

Research Article

Pore-Scale Modeling of Pressure-Driven Flow and Spontaneous Imbibition in Fracturing-Shut-In-Flowback Process of Tight Oil Reservoirs

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Tight oil reservoirs are characterized by multiple pore spaces where nano-micropores and multiscale fractures coexist, and each type of medium varies in scale, implying a tight coupling of multiscale fractures with matrix and giving rise to extremely complicated flow patterns. To further investigate its flow mechanism, we first construct three two-dimensional (2-D) fracture-pore geometry models based on microfocus computed tomography (CT) imaging of a typical tight rock. A pore-scale modeling workflow is thereafter developed using the Shan-Chen lattice Boltzmann model (SC-LBM) to simulate the pressure-driven flow and spontaneous imbibition. The influence of fracture-pore geometry on the pore-scale fluid exchange dynamics in the fracturing-shut-in-flowback process is clearly clarified. Results show that, for the porous medium model without fracture, the fracturing fluid can displace and replace some crude oil by spontaneous imbibition while a large amount of crude oil droplets remains unexploited away from the oil/water contact line, resulting in a low oil imbibition recovery. The injected fracturing fluid migrates into the deep position along the fractures, only a few entering the matrix pore space near the fractures. Small pores are the main channel for fracturing fluid to imbibe into the matrix pores, and the replaced crude oil droplets flow into fractures through large pores as intermittent or continuous pipe flow. The complexity of fracture network typically exerts a significant impact on the fluid exchange dynamics during pressure-driven flow and spontaneous imbibition. The more complex the fracture network, the larger the volume of fracturing fluid injected, the easier for oil droplets replaced from the matrix pores, and the more difficult for the flowback of fracturing fluid in the fracture-pore geometry model. Our understanding will provide a basis for explaining the underlying mechanisms of oil replacement by pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process.

1. Introduction

Abundant tight oil reservoirs exist in China, with large amounts of exploration discoveries in basins such as the Ordos, Junggar, Songliao, and Bohai Bay [1, 2]. To effectively exploit these tight oil reservoirs, the use of horizontal wells combined with volume fracturing techniques has become widespread, typically treated as one of the most promising ways for effective development of this type of reservoir. Tight oil reservoirs have complex storage spaces and strong heterogeneity and consist of matrix and multiscale fractures. The matrix is mainly composed of micrometer-nanometer pores, characterized by low permeability and limited flow distance. A large number of micro-nanoscale pore throats and cracks cause hydraulic fracturing fluid to undergo infiltration, suction, and oil drainage effects under capillary force, thereby increasing oil well productivity and improving recovery rate. Except for micro-nano-scale matrix pores, various fractures including hydraulic fractures, natural fractures, and microfractures are simultaneously observed. Each type of medium varies in scale, implying a tight coupling of multiscale fractures with matrix and giving rise to extremely complicated flow patterns [3].

Previous studies [4–6] indicated that spontaneous imbibition is one of the primary underlying mechanisms for

a large number of researchers have adopted the development method of "horizontal well + volume fracturing + shut-in well" to develop tight oil, which involves immediately shutting down the well after volume fracturing and shutting it for a period of time before opening the well for production. This has achieved good oil increase effects and effectively reduced water production. During the volume fracturing, shut-in, and subsequent flowback process in tight oil reservoir, fracturing fluid can spontaneously imbibe into the matrix pore space from the fractures motivated by the capillary force, replacing the crude oil droplets occupied in matrix pores. The pilot practice also proves that when sufficient imbibition is achieved by shut-in, oil production of horizontal well can significantly increase. However, the underlying mechanism of pore-scale fluid exchange influenced by pressure-driven flow and spontaneous imbibition within fracture-porous medium of tight oil reservoirs remains unclear, leading to the ineffective scheme design of increasing oil production and sharp difference in individual well productivity [7-9]. It is of great importance to perform pore-scale simulation of multiphase fluid flow during the fracturing-shut-in-flowback process in tight oil reservoirs. These understandings can reveal the underlying mechanisms of pore-scale fluid exchange during pressure-driven flow and spontaneous imbibition.

Modeling pore-scale flow is a complex fluid dynamic problem involving phase interface tracking and multicomponent and multiphase transport [10, 11]. It is typically affected by various factors, such as pore structure, wettability, and fluid properties. In recent decades, several efficient methods were widely utilized for pore-scale flow simulation [12], including pore network simulation, lattice Boltzmann method (LBM), volume of fluid method (VOF), smoothed particle hydrodynamics (SPH), level set method, and phase-field method. Pore network simulation [13] has significant advantages such as repeatability, quantifiability, and high computational efficiency. The pore network models include quasistatic pore network models and dynamic pore network models. The quasistatic pore network model is a simplified form of the dynamic pore network model, primarily used to obtain the material properties of porous media, such as relative permeability and capillary pressure. Compared with quasistatic pore network models, dynamic pore network models are more complex and entail higher computational costs. However, pore network models require topological description of actual rock microstructure; it remains a great challenge to accurately extract equivalent pore network models from images of tight rock microstructure. As a mesoscale method, LBM [14, 15] directly starts from a discrete model and constructs a bridge between macroscopic and microscopic, continuous and discrete based on molecular dynamics and statistical mechanics. It is pretty efficient to handle the complicated fluid interaction and impose boundary conditions and parallel programming, which has become an effective method for solving fluid flow and heat transfer problems in porous media. Other methods such as VOF, SPH, level set, and phase-field [16] are classified into the category of direct

numerical simulation (DNS) methods. They are based on discretization of multiphase Navier-Stokes (N-S) equations and coupling other partial differential equations to describe various physical and chemical phenomena occurred in porous media. The more fluid components are considered and the larger the computational domain, the more complex the pore-scale flow simulation and the more difficult in tracking fluid phase interfaces.

