Research Article

Statistical Inference for the Heteroscedastic Partially Linear Varying-Coefficient Errors-in-Variables Model with Missing Censoring Indicators

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In this paper, we focus on heteroscedastic partially linear varying-coefficient errors-in-variables models under right-censored data with censoring indicators missing at random. Based on regression calibration, imputation, and inverse probability weighted methods, we define a class of modified profile least square estimators of the parameter and local linear estimators of the coefficient function, which are applied to constructing estimators of the error variance function. In order to improve the estimation accuracy and take into account the heteroscedastic error, reweighted estimators of the parameter and coefficient function are developed. At the same time, we apply the empirical likelihood method to construct confidence regions and maximum empirical likelihood estimators of the parameter. Under appropriate assumptions, the asymptotic normality of the proposed estimators is studied. The strong uniform convergence rate for the estimators of the error variance function is considered. Also, the asymptotic chi-squared distribution of the empirical log-likelihood ratio statistics is proved. A simulation study is conducted to evaluate the finite sample performance of the proposed estimators. Meanwhile, one real data example is provided to illustrate our methods.

1. Introduction

In regression analysis, for a long period of time, the flexible and refined statistical regression models are widely applied in theoretical study and practical application. The main results related to parameter regression models and non-parameter regression models are rather mature. Recently, semiparameter regression models can reduce the high risk of misspecification related to parameter regression models and avoid the "curse of dimensionality" for nonparametric regression models. Thanks to their advantage, semiparametric regression models enjoy consideration attention from statisticians. Semiparametric regression models have various forms. Specially, partially linear varying-coefficient errors-in-variables (PLVCEV) model, as a typical example, was introduced by You and Chen [1] and has the following form:

\[
\begin{align*}
V & = X^T \beta + Z^T \alpha(U) + \epsilon, \\
\xi & = X + e,
\end{align*}
\]

(1)

where \( V \) is the response variable, \( X \in \mathbb{R}^p, Z \in \mathbb{R}^q \) are the covariates, \( \beta = (\beta_1, \ldots, \beta_p)^T \) is a vector of \( p \)-dimensional unknown parameter, \( \alpha(\cdot) = (\alpha_1(\cdot), \ldots, \alpha_q(\cdot))^T \) is an unknown \( q \)-dimensional vector of coefficient function, and \( \epsilon \) is the random error. The measurement error \( e \) is independent of \( (X, Z, U) \) with mean zero and covariance matrix \( \Sigma_e \). In order to identify the model, \( \Sigma_e \) is assumed to be known.
As one general and flexible semiparametric model, model (1) includes a variety of models of interest. When \( X \) is observed exactly, model (1) boils down to be PLVC model [2, 3]. When \( Z = 1, q = 1 \) and \( X \) is observed exactly, model (1) reduces to partially linear regression model [4]. When \( X \) is observed exactly, and \( \alpha(\cdot) \) is a constant vector, model (1) becomes a linear regression model. When \( q = 1 \) and \( Z=1 \), model (1) reduces to partially linear EV model [5]. For model (1), You and Chen [1] proposed estimators of parametric and nonparametric components and showed their asymptotic properties. Liu and Liang [6] constructed the asymptotical normality of jackknife estimator for error variance and standard chi-square distribution of jackknife empirical log-likelihood statistic. Fan et al. [7] established penalized profile least squares estimation of parameter and nonparameter in the model.

The literature mentioned above assumed that the random errors are homoscedastic, which means that the random error \( \varepsilon \) is independent of \( (X, Z, U) \). However, in many practical application fields, the error variance function may change with the variables. Heteroscedastic error models have attracted much attention of many scholars. For example, You et al. [8] considered the estimation of parametric and nonparametric parts for partially linear regression models with heteroscedastic errors. Fan et al. [9] constructed confidence regions of parameter for heteroscedastic PLCEV model based on empirical likelihood method. Shen et al. [10] discussed estimation and inference for PLVC model with heteroscedastic errors. Xu and Duan [11] extended the results of Shen et al. [10] to efficient estimation for PLVC model with heteroscedastic errors.

The above related works assumed that the responses are observed completely. However, in many practical fields, especially in biomedical studies and survival analysis, the response cannot be completely observed due to censored variables. Huang and Huang [12, 13] discussed the constructed confidence regions of the parameters for varying-coefficient single-index model and partially linear single-index EV model by empirical likelihood method under censored data, respectively. The aforementioned results require that the censoring indicators be always observed. However, the censoring indicators may not be observed completely. For example, the death of individual is attributable to the cause of interest that may require information completely. For example, the death of individual is attributable to the cause of interest that may require information completely. However, the censoring indicators may not be observed completely. For example, the death of individual is attributable to the cause of interest that may require information completely. However, in many practical fields, especially in biomedical studies and survival analysis, the response cannot be completely observed due to censored variables. Huang and Huang [12, 13] discussed the constructed confidence regions of the parameters for varying-coefficient single-index model and partially linear single-index EV model by empirical likelihood method under censored data, respectively. The aforementioned results require that the censoring indicators be always observed. However, the censoring indicators may not be observed completely. For example, the death of individual is attributable to the cause of interest that may require information completely. However, the censoring indicators may not be observed completely. For example, the death of individual is attributable to the cause of interest that may require information completely. However, in many practical fields, especially in biomedical studies and survival analysis, the response cannot be completely observed due to censored variables. In this paper, we assume that the censoring indicators are missing at random (MAR), which is common and reasonable in statistical analysis with missing data [15]. There are a lot of works related to missing censoring indicators. For example, Wang and Dinse [16] and Li and Wang [17] proposed weighted least square estimators of unknown parameter and proved their asymptotical normality for linear regression model. Shen and Liang [18] discussed the estimation and variable selection for PLVC quantile regression model. Wang et al. [19] considered composite quantile regression for linear regression model. However, there is no literature focusing on the estimation and confidence regions of heteroscedastic errors model with right-censored data when the censoring indicators are MAR.

In this paper, we consider modified profile least square (PLS) estimators of the unknown parameter and local linear estimators of the coefficient function. Besides the point estimation, we are also interested in interval estimation in terms of empirical likelihood (EL) method, which, first introduced by Owen [20], is a very effective method for constructing confidence regions, which enjoys a lot of nice properties over the normal approximation-based methods and bootstrap approach. Thanks to its advantage, there are a lot of literature-related EL methods to refer to. For instance, Fan et al. [21] considered penalized EL for high-dimensional PLCEV model. Wang and Drton [22] established estimation for linear structural equation models with dependent errors based on EL method. Fan et al. [23] discussed weighted EL for heteroscedastic varying-coefficient partially nonlinear model with missing data. Zou et al. [24] considered EL inference for partially linear single-index EV model with missing censoring indicators.

It is worth pointing out that it is innovative and interesting in studying the PLVC model with heteroscedastic errors under censoring indicators MAR. Thus, we consider estimation and confidence regions based on modified profiled LS method and EL inference, respectively. The main aims of this paper include the following aspects: (1) define a class of modified PLS estimators of the parameter and local linear estimators of coefficient function based on regression calibration, imputation, and inverse probability weighted approaches, and prove the asymptotical normality of the proposed estimators; (2) construct reweighted estimators of the parameter and coefficient function based on estimators of the error variance function, and establish the asymptotic properties of the proposed estimators; (3) develop the asymptotic standard chi-squared distribution of the empirical log-likelihood ratio functions, construct the confidence regions for the parameter, and propose the asymptotic distribution of the corresponding maximum EL estimators. Finally, a simulation study and a real data analysis are conducted to demonstrate the finite sample performance of the proposed procedures.

The rest of this paper is organized as follows. In Section 2, we construct modified PLE estimators of the parameter and local linear estimators of the coefficient function. In Section 3, we proposed empirical log-likelihood ratio statistics and maximum EL estimators. The main results are shown in Section 4. Section 5 presents simulation and real data analysis. In Section 6, we show some conclusions. The proofs of the main results are shown in Appendix.

2. Methodology

Suppose that \( \{V_i, X_i, Z_i, U_i\}, i = 1, \ldots, n \) is a sample from model (1), that is,

\[
\begin{align*}
V_i & = X_i^\top \beta + Z_i^\top \alpha(U_i) + \varepsilon_i, \\
\xi_i & = X_i + \varepsilon_i,
\end{align*}
\]

where the model error \( \varepsilon_i \) satisfies \( E(\varepsilon_i|X_i, Z_i, U_i) = 0 \) and \( \text{Var}(\varepsilon_i|X_i, Z_i, U_i) = \sigma^2(U_i) \), which is an unknown function of \( U_i \) representing heteroscedastic error. In the practical
Following Wang and Dinse [16], the estimator \( T_m \) assume that curse of dimensionality. Hence, throughout this paper, we high-dimensional, nonparametric estimation may cause "the method to estimate \( m \) unknown. One can use parametric and nonparametric

.. math::

   P(\delta_i = 1|Y_i, X_i, Z_i, U_i, \varsigma_i) = P(\delta_i = 1|Y_i, X_i, Z_i, U_i) = m(T_i).

(3)

.. math::

   \alpha_j(u) = \alpha_j(u_0) + \alpha'_j(u_0)(u - u_0),  \quad j = 1, \ldots, q, \quad (4)

where \( \alpha'_j(u) = \frac{\partial \alpha_j(u)}{\partial u} \). Then, \( (a_j, b_j) \) can be estimated by minimizing the following objective function:

.. math::

   \sum_{i=1}^{n} \frac{\delta_i}{1 - G(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{m} [a_j + b_j(U_i - u_0)]Z_{ij} \right)^2 K\left( \frac{U_i - u}{h_{1n}} \right),

(5)

where \( K(\cdot) \) is a kernel function, and \( 0 < h_{1n} \longrightarrow 0 \) is a bandwidth sequence. Due to the missing indicators, some \( \delta_i \) cannot be observed. Therefore, model (2) cannot be applied directly. One can replace \( \delta_i \) with its conditional expectation \( m(T_i) = E[\delta_i|T_i] \). Thus, \( (a_j, b_j) \) can be defined as the minimizer of

.. math::

   \sum_{i=1}^{n} m(T_i, \theta) \delta_i \left( 1 - m(T_i, \theta) \right)^{\xi(1-\delta_i)}.

