (1) meets

$$
\begin{equation*}
\sup _{-\rho \leq s \leq 0} \sum_{|i| \geq N}\left|u_{i}\left(s, \theta_{-t} \omega, u_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2} \leq \eta . \tag{70}
\end{equation*}
$$

Proof. Let $\xi(s)$ be a smooth cut-off function with

$$
\xi(s)= \begin{cases}0, & 0 \leq s \leq 1  \tag{71}\\ \xi(s), & 1 \leq s \leq 2 \\ 1, & s \geq 2\end{cases}
$$

where $0 \leq \xi(s) \leq 1, s \in \mathbb{R}^{+}$, and with a constant $C$ such that $\left|\xi^{\prime}(s)\right| \leq C$.

With $k \in \mathbb{Z}^{+}$, taking the inner product of (54) with the sequence $\left(\xi(|i| / k) v_{i}\right)_{i \in \mathbb{Z}}$, we obtain

$$
\begin{align*}
& \frac{1}{2} \frac{d}{d t} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}+v \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)(A v)_{i} v_{i} \\
& \quad+\lambda \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}=\sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) F_{i}\left(v_{i}+\varepsilon y_{i}\right) v_{i} \\
& \quad+\sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) f_{i}\left(v_{i}(t-\rho)+\varepsilon y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right) v_{i}  \tag{72}\\
& \quad+\sum_{i \in \mathbb{Z}} \theta\left(\frac{|i|}{k}\right) g_{i} v_{i}-v \varepsilon \sum_{i \in \mathbb{Z}} \theta\left(\frac{|i|}{k}\right)(A y)_{i} v_{i}
\end{align*}
$$

We now make the following estimate.

$$
\begin{align*}
& v \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)(A v)_{i} v_{i}=v \sum_{i \in \mathbb{Z}}\left(v_{i+1}-v_{i}\right) \\
& \quad \cdot\left[\left(\xi\left(\frac{|i+1|}{k}\right)-\xi\left(\frac{|i|}{k}\right)\right) v_{i+1}+\xi\left(\frac{|i|}{k}\right)\left(v_{i+1}-v_{i}\right)\right] \\
& =v \sum_{i \in \mathbb{Z}}\left(\xi\left(\frac{|i+1|}{k}\right)-\xi\left(\frac{|i|}{k}\right)\right)\left(v_{i+1}-v_{i}\right) v_{i+1} \\
& \quad+v \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(v_{i+1}-v_{i}\right)^{2} \\
& \quad \geq v \sum_{i \in \mathbb{Z}}\left(\xi\left(\frac{|i+1|}{k}\right)-\xi\left(\frac{|i|}{k}\right)\right)\left(v_{i+1}-v_{i}\right) v_{i+1} . \tag{73}
\end{align*}
$$

Using the property of the smooth cut-off function $\xi(s)$, we have

$$
\begin{align*}
& \left|\sum_{i \in \mathbb{Z}}\left(\xi\left(\frac{|i+1|}{k}\right)-\xi\left(\frac{|i|}{k}\right)\right)\left(v_{i+1}-v_{i}\right) v_{i+1}\right| \\
& \quad \leq \sum_{i \in \mathbb{Z}} \frac{\left|\xi^{\prime}\left(\varsigma_{i}\right)\right|}{k}\left|v_{i+1}-v_{i} \| v_{i+1}\right|  \tag{74}\\
& \quad \leq \frac{C}{k} \sum_{i \in \mathbb{Z}}\left(\left|v_{i+1}\right|^{2}+\left|v_{i}\right|\left|v_{i+1}\right|\right) \leq \frac{2 C}{k}\|v\|^{2},
\end{align*}
$$

which tells us that

$$
\begin{equation*}
v \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)(A v)_{i} v_{i} \geq \frac{-2 C v}{k}\|v\|^{2} \tag{75}
\end{equation*}
$$

It follows from the assumption $\left(A_{1}\right)$ and Young's inequality that

$$
\begin{align*}
\sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) F_{i}\left(v_{i}+\varepsilon y_{i}\right) v_{i}= & \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) F_{i}\left(v_{i}+\varepsilon y_{i}\right)\left(v_{i}+\varepsilon y_{i}\right) \\
& -\sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) F_{i}\left(v_{i}+\varepsilon y_{i}\right) \varepsilon y_{i} \\
\leq & \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(-\alpha_{1}\left|v_{i}+\varepsilon y_{i}\right|^{p}+\beta_{1, i}\right) \\
& +\varepsilon \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(\left(\alpha_{2}\left|v_{i}+\varepsilon y_{i}\right|^{p-1}+\beta_{2, i}\right)\left|y_{i}\right|\right) \\
\leq & C \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(1+\left|y_{i}\right|^{p}+\left|y_{i}\right|\right) \tag{76}
\end{align*}
$$

where $C$ is a positive constant depending on $\varepsilon, p, \alpha_{1}, \alpha_{2}, \sum_{i \in \mathbb{Z}} \beta_{1, i}, \sum_{i \in \mathbb{Z}} \beta_{2, i}, \xi(|i| / k)$ only.

