

Research Article

Some Properties of Solutions to Weakly Hypoelliptic Equations

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A linear different operator L is called weakly hypoelliptic if any local solution u of $Lu = 0$ is smooth. We allow for systems, that is, the coefficients may be matrices, not necessarily of square size. This is a huge class of important operators which cover all elliptic, overdetermined elliptic, subelliptic, and parabolic equations. We extend several classical theorems from complex analysis to solutions of any weakly hypoelliptic equation: the Montel theorem providing convergent subsequences, the Vitali theorem ensuring convergence of a given sequence, and Riemann's first removable singularity theorem. In the case of constant coefficients, we show that Liouville's theorem holds, any bounded solution must be constant, and any L^p -solution must vanish.

1. Introduction

Hypoelliptic partial differential equations form a huge class of linear PDEs many of which are very important in applications. This class contains all elliptic, overdetermined elliptic, subelliptic, and parabolic equations. Recall that a linear differential operator L is called hypoelliptic if any solution u to $Lu = f$ is smooth wherever f is smooth. The study of hypoelliptic operators was initiated by Hörmander and others; see, for example, [1–4].

We generalize this class of operators even further by only demanding that any solution u to $Lu = 0$ be smooth. We call such operators *weakly hypoelliptic*. This is not to be confused with partially hypoelliptic operators as introduced by Gårding and Malgrange [5] nor with the almost hypoelliptic operators due to Elliott [6]. We show by example that the class of weakly hypoelliptic operators is strictly larger than that of hypoelliptic operators. The example of a weakly hypoelliptic but nonhypoelliptic operator that we give is defined on \mathbb{R}^2 and is overdetermined elliptic on $\mathbb{R}^2 \setminus \{0\}$. It is of first order, and its principal symbol vanishes at 0. Thus, the class of weakly hypoelliptic operators allows for a certain degeneracy of the principal symbol on “small sets” and might be of interest for geometric applications.

Holomorphic functions are the solutions to the Cauchy-Riemann equations which are elliptic in the case of one variable and overdetermined elliptic in the case of several

variables. In any case, they are characterized as solutions to certain hypoelliptic PDEs. We show that the solutions to any weakly hypoelliptic equation share some of the nice properties of holomorphic functions which are familiar from classical complex analysis.

Montel's theorem says that a locally bounded sequence of holomorphic functions subconverges to a holomorphic function. This does not hold for real analytic functions. For instance, the sequence $u_j(x) = \cos(jx)$ is a uniformly bounded sequence of real-analytic functions on \mathbb{R} but does not have a convergent subsequence; see, for example, [7, Ex. 1.4.34]. We show that even a slightly stronger version of the Montel theorem holds for solutions to any weakly hypoelliptic equation: any locally L^1 -bounded sequence subconverges in the C^∞ -topology to a solution (Theorem 4). The Vitali theorem for holomorphic functions has a similar generalization (Theorem 6). For hypoelliptic equations, this has been known for many decades and has motivated the study of so-called Montel spaces in functional analysis.

In case the underlying domain is \mathbb{R}^n and the weakly hypoelliptic operator has constant coefficients and satisfies a weighed homogeneity condition, we show that the Liouville theorem holds: any bounded solution must be constant (Theorem 7), and any L^p -solution must be zero (Theorem 12). This applies to powers of the Laplace and Dirac operators but also to powers of the heat operator. In the proof, we

use a simple scaling argument and apply the general Montel theorem.

Finally, we generalize Riemann's first removable singularity theorem and show that a solution to a weakly hypoelliptic equation can be extended across a submanifold S of sufficiently high codimension provided that the solution is locally bounded near S (Theorem 14 and Corollary 15).

The general setup is such that we consider a linear differential operator L acting on sections of vector bundles. So, locally, L describes a system of linear PDEs with smooth coefficients. These coefficients may be matrices of not necessarily square size. Readers who are not too fond of geometric terminology may simply replace "manifolds" by "open subsets of \mathbb{R}^n " and "sections of vector bundles" by "vector-valued functions."

The classical proofs of these theorems for holomorphic functions are typically based on special properties of holomorphic functions such as Cauchy's integral formula. Therefore they may create the misleading impression that these theorems are also very special for holomorphic functions. In the contrary, the above mentioned theorems remain true for all solutions of the largest class of linear PDEs where one could hope for them to hold. Moreover, as we will see, the proofs of the general statements are actually rather simple.

2. Weakly Hypoelliptic Operators

Let M be an n -dimensional differentiable manifold equipped with a smooth positive n -density vol . Let $E \rightarrow M$ and $F \rightarrow M$ be real vector bundles. If the bundles are complex we simply forget the complex structure and consider them as real bundles. We denote the spaces of smooth sections by $C^\infty(M, E)$ and $C^\infty(M, F)$, respectively. Let $L : C^\infty(M, E) \rightarrow C^\infty(M, F)$ be a linear differential operator of order $k \in \mathbb{N}$. The fact that smooth sections are mapped to smooth sections encodes the smoothness of the coefficients of L in local coordinates. The operator L restricts to a linear map $\mathcal{D}(M, E) \rightarrow \mathcal{D}(M, F)$ where \mathcal{D} stands for compactly supported smooth sections.