When using lattice Boltzmann method to solve the multiphase flow problem, four LBM calculation models are typically categorized [15]: color-gradient model, pseudopotential model, free energy model, and incompressible multiphase flow model. As the earliest model introduced, the color-gradient LBM model [17] utilized two sets of particle density distribution functions ("blue" and "red") to represent two fluids and their flow states. The interaction between fluids is characterized by an additional collision term, making this model suitable for two-phase fluid flow with the same density ratio. The pseudopotential LBM model [18] also known as the Shan-Chen model introduced the concept of "long-range interaction potential between particles" in collision term, which represents the microscopic interactions between two-phase fluid particles and induces the formation of phase interfaces, mixing and diffusion between fluid phases. Due to its simplicity, ease of implementation, and Galilean transformation invariance, SC-LBM has become the most widely used multiphase LBM model. By introducing different equations of state (EOS) to calculate the interaction potential, the SC-LBM model can be utilized to calculate cases with density ratios higher than 1000. When the original SC-LBM method is employed to simulate two-phase fluid flow, surface tension, density ratio, and viscosity ratio are numerically calculated, but they are not independent. Sbragaglia et al. [19] pointed out that in order to estimate the interaction potential, a wider range of grid points than the adjacent ones can independently adjust surface tension and density ratio, which makes the simulated results better fit with the actual situation. The third LBM model is the free energy model, first proposed by Swift [20], and it tracks the evolution of the two-phase fluid interface by calculating the Poisson equation. Inamuro et al. [21] improved the free energy model, making it possible to calculate large density ratios. However, since it requires the calculation of the Poisson equation, it loses the original simplicity of the lattice Boltzmann method. The final type is the incompressible multiphase flow model [22], which employs two sets of particle distribution functions for calculation. One set of particle distribution function is used to invert the incompressible Navier-Stokes equations, and the other set is to invert the Cahn-Hilliard phase-field equation [23-25], which is utilized for interface tracking. The model has high accuracy, but its computational efficiency is relatively poor due to the use of complex difference scheme. It can be concluded that because of easy programming and high capacity for pore-scale simulation of multiphase fluid flow with high density ratio, the SC-LBM model has provided an effective approach to understand the underlying mechanisms of pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process of tight oil reservoirs.

At present, the research pertaining to tight oil reservoirs lacks consideration for the intricacies of pressure-driven

flow and spontaneous imbibition during the fracturing-shutin-flowback process. Moreover, the models used lack typical pore-throat characteristics of tight reservoirs. To address these issues, we have conducted research at the pore-scale level. Based on high-resolution microfocus CT imaging and digital image processing of a typical tight rock, three 2-D geometric models of different fracture-pore media are firstly constructed. By considering the synergistic effects of capillary and viscous forces, a SC-LBM is then proposed for pore-scale modeling of multiphase flow in tight fractureporous medium. After verifying the accuracy of the SC-LBM model, pore-scale simulation of pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process of tight oil reservoir is conducted. The influence of fracture-pore geometry on fluid exchange dynamics caused by pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process is fully studied.

2. Methodology

2.1. Fracture-Pore Geometry Model. The experimental devices [26] used for obtaining the images of rock microstructure mainly include magnetic resonance imaging (MRI), ultra-high-resolution imaging combined with focused ion beam and scanning electron microscopy (FIB-SEM), and industrial microfocus CT (micro-CT) imaging. MRI is commonly used in the medical field, but its resolution is relatively low. FIB-SEM [27-29] is a powerful technique that involves cutting ultrathin rock slices using FIB and then observing the new cutting surfaces by SEM. This process is repeated to obtain a series of 2-D slice images of the rock, which are then overlapped to establish a threedimensional rock microstructure. It allows for acquisition of the internal 3-D micro-nano-meter pore structure of rocks with high precision. In last decades, due to its rapid development, X-ray CT imaging has been widely used to obtain the microstructure of different kinds of rocks. In contrast to FIB-SEM, the industrial microfocus CT [30-35] is a nondestructive measurement device that uses X-rays to penetrate rocks from different angles. FIB-SEM is limited to depicting small sample sections, making it difficult to accurately investigate the differently sized structures in tight rock. By using certain efficient algorithms to retrieve slice information from the density of the rock microstructure, a 3-D digital rock can be obtained by overlaying the slice images. The resolution is generally at the micrometer scale. To observe the microstructure of rocks more accurately, Xray CT imaging technology with nanometer-level accuracy is gradually gaining attention.