By the assumption $\left(A_{2}\right)$ and Young's inequality, we get

$$
\begin{align*}
& \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) f_{i}\left(v_{i}(t-\rho)+\varepsilon y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right) v_{i} \\
& \leq \\
& \quad \frac{\lambda}{8} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}+\frac{4}{\lambda} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)  \tag{77}\\
& \quad \cdot C_{f}^{2}\left(\left|v_{i}(t-\rho)\right|^{2}+\left|\varepsilon y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right|^{2}\right)+\frac{2}{\lambda} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|\eta_{i}\right|^{2}
\end{align*}
$$

$\sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) g_{i} v_{i}=\sum_{|i| \geq k} \xi\left(\frac{|i|}{k}\right) g_{i} v_{i} \leq \frac{\lambda}{8} \sum_{|i| \geq k} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}+\frac{2}{\lambda} \sum_{|i| \geq k}\left|g_{i}\right|^{2}$.

By (72), (73), (75)-(78), we arrive at

$$
\begin{align*}
& \frac{1}{2} \frac{d}{d t} e^{9 t} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}+\left(\frac{3 \lambda}{4}-\frac{9}{2}\right) e^{9 t} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2} \\
& \leq e^{9 t}\left[\frac{2 C v}{k}\|v\|^{2}+C \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(1+\left|y_{i}\right|^{p}+\left|y_{i}\right|\right)\right. \\
& \quad+\frac{4}{\lambda} C_{f}^{2} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(t-\rho)\right|^{2}+\frac{4}{\lambda}\left(C_{f} \varepsilon\right)^{2} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{t-\rho} \omega_{i}\right)\right|^{2} \\
& \left.\quad+\frac{2}{\lambda} C_{\eta}+\frac{2}{\lambda} \sum_{|i| \geq k}\left|g_{i}\right|^{2}\right] \tag{79}
\end{align*}
$$

where $\sum_{i \in \mathbb{Z}} \xi(|i| / k)\left|\eta_{i}\right|^{2} \leq \sum_{i \in \mathbb{Z}}\left|\eta_{i}\right|^{2}=C_{\eta}$.
Integrating the above inequality from $T_{k}$ to $t$, we have

$$
\begin{align*}
e^{9 t} & \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2}+\left(\frac{3 \lambda}{2}-\vartheta\right) \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\right|^{2} d r \\
\leq & e^{9 T_{k}} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\left(T_{k}, \omega, v_{\tau}(s, \omega)\right)\right|^{2} \\
& +\frac{4 C v}{k} \int_{T_{k}}^{t} e^{9 r}\left\|v\left(r, \omega, v_{\tau}(s, \omega)\right)\right\|^{2} d r+2 C \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right) \\
& \cdot\left(1+\left|y_{i}\right|^{p}+\left|y_{i}\right|\right) d r+\frac{8}{\lambda} C_{f}^{2} \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r-\rho)\right|^{2} d r \\
& +\frac{8}{\lambda}\left(C_{f} \varepsilon\right)^{2} \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{r-\rho} \omega_{i}\right)\right|^{2} d r \\
& +\frac{4}{\lambda} \int_{T_{k}}^{t} e^{9 r}\left(C_{\eta}+\sum_{|i| \geq k}\left|g_{i}\right|^{2}\right) d r . \tag{80}
\end{align*}
$$