Let $E^* \rightarrow M$ and $F^* \rightarrow M$ be the dual bundles. Given L , there is a unique linear differential operator $L^* : C^\infty(M, F^*) \rightarrow C^\infty(M, E^*)$, the *formally dual operator*, characterized by

$$\int_M \langle Lu, \varphi \rangle \text{vol} = \int_M \langle u, L^* \varphi \rangle \text{vol} \quad (1)$$

for all $u \in C^\infty(M, E)$ and $\varphi \in C^\infty(M, F^*)$ such that $\text{supp}(u) \cap \text{supp}(\varphi)$ is compact. Here $\langle \cdot, \cdot \rangle$ denote the canonical pairing of E and E^* and of F and F^* .

We extend L to an operator, again denoted by L , mapping distributional sections to distributional sections, $L : \mathcal{D}'(M, E) \rightarrow \mathcal{D}'(M, F)$ by

$$(Lu)[\varphi] := u[L^* \varphi] \quad (2)$$

for all $u \in \mathcal{D}'(M, E)$ and $\varphi \in \mathcal{D}(M, F^*)$, compare for example, [8, Sec. 1.1.2]. Here we denote by $u[\psi]$ the evaluation of the distribution $u \in \mathcal{D}'(M, E)$ on the test section $\psi \in \mathcal{D}(M, E^*)$.

The differential operator L is called *hypoelliptic* if for any open subset $\Omega \subset M$ and any $u \in \mathcal{D}'(\Omega, E)$ such that Lu is smooth we have that u is smooth. Since we will be interested in solutions of $Lu = 0$ only, we make the following definition: The differential operator L is called *weakly hypoelliptic* if for any open subset $\Omega \subset M$ any $u \in \mathcal{D}'(\Omega, E)$ satisfying $Lu = 0$ must be smooth. Hörmander's work [1, Ch. III] (see also the proof of Theorem 2.1 in [9, p. 63]) shows that for operators with constant coefficients over $M = \mathbb{R}^n$ hypoellipticity and weak hypoellipticity are equivalent, at least in the scalar case, that is, if the coefficients of L are scalars rather than matrices. It seems likely that this is also true if the coefficients are constant matrices. In general however, if the coefficients are variable, the class of weakly hypoelliptic operators is strictly larger than that of hypoelliptic operators.

Example 1. Let $M = \mathbb{R}^2$, let E be the trivial real line bundle and F the trivial \mathbb{R}^2 -bundle. The operator $L = (L_1, L_2) : C^\infty(\mathbb{R}^2, \mathbb{R}) \rightarrow C^\infty(\mathbb{R}^2, \mathbb{R}^2)$ is given by

$$\begin{aligned} L_1 &= r \frac{\partial}{\partial r} - 2 = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} - 2, \\ L_2 &= r \frac{\partial}{\partial \theta} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}. \end{aligned} \quad (3)$$

Here (x, y) are the usual Cartesian coordinates while (r, θ) denote polar coordinates, $x = r \cos(\theta)$, $y = r \sin(\theta)$. On $\mathbb{R}^2 \setminus \{0\}$ the operator L is overdetermined elliptic (see below) and hence hypoelliptic. But L is not hypoelliptic on \mathbb{R}^2 because $u = r^2 \log r$ is not smooth while $Lu = (r^2, 0)$ is smooth.

We check that L is weakly hypoelliptic. Regularity is an issue at the origin only. Let $u \in \mathcal{D}'(\Omega, \mathbb{R})$ with $Lu = 0$ where Ω is an open disk in \mathbb{R}^2 centered at the origin. Then u is smooth on $\Omega \setminus \{0\}$. From $L_1 u = 0$ we see that $u = \alpha(\theta)r^2$ on $\Omega \setminus \{0\}$ and $L_2 u = 0$ shows that α does not depend on θ . Hence $u = \alpha r^2 = \alpha \cdot (x^2 + y^2)$ on $\Omega \setminus \{0\}$. Subtracting this smooth function we may without loss of generality assume that $\text{supp}(u) \subset \{0\}$. In this case, u is a linear combination of the delta function and its derivatives:

$$u = \sum_{i,j} \beta_{ij} \frac{\partial^{i+j} \delta_0}{\partial x^i \partial y^j}. \quad (4)$$

Fix i_0 and j_0 , and choose a test function $\varphi \in C_c^\infty(\Omega, \mathbb{R})$ which coincides with the monomial $x^{i_0} y^{j_0}$ on a neighborhood of the origin. Then, we see

$$\begin{aligned} 0 &= L_1 u[\varphi] \\ &= u \left[-\frac{\partial(x\varphi)}{\partial x} - \frac{\partial(y\varphi)}{\partial y} - 2\varphi \right] \\ &= u [-(i_0 + 1 + j_0 + 1 + 2) \cdot \varphi] \\ &= -(4 + i_0 + j_0) \cdot \sum_{i,j} \beta_{ij} \cdot (-1)^{i+j} \cdot \delta_0 \left[\frac{\partial^{i+j} \varphi}{\partial x^i \partial y^j} \right] \\ &= -(4 + i_0 + j_0) \cdot \beta_{i_0 j_0} \cdot (-1)^{i_0 + j_0} \cdot i_0! \cdot j_0!. \end{aligned} \quad (5)$$

Thus $\beta_{i_0 j_0} = 0$ for all i_0 and j_0 and therefore $u = 0$. To summarize, we have seen that L is weakly hypoelliptic, but not hypoelliptic.

