# AUXILIARY PRINCIPLE FOR GENERALIZED NONLINEAR VARIATIONAL-LIKE INEQUALITIES 

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#### Abstract

We introduce and study a new class of generalized nonlinear variational-like inequalities and prove an existence theorem of solutions for this kind of generalized nonlinear variational-like inequalities. By using the auxiliary principle technique, we construct a new iterative scheme for solving the class of the generalized nonlinear variational-like inequalities. The convergence of the sequence generated by the iterative algorithm is also discussed. Our results extend and unify the corresponding results due to Ding, Liu, Ume, Kang, Yao, and others.


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## 1. Introduction

Variational inequality theory has become a very effective and powerful tool for studying a wide range of problems arising in many diverse fields of pure and applied sciences. It is well known that one of the most important problems in variational inequality theory is the development of efficient and implementable iterative algorithms for solving various classes of variational inequalities and variational inclusions. In [3-38] there are a lot of iterative algorithms for finding the approximate solutions of various variational inequalities. Glowinski et al. [8] had developed the auxiliary principle technique. By using the auxiliary principle technique, Ding [3, 4], Ding and Tan [5], and Ding and Yao [6], Liu et al. [21, 28], Zeng et al. [37], Zeng et al. [38], and others suggested several iterative algorithms to compute approximate solutions for some classes of general nonlinear mixed variational inequalities and variational-like inequalities in reflexive Banach spaces.

Motivated and inspired by the research work in [3-38], in this paper, we introduce and study a new class of generalized nonlinear variational-like inequalities and prove an existence theorem of solutions for this kind of generalized nonlinear variational-like inequalities. By applying the result due to Chang [1,2] and the auxiliary principle technique, we suggest a new iterative scheme for solving the class of generalized nonlinear variational-like inequalities. The convergence of the sequence generated by the iterative
algorithm is also discussed. Our results extend and unify the corresponding results due to Ding [3], Liu et al. [21], Yao [36], and others.

## 2. Preliminaries

Throughout this paper, we assume that $H$ is a real Hilbert space with dual space $H^{*}$ and that $\langle u, v\rangle$ is the dual pairing between $u \in H$ and $v \in H^{*}$. Let $K$ be a nonempty closed convex subset of $H$, and let $A, B, C: K \rightarrow H, N: H \times H \times H \rightarrow H$, and $\eta: K \times K \rightarrow H^{*}$ be mappings. Suppose that $a: K \times K \rightarrow(-\infty, \infty)$ is a coercive continuous bilinear form, that is, there exist positive constants $c, d>0$ such that
(C1) $a(v, v) \geq c\|v\|^{2}$ for all $v \in K$;
(C2) $|a(u, v)| \leq d\|u\| \cdot\|v\|$ for all $u, v \in K$. It follows from (C1) and (C2) that $c \leq d$. Let $b: K \times K \rightarrow(-\infty,+\infty)$ be nondifferentiable and satisfy the following conditions:
(C3) $b$ is linear in the first argument;
(C4) $b$ is convex in the second argument;
(C5) $b$ is bounded, that is, there exists a constant $l>0$ satisfying

$$
\begin{equation*}
|b(u, v)| \leq l\|u\| \cdot\|v\| \quad \forall u, v \in K ; \tag{2.1}
\end{equation*}
$$

(C6) $b(u, v)-b(u, w) \leq b(u, v-w)$ for all $u, v, w \in K$.
Now we consider the following generalized nonlinear variational-like inequality.
For given $f \in H$, find $u \in K$ such that

$$
\begin{equation*}
\langle N(A u, B u, C u)-f, \eta(v, u)\rangle+a(u, v-u) \geq b(u, u)-b(u, v) \quad \forall v \in K . \tag{2.2}
\end{equation*}
$$