(7)

Let \( \delta_i = m(T_i, \theta) \). Since \( E[\delta_i] = E[m(T_i, \theta)] = E[E \delta_i|T_i] = E[\delta_i] \), we replace \( \delta_i \) with its estimator \( \hat{\delta}_i = m(T_i, \hat{\theta}_n) \). Hence, \( (a_j, b_j) \) can be estimated by minimizing the following objective function:

.. math::

   \sum_{i=1}^{n} \frac{\hat{\delta}_i}{1 - \hat{G}_n(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{m} [a_j + b_j(U_i - u_0)]Z_{ij} \right)^2 K\left( \frac{U_i - u}{h_{1n}} \right),

(8)

where \( \hat{G}_n(Y_i) \) is the estimator of \( G(\cdot) \), which is defined by

2.1. Modified Profile Least Squares Estimation. The local linear regression technique is employed to estimate the coefficient function \( \alpha(\cdot) \). If \( \alpha(\cdot) \) has twice continuous derivative at point \( u_0 \), for \( u \) in a small neighborhood of \( u_0 \), one can approximate \( \alpha(\cdot) \) by the following expansion with Taylor expansion:

.. math::

   \alpha_{j}(u) = a_{j}(u_0) + b_{j}(u_0)(u - u_0),  \quad j = 1, \ldots, q, \quad (4)

where \( a_{j}(u) = \frac{\partial \alpha_{j}(u)}{\partial u} \). Then, \( (a_{j}, b_{j}) \) can be estimated by minimizing the following objective function:

.. math::

   \sum_{i=1}^{n} \frac{\delta_i}{1 - G(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{m} [a_j + b_j(U_i - u_0)]Z_{ij} \right)^2 K\left( \frac{U_i - u}{h_{1n}} \right),

(5)

where \( K(\cdot) \) is a kernel function, and \( 0 < h_{1n} \longrightarrow 0 \) is a bandwidth sequence. Due to the missing indicators, some \( \delta_i \) cannot be observed. Therefore, model (2) cannot be applied directly. One can replace \( \delta_i \) with its conditional expectation \( m(T_i) = E[\delta_i|T_i] \). Thus, \( (a_{j}, b_{j}) \) can be defined as the minimizer of

.. math::

   \sum_{i=1}^{n} m(T_i, \theta) \delta_i \left( 1 - m(T_i, \theta) \right)^{\xi(1-\delta_i)}.

(7)

Let \( \delta_i = m(T_i, \theta) \). Since \( E[\delta_i] = E[m(T_i, \theta)] = E[E \delta_i|T_i] = E[\delta_i] \), we replace \( \delta_i \) with its estimator \( \hat{\delta}_i = m(T_i, \hat{\theta}_n) \). Hence, \( (a_{j}, b_{j}) \) can be estimated by minimizing the following objective function:

.. math::

   \sum_{i=1}^{n} \frac{\hat{\delta}_i}{1 - \hat{G}_n(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{m} [a_j + b_j(U_i - u_0)]Z_{ij} \right)^2 K\left( \frac{U_i - u}{h_{1n}} \right),

(8)

where \( \hat{G}_n(Y_i) \) is the estimator of \( G(\cdot) \), which is defined by
\[ \tilde{G}_n(y) = 1 - \prod_{i : Y_i \leq y} \left( \frac{n - R_i}{n - R_i + 1} \right)^{1 - \tilde{p}_n(y)}, \]

\[ R_i = \sum_{j=1}^{n} I(Y_j \leq Y_i), \]  

(9)

\[ \tilde{p}_n(y) = \frac{\sum_{i=1}^{n} \delta_i \xi \mathcal{L}((y - Y_i)/(a_n))}{\sum_{i=1}^{n} \delta_i \xi \mathcal{L}((y - Y_i)/(a_n))}, \]

which is the Nadaraya–Watson estimator of \( \mu(y) = E[\delta_i | Y_i = y] \) with the kernel function \( \mathcal{L}(\cdot) \) and bandwidth sequence \( 0 < a_n \rightarrow 0. \)

For notational simplicity, let \( Y = (Y_1, \ldots, Y_n)^T, X = (X_1, \ldots, X_n)^T, Z = (Z_1, \ldots, Z_n)^T, \)

\[
\begin{align*}
D_u &= \begin{pmatrix} U_1 I \cdots U_n I \end{pmatrix}, \\
M &= \begin{pmatrix} Z_1^\top \alpha(U_1) \\
& \vdots \\
& Z_n^\top \alpha(U_n) 
\end{pmatrix}, \\
\bar{Y}_1 &= Y_1 - S_i X, \\
\bar{X}_i &= X_i - S_i X, \\
\bar{\xi}_i &= \xi_i - S_i \xi, \\
\bar{\xi} &= (\bar{\xi}_1, \ldots, \bar{\xi}_n).
\end{align*}
\]

(10)

\[ \bar{\delta}_c = \left\{ \sum_{i=1}^{n} \frac{\bar{\delta}_i}{1 - \tilde{G}_n(Y_i)} \left( \bar{\xi}_i \bar{\xi}_i - \Sigma_x \right) \right\}^{-1} \sum_{i=1}^{n} \frac{\bar{\delta}_i}{1 - \tilde{G}_n(Y_i)} \bar{\xi}_i \bar{Y}_i. \]  

(12)

Then, the local linear regression estimator of \( \alpha(u) \) is defined as follows:

\[ \bar{\alpha}_c(u) = \left( \begin{pmatrix} \bar{\alpha}_c(u) \end{pmatrix} \right) \left( \begin{pmatrix} D_u^\top \bar{\Delta}_u D_u \end{pmatrix} \right)^{-1} D_u^\top \bar{\Delta}_u \omega_u (Y - \bar{\xi} \bar{\delta}_c). \]  

(13)

Let \( \bar{\delta}_m = \xi \delta_i + (1 - \xi) m(T_i, \theta) \). Since \( E[\delta^{m}_i] = E[\xi \delta_i + (1 - \xi) m(T_i, \theta)] = \bar{\delta}_i \) under the missing mechanism, we can impute \( \delta_i \) with \( \bar{\delta}_m = \xi \delta_i + (1 - \xi) m(T_i, \theta) \) in expression (6). Hence, \( (a_j, b_j) \) can be estimated by minimizing the following objective function:

\[
\sum_{i=1}^{n} \frac{1}{1 - \tilde{G}_n(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{n} [a_j + b_j (U_i - u_0)] Z_{ij} \right)^2 K \left( \frac{U_i - u}{h_{1n}} \right). 
\]  

(14)

If \( \beta \) is known, one can obtain the local linear estimator of coefficient function by

\[ \bar{\alpha}_m(u) = \left( \begin{pmatrix} \bar{\alpha}_m(u) \end{pmatrix} \right) \left( \begin{pmatrix} D_u^\top \bar{\Delta}_m D_u \end{pmatrix} \right)^{-1} D_u^\top \bar{\Delta}_m \omega_u (Y - \bar{\xi} \bar{\delta}_m). \]  

(15)

where \( \bar{\Delta}_m = \text{diag} \left( \delta^{m}_1 / (1 - \bar{\xi} \bar{\delta}_m(Y_1)), \ldots, \delta^{m}_n / (1 - \bar{\xi} \bar{\delta}_m(Y_n)) \right) \). Substituting (21) into the original model and eliminating bias produced by the measurement error, hence, we obtain the following modified PLS estimator of \( \bar{\beta} \) based on imputation method:

\[ \bar{\beta}_m = \left\{ \sum_{i=1}^{n} \frac{\bar{\delta}_i}{1 - \tilde{G}_n(Y_i)} \left( \bar{\xi}_i \bar{\xi}_i - \Sigma_x \right) \right\}^{-1} \sum_{i=1}^{n} \frac{\bar{\delta}_i}{1 - \tilde{G}_n(Y_i)} \bar{\xi}_i \bar{Y}_i. \]  

(16)

Thus, the local linear regression estimator of \( \alpha(\cdot) \) is defined as follows:

\[ \bar{\alpha}_m(u) = \left( \begin{pmatrix} \bar{\alpha}_m(u) \end{pmatrix} \right) \left( \begin{pmatrix} D_u^\top \bar{\Delta}_m D_u \end{pmatrix} \right)^{-1} D_u^\top \bar{\Delta}_m \omega_u (Y - \bar{\xi} \bar{\delta}_m). \]  

(17)

Let \( \bar{\delta}_m = (\xi \delta_i / \pi(Y_i)) + (1 - (\xi / \pi(Y_i))) m(T_i, \theta) \). Note that

\[ E[\delta^{m}_i] = E[(\xi \delta_i / \pi(Y_i)) + (1 - (\xi / \pi(Y_i))) m(T_i, \theta)] \] under MAR assumption. Hence, we substitute \( \delta_i \) with \( \bar{\delta}_m = (\xi \delta_i / \pi(Y_i)) + (1 - (\xi / \pi(Y_i))) m(T_i, \theta) \), where \( \pi(Y) = \sum_{i=1}^{n} \xi \Omega((y - Y_i)/b_n) / \sum_{i=1}^{n} \Omega ((y - Y_i)/b_n) \) is a nonparametric estimator of \( \pi(y) = E[\xi | Y = y] \) with kernel function \( \Omega(\cdot) \) and bandwidth sequence \( 0 < b_n \rightarrow 0. \) Hence, \( (a_j, b_j) \) can be estimated by minimizing the following objective function:

\[
\sum_{i=1}^{n} \frac{1}{1 - \tilde{G}_n(Y_i)} \left( Y_i - X_i^\top \beta - \sum_{j=1}^{n} [a_j + b_j (U_i - u_0)] Z_{ij} \right)^2 K \left( \frac{U_i - u}{h_{1n}} \right). 
\]  

(18)

If \( \beta \) is known, one can obtain the local linear estimator of coefficient function by

\[ \bar{\alpha}_m(u) = \left( \begin{pmatrix} \bar{\alpha}_m(u) \end{pmatrix} \right) \left( \begin{pmatrix} D_u^\top \bar{\Delta}_m D_u \end{pmatrix} \right)^{-1} D_u^\top \bar{\Delta}_m \omega_u (Y - \bar{\xi} \bar{\delta}_m), \]  

(19)
where \( \tilde{\Delta}_w = \text{diag}(\tilde{\sigma}_1/(1 - \tilde{G}_n(Y_1)), \ldots, \tilde{\sigma}_n/(1 - \tilde{G}_n(Y_n))) \).