For any weakly hypoelliptic operator we denote the kernel of $L : \mathcal{D}'(M, E) \rightarrow \mathcal{D}'(M, F)$ by $\mathcal{H}(M, L) \subset C^\infty(M, E)$.

For $j \in \mathbb{N}_0$ and any relatively compact measurable subset $A \subset M$ we define the C^j -norm of $u \in C^j(M, E)$ by

$$\|u\|_{C^j(A)} := \sup_{x \in A} \max \left(\left| \nabla^j u(x) \right|, \dots, |\nabla u(x)|, |u(x)| \right). \tag{6}$$

Here we have tacitly equipped E and the tangent bundle TM with a Riemannian metric and a connection ∇ . These data induce fiberwise norms and connections on the bundles $T^*M \otimes \dots \otimes T^*M \otimes E$. Note that $\nabla^j u$ is a section of $\underbrace{T^*M \otimes \dots \otimes T^*M}_{j \text{ factors}} \otimes E$. Since A is relatively compact, different

choices of metric and connections yield equivalent C^j -norms.

If $K \subset M$ is a compact subset, then we denote by $C^j(K, E)$ the set of all restrictions to K of j -times continuously differentiable sections, defined on an open neighborhood of K . Equipped with the norm $\|\cdot\|_{C^j(K)}$, $C^j(K, E)$ becomes a Banach space.

Similarly, we define the L^p -norm for $1 \leq p < \infty$ by

$$\|u\|_{L^p(A)}^p := \int_A |u|^p \text{vol}(x). \tag{7}$$

Again, different choices of the metric and the volume density yield equivalent L^p -norms. The L^∞ -norm extends the C^0 -norm to the space of all essentially bounded measurable sections. The starting points are the following hypoelliptic estimates (compare [10, p. 331, Prop. 2] for the hypoelliptic case).

Lemma 2 (hypoelliptic estimates). *Let L be weakly hypoelliptic. Then, for any $j \in \mathbb{N}$, for any compact subset $K \subset M$, and any open subset $\Omega \subset M$ containing K , there is a constant $C > 0$ such that*

$$\|u\|_{C^j(K)} \leq C \cdot \|u\|_{L^1(\Omega)}, \tag{8}$$

for all $u \in \mathcal{H}(M, L)$.

Proof. Let V be the kernel of the continuous linear map $L : L^1(\Omega, E) \subset \mathcal{D}'(\Omega, E) \rightarrow \mathcal{D}'(\Omega, F)$. Hence V is a closed subspace of $L^1(\Omega, E)$ and thus a Banach space with the norm $\|\cdot\|_{L^1(\Omega)}$. Since L is weakly hypoelliptic we have $V \subset C^\infty(\Omega, E)$. Thus we get the linear restriction map $\text{res} : V \rightarrow C^j(K, E)$, $u \mapsto u|_K$.

This map is closed. Namely, let $u_i \rightarrow u$ with respect to $\|\cdot\|_{L^1(\Omega)}$ and $\text{res}(u_i) \rightarrow v$ with respect to $\|\cdot\|_{C^j(K)}$. Then we also have $\text{res}(u_i) \rightarrow v$ with respect to $\|\cdot\|_{L^1(K)}$ and therefore $\text{res}(u) = v$ which proves closedness.

The closed graph theorem implies that res is bounded which is (8) for all $u \in \mathcal{H}(\Omega, L)$. In particular, (8) holds for all $u \in \mathcal{H}(M, L)$. \square

Corollary 3. *Let L be a weakly hypoelliptic operator over a compact manifold M (without boundary). Then $\mathcal{H}(M, L)$ is finite-dimensional.*

Proof. Since M is compact, we can take $K = \Omega = M$ in Lemma 2. Thus, the C^0 -norm and the C^1 -norm are equivalent on $\mathcal{H}(M, L)$. By the Arzelà-Ascoli theorem the embedding $C^1(M, E) \hookrightarrow C^0(M, E)$ is compact. Hence the identity map on $\mathcal{H}(M, L)$ is compact; thus $\mathcal{H}(M, L)$ is finite dimensional. \square

A differential operator L is called *elliptic* if the principal symbol $\sigma_L(\xi)$ is invertible for all nonzero covectors $\xi \in T^*M$. Elliptic regularity theory implies that all elliptic operators are hypoelliptic; see [11, Thm. 11.1.10] or [12, Ch. III, Sec. 5]. The class of elliptic operators contains many examples of high importance for applications such as the Laplace and Dirac operator.

More generally, if the principal symbol $\sigma_L(\xi)$ is injective instead of bijective for all nonzero covectors $\xi \in T^*M$, then one calls L *overdetermined elliptic*. In this case L^*L is elliptic where L^* denotes the formal adjoint of L . Now if $Lu|_\Omega$ is smooth, so is $L^*Lu|_\Omega$ and hence $u|_\Omega$ is smooth by elliptic regularity. Therefore overdetermined elliptic operators are hypoelliptic as well.