Special cases. If $N(A u, B u, C u)=A u-B u, f=0$, and $b(u, v)=\varphi(v)$ for all $u, v \in K$, where $\varphi: H \rightarrow(-\infty,+\infty)$ is a functional, then the generalized nonlinear variational-like inequality (2.2) is equivalent to finding $u \in K$ such that

$$
\begin{equation*}
\langle A u-B u, \eta(v, u)\rangle \geq \varphi(u)-\varphi(v) \quad \forall v \in K, \tag{2.3}
\end{equation*}
$$

which was introduced and studied by Ding [3].
If $N(A u, B u, C u)=A u-B u, f=0, b(u, v)=\varphi(v)$, and $\eta(u, v)=g u-g v$ for all $u, v \in K$, where $g: K \rightarrow H^{*}$ is a mapping, then the generalized nonlinear variational-like inequality (2.2) is equivalent to finding $u \in K$ such that

$$
\begin{equation*}
\langle A u-B u, g v-g u\rangle \geq \varphi(u)-\varphi(v) \quad \forall v \in K, \tag{2.4}
\end{equation*}
$$

which was studied by Yao [36].
Definition 2.1. Let $A, B: K \rightarrow H, N: H \times H \times H \rightarrow H$, and $\eta: K \times K \rightarrow H^{*}$ be mappings.
(1) $A$ is said to be Lipschitz continuous with constant $r$ if there exists a constant $r>0$ such that

$$
\begin{equation*}
\|A x-A y\| \leq r\|x-y\| \quad \forall x, y \in K \tag{2.5}
\end{equation*}
$$

(2) $N$ is said to be $\eta$-strongly monotone with constant $s$ with respect to $A$ in the first argument if there exists a constant $s>0$ such that

$$
\begin{equation*}
\langle N(A x, u, v)-N(A y, u, v), \eta(x, y)\rangle \geq s\|x-y\|^{2} \quad \forall x, y \in K, \forall u, v \in H . \tag{2.6}
\end{equation*}
$$

(3) $N$ is said to be $\eta$-monotone with respect to $A$ in the second argument if

$$
\begin{equation*}
\langle N(u, A x, v)-N(v, A y, v), \eta(x, y)\rangle \geq 0 \quad \forall x, y \in K, \forall u, v \in H . \tag{2.7}
\end{equation*}
$$

(4) $N$ is said to be Lipschitz continuous with constant $t$ in the third argument if there exists a constant $t>0$ such that

$$
\begin{equation*}
\|N(u, v, x)-N(u, v, y)\| \leq t\|x-y\| \quad \forall x, y, u, v \in H \tag{2.8}
\end{equation*}
$$

(5) $N$ is said to be $\eta$-hemicontinuous with respect to $A$ and $B$ in the first and second arguments if for any $x, y, z \in K$, the mapping $g:[0,1] \rightarrow(-\infty, \infty)$ defined by $g(t)=$ $\langle N(A(t x+(1-t) y), B(t x+(1-t) y), z), \eta(x, y)\rangle$ is continuous at $0^{+}$.
(6) $\eta$ is said to be Lipschitz continuous with constant $s$ if there exists a constant $s>0$ such that

$$
\begin{equation*}
\|\eta(x, y)\| \leq s\|x-y\| \quad \forall x, y \in K . \tag{2.9}
\end{equation*}
$$

(7) $\eta$ is said to be strongly monotone with constant $t$ if there exists a constant $t>0$ such that

$$
\begin{equation*}
\langle x-y, \eta(x, y)\rangle \geq t\|x-y\|^{2} \quad \forall x, y \in K . \tag{2.10}
\end{equation*}
$$

Lemma 2.2 [1, 2]. Let $X$ be a nonempty closed convex subset of a Hausdorff linear topological space $E$, and let $\phi, \psi: X \times X \rightarrow R$ be mappings satisfying the following conditions:
(a) $\psi(x, y) \leq \phi(x, y)$ for all $x, y \in X$, and $\psi(x, x) \geq 0$ for all $x \in X$;
(b) for each $x \in X, \phi(x, \cdot)$ is upper semicontinuous on $X$;
(c) for each $y \in X$, the set $\{x \in X: \psi(x, y)<0\}$ is a convex set;
(d) there exists a nonempty compact set $K \subset X$ and $x_{0} \in K$ such that $\psi\left(x_{0}, y\right)<0$ for all $y \in X \backslash K$.
Then there exists $\hat{y} \in K$ such that $\phi(x, \hat{y}) \geq 0$ for all $x \in X$.