It's easy to know that
$\int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r-\rho)\right|^{2} d r \leq \int_{T_{k}-\rho}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r)\right|^{2} d r$
$=\int_{T_{k}-\rho}^{T_{k}} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r)\right|^{2} d r+\int_{T_{k}}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r)\right|^{2} d r$
$\leq C_{1}+\int_{T_{k}}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}(r)\right|^{2} d r$,
where $C_{1}=\rho \sum_{i \in \mathbb{Z}} \xi(|i| / k) \sup _{r \in\left[T_{k}-\rho, T_{k}\right]} e^{9(r+\rho)}\left|v_{i}(r)\right|^{2}$. And
$\int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{r-\rho} \omega_{i}\right)\right|^{2} d r \leq C_{2}+\int_{T_{k}}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{r} \omega_{i}\right)\right|^{2} d r$,
where $C_{2}=\rho \sum_{i \in \mathbb{Z}} \xi(|i| / k) \sup _{r \in\left[T_{k}-\rho, T_{k}\right]} e^{9(r+\rho)}\left|y_{i}\left(\theta_{r} \omega_{i}\right)\right|^{2}$.
Hence, from (80)-(82) and the assumption ( $A_{5}$ ), then multiplying both sides of it by $e^{-9 t}$, we get, for $t \geq T_{k}=T_{k}(\omega)>\tau$,

$$
\begin{align*}
& \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\left(t, \omega, v_{\tau}(s, \omega)\right)\right|^{2} \leq e^{9\left(T_{k}-t\right)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\left(T_{k}, \omega, v_{\tau}(s, \omega)\right)\right|^{2} \\
& \quad+\frac{4 C v}{k} e^{-9 t} \int_{T_{k}}^{t} e^{9 r}\left\|v\left(r, \omega, v_{\tau}(s, \omega)\right)\right\|^{2} d r \\
& \quad+2 C e^{-9 t} \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(1+\left|y_{i}\right|^{p}+\left|y_{i}\right|\right) d r \\
& \quad+\frac{8}{\lambda}\left(C_{f} \varepsilon\right)^{2} e^{-9 t} \int_{T_{k}}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\right|^{2} d r  \tag{83}\\
& \quad+\frac{4}{9 \lambda}\left(C_{\eta}+\sum_{|i| \geq k}\left|g_{i}\right|^{2}\right)\left(1-e^{9\left(T_{k}-t\right)}\right)+\left(C_{3}+C_{4}\right) e^{-9 t},
\end{align*}
$$

where $C_{3}=(8 / \lambda) C_{f}^{2} C_{1}, C_{4}=(8 / \lambda)\left(C_{f} \varepsilon\right)^{2} C_{2}$.
We replace $\omega$ by $\theta_{-t} \omega$, and estimate each term on the righthand side of the above inequality. With $t$ instead of $T_{k}$ in (65), we have

$$
\begin{align*}
& e^{9\left(T_{k}-t\right)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\left(T_{k}, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2} \\
& \quad \leq e^{9\left(T_{k}-t\right)}\left\|v\left(T_{k}, \tau-T_{k}, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right\|^{2} \\
& \quad \leq e^{9\left(T_{k}-t\right)}\left(\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\|^{2} e^{-\epsilon\left(T_{k}-\tau\right)}+\frac{2 C r(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)\right) . \tag{84}
\end{align*}
$$

As we know, $v_{\tau}\left(s, \theta_{-t} \omega\right) \in K\left(\theta_{-t} \omega\right)$, namely, $\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\| \leq R\left(\theta_{-t} \omega\right) \quad$ (tempered), so there exists a $T_{1}(\eta, \omega)>T_{k}(\omega)$, such that when $t>T_{1}$,

$$
\begin{equation*}
e^{\vartheta\left(T_{k}-t\right)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|v_{i}\left(T_{k}, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2} \leq \frac{1}{28} \eta . \tag{85}
\end{equation*}
$$

Also by (65), we estimate

$$
\begin{align*}
& \frac{4 C v}{k} e^{-9 t} \int_{T_{k}}^{t} e^{9 r}\left\|v\left(r, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right\|^{2} d r \\
& \leq \frac{4 C v}{k} e^{-9 t}\left[\frac{e^{\tau \epsilon}}{\vartheta-\epsilon}\left\|v_{\tau}\left(s, \theta_{-t} \omega\right)\right\|^{2}\left(e^{(9-\epsilon) t}-e^{(9-\epsilon) T_{k}}\right)\right. \\
& \left.\quad+\left(\frac{2 C r(\omega)}{\vartheta \epsilon}+\frac{2}{\lambda \vartheta \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)\right)\left(e^{9 t}-e^{9 T_{k}}\right)\right] \tag{86}
\end{align*}
$$

where $\mathcal{V}-\epsilon \neq 0$. Therefore there exist $T_{2}(\eta, \omega)>T_{k}(\omega)$ and $N_{1}(\eta, \omega)>0$, such that as $t>T_{2}, k>N_{1}$,

$$
\begin{equation*}
\frac{4 C v}{k} e^{-9 t} \int_{T_{k}}^{t} e^{9 r}\left\|v\left(r, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right\|^{2} d r \leq \frac{1}{28} \eta \tag{87}
\end{equation*}
$$