Another way to generalize elliptic operators within the class of hypoelliptic operators is to consider *subelliptic operators with a loss of δ derivatives* where $\delta \in (0, 1)$. These operators can also be characterized by a condition on their principal symbol; see [13, Ch. XXVII] for details.

If L is *parabolic*, for example, if L describes the heat equation on a Riemannian manifold, then parabolic regularity using anisotropic Sobolev spaces shows that L is hypoelliptic; see for example, [14, Sec. 6.4].

In contrast, hyperbolic differential operators, for example, those which describe wave equations, are not hypoelliptic.

Table 1 is a (very incomplete) table of examples for hypoelliptic operators relevant for applications.

3. Convergence Results

Let $1 \leq p \leq \infty$. A family $\mathcal{F} \subset C^\infty(M, E)$ is called *locally L^p -bounded* if for each compact subset $K \subset M$ we have

$$\sup_{u \in \mathcal{F}} \|u(x)\|_{L^p(K)} < \infty. \tag{9}$$

Let $1 \leq p \leq q < \infty$. By Hölder's inequality, $\|u\|_{L^p(K)} \leq \text{vol}(K)^{(q-p)/pq} \cdot \|u\|_{L^q(K)}$. For $q = \infty$, we have $\|u\|_{L^p(K)} \leq \text{vol}(K)^{1/p} \cdot \|u\|_{L^\infty(K)}$. Therefore, local L^q -boundedness implies local L^p -boundedness whenever $q \geq p$. In particular, local L^1 -boundedness is the weakest of these boundedness conditions.

We say that a sequence (u_j) in $C^\infty(M, E)$ converges in the C^∞ -topology if the restriction to any compact subset $K \subset M$ converges in every C^j -norm. In other words, the sections and all their derivatives converge locally uniformly.

Theorem 4 (generalized Montel theorem). *Let L be a weakly hypoelliptic operator. Then, any locally L^1 -bounded sequence $u_1, u_2, \dots \in \mathcal{H}(M, L)$ has a subsequence which converges in the C^∞ -topology to some $u \in \mathcal{H}(M, L)$.*

TABLE 1: Examples of hypoelliptic differential operators.

L	M	E	F	$\mathcal{H}(M, L)$	Type	Reference
$\partial/\partial\bar{z}$, Cauchy-Riemann	Open subset of \mathbb{C}	Trivial \mathbb{C} -line bundle	Trivial \mathbb{C} -line bundle	Holomorphic functions	Elliptic	[15, Sec. I.5]
$\bar{\partial}_E$	Complex manifold	Holomorphic vector bundle	$E \otimes T^*M^{0,1}$	Holomorphic sections	Overdet. elliptic	[16, Sec. 0.5]
$\nabla^* \nabla + l.o.t.$, Laplace-type	Riemannian manifold	Riem. vector bundle with connection	E	Harmonic sections	Elliptic	[17, Sec. 2.1]
Δ^2 , bi-Laplacian	Riemannian manifold	Trivial \mathbb{R} -line bundle	Trivial \mathbb{R} -line bundle	Biharmonic functions	Elliptic	
D , Dirac	Riemannian spin manifold	Spinor bundle	Spinor bundle	Harmonic spinors	Elliptic	[12, Ch. II, §5]
$\partial/\partial t - \Delta$, heat operator	Interval \times Riemannian manifold	Trivial \mathbb{R} -line bundle	Trivial \mathbb{R} -line bundle		Parabolic	[14, Sec. 6.4]
Δ_X , sub-Laplacian	Sub-Riemannian manifold (bracket generating)	Trivial \mathbb{R} -line bundle	Trivial \mathbb{R} -line bundle		Subelliptic	[18, Thm. 1.1]
$\sum_j X_j^* X_j$, where $X_j =$ complex vector fields (bracket cond.)	\mathbb{R}^n	Trivial \mathbb{C} -line bundle	Trivial \mathbb{C} -line bundle		Sobolev-subell.	[19, Thm. C]
Bismut's hypoelliptic Laplacian	T^*X	$\oplus_{j=0}^n \wedge^j T^*T^*X$	E		Hypoelliptic	[20, Ch. 3]
$\partial^2/\partial x^2 + x\partial/\partial y - \partial/\partial t$, Kolmogorov	$(0, \infty) \times \mathbb{R}^2$	Trivial \mathbb{R} -line bundle	Trivial \mathbb{R} -line bundle		Hypoelliptic	[21, Sec. 22.2]

The experts will notice that this is a direct consequence of Lemma 2 because we have the following.

Proof (short). By Lemma 2, the sequence u_1, u_2, \dots is bounded with respect to the C^∞ -topology (in the sense of topological vector spaces). Since $C^\infty(M, E)$ is known to be a Montel space [22, p. 148, Cor. 2] so is the closed subspace $\mathcal{H}(M, L)$ (when equipped with the C^∞ -topology). This means that bounded closed subsets are compact; hence u_1, u_2, \dots has a convergent subsequence. \square

For those unfamiliar with the theory of Montel spaces, we can also provide the following.