## 3. Auxiliary problem and algorithm

Now we consider the following auxiliary problem with respect to the generalized nonlinear variational-like inequality (2.2). For any given $u \in K$, find $\widehat{w} \in K$ such that

$$
\begin{align*}
\langle\widehat{w}, \eta(v, \widehat{w})\rangle \geq & \langle u, \eta(v, \widehat{w})\rangle-\rho\langle N(A \widehat{w}, B \widehat{w}, C u)-f, \eta(v, \widehat{w})\rangle \\
& -\rho a(\widehat{w}, v-\widehat{w})-\rho b(u, v)+\rho b(u, \widehat{w}) \quad \forall v \in K, \tag{3.1}
\end{align*}
$$

where $\rho>0$ is a constant.

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Theorem 3.1. Let $K$ be a nonempty closed convex subset of $H$ and $f \in H$. Suppose that $a$ : $K \times K \rightarrow(-\infty, \infty)$ satisfies (C1) and (C2), $b: K \times K \rightarrow(-\infty, \infty)$ satisfies (C3)-(C6), and $A, B, C: K \rightarrow H$ and $N: H \times H \times H \rightarrow H$ are mappings such that $N$ is $\eta$-hemicontinuous with respect to $A$ and $B$ in the first and second arguments. Let $\eta: K \times K \rightarrow H^{*}$ be Lipschitz continuous with constant $\delta$ and strongly monotone with constant $\tau$, for each $y \in$ $K$, let $\eta(\cdot, y)$ be continuous and $\eta(y, x)=-\eta(x, y)$ for all $x, y \in K$. Assume that $N$ is $\eta$ strongly monotone with constant $\alpha$ with respect to $A$ in the first argument and $\eta$-monotone with respect to $B$ in the second argument. If for given $x, y, z \in H$ and $v \in K$, the mapping $\langle N(x, y, z), \eta(v, \cdot)\rangle$ is concave and upper semicontinuous, then the auxiliary problem (3.1) has a unique solution in $K$.

Proof. Let $u$ be in $K$. Define the functionals $\phi$ and $\psi: K \times K \rightarrow R$ by

$$
\begin{align*}
\phi(v, w)= & \langle v, \eta(v, w)\rangle-\langle u, \eta(v, w)\rangle+\rho\langle N(A v, B v, C u)-f, \eta(v, w)\rangle \\
& +\rho a(v, v-w)-\rho b(u, w)+\rho b(u, v), \\
\psi(v, w)= & \langle w, \eta(v, w)\rangle-\langle u, \eta(v, w)\rangle+\rho\langle N(A w, B w, C u)-f, \eta(v, w)\rangle  \tag{3.2}\\
& +\rho a(w, v-w)-\rho b(u, w)+\rho b(u, v)
\end{align*}
$$

for all $v, w \in K$.
We check that the functionals $\phi$ and $\psi$ satisfy all the conditions of Lemma 2.2 in the weak topology. It is easy to see for all $v, w \in K$,

$$
\begin{align*}
\phi(v, w) & -\psi(v, w) \\
= & \langle v-w, \eta(v, w)\rangle+\rho\langle N(A v, B v, C u)-N(A w, B v, C u), \eta(v, w)\rangle \\
& +\rho\langle N(A w, B v, C u)-N(A w, B w, C u), \eta(v, w)\rangle+\rho a(v-w, v-w)  \tag{3.3}\\
\geq & {[\tau+\rho(\alpha+c)]\|v-w\|^{2} \geq 0, }
\end{align*}
$$