Substituting (19) into the original model and eliminating bias produced by the measurement error. Hence, we can get the following modified PLS estimator of \( \beta \) based on inverse probability weighted method:

\[
\tilde{\beta}_w = \left\{ \sum_{i=1}^{n} \frac{\tilde{\delta}_i^{w}}{1 - \tilde{G}_n(Y_i)} \left( \tilde{\xi}_i^{+} - \xi_i \right) \right\}^{-1} \sum_{i=1}^{n} \frac{\tilde{\delta}_i^{w}}{1 - \tilde{G}_n(Y_i)} \tilde{\xi}_i Y_i.
\]

Hence, the local linear regression estimator of \( \alpha(\cdot) \) is defined as follows:

\[
\sum_{i=1}^{n} \frac{\tilde{\delta}_i^{c}}{1 - \tilde{G}_n(Y_i)} \left\{ \left( Y_i - \xi_i^{c} \tilde{\beta}_c - Z_i^{c} \tilde{\alpha}_c(U_i) \right)^2 - \tilde{\beta}_c^{+} \Sigma_c \tilde{\beta}_c \right\} - \mu_1 - v_1 (U_i - u) \right\} K \left( \frac{U_i - u}{h_{2n}} \right),
\]

the local linear regression estimator of \( \sigma^2(u) \) based on regression calibration method is defined by

\[
\tilde{\sigma}_c(u) = \sum_{i=1}^{n} W^c_{ni} \left\{ \left[ Y_i - \xi_i^{c} \tilde{\beta}_c - Z_i^{c} \tilde{\alpha}_c(U_i) \right]^2 - \tilde{\beta}_c^{+} \Sigma_c \tilde{\beta}_c \right\},
\]

where the weight function \( W^c_{ni}(\cdot) \) is defined by

\[
W^c_{ni}(u) = \frac{(nh_{2n})^{-1} \left\{ \frac{\tilde{\delta}_i^{c}}{1 - \tilde{G}_n(Y_i)} \right\} K \left( \frac{(U_i - u)/h_{2n}) \right) \left\{ A^c_{n1}(u) - (U_i - u) A^c_{n1}(u) \right\}^2}{A^c_{n1}(u) A^c_{n2}(u) - \left[ A^c_{n1}(u) \right]^2},
\]

with

\[
A^c_{nj} = \frac{1}{nh_{2n}} \sum_{i=1}^{n} \frac{\tilde{\delta}_i^{c}}{1 - \tilde{G}_n(Y_i)} K \left( \frac{U_i - u}{h_{2n}} \right), \quad \text{for } j = 0, 1, 2.
\]

By minimizing the following object function with respect to \( \mu_2 \),

\[
\sum_{i=1}^{n} \frac{\tilde{\delta}_i^{m}}{1 - \tilde{G}_n(Y_i)} \left\{ \left( Y_i - \xi_i^{m} \tilde{\beta}_m - Z_i^{m} \tilde{\alpha}_m(U_i) \right)^2 - \tilde{\beta}_m^{+} \Sigma_m \tilde{\beta}_m \right\} - \mu_2 - v_2 (U_i - u) \right\} K \left( \frac{U_i - u}{h_{2n}} \right),
\]

the local linear regression estimator of \( \sigma^2_m(u) \) based on imputation method is defined by

\[
\tilde{\sigma}_m(u) = \sum_{i=1}^{n} W^m_{ni} \left\{ \left[ Y_i - \xi_i^{m} \tilde{\beta}_m - Z_i^{m} \tilde{\alpha}_m(U_i) \right]^2 - \tilde{\beta}_m^{+} \Sigma_m \tilde{\beta}_m \right\},
\]

2.2. Estimation for Error Variance. In order to improve the estimation of parametric and nonparametric parts, we construct local linear estimators of the error variance function \( \sigma^2(\cdot) \) in this subsection. Note that

\[
\sigma^2(u) = E \left\{ \frac{\tilde{\delta}_i^{m}}{1 - G(Y_i)} \left[ (Y_i - \xi_i^{m} \tilde{\beta} - Z_i \alpha(U_i))^2 - \tilde{\beta}^{+} \Sigma_e \tilde{\beta} \right] \right\}.
\]
where the weight function $W^w_m(\cdot)$ is defined by

\[
W^w_m(u) = \frac{(nh_{2n})^{-1}(\delta_i^w/(1 - \hat{G}_n(Y_i)))K((U_i - u)/h_{2n}) (A^w_{12}(u) - (U_i - u)A^w_{11}(u))}{A^w_{11}(u)A^w_{22}(u) - [A^w_{12}(u)]^2},
\]

with

\[
A^w_{ij} = \frac{1}{nh_{2n}} \sum_{i=1}^n \frac{\delta_i^w}{1 - G_n(Y_i)} K\left(\frac{U_i - u}{h_{2n}}\right)(U_i - u)^j, \quad \text{for } j = 0, 1, 2.
\]

Note that

\[
\sum_{i=1}^n \frac{\delta_i^w}{1 - G_n(Y_i)} \left\{ \left( Y_i - \xi_i^* \hat{P}_w - Z_i^* \tilde{a}_w(U_i) \right)^2 - \hat{P}^*_w \Sigma_w \hat{P}_w \right\} - \mu_3 - v_3 (U_i - u)^2 K\left(\frac{U_i - u}{h_{2n}}\right),
\]

the local linear regression estimator of $\sigma^2(u)$ based on inverse probability weighted method is defined by

\[
\tilde{\sigma}^2_w(u) = \sum_{i=1}^n W^w_m \left\{ \left( Y_i - \xi_i^* \hat{P}_w - Z_i^* \tilde{a}_w(U_i) \right)^2 - \hat{P}^*_w \Sigma_w \hat{P}_w \right\},
\]

where the weight function $W^w_m(\cdot)$ is defined by

\[
W^w_m(u) = \frac{(nh_{2n})^{-1}(\delta_i^w/(1 - \hat{G}_n(Y_i)))K((U_i - u)/h_{2n}) (A^w_{12}(u) - (U_i - u)A^w_{11}(u))}{A^w_{11}(u)A^w_{22}(u) - [A^w_{12}(u)]^2},
\]

with

\[
A^w_{ij} = \frac{1}{nh_{2n}} \sum_{i=1}^n \frac{\delta_i^w}{1 - G_n(Y_i)} K\left(\frac{U_i - u}{h_{2n}}\right)(U_i - u)^j, \quad \text{for } j = 0, 1, 2.
\]

2.3. Reweighted Estimation. In this subsection, we construct the reweighted estimations of the parametric and non-parametric parts based on the error variance estimator $\tilde{\sigma}^2_\varepsilon(u)$ given in (23). By minimizing the following object function, then, we get the following reweighted estimator of $\beta$ based on the regression calibration method:

\[
\tilde{\beta}_c = \left\{ \sum_{i=1}^n \frac{\delta_i^e}{1 - G_n(Y_i)} \tilde{\sigma}^{-2}(U_i) \left( Y_i - \xi_i^e \tilde{\beta}_c - \xi_i^e \tilde{e}_c - \Sigma_e \right) \right\}^{-1}
\]

Furthermore, the reweighted estimator of the coefficient function $\alpha(u)$ is defined by

\[
\tilde{\alpha}_c(u) = (I_q \delta \bar{\alpha}_{c_\varepsilon} \Delta_x, D_x)^{-1} D_x \bar{\alpha}_{c_\varepsilon} \omega_y (Y - \xi \hat{\beta}_c).
\]

Similarly, based on the error variance estimator $\tilde{\sigma}^2_m(u)$ given in (28) and minimizing the following object function
\[
\sum_{i=1}^{n} \frac{\delta_i^m}{1 - G_n(Y_i)} \tilde{\sigma}_m^2(U_i) \left[ Y_i - \xi_i^\beta - \sum_{j=1}^{n} (a_j + b_j (U_i - u_0)) Z_{ij} \right]^2 - \beta^T \Sigma \beta \right] \cdot \left( \frac{U_i - u}{h_m} \right). 
\]

then, we get the reweighted estimator of \( \beta \) based on the imputation method:

\[
\tilde{\beta}_m = \left\{ \sum_{i=1}^{n} \frac{\delta_i^m}{1 - G_n(Y_i)} \tilde{\sigma}_m^2(U_i) \left( \tilde{\xi}_i \tilde{\xi}_i^T - \Sigma \right) \right\}^{-1} \sum_{i=1}^{n} \frac{\delta_i^m}{1 - G_n(Y_i)} \tilde{\sigma}_m^2(U_i) \tilde{\xi}_i Y_i. 
\]

Hence, the reweighted estimator of the coefficient function \( \alpha(u) \) is defined by

\[
\tilde{\alpha}_m(u) = (I_q 0) \left( D_n^T \omega_u \tilde{\alpha}_m D_u \right)^{-1} D_n^T \tilde{\alpha}_m \omega_u (Y - \tilde{\beta}_m). 
\]

\[
\sum_{i=1}^{n} \frac{\delta_i^w}{1 - G_n(Y_i)} \tilde{\sigma}_w^2(U_i) \left[ Y_i - \xi_i^\beta - \sum_{j=1}^{n} (a_j + b_j (U_i - u_0)) Z_{ij} \right]^2 - \beta^T \Sigma \beta \right] \cdot \left( \frac{U_i - u}{h_m} \right). 
\]

then, we get the reweighted estimator of \( \beta \) based on the inverse probability weighted method:

\[
\tilde{\beta}_w = \left\{ \sum_{i=1}^{n} \frac{\delta_i^w}{1 - G_n(Y_i)} \tilde{\sigma}_w^2(U_i) \left( \tilde{\xi}_i \tilde{\xi}_i^T - \Sigma \right) \right\}^{-1} \sum_{i=1}^{n} \frac{\delta_i^w}{1 - G_n(Y_i)} \tilde{\sigma}_w^2(U_i) \tilde{\xi}_i Y_i. 
\]

3. Empirical Likelihood

The confidence regions of the parameter can be constructed by the asymptotic distribution of Theorems 1 and 4. However, the estimation of asymptotic covariance is quite complicated. In this section, we shall employ the EL method to construct confidence regions for \( \beta \), which avoids to estimate the complicated covariance.

3.1. Regression Calibration Empirical Likelihood. We introduce the following auxiliary random vector based on regression calibration method:

\[
\tilde{\eta}_{ic} = \left( \frac{m(T_i, \tilde{\delta}_i)}{1 - G_n(Y_i)} \right)^{1/2} \tilde{\sigma}_c^2(U_i) \left[ \tilde{\xi}_i (Y_i - \tilde{\xi}_i^\beta) + \Sigma \beta \right]. 
\]

Thus, we define the empirical log-likelihood ratio function as follows:

\[
L_c(\beta) = \sup \left\{ \prod_{i=1}^{n} \left( n p_i \right): p_i \geq 0, \sum_{i=1}^{n} p_i = 1, \sum_{i=1}^{n} p_i \tilde{\eta}_{ic}(\beta) = 0 \right\}.
\]

The optimal value of \( p_i \) satisfying (46) is given by \( p_i = (1/n) \cdot (1/(1 + \lambda \tilde{\eta}_{ic}(\beta))) \), where \( \lambda = \lambda_c(\beta) \) is the solution to the equation \( \sum_{i=1}^{n} (\tilde{\eta}_{ic}(\beta) / (1 + \lambda \tilde{\eta}_{ic}(\beta))) = 0 \). By the Lagrange multiplier method, the corresponding empirical log-likelihood ratio function is represented as

\[
\tilde{L}_c(\beta) = \frac{2}{n} \sum_{i=1}^{n} \log \left\{ 1 + \lambda \tilde{\eta}_{ic}(\beta) \right\}.
\]

By maximizing \( \{-\tilde{L}_c(\beta)\} \), we can obtain a maximum EL estimator \( \tilde{\beta}_{cel} \) of \( \beta \) with regression calibration method.

3.2. Imputation Empirical Likelihood. We introduce the following auxiliary random vector based on imputation method:

\[
\tilde{\eta}_{icm} = \left( \frac{c \delta_i + (1-c)m(T_i, \tilde{\delta}_i)}{1 - G_n(Y_i)} \right)^{1/2} \tilde{\sigma}_m^2(U_i) \left[ \tilde{\xi}_i (Y_i - \tilde{\xi}_i^\beta) + \Sigma \beta \right]. 
\]
Hence, we define the empirical log-likelihood ratio function as follows:

$$I_m(\beta) = \sup \left\{ \prod_{i=1}^{n} (n p_i): \ p_i \geq 0, \sum_{i=1}^{n} p_i = 1, \sum_{i=1}^{n} p_i \tilde{h}_{im}(\beta) = 0 \right\}.$$  \hfill (49)

The optimal value of $p_i$ satisfying (49) is given by

$$p_i = (1/m) \cdot (1/(1 + \lambda^T \tilde{h}_{im}(\beta))),$$

where $\lambda = \lambda_{m}(\beta)$ is the solution to the equation $\sum_{i=1}^{n} (\tilde{h}_{im}(\beta)/(1 + \lambda^T \tilde{h}_{im}(\beta))) = 0$. By the Lagrange multiplier method, the corresponding empirical log-likelihood ratio function is

$$\tilde{I}_m(\beta) = 2 \sum_{i=1}^{n} \log \left[ 1 + \lambda^T \tilde{h}_{im}(\beta) \right].$$  \hfill (50)

By maximizing $\{-\tilde{I}_m(\beta)\}$, we can obtain a maximum EL estimator $\hat{\beta}_{med}$ of $\beta$ with imputation method.