Proof (elementary). Let $K \subset M$ be a compact subset. We choose an open, relatively compact subset $\Omega \Subset M$ containing K . We fix $j \in \mathbb{N}$. Since, by Lemma 2,

$$\|u_\nu\|_{C^{j+1}(K)} \leq C \cdot \|u_\nu\|_{L^1(\Omega)} \leq C \cdot \|u_\nu\|_{L^1(\bar{\Omega})} \leq C', \quad (10)$$

the sequence $(u_\nu)_\nu$ is bounded in the C^{j+1} -norm. By the Arzelà-Ascoli theorem there is a subsequence which converges in the C^j -norm over K . The diagonal argument yields a subsequence which converges in all C^j -norms over K , $j \in \mathbb{N}$.

Now we exhaust M by compact sets $K_1 \subset K_2 \subset K_3 \subset \dots \subset M$. We have seen that over each K_μ we can pass to a subsequence converging in all C^j -norms. Applying the diagonal argument once more, we find a subsequence converging in all C^j -norms over all K_μ . Thus we found a subsequence which converges in the C^∞ -topology to some $u \in C^\infty(M, E)$.

Since $L : C^\infty(M, E) \rightarrow C^\infty(M, F)$ is (sequentially) continuous with respect to the C^∞ -topology, we have $Lu = 0$, that is, $u \in \mathcal{H}(M, L)$. \square

The generalized Montel theorem applies to all examples listed in Table 1. Even in the case of holomorphic functions (in one or several variables) Theorem 4 is a slight improvement over the classical Montel theorem because the classical condition of local L^∞ -boundedness is replaced by the weaker condition of local L^1 -boundedness. The standard proof of the classical Montel theorem uses the Cauchy integral formula to show equicontinuity and then applies the Arzelà-Ascoli theorem, see for example, [7, Sec. 1.4.3].

In the case of harmonic functions on a Euclidean domain the Montel theorem is also classical. One can use estimates based on the Poisson kernel to show equicontinuity and then apply the Arzelà-Ascoli theorem [23, p. 35, Thm. 2.6].

The Montel theorem provides a criterion for the existence of a convergent subsequence. The next theorem provides a sufficient criterion which ensures that a given sequence converges itself.

Definition 5. Let L be a weakly hypoelliptic operator on M . A subset $A \subset M$ is called a *set of uniqueness* for L if for any $u \in \mathcal{H}(M, L)$ the condition $u|_A = 0$ implies $u = 0$.

Every dense subset A of M is a set of uniqueness because $\mathcal{H}(M, L) \subset C^0(M, E)$.

For holomorphic function of one variable, that is, $L = \partial/\partial\bar{z}$, the set A is a set of uniqueness if it has an accumulation point in $M \subset \mathbb{C}$.

Many (but not all) important elliptic operators have the so-called *weak unique continuation property*. This means that if A has nonempty interior, then it is a set of uniqueness provided that M is connected. Laplace- and Dirac-type operators belong to this class.

Theorem 6 (generalized Vitali theorem). *Let L be a weakly hypoelliptic operator and let $A \subset M$ be a set of uniqueness for L . Let $u_1, u_2, \dots \in \mathcal{H}(M, L)$ be a locally L^1 -bounded sequence. Suppose that the pointwise limit $\lim_{j \rightarrow \infty} u_j(x)$ exists for all $x \in A$.*

Then, $(u_j)_j$ converges in the C^∞ -topology to some $u \in \mathcal{H}(M, L)$.

Proof. By Theorem 4, every subsequence of $(u_j)_j$ has a subsequence for which the assertion holds. The limit functions for these subsequences are in $\mathcal{H}(M, L)$ and coincide on A ; hence they all agree. Hence, $(u_j)_j$ has a unique accumulation point $u \in \mathcal{H}(M, L)$.

If the sequence $(u_j)_j$ itself did not converge to u , then we could extract a subsequence staying outside a C^∞ -neighborhood of u . But this subsequence would again have a subsequence converging to u , a contradiction. \square

4. Liouville Property

We now concentrate on the case $M = \mathbb{R}^n$. All vector bundles over \mathbb{R}^n are trivial, so sections can be identified with functions $\mathbb{R}^n \rightarrow \mathbb{R}^N$. Hence, the coefficients of the differential operator L are $N \times N'$ -matrices. If these matrices do not depend on the point $x \in \mathbb{R}^n$ we say that L has constant coefficients. The Laplace operator Δ , the Dirac operator D and the heat operator $\partial/\partial x_1 - \sum_{j=2}^n (\partial^2/\partial x_j^2)$ are examples of hypoelliptic operators on \mathbb{R}^n with constant coefficients.

Let P be a polynomial in n real variables. Here P is allowed to have matrix-valued coefficients of fixed size. Let $w = (w_1, \dots, w_n)$ with $w_j > 0$. We call P *weighed homogeneous* with weight w if $P(t^{w_1}x_1, \dots, t^{w_n}x_n) = t^k P(x_1, \dots, x_n)$ for some k and all $t \in \mathbb{R}, x = (x_1, \dots, x_n) \in \mathbb{R}^n$. The corresponding differential operator with constant coefficients $L = P(\partial/\partial x) = P(\partial/\partial x_1, \dots, \partial/\partial x_n)$ is then also called weighed homogeneous. The Dirac and Laplace operator are examples for weighed homogeneous differential operators with weight $w = (1, \dots, 1)$ as well as the heat operator (weight $w = (2, 1, \dots, 1)$).