Using (66), for $k>N_{2}(\eta, \omega)>0$ we deduce

$$
\begin{align*}
& 2 C e^{-9 t} \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(1+\left|y_{i}\left(\theta_{-t} \omega\right)\right|^{p}+\left|y_{i}\left(\theta_{-t} \omega\right)\right|\right) d r \\
& \quad \leq \frac{2 C r(\omega)}{\vartheta} e^{-(\epsilon / 2) t}\left(1-e^{\vartheta\left(T_{k}-t\right)}\right), \tag{88}
\end{align*}
$$

so there is a $T_{3}(\eta, \omega)>T_{k}(\omega)$, such that as $t>T_{3}$,

$$
\begin{equation*}
2 C e^{-9 t} \int_{T_{k}}^{t} e^{9 r} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left(1+\left|y_{i}\left(\theta_{-t} \omega\right)\right|^{p}+\left|y_{i}\left(\theta_{-t} \omega\right)\right|\right) d r \leq \frac{1}{28} \eta . \tag{89}
\end{equation*}
$$

Applying (66), we also get

$$
\begin{align*}
\frac{8}{\lambda} & \left(C_{f} \varepsilon\right)^{2} e^{-9 t} \int_{T_{k}}^{t} e^{\vartheta(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{-t} \omega\right)\right|^{2} d r \\
& \leq \frac{8}{\lambda}\left(C_{f} \varepsilon\right)^{2} e^{-\vartheta t} \int_{T_{k}}^{t} e^{\vartheta(r+\rho)} r(\omega) e^{-(\epsilon / 2) t} d r  \tag{90}\\
& =\frac{8}{\vartheta \lambda}\left(C_{f} \varepsilon\right)^{2} r(\omega) e^{-9 t-(\epsilon / 2) t}\left(e^{\vartheta(t+\rho)}-e^{\vartheta\left(T_{k}+\rho\right)}\right) .
\end{align*}
$$

Thus there exists $T_{4}(\eta, \omega)>T_{k}(\omega)$, such that as $t>T_{4}$,

$$
\begin{equation*}
\frac{8}{\lambda}\left(C_{f} \varepsilon\right)^{2} e^{-9 t} \int_{T_{k}}^{t} e^{9(r+\rho)} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|y_{i}\left(\theta_{-t} \omega\right)\right|^{2} d r \leq \frac{1}{28} \eta . \tag{91}
\end{equation*}
$$

Since $g \in X$, there is $N_{3}(\eta, \omega)>0$, we obtain, for $k>N_{3}(\eta, \omega)>0$,

$$
\begin{equation*}
\frac{4}{\vartheta \lambda}\left(C_{\eta}+\sum_{|i| \geq k}\left|g_{i}\right|^{2}\right) \leq \frac{1}{28} \eta . \tag{92}
\end{equation*}
$$

By the same argument, we have $T_{5}(\eta, \omega)>T_{k}(\omega)$, when $t>T_{5}$, satisfying

$$
\begin{equation*}
\left|-\frac{4}{\vartheta \lambda}\left(C_{\eta}+\sum_{|i| \geq k}\left|g_{i}\right|^{2}\right) e^{9\left(T_{k}-t\right)}\right| \leq \frac{1}{28} \eta . \tag{93}
\end{equation*}
$$

Obviously, there is a $T_{6}(\eta, \omega)>T_{k}(\omega)$, when $t>T_{6}$, fulfilling

$$
\begin{equation*}
\left(C_{3}+C_{4}\right) e^{-9 t} \leq \frac{1}{28} \eta . \tag{94}
\end{equation*}
$$

Take $T(\eta, \omega)=\max \left\{T_{1}, T_{2}, T_{3}, T_{4}, T_{5}, T_{6}\right\}<T_{k}(\omega), N(\eta, \omega)=$ $\max \left\{N_{1}, N_{2}, N_{3}\right\}<0$. We collect (83)-(94) to yield, for every $t>T, k>N$,

$$
\begin{align*}
& \sup _{-\rho \leq s \leq 0} \sum_{|i| \geq 2 k}\left|u_{i}\left(s, \theta_{-t} \omega, u_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2} \\
& \quad \leq \sup _{-\rho \leq s \leq 0} \sum_{i \in \mathbb{Z}} \xi\left(\frac{|i|}{k}\right)\left|u_{i}\left(s, \theta_{-t} \omega, u_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2} \\
& \quad \leq 2 \sup _{-\rho \leq s \leq 0} \sum_{|i| \geq N}\left(\left|v_{i}\left(s, \theta_{-t} \omega, v_{\tau}\left(s, \theta_{-t} \omega\right)\right)\right|^{2}+\varepsilon^{2}\left|y_{i}\left(\theta_{-t} \omega\right)\right|^{2}\right) \leq \eta, \tag{95}
\end{align*}
$$

which concludes the proof.
With the same method like the proof of the Theorem 11 in [8], we can obtain the asymptotic compactness of the continuous RDS $\Phi$.