### 3.3 Inverse Probability Weighted Empirical Likelihood

We introduce the following auxiliary random vector based on inverse probability weighted method:

$$\tilde{h}_{iw}(\beta) = \frac{(\zeta_i / \tilde{h}_n(Y_i)) + (1 - (\zeta_i / \tilde{h}_n(Y_i)))m(T_i \tilde{h}_n)\sigma^2}{1 - G_n(Y_i)} \cdot (U_i) \left[ \xi_i (\tilde{Y}_i - \zeta_i \tilde{h}_n) + \Sigma_i \beta \right].$$  \hfill (51)

Then, we define the empirical log-likelihood ratio function as follows:

$$I_w(\beta) = \sup \left\{ \prod_{i=1}^{n} (n p_i): \ p_i \geq 0, \sum_{i=1}^{n} p_i = 1, \sum_{i=1}^{n} p_i \tilde{h}_{iw}(\beta) = 0 \right\}.$$  \hfill (52)

The optimal value of $p_i$ satisfying (52) is given by

$$p_i = (1/m) \cdot (1/(1 + \lambda^T \tilde{h}_{iw}(\beta))),$$

where $\lambda = \lambda_{w}(\beta)$ is the solution to the equation $\sum_{i=1}^{n} (\tilde{h}_{iw}(\beta)/(1 + \lambda^T \tilde{h}_{iw}(\beta))) = 0$. By the Lagrange multiplier method, the corresponding empirical log-likelihood ratio function is represented as

$$\tilde{I}_w(\beta) = 2 \sum_{i=1}^{n} \log \left[ 1 + \lambda^T \tilde{h}_{iw}(\beta) \right].$$  \hfill (53)

By maximizing $\{-\tilde{I}_w(\beta)\}$, we can obtain a maximum EL estimator $\hat{\beta}_{wel}$ of $\beta$ with inverse probability weighted method.

### 4. Main Results

For convenience and simplicity, we use $C_0, C_1, \ldots$ and $c_0, c_1, \ldots$ generically to represent any positive constants, which may take different values for each appearance. Let $\Gamma(u) = E[ZZ^T|U = u]$, $\Phi(u) = E[ZX^T|U = u]$, $\Psi = X - \Phi^{-1}(U)\Gamma^{-1}(U)Z$, $\Theta = [X + e - \Phi(U)\Gamma^{-1}(U)\Phi^T(U))(\epsilon - e\beta)]$ and $M^{Q2} = MM^T$. Denote

$$\Sigma_{11} = E \left\{ \frac{m(T, \theta)}{1 - G(Y)} \Psi \Psi^T \right\},$$

$$\Sigma_{12} = E \left\{ \frac{m(T, \theta)}{1 - G(Y)} \Theta + \Sigma \beta \right\} \sigma^2,$$

$$\Sigma_{21} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \Psi \Psi^T \right\},$$

$$\Sigma_{22} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \Theta + \Sigma \beta \right\} \sigma^2,$$

$$\Sigma_{111} = E \left\{ \frac{m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Psi \Psi^T \right\},$$

$$\Sigma_{112} = E \left\{ \frac{m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Theta + \Sigma \beta \right\} \sigma^2,$$

$$\Sigma_{121} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Psi^T \right\},$$

$$\Sigma_{122} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Theta + \Sigma \beta \right\} \sigma^2,$$

$$\Sigma_{1111} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Psi \Psi^T \right\},$$

$$\Sigma_{1112} = E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} \sigma^{-2} (U)\Theta + \Sigma \beta \right\} \sigma^2,$$

$$\Lambda_1 = s_6 E \left\{ \frac{m(T, \theta)}{1 - G(Y)} g^{-1}(U)\Gamma^{-1}(U)(\epsilon - e\beta)^2 \right\},$$

$$\Lambda_2 = s_5 E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} g^{-1}(U)\Gamma^{-1}(U)(\epsilon - e\beta)^2 \right\},$$

$$\Lambda_3 = s_5 E \left\{ \frac{c\delta + (c - 1)m(T, \theta)}{1 - G(Y)} g^{-1}(U)\Gamma^{-1}(U)(\epsilon - e\beta)^2 \right\} \frac{(U - U)^{-1}(U)(\epsilon - e\beta)^2}{1 - G(Y)} \sigma^{-2} (U)\Theta + \Sigma \beta \right\} \sigma^2.$$  \hfill (54)

In order to prove the main results, we give a set of assumptions that are stated in the following theorems:

(C1) The random variable $U$ has bounded support $\mathcal{U}$ and its density function $g(\cdot)$ is Lipschitz continuous and away from zero on its support.
(C2) There is \( s > 2 \) such that \( E(\|X_i\|^s) < \infty \) a.s., \( E(\|Z_i\|^s) < \infty \) a.s., \( E(|\epsilon_i|^s) < \infty \) a.s. \( \Gamma (u) \) and \( \Phi (u) \) are nonsingular matrices.

(C3) \( \{a_j(\cdot), j = 1, \ldots, q\} \) has continuous second derivatives in \( U \).

(C4) The variance function \( \sigma^2(\cdot) \) with uniform boundedness has continuous second-order derivation and is bounded away from zero.

(C5) The kernel \( K(\cdot) \) as a symmetric density function has compact support \([-1, 1]\), which is Lipschitz continuous, and satisfies \( \int_{-1}^{1} tK(t)dt = \kappa_j < \infty, \int_{-1}^{1} K^2(t)dt = \nu_j < \infty, j = 0, 1, 2 \).

(C6) Denote \( a_{H} = \inf \{t: H(t) = 1\} \) and \( a_{c} = \inf \{t: G(t) = 1\} \). Let \( a_{H} < a_{C} \) and \( G(\cdot) \) is continuous. \( H(t) \) is continuous for \( t > a_{H} \).

(C7) The kernel functions \( \Omega(\cdot) \) and \( L(\cdot) \) are bounded with compact supports, and \( na_n \rightarrow \infty \), \( na_n^\beta \rightarrow 0 \), \( nb_n \rightarrow \infty \) and \( nb_n^\beta \rightarrow 0 \).

(C8) \( \pi(\cdot) \) and \( \mu(\cdot) \) have bounded derivatives of order 1, and there exists \( c > 0 \) such that \( \inf \pi(\cdot) \geq c > 0 \).

(C9) \( I(\theta_0) \) is a positive definite. \( \nabla m(T_1, \theta_0) \) is continuous at \( \theta_0 \).

(C10) The bandwidth \( h_m \) satisfies \( h_m \rightarrow 0, nh_m \rightarrow \infty, nh_m^\beta \rightarrow 0 \) and \( nh_m^\beta/(\log n)^2 \rightarrow \infty \) for \( i = 1, 2, 3 \).

**Remark 1.**

(a) Assumptions (C1) and (C2) are used to establish the asymptotic normality and the oracle property of the estimators. Assumptions (C3) and (C4) are common conditions for varying-coefficients models with heteroscedastic error. Assumption (C5) requires that the kernel function is a proper density with finite second moment, which is required to derive the asymptotic variance of estimators. Assumption (C6) implies that \( 1 - G(Y) \) is bounded away from zero. Assumptions (C7)–(C9) are needed for the properties of \( G_n(Y) \) and \( m(T_1, \theta_0) \). Assumption (C10) underlines the relationship bandwidth with sample size \( n \), which implies the optimal bandwidth in nonparametric estimation.

(b) From the Taylor expansion and conclusion in Li and Wang [17], one can get

\[
\sqrt{n} \left( \hat{\theta}_n - \theta \right) = I^{-1}(\theta_0) \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \xi_i (\hat{\theta}_n - m(T_i, \theta_0)) \nabla m(T_i, \theta_0) \right) + o_p(1),
\]

which, together with assumption (C9), gives \( \hat{\theta}_n - \theta = O_p(n^{-1/2}) \).

The asymptotic properties of the proposed estimators are shown in the following theorems.

**Theorem 1.** Suppose that assumptions (C1)–(C10) are satisfied; then, we have

\[
\sqrt{n} \left( \hat{\beta}_n - \beta \right) \overset{D}{\rightarrow} N(0, \Sigma_{\beta}^{-1}),
\]

where \( \hat{\beta}_n \) is taken to be \( \hat{\beta}_c(u), \hat{\beta}_m(u) \), and \( \hat{\beta}_w(u) \). \( j = 1, 2, 3 \) correspond to \( \hat{\beta}_c, \hat{\beta}_m \) and \( \hat{\beta}_w \), respectively.

**Theorem 2.** Suppose that assumptions (C1)–(C10) are satisfied; then, we have

\[
\sqrt{n} h_n \left( \hat{\alpha}_n(u) - a(u) - \frac{1}{2} \frac{n}{h_n^2} a''(u) \right) \overset{D}{\rightarrow} N(0, \Lambda_1),
\]

where \( \hat{\alpha}_n(u) \) is taken to be \( \hat{\alpha}_c(u), \hat{\alpha}_m(u) \) and \( \hat{\alpha}_w(u) \). \( j = 1, 2, 3 \) correspond to \( \hat{\alpha}_c, \hat{\alpha}_m \) and \( \hat{\alpha}_w \), respectively.

**Theorem 3.** Suppose that assumptions (C1)–(C10) are satisfied; let \( \rho_n = \left( \log n/n h_n \right)^2 + h_n^2 \), then, we have

\[
\sup_u |\hat{\alpha}_n^2(u) - \alpha^2(u)| = O_p(\rho_n),
\]

where \( \hat{\alpha}_n^2(u) \) is taken to be one of \( \hat{\alpha}_c^2(u), \hat{\alpha}_m^2(u) \) and \( \hat{\alpha}_w^2(u) \).

**Theorem 4.** Suppose that assumptions (C1)–(C10) are satisfied; then, we have

\[
\sqrt{n} \left( \hat{\beta}_n - \beta \right) \overset{D}{\rightarrow} N(0, \Sigma_{\beta,1}^{-1}),
\]

where \( \hat{\beta}_n \) is taken to be one of \( \hat{\beta}_c(u), \hat{\beta}_m(u) \) and \( \hat{\beta}_w(u) \). \( j = 1, 2, 3 \) correspond to \( \hat{\beta}_c, \hat{\beta}_m \) and \( \hat{\beta}_w \), respectively.