We can now state the following Liouville-type theorem.

Theorem 7 (generalized Liouville theorem). *Let L be a weakly hypoelliptic operator over \mathbb{R}^n . Suppose that L has constant coefficients in $N' \times N$ -matrices and is weighed homogeneous.*

Then, each bounded function in $\mathcal{H}(\mathbb{R}^n, L)$ must be constant.

Proof. Let $u \in \mathcal{H}(\mathbb{R}^n, L)$ be bounded. For $\varepsilon > 0$, we put $u_\varepsilon(x) := u(\varepsilon^{-w_1}x_1, \dots, \varepsilon^{-w_n}x_n)$. Since u is bounded, the family (u_ε) is uniformly bounded. Moreover, $(Lu_\varepsilon)(x) = \varepsilon^{-k} Lu(\varepsilon^{-w_1}x_1, \dots, \varepsilon^{-w_n}x_n) = 0$ so that $u_\varepsilon \in \mathcal{H}(\mathbb{R}^n, L)$. By Theorem 4, there is a sequence $\varepsilon_j \searrow 0$ such that u_{ε_j} converges locally uniformly to some $v \in \mathcal{H}(\mathbb{R}^n, L)$. We observe $u_\varepsilon(0) = u(0)$ and hence $v(0) = u(0)$.

Fix $x \in \mathbb{R}^n$. For $\varepsilon > 0$ we put $x_\varepsilon := (\varepsilon^{w_1}x_1, \dots, \varepsilon^{w_n}x_n)$. Then $u_\varepsilon(x_\varepsilon) = u(x)$ and $x_\varepsilon \rightarrow 0$ as $\varepsilon \searrow 0$. Locally uniform convergence yields $u(x) = u_{\varepsilon_j}(x_{\varepsilon_j}) \rightarrow v(0) = u(0)$, hence $u(x) = u(0)$, so u is constant. \square

Example 8. We directly recover the classical Liouville theorems for holomorphic and for harmonic functions. In the case of bounded harmonic functions Nelson gave a particularly short proof based on the mean value property [24]. In fact, for harmonic functions it suffices to assume that they are bounded from below (or from above) [23, Thm. 3.1]. This cannot be deduced from Theorem 7 but the theorem also applies to biharmonic functions on \mathbb{R}^n or to solutions of higher powers of Δ . The function $u(x) = |x|^2$ is biharmonic, bounded from below and nonconstant. Hence unlike for harmonic functions we need to assume boundedness from above and from below to conclude that a biharmonic function is constant.

Similarly, bounded harmonic spinors on \mathbb{R}^n must be constant.

Remark 9. Here is a silly argument why all bounded polynomials on \mathbb{R}^n must be constant. Given such a polynomial u choose $\ell \in \mathbb{N}$ larger than half the degree of u . Then $\Delta^\ell u = 0$ and Theorem 7 applies.

Example 10. Theorem 7 also applies to the heat operator. Bounded solutions to the heat equation on $\mathbb{R}^n = \mathbb{R} \times \mathbb{R}^{n-1}$ must be constant. Note that there do exist nontrivial solutions on \mathbb{R}^n which vanish for $x_1 \leq 0$ [25, pp. 211–213]. They are unbounded on \mathbb{R}^{n-1} for each $x_1 > 0$ however.

Moreover, Theorem 7 applies to powers of the heat operator. So, for instance, bounded solutions to

$$\left(\frac{\partial}{\partial x_1} - \sum_{j=2}^n \frac{\partial^2}{\partial x_j^2} \right)^2 u = 0 \tag{11}$$

must be constant.

Remark 11. Theorem 7 does not hold for hyperbolic operators. The function $u(x_1, x_2) = \sin(x_1) \sin(x_2)$ is non-constant, bounded and solves the wave equation $\partial^2 u / \partial x_1^2 - \partial^2 u / \partial x_2^2 = 0$. Thus Theorem 7 does not extend to partially hypoelliptic operators in the sense of Gårding and Malgrange [5].

Theorem 12 (generalized Liouville theorem, L^p -version). *Let $1 \leq p < \infty$. Let L be a weakly hypoelliptic operator over \mathbb{R}^n . Suppose that L has constant coefficients in $N' \times N$ -matrices and is weighed homogeneous. Then,*

$$\mathcal{H}(\mathbb{R}^n, L) \cap L^p(\mathbb{R}^n, \mathbb{R}^N) = \{0\}. \tag{12}$$