In this study, the microstructure information of a typical tight rock is obtained by the industrial microfocus CT imaging. The 2-D grayscale CT images, with a resolution at the micrometer scale, are processed using the ImageJ software. In the X-ray microfocus CT scanning experiment, there is a significant difference in the penetration ability of the pore space and rock skeleton to X-rays. The high density of the rock skeleton results in weak penetration, while low density of the pore space leads to strong penetration. Consequently, within the CT grayscale image, areas of high brightness

depict the rock skeleton, whereas areas of low brightness denote the pore space. Appropriately selecting a threshold facilitates effective segmentation between the pore space and rock skeleton. This enables the binarization and threshold segmentation of the raw images, effectively dividing into fractures, pore space, and rock skeleton to obtain the fracture-pore geometry model. Based on pixel analysis of binary images, pixels within pores are designated a value of 0, while those on rock skeletons are assigned a value of 1. This binary coding effectively represents rock cores as a combination of 0s and 1s, forming the fundamental data used in reconstructing digital rock cores. This geometry model will be utilized for subsequent pore-scale flow simulations. The basic properties of the microfocus CT scanner used in this study are listed as follows: the sample diameter ranging from 1.0 mm to 70 mm, the voltage ranging from 40 kV to 150 kV, the scanning resolution ranging from $0.5\,\mu\text{m}$ to $35\,\mu\text{m}$, and the working energy ranging from 1.0 W to 10 W. In order to systematically explore the effect of fracture network on fluid exchange caused by pressuredriven flow and spontaneous imbibition in the fracturingshut it-flowback process of tight oil reservoirs, three representative fracture-pore geometry models are constructed here by inserting fractures of different shapes into the same matrix pore space with a resolution of $1.0 \,\mu\text{m}$.

2.2. SC-LBM Computational Model. As a fundamental equation of mesoscopic dynamics, the Boltzmann equation is derived from fluid molecular kinetics and statistical physics theory, which describes the fluid motion in porous media by the evolution of particle distribution functions. To facilitate numerical computations and reduce the complexities of solving the continuous Boltzmann equation, the continuous Boltzmann equation is discretized in time and space, while the fluid is abstracted as particles that collide and migrate in specific lattice directions. By selecting a suitable equilibrium distribution function and conducting the Chapman-Enskog expansion on the lattice Boltzmann evolution equation, the macroscopic N-S equation can be achieved. The lattice Boltzmann evolution equation with external force term [14, 15] can be described as

$$f_{\sigma,\alpha}(\boldsymbol{x} + \boldsymbol{e}_{\alpha}\Delta t, t + \Delta t) - f_{\sigma,\alpha}(\boldsymbol{x}, t) = -\frac{\Delta t}{\tau_{\sigma}} \left(f_{\sigma,\alpha}(\boldsymbol{x}, t) - f_{\sigma,\alpha}^{\text{eq}}(\boldsymbol{x}, t) \right) + F_{\sigma,\alpha}(\boldsymbol{x}, t)\Delta t,$$
(1)

where \mathbf{x} is the distribution function of phase σ at node \mathbf{x} and time t, $f_{\sigma,\alpha}^{\text{eq}}$ is the equilibrium distribution function, $F_{\sigma,\alpha}$ is the external force, and τ_{σ} is the relaxation time. The equilibrium distribution function for the model is given by the following equation:

$$f_{\sigma,\alpha}^{\rm eq} = \omega_{\alpha} \rho_{\sigma} \left[1 + \frac{3}{c^2} (\boldsymbol{e}_{\alpha} \boldsymbol{\cdot} \boldsymbol{u}) + \frac{9}{2c^4} (\boldsymbol{e}_{\alpha} \boldsymbol{\cdot} \boldsymbol{u})^2 - \frac{3}{2c^2} \boldsymbol{u}^2 \right], \quad (2)$$

where ω_{α} is the weight coefficient for each direction, $\omega_0 = 4/9$, $\omega_{1-4} = 1/9$, $\omega_{5-8} = 1/36$, ρ_{σ} is the fluid density, *c* is the migration speed of the microelement on the lattice, and *u* is the



FIGURE 1: Accuracy validation of the Young-Laplace equation.

TABLE 1: Input parameters of the SC-LBM model for model validation 1.

Lattice size	$220 \mathrm{lu} \times 220 \mathrm{lu}$	Physical size	$22 \text{ mm} \times 22 \text{ mm}$
Kinematic viscosity 1	0.001 m ² /s	Interface tension	$0.03 \ \mathrm{N \cdot m^{-1}}$
Kinematic viscosity 2	0.001 m ² /s	Interface thickness	5 lu
Density 1	1000 kg/m^3	G_1	2.0
Density 2	50 kg/m^3	G_2	0.6



FIGURE 2: Schematic diagram of wettability simulation example.

macroscopic velocity of the fluid. The subscript a indicates the discrete velocity directions. For this study, the D2Q9 lattice structure model is used, and the discrete velocities are defined as

 $\boldsymbol{e}_{\alpha} = \begin{cases} (0,0), a = 0, \\ \cos\left[\left(a-1\right)\frac{\pi}{2}\right], \sin\left[\left(a-1\right)\frac{\pi}{2}\right], a = 1-4, \\ \sqrt{2}\cos\left[\left(a-5\right)\right]\right)\frac{\pi}{2} + \frac{\pi}{4}\right], \sqrt{2}\sin\left[\left(a-5\right)\right]\right)\frac{\pi}{2} + \frac{\pi}{4}\right], a = 5-8. \end{cases}$ (3)