**Theorem 5.** Suppose that assumptions (C1)–(C10) are satisfied; then, we have

\[
\sqrt{n} h_n \left( \hat{\alpha}_n(u) - a(u) - \frac{1}{2} \frac{n}{h_n^2} a''(u) \right) \overset{D}{\rightarrow} N(0, \Lambda_1),
\]

where \( \hat{\alpha}_n(u) \) is taken to be one of \( \hat{\alpha}_c(u), \hat{\alpha}_m(u) \) and \( \hat{\alpha}_w(u) \). \( j = 1, 2, 3 \) correspond to \( \hat{\alpha}_c, \hat{\alpha}_m \) and \( \hat{\alpha}_w \), respectively.

**Theorem 6.** Suppose that assumptions (C1)–(C10) are satisfied; if \( \beta \) is the true value, then we have

\[
\hat{\rho}_n(\beta) \overset{D}{\rightarrow} X_1^2,
\]

where \( \hat{\rho}_n(\beta) \) denotes one of \( \hat{\rho}_c(\beta), \hat{\rho}_m(\beta) \), and \( \hat{\rho}_w(\beta) \). \( X_1^2 \) is a standard chi-squared random variable with 1 degree of freedom.

**Theorem 7.** Suppose that assumptions (C1)–(C10) are satisfied; then, we have

\[
\sqrt{n} \left( \hat{\beta}_{di} - \beta \right) \overset{D}{\rightarrow} N(0, \Sigma_{\beta,1}^{-1}),
\]

where \( \hat{\beta}_{ci} \) denotes one of \( \hat{\beta}_{cel}, \hat{\beta}_{mel} \) and \( \hat{\beta}_{wel} \). \( j = 1, 2, 3 \) correspond to \( \hat{\beta}_{cel}, \hat{\beta}_{mel} \) and \( \hat{\beta}_{wel} \), respectively.
Remark 2.

(a) From Theorems 1 and 4, the asymptotic variance of the reweighted estimator $\hat{\beta}_n$ is not greater than that of the modified profile LS estimator $\hat{\beta}_m$; that is, $\Sigma_{ij}^{-1}\Sigma_{ij}^{-1}\Sigma_{ij}^{-1}$ is a positive semidefinite matrix. The asymptotic variance of the reweighted estimator $\hat{\beta}_n$ is smaller than that of $\hat{\beta}_w$, and is larger than that of $\hat{\beta}_c$, which indicates that $\hat{\beta}_c$ performs the best, and $\hat{\beta}_w$ performs the worst. The modified PLS estimators $\hat{\beta}_c$, $\hat{\beta}_m$, $\hat{\beta}_w$ enjoy the same conclusion.

(b) From Theorems 2 and 5, the local polynomial estimator $\tilde{\alpha}_n(\cdot)$ and reweighted estimator $\tilde{\alpha}_w(\cdot)$ have the same asymptotic distribution, which reflects the characteristic of the local regression in nonparametric models.

Table 1: Choosing for $\nu$ and $a = (a_1, a_2, a_3)$ and corresponding CR and MR in model (63).

<table>
<thead>
<tr>
<th>$n$</th>
<th>CR (%)</th>
<th>MR (%)</th>
<th>$\nu$</th>
<th>$a = (a_1, a_2, a_3)$</th>
<th>$\theta = (\theta_1, \theta_2, \theta_3)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>10</td>
<td>10</td>
<td>9.25</td>
<td>(-6.0, -1.1, -1.1)</td>
<td>(-2.546, -0.595, -0.215)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>9.25</td>
<td>-1.3</td>
<td>(-1.3, -0.9, -0.8)</td>
<td>(-2.551, -0.351, -0.311)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>0.79</td>
<td>-6.1</td>
<td>(-6.1, -1.3, -1.0)</td>
<td>(-0.152, -0.222, -1.650)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>0.79</td>
<td>-1.5</td>
<td>(-1.5, -0.9, -0.7)</td>
<td>(-0.144, -0.213, -1.550)</td>
</tr>
<tr>
<td>400</td>
<td>10</td>
<td>10</td>
<td>9.25</td>
<td>(-6.0, -1.1, -1.1)</td>
<td>(-2.567, -0.601, -0.221)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>9.25</td>
<td>-1.3</td>
<td>(-1.3, -0.9, -0.8)</td>
<td>(-2.541, -0.355, -0.302)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>0.79</td>
<td>-6.1</td>
<td>(-6.1, -1.3, -1.0)</td>
<td>(-0.151, -0.213, -1.620)</td>
</tr>
<tr>
<td></td>
<td>40</td>
<td>0.79</td>
<td>-1.5</td>
<td>(-1.5, -0.9, -0.7)</td>
<td>(-0.145, -0.214, -1.550)</td>
</tr>
</tbody>
</table>

Figure 1: The QQ-plots of $\tilde{\alpha}_w(\cdot)$ based on $\Sigma_{e1}$ (a) and $\Sigma_{e2}$ (b) with heteroscedasticity coefficient $\gamma = 1$ (c) and $\gamma = 4$ (d) under CR = 10% and MR = 10%.
(c) From Theorem 6, the 100(1 − τ)% EL confidence region for β can be established as \( \{ar{l}_n(\beta) \leq \chi^2_1(1 − \tau)\} \), where \( \chi^2_1(1 − \tau) \) is the upper \((1 − \tau)\)-quantile of distribution of \( \chi^2_1 \).

5. Simulation

In this subsection, we carry out some numerical simulation to investigate the finite sample behavior of the proposed estimators. We compare the performance of the estimators based on the regression calibration method (CA), imputation method (IM) and inverse probability weighted method (IPW), and their corresponding reweighted estimators (R-CA, R-IM, R-IPW). Besides, we conduct a comparison of the EL method with the normal approximation (NA) approach in terms of coverage probabilities (CP) and average interval lengths (AL) under different settings. At the same time, we give a real data analysis. The kernel functions are taken as \( K(u) = (3/4)(1 − u^2)I(|u| \leq 1) \), \( L(u) = (15/16)(1 − u^2)^2I(|u| \leq 1) \), and \( \Omega(u) = (1/2)I(|u| \leq 1) \). The bandwidths \( h_{1n}, h_{2n}, h_{3n} \) have taken the same values by leave-one-sample-out cross-validation. The following simulation is based on 500 replications. The sample size \( n \) is chosen to be 100 and 400, repeatedly.

5.1. Simulation Experiments. The data are generated from the following the PLVCEV model:

\[
T_i = X_{i1}^\top \beta_1 + X_{i2}^\top \beta_2 + Z_i^\top \alpha(U_i) + \epsilon_i, \\
\xi_{i1} = X_{i1} + e_{i1}, \quad \xi_{i2} = X_{i2} + e_{i2}, \quad i = 1, \ldots, n,
\]

(63)

where \( \beta_1 = 1, \beta_2 = 2, \alpha(u) = \sin(2\pi u) \), the covariates \( X_{i1} \) and \( X_{i2} \) are from \( N(0, 1) \) and pairwise covariance \( \text{cov}(X_{ij}, X_{ik}) = 0.5^{|j-k|} \). \( Z_i \) is from \( U(-1, 1) \). \( U_i \) is from \( U(0, 1) \), the model error \( \epsilon_i \sim N(0, 1) \). The error variance function is taken as \( \sigma^2(u) = 0.25 + [\gamma(1 + \sin(2\pi u))]^2 \) for...


\[ y = 1 \text{ and } 4. \] The measurement error \( e_i \sim N(0, \Sigma) \). To represent different levels of measurement errors, we take \( \Sigma_i \) be \( \Sigma_{\varepsilon_1} = \text{diag}(0.5, 0.5) \) and \( \Sigma_{\varepsilon_2} = \text{diag}(0.25, 0.25) \) in the simulations, respectively. Let the censoring time \( C_i \) be from \( \exp(\nu) \), where \( \nu \) is adapted to get different censoring ratios (CR). For the missing mechanism, we take \( P(\xi_i | X_i, Z_i, U_i, Y_i) = 1/[1 + \exp(-a_1 - a_2 X_{i1} + Z_i - a_3 Y_i)] \). We choose different \( \nu \) and \( a = (a_1, a_2, a_3) \) to get different CR and missing ratios (MR). Suppose that \( m(T_i, \theta) \) follows a logistic model, that is, \( m(T_i, \theta) = 1/[1 + \exp(-\theta_1 - \theta_2 X_{i2} - \theta_3 Y_i)] \). Then, the parameter \( \theta = (\theta_1, \theta_2, \theta_3) \) is estimated by maximum likelihood method. See Table 1 for details.

In the first simulation, we study the finite sample performance of the proposed modified PLS estimators and reweighted estimators of \( \beta \) based on mean squared error (MSE) defined as

\[ \text{MSE}(\hat{\beta}_n) = \sqrt{\left( \hat{\beta}_n - \beta \right)^\top (\hat{\beta}_n - \beta)}, \quad (64) \]

and the global mean square error (GMSE) of \( \hat{\alpha}_n(u) \) defined as

\[ \text{GMSE} = \frac{1}{n_{\text{grid}} M} \sum_{m=1}^{M} \sum_{j=1}^{n_{\text{grid}}} \left| \hat{\alpha}_n(u_j) - \alpha(u_j) \right|^2, \quad (65) \]

where \( \{u_j \colon j = 1, 2, \ldots, n_{\text{grid}}\} \) is a sequence of grid points. In addition, we plot QQ-plots of the reweighted estimator \( \hat{\alpha}_w(u) \) for \( \alpha(u) \) under different settings in Figures 1 and 2. In the second simulations, we plot the curves of the proposed estimators \( \hat{\sigma}_i^2(u) \), \( \hat{\sigma}_m^2(u) \), and \( \hat{\sigma}_w^2(u) \) under different settings in Figures 3 and 4. In the third simulations, we consider CP and AL of the confidence regions for \( \beta \) based on the EL method (CPE, ALE) and NA method (CPN, ALN) with nominal level 0.95 under different settings in Table 2.

From Tables 2–4 and Figures 1–4, it can be seen that

1. In Tables 3 and 4, the MSE and GMSE of reweighted estimators are smaller than those of modified PLS estimators under the same setting. The results of IM estimators are smaller than those of IPW estimators, and bigger than those of RC estimators. The results increase as measurement error, heteroscedasticity error, and CR and/or MR increase. The results decrease as the sample size increases. The results above
imply that the reweighted estimators perform better than the modified PLS estimators. The RC method performs best, and IPW method performs worst, which confirms the theoretical results.

(2) In Table 2, the CP of reweighted estimators is larger than that of the modified PLS estimators. The CP of the RC method is the smallest, and that of the IPW method is the biggest under the same settings. The CP decreases as heteroscedasticity error and CR and/or MR increase. The results increase as sample size increases. The CP based on the EL method is smaller than that of the NA method. The AL performs in the opposite way.

(3) In Figures 1 and 2, the fit is better as decreasing the heteroscedasticity error and measurement error. The fit is worse as increasing CR and/or MR.

(4) In Figures 3 and 4, the proposed estimators of error variance perform better as decreasing measurement error, heteroscedasticity error, and CR and/or MR. The estimator $\sigma^2(\cdot)$ performs the best, and $\sigma^2_w(\cdot)$ performs the worst under the same settings.