Proof. Let $u \in \mathcal{H}(\mathbb{R}^n, L) \cap L^p(\mathbb{R}^n, \mathbb{R}^N)$. For $\varepsilon \in (0, 1]$, define u_ε as in the proof of Theorem 7. We use the same notation as in that proof. From

$$\begin{aligned} & \|u_\varepsilon\|_{L^p(\mathbb{R}^n)}^p \\ &= \int_{\mathbb{R}^n} |u(\varepsilon^{-w_1}x_1, \dots, \varepsilon^{-w_n}x_n)|^p dx_1 \cdots dx_n \\ &= \int_{\mathbb{R}^n} |u(y_1, \dots, y_n)|^p \varepsilon^{w_1 + \dots + w_n} dy_1 \cdots dy_n \\ &\leq \|u\|_{L^p(\mathbb{R}^n)}^p < \infty, \end{aligned} \tag{13}$$

we see that $(u_\varepsilon)_\varepsilon$ is an L^p -bounded family on \mathbb{R}^n . Using Theorem 4 as in the proof of Theorem 7, we find that u is constant. Since u is also L^p , it must be zero. \square

Remark 13. In the case of scalar constant coefficient hypoelliptic operators, Theorems 7 and 12 can also be seen as follows. If the polynomial P had a zero $x \neq 0$, then P would vanish along the curve $t \mapsto (t^{w_1}x_1, \dots, t^{w_n}x_n)$ by homogeneity. This would violate Hörmander’s hypoellipticity criterion [1, Thm. 3.3.I] for $L = P(\partial/\partial x)$. Thus, $x = 0$ is the only zero of P . Now, [26, Thm. 2.28] (whose proof is a simple application of the Fourier transform) says that any solution $u \in \mathcal{H}(\mathbb{R}^n, L)$ must be a polynomial. If it is in $L^\infty(\mathbb{R}^n)$ or in $L^p(\mathbb{R}^n)$, it must be constant or vanish, respectively.

5. Removable Singularities

Let M be a Riemannian manifold, and denote the Riemannian distance of $x, y \in M$ by $d(x, y)$. For a subset $S \subset M$, let $d(x, S) := \inf_{y \in S} d(x, y)$. For $r > 0$, we denote by

$$N(S, r) := \{x \in M \mid d(x, S) \leq r\} \setminus S \tag{14}$$

the closed r -neighborhood of S with S removed.

Theorem 14. *Let $S \subset M$ be an embedded submanifold of codimension $m \geq 1$. Let L be a weakly hypoelliptic operator of order $k \geq 1$ over M . Let $u \in \mathcal{H}(M \setminus S, L)$. Suppose that for each compact subset $K \subset M$ there exists a constant $C > 0$ such that for all sufficiently small $r > 0$*

$$\|u\|_{L^1(N(S,r) \cap K)} = o(r^k) \quad \text{as } r \searrow 0. \tag{15}$$

Then u extends uniquely to some $\bar{u} \in \mathcal{H}(M, L)$.

Proof. Uniqueness of the extension is clear because $M \setminus S$ is dense in M . To show existence let $\chi : \mathbb{R} \rightarrow \mathbb{R}$ be a smooth function such that

- (i) $\chi \equiv 0$ on $(-\infty, 1/2]$;
- (ii) $\chi \equiv 1$ on $[1, \infty)$;
- (iii) $0 \leq \chi \leq 1$ everywhere.

For $r > 0$, we define $\chi_r \in C^0(M)$ by

$$\chi_r(x) := \chi\left(\frac{d(x, S)}{r}\right). \tag{16}$$

Given a compact subset $K \subset M$ the function χ_r is smooth in a neighborhood of K provided that r is small enough. This is true because the function $x \mapsto d(x, S)$ is smooth on an open neighborhood of S with S removed.

We extend u to a distribution $\bar{u} \in \mathcal{D}'(M, E)$: let $\varphi \in \mathcal{D}(M, E^*)$ be a test section. The compact support of φ is denoted by K . For $r > 0$ sufficiently small $\chi_r \varphi \in \mathcal{D}(M \setminus S, E^*)$, we put

$$\bar{u}[\varphi] := \lim_{r \searrow 0} u[\chi_r \varphi]. \tag{17}$$

The limit exists because for $0 < r_1 \leq r_2$

$$\begin{aligned} & \left| u[\chi_{r_1} \varphi] - u[\chi_{r_2} \varphi] \right| \\ & \leq \int_{N(S, r_2) \cap K} |u(x)| \cdot |\chi_{r_1}(x) - \chi_{r_2}(x)| \\ & \quad \cdot |\varphi(x)| \operatorname{vol}(x) \\ & \leq 2 \cdot \|\varphi\|_{C^0(K)} \cdot \|u\|_{L^1(N(S, r_2) \cap K)} \\ & = o(r_2^k) \quad \text{as } r_2 \searrow 0. \end{aligned} \tag{18}$$

We check that \bar{u} is a distribution. Fix a compact subset $K \subset M$. Then, choosing $r_0 > 0$ sufficiently small, we obtain

$$\|\bar{u}\|_{L^1(K \setminus S)} = \|u\|_{L^1(N(S, r_0) \cap K)} + \|u\|_{L^1(\overline{K \setminus N(S, r_0)})} < \infty. \tag{19}$$

Here, the first summand is finite because of the assumption in the theorem and the second because $\overline{K \setminus N(S, r_0)}$ is a compact subset of $M \setminus S$. Hence, we find for all $\varphi \in \mathcal{D}(M, E^*)$ with $\operatorname{supp}(\varphi) \subset K$

$$\begin{aligned} |\bar{u}[\varphi]| &= \lim_{r \searrow 0} \left| \int_{K \setminus S} \langle u(x), \chi_r(x) \varphi(x) \rangle \operatorname{vol}(x) \right| \\ &\leq \|u\|_{L^1(K \setminus S)} \cdot \|\varphi\|_{C^0(K)}, \end{aligned} \tag{20}$$

so \bar{u} is continuous in φ .