The SC-LBM model defines a "pseudopotential" function to numerically represent the interactions between fluid parti-

cles and the interactions between fluid and wall surfaces:

$$F_{\sigma} = F_{c,\sigma} + F_{\mathrm{ads},\sigma}.$$
 (4)

The fluid interaction force is described as follows:

$$F_{c,\sigma}(\mathbf{x},t) = -G_c \psi_{\sigma}(\mathbf{x},t) \sum_{\mathbf{a}} w_{\alpha} \psi_{\sigma}(\mathbf{x} + \mathbf{e}_{\alpha} \Delta t, t) \mathbf{e}_{\alpha}, \quad (5)$$

where $F_{c,\sigma}(\mathbf{x}, t)$ is the interaction force between fluid particles surrounding node \mathbf{x} at time t and G_c is the interaction force coefficient between fluid particles, which can be adjusted to control the surface tension of the fluid. Fluids will separate with the proper magnitude, so the system can simulate two-phase immiscible fluid flow driven by

Lattice size	$300 \mathrm{lu} \times 100 \mathrm{lu}$	Physical size	$30\mathrm{mm} imes 10\mathrm{mm}$
Kinematic viscosity 1	$1.006 \times 10^{-6} \text{ m}^2/\text{s}$	Interface tension	$0.072 \text{ N} \cdot \text{m}^{-1}$
Kinematic viscosity 2	$1.506 \times 10^{-5} \text{ m}^2/\text{s}$	Interface thickness	3 lu
Density 1	998.2 kg/m^3	G_1	2.0
Density 2	1.205 kg/m^3	G_2	0.6

TABLE 2: Input parameters of the SC-LBM model for model validation 2.



FIGURE 3: SC-LBM simulation of rock wall with different contact angles.

interfacial tension. ψ_{σ} is the equivalent mass of fluid, which can be calculated using pseudopotential functions.

The traditional S-C LBM only considers the forces between neighboring particles. In this paper, we adopt the improved model proposed by Sbragaglia et al. [19], while considering the forces between next-nearest particles. The formula is as follows:

$$F_{c,\sigma}(\mathbf{x},t) = -\psi_{\sigma}(\mathbf{x},t) \sum_{a} w_{a} [G_{1}\psi_{\sigma}(\mathbf{x}+\mathbf{e}_{\alpha}\Delta t,t) + G_{2}\psi_{\sigma}(\mathbf{x}+2\mathbf{e}_{\alpha}\Delta t,t)] \mathbf{e}_{\alpha}$$
(6)

where G_1 and G_2 are the strength coefficients that control the interaction forces between neighboring particles and next-nearest particles, respectively. $F_{ads,\sigma}(\mathbf{x}, t)$ is the interaction force between node \mathbf{x} and the surrounding wall at time *t*:

$$F_{\text{ads},\sigma}(\mathbf{x},t) = -G_{ads,\sigma}\psi_{\sigma}(\mathbf{x},t)\sum_{\alpha}w_{\alpha}\psi(\rho_{w})s(\mathbf{x}+\mathbf{e}_{\alpha}\Delta t,t)\mathbf{e}_{\alpha},$$
(7)

where $G_{ads,\sigma}$ is the interaction force coefficient between fluid and wall surfaces, which can be adjusted to control the contact angle between fluid and wall surface.



FIGURE 4: Schematic diagram of layered two-phase flow between infinite parallel plates.

The macroscopic density and pressure for each component can be calculated as

$$\rho = \sum_{a=0}^{a-1} f_a,$$

$$p = c_s^2 \rho,$$
(8)

where c_s is the LBM speed of sound.

Due to its limitation in handling large density ratio problems, scholars made great effort to improve the applicability of the original SC-LBM computational model. By introducing multiple relaxation operators, using long-short range interaction potentials, and enhancing the equation of state [36–38], the single-component multiphase flow SC-LBM model was extended to high density ratio cases over 1000. Because of its origin from the traditional lattice Boltzmann equation, the SC-LBM computational model is relatively simple and easy to deal with the interaction between particles, which has a clearer physical meaning compared to the color-gradient LBM model. Therefore, we employed the SC-LBM computational model and utilized the C programming language for implementation. By simulating pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process of tight oil reservoirs, we aimed to explore the dynamics of fluid exchange.

3. Model Validation

3.1. The Young-Laplace Equation. The Young-Laplace equation [39] is a classical law used to describe the relationship between the pressure difference on both sides of a fluid interface and the interfacial tension in two-phase system. For a two-dimensional two-phase system without external forces,



FIGURE 5: Comparison of results for two-phase flow under different viscosity ratios.



(c) Branch-shaped fracture-pore model

FIGURE 6: Schematic of different fracture-pore geometry models used in this study.

as shown in Figure 1(a), one phase exists in the form of a circle within the other phase, with radius *R*. In steady state, the internal and external pressure difference ΔP and the interfacial tension σ are linearly related, and their expression is given by

$$\Delta P = \frac{\sigma}{R}.$$
 (9)

In order to simulate this two-phase system, the following parameters are defined in Table 1.