5.2. A Real Data Analysis. In real data analysis, we illustrate the methodology via an application to a dataset from a breast cancer clinical trial [25]. This clinical trial was conducted by the Eastern Cooperative Oncology Group, whose target was evaluating tamoxifen as a treatment for stage II breast cancer among elderly women, who are older than 65. There are 169 elderly women participating in the trial, and we focus on 79 women who died by the end of the trial. But, unfortunately, the cause of death is incomplete. Among them, 44 women died from breast cancer, 17 died from other known causes, and 18 died from unknown causes. Let the censoring indicator $\delta$ show whether the death was caused by breast cancer, and let the missing indicator $\varsigma$ show whether the cause of death was known. The dataset contains four covariates: whether the patients accepted the treatment (1, tamoxifen; 0, placebo), denoted as $X_1$; whether the estrogen receptor status was positive (1, yes; 0, unknown), denoted as $X_2$; whether there were four or more axillary lymph positive nodes (1, yes; 0, no), denoted as $Z$; and whether the primary tumor is 3 cm or larger (1, yes; 0, no), denoted as $U$. Then, we employ the following model to fit the data,

$$Y = X_1^T \beta_1 + X_2^T \beta_2 + Z^T \alpha(U) + \epsilon,$$

where $Y$ is the logarithm of the time to death due to breast cancer, which is censored, and the censoring indicator is MAR. The heteroscedastic error follows the form of $\text{Var}(\epsilon|X,Z,U) = \sigma^2(U)$. For the purpose of comparison, we compute both mean squared prediction error (MSE) and mean

![Figure 4: The curves of $\sigma^2(\cdot)$ (solid line), $\sigma^2_c(\cdot)$ (dotted line), $\sigma^2_m(\cdot)$ (dashed line), and $\sigma^2_w(\cdot)$ (dash-dotted line) based on $\Sigma_{e1}$ (a) and $\Sigma_{e2}$ (b) with heteroscedasticity coefficient $\gamma = 1$ (c) and $\gamma = 4$ (d) under CR = 40% and MR = 40%.](image)
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Table 5: The estimators, MSEs, and MADs for the breast cancer dataset.

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<th>( \hat{\beta}_2 )</th>
<th>MSE</th>
<th>MAD</th>
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From Table 5 and Figure 5, it can be seen that, (1) in Table 5, the estimators of \( \beta_1 \) are positive, which indicates that the breast-cancer deaths may live longer if they received the treatment. Among these estimators, the MSE and MAD based on the R-RC method are smallest, which confirms the conclusions in Theorems 1 and 4. (2) In Figure 5, the primary tumor size of patients is mainly from 0 to 3 cm. The survival time decreases obviously as the tumor size increases.

6. Conclusion

In this paper, we consider the estimation and confidence regions based on modified PLS method and EL inference for PLVCEV model with heteroscedastic errors under censoring indicators MAR, respectively. Asymptotic properties of the proposed estimators are established, and the confidence regions of parameter are constructed. In addition, a simulation study and real data analysis are conducted to illustrate our proposed method.

Xu and Duan [11] established efficient estimation for varying-coefficient heteroscedastic partially linear model with additive errors, but their results are confined in responses observed completely. It is an innovative and challenging topic to study the statistical inference for heteroscedastic PLVCEV model under right-censored data with censoring indicators MAR.

An interesting problem is whether we can extend the estimation method and incomplete data to functional regression models.

Appendix

Proof of Main Results

Lemma A.1. Let \( D_1, D_2, \ldots, D_n \) be independent and identically distributed (i.i.d.) random variables. If \( E[D_1^s] \) is bounded for \( s > 1 \), then \( \max_{1 \leq i \leq n} |D_i| = o(n^{1/s}) \) a.s.

Proof. Lemma A.1 can be verified as Lemma 3 in Owen [20]. □

Lemma A.2. Let \( (X_1, Y_1), \ldots, (X_n, Y_n) \) be i.i.d. random vectors, where \( Y_i \) and \( X_i \) are scalar random variables. Assume further that \( E[Y_1^s] < \infty \) and \( \sup_{u \in [0, 1]} \int |y|^s f(u, y)dy < \infty \), where \( f(\cdot, \cdot) \) denotes the joint density of \((X, Y)\). Let \( K(\cdot) \) be a bounded positive function with a bounded support and satisfying a Lipschitz condition. Then, \( \sup_{i,j} \left| \sum_{k=1}^n K_k (X_i - x) [Y_j - E(Y_j)]/\sum_{k=1}^n K_k (X_i - x)] \right| = O_p \left( \ln(1/h)nh^{1/2} \right) \) provided that \( nh^{2-\epsilon} \to \infty \) for some \( \epsilon < 1 - s^{-1} \).

Proof. Lemma A.2 comes from the basic corollary in Mack and Silverman [26]. □

Lemma A.3. Suppose that assumptions (C1)–(C10) hold; then, as \( n \to \infty \), it holds that
where \( j, j_1, j_2 = 1, \ldots, q \), \( I = \{0, 1, 2, 4 \} \), \( \Gamma(j, j_1) \) is the \((j, j_1)\)-th element of \( \Gamma(u) \) and \( y_n = \log n / (nh_{1n})^{1/2} + h_{1n}^2 \).

Proof. The proof of Lemma A.3 is similar to that of Lemma A.2 in Xia and Li [27]. \( \Box \)

**Lemma A.4.** Under the assumptions (C6)–(C8), then we have

\[
\begin{align*}
\zeta(Y_j, \delta_j, c_j; Y_i) &= -\left( \frac{\varsigma_j - \pi(Y_j)}{\pi(Y_j)} \right) \left( \delta_j - \mu(Y_j) \right) I(Y_j \leq Y_i) + \int_0^{Y_i} \frac{dH_n(s)}{(1 - H(s))^2} + I(Y_i, Y_j, \delta_j = 0) \\
R_n(Y_i) &= -\frac{e^{-2\varepsilon(Y_j)}}{2} (\Xi_n(Y_i) - \Xi(Y_i))^2 + e^{-2\varepsilon(Y_i)} (-\ln(1 - \tilde{G}_n(Y_i)) - \Xi_n(Y_i)) \\
&+ \frac{1}{n} \sum_{i=1}^{n} \left[ 1 - \tilde{p}_n(Y_j) \right] \left[ H_n(Y_i) - H(Y_i) \right] I(Y_j < Y_i) \\
&+ \frac{1}{n} \sum_{i=1}^{n} \left[ \tilde{p}_n(Y_j) - \mu(Y_j) \right] \left[ H_n(Y_i) - H(Y_i) \right] I(Y_i < Y_j) \\
&+ \int_0^{Y_i} \frac{dH_n(s)}{(1 - H(s))^2} + \int_0^{Y_i} \frac{\mu(x) [H_n(x) - H(x)]^2}{1 - H(x)} dH_n(x) \\
&= \frac{1}{n} \sum_{i=1}^{n} I(Y_i < Y_j) \frac{1}{n} \sum_{i=1}^{n} \varsigma_j(Y_j - Y_i) \Omega(Y_j - Y_i) \\
&+ \frac{1}{n} \sum_{i=1}^{n} I(Y_i < Y_j) \frac{1}{n} \sum_{i=1}^{n} \varsigma_j(Y_j - Y_i) \Omega(Y_j - Y_i) \\
&+ \frac{1}{n} \sum_{i=1}^{n} \xi_i \left( \delta_j - \mu(X_i) \right) \left[ \frac{1}{nb_n} \sum_{i=1}^{n} \frac{I(Y_j < t)}{(1 - H(Y_i)) V^*(Y_j)} \Omega(Y_j - Y_i) \right] \\
&+ \frac{1}{n} \sum_{i=1}^{n} \xi_i \left( \delta_j - \mu(Y_i) \right) \left[ \frac{1}{nb_n} \sum_{i=1}^{n} \frac{I(Y_i < t)}{(1 - H(Y_i)) V^*(Y_j)} \Omega(Y_j - Y_i) \right] \\
&= E_{\delta_j} - E_{\delta_j} \left[ \frac{1}{nb_n} \sum_{i=1}^{n} \frac{I(Y_j < Y_i)}{(1 - H(Y_i)) V^*(Y_j)} \Omega(Y_j - Y_i) \right] \\
&+ \int \frac{1}{n} \sum_{i=1}^{n} \xi_i \left( \delta_j - \mu(Y_i) \right) I(Y_i < t) \left[ \left( \frac{b_n u}{r} \right)^r P^{(r)}(Y_i) + \left( \frac{b_n u}{r} \right)^{r+1} P^{(r+1)}(Y_i) \right] \Omega(u) du \\
&+ \int \frac{1}{n} \sum_{i=1}^{n} \xi_i \left( \delta_j - \mu(Y_i) \right) I(Y_i + b_n u < Y_j) - I(Y_i < Y_j) \Omega(u) du,
\end{align*}
\]
with \( \bar{H}_1(t) = P(Y > t, \delta = 1) \), \( H_n = (1/n) \sum_{i=1}^{n} 1(Y \leq t) \), \( \Xi(Y_i) = \int_{0}^{Y_i} (dG(t) / (1 - G(t))) \), \( \Xi_n(Y_i) = \int_{0}^{Y_i} (1 - \tilde{\mu}_n(t)) dt / (1 - H_n(t)) \), \( V_n(Y_i) = (1/n) \sum_{i=1}^{n} \xi_i L(Y_i) - Y_i) / a_n \), \( V^*(Y) = \pi(Y_j h(Y_j) \) and \( P_1(x) = |p(x)(1 - H(x))|^{-1} \). \( \Xi^*(Y_i) \) is between \( \Xi_n(Y_i) \) and \( \Xi(Y_i) \). \( \Xi^* \) is between \(-\ln(1 - \tilde{G}_n(Y_i)) \) and \( \Xi_n(Y_i) \). \( Y^*_j \) is between \( Y_j \) and \( Y_j + b_j u \).

Proof. Following the proof of Theorem 1 in Wang and Ng [28], one can get the proof of Lemma A.4. To save space, here we omit the details. \( \square \)

Lemma A.5. Suppose that assumptions (C1)-(C10) hold; then, as \( n \to \infty \), we have \( \sup_{n \in \mathbb{N}} \| \bar{\alpha}_u(u) - \alpha(u) \| = O_P(\gamma_n) \) and \( \sup_{n \in \mathbb{N}} \| \bar{\tilde{\alpha}}_u(u) - \tilde{\alpha}(u) \| = O_P(\gamma_n) \).