which implies that $\phi$ and $\psi$ satisfy the condition (1) of Lemma 2.2. Since $a$ is a coercive continuous bilinear form, it follows that $a(v, v-w)$ is weakly upper semicontinuous with respect to $w$. Note that $b$ is convex and lower semicontinuous in the second argument and for given $x, y, z \in H, v \in K$, the mapping $\langle N(x, y, z), \eta(v, \cdot)\rangle$ is concave and upper semicontinuous. Therefore $\phi(v, \cdot)$ is weakly upper semicontinuous in the second argument and the set $\{v \in K: \psi(v, w)<0\}$ is convex for each $w \in K$. That is, the conditions (2) and (3) of Lemma 2.2 hold. Let $\bar{v} \in K$. Put

$$
\begin{gather*}
L=[\tau+\rho(\alpha+c)]^{-1}[\delta\|u-\bar{v}\|+\rho d\|\bar{v}\|+\rho \delta\|N(A \bar{v}, B \bar{v}, C u)-f\|+\rho l\|u\|]  \tag{3.4}\\
M=\{w \in K:\|w-\bar{v}\| \leq L\} .
\end{gather*}
$$

Clearly, $M$ is a weakly compact subset of $K$ and for any $w \in K \backslash M$,

$$
\begin{align*}
\psi(\bar{v}, w)= & \langle w, \eta(\bar{v}, w)\rangle-\langle u, \eta(\bar{v}, w)\rangle \\
& +\rho\langle N(A w, B w, C u)-f, \eta(\bar{v}, w)\rangle \\
& +\rho a(w, \bar{v}-w)-\rho b(u, w)+\rho b(u, \bar{v}) \\
\leq & -\langle w-\bar{v}, \eta(w, \bar{v})\rangle+\langle u-\bar{v}, \eta(w, \bar{v})\rangle \\
& -\rho\langle N(A w, B w, C u)-N(A \bar{v}, B w, C u), \eta(w, \bar{v})\rangle \\
- & \rho\langle N(A \bar{v}, B w, C u)-N(A \bar{v}, B \bar{v}, C u), \eta(w, \bar{v})\rangle  \tag{3.5}\\
- & \rho\langle N(A \bar{v}, B \bar{v}, C u)-f, \eta(w, \bar{v})\rangle \\
& -\rho a(w-\bar{v}, w-\bar{v})-\rho a(\bar{v}, w-\bar{v})+\rho b(u, \bar{v}-w) \\
\leq & -\|w-\bar{v}\|\{[\tau+\rho(\alpha+c)]\|w-\bar{v}\|-\delta\|u-\bar{v}\| \\
& \quad-\rho d\|\bar{v}\|-\rho \delta\|N(A \bar{v}, B \bar{v}, C u)-f\|-\rho l\|u\|\}<0,
\end{align*}
$$

which means that the condition (4) of Lemma 2.2 holds. Thus Lemma 2.2 ensures that there exists $\hat{w} \in K$ such that $\phi(v, \widehat{w}) \geq 0$ for all $v \in K$, that is,

$$
\begin{align*}
\langle v, \eta(v, \widehat{w})\rangle \geq & \langle u, \eta(v, \hat{w})\rangle-\rho\langle N(A v, B v, C u)-f, \eta(v, \widehat{w})\rangle \\
& -\rho a(v, v-\widehat{w})-\rho b(u, v)+\rho b(u, \widehat{w}) \quad \forall v \in K . \tag{3.6}
\end{align*}
$$

Let $t$ be in $(0,1]$ and let $v$ be in $K$. Replacing $v$ by $v_{t}=t v+(1-t) \widehat{w}$ in (3.6), we see that

$$
\begin{align*}
\left\langle v_{t}, \eta\left(v_{t}, \widehat{w}\right)\right\rangle \geq & \left\langle u, \eta\left(v_{t}, \widehat{w}\right)\right\rangle-\rho\left\langle N\left(A v_{t}, B v_{t}, C u\right)-f, \eta\left(v_{t}, \widehat{w}\right)\right\rangle \\
& -\rho a\left(v_{t}, v_{t}-\widehat{w}\right)-\rho b\left(u, v_{t}\right)+\rho b(u, \widehat{w}) \quad \forall v \in K . \tag{3.7}
\end{align*}
$$