For five cases where the radius of fluid 1 changes from R = 2 mm to R = 6 mm, the SC-LBM model is applied to determine the inside and outside pressure difference of two-phase fluids at the interface, and the calculation results

 TABLE 3: Input parameters of the SC-LBM model for spontaneous imbibition simulation.

G_1	G_2	$ au^w$	$ au^o$	$ ho^w$	$ ho^o$	β
2.0	0.6	1.5	1.6	0.97	0.97	-0.25

are shown in Figure 1(b). The analysis shows that inside and outside pressure difference ΔP follows a linear relationship with the reciprocal of the fluid 1 radius 1/*R*, which is highly consistent with the analytical solution of the Young-Laplace equation. This indicates that the SC-LBM model used in this study can accurately simulate the interaction between fluid phases at the interface.



FIGURE 7: Countercurrent imbibition simulation in the typical tight rock.

3.2. Contact Angle Calculation. To verify the accuracy of the SC-LBM model in simulating wettability, a domain with a lattice size of 300×100 is established as shown in Figure 2; other parameters are shown in Table 2. Periodic boundary conditions are imposed in the *x*-direction, and standard bounce-back boundary conditions are applied in the *y*-direction. The liquid droplet (fluid 1) is initially in a semicircular shape (with a diameter of 160 lattice units), located at the center of the bottom wall and surrounded by the gas phase (fluid 2). Here, *d* is the maximum distance between the two ends of the droplet, *h* is the maximum height of the droplet, and θ is the contact angle.

The dimensionless wetting parameter $\tilde{\omega}$ is 0.47611091, 0.0, and -0.47611091, respectively. The theoretical static contact angles of the droplet on the solid wall are 45°, 90°, and 135°, respectively. The droplet will spontaneously change from its initial state of $\theta = 90^{\circ}$ to the corresponding static contact angle.

The SC-LBM model is used to simulate the different wettability of rock surface, and the results are shown in Figure 3. When the simulation becomes stable, the contact angles under three different dimensionless wettability parameters $\tilde{\omega}$ are measured to be 44.8°, 90.1°, and 134.9°, respectively. The error between the measured contact angles and the theoretically estimated values is less than 0.45%. This demonstrates that the SC-LBM calculation model can accurately simulate the contact angle of a rock surface under three different conditions: wetting, neutral wetting, and nonwetting.

3.3. Layered Two-Phase Flow between Parallel Plates. In order to verify the accuracy of the SC-LBM model in calculating fluid velocity distribution, LBM simulations were conducted and compared with analytical solutions for problem of layered two-phase flow between infinite parallel plates [40–42]. As shown in Figure 4, fluid 1 (white) is located at the center of the plate with a density of ρ_1 and a dynamic



FIGURE 8: Oil imbibition recovery of countercurrent imbibition in tight porous medium model.

viscosity of v_1 , driven by the *x*-directional volume force F_1 ; fluid 2 (blue) is symmetrically distributed on both sides of fluid 1, with a density of ρ_2 and a dynamic viscosity of v_2 , driven by the *x*-directional volume force F_2 . The distance between the two infinite parallel plates is 2*H*, and the coordinate of the two-phase interface position is Y_i .

When the simulation reaches a steady state, for the positive *x*-axis, the theoretical solutions for the flow velocity in the cross-section can be expressed as

$$\begin{cases} 0 \le y < Y_i : \quad u = A_1 y^2 + C_1, \\ Y_i \le y \le H : \quad u = A_2 y^2 + B_2 y + C_2, \end{cases}$$
(10)

where

$$A_{1} = \frac{-F_{1}}{(2\rho_{1}\nu_{1})},$$

$$A_{2} = \frac{-F_{2}}{(2\rho_{2}\nu_{2})},$$

$$B_{2} = \frac{-2A_{2}Y_{i} + 2A_{1}Y_{i}(\rho_{1}\nu_{1})}{(\rho_{2}\nu_{2})},$$

$$C_{1} = (A_{2} - A_{1})Y_{i}^{2} - B_{2}(H - Y_{i}) - A_{2}H^{2},$$

$$C_{2} = -A_{2}H^{2} - B_{2}H$$
(11)

A research area with lattice units of 100×201 is established, corresponding to a physical fluid region of 100 mm $\times 200$ mm. In the *x*-direction, periodic boundary conditions are imposed, while standard wall bounce-back boundary conditions are utilized in the *y*-direction. Only a volume force $F_1 = 15 \text{ kg} \cdot \text{m}^{-2} \cdot \text{s}^{-2}$ is applied to fluid 1, and $F_2 = 0$ is applied to fluid 2. The density of fluid 1 is $\rho_1 = 50 \text{ kg} \cdot \text{m}^{-3}$,

TABLE 4: Input parameters of the SC-LBM model used for coupled pressure-driven flow and spontaneous imbibition simulation in fracture-pore geometry model.