Proof. We only prove the results about \( \bar{\alpha}_u(u) \). The results related on \( \bar{\tilde{\alpha}}_u(u) \) and \( \bar{\tilde{\alpha}}_u(u) \) can be proved similarly. By the definition of \( \bar{\alpha}_u(u) \) defined as (13) in Section 2, we can write

\[
\bar{\alpha}_u(u) - \alpha(u) = (I_{1, 0}) \left( D_u \bar{\omega}_x D_u^{-1} \right) \bar{\alpha}_u(u) + (I_{1, 0}) \left( D_u \bar{\omega}_x D_u^{-1} \right) \mathbf{e}
\]

(A.4)

Standard arguments yield that \( I_1 = 1_{\gamma_n} O_P(h_n^2) \). Following (A.9) in Shen et al. [10], we have \( I_1 = 1_{\gamma_n} O_P(\beta_n) \). Similarly, \( I_1 = 1_{\gamma_n} O_P(\rho_n) \). Note that \( \| \tilde{\beta} - \beta \| = O_p(\gamma_n) \) is easy to prove that \( I_3 = 1_{\gamma_n} O_P(n^{-1/2}) \). Therefore, the proof of \( \sup_{n \in \mathbb{N}} \| \bar{\alpha}_u(u) - \alpha(u) \| = O_P(\gamma_n) \) is finished. Using similar arguments, the verification of \( \sup_{n \in \mathbb{N}} \| \bar{\tilde{\alpha}}_u(u) - \alpha(u) \| = O_P(\gamma_n) \) can be done. \( \square \)

Lemma A.6. Suppose that assumptions (C1)-(C10) hold, and \( \tilde{\beta} \) is the true value; then, as \( n \to \infty \), we have

\[
(a) \quad \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \bar{\eta}_{n, \alpha}(\beta) \xrightarrow{D} N(0, \Sigma_{\beta}), \quad \frac{1}{n} \sum_{i=1}^{n} \bar{\eta}_{n, \alpha}(\beta) \bar{\eta}_{n, \alpha}^{\top}(\beta) \Sigma_{\beta}^{-1} \frac{1}{n} \sum_{i=1}^{n} \partial \bar{\eta}_{n, \alpha}(\beta) \partial \beta = - \Sigma_{\beta},
\]

\[
(b) \quad \max_{i \leq n, \alpha \beta} \| \bar{\eta}_{n, \alpha}(\beta) \| = O_P(n^{1/2}), \quad \frac{1}{n} \sum_{i=1}^{n} \| \bar{\eta}_{n, \alpha}(\beta) \|^{3} = o_{p}(n^{1/2}), \| \lambda \| = O_p(n^{-1/2}),
\]

(A.5)

where \( \bar{\eta}_{n, \alpha}(\beta) \) is taken to be one of \( \bar{\eta}_{l, \alpha}(\beta) \), \( \bar{\eta}_{l, m}(\beta) \) and \( \bar{\eta}_{l, \omega}(\beta) \). The values \( j = 1, 2, 3 \) correspond to \( \bar{\eta}_{l, \alpha}(\beta) \), \( \bar{\eta}_{l, m}(\beta) \) and \( \bar{\eta}_{l, \omega}(\beta) \), respectively.

Proof. We only prove the result related to \( \bar{\eta}_{l, \alpha}(\beta) \). The proofs of \( \bar{\eta}_{l, m}(\beta) \) and \( \bar{\eta}_{l, \omega}(\beta) \) can be confirmed similarly. The verification of (b) can be done by Lemma 3 given in Owen [29]. Here, we omit the details. Consider

\[
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \bar{\eta}_{l, \alpha}(\beta) = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \left( \frac{m(T_i, \theta_0)}{1 - G(Y_i)} + \frac{m(T_i, \theta_0) - m(T_i, \theta_0)}{1 - G(Y_i)} + \frac{m(T_i, \theta_0)(\bar{G}_n(Y_i) - G(Y_i))}{(1 - G_n(Y_i)) (1 - G(Y_i))} \right) \bar{\xi}_i (Y_i - \bar{\xi}_i \tilde{\beta}) + \Sigma_{\beta}
\]

(A.6)

From Theorem 3, we have

\[
D_1 = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \bar{\xi}^2_u (U_i) \bar{\xi}_i (M_i - S_i \mathbf{e}) + \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \bar{\xi}^2_u (U_i) \bar{\xi}_i (S_i - \mathbf{e}) \beta
\]
Since $M_i - S_i M = Z_i^* a(U_i) O_p$. Under assumption (C10), we have $D_{11} = o_p(1)$. Under assumption (C5), we have $S_i e = Z_i^* O_p(\log n h/m)$. On applying assumption (C10), one can get

$$D_{12} = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} m(T_i, \theta_0) [\tilde{\xi}_i - \Phi(U_i) \Gamma^{-1}(U_i) \Phi^T(U_i)] e_i + o_p(1).$$

(A.8)

Applying $S_i e = Z_i^* I^{-1}(U_i) E[Z_i e^T U_i] (1 + O_p(y_n)) = 0$, we have

$$D_{13} = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} m(T_i, \theta_0) [\tilde{\xi}_i - \Phi(U_i) \Gamma^{-1}(U_i) \Phi^T(U_i)] e_i + o_p(1).$$

(A.9)

Recalling Remark 1 and from the results in Theorem 3, it is easy to prove

$$D_2 = \frac{1}{n^{1/2}} \sum_{i=1}^{n} m(T_i, \theta_0) [\tilde{\xi}_i - \Phi(U_i) \Gamma^{-1}(U_i) \Phi^T(U_i)] e_i + o_p(1).$$

(A.10)

Under the missing mechanism and similar to the proof of $D_{11}$, it is easy to prove that $D_{2i} = o_p(1)$ for $i = 1, 2, 3, 4$. Hence, we have $D_2 = o_p(1)$. Consider

$$D_3 = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} m(T_i, \theta_0) (\tilde{\xi}_i (Y_i - \bar{X}_i) + \Sigma e)$$

$$= D_{31} + D_{32} + D_{33}.$$  

From Lemma A.4, we have

$$D_{31} = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} m(T_i, \theta_0) (\tilde{\xi}_i (Y_i - \bar{X}_i) + \Sigma e)$$

$$= D_{311} + D_{312} + D_{313} + D_{314} + D_{315}.$$
It is easy to prove \( M_i - S_i M = Z_i' \alpha(U_i)O_p(y_n) \), and we have \( D_{311} = o_p(1) \) under assumption (C10).

\[
E[D_{312}]^2 = \frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{n} E \left\{ \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \xi(Y_j, \delta_j, \zeta_j; Y_i) \sigma^{-2}(U_i) \xi(e_i - S_i \epsilon) \right\}^2 \\
\leq \frac{C}{n} E \left\{ \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \xi(Y_j, \delta_j, \zeta_j; Y_i) \sigma^{-2}(U_i) \xi(e_i - S_i \epsilon) \right\}^2 = O_p(n^{-1}).
\]

(A.13)

Hence, \( D_{312} = o_p(1) \). Similarly, we have \( D_{313} = o_p(1) \) and \( D_{314} = o_p(1) \). Compared with \( D_{311}, D_{315} \) is far smaller than \( D_{311} \), and then \( D_{315} = o_p(1) \). From Theorem 3, we have \( D_{32} = o_p(1) \). Similarly, \( D_{33} = o_p(1) \). Hence, we have \( D_3 = o_p(1) \). Note that \( m(T_i, \theta_0) - m(T_i, \theta_0) = \nabla m(T_i, \theta_0)(\hat{\theta}_n - \theta_0) + o_p(1) \). From assumption (C9), we get
\[
\max_{i \leq n} |m(T, \hat{\theta}_n) - m(T, \theta_0)| = O_p(n^{-1/2}).
\]

(A.14)

Thus, it can be checked that \( D_4 = o_p(1) \). Hence, combining with \( D_{14} \) and collecting the results above, one can obtain
\[
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \tilde{\eta}_{i,c}(\beta) = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \left\{ \xi_i - 1 \right\} + \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \xi_i + o_p(1).
\]

(A.15)

By the central limit theorem, we have
\[
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \tilde{\eta}_{i,c}(\beta) \xrightarrow{D} N(0, \Sigma_{11}).
\]

(A.16)

It follows from the law of large numbers that
\[
\frac{1}{n} \sum_{i=1}^{n} \tilde{\eta}_{i,c}(\beta) \tilde{\eta}_{i,c}^\top(\beta) \Sigma_{11}.
\]

(A.17)

Consider the partial derivative of \( \tilde{\eta}_{i,c}(\beta) \) with respect to \( \beta \), and then
\[
\Sigma_\epsilon = \frac{1}{n} \sum_{i=1}^{n} m(T_i, \tilde{\theta}_n) \frac{m(T_i, \tilde{\theta}_n) - m(T_i, \theta_0)}{1 - G(Y_i)} + \frac{m(T_i, \theta_0)(G_n(Y_i) - G(Y_i))}{1 - G(Y_i)} + \frac{(m(T_i, \tilde{\theta}_n) - m(T_i, \theta_0))(G_n(Y_i) - G(Y_i))}{1 - G(Y_i)} (\tilde{\xi}_i - \epsilon_s)
\]

(A.22)

\[
= \Sigma_{c1} + \Sigma_{c2} + \Sigma_{c3} + \Sigma_{c4}.
\]
Recalling the definition of $\bar{e}_i$ in Section 2, then we have

$$\Sigma_{c_1} = \frac{1}{n} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} (X_i - S_iX) \top (X_i - S_iX) + \frac{1}{n} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} (e_i - S_ie) \top (e_i - S_ie) - \Sigma_c$$

(A.23)

$$(X_i - S_iX) \top (X_i - S_iX) + (e_i - S_ie) \top (e_i - S_ie) - \Sigma_c = \Sigma_{c_{11}} + \Sigma_{c_{12}} + \Sigma_{c_{13}} + \Sigma_{c_{14}}.$$

Standard computations yield that $S_iX = Z_i \Gamma^{-1} (U_i) \Phi (U_i)$ $(1 + O_p (y_n))$; then, it is easy to calculate

$$\Sigma_{c_{11}} = \frac{1}{n} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] \top \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] + o_p (1).$$

(A.24)

Note that $S_ie = Z_i \Gamma^{-1} (U_i) E[Z_i e_i \top | U_i] (1 + O_p (y_n)) = 0$. Hence, we have $\Sigma_{c_{12}} = o_p (1)$, $\Sigma_{c_{13}} = o_p (1)$ and $\Sigma_{c_{14}} = (1/n) \sum_{i=1}^{n} (m(T_i, \theta_0)/1 - G(Y_i)) (e_i e_i \top - \Sigma_c) = 0$. Thus, it can be concluded that

$$\Sigma_{c_1} = \frac{1}{n} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] \top \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] + o_p (1).$$

(A.25)

Note that $\max_{1 \leq i \leq n} |m(T_i, \theta_0) - m(T_i, \theta_0)| = O_p (n^{-1/2})$, which indicates that $\Sigma_{c_{2}} = o_p (1)$. Consider

$$\Sigma_{c_3} = \frac{1}{n} \sum_{i=1}^{n} \left\{ \frac{m(T_i, \theta_0) (\bar{G}_n (Y_i) - G(Y_i))}{(1 - G(Y_i))^2} + \frac{m(T_i, \theta_0) (\bar{G}_n (Y_i) - G(Y_i))^2}{(1 - G(Y_i))^2 (1 - \bar{G}_n (Y_i))} \right\} (\bar{\xi}_i \bar{\xi}_i \top - \Sigma_c) = \Sigma_{c_{31}} + \Sigma_{c_{32}}.$$

(A.26)