Theorem 10. $\Phi$ is asymptotically compact for all $\omega \in \Omega^{\prime}$ : each sequence $q_{n} \in \Phi\left(t_{n}, \theta_{-t_{n}} \omega, K\left(\tau, \theta_{-t_{n}} \omega\right)\right)$ has a convergent subsequence in $X_{\rho}$ as $t_{n} \rightarrow \infty$.

We are now in a position to present our main result about the existence of $\mathscr{D}$-pullback attractor.

Theorem 11. Suppose that assumptions $\left(A_{1}\right)-\left(A_{6}\right)$ hold. Then the continuous RDS $\Phi$ associated with problems (1) and (2) has a unique $\mathscr{D}$-pullback attractor, which is characterized by, for each $\omega \in \Omega$,

$$
\begin{equation*}
\mathcal{A}(\omega)=\bigcap_{\kappa \geq t_{K}(\omega)} \overline{\bigcup_{t \geq \kappa} \Phi\left(t, \theta_{-t} \omega, K\left(\theta_{-t} \omega\right)\right)} . \tag{96}
\end{equation*}
$$

Proof. Note that the existence, uniqueness and characterization of the $\mathscr{D}$-pullback attractor of $\Phi$ follows from Proposition 5 immediately, based on Theorem 8. Lemma 9. and Theorem 10.

## 5. Ergodicity of the Systems

We discuss the ergodicity of the systems in this section.
There exists at least an invariant measure for the random dynamical system $\Phi\left(t, \omega, u_{\tau}(s, \omega)\right)$ induced by (23) and (24) (see [10]). The Markov semigroup $\left\{P_{t}\right\}_{t \geq 0}$ associated with them is denoted by
$P_{t} \varphi(x)=\mathbb{E}(\varphi(u(t, 0, x))), \quad t \geq 0 \quad x \in X_{\rho} \quad \varphi \in \mathscr{C}_{X_{\rho}}$,
where $\mathscr{C}_{X_{\rho}}$ is a space of bounded and uniformly continuous function on $X_{\rho}$.

The related transition probability $P_{t}(x, \cdot)$ is
$P_{t}(x, \Gamma)=\mathscr{L}(u(t, 0, x))(\Gamma), \quad t \geq 0 \quad x \in X_{\rho} \quad \Gamma \in \mathscr{B}_{X_{\rho}}$,
where $\mathscr{L}(\cdot)$ is a Banach algebra of all linear bounded operators from $X_{\rho}$ to $X_{\rho}$, and $\mathscr{B}_{X_{\rho}}$ is a $\sigma$-field of all Borel subsets of $X_{\rho}$.

Now we prove equation (23) is ergodic, i.e., the invariant measure is unique.

Assume $u\left(t, \varrho, u_{\varrho}\right), \varrho \in \mathbb{R}, t>\varrho$ to be a mild solution of equation

$$
\begin{equation*}
\frac{d u}{d t}+v A u+\lambda u=F(u)+f\left(u_{t}\right)+g+\varepsilon \frac{d W}{d t} \tag{99}
\end{equation*}
$$

with the initial conditions

$$
\begin{equation*}
u_{\varrho}=u(\varrho+s), \quad s \in[-\varrho, 0] . \tag{100}
\end{equation*}
$$

Suppose $\{S(t)\}_{t \geq \varrho}$ is a semigroup formed by $-v A-\lambda$, from Theorem 6, we have

$$
\begin{align*}
u\left(t, \varrho, u_{\varrho}\right)= & S(t-\varrho) u_{\varrho}-\int_{\varrho}^{t} S(t-h)\left(F(u)+f\left(u_{t}\right)\right) d h \\
& +\varepsilon \int_{\varrho}^{t} S(t-h) d W(h) \tag{101}
\end{align*}
$$

Put $\quad \zeta(t)=\varepsilon \int_{\varrho}^{t} S(t-h) d W(h) \quad$ and $\quad z(t)=u\left(t, \varrho, u_{\varrho}\right)-$ $\varepsilon \int_{\varrho}^{t} S(t-h) d W(h)$. Then $z(t)$ is a mild solution of

$$
\begin{equation*}
\frac{d z}{d t}=-(v A+\lambda) z(t)+F(z(t))+f\left(z_{t}\right)+g \tag{102}
\end{equation*}
$$

Theorem 12. The system (23) and (24) is ergodic.