G_1	G_2	$ au^w$	$ au^o$	$ ho^w$	$ ho^o$	β	Δho
2.0	0.6	1.5	1.6	0.97	0.97	-0.25	0.0485

and the density of fluid 2 is $\rho_2 = 1000 \text{ kg} \cdot \text{m}^{-3}$. The kinematic viscosity of two fluids is same $v_1 = v_2 = 0.01667 \text{ m}^2 \cdot \text{s}^{-1}$, and the interfacial tension is $\sigma = 0.03 \text{ N} \cdot \text{m}^{-1}$. The interface thickness *W* is set to 5 lattice units, and the grid velocity *c* is *c* = 100 m \cdot \text{s}^{-1}. The calculated velocity values and theoretical values under different fluid viscosity ratios were compared and analyzed, as shown in Figure 5; it can be seen that they are in good agreement. Through various simulations, the accuracy of the SC-LBM computational model used in this paper is fully demonstrated, and it can accurately calculate key parameters such as capillary force, velocity, and contact angle.

4. Results and Discussion

During the development of tight oil reservoirs, the interaction between multiphase fluids is inevitably involved. Due to the micro-nanosize of pore throats, the capillary-driven interaction between fluid and rock wall surface cannot be ignored. Influenced by the capillary pressure, the wettingphase fluid enters the fracture-pore geometry model and displaces the non-wetting-phase fluid; this phenomenon is known as spontaneous imbibition [43–46], which has been widely recognized as a key mechanism for oil replacement in the fracturing-shut-in-flowback process of tight oil reservoirs. In this paper, using the SC-LBM model, two-phase flow simulations are performed in the fracturing-shut-in-



FIGURE 9: Pore-scale flow simulation in the pressure-driven fracturing stage of different models.

flowback process of tight oil reservoir in order to unveil the fluid exchange dynamics at pore scale.

4.1. Simulation of Countercurrent Imbibition. We conducted pore-scale flow simulations of countercurrent imbibition in a typical tight rock using the SC-LBM. The porous medium depicted in Figure 6(a) was chosen as the geometry model. The model parameters used for flow simulation are listed in Table 3. In the study, the tight rock wall is strongly water-wet, and the contact angle between fracturing fluid and rock wall is 10.61°. The model is initially saturated with crude oil and placed in the fracturing fluid. Activated by the capillary pressure, the wetting-phase fracturing fluid imbibes into matrix pore space from the four boundaries of top, bottom, left, and right and gradually replaces some of the crude oil. The simulation results are shown in Figure 7.

As shown in Figure 7, in the early stage of countercurrent imbibition (t = 0, 50000), the fluid pressure distribution in the tight porous medium model is extremely uneven. The smaller the pore-throat radius, the greater the capillary



FIGURE 10: Oil saturation variation in the pressure-driven fracturing stage of different models.

pressure, forming a high-pressure zone in the small pores and a low-pressure zone in the large pores. In this model, a large number of connected and complex small pores are distributed in the lower left corner, and the wetting-phase fracturing fluid preferentially enters these pore spaces through the small pores, driven by high capillary pressures, while the non-wetting-phase crude oil droplets are gradually displaced from the large pores, resulting in the formation of trapped oil droplets. As the remaining oil occupied in matrix pore spaces is continuously recovered, the trapped oil droplets attached to the wall surface of the rock gradually increase (t = 200000, 300000, and 400000). Therefore, the small pores in the high-pressure zone are the main channels for fracturing fluid to imbibe into the matrix, while the large pores in the low-pressure zone are the main channels for crude oil to be extracted. As the countercurrent imbibition process continuously proceeds, the fluid pressure distribution in matrix pore space will tend to be consistent, eventually reaching a steady state (t = 500000). When the countercurrent imbibition is ended, only the crude oil droplets reached by the fracturing fluid in the matrix pore space can be effectively recovered, and a large amount of remaining oil trapped in the middle zone of the porous medium model cannot be extracted. It implies that the countercurrent imbibition process occurred in the tight porous medium model can merely reach a very low oil recovery.

Figure 8 shows the variation of oil imbibition recovery in the tight porous medium model. It indicates that at the beginning of countercurrent imbibition, the driving force of spontaneous imbibition is largest and more oil droplets are produced, resulting in a rapid increase in oil imbibition recovery. As the process continues, the oil imbibition recovery increases gradually and ultimately reaches a stable value. It is mainly due to the nano-micro-size distribution of pores and throats that relatively short transport distances, and high flow resistances are monitored for crude oil droplets difficult to be recovered from the matrix pore space. Once the pressure difference between the wetting-phase fluid and non-wetting-phase fluid reaches equilibrium, the countercurrent imbibition process will weaken.

4.2. Simulation of Pressure-Driven Flow and Spontaneous Imbibition. To reveal the pore-scale fluid exchange dynamics in the fracturing-shut-in-flowback process of tight oil reservoirs, two fracture-pore geometry models as shown in Figures 6(b) and 6(c) are constructed, and the SC-LBM model is used to conduct pore-scale modeling of pressure-driven flow and spontaneous imbibition occurred in three different stages as follows: hydraulic fracturing, shut in, and flowback for fracturing fluid. The influence of fracture-pore geometry on pore-scale fluid exchange in the different development stages of tight oil reservoirs is further clarified. The input parameters are listed in Table 4.