Notice that $b$ is convex in the second argument and $\langle N(x, y, z), \eta(v, \cdot)\rangle$ is concave and upper semicontinuous. From (C6) and (3.7) we infer that

$$
\begin{align*}
t\left[\left\langle v_{t}, \eta(v, \widehat{w})\right\rangle\right] \geq t & {\left[\langle u, \eta(v, \widehat{w})\rangle-\rho\left\langle N\left(A v_{t}, B v_{t}, C u\right)-f, \eta(v, \widehat{w})\right\rangle\right.} \\
& \left.-\rho a\left(v_{t}, v-\widehat{w}\right)-\rho b(u, v)+\rho b(u, \widehat{w})\right] \quad \forall v \in K \tag{3.8}
\end{align*}
$$

which implies that

$$
\begin{align*}
\left\langle v_{t}, \eta(v, \widehat{w})\right\rangle \geq & \langle u, \eta(v, \widehat{w})\rangle-\rho\left\langle N\left(A v_{t}, B v_{t}, C u\right)-f, \eta(v, \widehat{w})\right\rangle \\
& -\rho a\left(v_{t}, v-\widehat{w}\right)-\rho b(u, v)+\rho b(u, \widehat{w}) \quad \forall v \in K . \tag{3.9}
\end{align*}
$$

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Letting $t \rightarrow 0^{+}$in the above inequality, we conclude that

$$
\begin{align*}
\langle\widehat{w}, \eta(v, \widehat{w})\rangle \geq & \langle u, \eta(v, \widehat{w})\rangle-\rho\langle N(A \widehat{w}, B \widehat{w}, C u)-f, \eta(v, \widehat{w})\rangle \\
& -\rho a(\widehat{w}, v-\widehat{w})-\rho b(u, v)+\rho b(u, \widehat{w}) \quad \forall v \in K . \tag{3.10}
\end{align*}
$$

That is, $\widehat{w}$ is a solution of (3.1). Now we prove the uniqueness. For any two solutions $w_{1}, w_{2} \in K$ of (3.1) with respect to $u$, we know that

$$
\begin{align*}
\left\langle w_{1}, \eta\left(v, w_{1}\right)\right\rangle \geq & \left\langle u, \eta\left(v, w_{1}\right)\right\rangle-\rho\left\langle N\left(A w_{1}, B w_{1}, C u\right)-f, \eta\left(v, w_{1}\right)\right\rangle \\
& -\rho a\left(w_{1}, v-w_{1}\right)-\rho b(u, v)+\rho b\left(u, w_{1}\right),  \tag{3.11}\\
\left\langle w_{2}, \eta\left(v, w_{2}\right)\right\rangle \geq & \left\langle u, \eta\left(v, w_{2}\right)\right\rangle-\rho\left\langle N\left(A w_{2}, B w_{2}, C u\right)-f, \eta\left(v, w_{2}\right)\right\rangle \\
& -\rho a\left(w_{2}, v-w_{2}\right)-\rho b(u, v)+\rho b\left(u, w_{2}\right) \tag{3.12}
\end{align*}
$$

for all $v \in K$. Taking $v=w_{2}$ in (3.11) and $v=w_{1}$ in (3.12), we get that

$$
\begin{align*}
\left\langle w_{1}, \eta\left(w_{2}, w_{1}\right)\right\rangle \geq & \left\langle u, \eta\left(w_{2}, w_{1}\right)\right\rangle-\rho\left\langle N\left(A w_{1}, B w_{1}, C u\right)-f, \eta\left(w_{2}, w_{1}\right)\right\rangle \\
& -\rho a\left(w_{1}, w_{2}-w_{1}\right)-\rho b\left(u, w_{2}\right)+\rho b\left(u, w_{1}\right), \\
\left\langle w_{2}, \eta\left(w_{1}, w_{2}\right)\right\rangle \geq & \left\langle u, \eta\left(w_{1}, w_{2}\right)\right\rangle-\rho\left\langle N\left(A w_{2}, B w_{2}, C u\right)-f, \eta\left(w_{1}, w_{2}\right)\right\rangle  \tag{3.13}\\
& -\rho a\left(w_{2}, w_{1}-w_{2}\right)-\rho b\left(u, w_{1}\right)+\rho b\left(u, w_{2}\right) .
\end{align*}
$$