In terms of the expansion of $\bar{G}_n (Y_i) - G(Y_i)$ in Lemma A.4, one can get

$$\Sigma_{c_{31}} = \frac{1}{n} \sum_{i=1}^{n} \left\{ \frac{1}{n} \sum_{j=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} (\bar{Y}_j - \bar{Y}_i) \top (\bar{Y}_j - \bar{Y}_i) + R_n (\bar{Y}_i) \right\} (\bar{\xi}_i \bar{\xi}_i \top - \Sigma_c) = \Sigma_{c_{311}} + \Sigma_{c_{312}}.$$

(A.27)

Note that $E[\bar{\xi}_i \bar{\xi}_i \top | Y_i] = 0$. Based on the independence of $\{Y_i, \delta_i, \xi_i\}$, then we have $E[\Sigma_{c_{311}}] = O_p (n^{-1})$. Hence, it holds that $\Sigma_{c_{311}} = o_p (n^{-1/2})$. Compared with $\Sigma_{c_{311}}$, $\Sigma_{c_{312}}$ is far smaller than $\Sigma_{c_{311}}$, and then $\Sigma_{c_{312}} = o_p (1)$. Similarly, $\Sigma_{c_{31}} = o_p (1)$ and $\Sigma_{c_{32}} = o_p (1)$. Hence, we have $\Sigma_{c_3} = o_p (1)$. Following (A.20) in Lemma A.4, it is easy to prove $\Sigma_{c_4} = o_p (1)$. Collecting the results above, we have

$$\Sigma_{c} = \frac{1}{n} \sum_{i=1}^{n} \frac{m(T_i, \theta_0)}{1 - G(Y_i)} \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] \top \left[ X_i - Z_i \Gamma^{-1} (U_i) \Phi (U_i) \right] + o_p (1).$$

(A.28)
Analogous to the arguments as the proof of Lemma A.6 (a), then one can obtain

\[
A_z = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} m(T_i, \theta_i) \left\{ [\xi_i - \Phi(U_i)] \Phi^\top(U_i) \right\} (\xi_i - e_i \beta) + \Sigma_c \beta + o_p(1). \tag{A.29}
\]

Collecting the results above, the proof of Theorem 1 is completed.

Proof of Theorem 2. We only prove the results about \( \tilde{\alpha}_c(u) \). The results related on \( \tilde{\alpha}_m(u) \) and \( \tilde{\alpha}_w(u) \) can be proved similarly. By the definition of \( \tilde{\alpha}_c(u) \), we can write

\[
\tilde{\alpha}_c(u) - \alpha(u) = \left( I_q \right) [D_n^\top \omega \Delta D_n]^{-1} D_n^\top \Delta \omega_n (M - Z \alpha(u))
\]

\[
+ (I_q) [D_n^\top \omega \Delta D_n]^{-1} D_n^\top \Delta \omega_n \left( \epsilon - e \beta \right)
\]

\[
+ (I_q) [D_n^\top \omega \Delta D_n]^{-1} D_n^\top \Delta \omega_n \left( X(\beta - \bar{\beta}) + e \beta \right)
\]

\[
+ (I_q) [D_n^\top \omega \Delta D_n]^{-1} D_n^\top \Delta \omega_n \left( \tilde{\alpha}_c - \Delta \right) \omega_n (M + \epsilon - e \beta + X(\beta - \bar{\beta})) + O_p(n^{-1/2})
\]

\[
= B_1 + B_2 + B_3 + B_4.
\]

By Taylor expansion, it can be checked that

\[
M = \begin{pmatrix}
Z_1^\top \alpha(u) + (U_1 - u)Z_1^\top \alpha'(u) + \frac{1}{2}(U_1 - u)^2 Z_1^\top \alpha''(u) \\
\vdots \\
Z_n^\top \alpha(u) + (U_n - u)Z_n^\top \alpha'(u) + \frac{1}{2}(U_n - u)^2 Z_n^\top \alpha''(u)
\end{pmatrix} + o_p(h_{in}^2). \tag{A.31}
\]

Hence, from assumption (C5), we have

\[
B_1 = \frac{1}{2} h_{in}^2 \alpha''(u) + o_p(h_{in}^2). \tag{A.32}
\]

One direct simplification implies

\[
B_2 = g^{-1}(u) \Gamma^{-1}(u) \frac{1}{\sqrt{n h_{in}}} \sum_{i=1}^{n} m(T_i, \theta_i) Z_i K \left( \frac{U_i - u}{h_{in}} \right) (\xi_i - e_i \beta).
\]

\[
B_3 = O_p(n^{-1/2}). \tag{A.33}
\]

Theorem 1 implies that \( \|\bar{\beta} - \beta\| = O_p(n^{-1/2}) \). It is easy to verify that \( B_3 = O_p(n^{-1/2}) \) and \( B_4 = O_p(n^{-1/2 + 1/2}) \). Hence, we have

\[
\sqrt{n h_{in}} \left( \tilde{\alpha}_c(u) - \alpha(u) - \frac{1}{2} h_{in}^2 \alpha''(u) \right)
\]

\[
= g^{-1}(u) \Gamma^{-1}(u) \frac{1}{\sqrt{n h_{in}}} \sum_{i=1}^{n} m(T_i, \theta_i) Z_i K \left( \frac{U_i - u}{h_{in}} \right) (\xi_i - e_i \beta).
\]

By Slutsky's theorem, we finish the proof of Theorem 2.

Proof of Theorem 3. We only prove the results about \( \tilde{\alpha}_c(u) \). The results related on \( \tilde{\alpha}_m(u) \) and \( \tilde{\alpha}_w(u) \) can be proved similarly. To save space, here, we omit the details. Denote \( M_i = Z_i \alpha(U_i) \) and \( \tilde{M}_i = Z_i \tilde{\alpha}_c(U_i) \). Note that
\[ \hat{\sigma}_c^2(u) - \sigma^2(u) = \left\{ \sum_{i=1}^{n} \varepsilon_i W_m(u) \varepsilon_i - \sigma^2(u) \right\} - 2 \sum_{i=1}^{n} \left[ (M_i - \tilde{M}_i)^\top W_m(u) \varepsilon_i \right. \\
\left. - 2 \sum_{i=1}^{n} \left[ X_i \left( \tilde{\beta}_c - \beta \right) \right]^\top W_m(u) \varepsilon_i + \sum_{i=1}^{n} X_i \left( \tilde{\beta}_c - \beta \right) \right]^\top W_m(u) X_i \left( \tilde{\beta}_c - \beta \right) \\
+ \sum_{i=1}^{n} (M_i - \tilde{M}_i)^\top W_m(u) X_i \left( \tilde{\beta}_c - \beta \right) + \sum_{i=1}^{n} (M_i - \tilde{M}_i)^\top W_m(u) (M_i - \tilde{M}_i) \\
+ \left\{ \sum_{i=1}^{n} \left( e_j \right) W_m(u) (e_j) - \tilde{\beta}_c \Sigma \right\} =: Q_i \]  
(A.35)

Following Lemma 4.1 in Chiu [30], it is easy to prove that \( \sup_i \sum_i \varepsilon_i W_m(u) \varepsilon_i - \sigma^2(u) = O_p(\rho_n) \). From Theorem 3.5 in You and Chen [1], we have \( \sup \| \tilde{a}_c - (u) - \alpha(u) \| = O_p(\rho_n) \), which indicates that \( M_i - \tilde{M}_i = O_p(\rho_n) \). Based on the fact that \( \| \tilde{\beta}_c - \beta \| = O_p(n^{-1/2}) \), it is easy to prove \( Q_i = O_p(\rho_n) \) for \( i = 2, 3, \ldots, 8 \). In terms of Lemma A.2, one can obtain \( \sup_i |Q_i| = O_p(\rho_n) \), which completes the proof of Theorem 3.

\textbf{Proof.} of Theorem 4. Based on Theorem 3, similar to the arguments, the proof of Theorems 1 and 4 can be verified easily. \( \square \)

\textbf{Proof.} of Theorem 5. Theorem 1 implies that \( \| \tilde{a}_n - \beta \| = O_p(n^{-1/2}) \) and \( \sup \| \tilde{a}_n(u) - \alpha(u) \| = O_p(\rho_n) \). Analogous to the proof of Theorem 3, it is easy to verify Theorem 5. \( \square \)

\textbf{Proof.} of Theorem 6. Applying the Taylor expansion for the empirical log-likelihood ratio function, then we have

\[ \hat{\lambda}_n(\beta) = \left\{ \frac{1}{n} \sum_{i=1}^{n} \tilde{\eta}_{i,n}(\beta) \right\}^\top \left\{ \sum_{i=1}^{n} \tilde{\eta}_{i,n}(\beta) \tilde{\eta}_{i,n}(\beta) \right\}^{-1} \left\{ \frac{1}{n} \sum_{i=1}^{n} \tilde{\eta}_{i,n}(\beta) \right\} + o_p(1), \]  
(A.39)

in which, together with Lemma A.6, the proof of Theorem 6 is finished. \( \square \)

\textbf{Proof.} of Theorem 7. For convenience, let

\[ \Lambda_{jn}(\beta, \lambda) = \frac{1}{n} \sum_{i=1}^{n} \tilde{\eta}_{i,n}(\beta) \left( \frac{\partial \tilde{\eta}_{i,n}(\beta)}{\partial \beta} \right) \lambda, \]  
(A.40)

\[ \Lambda_{2n}(\beta, \lambda) = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{1 + \lambda \tilde{\eta}_{i,n}(\beta)} \tilde{\eta}_{i,n}(\beta). \]

Note that \( \beta^* \) and \( \lambda^* = \lambda(\beta^*) \) satisfy \( \Lambda_{jn}(\beta^*, \lambda^*) = 0 \) and \( \Lambda_{2n}(\beta^*, \lambda^*) = 0 \). By expanding \( \Lambda_{jn}(\beta^*, \lambda^*) = 0 \) at \( (\beta^*, 0)^\top \) for \( j = 1, 2 \), it can be shown that

\[ 0 = \Lambda_{jn}(\beta^*, \lambda^*) = \Lambda_{jn}(\beta, 0) + \frac{\partial \Lambda_{jn}(\beta, 0)}{\partial \beta} (\beta^* - \beta) + \frac{\partial \Lambda_{jn}(\beta, 0)}{\partial \lambda} \lambda^* + o_p(\|\beta\|), \]  
(A.41)

where \( \|\beta\| = \|\beta^* - \beta\| + \|\lambda^*\| \). Hence,
From Lemma A.6, we have $(1/n) \sum_{i=1}^{n} \tilde{h}_{i,n}(\beta) = O_{P}(n^{-1/2})$, $\|\tilde{\theta}_{n}\| = O_{P}(n^{-1/2})$ and $(1/n) \sum_{i=1}^{n} \partial \tilde{h}_{i,n}(\beta)/\partial \beta = -\Sigma_{12} (1 + o_{n}(1))$ which, together with Lemma A.6, shows the proof of Theorem 7.

**Data Availability**

The simulation study is based on the Monte Carlo simulation to study the finite sample performance of the proposed estimators. The real dataset is in [25]. Clinical trial E1178 conducted by the Eastern Cooperative Oncology Group compared tamoxifen therapy and placebo in elderly (age 65) women with stage II breast cancer.

**Conflicts of Interest**

The authors declare that they have no conflicts of interest.

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