In the fracturing stage, both the two fracture-pore models are initially saturated with crude oil (nonwetting phase). Driven by a constant pressure gradient, the fracturing fluid (wetting phase) is injected from the left side of the fracture-pore geometry model. In the shut-in stage, the oil-water distribution is the same as that obtained at the end of the fracturing stage. No external force is considered in the shut-in stage. The only driving force is the capillary pressure between fluid and rock wall surface, which induces spontaneous imbibition between fracture and matrix pore space. In the flowback stage, the initial fluid distribution is identical with that obtained at the end of the shut-in stage, the same pressure gradient is imposed reversely on both sides of the geometry model. Driven by the reverse pressure gradient, the remaining oil droplets occupied in the fracturepore geometry model will be gradually recovered.



(b) Branch-shaped fracture-pore geometry model

FIGURE 11: Pore-scale flow simulation in the shut-in imbibition stage of different models.

Figure 9 displays the oil-water exchange process in the pressure-driven fracturing stage of the straight-shaped and branch-shaped fracture-pore geometry models. In addition, the pressure profiles at the end of pressure-driven fracturing stage of different models can be found in Supplementary Material Figure S1. It can be seen that driven by a positive pressure gradient, the fracturing fluid mainly enters the fracture-pore model as a continuous pipe flow. The presence of fractures effectively expands the fluid flow path inside the tight matrix pore space, and the flow resistance of fracturing fluid in fractures is far less than that in the matrix pores. As a result, the injected fracturing fluid preferentially transports along the fractures towards to the deep positions of tight rock, and few fracturing fluid imbibes into the pores nearby the contact line between matrix and fractures. The more complex the fracture network is, the larger the contact area between matrix and fractures, and the greater the volume of fracturing fluid injected, the easier it is for crude oil droplets occupied in the matrix pore space flow towards the wellbore through the fractures. The results of straight-shaped fracture-pore geometry model and branch-shaped fracture-pore



FIGURE 12: Oil saturation variation in the shut-in imbibition stage of different models.

geometry model show that the injected fracturing fluid flows along the fracture, and only the crude oil in the fracture is displaced. Finally, cross-flow occurs in the fracture. In addition, the simulation results of branch-shaped fracturepore geometry model show that the fracturing fluid tends to flow along the original path rather than entering the branching fractures. The outcomes from both the straightshaped fracture-pore geometry model and the branchshaped fracture-pore geometry model reveal a consistent pattern: the injected fracturing fluid predominantly follows the fracture, displacing only the crude oil within it. Eventually, a cross-flow phenomenon emerges within the fracture. The fracturing fluid exhibits a preference for following the original pathway instead of entering branching fractures.

Figure 10 shows the dynamic oil saturation variation in the fracturing flow stage of different fracture-pore geometry models. It can be seen that the fracturing fluid preferentially enters the deep positions of the geometry model along the fractures, typically leading to a gradual decrease in oil saturation; the more complex the fracture network, the larger the contact area between matrix and fractures. Driven by the positive pressure gradient, the flow resistance of fracturing fluid injected inside the geometry model is smaller, and oil droplets initially occupied in the fractures are displaced into the matrix away from the injection side.

Figure 11 depicts the oil-water exchange process in the shut-in imbibition stage of the straight-shaped and branchshaped fracture-pore geometry models. In addition, the pressure profiles at the end of shut-in imbibition stage of different models can be found in Supplementary Material Figure S2. As can be seen, at the beginning of shut-in imbibition stage, the fracturing fluid mainly spread over

the fractures and the pore space nearby the matrix-fracture contact line. Controlled by nano-macrosizes of pore throats, the capillary pressure in small pores is greater, typically leading to the countercurrent imbibition process of the fracturing fluid from fractures into small pores. Capillary action serves as the primary driving force for oil droplets to migrate into the fractures. The recovered oil droplets flow into fracture through large pores, gradually accumulating into oil banks that move intermittently in fracture. The more complex the fracture network, the larger the matrix-fracture contact area, and the easier it is for the fracturing fluid to undergo countercurrent imbibition and oil replacement between fracture and matrix pores in the shut-in imbibition stage. The recovered oil droplets accumulate in fracture and flow outlet as pipe flow. In the branch-shaped fracture-pore geometry model, due to the effect of branching fractures, there are almost no trapped oil droplets, which continuously gather and flow towards large pores. During the spontaneous imbibition stage, branching fractures exert a more significant influence compared to the pressure-driven stage (Figure 11(b-4)).

Figure 12 shows the dynamic oil saturation variation in the shut-in imbibition stage of the two fracture-pore geometry models. It can be seen that the oil saturation changes slightly in the shut-in imbibition stage. The more complex the fracture network, the larger the contact area between matrix and fractures; the more fracturing fluid can imbibe into the matrix pores driven by the capillary pressure. In addition, as the number of cracks increases within a tight rock sample, the fractal nature of pore structure will be augmented. This leads to a reduction in the scale of pore channels, thereby decreasing the flow resistance experienced by oil droplets within these pores and consequently enhancing



(a) Straight-shaped fracture-pore geometry model





(b) Branch-shaped fracture-pore geometry model

FIGURE 13: Pore-scale flow simulation in the flowback production stage of different models.

flow efficiency. The remaining oil droplets are gradually replaced and accumulated in the fractures. However, there exists no driving force at both sides of the geometry model, so the oil droplets replaced by countercurrent imbibition continuously accumulate in the fractures. Figure 13 reflects the oil-water exchange process in the flowback production stage of the straight-shaped and branch-shaped fracture-pore geometry models. In addition, the pressure profiles at the end of flowback production stage of different models can be found in Supplementary Material



FIGURE 14: Oil saturation variation in the flowback production stage of different models.