Adding these inequalities, we deduce that

$$
\begin{align*}
\tau\left\|w_{1}-w_{2}\right\|^{2} \leq & -\rho\left\langle N\left(A w_{1}, B w_{1}, C u\right)-N\left(A w_{2}, B w_{1}, C u\right), \eta\left(w_{1}, w_{2}\right)\right\rangle \\
& -\rho\left\langle N\left(A w_{2}, B w_{1}, C u\right)-N\left(A w_{2}, B w_{2}, C u\right), \eta\left(w_{1}, w_{2}\right)\right\rangle \\
& -\rho a\left(w_{1}-w_{2}, w_{1}-w_{2}\right)  \tag{3.14}\\
\leq & -\rho(\alpha+c)\left\|w_{1}-w_{2}\right\|^{2},
\end{align*}
$$

which yields $w_{1}=w_{2}$. That is, $\widehat{w}$ is the unique solution of (3.1). This completes the proof.

By Theorem 3.1, we suggest the following algorithms for solving the generalized nonlinear variational-like inequality (2.2).

Algorithm 3.2. Suppose that $a: K \times K \rightarrow(-\infty, \infty)$ satisfies (C1), (C2), $b: K \times K \rightarrow$ $(-\infty, \infty)$ satisfies (C3)-(C6), and $A, B, C: K \rightarrow H, N: H \times H \times H \rightarrow H$ and $\eta: K \times K \rightarrow$ $H^{*}$ are mappings. For given $f \in H$ and $u_{0} \in K$, compute the sequence $\left\{u_{n}\right\}_{n \geq 0} \subset K$ by the following iterative scheme:

$$
\begin{align*}
\left\langle u_{n+1}, \eta\left(v, u_{n+1}\right)\right\rangle \geq & \left\langle u_{n}, \eta\left(v, u_{n+1}\right)\right\rangle-\rho\left\langle N\left(A u_{n+1}, B u_{n+1}, C u_{n}\right)-f, \eta\left(v, u_{n+1}\right)\right\rangle \\
& -\rho a\left(u_{n+1}, v-u_{n+1}\right)-\rho b\left(u_{n}, v\right)+\rho b\left(u_{n}, u_{n+1}\right)+\left\langle e_{n}, \eta\left(v, u_{n+1}\right)\right\rangle \tag{3.15}
\end{align*}
$$

for all $v \in K$ and $n \geq 0$, where $\left\{e_{n}\right\}_{n \geq 0} \subset H$ and $\rho>0$ is a constant.

## 4. Existence and convergence

In this section, we prove the existence of solution for the generalized nonlinear vari-ational-like inequality (2.2) and discuss the convergence of the sequence generated by Algorithm 3.2.

Theorem 4.1. Let $a, b, A, B, N, \eta$ be as in Theorem 3.1. Let $C: K \rightarrow H$ be Lipschitz continuous with constant $\xi$. Assume that $N$ is Lipschitz continuous with constant $\sigma$ in the third argument and strongly monotone with constant $\beta$ with respect to $C$ in the third argument and

$$
\begin{equation*}
\sigma \xi \geq \beta, \quad k=\frac{l-\alpha-c}{\delta}, \quad p=\frac{\tau}{\delta}, \quad \lim _{n \rightarrow \infty}\left\|e_{n}\right\|=0 \tag{4.1}
\end{equation*}
$$

