

Retraction

Retracted: Application of Neural Network in the Stability of Biped Robot and Embedded Control of Walking Mode

Journal of Electrical and Computer Engineering

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Journal of Electrical and Computer Engineering has retracted the article titled “Application of Neural Network in the Stability of Biped Robot and Embedded Control of Walking Mode” [1] due to concerns that the peer review process has been compromised.

Following an investigation conducted by the Hindawi Research Integrity team [2], significant concerns were identified with the peer reviewers assigned to this article; the investigation has concluded that the peer review process was compromised. We therefore can no longer trust the peer review process, and the article is being retracted with the agreement of the editorial board.

References

- [1] J. Zhang, Z. Yuan, H. Geng, S. Dong, F. Zhang, and J. Li, “Application of Neural Network in the Stability of Biped Robot and Embedded Control of Walking Mode,” *Journal of Electrical and Computer Engineering*, vol. 2022, Article ID 7474820, 10 pages, 2022.
- [2] L. Ferguson, “Advancing Research Integrity Collaboratively and with Vigour,” 2022, <https://www.hindawi.com/post/advancing-research-integrity-collaboratively-and-vigour/>.