Proof. We need to prove that there is a unique invariant measure $\mu$ for Markov semigroup $\left\{P_{t}\right\}_{t \geq 0}$. By the same discussion with a little change like (67), we get.

$$
\begin{equation*}
\|z(t)\| \leq\left\|z_{\tau}\right\| e^{(\epsilon / 2)(\varrho-t)}+\sqrt{\frac{2 C r(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)} . \tag{103}
\end{equation*}
$$

We know $\sup _{t \geq \rho} \mathbb{E}\|\zeta(t)\|<+\infty$, then

$$
\begin{align*}
\mathbb{E}\|u(t)\| & \leq \mathbb{E}\|z(t)\|+\sup _{t \geq \varrho} \mathbb{E}\|\zeta(t)\| \leq\left\|z_{\tau}\right\| e^{(\epsilon / 2)(\varrho-t)} \\
& +\sup _{t \geq \varrho} \mathbb{E}\|\zeta(t)\|+\sqrt{\frac{2 C r(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)} . \tag{104}
\end{align*}
$$

Let $t \geq 2 \varrho, s \in[-\varrho, 0]$, then $t+s \geq \varrho$ and
$\mathbb{E}\left\|u_{t}\right\| \leq\left\|z_{\tau}\right\| e^{(\epsilon / 2)(\rho-t)}+\sup _{t \geq e} \mathbb{E}\|\zeta(t)\|+\sqrt{\frac{2 \operatorname{Cr}(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)}$.
So, for arbitrary $u_{\varrho, 1}, u_{\varrho, 2} \in X_{\rho}, t+s \geq \varrho$, we induce

$$
\begin{equation*}
\left\|u\left(t+s, \varrho, u_{\varrho, 1}\right)-u\left(t+s, \varrho, u_{\rho, 2}\right)\right\| \leq\left\|u_{\varrho, 1}-u_{\varrho, 2}\right\| e^{(\epsilon / 2)(\varrho-t)} . \tag{106}
\end{equation*}
$$

For $\varrho_{0} \in \mathbb{R}$ and $\varrho_{0} \leq \varrho<2 \varrho \leq t$, we obtain

$$
\begin{align*}
& \mathbb{E}\left\|u\left(t+s, \varrho, u_{e}\right)-u\left(t+s, \varrho_{0}, u_{\varrho}\right)\right\| \leq \mathbb{E}\left\|u_{\varrho}-u\left(\varrho, \varrho_{0}, u_{\varrho}\right)\right\| e^{(\epsilon / 2)(\varrho-t)} \\
& \quad \leq 2\left(\left\|z_{\tau}\right\|+\sup _{t \geq e} \mathbb{E}\|\zeta(t)\|+\sqrt{\frac{2 C r(\omega)}{\epsilon}+\frac{2}{\lambda \epsilon}\left(C_{\eta}+2\|g\|^{2}\right)}\right) e^{(\epsilon / 2)(\varrho-t)} . \tag{107}
\end{align*}
$$

Hence, we know there is a random variable $\omega$ such that

$$
\begin{equation*}
\lim _{\varrho \rightarrow-\infty} \mathbb{E}\left\|u\left(0, \varrho, u_{\varrho}\right)-\omega\right\|=0 \tag{108}
\end{equation*}
$$

For arbitrary $u_{e} \in X_{\rho}$, we are led to

$$
\begin{equation*}
P_{t}\left(u_{\varrho}, \cdot\right)=\mathscr{L}\left(u\left(t, u_{\varrho}\right)\right)=\mathscr{L}\left(u\left(0,-t, u_{\varrho}\right)\right) \rightarrow \mu \tag{109}
\end{equation*}
$$

This tells us that, the law $\mu=\mathscr{L}(\omega)$ is the unique invariant measure for Markov semigroup $\left\{P_{t}\right\}_{t \geq 0}$. This accomplishes the proof.

## Data Availability

No data were used to support this study.

## Conflicts of Interest

The authors declare that they have no conflicts of interest.

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