ON THE EXISTENCE OF EQUATIONS OF EVOLUTION

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ABSTRACT. A time-independent, non-autonomous non-linear system governed by a principle of determinism (the state at a given time is determined by the initial state and by the control history during the intervening closed interval) is shown to obey a generalized evolution equation (1.2), where n is such that the state is continuously differentiable with respect to time whenever the control is of class C^n .

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1. INTRODUCTION.

The equations of evolution of time-independent, non-autonomous non-linear systems are almost universally taken as

$$u' = f(u, x) \quad (1.1)$$

where u is the output (or state) and x is the input (or control), both functions of time t with values in finite-dimensional vector spaces (say U and X , respectively), and the prime denotes differentiation with respect to time.

However, equation (1.1) is not the most general evolution equation. It may be regarded as a special case (corresponding to $n=0$) of

$$u' = f(u, x, x', \dots, x^{(n)}). \quad (1.2)$$

An example of the need for an equation of the form (2) occurs in the mechanics of inelastic continua. Here u is the vector whose components are the internal variables (or the inelastic strain), while x is stress or strain. Viscoelastic and viscoplastic materials are described by equation (1.1). Plastic materials, on the other hand, require equation (1.2) with $n=1$. In particular, for a rate-independent material the function f must be first-degree homogeneous in x' .

The difference between systems described by equations (1.1) and (1.2) (or, more generally, by equations (1.2) with different values of n) lies in the character of the solutions $u(t)$. If f is continuous, then the solution of (1.1) is continuously differentiable whenever x is a continuous function of time. On the other hand, solution

of (1.2) will not in general be continuously differentiable unless x is of class C^n . In other words, the choice of n in equation (1.2) depends on the way in which the system smooths the input: the greater the smoothing, the lower the value of n .

However, the existence of an equation of evolution cannot be assumed a priori for an arbitrary system. In this note we shall try to find sufficient conditions for the existence of an equation of evolution, and to relate the value of n to the smoothing property of the system.

2. MAIN RESULTS

We shall assume the system to be governed by a principle of determinism as follows: the value of u at time $t+\tau$ is determined by its value at time t and by the history of x during the interval $[t, t+\tau]$. We shall express this mathematically as follows. Let x^t be defined by $x^t(s) = x(t+s)$, and let x_τ^t denote the restriction of x^t to $[0, \tau]$. The pair $(u(t), x_\tau^t)$ may be regarded as determining a process of duration τ in the system; let P_τ denote the set of all such pairs determining possible processes in the system. Then there exists a mapping $\phi_\tau: P_\tau \rightarrow U$ such that

$$u(t+\tau) = \phi_\tau(u(t), x_\tau^t) \quad (2.1)$$

Furthermore, let C_τ^n denote the Banach space $C^n([0, \tau]; X)$, let $P_\tau^n = P_\tau \cap (U \times C_\tau^n)$. Then the smoothing property of the system may be expressed by saying that the left-hand side of (2.1) is differentiable with respect to τ whenever $(u(t), x_\tau^t) \in P_\tau^n$, that is, that the limit

$$\lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(u(t), x_\tau^t) - u(t)] \quad (2.2)$$

exists and is continuous in t under that condition. It is clear that this limit is determined by $u(t)$ and by the behavior of x in a neighborhood of t . It is not immediately clear that it should take the form of the right-hand side of (1.2). In fact, in order to derive this result we need to assume some properties of the restriction to P_τ^n of the mapping ϕ_τ , as given in the following theorem.

THEOREM. Let $\phi_\tau: P_\tau^n \rightarrow U$ be such that $\phi_\tau(a, \cdot)$ is locally Lipschitz (with respect to the C_τ^n norm), the local Lipschitz norm F_τ being $O(\tau)$ as $\tau \rightarrow 0+$. Then the limit

$$\lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(a, y) - a],$$

when it exists, depends only on $a, y, y', \dots, y^{(n)}$.

PROOF. Define $\bar{y} \in C_\tau^n$ by

$$\bar{y}(s) = y(0) + y'(0)s + \dots + y^{(n)}(0) \frac{s^n}{n!}$$

Let $\|\cdot\|_\tau$ denote the C_τ^n norm and $|\cdot|$ any finite-dimensional norm. Then

$$\begin{aligned} \|y - \bar{y}\|_\tau = \max \{ & \sup_{s \in [0, \tau]} |y(s) - y(0) - \dots - y^{(n)}(0) \frac{s^n}{n!}|, \\ & \sup_{s \in [0, \tau]} |y'(s) - y'(0) - \dots - y^{(n)}(0) \frac{s^{n-1}}{(n-1)!}|, \dots, \\ & \sup_{s \in [0, \tau]} |y^{(n)}(s) - y^{(n)}(0)| \}. \end{aligned}$$

Since the argument of each $|\cdot|$ is a continuous function of s that vanishes at 0, each supremum goes to zero as $\tau \rightarrow 0$, so that $\|y - \bar{y}\|_\tau \rightarrow 0$ as $\tau \rightarrow 0$. Now

$$\frac{1}{\tau} [\phi_\tau(a, y) - a] = \frac{1}{\tau} [\phi_\tau(a, y) - \phi_\tau(a, \bar{y})] + \frac{1}{\tau} [\phi_\tau(a, \bar{y}) - a];$$

but for the first term on the right-hand side we have

$$\frac{1}{\tau} \left| \phi_\tau(a, y) - \phi_\tau(a, \bar{y}) \right| \leq \frac{F_\tau}{\tau} \|y - \bar{y}\|_\tau,$$

so that this term goes to zero as $\tau \rightarrow 0$. Consequently,

$$\lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(a, y) - a] = \lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(a, \bar{y}) - a],$$

and this last limit, whenever it exists, depends only on a and on the parameters defining $\bar{y}$, that is, $y(0), y'(0), \dots, y^{(n)}(0)$. Q.E.D.

By the assumed smoothing property of the system the limit exists and is a continuous function of its arguments, $f(a, y(0), y'(0), \dots, y^{(n)}(0))$; it is this f that furnishes the right-hand side of equation (2).

As a very simple example, consider ϕ_τ given by

$$\phi_\tau(a, y) = a + y(\tau) - y(0).$$

This $\phi_\tau(a, \cdot)$ is Lipschitz (since it is a continuous linear mapping) on C_τ^0 , but the Lipschitz norm over this space is 2. On the other hand, we may rewrite it as

$$\phi_\tau(a, y) = a + \int_0^\tau y'(s) ds,$$

so that it is clearly a continuous linear mapping of C_τ^1 , and its (Lipschitz) norm is τ . Consequently, $n=1$, and indeed we have $f(a, y, y') = y'$.

A more sophisticated example, relevant to plasticity theory, is

$$\phi_\tau(a, y) = a + \int_0^\tau |y'(s)| ds.$$

This $\phi_\tau(a, \cdot)$ is not Lipschitz on C_τ^0 but it is Lipschitz on C_τ^1 :

$$|\phi_\tau(a, y) - \phi_\tau(a, \bar{y})| = \left| \int_0^\tau (|y'(s)| - |\bar{y}'(s)|) ds \right| \leq \int_0^\tau ||y'(s)| - |\bar{y}'(s)|| ds$$

$$\leq \tau \sup_{s \in [0, \tau]} ||y'(s)| - |\bar{y}'(s)|| \leq \tau \sup_{s \in [0, \tau]} |y'(s) - \bar{y}'(s)| \leq \tau \|y - \bar{y}\|_\tau,$$

so that once again $F_\tau = \tau$.