If there exist a constant $\rho$ satisfying

$$
\begin{equation*}
0<\rho<\frac{\tau}{l-\alpha-c}, \tag{4.2}
\end{equation*}
$$

and one of the following conditions:

$$
\begin{gather*}
\left|\rho-\frac{\beta-p k}{\sigma^{2} \xi^{2}-k^{2}}\right|<\frac{\sqrt{(\beta-p k)^{2}-\left(\sigma^{2} \xi^{2}-k^{2}\right)\left(1-p^{2}\right)}}{\sigma^{2} \xi^{2}-k^{2}}, \\
\sigma \xi>k, \quad|\beta-p k|>\sqrt{\left(\sigma^{2} \xi^{2}-k^{2}\right)\left(1-p^{2}\right)},  \tag{4.3}\\
\left|\rho-\frac{p k-\beta}{k^{2}-\sigma^{2} \xi^{2}}\right|>\frac{\sqrt{(\beta-p k)^{2}+\left(k^{2}-\sigma^{2} \xi^{2}\right)\left(1-p^{2}\right)}}{k^{2}-\sigma^{2} \xi^{2}}, \quad \sigma \xi<k,
\end{gather*}
$$

then the iterative sequence $\left\{u_{n}\right\}_{n \geq 0}$ generated by Algorithm 3.2 converges strongly to some $u \in K$ and $u$ is a solution of the generalized nonlinear variational-like inequality (2.2).

Proof. It follows from the proof of Theorem 3.1 that there exists a mapping $G: K \rightarrow K$ satisfying $G(u)=w$, where $w$ is the unique solution of (3.1) for each $u \in K$. Next we show that $G$ is a contraction mapping. Let $u_{1}$ and $u_{2}$ be arbitrary elements in $K$. Using (3.1), we see that

$$
\begin{align*}
\left\langle G u_{1}, \eta\left(v, G u_{1}\right)\right\rangle \geq & \left\langle u_{1}, \eta\left(v, G u_{1}\right)\right\rangle-\rho\left\langle N\left(A\left(G u_{1}\right), B\left(G u_{1}\right), C u_{1}\right)-f, \eta\left(v, G u_{1}\right)\right\rangle \\
& -\rho a\left(G u_{1}, v-G u_{1}\right)-\rho b\left(u_{1}, v\right)+\rho b\left(u_{1}, G u_{1}\right),  \tag{4.4}\\
\left\langle G u_{2}, \eta\left(v, G u_{2}\right)\right\rangle \geq & \left\langle u_{2}, \eta\left(v, G u_{2}\right)\right\rangle-\rho\left\langle N\left(A\left(G u_{2}\right), B\left(G u_{2}\right), C u_{2}\right)-f, \eta\left(v, G u_{2}\right)\right\rangle \\
& -\rho a\left(G u_{2}, v-G u_{2}\right)-\rho b\left(u_{2}, v\right)+\rho b\left(u_{2}, G u_{2}\right) \tag{4.5}
\end{align*}
$$

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for all $v \in K$. Letting $v=G u_{2}$ in (4.4) and $v=G u_{1}$ in (4.5), and adding these inequalities, we arrive at

$$
\begin{align*}
\tau\left\|G u_{1}-G u_{2}\right\|^{2} \leq & \left\langle G u_{1}-G u_{2}, \eta\left(G u_{1}, G u_{2}\right)\right\rangle \\
\leq & \left\langle u_{1}-u_{2}-\rho\left(N\left(A\left(G u_{2}\right), B\left(G u_{2}\right), C u_{1}\right)\right.\right. \\
& \left.\left.\quad-N\left(A\left(G u_{2}\right), B\left(G u_{2}\right), C u_{2}\right)\right), \eta\left(G u_{1}, G u_{2}\right)\right\rangle \\
& -\rho\left\langle N\left(A\left(G u_{1}\right), B\left(G u_{1}\right), C u_{1}\right)\right. \\
& \left.\quad-N\left(A\left(G u_{2}\right), B\left(G u_{1}\right), C u_{1}\right), \eta\left(G u_{1}, G u_{2}\right)\right\rangle \\
- & \rho\left\langle N\left(A\left(G u_{2}\right), B\left(G u_{1}\right), C u_{1}\right)\right.  \tag{4.6}\\
& \left.\quad-N\left(A\left(G u_{2}\right), B\left(G u_{2}\right), C u_{1}\right), \eta\left(G u_{1}, G u_{2}\right)\right\rangle \\
& -\rho a\left(G u_{1}-G u_{2}, G u_{1}-G u_{2}\right)+\rho b\left(u_{1}-u_{2}, G u_{2}-G u_{1}\right) \\
\leq & {\left[\delta \sqrt{1-2 \rho \beta+(\rho \sigma \xi)^{2}}+\rho l\right]\left\|u_{1}-u_{2}\right\|\left\|G u_{1}-G u_{2}\right\| } \\
& -\rho(\alpha+c)\left\|G u_{1}-G u_{2}\right\|^{2},
\end{align*}
$$