Figure S3. It demonstrates that in this pressure-driven flow stage, driven by the negative pressure gradient, the oil droplets occupied in matrix pores away from the inlet position preferentially enter the fractures as continuous pipe flow, and the fracturing fluid nearby the matrixfracture contact line is gradually back flowed. Influenced by the competition between the viscous force and capillary pressure, the more complex the fracture network, the more likely the fracturing fluid preserved inside the branchshaped fractures and deep matrix pores is unable to flowback. In addition, the fracturing fluid is also prone to retention in the pores where the large fractures intersect with the matrix.

Figure 14 shows the dynamic oil saturation variation in the flowback production stage of the two fracture-pore geometry models. It can be observed that the oil saturation gradually increases in the flowback production stage. The more complex the fracture network, the higher the initial oil saturation during the flowback production stage. The main reason is that, driven the same negative pressure gradient, the crude oil droplets in the deep matrix pores are displaced by the fracturing fluid and quickly flow into the fractures as continuous pipe flow. The fracturing fluid nearby the matrix-fracture contact line is continuously displaced and produced.

5. Conclusion

Tight oil reservoir is characterized by low porosity and ultralow permeability. Due to the presence of a large number of submicron pore throat and micron pore throat, the influence of microscale flow effects is significant. The traditional fluid flow theory of oil and gas cannot accurately describe the flow law. The simulation digital rock technology based on digital rock cores has built a bridge between microstructure and macroscopic response, accurately describing the spatial distribution of fluid, and has important theoretical significance for the scientific and efficient development of tight oil reservoirs. In this paper, we develop a pore-scale modeling workflow of pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process of tight oil reservoirs based on the SC-LBM. The underlying mechanisms of pore-scale fluid exchange in different fracture-pore geometry models are fully investigated. The following conclusions can be achieved:

- (1) The simulated results of the proposed SC-LBM model are highly consistent with the theoretical solutions of the classical equations, which demonstrates that the SC-LBM computational model used in this study can accurately calculate key properties such as the capillary pressure, flow velocity profile, and contact angle
- (2) For the porous medium geometry model without fracture, only the oil droplets occupied in the matrix pores swept by the fracturing fluid can be recovered by the countercurrent imbibition effect, and a large amount of crude oil droplets remain unexploited, implying a relatively low oil imbibition recovery. At the beginning of countercurrent imbibition, the oil imbibition recovery increases rapidly; as the capillary-driven imbibition continues, the oil imbibition recovery increases slowly and finally reaches a steady value
- (3) The existence of fracture can effectively enlarge the fluid flow path in the tight matrix pore space, thus obviously reducing the fluid flow resistance. In the pressure-driven fracturing stage, the fracturing fluid

mainly enters the fracture as continuous pipe flow, and few flow into the matrix pores nearby the matrix-fracture contact area. In the shut-in imbibition stage, the fracturing fluid occupied in fracture preferentially enters the small pores for countercurrent imbibition while the replaced crude oil droplets flow into the fractures through large pores and gradually accumulate into large oil banks that transport in the form of intermittent or continuous pipe flow inside the fractures. In the flowback production stage, the oil droplets trapped in the matrix pores away from the inlet preferentially enter the fractures as continuous pipe flow, and the fracturing fluid retained in matrix pores and fractures will be gradually produced

- (4) The complexity of fracture network can exert a significant influence on the pore-scale fluid exchange by pressure-driven flow and spontaneous imbibition in the fracturing-shut-in-flowback process of tight oil reservoirs. In the pressure-driven fracturing stage, a more complex fracture network usually results in a larger volume of fracturing fluid injected. In the shut-in imbibition stage, the injected fracturing fluid can interact with more oil droplets trapped in the matrix pores, and the recovered oil droplets gradually accumulate and flow into the wellbore as pipe flow. In the flowback production stage, the fracturing fluid occupied in the branch-shaped fractures and matrix pores tends to be retained and is difficult for flowback
- (5) There are some limitations to our study. First, the traditional filtering methods and image segmentation methods used in this study to process micro-CT images with strong heterogeneity have limitations. In addition, the association of grayscale information with mineral components remains unresolved. Second, our use of a two-dimensional geometric model necessitates the development of a three-dimensional counterpart for future simulations and analysis

Data Availability

The data used to support the findings of this study are included within the article.

Conflicts of Interest

The authors declare that there are no conflicts of interest.

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Supplementary Materials

Figure S1: pressure profiles at the end of pressure-driven fracturing stage of different models. Figure S2: pressure profiles at the end of shut-in imbibition stage of different models. Figure S3: pressure profiles at the end of flowback production stage of different models. (*Supplementary Materials*)

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