It remains to show that \bar{u} solves $L\bar{u} = 0$ in the distributional sense. For $\varphi \in \mathcal{D}(M, E^*)$, we compute

$$\begin{aligned} \bar{u}[L^* \varphi] &= \lim_{r \searrow 0} \int_{M \setminus S} \langle u(x), \chi_r(x) (L^* \varphi)(x) \rangle \operatorname{vol}(x) \\ &= \lim_{r \searrow 0} \int_{M \setminus S} \langle L(\chi_r u)(x), \varphi(x) \rangle \operatorname{vol}(x) \\ &= \lim_{r \searrow 0} \int_{M \setminus S} \left\langle \chi_r L u(x) + \sum_{j=0}^{k-1} P_j(\chi_r) u(x), \varphi(x) \right\rangle \\ & \quad \times \operatorname{vol}(x) \\ &= \lim_{r \searrow 0} \sum_{j=0}^{k-1} \int_{M \setminus S} \langle P_j(\chi_r) u(x), \varphi(x) \rangle \operatorname{vol}(x) \\ &= \lim_{r \searrow 0} \sum_{j=0}^{k-1} \int_{M \setminus S} \langle u(x), P_j(\chi_r)^* \varphi(x) \rangle \operatorname{vol}(x), \end{aligned} \tag{21}$$

where $P_j(\chi_r)$ is a linear differential operator of order j for each fixed r . It is obtained from the general Leibniz rule. The coefficients of $P_j(\chi_r)$ depend linearly on χ_r and its derivatives up to order $k - j$. Since χ_r is constant outside $N(S, r) \setminus N(S, r/2)$, the coefficients of $P_j(\chi_r)$ are supported in

$N(S, r) \setminus N(S, r/2)$. For this reason, the integration by parts above is justified; there are no boundary terms. We find

$$\begin{aligned} & \left| \int_{M \setminus S} \langle u(x), P_j(\chi_r)^* \varphi(x) \rangle \text{vol}(x) \right| \\ & \leq C \cdot \|\chi_r\|_{C^{k-j}(K)} \cdot \|\varphi\|_{C^j(K)} \cdot \|u\|_{L^1(N(S,r) \cap K)} \\ & \leq C' \cdot r^{j-k} \cdot \|\varphi\|_{C^j(K)} \cdot o(r^k) \\ & = o(r^j) \quad \text{as } r \searrow 0. \end{aligned} \tag{22}$$

Hence, $\bar{u}[L^* \varphi] = 0$, that is, $L\bar{u} = 0$ in the distributional sense. By weak hypoellipticity of L , the extension \bar{u} must be smooth and solves $L\bar{u} = 0$ in the classical sense. \square

Corollary 15. *Let L be a weakly hypoelliptic operator of order $k \geq 1$ over M . Let $S \subset M$ be an embedded submanifold of codimension $m \geq k + 1$. Let $u \in \mathcal{H}(M \setminus S, L)$ be locally bounded near S .*

Then, u extends uniquely to some $\bar{u} \in \mathcal{H}(M, L)$.

Proof. Since u is locally bounded near S , we have for any compact subset $K \subset M$

$$\begin{aligned} & \|u\|_{L^1(N(S,r) \cap K)} \\ & \leq \|u\|_{L^\infty(K \setminus S)} \cdot \text{vol}(N(S, r) \cap K) \\ & \leq C \cdot \|u\|_{L^\infty(K \setminus S)} \cdot r^m = O(r^m) \end{aligned} \tag{23}$$

as $r \searrow 0$. Since $m \geq k + 1$, we get $\|u\|_{L^1(N(S,r) \cap K)} = O(r^{k+1})$, and therefore $\|u\|_{L^1(N(S,r) \cap K)} = o(r^k)$ as $r \searrow 0$. Theorem 14 yields the claim. \square

Example 16. Let $M \subset \mathbb{C}^n$ be an open subset and $S \subset M$ a complex submanifold of complex codimension ≥ 1 . Then, any holomorphic function u on $M \setminus S$, locally bounded near S , extends uniquely to a holomorphic function on M . This is Corollary 15 with $k = 1$ and $m = 2$. It is classically known as *Riemann's first removable singularity theorem* [7, Thm. 4.2.1].

Note that S being a complex submanifold is actually irrelevant; any real submanifold of real codimension 2 will do. Moreover, by Theorem 14 one can relax the condition that u be locally bounded near S . A local estimate of the form $|u(x)| \leq C \cdot d(x, S)^{-\alpha}$ with $\alpha < 1$ is sufficient. This criterion is sharp because for $M = \mathbb{C}$, $S = \{0\}$, $L = \partial/\partial\bar{z}$, and $u(z) = 1/z$, we have a solution of $Lu = 0$ on $M \setminus S$ which satisfies $|u(z)| = d(x, S)^{-1}$ but does not extend across S .

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