that is,

$$
\begin{equation*}
\left\|G u_{1}-G u_{2}\right\| \leq \theta\left\|u_{1}-u_{2}\right\| \tag{4.7}
\end{equation*}
$$

where

$$
\begin{equation*}
\theta=\frac{\delta \sqrt{1-2 \rho \beta+(\rho \sigma \xi)^{2}}+\rho l}{\tau+\rho(\alpha+c)}<1 \tag{4.8}
\end{equation*}
$$

by (4.2) and one of (4.3). Therefore, $G: K \rightarrow K$ is a contraction mapping and has a unique fixed point $u \in K$. It follows from (3.1) that

$$
\begin{align*}
\langle u, \eta(v, u)\rangle \geq & \langle u, \eta(v, u)\rangle-\rho\langle N(A u, B u, C u)-f, \eta(v, u)\rangle \\
& -\rho a(u, v-u)-\rho b(u, v)+\rho b(u, u) \quad \forall v \in K, \tag{4.9}
\end{align*}
$$

which implies that

$$
\begin{equation*}
\langle N(A u, B u, C u)-f, \eta(v, u)\rangle+a(u, v-u) \geq b(u, u)-b(u, v) \quad \forall v \in K, \tag{4.10}
\end{equation*}
$$

that is, $u$ is a solution of the generalized nonlinear variational-like inequality (2.2).

Next, we consider the convergence of the iterative sequence generated by Algorithm 3.2. Taking $v=u_{n+1}$ in (4.9) and $v=u$ in (3.15), and adding these inequalities, we have

$$
\begin{align*}
\tau\left\|u_{n+1}-u\right\|^{2} \leq & \left\langle u_{n+1}-u, \eta\left(u_{n+1}, u\right)\right\rangle \\
\leq & \left\langle u_{n}-u-\rho\left(N\left(A u, B u, C u_{n}\right)-N(A u, B u, C u)\right), \eta\left(u_{n+1}, u\right)\right\rangle \\
& -\rho\left\langle N\left(A u_{n+1}, B u_{n+1}, C u_{n}\right)-N\left(A u, B u_{n+1}, C u\right), \eta\left(u_{n+1}, u\right)\right\rangle \\
& -\rho\left\langle N\left(A u, B u_{n+1}, C u_{n}\right)-N\left(A u, B u, C u_{n}\right), \eta\left(u_{n+1}, u\right)\right\rangle \\
& -\rho a\left(u_{n+1}-u, u_{n+1}-u\right)+\rho b\left(u_{n}-u, u-u_{n+1}\right)+\left\langle e_{n}, \eta\left(u_{n+1}, u\right)\right\rangle \\
\leq & {\left[\delta \sqrt{1-2 \rho \beta+(\rho \sigma \xi)^{2}}+\rho l\right]\left\|u_{n}-u\right\|\left\|\left\|u_{n+1}-u\right\|\right.} \\
& -\rho(\alpha+c)\left\|u_{n+1}-u\right\|^{2}+\left\|e_{n}\right\|\left\|u_{n+1}-u\right\| \tag{4.11}
\end{align*}
$$

for all $n \geq 1$. That is,

$$
\begin{equation*}
\left\|u_{n+1}-u\right\| \leq \theta\left\|u_{n}-u\right\|+\left\|e_{n}\right\| \rightarrow 0 \quad \text { as } n \longrightarrow \infty, \tag{4.12}
\end{equation*}
$$

where $\theta$ is defined by (4.8). It follows from (4.1) and (4.12) that the iterative sequence $\left\{u_{n}\right\}_{n \geq 0}$ generated by Algorithm 3.2 converges strongly to $u$. This completes the proof.

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